# ALMOST HERMITIAN STRUCTURE ON $\boldsymbol{S}^{6}$ 

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A differentiable manifold $M$ of even dimension is called to have an almost Hermitian structure, if there exist on $M$ a metric tensor field $g$ and a tensor field $\varphi$ of type $(1,1)$ such that

$$
\varphi_{a}^{i} \varphi_{j}^{\pi}=-\delta_{j,}^{i}, \quad g_{a b} \varphi_{i}^{a} \varphi_{j}^{b}=g_{i j} .
$$

It is well known that an almost Hermitian structure can be defined on a sphere $S^{i}$ of dimension 6 by making use of the algebra $C$ of Cayley numbers [1]. The group $G$ of all automorphisms of the algebra $C$ acts on $S^{6}$ transitively as a group of isometries [3]. We shall show that almost Hermitian structure on $S^{6}$ is invariant under the group $G$, i. e. the tensor fields $g$ and $\phi$ are invariant under $G$. Moreover there exists one and only one affine connection $\Lambda$ invariant under $G$ with respect to which $g$ and $\varphi$ are covariantly constant. The unique connection $\Lambda$ is actually obtained by making use of the fields $g$ and $\varphi$, and its torsion and curvature tensor fields are covariantly constant.

1. Almost Hermitian structure on $\boldsymbol{S}^{6}$. Let $\boldsymbol{C}$ be the algebra of Cayley numbers. Any element $\xi$ of $C$ may be written in the form

$$
\xi=X I+X^{0} e_{0}+X^{1} e_{1}+\ldots+X^{6} e_{6}=X I+x,
$$

where $X, X^{0}, X^{1}, \ldots, X^{6}$ are real numbers and $I, e_{0}, e_{1}, \ldots, e_{6}$ form a natural base of the algebra $C, I$ being the unit element of $C$. $\xi$ is called pure imaginary if $X=0$. All pure imaginary Cayley numbers form a 7 -dimensional subspace $E^{7}$ of $C$. The multiplication table is given by the following :

$$
\begin{array}{rlrl}
e_{i}^{2} & =-I & & (i=0,1, \ldots, 6), \\
e_{i} \cdot e_{j} & =-e_{j} \cdot e_{i} & (i \neq j ; i, j=0,1, \ldots, 6), \\
e_{0} \cdot e_{1} & =e_{2}, & e_{0} \cdot e_{3}=e_{i}, & e_{0} \cdot e_{5}=e_{i}, \\
e_{1} \cdot e_{4} & =e_{6}, & e_{1} \cdot e_{3}=-e_{5}, & e_{2} \cdot e_{3}=e_{0}, \quad e_{i} \cdot e_{4}=e_{5},
\end{array}
$$

and the other $e_{i} \cdot e_{j}$ are given by cyclic permutations of indices.
If $\eta=Y I+\sum_{=0}^{6} Y^{i} e_{i}=Y I+y$ is an element of $C$, then we have

$$
\xi \cdot \eta=X Y I-\sum_{i=0}^{6} X^{t} Y^{i} I+X y+Y x+\sum_{i, k=v}^{6}{ }_{i \neq k} X^{i} Y^{k} e_{i} \cdot e_{k} .
$$

For any two pure imaginary Cayley numbers $x, y$ we have

$$
x \cdot y=-\sum_{i=0}^{6} X^{i} Y^{i} I+\sum_{i, k=0}^{6}{ }_{i \neq k} X^{i} Y^{k} e_{i} \cdot e_{k},
$$

where $\sum_{i=0}^{3} X^{i} Y^{i}$ is the scalar product of two vectors $x$ and $y$ of $E^{7}$ and is denoted by $(x, y)$. The pure imaginary Cayley number $\sum_{i \neq k} X^{i} Y^{k} e_{i} e_{k}$ is called
the vector product of $x$ and $y$ and is denoted by $x \times y$. Then we have

$$
x \cdot y=-(x, y) I+x \times y .
$$

The operation of vector product is bilinear, and $x \times y$ is orthogonal to both $x$ and $y$. We have moreover $x \times y=-y \times x$.

The set of all vectors $x$ of $E^{7}$ such that $(x, x)=1$ is the unit sphere $S^{6}$. The scalar product in $E^{7}$ induces the natural metric tensor field $g$ on $S^{6}$. The tangent space $T_{x}$ of $S^{6}$ at $x \in S^{6}$ can naturally be identified with the subspace of $E^{7}$ orthogonal to $x$, and we use this identification throughout this paper A linear mapping $\varphi_{x}$ of $T_{x}$ onto itself is defined as follows:

$$
\varphi_{x}(y)=x \times y \text { for } y \in T_{x} .
$$

The correspondence $x \rightarrow \varphi_{x}$ defines a tensor field $\varphi$, which together with $g$ gives an almost Hermitian structure on $S^{6}$ [1].

If $G$ is the group of all automorphisms of the algebra $C$ of Cayley numbers, then it is a compact simple Lie group with the structure of Cartan's exceptional simple Lie algebra of type ( $G$ ) [3]. Every element of $G$ leaves the subspace $E^{7}$ invariant and is an orthogonal transformation on $E^{7}$. In this way $G$ acts on $S^{6}$ transitively. Let $H$ be the isotropic subgroup of $G$ leaving $e_{0}$ fixed. Then it is easily seen that $H$ is isomorphic to the natural real representation of the unimodular unitary group in three complex variables. Thus $H$ is connected. Hence $G$ is connected, because $G / H$ is a sphere.

The tensor field $\phi$ defined above is invariant under $G$. In fact, for any $s$ of $G, x$ of $S^{6}$ and $y$ of $T_{x}$ we have

$$
s\left(\varphi_{x}(y)\right)=s(x \times y)=s(x-y)=s(x) \cdot s(y)=s(x) \times s(y)=\varphi_{s(x)}(s(y))^{1} .
$$

Conversely, let $f$ be an orthogonal transformation of $E^{7}$ leaving invariant the tensor field $\varphi$ on $S^{6}$. There corresponds to $f$ a vector-space automorphism $f^{\prime}$ of the algebra $C$ such that $f^{\prime}(I)=I$ and the restriction of $f^{\prime}$ to $E^{7}$ coincides with $f$. It is not hard to see that $f^{\prime}(x \cdot y)=f^{\prime}(x) \cdot f^{\prime}(y)$ for $x, y$ of $E^{7}$, and hence $f^{\prime}(\xi \cdot \eta)=f^{\prime}(\xi) \cdot f^{\prime}(\eta)$ for any two Cayley numbers $\xi$ and $\eta$, i. e. $f^{\prime}$ is an automorphism of the algebra $C$. We assume throughout this paper that the sphere $S^{6}$ has almost Hermitian structure defined above. Thus we have

Theorem 1. The almost Hermitian structure on $S^{6}$ is invariant under the group $G$ of all automorphisms of Cayley numbers. Conversely, the group of all isometric transformations leaving invariant the almost Hermitian structure on $S^{6}$ is isomorphic to $G$.
2. An invariant affine connection $\Lambda$ on $\boldsymbol{S}^{6}$. We shall define on $S^{6}$ an invariant affine connection with required properties. Let $x=\sum_{i=0}^{6} X^{i} e_{i}$ and $y=\sum_{i=0}^{6} Y^{i} e_{i}$ be two pure imaginary Cayley numbers. Then we have

$$
x \times y=\sum_{j, k=0}^{6} A_{k}^{j} Y^{k} e_{j},
$$

[^0]where the matrix $\left(A_{k}^{\prime}\right)$ has the form [1]:
\[

\left($$
\begin{array}{c}
A_{0}^{0} \ldots A_{6}^{0} \\
\ldots \ldots . A_{6}^{6} \\
A_{0}^{6} \ldots \ldots A_{6}^{6}
\end{array}
$$\right)=\left($$
\begin{array}{rrrrrr}
0 & -X^{2} & X^{1} & -X^{4} & X^{5}-X^{6} & X^{5} \\
X^{2} & 0 & -X^{0} & X^{5} & -X^{6}-X^{3} & X^{4} \\
-X^{1} & X^{0} & 0 & -X^{0} & -X^{5} & X^{4} \\
X^{4} & -X^{5} & X^{6} & 0 & -X^{0} & X^{1} \\
-X^{2} \\
-X^{3} & X^{6} & X^{5} & X^{0} & 0 & -X^{2} \\
-X^{1} \\
X^{6} & X^{3} & -X^{4} & -X^{1} & X^{2} & 0 \\
-X^{5} & X^{4} & -X^{3} & X^{2} & X^{1} & X^{0} \\
0
\end{array}
$$\right) .
\]

As a local coordinate system ( $x^{1}, \ldots, x^{6}$ ) of $S^{6}$ in a neighborhood of the point $P_{0}\left(=e_{0}\right)=\left(X^{0}, X^{1}, \ldots, X^{i}\right)=(1,0, \ldots, 0)$, we set $x^{i}=X^{i}(i=1,2, \ldots, 6)$.. If we denote by $\varphi_{j}^{i}$ the components of the tensor field $\varphi$, then we have

$$
\varphi_{k}^{j}=A_{k}^{j}-\frac{A_{0}^{j} X^{k}}{X^{0}} \quad(j, k=1,2, \ldots, 6),
$$

where

$$
X^{k}=x^{6}, \quad X^{0}=\left\{1-\sum_{i=1}^{6}\left(x^{i}\right)^{2}\right\}^{\frac{1}{2}} .
$$

At the point $P_{0}$ we obtain

$$
\left(\boldsymbol{\varphi}_{k}^{j}\right)_{P_{0}}=A_{k}^{j}, \quad\left(\frac{\partial \boldsymbol{\varphi}_{k}^{j}}{\partial x^{i}}\right)_{P_{0}}=\frac{\partial A_{k}^{j}}{\partial X^{l}} .
$$

The metric tensor field $g$ has the components

$$
g_{i j}=\delta_{i j}+\frac{x^{i} x^{j}}{\left(X^{0}\right)^{2}}, \quad g^{i j}=\delta_{i j}-x^{i} x^{i},
$$

where $g^{i a} g_{a j}=\delta_{j}^{i}$. Hence the Christoffel symbol $\Gamma_{j k}^{j}$ of $g_{i j}$ is given by

$$
\Gamma_{j k}^{i}=x^{i}\left\{\delta_{j k}+\frac{x^{i} x^{6}}{\left(X^{0}\right)^{2}}\right\}
$$

We shall define an affine connection $\Lambda_{j k}^{i}$ on $S^{6}$ by the formula:

$$
\begin{equation*}
\Lambda_{j k}^{i}=\Gamma_{j k}^{i}-\frac{1}{2} \phi_{k ; a}^{i} \varphi_{j}^{\pi}, \tag{1}
\end{equation*}
$$

where $\varphi_{j ; k}^{i}$ is the covariant derivative of $\varphi_{j}^{i}$ with respect to the Riemannian connection $\Gamma_{j k}^{j}$. On the other hand we have

$$
\begin{equation*}
\varphi_{j ; k}^{i}+\varphi_{k ; j}^{i}=0 \tag{2}
\end{equation*}
$$

because the group $G$ is transitive on $S^{6}$ and

$$
\begin{gathered}
\left(\Gamma_{j k}^{i}\right)_{P_{0}}=0, \\
\left(\frac{\partial \varphi_{j}^{i}}{\partial x^{k}}\right)_{P_{0}}+\left(\frac{\partial \varphi_{k}^{i}}{\partial x^{i}}\right)_{P_{0}}=\frac{\partial A_{j}^{i}}{\partial X^{k}}+\frac{\partial A_{k}^{i}}{\partial X^{j}}=0 .
\end{gathered}
$$

By virtue of the equation (2), the connection $\Lambda_{j k}^{i}$ defined by (1) exactly coincides with the one introduced by A. Frölicher [1]. The affine connection $\Lambda_{j k}^{i}$ is obviously invariant under $G$. It is well known [1] that the tensor field $\boldsymbol{\rho}$ 'is a covariantly constant with respect to the connection $\Lambda_{j k}^{i}$ and the torsion tensor field of $\Lambda_{j k}^{j}$ is nothing but the Nijenhuis tensor field, i.e. the torsion tensor
field of the almost complex structure $\varphi$ on $S^{6}$. A. Frölicher [1] has shown that the torsion tensor field does not vanish at the point $P_{0}$. Hence it does not vanish at every point of $S^{6}$.

The covariant derivative $D_{i} g_{i j}$ with respect to $\Lambda_{j k}^{\prime}$ is zero. In fact,

$$
\begin{aligned}
& 2 D_{k} y_{i j}=\varphi_{k ; \pi}^{b} \varphi_{i}^{a} g_{b j}+\varphi_{k ; a}^{b} \varphi_{j}^{7} g_{i b}=-\varphi_{a ; k}^{b} \varphi_{i}^{\tau} g_{b j}-\varphi_{a ; k}^{b} \varphi_{j}^{a} g_{i b} \\
& =\phi_{j ; k}^{b} \varphi_{i}^{a} g_{b a}-\varphi_{b ; k}^{a} \varphi_{j}^{h} g_{i a}=-\varphi_{j ; k}^{h} \varphi_{b}^{n} g_{i a}+\varphi_{b}^{a} \varphi_{j ; k}^{\prime j} g_{i a}=0,
\end{aligned}
$$

since

$$
\phi_{j ; k}^{i}+\varphi_{k ; j}^{i}=0, g_{i a} \varphi_{j ; k}^{n}+g_{j a} \varphi_{i ; k}^{n}=0, \quad \varphi_{a ; k}^{i} \varphi_{j}^{i}+\varphi_{a}^{i} \varphi_{j ; k}^{\tau}=0 .
$$

For simplicity, an affine connection $\Lambda$ on an almost Hermitian space $M$ is called a $C$-connection, if the metric tensor field $g$ and the tensor field $\varphi$ defining the almost Hermitian structure on $M$ are covariantly constant with respect to $\Lambda$.

It has been proved in this section that the affine connection on $S^{6}$ defined by (1) is a $C$-connection and invariant under $G$.
3. Uniqueness of the invariant $C$-connection on $\boldsymbol{S}^{6}$. We shall prove in this section that there exists uniquely on $S^{6}$ an invariant $C$-connection. For this purpose we shall give some preliminary remarks.

Let $G$ and $H$ be as before, $\mathfrak{g}$ the Lie algebra of $G$, and $\mathfrak{h}$ the subalgebra of $\mathfrak{g}$ corresponding to $H$. Since $H$ is compact, there exists a subspace $\mathfrak{m}$ of $g$ such that

$$
\operatorname{ad}(h) \cdot \mathfrak{m} \subset \mathfrak{m}, \mathfrak{g}=\mathfrak{m}+\mathfrak{h} \quad \text { (direct sum as vector space) }
$$

for any $h \in . H$, where ad $(h)$ denotes the adjoint transformation of $h$ in $\mathfrak{g}$; that is, the homogeneous space $G / H$ is reductive [4]. We may identify the subspace $\mathfrak{m l}$ with the tangent space $T$ at the point $P_{0}=H$ of $G / H=S^{6}$. According to this identification, since $g$ and $\varphi$ are invariant under $G$, there exist a symmetric bilinear form $B$ on $\mathfrak{m} \times \mathfrak{m}$ corresponding to the metric tensor field $g$ on $S^{6}$ and a linear mapping $J: \mathfrak{m} \rightarrow \mathfrak{m}\left(-J^{2}=\right.$ identity) corresponding to the tensor field $\varphi$ on $S^{6}$ such that

$$
\begin{aligned}
& B(\operatorname{ad}(h) \cdot X, \quad \operatorname{ad}(h) \cdot Y)=B(X, Y), \\
& J \circ \operatorname{ad}(h)=\operatorname{ad}(h) \circ J, \quad B(J \cdot X, J \cdot Y)=B(X, Y)
\end{aligned}
$$

for any $X, Y \in \mathfrak{m}$ and $h \in H$.
If $\Lambda$ is an invariant affine connection on $G / H$, then there exists in a unique manner a bilinear mapping $\alpha: \mathfrak{m} \times \mathfrak{m} \rightarrow \mathfrak{m}$ which is invariant by the adjoint representation of $H$ on $\mathfrak{m}$, where the mapping $\alpha$ is the so-called connection function of $\Lambda$ [4]. If we introduce a linear mapping $\widetilde{\alpha}$ of $\mathfrak{m}$ into the Lie algebra $E(\mathfrak{m})$ of all linear endomorphisms of $m$ such that

$$
\widetilde{\alpha}(Z) \cdot Y=\alpha(Z, Y)
$$

for any $Y, Z \in \mathfrak{m}$, then by virtue of invariance of the connection function $\alpha$ we have

$$
\begin{align*}
\widetilde{\alpha}(\operatorname{ad}(U) \cdot Z) & =\operatorname{ad}(U) \circ \widetilde{\alpha( }(Z)-\widetilde{\alpha}(Z) \circ \operatorname{ad}(U)  \tag{3}\\
& =[\operatorname{ad}(U), \widetilde{\alpha}(Z)]
\end{align*}
$$

for any $Z \in \mathfrak{m}$ and $U \in \mathfrak{h}$, where $\operatorname{ad}(U)$ is the endomorphism of $\mathfrak{m}$ nduced by the adjoint transformation of $U(\in \mathfrak{h})$ in $\mathfrak{g}$. Let $W_{\alpha}$ be the image of $\mathfrak{m}$ by $\widetilde{\alpha}$, and ad( $(\mathfrak{l})$ the subalgebra of $E(\mathfrak{m})$ composed of all endomorphisms induced by the adjoint representation of $\mathfrak{h}$ on $\mathfrak{g}$. Then $W_{\alpha}$ is invaxiant under ad( $\mathfrak{h}$ ) because of the relation (3).

Assume moreover that the invariant tensor fields $g$ and $\varphi$ on $S^{6}$ are covarianly constant with respect to the connection $\Lambda$. Then the following relations hold true:

$$
B(\widetilde{\alpha}(Z) \cdot X, Y)+B(X, \widetilde{\alpha}(Z) \cdot Y)=0, \quad J \circ \widetilde{\alpha}(Z)=\widetilde{\alpha}(Z) \circ J
$$

for any $X, Y, Z \in \mathfrak{m}$. Hence the subspace $W_{\alpha}$ is contained in $\mathfrak{l}(3)$ which is the subalgebra of $E(\mathfrak{m})$ corresponding to the real representation of the unitary group in three complex variables. On the other hand, the subalgebra $\operatorname{ad}(\mathfrak{h})$ of $E(m)$ coincides with the subalgebra $\mathfrak{Z}(3)$ corresponding to the real representation of the unimodular unitary group in three complex variables. Thus, if we denote by $[\mathfrak{G}, \mathfrak{m}]$ the subspace of $\mathfrak{m}$ spanned by all elements of the form $[U, X]=\operatorname{ad}(U) \cdot X, \quad U \in \mathfrak{h}, \quad X \in \mathfrak{m}$, then we have $[\mathfrak{h}, \mathfrak{m}]=\mathfrak{m}$. From the fact just obtained and the relation (3), it follows easily that $W_{\alpha}$ is contained in the derived subalgebra of $\mathfrak{l}(3)$, that is, in $\mathfrak{N}(3)$. Consequently, $W_{\alpha}$ is an ideal of $\mathfrak{3}(3)$.

Since $W_{\alpha}$ is an ideal of the simple Lie algabra $\mathfrak{B}_{(3)}$ and $\operatorname{dim} W_{\alpha} \leqq 6$, we have $W_{\alpha}=\{0\}$. Hence $\widetilde{\alpha}=0$, i. e. the connection function $\alpha$ corresponding to the given invariant affine connection $\Lambda$ is equal to zero. That is to say, there exists one and only one invariant $C$-connection $S^{6}$ and it is the canonical connection of the second kind of the given reductive homogeneous space $G / H$ [4]. Then the covariant derivatives of its torsion and curvature tensor fields are zero.

Summing up the results obtained in the present and previous sections, we have the following theorem:

Theorem 2. On the homogeneous almost Hermitian space $S^{6}=G / H$ there exists one and only one invariant C-connection $\Lambda$, which is given by (1) in §2. The covariant derivatives of its torsion and curvature tensor fields are both zero, but its torsion tensor field istelf does not vanish at every point of $S^{6}$.

Recently, K. Yano [6] has given three remarkable $C$-connections in almost Hermitian spaces, and J. A. Schouten and K. Yano [5] have found a $C$-connection distinct from these three ones. By virtue of (2), these fonr $C$-connections on $S^{6}$ coincide with the one given by (1). This fact is, however a direct consequence of Theorem 2, because the four $C$-connections are invariant under $G$.

Let $G / H$ be a homogeneous almost Hermitian space of dimension $2 n$, and $\operatorname{dim} G=n^{2}+2 n-1(n>1)$. If $G / H$ is not flat as a homogeneous Riemannian space, then $n=3$ and moreover, if the homogeneous space $G / H$ is simply connected, it is isomorphic with the homogeneous almost Hermitiau spece $S^{6}$ considered in this paper[ 2]. Analogously, we have for general
cases that there exists on $G / H$ a unique invariant $C$-connection $\Lambda$.

## Bibliography

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[^0]:    1) For any $s \in G$ we denote by the same letter $s$ the differential mapping of the transformation $s: S^{6} \rightarrow S^{6}$.
