

A CRITERION FOR ISOMORPHISM OF ARTINIAN GORENSTEIN ALGEBRAS

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ABSTRACT. Let A be an Artinian Gorenstein algebra over an infinite field k of characteristic either 0 or greater than the socle degree of A . To every such algebra and a linear projection π on its maximal ideal \mathfrak{m} with range equal to the socle $\text{Soc}(A)$ of A , one can associate a certain algebraic hypersurface $S_\pi \subset \mathfrak{m}$, which is the graph of a polynomial map $P_\pi : \ker \pi \rightarrow \text{Soc}(A) \simeq k$. Recently, the following surprising criterion has been obtained: two Artinian Gorenstein algebras A, \tilde{A} are isomorphic if and only if any two hypersurfaces S_π and $S_{\tilde{\pi}}$ arising from A and \tilde{A} , respectively, are affinely equivalent. The proof is indirect and relies on a geometric argument. In the present paper, we give a short algebraic proof of this statement. We also discuss a connection, established elsewhere, between the polynomials P_π and Macaulay inverse systems.

1. Introduction. We consider Artinian local commutative associative algebras over a field k . Recall that such an algebra A is Gorenstein if and only if the socle $\text{Soc}(A)$ of A is a one-dimensional vector space over k (see, e.g., [11]). Gorenstein algebras frequently occur in various areas of mathematics and applications to physics (see, e.g., [2, 15]). For $k = \mathbb{C}$, in [8], we found a surprising criterion for two Artinian Gorenstein algebras to be isomorphic. The criterion was given in terms of a certain algebraic hypersurface S_π in the maximal ideal \mathfrak{m} of A associated to a linear projection π on \mathfrak{m} with range $\text{Soc}(A)$, where we assume that $\dim_k A > 1$. The hypersurface S_π passes through the origin and is the graph of a polynomial map $P_\pi : \ker \pi \rightarrow \text{Soc}(A) \simeq \mathbb{C}$. In [8], we showed that for $k = \mathbb{C}$ two Artinian Gorenstein algebras A, \tilde{A} are isomorphic if and only if any two hypersurfaces S_π and $S_{\tilde{\pi}}$ arising

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from A and \tilde{A} , respectively, are affinely equivalent, that is, there exists a bijective affine map $\mathcal{A} : \mathfrak{m} \rightarrow \tilde{\mathfrak{m}}$ such that $\tilde{A}(S_\pi) = S_{\tilde{\pi}}$.

It should be noted that the above criterion differs from the well-known criterion in terms of Macaulay inverse systems, where to an Artinian Gorenstein algebra A one also associates certain polynomials (see, e.g., [6, Proposition 2.2 and references]). Indeed, as the discussion in Section 5 shows, in general none of the polynomials P_π is an inverse system for A . The value of the method of [8] lies in the fact that affine equivalence for the hypersurfaces S_π and $S_{\tilde{\pi}}$ is sometimes easier to verify than the kind of equivalence required for inverse systems (see [6, formula (7)]). In Section 4, we give an example when this is indeed the case.

At the time of writing the article [8] we could not find an algebraic proof of our criterion, but, quite unexpectedly, discovered a proof based on the geometry of certain real codimension two quadrics in complex space. On the other hand, the hypersurface S_π can be introduced for an Artinian Gorenstein algebra A over any field k of characteristic either zero or greater than the socle degree ν of A . Therefore, it is natural to attempt to extend the result of [8] to all such algebras. Indeed, an extension of this kind was obtained in the recent paper [9]. The result was stated for fields of zero characteristic, but the proof is likely to work at least for some fields satisfying $\text{char}(k) > \nu$ as well. The argument proceeds by reducing the case of an arbitrary field to the case $k = \mathbb{C}$, and therefore the basis of the method of [9] remains the geometric idea of [8]. It would be very desirable, however, to find a purely algebraic argument directly applicable to any field. In this paper we present such an argument, in which neither geometry nor reduction to the case $k = \mathbb{C}$ is required and which works for any infinite field k with either $\text{char}(k) = 0$ or $\text{char}(k) > \nu$. We note that a very brief outline of the argument was given in [14], and the main purpose of this article is to provide full details. Another purpose of the paper is to exhibit our approach to Artinian Gorenstein algebras to a broad audience, and therefore the article is to some extent expository.

The paper is organized as follows. Section 2 contains necessary preliminaries and the precise statement of the criterion in Theorem 2.1. Our proof of Theorem 2.1 is given in Section 3. In Section 4, we demonstrate how this result works in applications (see Example 4.2). Namely, we consider an Artinian Gorenstein algebra A_0 , originally

presented in [9], of embedding dimension 3 and socle degree 4 whose Hilbert function is $\{1, 3, 3, 1, 1\}$. Further, we perturb A_0 to obtain a one-parameter family A_t of Artinian Gorenstein algebras of the same dimension and socle degree. While directly establishing a relationship between A_t and A_0 seems to be nontrivial, this can easily be done with the help of Theorem 2.1. Namely, using the theorem we show, in a rather elementary way, that each algebra A_t is in fact isomorphic to A_0 .

Next, in Section 5, we discuss the connection between the polynomials P_π and Macaulay inverse systems for any Artinian Gorenstein algebra A found in our earlier articles [1, 5]. The proof is short and, for the completeness of our exposition, we include it in the present paper as well. Namely, if P_π is regarded as a map from $\ker \pi$ to k (in which case we call it a *nil-polynomial*), then the restriction of P_π to any subspace of $\ker \pi$ that forms a complement to \mathfrak{m}^2 in \mathfrak{m} is an inverse system for A (see Remark 5.3). All these subspaces are of dimension equal to the embedding dimension $\text{emb dim } A$ of A ; thus, nil-polynomials can be viewed as extensions of certain inverse systems to spaces of dimension greater than $\text{emb dim } A$. As a result, since nil-polynomials are given explicitly, one obtains an effective formula for computing an inverse system for any Artinian Gorenstein algebra (see Theorem 5.1 and Remark 5.5). It appears that such a formula had not existed in the literature prior to our work (see, however, Remark 5.2).

Utilizing the above relationship between nil-polynomials and Macaulay inverse systems, at the end of Section 5 we revisit Example 4.2 and explain how isomorphism between A_t and A_0 can be established by using inverse systems. This turns out to be significantly harder to do than by applying the method based on nil-polynomials (at least, if one ignores the calculations required to find the relevant nil-polynomials). In general, to use inverse systems, one needs to compute them first, and Theorem 5.1 provides an explicit way for producing them from nil-polynomials. This fact alone shows that nil-polynomials are a new rather useful tool for the study of Artinian Gorenstein algebras.

2. Preliminaries. Let A be an Artinian Gorenstein algebra over a field k with identity element $\mathbf{1}$, maximal ideal \mathfrak{m} and socle $\text{Soc}(A) := \{x \in A : x\mathfrak{m} = 0\}$. Suppose that $\dim_k A > 1$ (i.e., $\mathfrak{m} \neq 0$) and denote by ν the socle degree of A , that is, the largest among all integers μ for

which $\mathfrak{m}^\nu \neq 0$. Observe that $\nu \geq 1$ and $\text{Soc}(A) = \mathfrak{m}^\nu$.

Assume now that either $\text{char}(k) = 0$ or $\text{char}(k) > \nu$ and define the *exponential map* $\exp : \mathfrak{m} \rightarrow \mathbf{1} + \mathfrak{m}$ by the formula

$$\exp(x) := \sum_{m=0}^{\nu} \frac{1}{m!} x^m,$$

where $x^0 := \mathbf{1}$. This map is bijective with the inverse given by

$$\log(\mathbf{1} + x) := \sum_{m=1}^{\nu} \frac{(-1)^{m+1}}{m} x^m, \quad x \in \mathfrak{m}.$$

Next, fix a linear projection π on A with range $\text{Soc}(A)$ and kernel containing $\mathbf{1}$ (we call such projections *admissible*). Set $\mathcal{K} := \ker \pi \cap \mathfrak{m}$, and let S_π be the graph of the polynomial map $P_\pi : \mathcal{K} \rightarrow \text{Soc}(A)$ of degree ν defined as follows:

$$(2.1) \quad P_\pi(x) := \pi(\exp(x)) = \pi\left(\sum_{m=2}^{\nu} \frac{1}{m!} x^m\right), \quad x \in \mathcal{K}$$

(note that for $\dim_k A = 2$ one has $P_\pi = 0$). Everywhere below we identify any point $(x, P_\pi(x)) \in S_\pi$ with the point $x + P_\pi(x) \in \mathcal{K} \oplus \text{Soc}(A) = \mathfrak{m}$ and therefore think of S_π as a hypersurface in \mathfrak{m} . Observe that the $\text{Soc}(A)$ -valued quadratic part of P_π is non-degenerate on \mathcal{K} since the $\text{Soc}(A)$ -valued bilinear form

$$(2.2) \quad b_\pi(a, c) := \pi(ac), \quad a, c \in A$$

is non-degenerate on A (see, e.g., [10, page 11]). Examples of hypersurfaces S_π explicitly computed for particular algebras can be found in [4, 8, 9] (see also Section 4 below).

We will now state the criterion for isomorphism of Gorenstein algebras that was obtained in [8, 9] for algebras over fields of zero characteristic.

Theorem 2.1. *Let A, \tilde{A} be Gorenstein algebras of finite vector space dimension greater than 1 and socle degree ν over an infinite field k with either $\text{char}(k) = 0$ or $\text{char}(k) > \nu$. Let, further, $\pi, \tilde{\pi}$ be admissible projections on A and \tilde{A} , respectively. Then A and \tilde{A} are isomorphic if and only if the hypersurfaces $S_\pi, S_{\tilde{\pi}}$ are affinely equivalent. Moreover,*

if $\mathcal{A} : \mathfrak{m} \rightarrow \tilde{\mathfrak{m}}$ is a linear isomorphism such that $\mathcal{A}(S_\pi) = S_{\tilde{\pi}}$, then \mathcal{A} is an algebra isomorphism.

3. Proof of Theorem 2.1. For every hypersurface S_π , we let \mathcal{S}_π be the graph over \mathcal{K} of the polynomial map $-P_\pi$ (see (2.1)). Observe that

$$(3.1) \quad \mathcal{S}_\pi = \{x \in \mathfrak{m} : \pi(\exp(x)) = 0\}.$$

Clearly, S_π and $S_{\tilde{\pi}}$ are affinely equivalent if and only if \mathcal{S}_π and $\mathcal{S}_{\tilde{\pi}}$ are affinely equivalent, and below we will obtain the first statement of the theorem with \mathcal{S}_π and $\mathcal{S}_{\tilde{\pi}}$ in place of S_π and $S_{\tilde{\pi}}$, respectively.

The necessity implication is proved as in [8, Proposition 2.2]. The argument is short, and for the completeness of our exposition we reproduce it below. The idea is to show that if π_1 and π_2 are admissible projections on A , then $\mathcal{S}_{\pi_1} = \mathcal{S}_{\pi_2} + x_0$ for some $x_0 \in \mathfrak{m}$. Clearly, the necessity implication is a consequence of this fact.

For every $y \in \mathfrak{m}$, let M_y be the multiplication operator from A to \mathfrak{m} defined by $a \mapsto ya$, and set $\mathcal{K}_1 := \ker \pi_1 \cap \mathfrak{m}$. The correspondence

$$y \mapsto \pi_1 \circ M_y|_{\mathcal{K}_1}$$

defines a linear map \mathfrak{L} from \mathcal{K}_1 into the space $L(\mathcal{K}_1, \text{Soc}(A))$ of linear maps from \mathcal{K}_1 to $\text{Soc}(A)$. Since, for every admissible projection π , the form b_π defined in (2.2) is non-degenerate on A , and since $\dim_k L(\mathcal{K}_1, \text{Soc}(A)) = \dim_k \mathcal{K}_1$, it follows that \mathfrak{L} is an isomorphism.

Next, let $\lambda := \pi_2 - \pi_1$, and observe that $\lambda(\mathbf{1}) = 0$, $\lambda(\text{Soc}(A)) = 0$. Clearly, $\lambda|_{\mathcal{K}_1}$ lies in $L(\mathcal{K}_1, \text{Soc}(A))$, and therefore there exists $y_0 \in \mathcal{K}_1$ such that $\lambda|_{\mathcal{K}_1} = \pi_1 \circ M_{y_0}|_{\mathcal{K}_1}$. We then have $\lambda = \pi_1 \circ M_{y_0}$ everywhere on A ; hence,

$$\pi_2(\exp(x)) = \pi_1\left(\left(\mathbf{1} + y_0\right)\exp(x)\right) = \pi_1(\exp(x + x_0))$$

for $x_0 := \log(\mathbf{1} + y_0)$, which implies $\mathcal{S}_{\pi_1} = \mathcal{S}_{\pi_2} + x_0$ as claimed.

We will now obtain the sufficiency implication. Let $\mathcal{A} : \mathfrak{m} \rightarrow \tilde{\mathfrak{m}}$ be an affine equivalence with $\mathcal{A}(S_\pi) = S_{\tilde{\pi}}$, and $z_0 := \mathcal{A}(0)$. Consider the linear map $\mathcal{L}(x) := \mathcal{A}(x) - z_0$, with $x \in \mathfrak{m}$. We will show that $\mathcal{L} : \mathfrak{m} \rightarrow \tilde{\mathfrak{m}}$ is an algebra isomorphism, which will imply that A and \tilde{A} are isomorphic.

Clearly, \mathcal{L} maps \mathcal{S}_π onto $\mathcal{S}_{\tilde{\pi}} - z_0$. Consider the admissible projection on \tilde{A} given by the formula $\tilde{\pi}'(a) := \tilde{\pi}(\widetilde{\text{exp}}(z_0)a)$, where $\widetilde{\text{exp}}$ is the exponential map associated to \tilde{A} . Formula (3.1) then implies $\mathcal{S}_{\tilde{\pi}} - z_0 = \mathcal{S}_{\tilde{\pi}'}$; hence, \mathcal{L} maps \mathcal{S}_π onto $\mathcal{S}_{\tilde{\pi}'}$.

Recall that \mathcal{S}_π is the graph of the polynomial map $-P_\pi : \mathcal{K} \rightarrow \text{Soc}(A)$ (see (2.1)). Set $n := \dim_k \mathfrak{m} - 1 = \dim_k \tilde{\mathfrak{m}} - 1$, and choose coordinates $\alpha = (\alpha_1, \dots, \alpha_n)$ in \mathcal{K} and a coordinate α_{n+1} in $\text{Soc}(A)$. In these coordinates, the hypersurface \mathcal{S}_π is written as

$$\alpha_{n+1} = \sum_{i,j=1}^n g_{ij} \alpha_i \alpha_j + \sum_{i,j,\ell=1}^n h_{ijk} \alpha_i \alpha_j \alpha_\ell + \dots,$$

where g_{ij} and $h_{ij\ell}$ are symmetric in all indices, (g_{ij}) is non-degenerate and the dots denote the higher-order terms. In [8, Proposition 2.10] (which works over any field of characteristic either zero or greater than ν) we showed that the above equation of \mathcal{S}_π is in *Blaschke normal form*, that is, one has

$$\sum_{ij=1}^n g^{ij} h_{ij\ell} = 0 \quad \text{for all } \ell, \text{ where } (g^{ij}) := (g_{ij})^{-1}.$$

We will now need the following lemma, which is a variant of the second statement of Proposition 1 in [3].

Lemma 3.1. *Let V and W be vector spaces over an infinite field k , with $\dim_k V = \dim_k W = N + 1$, $N \geq 0$. Choose coordinates $\beta = (\beta_1, \dots, \beta_N)$, β_{N+1} in V and coordinates $\gamma = (\gamma_1, \dots, \gamma_N)$, γ_{N+1} in W . Let $S \subset V$ and $T \subset W$ be hypersurfaces given, respectively, by the equations*

$$(3.2) \quad \beta_{N+1} = \mathcal{P}(\beta_1, \dots, \beta_N), \quad \gamma_{N+1} = \mathcal{Q}(\gamma_1, \dots, \gamma_N),$$

where \mathcal{P} and \mathcal{Q} are polynomials without constant and linear terms. Assume further that equations (3.2) are in Blaschke normal form. Then every bijective linear transformation of V onto W that maps S into T has the form

$$\gamma = C\beta, \quad \gamma_{N+1} = c\beta_{N+1},$$

where $C \in \text{GL}(N, k)$, $c \in k^*$ and β, γ are viewed as column-vectors.

Proof. Let $L : V \rightarrow W$ be a bijective linear transformation. Write L in the most general form

$$\gamma = C\beta + d\beta_{N+1}, \quad \gamma_{N+1} = \sum_{i=1}^N c_i\beta_i + c\beta_{N+1}$$

for some $c_1, \dots, c_N, c \in k, d \in k^N$, and $N \times N$ -matrix C with entries in k . Then the condition $L(S) \subset T$ is expressed as

$$(3.3) \quad \sum_{i=1}^N c_i\beta_i + c\mathcal{P}(\beta) \equiv \mathcal{Q}(C\beta + d\mathcal{P}(\beta)).$$

Since k is an infinite field, identity (3.3) implies that the coefficients at the same monomials on the left and on the right are equal. Then, since \mathcal{P} and \mathcal{Q} do not contain linear terms, it follows that $c_1 = \dots = c_N = 0$, and therefore, $C \in \mathrm{GL}(N, k)$, $c \in k^*$. Further, comparing the second- and third-order terms in (3.3), it is straightforward to see that the equations of both S and T cannot be in Blaschke normal form unless $d = 0$. \square

By Lemma 3.1, writing the hypersurface $\mathcal{S}_{\tilde{\pi}'}$ in some coordinates $\tilde{\alpha} = (\tilde{\alpha}_1, \dots, \tilde{\alpha}_n)$, $\tilde{\alpha}_{n+1}$ in $\tilde{\mathfrak{m}}$ chosen as above, we see that the map \mathcal{L} has the form

$$(3.4) \quad \tilde{\alpha} = C\alpha, \quad \tilde{\alpha}_{n+1} = c\alpha_{n+1}$$

for some $C \in \mathrm{GL}(n, k)$, $c \in k^*$. In coordinate-free formulation, (3.4) means that, with respect to the decompositions $\mathfrak{m} = \mathcal{K} \oplus \mathrm{Soc}(A)$ and $\tilde{\mathfrak{m}} = \tilde{\mathcal{K}} \oplus \mathrm{Soc}(\tilde{A})$, where $\tilde{\mathcal{K}} := \ker \tilde{\pi}' \cap \tilde{\mathfrak{m}}$, the map \mathcal{L} has the block-diagonal form, that is, there exist linear isomorphisms $L_1 : \mathcal{K} \rightarrow \tilde{\mathcal{K}}$ and $L_2 : \mathrm{Soc}(A) \rightarrow \mathrm{Soc}(\tilde{A})$ such that $\mathcal{L}(x+u) = L_1(x) + L_2(u)$, with $x \in \mathcal{K}$, $u \in \mathrm{Soc}(A)$. Therefore, for the corresponding polynomial maps P_π and $P_{\tilde{\pi}'}$ (see (2.1)) we have

$$(3.5) \quad L_2 \circ P_\pi = P_{\tilde{\pi}'} \circ L_1.$$

Clearly, identity (3.5) yields

$$(3.6) \quad L_2 \circ P_\pi^{[m]} = P_{\tilde{\pi}'}^{[m]} \circ L_1, \quad m = 2, \dots, \nu,$$

where $P_\pi^{[m]}$, $P_{\tilde{\pi}'}^{[m]}$ are the homogeneous components of degree m of P_π , $P_{\tilde{\pi}'}$, respectively, and ν is the socle degree of each of A and \tilde{A} (observe that the socle degrees of A and \tilde{A} are equal since, by (3.5), one has $\deg P_\pi = \deg P_{\tilde{\pi}'}$).

Let π_m be the symmetric $\text{Soc}(A)$ -valued m -form on \mathcal{K} defined as follows:

$$(3.7) \quad \pi_m(x_1, \dots, x_m) := \pi(x_1 \cdots x_m), \quad x_1, \dots, x_m \in \mathcal{K}, \quad m = 2, \dots, \nu.$$

By (2.1), we have

$$(3.8) \quad P_\pi^{[m]}(x) = \frac{1}{m!} \pi_m(x, \dots, x), \quad x \in \mathcal{K}, \quad m = 2, \dots, \nu.$$

We will focus on the forms π_2 and π_3 (in fact, it is shown in [8, Proposition 2.8] that every π_m with $m > 3$ is completely determined by π_2 and π_3). As in [8], we define a commutative product $(x, y) \mapsto x * y$ on \mathcal{K} by requiring the identity

$$(3.9) \quad \pi_2(x * y, z) = \pi_3(x, y, z)$$

to hold for all $x, y, z \in \mathcal{K}$. Due to the non-degeneracy of the form b_π defined in (2.2), the form π_2 is non-degenerate, and therefore, for any $x, y \in \mathcal{K}$, the element $x * y \in \mathcal{K}$ is uniquely determined by (3.9).

We need the following lemma.

Lemma 3.2. *For any two elements $x + u$ and $y + v$ of \mathfrak{m} , with $x, y \in \mathcal{K}$ and $u, v \in \text{Soc}(A)$, one has*

$$(3.10) \quad (x + u)(y + v) = x * y + \pi_2(x, y).$$

Proof. We write the product xy with respect to the decomposition $\mathfrak{m} = \mathcal{K} \oplus \text{Soc}(A)$ as $xy = (xy)_1 + (xy)_2$, where $(xy)_1 \in \mathcal{K}$ and $(xy)_2 \in \text{Soc}(A)$. It is then clear that $(xy)_2 = \pi_2(x, y)$. Therefore, to prove (3.10), we need to show that $x * y = (xy)_1$. This identity is obtained by a simple calculation similar to the one that occurs in the proof of Proposition 2.8 of [8] (cf., [9, Proposition 5.13]). Indeed, from

(3.7) and (3.9), for any $z \in \mathcal{K}$, one has

$$\begin{aligned}\pi_2(x * y, z) &= \pi_3(x, y, z) = \pi(xyz) \\ &= \pi\left([(xy)_1 + (xy)_2]z\right) = \pi((xy)_1 z) \\ &= \pi_2((xy)_1, z).\end{aligned}$$

Since π_2 is non-degenerate, the above identity implies $x * y = (xy)_1$ as required. \square

We shall now complete the proof of Theorem 2.1. Let $\tilde{\pi}_m$ be the symmetric $\text{Soc}(\tilde{A})$ -valued forms on $\tilde{\mathcal{K}}$ arising from the admissible projection $\tilde{\pi}'$ on $\tilde{\mathfrak{m}}$ as in (3.7), with $m = 2, \dots, \nu$. By (3.6) and (3.8), we have

$$(3.11) \quad \begin{aligned}L_2(\pi_m(x_1, \dots, x_m)) &= \tilde{\pi}_m(L_1(x_1), \dots, L_1(x_m)), \\ x_1, \dots, x_m &\in \mathcal{K}, \quad m = 2, \dots, \nu.\end{aligned}$$

Denote by $\tilde{*}$ the product on $\tilde{\mathcal{K}}$ defined by $\tilde{\pi}_2, \tilde{\pi}_3$ as in (3.9). Now, for all $x, y \in \mathcal{K}$ and $u, v \in \text{Soc}(A)$, Lemma 3.2 and identity (3.11) with $m = 2$ yield

$$(3.12) \quad \begin{aligned}\mathcal{L}\left((x+u)(y+v)\right) &= \mathcal{L}(x * y + \pi_2(x, y)) \\ &= L_1(x * y) + L_2(\pi_2(x, y)), \\ \mathcal{L}(x+u)\mathcal{L}(y+v) &= (L_1(x) + L_2(u))(L_1(y) + L_2(v)) \\ &\quad L_1(x)\tilde{*}L_1(y) + \tilde{\pi}_2(L_1(x), L_1(y)) \\ &= L_1(x)\tilde{*}L_1(y) + L_2(\pi_2(x, y)).\end{aligned}$$

Next, for any $z \in \mathcal{K}$, from (3.9) and identity (3.11) with $m = 2, 3$ one obtains

$$\begin{aligned}\tilde{\pi}_2(L_1(x)\tilde{*}L_1(y), L_1(z)) &= \tilde{\pi}_3(L_1(x), L_1(y), L_1(z)) \\ &= L_2(\pi_3(x, y, z)) = L_2(\pi_2(x * y, z)) \\ &= \tilde{\pi}_2(L_1(x * y), L_1(z)),\end{aligned}$$

which implies $L_1(x)\tilde{*}L_1(y) = L_1(x * y)$. It then follows from (3.12) that $\mathcal{L}((x+u)(y+v)) = \mathcal{L}(x+u)\mathcal{L}(y+v)$, that is, $\mathcal{L} : \mathfrak{m} \rightarrow \tilde{\mathfrak{m}}$ is an algebra isomorphism.

Finally, we will obtain the last statement of the theorem. Let $\mathcal{A} : \mathfrak{m} \rightarrow \tilde{\mathfrak{m}}$ be a linear isomorphism such that $\mathcal{A}(S_\pi) = S_{\tilde{\pi}}$. Consider the linear automorphisms \mathcal{F} of \mathfrak{m} and $\tilde{\mathcal{F}}$ of $\tilde{\mathfrak{m}}$ defined by

$$\begin{aligned}\mathcal{F}(x + u) &:= x - u, & x \in \mathcal{K}, u \in \text{Soc}(A), \\ \tilde{\mathcal{F}}(x + u) &:= x - u, & x \in \ker \tilde{\pi} \cap \tilde{\mathfrak{m}}, u \in \text{Soc}(\tilde{A}).\end{aligned}$$

Then the composition $\mathcal{A}_0 := \tilde{\mathcal{F}} \circ \mathcal{A} \circ \mathcal{F}$ is a linear transformation from \mathfrak{m} to $\tilde{\mathfrak{m}}$ that maps S_π onto $S_{\tilde{\pi}}$. By the above argument, it follows that \mathcal{A}_0 is an algebra isomorphism. On the other hand, one has $\mathcal{A}_0 = \mathcal{A}$. Thus, \mathcal{A} is an algebra isomorphism, and the proof of the theorem is complete. \square

4. Example of application of Theorem 2.1. Theorem 2.1 is particularly useful when at least one of the hypersurfaces $S_\pi, S_{\tilde{\pi}}$ is affinely homogeneous (recall that a subset \mathcal{S} of a vector space V is called *affinely homogeneous* if, for every pair of points $p, q \in \mathcal{S}$, there exists a bijective affine map \mathcal{A} of V such that $\mathcal{A}(\mathcal{S}) = \mathcal{S}$ and $\mathcal{A}(p) = q$). In this case, the hypersurfaces $S_\pi, S_{\tilde{\pi}}$ are affinely equivalent if and only if they are linearly equivalent. Indeed, if, for instance, S_π is affinely homogeneous and $\mathcal{A} : \mathfrak{m} \rightarrow \tilde{\mathfrak{m}}$ is an affine equivalence between $S_\pi, S_{\tilde{\pi}}$, then $\mathcal{A} \circ \mathcal{A}'$ is a linear equivalence between $S_\pi, S_{\tilde{\pi}}$, where \mathcal{A}' is an affine automorphism of S_π such that $\mathcal{A}'(0) = \mathcal{A}^{-1}(0)$. Clearly, in this case $S_{\tilde{\pi}}$ is affinely homogeneous as well.

The proof of Theorem 2.1 shows that every linear equivalence \mathcal{L} between $S_\pi, S_{\tilde{\pi}}$ has the block-diagonal form with respect to the decompositions $\mathfrak{m} = \mathcal{K} \oplus \text{Soc}(A)$ and $\tilde{\mathfrak{m}} = \tilde{\mathcal{K}} \oplus \text{Soc}(\tilde{A})$, where $\tilde{\mathcal{K}} := \ker \tilde{\pi} \cap \tilde{\mathfrak{m}}$, that is, there exist linear isomorphisms $L_1 : \mathcal{K} \rightarrow \tilde{\mathcal{K}}$ and $L_2 : \text{Soc}(A) \rightarrow \text{Soc}(\tilde{A})$ such that $\mathcal{L}(x + u) = L_1(x) + L_2(u)$, with $x \in \mathcal{K}, u \in \text{Soc}(A)$. Therefore, analogously to (3.6), for the corresponding polynomial maps P_π and $P_{\tilde{\pi}}$ (see (2.1)) we have

$$(4.1) \quad L_2 \circ P_\pi^{[m]} = P_{\tilde{\pi}}^{[m]} \circ L_1 \quad \text{for all } m \geq 2,$$

where, as before, $P_\pi^{[m]}, P_{\tilde{\pi}}^{[m]}$ are the homogeneous components of degree m of $P_\pi, P_{\tilde{\pi}}$, respectively.

Thus, Theorem 2.1 yields the following corollary (cf., [8, Theorem 2.11]).

Corollary 4.1. *Let A, \tilde{A} be Gorenstein algebras of finite vector space dimension greater than 1 and socle degree ν over an infinite field k with either $\text{char}(k) = 0$ or $\text{char}(k) > \nu$. Let, further, $\pi, \tilde{\pi}$ be admissible projections on A, \tilde{A} , respectively.*

- (i) *If A and \tilde{A} are isomorphic and at least one of $S_\pi, S_{\tilde{\pi}}$ is affinely homogeneous, then for some linear isomorphisms $L_1 : \mathcal{K} \rightarrow \tilde{\mathcal{K}}$ and $L_2 : \text{Soc}(A) \rightarrow \text{Soc}(\tilde{A})$ identity (4.1) holds. In this case, both S_π and $S_{\tilde{\pi}}$ are affinely homogeneous.*
- (ii) *If, for some linear isomorphisms $L_1 : \mathcal{K} \rightarrow \tilde{\mathcal{K}}$ and $L_2 : \text{Soc}(A) \rightarrow \text{Soc}(\tilde{A})$ identity (4.1) holds, then the hypersurfaces $S_\pi, S_{\tilde{\pi}}$ are linearly equivalent and therefore the algebras A and \tilde{A} are isomorphic.*

As shown in [9, subsection 8.2], the hypersurface S_π need not be affinely homogeneous in general. In [14] (see also [9]) we found a criterion for the affine homogeneity of some (hence every) hypersurface S_π arising from an Artinian Gorenstein algebra A . Namely, S_π is affinely homogeneous if and only if the action of the automorphism group of the nilpotent algebra \mathfrak{m} on the set of all hyperplanes in \mathfrak{m} complementary to $\text{Soc}(A)$ is transitive. Furthermore, we showed that this condition is satisfied if A is non-negatively graded in the sense that it can be represented as a direct sum

$$(4.2) \quad A = \bigoplus_{j \geq 0} A^j, \quad A^j A^\ell \subset A^{j+\ell},$$

where A^j are linear subspaces of A , with $A^0 = k$ (in this case $\mathfrak{m} = \bigoplus_{j > 0} A^j$ and $\text{Soc}(A) = A^d$ for $d := \max\{j : A^j \neq 0\}$). We stress that the grading $\{A^j\}$ in the above statement is *not* required to be standard, i.e., A^j may not coincide with $(A^1)^j$.

Note, however, that the existence of a non-negative grading on A is not a necessary condition for the affine homogeneity of S_π . For example, for any Artinian Gorenstein algebra of socle degree not exceeding 4 the hypersurfaces S_π are affinely homogeneous (see [9, Proposition 6.5]), whereas not every such algebra admits a non-negative grading. The case $\nu = 3$ is relatively easy; in fact, all algebras with this property were completely described in [6, Theorem 4.1]. The case $\nu = 4$ is much harder (see [9, subsection 7.2]), and the affine homogeneity of S_π makes

Corollary 4.1 an important tool in this case. We are confident that the approach discussed in this paper will help make significant advances on the classification problem at least for $\nu = 4$. Note that, as shown in [9, Proposition 7.5], the classification result of Theorem 4.1 of [6] can indeed be obtained by utilizing this method.

We will now give an example of how one can hope to apply our technique to algebras of socle degree 4.

Example 4.2. Let A_0 be the Artinian Gorenstein algebra introduced at the end of [9, subsection 8.1], namely,

$$A_0 := k[[x, y, z]]/J(x^4 + xy^2 + y^3 + xz^2),$$

where $k[[x, y, z]]$ is the algebra of formal power series in x, y, z and $J(f)$ is the Jacobian ideal of f , i.e., the ideal generated by the first-order partial derivatives of f . As explained in [9], this algebra does not admit *any* non-negative grading. Furthermore, the Hilbert function of A_0 is $\{1, 3, 3, 1, 1\}$, hence the associated graded algebra of A_0 is not Gorenstein (cf., [17, Proposition 9]). Also, one has $\nu = 4$ and $\dim_k A_0 = 9$.

Consider the following monomials in $k[[x, y, z]]$:

$$(4.3) \quad x^4, x, x^2, x^3, y, z, yz, z^2,$$

and let $e_{0,0}, \dots, e_{0,7}$ be the vectors in the maximal ideal \mathfrak{m}_0 of A_0 represented, respectively, by these monomials. It is not hard to show that $e_{0,0}, \dots, e_{0,7}$ are linearly independent; hence, they form a basis of \mathfrak{m}_0 . Choose π_0 to be the admissible projection on A_0 defined by the condition

$$\ker \pi_0 \cap \mathfrak{m}_0 = \langle e_{0,1}, \dots, e_{0,7} \rangle =: \mathcal{K}_0,$$

where $\langle \cdot \rangle$ denotes linear span (observe that $\text{Soc}(A_0) = \langle e_{0,0} \rangle$). Then, letting x_1, \dots, x_7 be the coordinates in \mathcal{K}_0 with respect to the basis $e_{0,1}, \dots, e_{0,7}$ and identifying $\text{Soc}(A_0)$ with k by means of $e_{0,0}$, we compute:¹

$$(4.4) \quad P_0 := P_{\pi_0} = x_1x_3 + \frac{1}{2}x_2^2 + 6x_2x_4 - \frac{8}{3}x_4x_7 - \frac{8}{3}x_5x_6 \\ + \frac{1}{2}x_1^2x_2 + 3x_1^2x_4 - 2x_1x_4^2 + \frac{4}{9}x_4^3 - \frac{4}{3}x_4x_5^2 + \frac{1}{24}x_1^4.$$

We will now perturb the algebra A_0 as follows:

$$A_t := k[[x, y, z]]/J(x^4 + tx^5 + xy^2 + y^3 + xz^2), \quad t \in k^*.$$

It is not hard to check that, for every t , the algebra A_t is Artinian Gorenstein of vector space dimension 9 and socle degree 4. By utilizing Corollary 4.1 (ii), we will now show that A_t is in fact isomorphic to A_0 for all t .

Let $e_{t,0}, \dots, e_{t,7}$ be the basis in the maximal ideal \mathfrak{m}_t of A_t whose elements are represented, respectively, by monomials (4.3). Let π_t be the admissible projection on A_t defined by

$$\ker \pi_t \cap \mathfrak{m}_t = \langle e_{t,1}, \dots, e_{t,7} \rangle =: \mathcal{K}_t$$

(observe that $\text{Soc}(A_t) = \langle e_{t,0} \rangle$). Then, denoting by y_1, \dots, y_7 the coordinates in \mathcal{K}_t with respect to the basis $e_{t,1}, \dots, e_{t,7}$ and identifying $\text{Soc}(A_t)$ with k by means of $e_{t,0}$, we have

$$(4.5) \quad \begin{aligned} P_t := P_{\pi_t} &= y_1 y_3 + \frac{1}{2} y_2^2 + 6y_2 y_4 - \frac{8}{3} y_4 y_7 - \frac{8}{3} y_5 y_6 \\ &+ \frac{15t}{2} y_1 y_4 - \frac{5t}{2} y_4^2 + \frac{1}{2} y_1^2 y_2 + 3y_1^2 y_4 - 2y_1 y_4^2 \\ &+ \frac{4}{9} y_4^3 - \frac{4}{3} y_4 y_5^2 + \frac{1}{24} y_1^4. \end{aligned}$$

Thus, we see that in the coordinates chosen as above, the polynomials P_0 and P_t coincide in homogeneous components of degrees 3 and 4 but their quadratic terms differ.

We now identify $\text{Soc}(A_0)$ and $\text{Soc}(A_t)$ by means of the vectors $e_{0,0}$ and $e_{t,0}$. Then, by Corollary 4.1 (ii), to prove that A_t is isomorphic to A_0 , it suffices to find a linear isomorphism $L : \mathcal{K}_t \rightarrow \mathcal{K}_0$ such that

$$(4.6) \quad P_t^{[m]} = P_0^{[m]} \circ L \quad \text{for } m = 2, 3, 4,$$

where, as before, $P_0^{[m]}$ and $P_t^{[m]}$ are the homogeneous components of degree m of P_0 , P_t , respectively. Define L by

$$\begin{aligned} x_j &= y_j, \quad \text{for } j \neq 3, 7, \\ x_3 &= y_3 + \frac{15t}{2} y_4, \\ x_7 &= \frac{15t}{16} y_4 + y_7. \end{aligned}$$

Clearly, this linear transformation satisfies (4.6), which shows that A_t is indeed isomorphic to A_0 for every t as claimed.

By the last statement of Theorem 2.1, the map L together with the identification of $\text{Soc}(A_0)$ and $\text{Soc}(A_t)$ is in fact an algebra isomorphism between \mathfrak{m}_t and \mathfrak{m}_0 . More precisely, the map defined on the basis elements as

$$\begin{aligned} e_{t,j} &\longmapsto e_{0,j}, & \text{for } j \neq 4, \\ e_{t,4} &\longmapsto \frac{15t}{2}e_{0,3} + e_{0,4} + \frac{15t}{16}e_{0,7} \end{aligned}$$

is an isomorphism from \mathfrak{m}_t onto \mathfrak{m}_0 . The corresponding isomorphism between A_t and A_0 is induced by the automorphism of $k[[x, y, z]]$ given by the following change of variables:

$$(4.7) \quad x \longmapsto x, \quad y \longmapsto y + \frac{15t}{16}z^2 + \frac{15t}{2}x^3, \quad z \longmapsto z.$$

It would be interesting to see whether formula (4.7) could be obtained directly using ideal generators.

One can produce an alternative proof of isomorphism of A_t and A_0 by making use of Macaulay inverse systems. We will explore this possibility in the next section and compare it with the proof given above.

5. Nil-polynomials and Macaulay inverse systems. With the exception of a further discussion of Example 4.2 given below, the material of this section is contained in [1, 5]. Since this material is highly relevant to the present paper's theme and the proofs involved are not long, we reproduce it here for the reader's benefit.

As before, let A be an Artinian Gorenstein algebra over a field k , with maximal ideal \mathfrak{m} and socle degree ν , where we assume that $\dim_k A > 1$ and either $\text{char}(k) = 0$ or $\text{char}(k) > \nu$. Next, let

$$M := \text{emb dim } A := \dim_k \mathfrak{m}/\mathfrak{m}^2$$

be the embedding dimension of A (notice that $M \geq 1$). Choose a basis $\mathcal{B} = \{e_1, \dots, e_M\}$ in a complement to \mathfrak{m}^2 in \mathfrak{m} and fix a linear form $\omega : A \rightarrow k$ with kernel complementary to $\text{Soc}(A)$. Now, we introduce

the following polynomial:

$$(5.1) \quad Q_{\omega, \mathcal{B}}(x_1, \dots, x_M) := \sum_{j=0}^{\nu} \frac{1}{j!} \omega\left((x_1 e_1 + \dots + x_M e_M)^j\right).$$

Notice that in (5.1) the element $(x_1 e_1 + \dots + x_M e_M)^j \in A$ may have a non-trivial projection to $\text{Soc}(A)$ parallel to $\ker \omega$ even for $j < \nu$, in which case $\omega(x_1 e_1 + \dots + x_M e_M)^j \neq 0$. In formulas (5.9) and (5.10) below, we compute polynomials of this kind for the algebras A_0 and A_t from Example 4.2.

Further, the elements e_1, \dots, e_M generate A as an algebra; hence, A is isomorphic to $k[x_1, \dots, x_M]/I$, where I is the ideal of all relations among e_1, \dots, e_M , i.e., polynomials $f \in k[x_1, \dots, x_M]$ with $f(e_1, \dots, e_M) = 0$. Observe that I contains the monomials $x_1^{\nu+1}, \dots, x_M^{\nu+1}$.

From now on we assume that $\text{char}(k) = 0$ (cf., Remark 5.2 below). For $f, g \in k[x_1, \dots, x_M]$, define

$$f \star g := f\left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_M}\right)(g).$$

It is well known that, since the quotient $k[x_1, \dots, x_M]/I$ is Gorenstein, there is a polynomial $g \in k[x_1, \dots, x_M]$ of degree ν such that $I = \text{Ann}(g)$, where

$$\text{Ann}(g) := \{f \in k[x_1, \dots, x_M] : f \star g = 0\}$$

is the *annihilator* of g . The freedom in choosing g with $\text{Ann}(g) = I$ is fully understood, namely, if $g_1, g_2 \in k[x_1, \dots, x_M]$ satisfy $\text{Ann}(g_1) = \text{Ann}(g_2) = I$, then $g_1 = h \star g_2$, where $h \in k[x_1, \dots, x_M]$ with $h(0) \neq 0$. Any polynomial g with $I = \text{Ann}(g)$ is called a *Macaulay inverse system* for the Artinian Gorenstein quotient $k[x_1, \dots, x_M]/I$.

Conversely, for any non-zero element $g \in k[x_1, \dots, x_M]$ the quotient $k[x_1, \dots, x_M]/\text{Ann}(g)$ is a (local) Artinian Gorenstein algebra of socle degree $\deg g$; hence, any polynomial is an inverse system of some Artinian Gorenstein quotient. It is well known that inverse systems can be used for solving the isomorphism problem for quotients of this kind as explained, for example, in [6, Proposition 2.2] (a precise statement is given at the end of this section). For details on inverse systems we refer the reader to [7, 12, 16] (a brief survey given in [6] is also helpful).

In applications, it is desirable to have an explicit formula for computing an inverse system for any Artinian Gorenstein quotient. As the following theorem shows, formula (5.1) achieves this purpose.

Theorem 5.1. [1, 5]. *Let A be a Gorenstein algebra of finite vector space dimension greater than 1 over a field of characteristic zero, with maximal ideal \mathfrak{m} , socle degree ν and embedding dimension M . Choose a basis $\mathcal{B} = \{e_1, \dots, e_M\}$ in a complement to \mathfrak{m}^2 in \mathfrak{m} , fix a linear form $\omega : A \rightarrow k$ with kernel complementary to $\text{Soc}(A)$ and consider the polynomial $Q_{\omega, \mathcal{B}}$ as defined in (5.1). Further, using the basis \mathcal{B} write the algebra A as a quotient $k[x_1, \dots, x_M]/I$. Then $Q_{\omega, \mathcal{B}}$ is an inverse system for $k[x_1, \dots, x_M]/I$.*

Proof. Fix any polynomial $f \in k[x_1, \dots, x_M]$

$$f = \sum_{0 \leq i_1, \dots, i_M \leq N} a_{i_1, \dots, i_M} x_1^{i_1} \dots x_M^{i_M}$$

and calculate

$$\begin{aligned} f \star Q_{\omega, \mathcal{B}} &= f \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_M} \right) (Q_{\omega, \mathcal{B}}) \\ &= \sum_{0 \leq i_1, \dots, i_M \leq N} a_{i_1, \dots, i_M} \sum_{j=i_1+\dots+i_M}^{\nu} \frac{1}{(j - (i_1 + \dots + i_M))!} \\ (5.2) \quad &\times \omega \left((x_1 e_1 + \dots + x_M e_M)^{j - (i_1 + \dots + i_M)} e_1^{i_1} \dots e_M^{i_M} \right) \\ &= \sum_{m=0}^{\nu} \frac{1}{m!} \omega \left((x_1 e_1 + \dots + x_M e_M)^m \right. \\ &\quad \times \left. \sum_{\substack{0 \leq i_1, \dots, i_M \leq N, \\ i_1 + \dots + i_M \leq \nu - m}} a_{i_1, \dots, i_M} e_1^{i_1} \dots e_M^{i_M} \right) \\ &= \sum_{m=0}^{\nu} \frac{1}{m!} \omega \left((x_1 e_1 + \dots + x_M e_M)^m f(e_1, \dots, e_M) \right). \end{aligned}$$

Since I is the ideal of all relations among e_1, \dots, e_M , formula (5.2) implies $I \subset \text{Ann}(Q_{\omega, \mathcal{B}})$.

Conversely, let $f \in k[x_1, \dots, x_M]$ be an element of $\text{Ann}(Q_{\omega, \mathcal{B}})$. Then

(5.2) yields

$$(5.3) \quad \sum_{m=0}^{\nu} \frac{1}{m!} \omega \left((x_1 e_1 + \cdots + x_M e_M)^m f(e_1, \dots, e_M) \right) = 0.$$

Collecting the terms containing $x_1^{i_1} \cdots x_M^{i_M}$ in (5.3) we obtain

$$(5.4) \quad \omega \left(e_1^{i_1} \cdots e_M^{i_M} f(e_1, \dots, e_M) \right) = 0$$

for all indices i_1, \dots, i_M . Since e_1, \dots, e_M generate A , identities (5.4) yield

$$(5.5) \quad \omega \left(A f(e_1, \dots, e_M) \right) = 0.$$

Further, since the bilinear form $(a, b) \mapsto \omega(ab)$ is non-degenerate on A , identity (5.5) implies $f(e_1, \dots, e_M) = 0$. Therefore, $f \in I$, which shows that $I = \text{Ann}(Q_{\omega, \mathcal{B}})$ as required. \square

We will now make a number of useful remarks.

Remark 5.2. For simplicity, we have chosen to discuss inverse systems only under the assumption $\text{char}(k) = 0$. For fields of positive characteristic one needs to pass to divided power rings (see, e.g., [12, Lemma 1.2] and [13, Appendix A]). If k is an arbitrary field and $\mathcal{D} \subset \text{Hom}_k(k[x_1, \dots, x_M], k)$ is the corresponding divided power ring, then an inverse system for a Gorenstein quotient $k[x_1, \dots, x_M]/I$ is defined to be an element $\lambda \in \mathcal{D}$ satisfying $\text{Ann}(\lambda) = I$, where

$$\text{Ann}(\lambda) := \{f \in k[x_1, \dots, x_M] : f \diamond \lambda = 0\},$$

with

$$(h \diamond \lambda)(g) := \lambda(hg), \quad h, g \in k[x_1, \dots, x_M].$$

In particular, it is easy to see that the lift to $k[x_1, \dots, x_M]$ of any form $\omega : k[x_1, \dots, x_M]/I \rightarrow k$ with kernel complementary to the socle is an inverse system for $k[x_1, \dots, x_M]/I$ in the sense of this definition. As J. Jelisiejew has pointed out to us, this last fact yields an alternative proof of Theorem 5.1. Namely, if $\text{char}(k) = 0$, we have:

- (i) \mathcal{D} and $k[x_1, \dots, x_M]$ are naturally isomorphic as $k[x_1, \dots, x_M]$ -modules;

- (ii) under this isomorphism, the definition of an inverse system as an element of \mathcal{D} agrees with that given prior to the statement of Theorem 5.1; and
- (iii) under this isomorphism, the lift of ω is mapped to the polynomial $Q_{\omega, \mathcal{B}}$.

Furthermore, if $\text{char}(k) > \nu$, one can also think of $Q_{\omega, \mathcal{B}}$ as an element of \mathcal{D} , and Theorem 5.1 remains valid. Finally, if $\text{char}(k)$ is arbitrary, the lift of ω to $k[x_1, \dots, x_M]$ is computed as follows

$$\sum_{m=0}^{\nu} \sum_{i_1 + \dots + i_M = m} \omega(e_1^{i_1} \dots e_M^{i_M}) X^{[i_1, \dots, i_M]},$$

which, for $\text{char}(k) = 0$ and $\text{char}(k) > \nu$, agrees with $Q_{\omega, \mathcal{B}}$.

Remark 5.3. Fix a hyperplane Π in \mathfrak{m} complementary to $\text{Soc}(A)$. A k -valued polynomial P on Π is called a *nil-polynomial for A* if there exists a linear form $\rho : A \rightarrow k$ such that $\ker \rho = \langle \Pi, \mathbf{1} \rangle$ and $P = \rho \circ \exp|_{\Pi}$. Note that $\deg P = \nu$. Upon identification of $\text{Soc}(A)$ with k , the class of nil-polynomials coincides with that of $\text{Soc}(A)$ -valued polynomial maps P_{π} introduced in (2.1). If $\dim_k A > 2$, then $\nu \geq 2$ and Π contains an M -dimensional subspace that forms a complement to \mathfrak{m}^2 in \mathfrak{m} . Fix any such subspace V , choose a basis $\mathcal{B} = \{e_1, \dots, e_M\}$ in V , and let x_1, \dots, x_M be the coordinates in V with respect to this basis. Then the polynomial $Q_{\rho, \mathcal{B}}$ given by formula (5.1) is exactly the restriction of the nil-polynomial P to V written in the coordinates x_1, \dots, x_M . Thus, one way to explicitly obtain an inverse system for an Artinian Gorenstein quotient is to restrict a socle-valued map P_{π} to a complement to \mathfrak{m}^2 in \mathfrak{m} lying in $\ker \pi \cap \mathfrak{m}$ and identify the socle with the field k . This observation provides a link between the classical approach to Artinian Gorenstein algebras by means of inverse systems and our criterion in Theorem 2.1.

Remark 5.4. Suppose that A is a *standard graded algebra*, i.e., A can be represented in the form (4.2) with $A^j = (A^1)^j$ for $j \geq 1$. Set

$$\Pi := \bigoplus_{j=1}^{\nu-1} A^j, \quad V := A^1.$$

In this case, for any choice of a basis $\mathcal{B} = \{e_1, \dots, e_M\}$ in V , the ideal I is homogeneous, i.e., generated by homogeneous relations. For an arbitrary nil-polynomial P on Π its restriction $Q_{\rho, \mathcal{B}}$ to V coincides with the homogeneous component of degree ν of P :

$$Q_{\rho, \mathcal{B}}(x_1, \dots, x_M) = \frac{1}{\nu!} \omega \left((x_1 e_1 + \dots + x_M e_M)^\nu \right).$$

Thus, Theorem 5.1 yields a simple proof of the well-known fact that a standard graded Artinian Gorenstein algebra, when written as a quotient by a homogeneous ideal, admits a homogeneous inverse system and all homogeneous inverse systems for such algebras are mutually proportional (see [7] and [16, pages 79–80]).

Remark 5.5. Theorem 5.1 easily generalizes to the case of Artinian Gorenstein quotients $k[x_1, \dots, x_m]/I$, where I lies in the ideal generated by x_1, \dots, x_m and m is not necessarily equal to the embedding dimension M of the quotient. Indeed, let e_1, \dots, e_m be the elements of $k[x_1, \dots, x_m]/I$ represented by x_1, \dots, x_m , respectively, and consider the element of $k[x_1, \dots, x_m]$ defined as follows:

$$(5.6) \quad R(x_1, \dots, x_m) := \sum_{j=0}^{\nu} \frac{1}{j!} \omega \left((x_1 e_1 + \dots + x_m e_m)^j \right),$$

where ω is a linear form on $k[x_1, \dots, x_m]/I$ with kernel complementary to the socle and ν is the socle degree of $k[x_1, \dots, x_m]/I$. Then, arguing as in the proof of Theorem 5.1, we see that R is an inverse system for $k[x_1, \dots, x_m]/I$. Thus, (5.6) is an explicit formula providing an inverse system for any Artinian Gorenstein quotient, and any other inverse system is obtained as $h \star R$, where $h \in k[x_1, \dots, x_m]$ does not vanish at the origin. Notice that, for $m > M$, no inverse system as in (5.6) comes from restricting a nil-polynomial to a subspace of \mathfrak{m} complementary to \mathfrak{m}^2 .

Thus, in order to decide whether two Artinian Gorenstein algebras are isomorphic, one can use either the classical approach, which utilizes inverse systems, or our method, which relies on nil-polynomials, and the two techniques are related as explained in Theorem 5.1 and Remark 5.3. In a particular situation, one of the approaches may work better than the other. For instance, as we saw in the preceding section, the

technique based on nil-polynomials is very appropriate for establishing that the algebras A_t in Example 4.2 are all isomorphic to A_0 . We will now obtain a different proof of this statement by the method based on inverse systems.

We first describe this method in general following the discussion that precedes [6, Proposition 2.2]. For $j = 1, 2$, let $B_j := k[x_1, \dots, x_m]/I_j$ be an Artinian Gorenstein quotient with socle degree $\nu \geq 1$ and inverse system g_j . Denote by $k_\nu[x_1, \dots, x_m]$ the vector space of polynomials in $k[x_1, \dots, x_m]$ of degree not exceeding ν . If $T_1, \dots, T_m \in k_\nu[x_1, \dots, x_m]$ vanish at the origin and have linearly independent linear parts, they induce a linear automorphism Φ_{T_1, \dots, T_m} of $k_\nu[x_1, \dots, x_m]$ as follows:

$$\begin{aligned} \Phi_{T_1, \dots, T_m} : f(x) &\mapsto f(T_1(x), \dots, T_m(x)) \\ &\pmod{\text{terms of degree } > \nu}, \end{aligned}$$

where $f \in k_\nu[x_1, \dots, x_m]$ and $x := (x_1, \dots, x_m)$. We now introduce a symmetric k -valued bilinear form on $k_\nu[x_1, \dots, x_m]$ as

$$[f, \tilde{f}] := (f \star \tilde{f})(0), \quad f, \tilde{f} \in k_\nu[x_1, \dots, x_m].$$

This form is clearly non-degenerate, and one can consider the linear map adjoint to Φ_{T_1, \dots, T_m} , i.e., the automorphism Φ_{T_1, \dots, T_m}^* of $k_\nu[x_1, \dots, x_m]$ defined by requiring that the identity

$$[f, \Phi_{T_1, \dots, T_m}^*(\tilde{f})] = [\Phi_{T_1, \dots, T_m}(f), \tilde{f}]$$

hold for all $f, \tilde{f} \in k_\nu[x_1, \dots, x_m]$.

Then, as explained in detail in [6], the algebras B_1 and B_2 are isomorphic if and only if there exist T_1, \dots, T_m as above and $h \in k[x_1, \dots, x_m]$ with $h(0) \neq 0$ such that

$$(5.7) \quad \Phi_{T_1, \dots, T_m}^*(g_1) = h \star g_2.$$

Note that the right-hand side of formula (5.7) is simply a replacement of the inverse system g_2 by another inverse system for the algebra B_2 . Clearly, (5.7) is equivalent to the identity

$$(5.8) \quad \left(\Phi_{T_1, \dots, T_m}(f) \star g_1 \right)(0) = \left(f \star (h \star g_2) \right)(0)$$

being satisfied for all $f \in k_\nu[x_1, \dots, x_m]$.

We now return to Example 4.2 and consider the algebras A_0 , A_t of socle degree $\nu = 4$ introduced there, with $t \in k^*$. Let $V_0 := \langle e_{0,1}, e_{0,4}, e_{0,5} \rangle$. This subspace forms a complement to \mathfrak{m}_0^2 in \mathfrak{m}_0 . Then, by Remark 5.3, setting $x_2 = x_3 = x_6 = x_7 = 0$ and replacing, respectively, x_1 , x_4 and x_5 by z_1 , z_2 and z_3 in formula (4.4), we obtain the inverse system

$$(5.9) \quad Q_0 := 3z_1^2z_2 - 2z_1z_2^2 + \frac{4}{9}z_2^3 - \frac{4}{3}z_2z_3^2 + \frac{1}{24}z_1^4$$

for the algebra A_0 represented as the quotient $k[z_1, z_2, z_3]/I_0$, with I_0 being the ideal of all relations among $e_{0,1}$, $e_{0,4}$ and $e_{0,5}$.

Analogously, let $V_t := \langle e_{t,1}, e_{t,4}, e_{t,5} \rangle$. This subspace is a complement to \mathfrak{m}_t^2 in \mathfrak{m}_t . Setting $y_2 = y_3 = y_6 = y_7 = 0$ and replacing, respectively, y_1 , y_4 and y_5 by z_1 , z_2 and z_3 in formula (4.5), one obtains the inverse system

$$(5.10) \quad Q_t := \frac{15t}{2}z_1z_2 - \frac{5t}{2}z_2^2 + 3z_1^2z_2 - 2z_1z_2^2 \\ + \frac{4}{9}z_2^3 - \frac{4}{3}z_2z_3^2 + \frac{1}{24}z_1^4$$

for the algebra A_t represented as the quotient $k[z_1, z_2, z_3]/I_t$, where I_t is the ideal of all relations among $e_{t,1}$, $e_{t,4}$ and $e_{t,5}$.

In accordance with (5.8), to show that A_t is isomorphic to A_0 , we need to find polynomials $T_1, T_2, T_3 \in k_4[z_1, z_2, z_3]$ vanishing at the origin and having linearly independent linear parts, as well as a polynomial $h \in k[z_1, z_2, z_3]$ with $h(0) \neq 0$, such that, for all $f \in k_4[z_1, z_2, z_3]$, one has

$$(5.11) \quad \left(\Phi_{T_1, T_2, T_3}(f) \star Q_t \right)(0) = \left(f \star (h \star Q_0) \right)(0).$$

After much computational experimentation, we discovered that (5.11) is satisfied for the following choice of T_j and h :

$$T_1 = z_1, \quad T_2 = z_2 - \frac{15t}{16}z_3^2 - \frac{15t}{2}z_1^3, \\ T_3 = z_3, \quad h \equiv 1.$$

Observe that, upon identification of x , y and z with z_1 , z_2 and z_3 , respectively, the change of variables $z_j \mapsto T_j$ is the inverse of the change of variables shown in (4.7), which agrees with formulas (5) and (6) in

[6]. Thus, we have obtained a second proof of the fact that A_t is indeed isomorphic to A_0 for all t .

To summarize, in the case of the algebras A_t from Example 4.2, once the relevant nil-polynomials have been found, the method for establishing isomorphism between Artinian Gorenstein algebras based on nil-polynomials as presented in Section 4 requires a substantially smaller computational effort than that based on inverse systems. Notice that nil-polynomials were utilized in this second proof as a tool for explicitly producing inverse systems.

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ENDNOTES

1. From this point on, the relevant polynomials P_π were found by using a **Singular**-based computer program, which had been kindly made available to us by W. Kaup.

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