# Critical Metrics of the Scalar Curvature Functional 

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## 1. Introduction.

Let $M$ be a compact connected $n$-manifold and $\mathscr{M}(M)$ the space of Riemannian metrics on $M$. We study the critical metrics of the following functional;

$$
\mathscr{S}^{p}: \mathscr{M}(M) \rightarrow \mathbf{R} ; \quad g \mapsto \frac{\int_{M} R_{g}^{p} d v_{g}}{\left(\int_{M} d v_{g}\right)^{(n-2 p) / n}},
$$

where $R_{g}$ is the scalar curvature of $g$ and $p \in \mathbf{N}$.
The first variation formula for $\mathscr{S}^{p}$ is

$$
\begin{equation*}
\nabla^{2} R_{g}^{p-1}=\frac{1}{n} \Delta R_{g}^{p-1} g+R_{g}^{p-1}\left(\operatorname{Ric}_{g}-\frac{R_{g}}{n} g\right) \tag{i}
\end{equation*}
$$

where $\mathrm{Ric}_{g}$ is the Ricci tensor of $g$. Taking the divergence of (i) with respect to $g$, we have

$$
\begin{equation*}
\Delta R_{g}^{p-1}=\frac{n-2 p}{2 p(n-1)}\left(R_{g}^{p}-\overline{R_{g}^{p}}\right), \tag{ii}
\end{equation*}
$$

where $\overline{R_{g}^{p}}=\int_{M} R_{g}^{p} d v_{g} / \int_{M} d v_{g}$. The equation (ii) is also the first variation formula for $\left.\mathscr{S}^{p}\right|_{C}$, where $C$ is a conformal class of $\mathscr{M}(M)$.

Obviously, if $R_{g} \equiv 0$ or $g$ is an Einstein metric, the metric $g$ satisfies the equation (i). A metric of constant scalar curvature satisfies the equation (ii). The question is whether the converses are true or not.

The case $p=1$ is well-known (e.g. [5]). When $n=2,\left.\mathscr{S}^{2}\right|_{c}$ was studied by Calabi ([4], see also Section 3). If $n \geq 4$ and $p=n / 2$, the answer is positive (e.g. [2]). If $n=3$, $p=2$ and $R_{g}$ does not change the sign, then the metric which satisfies (i) is of constant scalar curvature ([1]). According to Anderson ([1]), the general case is an open question.

In this paper, we show the following results which are extentions of Anderson's

[^0]result.
Theorem 1. Suppose $g$ satisfies the equation (ii). If any of the following condition is satisfied, then $R_{g}$ is constant:
(i) for $p \geq 3$, $(p-n / 2) \max R_{g} \leq 0$ or $(p-n / 2) \min R_{g} \leq 0$;
(ii) for $p=2$, $(2-n / 2) \max R_{g} \leq 0$ and $(2-n / 2) \min R_{g} \leq 0$.

Corollary. If $g$ satisfies (ii) and $(p-n / 2) R_{g} \leq 0$ then $R_{g}$ is constant.
Theorem 2. If $g$ satisfies the equation (i) and $R_{g} \geq 0$, then $g$ is an Einstein metric or $R_{g}$ is identically 0 .

From Theorem 1 and Theorem 2, we obtain the affirmative answer to our question in case $p \geq \max \{3, n / 2\}$, which implies a difficult part of the problem will be the case for relatively small $p$.

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## 2. Proof of Theorem 1.

It is easy to see that

$$
\Delta R_{g}^{p}=\frac{p}{p-1} R_{g} \Delta R_{g}^{p-1}+p R_{g}^{p-2}\left|\nabla R_{g}\right|^{2}
$$

Combining (ii) with this, we have

$$
\Delta R_{g}^{p}(x)=\frac{n-2 p}{2(n-1)(p-1)} R_{g}(x)\left(R_{g}^{p}(x)-\overline{R_{g}^{p}}\right),
$$

if either $x$ is a critical point of $R_{g}$ or $x$ is a critical point of $R_{g}^{p}$ for $p \geq 3$. Thus we see that if $R_{g}$ is not constant and if $p \geq 3$ then $(n-2 p) R_{g}\left(x_{1}\right) \leq 0$ at a maximum point $x_{1}$ of $R_{g}^{p}$ and $(n-2 p) R_{g}\left(x_{2}\right) \leq 0$ at a minimum point $x_{2}$ of $R_{g}^{p}$. If $R_{g}$ is not constant and $p$ is even then $(n-2 p) R_{g}\left(x_{1}\right)<0$. We then have $(n-2 p) R_{g} \leq 0$ if $p$ is odd, and $(n-2 p) R_{g}<0$ if $p$ is even and $R_{g}\left(x_{2}\right) \neq 0$. Again from (ii), if $p \geq 3$ and $R_{g}$ takes 0 somewhere then $\overline{R_{g}^{p}}=0$. Now it is easy to see the assertion (i). The assertion (ii) is proved by a similar argument.

## 3. The case of dimension 2.

In dimension 2, the equations (i) and (ii) become the following simple forms respectively:

$$
\begin{equation*}
\nabla^{2} R_{g}^{p-1}=\frac{1}{2} \Delta R_{g}^{p-1} g \tag{3.1}
\end{equation*}
$$

$$
\begin{equation*}
\Delta R_{g}^{p-1}=\frac{1-p}{p}\left(R_{g}^{p}-\overline{R_{g}^{p}}\right) . \tag{3.2}
\end{equation*}
$$

In [4], Calabi introduced the functional $\mathscr{S}^{2}$ on a complex manifold with a fixed Kähler class. In dimension 2, a Kähler class is nothing but a conformal class of metrics. Thus the equation to be considered will be (3.2).

Following the method given by Xu ([6]), we answer to our question for general $\mathscr{S}^{p}$.
Lemma 3.1. For $p \geq 2, g$ satisfies (3.1) if and only if $g$ is of constant scalar curvature.

Proof. From (3.1), $\nabla R_{g}^{p-1}$ is a conformal vector field. For a conformal vector field $X$, the following formula is well-known (e.g. [3]):

$$
\begin{equation*}
\int_{M} X R_{g} d v_{g}=0 \tag{3.3}
\end{equation*}
$$

Hence we have

$$
\int_{M} R_{g}^{p-2}\left|\nabla R_{g}\right|^{2} d v_{g}=0
$$

If $p$ is even, this implies $R_{g}$ is constant. If $p$ is odd, $R_{g}$ does not change a sign from Theorem 1. Thus $R_{g}$ is constant.

Lemma 3.2. (3.2) implies (3.1).
Proof. The Ricci identity shows that

$$
\frac{1}{2} \Delta|\nabla f|^{2}-\frac{1}{2} \operatorname{div}(\Delta f \nabla f)=\left|\nabla^{2} f-\frac{1}{2} \Delta f g\right|^{2}+\frac{1}{2} \nabla \Delta f \cdot \nabla f+\frac{R_{g}}{2}|\nabla f|^{2}
$$

where we have used $\operatorname{Ric}_{g}=\left(R_{g} / 2\right) g$ because $n=2$. Taking the integrals of the both sides, we have

$$
0=\int_{M}\left|\nabla^{2} f-\frac{1}{2} \Delta f g\right|^{2} d v_{g}+\frac{1}{2} \int_{M} \nabla \Delta f \cdot \nabla f d v_{g}+\frac{1}{2} \int_{M} R_{g}|\nabla f|^{2} d v_{g}
$$

We put $f=R_{g}^{p-1}$. Then it follows from (3.2) that

$$
\begin{aligned}
0= & \int_{M}\left|\nabla^{2} R_{g}^{p-1}-\frac{1}{2} \Delta R_{g}^{p-1} g\right|^{2} d v_{g} \\
& -\frac{(p-1)^{2}}{2} \int_{M} R_{g}^{2 p-3}\left|\nabla R_{g}\right|^{2} d v_{g}+\frac{(p-1)^{2}}{2} \int_{M} R_{g}^{2 p-3}\left|\nabla R_{g}\right|^{2} d v_{g} \\
= & \int_{M}\left|\nabla^{2} R_{g}^{p-1}-\frac{1}{2} \Delta R_{g}^{p-1} g\right|^{2} d v_{g}
\end{aligned}
$$

Hence (3.1) holds.

Remark. For $n \geq 3$, this lemma does not hold.
Theorem. For $p \geq 2, g$ satisfies (3.2) if and only if $g$ is of constant scalar curvature.

## 4. Proof of Theorem 2.

In this section we consider the equation (i). Lemma 3.1 gives a complete answer in dimension 2. There the formula (3.3) plays an important role. This will be interpreted as follows: Since $\nabla^{2} f=\frac{1}{2} \mathscr{L}_{\nabla f} g$ for any function $f$, the equation (i) gives us information on $\mathscr{L}_{\nabla R_{g}^{p-1}} g$. Naturally this leads to what will be $\mathscr{L}_{\nabla R_{g}^{p-1}} R_{g}$. We can regard the formula (3.3) as the integral of $\mathscr{L}_{X} R_{g}$ for $X=\nabla R_{g}^{p-1}$. Following this line, we proceed the argument in higher dimensional cases.

Recall that if a vector field $X$ and a 2-tensor $h$ satisfy $\mathscr{L}_{x} g=h$ then

$$
\mathscr{L}_{X} R_{g}=-\Delta \operatorname{tr} h+h_{; i j}^{i j}-\left\langle h, \mathrm{Ric}_{g}\right\rangle .
$$

Taking the integrals of the both sides, we obtain

$$
\int_{M} X R_{g} d v_{g}=-\int_{M}\left\langle h, \mathrm{Ric}_{g}\right\rangle d v_{g} .
$$

In view of the equation (i), we put

$$
X=\nabla R_{g}^{p-1}, \quad h=\frac{2}{n} \Delta R_{g}^{p-1} g+2 R_{g}^{p-1}\left(\operatorname{Ric}_{g}-\frac{R_{g}}{n} g\right),
$$

and we have

$$
\int_{M} \nabla R_{g}^{p-1} R_{g} d v_{g}=-\int_{M}\left(\frac{2}{n}\left(\Delta R_{g}^{p-1}\right) R_{g}+2 R_{g}^{p-1}\left|\mathrm{Ric}_{g}-\frac{R_{g}}{n} g\right|^{2}\right) d v_{g}
$$

By integration by parts we have

$$
(p-1)\left(1-\frac{2}{n}\right) \int_{M} R_{g}^{p-2}\left|\nabla R_{g}\right|^{2} d v_{g}=-2 \int_{M} R_{g}^{p-1}\left|\mathrm{Ric}_{g}-\frac{R_{g}}{n} g\right|^{2} d v_{g}
$$

Consequently we get

$$
\frac{(n-2)(p-1)}{2 n} \int_{M} R_{g}^{p-2}\left|\nabla R_{g}\right|^{2} d v_{g}=-\int_{M} R_{g}^{p-1}\left|\mathrm{Ric}_{g}-\frac{R_{g}}{n} g\right|^{2} d v_{g}
$$

From our assumption $R_{g} \geq 0$, the left hand side is non-negative. Therefore the integrand of the right side vanishes.

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