

Local times and Tanaka–Meyer formulae for càdlàg paths*

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Abstract

Three concepts of local times for deterministic càdlàg paths are developed and the corresponding pathwise Tanaka–Meyer formulae are provided. For semimartingales, it is shown that their sample paths a.s. satisfy all three pathwise definitions of local times and that all coincide with the classical semimartingale local time. In particular, this demonstrates that each definition constitutes a legit pathwise counterpart of probabilistic local times. The last pathwise construction presented in the paper expresses local times in terms of normalized numbers of interval crossings and does not depend on the choice of the sequence of grids. This is a new result also for càdlàg semimartingales, which may be related to previous results of Nicole El Karoui [11] and Marc Lemieux [23].

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1 Introduction

Stochastic calculus, with its foundational notions developed by Kyiosi Itô in the 1940s, is a *par excellence* probabilistic endeavour. The stochastic integral, the integration by parts formula – these basic building blocks are to be understood almost surely, and so is the edifice they span. This thinking has proved to be exceedingly powerful and fruitful, and underpins many beautiful developments in probability theory since

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then. Nevertheless, for decades now, mathematicians have been trying to develop a more analytic, pathwise understanding of these probabilistic objects. On one hand, this was, and is, driven by mathematical curiosity. The classical calculus remains an irresistible reference point and, e.g., in developing a notion of an integral it is important to understand when and how it can be seen as a limit of its Riemann sums. On the other hand, this was, and is, driven by applications. Stochastic differential equations have become a ubiquitous tool for mathematical modelling from physics, through biology to finance. Yet, they do not offer the same level of path-by-path description of the system’s evolution as the classical differential equations do. This becomes particularly problematic if one needs to work simultaneously with many probability measures, possibly mutually singular. One field where this proves important, and which has driven renewed interest in pathwise stochastic calculus, is robust mathematical finance, see for example [8] and the references therein. Both of the above reasons – mathematical curiosity and possible applications – are important for us. We add to this literature and develop a pathwise approach to stochastic calculus for càdlàg paths using local times.

In his seminal paper [14], Föllmer introduced, for twice continuously differentiable $f: \mathbb{R} \rightarrow \mathbb{R}$, a non-probabilistic version of the Itô formula

$$f(x_t) - f(x_0) = \int_0^t f'(x_{s-}) dx_s + \frac{1}{2} \int_0^t f''(x_s) d[x]_s^c + J_t^f(x), \quad t \in [0, T],$$

where $x: [0, T] \rightarrow \mathbb{R}$ is càdlàg and possesses a suitably defined quadratic variation $[x]$ such that, for $0 \leq t \leq T$,

$$[x]_t = [x]_t^c + \sum_{0 < s \leq t} (\Delta x_s)^2, \quad \text{where } \Delta x_t := x_t - x_{t-},$$

and $J_t^f(x)$ is defined by the following absolutely convergent series

$$J_t^f(x) := \sum_{0 < s \leq t} (\Delta f(x_s) - f'(x_{s-}) \Delta x_s).$$

In particular, this leads to a pathwise definition of the “stochastic” integral $\int_0^t f'(x_{s-}) dx_s$, assuming $[x]$ exists. Soon after, Stricker [35], showed that one could not extend the above to all continuous functions f . This could only be done adopting a much more bespoke discretisation and probabilistic methods, see for example [3, 19]. Accordingly, the main remaining challenge was to understand the case of functions f which are not twice continuously differentiable but are weakly differentiable, in some sense. In probabilistic terms, this realm is covered by the Tanaka–Meyer formula.

For continuous paths Föllmer’s pathwise Itô formula was generalized to a pathwise Tanaka–Meyer formulae in the early work of [36] and more recently in [29] and in [9], who offered a comprehensive study. Furthermore, we refer to [16] and [2, 8] for related work in a pathwise spirit. Our contribution here is to study this problem for càdlàg paths. Jump processes, e.g., Lévy processes, are of both theoretical and practical importance and, as stressed above, our study is motivated by both mathematical curiosity as well as applications. Already in the classical, probabilistic, setting stochastic calculus for jump processes requires novel insights over and above the continuous case. This was also observed in recent works focusing on Föllmer’s Itô calculus for càdlàg paths, see [5] and [17]. We face the same difficulty, which of course makes our study all the more interesting. In particular, we need more information and new ideas to handle jumps. This is consistent with the definition of quadratic variation for càdlàg paths, cf. [5].

Our non-probabilistic versions of Tanaka–Meyer formula, extend the above Itô formula allowing for functions f with weaker regularity assumptions than C^2 . More precisely,

we derive pathwise formulae

$$f(x_t) - f(x_0) = \int_0^t f'(x_{s-}) dx_s + \frac{1}{2} \int_{\mathbb{R}} L_t(x, u) f''(du) + J_t^f(x), \quad t \in [0, T],$$

for twice weakly differentiable functions f , supposing that the càdlàg path x possesses a suitable pathwise local time $L(x)$. As in the case of the Itô formula, there exists no unique pathwise sense to understand such a formula, see also Remark 2.14 below. We develop three natural pathwise approaches to local times and, consequently, to their stochastic calculus. First, we start with the key property relating local times and quadratic variation: the time-space occupation formula, and use it to define pathwise local times. Second, in the spirit of [14, 36], we discretise the path along a sequence of partitions and obtain local times as limits of discrete level crossings and stochastic integrals as limits of their Riemann sums. Finally, we discretise the integrand via the Skorokhod map which provides a natural approximation of the “stochastic” integral and links to the concept of truncated variation. In all of the three cases we show that a pathwise variant of the Tanaka–Meyer formula holds. Further, we prove that for a càdlàg semimartingale, all three constructions coincide a.s. with classical local times. This shows that all three approaches are legitimate extensions of the classical stochastic results to pathwise analysis. Each has its merits and limitations which we explore in detail. Our aim is to provide a comprehensive understanding of how to deal with jumps in the context of pathwise Tanaka–Meyer formulae. We thus do not seek further extensions of the setup, e.g., to cover time-dependent functions f , cf. [12], path-dependent functions, cf. [6, 18, 34], nor to develop higher order local times in the spirit of [7] for càdlàg paths. These, while interesting, would distract from the main focus of the paper and are left as avenues for future research.

Outline: In Section 2 we propose three notions of local times for càdlàg paths and establish the corresponding Tanaka–Meyer formulae. Then, in Section 3, we show that sample paths of semimartingales almost surely possess such local times and all three definitions agree a.s. in the classical stochastic world.

2 Pathwise local times and Tanaka–Meyer formulae

The first non-probabilistic version of Itô’s formula and the corresponding notion of pathwise quadratic variation of càdlàg paths was introduced by H. Föllmer in the seminal paper [14]. Before providing non-probabilistic versions of Tanaka–Meyer formulae and introducing the corresponding pathwise local times, we recall in the next subsection some results from [14].

2.1 Quadratic variation and the Föllmer–Itô formula

For $T \in (0, \infty)$, let $D([0, T]; \mathbb{R})$ be the space of all càdlàg (RCLL) functions $x: [0, T] \rightarrow \mathbb{R}$, that is, x is right-continuous and possesses finite left-limits at each $t \in [0, T]$. For $x \in D([0, T]; \mathbb{R})$ we set $x_{t-} := \lim_{s \uparrow t} x_s$ for $t \in (0, T]$, $x_{0-} := x_0$ and $\Delta x_s := x_s - x_{s-}$ for $s \in [0, T]$.

In order to define the summation over the jumps of a càdlàg function, we need the concept of summation over general sets, see for example [21, p.77–78]. Let I be a set, let $b: I \rightarrow \mathbb{R}$ be a real valued function and let \mathcal{I} be the family of all finite subsets of I . Since \mathcal{I} is directed when endowed with the order of inclusion \subseteq , the summation over I can be defined by

$$\sum_{i \in I} b_i := \lim_{\Gamma \in \mathcal{I}} \sum_{i \in \Gamma} b_i \tag{2.1}$$

as limit of a net, i.e., $\lim_{\Gamma \in \mathcal{I}} \sum_{i \in \Gamma} b_i =: l \in [-\infty, \infty]$ exists if, for any neighbourhood¹ V_l of l , there is $\Gamma \in \mathcal{I}$ such that for all $\tilde{\Gamma} \in \mathcal{I}$ such that $\tilde{\Gamma} \geq \Gamma$ (i.e., $\tilde{\Gamma} \supseteq \Gamma$) one has $\sum_{i \in \tilde{\Gamma}} b_i \in V_l$. If $b_i \geq 0$ for all $i \in I$, then it is easy to see that

$$\exists \sum_{i \in I} b_i = \sup \left\{ \sum_{i \in J} b_i : J \in \mathcal{I} \right\} \in [0, \infty]. \tag{2.2}$$

We say that the series $\sum_{i \in I} b_i$ is *absolutely summable* if the limit $\sum_{i \in I} |b_i|$ (which always exists, by (2.2)) is finite, in which case also the limit (2.1) exists and satisfies $|\sum_{i \in I} b_i| \leq \sum_{i \in I} |b_i|$, and there exists² a countable subset $K \subseteq I$ s.t. $b_i = 0$ if $i \in I \setminus K$.

For a continuous function $f: \mathbb{R} \rightarrow \mathbb{R}$ possessing a left-derivative f' , we now set

$$J_t^f(x) := \sum_{0 < s \leq t} (\Delta f(x_s) - f'(x_{s-}) \Delta x_s), \tag{2.3}$$

provided the sum exists. Furthermore, the space of continuous functions $f: \mathbb{R} \rightarrow \mathbb{R}$ is denoted by $C(\mathbb{R}) := C(\mathbb{R}; \mathbb{R})$, the space of twice continuously differentiable functions by $C^2(\mathbb{R}) := C^2(\mathbb{R}; \mathbb{R})$ and the space of smooth functions by $C^\infty(\mathbb{R}) := C^\infty(\mathbb{R}; \mathbb{R})$.

A *partition* $\pi = (t_j)_{j=0}^N$ is a finite sequence such that $0 = t_0 < t_1 < \dots < t_N = T$ (for some $N \in \mathbb{N}$). We write $|\pi| := \max_{j \in \mathbb{N}} |t_j - t_{j-1}|$ for its mesh size and define $\pi(t) := \pi \cap [0, t]$ the restriction of π to $[0, t]$. A sequence of partitions $(\pi^n)_{n \in \mathbb{N}}$ is said to be *refining* if for all $t_j \in \pi^n$ we also have $t_j \in \pi^{n+1}$ and a refining sequence $(\pi^n)_{n \in \mathbb{N}}$ is said to exhaust the jumps of x if for all $t \in [0, T]$ with $\Delta x_t \neq 0$, $t \in \pi^n$ for n large enough. The Dirac measure at $t \in [0, T]$ is denoted by δ_t .

Definition 2.1. Let $(\pi^n)_n$ be a sequence of partitions such that $\lim_{n \rightarrow \infty} |\pi^n| = 0$. A function $x \in D([0, T]; \mathbb{R})$ has quadratic variation $[x]$ along $(\pi^n)_n$ if the sequence of discrete measures

$$\mu_n := \sum_{t_j \in \pi^n} (x_{t_{j+1}} - x_{t_j})^2 \delta_{t_j}$$

converges weakly³ to a finite⁴ measure μ such that the jumps of the (increasing, càdlàg) function $[x]_t := \mu([0, t])$ are given by $\Delta[x]_t = (\Delta x_t)^2$ for all $t \in [0, T]$. $\mathbb{Q}((\pi^n)_n)$ denotes the set of functions in $D([0, T]; \mathbb{R})$ having a quadratic variation along $(\pi^n)_n$.

For $x \in \mathbb{Q}((\pi^n)_n)$, we write $[x]^c$ and $[x]^d$ for the continuous and purely discontinuous parts of the càdlàg function $[x]$ and note that by the above definition we have

$$[x]_t^d = \sum_{0 < s \leq t} (\Delta x_s)^2, \quad 0 < t \leq T.$$

We now recall Föllmer’s pathwise version of Itô’s formula for paths in $\mathbb{Q}((\pi^n)_n)$. Here and throughout, \int_0^t stands for $\int_{(0,t]}$ and increasing is understood as non-decreasing.

Theorem 2.2 ([14]). Let $x \in \mathbb{Q}((\pi^n)_n)$ and $f \in C^2(\mathbb{R})$. Then, the pathwise Itô formula

$$f(x_t) - f(x_0) = \int_0^t f'(x_{s-}) dx_s + \frac{1}{2} \int_0^t f''(x_s) d[x]_s^c + J_t^f(x), \quad t \in [0, T], \tag{2.4}$$

¹The space $[-\infty, \infty]$ is given the usual topology which makes it isomorphic to $[-1, 1]$; in particular one can take $(x - \varepsilon, x + \varepsilon)$ (resp. $(M, +\infty)$, resp. $(-\infty, -M)$), where $0 < \varepsilon < 1 < M < \infty$, as a neighbourhood basis of $x \in \mathbb{R}$ (resp. $+\infty$, resp. $-\infty$), and metrize this topology with the distance $d(x, y) := \arctan(|x - y|)$, where $\arctan(\pm\infty) := \pm\frac{\pi}{2}$, $x, y \in [-\infty, \infty]$.

²Since $I_n := \{i \in I : |b_i| \geq 1/n\}$ is finite for each n , because $\frac{\#I_n}{n} \leq \sum_{i \in I_n} |b_i| \leq \sum_{i \in I} |b_i| < \infty$.

³Meaning that $\int_0^T h d\mu_n \rightarrow \int_0^T h d\mu$ for every continuous $h: [0, T] \rightarrow \mathbb{R}$.

⁴If we were working on the unbounded time interval $[0, \infty)$ instead of $[0, T]$, we would have to ask, following [14], that μ is Radon (i.e., finite on compacts) and that $\mu_n \rightarrow \mu$ vaguely (i.e., $\int h d\mu_n \rightarrow \int h d\mu$ for every continuous h with compact support).

holds with $J_t^f(x)$ as in (2.3), and with

$$\int_0^t f'(x_{s-}) dx_s := \lim_{n \rightarrow \infty} \sum_{t_j \in \pi^n(t)} f'(x_{t_j})(x_{t_{j+1}} - x_{t_j}), \quad t \in [0, T], \quad (2.5)$$

where the series in (2.3) is absolutely convergent and the limit in (2.5) exists.

We note that, to define $\int_0^t f'(x_{s-}) dx_s$, Föllmer [14] takes limits of sums of the form

$$\sum_{\pi^n \ni t_j \leq t} g(x_{t_j})(x_{t_{j+1}} - x_{t_j}), \text{ whereas we consider } \sum_{t_j \in \pi^n} g(x_{t_j})(x_{t_{j+1} \wedge t} - x_{t_j \wedge t}).$$

This however has no consequences, since the difference between these two sums is

$$g(x_{t_c(\pi^n, t)})(x_{t_{c(\pi^n, t)+1}} - x_t), \quad \text{where } c(\pi, t) := \max\{j : \pi \ni t_j \leq t\},$$

which goes to zero as $|\pi^n| \rightarrow 0$ since g is bounded on $[\inf_{t \in [0, T]} x_t, \sup_{t \in [0, T]} x_t]$, x is càdlàg and $t < t_{c(\pi, t)+1} \leq t + |\pi|$. In consequence, Föllmer’s pathwise Itô formula (2.4) holds also with our definition of $\int_0^t f'(x_{s-}) dx_s$ and we shall exploit it in our proofs. Notice that analogously

$$\sum_{\pi^n \ni t_j \leq t} g(x_{t_j})(x_{t_{j+1}} - x_{t_j})^2 \quad \text{and} \quad \sum_{t_j \in \pi^n} g(x_{t_j})(x_{t_{j+1} \wedge t} - x_{t_j \wedge t})^2$$

differ by

$$g(x_{t_c})((x_{t_{c+1}} - x_{t_c})^2 - (x_t - x_{t_c})^2), \quad \text{with } c = c(\pi^n, t),$$

which goes to zero as $|\pi^n| \rightarrow 0$.

2.2 Local time via occupation measure

In order to extend the Itô formula for twice continuously differentiable functions f to twice weakly differentiable functions f , the notion of quadratic variation is not sufficient and the concept of local time is required. In probability theory there exist various classical approaches to define local times of stochastic processes. In the present deterministic setting, we first introduce a pathwise local time corresponding to the notation of local time as an occupation measure with respect to the quadratic variation.

The space of q -integrable (equivalence classes of) functions $g: \mathbb{R} \rightarrow \mathbb{R}$ is denoted by $L^q(\mathbb{R}) := L^q(\mathbb{R}; \mathbb{R})$ with corresponding norm $\|\cdot\|_{L^q}$ for $q \in [1, \infty]$ and $W^{k, q}(\mathbb{R}) := W^{k, q}(\mathbb{R}; \mathbb{R})$ stands for the Sobolev space of functions $g: \mathbb{R} \rightarrow \mathbb{R}$ which are k -times weakly differentiable in $L^q(\mathbb{R})$, for $k \in \mathbb{N}$. Moreover, $L^q(K; \mathbb{R})$ is the space of q -integrable functions $f: K \rightarrow \mathbb{R}$ for a Borel set $K \subset \mathbb{R}$ and we recall the left-continuous sign-function

$$\text{sign}(x) := \begin{cases} 1 & \text{if } x > 0 \\ -1 & \text{if } x \leq 0 \end{cases}.$$

We define, for $a, b \in \mathbb{R}$,

$$[[a, b]] := \begin{cases} [a, b] & \text{if } a \leq b \\ [b, a] & \text{if } a > b \end{cases} \quad \text{with } [a, a] := \emptyset.$$

Definition 2.3. Let $x \in \mathbb{Q}((\pi^n)_n)$. A Borel function $L(x, \cdot): [0, T] \times \mathbb{R} \rightarrow [0, \infty)$ is called the occupation local time of x if

$$\int_{-\infty}^{\infty} g(u) L_t(x, u) du = \int_0^t g(x_s) d[x]_s^c, \quad t \in [0, T], \quad (2.6)$$

holds for any positive Borel function $g: \mathbb{R} \rightarrow [0, \infty)$.

Naturally, this approach to local time is not new, see for example [1]. To extend Itô’s formula to a Tanaka–Meyer formula, as, e.g., in [31], we will consider the quantity

$$J_t(x, \cdot) := J_t^{f_u}(x), \quad \text{where } f_u := |\cdot - u|/2.$$

We will, at times, drop x from the notation, and simply write $L_t(u)$ and $J_t(u)$. It is straightforward to verify⁵ that

$$|x_s - u| - |x_{s-} - u| - \text{sign}(x_{s-} - u)\Delta x_s = 2|x_s - u|\mathbf{1}_{\llbracket x_{s-}, x_s \rrbracket}, \tag{2.7}$$

which yields the useful compact expression

$$J_t(x, u) = \sum_{0 < s \leq t} |x_s - u|\mathbf{1}_{\llbracket x_{s-}, x_s \rrbracket}(u), \quad u \in \mathbb{R}, \tag{2.8}$$

which readily implies that J is a positive and increasing function. In particular, see Remark 2.7 below, $L_t(\cdot)/2 + J_t(\cdot) \in L^p(\mathbb{R})$ if and only if $L_t(\cdot), J_t(\cdot) \in L^p(\mathbb{R})$. Notice that x is bounded, since it is càdlàg, and $L_t(u)$ and $J_t(u)$ equal 0 if u does not belong to the compact set $[\inf_{s \in [0, T]} x_s, \sup_{s \in [0, T]} x_s]$.

Definition 2.4. We let $\mathbb{L}_p((\pi^n)_n)$ denote the set of all paths $x \in \mathbb{Q}((\pi^n)_n)$ having an occupation local time L and such that $K_t(x, \cdot) := L_t(x, \cdot)/2 + J_t(x, \cdot) \in L^p(\mathbb{R})$ for all $t \in [0, T]$.

There is no common agreement in the related literature in probability theory as to whether L or $L/2$ is to be called local time, cf. [20, Remark 6.4]; here we decided to follow the convention made in the standard textbook [31]. A classical approach to extend Itô’s formula and, in particular, the “stochastic” integral $\int_0^t f'(x_{s-}) dx_s$ to twice weakly differentiable functions f , is to approximate the function f by smooth functions, cf. [20, Theorem 3.6.22] for the case of Brownian motion. For this purpose we consider a “mollifier” ρ , i.e., a positive function $\rho \in C^\infty(\mathbb{R})$ and such that $\int_{-\infty}^\infty \rho(u) du = 1$, and set $\rho_n(u) := n\rho(nu)$ for $n \in \mathbb{N}$. Given a function $f \in W^{2,q}(\mathbb{R})$ we approximate it via the convolution $f_n := \rho_n * f$. In this way, $f_n \in C^2(\mathbb{R})$, $f_n \rightarrow f$ in $W^{2,q}(\mathbb{R})$ if $q < \infty$ (if $q = \infty$ this is true if one assumes f'' is continuous) and, in particular, $\lim_{n \rightarrow \infty} f_n(x) = f(x)$ for $x \in \mathbb{R}$.

Proposition 2.5. Let $x \in \mathbb{L}_p((\pi^n)_n)$ and $f \in W^{2,q}(\mathbb{R})$ with $1/p + 1/q \geq 1$ and $q \in [1, \infty)$. Then, the series (2.3) defining $J_t^f(x)$ is absolutely convergent, $\int_0^t f'_n(x_{s-}) dx_s$ defined by (2.5) converges to the finite limit

$$\int_0^t f'(x_{s-}) dx_s := \lim_{n \rightarrow \infty} \int_0^t f'_n(x_{s-}) dx_s, \quad t \in [0, T], \tag{2.9}$$

which does not depend on the choice of ρ , and the pathwise Tanaka–Meyer formula

$$f(x_t) - f(x_0) = \int_0^t f'(x_{s-}) dx_s + \frac{1}{2} \int_{\mathbb{R}} L_t(x, u) f''(du) + J_t^f(x), \quad t \in [0, T], \tag{2.10}$$

holds with such definition of $\int_0^t f'(x_{s-}) dx_s$.

The statements hold for $q = \infty$ if f'' is continuous.

Because of Proposition 2.5, it is of interest to ask under which assumptions one can get that $L_t(x, \cdot)$ and $J_t(x, \cdot)$ are in $L^p(\mathbb{R})$. First, remark that, since both quantities are equal to 0 outside a compact, the p -integrability requirement in Definition 2.4 is a local one. Then, notice that if $x \in \mathbb{Q}((\pi^n)_n)$ has an occupation local time then $L_t, J_t \in L^1(\mathbb{R})$ (i.e., $x \in \mathbb{L}_1((\pi^n)_n)$), since

$$\int_{\mathbb{R}} L_t(x, u) du = [x]_t^c < \infty, \quad \int_{\mathbb{R}} J_t(x, u) du = \frac{1}{2} [x]_t^d < \infty.$$

⁵Either checking separately the six cases where $u \leq x_{s-} \leq x_s, x_{s-} \leq u \leq x_s$ etc., or using the identity (2.12) with the function $f_u(\cdot) := |\cdot - u|/2$ and noting that $f'_u(\cdot) = \text{sign}(\cdot - u)$.

Remark 2.6. If $p \in [1, \infty)$ and $C_p := 1/(p + 1)^{1/p}$ then

$$\|J_t(x, \cdot)\|_{L^p} \leq C_p \sum_{0 < s \leq t} |\Delta x_s|^{1 + \frac{1}{p}}.$$

This can be seen as a consequence of Minkowski’s integral inequality and of the identity

$$\int_{[a, b]} |b - u|^p \, du = \frac{|b - a|^{p+1}}{p + 1}. \tag{2.11}$$

A similar bound for L can be given under the stronger assumption $x \in \mathbb{L}_p^W((\pi^n)_n)$, see Definition 2.17 and equation (2.22) in the next subsection. Alternatively, if $x \in \mathbb{L}_1((\pi^n)_n)$, then p -summability for L , for $p \in (1, \infty)$, is equivalent to:

$$\|L_t(x, \cdot)\|_{L^p} = \sup \left\{ \int_0^t g(x_s) \, d[x]_s^c : \|g\|_{L^q} \leq 1 \right\} < \infty.$$

Notice that an occupation local time L is only unique up to equality a.e.⁶ u for each t ; in particular, L could be thought of as an equivalence class, and one is then led to look for good representatives. In particular, it is often of interest to have a version L which is càdlàg in t . This can be ensured along the same lines as standard results on càdlàg version of supermartingales since $L_s \leq L_t$ a.e. for any $0 \leq s \leq t$, $L_t \in L^1(\mathbb{R})$ for all t and $t \mapsto \int_{\mathbb{R}} L_t(u) \, du = [x]_t^c$ is continuous. Similarly, existence of a càdlàg version for J follows from the fact that $J_T(u) < \infty$ for a.e. u , that x is càdlàg and that $J_t(x, \cdot)$, see (2.8), is defined using jumps of x up to and including time t .

Remark 2.7. If x has an occupation local time L , then one can choose for each $t \in [0, T]$ a version $\tilde{L}_t(\cdot)$ of L_t such that $\tilde{L}_t(u)$ is positive, finite, càdlàg and increasing for each $u \in \mathbb{R}$. Moreover, $J_t(u)$ is positive, finite and càdlàg increasing for a.e. u . In particular, it follows that $L_t(\cdot), J_t(\cdot) \in L^p(\mathbb{R})$ holds for every $t \in [0, T]$ if and only if $L_T(\cdot), J_T(\cdot) \in L^p(\mathbb{R})$.

It can also be useful to have right-continuity of L, J in the variable u . For J here is a simple criterion; for L , it has to be assumed: cf. Remark 2.15 below.

Remark 2.8. Notice that

$$\text{TV}(J_t(x, \cdot), \mathbb{R}) := \sup \left\{ \sum_{i=0}^{N-1} |J_t(x, u_{i+1}) - J_t(x, u_i)| : (u_i)_{i=0}^N \subset \mathbb{R}, N \in \mathbb{N} \right\} \leq \sum_{0 < s \leq t} |\Delta x_s|,$$

and so if $\sum_{0 < s \leq t} |\Delta x_s| < \infty$ for all t , then $J_t(x, \cdot)$ is càdlàg and of finite variation for all $t \in [0, T]$.

As an application of having a version \tilde{L} of L which is càdlàg in t , notice that the occupation time formula (2.6) then extends to all positive Borel $h = h(s, u)$ as follows

$$\int_{-\infty}^{\infty} \left(\int_0^t h(s, u) \, d\tilde{L}_s(x, u) \right) \, du = \int_0^t h(s, x_s) \, d[x]_s^c, \quad t \in [0, T].$$

Moreover, since J is càdlàg in t it also satisfies a restricted occupation time formula: if $h = h(s, u)$ is a positive Borel function such that $h(s, u) = h(s, x_s)$ for a.e. $u \in [x_{s-}, x_s]$, then Fubini’s theorem gives that

$$\int_{-\infty}^{\infty} \left(\int_0^t h(s, u) \, dJ_s(x, u) \right) \, du = \frac{1}{2} \int_0^t h(s, x_s) \, d[x]_s^d,$$

and this observation seems to be new.

⁶Here, and elsewhere unless otherwise specified, a.e. u is with respect to the Lebesgue measure.

To facilitate the proof of Proposition 2.5, as well as for later use, let us recall some well known facts. A function $g: \mathbb{R} \rightarrow \mathbb{R}$ is convex iff its second distributional derivative g'' is a positive Radon measure. Thus $f: \mathbb{R} \rightarrow \mathbb{R}$ equals to the difference of two convex functions iff f'' is a signed Radon measure. We may then write $f = g - h$ with g, h convex and $|f''| = g'' + h''$ being the measure associated with the total variation of f , $\text{TV}(f'(\cdot), [0, t]) = |f''|([0, t])$. Given such f , f' denotes the left-derivative of f , which is left-continuous and of locally bounded variation and satisfies $f(b) - f(a) = \int_a^b f'(y) dy$ for all $a, b \in \mathbb{R}$. Thus for $b \geq a$ we get that

$$f(b) - f(a) - f'(a)(b - a) = \int_a^b (f'(u) - f'(a)) du = \int_{[a,b)} (b - u) f''(du),$$

where we used integration by parts. For $b < a$, we get instead

$$f(b) - f(a) - f'(a)(b - a) = \int_{[b,a)} (u - b) f''(du),$$

so we obtain the identity

$$J^f(a, b) := f(a) - f(b) - f'(b)(a - b) = \int_{\llbracket a,b)} |b - u| f''(du), \quad a, b \in \mathbb{R}, \quad (2.12)$$

which can often be used in proofs in lieu of the following representation

$$f(x) = ax + b + (|\cdot| * f'')(x), \quad x \in \mathbb{R}, \quad (2.13)$$

(which holds for some $a, b \in \mathbb{R}$), which is often used in the literature. Representation (2.13) holds whenever $\int_{\mathbb{R}} |a - u| f''(du) < \infty$ for all a (in particular if f'' has compact support), and is proved after Proposition 3.2 in [32, Appendix 3].

A version of the following statement appears without proof during the course of the proof of [31, Chapter 4, Theorem 70].

Lemma 2.9. *If $f: \mathbb{R} \rightarrow \mathbb{R}$ is a convex function then the series (2.3) defining $J_t^f(x)$ consists only of positive terms. If f equals to the difference of two convex functions and*

$$\int_{\mathbb{R}} J_t(x, u) |f''|(du) < \infty,$$

then the series (2.3) is absolutely convergent. In both cases, the series (2.3) defining $J_t^f(x)$ is well defined⁷ and satisfies

$$J_t^f(x) = \int_{\mathbb{R}} J_t(x, u) f''(du), \quad t \in [0, T]. \quad (2.14)$$

Proof. From (2.12) we get

$$J^f(x_s, x_{s-}) = \int_{\mathbb{R}} |x_s - u| \mathbf{1}_{\llbracket x_{s-}, x_s)}(u) f''(du). \quad (2.15)$$

If f is convex the series (2.3) defining $J_t^f(x)$ consists only of positive terms, and the thesis follows from (2.15), summing over $s \leq t$ and applying Fubini's theorem. If instead $f = g - h$ with g, h convex then $|f''| = g'' + h''$ and, by assumption, $\int_{\mathbb{R}} J_t(x, u) |f''|(du) < \infty$. (2.14) follows again from Fubini's theorem. The absolute convergence of the series (2.3) follows writing

$$|\Delta f(x_s) - f'(x_{s-})\Delta x_s| \leq (\Delta g(x_s) - g'(x_{s-})\Delta x_s) + (\Delta h(x_s) - h'(x_{s-})\Delta x_s),$$

summing the latter over $s \leq t$ and applying (2.14) to g and h . □

⁷See (2.1).

Remark 2.10. It follows from Lemma 2.9 and Hölder’s inequality that, if $J_t(x, \cdot) \in L^p(\mathbb{R})$ and $f''(du) = f''(u) du$ with $f'' \in L^q(\mathbb{R})$, where $p, q \geq 1$ are conjugate exponents, that is satisfy $1/p + 1/q = 1$, then the series (2.3) defining $J_t^f(x)$ is absolutely convergent. Moreover, if $J_t(x, \cdot)$ is bounded⁸ then the series (2.3) is absolutely convergent for every f which is a difference of convex functions: indeed, $J_t(x, \cdot) = 0$ outside a compact, and $|f''|(C) < \infty$ for every compact $C \subseteq \mathbb{R}$.

An alternative, possibly more intuitive but also more cumbersome, way of getting (2.15) is to define

$$g(\cdot) := |x_s - \cdot| \mathbf{1}_{[x_{s-}, x_s]}(\cdot),$$

which is in $L^1(\mathbb{R})$, equals zero outside a compact, and has distributional derivatives

$$Dg = (\Delta x_s) \delta_{x_{s-}} - \mathbf{1}_{[x_{s-}, \infty)} + \mathbf{1}_{[x_s, \infty)}, \quad D^2g = (\Delta x_s) D\delta_{x_{s-}} - \delta_{x_{s-}} + \delta_{x_s}.$$

Then equation (2.15) is simply⁹ the identity $\int_{\mathbb{R}} f(u) (D^2g)(du) = \int_{\mathbb{R}} g(u) (D^2f)(du)$.

Proof of Proposition 2.5. The series (2.3) defining $J_t^f(x)$ is absolutely convergent by Remark 2.10. If $h \in C^2(\mathbb{R})$, from Föllmer’s pathwise Itô formula (2.4), the definition of occupation local time L and of $K := L/2 + J$, and Lemma 2.9, it follows that

$$\int_0^t h'(x_{s-}) dx_s = h(x_t) - h(x_0) - \int_{\mathbb{R}} K_t(x, u) h''(du), \quad t \in [0, T], \tag{2.16}$$

holds with $\int_0^t h'(x_{s-}) dx_s$ defined via (2.5). Applying (2.16) to $h = f_n = \rho_n * f \in C^2(\mathbb{R})$ and taking limit as $n \rightarrow \infty$, the right-hand side converges to

$$f(x_t) - f(x_0) - \int_{\mathbb{R}} K_t(x, u) f''(u) du$$

because $K_t(x, \cdot) \in L^p(\mathbb{R})$ and $f_n \rightarrow f$ in $W^{2,q}(\mathbb{R})$ (so $f_n \rightarrow f$ pointwise and $f_n'' \rightarrow f''$ in $L^q(\mathbb{R})$). It follows that the LHS converges as well. \square

Remark 2.11. It follows from (2.14) that, whenever Tanaka–Meyer’s formula holds, it can be written as

$$f(x_t) - f(x_0) = \int_0^t f'(x_{s-}) dx_s + \int_{\mathbb{R}} K_t(x, u) f''(du), \quad t \in [0, T], \tag{2.17}$$

where we recall that $K_t(u) := L_t(u)/2 + J_t(u)$. While uncommon, writing (2.17) seems rather elegant and simpler than (2.10).

Remark 2.12. One can recover a continuous in time, for a.e. level u , version \tilde{L} of the occupation time L from knowing just a jointly measurable function $K_t(u)$ such that $K_t(u)$ is càdlàg increasing for a.e. u , $K_0 = 0$, $K_T \in L^1(\mathbb{R})$, and (2.17) holds for all $f \in C^2$ with $\int_0^t f'(x_{s-}) dx_s$ defined via (2.5). Indeed, $\tilde{L}(u)$ (resp. $J_t(u)$) is the continuous (resp. purely discontinuous) part of the increasing càdlàg function $K_t(u)$. To show this, consider that for $f \in C^2(\mathbb{R})$ Föllmer’s formula (2.4), (2.16) and Lemma 2.9 give that

$$K_t^f := \int_{\mathbb{R}} K_t^c(u) f''(u) du + \int_{\mathbb{R}} K_t^d(u) f''(u) du = \frac{1}{2} \int_0^t f''(x_s) d[x]_s^c + \int_{\mathbb{R}} J_t(u) f''(u) du,$$

⁸This happens for example if $\sum_{s \leq t} |\Delta x_s| < \infty$, by Remark 2.8.

⁹This equality holds a priori only when f is $C^\infty(\mathbb{R})$ (by definition of distributional derivatives). However, with some work it follows that it holds for any f which equals the difference of convex functions: indeed, since g is càdlàg, convolving against a mollifier with support in $[0, \infty)$ shows that there exist $f_\varepsilon \in C^\infty(\mathbb{R})$ such that $f_\varepsilon \rightarrow f$ uniformly on compacts and $\int g(u) (D^2 f_\varepsilon)(u) du \rightarrow \int g(u) d(D^2 f)$, as shown in [9, Proof of Theorem 5.2].

where K^c (resp. K^d) denotes the continuous (resp. purely discontinuous) part of $K \cdot (u)$. In each of the two above representations of the càdlàg increasing function K_t^f the first term is continuous and the second purely discontinuous, so by uniqueness of such decomposition

$$\int_{\mathbb{R}} K_t^c(u)g(u) \, du = \frac{1}{2} \int_0^t g(x_s) \, d[x]_s^c, \quad \int_{\mathbb{R}} K_t^d(u)g(u) \, du = \int_{\mathbb{R}} J_t(u)g(u) \, du$$

holds for any g of the form f'' , i.e., for any continuous g ; but then it also automatically holds for any Borel g , so $2K^c$ is an occupation local time of x and $J_t = K_t^d$ a.e. u for each t ; since J_t and K_t^d are càdlàg in t , $J_t = K_t^d$ a.e. u for all t .

Remark 2.13. For continuous paths x the above approximation argument can be used to obtain space-time Tanaka–Meyer formulae without relying on the representation (2.13), see [12]. Although elaborated in a probabilistic framework, the proofs in [12] are (primarily) of pathwise nature.

Remark 2.14. The definition of occupation local times and the generalization of Itô’s formula to only twice weakly differentiable functions in Proposition 2.5 is based on Föllmer’s notion of quadratic variation and his pathwise Itô formula (Theorem 2.2). However, the Föllmer–Itô formula is by no means the only pathwise Itô-type formula, which can be extended to an Tanaka–Meyer formula in the spirit of in Proposition 2.5. For example, one could also start from the pathwise Itô formula based on càdlàg rough paths ([15, Theorem 2.12]) or the one based on truncated variation ([27, Theorem 4.1]) and proceed in an analogous manner as done in the present subsection.

Remark 2.15. If x has an occupation local time L , then one can give explicit formulae for L . Indeed, since $L_t(\cdot) \in L^1(\mathbb{R})$, taking $\lim_{\varepsilon \downarrow 0}$ of (2.6) applied to $g := \mathbf{1}_{[u-\varepsilon, u+\varepsilon]}$ gives that

$$L_t(x, u) = \lim_{\varepsilon \downarrow 0} \frac{1}{2\varepsilon} \int_0^t \mathbf{1}_{[u-\varepsilon, u+\varepsilon]}(x_s) \, d[x]_s^c, \quad \text{for a.e. } u,$$

meaning that the limit on the right-hand side exists for a.e. $u \in \mathbb{R}$ and is a version of $L_t(\cdot)$. Analogously, if we can apply Tanaka–Meyer’s formula to the convex function $|\cdot - u|$ we get the following expression for L :

$$L_t(x, u) = |x_t - u| - |x_0 - u| - \int_0^t \text{sign}(x_{s-} - u) \, dx_s - 2J_t(x, u), \quad t \in [0, T]. \quad (2.18)$$

It is thus desirable to establish if (a version of) Proposition 2.5 holds in the case where $f: \mathbb{R} \rightarrow \mathbb{R}$ equals to the difference of two convex functions. This is the case under the additional assumptions that the mollifier ρ has compact support in $[0, \infty)$, that $J_t(u)$ is càdlàg in u for all t (see Remark 2.8), and that there exists a version \tilde{L}_t of the pathwise local time L_t which is càdlàg in u for all t (in particular, unlike in the stochastic setting, one cannot use (2.18) to prove that L has a version which is càdlàg in u for all t without running into circular arguments). Indeed, under these assumptions the proof of [9, Theorem 5.2] shows that $\int_{\mathbb{R}} g(u) f_n''(du) \rightarrow \int_{\mathbb{R}} g(u) f''(du)$ for any càdlàg g , and if we apply this to $g = K_t$ the rest of the proof of Proposition 2.5 goes through.

Remark 2.16. As in¹⁰ the stochastic setting, if we can¹¹ apply Tanaka–Meyer’s formula to the convex function $f(x) = (x - u)^+$, we find that the measure $dL \cdot (u)$ is supported by the set $\{s \in (0, t] : x_s = x_{s-} = u\}$, and correspondingly, the measure $dJ \cdot (u)$ is carried by the set

$$\{s \in (0, t] : u \in (x_{s-}, x_s) \text{ or } u \in (x_s, x_{s-}]\}$$

¹⁰One can apply the proof found in [31, Chapter 4, Theorem 69], which simplifies somewhat as we do not need to deal with the dependence on ω .

¹¹See Remark 2.15.

of times at which x jumps across¹² level u .

2.3 Local time via discretization

An alternative approach to achieve a pathwise Tanaka–Meyer formula goes back to Würmlmi [36] and is based on a discrete version of the Tanaka–Meyer formula. For continuous paths x this approach is well-understood and led to several extensions, see [29, 9, 7]. One feature of this discretization argument is that the “stochastic” integral $\int_0^t f'(x_{s-}) dx_s$ is still given as a limit of left-point Riemann sums, see also [8]. In the present subsection we generalize Würmlmi’s approach to the case of càdlàg paths x . Given a partition $\pi = (t_j)_{j=0}^n$ of $[0, T]$, we define the discrete level crossing time of x at u (along π) as the function

$$K_t^\pi(x, u) := \sum_{t_j \in \pi} |x_{t_{j+1} \wedge t} - u| \mathbf{1}_{\llbracket x_{t_j \wedge t}, x_{t_{j+1} \wedge t} \rrbracket}(u), \quad t \in [0, T]. \tag{2.19}$$

Then, applying (2.12) to $a = x_{t_i \wedge t}$, $b = x_{t_{i+1} \wedge t}$ and summing over i , we obtain the discrete version of Tanaka–Meyer formula

$$f(x_t) - f(x_0) - \sum_{t_i \in \pi} f'(x_{t_i})(x_{t_{i+1} \wedge t} - x_{t_i \wedge t}) = \int_{\mathbb{R}} K_t^\pi(u) f''(du). \tag{2.20}$$

Taking limits along a sequence of partitions $(\pi^n)_n$, with $|\pi^n| \rightarrow 0$, we obtain the following definition of L^p -level crossing time. We note that it extends the previous works for continuous paths, e.g., [8, Definition B.3]. We also note that using the same notation K_t as before will be justified by Proposition 2.19.

Definition 2.17. Let $x \in D([0, T]; \mathbb{R})$ and let $(\pi^n)_n$ be a sequence of partitions such that $|\pi^n| \rightarrow 0$. A function $K: [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is called the L^p -level crossing time of x (along $(\pi^n)_n$) if $K_t^{\pi^n}$ converges weakly in $L^p(\mathbb{R})$ to K_t for each $t \in [0, T]$ as $n \rightarrow \infty$, and $t \mapsto \int_{\mathbb{R}} K_t(u) du$ is right-continuous. The set $\mathbb{L}_p^W((\pi^n)_n)$ denotes all paths $x \in D([0, T]; \mathbb{R})$ having an L^p -level crossing time along $(\pi^n)_n$.

Lemma 2.18. The level crossing time K in Definition 2.17 is increasing in $t \in [0, T]$, i.e., $K_s(\cdot) \leq K_t(\cdot)$ a.e. for each $s \leq t$.

Proof. Given $\pi = (t_j)_j$, let $m(\pi, s)$ be the value of j such that $t_j < s \leq t_{j+1}$, and write

$$K_s^\pi = \sum_{j < m(\pi, s)} a_j(u) + |x_s - u| \mathbf{1}_{\llbracket x_{t_{m(\pi, s)}}, x_s \rrbracket}(u), \text{ where } a_j(u) := |x_{t_{j+1}} - u| \mathbf{1}_{\llbracket x_{t_j}, x_{t_{j+1}} \rrbracket}(u).$$

If $s < t$, analogously write

$$K_t^\pi - \sum_{j < m(\pi, s)} a_j(u) - a_{m(\pi, s)}(u) = \sum_{m(\pi, s) < j < m(\pi, t)} a_j(u) + |x_t - u| \mathbf{1}_{\llbracket x_{t_{m(\pi, t)}}, x_t \rrbracket}(u) =: R_{s,t}^\pi.$$

Thus

$$K_t^\pi - K_s^\pi - R_{s,t}^\pi = a_{m(\pi, s)}(u) - |x_s - u| \mathbf{1}_{\llbracket x_{t_{m(\pi, s)}}, x_s \rrbracket}(u) =: S_s(\pi, u),$$

and since $R_{s,t}^\pi \geq 0$ the thesis follows once we prove that $S_s(\pi^n, u) \rightarrow 0$ for every u when $|\pi^n| \rightarrow 0$. This holds since if $m(n) := m(\pi^n, s)$ then $t_{m(n)}$ and $t_{m(n)+1}$ converge to s , and $t_{m(n)} < s \leq t_{m(n)+1}$, so

$$a_{m(n)}(u) \quad \text{and} \quad |x_s - u| \mathbf{1}_{\llbracket x_{t_{m(n)}}, x_s \rrbracket}(u)$$

both converge to $|x_s - u| \mathbf{1}_{\llbracket x_{s-}, x_s \rrbracket}(u)$ as $n \rightarrow \infty$, since x is càdlàg. □

¹²More precisely, if the jump is downward, then x is allowed to jump from $x_{s-} = u$.

Notice that K_t is only defined as an equivalence class. Using the same arguments as in the discussion preceding Remark 2.7, for each t we can take the version of K_t such that the resulting process is càdlàg increasing in t for each u . From now on, we will always work with such a version and we let K^c (resp. K^d) denote the continuous (resp. purely discontinuous) part of the increasing càdlàg function $K(\cdot)$.

Proposition 2.19. *Suppose that $x \in \mathbb{L}_p^W((\pi^n)_n)$ for $p, q \in [1, \infty]$, with $1/p + 1/q = 1$, and let K be the L^p -level crossing time of x along $(\pi^n)_n$. If $f \in W^{2,q}(\mathbb{R})$, then the following limit exists (and is finite)*

$$\int_0^t f'(x_{s-}) dx_s := \lim_{n \rightarrow \infty} \sum_{t_i \in \pi^n} f'(x_{t_i})(x_{t_{i+1} \wedge t} - x_{t_i \wedge t}), \quad t \in [0, T], \quad (2.21)$$

and the pathwise Tanaka–Meyer formula (2.17) holds with this definition of $\int_0^t f'(x_{s-}) dx_s$ and K . Moreover, $2K^c$ is the occupation local time of x and $J_t(u)$ in (2.8) satisfies $J_t(u) = K_t^d(u)$ for a.e. u and for all $t \leq T$. In particular, also the pathwise Tanaka–Meyer formula (2.10) holds (with $L = 2K^c$), the two definitions (2.9) and (2.21) of $\int_0^t f'(x_{s-}) dx_s$ coincide, and $\mathbb{L}_p^W((\pi^n)_n) \subseteq \mathbb{L}^p((\pi^n)_n)$.

Proof of Proposition 2.19. Taking the limit as n goes to ∞ of the discrete Tanaka–Meyer formulae (2.20) applied to π^n , the RHS converges and hence also does the LHS. The pathwise Tanaka–Meyer formula (2.17) thus holds if using the definition (2.21). Now, from Remark 2.12 it follows that $2K^c$ satisfies the occupation time formula and the remaining statements readily follow. \square

Remark 2.20. Following the seminal paper [14], we consider the “stochastic” integral as limit of left-point Riemann sums (2.21) and not as limit of

$$\sum_{t_i \in \pi^n} f'(x_{t_i-})(x_{t_{i+1} \wedge t} - x_{t_i \wedge t}), \quad t \in [0, T].$$

In a probabilistic setting, where x is assumed to be a semimartingale, these limits coincide with the classical Itô integral almost surely (see [31, Chapter II.5, Theorem 21]) and so they are equal. In the present pathwise setting however, they could be different.

Remark 2.21. Applying Minkowski’s integral inequality and using the identity (2.11), we obtain that if $p \in [1, \infty)$ and $C_p := 1/(p + 1)^{1/p}$, then

$$\|K_t^\pi\|_{L^p} \leq C_p \sum_{t_i \in \pi} |x_{t_{i+1} \wedge t} - x_{t_i \wedge t}|^{1+\frac{1}{p}}.$$

In particular, if $x \in \mathbb{L}_p^W((\pi^n)_n)$, then the occupation local time L equals $2K^c$ and so satisfies

$$\|L_t\|_{L^p} \leq 2\|K_t\|_{L^p} \leq 2C_p \liminf_n \sum_{t_i \in \pi^n} |x_{t_{i+1} \wedge t} - x_{t_i \wedge t}|^{1+\frac{1}{p}} \quad \text{for every } p \in [1, \infty). \quad (2.22)$$

Remark 2.22. Given the definition of $J_t(u)$, it seems natural that, if $x \in \mathbb{L}_p^W((\pi^n)_n)$ and

$$J_t^\pi(u) := \sum_{t_i \in \pi(t)} \mathbf{1}_{(x_{t_i-}, x_{t_i}]}(u) |x_{t_i} - u|, \quad u \in \mathbb{R}, t \in [0, T],$$

then $J_t^{\pi^n}$ also converges weakly in $L^p(\mathbb{R})$. If we assume this and denote by L_t^d the limit, if $(\pi^n)_n$ are refining and $\cup_n \pi^n \supseteq \{s \in [0, T] : \Delta x_s \neq 0\}$, then $L_t^d = J_t = K_t^d$ a.e. In

particular, $K_t^{\pi^n} - J_t^{\pi^n}$ converges weakly in $L^p(\mathbb{R})$ to K_t^c . Indeed, if $f'' \in L^q(\mathbb{R})$, (2.12) gives

$$J_t^{f, \pi^n} := \sum_{t_i \in \pi^n(t)} f(x_{t_i}) - f(x_{t_i-}) - f'(x_{t_i-})(x_{t_i} - x_{t_i-}) = \int_{\mathbb{R}} J_t^{\pi^n}(u) f''(u) du, \quad (2.23)$$

so our assumptions and Lemma 2.9 imply that the series (2.3) defining J_t^f is absolutely convergent. Using the dominated convergence theorem we conclude that $J_t^{f, \pi^n} \rightarrow J_t^f$, so taking $n \rightarrow \infty$ in (2.23) we get

$$J_t^f = \int_{\mathbb{R}} L_t^d(u) f''(u) du,$$

so by Lemma 2.9 $L_t^d = J_t$ a.e.

2.4 Local time via normalized numbers of interval crossings

In Proposition 2.5 above we approximated f with regular functions f_n for which the “stochastic” integral $\int_0^t f'_n(x_{s-}) dx_s$ was defined via Theorem 2.2. An alternative regularisation idea would be to approximate the path x by sufficiently regular functions (x^n) , ensuring that the “stochastic” integral $\int_0^t f'(x_{s-}^n) dx_s$ is well-defined for each x^n (via integration by parts). We pursue this approach now using for x^n the solutions to the so-called double Skorokhod problem. This choice of approximations has the additional feature that it leads to a natural interpretation of the resulting local time in terms of interval crossings.

Let $V^1([0, T]; \mathbb{R}) \subset D([0, T]; \mathbb{R})$ and $V^+([0, T]; \mathbb{R}) \subset D([0, T]; \mathbb{R})$ be the space of all functions on $[0, T]$ with bounded variation (also called of finite total variation) and of all non-decreasing functions, respectively. Let us recall that for $[0, t] \subset [0, T]$ and $y: [0, T] \rightarrow \mathbb{R}$, the total variation of y on the interval $[0, t]$ is given by

$$\text{TV}(y, [0, t]) := \sup \left\{ \sum_{i=0}^{N-1} |y_{t_{i+1}} - y_{t_i}| : (t_i)_{i=0}^N \text{ is a partition of } [0, t], N \in \mathbb{N} \right\}.$$

Definition 2.23. Given $x \in D([0, T]; \mathbb{R})$ and $\varepsilon > 0$, a pair $(\phi^\varepsilon, -x^\varepsilon) \in D([0, T]; \mathbb{R}) \times V^1([0, T]; \mathbb{R})$ is called a solution to the Skorokhod problem on $[-\varepsilon/2, \varepsilon/2]$ if the following conditions are satisfied:

- (i) $x_t - x_t^\varepsilon = \phi_t^\varepsilon \in [-\varepsilon/2, \varepsilon/2]$ for every $t \in [0, T]$,
- (ii) $x^\varepsilon = x^{\varepsilon\uparrow} - x^{\varepsilon\downarrow}$ with $x^{\varepsilon\uparrow}, x^{\varepsilon\downarrow} \in V^+([0, T]; \mathbb{R}) \subset D([0, T]; \mathbb{R})$ and the corresponding measures $dx_t^{\varepsilon\uparrow}$ and $dx_t^{\varepsilon\downarrow}$ are supported in $\{t \in [0, T] : \phi_t^\varepsilon = \varepsilon/2\}$ and $\{t \in [0, T] : \phi_t^\varepsilon = -\varepsilon/2\}$, respectively,
- (iii) $\phi_0^\varepsilon = 0$.

A solution to the above Skorokhod problem exists and is unique, see [28, Proposition 2.7], and its properties are well studied in the literature, see, e.g., [22, 4]. Let us emphasise that for any $\varepsilon > 0$, x^ε is a càdlàg and piecewise monotonic path of bounded variation, which uniformly approximates x with accuracy $\varepsilon/2$.

While $f \circ y$ is of finite variation for all $y: [0, T] \rightarrow \mathbb{R}$ which are of finite variation if and only if f is locally Lipschitz (see [24]), we can nonetheless assert that $f(x^\varepsilon)$ is of finite variation for any $f \in W^{2,q}(\mathbb{R})$, because x^ε is a special function of finite variation: it is *piecewise monotonic*, i.e., there exists a partition $0 = a_0 < a_1 < \dots < a_{N+1} = T$ of $[0, T]$ s.t. x^ε is either increasing or decreasing on each I_i , where¹³

$$I_i := [a_i, a_{i+1}), i = 0, \dots, N - 1, \quad I_N := [a_N, a_{N+1}],$$

¹³[28, Remarks 2.5 and 2.6] imply that there is finite number of such intervals: otherwise, the càdlàg function ϕ^ε would have no left limit at the point $\lim_{i \rightarrow +\infty} a_i$, a contradiction.

see [28, formula (2.4)], where even a more general Skorokhod problem is considered. Thus, keeping in mind integration by parts for the Lebesgue–Stieltjes integral, for $\varepsilon > 0$ and $f \in W^{2,q}(\mathbb{R})$, $q \geq 1$, we can define

$$\int_0^t f'(x_{s-}) dx_s := f'(x_t^{\varepsilon})x_t - f'(x_0^{\varepsilon})x_0 - \int_0^t x_{s-} df'(x_s^{\varepsilon}) - \sum_{0 < s \leq t} \Delta x_s \Delta f'(x_s^{\varepsilon}), \quad (2.24)$$

where $\int_0^t x_{s-} df'(x_s^{\varepsilon})$ exists as the Lebesgue–Stieltjes integral and we recall the convention $\int_0^t = \int_{(0,t]}$. For a brief summary of the theory of Lebesgue–Stieltjes integration, we refer to [33, Chapter 4, Section 3.18]; we also remind the reader that, if x, y are of finite variation,

$$\int_0^t y_s dx_s = \int_0^t y_{s-} dx_s + \sum_{s \leq t} \Delta y_s \Delta x_s.$$

We will define the pathwise local time as normalised limits of the numbers of interval crossings. To this end, for $x \in D([0, T]; \mathbb{R})$, $z \in \mathbb{R}$, $\varepsilon > 0$ and $t \in (0, T]$ we define the number of upcrossings by the path x of the interval $(z - \varepsilon/2, z + \varepsilon/2)$ over the time $[0, t]$ by

$$u^{z,\varepsilon}(x, [0, t]) := \sup_{n \in \mathbb{N}} \sup_{0 \leq t_1 < s_1 < \dots < t_n < s_n \leq t} \sum_{i=1}^n \mathbf{1}_{\{x_{t_i} \leq z - \varepsilon/2 \text{ and } x_{s_i} \geq z + \varepsilon/2\}}.$$

The number of downcrossings $d^{z,\varepsilon}(x, [0, t])$ is defined analogously. We set

$$n^{z,\varepsilon}(x, [0, t]) := d^{z,\varepsilon}(x, [0, t]) + u^{z,\varepsilon}(x, [0, t]) \quad (2.25)$$

for the total number of crossings.

Definition 2.24. Consider a sequence $(c_n)_n$ such that $c_n > 0$ and $c_n \rightarrow 0$. For $x \in D([0, T]; \mathbb{R})$ denote by $(\phi^n, -x^n)$ the solution to the Skorokhod problem on $[-c_n/2, c_n/2]$, $n \in \mathbb{N}$. We denote $\mathbb{L}_p^S((c_n)_n)$ the set of all paths $x \in D([0, T]; \mathbb{R})$ such that, for all $0 < t \leq T$,

(i) the sequence of functions

$$\mathbb{R} \ni z \mapsto c_n \cdot n^{z,c_n}(x, [0, t]), \quad n \in \mathbb{N},$$

converges weakly in $L^p(\mathbb{R})$ as $n \rightarrow \infty$; and

(ii) the sequence of functions

$$\mathbb{R} \ni z \mapsto J_t(x^n, z), \quad n \in \mathbb{N},$$

defined by formula (2.8), converges weakly in $L^p(\mathbb{R})$ to $J_t(x, \cdot)$ as $n \rightarrow \infty$.

A function $L: [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ which is the weak limit in (ii) is called an L^p -interval crossing local time of x along $(c_n)_n$.

The corresponding pathwise Tanaka–Meyer formula reads as follows.

Proposition 2.25. Suppose that $x \in \mathbb{L}_p^S((c_n)_n)$ for $p, q \geq 1$ with $1/p + 1/q = 1$. If $f \in W^{2,q}(\mathbb{R})$, then the following limit exists and is finite

$$\int_0^t f'(x_{s-}) dx_s := \lim_{n \rightarrow \infty} \int_0^t f'(x_{s-}^n) dx_s, \quad t \in [0, T],$$

where the right-hand side is defined using (2.24), and the pathwise Tanaka–Meyer formula

$$f(x_t) - f(x_0) = \int_0^t f'(x_{s-}) dx_s + \frac{1}{2} \int_{\mathbb{R}} L_t(x, u) f''(du) + J_t^f(x), \quad t \in [0, T],$$

holds with such definition of $\int_0^t f'(x_{s-}) dx_s$ and with $J_t^f(x)$ as given in (2.3).

Before proving Proposition 2.25, we prove the following very intuitive lemma, where we write $g(x)$ for $g \circ x$.

Lemma 2.26. *Let $I \subseteq \mathbb{R}$ be an open interval (i.e., I is open and convex), $x: I \rightarrow [c, d]$ be càdlàg and monotonic (i.e., increasing or decreasing), and $g: [c, d] \rightarrow \mathbb{R}$ be absolutely continuous and increasing. If dx is concentrated on a Borel set F , then so is $dg(x)$.*

Proof. We can w.l.o.g. assume that $I = \mathbb{R}$, since otherwise we can trivially extend x to \mathbb{R} in a way that $\mathbb{R} \setminus I$ has dx mass 0. We have to prove that the dx null set $E := \mathbb{R} \setminus F$ is also a $dg(x)$ null set. Denote with \mathcal{L} the Lebesgue measure on \mathbb{R} . Let y be càdlàg monotonic, so if $I, J \subseteq \mathbb{R}$ are intervals with disjoint interiors, then so are $y(I), y(J)$ (even if $I \cap J = \emptyset$ does not imply $y(I) \cap y(J) = \emptyset$). Set $s(y) := 1$ (resp. $= -1$) if y is increasing (resp. decreasing). Since

$$\int_{\mathbb{R}} \mathbf{1}_A(u) dy_u = s(y) \int_{\mathbb{R}} \mathbf{1}_{y(A)}(u) du = s(y)\mathcal{L}(y(A)) \tag{2.26}$$

holds (by definition of dy) when A is an interval, it holds whenever $A \subseteq \mathbb{R}$ is a countable union of intervals $(I_n)_n$ with disjoint interiors (because the interiors of $(y(I_n))_n$ are disjoint).

Fix arbitrary $\varepsilon > 0$ and recall that there exists a $\delta > 0$ s.t. $\mathcal{L}(V) \leq \delta$ implies $\int \mathbf{1}_V dg = \mathcal{L}(g(V)) \leq \varepsilon$ whenever V is a finite union of intervals with disjoint interiors (by definition of absolute continuity), and thus whenever V is a countable union of intervals with disjoint interiors.

Now cover E with an open set $A \supseteq E$ s.t. $|\int \mathbf{1}_A dx| \leq \delta$; since A is open, it is a countable union of disjoint open intervals, so (2.26) with $y = x$ gives $\mathcal{L}(x(A)) \leq \delta$. Since $V := x(A) \supseteq x(E)$ is a countable union of intervals with disjoint interiors we get $\mathcal{L}(g(x(A))) \leq \varepsilon$, and so (2.26) with $y = g(x)$ gives $|\int \mathbf{1}_A dg(x)| \leq \varepsilon$. Thus $|\int \mathbf{1}_E dg(x)| \leq \varepsilon$ for any $\varepsilon > 0$, concluding the proof. \square

Proof of Proposition 2.25. We introduce first slightly modified numbers of interval (up-, down-) crossings by replacing \leq, \geq with $<, >$ in the inequality involving x_{t_i} in the definition of up- and down- crossings: for $z \in \mathbb{R}$, $\varepsilon \geq 0$, $t \in (0, T]$ and $x \in D([0, T]; \mathbb{R})$ we set

$$\begin{aligned} \tilde{u}^{z,\varepsilon}(x, [0, t]) &:= \sup_{n \in \mathbb{N}} \sup_{0 \leq t_1 < s_1 < \dots < t_n < s_n \leq t} \sum_{i=1}^n \mathbf{1}_{\{x_{t_i} < z - \varepsilon/2 \text{ and } x_{s_i} \geq z + \varepsilon/2\}}, \\ \tilde{d}^{z,\varepsilon}(x, [0, t]) &:= \sup_{n \in \mathbb{N}} \sup_{0 \leq t_1 < s_1 < \dots < t_n < s_n \leq t} \sum_{i=1}^n \mathbf{1}_{\{x_{t_i} > z + \varepsilon/2 \text{ and } x_{s_i} \leq z + \varepsilon/2\}}, \\ \tilde{n}^{z,\varepsilon}(x, [0, t]) &:= \tilde{d}^{z,\varepsilon}(x, [0, t]) + \tilde{u}^{z,\varepsilon}(x, [0, t]). \end{aligned}$$

As $f \in W^{2,q}(\mathbb{R})$, f' can be decomposed as the difference of two increasing AC (Absolutely Continuous) functions; since the result we want to prove is linear in f , we can assume w.l.o.g. that f' is increasing and AC. Moreover, since x (as defined on $[0, t]$) is bounded, and the result only depends on the behaviour of f on $[\inf x, \sup x]$, we can additionally assume w.l.o.g. that f'' has compact support. As the proposition holds trivially for affine functions, thanks to (2.13) we may further assume that

$$f(x) = (|\cdot| * f'')(x), \quad x \in \mathbb{R}.$$

Let us consider the integral $\int_0^t f'(x_{s-}^n) dx_s$. For $t \in [0, T]$ we have

$$\int_0^t f'(x_{s-}^n) dx_s = f'(x_t^n)x_t - f'(x_0^n)x_0 - \int_0^t x_{s-} df'(x_s^n) - \sum_{0 < s \leq t} \Delta x_s \Delta f'(x_s^n), \tag{2.27}$$

where $\int_0^t x_{s-} \, df'(x_s^n)$ is the Lebesgue–Stieltjes integral. Further, we have

$$\begin{aligned} \int_0^t x_{s-} \, df'(x_s^n) + \sum_{0 < s \leq t} \Delta x_s \Delta f'(x_s^n) &= \int_0^t x_s \, d\bar{f}'(x_s^n) \\ &= \int_0^t (x_s - x_s^n) \, df'(x_s^n) + \int_0^t x_s^n \, df'(x_s^n). \end{aligned} \tag{2.28}$$

To calculate the first integral we use the properties of f' and x^n .

Recall that the positive (resp. negative) part of dx^n is concentrated on $\{x - x^n = c_n/2\}$ (resp. $\{x - x^n = -c_n/2\}$). Thus, the identity

$$\int_I (x_s - x_s^n) \, df'(x_s^n) = \frac{c_n}{2} \text{TV}(f'(x^n), I), \tag{2.29}$$

holds if I is the interior of an interval on which x^n is increasing (resp. decreasing), by Lemma 2.26, and if I is a singleton, since in that case it reduces to the identity

$$(x_s - x_s^n) \Delta f'(x_s^n) = \frac{c_n}{2} |\Delta f'(x_s^n)|.$$

Since x^n is piecewise monotonic, we conclude that (2.29) holds for $I = [0, t]$.

Using (2.27), (2.28) and (2.29), we finally arrive at

$$\int_0^t f'(x_{s-}^n) \, dx_s = f'(x_t^n)x_t - f'(x_0^n)x_0 - \int_0^t x_s^n \, df'(x_s^n) - \frac{c_n}{2} \text{TV}(f'(x^n), [0, t]). \tag{2.30}$$

Let us note that the right side of (2.29) may be also calculated using the following generalisation of the Banach indicatrix theorem:

$$\text{TV}(f'(x^n), [0, t]) = \int_{\mathbb{R}} N^y(f'(x^n), [0, t]) \, dy, \tag{2.31}$$

where $N^y(g, [0, t])$ is the number of up- and down- crossings of the level y by càdlàg g , as defined in [26, Remark 1.3], which is closely related to the number of crossings $n^{y,\varepsilon}$ via the relation

$$N^y(g, [0, t]) = \lim_{\varepsilon \rightarrow 0^+} n^{y,\varepsilon}(g, [0, t]),$$

of which we will not make use, and which can be proved similarly to [26, Remark 1.4]. Moreover, the relationship

$$\int_{\mathbb{R}} N^y(f'(h), [0, t]) \, dy = \int_{\mathbb{R}} N^z(h, [0, t]) \, df'(z) \tag{2.32}$$

clearly holds for any monotonic $h: I \rightarrow \mathbb{R}$ defined on an open interval I , and thus holds for any completely monotonic h .

Thus, equation (2.30) may be rewritten as

$$\int_0^t x_s^n \, df'(x_s^n) = f'(x_t^n)x_t - f'(x_0^n)x_0 - \int_0^t f'(x_{s-}^n) \, dx_s - \frac{c_n}{2} \text{TV}(f'(x^n), [0, t])$$

which, thanks to (2.31), (2.32), takes the form

$$\begin{aligned} \int_0^t x_s^n \, df'(x_s^n) &= f'(x_t^n)x_t - f'(x_0^n)x_0 - \int_0^t f'(x_{s-}^n) \, dx_s \\ &\quad - \frac{c_n}{2} \int_{\mathbb{R}} N^z(x^n, [0, t]) \, df'(z). \end{aligned} \tag{2.33}$$

Now we will compute an alternative expression for $\int_0^t x_s^n df'(x_s^n)$. Since x^n and $f'(x^n)$ have finite total variation the rules of the Lebesgue–Stieltjes integral (integration by parts and the substitution rule) apply here and we have

$$\int_0^t x_s^n df'(x_s^n) = f'(x_t^n)x_t^n - f'(x_0^n)x_0^n - \int_0^t f'(x_s^n) dx_s^n + \sum_{0 < s \leq t} \Delta x_s^n \Delta f'(x_s^n) \quad (2.34)$$

and

$$\int_0^t f'(x_s^n) dx_s^n = f(x_t^n) - f(x_0^n) - \sum_{0 < s \leq t} (\Delta f(x_s^n) - f'(x_s^n) \Delta x_s^n). \quad (2.35)$$

Since

$$(\Delta f(x_s^n) - f'(x_s^n) \Delta x_s^n) + \Delta x_s^n \Delta f'(x_s^n) = \Delta f(x_s^n) - f'(x_{s-}^n) \Delta x_s^n,$$

whose sum over $s \leq t$ equals $J_t^f(x^n)$, substituting in (2.34) the value for $\int_0^t f'(x_s^n) dx_s^n$ obtained from (2.35) we get

$$\int_0^t x_s^n df'(x_s^n) = f'(x_t^n)x_t^n - f'(x_0^n)x_0^n - (f(x_t^n) - f(x_0^n)) + J_t^f(x^n). \quad (2.36)$$

Finally, equating the RHS of (2.36) and (2.33) we get

$$\begin{aligned} f(x_t^n) - f(x_0^n) &= \int_0^t f'(x_{s-}^n) dx_s + \frac{c_n}{2} \int_{\mathbb{R}} N^z(x^n, [0, t]) df'(z) + J_t^f(x^n) \\ &\quad - f'(x_t^n)(x_t - x_t^n) + f'(x_0^n)(x_0 - x_0^n). \end{aligned} \quad (2.37)$$

Let us now compute

$$\lim_{n \rightarrow \infty} c_n \int_{\mathbb{R}} N^z(x^n, [0, t]) df'(z).$$

Since the set of local extrema (maxima and minima) of any function $f: \mathbb{R} \rightarrow \mathbb{R}$ is countable (see e.g. [30, Lemma 5.1]), the numbers $N^z(x^n, [0, t])$ and $\tilde{n}^{z,0}(x^n, [0, t])$ are equal for all $z \in \mathbb{R}$ except a countable set, because they are equal if $z \notin \{x_0, x_t\}$ and z is not a local extremum of x . Similarly, for all $z \in \mathbb{R}$ except a countable set, the numbers $\tilde{n}^{z,c_n}(x, [0, t])$ and $n^{z,c_n}(x, [0, t])$ are equal, because they are equal if $z \notin \{x(0) \pm c_n/2, x(t) \pm c_n/2\}$ and $z \pm c_n/2$ are not local extrema of x . Next, by [28, Lemma 3.3 and 3.4], $\tilde{n}^{z,0}(x^n, [0, t])$ and $\tilde{n}^{z,c_n}(x, [0, t])$ differ by at most 2. Thus $N^z(x^n, [0, t])$ and $n^{z,c_n}(x, [0, t])$ differ by at most 2 for all but a countable number of $z \in \mathbb{R}$. Using this observation and noticing that $N^z(x^n, [0, t]) = n^{z,c_n}(x, [0, t]) = 0$ when $z < \inf_{s \in [0,t]} x_s - c_n/2$ or $z > \sup_{s \in [0,t]} x_s + c_n/2$ we have that

$$\lim_{n \rightarrow \infty} c_n \int_{\mathbb{R}} N^z(x^n, [0, t]) df'(z) = \lim_{n \rightarrow \infty} \int_{\mathbb{R}} c_n \cdot n^{z,c_n}(x, [0, t]) f''(z) dz = \int_{\mathbb{R}} L_t(z) f''(z) dz,$$

where the last equality follows from the first assumption in Definition 2.24. Also, by the second assumption in Definition 2.24 and Lemma 2.9

$$\lim_{n \rightarrow \infty} J_t^f(x^n) = \lim_{n \rightarrow \infty} \int_{\mathbb{R}} J_t(x^n, y) f''(y) dy = \int_{\mathbb{R}} J_t(x, y) f''(y) dy = J_t^f(x).$$

The last two limits together with (2.37) give the thesis. \square

Remark 2.27. To apply Proposition 2.25 we need to know when $J_t(x^n, \cdot)$ converge weakly in $L^p(\mathbb{R})$ to $J_t(x, \cdot) \in L^p(\mathbb{R})$ and $c_n \cdot n^{z,c_n}(x, [0, t])$ converges weakly in $L^p(\mathbb{R})$ to some $L_t \in L^p(\mathbb{R})$. However, in general, it is not even clear when $c_n \cdot n^{z,c_n}(x, [0, t])$ and

$J_t(x^n, \cdot)$ belong to $L^p(\mathbb{R})$ although we now give some sufficient criteria. If for some $r > 0$, the r -variation is finite, i.e.,

$$V^r(x, [0, T]) := \sup \left\{ \sum_{i=0}^{N-1} |x_{t_{i+1}} - x_{t_i}|^r : (t_i)_{i=0}^N \text{ is a partition of } [0, T], N \in \mathbb{N} \right\} < \infty,$$

then $c_n \cdot n^{z \cdot c_n}(x, [0, t])$ is bounded (and is equal 0 outside a compact subset of \mathbb{R}) and thus belongs to $L^p(\mathbb{R})$ for all $t \leq T$. It follows from the easy estimate: for any $z \in \mathbb{R}$

$$n^{z \cdot c_n}(x, [0, t]) \leq \frac{V^r(x, [0, t])}{c_n^r}.$$

Unfortunately, this observation does not yield any condition which guarantees $L_t \in L^p(\mathbb{R})$, except in the rather trivial case $r \leq 1$.

Similarly as in Remark 2.6 we have that if $p \in [1, \infty)$ and $\sum_{0 < s \leq t} |\Delta x_s|^{1+1/p} < \infty$ then $J_t(x^n, \cdot), J_t(x, \cdot) \in L^p(\mathbb{R})$: this follows from Minkowski’s inequality and the fact that for any $s > 0$, $|\Delta x_s^n| \leq |\Delta x_s|$ (see [28, (2.5)] or [25, Section 2]).

Since $x^n \rightarrow x$ uniformly, there exists $c \in \mathbb{R}$ s.t., for all $s \in [0, t]$,

$$\begin{aligned} |x_s^n| &\leq c \text{ for all } n \in \mathbb{N}, \\ \exists \lim_n |x_s^n - u| \mathbf{1}_{[x_{s-}^n, x_s^n]}(u) &= |x_s - u| \mathbf{1}_{[x_{s-}, x_s]}(u) \text{ for all } u \neq x_{s-}, x_s. \end{aligned} \tag{2.38}$$

Now let q be s.t. $1/p + 1/q = 1$, and fix any $f \in W^{2,q}(\mathbb{R})$ and $s \in [0, t]$. Since f'' is locally integrable, it follows from (2.38) and the dominated convergence theorem that

$$\int_{\mathbb{R}} |x_s^n - u| \mathbf{1}_{[x_{s-}^n, x_s^n]}(u) f''(u) du \rightarrow \int_{\mathbb{R}} |x_s - u| \mathbf{1}_{[x_{s-}, x_s]}(u) f''(u) du \quad \text{as } n \rightarrow \infty.$$

We can then apply again the dominated convergence theorem to obtain weak convergence of $J_t(x^n, \cdot)$ to $J_t(x, \cdot)$ in $L^p(\mathbb{R})$, using the domination

$$\int_{\mathbb{R}} |x_s^n - u| \mathbf{1}_{[x_{s-}^n, x_s^n]}(u) |f''(u)| du \leq C_p |\Delta x_s^n|^{1+\frac{1}{p}} \|f''\|_{L^q} \leq C_p |\Delta x_s|^{1+\frac{1}{p}} \|f''\|_{L^q},$$

which follows from the estimate $|\Delta x_s^n| \leq |\Delta x_s|$, Hölder’s inequality and (2.11).

3 Construction of local times for càdlàg semimartingales

The purpose of this section is to give probabilistic constructions of the pathwise local time, as introduced in Definitions 2.4, 2.17 and 2.24, for càdlàg semimartingales. In particular, we show that all three definitions agree a.s. and coincide with the classical probabilistic notion of local times for càdlàg semimartingales.

3.1 Local times via discretisation and as occupation measure

Let $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P})$ be a filtered probability space where the filtration $\mathbb{F} := (\mathbb{F}_t)_{t \in [0, \infty)}$ is supposed to satisfy the usual conditions. Given a càdlàg semimartingale $X = (X_t)_{t \in [0, \infty)}$ and $u \in \mathbb{R}$, one can define $\mathcal{J}_t(u)(\omega) := J_t(X(\omega), u)$, with $J_t(x, u)$ given by (2.8), and the increasing càdlàg adapted process $\mathcal{K}(u)$ by

$$2\mathcal{K}_t(u) := |X_t - u| - |X_0 - u| - \int_{(0, t]} \text{sign}(X_{s-} - u) dX_s. \tag{3.1}$$

It can then be shown that there exists a jointly measurable version of $\mathcal{K}_t(u, \omega)$ such that the family of processes $\mathcal{L} = 2\mathcal{K} - 2\mathcal{J}$, called the (classical) local time of X , satisfies

the Tanaka–Meyer formula (2.10) for $x = X(\omega)$ $\mathbb{P}(d\omega)$ -a.e., is càdlàg in t and is jointly measurable: see¹⁴ [31, Chapter 4, Section 7].

In the following we denote by $L^p(\mu)$ the L^p -space with respect to a measure μ . If $\pi = (\tau_k)_{k \in \mathbb{N}}$, where τ_k are $[0, \infty]$ -valued random variables such that $\tau_0 = 0, \tau_k \leq \tau_{k+1}$ with $\tau_k < \tau_{k+1}$ on $\{\tau_{k+1} < \infty\}$, and $\lim_{k \rightarrow \infty} \tau_k = \infty$, then π is called a random partition. If moreover $\{\tau_k \leq t\} \in \mathcal{F}_t$ for all k, t , then π is called an optional partition. We recall K_s^π was defined in (2.19). The following is the main theorem of this subsection.

Theorem 3.1. *Assume that $f: \mathbb{R} \rightarrow \mathbb{R}$ is a difference of two convex functions, $(\pi^n)_n$ are optional partitions of $[0, \infty)$ such that $|\pi^n \cap [0, t]| \rightarrow 0$ a.s. for all t and $X = (X_t)_{t \in [0, \infty)}$ is a càdlàg semimartingale. Then, there exists a subsequence $(n_k)_k$ such that, for ω outside of a \mathbb{P} -null set (which may depend on f''),*

$$\sup_{s \in [0, t]} \left| K_s^{\pi^{n_k}(\omega)}(X(\omega), u) - \mathcal{K}_s(\omega, u) \right| \rightarrow 0 \quad \text{in } L^p(|f''|(du)) \text{ as } k \rightarrow \infty$$

simultaneously for all $p \in [1, \infty), t \in [0, \infty)$.

Remark 3.2. Theorem 3.1 says that the pathwise crossing time $K^{\pi^n}(X, u)$ sampled along optional partitions $(\pi^n)_n$ (defined applying (2.19) to each path $X(\omega)$ and partition $\pi^n(\omega)$) converges to $\mathcal{K}(u)$. Applying Theorem 3.1 with $f(x) = x^2/2$ gives in particular that $\mathbb{P}(d\omega)$ -a.e. $X(\omega) \in \mathbb{L}_p^W((\pi^{n_k})_k) \subset \mathbb{L}_p((\pi^{n_k})_k)$ for all $p < \infty$ and $T > 0$, i.e., the L^p -level crossing time and the occupation local time exist for a.e. paths of a semimartingale. Indeed, $K_t^{\pi^{n_k}}(X, \cdot) \rightarrow \mathcal{K}_t(\cdot)$ strongly (and thus weakly) in $L^p(\mathbb{R})$ for a.e. ω , locally uniformly in t .

To prove the previous theorem we need some preliminaries. Given $p \in [1, \infty)$ we denote by \mathcal{S}^p the set of càdlàg special semimartingales X which satisfy

$$\|X\|_{\mathcal{S}^p} := \left\| [Y]_\infty^{1/2} \right\|_{L^p(\mathbb{P})} + \left\| \int_0^\infty d|V|_t \right\|_{L^p(\mathbb{P})} < \infty,$$

where $X = Y + V$ is the canonical semimartingale decomposition of X ,

$$[Y]_t := Y_t^2 - 2 \int_0^t Y_{s-} dY_s$$

is the quadratic variation of the martingale Y , and $|V|_t$ is the variation up to time t of the predictable process $(V_t)_{t \in [0, \infty)}$. We recall the existence of $c_p < \infty$ such that the inequality

$$\left\| \sup_{t \in [0, \infty)} |X_t| \right\|_{L^p(\mathbb{P})} \leq c_p \|X\|_{\mathcal{S}^p}, \tag{3.2}$$

holds for all local martingales X (this being one side of the Burkholder–Davis–Gundy inequalities), and thus also trivially extends to all $X \in \mathcal{S}^p$. The core of Theorem 3.1 is the following more technical statement.

Proposition 3.3. *Let $(\pi^n)_n$ be optional partitions of $[0, \infty)$ such that $|\pi^n \cap [0, t]| \rightarrow 0$ a.s. for all t . If $X \in \mathcal{S}^p$ for $p \in [1, \infty)$, and*

$$h^{\pi^n}(u) := \left\| \sup_{t \in [0, \infty)} \left| K_t^{\pi^n(\omega)}(X(\omega), u) - \mathcal{K}_t(\omega, u) \right| \right\|_{L^p(\mathbb{P})}, \quad u \in \mathbb{R},$$

then, for every $u \in \mathbb{R}$, $h^{\pi^n}(u) \rightarrow 0$ as $n \rightarrow \infty$ and $0 \leq h^{\pi^n}(u) \leq c_p \|X\|_{\mathcal{S}^p}$ for all $n \in \mathbb{N}$.

¹⁴Recall the identity (2.7) and notice that the notations used in [31] differ from ours: he calls A^a what we call $2\mathcal{K}(u)$.

As discussed in detail in [9] after Theorem 6.2, for a continuous process X and properly chosen $(\pi^n)_n$ the convergence of $K_t^{\pi^n}(X, u)$ is closely related to the number of upcrossings of X from the level u to the level $u + \varepsilon_n > u$. While stronger versions of the above theorems have already appeared in the case of continuous semimartingales (the strongest being [23, Theorem II.2.4]), in the càdlàg setting we were only able to locate in the literature a version of Theorem 3.1 where, under the strong assumption that $\sum_{s \leq t} |\Delta X_s| < \infty$ a.s., the $L^p(|f''|(du))$ convergence is replaced by pointwise convergence for all but countably many values of u , see [23, Theorem III.3.3]. Thus, compared to the literature, our method provides a novel strong conclusion, with the benefit of a simple proof. Other differences are that we consider the crossing time instead of the number of upcrossings, and we use any optional partitions such that $|\pi^n| \rightarrow 0$ instead of “Lebesgue partitions” (in the language of [9]).

Proof of Proposition 3.3. Consider the convex function $f(x) := |x - u|$ and let us take its left-derivative $\text{sign}(x - u)$ and its second (distributional) derivative $2\delta_u$. Subtracting from the discrete-time Tanaka–Meyer formula (2.20) its continuous-time stochastic counterpart (3.1) and considering the process $K_t^{\pi^n}(u)(\omega) := K_t^{\pi^n}(X(\omega), u)$ we obtain

$$0 = \int_0^t (H_s^{\pi^n}(u) - H_s(u)) dX_s + 2(K_t^{\pi^n}(u) - \mathcal{K}_t(u)), \tag{3.3}$$

where for $\pi^n = (\tau_i^n)_i$ by H^{π^n} and $H(u)$ we denote the predictable processes

$$H_s^{\pi^n}(u) := \sum_i \text{sign}(X_{\tau_i^n} - u) \mathbf{1}_{(\tau_i^n, \tau_{i+1}^n]}(s) \quad \text{and} \quad H_s(u) := \text{sign}(X_{s-} - u).$$

Now $h^{\pi^n}(u) \rightarrow 0$ for each $u \in \mathbb{R}$ follows from (3.2) and (3.3) if we show that

$$\int_0^\cdot H_s^{\pi^n}(u) dX_s \rightarrow \int_0^\cdot H_s(u) dX_s \quad \text{in } \mathcal{S}^p.$$

To this end fix n and u and notice that from

$$H_s^{\pi^n}(u) = \text{sign}(X_{\tau_i^n} - u), \quad \text{for } i \text{ such that } \tau_i^n < s \leq \tau_{i+1}^n$$

and $|\pi^n \cap [0, t]| \rightarrow 0$ a.s. for all t it follows that $H_s^{\pi^n}(u) \rightarrow H_s(u)$ a.s. for all s . Since $|H_s^{\pi^n}(u) - H_s(u)| \leq 2$, it follows that $\int_0^\cdot H_s^{\pi^n}(u) dX_s \rightarrow \int_0^\cdot H_s(u) dX_s$ in \mathcal{S}^p (by the dominated convergence theorem) and that

$$h^{\pi^n}(u) \leq \frac{c_p}{2} \left\| \int_0^\cdot (H_s^{\pi^n}(u) - H_s(u)) dX_s \right\|_{\mathcal{S}^p} \leq c_p \|X\|_{\mathcal{S}^p} \quad \text{for all } u \in \mathbb{R},$$

concluding the proof. □

Proof of Theorem 3.1. Let $(\tau_m)_m$ be a sequence of stopping times which prelocalizes X to \mathcal{S}^p (see e.g. [31, Chapter V, Theorem 4]), i.e., $\tau_m \uparrow \infty$ a.s. and $X^{\tau_m-} \in \mathcal{S}^p$ for all m . Let $\mu_i(A) := |f''|(A \cap [-i, i])$ and set, for $T > 0$,

$$G_n := G_n(\omega, T, u) := \sup_{t \leq T} |K_t^{\pi^{nk}}(\omega)(X(\omega), u) - \mathcal{K}_t(u, \omega)|$$

and $G_n^m := \mathbf{1}_{\{T < \tau_m\}} G_n$. Since μ_i is a finite measure, Proposition 3.3 implies that, as $n \rightarrow \infty$, G_n^m converges to 0 in $L^p(\mathbb{P} \times \mu_i)$ for all $m, i \in \mathbb{N}$ and $T \geq 0$. By Fubini’s theorem $\|G_n^m\|_{L^p(\mu_i)}$ converges to zero in $L^p(\mathbb{P})$, and so passing to a subsequence (without relabelling) we find that, for every ω outside a \mathbb{P} -null set $N_{i,m}^{p,T}$, $\|G_n^m(\omega, T, \cdot)\|_{L^p(\mu_i)} \rightarrow 0$. Then along a diagonal subsequence we obtain that $G_n^m(\omega, T, \cdot)$ converges to 0 in $L^p(\mu_i)$

for all $i, m, p, T \in \mathbb{N} \setminus \{0\}$ for every ω outside the null set $N_{f''} := \cup_{i,m,T,p \in \mathbb{N} \setminus \{0\}} N_{i,m}^{p,T}$. Since $G_n = G_n^m$ on $\{T < \tau_m\}$, $G_n \rightarrow 0$ in $L^p(\mu_i)$ for all $i, p, T \in \mathbb{N} \setminus \{0\}$ for every ω outside $N_{f''}$. Since outside a compact set $G_n(\omega, T, \cdot) = 0$ for all n , convergence in $L^p(\mu_i)$ for arbitrarily big i, p implies convergence in $L^p(|f''|(du))$ for all $p \in [1, \infty)$. Since $G_n(\omega, \cdot, u) = 0$ is increasing, convergence for arbitrarily big T implies convergence for all $T \in [0, \infty)$. \square

3.2 Local times via interval crossings

Recall the definition of L^p -interval crossing local time of a deterministic path along a sequence of positive reals tending to 0 in Definition 2.24. In this subsection we prove the following theorem.

Theorem 3.4. *Let $X = (X_t)_{t \in [0, \infty)}$ be a càdlàg semimartingale and $T > 0$. There exist a \mathbb{P} -null set E such that for any $\omega \in \Omega \setminus E$ and any sequence of positive reals $(c_n)_{n \in \mathbb{N}}$ which converges to 0, $x_t = X_t(\omega)$, $t \in [0, T]$, belongs to $\mathbb{L}_1^S((c_n)_{n \in \mathbb{N}})$ and for any $t \in [0, T]$ the L^1 -interval crossing local time of x along $(c_n)_{n \in \mathbb{N}}$, L_t , coincides (in $L^1(\mathbb{R})$) with the classical local time of X , \mathcal{L}_t .*

We note a difference in the above result when compared with Theorem 3.1. In the former, we obtained pathwise convergence on a subsequence and outside a null set which depended on the discretisation, i.e., on the optional partitions $(\pi^n)_n$ of $[0, \infty)$. Here, the method of discretisation is fixed and implicit in the Skorokhod problem, however we are able to obtain pathwise convergence, outside of a common null set E , simultaneously for all sequences (c_n) .

As noted already after the statement of Proposition 3.3, a similar result was proven in [23, Theorem III.3.3], namely that for any càdlàg semimartingale X , as $c \rightarrow 0$, $c \cdot n^{u,c}(X, [0, t]) \rightarrow \mathcal{L}_t^u$ a.s. for all but countably many $u \in \mathbb{R}$, where $n^{u,c}$ was defined in (2.25). However this was only established for semimartingales whose jumps are a.s. summable, i.e., $\sum_{0 < s \leq t} |\Delta X_s| < \infty$ for any $t > 0$.

Theorem 3.4 is easily proved using the following technical statement (of independent interest), about the quantity

$$Q_t^{z,d} := d \cdot n^{z,d}(X, [0, t]) - \frac{1}{d} \int_{z-d/2}^{z+d/2} \mathcal{L}_t^u \, du, \quad t \in [0, \infty).$$

Theorem 3.5. *Let $X = (X_t)_{t \in [0, \infty)}$ be a càdlàg semimartingale and \mathcal{L}_t^u , $t \geq 0$, $u \in \mathbb{R}$, its local times. If $(d_k)_{k \in \mathbb{N}}$ is a sequence of positive reals such that $\sum_{k \in \mathbb{N}} d_k < \infty$ then*

$$\int_{\mathbb{R}} |Q_t^{z,d_k}| \, dz \rightarrow 0 \quad \mathbb{P}(d\omega)\text{-a.e. as } k \rightarrow \infty, \tag{3.4}$$

and if $X \in S^{2p}$ for $p \in [1, \infty)$ and $|X|$ is bounded by a constant then for any $t \in [0, \infty)$

$$\exists \lim_{d \downarrow 0} \left\| \int_{\mathbb{R}} |Q_t^{z,d}| \, dz \right\|_{L^p(\mathbb{P})} = 0. \tag{3.5}$$

Let us now prove Theorem 3.4; the rest of the subsection will be devoted to the proof of Theorem 3.5.

Proof of Theorem 3.4. By standard properties of convolutions, for example [13, Theorem 8.14], $\frac{1}{d} \int_{z-d/2}^{z+d/2} \mathcal{L}_t^y \, dy \rightarrow \mathcal{L}_t^z$ in $L^1(\mathbb{R})$ as $d \rightarrow 0+$. By this and Theorem 3.5 there exists a \mathbb{P} -null set E_1 such that for any $\omega \in \Omega_1 = \Omega \setminus E_1$ and $x = X(\omega)$ the limit of $d_k \cdot n^{z,d_k}(x, [0, t])$ in $L^1(\mathbb{R})$ (thus also the weak limit in $L^1(\mathbb{R})$), where for example $d_k = k^{-2}$, exists and is equal $\mathcal{L}_t(\cdot)$ as $k \rightarrow \infty$. Now, for the given sequence $(c_n)_n$ and n

such that $c_n \leq 1/2$ define $k(n)$ to be such natural number that $d_{k(n)+1} < c_n \leq d_{k(n)}$. For such n we have bounds

$$\begin{aligned} \left(\frac{d_{k(n)+1}}{d_{k(n)}}\right) d_{k(n)} \cdot n^{\cdot, d_{k(n)}}(x, [0, t]) &\leq c_n \cdot n^{\cdot, c_n}(x, [0, t]) \\ &\leq \left(\frac{d_{k(n)}}{d_{k(n)+1}}\right) d_{k(n)+1} \cdot n^{\cdot, d_{k(n)+1}}(x, [0, t]). \end{aligned} \tag{3.6}$$

Notice, that since $d_k/d_{k+1} \rightarrow 1$ as $k \rightarrow \infty$, we have that for any $\omega \in \Omega_1$ the limits in $L^1(\mathbb{R})$ of both – lower and upper – bounds in (3.6) as $n \rightarrow \infty$ coincide with the limit of $d_k \cdot n^{\cdot, d_k}(x, [0, t])$ which is equal $\mathcal{L}_t(\cdot)$. Thus for $\omega \in \Omega_1$, $c_n \cdot n^{\cdot, c_n}(x, [0, t])$ tends in $L^1(\mathbb{R})$ to the same limit $\mathcal{L}_t(\cdot)$.

Let us denote $\Omega_2 = \Omega_1 \cap \{\omega \in \Omega : [X]_T(\omega) < \infty\}$. Naturally, $\mathbb{P}(\Omega_2) = 1$. For $\omega \in \Omega_2$ we also have $\sum_{0 < s \leq t} (\Delta X_s(\omega))^2 < \infty$. This observation together with Remark 2.27 yields that if $\omega \in \Omega_2$ and $x = X(\omega)$ then the sequence $(J_t(x^n, \cdot))_n$ converges weakly in $L^1(\mathbb{R})$ to $J_t(x, \cdot)$.

Thus we proved that for $\omega \in \Omega_2$ and $x = X(\omega)$ both required (weak) convergences hold, thus $x \in \mathbb{L}_1^S((c_n)_n)$. □

We now begin the proof of Theorem 3.5. It is achieved via several lemmas. From now on, $X = (X_t)_{t \in [0, \infty)}$ will be a càdlàg semimartingale, and $\mathcal{L}_t^u, t \geq 0, u \in \mathbb{R}$, its local times. We will also need to consider, given $d > 0$ and $z \in \mathbb{R}$, the semimartingale $X^{z,d}$, the processes $Y^{z,d}, \tilde{X}^{z,d}$, the functions $F^{z,d}, I_z^d: \mathbb{R} \rightarrow \mathbb{R}$ and the sequence of stopping times $(\tau_n^{z,d})_{n \in \mathbb{N}}$ defined as follows:

$$\begin{aligned} X_t^{z,d} &:= F^{z,d}(X_t), \quad \text{where } F^{z,d}(x) := (z - d/2) \vee (x \wedge (z + d/2)), \\ Y_t^{z,d} &:= X_t^{z,d} - X_{t-}^{z,d} - I_z^d(X_{t-}) \Delta X_t, \quad \text{where } I_z^d(x) := \mathbf{1}_{(z-d/2, z+d/2]}(x), \\ \tilde{X}_t^{z,d} &:= \sum_{n=1}^{\infty} X_{\tau_{n-1}^{z,d}}^{z,d} \mathbf{1}_{[\tau_{n-1}^{z,d}, \tau_n^{z,d})}(t), \end{aligned}$$

where the sequence of stopping times is defined by induction as follows: $\tau_0^{z,d} := 0$,

$$\tau_1^{z,d} := \begin{cases} \inf \{s > 0 : X_s^{z,d} \in \{z - d/2, z + d/2\}\} & \text{if } X_0^{z,d} \notin \{z - d/2, z + d/2\} \\ \inf \{s > 0 : |X_s^{z,d} - X_0^{z,d}| = d\} & \text{if } X_0^{z,d} \in \{z - d/2, z + d/2\} \end{cases},$$

and, for $n \geq 1$,

$$\tau_{n+1}^{z,d} := \begin{cases} \inf \{s > \tau_n^{z,d} : |X_s^{z,d} - X_{\tau_n^{z,d}}^{z,d}| = d\} & \text{if } \tau_n^{z,d} < \infty \\ \infty & \text{if } \tau_n^{z,d} = \infty \end{cases},$$

where we apply the usual conventions $\inf \emptyset := \infty$ and $[\infty, \infty) := \emptyset$.

The first step in the proof of Theorem 3.5 is to obtain a convenient formula for the quantity to be estimated, as we will now do.

Lemma 3.6. *There exists a càdàg adapted process $R^{z,d}$ with values in $(-2, 0]$ such that*

$$Q_t^{z,d} = R_t^{z,d} d + \frac{1}{d} \sum_{0 < s \leq t} (\Delta X_s^{z,d})^2 + \frac{2}{d} \int_0^t (X_{s-}^{z,d} - \tilde{X}_{s-}^{z,d}) dX_s^{z,d}, \quad t \in [0, \infty).$$

In the proof of Lemma 3.6, and later on, we will make use of the following simple lemma.

Lemma 3.7. $X^{z,d}$ is a semimartingale and the following identity holds

$$X_t^{z,d} - X_0^{z,d} = \frac{1}{2} \left(\mathcal{L}_t^{z-d/2} - \mathcal{L}_t^{z+d/2} \right) + \int_0^t I_z^d(X_{s-}) dX_s + \sum_{0 < s \leq t} Y_s^{z,d}, \quad t \in [0, \infty).$$

Proof. Expressing $F^{z,d}$ as

$$F^{z,d}(x) = z + \frac{1}{2} |x - (z - d/2)| - \frac{1}{2} |x - (z + d/2)| \tag{3.7}$$

shows that it equals the difference of convex functions, and allows to quickly calculate its derivatives as follows. Its first left-derivative is $(F^{z,d})'(x) = I_z^d(x)$, and its second (distributional) derivative is $(F^{z,d})'' = \delta_{z-d/2} - \delta_{z+d/2}$. The thesis follows from the Tanaka–Meyer formula applied to X and $F^{z,d}$ (see e.g. [31, Chapter IV, Theorem 70]). \square

Proof of Lemma 3.6. We have

$$n^{z,d}(X, [0, t]) = n^{z,d}(X^{z,d}, [0, t]). \tag{3.8}$$

We can now define

$$R_t^{z,d} := n^{z,d}(X^{z,d}, [0, t]) - \frac{1}{d^2} \sum_{n=1}^{\infty} \left(X_{\tau_n^{z,d} \wedge t}^{z,d} - X_{\tau_{n-1}^{z,d} \wedge t}^{z,d} \right)^2. \tag{3.9}$$

Notice that $R_t^{z,d} \in (-2, 0]$ since only the first and last non-zero term in the above sum may differ from d^2 , and they are then strictly smaller than d^2 . Let us now work out an alternative expression for $R_t^{z,d}$. Using integration by parts we get

$$\sum_{n=1}^{\infty} \left(X_{\tau_n^{z,d} \wedge t}^{z,d} - X_{\tau_{n-1}^{z,d} \wedge t}^{z,d} \right)^2 - [X^{z,d}]_t = 2 \int_0^t \left(X_{s-}^{z,d} - \tilde{X}_{s-}^{z,d} \right) dX_s^{z,d}, \tag{3.10}$$

where $[X^{z,d}]$ denotes the quadratic variation of $X^{z,d}$. Lemma 3.7 shows that

$$X_t^{z,d} - X_0^{z,d} - \int_0^t I_z^d(X_{s-}) dX_s$$

is a process of finite variation and thus, denoting by $[Y]^c$ the continuous part of the quadratic variation of the semimartingale Y , we get that

$$[X^{z,d}]_t^c = \left[\int_0^{\cdot} I_z^d(X_{s-}) dX_s \right]_t^c = \int_0^t I_z^d(X_{s-}) d[X]_s^c,$$

and so by the occupation formula (2.6) we get

$$[X^{z,d}]_t = [X^{z,d}]_t^c + \sum_{0 < s \leq t} (\Delta X_s^{z,d})^2 = \int_{z-d/2}^{z+d/2} \mathcal{L}_t^u du + \sum_{0 < s \leq t} (\Delta X_s^{z,d})^2. \tag{3.11}$$

Combining (3.8), (3.9), (3.10), and (3.11) yields the thesis. \square

To take advantage of the formula in Lemma 3.6, we need a more convenient expression for the integral with respect to $X^{z,d}$; to obtain one, we again employ Lemma 3.7. This leads us to have to estimate the integral in dz of three stochastic integrals (with respect to $\mathcal{L}^{z+d/2} - \mathcal{L}^{z-d/2}$, X and $\sum_{0 < s \leq \cdot} Y_s^{z,d}$, respectively); we will now do that, using a lemma for each integral.

Lemma 3.8. For $t \in [0, \infty)$, one has

$$\int_0^t \left(X_{s-}^{z,d} - \tilde{X}_{s-}^{z,d} \right) d\mathcal{L}_s^{z \pm d/2} = 0.$$

Proof. By [31, Chapter IV, Theorem 69]), each of the atomless measures $d\mathcal{L}_s^{z \pm d/2}$ is carried by the corresponding set

$$\{s > 0 : X_s = X_{s-} = z \pm d/2\},$$

and since the sets

$$\left\{ s > 0 : X_s = X_{s-} = z \pm d/2 \neq \tilde{X}_{s-}^{z,d} \right\}$$

are countable (because they are subsets of the jumps of the càdlàg process $\tilde{X}^{z,d}$), we conclude that $d\mathcal{L}_s^{z \pm d/2}$ is carried by the set

$$\left\{ s > 0 : X_s = X_{s-} = z \pm d/2 = \tilde{X}_{s-}^{z,d} \right\} \subseteq \left\{ s > 0 : X_{s-}^{z,d} = \tilde{X}_{s-}^{z,d} \right\}. \quad \square$$

The stochastic integral with respect to X will be estimated using the following lemma.

Lemma 3.9. Let $(H^z)_{z \in \mathbb{R}}$ be a measurable¹⁵ family of predictable process and assume that there exist constants $d, M \in (0, \infty)$ s.t., for all $s \geq 0$, $|H_s^z| \leq d$ a.s. for all $z \in \mathbb{R}$, and $H_s^z = 0$ a.s. for all $|z| > M + d/2$. Given a semimartingale S , define

$$W_t(S) := W_t^{z,d}(S) := \int_{\mathbb{R}} \left| \frac{2}{d} \int_0^t H_s^z I_z^d(X_{s-}) dS_s \right| dz.$$

If we assume that $S = V$ has finite variation $|V|_t < \infty$ a.s., then

$$|W_t(V)| \leq 2d \cdot |V|_t,$$

whereas if $S = N$ is a martingale s.t. $\mathbb{E}[N]_t^p < \infty$, then there exists a constant $C_p \in (0, \infty)$ (which depends only on p) s.t.

$$\mathbb{E}(W_t(N))^{2p} \leq (2M + d)^{2p-1} dC_p \mathbb{E}(N)_t^p. \quad (3.12)$$

Proof. Since $I_z^d(X_{s-}) = 1$ if $X_{s-} - \frac{d}{2} \leq z < X_{s-} + \frac{d}{2}$, and $I_z^d(X_{s-}) = 0$ otherwise, we get

$$\int_{\mathbb{R}} I_z^d(X_{s-}) dz = d \quad (3.13)$$

and so by Fubini’s theorem

$$|W_t(V)| \leq 2 \int_{\mathbb{R}} \left(\int_0^t I_z^d(X_{s-}) d|V|_s \right) dz = 2d |V|_t.$$

Since $(\int |g| d\mu)^p \leq \int |g|^p d\mu$ holds for any probability measure μ , we get that

$$\left(\int_{\Omega} |g| d\mu \right)^p \leq \mu(\Omega)^{p-1} \int_{\Omega} |g|^p d\mu \quad (3.14)$$

for any positive finite measure μ on Ω . Since

$$G_t^z := \frac{2}{d} \int_0^t H_s^z I_z^d(X_{s-}) dN_s$$

¹⁵We mean that the function $(z, \omega, t) \mapsto H_t^z(\omega)$ is $\mathcal{B}(\mathbb{R}) \times \mathcal{P}$ -measurable, where $\mathcal{B}(\mathbb{R})$ are the Borel sets and \mathcal{P} the predictable σ -algebra.

equals 0 when $|z| > M + d/2$, applying (3.14) it follows that

$$\mathbb{E}(W_t(N))^{2p} = \mathbb{E} \left(\int_{-M-d/2}^{M+d/2} |G_t^z| dz \right)^{2p} \leq (2M + d)^{2p-1} \mathbb{E} \left(\int_{\mathbb{R}} (G_t^z)^{2p} dz \right). \quad (3.15)$$

Burkholder-David-Gundy inequality applied to G^z gives that

$$\mathbb{E} (G_t^z)^{2p} \leq c_p \mathbb{E} \left(\sqrt{[G^z]_t} \right)^{2p} = c_p \mathbb{E} \left(\int_0^t \left(\frac{2}{d} H_s^z I_z^d (X_{s-}) \right)^2 d[N]_s \right)^p =: A_t^z. \quad (3.16)$$

Using first (3.14), and then $|H| \leq d$ and $(I_z^d)^{2p} = I_z^d$, we get the two inequalities

$$\begin{aligned} A_t^z &\leq c_p \mathbb{E} \left([N]_t^{p-1} \int_0^t \left(\frac{2}{d} H_s^z I_z^d (X_{s-}) \right)^{2p} d[N]_s \right) \\ &\leq 4^p c_p \mathbb{E} \left([N]_t^{p-1} \int_0^t I_z^d (X_{s-}) d[N]_s \right). \end{aligned} \quad (3.17)$$

Applying Fubini’s theorem and combining (3.15), (3.16) and (3.17) we get

$$\mathbb{E}(W_t(N))^{2p} \leq 4^p c_p (2M + d)^{2p-1} \mathbb{E} \left([N]_t^{p-1} \int_0^t \left(\int_{\mathbb{R}} I_z^d (X_{s-}) dz \right) d[N]_s \right),$$

and now (3.13) yields the thesis with $C_p := 4^p c_p$. □

To deal with the stochastic integral with respect to $\sum_{0 < s \leq \cdot} Y_s^{z,d}$ we will use the following lemma.

Lemma 3.10.

$$\int_{\mathbb{R}} dz \sum_{0 < s \leq t} |Y_s^{z,d}| \leq \sum_{0 < s \leq t} (\Delta X_s)^2 g_d(\Delta X_s),$$

where

$$g_d(x) := \begin{cases} 1 & \text{if } |x| \leq d \\ \frac{5d}{|x|} & \text{if } |x| > d \end{cases}, \quad x \in \mathbb{R}, d > 0.$$

Proof. Since the expression $\Delta f(X_s) - f'(X_{s-})\Delta X_s$ is linear in f and equals 0 when f is a constant, using (3.7) and (2.7) shows that

$$Y_s^{z,d} = Z_s^{z,-d} - Z_s^{z,d}, \text{ where } Z_s^{z,u} := |X_s - (z + u/2)| \mathbf{1}_{[X_{s-}, X_s)}(z + u/2), \quad z, u \in \mathbb{R},$$

and to conclude we only need to compute the L^1 -norm

$$\sum_{0 < s \leq t} \int_{\mathbb{R}} dz |Z_s^{z,-d} - Z_s^{z,d}|$$

of $Z_s^{z,-d} - Z_s^{z,d}$.

If $d \geq |\Delta X_s|$, then (2.11) with $p = 1$ gives that

$$\int_{\mathbb{R}} dz |Z_s^{z,-d} - Z_s^{z,d}| \leq \int_{\mathbb{R}} dz (|Z_s^{z,-d}| + |Z_s^{z,d}|) = (\Delta X_s)^2. \quad (3.18)$$

To deal with the case $d < |\Delta X_s|$, let us notice that

$$\text{if } z + d/2 < X_{s-} \wedge X_s \text{ or } z - d/2 > X_{s-} \vee X_s \text{ then } Z_s^{z,-d} = Z_s^{z,d} = 0$$

and

$$\text{if } X_{s-} \wedge X_s < z - d/2 < z + d/2 < X_{s-} \vee X_s \text{ then } |Z_s^{z,-d} - Z_s^{z,d}| \leq d.$$

The last estimate follows from the fact that if

$$X_{s-} \wedge X_s < z - d/2 < z + d/2 < X_{s-} \vee X_s,$$

then $Z_s^{z,-d} = |X_s - (z - d/2)|$, $Z_s^{z,d} = |X_s - (z + d/2)|$, and the inequality $||a| - |b|| \leq |a - b|$.

Finally, in the case

$$z \in [X_{s-} \wedge X_s - d/2, X_{s-} \wedge X_s + d/2] \cup [X_{s-} \vee X_s - d/2, X_{s-} \vee X_s + d/2]$$

we apply the estimate $|Z_s^{z,u}| \leq |\Delta X_s|$, valid for any $z, u \in \mathbb{R}$.

Putting together three considered cases we have the estimate

$$\begin{aligned} \int_{\mathbb{R}} dz |Z_s^{z,-d} - Z_s^{z,d}| &\leq \int_{X_{s-} \wedge X_s - d/2}^{X_{s-} \wedge X_s + d/2} dz (|Z_s^{z,-d}| + |Z_s^{z,d}|) + \int_{X_{s-} \wedge X_s + d/2}^{X_{s-} \vee X_s - d/2} dz \\ &\quad + \int_{X_{s-} \vee X_s - d/2}^{X_{s-} \vee X_s + d/2} dz (|Z_s^{z,-d}| + |Z_s^{z,d}|) \\ &\leq 2d|\Delta X_s| + (|\Delta X_s| - d)d + 2d|\Delta X_s| \leq 5d|\Delta X_s|. \end{aligned} \tag{3.19}$$

From (3.18), (3.19) it follows that the L^1 -norm of $Z_s^{z,-d} - Z_s^{z,d}$ is bounded by

$$\sum_{0 < s \leq t: d \geq |\Delta X_s|} (\Delta X_s)^2 + \sum_{0 < s \leq t} \mathbf{1}_{(0, |\Delta X_s|)}(d) 5d|\Delta X_s| = \sum_{0 < s \leq t} (\Delta X_s)^2 g_d(\Delta X_s),$$

which concludes the proof. □

Proof of Theorem 3.5. For now assume that X is in S^{2p} for some $p \in [1, \infty)$, and $|X|$ is bounded by a constant M . Since $n^{z,d}(X, [0, t])$ and \mathcal{L}_t^u are equal 0 for $|z|, |u| > M_t := \sup_{0 \leq s \leq t} |X_s| < \infty$, $Q_t^{z,d} = 0$ for any $z \notin [-M_t - d/2, M_t + d/2]$, and thus

$$\int_{\mathbb{R}} |Q_t^{z,d}| dz = \int_{-M_t - d/2}^{M_t + d/2} |Q_t^{z,d}| dz.$$

We can now apply Lemma 3.6 to estimate the latter as a sum of three terms. The first is

$$\left| \int_{-M_t - d/2}^{M_t + d/2} d \cdot R_t^{z,d} dz \right| \leq 2d \cdot 2 \cdot (M_t + d/2) = 4M_t d + 2d^2. \tag{3.20}$$

The second term is

$$\int_{-M_t - d/2}^{M_t + d/2} \frac{1}{d} \sum_{0 < s \leq t} (\Delta X_s^{z,d})^2 dz = \sum_{0 < s \leq t} \int_{-M_t - d/2}^{M_t + d/2} \frac{1}{d} (\Delta X_s^{z,d})^2 dz. \tag{3.21}$$

By definition of $X_s^{z,d}$ we have that $|\Delta X_s^{z,d}| \leq |\Delta X_s| \wedge d$, and if $X_{s-} < X_s$ then $\Delta X_s^{z,d} = 0$ whenever $z \notin [X_{s-} - \frac{d}{2}, X_s + \frac{d}{2}]$, and analogously if $X_s \leq X_{s-}$ then $\Delta X_s^{z,d} = 0$ whenever $z \notin [X_s - \frac{d}{2}, X_{s-} + \frac{d}{2}]$. This gives the first of the following inequalities

$$\int_{\mathbb{R}} \frac{1}{d} (\Delta X_s^{z,d})^2 dz \leq \frac{1}{d} (|\Delta X_s| \wedge d)^2 (|\Delta X_s| + d) \leq \frac{1}{d} (|\Delta X_s| \wedge d)^2 (|\Delta X_s| \vee d). \tag{3.22}$$

Thus, using the identity

$$\frac{1}{d} \left(|\Delta X_s| \wedge d \right)^2 \left(|\Delta X_s| \vee d \right) = (\Delta X_s)^2 \wedge (d|\Delta X_s|),$$

which can easily verified separately for the cases $d < |\Delta X_s|$ and $d \geq |\Delta X_s|$, combined with (3.22) and (3.21), gives that

$$\int_{-M_t-d/2}^{M_t+d/2} \frac{1}{d} \sum_{0 < s \leq t} (\Delta X_s^{z,d})^2 dz \leq 2 \sum_{0 < s \leq t} (\Delta X_s)^2 \wedge (d|\Delta X_s|) =: D_t^d. \tag{3.23}$$

The third and last term which we need to estimate is

$$\int_{\mathbb{R}} \left| \frac{2}{d} \int_0^t \left(X_{s-}^{z,d} - \tilde{X}_{s-}^{z,d} \right) dX_s^{z,d} \right| dz. \tag{3.24}$$

To do so, we use Lemma 3.7 to write this as the sum of the integrals with respect to $\mathcal{L}^{z+d/2} - \mathcal{L}^{z-d/2}$, X , and $\sum_{0 < s \leq \cdot} Y_s^{z,d}$. The first integral is zero, thanks to Lemma 3.8. To estimate the second integral (in dX), we write the canonical semimartingale decomposition $X = N + V$ of X as a local martingale N and a predictable process of finite variation V , and apply Lemma 3.9 with

$$H_s^z := X_{s-}^{z,d} - \tilde{X}_{s-}^{z,d}.$$

Assumptions of Lemma 3.9 are satisfied because

$$\left| X_{s-}^{z,d} - \tilde{X}_{s-}^{z,d} \right| \leq d \quad \text{for all } d, s > 0, z \in \mathbb{R}, \tag{3.25}$$

$X \in \mathcal{S}^{2p}$ implies $[N]_\infty \in L^p(\mathbb{R})$, $|V|_\infty \in L^{2p}(\mathbb{R})$, and from the implication

$$\text{if } X_{s-} \notin [z - d/2, z + d/2] \quad \text{then } X_{s-}^{z,d} - \tilde{X}_{s-}^{z,d} = 0$$

it follows that $X_{s-}^{z,d} - \tilde{X}_{s-}^{z,d} = 0$ unless $|z - X_{s-}| \leq d/2$, and since the constant M satisfies $M \geq \sup_{0 \leq s} |X_s|$, this implies that $X_{s-}^{z,d} - \tilde{X}_{s-}^{z,d} = 0$ for $|z| > M + d/2$. To estimate the third integral, we apply Lemma 3.10 and (3.25). Combining these three estimates we can bound the third term (the one in (3.24)), and this bound, combined with those obtained in (3.20) and (3.23) for the first and second terms gives that

$$\int_{\mathbb{R}} |Q_t^{z,d}| dz \leq 4M_t d + 2d^2 + D_t^d + 2d|V|_t + W_t^{z,d}(N) + 2 \sum_{0 < s \leq t} (\Delta X_s)^2 g_d(\Delta X_s). \tag{3.26}$$

Clearly (3.5) follows from (3.26) and the dominated convergence theorem, since any X in \mathcal{S}^{2p} satisfies $\mathbb{E}([X]_t^p + \sup_{s \leq t} |X_s|^{2p}) < \infty$ (see e.g. [10, Chapter 7, Section 3, Number 98, Page 295, Equations 98.5 and 98.7]), g_d satisfies $0 \leq g_d(x) \leq 5$ and $g_d(x) \rightarrow 0$ at all $x \neq 0$ as $d \downarrow 0$, and we use the fact that $\mathbb{E}(W_t^{z,d}(N))^p \leq \sqrt{\mathbb{E}(W_t^{z,d}(N))^{2p}}$, which goes to zero thanks to Lemma 3.9.

If X is an arbitrary semimartingale, to prove (3.4) we can assume w.l.o.g. that X is in \mathcal{S}^2 by pre-localisation, see e.g. [31, Chapter IV, Theorem 13]). Now let $d_k \geq 0$ be such that $\sum_{k=1}^\infty d_k < \infty$; the term $W_t^{z,d}(N)$ is controlled by the estimate (3.12), which gives that

$$\mathbb{E} \left(\sum_{k=1}^\infty \left(W_t^{z,d_k}(N) \right)^2 \right) < \infty,$$

from which we conclude that $W_t^{z,d_k}(N) \rightarrow 0$ a.s. as $k \rightarrow \infty$. As the remaining terms in (3.26) converge to 0 a.s. as $k \rightarrow \infty$ (the term $D_t^{d_k}$ and the last term by dominated convergence, the others trivially), (3.4) follows. \square

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