TAIWANESE JOURNAL OF MATHEMATICS Vol. 16, No. 5, pp. 1749-1762, October 2012 This paper is available online at http://journal.taiwanmathsoc.org.tw

## SHEPHARD TYPE PROBLEMS FOR GENERAL L<sub>p</sub>-PROJECTION BODIES

Wang Weidong and Wan Xiaoyan

Abstract. Lutwak, Yang and Zhang introduced  $L_p$ -projection bodies and Ludwig defined general  $L_p$ -projection bodies. In this paper, a solution to the Shephard problem for general  $L_p$ -projection bodies is established.

## 1. INTRODUCTION

For the set of convex bodies (compact, convex subsets with non-empty interiors) in Euclidean space  $\mathbb{R}^n$ , we write  $\mathcal{K}^n$ . The set of convex bodies containing the origin in their interiors in  $\mathbb{R}^n$  we write  $\mathcal{K}^n_o$ . Denote by  $\mathcal{S}^n_o$  the set of star bodies (about the origin) in  $\mathbb{R}^n$ . Let  $S^{n-1}$  denote the unit sphere in  $\mathbb{R}^n$ , V(K) the *n*-dimensional volume of body K and  $\omega_n = V(B)$  the volume of the standard unit ball B in  $\mathbb{R}^n$ .

If  $K \in \mathcal{K}^n$ , then its support function  $h_K$  is defined by [3]:

$$h_K(x) = h(K, x) = max\{x \cdot y : y \in K\}, \quad x \in \mathbb{R}^n,$$

where  $x \cdot y$  denotes the standard inner product of x and y.

The classical projection body was introduced by Minkowski [3, 18] at the turn of the previous century. For each  $K \in \mathcal{K}^n$ , the classical projection body,  $\Pi K$ , of K is the origin-symmetric convex body whose support function is given by

(1.1) 
$$h_{\Pi K}(u) = \frac{1}{2} \int_{S^{n-1}} |u \cdot v| \, dS(K, v),$$

for all  $u \in S^{n-1}$ . Here  $S(K, \cdot)$  denotes the surface area measure of K. The classical projection body is a very important object for study in the Brunn-Mnkowski theory. In particular, Shephard in [19] asked the following question:

Received September 1, 2011, accepted November 30, 2011.

Communicated by Sun-Yung Alice Chang.

2010 Mathematics Subject Classification: 52A40, 52A20.

Key words and phrases: General  $L_p$ -projection body, Shephard problem,  $L_p$ -affine surface area.

Research is supported in part by the Natural Science Foundation of China (Grant No. 10671117) and Science Foundation of China Three Gorges University.

**Question 1.** Suppose  $K, L \in \mathcal{K}^n$ . If

 $\Pi K \subseteq \Pi L,$ 

is it true that

$$V(K) \le V(L)?$$

Question 1 is called the Shephard problem. Since  $h_{\Pi K}(u)$  is just the (n-1)dimensional volume of the image of the projection of K on the subspace orthogonal to u, it asks whether convex bodies with smaller projections in all directions must have smaller volume. For centrally symmetric convex bodies K and L, Question 1 was solved independently by Petty [15] and Schneider [17], who showed that the answer is affirmative if  $n \leq 2$  and negative if  $n \geq 3$ . They also proved that the Shephard problem has an affirmative answer if L is the projection body of some convex bodies.

The notion of  $L_p$ -projection body was introduced by Lutwak, Yang and Zhang [12]. For each  $K \in \mathcal{K}_o^n$  and  $p \ge 1$ , the  $L_p$ -projection body,  $\Pi_p K$ , of K is the origin-symmetric convex body whose support function is given by

(1.2) 
$$h^{p}_{\Pi_{p}K}(u) = \frac{1}{n\omega_{n}c_{n-2,p}} \int_{S^{n-1}} |u \cdot v|^{p} dS_{p}(K, v),$$

for all  $u \in S^{n-1}$ , and

(1.3) 
$$c_{n,p} = \omega_{n+p} / \omega_2 \omega_n \omega_{p-1}.$$

Here  $S_p(K, \cdot)$  denotes the  $L_p$ -surface area measure of  $K \in \mathcal{K}_o^n$ . Lutwak [10] showed that the measure  $S_p(K, \cdot)$  is absolutely continuous with respect to the classical surface area measure  $S(K, \cdot)$  of K, and has Radon-Nikodym derivative

(1.4) 
$$\frac{dS_p(K,\cdot)}{dS(K,\cdot)} = h_K^{1-p}$$

The unusual normalization of definition (1.2) is chosen so that for the unit ball, B, we have  $\Pi_p B = B$ . In particular, for p = 1, the convex body  $\Pi_1 K$  is a dilate of the classical projection body  $\Pi K$  of K and  $\Pi_1 B = B$ .

Whereas classical projection bodies are notion of the Brunn-Minkowski theory,  $L_p$ -projection bodies belong to the  $L_p$ -Brunn-Minkowski theory and have attracted a lot of attention (see [8, 9, 12, 13, 14, 16, 20, 22, 23, 24]). In particular, Ryabogin and Zvavitch in [16] considered the following Shephard problem for the  $L_p$ -projection bodies:

**Question 2.** Suppose  $K, L \in \mathcal{K}_o^n$  and  $p \ge 1$ . If

$$\Pi_p K \subseteq \Pi_p L$$

is it true that

$$V(K) \le V(L), \text{ for } 1 \le p < n,$$

and

$$V(K) \ge V(L), \text{ for } p > n?$$

For p = 1, Question 2 is equivalent to Question 1. For p > 1 and  $n \ge 2$ , it was proved in [16] that the answer is negative. If  $K, L \in \mathcal{K}_o^n$  and L is the  $L_p$ -projection body of some convex body, Ryabogin and Zvavitch [16] proved that Question 2 has an affirmative answer [16]. Recently, Ma and Wang [14] studied a  $L_p$ -affine surface area form of the Shephard problem for the  $L_p$ -projection bodies.

Recall that Ludwig [8] (see also [6]) introduced asymmetric  $L_p$ -projection bodies. For  $K \in \mathcal{K}_o^n$  and  $p \ge 1$ , the asymmetric  $L_p$ -projection body,  $\Pi_p^+ K$ , of K is defined by

(1.5) 
$$h^{p}_{\Pi^{+}_{p}K}(u) = \alpha_{n,p} \int_{S^{n-1}} (u \cdot v)^{p}_{+} dS_{p}(K, v),$$

where  $(u \cdot v)_+ = \max\{u \cdot v, 0\}$  and

(1.6) 
$$\alpha_{n,p} = \frac{1}{n\omega_n c_{n-2,p}}$$

From (1.6) and (1.5), we see  $\Pi_p^+ B = B$ . In [6] they also defined

(1.7) 
$$\Pi_p^- K = \Pi_p^+ (-K).$$

Further, authors in [6, 8] introduced a function  $\varphi_{\tau}: \mathbb{R} \longrightarrow [0, +\infty)$  by

(1.8) 
$$\varphi_{\tau}(t) = |t| + \tau t$$

for  $\tau \in [-1, 1]$ , and for  $K \in \mathcal{K}_o^n$ ,  $p \ge 1$ , let  $\Pi_p^{\tau} K \in \mathcal{K}_o^n$  be the convex body with support function

(1.9) 
$$h^p_{\Pi^{\tau}_p K}(u) = \alpha_{n,p}(\tau) \int_{S^{n-1}} \varphi_{\tau}(u \cdot v)^p dS_p(K, v),$$

where

(1.10) 
$$\alpha_{n,p}(\tau) = \frac{\alpha_{n,p}}{(1+\tau)^p + (1-\tau)^p}.$$

The normalization is chosen such that  $\Pi_p^{\tau}B = B$  for every  $\tau \in [-1, 1]$ . Here  $\Pi_p^{\tau}K$  may be called general  $L_p$ -projection body. Obviously, if  $\tau = 0$  then  $\Pi_p^{\tau}K = \Pi_p K$ .

From (1.5), (1.7) and (1.9), Haberl and Schuster in [6] showed that for  $K \in \mathcal{K}_o^n$ ,  $p \ge 1$  and  $\tau \in [-1, 1]$ ,

$$\Pi_p^{\tau} K = f_1(\tau) \cdot \Pi_p^+ K +_p f_2(\tau) \cdot \Pi_p^- K,$$

Wang Weidong and Wan Xiaoyan

where

$$f_1(\tau) = \frac{(1+\tau)^p}{(1+\tau)^p + (1-\tau)^p}, \qquad f_2(\tau) = \frac{(1-\tau)^p}{(1+\tau)^p + (1-\tau)^p},$$

and " $+_p$ " denotes the Firey  $L_p$ -combination of convex bodies.

Associating with asymmetric  $L_p$ -projection bodies, Haberl and Schuster in [6] established general  $L_p$ -Petty projection inequalities and gave the extremum values of volume for the polar of asymmetric  $L_p$ -projection bodies.

In this article, we study the following Shephard type problem for general  $L_p$ -projection bodies:

**Question 3.** Suppose  $K, L \in \mathcal{K}_o^n$ ,  $p \ge 1$  and  $\tau \in [-1, 1]$ . If

$$\Pi_p^{\tau} K \subseteq \Pi_p^{\tau} L,$$

is it true that

$$V(K) \le V(L), \text{ for } 1 \le p < n,$$

and

$$V(K) \ge V(L), \text{ for } p > n?$$

Associated with Question 3, we first give the following affirmative answer:

**Theorem 1.1.** Let  $K \in \mathcal{K}_o^n$ ,  $p \ge 1$  and  $\tau \in [-1, 1]$ . If  $L \in \mathcal{Z}_p^{\tau, n}$  and  $\Pi_p^{\tau} K \subseteq \Pi_p^{\tau} L$ , then for  $n > p \ge 1$ ,

$$V(K) \le V(L);$$

for n < p,

$$V(K) \ge V(L).$$

In each case equality holds for p = 1 if and only if K is a translate of L, and for p > 1 if and only if K = L.

Here  $\mathcal{Z}_p^{\tau,n}$  denotes the set of general  $L_p$ -projection bodies of a parameter  $\tau$ , that is, the set of convex bodies K such that there is a convex body L with  $K = \prod_n^{\tau} L$ .

The original Shephard problem is in a certain sense dual to the famous Busemann-Petty problem (see [3, 7] for the definition and the solution). The (symmetric)  $L_p$  version of the Busemann-Petty problem was solved in [4, 26]. General  $L_p$ -intersection bodies were introduced in [5]. Theorem 1.1 corresponds to the solution of the general  $L_p$  Busemann-Petty problem by Haberl [4].

Let  $\mathcal{F}_o^n$  denote the set of convex bodies in  $\mathcal{K}_o^n$  with positive continuous curvature function. Further, we get a  $L_p$ -affine surface area form of the Shephard type problem for general  $L_p$ -projection bodies.

**Theorem 1.2.** Let  $K \in \mathcal{F}_o^n$ ,  $p \ge 1$  and  $\tau \in [-1, 1]$ . If  $L \in \mathcal{W}_p^{\tau, n}$  and  $\Pi_p^{\tau} K \subseteq \Pi_p^{\tau} L$ , then

$$\Omega_p(K) \le \Omega_p(L),$$

with equality for p = 1 if and only if K is a translate of L, and for p > 1 if and only if K = L.

Here

$$\mathcal{W}_p^{\tau,n} = \{ Q \in \mathcal{F}_o^n : there \ exists \ Z \in \mathcal{Z}_p^{\tau,n} \ with \ f_p(Q,\cdot) = h(Z,\cdot)^{-(n+p)} \},$$

and where  $f_p(Q, \cdot)$  is the  $L_p$ -curvature function of Q (see Section 2.5).

In Section 3, we shall prove general forms of Theorems 1.1-1.2, respectively.

### 2. BASIC NOTIONS

### 2.1. Radial Function and Polar Body

If K is a compact star-shaped (about the origin) set in  $\mathbb{R}^n$ , its radial function,  $\rho_K = \rho(K, \cdot) : \mathbb{R}^n \setminus \{0\} \longrightarrow [0, +\infty)$ , is defined

$$\rho(K, x) = \max\{\lambda \ge 0 : \lambda x \in K\}, \quad x \in \mathbb{R}^n \setminus \{0\}.$$

If  $\rho_K$  is positive and continuous, K will be called a star body (about the origin). Two star bodies K and L are said to be dilates (of one another) if  $\rho_K(u)/\rho_L(u)$  is independent of  $u \in S^{n-1}$ .

If K is nonempty in  $\mathbb{R}^n$ , the polar set of K,  $K^*$ , is defined by [3]

$$K^* = \{ x \in \mathbb{R}^n : x \cdot y \le 1, y \in K \}.$$

# 2.2. Firey L<sub>p</sub>-Combination and L<sub>p</sub>-Harmonic Radial Combination

For  $K, L \in \mathcal{K}^n$ , and  $\lambda, \mu \ge 0$  (not both zero), the Minkowski linear combination,  $\lambda K + \mu L \in \mathcal{K}^n$ , of K and L is defined by

$$h(\lambda K + \mu L, \cdot) = \lambda h(K, \cdot) + \mu h(L, \cdot),$$

where  $\lambda K = \{\lambda x : x \in K\}.$ 

For  $K, L \in \mathcal{K}_o^n$ ,  $p \ge 1$  and  $\lambda, \mu \ge 0$  (not both zero), the Firey  $L_p$ -combination,  $\lambda \cdot K +_p \mu \cdot L \in \mathcal{K}_o^n$ , of K and L is defined in [2] by

(2.1) 
$$h(\lambda \cdot K +_p \mu \cdot L, \cdot)^p = \lambda h(K, \cdot)^p + \mu h(L, \cdot)^p,$$

where "  $\cdot$  " in  $\lambda \cdot K$  denotes the Firey scalar multiplication.

For  $K, L \in S_o^n$ ,  $p \ge 1$  and  $\lambda, \mu \ge 0$  (not both zero), the  $L_p$ -harmonic radial combination,  $\lambda \star K +_{-p} \mu \star L \in S_o^n$ , of K and L is defined in [11] by

Wang Weidong and Wan Xiaoyan

(2.2) 
$$\rho(\lambda \star K +_{-p} \mu \star L, \cdot)^{-p} = \lambda \rho(K, \cdot)^{-p} + \mu \rho(L, \cdot)^{-p}.$$

Note that for convex bodies, the  $L_p$ -harmonic radial combination was investigated by Firey in [1].

## **2.3.** $L_p$ -Mixed Volume

Associated with Firey  $L_p$ -combination (2.1), Lutwak in [10] introduced the following: For  $K, L \in \mathcal{K}_o^n$  and  $p \ge 1$ , the  $L_p$ -mixed volume,  $V_p(K, L)$ , of K and L can be defined by

$$\frac{n}{p}V_p(K,L) = \lim_{\varepsilon \longrightarrow 0^+} \frac{V(K +_p \varepsilon \cdot L) - V(K)}{\varepsilon}.$$

Corresponding to each  $K \in \mathcal{K}_o^n$ , Lutwak ([10]) proved that there is a positive Borel measure,  $S_p(K, \cdot)$ , on  $S^{n-1}$  such that

(2.3) 
$$V_p(K,L) = \frac{1}{n} \int_{S^{n-1}} h_L^p(v) dS_p(K,v).$$

for each  $L \in \mathcal{K}_o^n$ . The measure  $S_p(K, \cdot)$  is just the  $L_p$ -surface area measure of K.

From formulas (2.3) and (1.4), it follows immediately that for each  $K \in \mathcal{K}_o^n$ ,

(2.4) 
$$V_p(K,K) = V(K) = \frac{1}{n} \int_{S^{n-1}} h_K(v) dS(K,v).$$

The Minkowski inequality for the  $L_p$ -mixed volume is called  $L_p$ -Minkowski inequality. The  $L_p$ -Minkowski inequality may be stated:

**Theorem 2.A.** If  $K, L \in \mathcal{K}_o^n$  and  $p \ge 1$ , then

(2.5) 
$$V_p(K,L) \ge V(K)^{\frac{n-p}{n}} V(L)^{\frac{p}{n}}$$

with equality for p = 1 if and only if K and L are homothetic, for p > 1 if and only if K and L are dilates.

A simple consequence of Theorem 2.A was established in [11]:

**Theorem 2.B.** Let  $K, L \in \mathcal{K}_o^n$  and  $p \ge 1$ . For all  $Q \in \mathcal{K}_o^n$ ,

$$V_p(K,Q) = V_p(L,Q)$$
 or  $V_p(Q,K) = V_p(Q,L)$ 

if and only if K is translation of L for p = 1, or K = L for p > 1.

# 2.4. L<sub>p</sub>-Dual Mixed Volume

Using the  $L_p$ -harmonic radial combination (2.2), Lutwak [11] introduced the notion of  $L_p$ -dual mixed volume. For  $K, L \in S_o^n$  and  $p \ge 1$ , the  $L_p$ -dual mixed volume,  $\widetilde{V}_{-p}(K, L)$ , of K and L is defined by

Shephard Type Problems for General  $L_p$ -Projection Bodies

$$\frac{n}{-p}\widetilde{V}_{-p}(K,L) = \lim_{\varepsilon \longrightarrow 0^+} \frac{V(K + p \varepsilon \star L) - V(K)}{\varepsilon}.$$

The definition above and the polar coordinate formula for volume give the following integral representation of the  $L_p$ -dual mixed volume:

(2.6) 
$$\widetilde{V}_{-p}(K,L) = \frac{1}{n} \int_{S^{n-1}} \rho_K^{n+p}(v) \rho_L^{-p}(v) dS(v),$$

where the integration is with respect to spherical Lebesgue measure S on  $S^{n-1}$ .

From (2.6), it follows that for each  $K \in \mathcal{S}_o^n$  and  $p \ge 1$ ,

(2.7) 
$$\widetilde{V}_{-p}(K,K) = V(K) = \frac{1}{n} \int_{S^{n-1}} \rho_K^n(v) dS(v)$$

Lutwak [11] established the  $L_p$ -dual Minkowski inequality:

**Theorem 2.C.** If  $K, L \in S_o^n$  and  $p \ge 1$ , then

(2.8) 
$$\widetilde{V}_{-p}(K,L) \ge V(K)^{\frac{n+p}{n}}V(L)^{-\frac{p}{n}},$$

with equality if and only if K and L are dilates.

A simple consequence of Theorem 2.C was established in [25]:

**Theorem 2.D.** Let  $K, L \in S_o^n$  and  $p \ge 1$ , For all  $Q \in S_o^n$ ,

$$\widetilde{V}_{-p}(K,Q) = \widetilde{V}_{-p}(L,Q)$$
 or  $\widetilde{V}_{-p}(Q,K) = \widetilde{V}_{-p}(Q,L)$ 

if and only if K = L.

# **2.5.** L<sub>p</sub>-Affine Surface Area

The notion of  $L_p$ -affine surface area was introduced by Lutwak in [11].

A convex body  $K \in \mathcal{K}_o^n$  is said to have a  $L_p$ - curvature function [11]  $f_p(K, \cdot)$ :  $S^{n-1} \longrightarrow \mathbb{R}$ , if its  $L_p$ -surface area measure  $S_p(K, \cdot)$  is absolutely continuous with respect to spherical Lebesgue measure S, and

(2.9) 
$$\frac{dS_p(K,\cdot)}{dS} = f_p(K,\cdot).$$

In [11], Lutwak proved that if  $K \in \mathcal{F}_o^n$  and  $p \ge 1$ , then the  $L_p$ -affine surface area of K have the integral representation

(2.10) 
$$\Omega_p(K) = \int_{S^{n-1}} f_p(K, u)^{\frac{n}{n+p}} dS(u).$$

Wang and Leng in [21] defined the *i*th  $L_p$ -mixed affine surface area as follows: For  $K, L \in \mathcal{F}_o^n$ ,  $p \ge 1$  and real *i*, the *i*th  $L_p$ -mixed affine surface area,  $\Omega_{p,i}(K, L)$ , of K and L is defined by

(2.11) 
$$\Omega_{p,i}(K,L) = \int_{S^{n-1}} f_p(K,u)^{\frac{n-i}{n+p}} f_p(L,u)^{\frac{i}{n+p}} dS(u).$$

In the case i = -p, we write  $\Omega_{p,-p}(K,L) = \Omega_{-p}(K,L)$  and see by (2.11) that

(2.12) 
$$\Omega_{-p}(K,L) = \int_{S^{n-1}} f_p(K,u) f_p(L,u)^{-\frac{p}{n+p}} dS(u).$$

If p = 1, then  $\Omega_{1,-1}(K, L)$  is just  $\Omega_{-1}(K, L)$  (see [9]). Obviously,

(2.13) 
$$\Omega_{-p}(K,K) = \Omega_p(K).$$

For the *i*th  $L_p$ -mixed affine surface area, Wang and Leng in [21] proved the following Minkowski inequality.

**Theorem 2.E.** If  $K, L \in \mathcal{F}_{o}^{n}$ ,  $p \geq 1$ ,  $i \in \mathbb{R}$ , then for i < 0 or i > n,

(2.14) 
$$\Omega_{p,i}(K,L)^n \ge \Omega_p(K)^{n-i}\Omega_p(L)^i$$

for 0 < i < n, inequality (2.14) is reversed. In every case, equality holds for p = 1 if and only if K and L are homothetic, for  $n \neq p > 1$  if and only if K and L are dilates. For i = 0 or i = n, (2.14) is an identity.

For i = -p in (2.14), we get that if  $K, L \in \mathcal{F}_o^n$ ,  $p \ge 1$ , then

(2.15) 
$$\Omega_{-p}(K,L)^n \ge \Omega_p(K)^{n+p} \Omega_p(L)^{-p},$$

with equality for p = 1 if and only if K and L are homothetic, for  $n \neq p > 1$  if and only if K and L are dilates.

From (2.15), we easily obtain that

**Theorem 2.F.** Let  $K, L \in \mathcal{F}_{o}^{n}$  and  $p \geq 1$ . For all  $Q \in \mathcal{F}_{o}^{n}$ ,

$$\Omega_{-p}(K,Q) = \Omega_{-p}(L,Q)$$

if and only if K is translation of L for p = 1, or if and only if K = L for p > 1.

## 2.6. General L<sub>p</sub>-Moment Bodies

Ludwig in [8] (also see [6]) introduced the notion of general  $L_p$ -moment body as follows: For  $K \in S_o^n$ ,  $p \ge 1$  and  $\tau \in [-1, 1]$ , the general  $L_p$ -moment body,  $M_p^{\tau}K$ , of K is the convex body whose support function is given by

(2.16) 
$$h_{M_p^{\tau}K}^p(u) = (n+p)\alpha_{n,p}(\tau) \int_K \varphi_{\tau}(u \cdot x)^p dx$$

for all  $u \in S^{n-1}$ . Here  $\varphi_{\tau}(u \cdot v)$  and  $\alpha_{n,p}(\tau)$  satisfy (1.8) and (1.10), respectively.

Using definitions (1.9) and (2.16), Haberl and Schuster ([6]) proved the following result:

**Theorem 2.G.** If  $K \in \mathcal{K}_o^n$ ,  $L \in \mathcal{S}_o^n$ ,  $p \ge 1$  and  $\tau \in [-1, 1]$ , then

(2.17)  $V_p(K, M_n^{\tau}L) = \widetilde{V}_{-p}(L, \Pi_n^{\tau,*}K).$ 

## 3. Shephard Type Problems

In the section, we will study Shephard type problems for general  $L_p$ -projection bodies. We first give a general version of Theorem 1.1. It may be regarded as an extension of the Shephard type problem to general  $L_p$ -projection bodies.

**Theorem 3.1.** Let  $K, L \in \mathcal{K}_o^n$ ,  $p \ge 1$  and  $\tau \in [-1, 1]$ . If  $\Pi_p^{\tau} K \subseteq \Pi_p^{\tau} L$ , then for every  $Q \in \mathcal{Z}_p^{\tau,n}$ ,

$$(3.1) V_p(K,Q) \le V_p(L,Q),$$

with equality for p = 1 if and only if K is a translate of L, and for p > 1 if and only if K = L.

**Lemma 3.1.** If  $K, L \in \mathcal{K}_o^n, p \ge 1$  and  $\tau \in [-1, 1]$ , then

(3.2) 
$$V_p(K, \Pi_p^{\tau}L) = V_p(L, \Pi_p^{\tau}K).$$

*Proof.* From (1.8) and (2.3), we easily obtain

$$V_{p}(L, \Pi_{p}^{\tau}K) = \frac{1}{n} \int_{S^{n-1}} h_{\Pi_{p}^{\tau}K}^{p}(u) dS_{p}(L, u)$$
  
$$= \frac{1}{n} \int_{S^{n-1}} \alpha_{n,p}(\tau) \int_{S^{n-1}} \varphi_{\tau}(u \cdot v)^{p} dS_{p}(K, v) dS_{p}(L, u)$$
  
$$= \frac{1}{n} \int_{S^{n-1}} h_{\Pi_{p}^{\tau}L}^{p}(v) dS_{p}(K, v)$$
  
$$= V_{p}(K, \Pi_{p}^{\tau}L).$$

Proof of Theorem 3.1. Since  $Q \in \mathbb{Z}_p^{\tau,n}$ , there exists  $M \in \mathcal{K}_o^n$  such that  $Q = \prod_p^{\tau} M$ . Thus by (3.2) and (2.3) we get

$$\frac{V_p(L,Q)}{V_p(K,Q)} = \frac{V_p(L,\Pi_p^{\tau}M)}{V_p(K,\Pi_p^{\tau}M)} = \frac{V_p(M,\Pi_p^{\tau}L)}{V_p(M,\Pi_p^{\tau}K)}$$

$$=\frac{\displaystyle\int_{S^{n-1}}h(\Pi_p^{\tau}L,u)^pdS_p(M,u)}{\displaystyle\int_{S^{n-1}}h(\Pi_p^{\tau}K,u)^pdS_p(M,u)}.$$

If  $\Pi_p^{\tau} K \subseteq \Pi_p^{\tau} L$ , this implies (3.1).

According to Theorem 2.B, we know equality holds in (3.1) for p = 1 if and only if K is a translate of L, and for p > 1 if and only if K = L. Obviously, above the condition of equality implies  $\Pi_p^{\tau} K = \Pi_p^{\tau} L$ .

*Proof of Theorem 1.1.* Since  $L \in \mathbb{Z}_p^{\tau,n}$ , taking Q = L in Theorem 3.1, and combining with (2.4) and inequality (2.5), we get

$$V(L) \ge V_p(K,L) \ge V(K)^{\frac{n-p}{n}} V(L)^{\frac{p}{n}}.$$

Hence, for  $n > p \ge 1$ ,  $V(K) \le V(L)$ ; for n < p,  $V(K) \ge V(L)$ .

Now, associated with the  $L_p$ -affine surface area, we give a general form of Theorem 1.2.

**Theorem 3.2.** Let  $K, L \in \mathcal{F}_o^n$ ,  $p \ge 1$  and  $\tau \in [-1, 1]$ . If  $\Pi_p^{\tau} K \subseteq \Pi_p^{\tau} L$ , then for every  $Q \in \mathcal{W}_p^{\tau,n}$ ,

(3.3) 
$$\Omega_{-p}(K,Q) \le \Omega_{-p}(L,Q),$$

with equality for p = 1 if and only if K is a translate of L, and for  $n \neq p > 1$  if and only if K = L.

*Proof.* Since  $Q \in \mathcal{W}_p^{\tau,n}$ , there exists  $Z \in \mathcal{Z}_p^{\tau,n}$  such that

$$f_p(Q,\cdot)^{-\frac{p}{n+p}} = h(Z,\cdot)^p$$

Moreover, for  $Z \in \mathbb{Z}_p^{\tau,n}$ , let  $Z = \prod_p^{\tau} M$  for  $M \in \mathcal{K}_o^n$ . Hence, using (2.9), (2.12), (2.3) and (3.2), we have

$$\begin{aligned} \frac{\Omega_{-p}(L,Q)}{\Omega_{-p}(K,Q)} &= \frac{\int_{S^{n-1}} f_p(Q,u)^{-\frac{p}{n+p}} dS_p(L,u)}{\int_{S^{n-1}} f_p(Q,u)^{-\frac{p}{n+p}} dS_p(K,u)} \\ &= \frac{\int_{S^{n-1}} h(Z,u)^p dS_p(L,u)}{\int_{S^{n-1}} h(Z,u)^p dS_p(K,u)} \\ &= \frac{V_p(L,Z)}{V_p(K,Z)} = \frac{V_p(L,\Pi_p^{\tau}M)}{V_p(K,\Pi_p^{\tau}M)} = \frac{V_p(M,\Pi_p^{\tau}L)}{V_p(M,\Pi_p^{\tau}K)} \\ &= \frac{\int_{S^{n-1}} h(\Pi_p^{\tau}L,u)^p dS_p(M,u)}{\int_{S^{n-1}} h(\Pi_p^{\tau}K,u)^p dS_p(M,u)}. \end{aligned}$$

If  $\Pi_p^{\tau} K \subseteq \Pi_p^{\tau} L$ , this implies (3.3).

According to Theorem 2.F, we know that equality holds in (3.3) for p = 1 if and only if K is a translate of L, and for p > 1 if and only if K = L. Obviously, above the condition of equality implies  $\Pi_p^{\tau} K = \Pi_p^{\tau} L$ .

Note that the case  $\tau = 0$  of Theorem 3.1 and Theorem 3.2 can be found in [13].

*Proof of Theorem 1.2.* Since  $L \in W_p^{\tau,n}$ , taking Q = L in Theorem 3.2, and together with (2.13) and inequality (2.15), we get

$$\Omega_p(L) \ge \Omega_{-p}(K,L) \ge \Omega_p(K)^{\frac{n+p}{n}} \Omega_p(L)^{-\frac{p}{n}},$$

----

i.e.,

$$\Omega_p(K) \le \Omega_p(L).$$

### 4. MONOTONICITY INEQUALITIES

Regarding Theorem 3.1, we can prove the following monotonicity inequalities for the general  $L_p$ -projection bodies.

**Theorem 4.1.** Let 
$$K, L \in \mathcal{K}_{o}^{n}$$
,  $p \geq 1$  and  $\tau \in [-1, 1]$ . If

(4.1) 
$$V_p(K,Q) \le V_p(L,Q),$$

then for every  $Q \in \mathcal{Z}_p^{\tau,n}$ ,

(4.2) 
$$V(\Pi_p^{\tau}K) \le V(\Pi_p^{\tau}L).$$

In every inequality equality holds for p = 1 if and only if K is a translate of L, and for p > 1 if and only if K = L.

*Proof of Theorem 4.1.* Since  $Q \in \mathbb{Z}_p^{\tau,n}$ , we take  $Q = \prod_p^{\tau} M$  for  $M \in \mathcal{K}_o^n$ . From this, (4.1) can be written as

$$V_p(K, \Pi_p^{\tau} M) \le V_p(L, \Pi_p^{\tau} M).$$

Together with (3.2), we get

$$V_p(M, \Pi_p^{\tau} K) \le V_p(M, \Pi_p^{\tau} L).$$

Letting  $M = \prod_{n=1}^{\tau} L$ , and using (2.4) and inequality (2.5), we have

$$V(\Pi_p^{\tau}L) \ge V_p(\Pi_p^{\tau}L, \Pi_p^{\tau}K) \ge V(\Pi_p^{\tau}L)^{\frac{n-p}{n}} V(\Pi_p^{\tau}K)^{\frac{p}{n}},$$

i.e., (4.2) is obtained.

According to Theorem 2.B, we see that the equality condition of (4.1) implies  $V(\Pi_p^{\tau}K) = V(\Pi_p^{\tau}L)$ . Therefore, we know that equalities hold in (4.1) and (4.2) for p = 1 if and only if K is a translate of L, and for p > 1 if and only if K = L.

**Theorem 4.2.** Let  $K, L \in \mathcal{K}_o^n$ ,  $p \ge 1$  and  $\tau \in [-1, 1]$ . If for every general  $L_p$ -moment body Q

(4.3) 
$$V_p(K,Q) \le V_p(L,Q),$$

then

(4.4) 
$$V(\Pi_p^{\tau,*}K) \ge V(\Pi_p^{\tau,*}L).$$

In every inequality equality holds for p = 1 if and only if K is a translate of L, and for p > 1 if and only if K = L.

*Proof.* Since Q is an general  $L_p$ -moment body, we take  $Q = M_p^{\tau} N$  for  $N \in S_o^n$ , inequality (4.3) can be written as

$$V_p(K, M_p^{\tau}N) \le V_p(L, M_p^{\tau}N).$$

This together with (2.17) gives

$$\widetilde{V}_{-p}(N, \Pi_p^{\tau,*}K) \le \widetilde{V}_{-p}(N, \Pi_p^{\tau,*}L)$$

Taking  $N = \prod_{p=1}^{\tau,*} L$ , using (2.7) and inequality (2.8), we get

$$V(\Pi_{p}^{\tau,*}L) \geq \widetilde{V}_{-p}(\Pi_{p}^{\tau,*}L,\Pi_{p}^{\tau,*}K) \geq V(\Pi_{p}^{\tau,*}L)^{\frac{n+p}{n}}V(\Pi_{p}^{\tau,*}K)^{-\frac{p}{n}}.$$

This yields (4.4).

According to Theorem 2.D, we see that the equality condition of (4.3) implies  $V(\Pi_p^{\tau,*}K) = V(\Pi_p^{\tau,*}L)$ . Therefore, we know that equality hold in (4.3) and (4.4) if and only if K = L.

#### ACKNOWLEDGMENT

The authors are most grateful to the referees for the extraordinary attention they gave to our paper.

### References

- W. J. Firey, Mean cross-section measures of harmonic means of convex bodies, *Pacific J. Math.*, **11** (1961), 1263-1266.
- 2. W. J. Firey, p-means of convex bodies, Math. Scand., 10 (1962), 17-24.

- 3. R. J. Gardner, *Geometric Tomography*, Cambridge Univ. Press, Cambridge, UK, 2nd ed., 2006.
- 4. C. Haberl, L<sub>p</sub> intersection bodies, Adv. Math., 217(6) (2008), 2599-2624.
- 5. C. Haberl and M. Ludwig, A characterization of  $L_p$  intersection bodies, International Mathematics Research Notices, Art ID 10548, 2006.
- C. Haberl and F. Schuster, General L<sub>p</sub> affine isoperimetric inequalities, J. Differential Geom., 83(1) (2009), 1-26.
- 7. A. Koldobsky, *Fourier analysis in convex geometry*, Mathematical Surveys and Monographs, 116, American Mathematical Society, Providence, RI, 2005.
- 8. M. Ludwig, Minkowski valuations, Trans. Amer. Math. Soc., 357 (2005), 4191-4213.
- 9. E. Lutwak, Centroid bodies and dual mixed volumes, *Proc. London Math. Soc.*, **60** (1990), 365-391.
- 10. E. Lutwak, The Brunn-Minkowski-Firey theory I: mixed volumes and the Minkowski problem, *J. Differential Geom.*, **38** (1993), 131-150.
- 11. E. Lutwak, The Brunn-Minkowski-Firey theory II: affine and geominimal surface areas, *Adv. Math.*, **118** (1996), 244-294.
- E. Lutwak, D. Yang and G. Y. Zhang, L<sub>p</sub> affine isoperimetric inequalities, J. Differential Geom., 56 (2000), 111-132.
- 13. S. J. Lv and G. S. Leng, The L<sub>p</sub>-curvature images of convex bodies and L<sub>p</sub>-projection bodies, *Proc. Indian Acad. Sci. Math. Sci.*, **118** (2008), 413-424.
- 14. T. Y. Ma and W. D. Wang, On the Analog of Shephard problem for the  $L_p$ -projection body, *Math. Inequal. Appl.*, **14(1)** (2011), 181-192.
- C. M. Petty, *Projection bodies*, Proc. Coll. Convexity, Copenhagen, 1965, Kφbenhavns Univ. Math. Inst., 1967, pp. 234-241.
- D. Ryabogin and A. Zvavitch, The Fourier transform and Firey projections of convex bodies, *Indiana Univ. Math. Journal*, 53 (2004), 667-682.
- 17. R. Schneider, Zu einem Problem von Shephard über Projectionen konvexer Körper, *Math. Z.*, **101** (1967), 71-82.
- 18. R. Schneider, *Convex Bodies: The Brunn-Minkowski Theory*, Cambridge Univ. Press, Cambridge, 1993.
- 19. G. C. Shephard, Shadow systems of convex bodies, Israel J. Math., 2 (1964), 229-236.
- 20. W. D. Wang, F. H. Lu and G. S. Leng, A type of monotonicity on the  $L_p$  centroid body and  $L_p$  projection body, *Math. Inequal. Appl.*, **8(4)** (2005), 735-742.
- W. D. Wang and G. S. Leng, L<sub>p</sub>-mixed affine surface area, J. Math. Anal. Appl., 335(1) (2007), 341-354.
- 22. W. D. Wang and G. S. Leng, The Petty projection inequality for L<sub>p</sub>-mixed projection bodies, *Acta Math. Sinica (English Series)*, **23(8)** (2007), 1485-1494.

- 23. W. D. Wang and G. S. Leng, On the L<sub>p</sub>-versions of the Petty's conjectured projection inequality and applications, *Taiwan J. Math.*, **12(5)** (2008), 1067-1086.
- 24. W. D. Wang and G. S. Leng, Some affine isoperimetric inequalities associated with  $L_p$ -affine surface area, *Houston J. Math.*, **34(2)** (2008), 443-453.
- 25. W. D. Wang, D. J. Wei and Y. Xiang, Some inequalities for the *L<sub>p</sub>*-curvature image, *J. Inequal. Appl.*, (2010), 1-12.
- 26. J. Yuan and W. S. Cheung, *L<sub>p</sub>*-intersection bodies, *J. Math. Anal. Appl.*, **339(2)** (2008), 1431-1439.

Wang Weidong and Wan Xiaoyan Department of Mathematics China Three Gorges University Yichang 443002 P. R. China E-mail: wdwxh722@163.com