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# Random walks in random hypergeometric environment 

Tal Orenshtein* ${ }^{*}$ Christophe Sabot ${ }^{\dagger}$


#### Abstract

We consider one-dependent random walks on $\mathbb{Z}^{d}$ in random hypergeometric environment for $d \geq 3$. These are memory-one walks in a large class of environments parameterized by positive weights on directed edges and on pairs of directed edges which includes the class of Dirichlet environments as a special case. We show that the walk is a.s. transient for any choice of the parameters, and moreover that the return time has some finite positive moment. We then give a characterization for the existence of an invariant measure for the process from the point of view of the walker which is absolutely continuous with respect to the initial distribution on the environment in terms of a function $\kappa$ of the initial weights. These results generalize [Sab11] and [Sab13] on random walks in Dirichlet environment. It turns out that $\kappa$ coincides with the corresponding parameter in the Dirichlet case, and so in particular the existence of such invariant measures is independent of the weights on pairs of directed edges, and determined solely by the weights on directed edges.


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Despite important progress in the ballistic, balanced, or perturbative regimes (see in particular [SZ99, Szn00, Szn02, SZ06, BZ07, BDR14, RAS09, BZ08, Law82, GZ12, $\mathrm{BD} 14]$ ), random walks in i.i.d. random environment in dimension $d \geq 2$ remain a very challenging model. The high non-reversibility of this model is at the heart of the difficulty and several of the basic questions concerning recurrence/transience, equivalence between directional transience and ballisticity, and diffusive behavior are still unsolved. The process viewed from the particle, which is a key tool for reversible models, is still only understood under specific conditions (see [Sab13, RA03, BCR16]).

[^0]The special case of random walks in random Dirichlet environment (RWDE), [ES06], where the environment is i.i.d. at each site and distributed according to a Dirichlet law, shows remarkable simplifications, while keeping the main phenomenological behavior as the general model (see [ST17] for a survey). For this special choice of distribution, a key property of "statistical invariance by time reversing" makes it possible to prove transience in dimension $d \geq 3$ [Sab11], existence of an invariant measure viewed from the particle absolutely continuous with respect to the static law, and equivalence between directional transience and ballisticity in dimension $d \geq 3$ [ST11, Sab13, Bou13, ST17].

The aim of this paper is to give a generalization of this model and of these results to a class of one-dependent random walks in random environment, based on some hypergeometric distributions. The hypergeometric functions defined in (1.2) below are a natural special functions constructed from the Dirichlet distributions. A generalization of the statistical time-reversal key property is proved (see Corollary 3.3 below), based on a duality property of these hypergeometric functions. The latter is a multidimensional generalization of the fact that ${ }_{2} F_{1}(a, b ; c, z)={ }_{2} F_{1}(b, a ; c, z)$ where ${ }_{2} F_{1}$ is the basic hypergeometric series (see e.g. [AKKI11], Section 1.2.1 for the definition and Section 1.3.1 for the integral representation).

This generalization is natural from the following considerations. The statistical timereversal property mentioned above makes it possible to write a rather efficient proof of transience and existence of an absolutely continuous invariant measure viewed from the particle in dimension $d \geq 3$, but it fails to give information on some other natural questions on random walks in random Dirichlet environment (RWDE), such as large deviation and Sznitman's $(T)$ condition. Nevertheless, in dimension 1 in the Dirichlet case, the large deviation rate function can be explicitly computed and involves some hypergeometric functions (see [ST17], section 8). The meaning of this computation remains still rather mysterious and the model investigated in this paper comes from an attempt to generalize the computation done in [ST17]. Besides, it is also natural to ask to what extent the strategy used for Dirichlet environments can be generalized. We believe that the class of Dirichlet environments is the only class of i.i.d. environments on which the random walk satisfies the statistical time-reversal property mentioned above. This paper shows nevertheless that a larger class of environments for one-dependent random walks share the same basic features as the Dirichlet environments.

## 1 Statement of the results

### 1.1 Hypergeometric functions

Denote by $\Delta^{(n)}:=\left\{u \in(0,1]^{n}: \sum_{i=1}^{n} u_{i}=1\right\}$ the open $n$-simplex. Define a function on vectors $u \in \Delta^{(n)}$

$$
\begin{equation*}
\varphi(\alpha, \beta ; Z ; u)=\left(\prod_{i=1}^{n} u_{i}^{\alpha_{i}-1}\right) \prod_{j=1}^{l}\left((Z \cdot u)_{j}^{-\beta_{j}}\right) \tag{1.1}
\end{equation*}
$$

where as parameters we take vectors $\alpha \in\left(\mathbb{R}_{+}^{*}\right)^{n}$ and $\beta \in\left(\mathbb{R}_{+}^{*}\right)^{l}$ that satisfy $\sum_{i} \alpha_{i}=\sum_{j} \beta_{j}$ and have strictly positive coordinates, and $l \times n$ matrix $Z=\left(Z_{j, i}\right)$ with strictly positive coefficients, where here and after we use the notation $\mathbb{R}_{+}^{*}=\{t \in \mathbb{R}: t>0\}$. Call functions of the following form hypergeometric functions:

$$
\begin{equation*}
\Phi(\alpha, \beta ; Z):=\int_{\Delta^{(n)}} \varphi(\alpha, \beta ; Z ; u) d u \tag{1.2}
\end{equation*}
$$

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Here the integral is computed according to the Lebesgue measure on the simplex $d u=d u_{1} \cdots d u_{n-1}$ so that $u_{n}=1-\sum_{i=1}^{n-1} u_{i}$. When $\left(Z_{j, i}\right)$ has strictly positive coefficients, we have for all $(Z \cdot u)_{j} \geq \underline{z}$, with $\underline{z}=\min _{i, j}\left(Z_{j, i}\right)$, so that the integral (1.2) is finite. These functions are classical generalized hypergeometric functions, see e.g. [AKKI11, Section 3.7.4.].

### 1.2 The model on $\mathbb{Z}^{d}$

We denote by $\left(e_{1}, \ldots, e_{d}\right)$ the canonical base of $\mathbb{R}^{d}$, and we set $e_{d+i}=-e_{i}$ for $i=$ $1, \ldots, d$. Consider the lattice $\mathbb{Z}^{d}$ endowed with its natural directed graph structure: $\mathcal{G}_{\mathbb{Z}^{d}}=\left(\mathbb{Z}^{d}, E_{\mathbb{Z}^{d}}\right)$, where $E=\left\{\left(x, x+e_{i}\right), x \in \mathbb{Z}^{d}, i=1, \ldots, 2 d\right\}$. The arc graph is the directed graph $\mathcal{H}_{\mathbb{Z}^{d}}=\left(E_{\mathbb{Z}^{d}}, K_{\mathbb{Z}^{d}}\right)$, with $K=K_{\mathbb{Z}^{d}} \subset E_{\mathbb{Z}^{d}} \times E_{\mathbb{Z}^{d}}$ given by

$$
K=\left\{\left(\left(x-e_{i}, x\right),\left(x, x+e_{j}\right)\right), x \in \mathbb{Z}^{d}, i, j=1, \ldots, 2 d\right\}
$$

Concretely, $K$ is the set of couples of succeeding edges that can be crossed by a random walker on the graph $\mathcal{G}_{\mathbb{Z}^{d}}$. The space $\Omega_{K} \subset(0,1]^{K}$ of random environments on $\mathcal{H}_{\mathbb{Z}^{d}}$ is the subspace of transition probabilities of nearest neighbor chains on $\mathcal{H}_{\mathbb{Z}^{d}}$ :

$$
\Omega_{K}=\left\{\left(\omega_{e, e^{\prime}}\right)_{\left(e, e^{\prime}\right) \in K} \in(0,1]^{K}, \text { such that } \forall e \in E, \sum_{e^{\prime},\left(e, e^{\prime}\right) \in K} \omega_{e, e^{\prime}}=1\right\}
$$

The space $\Omega_{K}$ also naturally describes the space of one-dependent Markov chain kernels on the graph $\mathbb{Z}^{d}$.

Let us now define the random environment. Fix some positive parameters ( $\alpha_{1}, \ldots, \alpha_{2 d}$ ) and a $2 d \times 2 d$ matrix $Z=\left(Z_{i, j}\right)$ with strictly positive coefficients.
The vectors $\left(u_{\left(x, x+e_{i}\right)}\right)_{i=1, \ldots, 2 d}, x \in V$, are chosen randomly and independently according to the same distribution on the simplex $\Delta^{(2 d)}$ with density

$$
\begin{equation*}
\frac{1}{\Phi(\alpha, \alpha ; Z)} \varphi(\alpha, \alpha ; Z ; u) \mathrm{d} u \tag{1.3}
\end{equation*}
$$

This defines a product law on $\left(u_{\left(x, x+e_{i}\right)}\right)_{x \in \mathbb{Z}^{d}, i=1, \ldots, 2 d}$ which is denote by $\mathrm{P}^{(\alpha, Z)}$. Denote by $\mathbb{E}^{(\alpha, Z)}$ the corresponding expectation. We now define a random environment on $K_{\mathbb{Z}^{d}}$ by first sampling $\left(u_{\left(x, x+e_{i}\right)}\right)_{x \in \mathbb{Z}^{d}, i=1, \ldots, 2 d}$ according to the last product law and the letting

$$
\begin{equation*}
\omega_{\left(x-e_{i}, x\right),\left(x, x+e_{j}\right)}=\frac{Z_{i, j} u_{x, x+e_{i}}}{\sum_{l=1}^{2 d} Z_{i, l} u_{x, x+e_{l}}}, x \in \mathbb{Z}^{d}, i, j=1, \ldots, 2 d . \tag{1.4}
\end{equation*}
$$

Naturally, $\omega$ defines the transition probabilities of a Markov chain on the arc graph $\mathcal{H}_{\mathbb{Z}^{d}}$, i.e. $w \in \Omega_{K}$, and the distribution $\mathbb{P}^{(\alpha, Z)}$ induces a probability distribution on the set of environments $\Omega_{K}$.

For an environment $\omega$ we denote by $P_{e, \omega}$ the law of the Markov chain $\left(X_{n}\right)_{n \in \mathbb{N}}$ on state space $E$ started at $e \in E$ with step distribution $\omega$. Whenever $\omega$ is sampled according to $\mathbb{P}^{(\alpha, Z)}$, we say that the last Markov chain is distributed according to the quenched law. Denote by $\mathbb{P}_{e}^{(\alpha, Z)}$ the marginal of the joint law of the Markov chain started at $e$ and the environment distributed according to $\mathbb{P}^{(\alpha, Z)}$. The latter is also called the averaged law, or the annealed law, of the walk $X$, and it is characterized by

$$
\mathbb{P}_{e}^{(\alpha, Z)}(\cdot)=\int P_{e, \omega}(\cdot) \mathrm{dP}^{(\alpha, Z)}(\omega)
$$

Remark that from (1.3), whenever $Z_{i, j}=Z_{i, 1}$ for all $i, j=1, \ldots, 2 d$, then we have $\omega_{\left(x-e_{i}, x\right),\left(x, x+e_{j}\right)}=u_{x, x+e_{j}}$. Therefore, it defines a Markov chain on the original graph $\mathcal{G}_{\mathbb{Z}^{d}}$, and moreover $\left(u_{x, x+e_{i}}\right)_{i=1, \ldots, 2 d}$ are independent and follow a Dirichlet distribution with parameters $\left(\alpha_{1}, \ldots, \alpha_{2 d}\right)$ at each site. Hence, it corresponds to RWDE mentioned in the introduction (for an overview on RWDE see [ST17]).

### 1.3 Order of Green function and Transience on $\mathbb{Z}^{d}, d \geq 3$

Fix parameters $\left(\alpha_{i}\right)_{i=1, \ldots, 2 d}$ and $\left(Z_{i, j}\right)_{i, j=1, \ldots, 2 d}$ as in Section 1.2 and let $\omega$ be distributed according to $\mathbb{P}^{(\alpha, Z)}$. Denote by $G_{\omega}\left(e_{0}, e_{0}\right)$ the Green function at $\left(e_{0}, e_{0}\right)$ of the Markov chain with jump probabilities $\omega$, that is, the $P_{e_{0}, \omega}$-expected number of returns to $e_{0}$.
Theorem 1.1. Let $\alpha$ and $Z$ be as in Section 1.2 and $d \geq 3$. Let $\tilde{\kappa}:=\min _{i=1, \ldots, 2 d}\left\{\alpha_{e_{i}}\right\}$. If $s<\tilde{\kappa}$, then

$$
\mathbb{E}_{e_{0}}^{(\alpha, Z)}\left[G_{\omega}\left(e_{0}, e_{0}\right)^{s}\right]<\infty
$$

In particular, $\omega-\mathbb{P}^{(\alpha, Z)}$ almost surely, $\left(X_{n}\right)$ is transient under the quenched law $P_{e_{0}, \omega}$.
Remark 1.2. A similar statement was proved in [Sab11, Theorem 1] in the Dirichlet case for $s<\kappa$, where $\kappa=\max \left\{2\left(\sum_{j=1}^{d} \alpha_{e_{j}}\right)-\left(\alpha_{e_{i}}-\alpha_{-e_{i}}\right): 1 \leq i \leq d\right\}$ (an interpretation of the parameter $\kappa$ is given at the end of Section 1.4). Hence, the last theorem generalizes this to the hypergeometric environment in the case $s<\tilde{\kappa}<\kappa$. The statement would certainly be also true in the case $\tilde{\kappa} \leq s<\kappa$ : to prove it in this regime, one would need to consider a max-flow type problem adapted to the $\operatorname{arc}$ graph $\mathcal{H}$, as in Section 7.2. of [ST17] together with our proof of Theorem 1.4. We don't include that analysis in the current paper, but we stress that it could be done using the same techniques.
Remark 1.3. As in the standard Dirichlet case, the case of dimension 2 is still mysterious. It is expected that the walk is recurrent when the weights are symmetric with respect to the axis (i.e. null expected drift at first step), hence the the Green function is a.s. infinite. When the weights are not symmetric, we would expect that there is no long range trapping effect in $d=2$ so that the integrability condition would be the same as in $d \geq 3$. But it is still far from being understood. In dimension $d=1$, it would be possible to adapt the proof of the Diriclet case (see [ST17] page 502) to compute the law of the probability starting from the edge $(0,1)$ to never come back to the edge $(0,1)$. It would give that the Green function is integrable for $s<|\alpha-\beta|$ when $\alpha$ (resp. $\beta$ ) are the weights of the right direction edge (resp. left direction edge). The integrability should not depend on the $Z$ parameters. When $\alpha=\beta$ the walk should be recurrent.

### 1.4 Invariant measure for the walker point of view

Let $\left(\tau_{x}\right)_{x \in \mathbb{Z}^{d}}$ be the shift maps on $\Omega_{K}$, where $\tau_{x}\left(\omega\left(e, e^{\prime}\right)\right):=\omega\left(x+e, x+e^{\prime}\right)$. Here $x+e:=\left(x+\underline{e}, x+\bar{e}^{\prime}\right)$ for $x \in \mathbb{Z}^{d}$ and $e=(\underline{e}, \bar{e}) \in E_{\mathbb{Z}^{d}}$. We also let $\tau_{e}:=\tau_{\bar{e}}$. Following the strategy of [Koz85] and [KV86], we define the process

$$
\bar{\omega}_{n}:=\tau_{X_{n}}\left(\bar{\omega}_{0}\right) \text { on } \Omega_{K}
$$

from the point of view of the walker with initial state $\bar{\omega}_{0} \sim \mathbb{P}$. Under $\mathbb{P}_{e_{0}}$, this is a Markov process on $\Omega_{K}$. Its infinitesimal generator $\mathcal{R}$ is given by

$$
\mathcal{R}(f)(\omega):=\sum_{i=1}^{2 d} \omega\left(e_{0}, e_{i}\right) f\left(\tau_{e_{i}}(\omega)\right)
$$

defined for measurable bounded functions $f$ on $\Omega_{K}$. Call a (probability) measure $Q$ on $\Omega_{K}$ invariant under $\mathcal{R}$ if $\int \mathcal{R} f Q(d \omega)=\int f Q(d \omega)$ for all measurable bounded functions $f$ on $\Omega_{K}$.

The main result of this section is the following generalization of Theorem 1 of [Sab13].
Theorem 1.4. Let $\kappa:=\max \left\{2\left(\sum_{j=1}^{d} \alpha_{e_{j}}\right)-\left(\alpha_{e_{i}}-\alpha_{-e_{i}}\right): 1 \leq i \leq d\right\}>0$ and assume $d \geq 3$. Then:

1. If $\kappa>1$ then there is a unique probability measure $\mathbb{Q}^{(\alpha, Z)}$ on $\Omega_{K}$ which is invariant under $\mathcal{R}$ and is absolutely continuous with respect to the initial measure $\mathbb{P}^{(\alpha, Z)}$.

Moreover, for every $p \in[1, \kappa)$ the Radon-Nikodym derivative $\frac{\mathrm{dQ}^{(\alpha, Z)}}{\mathrm{dP}^{(\alpha, Z)}}$ is in $L_{p}\left(\mathbb{P}^{(\alpha, Z)}\right)$. (In particular, trivially, the last assertion holds also for every $0<p<1$.)
2. If $\kappa \leq 1$ then there is no probability measure satisfying the invariance and absolute continuity properties of the last case.

The parameter $\kappa$ was considered first in [Sab11] in the context of $\mathbb{Z}^{d}$, and was introduced by Tournier [Tou09] for finite graphs. Let us give an interpretation of this parameter. If $S \subset V$ is a nonempty set of vertices, the outer boundary of $S$ is defined by

$$
\partial_{+}(S)=\{e \in E: \underline{e} \in S \text { but } \bar{e} \notin S\} .
$$

Define also $\alpha\left(\partial_{+}(S)\right)=\sum_{e \in \partial_{+}(S)} \alpha_{e}$, the total $\alpha$-strength of the edges leaving $S$. Then

$$
\begin{equation*}
\kappa=\max \left\{\alpha\left(\partial_{+}\left(\left\{0, \bar{e}_{i}\right\}\right)\right): i=1, \ldots, d\right\} \tag{1.5}
\end{equation*}
$$

represents the maximal weight of the outer boundary of a single edge. Roughly speaking, it means that the strongest traps in this model are the traps consisting of a single edge, and the strength of these traps is the outer weight. This last assertion is justified by the following lemma.
Lemma 1.5. Let $T_{i}=: \inf \left\{n \geq 0: X_{n} \notin\left\{\left\{0, e_{i}\right\},\left\{e_{i}, 0\right\}\right\}\right\}, i=1, \ldots, 2 d$, be the exist times from the set $\left\{\left\{0, e_{i}\right\},\left\{e_{i}, 0\right\}\right\}$ of directed edges. If $\kappa \leq 1, \mathbb{E}_{e_{0}}^{(\alpha, Z)}\left[T_{i}\right]=\infty$ for some $1 \leq i \leq 2 d$.

Proof. Using (1.4) and the independence of the $u_{e}$ between vertices, and noticing that un$\operatorname{der} P_{e_{0}, \omega}, T_{i}$ is a geometric random variable with expectation $\frac{1}{1-\omega\left(\left\{0, e_{i}\right\},\left\{e_{i}, 0\right\}\right) \omega\left(\left\{e_{i}, 0\right\},\left\{0, e_{i}\right\}\right)}$, the proof is concluded in a similar manner as in [Tou09, Chapter 3.2].

Remark 1.6. We believe that the statement of the last lemma can be strengthened to say that $\mathbb{E}_{e_{0}}^{(\alpha, Z)}\left[T_{i}^{s}\right]=\infty$ for some $1 \leq i \leq 2 d$ if and only if $s \geq \kappa$. Since the proof should be somewhat involved, and since we shall use only the weak form of the lemma (namely an implication in the case $s=1$ ), this is not done in the current paper.

## 2 General graphs

It is necessary for the proof to define our random environments on general graphs. This is done in Section 2.1 and 2.2 below.

### 2.1 Directed arc graph

Remember that a directed graph is connected if for any two vertices $x$ and $y$ there is a directed path connecting $x$ to $y$, or connecting $y$ to $x$. Let $\mathcal{G}=(V, E)$ be a connected directed graph with vertices and edges such that the in-degrees and out-degrees are finite at each vertex. Here and after in-degree (out-degree) of a vertex $x \in V$ is the number of vertices $y \in V$ that $(y, x) \in E$ (respectively, $(x, y) \in E$ ). For each edge $e$ we denote by $\underline{e}$ and $\bar{e}$ the tail and head of the edge so that $e=(\underline{e}, \bar{e})$, and we denote by $\check{e}=(\bar{e}, \underline{e})$ the "reversed edge". We denote by $\check{\mathcal{G}}=(V, \check{E})$ the reversed graph with edge set $\check{E}:=\{\check{e}, e \in E\}$.

We define the (directed and connected) arc graph $\mathcal{H}=(E, K)$ with nodes $E$ and arcs $K$ by setting $K:=\left\{k=\left(e, e^{\prime}\right) \in E^{2}: \bar{e}=\underline{e}^{\prime}\right\}$. In words, $\mathcal{H}$ is the graph so that its nodes are the edges of $\mathcal{G}$ and its arcs are directed pairs of edges of $\mathcal{G}$ that share a common vertex, the head of the first edge and the tail of the second one. Define the reversed graph $\check{\mathcal{H}}=(\check{E}, \check{K})$ by the relation $\left(\check{e}^{\prime}, \check{e}\right) \in \check{K} \leftrightarrow\left(e, e^{\prime}\right) \in K$. Clearly, $\check{\mathcal{H}}$ is also the arc graph of the reversed graph $\check{\mathcal{G}}$.

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Let $\Omega_{K} \subset(0,1]^{K}$ be defined by

$$
\Omega_{K}=\left\{\omega: \sum_{e^{\prime}:\left(e, e^{\prime}\right) \in K} \omega\left(e, e^{\prime}\right)=1, \forall e \in E\right\}
$$

seen as a topological (measurable) subspace of $(0,1]^{K}$ with the standard topology (Borel $\sigma$-algebra). The space $\Omega_{K}$ will be the space of environments of Markov chains on the directed graph $\mathcal{H}$. The space $\Omega_{\check{K}}$ is defined similarly for the reversed graph $\check{\mathcal{H}}=(\check{E}, \check{K})$. As in Section 1.2, we note that $\Omega_{K}$ also describes the one-dependent Markov chains on the graph $\mathcal{G}$.

### 2.2 The model on a general directed arc graph

Let $\mathcal{G}=(V, E)$ be a directed connected graph, and let $\mathcal{H}$ be the corresponding arc graph. Fix strictly positive parameters $\left(\alpha_{e}\right)_{e \in E}$ and $\left(Z_{e, e^{\prime}}\right)_{\left(e, e^{\prime}\right) \in K}$. Recall the definition of $\varphi$ and $\Phi$ in Section 1.1. For every $x \in V$, let

$$
\begin{equation*}
\varphi_{x}(\alpha ; Z ; u)=\varphi\left(\left(\alpha_{e}\right)_{\underline{e}=x},\left(\alpha_{e}\right)_{\bar{e}=x} ;\left(Z_{e, e^{\prime}}\right)_{\bar{e}=x=\underline{e}^{\prime}} ;\left(u_{e}\right)_{\underline{e}=x}\right) \tag{2.1}
\end{equation*}
$$

be defined for $u$ in the $\operatorname{deg}(x)$-simplex

$$
\Delta^{(x)}:=\left\{\left(u_{e}\right)_{\underline{e}=x}: u_{e}>0, \sum_{\{e: \underline{e}=x\}} u_{e}=1\right\} .
$$

Here $\operatorname{deg}(x)$ is the out-degree of $x$. Similarly we let, as in (1.2),

$$
\begin{equation*}
\Phi_{x}(\alpha ; Z):=\int_{\Delta^{(x)}} \varphi_{x}(\alpha ; Z ; u) \mathrm{d}_{x} u=\Phi\left(\left(\alpha_{e}\right)_{\underline{e}=x},\left(\alpha_{e}\right)_{\bar{e}=x} ;\left(Z_{e, e^{\prime}}\right)_{\bar{e}=x=e^{\prime}}\right) \tag{2.2}
\end{equation*}
$$

where $\mathrm{d}_{x} u=\prod_{e=x, e \neq e_{x}} \mathrm{~d} u_{e}$ is the measure on $\Delta^{(x)}$ defined in Section 1.1, where $e_{x}$ is an arbitrary choice of edge exiting $x$ (obviously, $d u$ does not depend on the choice of $e_{x}$ ). Let $U(x), x \in V$, be random vectors with values in $\Delta^{(x)}$, which are independent and distributed according to the density

$$
\frac{1}{\Phi_{x}(\alpha, Z)} \varphi_{x}(\alpha ; Z ; u) \mathrm{d}_{x} u
$$

For every $e \in E$ let $u_{e}:=U_{e}(\underline{e})$, the $e$ coordinate of the random vector $U(\underline{e})$. We denote by $\mathbb{P}^{(\alpha, Z)}$ the distribution on $\left(u_{e}\right)_{e \in E}$ defined in this way. Denote by $\mathbb{E}^{(\alpha, Z)}$ the corresponding expectation.

From the random variables $u_{e}, e \in E$, we construct an environment $\omega \in \Omega_{K}$ by

$$
\begin{equation*}
\omega\left(e, e^{\prime}\right):=\frac{Z_{e, e^{\prime}} u_{e^{\prime}}}{\sum_{e^{\prime \prime}: e^{\prime \prime}=x} Z_{e, e^{\prime \prime}} u_{e^{\prime \prime}}}, \quad \forall\left(e, e^{\prime}\right) \in K \tag{2.3}
\end{equation*}
$$

With a slight abuse of notation, we also denote by $\mathbb{P}^{(\alpha, Z)}$ the law thus induced on $\Omega_{K}$. For $\omega \in \Omega_{K}$ we denote by $P_{e, \omega}$ the law of the Markov chain $X$ on $E$ started at $e \in E$ with step distribution $\omega$. Whenever $\omega$ is sampled according to $\mathbb{P}^{(\alpha, Z)}$, the law of the last Markov chain is called the quenched law. Denote by $\mathbb{P}_{e}^{(\alpha, Z)}$ the marginal law of the joint law of the Markov chain started at $e$ and the environment distributed according to $\mathbb{P}^{(\alpha, Z)}$. The latter is also called the averaged law, or annealed law of the walk $X$, and is characterized by

$$
\mathbb{P}_{e}^{(\alpha, Z)}(\cdot)=\int P_{e, \omega}(\cdot) \mathrm{dP}^{(\alpha, Z)}(\omega)
$$

Note that, as in the case of $\mathbb{Z}^{d}$, if $\left(Z_{e, e^{\prime}}\right)_{\bar{e}=x=\underline{e}^{\prime}}, x \in V$, are matrices with constant rows (i.e. $Z_{e, e^{\prime}}=c_{e}$ for every $\left(e, e^{\prime}\right) \in K$ ), then $U(x)$ has the $\operatorname{Dirichlet}\left(\left(\alpha_{e}\right)_{\underline{e}=x}\right)$ distribution. Hence $\omega$ is an i.i.d $\operatorname{Dirichlet}\left(\left(\alpha_{e}\right)_{\underline{e}=x}\right)$ environment, and the walk is a standard random walk in Dirichlet environment.

The model defined in Section 1.2 on $\mathbb{Z}^{d}$ obviously corresponds to the case where the parameters $\left(\alpha_{e}\right)_{e \in E}$ and $\left(Z_{e, e^{\prime}}\right)_{\left(e, e^{\prime}\right) \in K}$ are given by
$\alpha_{x, x+e_{i}}=\alpha_{i}, \forall x \in \mathbb{Z}^{d}, i=1, \ldots, 2 d$, and $Z_{\left(x-e_{i}\right),\left(x+e_{j}\right)}=Z_{i, j}, \forall x \in \mathbb{Z}^{d}, i, j=1, \ldots, 2 d$,
with notation as in Section 1.2. We warn the reader about the little confusion of notation between $\left(\alpha_{i}\right)$ and $\left(\alpha_{e}\right)$ and $\left(Z_{i, j}\right)$ and $\left(Z_{e, e^{\prime}}\right)_{\left(e, e^{\prime}\right) \in K}$ but we think it will be clear enough from the context. Obviously, the model of Section 1.2 describes all the parameters on $\mathcal{H}_{\mathbb{Z}^{d}}$ which are invariant by translation, i.e. which satisfy $\alpha_{e}=\alpha_{x+e}$, for all $x \in \mathbb{Z}^{d}, e \in E$ and $Z_{e, e^{\prime}}=Z_{x+e, x+e^{\prime}}$, for all $x \in \mathbb{Z}^{d}$ and $\left(e, e^{\prime}\right) \in K$.

### 2.3 A remark on our motivation

The origin of this work comes from the following fact proved in [ST17, Section 8.3]. In dimension 1 the rate function of the annealed large deviation principal for the hitting time of a level $k$ is computed in terms of the hypergeometric function ${ }_{2} F_{1}$. The proof is based on the identification of the law of a the solution of a distributional equation, inspired by Chamayou and Letac, [CL91]. The symmetry property of ${ }_{2} F_{1}$, which is a special case of the duality property proved in Appendix A, is at the core of the argument. In the one-dimensional case, this identity generalizes the statistical time-reversal property. An very interesting problem, which is still open, is to find a multidimensional counterpart for the rate function formula.

Another motivation is to find other models that share the same type of statistical timereversal property with Dirichlet environments. We believe that Dirichlet environments are the only non-trivial model based on independent transition probabilities at each site that have this property. The model presented here is a natural extension of the Dirichlet environment that allows one-dependence of the quenched Markov chain and that shares similar property.

## 3 Main tools

### 3.1 Marginal and multiplicative moments

We assume in this chapter that the graph $\mathcal{G}$ is finite. Our first observation regarding the hypergeometric distribution is the distribution of its marginal. A direct computation gives that if $\omega$ is defined as in (2.3), then we have for $e, e^{\prime}$ so that $\bar{e}=x=\underline{e}^{\prime}$

$$
\begin{equation*}
\mathbb{E}^{(\alpha, Z)}\left[\omega\left(e, e^{\prime}\right)^{s}\right]=Z_{e, e^{\prime}}^{s} \frac{\Phi_{x}\left(\alpha+s\left(\delta_{e}+\delta_{e^{\prime}}\right), Z\right)}{\Phi_{x}(\alpha, Z)} \tag{3.1}
\end{equation*}
$$

In particular we see that the above is finite whenever the arguments of $\Phi_{x}$ is strictly positive, and in particular as long as $s>-\min \left\{\alpha_{e}, \alpha_{e^{\prime}}\right\}$. Note that in the Dirichlet case, e.g. whenever $Z \equiv 1$, we have that $\omega\left(e, e^{\prime}\right)=u_{e^{\prime}}$ has the Beta distribution $\operatorname{Beta}\left(\alpha_{e^{\prime}}, \sum_{\bar{e}=x} \alpha_{e}-\alpha_{e^{\prime}}\right)$.

Next, we shall expand the definition of the measure $\mathbb{P}^{(\alpha, Z)}$ on environments to include a possibility to increase or decrease the weights $\alpha$ and $Z$.

Assume here that $\mathcal{G}$ is finite. For a function $\xi: K \rightarrow \mathbb{R}$ let

$$
\bar{\xi}_{e}:=\sum_{\underline{e}^{\prime}=\bar{e}} \xi\left(e, e^{\prime}\right) \text { and } \underline{\xi}_{e^{\prime}}:=\sum_{\bar{e}=\underline{e}^{\prime}} \xi\left(e, e^{\prime}\right)
$$

be the total 'weight' leaving $e$, and entering $e^{\prime}$, respectively.

We now define the measure $\mathbb{P}^{(\alpha, \xi, Z)}$ on $\Omega_{K}$ by a similar procedure. For every $x \in V$ and $u \in \Delta^{(x)}$ we let

$$
\varphi_{x}(\alpha ; \xi ; Z ; u)=\varphi\left(\left(\alpha_{e}+\underline{\xi}_{e}\right)_{\underline{e}=x},\left(\alpha_{e}+\bar{\xi}_{e}\right)_{\bar{e}=x} ;\left(Z_{e, e^{\prime}}\right)_{\bar{e}=x=\underline{e}^{\prime}} ;\left(u_{e}\right)_{\underline{e}=x}\right)
$$

and similarly

$$
\Phi_{x}(\alpha ; \xi ; Z):=\int_{\Delta^{(x)}} \varphi_{x}(\alpha ; \xi ; Z ; u) \mathrm{d}_{x} u
$$

This is well-defined as long as $\alpha_{e}+\bar{\xi}_{e}>0$ and $\alpha_{e}+\underline{\xi}_{e}>0$ for all $e \in E$. Next, $U_{x}, x \in V$, are taken to be independent with density

$$
\frac{1}{\Phi_{x}(\alpha ; \xi ; Z)} \varphi_{x}(\alpha ; \xi ; Z ; u) \mathrm{d}_{x} u
$$

Putting $u_{e}:=U_{\underline{e}}(e), e \in E$, and constructing $\omega \in \Omega_{K}$ as in (2.3), we denote its quenched and annealed laws by $P_{e_{0}, \omega}$ and $\mathbb{P}_{e_{0}}^{(\alpha, \xi, Z)}$. Note that in the case $\xi \equiv 0$ we have $\mathbb{P}_{e_{0}}^{(\alpha, 0, Z)}=$ $\mathbb{P}_{e_{0}}^{(\alpha, Z)}$.

It will be beneficial to define

$$
\begin{equation*}
F(\alpha ; \xi ; Z):=\prod_{x \in V} \Phi_{x}(\alpha ; \xi ; Z), \text { and } F(\alpha ; Z):=F(\alpha ; 0 ; Z) \tag{3.2}
\end{equation*}
$$

Also, for functions $\beta, \gamma: A \rightarrow \mathbb{R}_{+}$so that $A$ is a finite set and $\beta$ is strictly positive, we define

$$
\begin{equation*}
\beta^{\gamma}:=\prod_{x \in A} \beta(x)^{\gamma(x)} \tag{3.3}
\end{equation*}
$$

A direct computation gives that for every $\xi, \Theta: K \rightarrow \mathbb{R}$

$$
\begin{equation*}
\mathbb{E}^{(\alpha, \Theta, Z)}\left[\omega^{\xi}\right]=Z^{\Theta+\xi} \cdot \frac{F(\alpha ; \Theta+\xi ; Z)}{F(\alpha ; \Theta ; Z)} \tag{3.4}
\end{equation*}
$$

as long as the right hand side of the equation is well defined.
If we think of $\mathbb{P}^{(\alpha, Z)}$ as the law of $\left(u_{e}\right)_{e \in E}$, i.e. a measure on $\prod_{x \in V} \Delta^{(x)}$, then the Radon-Nikodym derivative one gets by changing the values of $\alpha$ is explicit. Indeed, for $\theta: E \rightarrow \mathbb{R}_{+}$so that $\alpha_{e}>\theta_{e}$ for all $e \in E$, and for any random variable $Y(\omega)=(Y \circ \omega)(u)$

$$
\begin{equation*}
\mathbb{E}^{(\alpha, Z)}[Y]=\frac{F(\alpha+\theta, Z)}{F(\alpha, Z)} \mathbb{E}^{(\alpha+\theta, Z)}\left[\tilde{u}^{-\theta} \cdot Y\right] \tag{3.5}
\end{equation*}
$$

where

$$
\tilde{u}_{e}:=\frac{u_{e}}{\sum_{\underline{e^{\prime}}=\bar{e}} Z_{e, e^{\prime}} u_{e^{\prime}}} .
$$

### 3.2 Duality formula

A key feature of the hypergeometric functions defined in (1.2) is the following duality formula [AKKI11, Page 169], which has consequences regarding time-reversing. This will be discussed in Chapter 3.3, and a direct proof of Lemma 3.1 will be supplied in Appendix A. Define

$$
\begin{equation*}
B(\alpha)=B\left(\alpha_{1}, \ldots, \alpha_{n}\right)=\frac{\prod_{i=1}^{n} \Gamma\left(\alpha_{i}\right)}{\Gamma\left(\sum_{i=1}^{n} \alpha_{i}\right)}, \tag{3.6}
\end{equation*}
$$

where $\Gamma$ is the standard Gamma function, i.e. $\Gamma(t)=\int_{0}^{\infty} x^{t-1} e^{-x} d x$.
Lemma 3.1 (Duality formula). With the notation from (1.2), the following holds as soon as $\sum_{i=1}^{n} \alpha_{i}=\sum_{j=1}^{l} \beta_{j}$

$$
B(\alpha)^{-1} \Phi(\alpha, \beta, Z)=B(\beta)^{-1} \Phi\left(\beta, \alpha, Z^{t}\right)
$$

where $Z^{t}$ is the transposed matrix corresponds to $Z$.

We remark that in the Dirichlet case (e.g., whenever $Z \equiv 1$ ) both $\Phi(\alpha, \beta, Z)=B(\alpha)$ and $\Phi\left(\beta, \alpha, Z^{t}\right)=B(\beta)$ and so in this case the duality is trivial.

### 3.3 Time-reversal statistical invariance

In this section we assume that the graph $\mathcal{G}=(V, E)$ is finite. For $\omega \in \Omega_{K}$, let $\left.\pi^{\omega}=\left(\pi^{\omega}(e)\right)\right)_{e \in E}$ be the invariant probability measure of the Markov chain on $E$ with transition probabilities $\omega$. (Note that by ellipticity of $\omega$, the finite state Markov chain is a.s. irreducible and hence $\pi^{\omega}$ is a.s. unique.) Define the time reversed environment $\check{\omega} \in \Omega_{\check{K}}$ by letting

$$
\begin{equation*}
\check{\omega}\left(\check{e}^{\prime}, \check{e}\right)=\pi^{\omega}(e) \omega\left(e, e^{\prime}\right) \pi^{\omega}\left(e^{\prime}\right)^{-1} . \tag{3.7}
\end{equation*}
$$

Let $\check{\pi}^{\check{\omega}}$ be the invariant probability measure of the Markov chain on $\check{E}$ with transition probabilities $\check{\omega}$. Then, since $\check{\pi}^{\check{\omega}}$ is also the invariant probability measure of the time reversed chain defined by $\omega$, we have

$$
\begin{equation*}
\check{\pi}^{\omega}(\check{e})=\pi^{\omega}(e) \tag{3.8}
\end{equation*}
$$

for every $e \in E$. Note that $\check{\omega}$ is an element of $\Omega_{\check{K}}$.
Let $\breve{\alpha}_{\check{e}}:=\alpha_{e}$ for every $e \in E$. Also, denote $\check{Z}$ the 'reversed' matrices corresponds to $Z$, that is $\check{Z}_{\check{e}^{\prime}, \check{e}}=\left(Z^{t}\right)_{e^{\prime}, e}=Z_{e, e^{\prime}}$. Let $C=\left\{e_{0}, e_{1}, \ldots, e_{n}=e_{0}\right\}$ be a cycle in $\mathcal{H}, n=n(C)$ is its length. (The reader should notice that here $C$ is a cycle of edges, and so viewed as a sequence of vertices it has the form $\left\{\underline{e_{0}}, \underline{e_{1}}, \underline{e_{2}}, \ldots, \underline{e_{n}}=\underline{e_{0}}, \overline{e_{0}}=\underline{e_{1}}\right\}$, i.e., a cycle of vertices plus a repetition of the vertex $\underline{e_{1}}$.) Define $\check{C}:=\left\{\check{e}_{n}, \check{e}_{n-1}, \ldots, \check{e}_{0}=\check{e}_{n}\right\}$ to be the corresponding reversed cycle in $\mathcal{H}$. For a finite collection $\mathcal{C}$ of cycles we denote by $\check{\mathcal{C}}:=\{\check{C}: C \in \mathcal{C}\}$. Set $\omega_{C}:=\prod_{k=0}^{n-1} \omega_{e_{k}, e_{k+1}}$, and $\omega_{\mathcal{C}}:=\prod_{C \in \mathcal{C}} \omega_{C}$. By (3.7), we have

$$
\omega_{C}=\check{\omega}_{\check{C}}
$$

for all cycles $C$. Similarly, we set $Z_{C}:=\prod_{k=0}^{n-1} Z_{e_{k}, e_{k+1}}$ and $Z_{\mathcal{C}}:=\prod_{C \in \mathcal{C}} Z_{C}$. We have, by definition of $\check{Z}$, that $Z_{C}=\check{Z}_{\check{C}}$ for all cycle $C$.

We introduce now the divergence operator on the graph $\mathcal{G}$ : we define div : $\mathbb{R}^{E} \mapsto \mathbb{R}^{V}$ by

$$
\operatorname{div}(\theta)(x)=\sum_{\underline{e}=x} \theta(e)-\sum_{\bar{e}=x} \theta(e), \quad \forall \theta \in \mathbb{R}^{E}
$$

Lemma 3.2. Assume $\operatorname{div}(\alpha)=0$. The following hold for all finite collections of cycles $\mathcal{C}$,

$$
\mathbb{E}^{(\alpha, Z)}\left(\check{\omega}_{\check{\mathcal{C}}}\right)=\mathbb{E}^{(\check{\alpha}, \check{Z})}\left(\omega_{\check{\mathcal{C}}}\right)
$$

Proof. Denote by $N_{e}=N_{e}(\mathcal{C})$ the number of $0 \leq k \leq n-1$, so that $e=e_{k}$, where $e_{k} \in C$, for some $C \in \mathcal{C}$ of length $n=n(C)$. We denote similarly $\check{N}=\check{N}(\mathcal{C})$ the corresponding counting function for the collection of reversed cycles. Clearly, $N_{e}=\check{N}_{\check{e}}$.

A direct computation gives

$$
\begin{equation*}
\mathbb{E}^{(\alpha, Z)}\left(\omega_{\mathcal{C}}\right)=Z_{\mathcal{C}} \prod_{x \in V} \frac{\Phi_{x}(\alpha+N, Z)}{\Phi_{x}(\alpha, Z)}=Z_{\mathcal{C}} \frac{F(\alpha+N, Z)}{F(\alpha, Z)} \tag{3.9}
\end{equation*}
$$

Indeed, from the definition of the environment $\omega$, see (2.3), we have

$$
\omega_{\mathcal{C}}=Z_{\mathcal{C}} \prod_{x \in V}\left(\prod_{e^{\prime}, e^{\prime}=x} U_{e^{\prime}}^{N_{e^{\prime}}}\right)\left(\prod_{e, \bar{e}=x}\left(\sum_{\underline{e}^{\prime \prime}=x} Z_{e, e^{\prime \prime}} U_{e^{\prime \prime}}\right)^{-N_{e}}\right)
$$

the term $Z_{\mathcal{C}}$ coming from the term $Z_{e^{\prime}, e}$ in (2.3), the second term coming from the times when the cycle enters $e^{\prime}$, the last term coming from the times when the cycle leaves $e$. Combined, with the definitions (1.1), (2.1), (2.2), (3.2), it gives (3.9).

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Next, since $\operatorname{div}(\alpha)=0$, the Duality formula Lemma 3.1 says that for all $x \in V$,
$\Phi_{x}(\alpha, Z)=\Phi\left(\left(\alpha_{e}\right)_{\underline{e}=x},\left(\alpha_{e}\right)_{\bar{e}=x}, Z\right)=\frac{B\left(\left(\alpha_{e}\right)_{\underline{e}=x}\right)}{B\left(\left(\alpha_{e}\right)_{\bar{e}=x)}\right.} \Phi\left(\left(\alpha_{e}\right)_{\bar{e}=x},\left(\alpha_{e}\right)_{\underline{e}=x}, Z^{t}\right)=\frac{B\left(\left(\alpha_{e}\right)_{\underline{e}=x}\right)}{B\left(\left(\alpha_{e}\right)_{\bar{e}=x}\right)} \Phi_{x}(\check{\alpha}, \check{Z})$.
It implies that,

$$
F(\alpha, Z)=\frac{G(\alpha)}{G(\check{\alpha})} F(\check{\alpha}, \check{Z})
$$

where,

$$
G(\alpha):=\prod_{x \in V} B\left(\left(\alpha_{e}\right)_{\underline{e}=x}\right)
$$

Since $\operatorname{div}(\alpha)=0$, we have for all $x \in V, \sum_{\underline{e}=x} \alpha_{e}=\sum_{\bar{e}=x} \alpha_{e}$. Therefore,

$$
G(\alpha)=\prod_{x \in V} \frac{\prod_{\underline{e}=x} \Gamma\left(\alpha_{e}\right)}{\Gamma\left(\sum_{\underline{e}=x} \alpha_{e}\right)}=\frac{\prod_{e \in E} \Gamma\left(\alpha_{e}\right)}{\prod_{x \in V} \Gamma\left(\sum_{\underline{e}=x} \alpha_{e}\right)}=\frac{\prod_{e \in E} \Gamma\left(\alpha_{e}\right)}{\prod_{x \in V} \Gamma\left(\sum_{\bar{e}=x} \alpha_{e}\right)}=\prod_{x \in V} \frac{\prod_{\bar{e}=x} \Gamma\left(\alpha_{e}\right)}{\Gamma\left(\sum_{\bar{e}=x} \alpha_{e}\right)}=G(\check{\alpha}),
$$

where in the last equality we used the fact that $\check{\alpha}_{\check{e}}=\alpha_{e}$. Hence, $F(\alpha, Z)=F(\check{\alpha}, \check{Z})$.
Since $\mathcal{C}$ is a collection of cycles, it implies that $\operatorname{div}(N)=0$, the same applies for $\alpha+N$ and we get $F(\alpha+N, Z)=F(\check{\alpha}+\check{N}, \check{Z})$. From (3.9) and since $Z_{\mathcal{C}}=\check{Z}_{\check{\mathcal{C}}}$, we deduce

$$
\mathbb{E}^{(\alpha, Z)}\left(\check{\omega}_{\check{\mathcal{C}}}\right)=\mathbb{E}^{(\alpha, Z)}\left(\omega_{\mathcal{C}}\right)=Z_{\mathcal{C}} \frac{F(\alpha+N, Z)}{F(\alpha, Z)}=\check{Z}_{\check{\mathcal{C}}} \frac{F(\check{\alpha}+\check{N}, \check{Z})}{F(\check{\alpha}, \check{Z})}=\mathbb{E}^{(\check{\alpha}, \check{Z})}\left(\omega_{\check{\mathcal{C}}}\right)
$$

Corollary 3.3. Let $\omega \sim \mathbb{P}^{(\alpha, Z)}$. The time-reversing function $\omega \mapsto \check{\omega}$, where $\check{\omega}$ is defined as in (3.7), defines a new law $P$ on $\Omega_{\check{K}}$. Then, if $\operatorname{div}(\alpha)=0$,

$$
P=\mathbb{P}^{(\check{\alpha}, \check{Z})}
$$

Proof. Since $\omega\left(e, e^{\prime}\right)$ and $\pi^{\omega}(e)$ are positive and bounded by 1 , and $E$ and $K$ are finite, the law of $P$ is determined by its moments. That is, it's enough (and actually equivalent) to show that for any $\eta: \check{K} \rightarrow \mathbb{Z}_{+} \mathbb{E}^{(\alpha, Z)}\left[\check{\omega}^{\eta}\right]=\mathbb{E}^{(\check{\alpha}, \check{Z})}\left[\omega^{\eta}\right]$. Note that since the graph is finite and all $\omega\left(e, e^{\prime}\right) \in(0,1)$, under the quenched law the Markov chain and its time reversal are both recurrent. But now notice that the law of the recurrent Markov chain $\check{\omega}$ is determined by the law of its cycles. Indeed, for all $\left(e, e^{\prime}\right) \in K, \check{\omega}\left(\check{e}^{\prime}, \check{e}\right)=\sum_{C \in \mathcal{C}_{e, e^{\prime}}} \check{\omega}_{\breve{C}}$, where $\mathcal{C}_{e, e^{\prime}}$ is the family of all cycles $C$ starting at $e$, going immediately to $e^{\prime}$ and returning to $e$ for the first time. It clearly implies that if $\eta=\left(\eta_{e, e^{\prime}}\right)_{\left(e, e^{\prime}\right) \in \check{K}}$ is a positive vector, then $\check{\omega}^{\eta}$ can be written as a sum with positive coefficients of terms of the type $\check{\omega}_{\check{\mathcal{C}}}$, where $\mathcal{C}$ are finite collections of cycles. Using Lemma 3.2, it implies that

$$
\mathbb{E}^{(\alpha, Z)}\left(\check{\omega}^{\eta}\right)=\mathbb{E}^{(\check{\alpha}, \check{Z})}\left(\omega^{\eta}\right)
$$

We finish with an application from the proof of the last corollary. Set $H_{e}:=\inf \{n \geq$ $\left.0, \quad X_{n}=e\right\}$ and $H_{e_{0}}^{+}:=\inf \left\{n>0, \quad X_{n}=e_{0}\right\}$.
Corollary 3.4. For every $\left(e, e_{0}\right) \in K$, for $\omega \in K$,

$$
P_{e_{0}, \omega}\left[X_{H_{e_{0}}^{+-1}}=e\right]=P_{\check{e}_{0}, \check{\omega}}\left[X_{1}=\check{e}\right] .
$$

Proof. As in the last corollary, it follows from the fact that the weights are strictly positive $\mathbb{P}^{(\alpha, Z)}$-a.s., that the Markov chains on the finite graphs $\mathcal{H}, \mathscr{\mathcal { H }}$ are recurrent. Hence the probability $P_{\check{e}_{0}, \check{\omega}}\left[X_{1}=\check{e}\right]$ equals to the sum of the $\check{\omega}$ weight over of all cycles $\left\{\tilde{e}_{1}, \ldots, \tilde{e}_{n}\right\}$ with $\tilde{e}_{1}=\tilde{e}_{n}=\check{e}_{0}$ but $\tilde{e}_{i} \neq \check{e}_{0}$ for $1<i<n$, and $\tilde{e}_{2}=\check{e}$. To end one notices that the sum of $\omega$ weight over the reversed cycles gives exactly $P_{e_{0}, \omega}\left[X_{H_{e_{0}-1}^{+}}=e\right]$, and by Lemma 3.2 these probabilities are equal.

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### 3.4 Arc graph identities

We now use the same notation for the divergence operator on $\mathcal{G}$ also for the arc graph $\mathcal{H}$. div : $\mathbb{R}^{K} \rightarrow \mathbb{R}^{E}$ is defined by

$$
\begin{equation*}
\operatorname{div}(\Theta)(e)=\sum_{e^{\prime}:\left(e, e^{\prime}\right) \in K} \Theta\left(e, e^{\prime}\right)-\sum_{e^{\prime}:\left(e^{\prime}, e\right) \in K} \Theta\left(e^{\prime}, e\right), \tag{3.10}
\end{equation*}
$$

for $\Theta: K \rightarrow \mathbb{R}$ and $e \in E$. We also denote by $\check{\Theta}: \check{K} \rightarrow \mathbb{R}_{+}$the function so that $\Theta\left(\left(\breve{e}^{\prime}, \check{e}\right)\right)=\Theta\left(\left(e, e^{\prime}\right)\right)$. With a minor abuse of notation the divergent is analogous defined as div: $\mathbb{R}^{\check{K}} \rightarrow \mathbb{R}^{\check{E}}$. This gives

$$
\begin{equation*}
\operatorname{div}(\Theta)(e)=-\operatorname{div}(\check{\Theta})(\check{e}) \tag{3.11}
\end{equation*}
$$

for every $\Theta: K \rightarrow \mathbb{R}_{+}$and $e \in E$.
Lemma 3.5. The following formula holds for every $\omega \in \Omega_{K}$ and $\Theta: K \rightarrow \mathbb{R}_{+}$:

$$
\frac{\check{\omega}^{\check{ }}}{\omega^{\Theta}}=\left(\pi^{\omega}\right)^{\operatorname{div} \Theta}
$$

Proof. Indeed,

$$
\begin{aligned}
\frac{\check{\omega}^{\check{\Theta}}}{\omega^{\Theta}} & =\frac{\prod_{\left(e, e^{\prime}, \check{e}\right) \in \check{K}} \check{\omega}\left(\check{e}^{\prime}, \check{e}\right)^{\check{\Theta}\left(\check{e}^{\prime}, \check{e}\right)}}{\prod_{\left(e, e^{\prime}\right) \in K} \omega\left(e, e^{\prime}\right)^{\Theta\left(e, e^{\prime}\right)}} \\
& =\prod_{\left(e, e^{\prime}\right) \in K} \frac{\check{\omega}\left(\check{e}^{\prime}, \check{e}\right)^{\check{\Theta}\left(\check{e}^{\prime}, \check{e}\right)}}{\omega\left(e, e^{\prime}\right)^{\Theta\left(e, e^{\prime}\right)}} \\
& =\prod_{\left(e, e^{\prime}\right) \in K} \frac{\left(\pi^{\omega}(e) \omega\left(e, e^{\prime}\right) \pi^{\omega}\left(e^{\prime}\right)^{-1}\right)^{\Theta\left(e, e^{\prime}\right)}}{\omega\left(e, e^{\prime}\right)^{\Theta\left(e, e^{\prime}\right)}} \\
& =\prod_{e \in E} \pi^{\omega}(e)^{\left(\sum_{e^{\prime}:\left(e, e^{\prime}\right) \in K} \Theta\left(e, e^{\prime}\right)-\sum_{e^{\prime}:\left(e^{\prime}, e\right) \in K} \Theta\left(e^{\prime}, e\right)\right)} \\
& =\left(\pi^{\omega}\right)^{\operatorname{div} \Theta} \cdot \square
\end{aligned}
$$

### 3.5 Flows

## Flow identity

For $e_{0}, e \in E$ and $\gamma>0$, a flow from $e_{0}$ to $e$ of strength $\gamma$, is a function $\Theta: K \rightarrow \mathbb{R}_{+}$such that

$$
\operatorname{div}(\Theta)=\gamma\left(\delta_{e_{0}}-\delta_{e}\right)
$$

$\Theta: K \rightarrow \mathbb{R}_{+}$is a total flow from $e_{0}$ of strength $\gamma$ if it has the form

$$
\operatorname{div}(\Theta)=\gamma \sum_{e \in E}\left(\delta_{e_{0}}-\delta_{e}\right)
$$

Lemma 3.6. If $\Theta: K \rightarrow \mathbb{R}_{+}$is a total flow from $e_{0}$ of strength $\gamma$, then

$$
\left(\pi^{\omega}\right)^{\operatorname{div}(\Theta)}=\prod_{e \in E}\left(\frac{\pi^{\omega}\left(e_{0}\right)}{\pi^{\omega}(e)}\right)^{\gamma}
$$

Proof. First note that

$$
\gamma \sum_{e^{\prime} \in E}\left(\delta_{e_{0}}-\delta_{e^{\prime}}\right)(e)=\gamma \begin{cases}(|E|-1) & \text { if } e=e_{0} \\ -1 & \text { if } e \neq e_{0}\end{cases}
$$

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Hence,

$$
\begin{aligned}
\left(\pi^{\omega}\right)^{\operatorname{div}(\Theta)} & =\prod_{e \in E} \pi^{\omega}(e)^{\operatorname{div}(\Theta)(e)} \\
& =\prod_{e \in E} \pi^{\omega}(e)^{\gamma \sum_{e^{\prime} \in E}\left(\delta_{e_{0}}-\delta_{e^{\prime}}\right)(e)} \\
& =\pi^{\omega}\left(e_{0}\right)^{\gamma|E|} \prod_{e \in E} \pi^{\omega}(e)^{-\gamma} \\
& =\prod_{e \in E}\left(\frac{\pi^{\omega}\left(e_{0}\right)}{\pi^{\omega}(e)}\right)^{\gamma} \cdot \square
\end{aligned}
$$

## Construction of good flows

Consider first the lattice $\mathcal{G}_{\mathbb{Z}^{d}}=\left(\mathbb{Z}^{d}, E_{\mathbb{Z}^{d}}\right)$ (see Section 1.2). Let $(c(e))_{e \in E}$ be a set of positive weights on the edges, called capacities. A finite subset $S \subset E$ is called a cutset separating 0 from infinity if any infinite simple directed path starting at 0 crosses at least one directed edge of $S$ (simple means that the path never visits the same vertex twice). The mincut of the graph $\mathcal{G}_{\mathbb{Z}^{d}}$ with capacities $(c(e))$ is the value

$$
m(c)=\inf \left\{\sum_{e \in S} c(e): S \text { is a cutset }\right\} .
$$

Let $T_{N}=\left(V_{N}, E_{N}\right)$ be the $N$-torus graph in $d$ dimensions, that is the associated directed graph image of $\mathbb{Z}^{d}$ by projection on $(\mathbb{Z} / N \mathbb{Z})^{d}$. We identify the edge set $E_{N}$ with the edges $e$ of $E_{\mathbb{Z}^{d}}$ such that $\underline{e} \in[-N / 2, N / 2)^{d}$. Let $\mathcal{H}=\mathcal{H}_{N}=\left(E_{N}, K_{N}\right)$ be the corresponding arc graph. The following lemma supplies a total flow on the arc graph with good properties, and is a consequence of the max-flow min-cut theorem together with the transience of $\mathbb{Z}^{d}, d \geq 3$.
Lemma 3.7 (Min-cut total flow on $\mathcal{H}$ ). Let $d \geq 3$. Assume that $(c(e))_{e \in E_{\mathbb{Z}^{d}}}$ is uniformly bounded, i.e. there exist some constants $0<C_{1}<C_{2}<\infty$ such that $C_{1} \leq c(e) \leq C_{2}$ for all edge $e$. Fix $e_{0}$ to be an edge with $\bar{e}_{0}=0$. There is a constant $c_{2}$ so that for every large enough $N$ there is a non-negative function $\Theta=\Theta_{N}$ on $K_{N}$ with the following properties:

1. $\bar{\Theta}_{e} \leq c(e)+m(c) \mathbb{1}_{e=e_{0}}$ (almost below the capacity).
2. $\sum_{\left(e, e^{\prime}\right) \in K_{N}} \Theta\left(e, e^{\prime}\right)^{2}<c_{2}$ (bounded $L_{2}$ norm).
3. $\operatorname{div}(\Theta)=\frac{m(c)}{d N^{d}} \sum_{\tilde{e} \in E_{N}}\left(\delta_{e_{0}}-\delta_{\tilde{e}}\right)$ (total flow from $e_{0}$ ).
where $m(c)$ is the min cut of the network $c$.
For the proof we shall use the analogous
Lemma 3.8. [Sab13, Lemma 2] Let $d \geq 3$. Assume that $(c(e))_{e \in E_{\mathbb{Z}^{d}}}$ is uniformly bounded, i.e. there exist some constants $0<C_{1}<C_{2}<\infty$ such that $C_{1} \leq c(e) \leq C_{2}$ for all edge $e$. There is a constant $c_{1}$ so that for every large enough $N$ there is a non-negative function $\theta=\theta_{N}$ on $E_{N}$ with the following properties:
4. $\theta(e) \leq c(e)$ (below the capacity).
5. $\sum_{e \in E_{N}} \theta(e)^{2}<c_{1}$ (bounded $L_{2}$ norm).
6. $\operatorname{div}(\theta)(y)=\bar{\theta}_{y}-\underline{\theta}_{y}=\frac{m(c)}{N^{d}} \sum_{x \in V_{N}}\left(\delta_{0}-\delta_{x}\right)(y)$ (total flow from 0 ).
where $m(c)$ is the min cut of the network $c$.

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Proof of Lemma 3.7. Fix $N \geq 2$ and let $\theta$ be according to Lemma 3.8. Write simply $m=m(c)$. We define $\Theta=\Theta_{N}: K_{n} \rightarrow \mathbb{R}_{+}$by

$$
\begin{equation*}
\Theta\left(e, e^{\prime}\right)=\frac{\left(\theta(e)+m \mathbb{1}_{e=e_{0}}\right)\left(\theta\left(e^{\prime}\right)+\frac{m}{d N^{d}}\right)}{\bar{\theta}_{\bar{e}}+\frac{m}{N^{d}}}, \quad\left(e, e^{\prime}\right) \in K_{N} \tag{3.12}
\end{equation*}
$$

We claim that $\Theta$ satisfies the assertions of the lemma. First note that by property 1 of Lemma $3.8 \bar{\Theta}_{e}=\theta(e)+m \mathbb{1}_{e=e_{0}} \leq c(e)+m \mathbb{1}_{e=e_{0}}$. Next, by (3.12), $\Theta\left(e, e^{\prime}\right) \leq \theta(e)+m \mathbb{1}_{e=e_{0}}$. Therefore, by property 2 of Lemma 3.8

$$
\left.\sum_{\left(e, e^{\prime}\right) \in K_{N}} \Theta\left(e, e^{\prime}\right)^{2} \leq \sum_{e \in E_{N}} 2 d\left(\theta(e)+m \mathbb{1}_{e=e_{0}}\right)^{2}<2 d c_{1}+\left(c\left(e_{0}\right)+m\right)^{2}\right)=: c_{2}
$$

To end, by property 3 ) in Lemma 3.8 we have

$$
\begin{aligned}
\underline{\Theta}_{e^{\prime}} & =\left(\theta\left(e^{\prime}\right)+\frac{m}{d N^{d}}\right) \sum_{e: e \rightarrow e^{\prime}} \frac{\theta(e)+m \mathbb{1}_{e=e_{0}}}{\underline{\theta_{\theta^{\prime}}}+\frac{m}{d N^{d}}} \\
& =\left(\theta\left(e^{\prime}\right)+\frac{m}{d N^{d}}\right) \frac{\underline{\theta_{e^{\prime}}}+m \mathbb{1}_{\underline{e^{\prime}}=0}}{\overline{\theta_{e^{\prime}}}+\frac{m}{d N^{d}}} \\
& =\theta\left(e^{\prime}\right)+\frac{m}{d N^{d}} .
\end{aligned}
$$

Hence, $\operatorname{div}(\Theta)=m \mathbb{1}_{e=e_{0}}-\frac{m}{d N^{d}}=\frac{m}{d N^{d}} \sum_{\tilde{e} \in E_{N}}\left(\delta_{e_{0}}-\delta_{\tilde{e}}\right)$.

## 4 The Green function has a positive moment

In this section we prove Theorem 1.1. The proof follows closely the ones in [Sab11] and in [ST17, Section 7.2.]. Fix $e_{0}$ of the form $e_{0}=\left(x_{0}, 0\right)$. Let $N \in \mathbb{N}$ and define $G_{N}$ to be the graph with vertices $V_{N}=B(0, N) \cup\{\partial\}$, where $\partial$ is an additional vertex and $B(0, N)$ denotes a box in $\mathbb{Z}^{d}$ with side length $N$ around the origin, and edges $\hat{E}_{N}=E_{N} \cup\left\{\left(\partial, x_{0}\right)\right\}$, i.e. of the following types. The edges set $E_{N}$ is the set of directed edges between neighboring vertices inside $B(0, N)$ (as in $\mathbb{Z}^{d}$ ) and between the vertices in the inner boundary of $B(0, N)$ and $\partial$. (I.e., we identify all vertices on the boundary of $B(0, N)$ with the special vertex $\partial$.) We also add to $E_{N}$ one special edge ( $\partial, x_{0}$ ). Denote by $\mathcal{H}_{N}=\left(\hat{E}_{N}, K_{N}\right)$ the corresponding arc graph.
The weights $\alpha$ and $Z$ on $\mathbb{Z}^{d}$ naturally yield weights on $E_{N}$. We endow the special edge $\left(\partial, x_{0}\right)$ with weight $\alpha_{\left(\partial, x_{0}\right)}=\gamma$, for some $\gamma>0$ that will be defined later on, and set $Z_{e, e^{\prime}}=1$ whenever $\bar{e}=\partial$. Set also $Z_{\left(\left(\partial, x_{0}\right), e_{0}\right)}=1$. With this choice we note that on $\hat{E}_{N}$

$$
\operatorname{div}(\alpha)=\gamma\left(\delta_{\partial}-\delta_{0}\right)
$$

Consider now a unit flow $\theta: E_{N} \rightarrow \mathbb{R}_{+}$from 0 to $\partial$ (i.e. $\operatorname{div}(\theta)(e)=\delta_{0}-\delta_{\partial}$ ) and assume that $0 \leq \theta \leq 1$. Extend $\theta$ by 0 on the special edge ( $\partial, x_{0}$ ). We consider $\alpha+\gamma \theta$. These weights give a flow with null divergence on $\hat{E}_{N}$.
Set $H_{\left(\partial, x_{0}\right)}:=\inf \left\{n \geq 0, \quad X_{n}=\left(\partial, x_{0}\right)\right\}$ and $H_{e_{0}}^{+}:=\inf \left\{n>0, \quad X_{n}=e_{0}\right\}$. We can now apply Corollary 3.4 on $G_{N}$ to get that under the law $\mathbb{P}^{(\alpha+\gamma \theta, Z)}$

$$
\begin{aligned}
P_{e_{0}, \omega}\left[H_{\left(\partial, x_{0}\right)}<H_{e_{0}}^{+}\right] & \geq P_{e_{0}, \omega}\left[X_{H_{e_{0}}^{+}-1}=\left(\partial, x_{0}\right)\right] \\
& =P_{\check{e}_{0}, \check{\omega}}\left[X_{1}=\left(x_{0}, \partial\right)\right] .
\end{aligned}
$$

Hence, using (3.1), we have for $\epsilon>0$

$$
\begin{aligned}
\mathbb{E}^{(\alpha+\gamma \theta, Z)}\left[\left(P_{e_{0}, \omega}\left[H_{\left(\partial, x_{0}\right)}<H_{e_{0}}^{+}\right]\right)^{-\epsilon}\right] & \leq \mathbb{E}^{(\alpha+\gamma \theta, Z)}\left[\left(\check{\omega}\left(\check{e}_{0},\left(x_{0}, \partial\right)\right)\right)^{-\epsilon}\right] \\
& =\mathbb{E}^{(\check{\alpha}+\gamma \check{\theta}, \check{Z})}\left[\left(\omega\left(\check{e}_{0},\left(x_{0}, \partial\right)\right)\right)^{-\epsilon}\right] \\
& =\check{Z}_{\left(\check{e}_{0},\left(x_{0}, \partial\right)\right)}^{-\epsilon} \frac{\Phi_{x_{0}}\left(\check{\alpha}+\gamma \check{\theta}-\epsilon\left(\delta_{\check{e}_{0}}+\delta_{\left(x_{0}, \partial\right)}\right), \check{Z}\right)}{\Phi_{x_{0}}(\check{\alpha}, \check{Z})} \\
& =\frac{\Phi_{x_{0}}\left(\check{\alpha}+\gamma \check{\theta}-\epsilon\left(\delta_{\check{e}_{0}}+\delta_{\left(x_{0}, \partial\right)}\right), \check{Z}\right)}{\Phi_{x_{0}}(\check{\alpha}, \check{Z})}
\end{aligned}
$$

Now, as mentioned below (3.1)

$$
\begin{equation*}
\mathbb{E}^{(\alpha+\gamma \theta, Z)}\left[\left(P_{e_{0}, \omega}\left[H_{\left(\partial, x_{0}\right)}<H_{e_{0}}^{+}\right]\right)^{-\epsilon}\right] \leq C<\infty \tag{4.1}
\end{equation*}
$$

whenever $\epsilon<\min \left\{\alpha_{e_{0}}+\gamma \theta_{e_{0}}, \alpha_{\left(\partial, x_{0}\right)}+\gamma \theta_{\left(\partial, x_{0}\right)}\right\}$. In particular, the $-\epsilon$ moment is bounded by $C$ independently of $N$ as long as $\theta_{e_{0}} \leq 1$ and $0<\epsilon<\gamma \theta_{e_{0}}$. Now consider the Green function $G_{\omega}^{N}\left(e_{0}, e_{0}\right)$ of the quenched Markov chain in environment $\omega$, killed at the exit time of $B(0, N)$. We have

$$
G_{\omega}^{N}\left(e_{0}, e_{0}\right) \leq 1 / P_{e_{0}, \omega}\left[H_{\left(\partial, x_{0}\right)}<H_{e_{0}}^{+}\right] .
$$

Indeed, by the Markov property and irreducibility the right hand side equals the Green function at $\left(e_{0}, e_{0}\right)$ of the walk killed at the hitting time of the edge $\left(\partial, x_{0}\right)$. But the latter can be reached only via exiting $B(0, N)$ and so the inequality holds by coupling. Next, we use the Radon-Nikodym derivative (3.5) and apply Hölder inequality with $r, q>0$ such that $\frac{1}{q}+\frac{1}{r}=1$ :

$$
\begin{aligned}
\mathbb{E}^{(\alpha, Z)}\left[G_{\omega}^{N}(0,0)^{s}\right] & \leq \mathbb{E}^{(\alpha, Z)}\left[\left(P_{e_{0}, \omega}\left[H_{\left(\partial, x_{0}\right)}<H_{e_{0}}^{+}\right]\right)^{-s}\right] \\
& =\frac{F(\alpha+\gamma \theta, Z)}{F(\alpha, Z)} \mathbb{E}^{(\alpha+\gamma \theta, Z)}\left[\tilde{u}^{-\gamma \theta}\left(P_{e_{0}, \omega}\left[H_{\left(\partial, x_{0}\right)}<H_{e_{0}}^{+}\right]\right)^{-s}\right] \\
& \leq \frac{F(\alpha+\gamma \theta, Z)}{F(\alpha, Z)} \mathbb{E}^{(\alpha+\gamma \theta, Z)}\left[\tilde{u}^{-\gamma q \theta}\right]^{1 / q} \mathbb{E}^{(\alpha+\gamma \theta, Z)}\left[\left(P_{e_{0}, \omega}\left[H_{\left(\partial, x_{0}\right)}<H_{e_{0}}^{+}\right]\right)^{-r s}\right]^{1 / r} \\
& =\frac{F(\alpha+\gamma \theta, Z)^{1-\frac{1}{q}} F(\alpha+(1-q) \gamma \theta, Z)^{\frac{1}{q}}}{F(\alpha, Z)} \mathbb{E}^{(\alpha+\gamma \theta, Z)}\left[\left(P_{e_{0}, \omega}\left[H_{\left(\partial, x_{0}\right)}<H_{e_{0}}^{+}\right]\right)^{-r s}\right]^{1 / r} \\
& =\frac{F(\alpha+\gamma \theta, Z)^{\frac{1}{r}} F\left(\alpha+\frac{1}{1-r} \gamma \theta, Z\right)^{1-\frac{1}{r}}}{F(\alpha, Z)} \mathbb{E}^{(\alpha+\gamma \theta, Z)}\left[\left(P_{e_{0}, \omega}\left[H_{\left(\partial, x_{0}\right)}<H_{e_{0}}^{+}\right]\right)^{-r s}\right]^{1 / r} .
\end{aligned}
$$

To guarantee the right part of the product is bounded by some $C<\infty$ we need to choose $r$ and $\gamma$ so that $r s \leq \gamma \theta_{e_{0}}$, see (4.1). $F\left(\alpha+\frac{1}{1-r} \gamma \theta, Z\right)$ is finite if and only if

$$
\begin{equation*}
\gamma \frac{1}{r-1} \theta(e)<\alpha_{e}, \quad \forall e \in E_{N} \tag{4.2}
\end{equation*}
$$

Since $\theta \leq 1$, we can take $\gamma \frac{1}{r-1}<\tilde{\kappa}$ which means $r>\tilde{\kappa}+\frac{\gamma}{\tilde{\kappa}}$. With such a choice of $r$ we can take

$$
\begin{equation*}
s<\frac{\gamma \tilde{\kappa}}{\tilde{\kappa}+\gamma} . \tag{4.3}
\end{equation*}
$$

Next

$$
\frac{F(\alpha+\gamma \theta, Z)^{\frac{1}{r}} F\left(\alpha+\frac{1}{1-r} \gamma \theta, Z\right)^{1-\frac{1}{r}}}{F(\alpha, Z)}=\exp \left(\sum_{x \in V_{N}} \nu\left(\left(\alpha^{x}, \alpha_{x}\right),\left(\gamma \theta_{x}, \gamma \theta^{x}\right), Z_{x}\right)\right),
$$

where
$\nu((\alpha, \beta),(s, t), Z)=\frac{1}{r} \log \Phi(\alpha+s, \beta+t, Z)+\left(1-\frac{1}{r}\right) \log \Phi\left(\alpha+\frac{1}{1-r} s, \beta+\frac{1}{1-r} t, Z\right)-\log \Phi(\alpha, \beta, Z)$,
and $\theta_{x}=\sum_{e: \bar{e}=x}, \theta^{x}=\sum_{e: \underline{e}=x}$, and the corresponding notation for $\alpha$. (For the dimensions of the domain of $\nu$ the reader would notice that here it is evaluated in $((\alpha, \beta),(s, t), Z))=$ $\left.\left(\alpha^{x}, \alpha_{x}\right),\left(\gamma \theta_{x}, \gamma \theta^{x}\right), Z_{x}\right)$.) In our case, $\left(\alpha^{x}, \alpha_{x}, Z_{x}\right)=\left(\alpha^{0}, \alpha_{0}, Z_{0}\right)$ and so that $\left\{\alpha_{e}, Z_{e, e^{\prime}}\right.$ : $0 \in \underline{e}, \bar{e}\} \subset(a, b)$ for some $0<a<b<\infty$. Note that $\nu((\alpha, \beta),(s, t), Z)$ is $C^{2}$ on every compact subset contained in its domain. Moreover, we have $\nu(0)$ and $\frac{\mathrm{d}}{\mathrm{d} s_{i}} \nu=\frac{\mathrm{d}}{\mathrm{d} t_{j}} \nu=0$ in $(s, t)=(0,0)$. Therefore, there are $\epsilon, C_{r}>0$, depending only on $a, b$ such that $|\nu((\alpha, \beta),(s, t), Z)| \leq C_{r} t^{2}$ for all $-\epsilon<s, t \leq 2 d$. We got that

$$
\mathbb{E}^{(\alpha, Z)}\left[G_{\omega}^{N}(0,0)^{s}\right] \leq C \cdot \exp \left(C_{r}\|\theta\|^{2}\right)
$$

Take a unit flow $\theta$ on $E_{N}$ from 0 to $\partial$, such that $0 \leq \theta \leq 1, \theta_{e_{0}}>0$, and

$$
\sum_{e \in E_{N}} \theta_{e}^{2}=R_{N}
$$

where $R_{N}$ is the electrical resistance between 0 and $B(0, N)^{c}$ for the network $\mathbb{Z}^{d}$ with unit resistance on the bonds (see e.g. [ST17]). In dimension $d \geq 3$, we know that $\sup _{N} R_{N}=R(0, \infty)=: \tilde{C}<+\infty$ where $R(0, \infty)$ is the electrical resistance between 0 and $\infty$ for unit resistances on bonds. To sum up, we got

$$
\mathbb{E}^{(\alpha, Z)}\left[G_{\omega}^{N}(0,0)^{s}\right] \leq C \cdot \exp \left(C_{r} \tilde{C}^{2}\right),
$$

for every $s$ satisfying (4.3). Taking $\gamma$ arbitrarily large we can take $s$ up to $\tilde{\kappa}$, which completes the proof.

## 5 Proof of the invariant measure criterion

Proving Theorem 1.4 part 2 is done by following [Sab13][Chapter 5] where in the Proof of Theorem 1(II) there, for transience one uses our Theorem 1.1, and in the last paragraph there, instead of the cited Theorem 3 there, one uses our Lemma 1.5.

Part 1 of Theorem 1.4 is more involved. The strategy of the proof is to consider the Radon-Nikodym derivatives $f_{N}$ of the invariant probability measure for the process from the point of view of the walker defined on the edges the $N$-torus. Then, showing that if $p \in[1, \kappa)$ then the $L^{p}$ norm of $f_{N}$ with respect to the initial measure on the $N$-torus is uniformly bounded. This is the content of Lemma 5.1 below, where its proof is the main ingredient of the proof. We shall first state the lemma, following the necessary preparations in Chapters 3.4 and 3.3.

For the $N$-torus $T_{N}$ in $d$ dimensions with arc graph $\left(E_{N}, K_{N}\right)$ we denote $\Omega_{N}:=\Omega_{K_{N}}$ the corresponding space of environments. It is naturally identified with the space of the $N$-periodic environments on $\mathbb{Z}^{d}$. We denote by $\mathbb{P}_{N}^{(\alpha, Z)}$ the hypergeometric probability measure on $\Omega_{N}$ defined by (2.3) with parameters $\alpha$ and $Z . \mathbb{E}_{N}^{(\alpha, Z)}$ is its associated expectation operator. As before, we need to extend the definition to $\mathbb{P}_{N}^{(\alpha, \Theta, Z)}$ and $\mathbb{E}_{N}^{(\alpha, \Theta, Z)}$ whenever $\Theta: K_{N} \rightarrow \mathbb{R}$ and the measure is well-defined.

For $\omega \in \Omega_{N}$ we denote by $\pi_{N}^{\omega}=\left(\pi_{N}^{\omega}(e)\right)_{e \in E_{N}}$ the invariant probability measure of the Markov chain on $E_{N}$ with transition probabilities $\omega$ (it is unique since the environments are a.s. elliptic: $\left.\omega\left(e, e^{\prime}\right)>0\right)$.

Fix an initial edge $e_{0} \in \mathbb{E}^{d}$ so that $\bar{e}_{0}=0$. For $N \geq 2$, define $f_{N}: \Omega_{N} \rightarrow \mathbb{R}_{+}$by

$$
\begin{equation*}
f_{N}(\omega)=2 d N^{d} \cdot \pi_{N}^{\omega}\left(e_{0}\right) \tag{5.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathbb{Q}_{N}^{(\alpha, Z)}=f_{N} \cdot \mathbb{P}_{N}^{(\alpha, Z)} \tag{5.2}
\end{equation*}
$$

Lemma 5.1. Let $d \geq 3$. Fix $p \in[1, \kappa)$. Then, $\sup _{N \in \mathbb{N}}\left\|f_{N}\right\|_{L_{p}\left(\mathbb{P}_{N}^{(\alpha, Z)}\right)}<\infty$.
Using the Lemma, the proof is standard (see the paragraph after Lemma 1 in Sabot [Sab13], including the references therein). For convenience we shall give a sketch here. Consider $\mathbb{Q}_{N}^{(\alpha, Z)}$ and $\mathbb{P}_{N}^{(\alpha, Z)}$ as measures on $N$-periodic environments. Then, as a product measure over vertices (the matrices $\left(\omega\left(e, e^{\prime}\right)_{\left(\bar{e}=x=e^{\prime}\right)}, x \in V\right.$, are i.i.d.) $\mathbb{P}_{N}^{(\alpha, Z)}$ converges weakly to the probability measure $\mathbb{P}^{(\alpha, Z)}$. From the definition of $\pi_{N}^{\omega}\left(e_{0}\right)$ it holds that $\mathbb{Q}_{N}^{(\alpha, Z)}$ is invariant for the process viewed from the walker on $\Omega$. Since $\Omega$ is compact, then so does the space of product probability measures, and there is an increasing sequence of positive integers and a probability measure so that $\mathbb{Q}_{N_{k}}^{(\alpha, Z)} \rightarrow \mathbb{Q}^{(\alpha, Z)}$. Since the generator is weakly Feller (i.e. continuous with respect to the weak topology), it follows that the weak limit probability measure $\mathbb{Q}^{(\alpha, Z)}$ is invariant for the process viewed from the point of view of the walker on $\Omega$. For every continuous bounded function $g$ on $\Omega$, and every $1<p<\kappa$ we have

$$
\int g \mathrm{~d} \mathbb{Q}^{(\alpha, Z)} \leq c_{p}\|g\|_{L_{q}\left(\mathbb{P}^{(\alpha, Z)}\right)}
$$

where $\frac{1}{p}+\frac{1}{q}=1$ (see equation (2.14) in [BS12]). The last inequality shows that $\mathbb{Q}^{(\alpha, Z)}$ is absolutely continuous with respect to $\mathbb{P}^{(\alpha, Z)}$, and for $f=\frac{\mathrm{dQ}^{(\alpha, Z)}}{\mathrm{d} \mathbb{P}^{(\alpha, Z)}}$ we have $\|f\|_{L_{p}\left(\mathbb{P}^{(\alpha, Z)}\right)} \leq c_{p}$.

## Uniformly bounding the Radon-Nikodym derivatives on the torus

In this section we prove Lemma 5.1. Let $p \in[1, \kappa)$. Combining Lemma 3.5 and Lemma 3.6, if $\Theta_{N}: K_{N} \rightarrow \mathbb{R}_{+}$is satisfying

$$
\begin{equation*}
\operatorname{div}(\Theta)=\frac{p}{d N^{d}} \sum_{\tilde{e} \in E_{N}}\left(\delta_{e_{0}}-\delta_{\tilde{e}}\right) \tag{5.3}
\end{equation*}
$$

then

$$
\begin{equation*}
f_{N}^{p}(\omega) \leq \frac{\check{\omega}^{\check{\Theta}_{N}}}{\omega^{\Theta_{N}}} \tag{5.4}
\end{equation*}
$$

Remember that the root edge $e_{0}$ was chosen such that $\bar{e}_{0}=0$. In the sequel we will often simply write $e_{i}$ for the directed edge $\left(0, e_{i}\right)$ (remember that $e_{1}, \ldots, e_{d}$ is the base of $\mathbb{R}^{d}$ ). Now, by Hölder inequality, $1 \leq(2 d)^{\kappa} \sum_{i=1}^{2 d} \omega_{i}^{\kappa}$ where $\omega_{i}:=\omega\left(e_{0}, e_{i}\right)$. Therefore,

$$
\mathbb{E}^{(\alpha, Z)}\left[f_{N}^{p}\right] \leq(2 d)^{\kappa} \sum_{i=1}^{2 d} \mathbb{E}^{(\alpha, Z)}\left[\omega_{i}^{\kappa} f_{N}^{p}\right]
$$

Hence, from (5.4), Lemma 5.1 follows once we show that for every $1 \leq i \leq 2 d$ and $N \in \mathbb{N}$ there is $\Theta_{N}: K_{N} \rightarrow \mathbb{R}_{+}$satisfying (5.3), so that

$$
\begin{equation*}
\sup _{N \in \mathbb{N}} \mathbb{E}^{(\alpha, Z)}\left[\check{\omega}^{\check{\Theta}_{N}} \omega_{i}^{\kappa} \omega^{-\Theta_{N}}\right]<\infty \tag{5.5}
\end{equation*}
$$

We shall now prove (5.5). Let $\alpha^{(i)}, 1 \leq i \leq 2 d$, be the weights defined by $\alpha^{(i)}:=\alpha+\kappa \mathbb{1}_{e=e_{i}}$. I.e. $\alpha^{(i)}$ gives $\alpha$ an extra $\kappa$ on the specific edge $e_{i}$ but leaves it unchanged on all other edges. Then,

$$
\begin{equation*}
m\left(\alpha^{(i)}\right) \geq \kappa \tag{5.6}
\end{equation*}
$$

where $m(c)$ is the min cut of the network $(c(e))_{e \in \mathbb{E}\left(\mathbb{Z}^{d}\right)}$ on $\mathbb{Z}^{d}$ (that is, the minimal $c$-weight of a set separating 0 from $\infty$ ), see equation (3.10) and the paragraph below it in [Sab13]
for the proof. We shall now show (5.5) for the case $i=1$. The other $2 d-1$ possibilities are symmetric. Fix $N \geq 1$, and apply Lemma 3.7 with $c(e)=\alpha^{(1)}(e)$ to get $\tilde{\Theta}=\tilde{\Theta}_{N}$ with bounded $L_{2}$ norm, almost below the capacity

$$
\begin{equation*}
\tilde{\Theta}_{e} \leq \alpha^{(1)}(e)+m\left(\alpha^{(1)}\right) \mathbb{1}_{e=e_{0}} \tag{5.7}
\end{equation*}
$$

so that it is a total flow from $e_{0}$ with strength $\frac{m\left(\alpha^{(1)}\right)}{d N^{d}}$. Set

$$
\begin{equation*}
\Theta=\Theta_{N}:=\frac{p}{m\left(\alpha^{(1)}\right)} \tilde{\Theta} \tag{5.8}
\end{equation*}
$$

Then $\Theta$ is also total flow from $e_{0}$ with a bounded $L_{2}$ norm and with strength $\frac{p}{d N^{d}}$.
Remember the notation $\beta^{\gamma}$ from (3.3). Fix $q=q(\alpha, d)>0$ to be chosen later-on. Let $r>0$ be so that $\frac{1}{r}+\frac{1}{q}=1$. Using Hölder inequality, the Weak Reversibility Corollary 3.3, we have

$$
\begin{aligned}
\mathbb{E}^{(\alpha, Z)}\left[\check{\omega}^{\check{\Theta}} \omega_{1}^{\kappa} \omega^{-\Theta}\right] & \leq \mathbb{E}^{(\alpha, Z)}\left[\check{\omega}^{r \check{\Theta}}\right]^{1 / r} \mathbb{E}^{(\alpha, Z)}\left[\omega_{1}^{q \kappa} \omega^{-q \Theta}\right]^{1 / q} \\
& =\mathbb{E}^{(\check{\alpha}, \check{Z})}\left[\omega^{r \check{\Theta}}\right]^{1 / r} \mathbb{E}^{(\alpha, Z)}\left[\omega_{1}^{q \kappa} \omega^{-q \Theta}\right]^{1 / q} .
\end{aligned}
$$

Assume for the moment that the functions $F$ and $G$ below are well defined. This will be justified by a suitable choice of $q$. Using (3.4) we get:

$$
\begin{aligned}
\mathbb{E}^{(\check{\alpha}, \check{Z})}\left[\omega^{r \check{\Theta}}\right]^{1 / r} \mathbb{E}^{(\alpha, Z)}\left[\omega_{1}^{q \kappa} \omega^{-q \Theta}\right]^{1 / q} & =\check{Z}^{\check{\Theta}} \cdot Z^{-\Theta} \times \\
& \times\left(\frac{F(\check{\alpha} ; r \check{\Theta} ; \check{Z})}{F(\check{\alpha} ; \check{Z})}\right)^{1 / r} \times\left(\frac{F\left(\alpha+q \kappa \delta_{e_{1}} ;-q \Theta ; Z\right)}{F(\alpha ; Z)}\right)^{1 / q} \\
& =\left(\frac{F(\check{\alpha} ; r \check{\Theta} ; \check{Z})}{F(\check{\alpha} ; \check{Z})}\right)^{1 / r} \times\left(\frac{F\left(\alpha+q \kappa \delta_{e_{1}} ;-q \Theta ; Z\right)}{F(\alpha ; Z)}\right)^{1 / q} .
\end{aligned}
$$

Using the Duality Lemma 3.1 for the term with power $1 / r$, together with the fact that $\check{\alpha}_{\check{e}}=\alpha_{e}$ and $\bar{\Theta}_{\breve{e}^{\prime}}=\underline{\Theta}_{e^{\prime}}$, the last product equals

$$
\left(\frac{G(\alpha+r \underline{\Theta})}{G(\alpha+r \bar{\Theta})}\right)^{1 / r} \times \frac{F(\alpha ; r \Theta ; Z)^{1 / r} F\left(\alpha+q \kappa \delta_{e_{1}} ;-q \Theta ; Z\right)^{1 / q}}{F(\alpha ; Z)}
$$

Choice of $q$ : The terms in the products above will be well-defined if all the terms evaluated by $F$ and $G$ are strictly positive. Let us see what should $q>0$ satisfy to achieve that. First note that the terms with power $1 / r$ are strictly positive since so is $\alpha$, whereas $\Theta$ is non-negative. For the terms with power $1 / q$ to be strictly positive, we need to have

$$
\begin{equation*}
\alpha_{e}-q \bar{\Theta}_{e}+q \kappa \mathbb{1}_{e=e_{1}}>0 \tag{5.9}
\end{equation*}
$$

and

$$
\begin{equation*}
\alpha_{e}-q \underline{\Theta}_{e}+q \kappa \mathbb{1}_{e=e_{1}}>0 . \tag{5.10}
\end{equation*}
$$

Equation (5.8) gives $\bar{\Theta}_{e}=\frac{p}{m\left(\alpha^{(1)}\right)} \bar{\Theta}_{e}$. From (5.6) $p<\kappa \leq m\left(\alpha^{(1)}\right)$, and using (5.7), and the definition of $\alpha^{(1)}$, we get

$$
\bar{\Theta}_{e} \leq \frac{p}{\kappa} \alpha_{e}+p \mathbb{1}_{e=e_{1} \text { or } e=e_{0}} \leq \alpha_{e}+\kappa \text { and } \bar{\Theta}_{x} \leq \frac{p}{\kappa} \bar{\alpha}_{0}+p \mathbb{1}_{x=0} \text { or } x=\bar{e}_{1} \leq \bar{\alpha}_{0}+\kappa .
$$

Let $a:=\min \left\{\alpha_{e_{i}}: 1 \leq i \leq 2 d\right\}>0, b:=\max \left\{\alpha_{e_{i}}: 1 \leq i \leq 2 d\right\}$, and $B:=\max \{b, \kappa\}<\infty$. Then

$$
\bar{\Theta}_{e} \leq 2 B \text { and } \bar{\Theta}_{x} \leq d b+\kappa \leq(d+1) B
$$

Random walks in random hypergeometric environment
$\Theta$ is a total flow from $e_{0}$ of strength $\frac{p}{d N^{d}}$, and therefore

$$
\underline{\Theta}_{e}=\bar{\Theta}_{e}-p \mathbb{1}_{e=e_{0}}+\frac{p}{d N^{d}} \mathbb{1}_{e \neq e_{0}} \leq 2 B+\frac{p}{d N^{d}} \leq 3 B .
$$

Noting that $a \leq \alpha_{e}<\bar{\alpha}_{0}$, and choosing $q=q(\alpha, d)>0$ to satisfy

$$
q<\frac{a}{(d+1) B}
$$

then (5.9) and (5.10) follow, and so we have shown well-definability.
Next, since $a \leq \alpha_{e} \leq b$, and $\log \Gamma$ is $C^{1}$ on $\mathbb{R}_{*}$ (e.g., since the digamma function is holomorphic on $\mathbb{C} \backslash\{0,-1,-2, \ldots\}$ ), we have that it is Lipschitz in the domain, i.e. there is some constant $c_{3}=c_{3}(\alpha, d)$ so that

$$
\begin{equation*}
\frac{\Gamma(s+t+h))}{\Gamma(s+t)}=e^{\log \Gamma(s+t+h))-\log \Gamma(s+t)} \leq e^{c_{3} \cdot|h|} \tag{5.11}
\end{equation*}
$$

for all $s \in[a, b]$ and $t, t+h \in[0, b]$. Now, by (5.3) $\operatorname{div}(\Theta)=\bar{\Theta}-\underline{\Theta}$ is proportional to the volume of the box, and so by (5.11) we have

$$
\left.\prod_{e \in E_{N}} \Gamma\left(\alpha_{e}+r \underline{\Theta}_{e}\right) / \Gamma\left(\alpha_{e}+r \bar{\Theta}_{e}\right)\right) \leq \exp \left(\frac{c_{2} r p\left(d N^{d}-1\right)}{d N^{d}}\right) \exp \left(c_{2} r \frac{p}{d N^{d}}\right)^{\#\left\{e \in E_{N}, e \neq e_{0}\right\}} \leq e^{2 c_{3} r p}
$$

Similarly, since $r \sum_{\underline{e}=x}\left(\bar{\Theta}_{e}-\underline{\Theta}_{e}\right)=2 d r \cdot \sum_{\underline{e}=x} \operatorname{div}(\Theta)(e)$, by dividing to the to cases $x=(e)_{0}$ and $x \neq(e)_{0}$ and using (5.3), we have that

$$
\prod_{x \in V} \Gamma\left(\sum_{\underline{e}=x}\left(\alpha_{e}+r \underline{\Theta}_{e}\right)\right) / \Gamma\left(\sum_{\underline{e}=x}\left(\alpha_{e}+r \bar{\Theta}_{e}\right)\right) \leq e^{4 d^{2} c_{3} r p}
$$

To sum up, so far we have $\left(\frac{G(\alpha+r \Theta)}{G(\alpha+r \overline{\bar{\Theta}})}\right)^{1 / r} \leq\left(e^{4 d^{2} c_{3} r p}\right)^{1 / r}=e^{4 d^{2} c_{3} p}=: e^{c_{4}}$. Therefore

$$
\mathbb{E}^{(\alpha, Z)}\left[\omega_{1}^{\kappa} \check{\omega}^{\check{\Theta}} \omega^{-\Theta}\right] \leq \exp \left(c_{4}\right) \exp \left(\sum_{x \in T_{N}} \nu\left(\alpha^{x}, \alpha_{x}, \Theta_{x}\right)\right)
$$

where $\left.\Theta_{x}:=\Theta\left(e, e^{\prime}\right)\right)_{\bar{e}=x=e^{\prime}}$, and

$$
\begin{aligned}
\nu\left(\alpha^{x}, \alpha_{x}, \Theta_{x}\right): & : \frac{1}{r} \log \Phi\left(\left(\alpha_{e}+r \bar{\Theta}_{e}\right)_{\bar{e}=x},\left(\alpha_{e^{\prime}}+r \underline{\Theta}_{e^{\prime}}\right)_{e^{\prime}=x}, Z\right) \\
& +\frac{1}{q} \log \Phi\left(\left(\alpha_{e}-q \bar{\Theta}_{e}+q \kappa \mathbb{1}_{e=e_{1}}\right)_{\bar{e}=x},\left(\alpha_{e^{\prime}}-q \underline{\Theta}_{e^{\prime}}+q \kappa \mathbb{1}_{e^{\prime}=e_{1}}\right)_{e^{\prime}=x}, Z\right) \\
& -\log \Phi\left(\left(\alpha_{e}\right)_{\bar{e}=x},\left(\alpha_{e^{\prime}}\right)_{e^{\prime}=x}, Z\right) .
\end{aligned}
$$

Note that $\nu:[a, b]^{2 d} \times[a, b]^{2 d} \times[0, C]^{2} \rightarrow \mathbb{R}_{+}$is $C^{2}$ on a compact set. Moreover, it satisfies $\nu\left(\alpha^{x}, \alpha_{x}, \Theta_{x}\right)=0$ at $\Theta_{x}=0$ and $\frac{\partial}{\partial \Theta\left(e, e^{\prime}\right)} \nu\left(\alpha^{x}, \alpha_{x}, \Theta_{x}=0\right)=0$ at $\Theta_{x}=0$. By a 2nd order $2 d$-dimensional Taylor Theorem, there is a constant $c_{5}=c_{5}(\alpha, d)$ so that we have

$$
\nu\left(\alpha^{x}, \alpha_{x}, \Theta_{x}\right) \leq c_{5} \sum_{\bar{e}=x=e^{\prime}} \Theta\left(e, e^{\prime}\right)^{2}
$$

But by construction $\Theta$ has a bounded $L_{2}$ norm with some constant $c_{1}$. Therefore,

$$
\left.\mathbb{E}^{(\alpha, Z)}\left[\omega_{1}^{\kappa} \check{\omega}^{\check{\Theta}} \omega^{-\Theta}\right] \leq e^{c_{4}} \exp \left(c_{5} \sum_{e, e^{\prime} \in K_{N}} \Theta\left(e, e^{\prime}\right)^{2}\right)\right) \leq \exp \left(c_{4}+c_{5} c_{1}\right)
$$

This concludes the proof of the lemma.

Random walks in random hypergeometric environment

## A Duality of hypergeometric functions

In this section we give a direct proof for Lemma 3.1 on the duality relation for hypergeometric functions. Note that for every $t, \beta>0$

$$
\begin{equation*}
\frac{1}{\Gamma(\beta)} \int_{0}^{\infty} e^{-t v} v^{\beta-1} d v=t^{-\beta} \tag{A.1}
\end{equation*}
$$

Recall (1.1) and (1.2). The strategy is to first use (A.1) to construct a variable $v$ that will take a dual role of $u$ and then to add another variable to "free the variable $u$ from the simplex". The next step is to modify $u$ and $v$ to make the integral suitable for duality. The conclusion is by following the above steps in a reverse order with the new $v$ and $u$. Here is the calculation in detail followed by some clarifications.

$$
\begin{aligned}
\Phi(\alpha, \beta, Z) & =\int_{\Delta^{(n)}} \varphi(\alpha, \beta ; Z ; u) d u \\
& =\int_{\Delta^{(n)}}\left(\prod_{i=1}^{n} u_{i}^{\alpha_{i}-1}\right) \prod_{j=1}^{l}\left((Z \cdot u)_{j}^{-\beta_{j}}\right) d u \\
& =\int_{\Delta^{(n)}}\left(\prod_{i} u_{i}^{\alpha_{i}-1}\right) \int_{\mathbb{R}_{+}^{l}}\left(\prod_{j} \frac{v_{j}^{\beta_{j}-1}}{\Gamma\left(\beta_{j}\right)}\right) e^{-\langle v, Z \cdot u>} d v d u \\
& =\frac{1}{\prod_{j} \Gamma\left(\beta_{j}\right)} \int_{\Delta^{(n)}} \int_{\mathbb{R}_{+}^{l}}\left(\prod_{j} v_{j}^{\beta_{j}-1}\right)\left(\prod_{i} u_{i}^{\alpha_{i}-1}\right) e^{-\langle v, Z \cdot u>} d u d v \\
& =\frac{1}{\prod_{j} \Gamma\left(\beta_{j}\right)} \frac{1}{\Gamma\left(\sum_{i} \alpha_{i}\right)} \int_{\mathbb{R}_{+}^{n}} \int_{\mathbb{R}_{+}^{l}} e^{-\sum_{i} u_{i}}\left(\prod_{j} v_{j}^{\beta_{j}-1}\right)\left(\prod_{i} u_{i}^{\alpha_{i}-1}\right) e^{-<\frac{1}{\sum_{i} u_{i}} v, Z \cdot u>} d u d v \\
& =\frac{1}{\prod_{j} \Gamma\left(\beta_{j}\right)} \frac{1}{\Gamma\left(\sum_{i} \alpha_{i}\right)} \int_{\mathbb{R}_{+}^{n}} \int_{\mathbb{R}_{+}^{l}} e^{-\sum_{j} v_{j}}\left(\prod_{j} v_{j}^{\beta_{j}-1}\right)\left(\prod_{i} u_{i}^{\alpha_{i}-1}\right) e^{-<\frac{1}{\sum_{j} v_{j}} u, Z^{t} \cdot v>} d v d u \\
& =\frac{\prod_{i} \Gamma\left(\alpha_{i}\right)}{\prod_{j} \Gamma\left(\beta_{j}\right)} \frac{\Gamma\left(\sum_{j} \beta_{j}\right)}{\Gamma\left(\sum_{i} \alpha_{i}\right)} \int_{\Delta^{(l)}}\left(\prod_{j} u_{j}^{\beta_{j}-1}\right) \prod_{i}\left(Z^{t} \cdot u\right)_{j}^{-\beta_{j}} d u \\
& =\frac{\prod_{i} \Gamma\left(\alpha_{i}\right)}{\prod_{j} \Gamma\left(\beta_{j}\right)} \frac{\Gamma\left(\sum_{j} \beta_{j}\right)}{\Gamma\left(\sum_{i} \alpha_{i}\right)} \Phi\left(\beta, \alpha, Z^{t}\right)
\end{aligned}
$$

The third equality follows from (A.1). For the fifth equality, note that using the change of variables $\lambda=\sum_{i} w_{i}, u_{i}=\frac{1}{\lambda} w_{i}$, we have that

$$
\begin{array}{r}
\int_{w \in \mathbb{R}_{+}^{n}} \int_{v \in \mathbb{R}_{+}^{l}} e^{-\sum_{i} w_{i}}\left(\prod_{j} v_{j}^{\beta_{j}-1}\right)\left(\prod_{i} w_{i}^{\alpha_{i}-1}\right) e^{-<\frac{1}{\sum_{i} w_{i}} v, Z \cdot w>} d w d v \\
=\int_{\lambda \in \mathbb{R}_{+}} e^{-\lambda} \cdot \lambda^{\left(\sum_{i} \alpha_{i}-1\right)} \int_{u \in \Delta_{n}} \int_{\mathbb{R}_{+}^{l}} e^{-\sum_{i} u_{i}}\left(\prod_{j} v_{j}^{\beta_{j}-1}\right)\left(\prod_{i} u_{i}^{\alpha_{i}-1}\right) e^{-<v, Z \cdot u>} d \lambda d u d v \\
=\Gamma\left(\sum_{i} \alpha_{i}\right) \int_{u \in \Delta^{(n)}} \int_{v \in \mathbb{R}_{+}^{l}}\left(\prod_{j} v_{j}^{\beta_{j}-1}\right)\left(\prod_{i} u_{i}^{\alpha_{i}-1}\right) e^{-<v, Z \cdot u>} d u d v
\end{array}
$$

To see the sixth equality, make a change of variables $u \rightarrow \tilde{u}=\frac{\sum_{i} v_{j}}{\sum_{i} u_{i}} u$ and $v \rightarrow \tilde{v}=$ $\frac{\sum_{i} u_{i}}{\sum_{j} v_{j}} v$, and deduce the equality from the fact that $\sum_{i} \alpha_{i}=\sum_{j} \beta_{j}$. The one before last equality follows from the previous equalities by interchanging the roles of ( $\alpha, u, n, Z$ ) and $\left(\beta, v, l, Z^{t}\right)$. The last equality follows from the definition of $\Phi$. This gives the desired duality.

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