# ASYMPTOTIC EQUIVALENCE OF FUNCTIONAL LINEAR REGRESSION AND A WHITE NOISE INVERSE PROBLEM

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We consider the statistical experiment of functional linear regression (FLR). Furthermore, we introduce a white noise model where one observes an Itô process, which contains the covariance operator of the corresponding FLR model in its construction. We prove asymptotic equivalence of FLR and this white noise model in LeCam's sense under known design distribution. Moreover, we show equivalence of FLR and an empirical version of the white noise model for finite sample sizes. As an application, we derive sharp minimax constants in the FLR model which are still valid in the case of unknown design distribution.

**1. Introduction.** We consider the statistical problem of functional linear regression (FLR). In its standard version, one observes the data (**X**, **Y**) where  $\mathbf{X} = (X_1, \ldots, X_n)^T$  are i.i.d. random variables taking their values in C([0, 1]), that is, the set consisting of all continuous functions on the interval [0, 1], and  $\mathbf{Y} = (Y_1, \ldots, Y_n)^T$  with

(1.1) 
$$Y_j = \langle X_j, \theta \rangle + \varepsilon_j, \qquad j = 1, \dots, n,$$

where  $\langle \cdot, \cdot \rangle$  denotes the  $L_2([0, 1])$ -inner product throughout this work. The i.i.d. error variables  $\varepsilon_j$  are assumed to be centered and normally distributed with the variance  $\sigma^2$ . Moreover, all  $X_1, \varepsilon_1, \ldots, X_n, \varepsilon_n$  are independent. The goal is to estimate the regression function  $\theta \in \Theta \subseteq L_2([0, 1])$ . In general, we allow for such a structure of the function class  $\Theta$  which does not determine  $\theta$  up to finitely many real-valued parameters. Thus we consider a nonparametric estimation problem. Moreover we assume that  $EX_1 = 0$  and  $P[||X_1||_2 \ge x] \le C_{X,0} \exp(-C_{X,1}x^{C_{X,2}})$ for all x > 0 and some finite constants  $C_{X,0}, C_{X,1}, C_{X,2} > 0$  where  $|| \cdot ||_p, p \ge 1$ denotes the  $L_p([0, 1])$ -norm of some element of that space. Thus the tails of the design distribution are restricted. Such conditions are usual in nonparametric regression problems.

The FLR model has obtained considerable attention in the statistical community during the last years, which is reflected in the large amount of literature on this topic. Various of estimation procedures have been proposed to make the regression function  $\theta$  empirically accessible (see, e.g., [6–8, 12, 13]). The minimax

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convergence rates in FLR are investigated, for example, in [5, 8, 15]. In [4], adaptive estimation in FLR is considered. Generalizations of FLR are discussed in [18]. A central limit theorem for FLR is derived in [9]. In [24], practical applications of FLR in the field of medical statistics are described; the authors consider two real data sets on primary biliary cirrhosis and systolic blood pressure. For a comprehensive introduction to the field of functional data analysis in general, see [21].

In order to compare two statistical models, it is useful to prove asymptotic equivalence between those models. For the basic concept and a detailed description of this strong asymptotic property, we refer to [16] and [17]. Also, a review on this topic is given in the following section. As an important feature, if two models  $\mathfrak{E}_{1,n}$  and  $\mathfrak{E}_{2,n}$  are asymptotically equivalent, then  $\mathfrak{E}_{1,n}$  adopts optimal convergence rates and sharp asymptotic constants with respect to any bounded loss function from model  $\mathfrak{E}_{2,n}$  and vice versa. Thus, the theory of asymptotic equivalence does not only capture special loss functions such as the mean integrated squared error (MISE) or the pointwise mean squared error (MSE) but includes various types of semi-metrics between the estimator and the target function  $\theta$  and also addresses the estimation of characteristics of  $\theta$ , such as its support or its mode. Furthermore, superefficiency phenomena also coincide in both models when considering subclasses  $\Theta'$  of the target parameter space  $\Theta$ . In particular, research has focussed on proofs of asymptotic equivalence of experiments where n i.i.d. data are observed, whose distribution depends on some parameter  $\theta \in \Theta$ , and experiments where  $\theta$ occurs in the drift of an empirically accessible Itô process. For instance, Nussbaum [19] considers an asymptotically equivalent white noise model for density estimation, while Brown and Low [2] introduce such a model for nonparametric regression. In recent related literature on regression problems, Carter [10] studies the case of unknown error variance, and Reiss [22] extends asymptotic equivalence to the multivariate setting.

Returning to model (1.1), we suppose that the nuisance parameters  $\sigma$  and  $P_X$ , that is, the distribution of the  $X_j$ , are known. That allows us to exclude those quantities from the parameter space of the experiment and to fully concentrate on the estimation of  $\theta$ . This condition is also imposed in most papers dealing with asymptotic equivalence for nonparametric regression experiments. The work of [10] represents an exception where the corresponding white noise model becomes more difficult and, apparently, less useful to derive adoptable asymptotic properties. With respect to asymptotic equivalence, we restrict our consideration to the case of known  $P_X$ . However, in Section 5, we will show that the sharp minimax asymptotics with respect to the MISE are extendable to the case of unknown design distribution.

The main purpose of the current work is to prove asymptotic equivalence of model (1.1) and a statistical inverse problem in the white noise setting. That latter model is described by the observation of an Itô process Y(t),  $t \in [0, 1]$ , Y(0) = 0, driven by the stochastic differential equation

(1.2) 
$$dY(t) = [K\theta](t) dt + n^{-1/2} \sigma dW(t),$$

where W(t) denotes a standard Wiener process on the interval [0, 1], and K denotes a linear operator mapping from the Hilbert space  $L_2([0, 1])$  to itself. These models are also widely studied in mathematical statistics (see, e.g., [11] and [14]). They have their applications in the field of signal deblurring and econometrics. We will concentrate on a specific version of model (1.2) where K is equal to the unique positive symmetric square root  $\Gamma^{1/2}$  of the covariance operator  $\Gamma$ , that is,  $\Gamma^{1/2}\Gamma^{1/2} = \Gamma$  and  $\Gamma f = \int EX_1(\cdot)X_1(t) f(t) dt$  for any  $f \in L_2([0, 1])$ . Thus, the observation  $Y(t), t \in [0, 1]$ , is defined by Y(0) = 0 and

(1.3) 
$$dY(t) = [\Gamma^{1/2}\theta](t) dt + n^{-1/2}\sigma dW(t).$$

In [8], the authors remark on the similarity of models (1.1) and (1.3). In the current paper, we will rigorously establish asymptotic equivalence between those models. As an interesting feature, additional observation of the data  $X_1, \ldots, X_n$  would be redundant in model (1.3). All information about the design points is recorded by  $\Gamma$  in (1.3). Therefore, all what is observed in the corresponding white noise experiment is the process  $Y(t), t \in [0, 1]$ . After the general introduction to the property of asymptotic equivalence as used in the current paper in Section 2, we will first prove (nonasymptotic) equivalence of model (1.1) and an empirical version of model (1.3) where  $\Gamma$  is replaced by a noisy counterpart in Section 3. In Section 4, we prove asymptotic equivalence of (1.1) and (1.3) under some additional technical conditions. In Section 5, we show that the sharp lower bound which follows from the results of the previous section can be attained by specific estimators in the realistic case of unknown design distribution. A discussion of the findings and their conclusions are provided in Section 6.

**2.** Asymptotic equivalence. To recall the definition of asymptotic equivalence, we consider two (sequences of) statistical experiments  $\mathfrak{E}_{j,n} = (\Omega_{j,n}, \mathfrak{A}_{j,n}, P_{j,n,\theta}), j = j_1, j_2$ , with a joint parameter space  $\Theta$ , which may depend on *n*. The LeCam distance between  $\mathfrak{E}_{j_1,n}$  and  $\mathfrak{E}_{j_2,n}$  is defined by

$$\Delta(\mathfrak{E}_{j_1,n},\mathfrak{E}_{j_2,n}) = \max_{k=1,2} \inf_{K \in \mathfrak{K}_{j_k,n}} \sup_{\theta \in \Theta} \|K(P_{j_k,n,\theta}) - P_{j_{3-k},n,\theta}\|_{\mathrm{TV}},$$

where  $\|\cdot\|_{\text{TV}}$  is the total variation distance, and  $\Re_{j_k,n}$  denotes the collection of so-called transitions (see [23] and [19] for their exact definition). The statistical experiments  $\mathfrak{E}_{j_1,n}$  and  $\mathfrak{E}_{j_2,n}$  are called asymptotically equivalent if  $\Delta(\mathfrak{E}_{j_1,n},\mathfrak{E}_{j_2,n})$ converges to zero as  $n \to \infty$ , while they are called equivalent if  $\Delta(\mathfrak{E}_{j_1,n},\mathfrak{E}_{j_2,n}) = 0$  for all *n*.

In the framwork of our note, we will not use that general definition of (asymptotic) equivalence but our proofs lean on following sufficient conditions for these properties:

(i) We consider the following sufficient condition for asymptotic equivalence of  $\mathfrak{E}_{j_1,n}$  and  $\mathfrak{E}_{j_2,n}$ : We define the sets  $\mathcal{R}_{j,n,\theta}$ ,  $j = j_1, j_2, \theta \in \Theta$ , which contains all

real-valued integrable random variables *R* on the domain  $\Omega_{j,n}$  satisfying  $|R| \leq 1$ a.s. Thus any kind of bounded loss functions are captured by the classes  $\mathcal{R}_{j,n,\theta}$ so that the expectation *ER* with respect to the distribution  $P_{j,n,\theta}$  describes an arbitrary bounded and normalized statistical risk for estimating the parameter  $\theta$ under the observation scheme  $\mathfrak{E}_{j,n}$ . Now we define two sequences  $(T_{j_k,j_{3-k},n})_n$ , k = 1, 2, of  $(\mathfrak{A}_{j_k}, \mathfrak{A}_{j_{3-k}})$ -measurable mappings from  $\Omega_{j_k}$  to  $\Omega_{j_{3-k}}$ . As an essential condition, the  $T_{j_k,j_{3-k},n}$  must not depend on  $\theta$ . Hence,  $T_{j_k,j_{3-k},n}$  may be interpreted as a transformation of the data from an observation contained in the space  $\Omega_{j,n}$  to an observation which lies in  $\Omega_{3-j,n}$ . Thus a statistician who intends to construct an estimation procedure for  $\theta$  may always apply this transformation  $T_{j_k,j_{3-k},n}$  to an observation  $\omega \in \Omega_{j_k,n}$ . Then we obtain asymptotic equivalence of  $\mathfrak{E}_{j_1,n}$  and  $\mathfrak{E}_{j_2,n}$ when we can show the existence of such transformation sequences  $(T_{j_k,j_{3-k},n})_n$ , k = 1, 2, so that

(2.1) 
$$\sup_{\theta \in \Theta} \sup_{R_{j_{3-k},n,\theta} \in \mathcal{R}_{j_{3-k},n,\theta}} |ER_{j_{3-k},n,\theta} - E(R_{j_{3-k},n,\theta} \circ T_{j_k,j_{3-k},n})| \longrightarrow 0$$

as  $n \to \infty$  for all k = 1, 2. Accordingly, we have equivalence if the left-hand side in (2.1) equals 0 for any *n*. Intuitively speaking, after transforming the data drawn from model  $\mathfrak{E}_{j_1,n}$  according to  $T_{j_1,j_2,n}$ , the distance between any bounded statistical risk in model  $\mathfrak{E}_{j_2,n}$  on one hand and for the transformed data from model  $\mathfrak{E}_{j_1,n}$ becomes small for large *n* or is equal to zero for any *n*, respectively. The same condition must also hold true when exchanging  $j_1$  and  $j_2$ .

In the specific framework of our note, we assume, in addition, that all transformations  $T_{j_k,j_{3-k},n}$  must not depend on the nuisance parameter  $\sigma$ . That compensates the unrealistic condition of known  $\sigma$ . In particular,  $\sigma$  is not used to transform the data or to construct decision procedures or estimators. Therefore, our results also addresses the case of unknown  $\sigma$ . Nevertheless,  $\sigma$  must be viewed as uninteresting for the statistician, that is, it must not explicitly occur in the loss functions  $R_{j_k,j_{k+1}}$ . Thus, the problem of estimating  $\sigma$  is not covered by our approach.

(ii) Assume that the experiment  $\mathfrak{E}_{j_2,n}$  describes the observation of  $T(\omega)$  for  $\omega \in \Omega_{j_1,n,\theta}$  in experiment  $\mathfrak{E}_{j_1,n}$  where *T* is a sufficient statistic for  $\theta$  in experiment  $\mathfrak{E}_{j_1,n}$ . Then  $\mathfrak{E}_{j_1,n}$  and  $\mathfrak{E}_{j_2,n}$  are statistically equivalent (i.e., their LeCam distance vanishes) and, hence, asymptotically equivalent. That assertion holds true whenever the experiments are Polish spaces. This criterion is satisfied as all probability spaces considered in the current work are  $\mathbb{R}^d$ , C([0, 1]),  $L_2([0, 1])$  and some set products of those classes (see Lemma 3.2 in [2]).

(iii) If some experiments  $\mathfrak{E}_{j_1,n}$  and  $\mathfrak{E}_{j_2,n}$  on one hand, and  $\mathfrak{E}_{j_2,n}$  and  $\mathfrak{E}_{j_3,n}$  on the other hand, are (asymptotically) equivalent, then  $\mathfrak{E}_{j_1,n}$  and  $\mathfrak{E}_{j_3,n}$  are (asymptotically) equivalent, too. Also, (asymptotic) equivalence of  $\mathfrak{E}_{j_1,n}$  and  $\mathfrak{E}_{j_2,n}$  is a symmetric relation between the experiments.

(iv) Assume that some experiments  $\mathfrak{E}_{j_1,n}$  and  $\mathfrak{E}_{j_2,n}$  may be decomposed into two independent experiments  $\mathfrak{E}_{j_1,n,k}$  and  $\mathfrak{E}_{j_2,n,k}$ , k = 1, 2, respectively. Moreover,

we suppose that the experiments  $\mathfrak{E}_{j_1,n,1}$  and  $\mathfrak{E}_{j_2,n,1}$  on one hand and the experiments  $\mathfrak{E}_{j_1,n,2}$  and  $\mathfrak{E}_{j_2,n,2}$  on the other hand are (asymptotically) equivalent. Then, the combined experiments  $\mathfrak{E}_{j_1,n}$  and  $\mathfrak{E}_{j_2,n}$  are (asymptotically) equivalent as well.

Now,  $\mathfrak{E}_{1,n}$  denotes the underlying experiment of the FLR model (1.1); it is defined by  $\Omega_{1,n} = C([0,1])^{(n)} \times \mathbb{R}^{(n)}$ ,  $\mathfrak{A}_{1,n}$  denotes the Borel  $\sigma$ -algebra when considering the uniform metric on the functional components and the Euclidean metric on the real-valued components of  $\Omega_{1,n}$ . The corresponding probability measures  $P_{1,n,\theta}$  are well defined by the assumptions of the model (1.1). The parameter space  $\Theta \subseteq L_2([0,1])$  will be specified later. Still, the observations (**X**, **Y**) may be viewed as random variables having their domain on some basic probability space  $(\Omega, \mathfrak{A}, P)$ .

**3. Empirical covariance operator.** We define the linear covariance operator  $\Gamma: L_2([0, 1]) \rightarrow L_2([0, 1])$  by

$$\Gamma f = \int E X_1(\cdot) X_1(t) f(t) dt \qquad \forall f \in L_2([0,1]).$$

Writing  $K(s, t) = EX_1(s)X_1(t)$ , we realize that  $\Gamma$  is a Hilbert–Schmidt integral operator where

$$\int_0^1 \int_0^1 |K(s,t)|^2 \, ds \, dt \le (E \, \|X_1\|_2^2)^2 < \infty,$$

by the Cauchy–Schwarz inequality and the tail condition imposed on the distribution of  $||X_1||_2$ . Hence  $\Gamma$  is a continuous and compact operator. We have K(s, t) = K(t, s) for all  $s, t \in [0, 1]$  so that the operator  $\Gamma$  is self-adjoint. Furthermore, it is positive; that is, by Fubini's theorem we have

$$\langle f, \Gamma f \rangle = E |\langle X_1, f \rangle|^2 \ge 0$$

for any  $f \in L_2([0, 1])$ .

Then, some well-known results from functional analysis, in particular spectral theory for compact operators, may be applied. There exists an orthonormal basis  $\{\varphi_j\}_{j\geq 1}$  of the separable Hilbert space  $L_2([0, 1])$  which consists of eigenfunctions of  $\Gamma$ . The corresponding eigenvalues are denoted by  $\lambda_j \geq 0$ . The sequence  $(\lambda_n)_n$  converges to zero and may be viewed as monotonously decreasing without loss of generality. Those results are also used, for example, in [5]. Furthermore, for  $\Gamma$  as for any compact self-adjoint positive operator from  $L_2([0, 1])$  to itself, there exists a unique compact self-adjoint positive operator  $\Gamma^{1/2}$  from  $L_2([0, 1])$  to itself such that  $(\Gamma^{1/2})^2 = \Gamma$ ; then  $\Gamma^{1/2}$  is called the square root of  $\Gamma$ . We have  $\Gamma^{1/2}\varphi_j = \lambda_j^{1/2}\varphi_j$  for any  $j \geq 1$ .

We may define an empirically accessible version  $\hat{\Gamma}$  of  $\Gamma$  by replacing the expectation by the average; more precisely, we have

$$\hat{\Gamma}f = \frac{1}{n} \sum_{j=1}^n \int X_j(\cdot) X_j(t) f(t) dt \qquad \forall f \in L_2([0,1]).$$

Thus,  $\hat{\Gamma}$  may be viewed as the operator  $\Gamma$  when  $P_X$  equals the uniform distribution on the discrete set  $\{X_1, \ldots, X_n\}$ . Therefore, all properties derived for  $\Gamma$  in the previous paragraph can be taken over to  $\hat{\Gamma}$ . In particular,  $\hat{\varphi}_j$ , integer  $j \ge 1$ , denotes the orthonormal basis of the eigenfunctions of  $\hat{\Gamma}$  with the eigenvalues  $\hat{\lambda}_j$ .

Now we consider the conditional probability density  $p_{1,n,\theta}(y_1, \ldots, y_n | X_1, \ldots, X_n)$  of the data  $Y_1, \ldots, Y_n$  given the design functional observations  $X_1, \ldots, X_n$  in model (1.1). This density shall be understood with respect to the *n*-dimensional Lebesgue measure. We derive that

(3.1)  

$$p_{1,n,\theta}(y_1, \dots, y_n \mid X_1, \dots, X_n) = (2\pi)^{-n/2} \sigma^{-n} \prod_{j=1}^n \exp\left(-\frac{1}{2\sigma^2}(y_j - \langle X_j, \theta \rangle)^2\right) = (2\pi)^{-n/2} \sigma^{-n} \exp\left(-\|\mathbf{y} - \mathbf{x}\|^2/(2\sigma^2)\right),$$

with the vectors  $\mathbf{y} = (y_1, \ldots, y_n)^T$  and  $\mathbf{x} = (\langle X_1, \theta \rangle, \ldots, \langle X_n, \theta \rangle)^T$ . Moreover,  $\|\cdot\|$  denotes the Euclidean norm. Expanding  $\theta \in \Theta \subseteq L_2([0, 1])$  in the orthonormal basis  $\{\hat{\varphi}_i\}_{i>1}$  gives us that

(3.2) 
$$\langle X_j, \theta \rangle = \sum_{k=1}^{\infty} \langle X_j, \hat{\varphi}_k \rangle \langle \hat{\varphi}_k, \theta \rangle.$$

We impose the following condition on the distribution  $P_X$ :

(3.3) 
$$P[X_1 \in L] = 0, \qquad \text{for any deterministic linear subspace} \\ L \subseteq L_2([0, 1]) \text{ with } \dim L < \infty.$$

Intuitively, this assumption provides that the probability mass of the  $X_j$  fills the whole of  $L_2([0, 1])$ . Somehow, (3.3) is the functional data analog for continuity of a distribution of some real-valued random variables. It is satisfied when we take an appropriate Gaussian process for  $X_1$ , for instance. Condition (3.3) yields that the linear space generated by  $X_1, \ldots, X_n$  is *n*-dimensional almost surely. Otherwise, at least one of the  $X_j$  must be included in the linear hull of the other design variables. According to (3.3) that occurs with probability zero when employing the conditional probability measure given the data  $X_1, \ldots, X_{j-1}, X_{j+1}, \ldots, X_n$ . Finally, applying the expectation, we obtain the desired result for the unconditional distribution.

We realize that the range of  $\hat{\Gamma}$  is included in the linear hull of  $X_1, \ldots, X_n$ . By definition,  $\hat{\varphi}_j$  is contained in that *n*-dimensional space whenever  $\hat{\lambda}_j > 0$ . As the  $\hat{\varphi}_j$  form an orthonormal basis at most *n* of the eigenvalues  $\hat{\lambda}_j$  are nonvanishing. Furthermore, the linear independence of the  $X_1, \ldots, X_n$  implies that the functions  $\hat{\Gamma}X_k = n^{-1}\sum_{j=1}^n \langle X_j, X_k \rangle X_j, k = 1, \ldots, n$ , are linearly independent, too, so that

the range of  $\hat{\Gamma}$  is equal to the linear hull of  $X_1, \ldots, X_n$ . Clearly, the range of  $\hat{\Gamma}$  also coincides with the linear hull of all  $\hat{\varphi}_j$  with  $\hat{\lambda}_j > 0$ , from what follows  $\langle X_j, \hat{\varphi}_k \rangle = 0$  for all  $j = 1, \ldots, n$  and k > n. Also, we have  $\hat{\lambda}_j > 0$  for  $j = 1, \ldots, n$  and  $\hat{\lambda}_j = 0$  for j > n. Hence, (3.2) leads to the representation

(3.4) 
$$\langle X_j, \theta \rangle = \sum_{k=1}^n \langle X_j, \hat{\varphi}_k \rangle \langle \hat{\varphi}_k, \theta \rangle$$

for all j = 1, ..., n. Equation (3.4) is equivalent to the system of linear equations  $\mathbf{x} = \mathbf{Q}\mathbf{f}$  with the vector  $\mathbf{f} = (\langle \hat{\varphi}_1, \theta \rangle, ..., \langle \hat{\varphi}_n, \theta \rangle)^T$  and the matrix  $\mathbf{Q}$  with the components  $Q_{j,k} = \langle X_j, \hat{\varphi}_k \rangle, j, k = 1, ..., n$ . Then the conditional density  $p_{1,n,\theta}$  as in (3.1) may be written as

(3.5) 
$$p_{1,n,\theta}(y_1,\ldots,y_n \mid X_1,\ldots,X_n) = (2\pi)^{-n/2} \sigma^{-n} \exp(-\|\mathbf{y} - \mathbf{Qf}\|^2/(2\sigma^2)).$$

We consider that the (k, k')th component of the matrix  $\mathbf{Q}^T \mathbf{Q}$  is equal to

$$\sum_{j=1}^{n} \langle X_j, \hat{\varphi}_k \rangle \langle X_j, \hat{\varphi}_{k'} \rangle = n \langle \hat{\Gamma} \hat{\varphi}_k, \hat{\varphi}_{k'} \rangle = n \hat{\lambda}_k \cdot \delta_{k,k'}.$$

Thus  $\mathbf{Q}^T \mathbf{Q}$  is a diagonal matrix containing  $n\hat{\lambda}_k$  as its (k, k)th component. We denote the diagonal matrix having  $n^{1/2}\hat{\lambda}_k^{1/2}$  as its (k, k)th component by **D**. Obviously, **D** is invertible, and we define  $\mathbf{A} = \mathbf{Q}\mathbf{D}^{-1}$ . We have

$$\mathbf{A}^T \mathbf{A} = \mathbf{D}^{-1} \mathbf{Q}^T \mathbf{Q} \mathbf{D}^{-1} = \mathbf{I},$$

where **I** denotes the identity matrix. Also, this yields that  $\mathbf{A}\mathbf{A}^T = \mathbf{I}$  and that **A** is an orthogonal matrix. Thus,  $\|\mathbf{A}\mathbf{v}\| = \|\mathbf{v}\|$  for any vector  $\mathbf{v} \in \mathbb{R}^n$ . Equality (3.5) provides that

(3.6)  

$$p_{1,n,\theta}(y_1, \dots, y_n \mid X_1, \dots, X_n) = (2\pi)^{-n/2} \sigma^{-n} \exp(-\|\mathbf{A}\mathbf{A}^T\mathbf{y} - \mathbf{A}\mathbf{D}\mathbf{f}\|^2 / (2\sigma^2)) = (2\pi)^{-n/2} \sigma^{-n} \exp(-\|\mathbf{A}^T\mathbf{y} - \mathbf{D}\mathbf{f}\|^2 / (2\sigma^2)).$$

Referring to the notation of (2.1), we consider the expectation  $ER_{1,n,\theta}(\mathbf{X}, \mathbf{Y})$ where  $R_{1,n,\theta} \in \mathcal{R}_{1,n,\theta}$ . We derive that

$$ER_{1,n,\theta}(\mathbf{X}, \mathbf{Y}) = EE(R_{1,n,\theta}(\mathbf{X}, \mathbf{Y}) | \mathbf{X})$$
  

$$= E \int \cdots \int R_{1,n,\theta}(X_1, \dots, X_n; y_1, \dots, y_n)$$
  

$$\times p_{1,n,\theta}(y_1, \dots, y_n | X_1, \dots, X_n) dy_1 \cdots dy_n$$
  

$$= E \int \cdots \int R_{1,n,\theta}(X_1, \dots, X_n; \mathbf{Az})(2\pi)^{-n/2}$$
  

$$\times \sigma^{-n} \exp(-\|\mathbf{z} - \mathbf{Df}\|^2 / (2\sigma^2)) dz_1 \cdots dz_n$$
  

$$= ER_{1,n,\theta}(\mathbf{X}, \mathbf{AZ}),$$

where  $\mathbf{Z} = (Z_1, ..., Z_n)^T$  denotes a vector consisting of independent normally distributed random variables where  $Z_k$  has the mean

$$n^{1/2}\hat{\lambda}_k^{1/2}\langle\hat{\varphi}_k,\theta\rangle = \langle\hat{\varphi}_k,n^{1/2}\hat{\Gamma}^{1/2}\theta\rangle$$

and the variance  $\sigma^2$ , conditionally on the  $\sigma$ -algebra generated by **X**. Therefore, the  $Z_k$  may be represented as

(3.8) 
$$Z_k = \langle \hat{\varphi}_k, n^{1/2} \hat{\Gamma}^{1/2} \theta \rangle + \sigma \varepsilon_k, \qquad k = 1, \dots, n,$$

where  $\varepsilon_1, \ldots, \varepsilon_n$  are i.i.d. N(0, 1)-distributed random variables. The  $\varepsilon_j$  are independent of the  $\sigma$ -algebra generated by **X**. We have applied the integral transformation  $\mathbf{y} = \mathbf{A}\mathbf{z}$  where det  $\mathbf{A} = \pm 1$  due to the orthogonality of **A**. Note that the sign of the eigenfunctions  $\hat{\psi}_j$  may still be chosen; we can arrange that det  $\mathbf{A} = 1$ .

Now we define the statistical experiment  $\mathfrak{E}_{2,n}$  with the same parameter space  $\Theta$  as  $\mathfrak{E}_{1,n}$ ,  $(\Omega_{2,n}, \mathfrak{A}_{2,n}) = (\Omega_{1,n}, \mathfrak{A}_{1,n})$  and  $P_{2,n,\theta}$  as the probability measure generated by the random variable  $(\mathbf{X}, \mathbf{Z})$  with  $\mathbf{Z}$  as in (3.7). In the notation of Section 2, paragraph (i), we use the mapping  $T_{2,1,n}: \Omega_{2,n} \to \Omega_{1,n}$  defined by  $T_{2,1,n}(\mathbf{x}, \mathbf{z}) = (\mathbf{x}, \mathbf{A}\mathbf{z}), \mathbf{x} \in C_0([0, 1])^{(n)}, \mathbf{z} \in \mathbb{R}^n$ , as the data transformation from  $\mathfrak{E}_{2,n}$  to  $\mathfrak{E}_{1,n}$ . By definition, the matrix  $\mathbf{A}$  does not depend on the parameter  $\theta$  but only on the data  $X_1, \ldots, X_n$  and the known orthonormal basis  $\{\hat{\varphi}_j\}_{j\geq 1}$ . Also, it does not depend on  $\sigma$  as requested in the previous section. We have already derived that  $\mathbf{A}$  is an orthogonal matrix so that  $T_{2,1,n}$  is a bijective mapping from the set  $C_0([0, 1])^{(n)} \times \mathbb{R}^n$  to itself. Hence, its reverse mapping  $T_{2,1,n}^{-1}$  may be used as the data transformation  $T_{1,2,n}$ . Then, according to (2.1), we have proved the following lemma.

LEMMA 3.1. Under condition (3.3), the statistical experiments  $\mathfrak{E}_{1,n}$  and  $\mathfrak{E}_{2,n}$  are equivalent.

The random variables  $\varepsilon_j$ , integer *j*, as occurring in (3.8), may be represented by

$$\varepsilon_j = \int_0^1 \hat{\varphi}_j(t) \, dW(t),$$

where W denotes a standard Wiener process on [0, 1] which is independent of X. We deduce that the  $\varepsilon_1, \varepsilon_2, \ldots$  are an independent sequence of N(0, 1)-distributed random variables. Moreover, they are independent of  $X_1, \ldots, X_n$  although  $\hat{\varphi}_j$  depends on these design variables. That can be shown via the conditional characteristic function of  $(\varepsilon_1, \varepsilon_2, \ldots)$  given  $X_1, \ldots, X_n$ ; that is,

$$E\left[\exp\left(i\sum_{j=1}^{\infty}\int s_j\hat{\varphi}_j(t)\,dW(t)\right)\,\Big|\,X_1,\ldots,X_n\right] = \exp\left(-\frac{1}{2}\sigma^2\left\|\sum_{j=1}^{\infty}s_j\hat{\varphi}_j\right\|_2^2\right)$$
$$= \exp\left(-\frac{1}{2}\sigma^2\sum_{j=1}^{\infty}s_j^2\right)$$

for all real-valued sequences  $(s_m)_{m\geq 1}$  with  $\sum_{m=1}^{\infty} s_m^2 < \infty$ . Applying the expectation to the above equality, the unconditional characteristic function of  $(\varepsilon_1, \varepsilon_2, ...)$  turns out to coincide with the conditional one. We have

(3.9) 
$$Z_j = \langle \hat{\varphi}_j, n^{1/2} \hat{\Gamma}^{1/2} \theta \rangle + \sigma \int_0^1 \hat{\varphi}_j(t) \, dW(t) = \int \hat{\varphi}_j \, dZ(t)$$

for all j = 1, ..., n where  $Z(t), t \in [0, 1]$ , denotes an Itô process satisfying

(3.10) 
$$dZ(t) = n^{1/2} [\hat{\Gamma}^{1/2} \theta](t) dt + \sigma dW(t),$$

and Z(0) = 0. The differential dZ(t) shall be understood in the Itô sense.

Now we define the statistical experiment  $\mathfrak{E}_{3,n}$  with a completely functional observation structure. We fix that  $\Omega_{3,n} = C([0, 1])^{(n+1)}$  with the corresponding Borel  $\sigma$ -algebra  $\mathfrak{A}_{3,n}$ . The probability measure  $P_{3,n,\theta}$  is defined via the observation of **X** as in  $\mathfrak{E}_{2,n}$  and the Itô process Z(t),  $t \in [0, 1]$ , as defined in (3.10). The definition (3.9) of  $Z_j$  can be extended to j > n straightforwardly. As  $\hat{\lambda}_j = 0$ , we obtain that

$$Z_j = \sigma \int_0^1 \hat{\varphi}_j(t) \, dW(t) \qquad \forall j > n.$$

Moreover, Z(t) is uniquely determined by the  $Z_j$  for all integers  $j \ge 1$  and vice versa. That can be seen as follows:

$$Z(t) = \int \mathbb{1}_{[0,t]}(s) \, dZ(s) = \sum_{j=1}^{\infty} \langle \mathbb{1}_{[0,t]}, \hat{\varphi}_j \rangle Z_j$$

for all  $t \in [0, 1]$  where the infinite sum must be understood as an  $E \|\cdot\|_2^2$ -limit. That seems to cause some troubles as we only observe one element of the probability space. However, convergence in probability implies almost sure convergence of a subsequence so that Z(t) is fully accessible by the observation of all  $Z_j$ . On the other hand, by a similar argument, all  $Z_j$  are accessible (in practice, that means approximable arbitrarily precisely) by a trajectory of the process Z.

Hence the data set  $\{Z_j : j > n\}$  is independent of the  $Z_1, \ldots, Z_n$ , conditionally on the  $\sigma$ -algebra generated by **X**. Furthermore, the distribution of the  $Z_j$ , j > n, does not depend on the target parameter  $\theta$  so that  $Z_j$ , for j > n, does not contain any information about  $\theta$ . We conclude that  $(\mathbf{X}, Z_1, \ldots, Z_n)$  is a sufficient statistic for the observation scheme in the experiment  $\mathfrak{E}_{3,n}$ . We can utilize result (ii) from Section 2 in order to prove equivalence of the experiments  $\mathfrak{E}_{2,n}$  and  $\mathfrak{E}_{3,n}$ . Considering paragraph (iii) from Section 2, we may establish equivalence of the experiments  $\mathfrak{E}_{1,n}$  and  $\mathfrak{E}_{3,n}$ . This result is presented in the following theorem.

THEOREM 3.1. Under condition (3.3), the FLR statistical experiment  $\mathfrak{E}_{1,n}$  is equivalent to the model  $\mathfrak{E}_{3,n}$  where one observes **X** and the Itô process Z(t),  $t \in [0, 1]$ , as defined in (3.10).

4. Asymptotic approximation. In the previous section, we have derived a statistically equivalent white noise model for the FLR problem. However, the Itô process Z in (3.9) contains the noisy operator  $\hat{\Gamma}$  in its construction. In the current section, we will replace it by the covariance operator  $\Gamma$ .

For that purpose, we split the original experiment  $\mathfrak{E}_{1,n}$  into two independent parts  $\mathfrak{E}_{1,n,1}$  and  $\mathfrak{E}_{1,n,2}$  where  $\mathfrak{E}_{1,n,1}$  is based on the observation of the data  $(X_j, Y_j)$ ,  $j = 1, \ldots, m$ , and  $\mathfrak{E}_{1,n,2}$  consists of the residual data  $(X_j, Y_j)$ ,  $j = m+1, \ldots, n$ . The selection of the integer parameter *m* is deferred. The strategy of splitting the sample in the current context leans on [19]. Applying Theorem 3.1 to each of the experiments  $\mathfrak{E}_{1,n,k}$ , k = 1, 2, we obtain equivalence of  $\mathfrak{E}_{1,n,k}$  and the experiments  $\mathfrak{E}_{4,n,k}$  for k = 1, 2. Therein,  $\mathfrak{E}_{4,n,1}$  is defined by the observation of  $\mathbf{X}_1 = (X_1, \ldots, X_m)$  and the Itô process  $Z_1(t)$ ,  $t \in [0, 1]$ , specified by  $Z_1(0) = 0$  and

$$dZ_1(t) = m^{1/2} [\hat{\Gamma}_1^{1/2} \theta](t) dt + \sigma dW_1(t),$$

and accordingly  $\mathfrak{E}_{4,n,2}$  is defined by the observation of  $\mathbf{X}_2 = (X_{m+1}, \dots, X_n)$  and the Itô process  $Z_2(t), t \in [0, 1]$ , specified by  $Z_2(0) = 0$  and

$$dZ_2(t) = (n-m)^{1/2} [\hat{\Gamma}_2^{1/2}\theta](t) dt + \sigma dW_2(t).$$

Furthermore,  $\hat{\Gamma}_k$ , k = 1, 2, denotes the empirical covariance operator constructed by the data  $\mathbf{X}_1$  and  $\mathbf{X}_2$ , respectively. Also note that  $W_1$  and  $W_2$  are two independent standard Wiener processes. Using criterion (iv) in Section 2, the experiment  $\mathfrak{E}_{4,n}$ , which combines the independent experiments  $\mathfrak{E}_{4,n,1}$  and  $\mathfrak{E}_{4,n,2}$ , we deduce that  $\mathfrak{E}_{4,n}$  and  $\mathfrak{E}_{1,n}$  are equivalent.

From the experiment  $\mathfrak{E}_{4,n,1}$  we construct an estimator  $\hat{\theta}_1$  for  $\theta$ . We define that

$$\hat{\theta}_1 = \sum_{k=1}^K m^{-1/2} \lambda_k^{-1} \int [\hat{\Gamma}_1^{1/2} \varphi_k](t) \, dZ_1(t) \varphi_k,$$

where *K* is an integer-valued smoothing parameter still to be selected. Condition (3.3) guarantees that all  $\lambda_j$  are positive since, otherwise,  $\lambda_j = 0$  would yield that  $E|\langle X_1, \varphi_k \rangle|^2 = 0$  for all  $k \ge j$ , and hence  $\sum_{k\ge j} |\langle X_1, \varphi_k \rangle|^2 = 0$  a.s. so that  $X_1$  would lie in the linear hull of  $\varphi_1, \ldots, \varphi_{j-1}$ . Thus the estimator  $\hat{\theta}_1$  is well defined.

We introduce the data transformation  $T_{4,5,n}: \Omega_{4,n} \to \Omega_{5,n}$  where

$$T_{4,5,n}(\mathbf{x}_1, z_1, \mathbf{x}_2, z_2) = \left(\mathbf{x}_1, z_1, \mathbf{x}_2, z_2 - (n-m)^{1/2} \int_0^{\cdot} [\hat{\Gamma}_2^{1/2} \hat{\theta}_1](t) dt + (n-m)^{1/2} \int_0^{\cdot} [\Gamma^{1/2} \hat{\theta}_1](t) dt \right)$$

The transformation is fully accessible by the data drawn from the experiment  $\mathfrak{E}_{4,n,1}$  and the assumed knowledge of the distribution of **X**. We set  $(\Omega_{5,n}, \mathfrak{A}_{5,n}) =$ 

 $(\Omega_{4,n}, \mathfrak{A}_{4,n})$  where  $\Omega_{4,n} = C_0^m([0, 1]) \times C_0([0, 1]) \times C_0^{n-m}([0, 1]) \times C_0([0, 1])$ and  $\mathfrak{A}_{4,n}$  is the corresponding Borel  $\sigma$ -algebra. The data structure of  $\mathfrak{E}_{4,n}$  is represented by  $(\mathbf{X}_1, Z_1, \mathbf{X}_2, Z_2)$  when inserting the data set as an argument of the mapping  $T_{4,5,n}$ . Note that  $z_2 = Z_2$  may be inserted in the definition of the estimator  $\hat{\theta}_1$ . The integral occurring in the definition of  $\hat{\theta}_1$  is not defined for all continuous functions  $z_1$  but for almost all trajectories of  $Z_1$ . For the other negligible trajectories the integral may conventionally be put equal to zero to make the mapping  $T_{4,5,n}$  well defined on the whole of its domain.

We define the experiment  $\mathfrak{E}_{5,n}$  where ones observes the data

$$(\mathbf{X}_1, Z_1, \mathbf{X}_2, Z'_2) = T_{4,5,n}(\mathbf{X}_1, Z_1, \mathbf{X}_2, Z_2),$$

where the data  $X_1$ ,  $Z_1$ ,  $X_2$ ,  $Z_2$  are obtained under experiment  $\mathfrak{E}_{4,n}$ . The experiment  $\mathfrak{E}_{5,n}$  is defined on the probability space  $(\Omega_{5,n}, \mathfrak{A}_{5,n})$ . Considering the definition of  $T_{4,5,n}$ , we realize that the shift contained in the forth component is still available in the experiment  $\mathfrak{E}_{5,n}$  as the other components are kept. Therefore,  $T_{4,5,n}$  is an invertible transformation so that the experiments  $\mathfrak{E}_{4,n}$  and  $\mathfrak{E}_{5,n}$  are equivalent.

In the experiment  $\mathfrak{E}_{5,n}$ , the component  $Z'_2$  is still an Itô process conditionally on  $\mathbf{X}_1, \mathbf{X}_2, Z_1$ . Now we introduce the experiment  $\mathfrak{E}_{6,n}$  with  $(\Omega_{6,n}, \mathfrak{A}_{6,n}) = (\Omega_{5,n}, \mathfrak{A}_{5,n})$  where one observes the data  $\mathbf{X}_1, Z_1, \mathbf{X}_2$  and the Itô process  $S_2(t)$ ,  $t \in [0, 1]$  with  $S_2(0) = 0$  and

$$dS_2(t) = (n-m)^{1/2} [\Gamma^{1/2}\theta](t) dt + \sigma dW_2(t).$$

In the notation of Section 2, we consider that

(4.1)  

$$|ER_{j,n,\theta}(\mathbf{X}_{1}, Z_{1}, \mathbf{X}_{2}, Z_{2}') - ER_{j,n,\theta}(\mathbf{X}_{1}, Z_{1}, \mathbf{X}_{2}, S_{2})|$$

$$\leq E \left| 1 - \exp\left(-\sigma^{-1} \int \Delta_{5,6}(t) \, dW_{2}(t) - \frac{1}{2\sigma^{2}} \|\Delta_{5,6}\|_{2}^{2}\right) \right|^{1/2}$$

$$\leq 2E \left\{ 1 - \exp\left(-\frac{1}{2\sigma^{2}} \|\Delta_{5,6}\|_{2}^{2}\right) \right\}^{1/2}$$

$$\leq 2 \left\{ 1 - \exp\left(-\frac{1}{2\sigma^{2}} E \|\Delta_{5,6}\|_{2}^{2}\right) \right\}^{1/2},$$

where

$$\Delta_{5,6} = (n-m)^{1/2} (\Gamma^{1/2}\theta - \Gamma^{1/2}\hat{\theta}_1 + \hat{\Gamma}_2^{1/2}\hat{\theta}_1 - \hat{\Gamma}_2^{1/2}\theta)$$
  
=  $(n-m)^{1/2} (\Gamma^{1/2} - \hat{\Gamma}_2^{1/2})(\theta - \hat{\theta}_1).$ 

Therein, we have used Girsanov's theorem,  $||R_{j,n,\theta}||_{\infty} \le 1$  for  $R_{j,n,\theta} \in \mathcal{R}_{j,n,\theta}$  as j = 5, 6, the Bretagnolle–Huber inequality and Jensen's inequality in the last step.

Now we study the expectation occurring in (4.1) by Parseval's identity with respect to the basis  $\{\hat{\varphi}_{k,2}\}_{k\geq 1}$  and the orthogonal expansion of  $\hat{\varphi}_{k,2}$  with respect

to  $\{\varphi_j\}_{j\geq 1}$  where  $\{\hat{\varphi}_{k,2}\}_{k\geq 1}$  denotes the eigenfunctions of  $\hat{\Gamma}_2$  and  $\hat{\lambda}_{k,2}$  the corresponding eigenvalues.

$$\begin{split} E\|\Delta_{5,6}\|_{2}^{2} &= (n-m)\sum_{k=1}^{\infty} E\left|\sum_{j=1}^{\infty} \langle \hat{\Gamma}_{2}^{1/2} \varphi_{j} - \Gamma^{1/2} \varphi_{j}, \hat{\varphi}_{k,2} \rangle \langle \varphi_{j}, \theta - \hat{\theta}_{1} \rangle \right|^{2} \\ &= (n-m)\sum_{k=1}^{\infty} E\left|\sum_{j=1}^{\infty} (\lambda_{j}^{1/2} - \hat{\lambda}_{k,2}^{1/2}) \langle \varphi_{j}, \hat{\varphi}_{k,2} \rangle \langle \varphi_{j}, \theta - \hat{\theta}_{1} \rangle \right|^{2} \\ &\leq (n-m)\sum_{k=1}^{\infty} E\sum_{j=1}^{\infty} j^{-\gamma} |\lambda_{j} - \hat{\lambda}_{k,2}| |\langle \varphi_{j}, \hat{\varphi}_{k,2} \rangle|^{2} \\ &\times \sum_{j'=1}^{\infty} j'^{\gamma} E|\langle \varphi_{j'}, \theta - \hat{\theta}_{1} \rangle|^{2}, \end{split}$$

where we have used the Cauchy–Schwarz inequality for sums and the elementary inequality  $(\sqrt{x} - \sqrt{y})^2 \le |x - y|$  for all  $x, y \ge 0$ . Therein  $\gamma > 0$  is still to be selected. Also, the independence of  $\hat{\Gamma}_2$  and  $\hat{\theta}_1$  has been utilized. Then, we apply the Cauchy–Schwarz inequality with respect to the discrete random variable V satisfying  $P[V = |\hat{\lambda}_{k,2} - \lambda_j|] = |\langle \varphi_j, \hat{\varphi}_{k,2} \rangle|^2$  for all integers  $k \ge 1$  and some fixed integer j, conditionally on  $\mathbf{X}_2$ . We conclude that

$$\begin{split} E\|\Delta_{5,6}\|_{2}^{2} &\leq (n-m) \left\{ \sum_{j'=1}^{\infty} j'^{\gamma} E|\langle \varphi_{j'}, \theta - \hat{\theta}_{1} \rangle|^{2} \right\} \\ &\times E \sum_{j=1}^{\infty} j^{-\gamma} \left( \sum_{k=1}^{\infty} |\lambda_{j} - \hat{\lambda}_{k,2}|^{2} |\langle \varphi_{j}, \hat{\varphi}_{k,2} \rangle|^{2} \right)^{1/2} \\ &\leq (n-m) \left\{ \sum_{j'=1}^{\infty} j'^{\gamma} E|\langle \varphi_{j'}, \theta - \hat{\theta}_{1} \rangle|^{2} \right\} \\ &\times \sum_{j=1}^{\infty} j^{-\gamma} \{E\|\hat{\Gamma}_{2}\varphi_{j} - \Gamma\varphi_{j}\|_{2}^{2} \}^{1/2}. \end{split}$$

We consider that

$$E \| \hat{\Gamma}_{2} \varphi_{j} - \Gamma \varphi_{j} \|_{2}^{2} = E \left\| \frac{1}{n-m} \sum_{k=1}^{n-m} (X_{k} \langle X_{k}, \varphi_{j} \rangle - E X_{k} \langle X_{k}, \varphi_{j} \rangle) \right\|_{2}^{2}$$
  

$$\leq (n-m)^{-1} E \| X_{1} \|_{2}^{2} |\langle X_{1}, \varphi_{j} \rangle|^{2}$$
  

$$\leq (n-m)^{-1} c_{j}^{2} \langle \Gamma \varphi_{j}, \varphi_{j} \rangle + (n-m)^{-1} E \| X_{1} \|_{2}^{4} \mathbf{1}_{(c_{j},\infty)} (\| X_{1} \|_{2})$$
  
(4.2)

ASYMPTOTIC EQUIVALENCE

$$\leq (n-m)^{-1}c_j^2\lambda_j + (n-m)^{-1}\sum_{k>c_j-1}(k+1)^4 P[||X_1||_2 \geq k]$$
  
$$\leq \text{const.} \cdot (n-m)^{-1}(c_j^2\lambda_j + C_{X,0}\exp(-C_{X,1}c_j^{C_{X,2}}/2))$$

for *n* sufficiently large where the sequence  $(c_j)_j \uparrow \infty$  remains to be determined. In order to obtain those results, we impose the following:

CONDITION X. We assume that condition (3.3) holds true;  $C_{\lambda,2}j^{-\alpha} \ge \lambda_j \ge C_{\lambda,1}j^{-\alpha}$  for all integer  $j \ge 1$  and some  $\alpha \ge 2$ ,  $C_{\lambda,2} > C_{\lambda,1} > 0$ ;  $EX_1 = 0$ ;  $P[||X_1||_2 \ge x] \le C_{X,0} \exp(-C_{X,1}x^{C_{X,2}})$  for all x > 0 and some finite constants  $C_{X,0}, C_{X,1}, C_{X,2} > 0$ .

Condition X imposes a polynomial lower bound on the sequence of the eigenvalues of  $\Gamma$ . This assumption is very common in FLR (see, e.g., [5]). When Condition X is fixed the underlying inverse problem can be viewed as a moderately ill-posed problem unlike severely ill-posed problems where exponential decay of the eigenvalues occurs. Condition X also corresponds to the deconvolution setting with ordinary smooth error densities in the related field of density estimation based on contaminated data.

As an example for a stochastic process which satisfies Condition X, we mention the random variables

$$X = \sum_{j=1}^{\infty} j^{-\alpha/2} G_j \varphi_j,$$

where the  $\varphi_i$ , integer j, form an arbitrary orthonormal basis of  $L_2([0, 1])$ ; the  $G_i$  are i.i.d. real-valued centered random variables with a continuous distribution which is concentrated on some compact interval, and  $EG_1^2 = 1$ . We stipulate that  $\alpha > 2$ . Easy calculations yield that the coefficients  $j^{-\alpha}$  and  $\varphi_i$  are the eigenvalues and the eigenvectors of the corresponding covariance operator  $\Gamma$ , respectively. Stipulating that the sequence  $\{\|\varphi_j\|_{\infty}\}_{j\geq 1}$  is bounded above (as satisfied, e.g., by the Fourier polynomials), we can show that Condition X is fulfilled. In particular, the random variable (g, X) is continuously distributed for any  $g \in L_2([0, 1]) \setminus \{0\}$ since  $\langle g, \varphi_i \rangle \neq 0$  for at least one integer j so that the distribution of  $\langle g, X \rangle$  is just the convolution of an absolutely continuous distribution and some other distribution; hence the distribution of  $\langle g, \varphi_i \rangle$  has a Lebesgue density so that condition (3.3) can be verified. All other assumptions contained in Condition X can easily be checked. Another even more important example for design distributions are the Gaussian processes  $X(t) = \int_0^t \sigma(s) dW(s), t \in [0, 1]$ , where W denotes a standard Wiener process and  $\sigma$  is a sufficiently smooth function which is bounded from above and below by positive constants. These processes satisfy Condition X as well where  $\alpha = 2$ . The decay condition can be verified via the famous reflection principle of Wiener processes.

Returning to the investigation of an upper bound on  $E \|\Delta_{5,6}\|_2^2$ , the following inequality is evident:

(4.3)  

$$E \|\Delta_{5,6}\|_{2}^{2} \leq (n-m)^{1/2} \left\{ \sum_{j'=1}^{\infty} j'^{\gamma} E |\langle \varphi_{j'}, \theta - \hat{\theta}_{1} \rangle|^{2} \right\}$$

$$\times \sum_{j=1}^{\infty} j^{-\gamma} (c_{j}^{2} \lambda_{j} + C_{X,0} \exp(-C_{X,1} c_{j}^{C_{X,2}}))^{1/2}.$$

We deduce that

$$E|\langle \varphi_{j'}, \theta - \hat{\theta}_{1} \rangle|^{2}$$

$$= E \left| \langle \varphi_{j'}, \theta \rangle - 1_{\{j' \leq K\}} m^{-1/2} \lambda_{j'}^{-1} \int [\hat{\Gamma}_{1}^{1/2} \varphi_{j'}](t) dZ_{1}(t) \right|^{2}$$

$$= 1_{\{j' > K\}} |\langle \varphi_{j'}, \theta \rangle|^{2}$$

$$+ 1_{\{j' \leq K\}}$$

$$\times E \left| \lambda_{j'}^{-1} \langle \hat{\Gamma}_{1}\theta, \varphi_{j'} \rangle - \langle \theta, \varphi_{j'} \rangle + \sigma m^{-1/2} \lambda_{j'}^{-1} \int [\hat{\Gamma}_{1}^{1/2} \varphi_{j'}](t) dW_{1}(t) \right|^{2}$$

$$= 1_{\{j' > K\}} |\langle \varphi_{j'}, \theta \rangle|^{2}$$

$$+ 1_{\{j' \leq K\}} \lambda_{j'}^{-2} \{E|\langle \hat{\Gamma}_{1}\theta, \varphi_{j'} \rangle - \langle \Gamma\theta, \varphi_{j'} \rangle|^{2} + \sigma^{2} m^{-1} E \|\hat{\Gamma}_{1}^{1/2} \varphi_{j'}\|_{2}^{2} \}$$

$$\leq 1_{\{j' > K\}} |\langle \varphi_{j'}, \theta \rangle|^{2}$$

$$+ 1_{\{j' \leq K\}} \lambda_{j'}^{-2} \{m^{-1} \|\theta\|_{2}^{2} E \|X_{1}\|_{2}^{2} |\langle X_{1}, \varphi_{j'} \rangle|^{2} + \sigma^{2} m^{-1} \lambda_{j'} \}$$

$$\leq 1_{\{j' > K\}} |\langle \varphi_{j'}, \theta \rangle|^{2}$$

$$+ 1_{\{j' \leq K\}}$$

$$\times \lambda_{j'}^{-2} \{m^{-1} \|\theta\|_{2}^{2} (c_{j'}^{2} \lambda_{j'} + C_{X,0} \exp(-C_{X,1} c_{j'}^{C_{X,2}}/2)) + \sigma^{2} m^{-1} \lambda_{j'} \}.$$

For further investigation of the asymptotic quality of the estimator  $\hat{\theta}_1$ , some conditions on  $P_X$  and  $\Theta$  are required. They are stated such that—combined with Condition X—all previously imposed assumptions concerning those characteristics are included.

CONDITION T. We assume that

$$\sum_{k=1}^{\infty} (1+k^{2\beta}) |\langle \varphi_k, \theta \rangle|^2 \le C_{\Theta}$$

for all  $\theta \in \Theta$  and some constants  $\beta > (\alpha + 1)/2$  and  $C_{\Theta} < \infty$ , which are uniform with respect to  $\theta \in \Theta$ .

Condition T says that the  $\theta \in \Theta$  are uniformly well approximable with respect to the orthonormal basis consisting of the eigenfunctions of  $\Gamma$ . The parameter  $\beta$  describes the degree of this approximability. If the  $\varphi_k$  were some Fourier polynomials, then Condition T could be interpreted as Sobolev constraints on the set of the target functions.

We apply the parameter selection  $K \simeq m^{1/(2\beta+\alpha+1)}$ , and we fix that  $c_j = d_0 \log^{d_1} j$  with some constants  $d_0, d_1$  sufficiently large and that  $\gamma \in (0, \beta - \alpha/2 - 1/2)$ . Also, we choose  $m = \lfloor n/2 \rfloor$ . Inserting that result into (4.3), we deduce by Conditions X and T that

$$\sup_{\theta \in \Theta} E \|\Delta_{5,6}\|_2^2 = O(n^{(\alpha+1-2\beta+2\gamma)/(4\beta+2\alpha+2)} \log^{d_3} n) = o(1)$$

for some  $d_3 > 0$ , due to the inequality  $\beta > (\alpha + 1)/2$  and the suitable selection of  $\gamma$ . Revisiting inequality (4.1), we have finally proved by Section 2, paragraph (i) that the experiments  $\mathfrak{E}_{5,n}$  and  $\mathfrak{E}_{6,n}$  are asymptotically equivalent.

In the experiment  $\mathfrak{E}_{6,n}$ , the observation of  $S_2$  allows us to construct an estimator  $\hat{\theta}_2$  for  $\theta$  as well. It is given by

$$\hat{\theta}_2 = \sum_{k=1}^{K} (n-m)^{-1/2} \lambda_k^{-1} \int [\Gamma^{1/2} \varphi_k](t) \, dS_2(t) \varphi_k,$$

where the parameter *K* can be adopted from the estimator  $\hat{\theta}_1$ . We specify the transformation  $T_{6,7,n}: \Omega_{6,n} \to \Omega_{7,n}$  with

$$T_{6,7,n}(\mathbf{x}_1, z_1, \mathbf{x}_2, s_2) = \left(\mathbf{x}_1, z_1 - m^{1/2} \int_0^{\cdot} [\hat{\Gamma}_1^{1/2} \hat{\theta}_2](t) dt + m^{1/2} \int_0^{\cdot} [\Gamma^{1/2} \hat{\theta}_2](t) dt, \mathbf{x}_2, s_2\right).$$

Again the shift of the second component is accessible by the other components which are maintained under the mapping so that  $T_{6,7,n}$  is invertible. Therefore, we define the experiment  $\mathfrak{E}_{7,n}$  by the observation of  $T_{6,7,n}(\mathbf{X}_1, Z_1, \mathbf{X}_2, S_2)$  with  $(\mathbf{X}_1, Z_1, \mathbf{X}_2, S_2)$  as under the experiment  $\mathfrak{E}_{6,n}$ . Hence, we put  $(\Omega_{7,n}, \mathfrak{A}_{7,n}) =$  $(\Omega_{6,n}, \mathfrak{A}_{6,n})$  and obtain that  $\mathfrak{E}_{7,n}$  is equivalent to  $\mathfrak{E}_{6,n}$ .

We define the experiment  $\mathfrak{E}_{8,n}$  by the observation of  $(\mathbf{X}_1, S_1, \mathbf{X}_2, S_2)$  on the probability space  $(\Omega_{8,n}, \mathfrak{A}_{8,n}) = (\Omega_{7,n}, \mathfrak{A}_{7,n})$  where  $S_1$  denotes the Itô process with  $S_1(0) = 0$  and

$$dS_1(t) = m^{1/2} [\Gamma^{1/2}\theta](t) dt + \sigma dW_1(t).$$

We can show that  $\mathfrak{E}_{8,n}$  is asymptotically equivalent to  $\mathfrak{E}_{7,n}$  analogously to the proof of the asymptotic equivalence of  $\mathfrak{E}_{5,n}$  and  $\mathfrak{E}_{6,n}$ . The only remarkable modification concerns the application of the estimator  $\hat{\theta}_2$  instead of  $\hat{\theta}_1$ . However, even for that term we establish an upper bound at the same rate as for estimator  $\hat{\theta}_1$  since the asymptotic order of *m* and *n* – *m* coincide.

Taking a closer look at the data drawn from  $\mathfrak{E}_{8,n}$ , we realize that the random variables  $\mathbf{X}_1, S_1, \mathbf{X}_2, S_2$  are independent. That occurs as we have replaced the empirical covariance operators by the true deterministic one. Furthermore the data sets  $\mathbf{X}_1, \mathbf{X}_2$  do not carry any information on  $\theta$  so that  $S_1, S_2$  represent a sufficient statistic for the whole empirical information obtained under  $\mathfrak{E}_{8,n}$ . By Section 2, paragraph (ii), we conclude that  $\mathfrak{E}_{8,n}$  is equivalent to the experiment  $\mathfrak{E}_{9,n}$  in which only the observations  $S_1, S_2$  are available. Thus we put  $\Omega_{9,n} = C_0([0, 1]) \times C_0([0, 1])$  and  $\mathfrak{A}_{9,n}$  equal to the corresponding Borel  $\sigma$ algebra.

We define the transformation  $T_{9,10,n}: \Omega_{9,n} \to \Omega_{10,n}$  with  $(\Omega_{10,n}, \mathfrak{A}_{10,n}) = (\Omega_{9,n}, \mathfrak{A}_{9,n})$  by

$$T_{9,10,n}(s_1, s_2) = \mathbf{A}(s_1, s_2)^T$$

with the matrix

$$\mathbf{A} = \begin{pmatrix} m^{1/2}/n & (n-m)^{1/2}/n \\ m^{-1/2} & -(n-m)^{-1/2} \end{pmatrix}.$$

We easily verify that **A** is invertible so that the experiment  $\mathfrak{E}_{10,n}$  which is defined by the observation of  $(T_1, T_2) = T_{9,10,n}(S_1, S_2)$  is equivalent to the experiment  $\mathfrak{E}_{9,n}$ . We consider the characteristic function of the  $L_2([0, 1]) \times L_2([0, 1])$ -valued random variable  $(T_1, T_2)$ ,

$$E \exp(i \langle t_1, T_1 \rangle + i \langle t_2, T_2 \rangle)$$

$$= E \exp(i \langle \mathbf{e}_1^T \mathbf{A}^T(t_1, t_2)^T, S_1 \rangle) E \exp(i \langle \mathbf{e}_2^T \mathbf{A}^T(t_1, t_2)^T, S_2 \rangle)$$

$$= \exp\left(i \langle t_1, \int_0^{\cdot} [\Gamma^{1/2} \theta](t) dt \rangle\right)$$

$$\times \exp\left(-\frac{1}{2n} \sigma^2 \iint t_1(x_1) \min\{x_1, x_2\} t_1(x_2) dx_1 dx_2\right)$$

$$\times \exp\left(-\frac{1}{2} \left[\frac{1}{m} + \frac{1}{n-m}\right] \sigma^2 \iint t_2(x_1) \min\{x_1, x_2\} t_2(x_2) dx_1 dx_2\right)$$

for any  $t_1, t_2 \in L_2([0, 1])$  so that  $T_1$  and  $T_2$  are two Itô processes satisfying  $T_1(0) = T_2(0) = 0$  and

$$dT_1(t) = [\Gamma^{1/2}\theta](t) dt + n^{-1/2}\sigma dW_3(t),$$
  
$$dT_2(t) = \sigma \left(\frac{1}{m} + \frac{1}{n-m}\right)^{1/2} dW_4(t),$$

where  $W_3$  and  $W_4$  are two independent Wiener processes. Thus  $T_1$  and  $T_2$  are independent, and  $T_2$  is totally uninformative with respect to the target function  $\theta$ . Applying Section 2, paragraph (ii) again, we have established equivalence of  $\mathfrak{E}_{10,n}$  and the experiment  $\mathfrak{E}_{11,n}$ , which is equipped with  $\Omega_{11,n} = C_0([0, 1])$  and the cor-

responding Borel  $\sigma$ -algebra  $\mathfrak{A}_{11,n}$ , and characterized by the observation of the process  $T_1$ , which coincides with the process Y as defined in (1.3).

Summarizing we have shown asymptotic equivalence of the experiments  $\mathfrak{E}_{1,n}$  and  $\mathfrak{E}_{11,n}$ . That provides our final main result, which will be given as a theorem below.

THEOREM 4.1. Under the Conditions X and T, the FLR experiment  $\mathfrak{E}_{1,n}$  with known design distribution and independent  $N(0, \sigma^2)$ -distributed regression errors is asymptotically equivalent to the white noise experiment  $\mathfrak{E}_{11,n}$  where only the Itô process Y as in (1.3) is observed.

5. Sharp estimation for unknown  $P_X$ . We can combine our results with Theorem 1 in [11], which is due to [20], in order to derive a sharp minimax result with respect to the MISE for the FLR problem under known covariance operator. It follows from there that this sharp minimax risk corresponds to the sequence

$$a_n = \sigma^2 n^{-1} \sum_{k=1}^{\infty} \lambda_k^{-1} (1 - \gamma (1 + k^{2\beta})^{1/2})_+,$$

where  $\gamma$  is the unique solution of the equation

$$\frac{\sigma^2}{n} \sum_{k=1}^{\infty} \lambda_k^{-1} (1+k^{2\beta})^{1/2} (1-\gamma(1+k^{2\beta})^{1/2})_+ = C_{\Theta} \gamma,$$

under the conditions of Theorem 4.1. More concretely, there exists an estimator  $\hat{\theta}$  of  $\theta$  in the FLR model, which satisfies

$$\sup_{\theta \in \Theta} E \|\hat{\theta} - \theta\|_2^2 = a_n (1 + o(1)).$$

Thus, any other estimator in the underlying model satisfies the above equation when = is replaced by  $\geq$ . We have established sharp asymptotic constants.

Critically, we mention that the loss function  $a_n^{-1} \|\hat{\theta} - \theta\|_2^2$  is apparently not bounded. Still, asymptotic equivalence yields coincidence of sharp minimaxity for the loss function  $\min\{D_n, a_n^{-1} \|\hat{\theta} - \theta\|_2^2\}$  for some  $(D_n)_n \to \infty$  sufficiently slowly. We can show that, in the white noise inverse problem, the sharp constant result is extendable to the truncated loss function. Using Theorem 4.1, we have a sharp lower bound for the FLR model even for the truncated loss function.

However, the design distribution  $P_X$  is assumed to be known and occurs in the definition of the minimax estimator. On the other hand, the lower bound as derived from Theorem 4.1 in the previous section provides a lower bound for the FLR model in the case of unknown  $P_X$  as well since nonknowledge of  $P_X$  cannot improve this lower bound. Thus if we succeed in showing that some estimator

achieves these asymptotic properties under the assumption of unknown  $P_X$ , then sharp asymptotic minimaxity is extended to this more realistic condition. Assuming that all conditions of Theorem 4.1 except the knowledge of  $P_X$  hold true, we propose the estimator

(5.1) 
$$\hat{\theta} = \sum_{j} w_j \frac{1}{n} \sum_{l=1}^{n} Y_l \langle X_l, \hat{\varphi}_j \rangle \hat{\varphi}_j \hat{\lambda}_{j,\rho}^{-1}$$

for  $\theta$  where  $\hat{\lambda}_{j,\rho} = \max{\{\hat{\lambda}_j, n^{-\rho}\}}$  for some  $\rho \in (0, 1/2)$ . The weights  $w_j$  remain to be specified. Using the techniques of the papers of [5] and [15], the MISE of  $\hat{\theta}$  is equal to

(5.2) 
$$E \|\hat{\theta} - \theta\|_2^2 = \sum_k E \left| w_k \frac{\hat{\lambda}_k}{\hat{\lambda}_{k,\rho}} - 1 \right|^2 |\langle \hat{\varphi}_k, \theta \rangle|^2 + \frac{\sigma^2}{n} \sum_k E w_k^2 \frac{\hat{\lambda}_k}{\hat{\lambda}_{k,\rho}^2}.$$

We stipulate that for  $k > n^{\rho/\alpha}/\log n$  all weights  $w_k$  shall be put equal to zero. For all other k we have  $\lambda_k \ge 2n^{-\rho}$  for n sufficiently large so that

$$\begin{split} E\hat{\lambda}_{k}/\hat{\lambda}_{k,\rho}^{2} &\leq \frac{1}{(1-1/(2+\log k))\lambda_{k}} + n^{2\rho}\lambda_{k}P[\hat{\lambda}_{k}-\lambda_{k} < -\lambda_{k}/(2+\log k)] \\ &\leq \lambda_{k}^{-1} + \lambda_{k}^{-1} \Big(\frac{1}{\log k+1} + (2+\log k)^{2}O(n^{2\rho-1})\Big), \end{split}$$

where we have used Markov's inequality and that  $E|\hat{\lambda}_k - \lambda_k|^2$  is bounded from above by the expected squared Hilbert–Schmidt norm of  $\hat{\Gamma} - \Gamma$  and, hence, by  $O(n^{-1})$  (see, e.g., [1]). That requires the following assumption:

(5.3) 
$$\lambda_j - \lambda_{j+1} \ge \text{const.} \cdot j^{-\alpha - 1}$$

(see also [15]). We conclude that the second term in equation (5.2) has the same asymptotic order as

$$\{1 + O(1/\log\log n)\} \cdot \frac{\sigma^2}{n} \sum_k w_k^2 \lambda_k^{-1} + O(n^{-1}\log^{\alpha+1} n),$$

under the above restriction with respect to the selection of the weights. Focusing on the first term in (5.2), we deduce by the Cauchy–Schwarz inequality that

$$\sum_{k} E \left| w_{k} \frac{\hat{\lambda}_{k}}{\hat{\lambda}_{k,\rho}} - 1 \right|^{2} |\langle \hat{\varphi}_{k}, \theta \rangle|^{2} \leq \left\{ \left( \sum_{k} E \left| w_{k} \frac{\hat{\lambda}_{k}}{\hat{\lambda}_{k,\rho}} - 1 \right|^{2} |\langle \varphi_{k}, \theta \rangle|^{2} \right)^{1/2} + \text{const.} \cdot \left( \sum_{k} E |\langle \hat{\varphi}_{k} - \varphi_{k}, \theta \rangle|^{2} \right)^{1/2} \right\}^{2}.$$

We consider that

$$\begin{split} \sum_{k} E |\langle \hat{\varphi}_{k} - \varphi_{k}, \theta \rangle|^{2} &= \sum_{k} E \left| \sum_{j} \langle \hat{\varphi}_{k} - \varphi_{k}, \varphi_{j} \rangle \langle \varphi_{j}, \theta \rangle \right|^{2} \\ &\leq \text{const.} \cdot C_{\Theta} \sum_{k,j} j^{-2\beta} E |\langle \hat{\varphi}_{k} - \varphi_{k}, \varphi_{j} \rangle|^{2} \\ &= \text{const.} \cdot \sum_{j} j^{-2\beta} E |\langle \hat{\varphi}_{j} - \varphi_{j}, \varphi_{j} \rangle|^{2} \\ &+ \text{const.} \cdot \sum_{j} j^{-2\beta} \sum_{k \neq j} E |\langle \hat{\varphi}_{k} - \varphi_{k}, \varphi_{j} \rangle|^{2} \\ &\leq \text{const.} \cdot \sum_{j} j^{-2\beta} E \| \hat{\varphi}_{j} - \varphi_{j} \|_{2}^{2} \\ &+ \text{const.} \cdot \sum_{j} j^{-2\beta} \sum_{k \neq j} E |\langle \hat{\varphi}_{k}, \hat{\varphi}_{j} - \varphi_{j} \rangle|^{2} \\ &\leq \text{const.} \cdot \sum_{j} j^{-2\beta} E \| \hat{\varphi}_{j} - \varphi_{j} \|_{2}^{2} \end{split}$$

by exploiting the orthonormality of the  $\hat{\varphi}_j$  and the  $\varphi_j$  as well as Condition T and Parseval's identity. Bhatia, Davis and McIntosh [1] provide that the squared  $L_2([0, 1])$ -distance between  $\hat{\varphi}_j$  and  $\varphi_j$  is bounded from above by the squared Hilbert–Schmidt norm of  $\hat{\Gamma} - \Gamma$  multiplied by  $8j^{2\alpha+2}$  via condition (5.3). Thus we have

(5.4) 
$$\sum_{k} E |\langle \hat{\varphi}_{k} - \varphi_{k}, \theta \rangle|^{2} = O(n^{-1}),$$

where the constants contained in  $O(\cdot)$  do not depend on  $\theta$  whenever

$$(5.5) \qquad \qquad \beta > \alpha + 3/2.$$

Returning to the consideration of the first term in (5.2), we conclude that its asymptotic order reduces to that of

$$\sum_{k} E \left| w_k \frac{\hat{\lambda}_k}{\hat{\lambda}_{k,\rho}} - 1 \right|^2 |\langle \varphi_k, \theta \rangle|^2.$$

Then this term is bounded from above by

$$\sum_{k} |w_{k} - 1|^{2} |\langle \varphi_{k}, \theta \rangle|^{2} + \text{const.} \cdot \sum_{k=1}^{\lfloor n^{\rho/\alpha} / \log n \rfloor} |\langle \varphi_{k}, \theta \rangle|^{2} \lambda_{k}^{-2} E |\hat{\lambda}_{k} - \lambda_{k}|^{2} + O(n^{-2\beta\rho/\alpha} (\log n)^{2\beta})$$
$$\leq O(n^{-2\beta\rho/\alpha} (\log n)^{2\beta}) + \text{const.} \cdot C_{\Theta} / n + \sum_{k} |w_{k} - 1|^{2} |\langle \varphi_{k}, \theta \rangle|^{2}$$

by utilizing Condition T and again the results of [1]. The term  $O(n^{-2\beta\rho/\alpha})$  is asymptotically negligible [i.e., bounded by O(1/n)] whenever  $\rho > \alpha/(2\alpha + 3)$  as we have already imposed the condition (5.5). It follows that the MISE of (5.1) may be reduced to its asymptotically efficient terms, that is,

(5.6)  

$$E \|\hat{\theta} - \theta\|_{2}^{2} = \{1 + o(1)\} \left( \sum_{k} |w_{k} - 1|^{2} |\langle \varphi_{k}, \theta \rangle|^{2} + \frac{\sigma^{2}}{n} \sum_{k} w_{k}^{2} \lambda_{k}^{-1} \right) + O(n^{-1} \log^{\alpha + 1} n).$$

The right-hand side of (5.6), however, corresponds to the MISE of an oracle estimator which uses the true versions of the eigenvalues and eigenfunctions of  $\Gamma$ instead of the empirical ones. Also, it follows from [20] and [11] that the estimator  $\hat{\theta}$  as in (5.1) attains the sharp asymptotic minimax risk when the weights are chosen as

$$w_k = (1 - \gamma \beta_k)_+,$$

when writing  $\beta_k = (1 + k^{2\beta})^{1/2}$  with an appropriate deterministic parameter  $\gamma$ . More precisely, we consider  $\gamma_n$  which we define by the unique zero of the function  $\Phi = \Phi_1 - \Phi_2$  with

$$\Phi_1(x) = \sum_{k=1}^{\infty} \lambda_k^{-1} \beta_k (1 - x\beta_k)_+, \qquad \Phi_2(x) = C_{\Theta} x n / \sigma^2$$

for  $x \ge 0$  where  $\Phi_1$  and  $\Phi_2$  are continuous montonically decreasing and increasing, respectively. The selection  $\gamma = \gamma_n$  leads to asymptotic sharp optimality (see, e.g., [11]). Clearly, we have  $\gamma_n \simeq n^{-\beta/(2\beta+\alpha+1)}$ . Otherwise, not even the convergence rates are optimal as the required balance between the bias and the variance term is violated. By condition (5.5) our additional assumption saying that that  $w_k \equiv 0$  for  $k > n^{\rho/\alpha}/\log n$  is verified under this optimal selection of the weights when stipulating that  $\gamma > n^{-\beta/(2\beta+1)}$  as we have assumed  $\rho > \alpha/(2\alpha+3)$ .

Still, the suggested selector is an oracle choice as it requires knowledge of the true eigenvalues  $\lambda_j$ . That motivates us to consider a data-driven selector  $\hat{\gamma}$  of  $\gamma$ . First we split the sample  $(\mathbf{X}, \mathbf{Y})$  into two independent data sets  $(\mathbf{X}_j, \mathbf{Y}_j)$ , j = 1, 2. The first data set  $(\mathbf{X}_1, \mathbf{Y}_1)$  consists of *m* pairs  $(X_k, Y_k)$  where  $m \approx n(1 - 1/\log n)$ , and  $(\mathbf{X}_2, \mathbf{Y}_2)$  contains all the other observations. We employ  $(\mathbf{X}_1, \mathbf{Y}_1)$  to estimate the function  $\theta$  while the second data set (training data) is used to provide an selector of  $\gamma$ . Concretely, we fix  $\tilde{\gamma}$  as the unique zero of  $\hat{\Phi} = \hat{\Phi}_1 - \Phi_2$  where

(5.7) 
$$\hat{\Phi}_1(x) = \sum_{k=1}^{\infty} (\hat{\lambda}'_{k,\rho})^{-1} \beta_k (1 - x\beta_k)_+.$$

Therein, ' indicates that the estimator is based on the second data set. Then we define our selector of  $\hat{\gamma}$  as med{ $n^{-\beta/(3\beta+1)}, \tilde{\gamma}, n^{-\beta/(2\beta+1)}$ }. This truncation takes

into account the a priori knowledge about the true  $\gamma_n$  so that  $|\hat{\gamma} - \gamma_n| \le |\tilde{\gamma} - \gamma_n|$  almost surely for *n* sufficiently large.

Thus determining  $\hat{\gamma}$  does not require knowledge of  $P_X$ . Now let us consider the MISE of the estimator  $\hat{\theta}_{\hat{\gamma}}$  where the index indicates the incorporated choice of the parameter  $\gamma$ . By (5.6), we derive that

$$\begin{split} E \|\hat{\theta}_{\hat{\gamma}} - \theta\|_{2}^{2} \\ &= o(n^{-2\beta/(2\beta + \alpha + 1)}) \\ &+ \{1 + o(1)\} \\ &\times \left(\sum_{k=1}^{\infty} |\langle \varphi_{k}, \theta \rangle|^{2} E |(1 - \hat{\gamma} \beta_{k})_{+} - 1|^{2} + \frac{\sigma^{2}}{m} \sum_{k=1}^{\infty} \lambda \lambda_{k}^{-1} E (1 - \hat{\gamma} \beta_{k})_{+}^{2} \right), \end{split}$$

where the terms contained in o(1) do not depend on  $\gamma$ . As the asymptotic order of m and n coincides, the estimator based on m data attains the same asymptotic rates and constants as the estimator which uses even n data, so our above calculations remain valid. Therefore, the estimator  $\hat{\theta}_{\hat{\gamma}}$  attains sharp minimax rates and constants whenever

(5.8)  

$$\sum_{k=1}^{\infty} E|(1-\hat{\gamma}\beta_k)_{+} - (1-\gamma_n\beta_k)_{+}|^2|\langle\varphi_k,\theta\rangle|^2 + \frac{1}{m}\sum_{k=1}^{\infty}\lambda_k^{-1}E|(1-\hat{\gamma}\beta_k)_{+} - (1-\gamma_n\beta_k)_{+}|^2 = o(n^{-2\beta/(2\beta+\alpha+1)}),$$

uniformly with respect to  $\theta \in \Theta$ . The first term in (5.8) is bounded from above by const.  $\cdot E |\hat{\gamma} - \gamma_n|^2$ . The second term has the upper bound

$$O(c_n^{\alpha+2\beta+1}) \cdot E|\hat{\gamma} - \gamma_n|^2 + O(1/n) \cdot \sum_{k>c_n n^{1/(2\beta+\alpha+1)}}^{\lceil \text{const.}, n^{1/(2\beta+1)} \rceil} \lambda_k^{-1} P[\hat{\gamma} \le \beta_k^{-1}]$$

for some sequence  $(c_n)_n$  tending to infinity sufficiently slowly. We deduce by Markov's inequality that (5.8) is satisfied if

$$n^{\alpha/(2\beta+1)}\gamma_n^{-2\nu} \cdot E|\hat{\gamma} - \gamma_n|^{2\nu} + E|\hat{\gamma} - \gamma_n|^2 = o(n^{-2\beta/(2\beta+\alpha+1)})$$

for some fixed integer  $\nu$ . The assertion  $|\tilde{\gamma} - \gamma_n| > s_n$ , for some positive-valued sequence  $(s_n)_n \downarrow 0$  with  $s_n/\gamma_n \to 0$ , implies that

$$|\Phi_1(\gamma_n + s_n) - \Phi_1(\gamma_n + s_n)| > C_{\Theta} s_n n / \sigma^2$$

or

$$|\hat{\Phi}_{1}(\gamma_{n}-s_{n})-\Phi_{1}(\gamma_{n}-s_{n})|>C_{\Theta}s_{n}n/\sigma^{2}+|\Phi_{1}(\gamma_{n})-\Phi_{1}(\gamma_{n}-s_{n})|.$$

We have already imposed that  $\rho > \alpha/(2\alpha + 3)$  so that  $\lambda_k > n^{-\rho}$  for all  $k \le (\gamma_n - s_n)^{-1/\beta}$ . That, however, yields  $\|\hat{\Gamma}' - \Gamma\|_{\text{HS}} \ge \text{const.} \cdot s_n n^{-\rho} \gamma_n^{-1}$  where  $\|\cdot\|_{\text{HS}}$  denotes the Hilbert–Schmidt norm of an operator. Therein we have used the findings of [1] again and the monotonicity of the functions  $\hat{\Phi}_1$ ,  $\Phi_1$ ,  $\Phi_2$  as well as the definitions of  $\gamma_n$  and  $\tilde{\gamma}$ . We deduce by Markov's inequality that

$$E|\hat{\gamma} - \gamma_n|^{2\nu} = s_n^{2\nu} + P[|\tilde{\gamma} - \gamma_n| > s_n]$$
  
=  $s_n^{2\nu} + \text{const.} \cdot n^{2\rho\mu} s_n^{-2\mu} \gamma_n^{2\mu} E \|\hat{\Gamma}' - \Gamma\|_{\text{HS}}^{2\mu}$ 

for any integer  $\mu$ . As all moments of  $||X_1||_2$  are finite by Condition T we derive that

$$E \| \hat{\Gamma}' - \Gamma \|_{\text{HS}}^{2\mu} = O((n-m)^{-\mu}).$$

where we recall that  $\hat{\Gamma}'$  is based on the training data set, thus on  $n - m \simeq n/\log n$  observations. As  $\rho < 1/2$  we conclude by suitable choice of  $(s_n)_n$  that

$$E|\hat{\gamma}-\gamma_n|^{2\nu}=O([o_n\gamma_n]^{2\nu}),$$

where  $(o_n)_n$  denotes some sequence tending to zero at an algebraic rate. Choosing  $\nu$  sufficiently large, we can finally verify (5.8) yielding the following proposition which summarizes the investigation carried out in this section.

PROPOSITION 5.1. We consider the FLR model in the setting of Theorem 4.1 except the condition that  $P_X$  is known. In addition, suppose that (5.3), (5.5) and  $\rho \in (\alpha/(2\alpha + 3), 1/2)$ . Then, estimator (5.1) with the weight selector (5.7), which does not use  $P_X$  in its definition, attains the sharp minimax rate and constant with respect to the mean integrated squared error; viewed uniformly over the function class  $\Theta$  which is defined via Condition T.

Hence, under some additional conditions on the model, we have established sharp minimaxity in the case where  $P_X$  is unknown. Only an arbitrary number between  $\alpha/(2\alpha + 3)$  and 1/2 is supposed to be known.

6. Discussion and conclusions. We have proved equivalence of the FLR model and a white noise model involving an empirical covariance operator in Theorem 3.1. We mention that  $\sigma$  and  $P_X$  can be treated as real nuisance parameters in Section 3; more precisely, knowledge of those quantities is not needed to apply the data transformations.

In contrast, for the asymptotic approximation in Section 4,  $P_X$  must be known. Nevertheless, Section 5 shows that, with respect to the MISE, the sharp asymptotic minimax risk can be taken over to the case of unknown design distribution. Furthermore, under specific parametric assumption on  $P_X$ , the condition of known  $P_X$ can obviously be justified. Cai and Hall [5] explicitly mention Gaussian processes

as examples for the random design functions  $X_j$ . For instance, assuming that  $X_j$  can be represented as  $X_j(t) = \int \xi(s) dW_j(s)$  with independent standard Wiener processes  $W_j$  as already suggested in the previous section, we realize that the function  $\xi$  is precisely reconstrucable based on only one observation  $X_1$ . Then as  $\xi$  is known the distribution  $P_X$  is known as well. Therefore, under this shape of  $P_X$ , the assumption of known  $P_X$  is not unrealistic at all. This phenomenon is typical for the functional data approach and does not occur in multivariate linear regression with finite-dimensional covariates. From that point of view, the assumption of known design distribution causes less trouble in FLR compared to more standard regression problems. Still this does not address the completely nonparametric case for  $P_X$  and  $\theta$ .

As an interesting restriction, we have assumed that  $\beta > (1 + \alpha)/2$  in Condition T. Therefore, the quality of the approximation of the target curve  $\theta$  in the orthonormal basis consisting of the eigenvalues of the covariance operator of the design variables must be sufficiently high. If this basis consisted of Fourier polynomials then that assumption could be interpreted as a smoothness condition on  $\theta$ . That corresponds to the theorems in [19] and [2] where Hölder conditions are imposed, which correspond to  $\beta > 1/2$ , in order to prove asymptotic equivalence of the white noise model on one hand and density estimation and nonparametric regression on the other hand. Otherwise, counterexamles can be constructed (see [3]). To our best knowledge our work represents the first proof of white noise equivalence in a statistical inverse problem. It seems reasonable that the essential condition is extended to  $\beta > (1 + \alpha)/2$  in this setting as the selection  $\alpha = 0$  describes the setting of direct estimation (noninverse problems). Still, the question of whether our results are extendable to some  $\beta \le (1 + \alpha)/2$  remains open. In Section 5 we have studied the case of unknown  $P_X$ ; however, the regularity parameter  $\beta$  is still assumed to be known. Therefore, another interesting problem, which cannot be addressed within the framework of this paper, is whether this sharp risk can be achieved by an adaptive estimator, which does not use  $\beta$  and  $C_{\Theta}$  in its construction. Approaches to adaptivity in FLR are studied in [4]; however, that report seems to focus on optimal rates rather than optimal constants.

Also, combining Theorem 4.1 and the results of Brown and Low [2], we conclude that, under reasonable conditions, the FLR model is also equivalent to the standard nonparametric regression problem, under which the data

$$Y_j = [\Gamma^{1/2}\theta](x_j) + \sigma\varepsilon_j, \qquad j = 1, \dots, n,$$

are observed where the  $\varepsilon_j$  are i.i.d. and N(0, 1)-distributed, and the homogeneous fixed design setting  $x_j = j/n$ , j = 1, ..., n, is applied.

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