# CONVERGENCE IN DISTRIBUTION OF NONMEASURABLE RANDOM ELEMENTS 

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#### Abstract

A notion of convergence in distribution for non (necessarily) measurable random elements, due to Hoffmann-Jørgensen, is characterized in terms of weak convergence of finitely additive probability measures. A similar characterization is given for a strengthened version of such a notion. Further, it is shown that the empirical process for an exchangeable sequence can fail to converge, due to the nonexistence of any measurable limit, although it converges for an i.i.d. sequence. Because of phenomena of this type, Hoffmann-Jørgensen's definition is extended to the case of a nonmeasurable limit. In the extended definition, naturally suggested by the main results, the limit is a finitely additive probability measure.


1. Introduction. In some problems, the need arises for a notion of convergence in distribution for non (necessarily) measurable random elements. Examples are in the theory of empirical processes. Accordingly, a few definitions of convergence in distribution have been proposed. See Dudley (1966, 1967), Pyke and Shorack (1968) and Pollard (1984).

One more definition, due to Hoffmann-Jørgensen, has been recently analyzed by van der Vaart and Wellner (1996) and Dudley (1999) and taken as a basis for convergence of empirical processes and asymptotic statistics. Most statistical limit theorems, in fact, are just consequences of convergence of the (general) empirical process.

Hoffmann-Jørgensen's definition (HJ, in what follows) allows a rich and elegant theory and is very handy in applied situations. However, it also has some potential drawbacks and points to be developed. Indeed, (i) the case of a nonmeasurable limit is not covered; (ii) the probabilistic meaning should be deepened; and (iii) the underlying probability spaces of the random elements play a crucial role, since they determine outer expectations, and are to be explicitly declared to make the definition usable [cf. van der Vaart and Wellner (1996), pages 18 and 83].

In this paper, points (i)-(iii) are investigated. Our main result (Theorem 4) deals with (ii). It states that HJ is equivalent to convergence in distribution under all finitely additive extensions of the underlying probability measures. A similar characterization is given for a strengthened version of HJ. In view of Theorem 4, in our opinion, the probabilistic meaning of HJ is made more transparent. As to

[^0]point (i), it is shown that measurability of the limit can be a real limitation of HJ, even in simple problems. Indeed, the empirical process for an exchangeable sequence can fail to converge, due to the nonexistence of any measurable limit, although it converges for an i.i.d. sequence; see Example 11. Because of these phenomena, HJ is extended to the case of a nonmeasurable limit. In the extended definition, naturally suggested by Theorem 4, the limit is a finitely additive probability measure. Finally, point (iii) is briefly discussed in Section 2. It turns out that (iii) is more or less unavoidable as far as a definition is asked to work in nonmeasurable problems.

A last, general remark is the following. There are problems in probability and statistics which cannot be solved in the usual countably additive setting, while admitting a finitely additive solution. Examples can be found in conditional probability, statistical inference, filtering, stochastic integration and the first digit problem. Moreover, some widely used statistical procedures, like formal posteriors of improper priors, can be justified in a finitely additive setting only. See Bumby and Ellentuck (1969), Dubins (1975), Heath and Sudderth (1978, 1989), Karandikar (1982, 1988), Kallianpur and Karandikar (1983, 1988), Regazzini (1987), Berti and Rigo (1994, 1996, 1999) and Dubins and Prikry (1995). In a sense, convergence in distribution of nonmeasurable random elements is one more example of this type. Indeed, by next Theorem 4, HJ is basically a finitely additive definition.
2. Hoffmann-Jørgensen's definition. As far as possible, the notation is that of van der Vaart and Wellner (1996). Thus, $A$ is a directed set, $\mathbb{D}$ a metric space, $\mathscr{D}$ the Borel $\sigma$-field on $\mathbb{D}$ and $\mathrm{C}_{b}(\mathbb{D})$ the class of real bounded continuous functions on $\mathbb{D}$. For all $\alpha \in A,\left(\Omega_{\alpha}, \mathcal{A}_{\alpha}, P_{\alpha}\right)$ is a probability space and $X_{\alpha}: \Omega_{\alpha} \rightarrow \mathbb{D}$ an arbitrary map. Moreover, $(\Omega, \mathcal{A}, P)$ is a probability space and $X: \Omega \rightarrow \mathbb{D}$ a measurable map, that is, $X^{-1}(\mathscr{D}) \subset \mathcal{A}$. Because of measurability, the distribution $\mu$ of $X$ can be defined as $\mu(B)=P(X \in B)$ for all $B \in \mathcal{D}$, while the distribution of $X_{\alpha}$ cannot be defined on the whole of $\mathcal{D}$. So, we let

$$
\mathscr{D}_{\alpha}=\left\{B \in \mathscr{D}: X_{\alpha}^{-1}(B) \in \overline{\mathscr{A}_{\alpha}}\right\}, \quad \alpha \in A,
$$

be the sub- $\sigma$-field of $\mathscr{D}$ where the distribution of $X_{\alpha}$ can be unambiguously defined, $\left(\Omega_{\alpha}, \overline{\mathcal{A}_{\alpha}}, \overline{P_{\alpha}}\right)$ denoting the completion of $\left(\Omega_{\alpha}, \mathcal{A}_{\alpha}, P_{\alpha}\right)$. Clearly, $\mathcal{D}_{\alpha}=$ $\mathscr{D}$ whenever $X_{\alpha}$ is measurable. For $B \in \mathscr{D}_{\alpha}$, the "partial" distribution of $X_{\alpha}$ is just $\mu_{\alpha}(B)=\overline{P_{\alpha}}\left(X_{\alpha} \in B\right)$.

In the standard theory, the $X_{\alpha}$ are measurable and " $X_{\alpha} \rightarrow X$ in distribution" means $E f\left(X_{\alpha}\right) \rightarrow E f(X)$ for all $f \in C_{b}(\mathbb{D})$. To extend this definition to the present case, where the $X_{\alpha}$ need not be measurable, for all $\alpha \in A$ and $Z: \Omega_{\alpha} \rightarrow \overline{\mathbb{R}}$, let us define

$$
E^{*} Z=\inf \left\{E U: U: \Omega_{\alpha} \rightarrow \overline{\mathbb{R}} \text { measurable, } E U \text { exists, } U \geq Z\right\}
$$

and $E_{*} Z=-E^{*}(-Z)$. Here, $E U$ exists if at least one of $E U^{+}$and $E U^{-}$is finite, and in that case $E U=E U^{+}-E U^{-}$. In this notation, HJ (i.e., HoffmannJørgensen's definition) is

$$
X_{\alpha} \xrightarrow{\mathrm{HJ}} X \quad \Longleftrightarrow \quad E^{*} f\left(X_{\alpha}\right) \rightarrow E f(X) \quad \text { for all } f \in C_{b}(\mathbb{D}) .
$$

As noted in Section 1, despite its utility and elegance, some aspects of HJ need to be developed further. First, the case of a nonmeasurable limit $X$ is not covered. It will be seen in Example 11 how the measurability of $X$ can be a real limitation, even in simple problems. Second, the probabilistic content should still be investigated. Indeed, using outer expectations could appear something like a trick for avoiding measurability problems. Third, to make HJ usable, the underlying probability spaces ( $\Omega_{\alpha}, \mathcal{A}_{\alpha}, P_{\alpha}$ ) are to be explicitly declared, since they determine outer expectations. In van der Vaart and Wellner (1996) and Dudley (1999), for instance, the ( $\Omega_{\alpha}, \mathcal{A}_{\alpha}, P_{\alpha}$ ) are often taken to be the canonical spaces.

This paper focus on the three points above. The third one is dealt with in the rest of this section, while the other two are discussed in Sections 4 and 5.

At first sight, a definition of convergence which ignores $\left(\Omega_{\alpha}, \mathcal{A}_{\alpha}, P_{\alpha}\right)$, and only depends on $\left(\mathbb{D}, \mathscr{D}_{\alpha}, \mu_{\alpha}\right)$, could appear preferable. However, in various nonmeasurable situations, the $\mathscr{D}_{\alpha}$ are very poor or even trivial. If the adopted definition only depends on $\left(\mathbb{D}, \mathscr{D}_{\alpha}, \mu_{\alpha}\right)$, it is often quite arbitrary whether $X_{\alpha} \rightarrow X$ in distribution or not. We illustrate this by a trivial example.

Example 1. Suppose $\mathbb{D}=\{0,1\}, X_{\alpha}=I_{B_{\alpha}}$ and $X=I_{B}$, where $B \in \mathscr{A}$ and $B_{\alpha} \notin \overline{\mathcal{A}_{\alpha}}$ for all $\alpha$. Then $\mathscr{D}_{\alpha}=\{\varnothing, \mathbb{D}\}$ for all $\alpha$. Note also that $X_{\alpha} \xrightarrow{\mathrm{HJ}} X$ if and only if $\lim _{\alpha} P_{\alpha}^{*}\left(B_{\alpha}\right)=\lim _{\alpha} P_{\alpha *}\left(B_{\alpha}\right)=P(B)\left(P_{\alpha}^{*}\right.$ and $P_{\alpha *}$ denoting outer and inner measure, resp.).

In Example 1, according to any reasonable definition, $X_{\alpha} \rightarrow X$ in distribution should mean $\operatorname{Prob}\left(X_{\alpha}=1\right) \rightarrow P(X=1)$ for suitable estimates $\operatorname{Prob}\left(X_{\alpha}=1\right)$ of the nonavailable probabilities of the events $\left\{X_{\alpha}=1\right\}$. If a definition only depends on $\left(\mathbb{D}, \mathscr{D}_{\alpha}, \mu_{\alpha}\right)$, there are no sound rules for choosing $\operatorname{Prob}\left(X_{\alpha}=1\right)$ and, in this sense, convergence is quite arbitrary. Instead, a definition which makes use of the available information on ( $\Omega_{\alpha}, \mathcal{A}_{\alpha}, P_{\alpha}$ ) can work. For instance, suppose that $X_{\alpha} \rightarrow X$ in distribution whenever $\operatorname{Prob}\left(X_{\alpha}=1\right) \rightarrow P(X=1)$ for all admissible estimates $\operatorname{Prob}\left(X_{\alpha}=1\right)$, where "admissible" means

$$
P_{\alpha *}\left(X_{\alpha}=1\right) \leq \operatorname{Prob}\left(X_{\alpha}=1\right) \leq P_{\alpha}^{*}\left(X_{\alpha}=1\right)
$$

Then convergence amounts to $\lim _{\alpha} P_{\alpha}^{*}\left(X_{\alpha}=1\right)=\lim _{\alpha} P_{\alpha *}\left(X_{\alpha}=1\right)=P(X=1)$, which is precisely convergence according to HJ.

To sum up, it seems more or less unavoidable that the ( $\Omega_{\alpha}, \mathcal{A}_{\alpha}, P_{\alpha}$ ) are strongly involved in any definition which is asked to work in nonmeasurable problems.
3. Finitely additive probability measures. The finitely additive theory of probability, based on de Finetti's coherence principle and the subsequent work of Dubins and Savage, is well developed and understood by now. It includes the standard (countably additive) theory as a particular case. In this section, we collect for later use a few known facts on finitely additive probabilities and we state two preliminary lemmas.

Given any set $\mathcal{X}, \mathcal{P}(\mathcal{X})$ denotes the power set of $\mathcal{X}$. If $T: L \rightarrow \mathbb{R}$ is a functional on a linear space $L$ of real functions on $\mathcal{X}$, we let

$$
T^{*}(f)=\inf \{T(\phi): \phi \in L, \phi \geq f\} \quad \text { and } \quad T_{*}(f)=-T^{*}(-f)
$$

for each $f: \mathcal{X} \rightarrow \mathbb{R}$ (with the usual convention $\inf \varnothing=\infty$ ). A finitely additive probability (f.a.p.), defined on a field $\mathcal{E}$ of subsets of $\mathcal{X}$, is a nonnegative, finitely additive function $v$ on $\mathcal{E}$ such that $v(\mathcal{X})=1$. For $H \subset \mathcal{X}$, define $v^{*}(H)=$ $\inf \{v(B): B \in \mathcal{E}, B \supset H\}$ and $\nu_{*}(H)=1-v^{*}\left(H^{c}\right)$. Then, for all $H \subset \mathcal{X}$ and $c \in$ $\left[v_{*}(H), v^{*}(H)\right], v$ can be extended to an f.a.p. $v^{\prime}$ on $\mathcal{P}(X)$ such that $v^{\prime}(H)=c$. This follows from Lemma 2, which is also one of our main tools. It is essentially well known and we give a proof just to make the paper self-contained.

Lemma 2. Let $L$ and $M$ be linear spaces of real bounded functions on a set $\mathcal{X}$ and let $T: L \rightarrow \mathbb{R}$ and $U: M \rightarrow \mathbb{R}$ be linear functionals. Suppose $L$ includes the constants, $T$ is positive and $T(1)=1$. Then there is an f.a.p. $\beta$ on $\mathcal{P}(\mathcal{X})$ such that

$$
T(f)=\int f d \beta \quad \text { and } \quad U(g)=\int g d \beta \quad \text { for all } f \in L \text { and } g \in M
$$

if and only if

$$
U(g) \geq T_{*}(g) \quad \text { for all } g \in M
$$

In particular, given any bounded function $h$ on $\mathcal{X}$ and constant $c \in\left[T_{*}(h), T^{*}(h)\right]$, there is an f.a.p. $\beta$ on $\mathcal{P}(\mathcal{X})$ such that $T(f)=\int f d \beta$ for all $f \in L$ and $\int h d \beta=c$ [take $M=\{a h: a \in \mathbb{R}\}$ and $U(a h)=$ ac for all $a \in \mathbb{R}]$.

Proof. If $T$ and $U$ are integrals w.r.t. the same f.a.p. $\beta$, then

$$
U(g)=\int g d \beta \geq \sup \left\{\int \phi d \beta: \phi \in L, \phi \leq g\right\}=T_{*}(g) \quad \text { for all } g \in M
$$

Conversely, suppose $U \geq T_{*}$ on $M$. Since $U(g) \leq-T_{*}(-g)=T^{*}(g)$ for all $g \in M$, one has $T=U$ on $L \cap M$. Hence, if $f_{1}+g_{1}=f_{2}+g_{2}$ for some $f_{1}, f_{2} \in L$ and $g_{1}, g_{2} \in M$, then $T\left(f_{1}-f_{2}\right)=T\left(g_{2}-g_{1}\right)=U\left(g_{2}-g_{1}\right)$ and thus $T\left(f_{1}\right)+U\left(g_{1}\right)=T\left(f_{2}\right)+U\left(g_{2}\right)$. Therefore, it is possible to set

$$
V(f+g)=T(f)+U(g) \quad \text { for all } f \in L \text { and } g \in M
$$

and $V$ turns out to be a linear functional on $L+M$ extending both $T$ and $U$. If $f \in L, g \in M$ and $f+g \geq 0$, then $g \geq-f$ and thus $U(g) \geq T_{*}(g) \geq-T(f)$.

It follows that $V(f+g)=T(f)+U(g) \geq 0$, that is, $V$ is positive. By the HahnBanach theorem, $V$ can be extended to a linear positive functional $V_{0}$ defined on all real bounded functions on $\mathcal{X}$. Let $\beta(E)=V_{0}\left(I_{E}\right)$ for all $E \subset \mathcal{X}$. Then $V_{0}(h)=\int h d \beta$ for all bounded $h$ on $\mathcal{X}$, and this concludes the proof.

A well-established theory of weak convergence of f.a.p.'s has been available since Karandikar (1982, 1988); see also Girotto and Holzer (1993). Let $\mathbb{P}$ be the class of all f.a.p.'s on $\mathscr{D}$. Given $v_{\alpha}, v \in \mathbb{P}$, where $\alpha$ ranges over $A$, say that $v_{\alpha} \rightarrow v$ weakly in case $\int f d \nu_{\alpha} \rightarrow \int f d \nu$ for all $f \in C_{b}(\mathbb{D})$. If $v$ is regular on open sets, that is, $\nu(G)=\sup \{\nu(F): F$ closed, $F \subset G\}$ for all open $G \subset \mathbb{D}$, then

$$
v_{\alpha} \rightarrow \nu \text { weakly } \Longleftrightarrow \quad \limsup _{\alpha} v_{\alpha}(F) \leq \nu(F) \quad \text { for all closed } F \subset \mathbb{D}
$$

The implication " $\Leftarrow$ " holds even if $v$ is not regular on open sets. Further, each linear positive functional $T$ on $\mathrm{C}_{b}(\mathbb{D})$ satisfying $T(1)=1$ can be represented as $T(f)=\int f d \nu, f \in C_{b}(\mathbb{D})$, for some $v \in \mathbb{P}$ regular on open sets.

Finally, we give a technical lemma, needed for proving Theorem 4.
LEMMA 3. Given $v \in \mathbb{P}$, suppose that $v_{\alpha} \rightarrow v$ weakly whenever $v_{\alpha} \in \mathbb{P}$, $v_{\alpha}=\mu_{\alpha}$ on $\mathscr{D}_{\alpha}$ and $v_{\alpha}^{*}\left(X_{\alpha}\left(\Omega_{\alpha}\right)\right)=1$ for all $\alpha$. Then $\gamma_{\alpha} \rightarrow v$ weakly whenever $\gamma_{\alpha} \in \mathbb{P}$ and $\gamma_{\alpha}=\mu_{\alpha}$ on $\mathscr{D}_{\alpha}\left[\right.$ but not necessarily $\left.\gamma_{\alpha}^{*}\left(X_{\alpha}\left(\Omega_{\alpha}\right)\right)=1\right]$ for all $\alpha$.

Proof. Let $\gamma_{\alpha} \in \mathbb{P}$ be such that $\gamma_{\alpha}=\mu_{\alpha}$ on $\mathscr{D}_{\alpha}$ and let $f \in C_{b}(\mathbb{D})$. We have to show that $\int f d \gamma_{\alpha} \rightarrow \int f d \nu$. Denote $C_{\alpha}=X_{\alpha}\left(\Omega_{\alpha}\right)$. Since $\mu_{\alpha}^{*}\left(C_{\alpha}\right)=1$, there is an f.a.p. $\lambda_{\alpha}$ on $\mathscr{P}(\mathbb{D})$ extending $\mu_{\alpha}$ and satisfying $\lambda_{\alpha}\left(C_{\alpha}\right)=1$. Define

$$
L_{\alpha}=\left\{\phi+b I_{C_{\alpha}}: \phi \text { bounded and } \mathscr{D}_{\alpha} \text {-measurable on } \mathbb{D}, b \in \mathbb{R}\right\}
$$

and $T_{\alpha}(\psi)=\int \psi d \lambda_{\alpha}$ for all $\psi \in L_{\alpha}$. Fix $\psi=\phi+b I_{C_{\alpha}} \in L_{\alpha}$ such that $\psi \geq f$ and define

$$
h=(\phi+b) I_{\{f \leq \phi+b\}}+(\sup f) I_{\{f>\phi+b\}} .
$$

Then $\lambda_{\alpha}(\psi \neq h)=0, h$ is bounded and $h \geq f$. Also, $h$ is $\mathscr{D}_{\alpha}$-measurable since it is Borel measurable and $h\left(X_{\alpha}\right)=\phi\left(X_{\alpha}\right)+b$ is $\overline{\mathcal{A}_{\alpha}}$-measurable. By recalling that $\gamma_{\alpha}$ extends $\mu_{\alpha}$, one obtains

$$
T_{\alpha}(\psi)=T_{\alpha}(h)=\int h d \lambda_{\alpha}=\int h d \mu_{\alpha}=\int h d \gamma_{\alpha} \geq \int f d \gamma_{\alpha}
$$

Hence, $T_{\alpha}^{*}(f) \geq \int f d \gamma_{\alpha}$, which in turn implies $\int f d \gamma_{\alpha} \geq-T_{\alpha}^{*}(-f)=T_{\alpha *}(f)$. By Lemma 2, there is an f.a.p. $\beta_{\alpha}$ on $\mathscr{P}(\mathbb{D})$ such that $\int \psi d \beta_{\alpha}=T_{\alpha}(\psi)=\int \psi d \lambda_{\alpha}$ for all $\psi \in L_{\alpha}$ and $\int f d \beta_{\alpha}=\int f d \gamma_{\alpha}$. Call $\nu_{\alpha}^{f}$ the restriction of $\beta_{\alpha}$ to $\mathscr{D}$. Then $v_{\alpha}^{f}=\mu_{\alpha}$ on $\mathscr{D}_{\alpha}$ and $\left(v_{\alpha}^{f}\right)^{*}\left(C_{\alpha}\right)=1$, and thus the assumption of the lemma yields

$$
\int f d \gamma_{\alpha}=\int f d \beta_{\alpha}=\int f d v_{\alpha}^{f} \rightarrow \int f d \nu
$$

4. A characterization and a finitely additive extension of HJ. To define the convergence in distribution of $X_{\alpha}$ to $X$, say $X_{\alpha} \xrightarrow{d} X$, it is tempting to declare that $X_{\alpha} \xrightarrow{d} X$ means $v_{\alpha} \rightarrow \mu$ weakly whenever, for each $\alpha, v_{\alpha}$ is a possible distribution for $X_{\alpha}$. To realize this rough idea, clearly one has to decide what the distribution of a nonmeasurable random element is. In what follows, a distribution for $X_{\alpha}$ is any f.a.p. $v$ on $\mathscr{D}$ of the form $v=Q \circ X_{\alpha}^{-1}$, where $Q$ is an f.a.p. on $\mathcal{P}\left(\Omega_{\alpha}\right)$ extending $P_{\alpha}$. Hence, denoting by $\mathbb{P}_{\alpha}$ the class of all such distributions for $X_{\alpha}$, the above tentative definition becomes
(1) $\quad X_{\alpha} \xrightarrow{d} X \quad \Longleftrightarrow \quad v_{\alpha} \rightarrow \mu \quad$ weakly whenever $v_{\alpha} \in \mathbb{P}_{\alpha}$ for all $\alpha$.

In definition (1), using f.a.p.'s seems (to us) quite natural. The main reason is that the partial distribution $\mu_{\alpha}$ of $X_{\alpha}$ can fail to admit any countably additive extension to $\mathscr{D}$. Instead, in a finitely additive setting, extensions are always available. In particular, it may be that $X_{\alpha} \xrightarrow{d} X$ [according to (1)] even though no $X_{\alpha}$ admits a countably additive distribution on $\mathscr{D}$. Situations of this type can occur in very simple problems, as shown in Example 10. Another reason for using f.a.p.'s, even if of the theoretical type, is that the dual of $C_{b}(\mathbb{D})$ is just a space of bounded finitely additive measures. Finally, as noted in Section 3, the finitely additive theory of probability is sufficiently developed by now.

One more remark is in order. A distribution for $X_{\alpha}$ has been defined above by first extending $P_{\alpha}$ to $Q$ and then taking the image measure $Q \circ X_{\alpha}^{-1}$. Another reasonable possibility is to extend $\mu_{\alpha}$ directly, in such a way that the extension is supported by $X_{\alpha}\left(\Omega_{\alpha}\right)$, but without passing through image measures. That is, a distribution for $X_{\alpha}$ could be defined as any element of $\mathbb{T}_{\alpha}:=\left\{v \in \mathbb{P}: v=\mu_{\alpha}\right.$ on $\mathscr{D}_{\alpha}$ and $\left.\nu^{*}\left(X_{\alpha}\left(\Omega_{\alpha}\right)\right)=1\right\}$. This alternative definition of distribution for $X_{\alpha}$ is not used in the rest of the paper. It is worth noting, however, that it would induce a very strong notion of convergence-stronger than (1), in particular. In fact, since $\mathbb{P}_{\alpha} \subset \mathbb{T}_{\alpha}$, if $v_{\alpha} \rightarrow \mu$ weakly whenever $v_{\alpha} \in \mathbb{T}_{\alpha}$ for all $\alpha$ then $X_{\alpha} \xrightarrow{d} X$, while the converse is not true (see Example 1).

Our main result (Theorem 4) is that HJ is equivalent to definition (1). Moreover, the above-mentioned condition that $v_{\alpha} \rightarrow \mu$ weakly whenever $v_{\alpha} \in \mathbb{T}_{\alpha}$ for all $\alpha$ amounts to a strengthened version of HJ. To introduce the latter, for all $\alpha \in A$ and bounded Borel $f: \mathbb{D} \rightarrow \mathbb{R}$ define

$$
\begin{align*}
E^{0} f\left(X_{\alpha}\right)=\inf \left\{E \phi\left(X_{\alpha}\right): \phi: \mathbb{D}\right. & \rightarrow \mathbb{R} \text { bounded and Borel, } \\
& \left.\phi\left(X_{\alpha}\right) \text { is } \overline{\mathcal{A}_{\alpha}} \text {-measurable, } \phi\left(X_{\alpha}\right) \geq f\left(X_{\alpha}\right)\right\} . \tag{2}
\end{align*}
$$

$E^{0}$ is just another type of outer expectation. Since $E^{0} f\left(X_{\alpha}\right) \geq E^{*} f\left(X_{\alpha}\right)$, the condition

$$
\begin{equation*}
E^{0} f\left(X_{\alpha}\right) \rightarrow E f(X) \quad \text { for all } f \in C_{b}(\mathbb{D}) \tag{3}
\end{equation*}
$$

implies $X_{\alpha} \xrightarrow{\text { HJ }} X$. In this sense, (3) is a strengthening of HJ.

THEOREM 4. $\quad X_{\alpha} \xrightarrow{\text { HJ }} X$ if and only if $X_{\alpha} \xrightarrow{d} X$. Moreover, condition (3) holds if and only if $\nu_{\alpha} \rightarrow \mu$ weakly whenever $v_{\alpha} \in \mathbb{T}_{\alpha}$ for all $\alpha$.

Proof. Suppose $X_{\alpha} \xrightarrow{\text { HJ }} X$ and fix $\nu_{\alpha} \in \mathbb{P}_{\alpha}$ for each $\alpha$. Denoting by $Q_{\alpha}$ an f.a.p. on $\mathcal{P}\left(\Omega_{\alpha}\right)$, extending $P_{\alpha}$ and such that $v_{\alpha}=Q_{\alpha} \circ X_{\alpha}^{-1}$, one has

$$
E^{*} f\left(X_{\alpha}\right) \geq \int f\left(X_{\alpha}\right) d Q_{\alpha}=\int f d v_{\alpha} \geq E_{*} f\left(X_{\alpha}\right) \quad \text { for every } f \in C_{b}(\mathbb{D})
$$

Since $X_{\alpha} \xrightarrow{\mathrm{HJ}} X, E^{*} f\left(X_{\alpha}\right)$ and $E_{*} f\left(X_{\alpha}\right)$ both converge to $\int f d \mu$, so that $\int f d \nu_{\alpha} \rightarrow \int f d \mu$ for every $f \in C_{b}(\mathbb{D})$. Hence, $v_{\alpha} \rightarrow \mu$ weakly, that is, $X_{\alpha} \xrightarrow{d} X$. Conversely, assume $X_{\alpha} \xrightarrow{d} X$ and fix $f \in C_{b}(\mathbb{D})$. For each $\alpha$, define $T_{\alpha}(U)=$ $\int U d P_{\alpha}$ on $L_{\alpha}=\left\{U: U\right.$ bounded and $\mathcal{A}_{\alpha}$-measurable on $\left.\Omega_{\alpha}\right\}$ and note that $T_{\alpha}^{*}\left(f\left(X_{\alpha}\right)\right)=E^{*} f\left(X_{\alpha}\right)$. By Lemma 2, there is an f.a.p. $Q_{\alpha}$ on $\mathscr{P}\left(\Omega_{\alpha}\right)$ extending $P_{\alpha}$ and such that $E^{*} f\left(X_{\alpha}\right)=\int f\left(X_{\alpha}\right) d Q_{\alpha}$. Define $v_{\alpha}^{f}=Q_{\alpha} \circ X_{\alpha}^{-1}$ on $\mathcal{D}$. Since $X_{\alpha} \xrightarrow{d} X$ and $\nu_{\alpha}^{f} \in \mathbb{P}_{\alpha}$ for each $\alpha$, one obtains

$$
E^{*} f\left(X_{\alpha}\right)=\int f\left(X_{\alpha}\right) d Q_{\alpha}=\int f d v_{\alpha}^{f} \rightarrow \int f d \mu
$$

Since $f \in C_{b}(\mathbb{D})$ is arbitrary, it follows that $X_{\alpha} \xrightarrow{\text { HJ }} X$.
Next, the second part of the theorem is just a consequence of the first and the following fact

$$
\begin{equation*}
E^{0} f\left(X_{\alpha}\right)=\inf \left\{E \phi\left(X_{\alpha}\right): \phi: \mathbb{D} \rightarrow \mathbb{R} \text { bounded and } \mathscr{D}_{\alpha} \text {-measurable, } \phi \geq f\right\} \tag{4}
\end{equation*}
$$

Suppose, in fact, that (4) holds. Let $Z_{\alpha}=Z=I$, where $I$ denotes the identity on $\mathbb{D}$, and regard $Z_{\alpha}$ as defined on $\left(\mathbb{D}, \mathscr{D}_{\alpha}, \mu_{\alpha}\right)$ and $Z$ as defined on $(\mathbb{D}, \mathscr{D}, \mu)$. By (4), $E^{*} f\left(Z_{\alpha}\right)=E^{0} f\left(X_{\alpha}\right)$ for all $f \in C_{b}(\mathbb{D})$. Hence, the equivalence between HJ and (1) yields

$$
\begin{aligned}
& E^{0} f\left(X_{\alpha}\right) \rightarrow E f(X) \quad \text { for all } f \in C_{b}(\mathbb{D}) \\
& \quad \Longleftrightarrow \quad Z_{\alpha} \xrightarrow{\text { HJ }} Z \\
& \quad \Longleftrightarrow \quad Z_{\alpha} \xrightarrow{d} Z \\
& \Longleftrightarrow \quad \gamma_{\alpha} \rightarrow \mu \quad \text { weakly whenever } \gamma_{\alpha} \in \mathbb{P} \text { and } \gamma_{\alpha}=\mu_{\alpha} \text { on } \mathscr{D}_{\alpha} \text { for all } \alpha .
\end{aligned}
$$

Finally, by Lemma 3, the latter condition holds if and only if $v_{\alpha} \rightarrow \mu$ weakly whenever $v_{\alpha} \in \mathbb{T}_{\alpha}$ for all $\alpha$.

It remains to prove (4). Fix $\alpha \in A$ and a bounded Borel $f: \mathbb{D} \rightarrow \mathbb{R}$. Since $\mu_{\alpha}^{*}\left(X_{\alpha}\left(\Omega_{\alpha}\right)\right)=1$, there is an f.a.p. $\lambda_{\alpha}$ on $\mathcal{P}(\mathbb{D})$ extending $\mu_{\alpha}$ and such that $\lambda_{\alpha}\left(X_{\alpha}\left(\Omega_{\alpha}\right)\right)=1$. Let us call $\Phi$ and $\Phi_{0}$ the sets of functions $\phi$ 's involved in (2) and in (4), respectively. Since $\Phi_{0} \subset \Phi$, to get (4), it is enough to prove that for each $\phi \in \Phi$ there is $\phi_{0} \in \Phi_{0}$ with $E \phi_{0}\left(X_{\alpha}\right)=E \phi\left(X_{\alpha}\right)$. Given $\phi \in \Phi$, define $\phi_{0}$
by $\phi_{0}=\phi$ on $\{f \leq \phi\}$ and $\phi_{0}=\sup f$ on $\{f>\phi\}$. Then $\phi_{0}$ is bounded, $\phi_{0} \geq f$ everywhere and $\phi_{0}$ is $\mathscr{D}_{\alpha}$-measurable since is Borel measurable and $\phi_{0}\left(X_{\alpha}\right)=$ $\phi\left(X_{\alpha}\right)$ is $\overline{\mathcal{A}_{\alpha}}$-measurable. Hence, $\phi_{0} \in \Phi_{0}$. Finally, since $\lambda_{\alpha}\left(\phi_{0} \neq \phi\right)=0$, one obtains

$$
E \phi\left(X_{\alpha}\right)=\int \phi d \mu_{\alpha}=\int \phi d \lambda_{\alpha}=\int \phi_{0} d \lambda_{\alpha}=\int \phi_{0} d \mu_{\alpha}=E \phi_{0}\left(X_{\alpha}\right)
$$

Theorem 4, in our opinion, makes the probabilistic meaning of HJ more transparent.

Let us now turn to another issue. According to HJ, the limit $X$ of the nonmeasurable random elements $X_{\alpha}$ must be measurable. This fact is perhaps unsuitable from a theoretical point of view. Furthermore, as shown in Example 11, it can be a real limitation even in simple problems. Motivated by phenomena as in Example 11, we introduce an extension of HJ to the case of a nonmeasurable limit. Such an extension is naturally suggested by Theorem 4.

Suppose that

$$
\liminf _{\alpha} E_{*} f\left(X_{\alpha}\right) \geq \limsup _{\alpha} E^{*} f\left(X_{\alpha}\right) \quad \text { for all } f \in C_{b}(\mathbb{D})
$$

Then one can define the functional

$$
T(f)=\lim _{\alpha} E_{*} f\left(X_{\alpha}\right)=\lim _{\alpha} E^{*} f\left(X_{\alpha}\right) \quad \text { for all } f \in C_{b}(\mathbb{D}),
$$

and it is straightforward to see that $T$ is linear and positive with $T(1)=1$. Hence, $T$ is the integral w.r.t. some $v \in \mathbb{P}$, or, equivalently,

$$
\begin{equation*}
\int f d \nu=\lim _{\alpha} E^{*} f\left(X_{\alpha}\right) \quad \text { for all } f \in C_{b}(\mathbb{D}) \tag{5}
\end{equation*}
$$

Note that (5) also implies $\int f d \nu=\lim _{\alpha} E_{*} f\left(X_{\alpha}\right)$ for all $f \in C_{b}(\mathbb{D})$. Each such $\nu$ can be seen as a limit in distribution for $X_{\alpha}$.

DEFINITION 5. We say that $X_{\alpha}$ converges in distribution to $v$ and we write $X_{\alpha} \rightarrow v$, where $v \in \mathbb{P}$, if condition (5) holds.

Definition 5 clearly extends HJ. In fact, if $X_{\alpha} \xrightarrow{\text { HJ }} X$ ( $X$ is measurable with distribution $\mu$ ), then, in particular, $X_{\alpha} \rightarrow \mu$, and $\mu$ is the only countably additive element of $\mathbb{P}$ satisfying (5). Moreover, one deeper reason for regarding Definition 5 as an extension of HJ comes from Theorem 4 and the following result.

Theorem 6. Let $v \in \mathbb{P}$. Then $X_{\alpha} \rightarrow v$ if and only if

$$
\begin{equation*}
v_{\alpha} \rightarrow v \quad \text { weakly whenever } v_{\alpha} \in \mathbb{P}_{\alpha} \text { for each } \alpha \tag{6}
\end{equation*}
$$

Moreover, for $X_{\alpha} \rightarrow v$, it is sufficient (necessary and sufficient if $v$ is regular on open sets) that

$$
\begin{equation*}
\limsup _{\alpha} P_{\alpha}^{*}\left(X_{\alpha} \in F\right) \leq v(F) \quad \text { for all closed } F \subset \mathbb{D} \tag{7}
\end{equation*}
$$

Proof. Suppose $X_{\alpha} \rightarrow v$. For each $\alpha$, fix $v_{\alpha} \in \mathbb{P}_{\alpha}$ and take an f.a.p. $Q_{\alpha}$ on $\mathcal{P}\left(\Omega_{\alpha}\right)$ extending $P_{\alpha}$ and such that $v_{\alpha}=Q_{\alpha} \circ X_{\alpha}^{-1}$. Since

$$
E^{*} f\left(X_{\alpha}\right) \geq \int f\left(X_{\alpha}\right) d Q_{\alpha}=\int f d v_{\alpha} \geq E_{*} f\left(X_{\alpha}\right) \quad \text { for all } f \in C_{b}(\mathbb{D})
$$

condition (5) implies $v_{\alpha} \rightarrow v$ weakly. Conversely, suppose (6) holds and fix $f \in C_{b}(\mathbb{D})$. Arguing as in the proof of Theorem 4, for each $\alpha$ there is $\nu_{\alpha}^{f} \in \mathbb{P}_{\alpha}$ such that $\int f d \nu_{\alpha}^{f}=E^{*} f\left(X_{\alpha}\right)$, and thus (6) yields $\int f d \nu=\lim _{\alpha} \int f d \nu_{\alpha}^{f}=$ $\lim _{\alpha} E^{*} f\left(X_{\alpha}\right)$. Hence, $X_{\alpha} \rightarrow v$, and this proves the first part of the theorem. Next, assume (7) holds and fix $v_{\alpha} \in \mathbb{P}_{\alpha}$ for all $\alpha$. Since $v_{\alpha}(B) \leq P_{\alpha}^{*}\left(X_{\alpha} \in B\right)$ for all $B \in \mathscr{D}$, (7) implies $\limsup _{\alpha} v_{\alpha}(F) \leq v(F)$ for all closed $F \subset \mathbb{D}$. Hence, $v_{\alpha} \rightarrow v$ weakly, and the first part of the theorem yields $X_{\alpha} \rightarrow v$. Finally, suppose $X_{\alpha} \rightarrow v$ and $v$ is regular on open sets. Given a closed $F \subset \mathbb{D}$, for each $\alpha$ take $v_{\alpha}^{F} \in \mathbb{P}_{\alpha}$ such that $v_{\alpha}^{F}(F)=P_{\alpha}^{*}\left(X_{\alpha} \in F\right)$. Since $v_{\alpha}^{F} \rightarrow v$ weakly and $v$ is regular on open sets, one obtains

$$
\limsup _{\alpha} P_{\alpha}^{*}\left(X_{\alpha} \in F\right)=\limsup _{\alpha} v_{\alpha}^{F}(F) \leq v(F)
$$

The following proposition provides an additional criterion for deciding whether $X_{\alpha}$ converges in distribution to some limit.

Proposition 7. In order for $X_{\alpha} \rightarrow v$, for some $v \in \mathbb{P}$, it is necessary and sufficient that for any finite family $\left\{F_{1}, \ldots, F_{k}\right\}$ of closed subsets of $\mathbb{D}$ there is $\gamma \in \mathbb{P}$ such that

$$
\underset{\alpha}{\limsup } P_{\alpha}^{*}\left(X_{\alpha} \in F_{i}\right) \leq \gamma\left(F_{i}\right) \quad \text { for each } i=1, \ldots, k
$$

Proof. Let $\mathcal{C}$ be the class of closed subsets of $\mathbb{D}$. We first prove sufficiency. By Theorem 6, letting $\mathcal{R}_{F}=\left\{\gamma \in \mathbb{P}: \lim \sup _{\alpha} P_{\alpha}^{*}\left(X_{\alpha} \in F\right) \leq \gamma(F)\right\}$ for $F \in \mathcal{C}$, it is enough to prove $\bigcap_{F \in \mathfrak{C}} \mathcal{R}_{F} \neq \varnothing$. Let $[0,1]^{\mathscr{D}}$ be the set of functions from $\mathscr{D}$ to $[0,1]$, equipped with product topology. Then $[0,1]^{\mathscr{D}}$ is compact, $\mathscr{R}_{F}$ is closed in $[0,1]^{\mathcal{D}}$, and, by assumption, $\left\{\mathcal{R}_{F}: F \in \mathcal{C}\right\}$ has the finite intersection property. Hence, $\bigcap_{F \in \mathcal{C}} \mathscr{R}_{F} \neq \varnothing$. Conversely, suppose $X_{\alpha} \rightarrow v$ for some $v \in \mathbb{P}$. Since $\int f d \nu=\int f d \gamma, f \in C_{b}(\mathbb{D})$, for some $\gamma \in \mathbb{P}$ regular on open sets (cf. Section 3), one also has $X_{\alpha} \rightarrow \gamma$. Hence, Theorem 6 implies $\lim \sup _{\alpha} P_{\alpha}^{*}\left(X_{\alpha} \in F\right) \leq \gamma(F)$ for all $F \in \mathcal{C}$.

So far, $X$ has denoted a measurable random element. Suppose now that measurability is dropped and $X: \Omega \rightarrow \mathbb{D}$ is an arbitrary map. When is it possible to write $X_{\alpha} \xrightarrow{d} X$ ? In the spirit of this paper, we say that $X_{\alpha} \xrightarrow{d} X$ if $X_{\alpha}$ converges in distribution, according to Definition 5, and one of the limits $v$ is a possible distribution for $X$, that is, $v=Q \circ X^{-1}$ for some f.a.p. $Q$ on $\mathcal{P}(\Omega)$ extending $P$. The last result in this section provides a characterization of this fact.

Proposition 8. Let $v \in \mathbb{P},(\Omega, \mathcal{A}, P)$ a probability space and $X: \Omega \rightarrow \mathbb{D}$ any map. Then $v=Q \circ X^{-1}$ for some f.a.p. $Q$ on $\mathcal{P}(\Omega)$ extending $P$ if and only if

$$
\begin{equation*}
v^{*}(X(\Omega))=1 \quad \text { and } \quad v(B) \leq P^{*}(X \in B) \quad \text { for all } B \in \mathscr{D} . \tag{8}
\end{equation*}
$$

In particular, $X_{\alpha} \xrightarrow{d} X$ if and only if there is $\gamma \in \mathbb{P}$ such that

$$
X_{\alpha} \rightarrow \gamma, \quad \gamma^{*}(X(\Omega))=1, \quad \gamma(B) \leq P^{*}(X \in B) \quad \text { for all } B \in \mathscr{D} .
$$

Proof. Suppose (8) holds and let $C=X(\Omega)$. Since $v^{*}(C)=1$, there is an f.a.p. $\lambda$ on $\mathscr{P}(\mathbb{D})$ extending $v$ and such that $\lambda(C)=1$. If $B_{1}, B_{2} \in \mathscr{D}$ and $\left\{X \in B_{1}\right\}=\left\{X \in B_{2}\right\}$, then $B_{1} \cap C=B_{2} \cap C$, and thus $v\left(B_{1}\right)=\lambda\left(B_{1} \cap C\right)=$ $\lambda\left(B_{2} \cap C\right)=v\left(B_{2}\right)$. Hence, one can define $P_{0}(X \in B)=v(B)$ for all $B \in \mathscr{D}$ obtaining an f.a.p. $P_{0}$ on $\sigma(X):=\left\{X^{-1}(B): B \in \mathscr{D}\right\}$. Fix $H \in \sigma(X)$ and $G \in \mathcal{A}$ with $H \subset G$. Since $H=\{X \in B\}$ for some $B \in \mathscr{D}$, the second part of condition (8) implies

$$
P_{0}(H)=P_{0}(X \in B)=v(B) \leq P^{*}(X \in B) \leq P(G)
$$

By Theorem 3.6.1 of Bhaskara Rao and Bhaskara Rao (1983), there exists an f.a.p. $Q$ on $\mathcal{P}(\Omega)$ extending both $P$ and $P_{0}$. Thus, $v=Q \circ X^{-1}$, and this proves the "if" part. Finally, the "only if" part is trivial.
5. Empirical processes. In this section, we let $A=\mathbb{N}, D[0,1]$ is the space of real cadlag functions on $[0,1]$, and $l^{\infty}(S)$ is the space of real bounded functions on the set $S$. Both $D[0,1]$ and $l^{\infty}(S)$ are equipped with uniform distance. Among other things, it is shown that the empirical process for an exchangeable sequence can fail to converge, due to the nonexistence of any measurable limit, although it converges for an i.i.d. sequence; see Example 11.

Let $\xi_{1}, \xi_{2}, \ldots$ be i.i.d. random variables, defined on the probability space ( $\Omega, \mathcal{A}, P$ ) and taking values in the measurable space $(\mathcal{X}, \mathscr{B})$. Further, let $\mathcal{F}$ be a class of real measurable functions on $\mathcal{X}$ such that $E\left|f\left(\xi_{1}\right)\right|<\infty$ for all $f \in \mathcal{F}$ and $\sup _{f \in \mathcal{F}}\left|f(x)-E f\left(\xi_{1}\right)\right|<\infty$ for all $x \in \mathcal{X}$. Then, for each $n$, the $n$th empirical process

$$
\begin{equation*}
X_{n}(f)=\sqrt{n}\left(\frac{1}{n} \sum_{i=1}^{n} f\left(\xi_{i}\right)-E f\left(\xi_{1}\right)\right), \quad f \in \mathcal{F}, \tag{9}
\end{equation*}
$$

can be seen as a map $X_{n}: \Omega \rightarrow \mathbb{D}=l^{\infty}(\mathcal{F})$.
A measurable space $(S, \delta)$ is said to be standard if $S$ is a Borel set in some Polish space and $\delta$ the Borel $\sigma$-field on $S$. When $(\Omega, \mathcal{A})$ and $(\mathcal{X}, \mathcal{B})$ are standard spaces, one can conjecture that HJ is equivalent to its strengthened version given by (3). Actually, something more is true, provided $\mathcal{F}$ is rich enough to separate points in a suitable sense. In this case, in fact, $\mathbb{P}_{n}=\mathbb{T}_{n}$ for all $n$, and thus

Theorem 4 implies $X_{n} \xrightarrow{\text { HJ }} X$ if and only if (3) holds. Precisely, the condition on $\mathcal{F}$ is
for all $n$, there is $c_{n}>0$ such that $\sup _{f \in \mathcal{F}}\left|\sum_{i=1}^{n} f\left(u_{i}\right)-\sum_{i=1}^{n} f\left(v_{i}\right)\right| \geq c_{n}$ whenever $\left(u_{1}, \ldots, u_{n}\right)$ is not a permutation of $\left(v_{1}, \ldots, v_{n}\right)$.

Condition (10) holds, for instance, for various significant classes of indicators.
Proposition 9. Suppose $(\Omega, \mathcal{A})$ and $(\mathcal{X}, \mathcal{B})$ are standard spaces, $\mathcal{F}$ meets $(10), \mathbb{D}=l^{\infty}(\mathcal{F})$ and $X_{n}$ is given by (9). Then $\mathbb{P}_{n}=\mathbb{T}_{n}$.

Proof. Let $\phi=\left(\xi_{1}, \ldots, \xi_{n}\right), C \in \mathcal{A}$ and $\Pi$ the set of permutations $\pi$ of $\{1, \ldots, n\}$. By (10), $X_{n}(C)$ is closed in $l^{\infty}(\mathcal{F})$ and thus $X_{n}(C) \in \mathscr{D}$. Also, (10) implies

$$
X_{n}^{-1}\left(X_{n}(C)\right)=\bigcup_{\pi \in \Pi}\left\{\left(\xi_{\pi(1)}, \ldots, \xi_{\pi(n)}\right) \in \phi(C)\right\}
$$

Since $(\Omega, \mathcal{A})$ and $(\mathcal{X}, \mathscr{B})$ are standard spaces, $\phi(C)$ is analytic in $X^{n}$, so that $X_{n}^{-1}\left(X_{n}(C)\right)$ is analytic in $\Omega$, which implies $X_{n}^{-1}\left(X_{n}(C)\right) \in \overline{\mathcal{A}}$. Thus, $X_{n}(C) \in \mathscr{D}_{n}$ for all $C \in \mathcal{A}$. Now, fix $v \in \mathbb{T}_{n}$ and $B \in \mathscr{D}$. If $H \in \mathcal{A}$ and $H \supset$ $\left\{X_{n} \in B\right\}$, then

$$
v\left(B^{c}\right) \geq v\left(X_{n}\left(H^{c}\right)\right)=\mu_{n}\left(X_{n}\left(H^{c}\right)\right) \geq P\left(H^{c}\right),
$$

where the equality is due to $X_{n}\left(H^{c}\right) \in \mathscr{D}_{n}$ and $v=\mu_{n}$ on $\mathscr{D}_{n}$. Hence, $v(B) \leq$ $P(H)$, and this implies $\nu(B) \leq P^{*}\left(X_{n} \in B\right)$. By Proposition 8, it follows that $v \in \mathbb{P}_{n}$, and since $\mathbb{P}_{n} \subset \mathbb{T}_{n}$ this concludes the proof.

Note that, provided $(\mathcal{X}, \mathscr{B})$ is a standard space and (10) holds, Proposition 9 applies, in particular, when $\left\{\xi_{n}\right\}$ is the sequence of coordinate projections on $(\Omega, \mathcal{A})=\left(\mathcal{X}^{\infty}, \mathscr{B}^{\infty}\right)$. Note also that, as far as $X_{n}$ is defined through (9), Proposition 9 holds under any distributional assumption on $\left\{\xi_{n}\right\}$ (and not only if $\left\{\xi_{n}\right\}$ is i.i.d.).

We next give two examples. The first one shows that, as noted in Section 4, it may be that $X_{\alpha} \xrightarrow{d} X$ while no $X_{\alpha}$ admits a countably additive distribution on $\mathcal{D}$.

Example 10. Let $X_{n}$ be given by (9), where $\mathcal{X}=[0,1], \mathscr{B}$ is the Borel $\sigma$-field on $[0,1], \mathcal{F}=\left\{I_{[0, t]}: t \in[0,1]\right\}$ and $\left\{\xi_{n}\right\}$ is i.i.d. with $P\left(\xi_{1}=t\right)=0$ for all $t$. Clearly, by identifying $X_{n}(t)$ with $X_{n}\left(I_{[0, t]}\right), X_{n}$ can be seen as a map $X_{n}: \Omega \rightarrow \mathbb{D}=D[0,1]$. It is well known that $X_{n} \xrightarrow{\mathrm{HJ}} X$, where $X$ is a (scaled) Brownian bridge process, so that $X_{n} \xrightarrow{d} X$ by Theorem 4 . Note also that $\mathcal{F}$ meets (10), and thus, if ( $\Omega, \mathcal{A}$ ) is a standard space, Proposition 9 yields $v_{n} \rightarrow \mu$
weakly whenever $v_{n} \in \mathbb{T}_{n}$ for all $n$. As a contradiction, suppose now that the partial distribution $\mu_{n}$ of $X_{n}$ admits a countably additive extension to $\mathscr{D}$, say $\lambda_{n}$. Let

$$
\begin{aligned}
& J=\{x \in D[0,1]: x \text { has precisely } n \text { jumps }\}, \\
& U_{B}=\left\{x \in D[0,1]: \exists 0<t_{1}<\cdots<t_{n} \leq 1\right. \text { with } \\
&\left.\qquad \sum_{i=1}^{n} t_{i} \in B \text { and } x\left(t_{i}\right) \neq x\left(t_{i}-\right) \text { for all } i\right\} \\
& \quad \text { where } B \subset(0, n] .
\end{aligned}
$$

Since $U_{B}$ is open, one can define $\gamma_{n}(B)=\lambda_{n}\left(U_{B}\right)$ for all $B \subset(0, n]$. On noting that $U_{B} \cap U_{C} \cap J=\varnothing$ if $B \cap C=\varnothing$ and

$$
\mu_{n}(J)=\bar{P}\left(X_{n} \in J\right)=P\left(\xi_{1}, \ldots, \xi_{n} \text { all distinct and strictly positive }\right)=1
$$

it follows that $\gamma_{n}$ is a countably additive probability on $\mathcal{P}((0, n])$. Further, $\gamma_{n}(B)=$ $P\left(\sum_{i=1}^{n} \xi_{i} \in B\right)$ whenever $B$ is a Borel set, and thus $\gamma_{n}\{v\}=0$ for all $v \in(0, n]$. Therefore, the existence of a countably additive extension of $\mu_{n}$ to $\mathscr{D}$ implies the existence of a countably additive probability $\gamma_{n}$ on $\mathcal{P}((0, n])$ vanishing on singletons. But the latter fact is impossible in various models of the usual ZFC set theory. For instance, by Ulam's theorem, it is impossible under the continuum hypothesis.

Finally, let us turn to the second example, which is one of the basic motivations for extending HJ to the case of a nonmeasurable limit, as done in Section 4.

A random distribution function is a process, indexed by $\mathbb{R}$, whose paths are distribution functions. In the rest of the paper, $X^{F}$ denotes a process, on some probability space $\left(\Omega_{0}, \mathcal{A}_{0}, P_{0}\right)$, of the form

$$
X_{t}^{F}=W_{F(t)}^{0}, \quad t \in[0,1],
$$

where $W^{0}$ is a Brownian bridge process and $F$ a random distribution function independent of $W^{0}$. Let $\mathbb{D}=D[0,1]$ and let $\mathscr{D}_{b}$ denote the $\sigma$-field on $D[0,1]$ generated by the balls. Then $X^{F}: \Omega_{0} \rightarrow D[0,1]$ is measurable w.r.t. $\mathscr{D}_{b}$ but can fail to be measurable w.r.t. $\mathcal{D}$. Setting $C(I)=\{x \in D[0,1]: x(t)=x(t-)$ for all $t \in I\}$, where $I \subset(0,1]$, a set $B \subset D[0,1]$ is separable if and only if $B \subset C(I)$ for some $I$ such that $(0,1]-I$ is countable. Thus, $X^{F}$ has separable range whenever the $F$-paths have jumps within a fixed countable set. In this case, $X^{F}$ is measurable and tight (i.e., its probability distribution is tight). In particular, $X^{H}$ is measurable for any fixed (i.e., nonrandom) distribution function $H$. Let $\mu(\cdot, H)=P_{0}\left(X^{H} \in \cdot\right)$ be the probability distribution of $X^{H}$. For later purposes, note that $\mu(C(I), H)=0$ if $0<H(t)-H(t-)<1$ for some $t \in I$. We are now able to give the example.

Example 11. Let $\xi_{n}$ be the $n$th coordinate projection on $\left([0,1]^{\infty}, \mathscr{B}^{\infty}, P\right)$, where $\mathscr{B}$ is the Borel $\sigma$-field on $[0,1]$, and suppose that $\left\{\xi_{n}\right\}$ is exchangeable under $P$. By de Finetti's theorem,

$$
P(B)=\int P_{u}(B) P(d u) \quad \text { for all } B \in \mathscr{B}^{\infty}
$$

where, for all $u \in[0,1]^{\infty}, P_{u}$ is a law on $\mathscr{B}^{\infty}$ such that $\left\{\xi_{n}\right\}$ is i.i.d. under $P_{u}$. Letting $G(u, t)=P_{u}\left(\xi_{1} \leq t\right)$ [and using the standard notation $G(t)=G(\cdot, t)$ and $G(u)=G(u, \cdot)]$, the $n$th empirical process can be defined as

$$
X_{n}(t)=\sqrt{n}\left(\frac{1}{n} \sum_{i=1}^{n} I_{\left\{\xi_{i} \leq t\right\}}-G(t)\right), \quad t \in[0,1]
$$

Let the process $X^{F}$ be defined on $\left(\Omega_{0}, \mathcal{A}_{0}, P_{0}\right)$, where the random distribution function $F$ is distributed as $G$. Then the probability distribution of $X^{F}$ on $\mathscr{D}_{b}$, say $\mu_{b}$, can be expressed as

$$
\mu_{b}(B)=P_{0}\left(X^{F} \in B\right)=\int \mu(B, G(u)) P(d u) \quad \text { for all } B \in \mathscr{D}_{b}
$$

By the classical result for i.i.d. sequences, for almost all $u$, one has $X_{n} \xrightarrow{\mathrm{HJ}}$ $X^{G(u)}$ under $P_{u}$. Hence, for each bounded continuous $\mathscr{D}_{b}$-measurable function $f$ on $D[0,1]$, one obtains

$$
\begin{align*}
\lim _{n} E f\left(X_{n}\right) & =\lim _{n} \int E_{u} f\left(X_{n}\right) P(d u)=\int \lim _{n} E_{u} f\left(X_{n}\right) P(d u) \\
& =\iint f(x) \mu(d x, G(u)) P(d u)=E_{0}\left(f\left(X^{F}\right)\right), \tag{11}
\end{align*}
$$

where $E_{u}$ and $E_{0}$ denote expectation w.r.t. $P_{u}$ and $P_{0}$. It follows that $X_{n} \xrightarrow{\mathrm{HJ}} X^{F}$ provided $\left(\Omega_{0}, \mathcal{A}_{0}, P_{0}\right)$ and $X^{F}$ can be taken such that $X^{F}$ is measurable and tight. In particular, this happens if $\xi_{1}$ has a discrete distribution or if $P\left(\xi_{1}=\xi_{2}\right)=0$. See Theorem 1.7.2 of van der Vaart and Wellner (1996) and Theorem 4.5 of Berti, Pratelli and Rigo (2004).

Now, let us take $P$ such that $\left\{\xi_{n}\right\}$ is exchangeable, $P\left(\xi_{1}=t\right)=0$ for all $t$ and

$$
G(u, t)=P_{u}\left(\xi_{1} \leq t\right)=\frac{1}{2}\left(t+I_{[0, t]}\left(\xi_{1}(u)\right)\right) \quad \text { for } t \in[0,1] \text { and } u \in[0,1]^{\infty}
$$

If $B \in \mathscr{D}$ is separable, then $B \in \mathscr{D}_{b}$ and $B \subset C(I)$ for some $I \subset(0,1]$ such that $(0,1]-I$ is countable. Since $G(u)$ has a jump of size $\frac{1}{2}$ at $\xi_{1}(u)$ if $\xi_{1}(u)>0$, one has $\mu(B, G(u)) \leq \mu(C(I), G(u))=0$ if $\xi_{1}(u) \in I$, and thus

$$
\mu_{b}(B)=\int_{\left\{\xi_{1} \in I\right\}} \mu(B, G(u)) P(d u)=0 .
$$

If $\mu_{b}$ admits a countably additive extension to $\mathscr{D}$, then, since $\mu_{b}$ vanishes on separable Borel sets, $D[0,1]$ has measurable cardinality; see Dudley (1999),
page 403. But this is impossible in various models of ZFC. For instance, since $\operatorname{card} D[0,1]=\operatorname{card} \mathbb{R}$, it is impossible under the continuum hypothesis. As a consequence, no measurable random element $X$ of $D[0,1]$, defined on any probability space, satisfies $X_{n} \xrightarrow{\mathrm{HJ}} X$. In view of (11), in fact, the distribution of such $X$ would be a countably additive probability on $\mathscr{D}$ which extends $\mu_{b}$.

In Example 11, $X_{n}$ can fail to converge according to HJ , due to the nonexistence of any measurable limit, even if $X_{n} \xrightarrow{\mathrm{HJ}} X^{G(u)}$ under $P_{u}$ for almost all $u$. An obvious question is whether $X_{n} \rightarrow v$, for some $v \in \mathbb{P}$, according to Definition 5 . Our conjecture is that the answer is affirmative, and one reason is the following.

Let $L$ be the space of bounded continuous $\mathscr{D}_{b}$-measurable functions on $D[0,1]$, and for $f \in L$ let $T(f)=E_{0}\left(f\left(X^{F}\right)\right)=\int f d \mu_{b}$. If $B \subset D[0,1]$ and $f \leq I_{B} \leq g$ for some $f, g \in L$, then (11) yields

$$
T(f)=\lim _{n} E f\left(X_{n}\right) \leq \limsup _{n} P^{*}\left(X_{n} \in B\right) \leq \lim _{n} E g\left(X_{n}\right)=T(g),
$$

so that $T_{*}\left(I_{B}\right) \leq \lim \sup _{n} P^{*}\left(X_{n} \in B\right) \leq T^{*}\left(I_{B}\right)$. This inequality gives some hope of successfully applying Proposition 7. Suppose, in fact, that, for given closed sets $F_{1}, \ldots, F_{k}$, there is a linear functional $U$ on the linear span $M$ of $I_{F_{1}}, \ldots, I_{F_{k}}$ such that

$$
\begin{array}{rlrl}
U(g) \geq T_{*}(g) & \text { for all } g \in M, \\
\limsup _{n} P^{*}\left(X_{n} \in F_{i}\right) \leq U\left(I_{F_{i}}\right) & & \text { for } i=1, \ldots, k .
\end{array}
$$

Then Lemma 2 grants the existence of $\gamma \in \mathbb{P}$ satisfying

$$
T(f)=\int f d \gamma \quad \text { for all } f \in L
$$

and

$$
U\left(I_{F_{i}}\right)=\gamma\left(F_{i}\right) \quad \text { for } i=1, \ldots, k,
$$

and in turn Proposition 7 implies $X_{n} \rightarrow v$ for some $v \in \mathbb{P}$. The point, thus, is the existence of a certain linear functional $U$ on $M$. For $k=1$, such $U$ surely exists. We suspect it exists for any $k$, but we do not have a proof.

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