

## Research Article

# Relaxation Problems Involving Second-Order Differential Inclusions

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We present relaxation problems in control theory for the second-order differential inclusions, with four boundary conditions,  $\ddot{u}(t) \in F(t, u(t), \dot{u}(t))$  a.e. on  $[0, 1]$ ;  $u(0) = 0$ ,  $u(\eta) = u(\theta) = u(1)$  and, with  $m \geq 3$  boundary conditions,  $\ddot{u}(t) \in F(t, u(t), \dot{u}(t))$  a.e. on  $[0, 1]$ ;  $\dot{u}(0) = 0$ ,  $u(1) = \sum_{i=1}^{m-2} a_i u(\xi_i)$ , where  $0 < \eta < \theta < 1$ ,  $0 < \xi_1 < \xi_2 < \dots < \xi_{m-2} < 1$  and  $F$  is a multifunction from  $[0, 1] \times \mathbb{R}^n \times \mathbb{R}^n$  to the nonempty compact convex subsets of  $\mathbb{R}^n$ . We have results that improve earlier theorems.

## 1. Introduction

Second-order differential inclusions of three boundary conditions were studied by many authors [1–6], using Hartman-type functions. Such a function was first introduced by [7] for two boundary conditions. Moreover, in [8] we consider second-order differential inclusions with four boundary conditions,

$$\begin{aligned} \ddot{u}(t) &\in F(t, u(t), \dot{u}(t)), \quad \text{a.e. on } [0, T], \\ u(0) &= x_0, \quad u(\eta) = u(\theta) = u(T), \end{aligned} \quad (1)$$

where  $0 < \eta < \theta < T$  and  $F$  is a multifunction from  $[0, T] \times \mathbb{R}^n \times \mathbb{R}^n$  to the nonempty compact subsets of  $\mathbb{R}^n$ , while in [9] we study four-point boundary value problems for differential inclusions and differential equations with and without multivalued moving constraints.

In the present paper, we study relaxation results for the second-order differential inclusions, with four boundary conditions,

$$\begin{aligned} \ddot{u}(t) &\in F(t, u(t), \dot{u}(t)), \quad \text{a.e. on } [0, 1], \\ u(0) &= 0, \quad u(\eta) = u(\theta) = u(1) \end{aligned} \quad (P)$$

and, with  $m \geq 3$  boundary conditions,

$$\begin{aligned} \ddot{u}(t) &\in F(t, u(t), \dot{u}(t)), \quad \text{a.e. on } [0, 1], \\ \dot{u}(0) &= 0, \quad u(1) = \sum_{i=1}^{m-2} a_i u(\xi_i), \end{aligned} \quad (Q)$$

where  $0 < \eta < \theta < 1$ ,  $0 < \xi_1 < \xi_2 < \dots < \xi_{m-2} < 1$ , and  $F$  is a multifunction from  $[0, 1] \times \mathbb{R}^n \times \mathbb{R}^n$  to the non-empty compact subsets of  $\mathbb{R}^n$ .

In conjunction with Problem (P) and Problem (Q) we also consider the following problems:

$$\begin{aligned} \dot{u}(t) &\in \text{ext } F(t, u(t), \dot{u}(t)), \quad \text{a.e. on } [0, 1], \\ u(0) &= 0, \quad u(\eta) = u(\theta) = u(1), \end{aligned} \quad (P_e)$$

$$\begin{aligned} \dot{u}(t) &\in \text{ext } F(t, u(t), \dot{u}(t)), \quad \text{a.e. on } [0, 1], \\ \dot{u}(0) &= 0, \quad u(1) = \sum_{i=1}^{m-2} a_i u(\xi_i). \end{aligned} \quad (Q_e)$$

By  $\text{ext } F(t, u(t), \dot{u}(t))$ , we denote the set of extreme points of  $F(t, u(t), \dot{u}(t))$ .

## 2. Notations and Preliminaries

Throughout this paper we let  $I = [0, 1]$  and  $0 < \xi_1 < \xi_2 < \dots < \xi_{m-2} < 1$ . We will use the following definitions, notations, and summarize some results.

(i) A multifunction  $F$  from a metric space  $(X, d)$  to the set  $P_f(Y)$  of all closed subsets of another metric space  $Y$  is lower semicontinuous (*l. s. c.*) at  $x_0 \in X$  if for every open subset  $V$  in  $Y$  with  $F(x_0) \cap V \neq \emptyset$  there exists an open subset  $U$  in  $X$  such that  $x_0 \in U$  and  $F(x) \cap V \neq \emptyset$  for all  $x \in U$ .  $F$  is *l. s. c.* if it is *l. s. c.* at each  $x_0 \in X$ .

(ii)  $F$  is upper semicontinuous (*u. s. c.*) at  $x_0 \in X$  if for every open subset  $V$  in  $Y$  and containing  $F(x_0)$  there exists an open subset  $U$  in  $X$  such that  $x_0 \in U$  and  $F(x) \subseteq V$ , for all  $x \in U$ .  $F$  is *u. s. c.* if it is *u. s. c.* at each  $x_0 \in X$ .

(iii) A multifunction  $F$  from  $I$  into the set  $P_f(X)$  of all closed subsets of  $X$  is measurable if for all  $x \in X$  the function  $t \rightarrow d(x, F(t)) = \inf\{\|x - y\| : y \in F(t)\}$  is measurable [10–13].

(iv) Let  $(\Omega, \Sigma)$  be a measurable space and  $X$  a separable Banach space. We say that  $F : \Omega \rightarrow P_f(X)$  is graph measurable if

$$gr(F) = \{(z, x) \in \Omega \times X : x \in F(z)\} \in \Sigma \times \mathcal{B}(X), \quad (2)$$

where  $\mathcal{B}(X)$  is the Borel  $\sigma$ -field of  $X$ . For further details we refer to [14–16].

(v)  $F$  is continuous if it is lower and upper semicontinuous.

(vi) For each  $A, B \in P_f(X)$ , the Hausdorff metric is defined by

$$d_H(A, B) = \max \left[ \sup_{a \in A} d(a, B), \sup_{b \in B} d(b, A) \right]. \quad (3)$$

It is known that the space  $(P_f(X), d_H)$  is a generalized metric space, if the sets are not bounded (see, for instance, [14, 15]).

(vii) A multifunction  $F$  is Hausdorff continuous ( $d_H$ -continuous) if it is continuous from  $X$  into the metric space  $(P_f(Y), d_H)$ .

(viii) If  $F$  has compact values in  $Y$ , then  $F$  is  $d_H$ -continuous if and only if it is continuous [14, 17].

(ix) We denote by  $P_{kc}(\mathbb{R}^n)$  the nonempty compact convex subsets of  $\mathbb{R}^n$ .

(x) The Banach spaces  $C(I, \mathbb{R}^n)$ ,  $C^1(I, \mathbb{R}^n)$ , and  $C^2(I, \mathbb{R}^n)$  endowed with the norms

$$\|u\|_C = \max_{t \in I} \|u(t)\|, \quad \|u\|_{C^1} = \max\{\|u\|_C, \|\dot{u}\|_C\}, \quad (4)$$

$$\|u\|_{C^2} = \max\{\|u\|_C, \|\dot{u}\|_C, \|\ddot{u}\|_C\},$$

respectively.

(xi)  $L_w^1(I, \mathbb{R}^n)$  denotes the space  $L^1(I, \mathbb{R}^n)$  equipped with weak norm  $\|\cdot\|_w$  which is defined by

$$\|h\|_w = \sup \left\{ \left\| \int_a^b h(t) dt \right\| : 0 \leq a \leq b \leq 1 \right\}. \quad (5)$$

(xii)  $W^{2,1}(I, \mathbb{R}^n)$  is the Sobolev space of functions  $u : I \rightarrow \mathbb{R}^n$ ,  $u$  and  $\dot{u}$  are both absolutely continuous functions so  $\dot{u}(t) \in$

$L^1(I, \mathbb{R}^n)$  and it is equipped with the norm  $\|u\|_{W^{2,1}(I, \mathbb{R}^n)} = \|u\|_{L^1(I, \mathbb{R}^n)} + \|\dot{u}\|_{L^1(I, \mathbb{R}^n)} + \|\ddot{u}\|_{L^1(I, \mathbb{R}^n)}$ .

(xiii) Let  $R : I \rightarrow 2^{\mathbb{R}^n}$  be a multifunction and  $\delta_R^1 = \{h \in L^1(I, \mathbb{R}^n) : h(t) \in R(t)\}$ .

(xiv) By a solution of  $(P)$  (resp., of  $(P_e)$ ) we mean a function  $u \in W^{2,1}(I, \mathbb{R}^n)$  such that  $\dot{u}(t) = h(t)$  a.e. on  $I$  with  $h \in \delta_{F(\cdot, u(\cdot), \dot{u}(\cdot))}^1$  (resp.,  $h \in \delta_{\text{ext}F(\cdot, u(\cdot), \dot{u}(\cdot))}^1$ ) and  $u(0) = 0$ ,  $u(1) = u(\theta) = u(1)$ .

(xv) By a solution of  $(Q)$  (resp., of  $(Q_e)$ ) we mean a function  $u \in W^{2,1}(I, \mathbb{R}^n)$  such that  $\dot{u}(t) = h(t)$  a.e. on  $I$  with  $h \in \delta_{F(\cdot, u(\cdot), \dot{u}(\cdot))}^1$  (resp.,  $h \in \delta_{\text{ext}F(\cdot, u(\cdot), \dot{u}(\cdot))}^1$ ) and  $\dot{u}(0) = 0$ ,  $u(1) = \sum_{i=1}^{m-2} a_i u(\xi_i)$ .

(xvi) In the sequel by  $\Delta_P$  (resp.,  $\Delta_{P_e}$ ) we denote the solution set of Problem  $(P)$  (resp., of Problem  $(P_e)$ ). Moreover, by  $\Delta_Q$  (resp.,  $\Delta_{Q_e}$ ) we denote the solution set of Problem  $(Q)$  (resp., of Problem  $(Q_e)$ ).

**Definition 1.** Let  $E$  be a Banach space and let  $Y$  be a metric space. A multifunction  $G : I \times Y \rightarrow P_{ck}(E)$  has the Scorza-Draceni property (the SD-property) if for every  $\varepsilon > 0$  there exists a closed set  $A \subset I$  such that the Lebesgue measure  $\mu(I \setminus A)$  is less than  $\varepsilon$  and  $G|_{A \times Y}$  is continuous. The multifunction  $G$  is called integrably bounded on compacta in  $Y$  if, for any compact subset  $Q \subset Y$ , we can find an integrable function  $\mu_Q : I \rightarrow \mathbb{R}^+$  such that  $\sup\{\|y\| : y \in G(t, z)\} \leq \mu_Q(t)$ , for almost every  $z \in Q$ .

**Theorem 2** (see [18]). *Let  $Y$  be a complete metric space,  $E$  a separable Banach space,  $E_\sigma$  the Banach space  $E$  endowed with the weak topology,  $M : I \times Y \rightarrow P_{ck}(E_\sigma)$ , and  $K$  a compact subset of  $C(I, Y)$ . Furthermore, let  $R : K \rightarrow 2^{L^1(I, E)}$  be a multifunction defined by*

$$R(y) = \{g \in L^1(I, E) : g(t) \in M(t, y(t)) \text{ a.e. on } I\}. \quad (6)$$

*If  $M$  has the SD-property and is integrably bounded on compacta in  $Y$ , then the set*

$$A_K = \{f \in C(K, L_w^1(I, E)) : f(y) \in R(y) \ \forall y \in K\} \quad (7)$$

*is nonempty complete subset of the space  $C(K, L_w^1(I, E))$ . Moreover,  $A_K = \overline{A_{\text{ext}K}}$  where  $L_w^1(I, E)$  is the space of equivalence classes of Bochner-integrable functions  $v : I \rightarrow E$  with the norm  $\|v\|_w = \sup_{t \in T} \left\| \int_0^t v(s) ds \right\|$  and*

$$A_{\text{ext}K} = \{f \in C(K, L_w^1(I, E)) : f(y) \in \text{ext}R(y) \ \forall y \in K\}. \quad (8)$$

**Lemma 3** (see [19]). *For  $p$  such that  $1 < p < \infty$  let  $\{u_n, u\}_{n \in \mathbb{N}} \subseteq L^p(I, \mathbb{R}^n)$ ,  $\sup_{n \in \mathbb{N}} \|u_n\|_p < \infty$  and  $u_n \rightarrow u$  with respect to the weak norm  $\|\cdot\|_w$ . Then  $u_n \rightarrow u$  weakly in  $L^p(I, \mathbb{R}^n)$ .*

Next we state a preliminary lemma, for  $0 < \eta < \theta < 1$ , which is useful in the study of four boundary problems for the differential equations and the differential inclusions, and

moreover we summarize some properties of a Hartman-type function.

**Lemma 4** (see [8]). *Let  $G : I \times I \rightarrow \mathbb{R}$  be the function defined as follows:*

as  $0 \leq t < \eta$ ,

$$G(t, \tau) = \begin{cases} -\tau & \text{if } 0 \leq \tau \leq t \\ -t & \text{if } t < \tau \leq \eta \\ \frac{t(\tau - \theta) + (\tau - \eta)}{\theta - \eta} & \text{if } \eta < \tau \leq \theta \\ \frac{1 - \tau}{1 - \theta} & \text{if } \theta < \tau \leq 1, \end{cases} \quad (9)$$

when  $\eta \leq t < \theta$ ,

$$G(t, \tau) = \begin{cases} -\tau & \text{if } 0 \leq \tau \leq \eta \\ \frac{\tau(t - \theta + 1) + \eta(\tau - t - 1)}{\theta - \eta} & \text{if } \eta < \tau \leq t \\ \frac{t(\tau - \theta) + (\tau - \eta)}{\theta - \eta} & \text{if } t < \tau \leq \theta \\ \frac{1 - \tau}{1 - \theta} & \text{if } \theta < \tau \leq 1, \end{cases} \quad (10)$$

lastly if  $\theta \leq t \leq 1$ ,

$$G(t, \tau) = \begin{cases} -\tau & \text{if } 0 \leq \tau \leq \eta \\ \frac{\eta(\tau - t - 1) + \tau(t - \theta + 1)}{\theta - \eta} & \text{if } \eta < \tau \leq \theta \\ \frac{1 - \tau}{1 - \theta} + (t - \tau) & \text{if } \theta < \tau \leq t \\ \frac{1 - \tau}{1 - \theta} & \text{if } t < \tau \leq 1. \end{cases} \quad (11)$$

Then the following hold.

(i) If  $u \in W^{2,1}(I, \mathbb{R}^n)$  with  $u(0) = x_0, u(1) = u(\theta) = u(\eta)$ , then

$$u(t) = x_0 + \int_0^1 G(t, \tau) \ddot{u}(\tau) d\tau, \quad \forall t \in I; \quad (12)$$

(ii) if  $w \in L^1(I, \mathbb{R}^n)$ , then for all  $t \in I$ ,

$$\begin{aligned} \int_0^1 G(t, \tau) w(\tau) d\tau &= \int_0^t (t - \tau) w(\tau) d\tau \\ &\quad - \int_0^\eta \frac{t(\tau - \eta)(t + 1)}{\theta - \eta} w(\tau) d\tau \\ &\quad + \int_0^\theta \frac{t(\tau - \theta) + (\tau - \eta)}{\theta - \eta} w(\tau) d\tau \\ &\quad + \int_\theta^1 \frac{1 - \tau}{1 - \theta} w(\tau) d\tau; \end{aligned} \quad (13)$$

(iii)  $\sup_{t, \tau \in I} |G(t, \tau)| \leq 2, \sup_{t, \tau \in I} |\partial G(t, \tau) / \partial t| \leq 1.$

Let  $c_1, c_2, a \in L^p(I, \mathbb{R}^+), 1 < p < \infty$ , and let  $L$  be a linear operator from  $C(I, \mathbb{R}) \times C(I, \mathbb{R})$  to  $C(I, \mathbb{R}) \times C(I, \mathbb{R})$  defined by  $L(f, g) = (\underline{f}, \underline{g})$  such that, for all  $t \in I$ ,

$$\begin{aligned} \underline{f}(t) &= \int_0^T |G(t, \tau)| (c_1(\tau) f(\tau) + c_2(\tau) g(\tau)) d\tau, \\ \underline{g}(t) &= \int_0^T \left| \frac{\partial G(t, \tau)}{\partial t} \right| (c_1(\tau) f(\tau) + c_2(\tau) g(\tau)) d\tau. \end{aligned} \quad (14)$$

If  $c_1 = c_2 = 0$ , then clearly  $L = 0$ . We note that if  $\mathcal{K} = \{(h_1, h_2) \in C(I, \mathbb{R}) \times C(I, \mathbb{R}) : h_1(t), h_2(t) \geq 0, \forall t \in I\}$ , then  $L(\mathcal{K}) \subseteq \mathcal{K}$ . Moreover, the spectral radius  $r(L) = \lim \|L^n\|^{1/n}$  is an eigenvalue of  $L$  with an eigenvector in  $\mathcal{K}$  [20].

### 3. Relaxation Theorems

In this section, both Theorems 5 and 7 improve [19, Theorem 4.1] with [21, Theorem 6]. Indeed in [19] Papageorgiou considered  $(P)$  and  $(P_e)$  with the two boundary conditions  $u(0) = u(1) = 0$  and in [21] Ibrahim and Gomaa study the same problems with three boundary conditions  $u(0) = x_0, u(\eta) = u(1)$ .

**Theorem 5.** *Let  $F : I \times \mathbb{R}^n \times \mathbb{R}^n \rightarrow P_{kc}(\mathbb{R}^n)$  be a multifunction such that*

(i) for each  $(x, y) \in \mathbb{R}^n \times \mathbb{R}^n$ , the multifunction  $F(\cdot, x, y)$  is measurable,

(ii)  $d_H(F(t, x, y), F(t, x', y')) \leq \alpha_1(t) \|x - x'\| + \alpha_2(t) \|y - y'\|$  a.e. with  $\alpha_1, \alpha_2 \in L^1(I, \mathbb{R}^+)$  and  $\|\alpha_1 + \alpha_2\| < 1/2$ ,

(iii) for each  $(t, x, y) \in I \times \mathbb{R}^n \times \mathbb{R}^n$ ,

$$\begin{aligned} \|F(t, x, y)\| &= \sup \{\|v\| : v \in F(t, x, y)\} \\ &\leq a(t) + c_1(t) \|x\| + c_2(t) \|y\| \end{aligned} \quad (15)$$

with  $a, c_1, c_2 \in L^p(I, \mathbb{R}^+), 1 < p < \infty$ ,

(iv) the spectral radius,  $r(L)$ , is less than 1.

Then for each solution  $u \in \Delta_{P_e}$ , there is a sequence  $(u_m(\cdot))_{m \in \mathbb{N}} \subset \Delta_P$  converging to  $u(\cdot)$  in  $(C^1(I, \mathbb{R}^n), \|\cdot\|_{C^1})$ .

*Proof.* From [9, Theorem 2.1], we obtain  $\Delta_{P_e} \neq \emptyset$ . Moreover, we can say that  $\|F(t, x, y)\| \leq a_1(t)$  a.e. on  $I$  for some  $a_1 \in L^p(I, \mathbb{R}^+)$ . Let  $u \in \Delta_P$ . Then

$$\ddot{u}(t) = h(t), \quad \text{a.e. on } I, \quad (16)$$

$$u(0) = 0, \quad u(\eta) = u(\theta) = u(1),$$

where  $h(t) \in F(t, u(t), \dot{u}(t))$  a.e. on  $I$ . Assume that  $f : L^1(I, \mathbb{R}^n) \rightarrow C^1(I, \mathbb{R}^n)$  is a function such that, for each  $h \in L^1(I, \mathbb{R}^n), f(h) \in W^{1,2}(I, \mathbb{R}^n)$  is the unique solution of the second-order differential equation

$$\ddot{u}(t) = h(t), \quad \text{a.e. on } I, \quad (P_h)$$

$$u(0) = 0, \quad u(\eta) = u(\theta) = u(1).$$

Let  $\mathcal{S} = \{u \in L^1(I, \mathbb{R}^n) : \|u(t)\| \leq a_1(t) \text{ a.e. on } I\}$ . It is easy to see that  $f(\mathcal{S})$  is convex. Let  $(u_n)_{n \in \mathbb{N}}$  be a sequence in  $f(\mathcal{S})$ . Hence,  $u_n \in W^{2,1}(I, \mathbb{R}^n)$  with  $u_n(0) = x_0$ ,  $u_n(\eta) = u_n(\theta) = u_n$  (17) and

$$\begin{aligned} u_n(t) &= x_0 + \int_0^t (t-\tau) \ddot{u}_n(\tau) d\tau \\ &\quad - \int_0^\eta \frac{t(\tau-\eta)(t+1)}{\theta-\eta} \ddot{u}_n(\tau) d\tau \\ &\quad + \int_0^\theta \frac{t(\tau-\theta) + (\tau-\eta)}{\theta-\eta} \ddot{u}_n(\tau) d\tau \\ &\quad + \int_\theta^1 \frac{1-\tau}{1-\theta} \ddot{u}_n(\tau) d\tau. \end{aligned} \quad (17)$$

Then,

$$\lim_{n \rightarrow \infty} u_n(t) = \int_0^1 G(t, \tau) \ddot{u}(\tau) d\tau = u(t), \quad (18)$$

which means that  $f(\mathcal{S})$  is a compact subset of  $C^1(I, \mathbb{R}^n)$ . Set

$$\begin{aligned} \mathcal{P}_\varepsilon(t) &= \{x \in F(t, v(t), \dot{v}(t)) : \|h(t) - x\| < \varepsilon \\ &\quad + d(h(t), F(t, v(t), \dot{v}(t)))\}, \end{aligned} \quad (19)$$

where  $\varepsilon > 0$  and  $v \in f(\mathcal{S})$ . Hence, for each  $t \in I$ ,  $\mathcal{P}_\varepsilon(t) \neq \emptyset$ . Assume that  $\mathcal{B}(I)$  and  $\mathcal{B}(\mathbb{R}^n)$  are the Borel  $\sigma$ -fields of  $I$  and  $\mathbb{R}^n$ , respectively. From condition, (i) the function  $t \rightarrow F(t, v(t), \dot{v}(t))$  is measurable. Hence,  $grF(\cdot, v(\cdot), \dot{v}(\cdot)) \in \mathcal{B}(I) \times \mathcal{B}(\mathbb{R}^n)$  and  $(t, x) \rightarrow \varepsilon d(h(t), F(t, v(t), \dot{v}(t))) - \|h(t) - x\|$  is measurable in  $t$  and continuous in  $x$  that is jointly measurable. Thus, by Aumann's selection theorem, there exists a measurable selection  $s_\varepsilon$  of  $\mathcal{P}_\varepsilon$  such that  $s_\varepsilon(t) \in \mathcal{P}_\varepsilon(t)$  for each  $t \in I$ . Now we define a multifunction  $\mathcal{Q}_\varepsilon : f(\mathcal{S}) \rightarrow 2^{L^1(I, \mathbb{R}^n)}$  by the following:

$$\begin{aligned} \mathcal{Q}_\varepsilon(v) &= \{x \in \delta_{F(\cdot, v(\cdot), \dot{v}(\cdot))}^1 : \\ &\quad \|h(t) - x\| < \varepsilon + d(h(t), F(t, v(t), \dot{v}(t))) \text{ a.e. on } I\}, \end{aligned} \quad (20)$$

with  $\mathcal{Q}_\varepsilon(v)(t) \neq \emptyset$  for each  $v \in f(\mathcal{S})$ . From [22, Proposition 4],  $\mathcal{Q}_\varepsilon$  is *l. s. c.* and clearly has decomposable values. Applying [22, Theorem 3], we have a continuous selection  $S_\varepsilon$  of  $\mathcal{Q}_\varepsilon$ . Therefore,

$$\begin{aligned} \|h(t) - S_\varepsilon(v)(t)\| &\leq \varepsilon + d(h(t), F(t, v(t), \dot{v}(t))) \\ &\leq \varepsilon + \alpha_1(t) \|u(t) - v(t)\| \\ &\quad + \alpha_2(t) \|\dot{u}(t) - \dot{v}(t)\| \text{ a.e. on } I. \end{aligned} \quad (21)$$

From Theorem 2, we find a continuous function  $\xi_\varepsilon : f(\mathcal{S}) \rightarrow L^1_w(I, \mathbb{R}^n)$  such that  $\xi_\varepsilon(v) \in \text{ext}\delta_{F(\cdot, v(\cdot), \dot{v}(\cdot))}^1$  and  $\|S_\varepsilon(v) - \xi_\varepsilon(v)\| <$

$\varepsilon$  for each  $v \in f(\mathcal{S})$ . Define a multifunction  $R : f(\mathcal{S}) \rightarrow 2^{L^1(I, \mathbb{R}^n)}$  by

$$R(u) = \{g \in L^1(I, \mathbb{R}^n) : g(t) \in F(t, u(t), \dot{u}(t)) \text{ a.e. on } I\}. \quad (22)$$

Assume that  $Y = \mathbb{R}^n \times \mathbb{R}^n$  and set a multifunction  $M : I \times Y \rightarrow 2^{\mathbb{R}^n}$  such that  $M(t, (x, y)) = F(t, x, y)$ . From Theorem 3.1 in [23],  $M$  has SD-property.  $R$  has nonempty convex values. Let  $(g_n)_{n \in \mathbb{N}}$  be a sequence in  $R(u)$  for some  $u \in f(\mathcal{S})$ . So, for each  $t \in I$ ,

$$\lim_{n \rightarrow \infty} g_n(t) = g(t) \in F(t, u(t), \dot{u}(t)) \quad (23)$$

because  $F$  has closed values in  $\mathbb{R}^n$ . Therefore,  $g \in \delta_{F(\cdot, u(\cdot), \dot{u}(\cdot))}^1$  which implies that  $R(\cdot)$  has compact values in  $\mathbb{R}^n$ . We can apply Theorem 2 to find a continuous function  $\theta : f(\mathcal{S}) \rightarrow L^1_w(I, \mathbb{R}^n)$  such that  $\theta(u) \in \text{ext}(R(u))$ , for all  $u \in f(\mathcal{S})$ . We see that  $\theta(u)(t) \in \text{ext}(M(t, (u(t), \dot{u}(t))))$  [24], hence  $\theta(u)(t) \in \text{ext}F(t, u(t), \dot{u}(t))$  a.e. on  $I$ . Assume that  $\eta : f(\mathcal{S}) \rightarrow W^{1,2}(I, \mathbb{R}^n)$  is the function which for each  $u \in f(\mathcal{S})$ ,  $\eta(u) = g(\theta(u))$ . For each  $u \in f(\mathcal{S})$ , we have  $\|\theta(u)(t)\| \leq a_1$  and so  $\theta(u) \in \mathcal{S}$ . Then,  $\eta$  is a function from  $f(\mathcal{S})$  into  $f(\mathcal{S})$  and also we see that  $\eta$  is continuous [19]. Now let  $\varepsilon_n \rightarrow 0$ ,  $S_{\varepsilon_n} = S_n$  and  $\xi_n = \xi_{\varepsilon_n}$ . Then, for each  $n \in \mathbb{N}$ , the function  $fo\xi_n$  is a continuous function from the compact set  $f(\mathcal{S})$  into itself. From Schauder's fixed point theorem,  $fo\xi_n$  has a fixed point  $u_n$ , but  $\text{ext}\delta_{F(\cdot, v(\cdot), \dot{v}(\cdot))}^1 = \delta_{\text{ext}F(\cdot, v(\cdot), \dot{v}(\cdot))}^1$  [24] so  $u_n \in \Delta_{P_\varepsilon}$ . By passing to a subsequence if necessary, we may assume that  $u_n \rightarrow \hat{u}$  in  $C^1(I, \mathbb{R}^n)$ . Then, we obtain

$$\begin{aligned} &\|u_n(t) - u(t)\| \\ &\leq \int_0^1 \left\| \int_0^t (t-\tau) (\xi_n(\tau) - h(\tau)) d\tau \right. \\ &\quad \left. - \int_0^\eta \frac{t(\tau-\eta)(t+1)}{\theta-\eta} (\xi_n(\tau) - h(\tau)) d\tau \right. \\ &\quad \left. + \int_0^\theta \frac{t(\tau-\theta) + (\tau-\eta)}{\theta-\eta} (\xi_n(\tau) - h(\tau)) d\tau \right. \\ &\quad \left. + \int_\theta^1 \frac{1-\tau}{1-\theta} (\xi_n(\tau) - h(\tau)) d\tau \right\| ds \\ &\leq \int_0^1 \left[ \int_0^t (t-\tau) \|\xi_n(\tau) - S_n(\tau)\| d\tau \right. \\ &\quad \left. + \int_0^t (t-\tau) \|h(\tau) - S_n(\tau)\| d\tau \right. \\ &\quad \left. + \int_0^\eta \frac{t(\tau-\eta)(t+1)}{\theta-\eta} (\xi_n(\tau) - S_n(\tau)) d\tau \right. \\ &\quad \left. + \int_0^\theta \frac{t(\tau-\eta)(t+1)}{\theta-\eta} \|h(\tau) - S_n(\tau)\| d\tau \right. \\ &\quad \left. + \int_0^\theta \frac{t(\tau-\eta)(t+1)}{\theta-\eta} \|h(\tau) - S_n(\tau)\| d\tau \right. \\ &\quad \left. + \int_0^\theta \frac{t(\tau-\eta)(t+1)}{\theta-\eta} \|h(\tau) - S_n(\tau)\| d\tau \right] ds \end{aligned}$$

$$\begin{aligned}
 & + \int_{\theta}^1 \frac{1-\tau}{1-\theta} \|\xi_n(\tau) - S_n(\tau)\| d\tau \\
 & + \int_{\theta}^1 \frac{1-\tau}{1-\theta} \|h(\tau) - S_n(\tau)\| d\tau \Big] ds.
 \end{aligned} \tag{24}$$

But  $\xi_n - S_n \rightarrow 0$  with respect to the norm  $\|\cdot\|_w$  from Lemma 3 we get  $\xi_n - S_n \rightarrow 0$  weakly in  $L^1(I, \mathbb{R}^n)$ . So we have

$$\begin{aligned}
 & \int_0^t (t-\tau) \|\xi_n(\tau) - S_n(\tau)\| d\tau \\
 & + \int_0^\eta \frac{t(\tau-\eta)(t+1)}{\theta-\eta} \|\xi_n(\tau) - S_n(\tau)\| d\tau \\
 & + \int_{\theta}^1 \frac{1-\tau}{1-\theta} \|\xi_n(\tau) - S_n(\tau)\| d\tau \rightarrow 0.
 \end{aligned} \tag{25}$$

Moreover,

$$\begin{aligned}
 & \int_0^1 \left[ \int_0^t (t-\tau) \|h(\tau) - S_n(\tau)\| d\tau \right. \\
 & + \int_0^\eta \frac{t(\tau-\eta)(t+1)}{\theta-\eta} (\xi_n(\tau) - S_n(\tau)) d\tau \\
 & + \left. \int_{\theta}^1 \frac{1-\tau}{1-\theta} \|h(\tau) - S_n(\tau)\| d\tau \right] ds \\
 & \leq \int_0^1 \left[ \int_0^t (t-\tau) (\varepsilon_n + \alpha_1(\tau) \|u(\tau) - u_n(\tau)\| \right. \\
 & \quad \left. + \alpha_2(\tau) \|\dot{u}(\tau) - \dot{u}_n(\tau)\|) \right. \\
 & + \int_0^\eta \frac{t(\tau-\eta)(t+1)}{\theta-\eta} (\varepsilon_n + \alpha_1(\tau) \|u(\tau) - u_n(\tau)\| \\
 & \quad \left. + \alpha_2(\tau) \|\dot{u}(\tau) - \dot{u}_n(\tau)\|) \right. \\
 & + \left. \int_{\theta}^1 \frac{1-\tau}{1-\theta} (\varepsilon_n + \alpha_1(\tau) \|u(\tau) - u_n(\tau)\| \right. \\
 & \quad \left. + \alpha_2(\tau) \|\dot{u}(\tau) - \dot{u}_n(\tau)\|) \right] ds.
 \end{aligned} \tag{26}$$

As  $n \rightarrow \infty$ , we have

$$\begin{aligned}
 & \|\hat{u}(t) - u(t)\| \\
 & \leq \int_0^1 \left[ \int_0^t (t-\tau) (\alpha_1(\tau) \|u(\tau) - \hat{u}(\tau)\| \right. \\
 & \quad \left. + \alpha_2(\tau) \|\dot{u}(\tau) - \dot{\hat{u}}(\tau)\|) d\tau \right.
 \end{aligned}$$

$$\begin{aligned}
 & + \int_0^\eta \frac{t(\tau-\eta)(t+1)}{\theta-\eta} (\alpha_1(\tau) \|u(\tau) - \hat{u}(\tau)\| \\
 & \quad \left. + \alpha_2(\tau) \|\dot{u}(\tau) - \dot{\hat{u}}(\tau)\|) d\tau \right. \\
 & + \left. \int_{\theta}^1 \frac{1-\tau}{1-\theta} (\alpha_1(\tau) \|u(\tau) - \hat{u}(\tau)\| \right. \\
 & \quad \left. + \alpha_2(\tau) \|\dot{u}(\tau) - \dot{\hat{u}}(\tau)\|) d\tau \right] ds \\
 & \leq \|u - \hat{u}\|_{C^1(I, \mathbb{R}^n)} \left( \int_0^t (t-\tau) (\alpha_1(\tau) + \alpha_2(\tau)) d\tau \right. \\
 & \quad + \int_0^\eta \frac{t(\tau-\eta)(t+1)}{\theta-\eta} (\alpha_1(\tau) + \alpha_2(\tau)) d\tau \\
 & \quad \left. + \int_{\theta}^1 \frac{1-\tau}{1-\theta} (\alpha_1(\tau) + \alpha_2(\tau)) d\tau \right) \\
 & = \|u - \hat{u}\|_{C^1(I, \mathbb{R}^n)} \int_0^1 |G(t, \tau)| (\alpha_1(\tau) + \alpha_2(\tau)) d\tau \\
 & \leq 2\|u - \hat{u}\|_{C^1(I, \mathbb{R}^n)} \|\alpha_1(\tau) + \alpha_2(\tau)\|.
 \end{aligned} \tag{27}$$

Since by assumption (ii),  $\|\alpha_1 + \alpha_2\| < 1/2$  we get  $u = \hat{u}$ . So  $u_n \rightarrow u$  in  $C^1(I, \mathbb{R}^n)$  and  $u \in \overline{\Delta_P}$  where the closure is taken in  $C^1(I, \mathbb{R}^n)$  which means that  $\Delta_P \subseteq \overline{\Delta_P}$ . Therefore, the proof is complete if we show that  $\Delta_P$  is closed. Indeed if  $v_n \in \Delta_P$  and  $v_n \rightarrow v$  in  $C^1(I, \mathbb{R}^n)$ , then  $v_n = f(y_n)$  for  $y_n \in \delta_{F(t, v(\cdot), \dot{v}(\cdot))}^1$ . From assumption (iii) and the Dunford-Pettis theorem,  $\{y_n\}_{n \in \mathbb{N}}$  is weakly sequentially compact in  $L^1(I, \mathbb{R}^n)$ . So we can say that  $\{y_n\}_{n \in \mathbb{N}}$  in  $L^1(I, \mathbb{R}^n)$ . By [25, Theorem 3.1], we get

$$\begin{aligned}
 & y(t) \in \overline{\text{conv}} \overline{\lim} \{y_n(t)\}_{n \in \mathbb{N}} \subseteq \overline{\text{conv}} \overline{\lim} F(t, v_n(t), \dot{v}_n(t)) \\
 & = F(t, v(t), \dot{v}(t)) \quad \text{a.e. on } I.
 \end{aligned} \tag{28}$$

Moreover,  $f(y_n) \rightarrow f(y)$  in  $L^1(I, \mathbb{R}^n)$  for  $y \in L^1(I, \mathbb{R}^n)$  and  $y(t) \in F(t, v(t), \dot{v}(t))$  a.e. on  $I$ . Hence,  $v \in \Delta_P$ ; that is  $\Delta_P$  is closed in  $C^1(I, \mathbb{R}^n)$ .  $\square$

Now we consider the following assumptions:

- (A<sub>1</sub>)  $\beta \in (0, \pi/2)$ ,  $a_i > 0$  and  $\sum_{i=1}^{m-2} a_i < 1$ ;
- (A<sub>2</sub>)  $\sum_{i=1}^{m-2} a_i \cos \beta \xi_i - \cos \beta > 0$  and  $K_m = 1 / \sum_{i=1}^{m-2} a_i \cos \beta \xi_i - \cos \beta$ ;
- (A<sub>3</sub>)  $C_0 = (\sin \beta / \beta)(1 + K_m)$  and  $C_1 = \min\{K_m + 1, K_m \sin^2 \beta\}$ ;

$$(A_4) S = \{u \in C^2(I, \mathbb{R}^n) : \dot{u}(0) = 0, u(1) = \sum_{i=1}^{m-2} a_i u(\xi_i)\};$$

(A<sub>5</sub>)  $\mathcal{G} : I \times I \rightarrow \mathbb{R}$  is defined by

$$\mathcal{G}(t, s) = \begin{cases} \frac{1}{\beta} \sin \beta(t-s) & \text{if } 0 \leq s \leq t \leq 1 \\ 0 & \text{if } 0 \leq t \leq s \leq 1 \end{cases} + \frac{K_m}{\beta} \cos \beta t \begin{cases} \sin \beta(1-s) - \sum_{i=1}^{m-2} a_i \sin \beta(\xi_i - s), & \text{if } 0 \leq s \leq \xi_1, \\ \sin \beta(1-s) - \sum_{i=2}^{m-2} a_i \sin \beta(\xi_i - s), & \text{if } \xi_1 < s \leq \xi_2, \\ \sin \beta(1-s) - \sum_{i=3}^{m-2} a_i \sin \beta(\xi_i - s), & \text{if } \xi_2 < s \leq \xi_3, \\ \vdots \\ \sin \beta(1-s) - \sum_{i=k}^{m-2} a_i \sin \beta(\xi_i - s), & \text{if } \xi_{k-1} < s \leq \xi_k, \\ \vdots \\ \sin \beta(1-s), & \text{if } \xi_{m-2} < s \leq 1. \end{cases} \quad (29)$$

**Lemma 6** (see [26]). *If the assumptions (A<sub>1</sub>)–(A<sub>5</sub>) hold, then*

- (i)  $0 \leq \mathcal{G}(t, s) \leq C_0$  for all  $(t, s) \in I \times I$ ,
- (ii)  $\sup_{t,s \in I} |\partial \mathcal{G}(t, s) / \partial t| \leq C_1$ ,
- (iii) for each  $x \in C^1(I, \mathbb{R}^n)$  there exists a unique function  $u_x \in S$  such that

$$u_x(t) = \int_0^1 \mathcal{G}(t, s) x(s) ds, \quad (30)$$

- (iv)  $(\int_0^1 |\mathcal{G}(t, s)|^k ds)^{1/k} \leq C_0$  and  $(\int_0^1 |(\partial \mathcal{G} / \partial t)(t, s)|^k ds)^{1/k} \leq C_1$ .

*Proof.* (ii) Since

$$\frac{\partial \mathcal{G}(t, s)}{\partial t} = \begin{cases} \cos \beta(t-s) & \text{if } 0 \leq s \leq t \leq 1 \\ 0 & \text{if } 0 \leq t \leq s \leq 1 \end{cases} - K_m \sin \beta t \begin{cases} \sin \beta(1-s) - \sum_{i=1}^{m-2} a_i \sin \beta(\xi_i - s), & \text{if } 0 \leq s \leq \xi_1, \\ \sin \beta(1-s) - \sum_{i=2}^{m-2} a_i \sin \beta(\xi_i - s), & \text{if } \xi_1 < s \leq \xi_2, \\ \sin \beta(1-s) - \sum_{i=3}^{m-2} a_i \sin \beta(\xi_i - s), & \text{if } \xi_2 < s \leq \xi_3, \\ \vdots \\ \sin \beta(1-s) - \sum_{i=k}^{m-2} a_i \sin \beta(\xi_i - s), & \text{if } \xi_{k-1} < s \leq \xi_k, \\ \vdots \\ \sin \beta(1-s), & \text{if } \xi_{m-2} < s \leq 1, \end{cases} \quad (31)$$

then  $\sup_{t,s \in I} \partial \mathcal{G}(t, s) / \partial t \leq 1 + K_m$ . Furthermore,

$$\frac{\partial \mathcal{G}(t, s)}{\partial t} \geq K_m \sin \beta t \left[ \sum_{i=1}^{m-2} a_i \sin(\xi_i - s) - \sin \beta(1 - \beta) \right] \geq -K_m \sin^2 \beta \quad (32)$$

and thus  $\sup_{t,s \in I} |\partial \mathcal{G}(t, s) / \partial t| \leq C_1$ . □

**Theorem 7.** *Assume that the assumptions (A<sub>1</sub>) and (A<sub>2</sub>) hold. Let  $F$  be a multifunction from  $I \times \mathbb{R}^n \times \mathbb{R}^n$  to  $P_{kc}(\mathbb{R}^n)$  satisfying the following conditions:*

- (a) for each  $(x, y) \in \mathbb{R} \times \mathbb{R}$ , the multifunction  $F(\cdot, x, y)$  is measurable;
- (b) for each  $t \in I$ , the function  $(x, y) \rightarrow F(t, x, y)$  is continuous with respect to the Hausdorff metric  $d_H$ ;
- (c) for each  $(t, x, y) \in I \times \mathbb{R}^n \times \mathbb{R}^n$

$$\|F(t, x, y)\| \leq \sup \{\|v\| : v \in F(t, x, y)\} \leq a(t) + c_1(t) \|x\| + c_2(t) \|y\|; \quad (33)$$

- (d) the spectral radius  $r(L)$  of  $L$  is less than one.

Then Problem (Q<sub>e</sub>) admits a solution in  $S$ .

*Proof.* We can say that  $\|F(t, x, y)\| \leq a_1(t)$  a.e. on  $I$  for some  $a_1 \in L^p(I, \mathbb{R}^+)$  [9]. Let  $x \in C^1(I, \mathbb{R}^n)$  and let  $u \in C^2(I, \mathbb{R}^n)$  be the unique solution of the problem

$$\begin{aligned} \ddot{u}(t) &= x(t), \quad \text{a.e. on } I, \\ \dot{u}(0) &= 0, \quad u(1) = \sum_{i=1}^{m-2} a_i u(\xi_i). \end{aligned} \quad (*)$$

From Lemma 6, we have  $u(t) = \int_0^1 \mathcal{G}(t, s)x(s)ds, \forall t \in I$ . Thus, we define a function  $f : C^1(I, \mathbb{R}^n) \rightarrow C^2(I, \mathbb{R}^n)$  such that  $f(x)$  is the unique solution of (\*). Let

$$\mathcal{V} = \{x \in C^1(I, \mathbb{R}^n) : \|x(t)\| \leq a_1(t) \text{ a.e. on } I\}. \quad (34)$$

From the Dunford-Pettis theorem,  $\mathcal{V}$  is weakly compact and then  $f(\mathcal{V})$  is convex and compact subset of  $C^2(I, \mathbb{R}^n)$ . Let  $\mathcal{Y} = \mathbb{R}^n \times \mathbb{R}^n$ . If  $\mathcal{K} = f(\mathcal{V}), \mathcal{R} : \mathcal{K} \rightarrow 2^{L^1(I, \mathbb{R}^n)}$  and  $\mathcal{M} : I \times \mathcal{Y} \rightarrow 2^{\mathbb{R}^n}$ , where  $\mathcal{R}(u) = \{g \in L^1(I, \mathbb{R}^n) : g(t) \in F(t, u(t), \dot{u}(t)) \text{ a.e. on } I\}$  and  $\mathcal{M}(t, (x, y)) = F(t, x, y)$ , then  $\mathcal{M}$  has SD-property [23]. It is easy to show that  $\mathcal{R}$  is nonempty and convex subset of  $L^1(I, \mathbb{R}^n)$ . If  $f_n$  is a sequence in  $\mathcal{R}(u)$  for some  $u \in \mathcal{K}$ , then  $\lim_{n \rightarrow \infty} f_n(t) = f(t) \in F(t, u(t), \dot{u}(t))$ , where the values of  $F$  are closed. Therefore, the values of  $\mathcal{R}$  are weakly compact. According to Theorem 5 there exists a continuous function  $r : \mathcal{K} \rightarrow L^1_w(I, \mathbb{R}^n)$  with  $r(u) \in \text{ext}(\mathcal{R}(u))$ , for all  $u \in \mathcal{K}$ . Thus,  $r(u)(t) \in \text{ext}(\mathcal{M}(t, u(t), \dot{u}(t)))$  a.e. on  $I$  [24] which implies  $r(u)(t) \in \text{ext}(F(t, u(t), \dot{u}(t)))$  a.e. on  $I$ . If  $u \in f(\mathcal{V})$ , then  $\|r(u)(t)\| \leq a_1$  and so  $r(u) \in \mathcal{V}$ . Put  $\theta : f(\mathcal{V}) \rightarrow W^{2,1}(I, \mathbb{R}^n)$  such that  $\theta(u) = f(r(u))$ , thus  $\theta$  is a continuous function from  $f(\mathcal{V})$  into  $f(\mathcal{V})$  [19]. From Schauder's fixed point theorem, there exists  $x \in f(\mathcal{V})$  such that  $x = \theta(x) = f(r(x))$  which means that there is  $x \in S \subseteq C^2(I, \mathbb{R}^n)$  such that  $\dot{x}(t) \in \text{ext}(F(t, x(t), \dot{x}(t)))$ .  $\square$

**Theorem 8.** *In the setting of Theorem 7, if one replaces condition (b) by the following condition:*

(b)'  $d_H(F(t, x, y), F(t, x', y')) \leq k_1 \|x - x'\| + k_2 \|y - y'\|$  a.e. with  $k_1 \geq 0, k_2 \geq 0$  and  $|k_1 + k_2| < 1/2C_0$ .

Then  $\Delta_{Q_\varepsilon}$  is nonempty and  $\overline{\Delta_{Q_\varepsilon}} = \Delta_Q$  where the closure taken in  $C^2(I, \mathbb{R}^n)$ .

*Proof.* From Theorem 7, we have  $\Delta_{Q_\varepsilon} \neq \emptyset$ . Moreover,  $\|F(t, x, y)\| \leq b_1(t)$  a.e. on  $I$  for some  $b_1 \in L^p(I, \mathbb{R}^+)$ . Let  $u \in \Delta_Q$ . Then

$$\begin{aligned} \ddot{u}(t) &= h(t), \quad \text{a.e. on } I, \\ \dot{u}(0) &= 0, \quad u(1) = \sum_{i=1}^{m-2} a_i u(\xi_i), \end{aligned} \quad (35)$$

where  $h(t) \in F(t, u(t), \dot{u}(t))$  a.e. on  $I$ . Assume that  $f' : C^1(I, \mathbb{R}^n) \rightarrow C^2(I, \mathbb{R}^n)$  is a function such that, for each

$h \in C^1(I, \mathbb{R}^n), f'(h) \in C^2(I, \mathbb{R}^n)$  is the unique solution of the second-order differential equation

$$\begin{aligned} \ddot{u}(t) &= h(t), \quad \text{a.e. on } I, \\ \dot{u}(0) &= 0, \quad u(1) = \sum_{i=1}^{m-2} a_i u(\xi_i). \end{aligned} \quad (Q_h)$$

Let  $S = \{u \in C^1(I, \mathbb{R}^n) : \|u(t)\| \leq b_1(t) \text{ a.e. on } I\}$ . So  $f'(S)$  is convex. Let  $(u_n)_{n \in \mathbb{N}}$  be a sequence in  $f'(S)$ . Hence,  $u_n \in C^2(I, \mathbb{R}^n)$  with  $u_n(0) = 0, \dot{u}_n(0) = 0, u_n(1) = \sum_{i=1}^{m-2} a_i u_n(\xi_i)$ . Then from Lemma 6,

$$\lim_{n \rightarrow \infty} u_n(t) = \int_0^1 \mathcal{G}(t, \tau) \ddot{u}(\tau) d\tau = u(t), \quad (36)$$

hence,  $f'(S)$  is a compact subset of  $C^2(I, \mathbb{R}^n)$ . Set

$$\begin{aligned} \mathcal{Q}_\varepsilon(t) &= \{x \in F(t, v(t), \dot{v}(t)) : \\ &\|h(t) - x\| < \varepsilon + d(h(t), F(t, v(t), \dot{v}(t)))\}, \end{aligned} \quad (37)$$

where  $\varepsilon > 0$  and  $v \in f'(S)$ . Hence, for each  $t \in I, \mathcal{Q}_\varepsilon(t) \neq \emptyset$ . Assume that  $\mathcal{B}(I)$  and  $\mathcal{B}(\mathbb{R}^n)$  are the Borel  $\sigma$ -fields of  $I$  and  $\mathbb{R}^n$ , respectively. From condition (i), the function  $t \rightarrow F(t, v(t), \dot{v}(t))$  is measurable. Hence,  $grF(\cdot, v(\cdot), \dot{v}(\cdot)) \in \mathcal{B}(I) \times \mathcal{B}(\mathbb{R}^n)$  and  $(t, x) \rightarrow \varepsilon d(h(t), F(t, v(t), \dot{v}(t))) - \|h(t) - x\|$  is measurable in  $t$  and continuous in  $x$  that is jointly measurable. Thus, by Aumann's selection theorem, there exists a measurable selection  $s_\varepsilon$  of  $\mathcal{Q}_\varepsilon$  such that  $s_\varepsilon(t) \in \mathcal{Q}_\varepsilon(t)$  for each  $t \in I$ . Now we define a multifunction  $\mathcal{Q}_\varepsilon : f'(S) \rightarrow 2^{C^1(I, \mathbb{R}^n)}$  by the following:

$$\begin{aligned} \mathcal{Q}_\varepsilon(v) &= \{x \in \delta_{F(\cdot, v(\cdot), \dot{v}(\cdot))}^1 : \|h(t) - x\| \\ &< \varepsilon + d(h(t), F(t, v(t), \dot{v}(t))) \text{ a.e. on } I\}, \end{aligned} \quad (38)$$

with  $\mathcal{Q}_\varepsilon(v)(t) \neq \emptyset$  for each  $v \in f'(S)$ . From [22, Proposition 4],  $\mathcal{Q}_\varepsilon$  is l. s. c. and clearly has decomposable values. Applying [22, Theorem 3], we have a continuous selection  $S_\varepsilon$  of  $\mathcal{Q}_\varepsilon$ . Therefore,

$$\begin{aligned} \|h(t) - S_\varepsilon(v)(t)\| &\leq \varepsilon + d(h(t), F(t, v(t), \dot{v}(t))) \\ &\leq \varepsilon + k_1(t) \|u(t) - v(t)\| \\ &\quad + k_2(t) \|\dot{u}(t) - \dot{v}(t)\| \quad \text{a.e. on } I. \end{aligned} \quad (39)$$

From Theorem 2, we find a continuous function  $\xi'_\varepsilon : f'(S) \rightarrow L^1_w(I, \mathbb{R}^n)$  such that  $\xi'_\varepsilon(v) \in \text{ext} \delta_{F(\cdot, v(\cdot), \dot{v}(\cdot))}^1$  and  $\|S_\varepsilon(v) - \xi'_\varepsilon(v)\| < \varepsilon$  for each  $v \in f'(S)$ . Define a multifunction  $R' : f'(S) \rightarrow 2^{C^1(I, \mathbb{R}^n)}$  by

$$R'(u) = \{g \in C^1(I, \mathbb{R}^n) : g(t) \in F(t, u(t), \dot{u}(t)) \text{ a.e. on } I\}. \quad (40)$$

As in Theorem 5, let  $Y = \mathbb{R}^n \times \mathbb{R}^n$  and set a multifunction  $M : I \times Y \rightarrow 2^{\mathbb{R}^n}$  such that  $M(t, (x, y)) = F(t, x, y)$ . From [23, Theorem 3.1],  $M$  has SD-property.  $R'$  has nonempty convex values. Let  $(g_n)_{n \in \mathbb{N}}$  be a sequence in  $R'(u)$  for some  $u \in f'(S)$ . So, for each  $t \in I$ ,

$$\lim_{n \rightarrow \infty} g_n(t) = g(t) \in F(t, u(t), \dot{u}(t)) \quad (41)$$

because  $F$  has closed values in  $\mathbb{R}^n$ . Therefore,  $g \in \delta_{F(\cdot, u(\cdot), \dot{u}(\cdot))}^1$  which implies  $R'(\cdot)$  has compact values in  $\mathbb{R}^n$ . We can apply Theorem 2 to find a continuous function  $\theta' : f'(S) \rightarrow L_w^1(I, \mathbb{R}^n)$  such that  $\theta'(u) \in \text{ext}(R'(u))$ , for all  $u \in f'(S)$ . We see that  $\theta'(u)(t) \in \text{ext}(M(t, (u(t), \dot{u}(t))))$  [24], hence  $\theta'(u)(t) \in \text{ext}F(t, u(t), \dot{u}(t))$  a.e. on  $I$ . Assume that  $\eta' : f'(S) \rightarrow C^2(I, \mathbb{R}^n)$  is the function which for each  $u \in f'(S)$ ,  $\eta'(u) = g(\theta'(u))$ . For each  $u \in f'(S)$ , we have  $\|\theta'(u)(t)\| \leq b_1$  and so  $\theta'(u) \in S$ . Then,  $\eta'$  is a function from  $f'(S)$  into  $f'(S)$  and also we see that  $\eta'$  is continuous [19]. Now let  $\varepsilon_n \rightarrow 0$ ,  $S_{\varepsilon_n} = S_n$  and  $\xi'_n = \xi'_{\varepsilon_n}$ . Then, for each  $n \in \mathbb{N}$ , the function  $f' \circ \xi'_n$  is a continuous function from the compact set  $f'(S)$  into itself. From Schauder's fixed point theorem,  $f \circ \xi'_n$  has a fixed point  $u_n$ , but  $\text{ext} \delta_{F(\cdot, v(\cdot), \dot{v}(\cdot))}^1 = \delta_{\text{ext}F(\cdot, v(\cdot), \dot{v}(\cdot))}^1$  [24] so  $u_n \in \Delta_{P_\varepsilon}$ . Assume that  $u_n \rightarrow \hat{u}$  in  $C^2(I, \mathbb{R}^n)$ . From Lemma 6, we obtain

$$\begin{aligned} \|u_n(t) - u(t)\| &\leq \int_0^1 \left[ \int_0^1 |\mathcal{G}(t, \tau)| \|\xi'_n(\tau) - S_n(\tau)\| d\tau \right. \\ &\quad \left. + \int_0^1 |\mathcal{G}(t, \tau)| \|(S_n(\tau) - h(\tau))\| d\tau \right] ds. \end{aligned} \quad (42)$$

But  $\xi'_n - S_n \rightarrow 0$  with respect to the norm  $\|\cdot\|_w$  and from Lemma 3 we get  $\xi'_n - S_n \rightarrow 0$  weakly in  $C^1(I, \mathbb{R}^n)$ . So we have

$$\int_0^1 |\mathcal{G}(t, \tau)| \|\xi'_n(\tau) - S_n(\tau)\| d\tau \rightarrow 0. \quad (43)$$

Moreover, as  $n \rightarrow \infty$  we have

$$\begin{aligned} \|\hat{u}(t) - u(t)\| &\leq \|u - \hat{u}\|_{C^1(I, \mathbb{R}^n)} \int_0^1 |\mathcal{G}(t, \tau)| (k_1(\tau) + k_2(\tau)) d\tau \\ &\leq \|u - \hat{u}\|_{C^1(I, \mathbb{R}^n)} \|k_1(\tau) + k_2(\tau)\|_{C_0}. \end{aligned} \quad (44)$$

Since by assumption (ii),  $\|k_1 + k_2\| < 1/2C_0$ , thus from Lemma 6, we get  $u = \hat{u}$ . So  $u_n \rightarrow u$  in  $C^2(I, \mathbb{R}^n)$  and  $u \in \overline{\Delta_Q}$  where the closure is taken in  $C^2(I, \mathbb{R}^n)$  which means that  $\Delta_P \subseteq \overline{\Delta_{P_\varepsilon}}$ . If  $v_n \in \Delta_Q$  and  $v_n \rightarrow v$  in  $C^2(I, \mathbb{R}^n)$ , then  $v_n = f'(y_n)$  for  $y_n \in \delta_{F(\cdot, v(\cdot), \dot{v}(\cdot))}^1$ . From assumption (iii) and the Dunford-Pettis theorem,  $\{y_n\}_{n \in \mathbb{N}}$  is weakly sequentially compact in  $C^2(I, \mathbb{R}^n)$ . By [25, Theorem 3.1], we get

$$\begin{aligned} y(t) &\in \overline{\text{conv} \lim \{y_n(t)\}_{n \in \mathbb{N}}} \subseteq \overline{\text{conv} \lim F(t, v_n(t), \dot{v}_n(t))} \\ &= F(t, v(t), \dot{v}(t)) \quad \text{a.e. on } I. \end{aligned} \quad (45)$$

Moreover,  $f'(y_n) \rightarrow f'(y)$  in  $C^2(I, \mathbb{R}^n)$  for  $y \in C^2(I, \mathbb{R}^n)$  and  $y(t) \in F(t, v(t), \dot{v}(t))$  a.e. on  $I$ . Hence,  $v \in \Delta_Q$ ; that is,  $\Delta_Q$  is closed in  $C^2(I, \mathbb{R}^n)$ .  $\square$

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