# CODIMENSION ONE LOCALLY FREE ACTIONS OF SOLVABLE LIE GROUPS 

Dedicated to Professor Fuichi Uchida on his sixtieth birthday

Aiko Yamakawa and Nobuo Tsuchiya

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#### Abstract

Let $G$ be a non-unimodular solvable Lie group which is a semidirect product of $\boldsymbol{R}^{m}$ and $\boldsymbol{R}^{n}$. We consider a codimension one locally free volume preserving action of $G$ on a closed manifold. It is shown that, under some conditions on the group $G$, such an action is homogeneous. It is also shown that such a group $G$ has a homogeneous action if and only if the structure constants of $G$ satisfy certain algebraic conditions.


Introduction. By a locally free action of a Lie group $G$, we mean an action all of whose isotropy subgroups are discrete. A locally free action $\Phi$ then induces a foliation $\mathcal{F}_{\Phi}$ whose leaves are given by the orbits of $\Phi$. The primary purpose of this paper is to investigate the behavior of codimension one locally free actions of some solvable Lie groups on closed manifolds.

To begin with, let $G$ be a nilpotent Lie group. Then, from the point of view of foliation theory, Hector, Ghys and Moriyama [8] proved that the codimension one foliation $\mathcal{F}_{\Phi}$ is almost without holonomy. That is, each non-compact leaf of $\mathcal{F}_{\Phi}$ has trivial leaf holonomy ([7, IV-2.11]). This implies that the qualitative structure of $\mathcal{F}_{\Phi}$ is comparatively simple.

When $G$ is solvable but not nilpotent, the structure of $\mathcal{F}_{\boldsymbol{\Phi}}$ is more complicated. Even in the case where $G$ is the real affine group

$$
\operatorname{Aff}^{+}(\boldsymbol{R})=\left\{\left.\left(\begin{array}{rr}
e^{t} & x \\
0 & 1
\end{array}\right) \right\rvert\, t, x \in \boldsymbol{R}\right\}
$$

which is the simplest non-nilpotent solvable Lie group, it is known ([5, Propositions II.1.4 and II.1.5]) that all leaves of $\mathcal{F}_{\Phi}$ are dense and there exists a leaf with non-trivial leaf holonomy. However, by assuming the existence of an invariant volume form, Ghys obtained the following remarkable result, which shows the smooth rigidity of codimension one locally free $\mathrm{Aff}^{+}(\boldsymbol{R})-$ actions.

Theorem ([5, Theorem B]). Let $G$ be $\operatorname{Aff}^{+}(\boldsymbol{R})$. Let $\Phi: G \times M \rightarrow M$ be a locally free $G$-action of class $C^{r}(r \geq 2)$ on a closed smooth 3-manifold $M$. Suppose that the action $\Phi$ preserves a volume form of class $C^{0}$. Then $\Phi$ is $C^{r-1}$-conjugate to a homogeneous action.

To be precise, let $\Phi$ and $\Phi^{\prime}$ be $C^{r}$-actions of a Lie group $G$ on manifolds $M$ and $M^{\prime}$, respectively. Then $\Phi$ and $\Phi^{\prime}$ are said to be $C^{s}$-conjugate ( $s \leq r$ ) if there exist an isomorphism

[^0]$\varphi$ of $G$ and a $C^{s}$-diffeomorphism $f$ from $M$ to $M^{\prime}$ such that $f \circ \Phi=\Phi^{\prime} \circ(\varphi \times f)$. If a Lie group $H$ contains $G$ and a cocompact discrete subgroup $\Gamma$ as well, then $G$ acts on the compact homogeneous manifold $H / \Gamma$ by left translations. Such an action is called a homogeneous action. Note that a homogeneous action preserves the natural volume form of $H / \Gamma$ that is induced from a right and left invariant volume form of $H$.

Following the above theorem of Ghys, several rigidity results have since been obtained for actions of Lie groups other than $\mathrm{Aff}^{+}(\boldsymbol{R})$ ([1], [2] and [6]).

In this paper, we consider non-nilpotent solvable Lie groups $G$ which are semidirect products of $\boldsymbol{R}^{m}$ and $\boldsymbol{R}^{n}$, and study the rigidity of codimension one locally free volume preserving actions of $G$. To state our main results, we fix some notation.

For consistency with the case of $\mathrm{Aff}^{+}(\boldsymbol{R})=\boldsymbol{R}_{+} \ltimes \boldsymbol{R}$, we use the multiplicative notation for $\boldsymbol{R}^{m}$. Since the group structure of $G=\boldsymbol{R}_{+}^{m} \ltimes \boldsymbol{R}^{n}$ is determined by a homomorphism $\psi: \boldsymbol{R}_{+}^{m} \rightarrow \operatorname{Aut}\left(\boldsymbol{R}^{n}\right) \cong G L(n, \boldsymbol{R})$, we write the semidirect product by $\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$. We assume that $\psi$ is diagonalizable. By changing the semidirect product structure of $G$ if necessary, we may assume furthermore that $\psi$ is locally injective, and in particular $m \leq n$ (Lemma 1.1).

Take a basis $\left\{\mathbf{e}_{j} \mid 1 \leq j \leq m\right\}$ of $\boldsymbol{R}^{m}$ and put $d \psi\left(\mathbf{e}_{j}\right)=: A_{j} \in M(n, \boldsymbol{R})$, where $d \psi$ is the differential of $\psi$. Then the matrices $\left\{A_{j}\right\}$ are simultaneously diagonalizable. Denote by $\lambda_{i}^{j}$ the $i$-th diagonal element of the diagonalized form of $A_{j}$, and by $\Lambda_{\psi}$ the $n \times m$-matrix whose $i$-th row vector is given by $\Lambda_{i}:=\left(\lambda_{i}^{1}, \lambda_{i}^{2}, \ldots, \lambda_{i}^{m}\right)(1 \leq i \leq n)$. We call $\Lambda_{\psi}$ the structure matrix of $G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$ (see Section 1.1). Put $\beta:=\sum_{i=1}^{n} \Lambda_{i}$.

A main theorem of this paper is the following.
THEOREM 1. Let $G=\boldsymbol{R}_{+}^{m} \ltimes{ }_{\psi} \boldsymbol{R}^{n}(0<m \leq n)$ and $M$ an $(m+n+1)$-dimensional connected closed orietable smooth manifold. Let $\Phi: G \times M \rightarrow M$ be a locally free smooth action preserving a volume form $\Omega$ of class $C^{0}$. Suppose that the homomorphism $\psi$ is diagonalizable, locally injective and the structure matrix $\Lambda_{\psi}$ of $G$ satisfies

$$
\beta \notin\left\{a_{i} \Re \Lambda_{i}, b_{j} \Re \Lambda_{j}-\Re \Lambda_{k} \mid 0 \leq a_{i}, b_{j} \leq 1,1 \leq i, j, k \leq n\right\} .
$$

Then $M$ is a solvmanifold and $\Phi$ is $C^{\infty}$-conjugate to a homogeneous action.
The other result is the following theorem which gives a necessary and sufficient condition for $G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$ to have a codimension one homogeneous action. Two $n \times m$-matrices $\Lambda$ and $\Lambda^{\prime}$ are said to be equivalent if $\Lambda^{\prime}=K \Lambda P$, where $K$ is an $n$-square matrix which exchanges rows of $\Lambda$ and $P \in G L(m, \boldsymbol{R})$.

Theorem 2. Let $G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}(0<m \leq n)$. Suppose that the homomorphism $\psi$ is diagonalizable, locally injective and the structure matrix $\Lambda_{\psi}$ of $G$ satisfies

$$
\Lambda_{i} \neq \mathbf{0}(1 \leq i \leq n) \quad \text { and } \quad \beta \notin\left\{ \pm \Lambda_{i}, \Lambda_{i}-\Lambda_{j} \mid 1 \leq i, j \leq n\right\} .
$$

Then, $G$ has a codimension one homogeneous action if and only if the $(n+1) \times m$-matrix $\left(\Lambda_{\psi}^{t},-\beta^{t}\right)^{t}$ is equivalent to a matrix $\hat{\Lambda}$ satisfying the following conditions.
(1) There exist $u_{k} \times m$-matrices $\Lambda(k)(1 \leq k \leq d)$ such that $\hat{\Lambda}^{t}=\left(\Lambda(1)^{t}, \Lambda(2)^{t}, \ldots\right.$, $\left.\Lambda(d)^{t}\right)^{t}$.
(2) For each $k(1 \leq k \leq d)$, let $\lambda_{i}^{j}(k)$ be the $(i, j)$-element of $\Lambda(k)$. Then each number $\exp \left( \pm \lambda_{i}^{j}(k)\right)$ is an algebraic integer, and there exists an algebraic integer $\alpha_{k}$ of degree $u_{k}$ such that $\exp \lambda_{i}^{j}(k)=\sigma_{k}^{(i)}\left(\exp \lambda_{1}^{j}(k)\right) \in \boldsymbol{Q}\left(\sigma_{k}^{(i)}\left(\alpha_{k}\right)\right)\left(1 \leq j \leq m, 1 \leq i \leq u_{k}\right)$. Here $\left\{\sigma_{k}^{(i)} \mid 1 \leq i \leq u_{k}, \sigma_{k}^{(1)}=\mathrm{id}\right\}$ is the set of all conjugation mappings of $\boldsymbol{Q}\left(\alpha_{k}\right)$.

The assumptions on the structure matrices in Theorems 1 and 2 depend only on their equivalence classes, thus, only on the isomorphism classes of the Lie groups $G$ (Lemma 1.2 and Proposition 1.3). If $m<n$, then the set of isomorphism classes of $\left\{\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n} \mid \Lambda_{\psi}\right.$ satisfies the assumptions of Theorems 1 and 2$\}$ has the cardinality of a continuum. Among them, only countably many Lie groups have codimension one homogeneous actions from Theorem 2, and hence, have codimension one locally free volume preserving actions on closed manifolds from Theorem 1 (Corollary 4.4). If $m=n$, then the group $\boldsymbol{R}_{+}^{n} \ltimes_{\psi} \boldsymbol{R}^{n}$ is isomorphic to $\operatorname{Aff}^{+}(\boldsymbol{R})^{l} \times \widetilde{\operatorname{Aff}}(\boldsymbol{C})^{r}$ for some non-negative integers $l$ and $r$ such that $l+2 r=n$ (Proposition 1.4), where $\widetilde{\text { Aff }}(\boldsymbol{C})$ denotes the universal covering group of the complex affine group. As a corollary of Theorem 2, it is shown that such a Lie group has a codimension one homogeneous action (Corollary 2.5).

This paper is organized as follows. In Section 1, we investigate fundamental properties of Lie groups of the form $\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$. In Section 2, we study cocompact discrete subgroups of Lie groups of the form $\boldsymbol{R}_{+}^{m} \ltimes_{\varphi} \boldsymbol{R}^{n+1}$, and then prove Theorem 2 and Corollary 2.5. Section 3 and Section 4 are devoted to proving Theorem 1. The proof of Theorem 1 is given by improving the methods developed in [5], [2] and [6].

Throughout this paper, by manifolds we mean connected closed orientable smooth manifolds, and by actions we mean smooth actions unless otherwise specified. We use the following notation:

1. For $\mathbf{v} \in \boldsymbol{C}^{n}, \mathfrak{R} \mathbf{v}$ (resp. $\mathfrak{J} \mathbf{v}$ ) denotes the real (resp. imaginary) part of $\mathbf{v}$.
2. $\boldsymbol{R}_{+}$denotes the multiplicative group of positive real numbers.
3. For $\mathbf{x}, \mathbf{y} \in \boldsymbol{C}^{n}, \mathbf{x} \cdot \mathbf{y}$ denotes the standard inner product $\mathbf{x}^{t} \overline{\mathbf{y}}=\sum_{i=1}^{n} x_{i} \bar{y}_{i}$.
4. For an $n$-row vector $\mathbf{u}$ and an $n$-column vector $\mathbf{v}$, the product $\mathbf{u} \overline{\mathbf{v}}$ as matrices is often written by the same notation $\mathbf{u} \cdot \mathbf{v}$.
5. $E_{n}$ denotes the $n$-square identity matrix and $J$ denotes the matrix $\left(\begin{array}{cc}0 & -1 \\ 1 & 0\end{array}\right)$.
6. For $n_{i}$-square matrices $A_{i}(1 \leq i \leq k)$, we denote by $\operatorname{diag}\left(A_{1}, A_{2}, \ldots, A_{k}\right)$ the ( $\sum_{i=1}^{k} n_{i}$ )-square block-diagonal matrix.
7. $M(n, m, \boldsymbol{K})($ resp. $M(n, \boldsymbol{K}))$ denote the set of all $\boldsymbol{K}$-matrices of type $n \times m$ (resp. $n \times n$ ).
8. On the group $\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$. In this section we study basic properties of Lie groups of the form $\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$.
1.1 Structure matrix of the group $\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$. Let $\mathbf{t}=\left(t_{1}, t_{2}, \cdots, t_{m}\right)^{t} \in \boldsymbol{R}^{m}, \mathbf{x}=$ $\left(x_{1}, x_{2}, \cdots, x_{n}\right)^{t} \in \boldsymbol{R}^{n}$, and let exp $\mathbf{t}$ be the vector $\left(e^{t_{1}}, e^{t_{2}}, \cdots, e^{t_{m}}\right)^{t} \in \boldsymbol{R}_{+}^{m}$. We denote by $\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$ the semidirect product group of $\boldsymbol{R}_{+}^{m}$ and $\boldsymbol{R}^{n}$ determined by a homomorphism $\psi: \boldsymbol{R}_{+}^{m} \rightarrow \operatorname{Aut}\left(\boldsymbol{R}^{n}\right) \cong G L(n, \boldsymbol{R})$. By definition, $\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$ is the direct product $\boldsymbol{R}_{+}^{m} \times \boldsymbol{R}^{n}$
as a set, and the multiplication law is given as follows ( $[10$, p. 18]):

$$
(\exp \mathbf{t}, \mathbf{x})\left(\exp \mathbf{t}^{\prime}, \mathbf{x}^{\prime}\right)=\left(\exp \left(\mathbf{t}+\mathbf{t}^{\prime}\right), \mathbf{x}+\psi(\exp \mathbf{t})\left(\mathbf{x}^{\prime}\right)\right), \quad \mathbf{t}, \mathbf{t}^{\prime} \in \boldsymbol{R}^{m}, \mathbf{x}, \mathbf{x}^{\prime} \in \boldsymbol{R}^{n}
$$

In this paper, we always assume that the homomorphism $\psi$ is diagonalizable. That is, we assume that the matrix $d \psi(\mathbf{t})$ is diagonalizable over $\boldsymbol{C}$ for any $\mathbf{t} \in \boldsymbol{R}^{m}$, where $d \psi: \boldsymbol{R}^{m} \rightarrow$ $M(n, \boldsymbol{R})$ denotes the differential of $\psi$.

Take a basis $\left\{\mathbf{e}_{j} \mid 1 \leq j \leq m\right\}$ of $\boldsymbol{R}^{m}$ and put $d \psi\left(\mathbf{e}_{j}\right)=: A_{j}$. Choose a complex $n$ square matrix $U$ which simultaneously diagonalizes $\left\{A_{j} \mid 1 \leq j \leq m\right\}$, and let $\lambda_{i}^{j}$ be the $i$-th diagonal element of $U^{-1} A_{j} U$. Let $\Lambda_{\psi} \in M(n, m, \boldsymbol{C})$ be the matrix whose $(i, j)$-element is $\lambda_{i}^{j}$. We call the matrix $\Lambda_{\psi}$ the structure matrix (with respect to $\left\{\mathbf{e}_{j}\right\}$ and $U$ ) of the semidirect product group $G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$. Denote by $\Lambda_{i} \in \boldsymbol{C}^{m}$ the $i$-th row vector of $\Lambda_{\psi}$. Note that, if $\Lambda_{i} \in \boldsymbol{C}^{m} \backslash \boldsymbol{R}^{m}$, then there exists a permutation $\sigma \in \mathcal{S}_{n}$ such that $\overline{\Lambda_{i}}=\Lambda_{\sigma(i)}(1 \leq i \leq n)$.

Two matrices $\Lambda, \Lambda^{\prime} \in M(n, m, \boldsymbol{C})$ are said to be equivalent if $\Lambda^{\prime}=K \Lambda P$, where $K$ is an $n$-square matrix which exchanges rows of $\Lambda$ and $P \in G L(m, \boldsymbol{R})$. It is easy to see that the equivalence class of the structure matrix $\Lambda_{\psi}$ does not depend on the choice of $\left\{\mathbf{e}_{j}\right\}$ or $U$.

Denote by $N_{G}$ the maximal connected nilpotent normal subgroup of $G$ ([13, p. 2]).
Lemma 1.1. (1) If $\boldsymbol{R}-\operatorname{rank}\left(\Lambda_{\psi}\right)=m-s(s>0)$, then the group $G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$ has another semidirect product structure $G=\boldsymbol{R}_{+}^{m-s} \ltimes_{\psi^{\prime}} \boldsymbol{R}^{n+s}$, where $\boldsymbol{R}-\operatorname{rank}\left(\Lambda_{\psi^{\prime}}\right)=m-s$.
(2) $\boldsymbol{R}-\operatorname{rank}\left(\Lambda_{\psi}\right)=m$ if and only if $N_{G}=\{\mathbf{1}\} \ltimes_{\psi} \boldsymbol{R}^{n}$.

Proof. Suppose $\boldsymbol{R}-\operatorname{rank}\left(\Lambda_{\psi}\right)=m-s$. Choose a basis $\left\{\mathbf{e}_{j}^{\prime} \mid 1 \leq j \leq m\right\}$ of $\boldsymbol{R}^{m}$ such that the subset $\left\{\mathbf{e}_{j}^{\prime} \mid m-s+1 \leq j \leq m\right\}$ spans the kernel of $d \psi: \boldsymbol{R}^{m} \rightarrow M(n, \boldsymbol{R})$. Define a homomorphism $\psi^{\prime}: \boldsymbol{R}_{+}^{m-s} \rightarrow G L(n+s, \boldsymbol{R})$ by $\psi^{\prime}\left(\exp \left(\mathbf{e}_{j}^{\prime}\right)\right):=\operatorname{diag}\left(\psi\left(\exp \left(\mathbf{e}_{j}^{\prime}\right)\right), E_{s}\right)(1 \leq j \leq$ $m-s$ ), and consider the semidirect product $\boldsymbol{R}_{+}^{m-s} \ltimes_{\psi^{\prime}} \boldsymbol{R}^{n+s}$. Then it is easy to see that the map $\left(\exp \left(\sum_{j=1}^{m} t_{j} \mathbf{e}_{j}^{\prime}\right),\left(x_{1}, \ldots, x_{n}\right)\right) \mapsto\left(\exp \left(\sum_{j=1}^{m-s} t_{j} \mathbf{e}_{j}^{\prime}\right),\left(x_{1}, \ldots, x_{n}, t_{m-s+1}, \ldots, t_{m}\right)\right)$ determines an isomorphism from $G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$ to $\boldsymbol{R}_{+}^{m-s} \ltimes_{\psi^{\prime}} \boldsymbol{R}^{n+s}$. Obviously the homomorphism $\psi^{\prime}$ is diagonalizable and $\boldsymbol{R}-\operatorname{rank}\left(\Lambda_{\psi^{\prime}}\right)=m-s$. Thus we have proved (1) and the sufficiency part of (2) because $N_{G} \supset\{\mathbf{1}\} \ltimes_{\psi^{\prime}} \boldsymbol{R}^{n+s}$.

We prove the necessity in (2). Suppose $N_{G} \supsetneqq\{\mathbf{1}\} \ltimes_{\psi} \boldsymbol{R}^{n}$. Choose (exps, x) $\in N_{G} \backslash$ $\{\mathbf{1}\} \ltimes_{\psi} \boldsymbol{R}^{n}$. Then the $d$-th iterated commutator of $(\exp a \mathbf{s}, \mathbf{x})(a \in \boldsymbol{R})$ and $\left(\mathbf{1}, \mathbf{x}^{\prime}\right)\left(\mathbf{x}^{\prime} \in\right.$ $\left.\boldsymbol{R}^{\boldsymbol{n}}\right)$ is given by $\left[(\exp a \mathbf{s}, \mathbf{x}), \cdots,\left[(\exp a \mathbf{s}, \mathbf{x}),\left[(\exp a \mathbf{s}, \mathbf{x}),\left(\mathbf{1}, \mathbf{x}^{\prime}\right)\right]\right] \cdots\right]=(\mathbf{1},(\psi(\exp a \mathbf{s})-$ $\left.\mathrm{id})^{d}\left(\mathbf{x}^{\prime}\right)\right)$. Since $N_{G}$ is nilpotent, there is $d>0$ such that $(\psi(\exp a \mathbf{s})-\mathrm{id})^{d}=0$ for any $a \in \boldsymbol{R}$. This implies $\Lambda_{\psi} \mathbf{s}=\mathbf{0}$ and $\boldsymbol{R}-\operatorname{rank}\left(\Lambda_{\psi}\right)<m$.

Note that $\boldsymbol{R}-\operatorname{rank}\left(\Lambda_{\psi}\right)=m$ if and only if $\psi$ is locally injective, that is, $d \psi$ is injective. By Lemma 1.1(1), in considering a semidirect product $\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$, we may assume that the homomorphism $\psi$ is locally injective (and in particular, $m \leq n$ ). Put $D(n, m):=\left\{\boldsymbol{R}_{+}^{m} \ltimes_{\psi}\right.$ $\boldsymbol{R}^{n} \mid \psi$ is diagonalizable and locally injective $\}$, and let $\mathcal{D}(n, m)$ denote the set of isomorphism classes of $D(n, m)$. From Lemma 1.1, we obtain the following.

Lemma 1.2. Let $G$ be a Lie group. Then $G \in \mathcal{D}(n, m)$ if and only if the following conditions are satisfied: (1) $N_{G} \cong \boldsymbol{R}^{n}$ and $G / N_{G} \cong \boldsymbol{R}^{m}$. (2) The natural exact sequence $1 \xrightarrow{\mathfrak{l}} N_{G} \rightarrow G \rightarrow G / N_{G} \rightarrow 1$ has a splitting $\xi: G / N_{G} \rightarrow G$. (3) The homomorphism $\psi: G / N_{G} \rightarrow \operatorname{Aut}\left(N_{G}\right)$ determined by $\iota(\psi(h))(g)=\xi(h) \iota(g) \xi(h)^{-1}\left(g \in N_{G}, h \in G / N_{G}\right)$ is diagonalizable.

Let $S(n, m):=\{\Lambda \in M(n, m, \boldsymbol{C}) \mid \boldsymbol{R}-\operatorname{rank}(\Lambda)=m$ and $\bar{\Lambda}=K \Lambda$ for some row exchanging matrix $K\}$. The structure matrix of a semidirect product group $G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n} \in$ $D(n, m)$ belongs to $S(n, m)$. Let $\mathcal{S}(n, m)$ denote the set of equivalence classes of matrices in $S(n, m)$.

PRoposition 1.3. The map $\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n} \mapsto \Lambda_{\psi}$ induces a bijection from $\mathcal{D}(n, m)$ to $\mathcal{S}(n, m)$.

Proof. We show the well-definedness of the induced map. Suppose $G=G / N_{G} \ltimes_{\psi}$ $N_{G}$ and $G^{\prime}=G^{\prime} / N_{G^{\prime}} \ltimes \psi^{\prime} N_{G^{\prime}}\left(G, G^{\prime} \in \mathcal{D}(n, m)\right)$ are isomorphic by $\phi: G \rightarrow G^{\prime}$. Then the isomorphism $\phi$ naturally induces two isomorphisms $\phi_{0}: N_{G} \rightarrow N_{G^{\prime}}$ and $\phi_{1}: G / N_{G} \rightarrow$ $G^{\prime} / N_{G^{\prime}}$, which satisfy the following condition:

$$
\phi_{0}^{-1}\left(\psi^{\prime}\left(\phi_{1}(\exp \mathbf{t})\right)\left(\phi_{0}(\mathbf{x})\right)\right)=\psi(\exp \mathbf{t})(\mathbf{x}), \quad \exp \mathbf{t} \in G / N_{G}, \mathbf{x} \in N_{G}
$$

It follows that the groups $G$ and $G^{\prime}$ have equivalent structure matrices. The rest of the proof is easy and is omitted.

Lemma 1.2 and Proposition 1.3 imply that $\mathcal{D}(n, m) \cap \mathcal{D}\left(n^{\prime}, m^{\prime}\right)=\emptyset$ if $(n, m) \neq\left(n^{\prime}, m^{\prime}\right)$, and the equivalence class of the structure matrix of $G \in \cup_{n, m} \mathcal{D}(n, m)$ is determined by its isomorphism class. It is easy to see that the assumptions on structure matrices in Theorems 1 and 2 , and in the succeeding Propositions as well, depend only on their equivalence classes. By these reasons, as the structure matrix of a given Lie group $G \in \mathcal{D}(n, m)$ we may take any representative in its equivalence class.
1.2. Canonical coordinates. Let $l$ and $r$ be non-negative integers such that $l+2 r=n$. We say that $\Lambda \in S(n, m)$ is of type $(l, r)$ if $\Lambda$ has $l$ real row vectors and $2 r$ non-real row vectors. In that case, we say that $\Lambda$ is well-arranged if the last $2 r$ row vectors are non-real and $\overline{\Lambda_{l+2 j-1}}=\Lambda_{l+2 j}(1 \leq j \leq r)$.

Let $G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n} \in D(n, m)$. We also say that $G$ is of type $(l, r)$ if its structure matrix $\Lambda_{\psi}=\left(\lambda_{i}^{j}\right)$ is of type $(l, r)$. For such a $G$, up to equivalence, we may assume that $\Lambda_{\psi}$ is well-arranged, and can take a coordinate $(\exp \mathbf{t}, \mathbf{x})$ of $G$ so that the differential $d \psi(\mathbf{t})$ is given by the following real canonical form.

$$
\begin{align*}
d \psi(\mathbf{t})=\operatorname{diag} & \left(\sum_{j=1}^{m} \lambda_{1}^{j} t_{j}, \ldots, \sum_{j=1}^{m} \lambda_{l}^{j} t_{j},\left(\sum_{j=1}^{m}\left(\Re \lambda_{l+1}^{j}\right) t_{j}\right) E_{2}+\left(\sum_{j=1}^{m}\left(\Im \lambda_{l+1}^{j}\right) t_{j}\right) J, \ldots,\right. \\
& \left.\left(\sum_{j=1}^{m}\left(\Re \lambda_{l+2 r-1}^{j}\right) t_{j}\right) E_{2}+\left(\sum_{j=1}^{m}\left(\Im \lambda_{l+2 r-1}^{j}\right) t_{j}\right) J\right) . \tag{1.1}
\end{align*}
$$

Such a coordinate of $G$ will be called a canonical coordinate.

From now on, we assume that the structure matrix of $G \in \mathcal{D}(n, m)$ is well-arranged and $G$ has a canonical coordinate, unless otherwise specified.
1.3. The case of $m=n$. Let $G_{n}(l, r)$ be the Lie group $\boldsymbol{R}_{+}^{n} \ltimes_{\psi_{n}(l, r)} \boldsymbol{R}^{n}$ in $D(n, n)$, where the homomorphism $\psi_{n}(l, r)$ is defined by

$$
d \psi_{n}(l, r)(\mathbf{t})=\operatorname{diag}\left(t_{1}, \ldots, t_{l},\left(t_{l+1} E_{2}+t_{l+r+1} J\right), \ldots,\left(t_{l+r} E_{2}+t_{l+2 r} J\right)\right)
$$

It is easy to see that the group $G_{n}(l, r)$ is isomorphic to $\operatorname{Aff}^{+}(\boldsymbol{R})^{l} \times \widetilde{\operatorname{Aff}}(\boldsymbol{C})^{r}$.
Proposition 1.4. Let $G=\boldsymbol{R}_{+}^{n} \ltimes_{\psi} \boldsymbol{R}^{n} \in D(n, n)$ be of type $(l, r)$. Then $G$ is isomorphic to $\operatorname{Aff}^{+}(\boldsymbol{R})^{l} \times \widetilde{\operatorname{Aff}}(\boldsymbol{C})^{r}$.

Proof. Let

$$
P:=\left(\Lambda_{1}^{t}, \Lambda_{2}^{t}, \ldots, \Lambda_{l}^{t}, \Re \Lambda_{l+1}^{t}, \Re \Lambda_{l+3}^{t}, \ldots, \Re \Lambda_{l+2 r-1}^{t}, \mathfrak{\Im} \Lambda_{l+1}^{t}, \Im \Lambda_{l+3}^{t}, \ldots, \mathfrak{\Im} \Lambda_{l+2 r-1}^{t}\right)^{t}
$$

Then it is easy to see that $\Lambda_{\psi} P^{-1}=\Lambda_{\psi_{n}(l, r)}$. From Proposition 1.3 it follows that $G$ is isomorphic to $G_{n}(l, r)$, and hence to $\operatorname{Aff}^{+}(\boldsymbol{R})^{l} \times \widetilde{\operatorname{Aff}}(\boldsymbol{C})^{r}$.
1.4. Lie algebra of $\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$. Let $G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n} \in D(n, m)$ be of type $(l, r)$. Then the Lie algebra $\mathcal{G}$ of right invariant vector fields on $G$ is generated by the following elements:

$$
\begin{align*}
X_{i}= & \frac{\partial}{\partial x_{i}} \quad(1 \leq i \leq n), \\
Y_{j}= & -\frac{\partial}{\partial t_{j}}-\sum_{k=1}^{l} \lambda_{k}^{j} x_{k}\left(\frac{\partial}{\partial x_{k}}\right) \\
& -\sum_{k=1}^{r}\left(\Re \lambda_{l+2 k-1}^{j}\right)\left(x_{l+2 k-1}\left(\frac{\partial}{\partial x_{l+2 k-1}}\right)+x_{l+2 k}\left(\frac{\partial}{\partial x_{l+2 k}}\right)\right)  \tag{1.2}\\
& +\sum_{k=1}^{r}\left(\Im \lambda_{l+2 k-1}^{j}\right)\left(x_{l+2 k}\left(\frac{\partial}{\partial x_{l+2 k-1}}\right)-x_{l+2 k-1}\left(\frac{\partial}{\partial x_{l+2 k}}\right)\right) \quad(1 \leq j \leq m) .
\end{align*}
$$

They satisfy the following commutation relations:

$$
\begin{align*}
& {\left[X_{i}, X_{i^{\prime}}\right]=\left[Y_{j}, Y_{j^{\prime}}\right]=0 \quad\left(1 \leq i, i^{\prime} \leq n, 1 \leq j, j^{\prime} \leq m\right)} \\
& {\left[Y_{j}, X_{i}\right]=\lambda_{i}^{j} X_{i} \quad(1 \leq i \leq l, 1 \leq j \leq m)}  \tag{1.3}\\
& {\left[Y_{j}, X_{l+2 k-1}\right]=\left(\Re \lambda_{l+2 k-1}^{j}\right) X_{l+2 k-1}+\left(\Im \lambda_{l+2 k-1}^{j}\right) X_{l+2 k},} \\
& {\left[Y_{j}, X_{l+2 k}\right]=-\left(\Im \lambda_{l+2 k-1}^{j}\right) X_{l+2 k-1}+\left(\Re \lambda_{l+2 k-1}^{j}\right) X_{l+2 k} \quad(1 \leq j \leq m, 1 \leq k \leq r)}
\end{align*}
$$

For an element $g=(\exp t, \mathbf{x})$ of $G$, the left translation $L_{g}$ and the inner automorphism $\operatorname{Ad}(g)=L_{g} R_{g^{-1}}$ act on these vector fields according to the following formulas:

$$
\begin{aligned}
& \left(L_{g}\right)_{*} X_{i}=e^{\Lambda_{i} \cdot \mathbf{t}} X_{i} \quad(1 \leq i \leq l), \\
& \left(L_{g}\right)_{*}\binom{X_{l+2 j-1}}{X_{l+2 j}}=e^{\left(\Re \Lambda_{l+2 j-1}\right) \cdot \mathbf{t}} \exp \left(\left(-\left(\Im \Lambda_{l+2 j-1}\right) \cdot \mathbf{t}\right) J\right)\binom{X_{l+2 j-1}}{X_{l+2 j}}
\end{aligned}
$$

$$
\begin{equation*}
(1 \leq j \leq r) \tag{1.4}
\end{equation*}
$$

$$
\begin{aligned}
\left(L_{g}\right)_{*} Y_{j}= & Y_{j}+\sum_{k=1}^{l} \lambda_{k}^{j} x_{k} X_{k}+\sum_{k=1}^{r}\left(\Re \lambda_{l+2 k-1}^{j}\right)\left(x_{l+2 k-1} X_{l+2 k-1}+x_{l+2 k} X_{l+2 k}\right) \\
& -\sum_{k=1}^{r}\left(\mathfrak{J} \lambda_{l+2 k-1}^{j}\right)\left(x_{l+2 k} X_{l+2 k-1}-x_{l+2 k-1} X_{l+2 k}\right) \quad(1 \leq j \leq m) .
\end{aligned}
$$

1.5. Unimodular Lie group containing $\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$. Let $G$ be a Lie group. The modular function $\Delta: G \rightarrow \boldsymbol{R}_{+}$is defined by $\Delta(g)=|\operatorname{det}(\operatorname{Ad} g)|$, which measures the deficiency of left invariance of the right invariant volume form of $G$. The Lie group $G$ is said to be unimodular if $\Delta(G)=1$. In particular, if $G$ is connected, $G$ is unimodular if and only if it has a biinvariant volume form. It is easy to see that a Lie group is unimodular if it contains a cocompact discrete subgroup.

Let $G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n} \in D(n, m)$. Denote by $\beta$ the real row $m$-vector $\sum_{i=1}^{n} \Lambda_{i}$. From the formula (1.4), the modular function $\Delta: G \rightarrow \boldsymbol{R}_{+}$is given by $\Delta(\exp \mathbf{t}, \mathbf{x})=\exp \left(\sum_{i=1}^{n} \Lambda_{i}\right.$. $\mathbf{t})=\exp (\beta \cdot \mathbf{t})$.

PRoposition 1.5. Let $G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n} \in D(n, m)$. Suppose that the structure matrix $\Lambda_{\psi}$ of $G$ satisfies

$$
\Lambda_{i} \neq \mathbf{0}(1 \leq i \leq n) \quad \text { and } \quad \beta \notin\left\{ \pm \Lambda_{i}, \Lambda_{i}-\Lambda_{j} \mid 1 \leq i, j \leq n\right\} .
$$

Then there exists uniquely an ( $m+n+1$ )-dimensional simply connected unimodular Lie group $H$ which contains $G$ as a subgroup.

Proof. Consider the Lie group $\tilde{G}:=\boldsymbol{R}_{+}^{m} \ltimes_{\tilde{\psi}} \boldsymbol{R}^{n+1} \in D(n+1, m)$, whose structure matrix $\Lambda_{\tilde{\psi}}$ is given by $\left(\Lambda_{\psi}^{t},-\beta^{t}\right)^{t}$. Note that the group $\tilde{G}$ is unimodular and there is a natural embedding of $G$ into $\tilde{G}$.

We prove the uniqueness. Let $H$ be an $(m+n+1)$-dimensional simply connected unimodular Lie group which contains $G$. Suppose $G$ is of type $(l, r)$, and let $\left\{X_{i}(1 \leq i \leq\right.$ $\left.n), Y_{j}(1 \leq j \leq m)\right\}$ be the basis of the Lie algebra $\mathcal{G}$ of $G$ given in (1.2). From the assumption on $\Lambda_{\psi}$, we can take a vector $\mathbf{t}=\left(t_{1}, t_{2}, \ldots, t_{m}\right)^{t} \in \boldsymbol{R}^{m}$ which satisfies

$$
\begin{align*}
& \beta \cdot \mathbf{t} \neq 0, \quad\left(\beta \pm \Lambda_{i}\right) \cdot \mathbf{t} \neq 0(1 \leq i \leq l), \quad \Lambda_{i} \cdot \mathbf{t} \neq 0(1 \leq i \leq l), \\
& \left(\Lambda_{i}-\beta\right) \cdot \mathbf{t} \neq \Lambda_{j} \cdot \mathbf{t}(1 \leq i, j \leq n), \quad\left(\Im \Lambda_{l+2 k-1}\right) \cdot \mathbf{t} \neq 0(1 \leq k \leq r) . \tag{1.5}
\end{align*}
$$

For such a $\mathbf{t}$, put $Y:=\sum_{j=1}^{m} t_{j} Y_{j}$. Then we have

$$
\begin{align*}
& {\left[Y, Y_{j}\right]=0(1 \leq j \leq m), \quad\left[Y, X_{i}\right]=\left(\Lambda_{i} \cdot \mathbf{t}\right) X_{i}(1 \leq i \leq l)} \\
& {\left[Y, X_{l+2 k-1}-\sqrt{-1} X_{l+2 k}\right]=\left(\Lambda_{l+2 k-1} \cdot \mathbf{t}\right)\left(X_{l+2 k-1}-\sqrt{-1} X_{l+2 k}\right),}  \tag{1.6}\\
& {\left[Y, X_{l+2 k-1}+\sqrt{-1} X_{l+2 k}\right]=\left(\Lambda_{l+2 k} \cdot \mathbf{t}\right)\left(X_{l+2 k-1}+\sqrt{-1} X_{l+2 k}\right)(1 \leq k \leq r)}
\end{align*}
$$

Let $\mathcal{H}$ be the Lie algebra of $H$, and take $Z \in \mathcal{H} \backslash \mathcal{G}$. Since $H$ is unimodular, we have $\operatorname{tr}(\operatorname{ad} Y)=0$. Hence, from (1.6), the bracket $[Y, Z]$ is given by $-(\beta \cdot \mathbf{t}) Z+\sum_{i=1}^{n} a_{i} X_{i}+$ $\sum_{j=1}^{m} b_{j} Y_{j}$ for some $a_{i}, b_{j} \in \boldsymbol{R}$. Put $T:=Z+\sum_{i=1}^{n} c_{i} X_{i}+\sum_{j=1}^{m} d_{j} Y_{j}$, where $d_{j}=$
$-b_{j} /(\beta \cdot \mathbf{t})(1 \leq j \leq m), c_{i}=-a_{i} /\left(\left(\beta+\Lambda_{i}\right) \cdot \mathbf{t}\right)(1 \leq i \leq l)$, and

$$
\binom{c_{l+2 k-1}}{c_{l+2 k}}=\left(\begin{array}{cc}
\left(\Re \Lambda_{l+2 k-1}+\beta\right) \cdot \mathbf{t} & -\left(\Im \Lambda_{l+2 k-1}\right) \cdot \mathbf{t} \\
\left(\Im \Lambda_{l+2 k-1}\right) \cdot \mathbf{t} & \left(\Re \Lambda_{l+2 k-1}+\beta\right) \cdot \mathbf{t}
\end{array}\right)^{-1}\binom{-a_{l+2 k-1}}{-a_{l+2 k}} \quad(1 \leq k \leq r) .
$$

Then, an easy calculation shows that $[Y, T]=-(\beta \cdot \mathbf{t}) T$.
Next we show $\left[X_{i}, T\right]=0(1 \leq i \leq n)$. From the Jacobi identity for the triple $\left(Y, X_{i}, T\right)$, we have $\left[Y,\left[X_{i}, T\right]\right]=\left(\left(\Lambda_{i}-\beta\right) \cdot \mathbf{t}\right)\left[X_{i}, T\right]$. This shows that $\left(\Lambda_{i}-\beta\right) \cdot \mathbf{t}$ would be an eigenvalue of ad $Y$ if $\left[X_{i}, T\right] \neq 0$. However, from (1.5) and (1.6), we see that it is not the case, and hence $\left[X_{i}, T\right]=0$. Replacing $X_{i}$ by $X_{l+2 k-1} \pm \sqrt{-1} X_{l+2 k}$, we also obtain $\left[X_{l+2 k-1}, T\right]=\left[X_{l+2 k}, T\right]=0$.

Similarly, the Jacobi identity for the triple $\left(Y, Y_{j}, T\right)$ gives the identity $\left[Y,\left[Y_{j}, T\right]\right]=$ $-(\beta \cdot \mathbf{t})\left[Y_{j}, T\right]$. This shows that $\left[Y_{j}, T\right]=a T$ for some $a \in \boldsymbol{R}$. From (1.3) and $\operatorname{tr}\left(\operatorname{ad} Y_{j}\right)=0$, we conclude that $\left[Y_{j}, T\right]=-\left(\sum_{i=1}^{n} \lambda_{i}^{j}\right) T$.

The Lie algebra $\mathcal{H}$ is spanned by the vector fields $\left\{T, X_{i}(1 \leq i \leq n), Y_{j}(1 \leq j \leq m)\right\}$ whose bracket products are now completely determined. Since $\mathcal{H}$ is isomorphic to the Lie algebra of $\tilde{G}$, the simply connected Lie group $H$ is isomorphic to $\tilde{G}$.
2. Homogeneous actions. The object of this section is to prove Theorem 2.
2.1. Eigenvalues of commuting integer matrices. In this subsection, we investigate a relation between the eigenvalues of commuting integer matrices.

Let $\boldsymbol{Q}(\alpha)$ be an algebraic number field of degree $u$. Denote by $\mathcal{O}(\alpha) \subset \boldsymbol{Q}(\alpha)$ the subring of all algebraic integers in $\boldsymbol{Q}(\alpha)$. As a $\boldsymbol{Z}$-module, $\mathcal{O}(\alpha)$ has a $\boldsymbol{Z}$-basis consisting of $u$ algebraic integers $w_{1}, w_{2}, \ldots, w_{u}$. Such a basis is called an integral basis. Put $B=\left\{1, \alpha, \ldots, \alpha^{u-1}\right\}$ and $B^{\prime}=\left\{\omega_{1}, \ldots, \omega_{u}\right\}$. Then both $B$ and $B^{\prime}$ are $\boldsymbol{Q}$-bases of the $\boldsymbol{Q}$-vector space $\boldsymbol{Q}(\alpha)$. Let $\left\{\sigma^{(i)} \mid 1 \leq i \leq u\right\}$ be the set of all conjugation mappings of $\boldsymbol{Q}(\alpha)$, where $\sigma^{(1)}$ is the identity map (see, e.g., [4]).

For an element $\gamma \in \boldsymbol{Q}(\alpha)$, define a linear transformation $T_{\gamma}$ of the $\boldsymbol{Q}$-vector space $\boldsymbol{Q}(\alpha)$ by $T_{\gamma}(x)=\gamma x$ for all $x \in \boldsymbol{Q}(\alpha)$. Denote by $\left[T_{\gamma}\right]_{B^{\prime \prime}}$ the matrix of $T_{\gamma}$ with respect to a basis $B^{\prime \prime}$. When $\gamma=\alpha$, the matrix $\left[T_{\alpha}\right]_{B^{\prime \prime}}$ has distinct eigenvalues $\sigma^{(1)}(\alpha)=$ $\alpha, \sigma^{(2)}(\alpha), \ldots, \sigma^{(u)}(\alpha)$, and is diagonalizable. Since each $\gamma \in \boldsymbol{Q}(\alpha)$ is expressed as a $\boldsymbol{Q}$ polynomial $\sum_{s=0}^{u-1} a_{s} \alpha^{s}\left(a_{s} \in \boldsymbol{Q}\right)$, the matrix $\left[T_{\gamma}\right]_{B^{\prime \prime}}=\sum_{s=0}^{u-1} a_{s}\left(\left[T_{\alpha}\right]_{B^{\prime \prime}}\right)^{s}$ is diagonalizable and has eigenvalues $\sigma^{(1)}(\gamma), \sigma^{(2)}(\gamma), \ldots, \sigma^{(u)}(\gamma)$. If $\gamma$ is a unit in $\mathcal{O}(\alpha)$, then the matrix $\left[T_{\gamma}\right]_{B^{\prime}}$ lies in $G L(u, Z)$.

Let $h(x)=\sum_{s=0}^{u} q_{s} x^{s}$ be an irreducible monic $\boldsymbol{Q}$-polynomial of degree $u$. Consider the companion matrix $U(h)$ of $h(x)$ :

$$
U(h):=\left(\begin{array}{c|c}
0 & -q_{0} \\
\hline & -q_{1} \\
E_{u-1} & \vdots \\
& -q_{u-1}
\end{array}\right) .
$$

If $\alpha$ is a root of $h(x)$, then $U(h)$ coincides with the matrix $\left[T_{\alpha}\right]_{B}$.

The following sublemma is well-known (see, e.g., [3, Proposition 6 in §5, Chapter VII]).
Sublemma 2.1. Let $C \in G L(n+1, Q)$ and $\chi_{C}(x)$ the eigenpolynomial of $C$. Let $\chi_{C}(x)=h_{1}(x) h_{2}(x) \cdots h_{d}(x)$ be the decomposition of $\chi_{C}(x)$ into irreducible monic $\boldsymbol{Q}$ polynomials. If $C$ is diagonalizable, then there exists a non-singular rational matrix $P$ such that

$$
P^{-1} C P=\operatorname{diag}\left(U\left(h_{1}\right), U\left(h_{2}\right), \ldots, U\left(h_{d}\right)\right)
$$

Now we prove the main lemma of this subsection.
LEMMA 2.2. Let $\left\{A_{j} \mid 1 \leq j \leq m\right\}$ be commuting, diagonalizable real ( $n+1$ )-square matrices such that $\exp A_{j} \in S L(n+1, Z)$ for any $j$. Let $\operatorname{diag}\left(\lambda_{1}^{j}, \lambda_{2}^{j}, \ldots, \lambda_{n+1}^{j}\right)$ be a simultaneousely diagonalized form of $A_{j}(1 \leq j \leq m)$, and let $\Lambda$ be the matrix whose ( $i, j$ )-element is $\lambda_{i}^{j}$. Then there are an integer vector $\mathbf{t}=\left(t_{1}, t_{2}, \ldots, t_{m}\right)^{t} \in \boldsymbol{Z}^{m}$ and a positive integer $p$ for which the following hold.

Put $A:=p \sum_{j=1}^{m} t_{j} A_{j}$, and let $h_{1}(x) h_{2}(x) \ldots h_{d}(x)$ be the $\mathbf{Z}$-irreducible decomposition of the eigenpolynomial of $\exp A$.
(1) There exists a non-singular rational matrix $P$ such that

$$
\begin{aligned}
P^{-1}(\exp A) P & =\operatorname{diag}\left(U\left(h_{1}\right), U\left(h_{2}\right), \ldots, U\left(h_{d}\right)\right), \\
P^{-1}\left(\exp p A_{j}\right) P & =\operatorname{diag}\left(B_{j}(1), B_{j}(2), \ldots, B_{j}(d)\right) \quad(1 \leq j \leq m),
\end{aligned}
$$

where $B_{j}(k) \in G L\left(u_{k}, \boldsymbol{Q}\right)$ and $u_{k}=\operatorname{deg} h_{k}(x)(1 \leq k \leq d)$.
(2) For each $j(1 \leq j \leq m)$ and $k(1 \leq k \leq d)$, there exist $b_{j k s} \in \boldsymbol{Q}\left(0 \leq s \leq u_{k}-1\right)$ such that $B_{j}(k)=\sum_{s=0}^{u_{k}-1} b_{j k s} U\left(h_{k}\right)^{s}$. Hence, denoting by $\alpha_{k}$ a root of $h_{k}(x)$ and by $\sigma_{k}^{(1)}=$ id, $\sigma_{k}^{(2)}, \ldots, \sigma_{k}^{\left(u_{k}\right)}$ the conjugation mappings of $\boldsymbol{Q}\left(\alpha_{k}\right)$, the matrices $U\left(h_{k}\right)$ and $B_{j}(k)$ are simultaneously diagonalized to

$$
\operatorname{diag}\left(\sigma_{k}^{(1)}\left(\alpha_{k}\right), \sigma_{k}^{(2)}\left(\alpha_{k}\right), \ldots, \sigma_{k}^{\left(u_{k}\right)}\left(\alpha_{k}\right)\right) \quad \text { and } \quad \operatorname{diag}\left(\beta_{1}^{j}(k), \beta_{2}^{j}(k), \ldots, \beta_{u_{k}}^{j}(k)\right)
$$

respectively, where $\beta_{1}^{j}(k)=\sum_{s=0}^{u_{k}-1} b_{j k s}\left(\alpha_{k}\right)^{s}$ and $\beta_{i}^{j}(k)=\sigma_{k}^{(i)}\left(\beta_{1}^{j}(k)\right)$. Moreover each $\beta_{i}^{j}(k)$ is a unit in $\mathcal{O}(\alpha)$.
(3) Put $l(k):=\sum_{t=1}^{k-1} u_{t}(1 \leq k \leq d)$. Then there exists a permutation $\tau \in \mathcal{S}_{n+1}$ such that $\beta_{i}^{j}(k)=\exp \left(p \lambda_{\tau(i+l(k))}^{j}\right)$ for any $i, j$ and $k$.

Proof. Denote by $\Lambda_{i}$ the $i$-th row vector of $\Lambda$. For each $i, i^{\prime}$, consider the subgroup $K_{i i^{\prime}}=\left\{\mathbf{t} \in \boldsymbol{Z}^{m} \mid\left(\Lambda_{i}-\Lambda_{i^{\prime}}\right) \cdot \mathbf{t} \in 2 \pi \sqrt{-1} \boldsymbol{Q}\right\}$ of $\boldsymbol{Z}^{m}$. Take an integer vector $\mathbf{t}=$ $\left(t_{1}, t_{2}, \ldots, t_{m}\right)^{t} \in\left(\bigcup_{\text {rank } K_{i i^{\prime}}<m} K_{i i^{\prime}}\right)^{c}$ and a positive integer $p$ such that $p\left(\Lambda_{i}-\Lambda_{i^{\prime}}\right) \in$ $2 \pi \sqrt{-1} \boldsymbol{Z}^{m}$ whenever $\Lambda_{i}-\Lambda_{i^{\prime}} \in 2 \pi \sqrt{-1} \boldsymbol{Q}^{m}$. Put $A:=p \sum_{j=1}^{m} t_{j} A_{j}$. Then the set of eigenvalues of $A$ (resp. $p A_{j}$ ) is given by $\left\{p \Lambda_{i} \cdot \mathbf{t} \mid 1 \leq i \leq n+1\right\}$ (resp. $\left\{p \lambda_{i}^{j} \mid 1 \leq i \leq n+1\right\}$ ). It is easy to see that, for each $i, i^{\prime}\left(1 \leq i, i^{\prime} \leq n+1\right)$, the following three conditions are equivalent:
(A) $\operatorname{rank} K_{i i^{\prime}}=m$,
(B) $\exp \left(p \Lambda_{i} \cdot \mathbf{t}\right)=\exp \left(p \Lambda_{i^{\prime}} \cdot \mathbf{t}\right)$,
(C) $\exp \left(p \lambda_{i}^{j}\right)=\exp \left(p \lambda_{i^{\prime}}^{j}\right)(1 \leq j \leq m)$.

From the implication $(\mathrm{B}) \Rightarrow(\mathrm{C})$, it follows that each eigenvector of $\exp A$ is also an eigenvector of $\exp p A_{j}$ for each $j$.

On the other hand, from Sublemma 2.1, there is a non-singular rational matrix $P$ such that $P^{-1}(\exp A) P=\operatorname{diag}\left(U\left(h_{1}\right), U\left(h_{2}\right), \ldots, U\left(h_{d}\right)\right)$. For each $k(1 \leq k \leq d)$, take a matrix $V(k)$ diagonalizing $U\left(h_{k}\right)$, and put $V:=\operatorname{diag}(V(1), V(2), \ldots, V(d))$. Then the matrix $P V$ diagonalizes $\exp A$, and hence $\exp p A_{j}$ for each $j$. This shows that there exist $B_{j}(k) \in G L\left(u_{k}, \boldsymbol{Q}\right)$ such that $P^{-1}\left(\exp p A_{j}\right) P=\operatorname{diag}\left(B_{j}(1), B_{j}(2), \ldots, B_{j}(d)\right)$. Hence we have proved (1).

Let $\alpha_{k}$ be a root of $h_{k}(x)$ and take the basis $B=\left\{1, \alpha_{k},\left(\alpha_{k}\right)^{2}, \ldots,\left(\alpha_{k}\right)^{u_{k}-1}\right\}$ of the $\boldsymbol{Q}$ vector space $\boldsymbol{Q}\left(\alpha_{k}\right)$. Then we can define a linear map $T_{j}(k)$ of $\boldsymbol{Q}\left(\alpha_{k}\right)$ by $\left[T_{j}(k)\right]_{B}:=B_{j}(k)$. Since $U\left(h_{k}\right)$ and $B_{j}(k)$ are commutative and $U\left(h_{k}\right)=\left[T_{\alpha_{k}}\right]_{B}$, the linear maps $T_{\alpha_{k}}$ and $T_{j}(k)$ are also commutative. Therefore we have, for each $x=\sum_{s=0}^{u_{k}-1} a_{s}\left(\alpha_{k}\right)^{s} \in \boldsymbol{Q}\left(\alpha_{k}\right)$,

$$
T_{j}(k)\left(\sum_{s=0}^{u_{k}-1} a_{s}\left(\alpha_{k}\right)^{s}\right)=\sum_{s=0}^{u_{k}-1} a_{s} T_{j}(k)\left(T_{\alpha_{k}}\right)^{s}(1)=\left(\sum_{s=0}^{u_{k}-1} a_{s}\left(\alpha_{k}\right)^{s}\right) T_{j}(k)(1)
$$

This shows that $T_{j}(k)$ is the linear map given by $T_{j}(k)(x)=T_{j}(k)(1) x$. Put $\beta_{1}^{j}(k):=$ $T_{j}(k)(1)$. Then there exist $b_{j k s} \in \boldsymbol{Q}\left(0 \leq s \leq u_{k}-1\right)$ such that $\beta_{1}^{j}(k)=\sum_{s=0}^{u_{k}-1} b_{j k s}\left(\alpha_{k}\right)^{s}$, and hence the matrix $\left[T_{j}(k)\right]_{B}=B_{j}(k)$ is of the form $\sum_{s=0}^{u_{k}-1} b_{j k s}\left[T_{\alpha_{k}}\right]_{B}^{s}=\sum_{s=0}^{u_{k}=1} b_{j k s} U\left(h_{k}\right)^{s}$. Since $\exp \left( \pm p A_{j}\right) \in S L(n+1, \boldsymbol{Z})$, each number $\beta_{i}^{j}(k)$ is a unit in $\mathcal{O}\left(\alpha_{k}\right)$. This proves (2).

The assertion (3) follows from the definition of the numbers $\left\{\beta_{i}^{j}(k)\right\}$.
2.2. Cocompact discrete subgroups of $\boldsymbol{R}_{+}^{m} \ltimes \boldsymbol{R}^{n+1}$. In this subsection we give a necessary and sufficient condition for a unimodular Lie group $H=\boldsymbol{R}_{+}^{m} \ltimes_{\varphi} \boldsymbol{R}^{n+1} \in D(n+1, m)$ to have a cocompact discrete subgroup.

Lemma 2.3. Let $H=\boldsymbol{R}_{+}^{m} \ltimes_{\varphi} \boldsymbol{R}^{n+1}$ be a group in $D(n+1, m)$. Let $\Gamma$ be a cocompact discrete subgroup of $H$. Then the following hold.
(1) The intersection $\Gamma_{0}:=\Gamma \cap \boldsymbol{R}^{n+1}$ is a cocompact discrete subgroup of $\boldsymbol{R}^{n+1} \cong$ $\{\mathbf{1}\} \ltimes_{\psi} \boldsymbol{R}^{n+1}$.
(2) The quotient $\Gamma_{1}:=\Gamma / \Gamma_{0} \subset \boldsymbol{R}_{+}^{m}$ is a cocompact discrete subgroup of $\boldsymbol{R}_{+}^{m} \cong$ $H /\left(\{\mathbf{1}\} \ltimes_{\psi} \boldsymbol{R}^{n+1}\right)$.
(3) With respect to any generating sets $\left\{\exp \mathbf{e}_{j} \mid 1 \leq j \leq m\right\}$ of $\Gamma_{1}$ and $\left\{\mathbf{f}_{i} \mid 1 \leq i \leq\right.$ $n+1\}$ of $\Gamma_{0}$, the homomorphism $\varphi: \boldsymbol{R}_{+}^{m} \rightarrow \operatorname{Aut}\left(\boldsymbol{R}^{n+1}\right) \cong G L(n+1, \boldsymbol{R})$ is expressed as follows: Put $d \varphi\left(\mathbf{e}_{j}\right)=: A_{j} \in M(n+1, \boldsymbol{R})(1 \leq j \leq m)$. Then the matrices $\left\{A_{j}\right\}$ are commutative, $\exp A_{j} \in S L(n+1, \boldsymbol{Z})$ and $\varphi\left(\exp \left(\sum_{j=1}^{m} t_{j} \mathbf{e}_{j}\right)\right)=\exp \left(\sum_{j=1}^{m} t_{j} A_{j}\right)$.

Proof. Obviously, $\Gamma_{0}$ is discrete in $\boldsymbol{R}^{n+1}$. From Lemma 1.1(2), the normal subgroup $\boldsymbol{R}^{n+1}$ of $H$ coincides with $N_{H}$. By a theorem of Mostow ([13, Theorem 3.4]), $N_{H} \cap \Gamma$ is cocompact in $N_{H}$. Hence (1) is proved.

The extension $1 \rightarrow \boldsymbol{R}^{n+1} \xrightarrow{\iota} H \xrightarrow{\pi} \boldsymbol{R}_{+}^{m} \rightarrow 1$ induces continuous maps $\boldsymbol{R}^{n+1} / \Gamma_{0} \xrightarrow{i}$ $H / \Gamma \xrightarrow{\bar{\pi}} \boldsymbol{R}_{+}^{m} / \Gamma_{1}$. The quotient $\boldsymbol{R}_{+}^{m} / \Gamma_{1}$ is the continuous image of the compact space $H / \Gamma$
by $\bar{\pi}$ and hence is compact. Suppose $\Gamma_{1}$ is not discrete in $\boldsymbol{R}_{+}^{m}$. Then there is a sequence $\left\{\exp \mathbf{t}_{k} \mid k=1,2, \ldots\right\}$ in $\Gamma_{1}$ such that $\lim _{k \rightarrow \infty} \exp \mathbf{t}_{k}=\exp \mathbf{t}_{\infty} \in \Gamma_{1} \subset \boldsymbol{R}_{+}^{m}$ and $\exp \mathbf{t}_{k} \neq$ $\exp \mathbf{t}_{\infty}$ for all $k$. From (1) there is a compact fundamental domain $K \subset \boldsymbol{R}^{n+1}$ for the subgroup $\Gamma_{0} \subset \boldsymbol{R}^{n+1}$. So, for each $k$, we can take a lift $\left(\exp \mathbf{t}_{k}, \mathbf{x}_{k}\right) \in \Gamma$ of $\exp \mathbf{t}_{k} \in \Gamma_{1}$ such that $\mathbf{x}_{k} \in K$. Because the sequence $\left\{\left(\exp \mathbf{t}_{k}, \mathbf{x}_{k}\right)\right\} \subset \Gamma$ is both discrete and lies in a compact subset of $\boldsymbol{R}_{+}^{m} \times \boldsymbol{R}^{n+1}$, it is a finite set. This contradicts the choice of $\left\{\exp \mathbf{t}_{k}\right\}$. We have thus proved (2).

We now prove the third assertion. From (1) and (2), the group $\Gamma_{0}$ (resp. $\Gamma_{1}$ ) is isomorphic to $\boldsymbol{Z}^{n+1}\left(\operatorname{resp} . \exp \left(\boldsymbol{Z}^{m}\right)\right)$. For any element $\exp \mathbf{t} \in \Gamma_{1}$ and its lift $(\exp \mathbf{t}, \mathbf{x}) \in \Gamma$, we have $(\exp \mathbf{t}, \mathbf{0}) \Gamma_{0}(\exp \mathbf{t}, \mathbf{0})^{-1}=(\exp \mathbf{t}, \mathbf{x}) \Gamma_{0}(\exp \mathbf{t}, \mathbf{x})^{-1}=\Gamma_{0}$. It follows that $\varphi(\exp \mathbf{t}) \in$ $\operatorname{Aut}\left(\boldsymbol{R}^{n+1}, \Gamma_{0}\right):=\left\{f \in \operatorname{Aut}\left(\boldsymbol{R}^{n+1}\right) \mid f\left(\Gamma_{0}\right)=\Gamma_{0}\right\}$. The group $\operatorname{Aut}\left(\boldsymbol{R}^{n+1}, \Gamma_{0}\right)$ is identified with $G L(n+1, Z)$, whenever we choose a generating set of $\Gamma_{0}$. Obviously, $\varphi\left(\Gamma_{1}\right) \subset$ $S L(n+1, Z)$.

Now we are in a position to prove the main proposition of this subsection.
PRoposition 2.4. Let $H=\boldsymbol{R}_{+}^{m} \ltimes_{\varphi} \boldsymbol{R}^{n+1}$ be a unimodular Lie group in $D(n+1, m)$. Then $H$ contains a cocompact discrete subgroup if and only if the structure matrix $\Lambda_{\varphi}$ of $H$ is equivalent to a matrix $\hat{\Lambda}$ satisfying the following conditions.
(1) There exist $\Lambda(k) \in M\left(u_{k}, m, \boldsymbol{C}\right)(1 \leq k \leq d)$ such that $\hat{\Lambda}^{t}=\left(\Lambda(1)^{t}, \Lambda(2)^{t}, \ldots\right.$, $\left.\Lambda(d)^{t}\right)^{t}$.
(2) For each $k(1 \leq k \leq d)$, there exists an algebraic integer $\alpha_{k}$ of degree $u_{k}$ such that $\exp \lambda_{i}^{j}(k)=\sigma_{k}^{(i)}\left(\exp \lambda_{1}^{j}(k)\right) \in \boldsymbol{Q}\left(\sigma_{k}^{(i)}\left(\alpha_{k}\right)\right)\left(1 \leq j \leq m, 1 \leq i \leq u_{k}\right)$. Here $\left\{\sigma_{k}^{(i)} \mid 1 \leq\right.$ $i \leq u_{k}, \sigma_{k}^{(1)}=\mathrm{id} \mathrm{\}}$ is the set of all conjugation mappings of $\boldsymbol{Q}\left(\alpha_{k}\right)$, and $\lambda_{i}^{j}(k)$ denotes the $(i, j)$-element of $\Lambda(k)$.
(3) Each number $\exp \left( \pm \lambda_{i}^{j}(k)\right)$ is an algebraic integer.

Proof. Suppose that $H$ contains a cocompact discrete subgroup. From (3) in Lemma 2.3, we can choose a basis $\left\{\mathbf{e}_{j} \mid 1 \leq j \leq m\right\}$ of $\boldsymbol{R}^{m}$ such that $\exp A_{j} \in S L(n+1, \boldsymbol{Z})$ for $A_{j}:=d \varphi\left(\mathbf{e}_{j}\right)$. We apply Lemma 2.2 to these matrices $\left\{A_{j}\right\}$. Then the structure matrix $\Lambda_{\varphi}=\Lambda=\left(\lambda_{i}^{j}\right)$ of $H$ is equivalent to a matrix $\hat{\Lambda}$ whose $(i, j)$-element is $p \lambda_{\tau(i)}^{j}$, where $\Lambda \in S(n+1, m), p \in \boldsymbol{Z}$ and $\tau \in \mathcal{S}_{n+1}$ are as in the lemma. The matrix $\hat{\Lambda}$ satisfies the conditions (1)-(3) from Lemma 2.2.

Next we prove the sufficiency. From (2), for each $j(1 \leq j \leq m)$, we can define a linear automorphism $T_{j}(k)$ of $\boldsymbol{Q}\left(\alpha_{k}\right)$ by $T_{j}(k)(x)=\left(\exp \lambda_{1}^{j}(k)\right) x$. Let $B^{\prime}(k)$ be an integral basis of $\mathcal{O}\left(\alpha_{k}\right)$. Then, there exists $V(k) \in G L\left(u_{k}, \boldsymbol{C}\right)$ such that $V(k)^{-1}\left[T_{j}(k)\right]_{B^{\prime}(k)} V(k)=$ $\operatorname{diag}\left(\exp \lambda_{1}^{j}(k), \exp \lambda_{2}^{j}(k), \ldots, \exp \lambda_{u_{k}}^{j}(k)\right)$. From (3), $\left[T_{j}(k)\right]_{B^{\prime}(k)} \in G L\left(u_{k}, \boldsymbol{Z}\right)$. Because $H$ is unimodular, $\sum_{k=1}^{d} \sum_{i=1}^{u_{k}} \lambda_{i}^{j}(k)=0$. It follows that the matrix $X_{j}:=\operatorname{diag}\left(\left[T_{j}(1)\right]_{B^{\prime}(1)}\right.$, $\left.\left[T_{j}(2)\right]_{B^{\prime}(2)}, \ldots,\left[T_{j}(d)\right]_{B^{\prime}(d)}\right)$ is in $S L(n+1, \boldsymbol{Z})$. It is easy to see that there exist commuting, diagonalizable matrices $C_{j} \in M(n+1, \boldsymbol{R})$ such that (a) $\exp C_{j}=X_{j}$ and (b) the eigenvalues of $C_{j}$ are $\left\{\lambda_{i}^{j}(k) \mid 1 \leq i \leq u_{k}, 1 \leq k \leq d\right\}$.

Now define a homomorphism $\varphi^{\prime}: \boldsymbol{R}_{+}^{m} \rightarrow S L(n+1, \boldsymbol{R})$ by $\varphi^{\prime}\left(\exp \left(t_{1}, \ldots, t_{m}\right)^{t}\right)=$ $\exp \left(\sum_{j=1}^{m} t_{j} C_{j}\right)$, and put $H^{\prime}:=\boldsymbol{R}_{+}^{m} \ltimes_{\varphi^{\prime}} \boldsymbol{R}^{n+1}$. From (a), $H^{\prime}$ contains a cocompact discrete subgroup $\Gamma^{\prime}:=\exp \left(\mathbf{Z}^{m}\right) \ltimes_{\varphi^{\prime}} \mathbf{Z}^{n+1}$. From (b), the structure matrix of $H^{\prime}$ is equivalent to $\hat{\Lambda}$, and hence to $\Lambda_{\varphi}$. Thus $H^{\prime}$ is isomorphic to $H$ from Proposition 1.3. Consequently, $H$ also has a cocompact discrete subgroup.

It should be remarked that a general theorem of Mostow [11] gives a necessary and sufficient condition for a solvable Lie group to have a cocompact discrete subgroup. On the other hand, our conditions in Proposition 2.4 are for Lie groups of the form $H=\boldsymbol{R}_{+}^{m} \ltimes_{\varphi} \boldsymbol{R}^{n+1}$ and are more concrete.
2.3. Proof of Theorem 2. From Proposition 2.4, we can now prove Theorem 2 in Introduction.

Proof of Theorem 2. Let $H$ be an $(m+n+1)$-dimensional simply connected unimodular Lie group which contains $G$. From Proposition 1.5, $H$ is isomorphic to $\tilde{G}=$ $\boldsymbol{R}_{+}^{m} \ltimes_{\tilde{\psi}} \boldsymbol{R}^{n+1} \in D(n+1, m)$ whose structure matrix $\Lambda_{\tilde{\psi}}$ is given by $\left(\Lambda_{\psi}^{t},-\beta^{t}\right)^{t}$. Thus the theorem follows from Proposition 2.4.

In the case where $m=n$, we obtain a corollary of Theorem 2.
Corollary 2.5. Let $G=\boldsymbol{R}_{+}^{n} \ltimes_{\psi} \boldsymbol{R}^{n}(n \geq 2)$ be a group in $D(n, n)$. Then $G$ has a codimension one homogeneous action.

Note that, when $n \geq 2$, the asumptions that (1) $\Lambda_{i} \neq \mathbf{0}(1 \leq i \leq n)$ and (2) $\beta \notin$ $\left\{ \pm \Lambda_{i}, \Lambda_{i}-\Lambda_{j} \mid 1 \leq i, j \leq n\right\}$ in Theorem 2 follow from the local injectivity of $\psi$. When $n=1$, the condition (2) does not hold. But, in this case, the Lie group $G=\boldsymbol{R}_{+}^{1} \ltimes_{\psi} \boldsymbol{R}^{1}$ is isomorphic to $\mathrm{Aff}^{+}(\boldsymbol{R})$ and the conclusion of the corollary is true (see, e.g., [5]).

To prove Corollary 2.5, we first show a lemma.
Lemma 2.6. For each integer $s \geq 2$ and a pair of non-negative integers $(t, u)$ such that $t+2 u=s$, there exists an irreducible monic $\boldsymbol{Z}$-polynomial of degree $s$ which has $t$ real roots and $2 u$ non-real roots.

Proof. For the given integer $s$, let $f_{s}(x)=(-1)^{s-1}(x-4)\left(x-4^{2}\right) \cdots\left(x-4^{s}\right)$, and $\left\{f_{s}\left(\alpha_{i}\right)\right\}\left(\alpha_{1}<\alpha_{2}<\cdots<\alpha_{s-1}\right)$ be the set of all local maxima and minima of $f_{s}(x)$. Obviously one has (1) $4^{i}<\alpha_{i}<4^{i+1}(1 \leq i \leq s-1)$ and (2) $f_{s}\left(\alpha_{2 j-1}\right)>0>f_{s}\left(\alpha_{2 j}\right)$ $(j=1,2, \ldots)$. Put $a_{i}:=\left(4^{i}+4^{i+1}\right) / 2(1 \leq i \leq s+1)$. Then, by some calculations, one can show (3) $f_{s}\left(\alpha_{1}\right) \geq f_{s}\left(a_{1}\right) \geq 36$ and (4) $\left|f_{s}\left(a_{i+1}\right)\right| \geq\left|f_{s}\left(a_{i}\right)\right| \geq 2\left|f_{s}\left(\alpha_{i-1}\right)\right|(2 \leq i \leq s)$. Let $u_{0}$ be the largest integer such that $2 u_{0} \leq s$. From (2), (3) and (4), we have (5):

$$
\begin{aligned}
0<f_{s}\left(a_{1}\right)-2<f_{s}\left(\alpha_{1}\right) & <f_{s}\left(a_{3}\right)-2<f_{s}\left(\alpha_{3}\right)< \\
& \cdots<f_{s}\left(a_{2 u_{0}-1}\right)-2<f_{s}\left(\alpha_{2 u_{0}-1}\right)<\left|f_{s}\left(a_{2 u_{0}+1}\right)\right|-2 .
\end{aligned}
$$

For each integer $u\left(0 \leq u \leq u_{0}\right)$, put $f_{s, u}(x):=f_{s}(x)-\left(\left|f_{s}\left(a_{2 u+1}\right)\right|-2\right)$. Then the monic $Z$-polynomial $f_{s, u}(x)$ is irreducible from Eisenstein's Irreducibility Criterion. Furthermore, from (5), the polynomial $f_{s, u}(x)$ has exactly $2 u$ non-real roots.

Proof of Corollary 2.5. Suppose $G$ is of type $(l, r)$. Then from Proposition 1.4, $G$ is isomorphic to $G_{n}(l, r)=\boldsymbol{R}_{+}^{n} \ltimes_{\psi_{n}(l, r)} \boldsymbol{R}^{n} \cong \operatorname{Aff}^{+}(\boldsymbol{R})^{l} \times \widetilde{\operatorname{Aff}}(\boldsymbol{R})^{r}$. From Lemma 2.6, there is a real algebraic integer $\alpha$ whose minimal polynomial has $(l+1)$ real roots and $2 r$ non-real roots. Take a system of fundamental units $\Xi:=\left\{\xi_{j} \mid 1 \leq j \leq l+r\right\}$ of $\boldsymbol{Q}(\alpha)$ (see, e.g., [4, IV.4]). As before, let $\left\{\sigma^{(1)}=\mathrm{id}, \sigma^{(2)}, \ldots, \sigma^{(n+1)}\right\}$ be the set of all conjugation mappings of $\boldsymbol{Q}(\alpha)$. By rearranging the numbering if necessary, we can assume, for each $j$, that $\sigma^{(i)}\left(\xi_{j}\right)(1 \leq i \leq l)$ and $\sigma^{(l+2 r+1)}\left(\xi_{j}\right)$ are real numbers and the others satisfy $\overline{\sigma^{(l+2 i-1)}\left(\xi_{j}\right)}=$ $\sigma^{(l+2 i)}\left(\xi_{j}\right)(1 \leq i \leq r)$. Note that $\sum_{i=1}^{n+1} \log \left|\sigma^{(i)}\left(\xi_{j}\right)\right|=0$ for each $j$.

Define the $(l+r)$-square matrix $\log \Xi$ and the $r \times(l+r)$-matrix $\operatorname{Arg} \Xi$ by:

$$
\begin{aligned}
& (i, j) \text {-element of } \log \Xi= \begin{cases}\log \left|\sigma^{(i)}\left(\xi_{j}\right)\right| & \text { if } 1 \leq i \leq l, \\
\log \left|\sigma^{(2 i-l-1)}\left(\xi_{j}\right)\right| & \text { if } l+1 \leq i \leq l+r, \\
(i, j) \text {-element of } \operatorname{Arg} \Xi & =\arg \left(\sigma^{(l+2 i-1)}\left(\xi_{j}\right)\right) \\
1 \leq i \leq r\end{cases}
\end{aligned}
$$

Put

$$
\Lambda_{\Xi}:=2\left(\begin{array}{cc}
\log \Xi & 0 \\
\operatorname{Arg} \Xi & \pi E_{r}
\end{array}\right) .
$$

It is well-known that $\operatorname{det} \log \Xi \neq 0$. Thus the matrix $\Lambda_{\Xi}$ is non-singular. Consider the product matrix

$$
\hat{\Lambda}:=\binom{\Lambda_{\psi_{n}(l, r)}}{-\beta} \Lambda_{\Xi}, \quad \text { where } \beta=(\underbrace{1, \ldots, 1}_{l}, \underbrace{2, \ldots, 2}_{r}, \underbrace{0, \ldots, 0}_{r}) .
$$

Then the exponential of the $(i, j)$-element of $\hat{\Lambda}$ is $\sigma^{(i)}\left(\xi_{j}\right)^{2}$ if $1 \leq j \leq l+r$, and 1 if $l+r+1 \leq j \leq l+2 r$, and lies in $\mathcal{O}\left(\sigma^{(i)}(\alpha)\right)$. So the matrix $\hat{\Lambda}$ satisfies the conditions (1) and (2) in Theorem 2 with $d=1$ and $\alpha_{1}=\alpha$. The corollary follows from Theorem 2.

In [14], the first author studied the classification of codimension one homogeneous actions of $\mathrm{Aff}^{+}(\boldsymbol{R})^{n}$.
3. Existence of an equivariant transverse vector field. Let $G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$ be a group in $D(n, m)$, and let $M$ be an ( $m+n+1$ )-dimensional closed orientable manifold. The purpose of this section is to prove that, for a volume preserving locally free action $\Phi$ of $G$ on $M$, there exists uniquely an equivariant transverse vector field of class $C^{0}$. That is, we prove Proposition 3.1 stated below.
3.1. Statement of the result. We have a natural homomorphism $\Phi^{+}$from the Lie algebra $\mathcal{G}$ of right invariant vector fields on $G$ to the Lie algebra $\mathcal{X}(M)$ of smooth vector fields on $M$, which is defined by

$$
\Phi^{+}(X)_{p}(f)=\lim _{t \rightarrow 0} \frac{f(\Phi(\exp t X, p))-f(p)}{t}, \quad X \in \mathcal{X}(M) \text { and } f \in C_{p}^{\infty}(M)
$$

Here $C_{p}^{\infty}(M)$ is the set of germs of smooth functions at a point $p$ in $M$. Since $\Phi$ is locally free, the vector field $\Phi^{+}(X)$ is nowhere zero if $X \neq 0$. To simplify the notation, we denote $\Phi^{+}(X)$ by $X^{*}$. For $g \in G$, we denote the diffeomorphism $\Phi(g, \quad)$ of $M$ by $\Phi_{g}$ and the induced homomorphism $\left(\Phi_{g}\right)_{*}$ (resp. $\left.\left(\Phi_{g}\right)^{*}\right)$ of $\mathcal{X}(M)$ (resp. $\wedge T^{*}(M)$ ) by $g_{*}$ (resp. $g^{*}$ ). An
element $g \in G$ acts on a vector field $X^{*}$ as follows: $g_{*} X^{*}=g_{*}\left(\Phi^{+}(X)\right)=\Phi^{+}\left(\left(L_{g}\right)_{*} X\right)=$ $\left(\left(L_{g}\right)_{*} X\right)^{*}$.

Let $\left\{X_{1}^{*}, \ldots, X_{n}^{*}, Y_{1}^{*}, \ldots, Y_{m}^{*}\right\}$ be the vector fields on $M$ which are induced from the basis $\left\{X_{1}, \ldots, X_{n}, Y_{1}, \ldots, Y_{m}\right\}$ of $\mathcal{G}$ given in Section 1.4. Recall the modular function $\Delta$ : $G \rightarrow \boldsymbol{R}_{+}$is given by $\Delta((\exp \mathbf{t}, \mathbf{x}))=\exp \left(\sum_{i=1}^{n} \Lambda_{i} \cdot \mathbf{t}\right)=\exp (\beta \cdot \mathbf{t})$. Here $\Lambda_{i}$ is the $i$-th row vector of the structure matrix $\Lambda_{\psi}$ and $\beta=\sum_{i=1}^{n} \Lambda_{i}$.

Proposition 3.1. Let $G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}(0<m \leq n)$ be a group in $D(n, m)$, and let $M$ be an $(m+n+1)$-dimensional connected closed orientable manifold. Let $\Phi: G \times M \rightarrow M$ be a locally free action which preserves a volume form $\Omega$ of class $C^{0}$. Suppose that the structure matrix $\Lambda_{\psi}$ of $G$ satisfies

$$
\beta \notin\left\{a_{i} \Re \Lambda_{i}, b_{j} \Re \Lambda_{j}-\Re \Lambda_{k} \mid 0 \leq a_{i}, b_{j} \leq 1,1 \leq i, j, k \leq n\right\} .
$$

Then there exists uniquely a vector field $T$ of class $C^{0}$ on $M$ such that
(1) $\Omega\left(X_{1}^{*}, \ldots, X_{n}^{*}, Y_{1}^{*}, \ldots, Y_{m}^{*}, T\right)=1$ and $\quad$ (2) $g_{*} T=\Delta(g)^{-1} T$ for any $g \in G$.
3.2. Homothety equivariance. In this subsection, we show the following lemma.

Lemma 3.2. Let $G, M, \Phi$ and $\Omega$ be the same as in Proposition 3.1. Then there exists uniquely a vector field $T$ of class $C^{0}$ satisfying the following conditions:
(1) $\Omega\left(X_{1}^{*}, \ldots, X_{n}^{*}, Y_{1}^{*}, \ldots, Y_{m}^{*}, T\right)=1$,
(2) $\quad(\exp \mathbf{t}, \mathbf{0})_{*} T=\Delta((\exp \mathbf{t}, \mathbf{0}))^{-1} T=e^{-\beta \cdot \mathbf{t}} T \quad$ for any $\mathbf{t} \in \boldsymbol{R}^{m}$.

We prove the lemma through four steps.
Step 1. We assume $G$ is of type $(l, r)$, and use a canonical coordinate of $G$ so that $d \psi(\mathbf{t})$ is described as in (1.1).

From a theorem of Ghys ( $[5$, Theorem A]), the above volume form $\Omega$ is smooth. Take a smooth vector field $Z$ on $M$ satisfying $\Omega\left(X_{1}^{*}, \ldots, X_{n}^{*}, Y_{1}^{*}, \ldots, Y_{m}^{*}, Z\right)=1$. Then for each $g=(\exp \mathbf{t}, \mathbf{x}) \in G$ we have, from (1.4),

$$
\begin{aligned}
1 & =g^{*} \Omega\left(X_{1}^{*}, \ldots, X_{n}^{*}, Y_{1}^{*}, \ldots, Y_{m}^{*}, Z\right) \\
& =\Omega\left(g_{*} X_{1}^{*}, \ldots, g_{*} X_{n}^{*}, g_{*} Y_{1}^{*}, \ldots, g_{*} Y_{m}^{*}, g_{*} Z\right) \\
& =e^{\beta \cdot \mathbf{t}} \Omega\left(X_{1}^{*}, \ldots, X_{n}^{*}, Y_{1}^{*}, \ldots, Y_{m}^{*}, g_{*} Z\right)
\end{aligned}
$$

Thus we can write $g_{*} Z \equiv e^{-\beta \cdot \mathbf{t}} Z\left(\bmod \left(X_{1}^{*}, \ldots, X_{n}^{*}, Y_{1}^{*}, \ldots, Y_{m}^{*}\right)\right)$. Hence, for each $\mathbf{t} \in \boldsymbol{R}^{m}$, there are families of smooth functions $\left\{\phi_{\mathbf{t}}^{k} \mid 1 \leq k \leq m\right\}$ and $\left\{\psi_{\mathbf{t}}^{k} \mid 1 \leq k \leq n\right\}$ on $M$, indexed by $\mathbf{t}$, such that

$$
\begin{equation*}
(\exp \mathbf{t}, \mathbf{0})_{*} Z=e^{-\beta \cdot \mathbf{t}} Z+\sum_{k=1}^{m} \phi_{\mathbf{t}}^{k} Y_{k}^{*}+\sum_{k=1}^{n} \psi_{\mathbf{t}}^{k} X_{k}^{*} \tag{3.1}
\end{equation*}
$$

These functions satisfy the following transition formulas.

Sublemma 3.3.

$$
\begin{gather*}
\phi_{\mathbf{t}^{\prime}+\mathbf{t}}^{k}=e^{-\beta \cdot \mathbf{t}} \phi_{\mathbf{t}^{\prime}}^{k}+\phi_{\mathbf{t}}^{k} \circ \Phi_{\left(\exp \left(-\mathbf{t}^{\prime}\right), \mathbf{0}\right)} \quad(1 \leq k \leq m),  \tag{3.2}\\
\psi_{\mathbf{t}^{\prime}+\mathbf{t}}^{i}=e^{-\beta \cdot \mathbf{t}} \psi_{\mathbf{t}^{\prime}}^{i}+e^{\Lambda_{i} \cdot \mathbf{t}^{\prime}} \psi_{\mathbf{t}}^{i} \circ \Phi_{\left(\exp \left(-\mathbf{t}^{\prime}\right), \mathbf{0}\right)} \quad(1 \leq i \leq l),  \tag{3.3}\\
\binom{\psi_{\mathbf{t}^{\prime}+2 j+1}^{l+2 j-1}}{\psi_{\mathbf{t}^{\prime}+\mathbf{t}}^{l+2}}=e^{-\beta \cdot \mathbf{t}}\binom{\psi_{\mathbf{t}^{\prime}}^{l+2 j-1}}{\psi_{\mathbf{t}^{\prime}}^{l+2 j}} \\
+e^{\Re \Lambda_{l+2 j-1} \cdot \mathbf{t}^{\prime}} \exp \left(\left(\Im \Lambda_{l+2 j-1} \cdot \mathbf{t}^{\prime}\right) J\right)\binom{\psi_{\mathbf{t}}^{l+2 j-1} \circ \Phi_{\left(\exp \left(-\mathbf{t}^{\prime}\right), \mathbf{0}\right)}}{\psi_{\mathbf{t}}^{l+2 j} \circ \Phi_{\left(\exp \left(-\mathbf{t}^{\prime}\right), \mathbf{0}\right)}} \quad(1 \leq j \leq r) \tag{3.4}
\end{gather*}
$$

Proof. From (3.1) and (1.4), the right hand side of

$$
\left(\exp \left(\mathbf{t}^{\prime}+\mathbf{t}\right), \mathbf{0}\right)_{*} Z=\left(\exp \mathbf{t}^{\prime}, \mathbf{0}\right)_{*} \circ(\exp \mathbf{t}, \mathbf{0})_{*} Z
$$

is calculated as

$$
\begin{aligned}
& e^{-\beta \cdot\left(\mathbf{t}^{\prime}+\mathbf{t}\right)} Z+e^{-\beta \cdot \mathbf{t}}\left\{\sum_{k=1}^{m} \phi_{\mathbf{t}^{\prime}}^{k} Y_{k}^{*}+\sum_{k=1}^{n} \psi_{\mathbf{t}^{\prime}}^{k} X_{k}^{*}\right\} \\
& \quad+\sum_{k=1}^{m} \phi_{\mathbf{t}}^{k} \circ \Phi_{\left(\exp \left(-\mathbf{t}^{\prime}\right), 0\right)} Y_{k}^{*}+\sum_{i=1}^{l} \psi_{\mathbf{t}}^{i} \circ \Phi_{\left(\exp \left(-\mathbf{t}^{\prime}\right), 0\right)} e^{\Lambda_{i} \cdot \mathbf{t}^{\prime}} X_{i}^{*} \\
& \quad+\sum_{j=1}^{r} \psi_{\mathbf{t}}^{l+2 j-1} \circ \Phi_{\left(\exp \left(-\mathbf{t}^{\prime}\right), 0\right)} e^{a_{j}}\left(\cos b_{j} X_{l+2 j-1}^{*}+\sin b_{j} X_{l+2 j}^{*}\right) \\
& \quad+\sum_{j=1}^{r} \psi_{\mathbf{t}}^{l+2 j} \circ \Phi_{\left(\exp \left(-\mathbf{t}^{\prime}\right), 0\right)} e^{a_{j}}\left(-\sin b_{j} X_{l+2 j-1}^{*}+\cos b_{j} X_{l+2 j}^{*}\right)
\end{aligned}
$$

where we put $\Lambda_{l+2 j-1} \cdot \mathbf{t}^{\prime}=a_{j}+b_{j} \sqrt{-1}\left(1 \leq j \leq r, a_{j}, b_{j} \in \boldsymbol{R}\right)$. The lemma follows immediately from this identity.

Let $C^{0}(M)$ denote the space of all continuous functions on $M$ with the distance function $d$ induced from the supremum norm $\left\|\|\right.$. Any vector field $T$ of class $C^{0}$ satisfying (1) in Lemma 3.2 is described as

$$
\begin{equation*}
T=Z+\sum_{k=1}^{m} F^{k} Y_{k}^{*}+\sum_{k=1}^{n} G^{k} X_{k}^{*}, \quad F^{k}, G^{k} \in C^{0}(M) \tag{3.5}
\end{equation*}
$$

We show that, by choosing suitable continuous functions $F^{k}$ and $G^{k}$, the vector field $T$ satisfies the equivariance condition (2) in Lemma 3.2.

Step 2. In this step we choose the functions $F^{k}(1 \leq k \leq m)$. From (3.5), (3.1) and (1.4), we have

$$
(\exp \mathbf{t}, \mathbf{0})_{*} T \equiv e^{-\beta \cdot \mathbf{t}} Z+\sum_{k=1}^{m} \phi_{\mathbf{t}}^{k} Y_{k}^{*}+\sum_{k=1}^{m} F^{k} \circ \Phi_{(\exp (-\mathbf{t}), \mathbf{0})} Y_{k}^{*} \quad\left(\bmod \left(X_{1}^{*}, \cdots, X_{n}^{*}\right)\right) .
$$

Hence the vector field $T$ satisfies the congruence $(\exp \mathbf{t}, \mathbf{0})_{*} T \equiv e^{-\beta \cdot \mathbf{t}} T\left(\bmod \left(X_{1}^{*}, \ldots, X_{n}^{*}\right)\right)$ if and only if each of the function $F^{k}(1 \leq k \leq m)$ satisfies the equality

$$
\begin{equation*}
F^{k}=e^{\beta \cdot \mathbf{t}}\left(\phi_{\mathbf{t}}^{k}+F^{k} \circ \Phi_{(\exp (-t), \mathbf{0})}\right) \tag{3.6}
\end{equation*}
$$

For each $k(1 \leq k \leq m)$ and each $\mathbf{t} \in \boldsymbol{R}^{m}$, consider a continuous operator $U_{\mathbf{t}}^{k}$ from $C^{0}(M)$ to itself defined by

$$
U_{\mathbf{t}}^{k}(F):=e^{\beta \cdot \mathbf{t}}\left(\phi_{\mathbf{t}}^{k}+F \circ \Phi_{(\exp (-\mathbf{t}), \mathbf{0})}\right)
$$

Obviously, we have $d\left(U_{\mathbf{t}}^{k}(F), U_{\mathbf{t}}^{k}\left(F^{\prime}\right)\right)=e^{\beta \cdot \mathbf{t}} d\left(F, F^{\prime}\right)$. So the operator $U_{\mathbf{t}_{0}}^{k}$ is Lipshitz contracting and has a unique fixed point if $\beta \cdot \mathbf{t}_{0}<0$. From the assumption on $\Lambda_{\psi}$, the vector $\beta$ is non-zero, and hence such a vector $\mathbf{t}_{0}$ can be chosen. Furthermore, from the identity $\phi_{\mathbf{t}+\mathbf{t}^{\prime}}^{k}=\phi_{\mathbf{t}^{\prime}+\mathbf{t}}^{k}$ and (3.2), the family of operators $\left\{U_{\mathbf{t}}^{k} \mid \mathbf{t} \in \boldsymbol{R}^{m}\right\}$ is abelian. Thus if $F_{0}^{k}$ is a fixed point of $U_{\mathbf{t}_{0}}^{k}$, then, for an arbitrary $\mathbf{t} \in \boldsymbol{R}^{m}$, the function $U_{\mathbf{t}}^{k}\left(F_{0}^{k}\right)$ is also a fixed point of $U_{\mathbf{t}_{0}}^{k}$. Consequently, from the uniqueness of the fixed point of $U_{t_{0}}^{k}$, there exists uniquely a continuous function $F_{0}^{k}$ on $M$ which is a common fixed point of the operators $U_{\mathbf{t}}^{k}$ for any $\mathbf{t} \in \boldsymbol{R}^{m}$, and satisfies (3.6). Using this function $F_{0}^{k}$ as $F^{k}$ in (3.5), we obtain

$$
\begin{equation*}
(\exp \mathbf{t}, \mathbf{0})_{*} T \equiv e^{-\beta \cdot \mathbf{t}}\left(Z+\sum_{k=1}^{m} F^{k} Y_{k}^{*}\right) \quad\left(\bmod \left(X_{1}^{*}, \ldots, X_{n}^{*}\right)\right) \tag{3.7}
\end{equation*}
$$

Step 3. Next we choose the functions $G^{i}(1 \leq i \leq l)$ in (3.5). From (3.7), (3.1) and (1.4) we have

$$
\begin{aligned}
&(\operatorname{expt}, \mathbf{0})_{*} T \equiv e^{-\beta \cdot \mathbf{t}}\left(Z+\sum_{k=1}^{m} F^{k} Y_{k}^{*}\right)+\sum_{i=1}^{l}\left(\psi_{\mathbf{t}}^{i}+e^{\Lambda_{i} \cdot \mathbf{t}} G^{i} \circ \Phi_{(\exp (-\mathbf{t}), \mathbf{0})) X_{i}^{*}}\right. \\
&\left(\bmod \left(X_{l+1}^{*}, \ldots, X_{l+2 r}^{*}\right)\right)
\end{aligned}
$$

For each $i(1 \leq i \leq l)$ and each $\mathbf{t} \in \boldsymbol{R}^{m}$, define an operator $V_{\mathbf{t}}^{i}$ on $C^{0}(M)$ by

$$
V_{\mathbf{t}}^{i}(G):=e^{\beta \cdot \mathbf{t}}\left(\psi_{\mathbf{t}}^{i}+e^{\Lambda_{i} \cdot \mathbf{t}} G \circ \Phi_{(\exp (-\mathbf{t}), \mathbf{0})}\right)
$$

Then we have $d\left(V_{\mathbf{t}}^{i}(G), V_{\mathbf{t}}^{i}\left(G^{\prime}\right)\right)=e^{\left(\beta+\Lambda_{i}\right) \cdot \mathbf{t}} d\left(G, G^{\prime}\right)$. From the assumption on $\Lambda_{\psi}$, we can choose a vector $\mathbf{t}_{0}$ with $\left(\beta+\Lambda_{i}\right) \cdot \mathbf{t}_{0}<0$. The commutativity of the operators $\left\{V_{\mathbf{t}}^{i}\right\}$ follows from (3.3). Thus, as in Step 2, there exists uniquely a function $G^{i}$ which is fixed by $V_{\mathbf{t}}^{i}$ for any $\mathbf{t} \in \boldsymbol{R}^{m}$. Using such a $G^{i}$ in the expression (3.5) of $T$, we obtain

$$
\begin{equation*}
(\exp \mathbf{t}, \mathbf{0})_{*} T \equiv e^{-\beta \cdot \mathbf{t}}\left(Z+\sum_{k=1}^{m} F^{k} Y_{k}^{*}+\sum_{i=1}^{l} G^{i} X_{i}^{*}\right) \quad\left(\bmod \left(X_{l+1}^{*}, \ldots, X_{l+2 r}^{*}\right)\right) \tag{3.8}
\end{equation*}
$$

Step 4. Lastly, we consider the functions $G^{l+2 j-1}, G^{l+2 j}(1 \leq j \leq r)$ in (3.5). In this case we define an operator $W_{\mathbf{t}}^{j}$ on the product space $C^{0}(M) \times C^{0}(M)$ as follows:

$$
W_{\mathbf{t}}^{j}\binom{G}{G^{\prime}}:=e^{\beta \cdot \mathbf{t}}\left\{\binom{\psi_{\mathbf{t}}^{l+2 j-1}}{\psi_{\mathbf{t}}^{l+2 j}}+e^{\Re \Lambda_{l+2 j-1} \cdot \mathbf{t}} \exp \left(\left(\Im \Lambda_{l+2 j-1} \cdot \mathbf{t}\right) J\right)\binom{G \circ \Phi_{(\exp (-\mathbf{t}), \mathbf{0})}}{G^{\prime} \circ \Phi_{(\exp (-\mathbf{t}), \mathbf{0})}}\right\} .
$$

Again we have

$$
d\left(W_{\mathbf{t}}^{j}\binom{G}{G^{\prime}}, W_{\mathbf{t}}^{j}\binom{H}{H^{\prime}}\right)=e^{\left(\beta+\Re \Lambda_{l+2 j-1}\right) \cdot \mathbf{t}} d\left(\binom{G}{G^{\prime}},\binom{H}{H^{\prime}}\right) .
$$

From the assumption on $\Lambda_{\psi}$, we can choose a vector $\mathbf{t}_{0}$ such that $\left(\beta+\Re \Lambda_{l+2 j-1}\right) \cdot \mathbf{t}_{0}<0$. The commutativity of the operators $\left\{W_{\mathbf{t}}^{j}\right\}$ follows from (3.4). Thus, as in Steps 2 and 3, using the unique pair of functions $\left(G^{l+2 j-1}, G^{l+2 j}\right)^{t}$ fixed by $W_{\mathbf{t}}^{j}$ for all $\mathbf{t} \in \boldsymbol{R}^{m}$, we obtain

$$
(\exp \mathbf{t}, \mathbf{0})_{*} T=(\exp \mathbf{t}, \mathbf{0})_{*}\left(Z+\sum_{k=1}^{n} F^{k} Y_{k}^{*}+\sum_{k=1}^{n} G^{k} X_{k}^{*}\right)=e^{-\beta \cdot \mathbf{t}} T .
$$

Through Steps 1 to 4, we have found a continuous vector field $T$ which satisfies (1) and (2) in Lemma 3.2. By the construction, the vector field $T$ is unique. This completes the proof of Lemma 3.2.
3.3. $G$-equivariance. Next we show that the vector field $T$ in Lemma 3.2 is equivariant by any $g \in G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$. Namely, we prove the following

Lemma 3.4. Let $G, M, \Phi$ and $\Omega$ be the same as in Proposition 3.1. Let $T$ be a vector field satisfying (1) and (2) in Lemma 3.2. Then $g_{*} T=e^{-\beta \cdot \mathbf{t}}$ T for any $g=(\exp \mathbf{t}, \mathbf{x}) \in G$.

For $g=(\exp \mathbf{t}, \mathbf{x}) \in G$, there exists a family of continuous functions $\mu_{g}^{k}$ and $\nu_{g}^{k}$ on $M$ indexed by $g \in G$ such that

$$
\begin{equation*}
(\exp \mathbf{t}, \mathbf{x})_{*} T=e^{-\beta \cdot \mathbf{t}} T+\sum_{k=1}^{m} \mu_{g}^{k} Y_{k}^{*}+\sum_{k=1}^{n} v_{g}^{k} X_{k}^{*} \tag{3.9}
\end{equation*}
$$

We prove the lemma by showing that the functions $\mu_{g}^{k}$ and $\nu_{g}^{k}$ are identically zero. By the assumption we have

$$
\begin{equation*}
\mu_{(\exp t, \mathbf{0})}^{k}=v_{(\exp t, \mathbf{0})}^{k}=0 \tag{3.10}
\end{equation*}
$$

In the following, we omit the detail of calculations.
3.3.1. Nullity of $\mu_{g}^{k} . \quad$ From (3.9) and (1.4), for $g=(\exp \mathbf{t}, \mathbf{x})$ and $h=\left(\exp \mathbf{t}^{\prime}, \mathbf{x}^{\prime}\right) \in$ $G$, the following congruence is derived.

$$
(h g)_{*} T \equiv e^{-\beta \cdot\left(\mathbf{t}+\mathbf{t}^{\prime}\right)} T+\sum_{k=1}^{m}\left(e^{-\beta \cdot \mathbf{t}} \mu_{h}^{k}+\mu_{g}^{k} \circ \Phi_{h^{-1}}\right) Y_{k}^{*} \quad\left(\bmod \left(X_{1}^{*}, \cdots, X_{n}^{*}\right)\right) .
$$

Thus the following transition formula holds.

$$
\begin{equation*}
\mu_{h g}^{k}=e^{-\beta \cdot \mathbf{t}} \mu_{h}^{k}+\mu_{g}^{k} \circ \Phi_{h^{-1}} \tag{3.11}
\end{equation*}
$$

Let $\mathbf{f}_{i}$ denote the $i$-th unit vector in $\boldsymbol{R}^{n}$. Then from (3.10) and (3.11), the following equalities are derived.

$$
\begin{equation*}
\mu_{\left(1, e^{\Lambda_{i} \cdot \mathbf{t}} \mathbf{x} \boldsymbol{f}_{i}\right)}^{k}=\mu_{(\exp \mathbf{t}, \mathbf{0})\left(1, \times \boldsymbol{f}_{\boldsymbol{i}}\right)(\exp (-\mathbf{t}), \mathbf{0})}^{k}=e^{\beta \cdot \mathbf{t}} \mu_{\left(1, \boldsymbol{x} \mathbf{f}_{i}\right)}^{k} \circ \Phi_{(\exp (-\mathbf{t}), \mathbf{0})} \quad(1 \leq i \leq l) \tag{3.12}
\end{equation*}
$$

$$
\begin{align*}
& \mu_{\left(1, e^{\Re / \Lambda_{l+2 j-1}} \mathbf{t}^{\mathbf{t}} \exp \left(\left(\mathfrak{3} \Lambda_{l+2 j-1} \cdot \mathbf{t}\right) J\right)\left(x_{1} \mathbf{f}_{l+2 j-1}+x_{2} \mathbf{f}_{l+2 j}\right)\right)} \\
& \quad=e^{\beta \cdot \mathbf{t}} \mu_{\left(1, x_{1} \mathbf{f}_{l+2 j-1}+x_{2} \mathbf{f}_{l+2 j}\right)}^{k} \circ \Phi_{(\exp (-\mathbf{t}), \mathbf{0})} \quad(1 \leq j \leq r),  \tag{3.13}\\
& \mu_{\left(1, \mathbf{x}+\mathbf{x}^{\prime}\right)}^{k}=\mu_{(1, \mathbf{x})}^{k}+\mu_{\left(1, \mathbf{x}^{\prime}\right)}^{k} \circ \Phi_{(1,-\mathbf{x})}^{k},  \tag{3.14}\\
& \mu_{(\exp \mathbf{t}, \mathbf{x})}^{k}=\mu_{(\mathbf{1}, \mathbf{x})(\exp \mathbf{t}, \mathbf{0})}^{k}=e^{-\beta \cdot \mathbf{t}} \mu_{(\mathbf{1}, \mathbf{x})}^{k} . \tag{3.15}
\end{align*}
$$

Hence we obtain the following relations on the supremum norms of $\mu_{g}^{k}$.

$$
\begin{align*}
& \left\|\mu_{\left(1, e^{\Lambda_{i} \cdot \mathbf{t}_{x}}\right)}^{k}\right\|=e^{\beta \cdot \mathbf{t}}\left\|\mu_{\left(1, x \boldsymbol{f}_{i}\right)}^{k}\right\| \quad(1 \leq i \leq l),  \tag{3.16}\\
& \left.\| \mu_{\left(1, e^{, ~ M} \Lambda_{l+2 j-1} \cdot t\right.} \exp \left(\left(3 \Lambda_{l+2 j-1} \cdot \mathbf{t}\right) J\right)\left(x_{1} \mathbf{f}_{l+2 j-1}+x_{2} \mathbf{f}_{l+2 j}\right)\right) \| \\
& =e^{\beta \cdot \mathbf{t}}\left\|\mu_{\left(1, x_{1} \mathbf{f}_{l+2 j-1}+x_{2} \mathbf{f}_{l+2 j}\right)}^{k}\right\| \quad(1 \leq j \leq r),  \tag{3.17}\\
& \left\|\mu_{\left(1, \mathbf{x}+\mathbf{x}^{\prime}\right)}^{k}\right\| \leq\left\|\mu_{(1, \mathbf{x})}^{k}\right\|+\left\|\mu_{\left(1, \mathbf{x}^{\prime}\right)}^{k}\right\| . \tag{3.18}
\end{align*}
$$

Let $\mathbf{x}=\left(x_{1}, x_{2}, \ldots, x_{n}\right)^{t} \in \boldsymbol{R}^{n}$. Then from (3.18), we have

$$
\left\|\mu_{(\mathbf{1}, \mathbf{x})}^{k}\right\| \leq \sum_{i=1}^{l}\left\|\mu_{\left(\mathbf{1}, x_{i} \mathbf{f}_{i}\right)}^{k}\right\|+\sum_{j=1}^{r}\left\|\mu_{\left(\mathbf{1}, x_{l+2 j-1} \mathbf{f}_{l+2 j-1}+x_{l+2 j} \mathbf{f}_{l+2 j)}\right.}\right\|
$$

From this inequality and (3.15), to prove $\mu_{(\text {exp } \mathbf{t}, \mathbf{x})}^{k}=0$, it is sufficient to show $\mu_{\left(1, x_{i} \mathbf{f}_{i}\right)}^{k}=$ $\mu_{\left(1, x_{l+2 j-1} \mathbf{f}_{l+2 j-1}+x_{l+2} \mathbf{f}_{l+2 j}\right)}^{k}=0(1 \leq i \leq l, 1 \leq j \leq r)$. For notational convenience, we put $(\mathbf{x})_{j}:=x_{l+2 j-1} \mathbf{f}_{l+2 j-1}+x_{l+2 j} \mathbf{f}_{l+2 j}$. For a fixed $k(1 \leq k \leq m)$, define non-decreasing functions $\tau_{i}^{k}$ and $\sigma_{j}^{k}$ on $\boldsymbol{R}_{+} \cup\{0\}$ by

$$
\tau_{i}^{k}(d):=\sup _{\left|x_{i}\right| \leq d}\left\|\mu_{\left(\mathbf{1}, x_{i} \mathbf{f}_{i}\right)}^{k}\right\| \quad(1 \leq i \leq l) \quad \text { and } \quad \sigma_{j}^{k}(d):=\sup _{\left\|(\mathbf{x})_{j}\right\| \leq d}\left\|\mu_{\left(\mathbf{1},(\mathbf{x})_{j}\right)}^{k}\right\| \quad(1 \leq j \leq r) .
$$

We first show $\tau_{i}^{k}=0(1 \leq i \leq l)$, and hence $\mu_{\left(\mathbf{1}, x_{i} \mathbf{f}_{i}\right)}^{k}=0$.
Sublemma 3.5. (1) For each $i(1 \leq i \leq l)$ and $\mathbf{t} \in \boldsymbol{R}^{m}$, we have

$$
\begin{equation*}
\tau_{i}^{k}\left(e^{\Lambda_{i} \cdot \mathbf{t}} r\right)=e^{\beta \cdot \mathbf{t}} \tau_{i}^{k}(r) \quad \text { for any } r>0 \tag{3.19}
\end{equation*}
$$

(2) For each $i(1 \leq i \leq l)$ and $\mathbf{t} \in \boldsymbol{R}^{m}$ such that $\Lambda_{i} \cdot \mathbf{t} \neq \mathbf{0}$, we have

$$
\begin{equation*}
\tau_{i}^{k}(d)=d^{\frac{\beta \cdot t}{\Lambda_{i} t}} \tau_{i}^{k}(1) \quad \text { for any } d>0 \tag{3.20}
\end{equation*}
$$

(3) For each $i(1 \leq i \leq l)$, we have

$$
\begin{equation*}
\tau_{i}^{k}(d) \leq(d+1) \tau_{i}^{k}(1) \quad \text { for any } d>0 \tag{3.21}
\end{equation*}
$$

Proof. The first assertion follows directly from (3.16). The second assertion follows from (3.19) by putting $r=1$ and $d=e^{\Lambda_{i} \cdot \mathbf{t}}$.

It follows from (3.18) that $\tau_{i}^{k}\left(d+d^{\prime}\right) \leq \tau_{i}^{k}(d)+\tau_{i}^{k}\left(d^{\prime}\right)$. For $d>0$, choose a positive integer $a$ such that $d \leq a<d+1$. Then we have $\tau_{i}^{k}(d) \leq \tau_{i}^{k}(a) \leq a \tau_{i}^{k}(1) \leq(d+1) \tau_{i}^{k}(1)$. We have thus proved the third assertion.

If $\Lambda_{i}=\mathbf{0}$, then from (1) in Sublemma 3.5 we have $\tau_{i}^{k}(r)=e^{\beta \cdot \mathbf{t}} \tau_{i}^{k}(r)$. Hence, from the assumption $\beta \neq \mathbf{0}$, we obtain $\tau_{i}^{k}(r)=0$ for any $r>0$. When $\Lambda_{i} \neq \mathbf{0}$, we first suppose
$\beta \neq a_{i} \Lambda_{i}\left(a_{i}>0\right)$. Then we can choose a vector $\mathbf{t} \in \boldsymbol{R}^{m}$ such that $\Lambda_{i} \cdot \mathbf{t}<0<\beta \cdot \mathbf{t}$. For such a $t$, we have

$$
\tau_{i}^{k}\left(e^{\Lambda_{i} \cdot \mathbf{t}} d\right) \leq \tau_{i}^{k}(d) \leq e^{\beta \cdot \mathbf{t}} \tau_{i}^{k}(d)
$$

Thus, from (3.19) we obtain $\tau_{i}^{k}(d)=e^{\beta \cdot \mathbf{t}} \tau_{i}^{k}(d)$ and hence $\tau_{i}^{k}(d)=0$.
Next suppose $\beta=a_{i} \Lambda_{i}\left(a_{i}>0\right)$. Then, from the assumption on $\Lambda_{\psi}, a_{i}$ is larger than 1. So we can choose a vector $\mathbf{t} \in \boldsymbol{R}^{m}$ such that $0<\Lambda_{i} \cdot \mathbf{t}<\beta \cdot \mathbf{t}$. Put $b:=(\beta \cdot \mathbf{t}) /\left(\Lambda_{i} \cdot \mathbf{t}\right)(>1)$. Then from (3.20) and (3.21) we have

$$
d^{b} \tau_{i}^{k}(1)=\tau_{i}^{k}(d) \leq(d+1) \tau_{i}^{k}(1) \quad \text { for any } d>0
$$

So we obtain $\tau_{i}^{k}(1)=0$, and hence $\tau_{i}^{k}(d)=0$. Thus we have proved $\tau_{i}^{k}(d)=0(1 \leq k \leq$ $m, 1 \leq i \leq l)$.

Similarly, one can prove $\sigma_{j}^{k}(d)=0(1 \leq k \leq m, 1 \leq j \leq r)$, using (3.17) instead of (3.16). From the nullity of $\tau_{i}^{k}$ and $\sigma_{j}^{k}$, we have the required result $\mu_{g}^{k}=0$ for any $k$ ( $1 \leq k \leq m$ ).
3.3.2. Nullity of $v_{g}^{k}$. The nullity of $v_{g}^{k}(1 \leq k \leq n)$ is proved in a fashon similar to the case of $\mu_{g}^{k}$. So we only remark the formulas corresponding to (3.11), (3.12) and (3.13), but omit the detail of the proof. All the formulas are given under the assumption that $\mu_{g}^{k}=0$ $(1 \leq k \leq m)$. As before, we put $g=(\exp \mathbf{t}, \mathbf{x}), h=\left(\exp \mathbf{t}^{\prime}, \mathbf{x}^{\prime}\right)$. We continue to use the notation $(\mathbf{x})_{j}=x_{l+2 j-1} \mathbf{f}_{l+2 j-1}+x_{l+2 j} \mathbf{f}_{l+2 j}$.

Sublemma 3.6. (1) Case of $1 \leq k \leq l$.

$$
\begin{aligned}
& v_{h g}^{k}=e^{-\beta \cdot \mathbf{t}} v_{h}^{k}+e^{\Lambda_{k} \cdot \mathbf{t}^{\prime}} \nu_{g}^{k} \circ \Phi_{h^{-1}}, \\
& \nu_{\left(\mathbf{1}, e^{\Lambda}{ }^{\Lambda} \cdot \mathbf{t}_{\left.x_{i} \mathbf{f}_{i}\right)}\right.}^{k}=e^{\left(\beta+\Lambda_{k}\right) \cdot \mathbf{t}} v_{\left(\mathbf{1}, x_{i} \mathbf{f}_{i}\right)}^{k} \circ \Phi_{(\exp (-\mathbf{t}), \mathbf{0})} \quad(1 \leq i \leq l), \\
& \nu_{\left(1, e^{M \Lambda_{l+2 j-1}} \cdot \mathbf{t} \exp \left(\left(\Im \Lambda_{l+2 j-1} \cdot \mathbf{t}\right) J\right)(\mathbf{x})_{j}\right)}^{k}=e^{\left(\beta+\Lambda_{k}\right) \cdot \mathbf{t}} v_{\left(\mathbf{1},(\mathbf{x})_{j}\right)}^{k} \circ \Phi_{(\exp (-\mathbf{t}), \mathbf{0})} \quad(1 \leq j \leq r) .
\end{aligned}
$$

(2) Case of $l+1 \leq k \leq l+2 r$. Let $k^{\prime}:=[(k-l+1) / 2]=$ the largest integer not greater than $(k-l+1) / 2$.

$$
\begin{aligned}
& \binom{v_{h g}^{l+2 k^{\prime}-1}}{v_{h g}^{l+2 k^{\prime}}}=e^{-\beta \cdot \mathbf{t}}\binom{v_{h}^{l+2 k^{\prime}-1}}{v_{h}^{l+2 k^{\prime}}}+e^{a\left(\mathbf{t}^{\prime}\right)} \exp \left(b\left(\mathbf{t}^{\prime}\right) J\right)\binom{v_{g}^{l+2 k^{\prime}-1} \circ \Phi_{h^{-1}}}{v_{g}^{l+2 k^{\prime}} \circ \Phi_{h^{-1}}},
\end{aligned}
$$

$$
\begin{aligned}
& \binom{\left.\nu_{\left(1, e^{c(t)}\right.}^{l+2 k^{\prime}-1} \exp (d(\mathbf{t}) J)(\mathbf{x})_{j}\right)}{\left.v_{\left(\mathbf{1}, e^{c(t)}\right.}^{l+k^{\prime}} \exp (d(\mathbf{t}) J)(\mathbf{x})_{j}\right)}=e^{\beta \cdot \mathbf{t}} e^{a(\mathbf{t})} \exp (b(\mathbf{t}) J)\binom{\nu_{\left(\mathbf{1},(\mathbf{x}) \mathbf{x}_{j}\right)}^{l+2 k^{\prime}-1} \circ \Phi_{(\exp (-\mathbf{t}), \mathbf{0})}}{\nu_{\left(\mathbf{1},(\mathbf{x})_{j}\right)} \circ \Phi_{(\exp (-\mathbf{t}), \mathbf{0})}} \quad(1 \leq j \leq r),
\end{aligned}
$$

where $\Lambda_{l+2 k^{\prime}-1} \cdot \mathbf{t}=a(\mathbf{t})+b(\mathbf{t}) \sqrt{-1}$ and $\Lambda_{l+2 j-1} \cdot \mathbf{t}=c(\mathbf{t})+d(\mathbf{t}) \sqrt{-1}(a(\mathbf{t}), b(\mathbf{t}), c(\mathbf{t}), d(\mathbf{t}) \in$ $\boldsymbol{R}$ ).

This completes the proof of Lemma 3.4 and Proposition 3.1.
4. Proof of Theorem 1. In this section we first prove Proposition 4.1 which states that the vector field $T$ in Proposition 3.1 is smooth, and then complete the proof of Theorem 1. Let $\left\{X_{1}, \ldots, X_{n}, Y_{1}, \ldots, Y_{m}\right\}$ be the basis of the Lie algebra of $G$ given in Section 1.4.

PROPOSITION 4.1. Let $G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}(0<m \leq n)$ be a group in $D(n, m)$ and let $M$ be an $(m+n+1)$-dimensional connected closed orientable manifold. Let $\Phi: G \times M \rightarrow M$ be a locally free action which preserves a volume form $\Omega$ of class $C^{0}$. Suppose that the structure matrix $\Lambda_{\psi}$ of $G$ satisfies

$$
\beta \notin\left\{a_{i} \Re \Lambda_{i} \mid-1 \leq a_{i} \leq 0,1 \leq i \leq n\right\} .
$$

Suppose furthermore that there exists a $C^{0}$-vector field $T$ on $M$ such that $\Omega\left(X_{1}^{*}, \ldots, X_{n}^{*}\right.$, $\left.Y_{1}^{*}, \ldots, Y_{m}^{*}, T\right)=1$ and $g_{*} T=\Delta(g)^{-1} T$ for any $g \in G$. Then the vector field $T$ is smooth.

For the proof we use the invariant manifold theory of hyperbolic diffeomorphisms ([9]). Let $S:=\left\{\mathbf{t} \in \boldsymbol{R}^{m} \mid-\beta \cdot \mathbf{t}>0,-\beta \cdot \mathbf{t} \neq \Re \Lambda_{i} \cdot \mathbf{t}(1 \leq i \leq n)\right\}$. Choose $\mathbf{t} \in S$, and define $u(\mathbf{t}):=\left\{i \in\{1, \ldots, n\} \mid-\beta \cdot \mathbf{t}<\mathfrak{R} \Lambda_{i} \cdot \mathbf{t}\right\}$. Put $F:=\Phi_{(\exp \mathbf{t}, 0)}$. Then we have an $F$-invariant continuous splitting $T(M)=E_{1} \oplus E_{2}$, where $E_{1}$ (resp. $E_{2}$ ) is generated by the vector fields $\left\{X_{i}^{*}(i \in u(\mathbf{t})), T\right\}\left(\right.$ resp. $\left.\left\{X_{i}^{*}(i \notin u(\mathbf{t})), Y_{j}^{*}(1 \leq j \leq m)\right\}\right)$. Let $\rho>1$ be a real number such that $\max \left\{\left|e^{\Lambda_{i} \cdot \mathbf{t}}\right| \mid i \notin u(\mathbf{t})\right\}<\rho<e^{-\beta \cdot \mathbf{t}}$. The splitting $E_{1} \oplus E_{2}$ satisfies the following property.

Lemma 4.2. There exists a smooth Riemannian metric || of $M$ such that $0 \neq v \in$ $E_{1} \Rightarrow\left|F_{*}(v)\right|>\rho|v|$, and $0 \neq v \in E_{2} \Rightarrow\left|F_{*}(v)\right|<\rho|v|$.

Proof. For each $\delta>0$ choose a smooth vector field $T_{\delta}$ on $M$ such that $\Omega\left(X_{1}^{*}, \ldots, X_{n}^{*}\right.$, $\left.Y_{1}^{*}, \ldots, Y_{m}^{*}, T_{\delta}\right)=1$ and $\lim _{\delta \rightarrow 0} T_{\delta}=T$ in the $C^{0}$-topology. Let $\left.\left|\left.\right|_{0}\right.$ (resp. $\left.|\right|_{\delta}\right)$ be the $C^{0}$ - (resp. $C^{\infty_{-}}$) Riemannian metric of $M$ such that the vectors $\left\{\left(X_{i}^{*}\right)_{p},\left(Y_{j}^{*}\right)_{p}, T_{p}\right\}$ (resp. $\left.\left\{\left(X_{i}^{*}\right)_{p},\left(Y_{j}^{*}\right)_{p},\left(T_{\delta}\right)_{p}\right\}\right)$ are orthonormal at any point $p \in M$. Then, for each $\delta>0$, there exists $\varepsilon(\delta)>0$ such that (1) $(1-\varepsilon(\delta))|v|_{0} \leq|v|_{\delta} \leq(1+\varepsilon(\delta))|v|_{0}$ for all $v \in T(M)$ and (2) $\lim _{\delta \rightarrow 0} \varepsilon(\delta)=0$.

Let $\rho_{1}$ be a positive number such that $\rho<\rho_{1}<e^{-\beta \cdot \mathbf{t}}$. From the formula (1.4) and $F_{*} T=e^{-\beta \cdot \mathbf{t}} T$, it is easy to see that $0 \neq v \in E_{1} \Rightarrow\left|F_{*}(v)\right|_{0}>\rho_{1}|v|_{0}$. Then we have

$$
\left|F_{*}(v)\right|_{\delta} \geq(1-\varepsilon(\delta))\left|F_{*}(v)\right|_{0}>(1-\varepsilon(\delta)) \rho_{1}|v|_{0} \geq \frac{1-\varepsilon(\delta)}{1+\varepsilon(\delta)} \rho_{1}|v|_{\delta}
$$

So, if we choose $\delta_{1}>0$ small enough so that $\left((1-\varepsilon(\delta)) \rho_{1}\right) /(1+\varepsilon(\delta)) \geq \rho$ for any $\delta \leq \delta_{1}$, then we have $\left|F_{*}(v)\right|_{\delta}>\rho|v|_{\delta}\left(\delta \leq \delta_{1}\right)$. Similarly we can choose $\delta_{2}<\delta_{1}$ so that the metric $\left|\left.\right|_{\delta}\right.$ also satisfies the second condition if $\delta \leq \delta_{2}$.

By Lemma 4.2, the diffeomorphism $F$ is $\rho$-pseudo hyperbolic ([9], §5). From Theorem (5.5) in [9], the continuous plane field $E_{1}$ is uniquely integrable and is tangent to a $C^{0}$ foliation, denoted by $\mathcal{W}(\mathbf{t})$, with $C^{\infty}$-leaves.

Lemma 4.3. The foliation $\mathcal{W}(\mathbf{t})$ is preserved by the action $\Phi$ and is smooth.
Proof. For each $g \in G$, we have $g_{*} E_{1}=E_{1}$. So the action $\Phi$ preserves the foliation $\mathcal{W}(\mathbf{t})$.

Let $G_{2}$ be the subgroup of $G$ defined, with respect to the canonical coordinate of $G$, by

$$
G_{2}=\left\{\left(\exp \mathbf{s},\left(x_{1}, \ldots, x_{n}\right)^{t}\right) \in G \mid \mathbf{s} \in \boldsymbol{R}^{m}, x_{i}=0 \text { for } i \in u(\mathbf{t})\right\} .
$$

Consider the restricted action $\left.\Phi\right|_{G_{2}}: G_{2} \times M \rightarrow M$. Then the action $\left.\Phi\right|_{G_{2}}$ is locally free and preserves the foliation $\mathcal{W}(\mathbf{t})$. Furthermore the orbit foliation $\mathcal{F}_{\Phi_{G_{2}}}$ is of complementary dimension and is transverse to $\mathcal{W}(\mathbf{t})$. In other words, the foliation $\mathcal{W}(\mathbf{t})$ is a transversely $G_{2}$ foliation ([7, p. 152]).

We will show the smoothness of $\mathcal{W}(\mathbf{t})$ from this fact. Let $n_{1}=\operatorname{dim} E_{1}$ and let $D$ be the unit disc in $\boldsymbol{R}^{n_{1}}$. Take an arbitrary point $p \in M$. Since each leaf of $\mathcal{W}(\mathbf{t})$ is of class $C^{\infty}$, there is a smooth embedding $f_{0}: D \rightarrow M$ such that $f_{0}(\mathbf{0})=p$ and $f_{0}(D)$ is contained in a leaf of $\mathcal{W}(\mathbf{t})$. Define a $C^{\infty}$-map $f: D \times G_{2} \rightarrow M$ by $f(x, \mathrm{~g})=\Phi_{g}\left(f_{0}(x)\right)$. Then there exists in $G_{2}$ a neighbourhood $V$ of the identity element such that $\left.f\right|_{D \times V}: D \times V \rightarrow M$ is an into diffeomorphism. For each $g \in G_{2}$, the image $f(D \times\{g\})$ is contained in a leaf of $\mathcal{W}(\mathbf{t})$ because $\left.\Phi\right|_{G_{2}}$ preserves $\mathcal{W}(\mathbf{t})$. This shows that the foliation $\mathcal{W}(\mathbf{t})$ has a smooth distinguished chart $\left.f\right|_{D \times V}$ at $p$. Since $p$ is arbitrary, the foliation $\mathcal{W}(\mathbf{t})$ is smooth on $M$.

Proof of Proposition 4.1. From the assumption on the structure matrix, for each $i(1 \leq i \leq n)$, there exists $\mathbf{t}_{i} \in S$ such that $-\beta \cdot \mathbf{t}_{i}>\mathfrak{R} \Lambda_{i} \cdot \mathbf{t}_{i}$. Then we have $\bigcap_{i=1}^{n} u\left(\mathbf{t}_{i}\right)=\emptyset$, and $\mathcal{T}=\bigcap_{i=1}^{n} \mathcal{W}\left(\mathbf{t}_{i}\right)$ is a one dimensional foliation tangent to $T$. Note that the foliation $\mathcal{T}$ is smooth from Lemma 4.3. Since $T$ is tangent to $\mathcal{T}$ and satisfies $\Omega\left(X_{1}^{*}, \ldots, X_{n}^{*}, Y_{1}^{*}, \ldots\right.$, $\left.Y_{m}^{*}, T\right)=1$ for the smooth volume form $\Omega$ (see Step 1 in Section 3.2), the vector field $T$ is smooth.

We are now in a position to prove Theorem 1 in Introduction. Note that the assumption on the structure matrix in Proposition 4.1 follows from that in Proposition 3.1.

Proof of Theorem 1. By Proposition 3.1, there exists a continuous vector field $T$ on $M$ such that $\Omega\left(X_{1}^{*}, \ldots, X_{n}^{*}, Y_{1}^{*}, \ldots, Y_{m}^{*}, T\right)=1$ and $g_{*} T=\Delta(g)^{-1} T$ for any $g \in G$. From Proposition 4.1, the vector field $T$ is smooth.

Let $\left\{\phi_{t} \mid t \in \boldsymbol{R}\right\}$ be the flow of $M$ generated by the $C^{\infty}$ vector field $T$. Let $g \in G$. Because $g_{*} T=\Delta(g)^{-1} T$, we have

$$
\begin{equation*}
\Phi_{g} \circ \phi_{t} \circ \Phi_{g^{-1}}=\phi_{\Delta(g)^{-1} t} \tag{4.1}
\end{equation*}
$$

Let $\hat{G}=G \ltimes_{\Delta^{-1}} \boldsymbol{R}$ be the semidirect product of $G$ and $\boldsymbol{R}$ determined by the homomorphism $\Delta^{-1}: G \rightarrow \boldsymbol{R}_{+} \subset G L(1, \boldsymbol{R})$. From (4.1) we can define a smooth action $\hat{\Phi}$ of $\hat{G}$ on $M$ by $\hat{\Phi}(g, t)=\phi_{t} \circ \Phi_{g}$. Since the flow $\phi_{t}$ is transverse to the foliation $\mathcal{F}_{\Phi}$ and $\Phi$ is locally free, the action $\hat{\Phi}$ is also locally free. A locally free action $\hat{\Phi}$ of an $(m+n+1)$-dimensional Lie group $\hat{G}$ on an ( $m+n+1$ )-dimensional connected manifold has a single orbit, and hence $\hat{\Phi}$ is homogeneous. It follows that the action $\Phi$, which is the restriction of $\hat{\Phi}$ to the subgroup $G \subset \hat{G}$, is homogeneous. Since $\hat{G}$ is solvable, $M$ is a solvmanifold.

REMARK. The group $\hat{G}$ in the proof of Theorem 1 is naturally isomorphic to the Lie group $\tilde{G}$ constructed in the proof of Proposition 1.5.

From Theorems 1 and 2, we have the following corollary.

Corollary 4.4. Let $G=\boldsymbol{R}_{+}^{m} \ltimes_{\psi} \boldsymbol{R}^{n}$ be a group in $D(n, m)$. Suppose that the structure matrix $\Lambda_{\psi}$ of $G$ satisfies

$$
\Lambda_{i} \neq \mathbf{0}(1 \leq i \leq n) \quad \text { and } \quad \beta \notin\left\{a_{i} \Re \Lambda_{i}, b_{j} \Re \Lambda_{j}-\Re \Lambda_{k} \mid 0 \leq a_{i}, b_{j} \leq 1,1 \leq i, j, k \leq n\right\}
$$

If the matrix $\left(\Lambda_{\psi}^{t},-\beta^{t}\right)^{t}$ is not equivalent to a matrix $\hat{\Lambda}$ satisfying the conditions (1) and (2) in Theorem 2, then $G$ has no codimension one locally free volume preserving action on a closed manifold.

When $m=n \geq 2$, the structure matrix of $G \in D(n, n)$ always satisfies the assumption on $\Lambda_{\psi}$ in Theorem 1. Thus, from Proposition 1.5, Corollary 2.5 and Theorem 1, we also obtain the following concluding corollary.

Corollary 4.5. Let $G=\boldsymbol{R}_{+}^{n} \ltimes_{\psi} \boldsymbol{R}^{n}(n \geq 2)$ be a group in $D(n, n)$. Then we have the following.
(1) There exists uniquely a simply connected unimodular Lie group which contains $G$ as a subgroup.
(2) $G$ has a codimension one homogeneous action.
(3) If $G$ acts on a $(2 n+1)$-dimensional connected closed orientable manifold locally freely and preserves a volume form of class $C^{0}$, then the action is $C^{\infty}$-conjugate to a homogeneous action.

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Department of Mathematics
International Christian University
Osawa, Mitaka, Tokyo, 181-0015
Japan
E-mail address: yamakawa@icu.ac.jp

E-mail address: yamakawa@icu.ac.jp

Department of Mathematics
Toin University of Yokohama
Kurogane, Aoba, Yokohama, 225-8502
Japan
E-mail address: tsuchiya@cc.toin.ac.jp


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