# TWO OPTIMAL INEQUALITIES FOR ANTI-HOLOMORPHIC SUBMANIFOLDS AND THEIR APPLICATIONS 

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#### Abstract

The $C R \delta$-invariant for $C R$-submanifolds was introduced by B.-Y. Chen in a recent article [13]. In this paper, we prove two new optimal inequalities for anti-holomorphic submanifolds in complex space forms involving the $C R \delta$-invariant. Moreover, we obtain some classification results for certain antiholomorphic submanifolds in complex space forms which satisfy the equality case of either inequality.


## 1. Introduction

Let $\tilde{M}$ be a Kähler manifold with complex structure $J$ and let $N$ be a Riemannian manifold isometrically immersed in $\tilde{M}$. For each point $x \in N$, we denote by $\mathcal{D}_{x}$ the maximal complex subspace $T_{x} N \cap J\left(T_{x} N\right)$ of the tangent space $T_{x} N$ of $N$. If the dimension of $\mathcal{D}_{x}$ is the same for all $x \in N$, then $\left\{\mathcal{D}_{x}, x \in N\right\}$ defines a holomorphic distribution $\mathcal{D}$ on $N$. A subspace $\mathcal{V}$ of $T_{x} N, x \in N$, is called totally real if $J(\mathcal{V})$ is a subspace of the normal space $T_{x}^{\perp} N$ at $x$. A submanifold $N$ of a Kahler manifold is called a totally real submanifold if each tangent space of $N$ is totally real.

A submanifold $N$ of a Kahler manifold $M$ is called a $C R$-submanifold if there exists a totally real distribution $\mathcal{D}^{\perp}$ on $N$ whose orthogonal complement is the holomorphic distribution $\mathcal{D}$ (cf. [1, 8, 12]), i.e.,

$$
T N=\mathcal{D} \oplus \mathcal{D}^{\perp}, \quad J \mathcal{D}_{x}^{\perp} \subset T_{x}^{\perp} N, \quad x \in N
$$

Throughout this paper, we denote by $h$ the complex rank of the holomorphic distribution $\mathcal{D}$ and by $p$ the (real) rank of the totally real distribution $\mathcal{D}^{\perp}$ for a $C R$-submanifold. A

[^0]warped product submanifold $N^{T} \times{ }_{f} N^{\perp}$ with warping function $f$ in a Kahler manifold $\tilde{M}$ is called a $C R$-warped product if $N^{T}$ is a holomorphic submanifold and $N^{\perp}$ is a totally real submanifold of $\tilde{M}$.

It is well-known that the totally real distribution $\mathcal{D}^{\perp}$ of every $C R$-submanifold of a Kähler manifold is an integrable distribution (cf. [8, 10, 12]).

In order to provide some answers to an open question concerning minimal immersions proposed by S. S. Chern in the 1960s and to provide some applications of the well-known Nash embedding theorem, the second author introduced in early 1990s the notion of $\delta$-invariants (see $[6,12,14,20]$ for details). For a $C R$-submanifold $N$ of a Kähler manifold, he introduced in [13] a $\delta$-invariant $\delta(\mathcal{D})$, called the $C R \delta$-invariant, defined by

$$
\begin{equation*}
\delta(\mathcal{D})(x)=\tau(x)-\tau\left(\mathcal{D}_{x}\right), \tag{1.1}
\end{equation*}
$$

where $\tau$ is the scalar curvature of $N$ and $\tau(\mathcal{D})$ is the scalar curvature of the holomorphic distribution $\mathcal{D}$ of $N$ (see [12] for details). In [13], the second author established a sharp inequality involving the $C R \delta$-invariant $\delta(\mathcal{D})$ for anti-holomorphic warped product submanifolds in complex space forms.

In this paper, we prove two new optimal inequalities involving the $C R \delta$-invariant for arbitrary anti-holomorphic submanifolds in complex space forms. Moreover, we obtain some classification results for anti-holomorphic submanifolds in complex space forms which satisfy the equality case of either inequality.

## 2. Preliminaries

### 2.1. Basic definitions and formulas

Let $N$ be a Riemannian $n$-manifold equipped with an inner product $\langle$,$\rangle . Denote$ by $\nabla$ the Levi-Civita connection of $N$.

Assume that $N$ is isometrically immersed in a Kahler manifold $\tilde{M}$. Then the formulas of Gauss and Weingarten are given respectively by (cf. [5, 12])

$$
\begin{align*}
& \tilde{\nabla}_{X} Y=\nabla_{X} Y+\sigma(X, Y),  \tag{2.1}\\
& \tilde{\nabla}_{X} \xi=-A_{\xi} X+D_{X} \xi, \tag{2.2}
\end{align*}
$$

for vector fields $X$ and $Y$ tangent to $N$ and $\xi$ normal to $N$, where $\tilde{\nabla}$ denotes the Levi-Civita connection on $\tilde{M}, \sigma$ is the second fundamental form, $D$ is the normal connection, and $A$ is the shape operator of $N$.

The second fundamental form $\sigma$ and the shape operator $A$ are related by

$$
\begin{equation*}
\left\langle A_{\xi} X, Y\right\rangle=\langle\sigma(X, Y), \xi\rangle, \tag{2.3}
\end{equation*}
$$

where $\langle$,$\rangle is the inner product on N$ as well as on $\tilde{M}$. The mean curvature vector of $N$ is defined by

$$
\begin{equation*}
\vec{H}=\left(\frac{1}{n}\right) \operatorname{trace} \sigma, \quad n=\operatorname{dim} N \tag{2.4}
\end{equation*}
$$

The squared mean curvature $H^{2}$ is given by $H^{2}=\langle\vec{H}, \vec{H}\rangle$.
The equation of Gauss is

$$
\begin{align*}
R(X, Y ; Z, W)= & \tilde{R}(X, Y ; Z, W)+\langle\sigma(X, W), \sigma(Y, Z)\rangle  \tag{2.5}\\
& -\langle\sigma(X, Z), \sigma(Y, W)\rangle
\end{align*}
$$

for vectors $X, Y, Z, W$ tangent to $N$, where $R$ and $\tilde{R}$ denote the Riemann curvature tensors of $N$ and $\tilde{M}$, respectively.

For the second fundamental form $\sigma$, we define its covariant derivative $\bar{\nabla} \sigma$ with respect to the connection on $T N \oplus T^{\perp} N$ by

$$
\begin{equation*}
\left(\bar{\nabla}_{X} \sigma\right)(Y, Z)=D_{X}(\sigma(Y, Z))-\sigma\left(\nabla_{X} Y, Z\right)-\sigma\left(Y, \nabla_{X} Z\right) . \tag{2.6}
\end{equation*}
$$

The equation of Codazzi is

$$
\begin{equation*}
(\tilde{R}(X, Y) Z)^{\perp}=\left(\bar{\nabla}_{X} \sigma\right)(Y, Z)-\left(\bar{\nabla}_{Y} \sigma\right)(X, Z), \tag{2.7}
\end{equation*}
$$

for vectors $X, Y, Z$ tangent to $N$, where $(\tilde{R}(X, Y) Z)^{\perp}$ denotes the normal component of $\tilde{R}(X, Y) Z$.

### 2.2. Real hypersurfaces

A real hypersurface $N$ of a Kahler manifold $\tilde{M}$ is called a Hopf hypersurface if $J \xi$ is a principal curvature vector, i.e., an eigenvector of the shape operator $A_{\xi}$, where $\xi$ is a unit normal vector of $N$. Obviously, every Hopf hypersurface is mixed totally geodesic.

A real hypersurface $N$ of a Kähler manifold $\tilde{M}$ with $\operatorname{dim}_{\mathbf{C}} \tilde{M}=m$ is called totally real $m$-ruled if for each point $x \in N$ there exists an $m$-dimensional totally real totally geodesic submanifold $V_{x}^{m}$ of $N$ through $x$.

### 2.3. Complex space forms

A Kähler manifold of constant holomorphic sectional curvature is called a complex space form. Throughout this paper, we denote a complete, simply-connected (complex) $m$-dimensional complex space form of constant holomorphic sectional curvature $4 c$ by $\tilde{M}^{m}(4 c)$.

It is well-known that $\tilde{M}^{m}(4 c)$ is holomorphically isometric to the complex projective $m$-space $C P^{m}(4 c)$, the complex Euclidean $m$-space $\mathbf{C}^{m}$, or the complex hyperbolic $m$-space $C H^{m}(4 c)$ according to $c>0, c=0$, or $c<0$, respectively.

The curvature tensor $\tilde{R}$ of a complex space form $\tilde{M}^{m}(4 c)$ satisfies

$$
\begin{align*}
\tilde{R}(U, V, W)= & c\{\langle V, W\rangle U-\langle X, W\rangle V+\langle J V, W\rangle J U  \tag{2.8}\\
& -\langle J U, W\rangle J V+2\langle U, J V\rangle J W\}
\end{align*}
$$

### 2.4. Anti-holomorphic submanifolds and $C R$-submanifolds

A $C R$-submanifold $N$ of a Kähler manifold $\tilde{M}$ is called anti-holomorphic if we have

$$
J \mathcal{D}_{x}^{\perp}=T_{x}^{\perp} N, \quad x \in N .
$$

A $C R$-submanifold is called mixed totally geodesic if its second fundamental form $\sigma$ satisfies $\sigma(X, Z)=0$ for any $X \in \mathcal{D}$ and $Z \in \mathcal{D}^{\perp}$.

A mixed totally geodesic $C R$-submanifold is called mixed foliate if its holomorphic distribution $\mathcal{D}$ is also integrable. Moreover, a $C R$-submanifold $N$ is called a $C R$ product if it is a Riemannian product of a holomorphic submanifold $N^{T}$ and a totally real submanifold $N^{\perp}$ of $\tilde{M}$.

Obviously, real hypersurfaces of a Kähler manifold are exactly anti-holomorphic submanifolds with $p=\operatorname{rank} \mathcal{D}^{\perp}=1$.

## 2.5. $H$-umbilical Lagrangian submanifolds

An anti-holomorphic submanifold of a Kähler manifold is called Lagrangian if $\mathcal{D}=\{0\}$, i.e.,

$$
J\left(T_{x} N\right)=T_{x}^{\perp} N, \quad x \in N
$$

A Lagrangian submanifold is said to be $H$-umbilical if its second fundamental form satisfies the following simple form (cf. [7]):

$$
\begin{align*}
& \sigma\left(e_{1}, e_{1}\right)=\varphi J e_{1}, \quad \sigma\left(e_{1}, e_{j}\right)=\psi J e_{j}, \\
& \sigma\left(e_{2}, e_{2}\right)=\cdots=\sigma\left(e_{n}, e_{n}\right)=\psi J e_{1},  \tag{2.9}\\
& \sigma\left(e_{j}, e_{k}\right)=0, \quad j \neq k, \quad j, k=2, \ldots, n,
\end{align*}
$$

for some suitable functions $\varphi$ and $\psi$ with respect to some suitable orthonormal local frame field $\left\{e_{1}, \ldots, e_{n}\right\}$.

Since there do not exist umbilical Lagrangian submanifold in Kâhler manifolds, $H$-umbilical Lagrangian submanifolds are the simplest Lagrangian submanifolds next to totally geodesic one (cf. [7]).

## 3. Some Basic Lemmas for $C R$-Submanifolds

We need the following two lemmas from $[1,8]$ for later use.
Lemma 3.1. Let $N$ be a $C R$-submanifold of a Kähler manifold $\tilde{M}$. Then we have:
(1) the totally real distribution $\mathcal{D}^{\perp}$ is an integrable distribution,
(2) $\langle\sigma(U, J X), J Z\rangle=\left\langle\nabla_{U} X, Z\right\rangle$,
(3) $A_{J Z} W=A_{J W} Z$,
for vector field $U$ tangent to $N, X, Y$ in $\mathcal{D}$, and $Z, W$ in $\mathcal{D}^{\perp}$.
Lemma 3.2. Let $N$ be a $C R$-submanifold of a Kähler manifold $\tilde{M}$. Then we have:
(1) the holomorphic distribution $\mathcal{D}$ is integrable if and only if

$$
\begin{equation*}
\langle\sigma(X, J Y), J Z\rangle=\langle\sigma(J X, Y), J Z\rangle \tag{3.1}
\end{equation*}
$$

holds for any $X, Y \in \mathcal{D}$ and $Z \in \mathcal{D}^{\perp}$,
(2) the leaves of the totally real distribution $\mathcal{D}^{\perp}$ are totally geodesic in $N$ if and only if

$$
\begin{equation*}
\langle\sigma(X, Z), J W\rangle=0 \tag{3.2}
\end{equation*}
$$

holds for any $X \in \mathcal{D}$ and $Z, W \in \mathcal{D}^{\perp}$.
We also recall the following result for later use.
Lemma 3.3. A complex space form $\tilde{M}^{m}(4 c)$ with $c \neq 0$ admits no mixed foliate proper $C R$-submanifolds.

Lemma 3.3 is due to [2] for $c>0$ and due to [16] for $c<0$.
For mixed foliate $C R$-submanifolds in a complex Euclidean space, we have the following result from [8].

Lemma 3.4. Let $N$ be a $C R$-submanifold of $\mathbf{C}^{m}$. Then $N$ is mixed foliate if and only if $N$ is a $C R$-product.

We also need the following result from [8, Theorem 4.6].
Lemma 3.5. Every $C R$-product in a complex Euclidean $m$-space $\mathbf{C}^{m}$ is a direct product of a holomorphic submanifold of a linear complex subspace and a totally real submanifold of another linear complex subspace.
4. An Inequality for Anti-holomorphic Submanifolds with $p \geq 2$

Let $N$ be a $C R$-submanifold of a Kähler manifold. Denote by $\mathcal{D}$ and $\mathcal{D}^{\perp}$ the holomorphic distribution and the totally real distribution of $N$ as before. For a $C R$ submanifold $N$, let us choose a local orthonormal frame $\left\{e_{1}, \ldots, e_{2 h+p}\right\}$ on $N$ in such
way that $e_{1}, \ldots, e_{h}, e_{h+1}, \ldots, e_{2 h}$ are in $\mathcal{D}$ and $e_{2 h+1}, \ldots, e_{2 h+p}$ are in $\mathcal{D}^{\perp}$, where $e_{h+1}=J e_{1}, \ldots, e_{2 h}=J e_{h}$.

The $C R \delta$-invariant, denoted by $\delta(\mathcal{D})$, for a $C R$-submanifold $N$ with $p=\operatorname{rank} \mathcal{D}^{\perp}$ $\geq 1$ is defined by (see [13] for details)

$$
\begin{equation*}
\delta(\mathcal{D})(x)=\tau(x)-\tau\left(\mathcal{D}_{x}\right) \tag{4.1}
\end{equation*}
$$

where $\tau$ and $\tau(\mathcal{D})$ denote the scalar curvature of $N$ and the scalar curvature of the holomorphic distribution $\mathcal{D} \subset T N$, respectively.

Through out this paper, we shall use the following convention on the range of indices unless mentioned otherwise:

$$
\begin{gathered}
i, j, k=1, \ldots, 2 h ; \alpha, \beta, \gamma=1, \ldots, h \\
r, s, t=2 h+1, \ldots, 2 h+p ; A, B, C=1, \ldots, 2 h+p
\end{gathered}
$$

For a $C R$-submanifold $N$ we define the two partial mean curvature vectors $\vec{H}_{\mathcal{D}}$ and $\vec{H}_{\mathcal{D}^{\perp}}$ of $N$ by

$$
\begin{equation*}
\vec{H}_{\mathcal{D}}=\frac{1}{2 h} \sum_{i=1}^{2 h} \sigma\left(e_{i}, e_{i}\right), \quad \vec{H}_{\mathcal{D}^{\perp}}=\frac{1}{p} \sum_{r=2 h+1}^{2 h+p} \sigma\left(e_{r}, e_{r}\right) \tag{4.2}
\end{equation*}
$$

An anti-holomorphic submanifold $N$ of a Kahler manifold $\tilde{M}$ is called minimal (resp., $\mathcal{D}$-minimal or $\mathcal{D}^{\perp}$-minimal) if $H=0$ holds identical (resp., $\vec{H}_{\mathcal{D}}=0$ or $\vec{H}_{\mathcal{D}^{\perp}}=$ 0 hold identically).

We define the coefficients of the second fundamental form by

$$
\sigma_{A B}^{r}=\left\langle\sigma\left(e_{A}, e_{B}\right), J e_{r}\right\rangle
$$

for $A, B=1, \ldots, 2 h+p$ and $r=1, \ldots, p$.
For anti-holomorphic submanifolds with $p=\operatorname{rank} \mathcal{D}^{\perp} \geq 2$, we have the following optimal inequality.

Theorem 4.1. Let $N$ be an anti-holomorphic submanifold of a complex space form $\tilde{M}^{h+p}(4 c)$ with $h=\operatorname{rank}_{\mathbf{C}} \mathcal{D} \geq 1$ and $p=\operatorname{rank} \mathcal{D}^{\perp} \geq 2$. Then we have

$$
\begin{equation*}
\delta(\mathcal{D}) \leq \frac{(p-1)(2 h+p)^{2}}{2(p+2)} H^{2}+\frac{p}{2}(4 h+p-1) c \tag{4.3}
\end{equation*}
$$

The equality sign of (4.3) holds identically if and only if the following three conditions are satisfied:
(a) $N$ is $\mathcal{D}$-minimal, i.e., $\vec{H}_{\mathcal{D}}=0$,
(b) $N$ is mixed totally geodesic, and
(c) there exist an orthonormal frame $\left\{e_{2 h+1}, \ldots, e_{n}\right\}$ of $\mathcal{D}^{\perp}$ such that the second fundamental $\sigma$ of $N$ satisfies

$$
\begin{cases}\sigma_{r r}^{r}=3 \sigma_{s s}^{r}, & \text { for } 2 h+1 \leq r \neq s \leq 2 h+p,  \tag{4.4}\\ \sigma_{s t}^{r}=0, & \text { for distinct } r, s, t \in\{2 h+1, \ldots, 2 h+p\}\end{cases}
$$

Proof. Let $N$ be an anti-holomorphic submanifold in a complex space form $\tilde{M}^{h+p}(4 c)$. Let us choose an orthonormal frame $\left\{e_{1}, \ldots, e_{2 h+p}\right\}$ on $N$ as above.

It follows from the equation of Gauss and the definition of $C R \delta$-invariant that $\delta(\mathcal{D})$ satisfies

$$
\begin{align*}
\delta(\mathcal{D})= & \sum_{i=1}^{2 h} \sum_{r=2 h+1}^{2 h+p} K\left(e_{i}, e_{r}\right)+\sum_{2 h+1 \leq r \neq s \leq 2 h+p} \frac{1}{2} K\left(e_{r}, e_{s}\right) \\
= & \sum_{i=1}^{2 h} \sum_{r=2 h+1}^{2 h+p}\left\langle\sigma\left(e_{i}, e_{i}\right), \sigma\left(e_{r}, e_{r}\right)\right\rangle+\sum_{r, s=2 h+1}^{2 h+p} \frac{1}{2}\left\langle\sigma\left(e_{r}, e_{r}\right), \sigma\left(e_{s}, e_{s}\right)\right\rangle  \tag{4.5}\\
& -\sum_{i=1}^{2 h} \sum_{r=2 h+1}^{2 h+p}\left\|\sigma\left(e_{i}, e_{r}\right)\right\|^{2}-\sum_{r, s=2 h+1}^{2 h+p} \frac{1}{2}\left\|\sigma\left(e_{r}, e_{s}\right)\right\|^{2} \\
& +\frac{p}{2}(4 h+p-1) c .
\end{align*}
$$

On the other hand, we have

$$
\begin{align*}
\sum_{i=1}^{2 h} & \sum_{r=2 h+1}^{2 h+p}\left\langle\sigma\left(e_{i}, e_{i}\right), \sigma\left(e_{r}, e_{r}\right)\right\rangle+\sum_{r, s=2 h+1}^{2 h+p} \frac{1}{2}\left\langle\sigma\left(e_{r}, e_{r}\right), \sigma\left(e_{s}, e_{s}\right)\right\rangle \\
& -\sum_{r, s=2 h+1}^{2 h+p} \frac{1}{2}\left\|\sigma\left(e_{r}, e_{s}\right)\right\|^{2}  \tag{4.6}\\
\quad= & \frac{(2 h+p)^{2}}{2} H^{2}-2 h^{2}\left|\vec{H}_{\mathcal{D}}\right|^{2}-\frac{1}{2}\left\|\sigma_{\mathcal{D}^{\perp}}\right\|^{2},
\end{align*}
$$

where $\left\|\sigma_{\mathcal{D}^{\perp}}\right\|^{2}$ is defined by

$$
\begin{equation*}
\left\|\sigma_{\perp}\right\|^{2}=\sum_{r, s=2 h+1}^{2 h+p}\left\|\sigma\left(e_{r}, e_{s}\right)\right\|^{2} . \tag{4.7}
\end{equation*}
$$

By combining (4.5) and (4.6) we find

$$
\begin{align*}
\delta(\mathcal{D})= & \frac{(2 h+p)^{2}}{2} H^{2}+\frac{p}{2}(4 h+p-1) c-2 h^{2}\left|\vec{H}_{\mathcal{D}}\right|^{2} \\
& -\sum_{i=1}^{2 h} \sum_{r=2 h+1}^{2 h+p}\left\|\sigma\left(e_{i}, e_{r}\right)\right\|^{2}-\frac{1}{2}\left\|\sigma_{\mathcal{D}^{\perp}}\right\|^{2} . \tag{4.8}
\end{align*}
$$

It follows from statement (2) of Lemma 3.1 the coefficients of the second fundamental form satisfy

$$
\begin{equation*}
\sigma_{s t}^{r}=\sigma_{r t}^{s}=\sigma_{r s}^{t} . \tag{4.9}
\end{equation*}
$$

We find from (4.2), (4.7) and (4.9) that

$$
\begin{align*}
& (p+2)\left\|\sigma_{\mathcal{D}^{\perp}}\right\|^{2}-3 p^{2}\left|H_{\mathcal{D}^{\perp}}\right|^{2}=(p-1) \sum_{r=2 h+1}^{2 h+p}\left(\sum_{s=2 h+1}^{2 h+p} \sigma_{s s}^{r}\right)^{2} \\
& \quad+\sum_{2 h+1 \leq r \neq s \leq 2 h+p} 3(p+1)\left(\sigma_{s s}^{r}\right)^{2}+\sum_{2 h+1 \leq r<s<t \leq 2 h+p} 6(p+2)\left(\sigma_{s t}^{r}\right)^{2} \\
& \quad+\sum_{r=2 h+1}^{2 h+p} \sum_{2 h+1 \leq s<t \leq 2 h+p} 2(p+2) \sigma_{s s}^{r} \sigma_{t t}^{r} \\
& =\sum_{r=2 h+1}^{2 h+p}(p-1)\left(\sigma_{r r}^{r}\right)^{2}+\sum_{2 h+1 \leq r \neq s \leq 2 h+p} 3(p+1)\left(\sigma_{s s}^{r}\right)^{2}  \tag{4.10}\\
& \quad+\sum_{2 h+1 \leq r<s<t \leq 2 h+p} 6(p+2)\left(\sigma_{s t}^{r}\right)^{2}-\sum_{r=2 h+1}^{2 h+p} \sum_{2 h+1 \leq s<t \leq 2 h+p} 6 \sigma_{s s}^{r} \sigma_{t t}^{r} \\
& = \\
& \sum_{2 h+1 \leq r<s<t \leq 2 h+p} 6(p+2)\left(\sigma_{s t}^{r}\right)^{2}+\sum_{2 h+1 \leq s \neq r \leq 2 h+p}\left(\sigma_{r r}^{r}-3 \sigma_{s s}^{r}\right)^{2} \\
& \quad+\sum_{r \neq s, t} \sum_{2 h+1 \leq s<t \leq 2 h+p} 3\left(\sigma_{s s}^{r}-\sigma_{t t}^{r}\right)^{2} \\
& \geq 0 .
\end{align*}
$$

Thus we get

$$
\begin{equation*}
\left\|\sigma_{\mathcal{D}^{\perp}}\right\|^{2} \geq \frac{3 p^{2}}{p+2}\left|H_{\mathcal{D}^{\perp}}\right|^{2} \tag{4.11}
\end{equation*}
$$

with equality holding if and only if

$$
\begin{array}{ll}
\sigma_{r r}^{r}=3 \sigma_{s s}^{r}, & \text { for } 2 h+1 \leq r \neq s \leq 2 h+p  \tag{4.12}\\
\sigma_{s t}^{r}=0, & \text { for distinct } r, s, t \in\{2 h+1, \ldots, 2 h+p\}
\end{array}
$$

Now, by combining (4.8) and (4.11), we obtain

$$
\begin{align*}
& \frac{(2 h+p)^{2}}{2} H^{2}+\frac{p}{2}(4 h+p-1) c-\delta(\mathcal{D}) \\
& \quad \geq 2 h^{2}\left|\vec{H}_{\mathcal{D}}\right|^{2}+\sum_{i=1}^{2 h} \sum_{r=2 h+1}^{2 h+p}\left\|\sigma\left(e_{i}, e_{r}\right)\right\|^{2}+\frac{3 p^{2}}{2(p+2)}\left|H_{\mathcal{D}^{\perp}}\right|^{2} \tag{4.13}
\end{align*}
$$

$$
\begin{aligned}
& =\frac{3}{2(p+2)}\left\{(2 h+p)^{2} H^{2}-4 h^{2}\left|\vec{H}_{\mathcal{D}}\right|^{2}-2 \sum_{i=1}^{2 h} \sum_{r=2 h+1}^{2 h+p}\left\|\sigma\left(e_{i}, e_{r}\right)\right\|^{2}\right\} \\
& +2 h^{2}\left|\vec{H}_{\mathcal{D}}\right|^{2}+\sum_{i=1}^{2 h} \sum_{r=2 h+1}^{2 h+p}\left\|\sigma\left(e_{i}, e_{r}\right)\right\|^{2} \\
& =\frac{3(2 h+p)^{2}}{2(p+2)} H^{2}+\frac{2 h^{2}(p-1)}{p+2}\left|\vec{H}_{\mathcal{D}}\right|^{2}+\frac{p-1}{p+2} \sum_{i=1}^{2 h} \sum_{r=2 h+1}^{2 h+p}\left\|\sigma\left(e_{i}, e_{r}\right)\right\|^{2} \\
& \geq \frac{3(2 h+p)^{2}}{2(p+2)} H^{2} .
\end{aligned}
$$

It is obvious that the equality of the last inequality in (4.13) holds if and only if $N$ is $\mathcal{D}$-minimal and mixed totally geodesic. Consequently, we may obtain inequality (4.3) from (4.13).

It is straightforward to verify that the equality sign of (4.3) holds identically if and only if conditions (a), (b) and (c) of Theorem 4.1 are satisfied.

## 5. Anti-holomorphic Submanifolds with $p \geq 2$ satisfying Equality

First, we give the following example satisfying the equality case of (4.3).
Example 5.1. Let $w: S^{p}(1) \rightarrow \mathbf{C}^{p}, p \geq 2$, be the map of the unit $p$-sphere $S^{p}(1)$ into $\mathbf{C}^{p}$ defined by

$$
w\left(y_{0}, y_{1}, \ldots, y_{p}\right)=\frac{1+\mathrm{i} y_{0}}{1+y_{0}^{2}}\left(y_{1}, \ldots, y_{p}\right), \quad y_{0}^{2}+y_{1}^{2}+\ldots+y_{p}^{2}=1
$$

The map $w$ is a (non-isometric) Lagrangian immersion with one self-intersection point. This immersion is called the Whitney $p$-sphere. It is well-known that Whitney spheres are the only $H$-umbilical Lagrangian submanifolds of the complex Euclidean spaces satisfying $\alpha=3 \beta \neq 0$ in (2.8) (see for instance, [4, 12]).

Consider the product immersion:

$$
\phi: \mathbf{C}^{h} \times S^{p}(1) \rightarrow \mathbf{C}^{h} \oplus \mathbf{C}^{p}=\mathbf{C}^{h+p}
$$

defined by

$$
\begin{equation*}
\phi(z, x)=(z, w(x)), \quad \forall z \in \mathbf{C}^{h}, \quad \forall x \in S^{p}(1) . \tag{5.1}
\end{equation*}
$$

It is straight-forward to verify that $\phi$ is an anti-holomorphic isometric immersion which satisfies the equality sign of (4.3) identically.

In this section we provide the following two classification theorems for antiholomorphic submanifolds satisfying the equality case of (4.3) identically.

Theorem 5.1. Let $N$ be an anti-holomorphic submanifold of a complex space form $\tilde{M}^{h+p}(4 c)$ with $h=\operatorname{rank}_{\mathbf{C}} \mathcal{D} \geq 1$ and $p=\operatorname{rank} \mathcal{D}^{\perp} \geq 2$. If $N$ satisfies the equality case of (4.3) identically and if the holomorphic distribution $\mathcal{D}$ is integrable, then $c=0$ so that $\tilde{M}^{h+p}(4 c)=\mathbf{C}^{h+p}$. Moreover, either
(i) $N$ is a totally geodesic anti-holomorphic submanifold of $\mathbf{C}^{h+p}$ or,
(ii) up to dilations and rigid motions of $\mathbf{C}^{h+p}, N$ is given by an open portion of the following product immersion:

$$
\phi: \mathbf{C}^{h} \times S^{p}(1) \rightarrow \mathbf{C}^{h+p} ; \quad(z, x) \mapsto(z, w(x)), \quad z \in \mathbf{C}^{h}, x \in S^{p}(1)
$$

where $w: S^{p}(1) \rightarrow \mathbf{C}^{p}$ is the Whitney p-sphere defined in Example 5.1.
Proof. Assume that $N$ is an anti-holomorphic submanifold of a complex space form $\tilde{M}^{h+p}(4 c)$ with $h=\operatorname{rank}_{\mathbf{C}} \mathcal{D} \geq 1$ and $p=\operatorname{rank} \mathcal{D}^{\perp} \geq 2$. If $N$ satisfies the equality case of (4.3) and if the holomorphic distribution $\mathcal{D}$ is integrable, then it follows from Theorem 4.1 that $N$ is mixed foliate. Hence Lemma 3.3 implies that $c=0$. Therefore, according to Lemma 3.4, $N$ is a $C R$-product. Hence, $N$ is locally a $C R$-product given by

$$
\mathbf{C}^{h} \times N^{\perp} \subset \mathbf{C}^{h} \times \mathbf{C}^{p}
$$

where $\mathbf{C}^{h}$ is a complex Euclidean $h$-subspace and $N^{\perp}$ is a Lagrangian submanifold of $\mathbf{C}^{p}$. Consequently, condition (c) of Theorem 4.1 implies that $N^{\perp}$ is a Lagrangian $H$-umbilical submanifold in $\mathbf{C}^{p}$ whose second fundamental form satisfying

$$
\begin{align*}
& \sigma\left(e_{2 h+1}, e_{2 h+1}\right)=3 \lambda J e_{2 h+1}, \quad \sigma\left(e_{2 h+1}, e_{s}\right)=\lambda J e_{s} \\
& \sigma\left(e_{2 h+2}, e_{2 h+2}\right)=\cdots=\sigma\left(e_{2 h+p}, e_{2 h+p}\right)=\lambda J e_{2 h+1}  \tag{5.2}\\
& \sigma\left(e_{r}, e_{s}\right)=0, \quad 2 h+2 \leq r \neq s \leq 2 h+p
\end{align*}
$$

for some suitable function $\lambda$ with respect to some suitable orthonormal local frame field $\left\{e_{2 h+1}, \ldots, e_{2 h+p}\right\}$ of $T N^{\perp}$.

If $\lambda=0$, then $N^{\perp}$ is an open portion of a totally geodesic totally real $p$-plane in $\mathbf{C}^{p}$. Hence, in this case $N$ is a totally geodesic anti-holomorphic submanifold.

If $\lambda \neq 0$, it follows from (5.2) that, up to dilations and rigid motions, $N^{\perp}$ is an open part of the Whitney $p$-sphere in $\mathbf{C}^{p}$ (cf. [4, 12]). Therefore, up to dilations and rigid motions of $\mathbf{C}^{h+p}$ the anti-holomorphic submanifold is locally given by the product immersion:

$$
\begin{equation*}
\phi: \mathbf{C}^{h} \times S^{p}(1) \rightarrow \mathbf{C}^{h+p} ; \quad(z, x) \mapsto(z, w(x)) \tag{5.3}
\end{equation*}
$$

for $z \in \mathbf{C}^{h}$ and $x \in S^{p}(1)$, where $w: S^{p}(1) \rightarrow \mathbf{C}^{p}$ is the Whitney $p$-sphere.
The converse is easy to verify.

Theorem 5.2. Let $N$ be an anti-holomorphic submanifold in a complex space form $\tilde{M}^{1+p}(4 c)$ with $h=\operatorname{rank}_{\mathbf{C}} \mathcal{D}=1$ and $p=\operatorname{rank} \mathcal{D}^{\perp} \geq 2$. Then we have

$$
\begin{equation*}
\delta(\mathcal{D}) \leq \frac{(p-1)(p+2)^{2}}{2(p+2)} H^{2}+\frac{p}{2}(p+3) c . \tag{5.4}
\end{equation*}
$$

The equality case of (5.4) holds identically if and only if $c=0$ and either
(i) $N$ is a totally geodesic anti-holomorphic submanifold of $\mathbf{C}^{h+p}$ or,
(ii) up to dilations and rigid motions, $N$ is given by an open portion of the following product immersion:

$$
\phi: \mathbf{C} \times S^{p}(1) \rightarrow \mathbf{C}^{1+p} ; \quad(z, x) \mapsto(z, w(x)), \quad z \in \mathbf{C}, x \in S^{p}(1)
$$

where $w: S^{p}(1) \rightarrow \mathbf{C}^{p}$ is the Whitney $p$-sphere.
Proof. Let $N$ be an anti-holomorphic submanifold in a complex space form $\tilde{M}^{1+p}(4 c)$. Then we have inequality (5.4) from inequality (4.3).

Assume that $N$ satisfies the equality case of (5.4) identically. Then Theorem 4.1 implies that $N$ satisfies conditions (a), (b) and (c) of Theorem 4.1.

By condition (a), $N$ is $\mathcal{D}$-minimal. Thus we find

$$
\begin{equation*}
\sigma\left(J e_{1}, J e_{1}\right)=-\sigma\left(e_{1}, e_{1}\right) \tag{5.5}
\end{equation*}
$$

for any unit vector $e_{1} \in \mathcal{D}$. It is direct to verify from (5.5) and polarization that the second fundamental form satisfies the following condition:

$$
\sigma(X, J Y)=\sigma(J X, Y), \quad \forall X, Y \in \mathcal{D}
$$

Therefore, according to Lemma 3.2(1), we may conclude that $\mathcal{D}$ is integrable. Consequently, we obtain Theorem 5.2 from Theorem 5.1.

## 6. An Optimal Inequality for Real Hypersurfaces

Clearly, anti-holomorphic submanifolds with $\operatorname{rank} \mathcal{D}^{\perp}=1$ are nothing but real hypersurfaces. The Ricci tensor Ric of real hypersurfaces in complex space forms have been studied in [11, 17, 19] among others.

In the following, a Hopf hypersurface $N$ is called special if $J \xi$ is an eigenvector of $A_{\xi}$ with eigenvalue 0 , i.e., $A_{\xi}(J \xi)=0$, where $\xi$ is a unit normal vector field.

For real hypersurfaces, we have the following.
Theorem 6.1. If $N$ is a real hypersurface of a complex space form $\tilde{M}^{h+1}(4 c)$, then the Ricci tensor Ric of $N$ satisfies

$$
\begin{equation*}
\operatorname{Ric}(J \xi, J \xi) \leq \frac{(2 h+1)^{2}}{2} H^{2}+2 h c . \tag{6.1}
\end{equation*}
$$

where $\xi$ is a unit normal vector field of $N$ in $\tilde{M}^{h+1}(4 c)$.
The equality sign of (6.1) holds identically if and only if $N$ is a minimal special Hopf hypersurface.

Proof. Let $N$ be a real hypersurface of a complex space form $\tilde{M}^{h+1}(4 c)$. Then it follows from the definition of $\delta(\mathcal{D})$ that

$$
\begin{equation*}
\delta(\mathcal{D})=\operatorname{Ric}(J \xi, J \xi) \tag{6.2}
\end{equation*}
$$

Let us choose an orthonormal frame $\left\{e_{1}, \ldots, e_{h}, e_{h+1}=J e_{1}, \ldots, e_{2 h}=J e_{h}\right\}$ for the holomorphic distribution $\mathcal{D}$ and let $e_{2 h+1}$ be a unit vector field in $\mathcal{D}^{\perp}$.

We put

$$
\begin{equation*}
\sigma_{a, b}=\left\langle\sigma\left(e_{a}, e_{b}\right), J e_{2 h+1}\right\rangle, \quad a, b=1, \ldots, 2 h+1 \tag{6.3}
\end{equation*}
$$

Let us define the connection forms by

$$
\begin{align*}
& \nabla_{X} e_{i}=\sum_{j=1}^{2 h} \omega_{i}^{j}(X) e_{j}+\omega_{i}^{2 h+1}(X) e_{2 h+1} \\
& \nabla_{X} e_{2 h+1}=\sum_{j=1}^{2 h} \omega_{2 h+1}^{j}(X) e_{j} \tag{6.4}
\end{align*}
$$

for $i=1, \ldots, 2 h$. It follows from (4.1) and the equation of Gauss that

$$
\begin{equation*}
\delta(\mathcal{D})=\sum_{i=1}^{2 h} \sigma_{i, i} \sigma_{2 h+1,2 h+1}-\sum_{i=1}^{2 h}\left(\sigma_{i, 2 h+1}\right)^{2}+2 h c \tag{6.5}
\end{equation*}
$$

On the other hand, we have

$$
\begin{equation*}
\sum_{i=1}^{2 h} \sigma_{i, i} \sigma_{2 h+1,2 h+1}=\frac{(2 h+1)^{2}}{2} H^{2}-\frac{1}{2}\left(\sigma_{2 h+1,2 h+1}\right)^{2}-2 h^{2}\left|\vec{H}_{\mathcal{D}}\right|^{2} \tag{6.6}
\end{equation*}
$$

By combining (6.6) and (6.6) we obtain

$$
\begin{align*}
\delta(\mathcal{D})= & \frac{(2 h+1)^{2}}{2} H^{2}+2 h c-2 h^{2}\left|\vec{H}_{\mathcal{D}}\right|^{2}-\frac{1}{2}\left(\sigma_{2 h+1,2 h+1}\right)^{2} \\
& -\sum_{i=1}^{2 h}\left(\sigma_{i, 2 h+1}\right)^{2}  \tag{6.7}\\
\leq & \frac{(2 h+1)^{2}}{2} H^{2}+2 h c .
\end{align*}
$$

It follows from (6.7) and Lemma 3.2(2) that the equality sign of inequality (6.1) holds identically if and only if the following two statements hold:
(i) $N$ is a special Hopf hypersurface and
(ii) $N$ is $\mathcal{D}$-minimal in $\tilde{M}^{h+1}(4 c)$.

Obviously, conditions (i) and (ii) imply that $N$ is a minimal real hypersurface of $\tilde{M}^{h+1}(4 c)$.

The converse is easy to verify.
The following corollary follows easily from Theorem 6.1.
Corollary 6.1. Let $N$ be a real hypersurface of a complex space form $\tilde{M}^{h+1}(4 c)$. If $N$ satisfies the equality case of (6.1) identically, then the holomorphic distribution of $N$ is non-integrable, unless $c=0$ and $N$ is totally geodesic.

Proof. Under the hypothesis, if $N$ satisfies the equality case of (6.1) identically and if the holomorphic distribution $\mathcal{D}$ is integrable, then Theorem 6.1 implies that $N$ is mixed foliate. So, it follows from Lemma 3.3 and Lemma 3.4 that $c=0$ and $N$ is a $C R$-product of a complex $h$-subspace in $\mathbf{C}^{h}$ and an open portion of line in $\mathbf{C}$. Consequently, $N$ must be totally geodesic.

## 7. Some Applications of Theorem 6.1

We need the following lemma.
Lemma 7.1. Let $N$ be a special Hopf hypersurface of a complex space form $\tilde{M}^{h+1}(4 c)$. Then there exist an orthonormal frame $\left\{e_{1}, \ldots, e_{h}, e_{h+1}=J e_{1}, \ldots, e_{2 h}=\right.$ $\left.J e_{h}\right\}$ of $\mathcal{D}$ and an integer $k \leq h$ such that

$$
\begin{align*}
& \sigma\left(e_{\alpha}, e_{\beta}\right)=\lambda_{\alpha} \delta_{\alpha \beta} \xi, \quad \sigma\left(e_{h+\alpha}, e_{h+\beta}\right)=\mu_{\alpha} \delta_{\alpha \beta} \xi, \quad 1 \leq \alpha, \beta \leq k ;  \tag{7.1}\\
& \sigma\left(e_{a}, e_{b}\right)=0, \text { otherwise }
\end{align*}
$$

with $\lambda_{\alpha} \mu_{\alpha}=c$, where $\kappa_{1}, \ldots, \kappa_{k}$ are nonzero functions.
Proof. Let $N$ be a special Hopf hypersurface of $\tilde{M}^{h+1}(4 c)$ and let $e_{2 h+1}$ be a unit vector field in $\mathcal{D}^{\perp}$. Then $\xi=J e_{2 h+1}$ is a unit normal vector field. Thus we have

$$
\begin{equation*}
\sigma\left(U, e_{2 h+1}\right)=0, \quad U \in T N . \tag{7.2}
\end{equation*}
$$

For an eigenvector $X$ of $A_{\xi}$ with eigenvalue $\kappa \neq 0$, we may choose an orthonormal frame $\left\{e_{1}, \ldots, e_{h}, e_{h+1}=J e_{1}, \ldots, e_{2 h}=J e_{h}\right\}$ with $e_{1}=X$. Hence we find

$$
\begin{equation*}
A_{\xi}\left(e_{1}\right)=\kappa e_{1} . \tag{7.3}
\end{equation*}
$$

From (6.3), (6.4) and Lemma 3.1(2) we derive that

$$
\begin{align*}
& \omega_{\alpha}^{2 h+1}\left(e_{\beta}\right)=\sigma_{\alpha+h, \beta}, \quad \omega_{h+\alpha}^{2 h+1}\left(e_{\beta}\right)=-\sigma_{\alpha, \beta}, \\
& \omega_{\alpha}^{2 h+1}\left(e_{h+\beta}\right)=\sigma_{h+\alpha, h+\beta}, \quad \omega_{h+\alpha}^{2 h+1}\left(e_{h+\beta}\right)=-\sigma_{\alpha, h+\beta} . \tag{7.4}
\end{align*}
$$

It follows from (2.8) that

$$
\begin{equation*}
\left(\tilde{R}\left(e_{\alpha}, e_{h+\beta}\right) e_{2 h+1}\right)^{\perp}=-2 c \delta_{\alpha \beta} J e_{2 h+1} \tag{7.5}
\end{equation*}
$$

On the other hand, we find from (7.2), (7.4) and the equation of Codazzi that

$$
\begin{align*}
\left(\tilde{R}\left(e_{\alpha}, e_{h+\beta}\right) e_{2 h+1}\right)^{\perp} & =\left(\bar{\nabla}_{e_{\alpha}} \sigma\right)\left(e_{h+\beta}, e_{2 h+1}\right)-\left(\bar{\nabla}_{e_{h+\beta}} \sigma\right)\left(e_{\alpha}, e_{2 h+1}\right) \\
& =2 \sum_{\gamma=1}^{h}\left(\sigma_{\alpha, h+\gamma} \sigma_{\gamma, h+\beta}-\sigma_{\alpha, \gamma} \sigma_{h+\beta, h+\gamma}\right) J e_{2 h+1} \tag{7.6}
\end{align*}
$$

By combining (7.5) and (7.6) we find

$$
\begin{equation*}
\sum_{\gamma=1}^{h}\left(\sigma_{\alpha, \gamma} \sigma_{h+\beta, h+\gamma}-\sigma_{\alpha, h+\gamma} \sigma_{\gamma, h+\beta}\right)=c \delta_{\alpha \beta}, \quad 1 \leq \alpha, \beta \leq h \tag{7.7}
\end{equation*}
$$

Also, it follows from $\left(\tilde{R}\left(e_{\beta}, e_{\alpha}\right) e_{2 h+1}\right)^{\perp}=\sigma\left(e_{\alpha}, \nabla_{e_{\beta}} e_{2 h+1}\right)-\sigma\left(e_{\beta}, \nabla_{e_{\alpha}} e_{2 h+1}\right)$ that

$$
\begin{equation*}
\sum_{\gamma=1}^{h}\left(\sigma_{\alpha, h+\gamma} \sigma_{\beta, \gamma}-\sigma_{\alpha, \gamma} \sigma_{\beta, h+\gamma}\right)=0 \tag{7.8}
\end{equation*}
$$

Condition (7.3) gives

$$
\begin{equation*}
\sigma_{11}=\kappa \neq 0, \quad \sigma_{1 a}=0, \quad \text { otherwise } \tag{7.9}
\end{equation*}
$$

Now, by combining (7.7), (7.8) and (7.9) we obtain

$$
\kappa \sigma_{1^{*} 1^{*}}=c \text { and } \sigma_{1^{*} a}=0, \text { for } a=1, \ldots, h, 2^{*}, \ldots, h^{*}
$$

which implies that $J X=e_{1^{*}}$ is an eigenvector of $A_{\xi}$ with eigenvalue $c / \kappa$. By applying this fact, we conclude the lemma.

Remark 7.1. Lemma 7.1 is due to [18] and [3] for $c>0$ and $c<0$, respectively,
Lemma 7.1 implies the following two lemmas.
Lemma 7.2. If $N$ is a special Hopf hypersurface of $\mathbf{C}^{h+1}$, then there exists an orthonormal frame $\left\{e_{1}, \ldots, e_{h}, e_{h+1}=J e_{1}, \ldots, e_{2 h}=J e_{h}\right\}$ of $\mathcal{D}$ and an integer $k \leq h$ such that

$$
\begin{equation*}
\sigma\left(e_{\alpha}, e_{\beta}\right)=\lambda_{\alpha} \delta_{\alpha \beta} \xi, \quad \sigma\left(e_{a}, e_{b}\right)=0, \text { otherwise } \tag{7.10}
\end{equation*}
$$

for $1 \leq \alpha, \beta \leq k$, where $\lambda_{1}, \ldots, \lambda_{k}$ are nonzero functions.

Proof. Under the hypothesis, Lemma 7.1 implies that there is an orthonormal frame $\left\{e_{1}, \ldots, e_{h}, e_{h+1}=J e_{1}, \ldots, e_{2 h}=J e_{h}\right\}$ of $\mathcal{D}$ such that

$$
\begin{align*}
& \sigma\left(e_{\alpha}, e_{\beta}\right)=\lambda_{\alpha} \delta_{\alpha \beta} \xi, \quad \sigma\left(e_{h+\gamma}, e_{h+\eta}\right)=\mu_{\gamma} \delta_{\gamma \eta} \xi \\
& \sigma\left(e_{a}, e_{b}\right)=0, \text { otherwise }  \tag{7.11}\\
& 1 \leq \alpha, \beta \leq n_{1} ; \quad n_{1}+1 \leq \gamma, \eta \leq n_{1}+n_{2}
\end{align*}
$$

where $n_{1}, n_{2}$ are integers and $\lambda_{1}, \ldots, \lambda_{n_{1}+n_{2}}$ are functions. Thus, after replacing

$$
e_{n_{1}+1}, \ldots, e_{n_{1}+n_{2}}, J e_{n_{1}+1}, \ldots, J e_{n_{1}+n_{2}} \mu_{n_{1}+1}, \ldots, \mu_{n_{1}+n_{2}}
$$

by $J e_{n_{1}+1}, \ldots, J e_{n_{1}+n_{2}},-e_{n_{1}+1}, \ldots,-e_{n_{1}+n_{2}}, \lambda_{n_{1}+1}, \ldots, \lambda_{n_{1}+n_{2}}$, respectively, we obtain (7.10).

Lemma 7.3. Let $N$ be a special Hopf hypersurface of $C P^{h+1}$ (4) (resp., $C H^{h+1}$ $(-4))$. Then there exists an orthonormal frame $\left\{e_{1}, \ldots, e_{h}, e_{h+1}=J e_{1}, \ldots, e_{2 h}=\right.$ $\left.J e_{h}\right\}$ of the holomorphic distribution $\mathcal{D}$ such that

$$
\begin{aligned}
& \sigma\left(e_{\alpha}, e_{\beta}\right)=\lambda_{\alpha} \delta_{\alpha \beta} \xi, \quad \sigma\left(e_{h+\alpha}, e_{h+\beta}\right)=\frac{\delta_{\alpha \beta}}{\lambda_{\alpha}} \xi, \quad \sigma\left(e_{a}, e_{b}\right)=0 \text { otherwise } \\
& \text { (resp., } \left.\sigma\left(e_{\alpha}, e_{\beta}\right)=\lambda_{\alpha} \delta_{\alpha \beta} \xi, \sigma\left(e_{h+\alpha}, e_{h+\beta}\right)=-\frac{\delta_{\alpha \beta}}{\lambda_{\alpha}} \xi, \sigma\left(e_{a}, e_{b}\right)=0, \text { otherwise }\right),
\end{aligned}
$$

for $1 \leq \alpha, \beta \leq h$, where $\lambda_{1}, \ldots, \lambda_{h}$ are nowhere zero functions.
By applying Theorem 6.1 and Lemma 7.1, we have the following.
Theorem 7.1. If $N$ is a real hypersurface of $\tilde{M}^{2}(4 c)$, then we have

$$
\begin{equation*}
\operatorname{Ric}(J \xi, J \xi) \leq \frac{9}{2} H^{2}+2 c \tag{7.12}
\end{equation*}
$$

The equality sign of (7.12) holds identically if and only if $c=0$ and $N$ is totally geodesic.

Proof. Let $N$ be a real hypersurface of a complex space form $\tilde{M}^{2}(4 c)$. Then we obtain (7.12) from (6.1). Assume that $N$ satisfies the equality case of (7.12) identically. Then Theorem 6.1 implies that $N$ is a minimal special Hopf hypersurface. Therefore, by Lemma 7.1 there exists a unit vector field $e_{1}$ in $\mathcal{D}$ such that

$$
\begin{align*}
& \sigma\left(e_{1}, e_{1}\right)=\lambda J e_{3}, \sigma\left(e_{2}, e_{2}\right)=-\lambda J e_{3} \\
& \sigma\left(e_{1}, e_{2}\right)=\sigma\left(e_{2}, e_{3}\right)=0, a=1,2,3 \tag{7.13}
\end{align*}
$$

for some function $\lambda$. It follows from (7.13) and Lemma 3.1(2) that

$$
\begin{equation*}
\omega_{1}^{3}\left(e_{1}\right)=\omega_{2}^{3}\left(e_{2}\right)=0, \omega_{3}^{2}\left(e_{1}\right)=\omega_{3}^{1}\left(e_{2}\right)=\lambda \tag{7.14}
\end{equation*}
$$

On the other hand, we find from $\left(\tilde{R}\left(e_{1}, e_{2}\right) e_{3}\right)^{\perp}=\left(\bar{\nabla}_{e_{1}} \sigma\right)\left(e_{2}, e_{3}\right)-\left(\bar{\nabla}_{e_{2}} \sigma\right)\left(e_{1}, e_{3}\right)$, (2.8) and (7.4) that $-2 c=\lambda\left(\omega_{3}^{1}\left(e_{2}\right)+\omega_{3}^{2}\left(e_{1}\right)\right)$. Combining this with (7.14) gives

$$
\begin{equation*}
c=-\lambda^{2} \leq 0 \tag{7.15}
\end{equation*}
$$

If $c=0$, (7.15) implies that $\lambda=0$. Thus $N$ is a totally geodesic hypersurface.
If $c<0$, it follows from (7.15) that $\lambda$ is a nonzero constant. Thus, $N$ is a minimal Hopf hypersurface of $C H^{2}\left(-\lambda^{2}\right)$ with three constant principal curvatures $0, \lambda,-\lambda$. But this is impossible according to Theorem 1 of [3].

The converse is easy to verify.
For real hypersurfaces in $\mathbf{C}^{3}$, we have the following.
Theorem 7.2. Let $N$ be a real hypersurface of $\mathbf{C}^{3}$. We have

$$
\begin{equation*}
\operatorname{Ric}(J \xi, J \xi) \leq \frac{25}{2} H^{2} \tag{7.16}
\end{equation*}
$$

If the equality case of (7.16) holds identically, then $N$ is a totally real 3-ruled minimal submanifold of $\mathbf{C}^{3}$.

Proof. Let $N$ be a real hypersurface of $\mathbf{C}^{3}$. Then we find inequality (7.16) from (6.1) of Theorem 6.1.

Assume that $N$ satisfies the equality case of (7.16) identically. Then it follows from Theorem 6.1 and Lemma 7.2 that there exists an orthonormal local frame $\left\{e_{1}, e_{2}, e_{3}=\right.$ $\left.J e_{1}, e_{4}=J e_{2}, e_{5}\right\}$ on $N$ such that

$$
\begin{align*}
\sigma\left(e_{1}, e_{1}\right) & =\lambda \xi, \quad \sigma\left(e_{2}, e_{2}\right)=-\lambda \xi  \tag{7.17}\\
\sigma\left(e_{a}, e_{b}\right) & =0 \text { otherwise }
\end{align*}
$$

for some function $\lambda$.
Let us put $W=\{x \in N: \lambda(x) \neq 0\}$, which is an open subset of $W$.
Case (a). $W=\emptyset$. In this case, $N$ is a totally geodesic hypersurface. In particular, $N$ is a totally real 3-ruled minimal submanifold of $\mathbf{C}^{3}$.

Case (b). $W \neq \emptyset$. If we put $\mathcal{D}_{1}=\operatorname{Span}\left\{e_{1}, e_{2}\right\}$ and $\mathcal{D}_{2}=\operatorname{Span}\left\{e_{3}, e_{4}, e_{5}\right\}$, then we find from (7.17) that

$$
\begin{equation*}
\sigma\left(\mathcal{D}_{2}, T N\right)=\{0\}, \text { i.e., } A_{\xi} V=0, \quad \forall V \in \mathcal{D}_{2} \tag{7.18}
\end{equation*}
$$

Thus, after applying (7.18) and the Codazzi equation

$$
\left(\bar{\nabla}_{U} \sigma\right)(V, X)=\left(\bar{\nabla}_{V} \sigma\right)(U, X), \quad U, V \in \mathcal{D}_{2}, \quad X \in \mathcal{D}_{1}
$$

we obtain $\sigma([U, V], X)=0$. Therefore, it follows from (7.17) and $\lambda \neq 0$ that $\mathcal{D}_{2}$ is an integrable distribution.

Also, from (7.17) we derive that

$$
\begin{aligned}
\lambda\left\langle\nabla_{U} V, e_{1}\right\rangle & =\left\langle\nabla_{U} V, A_{\xi} e_{1}\right\rangle \\
& =-\left\langle V,\left(\nabla_{U} A_{\xi}\right) e_{1}\right\rangle-\left\langle V, A_{\xi}\left(\nabla_{U} e_{1}\right)\right\rangle \\
& =-\left\langle V,\left(\nabla_{e_{1}} A_{\xi}\right) U\right\rangle-\left\langle A_{\xi} V, \nabla_{U} e_{1}\right\rangle \\
& =-\left\langle V, \nabla_{e_{1}}\left(A_{\xi} U\right)\right\rangle+\left\langle V, A_{\xi}\left(\nabla_{e_{1}} X\right)\right\rangle \\
& =0
\end{aligned}
$$

for $U, V$ in $\mathcal{D}_{2}$. Hence we find $\left\langle\nabla_{U} V, e_{1}\right\rangle=0$. Similarly, we have $\left\langle\nabla_{U} V, e_{2}\right\rangle=0$. After combining these with (7.18), we conclude that each leave of $\mathcal{D}_{2}$ is a totally real totally geodesic submanifold of $\mathbf{C}^{3}$. Consequently, each connected component of $W$ is a totally real 3-ruled minimal submanifold of $\mathbf{C}^{3}$. If $W$ is dense in $N$, we have the same conclusion by continuity.

If $W$ is not dense in $N$, then the interior of each connected component of $N-$ $W$ is a totally geodesic real hypersurface of $\mathbf{C}^{3}$, which is obviously totally real 3ruled. Consequently, by continuity the whose $N$ is a totally real 3-ruled minimal submanifold.

For real hypersurfaces in $C P^{3}(4)$, we have
Proposition 7.1. If $N$ is a real hypersurface of $C P^{3}(4)$, then we have

$$
\begin{equation*}
\operatorname{Ric}(J \xi, J \xi) \leq \frac{25}{2} H^{2}+4 \tag{7.19}
\end{equation*}
$$

The equality sign of (7.19) holds identically if and only if locally there exists an orthonormal frame $\left\{e_{1}, e_{2}, e_{3}=J e_{1}, e_{4}=J e_{2}, e_{5}\right\}$ such that

$$
\begin{align*}
\sigma\left(e_{1}, e_{1}\right) & =\lambda \xi, \sigma\left(e_{2}, e_{2}\right)=-\lambda \xi \\
\sigma\left(e_{3}, e_{3}\right) & =\frac{1}{\lambda} \xi, \sigma\left(e_{4}, e_{4}\right)=-\frac{1}{\lambda} \xi  \tag{7.20}\\
\sigma\left(e_{a}, e_{b}\right) & =0 \text { otherwise }
\end{align*}
$$

where $\lambda$ is a nowhere zero function.
Proof. Follows from Theorem 6.1 and Lemma 7.3.
Similarly, we also have the following result for real hypersurfaces in $\mathrm{CH}^{3}(-4)$ by Theorem 6.1 and Lemma 7.3.

Proposition 7.2. If $N$ is a real hypersurface of $\mathrm{CH}^{3}(-4)$, then we have

$$
\begin{equation*}
\operatorname{Ric}(J \xi, J \xi) \leq \frac{25}{2} H^{2}-4 \tag{7.21}
\end{equation*}
$$

The equality sign of (7.21) holds identically if and only if locally there exists an orthonormal frame $\left\{e_{1}, e_{2}, e_{3}=J e_{1}, e_{4}=J e_{2}, e_{5}\right\}$ on $N$ such that

$$
\begin{align*}
& \sigma\left(e_{1}, e_{1}\right)=\lambda \xi, \sigma\left(e_{2}, e_{2}\right)=-\lambda \xi \\
& \sigma\left(e_{3}, e_{3}\right)=-\frac{1}{\lambda} \xi, \sigma\left(e_{4}, e_{4}\right)=\frac{1}{\lambda} \xi  \tag{7.22}\\
& \sigma\left(e_{a}, e_{b}\right)=0 \text { otherwise }
\end{align*}
$$

where $\lambda$ is a nowhere zero function.
Proposition 7.1 and Proposition 7.2 imply immediately the following.
Corollary 7.2. Every real hypersurface of $C P^{3}(4)$ (resp., of $\left.C H^{3}(-4)\right)$ satisfying the equality case of (7.19) (resp., the equality case of (7.21)) is $\delta(2,2)$-ideal in the sense of $[9,12]$.

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