## DISTRIBUTION OF MINIMAL VARIETIES IN SPHERES IN TERMS OF THE COORDINATE FUNCTIONS

## OSCAR PERDOMO

ABSTRACT. Let M be a compact k-dimensional Riemannian manifold minimally immersed in the unit n-dimensional sphere  $S^n$ . It is easy to show that for any  $p \in S^n$  the boundary of the geodesic ball in  $S^n$  with radius  $\pi/2$  and center at p (in this case this boundary is an equator) must intercept the manifold M. When the codimension is 1, i.e., k=n-1, it is known that the Ricci curvature is not greater than 1. We will prove that if the Ricci curvature is not greater than  $1-\alpha^2/(n-2)$ , then the boundary of every geodesic ball with radius  $\cot^{-1}(\alpha)$  must intercept the manifold M. We give examples of manifolds for which the radius  $\cot^{-1}(\alpha)$  is optimal. Next, for any codimension, i.e., for any  $M^k \subset S^n$ , we find a number  $r_1$  that depends only on n such that for any collection of n+1 points  $\{p_i\}_{i=1}^{n+1}$  in  $S^n$  that constitutes an orthonormal basis of  $\mathbb{R}^{n+1}$ , the union of the boundaries of the geodesic balls with radius  $r_1$  and center  $p_i$ ,  $i=1,2,\ldots,n+1$ , must intercept the manifold M.

1. Introduction and preliminaries. Let M be a compact, oriented minimal hypersurface immersed in the n-dimensional unit sphere  $S^n$ . Let  $\nu$  be a unit normal vector field along M. For any tangent vector  $v \in T_m M$ ,  $m \in M$ , the shape operator A is given by  $A(v) = -\overline{D}_v \nu$  where  $\overline{D}$  denotes the Levi Civita connection in  $\mathbf{R}^{n+1}$ . With the same notation, for any tangent vector field W, the Levi Civita connection on M is given by  $D_v W = (\overline{D}_v W)^T$  where  $(\phantom{-})^T$  denotes the orthogonal projection from  $\mathbf{R}^{n+1}$  to  $T_m M$ . For a function  $f: M \to \mathbf{R}$ ,  $\nabla f$  will denote the gradient of f. For any pair of vectors  $v, w \in T_m M$  the Hessian of f is given by  $H(f)(v, w) = \langle D_v \nabla f, w \rangle$ , where  $\langle \phantom{-}, \phantom{-} \rangle$  denotes the inner product in  $\mathbf{R}^{n+1}$ . The Laplacian of f is given by  $\Delta(f) = \sum_{i=1}^{n-1} H(f)(v_i, v_i)$  where  $\{v_i\}_{i=1}^{n-1}$  is an orthonormal basis of  $T_m M$ .

For a given  $w \in \mathbf{R}^{n+1}$ , let us define the functions  $l_w : M \to \mathbf{R}$  and  $f_w : M \to \mathbf{R}$  by  $l_w(m) = \langle m, w \rangle$  and  $f_w(m) = \langle \nu(m), w \rangle$ . Clearly

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the function  $l_w$  is the restriction to M of the linear function in  $\mathbb{R}^{n+1}$  whose gradient is the constant vector w; therefore, the gradient of the function  $l_w$  at  $m \in M$  is the projection of the vector w to  $T_m M$ , i.e.,

$$\nabla l_w = w^T = w - l_w(m)m - f_w(m)\nu(m).$$

Let  $v_i, v_j$  be two vectors in  $T_m M$ . The Hessian of  $l_w$  at  $m \in M$  is given by

(1.1) 
$$H(l_w)(v_i, v_j) = \langle D_{v_i} \nabla l_w, v_j \rangle = \langle \overline{D}_{v_i} \nabla l_w, v_j \rangle$$
$$= -l_w \langle v_i, v_j \rangle - f_w \langle \overline{D}_{v_i} \nu, v_j \rangle$$
$$= -l_w \langle v_i, v_j \rangle + f_w \langle A(v_i), v_j \rangle.$$

From the equation above and the fact that A is traceless (minimality of M) we get that

$$(1.2) \Delta l_w = -(n-1)l_w.$$

Remark 1.3. As a corollary of equation (1.2) we get that every coordinate function  $l_w$  must change sign; therefore, the boundary of every geodesic ball with radius  $\pi/2$  must intersect M.

Given any nonequatorial compact minimal hypersurface in  $S^n$  we know that there exists a radius r,  $r < \pi/2$ , such that M must intersect the boundary of *every* geodesic ball in  $S^n$  with radius r. Let  $\gamma_M$  be the minimum r with the property above. In Section 2 we will use the expression for the Hessian of the coordinate function  $l_w$  to find an upper bound for  $\gamma_M$ , namely we will show:

**Theorem 1.4.** Let  $M^{n-1}$  be a minimal hypersurface immersed in  $S^n$ , and let  $\{\lambda_i(m)\}_{i=1}^{n-1}$  be the eigenvalues of the shape operator at  $m \in M$ . Define  $\bar{\alpha}(m) = \min\{|\lambda_i(m)|, i=1,\ldots,n-1\}$  and let  $\alpha$  be the minimum over M of the function  $\bar{\alpha}$ . If  $r_0$  satisfies that  $\cot(r_0) = \alpha$  and  $0 < r_0 \le \pi/2$ , i.e.,  $r_0 = \cot^{-1}(\alpha)$ , then the boundary of every geodesic ball in  $S^n$  with radius  $r_0$  must intersect M.

Notice that if  $\alpha = 0$ , then Theorem 1.4 reduces to Remark 1.3. A direct computation shows that, if M is the minimal Clifford hypersurface,  $M = \{(x,y) \in \mathbf{R}^{s+1} \times \mathbf{R}^{s+1} : ||x||^2 = ||y||^2 = 1/2\}$ , then for any

 $r < \pi/4$ , the boundary of the geodesic ball with center at  $(1,0,\ldots,0)$  does not intersect M, therefore  $\gamma_M \ge \pi/4$ . The principal eigenvalues of the shape operator A of M are either 1 or -1 everywhere, then  $\alpha = 1$  in this case and we get that  $\pi/4 = \cot^{-1}(1) \ge \gamma M \ge \pi/4$ . This example shows that the estimate in Theorem 1.4 is sharp.

Let us rewrite Theorem 1.4 in terms of the curvature of M. Denote by R and Ricci the curvature tensor and the Ricci curvature of M, respectively. The Gauss equation states that

$$\langle R(v,w)v,w\rangle = \langle v,v\rangle\langle w,w\rangle - \langle v,w\rangle\langle v,w\rangle + \langle A(v),v\rangle\langle A(w),w\rangle - \langle A(w),v\rangle\langle A(v),w\rangle.$$

Therefore, if  $\{v_i\}_{i=1}^{i=n-1}$  is an orthonormal basis of  $T_mM$ , we have

$$\begin{aligned} \operatorname{Ricc}\left(v\right) &= \frac{1}{n-2} \bigg( \sum_{i=1}^{n-1} \langle R(v,v_i)v,v_i \bigg) \\ &= \frac{\sum_{i=1}^{n-1} \left( \langle v,v \rangle \langle e_i,e_i \rangle - \langle e_i,v \rangle \langle e_i,v \rangle \right)}{n-2} \\ &+ \frac{\langle A(v),v \rangle \langle A(e_i),e_i \rangle - \langle A(e_i),v \rangle \langle A(e_i),v \rangle)}{n-2} \\ &= \frac{(n-1)|v|^2 - |v|^2 - |A(v)|^2}{n-2} \\ &= |v|^2 - \frac{|A(v)|^2}{n-2}. \end{aligned}$$

By the equation above, we get that another way to define  $\alpha$  is given by

$$\max_{v \in T^1 M} \operatorname{Ricc}(v) = 1 - \frac{\alpha^2}{n - 2}$$

where  $T^1M = \{v \in T_mM : m \in M \text{ and } |v| = 1\}$ . By the observations made above, we get

Corollary 1.5. Let  $M \subset S^n$  be a minimal hypersurface. If  $\text{Ricc}(v) \leq 1 - \alpha^2/(n-2)$  for every  $v \in T^1M$ , then the boundary of every geodesic ball in the sphere with radius  $\cot^{-1}(\alpha)$  must intersect M.

The result in the previous corollary needs the minimality condition. To see this, it is enough to look at the following family of flat surfaces in  $S^3$  given by

$$M_{r_1r_2} = \{(x,y) \in \mathbf{R}^2 \times \mathbf{R}^2 : |x|^2 = r_1^2, |y|^2 = r_2^2, r_1^2 + r_2^2 = 1$$
 and  $r_1 < r_2 \}.$ 

A direct computation shows that  $\gamma_{M_{r_1r_2}} = \sin^{-1}(r_2)$ . We also have that  $\alpha$  is 1 because all these surfaces are flat; therefore, if  $r_1 < r_2$ , then  $\gamma_{M_{r_1r_2}} > \pi/4$ ; hence,  $\pi/4 = \cot^{-1}(\alpha)$  is not an upper bound for  $\gamma_{M_{r_1r_2}}$ . The examples above show us that among all Euclidean products of circles in  $S^3$ , the minimal Clifford tori are the ones that best make the work of "trying to be as close to every point in  $S^3$  as possible". In other words the minimal Clifford torus minimizes  $\gamma_{M_{r_1r_2}}$  in the family  $M_{r_1r_2}$ .

Our second result states that if M is a minimal variety in  $S^n$ , then at least one of its coordinate functions must take the value  $-(1-\sqrt{(n-2)/(n+1)})$  at some point. Namely, we will show

**Theorem 1.6.** Let  $M^k$  be a minimal k-dimensional manifold immersed in the n-dimensional unit sphere  $S^n$ . Then for every orthonormal basis of  $\mathbf{R}^{n+1}$ ,  $\{p_i\}_{i=1}^{i=n-1}$  for some i, M must intersect the boundary of geodesic ball with center at  $p_i$  and radius  $\cos^{-1}(1-\sqrt{(n-2)/(n+1)})$ .

Before I proceed, I would like to thank Professor Bruce Solomon for his lessons on mathematics and his comments on this paper. I would also like to thank Professor Peter Li for meeting with me to discuss mathematics; one of his comments motivated the idea for Theorem 1.4.

2. Proof of the theorems. We start this section stating and proving Theorem 1.4. This result is a consequence of equation (1.1) for the Hessian of the coordinate functions. Notice that in both of the Theorems, 1.4 and 1.5, we may assume that our manifold M is orientable, since otherwise the results follow by applying the theorem to the double covering of M.

**Theorem 1.4.** Let  $M^{n-1}$  be a minimal hypersurface immersed in  $S^n$ , and let  $\{\lambda_i(m)\}_{i=1}^{n-1}$  be the eigenvalues of the shape operator at  $m \in M$ . Define  $\bar{\alpha}(m) = \min\{|\lambda_i(m)|, i = 1, \ldots, n-1\}$  and let  $\alpha$  be the minimum over M of the function  $\bar{\alpha}$ . If  $r_0$  satisfies that  $\cot(r_0) = \alpha$  and  $0 < r_0 \le \pi/2$ , i.e.,  $r_0 = \cot^{-1}(\alpha)$ , then the boundary of every geodesic ball in  $S^n$  with radius  $r_0$  must intersect M.

Proof. Since the result is trivial when M is totally geodesic we will assume that this is not the case. Notice that it is enough to prove that for every  $v \in S^n$  the minimum of the coordinate function  $l_v : M \to \mathbf{R}$  over M is less than or equal to  $-\alpha/\sqrt{1+\alpha^2}$ . Let  $m_0$  be a point in M where the function  $l_v$  reaches its minimum. Since M is not an equator we have that  $l_v(m_0) < 0$ . We need to show that  $l_v(m_0) \leq -\alpha/\sqrt{1+\alpha^2}$  or equivalently  $|l_v(m_0)| \geq \alpha/\sqrt{1+\alpha^2}$ . Since  $m_0$  is a critical point of the function  $l_v$  we have  $\nabla l_v = 0$ , therefore,

$$(2.1) 1 = ||v||^2 = \langle v, m_0 \rangle^2 + \langle \nu(v), m_0 \rangle^2 + ||\nabla l_v||^2 = l_v(m_0)^2 + f_v(m_0)^2.$$

Let  $\{v_i\}_{i=1}^{n-1}$  be an orthonormal basis of  $T_{m_0}M$  that diagonalizes the shape operator A at  $m_0$ . Since  $m_0$  is a minimum of  $l_v$  we get for  $i = 1, \ldots, n-1$  that

$$(2.3) 0 \leq H(l_v)(v_i, v_i) = -l_v(m_0)\langle v_i, v_i \rangle + f_v(m_0)\langle A(v_i), v_i \rangle$$
  
=  $-l_v(m_0) + f_v(m_0)\lambda_i$ .

Since  $\sum_{i=1}^{n-1} \lambda_i = 0$  we can pick k such that  $-f_v(m_0)\lambda_k$  is not negative. Using the definition of  $\alpha$ , equation (2.1) and the inequalities (2.3) we get

$$|l_v(m_0)| = -l_v(m_0) \ge -f_v(m_0)\lambda_k = |-f_v(m_0)||\lambda_k| \ge \alpha \sqrt{1 - l_v(m_0)^2}.$$

Finally from the inequality above we can easily deduce the inequality we were looking for:  $|l_v(m_0)| \ge \alpha/\sqrt{1+\alpha^2} = \beta$ .

A direct computation shows that the formula for the Laplacian of the coordinate functions, (1.2), holds true for any codimension, i.e., we have that if  $M^k$  is a k-dimensional manifold minimally immersed in  $S^n$ , then  $-\Delta l_w = k l_w$ .

Now we will prove our second result. For the reader's convenience we will restate this theorem.

**Theorem 1.6.** Let  $M^k$  be a minimal k-dimensional manifold immersed in the n-dimensional unit sphere  $S^n$ . Then for every orthonormal basis of  $\mathbf{R}^{n+1}$ ,  $\{p_i\}_{i=1}^{i=n-1}$  for some i, M must intersect the boundary of geodesic ball with center at  $p_i$  and radius  $\cos^{-1}(1-\sqrt{(n-2)/(n+1)})$ .

*Proof.* Notice that it is enough to prove that at least one of the coordinate functions  $l_{p_i}$  takes a value less than or equal to  $-(1-\sqrt{(n-2)/(n+1)})$ . We will proceed by contradiction. Let us assume that all the functions  $l_i=l_{p_i}$  are greater than or equal to  $-(1-\sqrt{(n-2)/(n+1)})$ . Therefore the vector fields  $X_i=(1+l_i)^{-1}\nabla l_i$  are well defined. Let us compute the divergence of  $X_i$ :

$$\operatorname{div}(X_i) = -(1+l_i)^{-2} \|\nabla l_i\|^2 + (1+l_i)^{-1} (-kl_i)$$
$$= \frac{k}{2} \left( -1 + (1+l_i)^{-2} \left( 1 - \frac{2}{k} \|\nabla l_i\|^2 - l_i^2 \right) \right).$$

Since  $(1+l_i)^{-2} \leq (1-(1-\sqrt{(n-2)/(n+1)}))^{-2} = (n+1)/(n-2)$  by assumption and  $1-2/k||\nabla l_i||^2 - l_i^2 > 0$ , we get from the expression above after using the divergence theorem that,

$$0 = \int_{M} \left( -1 + (1 + l_{i})^{-2} \left( 1 - \frac{2}{k} \|\nabla l_{i}\|^{2} - l_{i}^{2} \right) \right)$$
$$< \int_{M} \left( -1 + \frac{n+1}{n-2} \left( 1 - \frac{2}{k} \|\nabla l_{i}\|^{2} - l_{i}^{2} \right) \right).$$

Notice that  $\sum_{i=1}^{n+1} l_i^2 = 1$  and by Stoke's theorem  $\int_M \|\nabla l_i\|^2 = k \int_M l_i^2$ . Then if we sum the inequalities above from i = 1 to i = n + 1, we get

$$0 < \sum_{i=1}^{n+1} \int_{M} \left( -1 + \frac{n+1}{n-2} \left( 1 - \frac{2}{k} ||\nabla l_{i}||^{2} - l_{i}^{2} \right) \right)$$
$$= \int_{M} \left( -(n+1) + \frac{n+1}{n-2} (n+1-2-1) \right) = 0.$$

This contradiction proves the theorem.  $\Box$ 

Remark. The case n=3 in the theorem above is also a consequence of the fact that any two minimal surfaces in  $S^3$  must intersect [1]. For any minimal surface M in  $S^3$  the surface  $-M=\{p\in S^3: -p\in M\}$  is also minimal. If  $m_0\in -M\cap M$  then one can check that either  $m_0$  or  $-m_0$  must intersect the union of the four geodesic balls with center at  $p_i$  and radius 1/2.

## REFERENCES

1. T. Frankel, On the fundamental group of a compact minimal submanifold, Ann. of Math. 83 (1966), 68–73.

 $E ext{-}mail\ address: }$  osperdom@univalle.edu.co