

## Amoebas, convexity and the volume of integer polytopes

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### Abstract.

To any given Laurent polynomial  $f$  on  $\mathbf{C}_*^n$  we associate two natural convex functions  $M_f$  and  $N_f$  on  $\mathbf{R}^n$ . We compute the Hessian of  $M_f$  and obtain an explicit formula for the volume of the Newton polytope  $\Delta_f$ . We also establish asymptotic formulas relating our convex functions to coherent triangulations of  $\Delta_f$  and to the secondary polytope.

### §1.

Let  $A \subset \mathbf{Z}^n$  be a finite set and consider a general Laurent polynomial  $f(z) = \sum_{\alpha \in A} a_\alpha z^\alpha$ , with complex coefficients and  $z \in \mathbf{C}_*^n$ . The Newton polytope  $\Delta_f$  is defined as the convex hull of  $A$  (in  $\mathbf{R}^n \supset \mathbf{Z}^n$ ), or more accurately, as the convex hull of those  $\alpha$  for which  $a_\alpha \neq 0$ . The amoeba  $\mathbf{A}_f$  is defined to be the image of the zero set of  $f$  under the mapping  $\text{Log} : \mathbf{C}_*^n \rightarrow \mathbf{R}^n$  given by  $(z_1, \dots, z_n) \mapsto (\log |z_1|, \dots, \log |z_n|)$ . In the sequel we use the notation  $|z_j| = t_j$  and  $\log |z_j| = x_j$ .

We are going to deal with the two functions

$$M_f(x) = \log \left( \sum_{\alpha \in A} |a_\alpha| e^{\langle \alpha, x \rangle} \right)$$

and

$$N_f(x) = \frac{1}{(2\pi)^n} \int_{[0, 2\pi]^n} \log |f(e^{x+i\theta})| d\theta_1 \wedge \dots \wedge d\theta_n.$$

They are both convex functions in  $\mathbf{R}^n$  with the property that their gradient mappings map  $\mathbf{R}^n$  to the Newton polytope  $\Delta_f$ . More precisely, the mapping  $\text{grad } M_f$  is a diffeomorphism  $\mathbf{R}^n \rightarrow \text{int } \Delta_f$ , whereas

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$\text{grad } N_f$  maps  $\mathbf{R}^n$  onto the closed polytope  $\Delta_f$  with each connected component of  $\mathbf{R}^n \setminus \mathbf{A}_f$  being sent to one of the integer vectors  $\Delta_f \cap \mathbf{Z}^n$ , called the order of that connected component. (See [5] for more on this.)

Introducing the corresponding Monge–Ampère measures

$$\text{Hess } M_f = \text{Jac grad } M_f \quad \text{and} \quad \text{Hess } N_f = \text{Jac grad } N_f,$$

we conclude from general facts on convex functions, see [6], that these are both positive measures with total masses equal to  $\text{Vol } \Delta_f$ .

Let us order the set  $A$  as  $\{\alpha^0, \alpha^1, \dots, \alpha^N\}$ , and consider, for any increasing multi-index  $J = \{j_0, \dots, j_n\} \in \{0, 1, \dots, N\}^{1+n}$ , the square matrix  $A_J$  having the  $(1+n)$ -vectors  $(1, \alpha^{j_k})$  as its columns. Observe that  $|\det(A_J)|$  equals  $n!$  times the volume of the simplex  $\sigma_J$  with vertices in  $\alpha^{j_0}, \dots, \alpha^{j_n}$ . We begin with an explicit computation.

**Proposition 1.1** *The push-forward of the measure  $\text{Hess } M_f$  under the mapping  $\text{Exp}: \mathbf{R}^n \rightarrow \mathbf{R}_+^n$  defined by  $(x_1, \dots, x_n) \mapsto (e^{x_1}, \dots, e^{x_n})$ , is given by Lebesgue measure times a rational function  $h_f/F^{1+n}$ , with the polynomial  $h_f$  explicitly given by*

$$h_f(t) = \sum'_{|J|=1+n} \det^2(A_J) |a_{\alpha^{j_0}}| t^{\alpha^{j_0}} \cdots |a_{\alpha^{j_n}}| t^{\alpha^{j_n}}.$$

Here the summation is over all increasing multi-indices  $J$ , and  $F$  is obtained from  $f$  by replacing each coefficient  $a_\alpha$  by  $|a_\alpha|$ .

*Proof:* The gradient of  $M_f$  equals the moment map (cf. [4], p.198)

$$\text{grad } M_f(x) = \frac{\sum_{\alpha \in A} \alpha |a_\alpha| e^{(\alpha, x)}}{\sum_{\alpha \in A} |a_\alpha| e^{(\alpha, x)}} = \frac{\sum_{\alpha \in A} \alpha |a_\alpha| t^\alpha}{\sum_{\alpha \in A} |a_\alpha| t^\alpha},$$

which means that  $\text{Hess } M_f(x) = \det(\partial^2 M_f(x)/\partial x_j \partial x_k)$  is equal to

$$\left| \frac{\sum_{\alpha \in A} \alpha_j \alpha_k |a_\alpha| t^\alpha}{\sum_{\alpha \in A} |a_\alpha| t^\alpha} - \frac{(\sum_{\alpha \in A} \alpha_j |a_\alpha| t^\alpha)(\sum_{\alpha \in A} \alpha_k |a_\alpha| t^\alpha)}{(\sum_{\alpha \in A} |a_\alpha| t^\alpha)^2} \right|,$$

and if we introduce the abbreviation  $c_\alpha = |a_\alpha| t^\alpha$  we may re-write the above  $n \times n$ -determinant as the following  $(1+n) \times (1+n)$ -determinant:

$$\frac{1}{(\sum c_\alpha)^{1+n}} \begin{vmatrix} \sum c_\alpha & \sum \alpha_1 c_\alpha & \cdots & \sum \alpha_n c_\alpha \\ \sum \alpha_1 c_\alpha & \sum \alpha_1 \alpha_1 c_\alpha & \cdots & \sum \alpha_1 \alpha_n c_\alpha \\ \cdots & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots \\ \sum \alpha_n c_\alpha & \sum \alpha_n \alpha_1 c_\alpha & \cdots & \sum \alpha_n \alpha_n c_\alpha \end{vmatrix}. \quad (*)$$

Now we consider the  $(1 + n) \times (1 + N)$ -matrix

$$B = \begin{pmatrix} \sqrt{c_{\alpha^0}} & \sqrt{c_{\alpha^1}} & \cdots & \sqrt{c_{\alpha^N}} \\ \alpha_1^0 \sqrt{c_{\alpha^0}} & \alpha_1^1 \sqrt{c_{\alpha^1}} & \cdots & \alpha_1^N \sqrt{c_{\alpha^N}} \\ \cdots & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots \\ \alpha_n^0 \sqrt{c_{\alpha^0}} & \alpha_n^1 \sqrt{c_{\alpha^1}} & \cdots & \alpha_n^N \sqrt{c_{\alpha^N}} \end{pmatrix},$$

and make two observations. First, the determinant  $(*)$  is equal to  $\det(B B^{\text{tr}})/F(t)^{1+n}$ . Second, the polynomial  $h_f$  is equal to the sum of the squares of all the maximal minors of  $B$ . The desired identity  $\text{Hess } M_f = h_f/F^{1+n}$  therefore follows from the Cauchy–Binet formula, see [3], which says that the determinant of the product  $B B^{\text{tr}}$  is indeed equal to the sum of the squares of the minors of  $B$ .

We remark that  $h_f$  is the non-homogeneous toric Jacobian of the extended gradient  $(F, t_1 \partial_1 F, \dots, t_n \partial_n F)$ , see [2] and Proposition 1.2 in [1], where a similar computation was carried out. Combining our Proposition 1.1 with the fact that the total mass of  $\text{Hess } M_f$  is equal to  $\text{Vol } \Delta_f$ , we obtain the following explicit, elementary, and apparently new formula for the volume of the Newton polytope.

**Theorem 1.2** *The volume of the Newton polytope  $\Delta_f$  can be computed by means of the closed formula*

$$\text{Vol } \Delta_f = \int_{\mathbf{R}_+^n} \frac{h_f(t)}{(F(t))^{1+n}} \frac{dt_1 \wedge \cdots \wedge dt_n}{t_1 \cdots t_n}. \tag{**}$$

We knew a priori that this integral should converge, since the measure  $\text{Hess } M_f$  has a finite mass, but the convergence now also follows from the obvious fact that the Newton polytope of  $h_f$  is contained in the interior of  $(1 + n) \Delta_f$ .

Regarding the function  $N_f$ , we recall the following result from [5]. Remember that a polyhedral subdivision is a generalized triangulation whose elements are polyhedra (but not necessarily simplices).

**Theorem 1.3** *The piecewise linear convex function  $\max_{\alpha}(c_{\alpha} + \langle \alpha, x \rangle)$ , where  $c_{\alpha} + \langle \alpha, x \rangle = N_f(x)$  in the component of  $\mathbf{R}^n \setminus \mathbf{A}_f$  of order  $\alpha$ , defines a polyhedral subdivision of  $\mathbf{R}^n$  whose  $(n - 1)$ -skeleton is contained in  $\mathbf{A}_f$ , while its Legendre transform similarly defines a dual polyhedral subdivision  $\mathbf{T}_f$  of  $\Delta_f$ . A vector  $\alpha$  is a vertex in  $\mathbf{T}_f$  if and only if  $\mathbf{R}^n \setminus \mathbf{A}_f$  has a component of order  $\alpha$ .*

§2.

In this section we shall study the asymptotic behaviour of Theorems 1.2 and 1.3 as the coefficients  $a_\alpha$  tend to infinity. More precisely, we will set  $a_\alpha = \lambda^{s_\alpha}$  for some fixed vector  $(s_\alpha) \in \mathbf{R}^A$  and  $\mathbf{R} \ni \lambda \rightarrow \infty$ . We recall from [4] that the so-called secondary polytope  $\Sigma_A \subset \mathbf{Z}^A$  has the property that its vertices are in bijective correspondence with the coherent triangulations of  $\Delta_f$ , and that a triangulation is coherent if it can be defined by a convex (or concave) piecewise linear function (as in Theorem 1.3).

For any vertex  $v$  of  $\Sigma_A$ , the normal cone  $N_v$ , which consists of all vectors  $(s_\alpha) \in \mathbf{R}^A$  such that  $(s, v) = \max_{w \in \Sigma_A} (s, w)$ , has a non-empty interior. Any vector  $(s_\alpha)$  from  $\text{int } N_v$ , that is, such that  $(s, v) > (s, w)$  for all  $w \in \Sigma_A$  with  $v \neq w$ , can be used to produce the associated coherent triangulation  $\mathbf{T}_v$  of  $\Delta_f$  in the following way. Let  $g_s$  be the piecewise linear concave function on  $\Delta_f$  whose graph equals the upper boundary of the convex hull of the union of half lines  $\{(\alpha, y); \alpha \in A, y \leq s_\alpha\}$ . Then  $\mathbf{T}_v$  is obtained by projecting the linear pieces of the graph of  $g_s$  down to  $\Delta_f$ . Notice that  $-g_s$  is the Legendre transform of the piecewise linear convex function  $\max_\alpha (s_\alpha + \langle \alpha, x \rangle)$  on  $\mathbf{R}^n$ .

The polynomial  $h_f$ , and hence the whole volume formula in Theorem 1.2, contains one term for each subsimplex  $\sigma_J$  with vertices in  $A$ . Asymptotically, it is only the terms corresponding to the disjoint simplices of a coherent triangulation that survive, as shown by the following theorem.

**Theorem 2.1** *Let  $v$  be a vertex of the secondary polytope  $\Sigma_A$ , and take a vector  $(s_\alpha) \in \mathbf{R}^A$  in the interior of the normal cone  $N_v$ . Set the coefficients  $a_\alpha$  of  $f$  equal to  $\lambda^{s_\alpha}$ . Then the term  $I_J(\lambda)$  in (\*\*) corresponding to the multi-index  $J$  satisfies*

$$\lim_{\lambda \rightarrow \infty} I_J(\lambda) = \begin{cases} \text{Vol } \sigma_J, & \text{if } \sigma_J \in \mathbf{T}_v, \\ 0, & \text{otherwise.} \end{cases}$$

*Proof:* Recalling the formula for  $h_f$ , we see that

$$I_J(\lambda) = \int_{\mathbf{R}_+^n} \frac{\det^2(A_J) \lambda^{s_{\alpha^0}} t^{\alpha^0} \dots \lambda^{s_{\alpha^N}} t^{\alpha^N}}{(\lambda^{s_{\alpha^0}} t^{\alpha^0} + \lambda^{s_{\alpha^1}} t^{\alpha^1} + \dots \lambda^{s_{\alpha^N}} t^{\alpha^N})^{1+n}} \frac{dt_1 \wedge \dots \wedge dt_n}{t_1 \dots t_n}.$$

If we perform the monomial substitution  $u_k = \lambda^{s_{\alpha} j_k} t^{\alpha^{j_k}} / \lambda^{s_{\alpha} j_0} t^{\alpha^{j_0}}$ , for  $k = 1, \dots, n$ , we arrive at

$$I_J(\lambda) = \int_{\mathbf{R}_+^n} \frac{|\det(A_J)| du_1 \wedge \dots \wedge du_n}{(1 + u_1 + \dots + u_n + \delta(\lambda))^{1+n}},$$

where  $\delta(\lambda)$  is a finite sum of fractional monomials  $\lambda^{r_0} u_1^{r_1} \dots u_n^{r_n}$ , with  $r \in \mathbf{Q}^{1+n}$  and  $r_0 \neq 0$ . Now, it is not hard to verify that the simplex  $\sigma_J$  belongs to the triangulation  $\mathbf{T}_v$  precisely if all the exponents  $r_0$  are negative. In this case the term  $\delta(\lambda)$  tends to zero, and since the integral of  $du_1 \wedge \dots \wedge du_n / (1 + u_1 + \dots + u_n)^{1+n}$  over the positive orthant is equal to  $1/n!$ , we conclude that  $I_J(\lambda) \rightarrow |\det(A_J)|/n!$  as claimed. Otherwise, the denominator in the integrand goes to infinity, and the integral  $I_J(\lambda)$  tends to zero.

The proof of the next result is essentially parallel to that of Theorem 9 in [7] and will be omitted.

**Theorem 2.2** *Let  $v$  be a vertex of the secondary polytope  $\Sigma_A$ , and take a vector  $(s_{\alpha})$  as in Theorem 2.1. Set the coefficients  $a_{\alpha}$  of  $f$  equal to  $\lambda^{s_{\alpha}}$  and denote the new polynomial by  $f^{\lambda}$ . For large values of the parameter  $\lambda$  the polyhedral subdivision  $\mathbf{T}_{f^{\lambda}}$  from Theorem 1.3 will then coincide with the coherent triangulation  $\mathbf{T}_v$ .*

We end with a closer look at a one-dimensional case.

**Example 2.3** Consider a one-variable polynomial of the form  $f(t) = 1 + a_1 t + \dots + a_{n-1} t^{n-1} + t^n$ . For each  $m = 0, 1, \dots, 2n - 2$  the so-called Ostrogradski method for finding the rational part of a primitive function can be realized with the explicit formula

$$\int \frac{t^m dt}{f(t)^2} = -\frac{P_m(t)}{f(t)} + \int \frac{Q_m(t) dt}{f(t)},$$

where the  $P_m$  and  $Q_m$  are polynomials of degrees  $n - 1$  and  $n - 2$  respectively. To be specific, one has  $P_m(t) = \sum_{k=0}^{n-1} A_{m,k} t^k$  and  $Q_m(t) = P'_m(t) + \sum_{\ell=0}^{n-2} B_{m,\ell} t^{\ell}$ , with the  $(2n-1) \times (2n-1)$ -matrix  $(B_{m,\ell}, A_{m,k})$  being the inverse of the standard Sylvester matrix (see [4], p.405) whose determinant equals the discriminant  $D_n$  of  $f$ . Now, if we collect terms in  $h_f$  and write  $t^{-1} h_f(t) = \sum_{m=0}^{2n-2} C_m t^m$ , then it holds that  $\sum_m A_{m,k} C_m = (n-k)a_k$  and  $\sum_m B_{m,\ell} C_m = -(\ell+1)(n-\ell-1)a_{\ell+1}$ . (Here  $a_0 = a_n = 1$ .) This implies in particular that if we replace the individual terms

$$\int_0^{\infty} \frac{(j_1 - j_0)^2 a_{j_0} a_{j_1} t^{j_0+j_1-1} dt}{f(t)^2}$$

in formula (\*\*) by their principal parts

$$-\left. \frac{(j_1 - j_0)^2 a_{j_0} a_{j_1} P_{j_0+j_1-1}(t)}{f(t)} \right|_0^\infty = (j_1 - j_0)^2 a_{j_0} a_{j_1} A_{j_0+j_1-1,0}$$

then they still sum to  $\text{Vol } \Delta_f = n$ . In other words, the individual terms of (\*\*), which are not themselves rational functions of the coefficients  $a_j$ , can be replaced by rational expressions so that the volume formula still holds true. Since these expressions all have the discriminant  $D_n$  as their denominator, this means we have in a canonical way associated polynomials (the numerators) with all subsimplices  $[j_0, j_1]$  so that their sum is equal to  $nD_n$ . In fact, the linear form on the vector space  $\langle 1, t, \dots, t^{2n-2} \rangle$  given by

$$t^m \mapsto P_m(0) \quad (= A_{m,0})$$

coincides with the toric residue associated to the mapping  $(f, tf')$ .

### References

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