

ALGEBRAICALLY TRIVIAL DECOMPOSITIONS OF HOMOTOPY 3-SPHERES¹

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Every compact 3-manifold M^3 without boundary possesses a cell-decomposition Ψ that contains just one vertex, say O , (see for instance [3, Sec. 5]). From Ψ we may read by a well-known procedure (see [7, §62]) a “corresponding” presentation

$$\mathfrak{P}(\Psi) = (\{g_1, \dots, g_a\}, \{r_1, \dots, r_b\})$$

of the fundamental group $\pi_1(M^3)$ where the generators g_1, \dots, g_a are in 1-1 correspondence with the (oriented) 1-dimensional elements E_1^1, \dots, E_a^1 of Ψ and the relators r_1, \dots, r_b are in 1-1 correspondence with the 2-dimensional elements E_1^2, \dots, E_b^2 of Ψ , i.e., r_j is a word in the $g_i^{\pm 1}$'s obtained by running once around the boundary of E_j^2 . In this way the relators r_j are uniquely defined up to cyclic permutations and inversions, i.e., if we denote by $\langle r_j \rangle$ the set of all cyclic permutations of r_j and of r_j^{-1} then the $\langle r_j \rangle$'s are uniquely defined.

In the special case that M^3 is a homotopy 3-sphere, $\mathfrak{P}(\Psi)$ is a presentation of the trivial group. However, it is—in general—an unsolved problem to recognize whether or not a given presentation $\mathfrak{P}(\Psi)$ presents the trivial group; this problem seems to be extremely difficult and it may be unsolvable, since the triviality problem of group theory is unsolvable (see [1], [6]). One might expect that these group theoretic difficulties are also the reason for the difficulties of the Poincaré problem. But the result of this paper shows that this is not so: We shall prove that every homotopy 3-sphere M^3 possesses a cell-decomposition Ψ such that the corresponding presentation

$$\mathfrak{P}(\Psi) = (\{g_1, \dots, g_a\}, \{r_1, \dots, r_b\})$$

is *obviously trivial*, i.e., such that $\mathfrak{P}(\Psi)$ can be transformed by simple cancellation operations (without changing the generators g_i and the number b of relators) into the “standard trivial presentation”

$$\mathfrak{D} = (\{g_1, \dots, g_a\}, \{g_1, \dots, g_a, *^{b-a}\})$$

where $*^{b-a}$ means that \mathfrak{D} contains $b - a$ times the empty relator (i.e., the relations of \mathfrak{D} are $g_1 = 1, \dots, g_a = 1$, and $b - a$ times the trivial relation $1 = 1$). To make this precise we say that a presentation \mathfrak{P} is obtained from

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² Here the equality sign means that both sides of the equation represent the same group element; but in general, if not stated otherwise, we call two words equal if and only if they read, letter by letter, in the same way.

a presentation $\mathfrak{P}' = (\{g_1, \dots, g_a\}, \{r'_1, \dots, r'_b\})$ by a *cancellation operation* of Type 1 or 2, respectively, if the following holds:

Type 1. (Cancelling a syllable $g_i^{-1} g_i$.) For some i, j ($i = 1, \dots, a$; $j = 1, \dots, b$) there is a word r'' such that $g_i^{-1} g_i r'' \in \langle r'_j \rangle$ and \mathfrak{P}'' is obtained by replacing r'_j by r'' . (Note that this operation does not in general allow cancelling a syllable $g_i g_i^{-1}$.)

Type 2. (Cancelling a syllable which is itself a relator.) For some j, k ($j, k = 1, \dots, b$; $j \neq k$) there are words r'_k, r'' such that $r'_k \in \langle r'_k \rangle, r'_k r'' \in \langle r'_j \rangle$, and \mathfrak{P}'' is obtained by replacing r'_j by r'' ; the length l of r'_k is called the *length* of the cancellation operation.

We shall prove the following

THEOREM. *If M^3 is a homotopy 3-sphere then there exists a cell-decomposition Ψ of M^3 , containing just one vertex O , such that a corresponding presentation*

$$\mathfrak{P}(\Psi) = (\{g_1, \dots, g_a\}, \{r_1, \dots, r_b\})$$

of the fundamental group $\pi_1(M^3)$ with generators g and relators r can be transformed into the standard trivial presentation

$$\mathfrak{Q} = (\{g_1, \dots, g_a, g_1, \dots, g_a, *^{b-a}\})$$

by means of a finite sequence of cancellation operations of Type 1 and a subsequent finite sequence of cancellation operations of Type 2 with lengths not exceeding 3.

One might call a cell-decomposition Ψ with the above properties “*algebraically trivial*”. I hope that the above theorem will be useful for deriving a proof of the Poincaré conjecture. However, this remains a difficult problem. A reason for the difficulty is the lack of correspondence between Tietze transformations of the group presentation $\mathfrak{P}(\Psi)$ and transformations of the cell-decomposition Ψ . If a presentation \mathfrak{Q} is derived from $\mathfrak{P}(\Psi)$ by a Tietze transformation then we may ask the question: does there exist a cell-decomposition Ω of M^3 such that \mathfrak{Q} corresponds to Ω ? Let us call the Tietze transformation *good* if the answer to the question is “yes”, and *bad* if the answer is “no”. Unfortunately, most Tietze transformations are bad from this point of view. The only large class of good and simple Tietze transformations I know are the *eliminations*: If $\mathfrak{P}(\Psi) = (\{g_1, \dots, g_a\}, \{r_1, \dots, r_b\})$ contains a relator, say r_l , such that for some k $g_k w^{-1} \in \langle r_l \rangle$ where w is a word in the g_i 's not containing $g_k^{\pm 1}$, and if \mathfrak{Q} is obtained from $\mathfrak{P}(\Psi)$ by deleting g_k and r_l and replacing in all relators r_j ($j \neq l$) the letter $g_k^{\pm 1}$ by the word $w^{\pm 1}$, then the Tietze transformation $\mathfrak{P}(\Psi) \rightarrow \mathfrak{Q}$ is good. Moreover, I would like to remark without proof: If it were possible to restrict the lengths of the cancellation operations in our theorem to 2 instead of 3 then the sequence of cancellation operations could be changed into a sequence of good Tietze transformations. This would mean a proof of the Poincaré conjecture since it is easy

to show that M^3 is a 3-sphere if it possesses a cell-decomposition Ω such that the standard trivial presentation \mathfrak{D} corresponds to Ω .

Proof of the theorem

1. Preliminaries. Let M^3 be a *homotopy 3-sphere*, i.e., a compact, simply connected 3-manifold without boundary.

We choose the semilinear standpoint as described in [4, Sec. 3]; i.e., we assume that all point sets, denoted by *capital roman letters*, are *piecewise rectilinear polyhedral point sets* in a euclidean space \mathbb{E}^n of sufficiently large dimension n , etc. We denote the *closure*, *boundary*, and *interior* of a point set X by \bar{X} , $\cdot X$, $^\circ X$, respectively.

2. The idea of the proof. First we consider (as in [3], [5]) a cell-decomposition Γ of M^3 into one vertex E^0 , r open arcs E_i^1 , r open disks E_i^2 , and one open 3-cell, and a singular fan V^2 corresponding to Γ (i.e., a wedge of r singular disks V_i^2 with $\cdot V_i^2 = \bar{E}_i^1$ where the V_i^2 's may intersect themselves and each other in double arcs; for details see [3, Sec. 5, 6]). Let T^3 be a small neighborhood of $\cdot V^2$ in M^3 . Now we consider the "middle parts," A_{*j}^1 , of the double arcs A_j^1 ($j = 1, \dots, s$) of V^2 that lie outside of $\cdot T^3$ (see Fig. 1) and the "middle part" V_*^2 of V^2 obtained from V^2 by removing its boundary $\cdot V^2$ and the open annuli that lie in the $V_i^2 \cap T^3$'s between $\cdot V_i^2$ and $V_i^2 \cap \cdot T^3$. Since T^3 is a Heegaard-handlebody in M^3 we can "project" the A_{*j}^1 's into $\cdot T^3$ (in the same way we projected the arcs B in [5, Sec. 3]) so that we obtain a projection cylinder K_j^2 for each arc A_{*j}^1 . Now we "thicken" V_*^2 and we obtain by this a 3-dimensional polyhedron V_*^3 where $V_*^3 + T^3$ is obviously a handlebody with s handles corresponding to the A_{*j}^1 's. Moreover, one can show that $V_*^3 + T^3$ is a Heegaard-handlebody in M^3 , and that those parts, say K_{*h}^2 ($h = 1, \dots, b$), of the projection cylinders K_j^2 that lie outside of $^\circ(V_*^3 + T^3)$ contain a complete system of meridian disks of $M^3 - ^\circ(V_*^3 + T^3)$.

Now one may expect to obtain an especially simple Heegaard-diagram of M^3 (and a corresponding cell-decomposition Ψ ; compare [5, Sec. 8]) from the handlebody $V_*^3 + T^3$ and the outer meridian disks K_{*h}^2 . It remains to select inner meridian disks X_j^2 ($j = 1, \dots, s$) of $V_*^3 + T^3$ in a suitable way. This can be done as indicated in Fig. 1: The polyhedron X_j in Fig. 1 consists of two disks in T^3 , parallel to the disk $V_{x^*j}^2 \subset V_*^2 \cap T^3$, and one arc outside of $^\circ T^3$ joining these disks in V_*^3 (encircling A_{*j}^1 and the disk $V_{x^*j}^2 \subset V_*^3 + T^3$). If V_*^3 is thickened to V_*^3 then the joining arc of X_j may be thickened to a disk which (together with the two disks in T^3) yields a meridian disk X_j^2 of $V_*^3 + T^3$.

First let us discuss the pleasant case that the arcs A_{*j}^1 are unknotted and unlinked over $\cdot T^3$, i.e., that there can be found projection cylinders K_j^2 which are nonsingular and pairwise disjoint. In this case we obtain a Heegaard-diagram³ which is so simple that it is fairly easy to show that M^3 is a 3-sphere:

³ Here we admit the case that the number of "outer" meridian circles $\cdot K_{*h}^2$ is greater than the genus s of the Heegaard-surface $\cdot(V_*^3 + T^3)$.

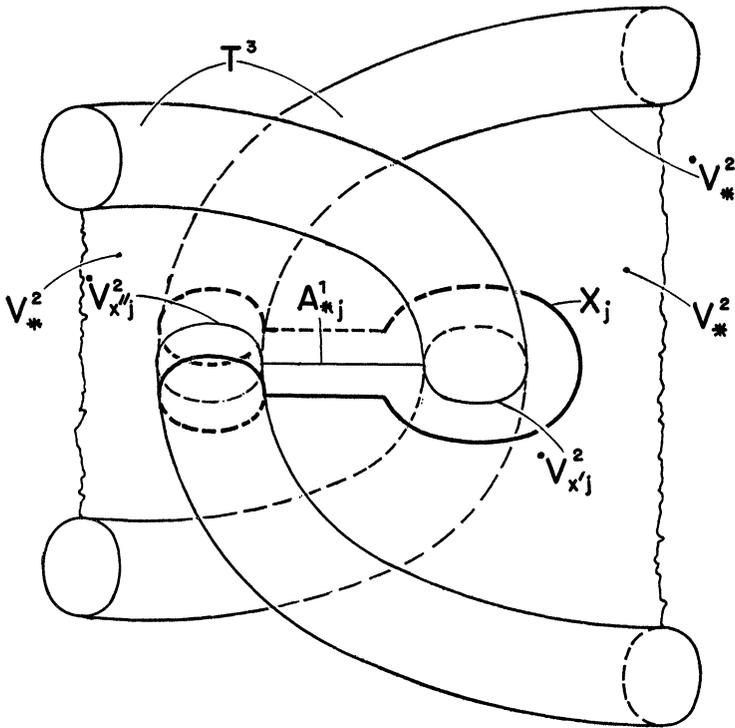


FIG. 1

The “projection arc” $\cdot K_j^2 \cap \cdot T^3$ of A_{*j}^1 (see Fig. 2) intersects the meridian circle $\cdot X_j^2$ in a point near the point $\cdot A_{*j}^1 \cap \cdot V_{x'k}^2$; it may have further intersections with the circles $\cdot V_{x'k}^2, \cdot V_{x''k}^2$ ($k = 1, \dots, s$) and with $\cdot V_*^2$ where the intersections with the $\cdot V_{x'k}^2$'s and $\cdot V_{x''k}^2$'s lie close to intersections of K_j^2 with the X_k^2 's. (In Fig. 2 it is assumed that the projection arc, from left to right, intersects the circles $\cdot V_{x''p}^2, \cdot V_{x'f}^2, \cdot V_{x'l}^2, \cdot V_*^2, \cdot V_{x''m}^2, \cdot V_{x''q}^2$.) We may easily achieve that no connected component of $\cdot V_*^3 \cap \cdot K_j^2$ is a closed curve but that all these connected components are open arcs with end points in $\cdot (K_j^2 \cap \cdot T^3)$. Now, $\cdot (K_j^2 - V_*^2)$ contains at least one “inner” component, say K_{*1}^2 , that borders on just one connected component of $V_*^2 \cap K_j^2$. (In Fig. 2 the components K_{*1}^2 and K_{*s}^2 are inner ones.) This disk K_{*1}^2 corresponds to a relator r_1 of the group presentation \mathfrak{P} corresponding to our Heegaard-diagram (the generators g_k corresponding to the oriented meridian⁴ circles $\cdot X_k^2$) where the

⁴ By this we mean that the generator g_k may be represented by an oriented simple closed curve in $\cdot (T^3 + V_*^3)$ that pierces $\cdot X_k^2$ in just one point, in the positive sense, and is disjoint from $\cdot X_1^2, \dots, \cdot X_{k-1}^2, \cdot X_{k+1}^2, \dots, \cdot X_s^2$. Each intersection point in $\cdot K_{*1}^2 \cap \cdot X_k^2$ corresponds to a letter $g_k^{\pm 1}$ in the word r_1 .

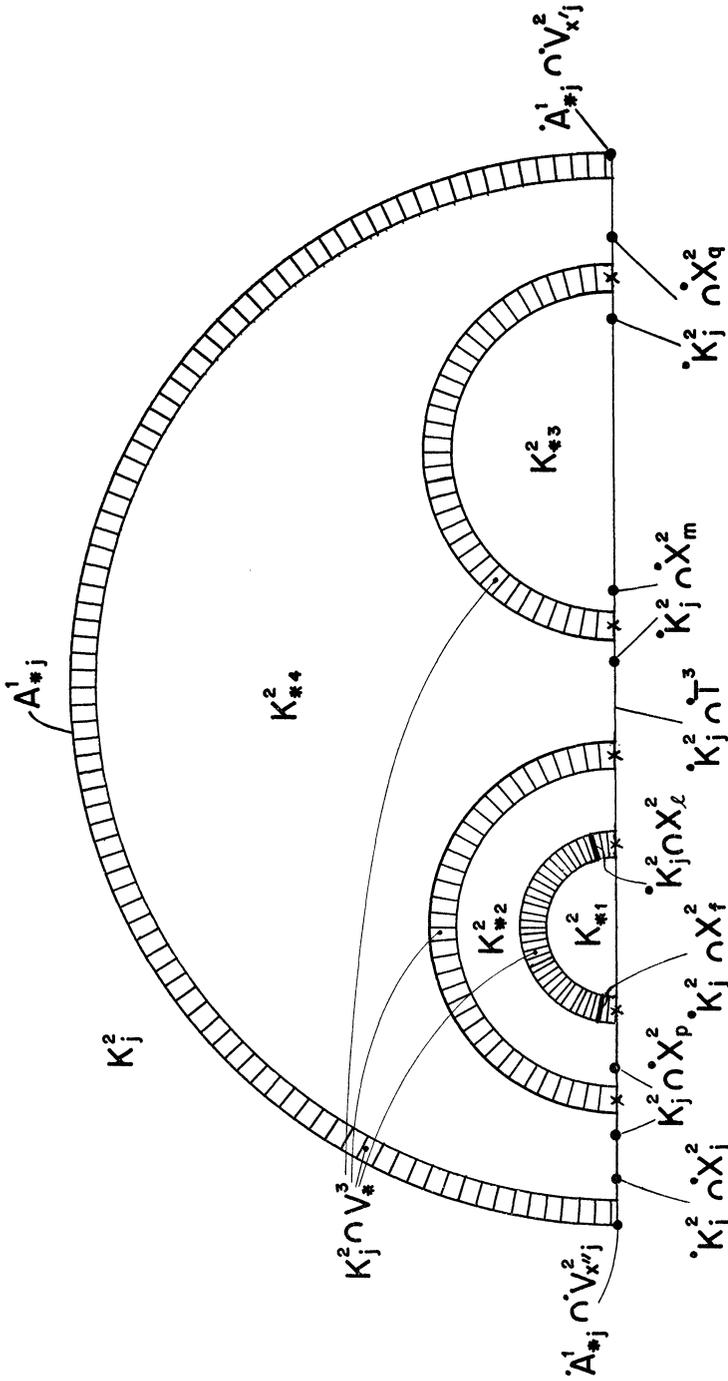


FIG.2 The points on $K_j \cap T^3$ marked by x mean from left to right intersections with $V_{*p}^2, V_{*f}^2, V_{*\ell}^2, V_{*m}^2, V_{*q}^2$

length of r_1 is at most 2. Moreover, if $K_{*1}^2 \neq \neg(K_j^2 - V_*^3)$, then there is another connected component, say K_{*2}^2 , of $\neg(K_j^2 - V_*^3)$ that corresponds to a relator r_2 which contains r_1 as a syllable. That means that we can simplify \mathfrak{B} by a cancellation operation of Type 2 whose length is not greater than 2. Then, if

$$K_{*1}^2 + K_{*2}^2 \neq \neg(K_j^2 - V_*^3),$$

we can carry out another cancellation operation of that type, and so on, until we obtain a relator equal to g_j . This can be done for all $j = 1, \dots, s$, yielding a standard trivial presentation \mathfrak{D} . Now it is not difficult to show that this sequence of cancellation operations can be replaced by a sequence of good Tietze transformations since no cancellation operation is of length greater than 2. (A cancellation operation of length 2 can be replaced by an elimination such that in all relators a certain generator g_f is replaced by another generator $g_f^{\pm 1}$, and by certain subsequent operations which can be arranged to be good Tietze transformations; the essential point is that the lengths of the relators do not increase under these eliminations.) Hence there is a cell-decomposition Ψ_0 of M^3 that is obviously a cell-decomposition of a 3-sphere.

Of course, one may try to find Γ and V^2 so that the A_{*j}^1 's are unknotted and unlinked over T^3 . This would prove the Poincaré conjecture. But my attempts in this direction failed. (It was possible to achieve the unknottedness but not the unlinkedness.)

Now we are left with the general case, namely that the arcs A_{*j}^1 may be knotted and linked over T^3 . We may apply a cheap trick: We consider the double arcs, say C_1^1, \dots, C_u^1 , of the projection cylinder $K^2 = \bigcup_{j=1}^s K_j^2$ (compare Fig. 5, Case 2, in Sec. 4) and we add small neighborhoods C_1^3, \dots, C_u^3 of them (in $M^3 - T^3$) to T^3 , obtaining an expanded handlebody T_\vee^3 . Now we have enforced that those pieces, say A_{jk}^1 , of the A_{*j}^1 's that lie outside of T_\vee^3 are unknotted and unlinked over T_\vee^3 , where we simply take $K^2 - T_\vee^3$ for the projection cylinder. Then the connected components of the projection cylinder (i.e., the projection cylinders of the A_{jk}^1 's into T_\vee^3) yield diagrams very similar to Fig. 2. But the essential difference is that the handlebody $V_*^3 + T_\vee^3$ has more handles than $V_*^3 + T^3$ (corresponding to the connected components of the $C_m^3 \cap V_*^3$'s); therefore we need additional meridian disks in $V_*^3 + T_\vee^3$ (which we shall construct in detail in Sec. 7). These additional meridian disks intersect the projection cylinder, with the result that the "inner disks" correspond to relators which may contain "cancellation syllables" $g_i^{-1}g_i$ and which may remain of length 3 even after the cancellation syllables are deleted. That is the reason why this attempt yields a proof of our theorem but not a proof of the Poincaré conjecture.

3. Projecting the 1-skeleton of a cell-decomposition Δ of the singular fan V_*^2 into the Heegaard-surface T^3 . We consider a cell-decomposition Γ of M^3 that contains just one vertex E^0 , just r elements $E_1^1, \dots, E_r^1, E_1^2, \dots,$

E_r^2 , of each dimension 1 and 2 ($r \neq 0$), and just one 3-dimensional element E^3 (see [3, Sec. 5]). Further we consider a singular fan V^2 , defined by a map $\zeta : V'^2 \rightarrow M^3$, (as in [3, Sec. 6]), such that the only singularities of V^2 are double arcs A_1^1, \dots, A_s^1 ($s \neq 0$) with inverse images $A_j'^1, A_j''^1$ ($j = 1, \dots, s$) as in Fig. 3, and such that $V^2 = \cup_{i=1}^r \bar{E}_i^1$, where V'^2 consists of disks $V_i'^2$ ($i = 1, \dots, r$) with just one common vertex E'^0 in their boundaries and with $\zeta(V_i'^2) = \bar{E}_i^1$. We choose a small neighborhood T^3 of $\cup_{i=1}^r \bar{E}_i^1$ in M^3 (as in [5, Sec. 2]) which is a Heegaard-handlebody in M^3 .

Notation. (See Fig. 3.) We denote the connected components of $\zeta^{-1}(V^2 \cap T^3)$ by $V_T'^2, V_{\mathbf{x}'j}^2, V_{\mathbf{x}''j}^2$ ($j = 1, \dots, s$) such that $V_T'^2, V_{\mathbf{x}'j}^2, V_{\mathbf{x}''j}^2$ are neighborhoods of $V^2, A_j'^1 \cap V^2, A_j''^1 \cap V^2$, respectively, in V'^2 . Further we denote

$$\begin{aligned} &-(V'^2 - V_T'^2), \quad -(V_i'^2 - V_T'^2), \quad -[A_j'^1 - (V_T'^2 + V_{\mathbf{x}'j}^2)], \\ & \quad \quad \quad -[A_j''^1 - (V_T'^2 + V_{\mathbf{x}''j}^2)] \end{aligned}$$

by $V_*'^2, V_{*i}^2, A_{*j}^1, A_{*j}''^1$, respectively. We denote the images under ζ by omitting upper primes, i.e., $\zeta(V_T'^2), \zeta(V_{\mathbf{x}'j}^2), \zeta(A_{*j}^1) = \zeta(A_{*j}''^1)$, etc., are denoted by $V_T^2, V_{\mathbf{x}'j}^2, A_{*j}^1$, etc., respectively. Finally we denote $\cup_{j=1}^s A_{*j}^1$ by A_*^1 .

We choose a coherent orientation ω_M of M^3 and an orientation ω_V of V_*^2 that is carried over by ζ from a coherent orientation ω_V' of $V_*'^2$; now, if an oriented arc O^1 intersects V_*^2 in a piercing point, not in A_*^1 , then we call this intersection *positive* or *negative* according to whether the corresponding intersection number (see [7, §73]) is positive or negative.

We choose a cell-decomposition $\Gamma_{\#}^1$ of M^3 which is dual to Γ (compare [5, Sec. 3]) such that the 1-skeleton $G_{\#}^1$ of $\Gamma_{\#}^1$ is disjoint from $T^3 + A_*^1$, such that the vertex of $\Gamma_{\#}^1$ does not lie in V_*^2 , and such that the 1-dimensional elements of $\Gamma_{\#}^1$ intersect V_*^2 at most in isolated piercing points. Then we choose a small neighborhood $T_{\#}^3$ of $G_{\#}^1$ in M^3 and we denote the "handle-shell" $M^3 - \circ(T^3 + T_{\#}^3)$ by F^3 and $V_*^2 \cap F^3$ by V_F^2 .

Now we can project V_F^2 "nicely" into the handle-surface T^3 :

Our main objective is, of course, to nicely project the double arcs A_{*j}^1 of V_*^2 . But the double arcs of the projection cylinders, corresponding to the overcrossings⁵ of A_*^1 , will pierce V_*^2 in points that do not lie in A_*^1 . These piercing points will correspond to certain handles of the Heegaard-handlebody we shall construct. Therefore we shall also need arcs in V_*^2 which join the piercing points to points in V_*^2 , and we shall have to consider projection cylinders of these arcs; the additional projection cylinders so obtained will contain additional double arcs, yielding additional piercing points with V_*^2 , and so on. For this reason it seems convenient to consider a cell-decomposition Δ of V_F^2 and to demand that all its elements project in a nice way:

LEMMA 1. F^3 can be represented as cartesian product $T^3 \times I_F^1$, where I_F^1

⁵ We use the expressions "over"- and "under-crossingpoint", "projection cylinder", etc., as in [5].

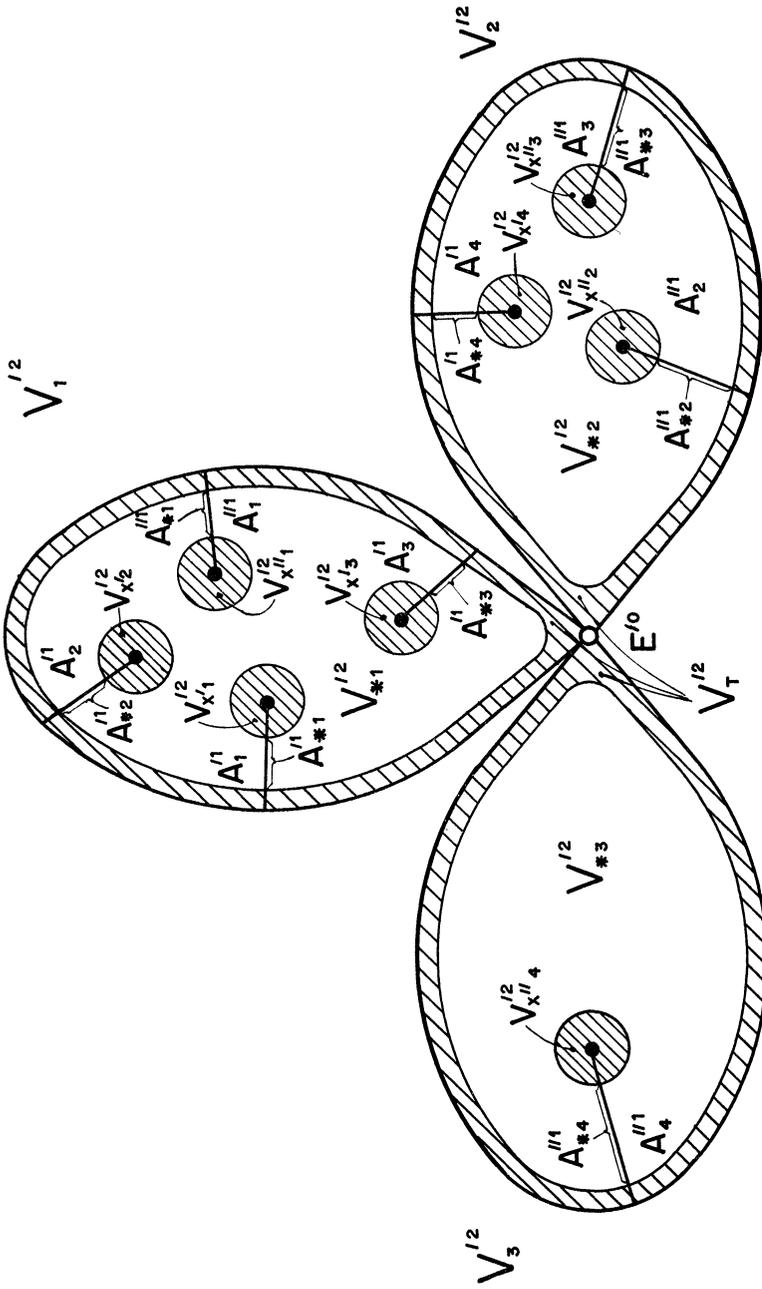


FIG. 3

means a unit interval $0 \leq x_F \leq 1$, such that $p \times 0 = p$ for all $p \in \cdot T^3$, and such that there exists a cell-decomposition Δ of V_F^2 with the following properties:

- (1) Δ projects normally into $\cdot T^3$, i.e.,
 - (1a) if N is an element of Δ and if $p \in \cdot T^3$ then $p \times I_F^1$ intersects N in at most one point;
 - (1b) if N_1, N_2 are elements of Δ and if D is the union of all points $p \in \cdot T^3$ such that $p \times I_F^1$ intersects both N_1 and N_2 then D is a cell or is empty;
 - (1c) if in (1b) the dimensions of N_1, N_2 are d_1, d_2 , respectively, and if D is not empty then the dimension of D is $d_1 + d_2 - 2$;
 - (1d) if $p \in \cdot T^3$ then $p \times I_F^1$ intersects the 1-skeleton of Δ in at most two points;
 - (1e) if $p \times I_F^1$ ($p \in \cdot T^3$) intersects two edges N_1^1, N_2^1 of Δ in the points $p \times a_1, p \times a_2$, respectively, ($0 \leq a_2 < a_1 \leq 1$) then N_1^1 overcrosses N_2^1 (i.e., N_2^1 pierces the projection cylinder⁵ of N_1^1 in $p \times a_2$, see [5, Sec. 3]; if $a_2 = 0$ then N_2^1 pierces the projection arc of N_1^1 in $\cdot T^3$).

- (2) Δ is sufficiently fine, i.e.,
 - (2a) if q is a vertex of Δ that lies in $\circ V_F^2 - A_*^1$ then q can be joined to a point q_0 in $\cdot V_F^2 - \cdot A_*^1$ by an arc Q^1 that lies in the 1-skeleton of Δ so that $\circ Q^1$ lies in $\circ V_F^2 - A_*^1$;
 - (2b) if N^1 is an edge of Δ then N^1 overcrosses $A_*^1 + \cdot V_F^2$ at most once.

(3) V_F^2 is not folded and not twisted along A_*^1 , i.e., there exists a small neighborhood U_A^3 of A_*^1 in F^3 such that the following holds:

if O^1 is an oriented interval in U_A^3 , in the x_F -direction (i.e., an arc in U_A^3 that projects into one point in $\cdot T^3$ and that is oriented in the direction of increasing x_F) then $\zeta^{-1}(O^1 \cap V_F^2)$ consists of at most two points and all piercings of O^1 through $V_F^2 - A_*^1$ are positive.

Proof. I. Let \mathbb{E}^4 be a euclidean 4-space and let us denote one of its coordinates by x_F and the unit interval of the x_F -axis by I_F^1 . We choose a (semilinear) homeomorphism η_T of T^3 into the 3-dimensional subspace $x_F = 0$ of \mathbb{E}^4 and we denote $\eta_T(T^3)$ by $T^{\vee 3}$. We denote the handle shell $\cdot T^{\vee 3} \times I_F^1$ by $F^{\vee 3}$ and we associate with any point $q \in F^{\vee 3}$ the coordinates (p, a) so that p is the projection of q into $\cdot T^{\vee 3}$ in the x_F -direction and a is the x_F -coordinate of q . We can extend η_T to a (semilinear) homeomorphism η of $T^3 + F^3$ onto $T^{\vee 3} + F^{\vee 3}$. We denote $\eta(V_F^2)$ by $V_I^{\vee 2}$ and $\eta(A_*^1)$ by $A_{*I}^{\vee 1}$. We choose a rectilinear triangulation Δ_T of $\cdot T^{\vee 3}$ and a corresponding "prismatical" decomposition Λ of $F^{\vee 3}$: For the elements of Λ we take $W \times 0, W \times \circ I_F^1$, and $W \times 1$ for all $W \in \Delta_T$.

II. We can transform $V_I^{\vee 2}$ by a "small isotopic deformation" into a polyhedron $V_{II}^{\vee 2}$ such that the transform $A_{*I}^{\vee 1}$ of $A_{*I}^{\vee 1}$ projects normally into $\cdot T^{\vee 3}$ and is in "normal position" with respect to Λ ; by this we mean: There exists a self-homeomorphism ϑ_I of $F^{\vee 3}$ which is the identity outside of a small neighborhood of $A_{*I}^{\vee 1}$ in $F^{\vee 3}$ such that $\vartheta_I(\cdot F^{\vee 3}) = \cdot F^{\vee 3}$, and such that with the notation $\vartheta_I(V_I^{\vee 2}) = V_{II}^{\vee 2}, \vartheta_I(A_{*I}^{\vee 1}) = A_*^{\vee 1}$ the following holds: (II.i) if $p \in \cdot T^{\vee 3}$

then $p \times I_{\mathbb{F}}^1$ intersects $A_*^{\vee 1}$ in at most two points; (II.ii) if $p \in A_*^{\vee 1}$ then $(p \times I_{\mathbb{F}}^1) \cap A_*^{\vee 1}$ is empty; (II.iii) if $p \times I_{\mathbb{F}}^1$ intersects $A_*^{\vee 1}$ in two points $p \times a_1, p \times a_2$ ($p \in T^{\vee 3}, 0 < a_2 < a_1 < 1$) then p lies in an open triangle of Λ_T and there are small neighborhoods N_1^1, N_2^1 of $p \times a_1, p \times a_2$, respectively, in $A_*^{\vee 1}$ which are straight line segments such that N_1^1 overcrosses N_2^1 ; (II.iv) $A_*^{\vee 1}$ is disjoint from the 1-skeleton of Λ , and $A_*^{\vee 1}$ intersects the 2-dimensional elements of Λ at most in isolated piercing points.

III. We choose a small neighborhood U_*^3 of $A_*^{\vee 1}$ in $F^{\vee 3}$, and we can find a small neighborhood U^3 of $A_*^{\vee 1}$ in U_*^3 such that (see Fig. 4) the following holds: (0) if $O^{\vee 1}$ is an interval in U_*^3 , in the $x_{\mathbb{F}}$ -direction, then $O^{\vee 1} \cap U^3$ is connected (or empty) and $O^{\vee 1} \cap U^3$ consists of at most two points.

To obtain U^3 we may choose a rectilinear triangulation Ξ of $A_*^{\vee 1}$ which contains all intersection points of $A_*^{\vee 1}$ with 2-elements of Λ as vertices, but

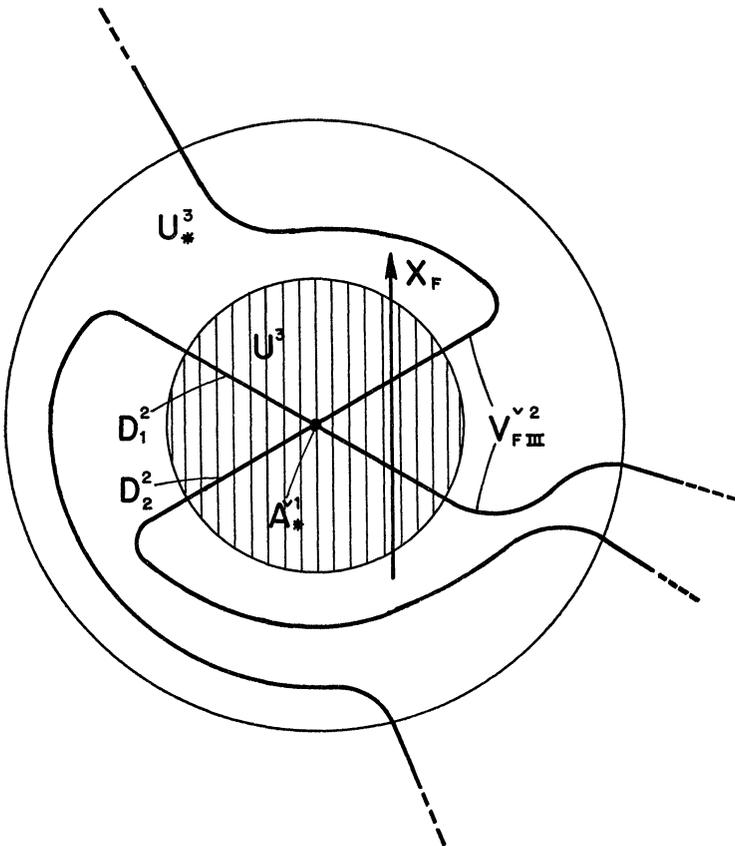
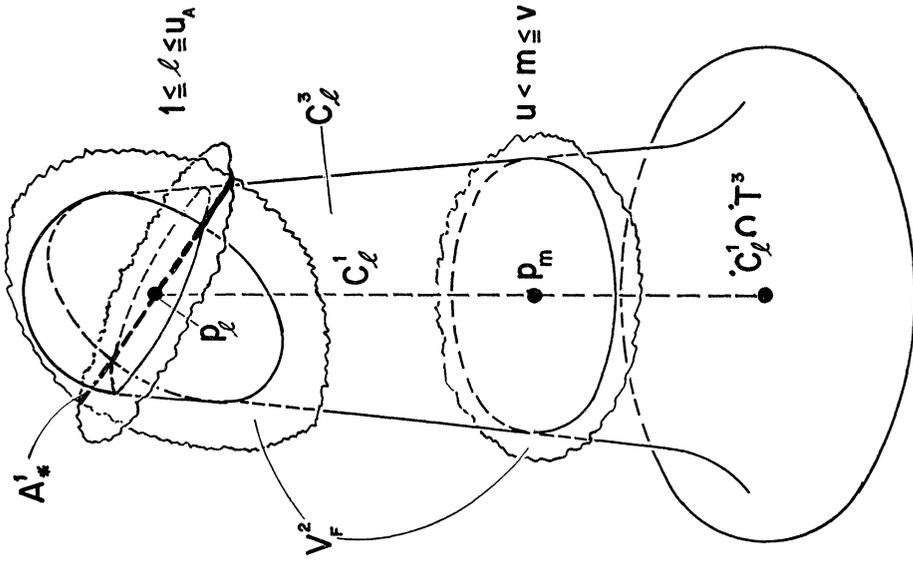
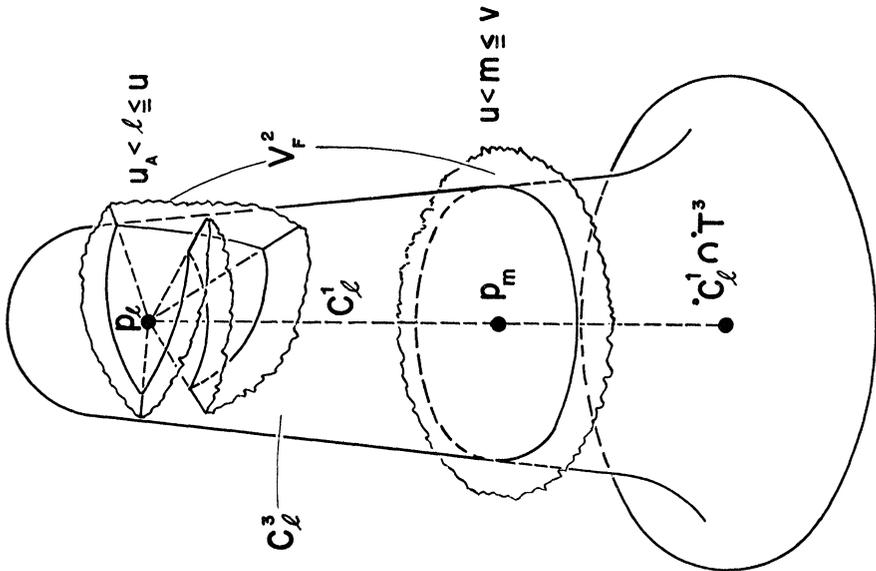


FIG.4 (Cross section)



Case 2: p_ℓ lies in A_*^1



Case 1: p_ℓ is a vertex of Δ

FIG.5

does not contain any over- or under-crossing point of A_*^{-1} as a vertex. Then we can find a rectilinear sub-triangulation Λ_T^* of Λ_T and a corresponding prismatical subdivision Λ^* of Λ such that every vertex of Ξ lies in a 2-element of Λ^* and such that Λ^*, A_*^{-1} have the properties (II.iii) and (II.iv). We denote the open, rectilinear intervals in which A_*^{-1} intersects the 3-elements of Λ^* by D_1^1, \dots, D_w^1 such that the D_i^1 's lie in the order of the enumeration in A_*^{-1} , and we assume that the neighborhood U_*^3 is small with respect to Λ^* ; further we denote the 3-element of Λ^* that contains D_i^1 by P_i^3 . Now we can find small, cylindrical neighborhoods U_i^3, \dots, U_w^3 of $\bar{D}_1^1, \dots, \bar{D}_w^1$, respectively, in $U_*^3 \cap \bar{P}_1^3, \dots, U_*^3 \cap \bar{P}_w^3$, respectively, that have the property (0) such that $U_i^3 \cap U_{i-1}^3$ is either empty (if \bar{D}_{i-1}^1 and \bar{D}_i^1 are "end pieces" of connected components of A_*^{-1}) or is a connected component of $U_i^3 \cap P_i^3$ and also a connected component of $U_{i-1}^3 \cap P_{i-1}^3$ (and such that $U_j^3 \cap U_i^3$ is empty whenever $|i - j| > 1$). Then $U^3 = \bigcup_{i=1}^w U_i^3$ has the demanded properties. Now we can "isotopically smooth out" $V_{II}^{\vee 2}$ in the neighborhood U^3 of A_*^{-1} and "wind it about A_*^{-1} " so that it is pierced by the intervals $O^{\vee 1}$ in the demanded way. By this we mean: We can find a self-homeomorphism ϑ_{II} of $F^{\vee 3}$ with $\vartheta_{II}(U_i^3) = U_i^3$ and $\vartheta_{II}(P_i^3) = P_i^3$ (for all $i = 1, \dots, w$) which is the identity on $-(F^{\vee 3} - U_*^3)$ and on A_*^{-1} such that the image $V_{III}^{\vee 2}$ of $V_{II}^{\vee 2}$ under ϑ_{II} has the following properties: (III.i) if U_0^3 is a connected component of U^3 then $V_{III}^{\vee 2} \cap U_0^3$ consists of two disks D_1^2, D_2^2 , piercing each other in $A_*^{-1} \cap U_0^3$, such that every interval $O^{\vee 1} \subset U_*^3$ in x_F -direction intersects each disk D_1^2, D_2^2 in at most one point; (III.ii) if an interval $O^{\vee 1}$ in x_F -direction pierces D_1^2 or D_2^2 then the intersection number is positive when $O^{\vee 1}$ is oriented in the direction of increasing x_F and $D_1^2, D_2^2, F^{\vee 3}$ are oriented according to ω_V, ω_M , respectively, carried over by $\vartheta_{II} \vartheta_I \eta$; (III.iii) there exists a *rectilinear* triangulation Δ_0^3 of $V_{III}^{\vee 2}$ such that no vertex of Δ_0^3 is an over- or under-crossing point of A_*^{-1} .

To obtain ϑ_{II} we first deform $V_{II}^{\vee 2} \cap U_1^3$ in a suitable way, i.e. we can find a self-homeomorphism ϑ_1 of $F^{\vee 3}$ with $\vartheta_1(P_1^3) = P_1^3$ which is the identity outside of a small neighborhood of U_1^3 in $F^{\vee 3}$ and on A_*^{-1} such that the conditions (III.i, ii, iii) hold with U^3 replaced by U_1^3 and $V_{III}^{\vee 2}$ replaced by $\vartheta_1(V_{II}^{\vee 2})$. Then we can find, step by step, self-homeomorphisms $\vartheta_2, \dots, \vartheta_w$ of $F^{\vee 3}$ with $\vartheta_i(P_i^3) = P_i^3$ such that ϑ_i is the identity on A_*^{-1} , on U_{i-1}^3 , and outside of a small neighborhood of U_i^3 , and such that (III.i, ii, iii) hold with U^3 replaced by $U_1^3 + \dots + U_i^3$ and $V_{III}^{\vee 2}$ replaced by $\vartheta_i \vartheta_{i-1} \dots \vartheta_1(V_{II}^{\vee 2})$. Then we may take $\vartheta_w \dots \vartheta_1$ for ϑ_{II} .

$V_{III}^{\vee 2}$ and Δ_0^3 fulfill the conditions corresponding to (3) and (1a), (1b). Moreover, each connected component of $V_{III}^{\vee 2} - A_*^{-1}$ contains in its boundary arcs of $\vartheta_{II} \vartheta_I \eta(V_*^2 - A_*^{-1})$. So if $\Delta_{III}^{\vee 2}$ is a regular subdivision of Δ_0^3 (obtained by starring each edge and each triangle of Δ_0^3) then each vertex q of $\Delta_{III}^{\vee 2}$ can be joined to a vertex in $\vartheta_{II} \vartheta_I \eta(V_*^2 - A_*^{-1})$ by an edge path in the 1-skeleton of $\Delta_{III}^{\vee 2}$ whose interior lies in $V_{III}^{\vee 2} - A_*^{-1}$, i.e., the condition corresponding to (2a) is fulfilled by $V_{III}^{\vee 2}$ and $\Delta_{III}^{\vee 2}$. We choose $\Delta_{III}^{\vee 2}$ so that it fulfills condition

(III.iii) (i.e., none of the starring points is an over- or under-crossing point of A_*^1).

IV. Now we can deform $V_{III}^{\vee 2}$ and Δ_{III}^{\vee} by a small isotopic deformation, leaving A_*^1 pointwise fixed, into a polyhedron $V^{\vee 2}$ and a triangulation Δ_{IV}^{\vee} of $V^{\vee 2}$, respectively, such that the rectilinearity of the triangulation may be destroyed, but (IV.i) the conditions (1a), (1b), (3) are preserved, and (IV.ii) the conditions corresponding to (1c, d, e) are also fulfilled. We denote the corresponding self-homeomorphism of $F^{\vee 3}$ by ϑ_{III} .

V. We can subdivide the edges of Δ_{IV}^{\vee} by new vertices in such a way that the condition corresponding to (2b) is fulfilled and such that all the other conditions are preserved. We call the cell-decomposition so obtained Δ^{\vee} .

VI. Now we carry over the product representation of $F^{\vee 3}$ and the decomposition Δ^{\vee} from $F^{\vee 3}$ to F^3 by means of the homeomorphism $(\eta | F^3)^{-1} \vartheta_I^{-1} \vartheta_{II}^{-1} \vartheta_{III}^{-1} : F^{\vee 3} \rightarrow F^3$, denoted by κ . In other words, we associate with each point $q \in F^3$ the coordinates $(\kappa(p^{\vee}), a)$ where (p^{\vee}, a) are the coordinates of $\kappa^{-1}(q)$ in $F^{\vee 3}$; by this we define the product representation $F^3 = T^3 \times I_F^1$ of F^3 ; further we denote by Δ the cell-decomposition of $V_F^2 = \kappa(V^{\vee 2})$ whose elements are the images under κ of the elements of Δ^{\vee} . Then all conditions of Lemma 1 are fulfilled (where we choose for U_A^3 a small neighborhood of A_*^1 in $\kappa(U^3)$). This proves Lemma 1.

4. Expanding the handlebody T^3 into T^3_{\wedge} . By $\Delta(\overset{\circ}{V}_F^2)$ we mean the set of those elements of Δ that lie in $\overset{\circ}{V}_F^2$. We consider the set $\{p_1, \dots, p_u\}$ of all points that are either vertices of $\Delta(\overset{\circ}{V}_F^2)$ or undercrossing points⁵ of the 1-skeleton of $\Delta(\overset{\circ}{V}_F^2)$. Let C_1^1, \dots, C_u^1 be the projection intervals of p_1, \dots, p_u , respectively (i.e., the arcs in F^3 , in x_F -direction, joining the p 's to points in T^3). Then we choose small, pairwise disjoint neighborhoods C_1^3, \dots, C_u^3 of C_1^1, \dots, C_u^1 , respectively, in F^3 (see Fig. 5 which shows the two most complicated cases) and we denote the handlebody $T^3 + \bigcup_{i=1}^u C_i^3$ by T^3_{\wedge} . We choose the C_i^3 's so that each interval $p \times I_F^1$ with $p \in C_i^3 \cap T^3$ intersects $\overset{\circ}{(}C_i^3 - T^3)$ in just one point (which is a piercing point if $p \in \overset{\circ}{(}C_i^3 \cap T^3)$).

Notation. (See Fig. 6.) We choose an orientation ω_A of A_*^1 such that the arc $A_{*j}^1 (j = 1, \dots, s)$ is oriented from its boundary point in $V_{X'j}^2$ to its boundary point in $V_{X^*j}^2$. We arrange the enumeration of the points p_1, \dots, p_u so that p_1, \dots, p_{u_A} lie in A_*^1 and that p_{u_A+1}, \dots, p_u do not lie in A_*^1 ; moreover, if a point p runs through $A_{*1}^1, \dots, A_{*s}^1$ in the order of the enumeration and in the direction of ω_A then we assume that p meets the points p_1, \dots, p_{u_A} in the order of the enumeration. For convenience we denote the points p_1, \dots, p_{u_A} also by

$$p_{11}, \dots, p_{1t_1}, p_{21}, \dots, p_{2t_2}, \dots, p_{s1}, \dots, p_{st_s}$$

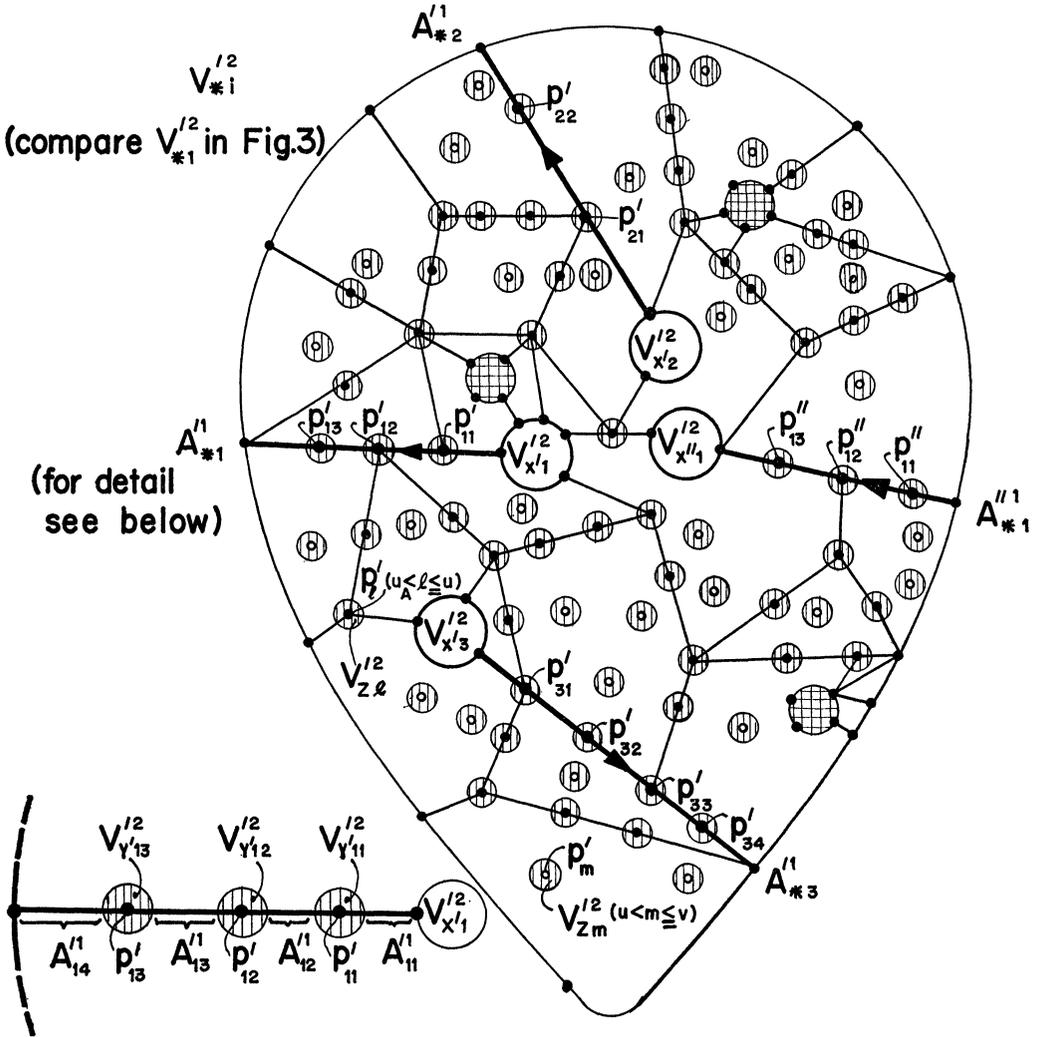


FIG.6 The arrows correspond to ω_A ; the arcs and intervals map into the 1-skeleton of Δ ; the points \circ map into $U_{\ell=1}^u \circ C_\ell^1 \cap V_F^2$; $\zeta^{-1}(U_{\ell=1}^u C_\ell^1 \cap V_F^2)$ is indicated by hatching, $\zeta^{-1}(T_\#^3 \cap V_*^2)$ by double hatching.

so that p_{j_1}, \dots, p_{j_t} lie in A_{*j}^1 in the order of the second index, between $\circ V_{\mathbb{X}'j}^2$ and $\circ V_{\mathbb{X}''j}^2$ ($u_A = \sum_{j=1}^s t_j$). We denote the points in $U_{i=1}^u \circ C_i^3 \cap V_{\mathbb{F}}^2$ by p_{u+1}, \dots, p_v . The inverse images $\zeta^{-1}(p_{jk})$ of p_{jk} ($j = 1, \dots, s$; $k = 1, \dots, t_j$) are denoted by p'_{jk} and p''_{jk} so that $p'_{jk} \in A_{*j}^1$ and $p''_{jk} \in A_{*j}^1$; the point $\zeta^{-1}(p_m)$ ($m = u_A + 1, \dots, v$) is denoted by p'_m . Further we denote that connected component of $\zeta^{-1}(U_{i=1}^u \circ C_i^3 \cap V_{\mathbb{F}}^2)$ that is a neighborhood of p'_{jk}, p''_{jk}, p'_m , respectively, ($j = 1, \dots, s$; $k = 1, \dots, t_j$; $m = u_A + 1, \dots, v$) by $V_{\mathbb{Y}'jk}^2, V_{\mathbb{Y}''jk}^2, V_{\mathbb{Z}m}^2$, respectively; and we denote $\zeta(V_{\mathbb{Y}'jk}^2), \zeta(V_{\mathbb{Y}''jk}^2), \zeta(V_{\mathbb{Z}m}^2)$ by $V_{\mathbb{Y}'jk}^2, V_{\mathbb{Y}''jk}^2, V_{\mathbb{Z}m}^2$, respectively. Finally we denote the connected components of $A_{*j}^1 - U_{i=1}^u \circ C_i^3$ by $A_{j_1}^1, \dots, A_{j_{t_j+1}}^1$ so that the A_{jk}^1 's lie in A_{*j}^1 in the order of the index k (in the sense of the orientation ω_A); and we denote the connected components of $\zeta^{-1}(A_{jk}^1)$ by $A'_{jk}{}^1$ and $A''_{jk}{}^1$ so that $A'_{jk}{}^1 \subset A_{*j}^1$ and $A''_{jk}{}^1 \subset A_{*j}^1$.

5. Trees in $V_{\mathbb{F}}^2$. The intersections $V_{\mathbb{Z}l}^2$ ($l = u_A + 1, \dots, v$) of $U_{h=1}^u C_h^3$ with $V_{\mathbb{F}}^2$ correspond to certain handles of the handlebody H^3 composed of T^3_{\wedge} and a polyhedron V^3_* obtained from V^2_* by thickening. We shall need disks in M^3 with boundaries in H^3 that correspond to these handles in the following way: The boundary of the first disk, say $K^2_{u_A+1}$, runs just once over the handle corresponding to $V^2_{\mathbb{Z}u_A+1}$ (under proper notation) and over no other handles that correspond to $V^2_{\mathbb{Z}l}$'s. The boundary of the $(m - u_A)^{\text{th}}$ disk ($u_A < m \leq v$), K^2_m , runs just once over the handle corresponding to $V^2_{\mathbb{Z}m}$ but not over handles that correspond to $V^2_{\mathbb{Z}l}$'s with $l > m$. We can find such disks K^2_m in a convenient way in the projection cylinder of some polyhedron J^1 (see Fig. 7) in the 1-skeleton of Δ that contains all the points p_{u_A+1}, \dots, p_u and that consists of trees each of which contains just one point in $V^2_* - A^1_*$.

LEMMA 2. *In the 1-skeleton of Δ there exists a 1-dimensional polyhedron J^1 with the following properties:*

- (i) every connected component of J^1 is a tree (i.e., simply connected) that contains just one point in $V^2_* - A^1_*$, the so-called base point, and otherwise lies in $\circ V_{\mathbb{F}}^2 - A^1_*$;
- (ii) J^1 contains all the points p_{u_A+1}, \dots, p_u ;
- (iii) if p is an end point of J^1 (i.e., a point in $J^1 \cap V_{\mathbb{F}}^2$ from which just one edge of J^1 originates) then p is one of the points p_{u_A+1}, \dots, p_u .

Proof. Let p_l be an arbitrary point with $u_A < l \leq u$. Then, because of property (2a) of Δ (in Lemma 1), there is an arc, say Q^1_l , that lies in the 1-skeleton of Δ so that $\circ Q^1_l \subset \circ V_{\mathbb{F}}^2 - A^1_*$, and $\circ Q^1_l = p_l + q_l$ where q_l is a point in $V^2_* - A^1_*$.

Now we consider the following sequence $J^1_{(1)}, \dots, J^1_{(u-u_A)}$ of 1-dimensional polyhedra: $J^1_{(1)} = Q^1_{u_A+1}$. If $p_{u_A+h+1} \in J^1_{(h)}$ ($1 \leq h < u - u_A$) then we take $J^1_{(h+1)} = J^1_{(h)}$. If $p_{u_A+h+1} \notin J^1_{(h)}$ then $Q^1_{u_A+h+1}$ contains an arc, say Q^1_{\sim} , such that $\circ Q^1_{\sim} = p_{u_A+h+1} + q_{\sim}$ where $q_{\sim} \in J^1_{(h)}$ or $q_{\sim} = q_{u_A+h+1}$ (in which case $Q^1_{\sim} = Q^1_{u_A+h+1}$) and such that $\circ Q^1_{\sim} \cap J^1_{(h)} = \emptyset$; then we take $J^1_{(h+1)} = J^1_{(h)} + Q^1_{\sim}$.

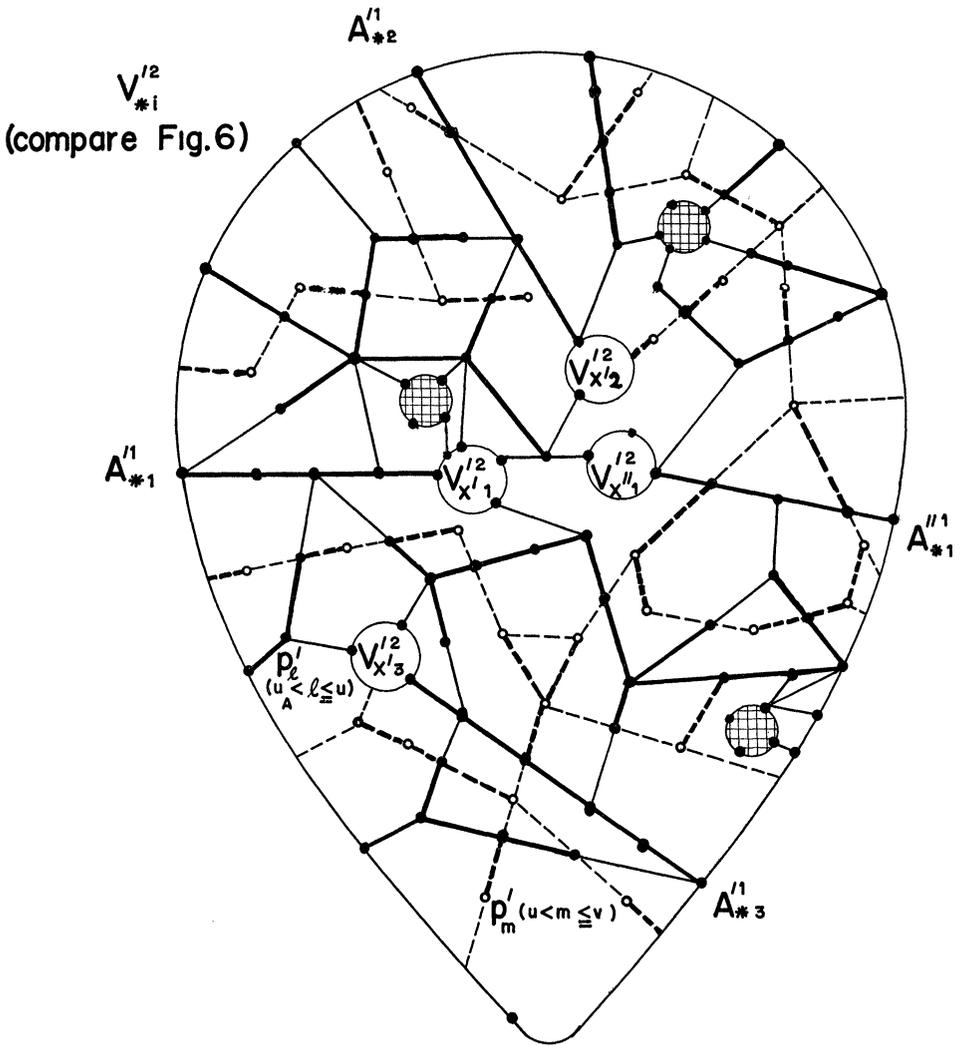


FIG. 7 The heavy segments mean $\zeta^{-1}(J^1 + A_{*}^1)$;
 the dotted segments mean $\zeta^{-1}(\bar{V}_F^2 \cap K^2)$;
 the heavy dotted segments mean $\zeta^{-1}(J_{\#}^1)$.

Each $J_{(h)}^1$ has properties (i) and (iii); the last element, $J_{(u-u_A)}^1$, has all three properties demanded for J^1 which proves Lemma 2.

Notation. We denote the projection cylinder⁵ of $J^1 + A_{*}^1$ by K^2 . (We assume that the neighborhoods C_i^2 of Sec. 4 are small also with respect to K^2 .)

LEMMA 2_#. In $\bar{V}_{\mathbb{F}}^2 \cap \circ K^2$ there exists a 1-dimensional polyhedron $J_{\#}^1$ (see Fig. 7) with the following properties:

- (i)_# every connected component of $J_{\#}^1$ is a tree that contains just one point in the 1-skeleton of Δ , the "base point" (it follows that a base point of $J_{\#}^1$ is either one of the points p_1, \dots, p_u or lies in $\bar{V}_{\mathbb{F}}^2 \cap \circ T^3 - \circ A_{\#}^1$);
- (ii)_# $J_{\#}^1$ contains all the points p_{u+1}, \dots, p_v ;
- (iii)_# if p is an end point of $J_{\#}^1$ ($p \in J_{\#}^1$; p is not a base point) then p is one of the points p_{u+1}, \dots, p_v .

Proof. Let p_m be an arbitrary point with $u < m \leq v$. Then p_m lies in a 2-dimensional element, say N_m^2 , of Δ (see Fig. 8); moreover, p_m lies under a point $p_{\mu(m)}$ with $u_A < \mu(m) \leq u$. Now let $J_{\#}^1$ be that connected component of J^1 that contains $p_{\mu(m)}$ and let $q_{\#}$ be its base point. Then $q_{\#}$ does not lie over or in N_m^2 , and hence the projection cylinder $K_{\#}^2$ of $J_{\#}^1$ intersects N_m^2 in a 1-dimensional polyhedron that contains an arc, say Q_m^1 , so that $\circ Q_m^1 \subset N_m^2$ and $\circ Q_m^1 = p_m + q_m$ where q_m is a point in N_m^2 (see Fig. 8). Now we may continue as in the second paragraph of the proof of Lemma 2 (replacing l by m , $J_{\#}^1$ by $J_{\#}^1$, u by v , and u_A by u). This proves Lemma 2_#.

Notation. We arrange the enumeration of the points p_{u_A+1}, \dots, p_v so that for each $m = u_A + 1, \dots, v$ $J^1 + J_{\#}^1$ contains an arc, denoted by J_m^1 , that joins p_m either to a point in $(\bar{V}_{\mathbb{F}}^2 \cap \circ T^3 - \circ A_{\#}^1) + \circ A_{\#}^1$ or to a point $p_{\lambda(m)}$ with $u_A < \lambda(m) < m$ so that $\circ J_m^1$ does not contain any point p_l ($l = 1, \dots, v$).

6. A prismatical neighborhood $V_{\#}^3$ of $V_{\#}^2$. We "thicken" $V_{\#}^2$. First we choose a "prismatic neighborhood" $V_{\#}^3$ of $V_{\#}^2$, i.e., a polyhedron containing $V_{\#}^2$ (and consisting of r pairwise disjoint 3-cells, disjoint from M^3) that can be represented as cartesian product $V_{\#}^2 \times I_V^1$, where I_V^1 means an interval $-1 \leq x_V \leq +1$, with $p' \times 0 = p'$ for all $p' \in V_{\#}^2$. Then we extend the map $\zeta | V_{\#}^2$ to a map $\tilde{\zeta}: V_{\#}^3 \rightarrow M^3$ such that the following holds:

Notation. $V_{\#i}^3$ means $V_{\#i}^2 \times I_V^1$; $V_{\#}^3, V_{\#i}^3$ mean $\tilde{\zeta}(V_{\#}^3), \tilde{\zeta}(V_{\#i}^3)$, respectively.

- (1) $V_{\#}^3 - \circ T^3$ is a small neighborhood of $V_{\#}^2 - \circ T^3$ in $M^3 - \circ T^3$.

Notation. (See Fig. 9.) Let $K_{\#}^2$ be the projection cylinder of A_{jk}^1 ($j = 1, \dots, s; k = 1, \dots, t_j + 1$) or of J_m^1 ($m = u_A + 1, \dots, v$), and let $K_{\#}^2$ be that connected component of $\bar{(K_{\#}^2 - \cup_{i=1}^u C_i^3)} \cap V_{\#}^3$ that contains A_{jk}^1 or $\bar{(J_m^1 - \cup_{i=1}^u C_i^3)}$, respectively; then we denote $\bar{[(K_{\#}^2 - \cup_{i=1}^u C_i^3) - K_{\#}^2]}$ by K_{jk}^2 or K_m^2 , respectively.⁶ Further we denote $\bar{K_{\#}^2} \cap \bar{K}_{jk}^2, \bar{K_{\#}^2} \cap \bar{K}_m^2$ by K_{Vjk}^1, K_{Vm}^1 , respectively, and $\bar{K}_{jk}^2 - \circ K_{Vjk}^1, \bar{K}_m^2 - \circ K_{Vm}^1$ by K_{Tjk}^1, K_{Tm}^1 , respectively.

⁶ It is essential to remark that $K_{\#}^2$ is a neighborhood of A_{jk}^1 or $\bar{(J_m^1 - \cup_{i=1}^u C_i^3)}$, respectively, in $\bar{(K_{\#}^2 - \cup_{i=1}^u C_i^3)}$, and that consequently the K_{jk}^2 's and K_m^2 's are disks. This holds since none of those 2-elements of Δ that are incident to A_{jk}^1 or J_m^1 , respectively, intersects $K_{\#}^2$ [because of (1a) in Lemma 1].

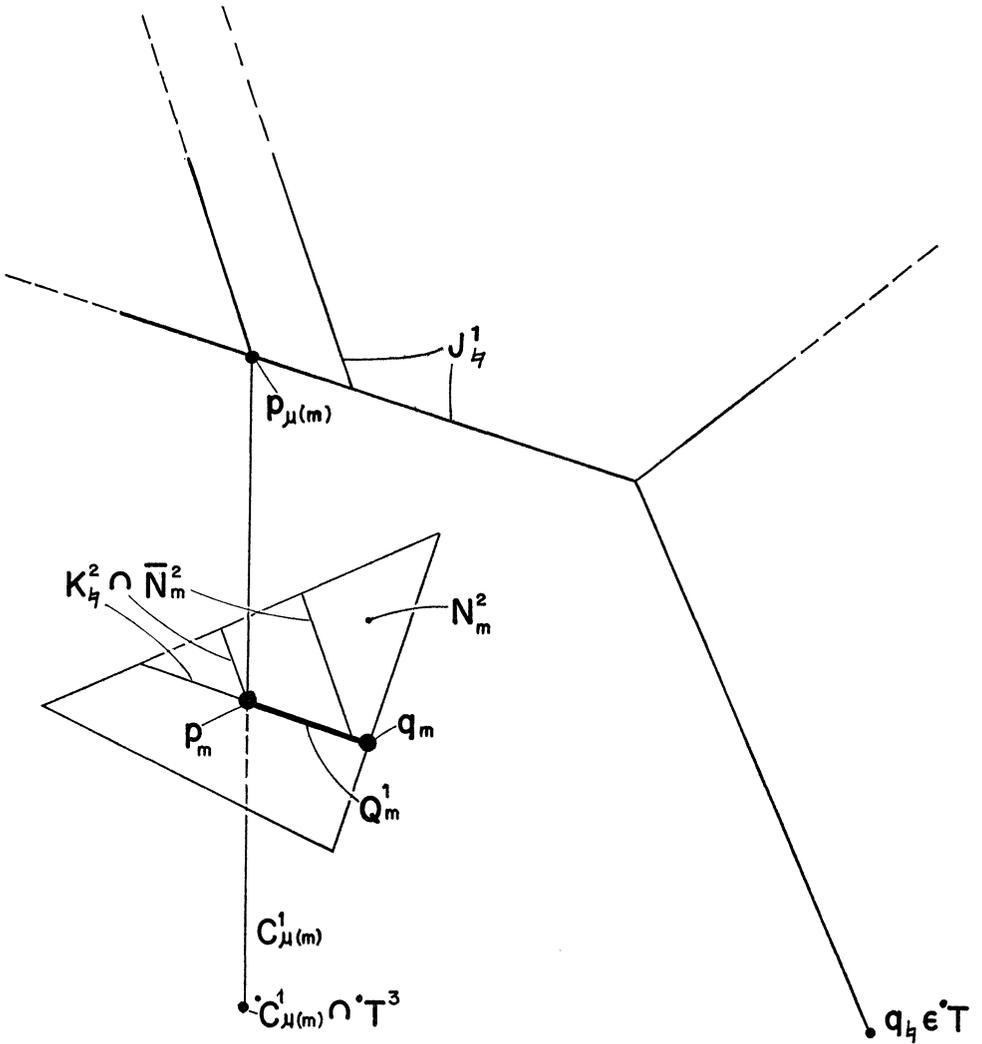
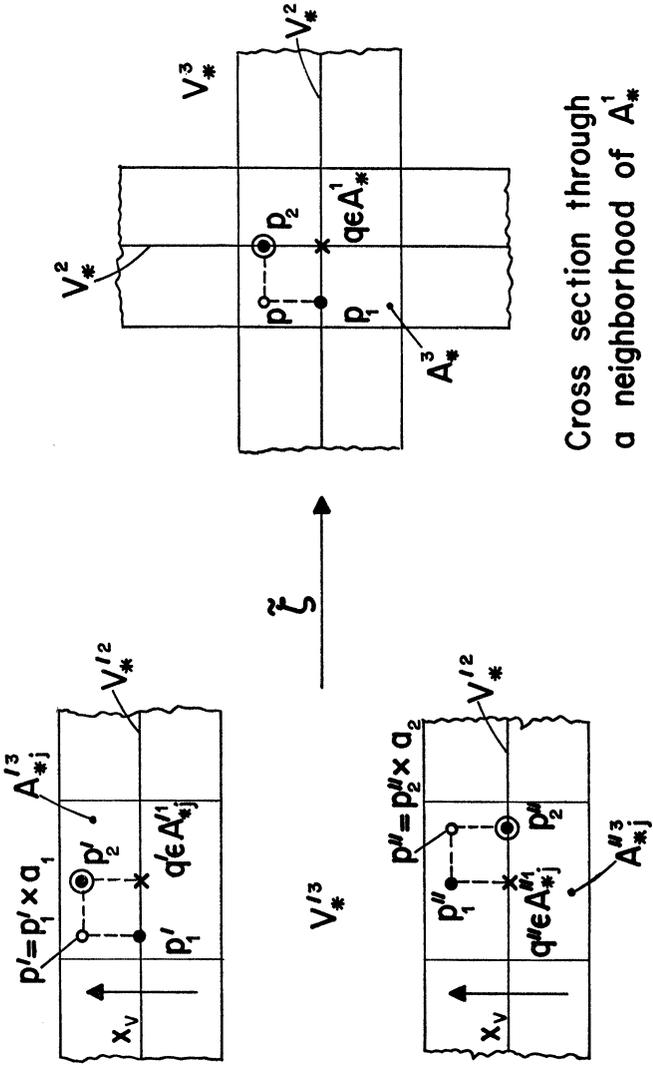


FIG. 8

(2) $T^3, T_\lambda^3, F^3, V^2, V_T^2, K_{jk}^2 - K_{Vjk}^1$, and $K_m^2 - K_{V_m}^1$ ($j = 1, \dots, s$; $k = 1, \dots, t_j + 1$; $m = u_A + 1, \dots, v$) intersect V_*^3 *prismatically* with respect to x_V, ξ ; i.e.,

$$\xi^{-1}(T^3 \cap V_*^3) = [\xi^{-1}(T^3 \cap V_*^2)] \times I_V^1$$

and correspondingly for T_λ^3, F^3 , etc.



Cross section through a neighborhood of A^*

FIG. 10

(3) The singularities of V_*^3 are *orthogonal with respect to $x_V, \tilde{\zeta}$* ; by this we mean the following (see Fig. 10):

(3.1) The set of all singular points of V_*^3 with respect to $\tilde{\zeta}$ is a neighborhood, denoted by A_*^3 , of A_*^1 in $M^3 - T^3$ which is small with respect to V_*^2 and intersects V_*^3 prismatically with respect to $x_V, \tilde{\zeta}$.

(3.2) Let A_{*j}^3 and $A_{*j}''^3$ ($j = 1, \dots, s$) be connected components of $\tilde{\zeta}^{-1}(A_*^3)$ such that $A_{*j}^1 \subset A_{*j}^3$ and $A_{*j}^1 \subset A_{*j}''^3$, then $\tilde{\zeta} | A_{*j}^3, \tilde{\zeta} | A_{*j}''^3$, and $\tilde{\zeta} | [V_*^3 - \tilde{\zeta}^{-1}(A_*^3)]$ are homeomorphisms.

(3.3) Let p be an arbitrary point of A_*^3 and let p', p'' be the two points of $\tilde{\zeta}^{-1}(p), p' = p'_1 \times a_1, p'' = p''_2 \times a_2$ ($p'_1, p''_2 \in V_*^2; a_1, a_2 \in [-1, 1]$); denote $\zeta(p'_1), \zeta(p''_2)$ by p_1, p_2 , respectively; now let p'_1, p''_2 be that point of $\tilde{\zeta}^{-1}(p_1), \tilde{\zeta}^{-1}(p_2)$, respectively, that is different from p'_1, p''_2 , respectively. Then there is a point $q \in A_*^1$ with $\zeta^{-1}(q) = q' + q''$ such that $p'_1 = q'' \times a_2$ and $p''_2 = q' \times a_1$.

(4) If $p' \in V_*^2$ such that $\zeta(p) \notin A_*^1$, and if (see Fig. 11) the interval $\tilde{\zeta}(p' \times I_V^1)$ is oriented according to increasing x_V , then the intersection of $\tilde{\zeta}(p' \times I_V^1)$ and V_*^2 is positive (with respect to the orientations ω_V and ω_M introduced in Sec. 3).

(5) (See Fig. 11.) Let A_{jk}^3 ($j = 1, \dots, s; k = 1, \dots, t_j + 1$) be that connected component of $(A_*^3 - \cup_{i=1}^u C_i^3)$ that contains A_{jk}^1 ; then K_{Vjk}^1 lies in A_{jk}^3 so that

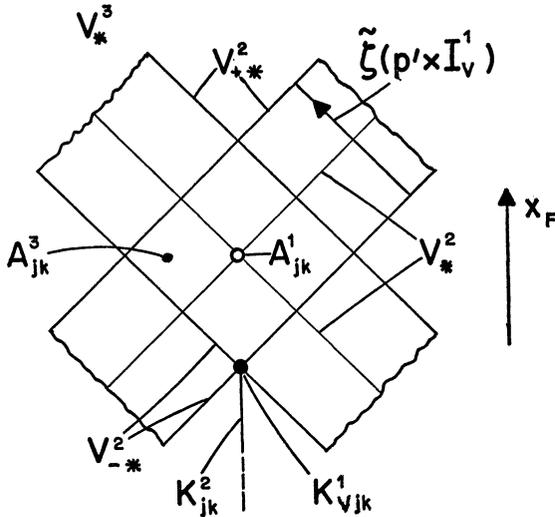


FIG. 11 (Cross section)

$$\tilde{\zeta}^{-1}(K_{\mathbb{V}jk}^1) \subset V_*^{/2} \times -1.$$

Further

$$\zeta^{-1}(K_{\mathbb{V}m}^1) \subset \zeta^{-1}(J_m^1) \times \pm 1$$

(for all $m = u_A + 1, \dots, v$).

Notation. We denote the connected components of $\tilde{\zeta}^{-1}(-[V_*^3 \cap \circ T_\wedge^3])$ by $V_{\mathbb{X}'j}^3, V_{\mathbb{X}''j}^3, V_{\mathbb{Y}'jk}^3, V_{\mathbb{Y}''jk}^3, V_{\mathbb{Z}m}^3$ so that

$$V_{\mathbb{X}'j}^3 = V_{\mathbb{X}'j}^{/2} \times I_{\mathbb{V}}^1, \dots, V_{\mathbb{Z}m}^3 = V_{\mathbb{Z}m}^{/2} \times I_{\mathbb{V}}^1;$$

correspondingly we denote $\tilde{\zeta}(V_{\mathbb{X}'j}^3), \dots, \tilde{\zeta}(V_{\mathbb{Z}m}^3)$ by $V_{\mathbb{X}'j}^3, \dots, V_{\mathbb{Z}m}^3$, respectively. Let $A_*^3, A_{*j}^3, A_{*j}^3, A_{jk}^3$ be as introduced in (3.1), (3.2), (5), respectively, and correspondingly

$$A_{jk}^3 = \tilde{\zeta}^{-1}(A_{jk}^3) \cap A_{*j}^3, \quad A_{jk}^3 = \tilde{\zeta}^{-1}(A_{jk}^3) \cap A_{*j}^3;$$

further we denote $A_{*j}^3 \cap V_*^{/2}, A_{jk}^3 \cap V_*^{/2}$, etc., by $A_{*j}^{/2}, A_{jk}^{/2}$, etc. Finally we denote $V_{\mathbb{X}'j}^{/2} \times +1, V_{\mathbb{X}'j}^{/2} \times -1$ by $V_{+\mathbb{X}'j}^{/2}, V_{-\mathbb{X}'j}^{/2}$, respectively, and correspondingly $V_{\mathbb{X}''j}^{/2} \times \pm 1, V_{\mathbb{Y}'jk}^{/2} \times \pm 1$, etc., by $V_{\pm\mathbb{X}''j}^{/2}, V_{\pm\mathbb{Y}'jk}^{/2}$, etc., and $\tilde{\zeta}(V_{\pm\mathbb{X}'j}^{/2})$, etc., by $V_{\pm\mathbb{X}'j}^2$, etc.

7. Constructing meridian disks X_j^2, Y_{jk}^2, Z_m^2 in $H^3 = T_\wedge^3 + V_*^3$. We denote the handlebody $T_\wedge^3 + V_*^3$ by H^3 . For the following construction see Fig. 12.

We choose pairwise disjoint, small neighborhoods $U_{\Delta j}^{/2}$ ($j = 1, \dots, s$) of $A_{*j}^{/2} + V_{\mathbb{X}'j}^{/2} + \bigcup_{k=1}^{t_j} V_{\mathbb{Y}'jk}^{/2}$ in $V_*^{/2}$.

$\bar{\cdot}(U_{\Delta j}^{/2} - \bar{\cdot}V_*^{/2})$ is an arc, denoted by $X_{\mathbb{V}j}^{/1}$, with boundary points in $\bar{\cdot}V_*^{/2}$. (We denote $X_{\mathbb{V}j}^{/1} \times I_{\mathbb{V}}^1, \zeta(X_{\mathbb{V}j}^{/1}), \tilde{\zeta}(X_{\mathbb{V}j}^{/1} \times I_{\mathbb{V}}^1)$ by $X_{\mathbb{V}j}^{/2}, X_{\mathbb{V}j}^1, X_{\mathbb{V}j}^2$, respectively.)

Then we choose pairwise disjoint disks $X_{(j)}^2, X_j^2$ which are topologically parallel to $V_{-\mathbb{X}''j}^2, V_{+\mathbb{X}''j}^2$, respectively, in T^3 , such that

$$(\bar{\cdot}X_{(j)}^2 + \bar{\cdot}X_j^2) \cap V_*^3 = \bar{\cdot}X_{\mathbb{V}j}^2 \cap \bar{\cdot}T^3$$

and such that the parallelism is with respect to $V^2, V_*^3, \bar{\cdot}K^2, T_\wedge^3$ (as defined in [4, Sec. 3]).

Now we denote the disks $X_{\mathbb{V}j}^2 + X_{(j)}^2 + X_j^2$ by X_j^2 .

Each $\bar{\cdot}(V_{\mathbb{Y}'jk}^2 - A_*^3)$ and $\bar{\cdot}(V_{\mathbb{Y}''jk}^2 - A_*^3)$ ($j = 1, \dots, s; k = 1, \dots, t_j$) consists of two connected components $V_{\mathbb{Y}'(jk)}^2, V_{\mathbb{Y}''(jk)}^2$ and $V_{\mathbb{Y}''(jk)}^2, V_{\mathbb{Y}'(jk)}^2$, respectively; we arrange the notation so that $\bar{\cdot}V_{\mathbb{Y}'(jk)}^2, \bar{\cdot}V_{\mathbb{Y}''(jk)}^2$ intersect V_{+*}^2 (in one arc each) and that $\bar{\cdot}V_{\mathbb{Y}''(jk)}^2, \bar{\cdot}V_{\mathbb{Y}'(jk)}^2$ intersect V_{+*}^2 (in one arc each).

We choose pairwise disjoint arcs $B_{\mathbb{Y}'(jk)}^1, B_{\mathbb{Y}''(jk)}^1, B_{\mathbb{Y}''(jk)}^1, B_{\mathbb{Z}m}^1$ ($j = 1, \dots, s; k = 1, \dots, t_j; m = u_A + 1, \dots, v$) in $V_{\mathbb{F}}^2 - (A_*^3 + \circ T_\wedge^3)$ that join points in $\bar{\cdot}V_{\mathbb{Y}'(jk)}^2, \bar{\cdot}V_{\mathbb{Y}''(jk)}^2, \bar{\cdot}V_{\mathbb{Y}''(jk)}^2, \bar{\cdot}V_{\mathbb{Z}m}^2$, respectively, to points in $\bar{\cdot}V_*^2$, such that the following holds (Fig. 12 shows the inverse images of the B 's marked by upper primes):

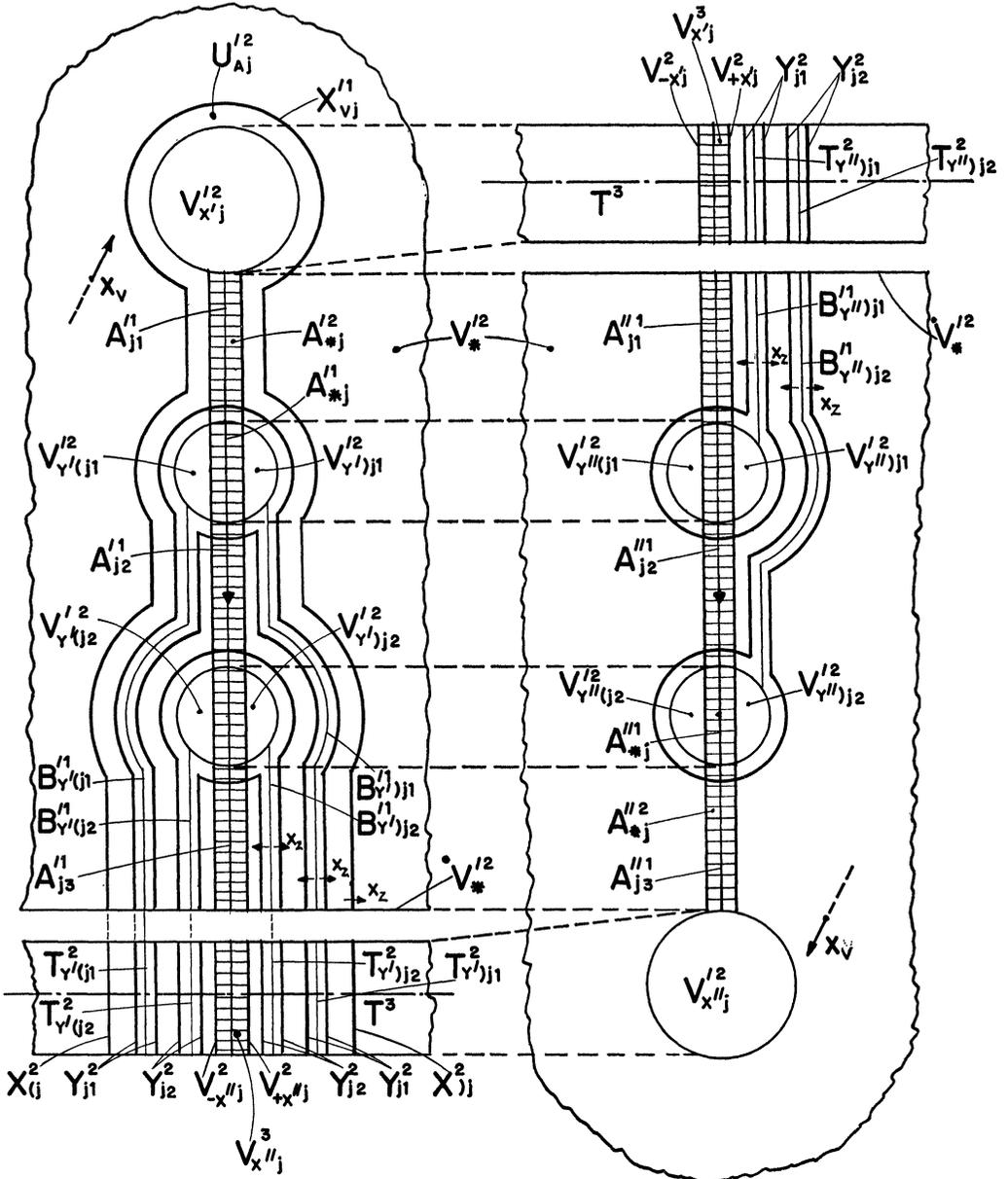


FIG. 12

(1) $B_{Y'(jk)}^1$ and $B_{Y'jk}^1$ lie in the boundary of a small neighborhood, say $U_{A'jk}^3$, of

$$A_{jk+1}^3 + V_{Y'jk+1}^3 + \cdots + A_{jt_j}^3 + V_{Y'jt_j}^3 + A_{jt_j+1}^3$$

in M^3 (with $U_{A'jk}^3 \subset \circ U_{A'jk-1}^3$ if $k > 1$);

(2) $B_{Y''jk}^1$ lies in the boundary of a small neighborhood, say $U_{A''jk}^3$, of

$$A_{j1}^3 + V_{Y''j1}^3 + \cdots + A_{jk-1}^3 + V_{Y''jk-1}^3 + A_{jk}^3$$

in M^3 (with $U_{A''jk}^3 \subset \circ U_{A''jk+1}^3$ if $k < t_j$);

(3) $B_{Z_m}^1$ is disjoint from $\cdot K^2$ and from the X_j^2 's; $\circ B_{Z_m}^1$ is disjoint from $\cdot T_\wedge^3$; $B_{Z_m}^1$ intersects K^2 at most in isolated piercing points.

We denote $\xi(\xi^{-1}(B_{Y'(jk)}^1) \times I_V^1)$ by $B_{Y'(jk)}^2$; etc.

We choose pairwise disjoint meridian disks $T_{Y'(jk)}^2, T_{Y'jk}^2, T_{Y''jk}^2, T_{Z_m}^2$ of T^3 which are disjoint from $\cup_{h=1}^s X_h^2$ such that

(a) $T_{Y'(jk)}^2 \cap V_*^3 = \cdot T_{Y'(jk)}^2 \cap \cdot V_*^3 = \cdot B_{Y'(jk)}^2 \cap \cdot T^3$, etc.,
 $T_{Z_m}^2 \cap V_*^3 = \cdot T_{Z_m}^2 \cap \cdot V_*^3 = \cdot B_{Z_m}^2 \cap \cdot T^3$;

(b) $T_{Y'(jk)}^2, T_{Y'jk}^2, T_{Y''jk}^2$ are topologically parallel to $V_{-x''j}^2, V_{+x''j}^2, V_{+x'j}^2$, respectively, in T^3 , with respect to $V^2, \cdot K^2, T_\wedge^3$;

(c) $\cdot T_{Z_m}^2$ is disjoint from the $\cdot C_i^3$'s (i.e., $\cdot T_{Z_m}^2 \subset \circ [T^3 \cap \cdot T_\wedge^3]$) and intersects $\cdot K^2 \cap \cdot T^3$ at most in isolated piercing points;

(d) $T_{Z_m}^2$ intersects $\cdot V^2$ in just one point, different from E^0 , and intersects V^2 in just one arc which is a piercing arc.

Now we choose pairwise disjoint, small neighborhoods $U_{Y'jk}^3$ and $U_{Z_m}^3$ of

$$V_{Y'jk}^3 + V_{Y''jk}^3 + B_{Y'(jk)}^2 + B_{Y'jk}^2 + B_{Y''jk}^2 + T_{Y'(jk)}^2 + T_{Y'jk}^2 + T_{Y''jk}^2$$

and

$$V_{Z_m}^3 + B_{Z_m}^2 + T_{Z_m}^2,$$

respectively, in M^3 , which intersect V_*^3 prismatically with respect⁷ to x_V, ξ . Then we denote the disks $\cdot U_{Y'jk}^3 \cap H^3, \cdot U_{Z_m}^3 \cap H^3$ by Y_{jk}^2, Z_m^2 , respectively.

We have $\cdot X_j^2, \cdot Y_{jk}^2, Z_m^2 \subset \cdot H^3$ and $\circ X_j^2, \circ Y_{jk}^2, \circ Z_m^2 \subset \circ H^3$; hence the disks X_j^2, Y_{jk}^2, Z_m^2 are meridian disks of H^3 .

Thickening the meridian disks. Let X_j^3, Y_{jk}^3, Z_m^3 be pairwise disjoint, small neighborhoods of X_j^2, Y_{jk}^2, Z_m^2 , respectively, in H^3 which intersect V_*^3 prismatically with respect⁷ to x_V, ξ ; we can represent them as cartesian products $X_j^2 \times I_Z^1, Y_{jk}^2 \times I_Z^1, Z_m^2 \times I_Z^1$, respectively, where I_Z^1 is an interval $-1 \leq x_Z \leq +1$, such that the following holds:

- (α) $p \times 0 = p$ for all $p \in X_j^2, Y_{jk}^2, Z_m^2$;
- (β) the top and bottom disks

$$X_j^2 \times \pm 1, Y_{jk}^2 \times \pm 1, Z_m^2 \times \pm 1,$$

⁷ This is possible because of the orthogonality condition (3) in Sec. 6.

denoted by $X_{\pm j}^2, Y_{\pm jk}^2, Z_{\pm m}^2$, respectively, are the connected components of $\cdot(X_j^3 \cap \circ H^3), \cdot(Y_{jk}^3 \cap \circ H^3), \cdot(Z_m^3 \cap \circ H^3)$,

respectively; (these disks are not indicated in Fig. 12, but the x_z -direction is indicated by small arrows);

- (γ) $\zeta^{-1}(X_{-j}^2 \cap V_{\star}^2)$ separates $\zeta^{-1}(X_{+j}^2 \cap V_{\star}^2)$ from $V_{X'j}^{\prime 2}$ in $V_{\star}^{\prime 2}$,
 $Y_{-jk}^2 \cap V_{\star}^2$ separates $Y_{+jk}^2 \cap V_{\star}^2$ from $V_{Y'jk}^2 + V_{Y''jk}^2$ in V_{\star}^2 ,
 $Z_{-m}^2 \cap V_{\star}^2$ separates $Z_{+m}^2 \cap V_{\star}^2$ from V_{Zm}^2 in V_{\star}^2 ;
- (δ) $T^3, V^2, A_{\star}^3, K^2$ intersect X_j^3, Y_{jk}^3, Z_m^3 prismatically with respect to x_z ;

(ε) the intersections $X_j^3 \cap V_{\star}^3, Y_{jk}^3 \cap V_{\star}^3, Z_m^3 \cap V_{\star}^3$ are *orthogonal with respect to x_z, x_v, ξ* , i.e., the following condition is fulfilled which is completely analogous to (3.3) in Sec. 6 (compare Fig. 10):

Let p be an arbitrary point of $X_j^3 \cap V_{\star}^3, Y_{jk}^3 \cap V_{\star}^3$, or $Z_m^3 \cap V_{\star}^3$ and let p'' be a point in $\zeta^{-1}(p)$ where $p = p_1 \times_z a_1$ and $p'' = p_2'' \times_v a_2$ (we use the symbols \times_z and \times_v to distinguish the product representation of the X_j^3, Y_{jk}^3, Z_m^3 's from that of V_{\star}^3); denote $\zeta(p_2'')$ by p_2 ; now, if $p \notin A_{\star}^3$, let $p_1'' = \zeta^{-1}(p_1)$, and if $p \in A_{\star}^3$ let p_1'' be that point in $\zeta^{-1}(p_1)$ that lies in the same connected component of $\zeta^{-1}(A_{\star}^3)$ as p'' . Then there is a point q in $X_j^2 \cap V_{\star}^2, Y_{jk}^2 \cap V_{\star}^2$, or $Z_m^2 \cap V_{\star}^2$, respectively, and there is a point q'' in $\zeta^{-1}(q)$ such that $p_1'' = q'' \times_v a_2$ and $p_2 = q \times_z a_1$.

8. H^3 is a Heegaard-handlebody in M^3 . We denote the connected components of $K^2 - \circ H^3$ by $K_{\star 1}^2, \dots, K_{\star b}^2$. Note that these are disks (because of (1) in Lemma 1).

LEMMA 3. H^3 is a Heegaard-handlebody in M^3 , and more in detail we have:

(a) $\cdot[H^3 - (U_{j=1}^s X_j^3 + U_{j,k=1}^{s,t_j} Y_{jk}^3 + U_{m=u_A+1}^v Z_m^3)]$ is a 3-cell, say W^3 , i.e., H^3 is a handlebody, the disks X_j^3, Y_{jk}^3, Z_m^3 form a complete system of meridian disks of H^3 , and the genus a of H^3 is equal to

$$s + \sum_{j=1}^s t_j + (v - u_A) = v + s;$$

(b) the connected components of $M^3 - (H^3 + K^2)$ are open 3-cells, i.e., $M^3 - \circ H^3$ is a handlebody, the disks $K_{\star 1}^2, \dots, K_{\star b}^2$ contain a complete system of meridian disks of $M^3 - \circ H^3$, and $b \geq a$.

Proof of (a). Let $T_{\wedge}^{\prime 3}$ be a handlebody of genus r , disjoint from M^3 , such that

$$T_{\wedge}^{\prime 3} \cap V_{\wedge}^3 = \cdot T_{\wedge}^{\prime 3} \cap \cdot V_{\star}^3 = \cdot V_{\star}^{\prime 2} \times I_v^1,$$

such that $T_{\wedge}^{\prime 3} + V_{\star}^3$ is a 3-cell, denoted by $H^{\prime 3}$, and such that there is a map $\xi : H^{\prime 3} \rightarrow H^3$ of $H^{\prime 3}$ onto H^3 with $\xi|V_{\star}^3 = \zeta$ and with $\xi|T_{\wedge}^{\prime 3}$ a homeomorphism of $T_{\wedge}^{\prime 3}$ onto T_{\wedge}^3 .

The connected components of

$$\cdot[H^{\prime 3} - \xi^{-1}(U_{j=1}^s X_j^3 + U_{j,k=1}^{s,t_j} Y_{jk}^3 + U_{m=u_A+1}^v Z_m^3)]$$

are 3-cells; we may denote them by $H_0^{\prime 3}, H_{A^{\prime}jl}^{\prime 3}, H_{Y^{\prime}jk}^{\prime 3}, H_{Y^{\prime}jk}^{\prime 3}, H_{Z_m}^{\prime 3}$ ($j = 1, \dots, s; k = 1, \dots, t_j; l = 1, \dots, t_j + 1; m = u_A + 1, \dots, v$) such that (compare Fig. 12) $H_{A^{\prime}jl}^{\prime 3} \cap A_{*j}^{\prime 1}$ is an arc in $A_{jl}^{\prime 1}$, $H_{Y^{\prime}jk}^{\prime 3}$ contains $V_{Y^{\prime}jk}^{\prime 2}$, $H_{Y^{\prime}jk}^{\prime 3}$ contains $V_{Y^{\prime}jk}^{\prime 2}$, and $H_{Z_m}^{\prime 3}$ contains $V_{Z_m}^{\prime 2}$. The restrictions

$$\xi \mid H_0^{\prime 3}, \quad \xi \mid \bigcup_{j,k=1}^{s,t_j} H_{Y^{\prime}jk}^{\prime 3}, \quad \xi \mid \bigcup_{j,k=1}^{s,t_j} H_{Y^{\prime}jk}^{\prime 3},$$

$$\xi \mid (\bigcup_{j,l=1}^{s,t_j+1} H_{A^{\prime}jl}^{\prime 3} + \bigcup_{m=u_A+1}^v H_{Z_m}^{\prime 3})$$

are homeomorphisms.

Now $\xi(H_{Y^{\prime}jk}^{\prime 3}) + \xi(H_{Y^{\prime}jk}^{\prime 3})$ ($j = 1, \dots, s; k = 1, \dots, t_j$) are pairwise disjoint 3-cells, say H_{Yjk}^3 , and

$$\xi(H_0^{\prime 3}) + \bigcup_{j,l=1}^{s,t_j+1} \xi(H_{A^{\prime}jl}^{\prime 3}) + \bigcup_{m=u_A+1}^v \xi(H_{Z_m}^{\prime 3})$$

is a 3-cell, say H_{00}^3 , where

$$H_{00}^3 \cap H_{Yjk}^3 = V_{Y^{\prime}jk}^3 + V_{Y^{\prime}jk}^3.$$

Now $H_{00}^3 + \bigcup_{j,k=1}^{s,t_j} H_{Yjk}^3$ is a 3-cell and is equal to

$$-[H^3 - (\bigcup_{j=1}^s X_j^3 + \bigcup_{j,k=1}^{t_j} Y_{jk}^3 + \bigcup_{m=u_A+1}^v Z_m^3)]$$

which proves (a).

Proof of (b). First we prove that the first homology group $\mathcal{H}_1(H^3 + K^2)$ is trivial: We denote by $\alpha_{X_j}, \alpha_{Y_{jk}}, \alpha_{Z_m}$ ($j = 1, \dots, s; k = 1, \dots, t_j; m = u_A + 1, \dots, v$) those elements of $\mathcal{H}_1(H^3)$ which correspond to piercings of X_j^2, Y_{jk}^2, Z_m^2 , respectively (i.e., α_{X_1} may be represented by an oriented simple closed curve in H^3 that intersects X_1^2 in just one prismatical arc with induced orientation in the direction of increasing x_Z , and that is disjoint from X_2^2, \dots, X_s^2 , and from the Y_{jk}^2 's and Z_m^2 's; etc.). The α 's form a basis of $\mathcal{H}_1(H^3)$. Let α be the inclusion map $H^3 \subset H^3 + K^2$ and let

$$\alpha_* : \mathcal{H}_1(H^3) \rightarrow \mathcal{H}_1(H^3 + K^2)$$

be induced by α , then the $\alpha_*(\alpha)$'s form a basis of $\mathcal{H}_1(H^3 + K^2)$. Now the properly oriented boundary $\cdot K_{j1}^{\rightarrow 2}$ of K_{j1}^2 (Sec. 6) belongs to $\alpha_{Y_{j1}}$, further $\cdot K_{jk}^{\rightarrow 2}$ belongs to $\alpha_{Y_{jk}} - \alpha_{Y_{j,k-1}}$ for all $k = 2, \dots, t_j$, and finally $\cdot K_{jt_j+1}^{\rightarrow 2}$ belongs to $\alpha_{X_j} + \alpha_{Y_{jt_j}}$ (compare the more detailed discussion of the $\cdot K_{jk}^{\rightarrow 2}$'s in Sec. 10.1); hence

$$\alpha_*(\alpha_{Y_{j1}}) = \dots = \alpha_*(\alpha_{Y_{jt_j}}) = \alpha_*(\alpha_{X_j}) = 0$$

where 0 means the zero-element of $\mathcal{H}_1(H^3 + K^2)$. Similarly, $\cdot K_m^{\rightarrow 2}$ ($m = u_A + 1, \dots, v$) belongs (compare Fig. 9) either to $\alpha_{Z_m} - \alpha_{Z_{\lambda(m)}}$ (where $u_A < \lambda(m) < m$, see Sec. 5) or to $\alpha_{Z_m} + \flat$ with $\alpha_*(\flat) = 0$; hence

$$\alpha_*(\alpha_{Z_{u_A+1}}) = \dots = \alpha_*(\alpha_{Z_v}) = 0,$$

i.e., $\mathcal{H}_1(H^3 + K^2)$ is trivial, Q.E.D.

Let $K_{*1}^3, \dots, K_{*b}^3$ be pairwise disjoint, small neighborhoods of $K_{*1}^2, \dots,$

K_{*b}^2 , respectively, in $M^3 - \circ H^3$. Then $H^3 + \cup_{i=1}^b K_{*i}^3$ is a 3-manifold with trivial first homology group (since $H^3 + \cup_{i=1}^b K_{*i}^3$ collapses to $H^3 + K^2$), hence $(H^3 + \cup_{i=1}^b K_{*i}^3)$ consists of 2-spheres only (see [7, §64]); but these 2-spheres lie in the handlebody $M^3 - \circ T^3$, and therefore, as a consequence of the Alexander theorem [2], bound 3-cells in $M^3 - \circ T^3$. Therefore $M^3 - (H^3 + \cup_{i=1}^b K_{*i}^3)$ consists of open 3-cells, and hence $M^3 - (H^3 + K^2)$ consists of open 3-cells. This proves (b).

9. Constructing the cell-decomposition Ψ of M^3 . We take for Ψ a cell-decomposition of M^3 , corresponding to the Heegaard-handlebody H^3 with the two systems

$$\{X_j^2, Y_{jk}^2, Z_m^2\}, \quad \{K_{*i}^2\}$$

of meridian disks (compare [5, Sec. 8]):

For the only vertex of Ψ we choose a point O in $\circ W^3$. For the 1-dimensional elements of Ψ we choose pairwise disjoint, open arcs $E_{X_j}^{*1}, E_{Y_{jk}}^{*1}, E_{Z_m}^{*1}$ in $\circ H^3$ with common boundary O such that H^3 is a neighborhood of the 1-skeleton G^{*1} of Ψ , and such that $E_{X_j}^{*1}$ intersects X_j^3 in just one prismatical arc and is disjoint from $X_1^3, \dots, X_{j-1}^3, X_{j+1}^3, \dots, X_s^3$, from the Y^3 's, and from the Z^3 's; etc. For the 2-dimensional elements of Ψ we choose pairwise disjoint, open disks $E_1^{*2}, \dots, E_b^{*2}$ in $M^3 - G^{*1}$ such that

$$E_i^{*2} \cap (M^3 - \circ H^3) = K_{*i}^2, \quad E_i^{*2} \subset G^{*1},$$

and such that $E_i^{*2} \cap \circ H^3$ is an open annulus, say $E_{H^i}^{*2}$ which intersects X_j^3, Y_{jk}^3, Z_m^3 prismatically with respect to x_Z so that X_j^2, Y_{jk}^2, Z_m^2 are intersected (at most) in open arcs each of which joins G^{*1} to H^3 . For the 3-dimensional elements of Ψ we take the connected components of $M^3 - \cup_{i=1}^b \bar{E}_i^{*2}$.

We choose a coherent orientation of G^{*1} so that in $E_{X_j}^{*1} \cap X_j^3, E_{Y_{jk}}^{*1} \cap Y_{jk}^3, E_{Z_m}^{*1} \cap Z_m^3$ the direction of $E_{X_j}^{*1}, E_{Y_{jk}}^{*1}, E_{Z_m}^{*1}$, respectively, coincides with the direction of increasing x_Z ; then we associate generators $g_{X_j}, g_{Y_{jk}}, g_{Z_m}$ of $\pi_1(M^3)$ with the so oriented 1-spheres $\bar{E}_{X_j}^{*1}, \bar{E}_{Y_{jk}}^{*1}, \bar{E}_{Z_m}^{*1}$, respectively, (with base point O). Now we may read relators r_1, \dots, r_b from the 2-elements $E_1^{*2}, \dots, E_b^{*2}$, respectively, and we denote the presentation

$$(\{g_{X_j}, g_{Y_{jk}}, g_{Z_m}\}, \{r_i\})$$

of $\pi_1(M^3)$ by $\mathfrak{P}(\Psi)$.

10. Relator-diagrams corresponding to the presentation $\mathfrak{P}(\Psi)$ of $\pi_1(M^3)$. We map the disks K_{jk}^2, K_m^2 ($j = 1, \dots, s; k = 1, \dots, t_j; m = u_A + 1, \dots, v$; see Sec. 5 and Fig. 9) onto pairwise disjoint disks R_{jk}^2, R_m^2 , respectively, (see Fig. 13 which corresponds to Fig. 9 if one assumes that $m > u, p_{i_3} = p_{j_2}$, and $t_j = 2$, compare Fig. 12), by means of maps

$$\kappa_{jk} : K_{jk}^2 \rightarrow R_{jk}^2, \quad \kappa_m : K_m^2 \rightarrow R_m^2,$$

respectively⁸, such that:

- (i) the restrictions of κ_{jk} , κ_m to the open disks $\overset{\circ}{K}_{*i}^2$ ($i = 1, \dots, b$) are homeomorphisms;
- (ii) κ_{jk} , κ_m map each connected component of $K_{jk}^2 \cap W^3$, $K_m^2 \cap W^3$, respectively, into a single point;
- (iii) if L is a connected component of the intersection of K_{jk}^2 or K_m^2 with $X_h^3 - \overset{\circ}{W}^3$, $Y_{hl}^3 - \overset{\circ}{W}^3$, or $Z_q^3 - \overset{\circ}{W}^3$, then κ_{jk} or κ_m , respectively, maps L onto an open arc in such a way that all points with the same x_Z -coordinate have the same image point (but points with different x_Z -coordinates map always into different points).

If L as in (iii) then we orientate the image $\kappa_{jk}(L)$ or $\kappa_m(L)$, respectively, according to the direction of increasing x_Z , and we associate it with the generator g_{Xh} , g_{Yjk} , g_{Zq} , respectively.

We consider the cell-decompositions Θ_{jk} , Θ_m of R_{jk}^2 , R_m^2 , respectively, into the connected components of the images of $K_{jk}^2 \cap \overset{\circ}{K}_{*i}^2$, $K_{jk}^2 \cap W^3$, $K_{jk}^2 \cap (X_h^3 - \overset{\circ}{W}^3)$, etc., etc. From each 2-dimensional element of Θ_{jk} or Θ_m we may read the relator r_i that is associated with the inverse image disk K_{*i}^2 . We call the decomposition Θ_{jk} or Θ_m , together with the association of its oriented edges to the generators g and of its 2-elements to the relators r (see Fig. 13) a *relator-diagram corresponding to* $\mathfrak{B}(\Psi)$ and we denote it by \mathfrak{R}_{jk} or \mathfrak{R}_m , respectively. From the boundary of R_{jk}^2 or R_m^2 we may read a word $r_{jk}^{\#}$ or $r_m^{\#}$, respectively, in the generators g (where all members of the cyclic class $\langle r_{jk}^{\#} \rangle$ or $\langle r_m^{\#} \rangle$, respectively, are equivalent). Now the relator-diagram \mathfrak{R}_{jk} shows that² $r_{jk}^{\#} = 1$ is a true relation in the group $\pi_1(M^3)$; etc. Diagrams like these have been used by E. R. Van Kampen and other authors; see for instance [8].

For the proof of the theorem we shall need some special properties of our relator-diagrams \mathfrak{R} :

(10.1) By inspection of the curves $\overset{\circ}{K}_{jk}^2$ and $\overset{\circ}{K}_m^2$ we see that we can write for all $j = 1, \dots, s$; $m = u_A + 1, \dots, v$ (compare Fig. 12):

$$\begin{aligned}
 r_{j1}^{\#} &= g_{Yj1} e_{j1} \\
 r_{jk}^{\#} &= g_{Yjk} g_{Yjk-1}^{-1} e_{jk} \quad (\text{for all } k = 2, \dots, t_j) \\
 r_{jt_j+1}^{\#} &= g_{Xj} e_{jt_j+1} g_{Yjt_j} e_{jt_j+1}^{\#} \\
 r_m^{\#} &= g_{Zm} e_m && \text{if } J_m^1 \text{ joins } p_m \text{ to } \overset{\circ}{V}_*^2 \\
 (\ast) \quad &= g_{Zm} e_m^{\#} g_{Xj_m}^{-1} e_m && \text{if } J_m^1 \text{ joins } p_m \text{ to } \overset{\circ}{V}_{X'j_m}^2 \\
 &= g_{Zm} e_m^{\#} g_{Xj_m} e_m && \text{if } J_m^1 \text{ joins } p_m \text{ to } \overset{\circ}{V}_{X''j_m}^2 \\
 &= g_{Zm} e_m^{\#} g_{Xj_m}^{-1} e_m^{\#} g_{Yj_mk_m}^{-1} e_m && \text{if } J_m^1 \text{ joins } p_m \text{ to } p_{j_mk_m} \text{ and meets} \\
 & && \overset{\circ}{V}_{Y'j_mk_m}^2
 \end{aligned}$$

⁸ These maps are not semilinear, but can be taken piecewise algebraic.

$$\begin{aligned}
 &= g_{Zm} e_m^\# g_{Yjm^k}^{-1} e_m && \text{if } J_m^1 \text{ joins } p_m \text{ to } p_{jm^k} \text{ and meets} \\
 & && \cdot V_{Y^j m^k}^2 \\
 &= g_{Zm} e_m^\# g_{Z\lambda(m)}^{-1} e_m && \text{if } J_m^1 \text{ joins } p_m \text{ to } p_{\lambda(m)} \text{ (case of Fig.} \\
 & && \text{13),}
 \end{aligned}$$

where the e 's are words in the g 's that are either empty or cancel to the empty word by repeated deleting of syllables g_{\vee}^{-1} (\vee stands for Xc , Ycd , or Ze ; $c = 1, \dots, s$; $d = 1, \dots, t_c$; $e = u_A + 1, \dots, v$).

More in detail: The e 's are products of syllables of

Type a.

$$g_{Xh}^{-1} g_{Yh}^{-1} g_{Yh1} \cdots g_{Yht_h}^{-1} g_{Yht_h} g_{Yht_h}^{-1} g_{Yht_h} \cdots g_{Yh1}^{-1} g_{Yh1} g_{Xh}$$

which occur in e_{\sim} (\sim stands for a pair of indices jk or a single index m), corresponding to the intersections $K_{T\sim}^1 \cap \cdot V_{X^h}^2$ (compare Fig. 12) and of

Type b. $g_{\vee}^{-1} g_{\vee}$, but not $g_{Xc}^{-1} g_{Xc}$ for any $c = 1, \dots, s$, which occur in e_{\sim} , $e_{\sim}^\#$, $e_{\sim}^{\#\#}$ corresponding to the intersections $K_{T\vee}^1 \cap \cdot V_{\vee}^2$ and $K_{V\sim}^1 \cap \cdot B_{\vee}^2$ (where T_{Ycd}^2 , B_{Ycd}^2 stand for

$$T_{Y'(cd)}^2 + T_{Y''(cd)}^2 + T_{Y'''(cd)}^2, \quad B_{Y'(cd)}^2 + B_{Y''(cd)}^2 + B_{Y'''(cd)}^2,$$

respectively).

We always have

$$e_{j^t j^{t+1}}^\# = g_{Yj^t}^{-1} g_{Yj^t} \cdots g_{Yj^1}^{-1} g_{Yj^1}$$

and

$$e_m^{\#\#} = g_{Yj_{m1}}^{-1} g_{Yj_{m1}} \cdots g_{Yj_{m^{k_m-1}}}^{-1} g_{Yj_{m^{k_m-1}}}$$

The relations² $r^{\#\#} = 1$ show obviously that $\pi_1(M^8)$ is the trivial group.

(10.2) It is essential that the decompositions Θ_{\sim} are especially simple: The 1-skeleton of Θ_{\sim} intersects $\circ R_{\sim}^2$ in pairwise disjoint open arcs with boundaries in $\cdot R_{\sim}^2$ (see Fig. 13); we denote these open arcs (in all the $\circ R_{\sim}^2$'s) by Q_1^1, \dots, Q_w^1 ; the \bar{Q}_f^1 's ($f = 1, \dots, w$) are the images of the connected components of $\circ K_{\sim}^2 \cap V_{\sim}^2$ under κ_{\sim} (where these components are open arcs, say P_1^1, \dots, P_w^1 , with boundaries in $K_{T\sim}^1$ such that either

$$\bar{P}_{f_1}^1 = \bar{P}_{f_2}^1 \quad \text{or} \quad \bar{P}_{f_1}^1 \cap \bar{P}_{f_2}^1 = \emptyset$$

if $f_1, f_2 \in \{1, \dots, w\}$). We denote the words corresponding to Q_1^1, \dots, Q_w^1 by q_1, \dots, q_w , respectively. In detail, we have the following five types of words q_f (corresponding to six types of arcs \bar{P}_f^1 ; $f = 1, \dots, w$):

(Type 1) $q_f = g_{Zl} e_{Qf} g_{Zm}^{-1}$ if P_f^1 joins $\cdot V_{Zl}^2$ to $\cdot V_{Zm}^2$ ($m \neq 1$)

(Type 2) $q_f = g_{Xj} e_{Qf} g_{Zm}^{-1}$ if P_f^1 joins $\cdot V_{X^j}^2$ to $\cdot V_{Zm}^2$

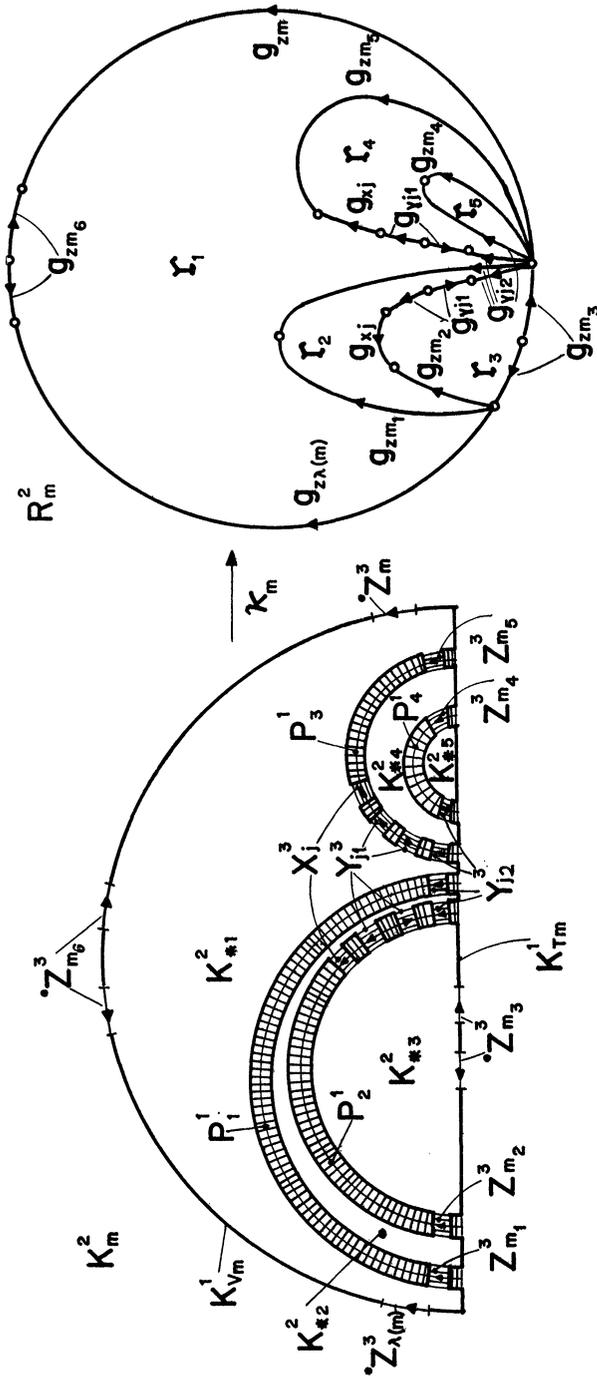


FIG.13 $K_m^2 \cdot W^3$ is drawn heavy;
the arrows indicate x_z ;

$$\begin{aligned}
 Q_1 &= g_{y12} g_{zm_1}^{-1} (\mathcal{E}_{\alpha_1} \text{ empty}) \\
 Q_2 &= g_{y12} g_{y1i}^{-1} g_{yij} g_{xj} g_{zm_2}^{-1} \\
 Q_3 &= g_{y12} g_{y1i}^{-1} g_{yij} g_{xj} g_{zm_3}^{-1} \\
 Q_4 &= g_{y12} g_{y1i}^{-1} g_{yij} g_{xj} g_{zm_4}^{-1} \\
 \Gamma_1 &= g_{zm} g_{zm_6}^{-1} g_{zm_6} g_{z\lambda(m)} g_{zm_1} g_{y12} g_{y1i}^{-1} g_{yij} g_{xj} g_{zm_5}^{-1} \\
 \Gamma_2 &= g_{zm_2} g_{xj}^{-1} g_{y1i}^{-1} g_{yij} g_{y12} g_{y1i}^{-1} g_{yij} g_{zm_1}^{-1} \\
 \Gamma_3 &= g_{y12} g_{y1i}^{-1} g_{yij} g_{xj} g_{zm_2} g_{zm_3} g_{zm_3}^{-1} \\
 \Gamma_4 &= g_{zm_5} g_{xj}^{-1} g_{y1i}^{-1} g_{yij} g_{y12} g_{y1i}^{-1} g_{yij} g_{zm_4}^{-1} \\
 \Gamma_5 &= g_{zm_4} g_{y12}^{-1} \\
 \Gamma_m^{\#} &= g_{zm} g_{zm_6}^{-1} g_{zm_6} g_{z\lambda(m)} g_{zm_1}^{-1} g_{zm_3} g_{zm_3}^{-1}
 \end{aligned}$$

(Type 3) $q_f = e_{Q_f} g_{Z_m}^{-1}$ if P_f^1 joins $V_{X^*j}^2$ to $V_{Z_m}^2$ (for some $j = 1, \dots, s$)

or if P_f^1 joins V_*^2 to $V_{Z_m}^2$

(Type 4) $q_f = g_{Xjk} e_{Q_f} g_{Z_m}^{-1}$ if P_f^1 joins $V_{Y^*k}^2$ to $V_{Z_m}^2(P_1^1, P_4^1$ in Fig. 13)

(Type 5) $q_f = g_{Xjk} e_{Q_f}^{\#} g_{Xj} e_{Q_f} g_{Z_m}^{-1}$ if P_f^1 joins $V_{Y^*jk}^2$ to $V_{Z_m}^2(P_2^1, P_3^1$ in Fig. 13)

where e_{Q_f} and $e_{Q_f}^{\#}$ are products of syllables $g_{\downarrow}^{-1} g_{\downarrow}$ which correspond to the intersections of P_f^1 with B_{\downarrow}^1 . We do not have more than these six types of arcs P_f^1 since it follows from the property (2b) of Δ (Lemma 1, Sec. 3) that at least one boundary point of P_f^1 lies in the boundary of a disk $V_{Z_m}^2$. It is remarkable that the word q_f cancels down to a word of length either 1 (Type 3), or 2 (Types 1, 2, 4), or 3 (Type 5).

(10.3) If there are two (or three) edges of Θ_{\sim} in R_{\sim}^2 that do not correspond to parts of e_{\sim} , $e_{\sim}^{\#}$, or $e_{\sim}^{\#\#}$ in $(\#)$ then (any two of) these edges are not separated by the Q_f^1 's in R_{\sim}^2 . Similarly, if two edges in R_{\sim}^2 correspond to a syllable $g_{\downarrow}^{-1} g_{\downarrow}$ of Type b in e_{\sim} , $e_{\sim}^{\#}$, or $e_{\sim}^{\#\#}$ then these edges are not separated by the Q_f^1 's in R_{\sim}^2 .

(10.4) Another essential property of the relator-diagrams \mathfrak{R}_{\sim} is the following: if i is a fixed integer, $1 \leq i \leq b$, then the decompositions Θ_{jk} , Θ_l ($j = 1, \dots, s; k = 1, \dots, t_j + 1; l = u_A + 1, \dots, u$) contain all together just one 2-dimensional element that is associated with⁹ the relator r_i . However, the decompositions $\Theta_{u+1}, \dots, \Theta_v$ may contain some more 2-dimensional elements associated with r_i ; but in this case, if Θ_{\approx} (where \approx stands for two fixed indices $j_0 k_0$ or for one fixed index l_0 with $u_A < l_0 \leq u$) and Θ_m ($u < m \leq v$) each contain an element associated with r_i , then Θ_m is isomorphic to a "part" of Θ_{\approx} , i.e., we have $K_m^2 \subset K_{\approx}^2$ and there exists a homeomorphism

$$\alpha_m : R_m^2 \rightarrow R_{\approx}^2$$

of R_m^2 into R_{\approx}^2 such that $\{\kappa_m = \alpha_m^{-1} \cdot (\kappa_{\approx} | K_m^2)\}$, where α_m carries elements of Θ_m onto elements of Θ_{\approx} , preserving the association of these elements to the g 's and r 's. Moreover, $\alpha_m(R_m^2)$ intersects R_{\approx}^2 in just one of the open arcs Q_f^1 .

11. Conclusion. It remains to show that the presentation $\mathfrak{B}(\Psi)$ can be transformed into $(\{g_{\downarrow}\}, \{g_{\downarrow}, *^{b-a}\})$ by cancellation operations as asserted in the theorem. Guided by the relator-diagrams we first transform $\mathfrak{B}(\Psi)$ into a presentation whose relators are derived from the $r_{\sim}^{\#}$'s by deleting all the cancellation words $e, e^{\#}, e^{\#\#}$. The rest is obvious.

Step i. Removing the cancellation syllables of Type a from the $r_{\sim}^{\#}$'s (see Fig.

⁹ Of course, there may be other 2-elements associated with relators, say r_{i_1}, r_{i_2}, \dots , such that $r_{i_1} = r_{i_2} = \dots = r_i$ (letter by letter), but then i_1, i_2, \dots, i are pairwise distinct.

14). We transform the relator-diagrams \mathfrak{R}_\sim in the following way:

Let P_d^1 be an open arc in ${}^{\circ}K_\sim^2 \cap V_\sim^2$ [\sim stands, as in (10.4), for j_0k_0 or l_0 ; $j_0 = 1, \dots, s; k_0 = 1, \dots, t_{j_0} + 1; l_0 = u_\Delta + 1, \dots, u$] that joins a point, say p , in ${}^{\circ}V_{x'j}^2$ to a point in ${}^{\circ}V_{ze}^2$. Then $\kappa_\sim(P_d^1)$ is an arc Q_d^1 in R_\sim^2 , corresponding to a word $q_d = e_{Q_d} g_{ze}^{-1}$ of Type 3 as considered in (10.2). From $\kappa_\sim(p)$ there originate two arcs, say $N_\rightarrow^1, N_\leftarrow^1$, in R_\sim^2 , that correspond (if oriented towards $\kappa_\sim(p)$) to the same word

$$n = g_{xj}^{-1} g_{yjl}^{-1} g_{yjl} \cdots g_{yjt}^{-1} g_{yjt}$$

where nm^{-1} is a syllable of Type a in e_\sim as discussed in (10.1)). Now we replace R_\sim^2 by a disk R_\sim^{*2} corresponding to an identification of N_\rightarrow^1 to N_\leftarrow^1 , i.e., so that there is a map β_\sim of R_\sim^2 onto R_\sim^{*2} which is one-to-one on $R_\sim^2 - (N_\rightarrow^1 + N_\leftarrow^1)$, on N_\rightarrow^1 , and on N_\leftarrow^1 , which maps N_\rightarrow^1 and N_\leftarrow^1 onto the same arc N^1 , and which maps the elements of Θ_\sim onto elements of a cell-decomposition Θ_\sim^* of R_\sim^{*2} (where R_\sim^{*2} is disjoint from M^3 and from the R^2 's). We replace \mathfrak{R}_\sim by the relator-diagram \mathfrak{R}_\sim^* (consisting of Θ_\sim^* and the association of its 1- and 2-elements to the g 's and r 's as carried over by β_\sim). We denote the open arc $[\beta_\sim(Q_d^1) + N^1]$ by Q_d^{*1} and $\beta_\sim(Q_f^1)$ by Q_f^{*1} for all $Q_f^1 \subset R_\sim^2$ ($f = 1 \cdots, w; f \neq d$); then to Q_d^{*1} there corresponds the word

$$q_d^* = nq_d = g_{xj}^{-1} g_{yjl}^{-1} g_{yjl} \cdots g_{yjt}^{-1} g_{yjt} e_{Q_d} g_{ze}^{-1}$$

let us call this "of Type 3* ". To R_\sim^{*2} there corresponds a word $r_\sim^{*#}$ that is obtained from r_\sim^* by deleting a syllable nm^{-1} . We remark that \mathfrak{R}_\sim^* is a relator-diagram corresponding to $\mathfrak{F}(\Psi)$ and that \mathfrak{R}_\sim^* has also the properties stated for \mathfrak{R}_\sim in (10.3).

We carry out the above procedure for all those disks K_m^2 that contain the open arc P_d^1 ; (these disks K_m^2 lie in K_\sim^2 , and $m > u$). We denote the corresponding maps by $\beta_m : R_m^2 \rightarrow R_m^{*2}$, and the relator-diagrams and decompositions so obtained by \mathfrak{R}_m^* and Θ_m^* , respectively. If K_\sim^2 [\sim stands for jk or m as in Sec. 10] does not contain P_d^1 then we simply denote the identity map on R_\sim^2 by β_\sim , and $\mathfrak{R}_\sim, R_\sim^2, \Theta_\sim$ by $\mathfrak{R}_\sim^*, R_\sim^{*2}, \Theta_\sim^*$, respectively; etc. Now the relator-diagrams \mathfrak{R}_m^* have again the property stated in (10.4): We obtain the required homeomorphisms α_m^* ($m = u + 1, \dots, v$) by taking

$$\begin{aligned} \alpha_m^* &= \alpha_m \quad \text{if } K_m^2 \not\subset K_\sim^2 \\ &= \beta_\sim \alpha_m \beta_m^{-1} \quad \text{if } K_m^2 \subset K_\sim^2 \end{aligned} \quad (\text{see Fig. 14}),$$

where we assume that β_m has been chosen in such a way that if two points p_1, p_2 of R_\sim^2 have the same image point under β_\sim then $\alpha_m^{-1}(p_1)$ and $\alpha_m^{-1}(p_2)$ have the same image point under β_m .

We carry out the procedure described in the above two paragraphs for all P_d^1 's of the type considered and we obtain in this way relator-diagrams \mathfrak{R}^I corresponding to $\mathfrak{F}(\Psi)$. (We use the notation $R_\sim^{I2}, \Theta_\sim^I, Q_f^I, r_\sim^{I\#}, \alpha_m^I$, etc., for the disks, decompositions, etc., of the \mathfrak{R}^I 's.) The words $r_\sim^{I\#}$ are still of

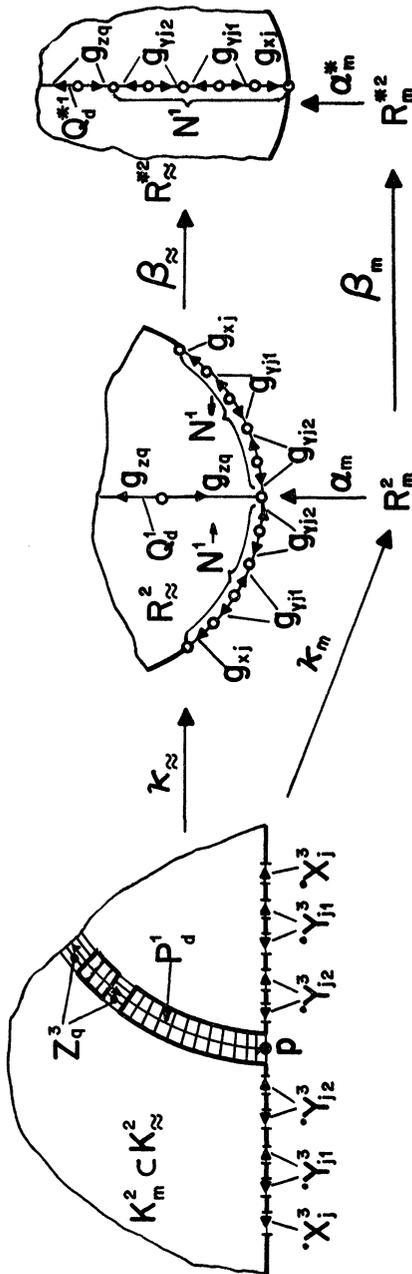


FIG. 14

the form $(*)$, but we have the following essential simplification: all the cancellation words $e_{\sim}^I, e_{\sim}^{I\#}, e_{\sim}^{I\#\#}$ are products of syllables $g_{\sim}^{-1}g_{\sim}$ of Type b in such a way that both edges in R_{\sim}^{I2} that correspond to such a syllable lie in the boundary of the same 2-dimensional element of Θ_{\sim}^I (since all syllables of Type a have been deleted, but (10.3) has been preserved). The \mathfrak{R}_{\sim}^I 's have also the property (10.2), modified by admitting q 's of Type 3*, and the properties (10.3) and (10.4).

Step ii. "Outer" cancellations (see Fig. 15). We consider an arc, say L^1 , in R_{\sim}^{I2} (\sim stands again for j_0k_0 or l_0) that corresponds to a syllable $g_{\sim}^{-1}g_{\sim}$ of Type b in $e_{\sim}^I, e_{\sim}^{I\#},$ or $e_{\sim}^{I\#\#}$. Because of (10.3) all of L^1 lies in the boundary of just one 2-dimensional element of Θ_{\sim}^I corresponding to a relator, say r_{i_0} ($i_0 = 1, \dots, b$). So we may cancel the corresponding syllable $g_{\sim}^{-1}g_{\sim}$ in r_{i_0} (cancellation operation of Type 1) which yields a new relator, say $r_{i_0}^{I*}$ and a new presentation

$$\mathfrak{P}^{I*} = (\{g_{xj}, g_{xjk}, g_{zm}\}, \{r_i^{I*}\})$$

where $r_i^{I*} = r_i$ if $i \neq i_0$.

Now we replace R_{\sim}^{I2} by a disk R_{\sim}^{I*2} corresponding to shrinking L^1 to one point, i.e., so that there is a map β_{\sim}^{I*} of R_{\sim}^{I2} onto R_{\sim}^{I*2} which¹⁰ is one-to-one on $R_{\sim}^{I2} - L^1$, which maps L^1 into one point, and which maps the elements of Θ^I onto elements of a cell-decomposition Θ_{\sim}^{I*} of R_{\sim}^{I*2} . Now \mathfrak{R}_{\sim}^{I*} (consisting of Θ_{\sim}^{I*} and the association of its 1- and 2-elements to the g 's and r^{I*} 's as induced by β_{\sim}^{I*}) is a relator-diagram corresponding to \mathfrak{P}^{I*} (since by (10.4) r_{i_0} occurs just once in Θ_{\sim}^I). In the same way we replace all those relator-diagrams \mathfrak{R}_m^I whose decompositions Θ_m^I contain a 2-element associated with r_{i_0} by relator-diagrams \mathfrak{R}_m^{I*} (defined by maps $\beta_m^{I*} : R_m^{I2} \rightarrow R_m^{I*2}$ that map the arcs $(\alpha_m^I)^{-1}(L^1)$ into single points). For the remaining \mathfrak{R}_{\sim}^I 's we take β_{\sim}^{I*} to be the identity on R_{\sim}^{I2} , and we take $\mathfrak{R}_{\sim}^{I*} = \mathfrak{R}_{\sim}^I$, etc. Then the \mathfrak{R}_{\sim}^{I*} 's are relator-diagrams corresponding to \mathfrak{P}^{I*} and possess the properties (10.1), (10.2, modified by admitting q^{I*} 's of Type 3*), (10.3), and (10.4).

We carry out the above procedure for all arcs of the considered type, and we obtain in this way (by cancellation operations of Type 1) a presentation

$$\mathfrak{P}^{II} = (\{g_{xj}, g_{xjk}, g_{zm}\}, \{r_i^{II}\})$$

and corresponding relator-diagrams \mathfrak{R}^{II} . (We use the notation $Q_j^{III}, r_{\sim}^{III\#}, \alpha_m^{III}$, etc., in the obvious way.) Now the cancellation words $e_{\sim}^{II}, e_{\sim}^{II\#}, e_{\sim}^{II\#\#}$ are empty, except, may be, if \sim stands for m with $m > u$. Furthermore, the boundaries of all those open arcs Q_j^{III} that lie in some R_{\sim}^{II2} are equal to just one point in R_{\sim}^{II2} (compare Fig. 16).

Step iii. "Inner" cancellations. Now we consider those arcs L^1 in the Q_j^{III} 's that lie in disks R_{\sim}^{II2} and that correspond to syllables $g_{\sim}^{-1}g_{\sim}$. As in Step ii we cancel, step by step, all the corresponding syllables in the r_i^{III} 's (cancellation operations of Type 1), and we obtain in this way a presentation

$$\mathfrak{P}^{III} = (\{g_{xj}, g_{xjk}, g_{zm}\}, \{r_i^{III}\}).$$

¹⁰ These maps are not semilinear, but can be taken piecewise algebraic.

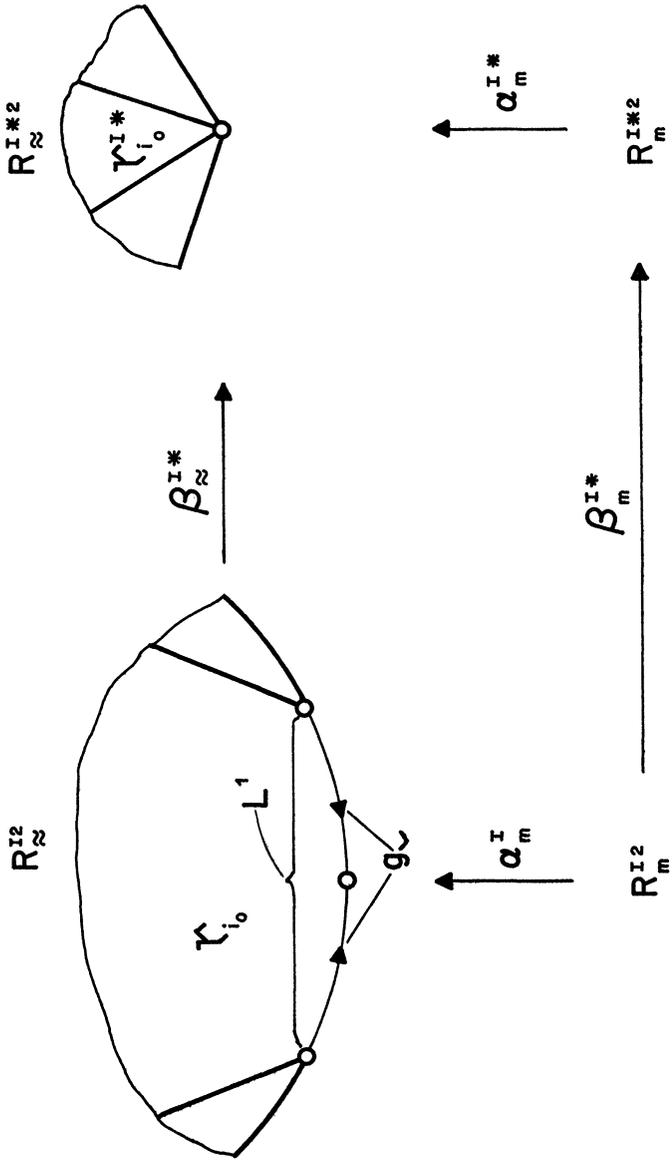


FIG. 15

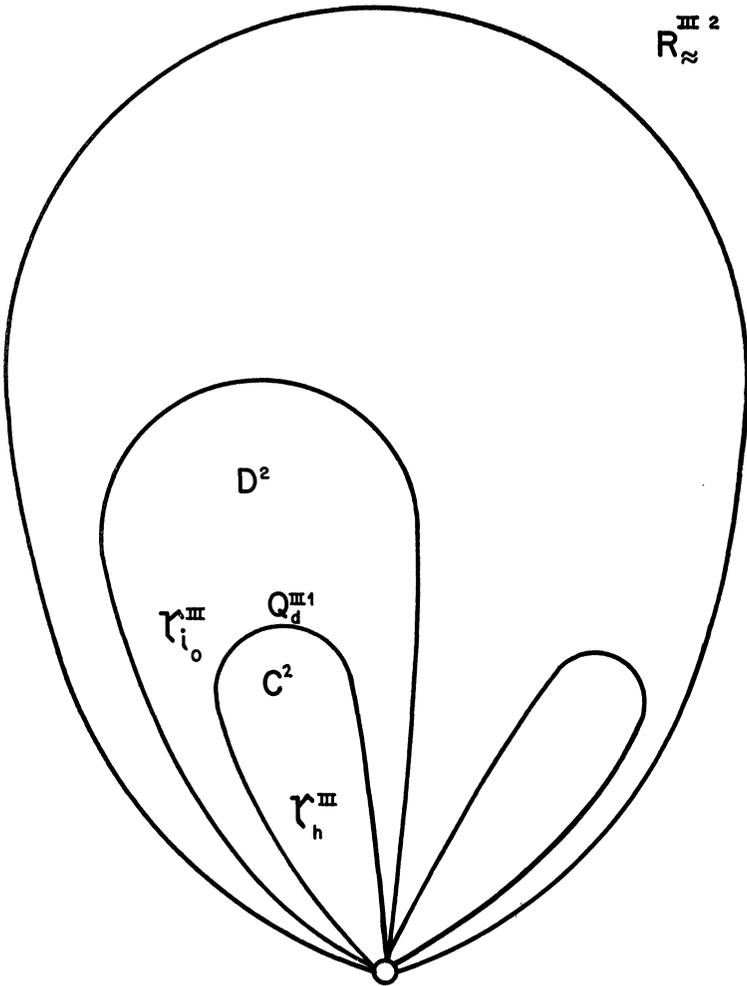


FIG. 16

Then, again as in Step ii, we construct relator-diagrams $\mathfrak{R}_{\approx}^{III}$ and \mathfrak{R}_m^{III} that correspond to \mathfrak{B}^{III} by shrinking arcs to points. (Note that the arcs $(\alpha_m^{II})^{-1}(L^1)$ may lie in R_m^{II2} as well as in R_m^{II2} ($m > u$).) The \mathfrak{R}^{III} 's possess again the properties (10.1), (10.2, modified), (10.3), (10.4).

The words $r_{\approx}^{III\#}$ read from the R^{III2} 's are of the form

$$r_{j1}^{III\#} = g_{xj1} ; \quad r_{jk}^{III\#} = g_{xjk} g_{xjk-1}^{-1} \quad (k = 2, \dots, t_j) ;$$

$$r_{yjt_j+1}^{III\#} = g_{xj} g_{yjt_j} ;$$

$$(III \#) \quad r_m^{III\#} = \text{either } g_{zm}, \text{ or } g_{zm} g_{xj_m}^{\pm 1}, \text{ or } g_{zm} g_{xj_m}^{-1} g_{yjm^k m}^{-1},$$

$$\text{or } g_{zm} g_{yjm^k m}^{-1}, \text{ or } g_{zm} g_{z\lambda(m)}^{-1}, \quad \lambda(m) < m,$$

and the words q_f^{III} ($f = 1, \dots, w$) read from the Q_f^{III} 's are of the form

$$q_f^{III} = \text{either } g_{zi} g_{zm}^{-1}, \text{ or } g_{xj}^{\pm 1} g_{zm}^{-1}, \text{ or } g_{zm}^{-1}, \text{ or } g_{yjk} g_{zm}^{-1}, \text{ or } g_{yjk} g_{xj} g_{zm}^{-1}.$$

Step iv. Deleting Q^1 's (see Fig. 16). Provided that $w \neq 0$ there exists a disk R_{\approx}^{III2} that contains at least one of the open arcs Q_f^{III} . Then there is at least one open arc, say Q_d^{III} that lies in R_{\approx}^{III2} in such a way that \bar{Q}_d^{III} is the boundary of a 2-dimensional element, say C^2 , of Θ_{\approx}^{III} . There is just one other element, say D^2 , of Θ_{\approx}^{III} whose boundary contains \bar{Q}_d^{III} . Let r_h^{III} and $r_{i_0}^{III}$ ($h \neq i_0$) be the relators associated with C^2 and D^2 , respectively; then q_d^{III} is equal to a member of $\langle r_h^{III} \rangle$, and some member of $\langle r_{i_0}^{III} \rangle$ can be written as $(q_d^{III})^{\pm 1} r_{i_0}^{IV}$ (where $r_{i_0}^{IV}$ is some word in the g 's). Now we replace $r_{i_0}^{III}$ by $r_{i_0}^{IV}$ (cancellation operation of Type 2 and of length 1, 2, or 3) and we obtain in this way a presentation \mathfrak{P}^{IV} from \mathfrak{P}^{III} .

Then we construct relator-diagrams $\mathfrak{R}_{\approx}^{IV}$ that correspond to \mathfrak{P}^{IV} as follows: First we delete from Θ_{\approx}^{III} those elements that lie in Q_d^{III} , and we replace the elements C^2, D^2 by the open disk $C^2 + Q_d^{III} + D^2$; this yields Θ_{\approx}^{IV} (where $R_{\approx}^{IV2} = R_{\approx}^{III2}$ and the new 2-dimensional element of Θ_{\approx}^{IV} is associated with $r_{i_0}^{IV}$). If the relator $r_{i_0}^{III}$ is associated with a 2-dimensional element, say D_0^2 , of a decomposition Θ_m^{III} , different from Θ_{\approx}^{III} , then [by (10.4)] $m > u$, and $\alpha_m^{III}(R_m^{III2})$ contains Q_d^{III} in its interior (since otherwise the closed curve \bar{Q}_d^{III} would lie in $\alpha_m^{III}(R_m^{III2})$, but would not be equal to $\alpha_m^{III}(R_m^{III2})$ in contradiction to the fact that $\alpha_m^{III}(R_m^{III2})$ is a disk). Hence $\circ R_m^{III2}$ contains $(\alpha_m^{III})^{-1}(Q_d^{III})$ which is one of the Q_f^{III} 's, say Q_c^{III} , and Θ_m^{III} possesses an element $C_0^2 = (\alpha_m^{III})^{-1}(C^2)$ that is associated with r_h^{III} . Then we delete from Θ_m^{III} those elements that lie in Q_c^{III} , and we replace the elements C_0^2 and D_0^2 by $C_0^2 + Q_c^{III} + D_0^2$ (which we associate with $r_{i_0}^{IV}$). This yields Θ_m^{IV} . For the remaining $\mathfrak{R}_{\approx}^{III}$'s we take $\mathfrak{R}_{\approx}^{IV} = \mathfrak{R}_{\approx}^{III}$. We write $r_i^{IV} = r_i^{III}$ if $i \neq i_0$.

Now the $\mathfrak{R}_{\approx}^{IV}$'s have again the properties (10.1), (10.2, modified), (10.3), (10.4), and $r_{\approx}^{IV\#} = r_{\approx}^{III\#}$, but the number w^{IV} of open arcs Q_f^{IV} ($f = 1, \dots, w^{IV}$) is smaller than w .

Step v. Deleting all Q^1 's. We repeat the procedure of Step iv as often as possible and finally obtain in this way (after at most w steps) a presentation $\mathfrak{P}^V = (\{g_{\cdot}\}, \{r_{i_{\sim}}^V\})$ and corresponding relator-diagrams \mathfrak{R}_{\approx}^V such that each decomposition Θ_{\approx}^V possesses just one 2-dimensional element. That means that each of the $v + s$ words $r_{\approx}^{V\#} = r_{\approx}^{III\#}$ [see (III #)] is at the same time a member of a class, say $\langle r_{i_{\sim}}^V \rangle$, where we may assume that the notation is so arranged that $1 \leq i_{\sim} \leq v + s$; (we do not specify the remaining relators $r_{v+s+1}^V, \dots, r_b^V$). Further we may assume that $r_{\approx}^{V\#}$ is a cyclic permutation of $r_{i_{\sim}}^V$ and not one of $(r_{i_{\sim}}^V)^{-1}$; (this can be arranged by proper choice of the direction in which $r_{i_{\sim}}^V$ is read when the last open arc Q^1 is removed in $\circ R_{\approx}^{III2}$).

Step vi. Obviously we can transform \mathfrak{P}^V by a sequence of cancellation operations of Type 2 and length 1 (a relator out of $\langle g_{\mathbf{x}jk} g_{\mathbf{x}jk-1}^{-1} \rangle$ is replaced by a relator $g_{\mathbf{x}jk}$ where another relator is equal to $g_{\mathbf{x}jk-1}$, $k = 2, \dots, t_j$; etc.) into a presentation

$$\mathfrak{P}^{VI} = (\{g_v\}, \{g_v, r_{v+s+1}^{VI}, \dots, r_b^{VI}\})$$

where $r_i^{VI} = r_i^V$ for $i = v + s + 1, \dots, b$. Now we can transform \mathfrak{P}^{VI} by a sequence of cancellation operations of Type 2 and length 1 (a relator $g_v^{\pm 1} r''$ is replaced by r'' where another relator is equal to g_v) into the presentation $(\{g_v\}, \{g_v, *^{b-(v+s)}\})$. This finishes the proof of the theorem.

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