# SYMMETRIC POSITIVE DEFINITE MULTILINEAR FUNCTIONALS WITH A GIVEN AUTOMORPHISM 

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Let $V$ be an $n$-dimensional vector space over the real numbers $R$ and let $\varphi$ be a multilinear functional,

$$
\begin{equation*}
\varphi: \stackrel{m}{x} V \longrightarrow R \tag{1}
\end{equation*}
$$

i.e., $\varphi\left(x_{1}, \cdots, x_{m}\right)$ is linear in each $x_{j}$ separately, $j=1, \cdots, m$. Let $H$ be a subgroup of the symmetric group $S_{m}$. Then $\varphi$ is said to be symmetric with respect to $H$ if

$$
\begin{equation*}
\varphi\left(x_{o(1)}, \cdots, x_{o(m)}\right)=\varphi\left(x_{1}, \cdots, x_{m}\right) \tag{2}
\end{equation*}
$$

for all $\sigma \in H$ and all $x_{j} \in V, j=1, \cdots, m$. (In general, the range of $\varphi$ may be a subset of some vector space over $R$.) Let $T: V \rightarrow V$ be a linear transformation. Then $T$ is an automorphism with respect to $\varphi$ if

$$
\varphi\left(T x_{1}, \cdots, T x_{m}\right)=\varphi\left(x_{1}, \cdots, x_{m}\right)
$$

for all $x_{i} \in V, i=1, \cdots, m$. It is easy to verify that the set $\mathfrak{A}(H, T)$ of all $\varphi$ which are symmetric with respect to $H$ and which satisfy (3) constitutes a subspace of the space of all multilinear functionals symmetric with respect to $H$. We denote this latter set by $M_{m}(V, H, R)$.

We shall say that $\varphi$ is positive definite if

$$
\varphi(x, \cdots, x)>0
$$

for all nonzero $x$ in $V$, and we shall denote the set of all positive definite $\varphi$ in $\mathfrak{A}(H, T)$ by $P(H, T)$. It can be readily verified that $P(H, T)$ is a convex cone in $\mathfrak{A}(H, T)$.

Our main results follow.

Theorem 1. If $P(H, T)$ is nonempty then
(a) $m$ is even
and
(b) every eigenvalue of $T$ has modulus 1.

If, in addition, $T$ has only real eigenvalues then
(c) every elementary divisor of $T$ is linear.

Conversely if (a), (b) and (c) hold then $P(H, T)$ is nonempty. Moreover, if $P(H, T)$ is nonempty then $\mathfrak{A}(H, T)$ is the linear closure of $P(H, T)$.

In Theorem 2 we shall investigate the dimension of $\mathfrak{A}(H, T)$ in the event $P(H, T)$ is not empty. To do this we must introduce some combinatorial notation. Let $\Gamma_{m, n}$ denote the set of all sequences
$\omega=\left(\omega_{1}, \cdots, \omega_{m}\right)$ of length $m, 1 \leqq \omega_{i} \leqq n, i=1, \cdots, m$. Introduce an equivalence relation $\sim$ in $\Gamma_{m, n}$ as follows: $\alpha \sim \beta$ if there exists a $\sigma \in H$ such that

$$
\alpha^{\sigma}=\beta
$$

where $\alpha^{\sigma}=\left(\alpha_{\sigma(1)}, \cdots, \alpha_{\sigma(m)}\right)$. Let $\Delta$ be a system of distinct representatives for $\sim$, i.e., $\Delta$ is a set of sequences, one from each equivalence class with respect to $\sim$. We specify $\Delta$ uniquely by choosing each element $\alpha \in J$ to be lowest in lexicographic order in the equivalence class in which $\alpha$ occurs.

Theorem 2. If $P(H, T)$ is nonempty and $T$ has real eigenvalues $\gamma_{1}, \cdots, \gamma_{n}$ then $\gamma_{i}= \pm 1, i=1, \cdots, n$. Suppose

$$
\gamma_{i_{1}}=\cdots=\gamma_{i_{p}}=1, \quad \gamma_{j}=-1, \quad j \neq i_{1}, \cdots, i_{p}
$$

Let $\mu_{p}$ be the number of sequences $\omega$ in $\Delta$ such that the total number of occurrences of $i_{1}, \cdots, i_{p}$ in $\omega$ is even. Then

$$
\begin{equation*}
\operatorname{dim} \mathfrak{H}(H, T)=\mu_{p} \tag{5}
\end{equation*}
$$

Corollary. If $H=S_{m}$ in Theorem 2 and $T$ has $p$ eigenvalues 1 and $n-p$ eigenvalues -1 then

$$
\operatorname{dim} \mathfrak{N}(H, T)=\sum_{k=0}^{m / 2}\binom{p-1+2 k}{p-1}\binom{n-p-1+m-2 k}{n-p-1}
$$

In case $m=2, H=S_{2}, \mathfrak{H}(H, T)$ is the totality of symmetric bilinear functionals $\varphi$ for which

$$
\varphi\left(T x_{1}, T x_{2}\right)=\varphi\left(x_{1}, x_{2}\right), \quad x_{1}, x_{2} \in V
$$

and $P(H, T)$ is just the cone of positive definite $\varphi$ in $\mathfrak{Y}(H, T)$ i.e.,

$$
\varphi(x, x) \geqq 0
$$

with equality only if $x=0$. In this case we need not assume that $T$ has real eigenvalues in order to analyze $\mathfrak{Y}(H, T)$. We can easily prove the following result by our methods, most parts of which are known (see e.g. [1], Chapter 7).

Theorem 3. Assume that $m=2$ and $H=S_{2}$. Then $P(H, T)$ is nonempty if and only if
(a) Thas linear elementary divisors over the complex field,
(b) every eigenvalue of $T$ has modulus 1.

Suppose that $T$ has distinct complex eigenvalues

$$
\gamma_{k}=a_{k}+i b_{k} \quad\left(\text { and } \bar{\gamma}_{k}=a_{k}-i b_{k}\right)
$$

of multiplicity $e_{k}, k=1, \cdots, p$ and real eigenvalues

$$
\gamma_{k}=r_{k}, \quad k=\sum_{j=1}^{p} 2 e_{j}+1, \cdots, n
$$

If $P(H, T)$ is nonempty then the elementary divisors of $T$ over the real field are

$$
\begin{array}{rc}
\lambda^{2}-2 \lambda a_{k}+1, & e_{k} \text { times, } \quad k=1, \cdots, p, \\
\lambda-1, & q \text { times } \\
\lambda+1, & l \text { times }
\end{array}
$$

where

$$
\sum_{j=1}^{p} 2 e_{j}+q+l=n
$$

Moreover, $\mathfrak{Y}(H, T)$ is the linear closure of $P(H, T)$,

$$
\operatorname{dim} \mathfrak{A}(H, T)=\frac{q(q+1)}{2}+\frac{l(l+1)}{2}+\sum_{j=1}^{p} e_{j}^{2}
$$

and there exists a basis $E$ of $V$ such that $\mathfrak{Y}(H, T)$ consists of the set of all $\varphi$ whose matrix representations with respect to $E,[\varphi]_{E}^{E}$, have the following form:

$$
\begin{equation*}
[\varphi]_{E}^{E}=\sum_{k=1}^{p} \cdot\left(X_{k} \otimes I_{2}+Y_{k} \otimes F\right)+H_{q}+H_{l} \tag{6}
\end{equation*}
$$

In (6), the dot indicates direct sum, $\otimes$ denotes the Kronecker product, $F=\left[\begin{array}{cc}0 & 1 \\ -1 & 0\end{array}\right], X_{k}$ is $e_{k}$-square symmetric, $Y_{k}$ is $e_{k}$-square skew-symmetric, $H_{q}$ and $H_{l}$ are $q$-square and $l$-square symmetric respectively.
2. Proofs. Let $V^{m}(H)$ denote the symmetry class of tensors associated with $H$ [2]. That is, there exists a fixed multilinear function $\tau: \mathbf{X}_{1}^{m} V \rightarrow V^{m}(H)$ symmetric with respect to $H$, for which
(i) the linear closure of $\tau\left(\mathbf{X}_{1}^{m} V\right)$ is $V^{m}(H)$
(ii) the pair $\left(V^{m}(H), \tau\right)$ is universal: given any space $U$ and any multilinear function $\varphi: \times_{1}^{m} V \rightarrow U$ symmetric with respect to $H$, there exists a (unique) linear $h_{\varphi}: V^{m}(H) \rightarrow U$ satisfying

$$
\begin{equation*}
h_{\varphi} \tau=\varphi . \tag{7}
\end{equation*}
$$



We shall denote $\tau\left(x_{1}, \cdots, x_{m}\right)$ by $x_{1} * \cdots * x_{m}$, and $x_{1} * \cdots * x_{m}$ is called a decomposable tensor or a symmetric product of $x_{1}, \cdots, x_{m}$. If we take $\varphi\left(x_{1}, \cdots, x_{m}\right)$ to be $T x_{1} * \cdots * T x_{m}$ in (7) then $h_{\varphi}$ is denoted by $K(T)$ and is called the induced transformation on $V^{m}(H)$.

Before we embark on the proof of Theorem 1 we can define $\mathfrak{A}(H, T)$ in terms of $V^{m}(H)$. First observe that the mapping $\theta$ from the space of multilinear functionals $\rho$ symmetric with respect to $H$ to the dual space of $V^{m}(H)$,

$$
\theta: M_{m}(V, H, R) \longrightarrow\left(V^{m}(H)\right)^{*},
$$

defined by

$$
\theta(\varphi)=h_{\varphi},
$$

is one-to-one linear, and onto. That is, the correspondence $\varphi \leftrightarrow h_{\varphi}$ is linear bijective. Now, the subspace $\mathfrak{U}(H, T)$ of $M_{m}(V, H, R)$ is defined by

$$
\varphi\left(T x_{1}, \cdots, T x_{m}\right)=\varphi\left(x_{1}, \cdots, x_{m}\right)
$$

or in view of (7) by

$$
h_{\varphi}\left(T x_{1} * \cdots * T x_{m}\right)=h_{\varphi}\left(x_{1} * \cdots * x_{m}\right),
$$

for all $x_{i} \in V, i=1, \cdots, m$. In other words, since the decomposable tensors span $V^{m}(H)$ (see (i) above), $\varphi \in \mathfrak{A}(H, T)$ if and only if $\theta(\varphi)=h_{\varphi}$ satisfies

$$
h_{\varphi} K(T)=h_{\varphi},
$$

or

$$
\begin{equation*}
h_{\varphi}(K(T)-I)=0 \tag{8}
\end{equation*}
$$

where $I$ is the identity mapping on $V^{m}(H)$. We have proved the following.

Lemma 1. $\mathfrak{A}(H, T)$ is nonempty if and only if $K(T)-I$ is singular. Also,

$$
\begin{equation*}
\operatorname{dim} \mathfrak{A}(H, T)=\eta(K(T)-I) \tag{9}
\end{equation*}
$$

where $\eta$ is the nullity of the indicated transformation.
Lemma 2. If $P(H, T)$ is nonempty then $m$ is even and every eigenvalue of $T$ has modulus 1. Moreover, corresponding to real eigenvalues, $T$ has only linear elementary divisors.

Proof. If $\varphi \in P(H, T)$ and $x \neq 0$ then

$$
\varphi(-x, \cdots,-x)=(-1)^{m} \varphi(x, \cdots, x)
$$

and hence $(-1)^{m}>0$ and $m$ is even. Suppose that $\gamma$ is a real eigenvalue of $T$ with corresponding eigenvector $x$. Then

$$
\begin{aligned}
\varphi(T x, \cdots, T x) & =\varphi(\gamma x, \cdots, \gamma x) \\
& =\gamma^{m} \varphi(x, \cdots, x) .
\end{aligned}
$$

Since $\varphi \in P(H, T), \varphi(T x, \cdots, T x)=\varphi(x, \cdots, x)>0$ and hence $\gamma^{m}=1$ and $\gamma= \pm 1$. If $\gamma$ were involved in an elementary divisor of degree greater than 1 then there would exist linearly independent vectors $u_{1}$ and $u_{2}$ such that $T u_{1}=\gamma u_{1}, T u_{2}=\gamma u_{2}+u_{1}$ and hence

$$
\varphi\left(T u_{1}, \cdots, T u_{1}, T u_{2}\right)=\varphi\left(\gamma u_{1}, \cdots, \gamma u_{1}, \gamma u_{2}+u_{1}\right)
$$

Now

$$
\begin{aligned}
\varphi\left(u_{1}, \cdots, u_{1}, u_{2}\right) & =\gamma^{m} \varphi\left(u_{1}, \cdots, u_{1}, u_{2}\right) \\
& =\varphi\left(\gamma u_{1}, \cdots, \gamma u_{1}, \gamma u_{2}\right)
\end{aligned}
$$

so that

$$
\begin{aligned}
0 & =\varphi\left(\gamma u_{1}, \cdots, \gamma u_{1}, \gamma u_{2}+u_{1}\right)-\varphi\left(\gamma u_{1}, \cdots, \gamma u_{1}, \gamma u_{2}\right) \\
& =\varphi\left(\gamma u_{1}, \cdots, \gamma u_{1}, u_{1}\right) \\
& =\gamma^{m-1} \varphi\left(u_{1}, \cdots, u_{1}\right)
\end{aligned}
$$

a contradiction.
We now show that any complex eigenvalue of $T$ has modulus 1. Since $\gamma=a+i b$ is now assumed not to be real there exists a pair of linearly independent vectors $v_{1}$ and $v_{2}$ in $V$ such that

$$
\begin{align*}
& T v_{1}=a v_{1}-b v_{2}  \tag{10}\\
& T v_{2}=b v_{1}+a v_{2}
\end{align*}
$$

Let $\bar{V}$ be the extension of $V$ to an $n$-dimensional space over the complex field. Now $\varphi \in \mathfrak{Z}(H, T)$ means that

$$
\begin{equation*}
\varphi\left(T x_{1}, \cdots, T x_{m}\right)-\varphi\left(x_{1}, \cdots, x_{m}\right)=0 \tag{11}
\end{equation*}
$$

is an identity in $x_{1}, \cdots, x_{m}$. If we express the vectors in $\bar{V}$ in terms of a basis in $V$ (using in general complex rather than real coefficients) the identity (11) continues to hold since it is a homogeneous polynomial of degree $m$ in the components of $x_{1}, \cdots, x_{m}$, vanishing for all real values of these components. Of course it is not true that

$$
\varphi(x, \cdots, x)>0
$$

continues to hold for nonzero $x \in \bar{V}$. Now define

$$
\begin{align*}
& e_{1}=v_{1}+i v_{2} \in \bar{V} \\
& e_{2}=v_{1}-i v_{2} \in \bar{V} \tag{12}
\end{align*}
$$

and observe that $e_{1}$ and $e_{2}$ are linearly independent in $\bar{V}$ and satisfy

$$
\begin{aligned}
& T e_{1}=\gamma e_{1} \\
& T e_{2}=\bar{\gamma} e_{2} .
\end{aligned}
$$

Let $\omega=\left(\omega_{1}, \cdots, \omega_{m}\right)$ be a sequence for which each $\omega_{i}$ is either 1 or $2, i=1, \cdots, m$ :

$$
\varphi\left(T e_{\omega_{1}}, \cdots, T e_{\omega_{m}}\right)=\gamma^{k} \bar{\gamma}^{m-k} \varphi\left(e_{\omega_{1}}, \cdots, e_{\omega_{m}}\right),
$$

where $k$ of the $\omega_{i}$ are 1 and $m-k$ are 2 . But by the above remarks

$$
\varphi\left(T e_{\omega_{1}}, \cdots, T e_{\omega_{m}}\right)=\varphi\left(e_{\omega_{1}}, \cdots, e_{\omega_{m}}\right)
$$

and taking absolute values we have

$$
\left(|\gamma|^{m}-1\right)\left|\varphi\left(e_{\omega_{1}}, \cdots, e_{\omega_{m}}\right)\right|=0
$$

Thus if $|\gamma| \neq 1$ it follows that

$$
\begin{equation*}
\varphi\left(e_{\omega_{1}}, \cdots, e_{\omega_{m}}\right)=0 \tag{13}
\end{equation*}
$$

for all $\omega$ for which $\omega_{i}$ is 1 or 2 for $i=1, \cdots, m$. From (12) we have $v_{1}=\left(e_{1}+e_{2}\right) / 2$ and hence using (13) we see that

$$
\begin{align*}
\varphi\left(v_{1}, \cdots, v_{1}\right) & =\varphi\left(\frac{e_{1}+e_{2}}{2}, \cdots, \frac{e_{1}+e_{2}}{2}\right)  \tag{14}\\
& =0
\end{align*}
$$

However $v_{1} \in V$ and $\varphi \in P(H, T)$ and therefore (14) is a contradiction. Thus $|\gamma|=1$ and the proof of Lemma 2 is complete.

Lemma 3. If $m$ is even, and $T$ has real eigenvalues $r_{1}, \cdots, r_{n}$, and every elementary divisor of $T$ is linear then $P(H, T)$ is nonempty.

Proof. Since $T$ has linear elementary divisors there exists a basis for $V$ of eigenvectors $e_{1}, \cdots, e_{n}$. Let $g_{1}, \cdots, g_{n}$ be a dual basis in $V^{*}$. Let $g_{t}^{m}$ denote the multilinear functional whose value for any $x_{1}, \cdots, x_{m}$ in $V$ is

$$
\prod_{j=1}^{m} g_{t}\left(x_{j}\right)
$$

Clearly $g_{t}^{m} \in M_{m}(V, H, R)$. Set

$$
\varphi=\sum_{t=1}^{n} g_{t}^{m} .
$$

Then if $x_{j}=\sum_{k=1}^{n} \xi_{j k} e_{k}, j=1, \cdots, m$, and $T e_{k}=r_{k} e_{k}, k=1, \cdots, n$,

$$
\begin{aligned}
\varphi\left(T x_{1}, \cdots, T x_{m}\right) & =\sum_{t=1}^{n} \prod_{j=1}^{m} g_{t}\left(T x_{j}\right) \\
& =\sum_{t=1}^{n} \prod_{j=1}^{n} g_{t}\left(\sum_{k=1}^{n} \xi_{j k} T e_{k}\right) \\
& =\sum_{t=1}^{n} \prod_{j=1}^{m} \xi_{j t} r_{t} \\
& =\sum_{t=1}^{n} r_{t}^{m} \prod_{j=1}^{m} \xi_{j t} \\
& =\sum_{t=1}^{n} \prod_{j=1}^{m} \xi_{j t} \\
& =\sum_{t=1}^{n} \prod_{j=1}^{n} g_{t}\left(x_{j}\right) \\
& =\varphi\left(x_{1}, \cdots, x_{m}\right) .
\end{aligned}
$$

Hence $\varphi \in \mathfrak{R}(H, T)$. Moreover, if $x=\sum_{t=1}^{n} c_{t} e_{t}$ then

$$
\begin{aligned}
\varphi(x, \cdots, x) & =\sum_{t=1}^{n} g_{t}(x)^{m} \\
& =\sum_{t=1}^{n} c_{t}^{m} .
\end{aligned}
$$

But $m$ is even and hence $\varphi \in P(H, T)$. To complete the proof of Theorem 1 we note that if $\varphi \in P(H, T)$ and if $e_{1}, \cdots, e_{n}$ is any basis of $V$ then $\varphi(x, x, \cdots, x)$ is a homogeneous polynomial of degree $m$ in $c_{1}, \cdots, c_{n}$. Hence, on the compact hypersphere $S$ defined by $\sum_{t=1}^{n} c_{t}^{2}=1$ in $V, \varphi$ must assume a positive minimum value $m_{\varphi}$. By a similar argument for any $\psi \in \mathfrak{A}(H, T),|\psi|$ must assume a maximum $M_{\psi}$ for $\sum_{t=1}^{n} c_{t}^{2}=1$. Now let $\psi$ be an arbitrary element of $\mathfrak{A}(H, T)$ and choose a positive constant $a$ such that $a>M_{\psi} / m_{e}$. If $0 \neq x \in V$ and $\|x\|^{2}=$ $\sum_{t=1}^{n} c_{t}^{2}$ then $(x /\|x\|) \in S$ and

$$
\begin{aligned}
a \varphi(x, \cdots, x)-\psi(x, \cdots, x)= & a\|x\|^{m} \varphi\left(\frac{x}{\|x\|}, \cdots, \frac{x}{\|x\|}\right) \\
& -\|x\|^{m} \psi\left(\frac{x}{\|x\|}, \cdots, \frac{x}{\|x\|}\right) \\
\geqq & \|x\|^{m}\left(a m_{\varphi}-M_{\psi}\right) \\
> & 0 .
\end{aligned}
$$

In other words,

$$
a \varphi-\psi \in P(H, T)
$$

so that $\psi$ is a linear combination of elements in $P(H, T)$.
To proceed to the proof of Theorem 2 we use Theorem 1 to conclude immediately that since $T$ has real eigenvalues the elementary divisors are all linear and thus there exists a basis of eigenvectors of $T$ :

$$
T e_{k}=\gamma_{k} e_{k}, \quad k=1, \cdots, n .
$$

It is not difficult to show [2] that the decomposable tensors

$$
e_{\omega}^{*}=e_{\omega_{1}} * \cdots * e_{\omega_{m}}, \quad \omega \in \Delta,
$$

constitute a basis for $V^{m}(H)$.
We compute that

$$
\begin{align*}
K(T) e_{\omega}^{*} & =T e_{\omega_{1}} * \cdots * T e_{\omega_{m_{2}}} \\
& =\gamma_{\omega_{1}} e_{\omega_{1}} * \cdots * \gamma_{\omega_{m}} e_{\omega_{m}}  \tag{15}\\
& =\prod_{t=1}^{n} \gamma_{t}^{m} t^{(\omega)} e_{\omega}^{*}
\end{align*}
$$

where $m_{t}(\omega)$ denotes the multiplicity of occurrence of $t$ in $\omega, t=$ $1, \cdots, n$. The formula (15) shows that $(K(T)-I) e_{\omega}^{*}$ is 0 or a nonzero multiple of $e_{\omega}^{*}$ according as

$$
\prod_{t=1}^{n} \gamma_{t}^{m_{t}(\omega)}
$$

is 1 or -1 . Now we can assume without loss of generality that the eigenvalues $\gamma_{1}, \cdots, \gamma_{n}$ are so organized that $\gamma_{1}=\cdots=\gamma_{p}=1, \gamma_{p+1}=$ $\cdots=\gamma_{n}=-1$. (This is of course merely a notational convenience.) Then

$$
\begin{aligned}
\prod_{t=1}^{n} \gamma_{t}^{m_{t}(\omega)} & =\prod_{t=p+1}^{n}(-1)^{m_{t}(\omega)} \\
& =(-1)^{m-\sum_{t=1}^{p} m_{t}(\omega)} \\
& =(-1)_{t=1}^{\sum_{t} m_{t}(\omega)} .
\end{aligned}
$$

Thus $\prod_{t=1}^{n} \gamma_{t}^{m_{t}(\omega)}=1$ if and only if $\sum_{t=1}^{p} m_{t}(\omega)$ is even. This last statement just means that $1, \cdots, p$ (i.e., $i_{1}, \cdots, i_{p}$ ) occur altogether an even number of times in $\omega$.

The proof of the corollary is completed by first noting that if $H=S_{m}$ then the set $\Delta$ is the totality of nondecreasing sequences of length $m$ chosen from $1, \cdots, n$. Thus by Theorem 2 if $P(H, T)$ is
nonempty and $T$ has real eigenvalues $\gamma_{1}, \cdots, \gamma_{n}$ then these eigenvalues are $\pm 1$ and we lose no generality in assuming that $\gamma_{1}=\cdots=\gamma_{p}=1$, $\gamma_{p+1}=\cdots=\gamma_{n}=-1$. We want to count the total number of $\omega$ in $\Delta$ for which

$$
\begin{equation*}
\sum_{t=1}^{p} m_{t}(\omega) \equiv 0 \quad(\bmod 2) \tag{16}
\end{equation*}
$$

Now, a sequence satisfying (16) may be constructed as follows. Suppose that $k$ is a fixed integer, $0 \leqq 2 k \leqq m$, and we count the number of sequences in $\Delta$ in which $\sum_{t=1}^{p} m_{t}(\omega)=2 k$. The total number of nondecreasing sequences of length $2 k$ using the integers $1, \cdots, p$ is

$$
\binom{p+2 k-1}{2 k}=\binom{p-1+2 k}{p-1}
$$

and any one of these can be completed to a nondecreasing sequence of length $m$ by adjoining a nondecreasing sequence of length $m-2 k$ using the integers $p+1, \cdots, n$. There are a total of

$$
\binom{n-p+m-2 k-1}{m-2 k}=\binom{n-p-1+m-2 k}{n-p-1}
$$

ways of doing this. This completes the proof of the corollary.
To proceed to the proof of Theorem 3 we remark that Theorem 1 cannot be directly applied because we are not assuming that the eigenvalues of $T$ are real; in general this is not the case. However the statement (b) does follow from Theorem 1. If $E$ is any basis of $V, A$ is the matrix representation of $T$, and $C=[\varphi]_{E}^{E}$, then to say that $\varphi \in \mathfrak{U}(H, T)$ is equivalent to the assertion that

$$
\begin{equation*}
A^{T} C A=C \tag{17}
\end{equation*}
$$

If $\varphi \in P(H, T)$ then $C$ is a positive definite symmetric matrix and can therefore be written $C=K^{2}$, where $K$ is also positive definite symmetric. Then (17) is immediately equivalent to the statement that $K A K^{-1}$ is a real orthogonal matrix and (a) is evident. Conversely if (a) and (b) obtain then there exists a real nonsingular matrix $S$ such that $S^{-1} A S$ is a direct sum of a diagonal matrix with $\pm 1$ along the main diagonal together with certain 2 -square matrices of the form

$$
\left[\begin{array}{cc}
a_{k} & b_{k}  \tag{18}\\
-b_{k} & a_{k}
\end{array}\right]
$$

Since $\left|\gamma_{k}\right|=1, k=1, \cdots, n$, the matrix (18) is orthogonal and hence $S^{-1} A S=U$ where $U$ is an $n$-square real orthogonal matrix. If we set
$\left(S^{T}\right)^{-1} S^{-1}=C$ then $C$ is a positive definite symmetric matrix and we compute that

$$
\begin{aligned}
A^{\tau} C A & =\left(S^{-1}\right)^{7} U^{T} S^{T}\left(S^{T}\right)^{-1} S^{-1} S U S^{-1} \\
& =\left(S^{-1}\right)^{T} S^{-1} \\
& =C .
\end{aligned}
$$

Thus if $[\rho]_{E}^{E}=C$ then $\varphi \in P(H, T)$. The dimension of $\mathfrak{A l}(H, T)$ can equally well be computed as in the general case by finding $\eta(K(T)-I)$ where $K(T)$ is the induced mapping on the complex space of 2 -symmetric tensors over $\bar{V}$, i.e., $\bar{V}^{2}\left(S_{2}\right)$. The mapping $K(T)$ is just the 2nd Kronecker power of $T$ restricted to the second symmetric space. This mapping is customarily denoted by $P_{2}(T)[5]$. Since $T$ has a basis of eigenvectors $v_{1}, \cdots, v_{n}$, so does $P_{2}(T)$ and, for $1 \leqq i \leqq j \leqq n$,

$$
P_{2}(T) v_{i} * v_{j}=\gamma_{i} \gamma_{j} v_{i} * v_{j}
$$

Thus $\operatorname{dim} \mathfrak{A}(H, T)$ is precisely the number of pairs of integers $(i, j)$, $1 \leqq i \leqq j \leqq n$, for which

$$
\begin{equation*}
\gamma_{i} \gamma_{j}=1 \tag{19}
\end{equation*}
$$

But $T$ has the distinct eigenvalues $a_{k}+i b_{k}$ of multiplicity $e_{k}, k=1, \cdots$, $p$. This yields a total of

$$
\sum_{t=1}^{p} e_{t}^{2}
$$

pairs ( $i, j$ ) for which (19) is satisfied. Also, $T$ has 1 as an eigenvalue $q$ times and -1 as an eigenvalue $l$ times and this yields an additional

$$
\frac{q(q+1)}{2}+\frac{l(l+1)}{2}
$$

pairs ( $i, j$ ) for which (19) is satisfied. This proves that

$$
\operatorname{dim} \mathfrak{Y}(H, T)=\frac{q(q+1)}{2}+\frac{l(l+1)}{2}+\sum_{j=1}^{p} e_{j}^{2} .
$$

We now turn to the derivation of (6). First, we assert that since $T$ has linear elementary divisors over the complex numbers [4] there exists a basis $E$ of $V$ such that the matrix representation of $T$ has the following form:

$$
A=\sum_{k=1}^{p} I_{e_{k}} \otimes\left[\begin{array}{cc}
a_{k} & b_{k}  \tag{20}\\
-b_{k} & a_{k}
\end{array}\right]+I_{q}+-I_{l}
$$

where $I_{s}$ is the $s$-square identity matrix. We set $C=[\varphi]_{E}^{E}$ and partition $C$ conformally with (20):

$$
C=\left[\begin{array}{ccc|cc}
C_{11} & \cdots & C_{1 d} & & \\
\vdots & & \vdots & & Z \\
C_{d 1} & \cdots & C_{d d} & & \\
\hline & & C_{q} & C_{r} \\
Z^{T} & & \\
& & C_{r}^{T} & C_{l}
\end{array}\right],
$$

$C_{i j}$ is 2-square, $i, j=1, \cdots, d=\sum_{j=1}^{p} e_{j}, C_{q}$ is $q$-square symmetric and $C_{l}$ is $l$-square symmetric. Set $L=\sum_{k=1}^{p} I_{e_{k}} \otimes\left(a_{k} I_{2}+b_{k} F\right)$ and observe that for (17) to be satisfied $Z$ must satisfy

$$
\begin{equation*}
L^{T} Z\left(I_{q}+-I_{l}\right)=Z \tag{21}
\end{equation*}
$$

Now, $L^{T} \otimes\left(I_{q}+-I_{l}\right)$ has eigenvalues $\pm\left(a_{k} \pm i b_{k}\right)$ [3, p. 9] and none of these is equal to 1 . Hence (21) has only the zero matrix as a solution. Similarly we see that $C_{r}=0$. Next, consider a typical $C_{i j}, j>i$, call it $K$. Then $K$ must satisfy an equation of the form

$$
\begin{equation*}
\left(a_{s} I_{2}-b_{s} F\right) K\left(a_{r} I_{2}+b_{r} F\right)=K \tag{22}
\end{equation*}
$$

The matrix

$$
\left(a_{s} I_{2}-b_{s} F\right) \otimes\left(a_{r} I_{2}+b_{r} F\right)
$$

has eigenvalues

$$
\begin{equation*}
\left(a_{s} \pm i b_{s}\right)\left(a_{r} \pm i b_{r}\right) \tag{23}
\end{equation*}
$$

If $r \neq s$, (23) cannot be 1 and in this case $K=0$. If $r=s$ then precisely two of the four complex numbers (23) are 1. Thus the nullity of the matrix

$$
\begin{equation*}
\left(a_{s} I_{2}-b_{s} F\right) \otimes\left(a_{s} I_{2}+b_{s} F\right)-I_{4} \tag{24}
\end{equation*}
$$

is 2. But $K=I_{2}$ and $K=F$ are two linearly independent solutions to (22) for $r=s$. Also note that since $C$ is symmetric $C_{i i}$ must be a multiple of $I_{2}$. It follows that the submatrix

$$
\left[\begin{array}{ccc}
C_{11} & \cdots & C_{1 d} \\
\vdots & & \vdots \\
C_{d 1} & \cdots & C_{d d}
\end{array}\right]
$$

is itself a direct sum of $2 e_{k}$-square matrices of the form


This matrix is of the form $X_{k} \otimes I_{2}+Y_{k} \otimes F$ where $X_{k}=\left(x_{i j}\right)$ is $e_{k}$ square symmetric and $Y_{k}=\left(y_{i j}\right)$ is $e_{k}$-square skew-symmetric. This completes the proof of Theorem 3.
3. Some examples. Let $m=2 p$ and let $S_{p}^{\prime}$ be the symmetric group of degree $p$ on $p+1, \cdots, m$. In general if $V$ is a Euclidean space with inner product $(x, y)$ then $V^{m}(H)$ is also a Euclidean space [2] in which the inner product of two symmetric products $x_{1} * \cdots * x_{m}$ and $y_{1} * \cdots * y_{m}$ is given by

$$
\begin{equation*}
\left(x_{1} * \cdots * x_{m}, y_{1} * \cdots * y_{m}\right)=\frac{1}{m!} \sum_{\sigma \in H} \prod_{i=1}^{m}\left(x_{i}, y_{\sigma(i)}\right) \tag{25}
\end{equation*}
$$

Set $H=S_{p} \times S_{p}^{\prime}$ (direct product) and define $\varphi \in M_{m}(V, H, R)$ by

$$
\begin{equation*}
\varphi\left(x_{1}, \cdots, x_{p}, x_{p+1}, \cdots, x_{m}\right)=\left(x_{1} * \cdots * x_{p}, x_{p+1} * \cdots * x_{m}\right) \tag{26}
\end{equation*}
$$

Clearly $\varphi$ is symmetric with respect to $H$ and

$$
\begin{aligned}
\varphi(x, \cdots, x, x, \cdots, x) & =\|x * \cdots * x\|^{2} \\
& \geqq 0 .
\end{aligned}
$$

Moreover $x * \cdots * x=0$ if and only if $x=0$ [2]. Hence $\varphi$ is positive definite. Now suppose that $\varphi \in P(H, T)$ where $T: V \rightarrow V$. Then

$$
\varphi\left(T x_{1}, \cdots, T x_{p}, T x_{p+1}, \cdots, T x_{m}\right)=\varphi\left(x_{1}, \cdots, x_{m}\right)
$$

and from (26) we have

$$
\begin{equation*}
\left(T x_{1} * \cdots * T x_{p}, T x_{p+1} * \cdots * T x_{m}\right)=\left(x_{1} * \cdots * x_{p}, x_{p+1} * \cdots * x_{m}\right) \tag{27}
\end{equation*}
$$

It follows from (27) that

$$
\begin{equation*}
K\left(T^{*} T\right)=I \tag{28}
\end{equation*}
$$

where $T^{*}$ is the adjoint of $T$ and $K(T)$ is the induced transformation in the symmetry class $V^{p}\left(S_{p}\right)$. It is not difficult to show [7] that (28) implies that $T^{*} T=\omega I_{v}$ where $|\omega|=1$. However, since $T^{*} T$ is positive definite, $T^{*} T=I_{V}$, and hence $T$ is orthogonal. It follows that $T$ must have linear elementary divisors over the complex numbers.

In Theorem 1 we proved only that if $P(H, T)$ is nonempty then $T$ has linear elementary divisors corresponding to real eigenvalues. We conjecture that in fact the preceding example is typical in the sense that $T$ always has linear elementary divisors over the complex numbers if $P(H, T)$ is assumed to be nonempty.

We now give an example to show that if $\varphi \in \mathfrak{H}(H, T)$, but $\varphi$ is not positive definite, then the elementary divisors of $T$ over the complex numbers need not be linear. Let $H=S_{2}$ and let $\operatorname{dim} V=4$. Choose $T$ to have

$$
\left(\lambda^{2}+1\right)^{2}
$$

as its only elementary divisor. Then there exists a real basis $E=$ $\left\{e_{1}, \cdots, e_{4}\right\}$ of $V$ so that

$$
[T]_{E}^{E}=\left[\begin{array}{rrrr}
0 & 0 & 0 & -1 \\
1 & 0 & 0 & 0 \\
0 & 1 & 0 & -2 \\
0 & 0 & 1 & 0
\end{array}\right]
$$

Let $A=[T]_{E}^{E}$. Then from (17) it suffices to determine a symmetric matrix $C$ such that

$$
\begin{equation*}
A^{T} C A=C \tag{29}
\end{equation*}
$$

Define $C$ as follows:

$$
C=\left[\begin{array}{rrrr}
0 & 1 & 0 & -3 \\
1 & 0 & 1 & 0 \\
0 & 1 & 0 & 1 \\
-3 & 0 & 1 & 0
\end{array}\right]
$$

Then $C$ is symmetric (but not positive definite) and (29) is easily
verified. This example also shows that $P(H, T)$ is empty. It is routine to verify that $\operatorname{dim} \mathfrak{U}(H, T)=1$ in this case but the formula (5) produces the integer 4.

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