# ON FUNCTIONAL EQUATIONS CONNECTED WITH <br> DIRECTED DIVERGENCE, INACCURACY AND GENERALIZED DIRECTED DIVERGENCE 

Pl. Kannappan and C. T. Ng


#### Abstract

The measures directed divergence, inaccuracy as well as generalized directed divergence occurring in information theory can be characterized by the symmetry, expansibility, branching, and additivity properties together with some regularity and initial conditions. In this paper some functional equations generalizing those implicit in these characterizations shall be treated.


1. Introduction. Let $\Delta_{n}=\left\{P=\left(p_{1}, p_{2}, \cdots, p_{n}\right) \mid p_{i} \geqq 0\right.$ and $\left.\sum_{i=1}^{n} p_{i}=1\right\}$ and $\Delta_{n}^{\prime}=\left\{P=\left(p_{1}, p_{2}, \cdots, p_{n}\right) \mid p_{i}>0\right.$ and $\left.\sum_{i=1}^{n} p_{i} \leqq 1\right\}$ be the set of all finite complete and incomplete probability distributions respectively. In 1948 C. E. Shannon [16] introduced the following measure of information

$$
\begin{equation*}
H_{n}(P)=-\sum_{i=1}^{n} p_{i} \log p_{i} \tag{1.1}
\end{equation*}
$$

on $\Delta_{n}$ which is now known as Shannon's entropy. This has been generalized to inaccuracy [10]. Inaccuracy and the related quantities directed divergence or information gain $[11,15]$ and generalized directed divergence [3] are given by

$$
\begin{align*}
& H_{n}(P \| Q)=-\sum_{i=1}^{n} p_{i} \log q_{i}, \quad\left(P \in \Delta_{n}, Q \in \Delta_{n} \text { or } \Delta_{n}^{\prime}\right),  \tag{1.2}\\
& I_{n}(P \| Q)=\sum_{i=1}^{n} p_{i} \log \frac{p_{i}}{q_{i}}, \quad\left(P \in \Delta_{n}, Q \in \Delta_{n} \text { or } \Delta_{n}^{\prime}\right), \tag{1.3}
\end{align*}
$$

and

$$
\begin{equation*}
D_{n}(P \| Q \mid R)=\sum_{i=1}^{n} p_{i} \log \frac{q_{2}}{r_{i}}, \quad\left(P \in \Delta_{n}, Q, R \in \Delta_{n} \text { or } \Delta_{n}^{\prime}\right) \tag{1.4}
\end{equation*}
$$

respectively. While characterizing these measures we come across the following functional equations

$$
\begin{align*}
& \sum_{i=1}^{n} \sum_{j=1}^{m} F\left(p_{i} q_{j}\right)=\sum_{i=1}^{n} F\left(p_{i}\right)+\sum_{j=1}^{m} F\left(q_{j}\right), \quad\left(P \in \Delta_{n}, Q \in \Delta_{m}\right)  \tag{1.5}\\
& \sum_{i=1}^{n} \sum_{j=1}^{m} F\left(p_{i} q_{j}, x_{i} y_{j}\right)=\sum_{i=1}^{n} F\left(p_{i}, x_{i}\right)+\sum_{j=1}^{m} F\left(q_{j}, y_{j}\right),  \tag{1.6}\\
& \quad\left(P \in \Delta_{n}, Q \in \Delta_{m}, X \in \Delta_{n} \text { or } \Delta_{n}^{\prime}, Y \in \Delta_{m} \text { or } \Delta_{m}^{\prime}\right)
\end{align*}
$$

and

$$
\begin{align*}
\sum_{i=1}^{n} \sum_{j=1}^{m} F\left(p_{\imath} q_{j}, x_{\imath} y_{j}, u_{\imath} v_{j}\right) & =\sum_{i=1}^{n} F\left(p_{i}, x_{i}, u_{\imath}\right)+\sum_{j=1}^{m} F\left(q_{j}, y_{j}, v_{j}\right)  \tag{1.7}\\
& \left(P \in \Delta_{n}, Q \in \Delta_{m}, X, U \in \Delta_{n} \text { or } \Delta_{n}^{\prime}, Y, V \in \Delta_{m} \text { or } \Delta_{m}^{\prime}\right)
\end{align*}
$$

(cf. [2], [4], [5], [6], [7], [8], [9], [13]).
For the motivation to consider (1.6) and (1.7) and the application of this result, refer to the Remark at the end of this paper.

In this paper we consider the functional equation

$$
\begin{align*}
& \sum_{i=1}^{2} \sum_{j=1}^{3} F_{i j}\left(p_{i} q_{j}, x_{2} y_{2}\right)=\sum_{i=1}^{2} G_{2}\left(p_{i}, x_{2}\right)+\sum_{j=1}^{3} H_{j}\left(q_{j}, y_{j}\right)  \tag{1.8}\\
&\left(P \in \Delta_{2}, Q \in \Delta_{3}, X \in \Delta_{2}^{\prime}, Y \in \Delta_{3}^{\prime}\right)
\end{align*}
$$

for unknown functions $F_{i, j}, G_{i}, H_{j}$. Then this gives the measurable solutions of (1.6) for all $P \in \Delta_{2}, Q \in \Delta_{3}, X \in \Delta_{2}^{\prime}, Y \in \Delta_{3}^{\prime}$ as a special case. The measurable solution of (1.7) for $P \in \Delta_{2}, Q \in \Delta_{3}, X, U \in \Delta_{2}^{\prime}, Y, V \in \Delta_{3}^{\prime}$ can also be obtained by a reduction to (1.8).

In solving (1.8) we make use of the following result of C. T. Ng [13]:

THEOREM 1.1. The measurable solutions of the functional equation

$$
\begin{equation*}
\sum_{i=1}^{2} \sum_{j=1}^{3} F_{i, j}\left(p_{2} q_{j}\right)=\sum_{i=1}^{2} G_{i}\left(p_{2}\right)+\sum_{j=1}^{3} H_{j}\left(q_{j}\right), \tag{1.9}
\end{equation*}
$$

for all $P \in \Delta_{2}, Q \in \Lambda_{3}$, are given by

$$
\left\{\begin{align*}
H_{1}(q)= & a q \log q+b_{1} q+c_{1}, H_{2}(q)=a q \log q+\left(b_{1}+d\right) q+c_{4}  \tag{1.10}\\
H_{3}(q)= & a q \log q+\left(b_{1}+e\right) q+c_{7}, F_{11}(p)=a p \log p+b_{2} p+c_{2} \\
F_{12}(p)= & a p \log p+\left(b_{2}+d\right) p+c_{5}, \\
F_{1,3}(p)= & a p \log p+\left(b_{2}+e\right) p+c_{8}, \\
F_{2,1}(p)= & a p \log p+b_{3} p+c_{3}, F_{22}(p)=a p \log p+\left(b_{3}+d\right) p+c_{6} \\
F_{2,3}(p)= & a p \log p+\left(b_{3}+e\right) p+c_{9}, G_{1}(p)=g(p), \\
G_{2}(p)= & -g(1-p)+a[p \log p+(1-p) \log (1-p)] \\
& +\left(b_{3}-b_{2}\right) p+\left(b_{2}-b_{1}\right)-c_{1}+c_{2}+c_{3}-c_{4}+c_{5}+c_{6} \\
& -c_{7}+c_{8}+c_{9},
\end{align*}\right.
$$

where $a, b_{1}, b_{2}, b_{3}, c_{1}, c_{2}, \cdots, c_{9}, d, e$ are arbitrary constants and $g$ is an arbitrary measurable function.
2. Measurable solutions of the functional equations (1.6) and (1.8). We first suppose that equation (1.8) is to hold for all $P \in \Delta_{2}$, $Q \in \Delta_{3}, X \in \Delta_{2}^{\prime}, Y \in \Delta_{3}^{\prime}$, where $\left.F_{i, j}, G_{i}, H_{j}:[0,1] \times\right] 0,1[\rightarrow R$ are functions measurable in their first variables.

For arbitrarily fixed $x_{i}, y_{j}$ in $] 0,1\left[\right.$ with $\sum_{i=1}^{2} x_{i} \leqq 1, \sum_{j=1}^{3} y_{j} \leqq 1$, equation (1.8) is of the form (1.9) in the $p_{i}$ 's and $q_{j}$ 's. Therefore, by Theorem 1.1 there exist 'constants' $a\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right), b_{i}\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right)$, $i=1,2,3, c_{j}\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right), j=1,2, \cdots, 9, d\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right), e\left(x_{1}, x_{2}\right.$, $\left.y_{1}, y_{2}, y_{3}\right)$ and a measurable function $g\left(\cdot, x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right)$ such that

$$
\begin{align*}
& \left\{\begin{aligned}
G_{1}\left(p, x_{1}\right)= & g\left(p, x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right), \\
G_{2}\left(p, x_{2}\right)= & -g\left(1-p, x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right)+a\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right)[p \log p \\
& +(1-p) \log (1-p)]+\left(b_{3}-b_{2}\right)\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right) p \\
& +\left(b_{2}-b_{1}-c_{1}+c_{2}+c_{3}-c_{4}+c_{5}+c_{6}-c_{7}+c_{8}\right. \\
& \left.+c_{9}\right)\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right) .
\end{aligned}\right. \tag{2.2}
\end{align*}
$$

From (2.1) we get

$$
\begin{equation*}
a\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right) \equiv \mathrm{constant}=a \tag{2.3}
\end{equation*}
$$

and

$$
\left\{\begin{array}{l}
b_{1}\left(x, x_{2}, y_{1}, y_{2}, y_{3}\right) \equiv \text { a function of } y_{1} \text { only }=b_{1}\left(y_{1}\right),  \tag{2.4}\\
b_{1}\left(y_{1}\right)+d\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right) \equiv \text { a function of } y_{2}=\theta_{1}\left(y_{2}\right), \\
b_{1}\left(y_{1}\right)+e\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right) \equiv \text { a function of } y_{3}=\phi_{1}\left(y_{3}\right), \\
b_{2}\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right) \equiv \text { a function of } x_{1} y_{1}=b_{2}\left(x_{1} y_{1}\right),
\end{array}\right.
$$

(2.4) $\left\{\begin{array}{l}b_{2}\left(x_{1} y_{1}\right)+d\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right) \equiv \text { a function of } x_{1} y_{2}=\theta_{2}\left(x_{1} y_{2}\right), \\ b_{2}\left(x_{1} y_{1}\right)+e\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right) \equiv \text { a function of } x_{1} y_{3}=\phi_{2}\left(x_{1} y_{3}\right), \\ b_{3}\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right) \equiv \text { a function of } x_{2} y_{1}=b_{3}\left(x_{2} y_{1}\right), \\ b_{3}\left(x_{2} y_{1}\right)+d\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right) \equiv \text { a function of } x_{2} y_{2}=\theta_{3}\left(x_{2} y_{2}\right), \\ b_{3}\left(x_{2} y_{1}\right)+e\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right) \equiv \text { a function of } x_{2} y_{3}=\phi_{3}\left(x_{2} y_{3}\right),\end{array}\right.$
where $x_{i}, y_{j}$ are in $] 0,1\left[\right.$ with $\sum_{i=1}^{2} x_{i} \leqq 1$ and $\sum_{j=1}^{3} y_{j} \leqq 1$. Similarly

$$
\left\{\begin{array}{l}
c_{1}\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right)=c_{1}\left(y_{1}\right),  \tag{2.5}\\
c_{2}\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right)=c_{2}\left(x_{1} y_{1}\right), \\
c_{3}\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right)=c_{3}\left(x_{2} y_{1}\right), \\
c_{4}\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right)=c_{4}\left(y_{2}\right), \\
c_{5}\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right)=c_{5}\left(x_{1} y_{2}\right), \\
c_{6}\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right)=c_{6}\left(x_{2} y_{2}\right), \\
c_{7}\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right)=c_{7}\left(y_{3}\right), \\
c_{8}\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right)=c_{8}\left(x_{1} y_{3}\right), \\
c_{9}\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right)=c_{9}\left(x_{2} y_{3}\right),
\end{array}\right.
$$

where $x_{i}, y_{j}$ are in ]0, 1 with $\sum_{i=1}^{2} x_{i} \leqq 1$ and $\sum_{j=1}^{3} y_{j} \leqq 1$.
The simultaneous equations (2.4) are equivalent to

$$
\left\{\begin{align*}
d\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right) & =\theta_{1}\left(y_{2}\right)-b_{1}\left(y_{1}\right)=\theta_{2}\left(x_{1} y_{2}\right)-b_{2}\left(x_{1} y_{1}\right)  \tag{2.6}\\
& =\theta_{3}\left(x_{2} y_{2}\right)-b_{3}\left(x_{2} y_{2}\right) \\
e\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right) & =\phi_{1}\left(y_{3}\right)-b_{1}\left(y_{1}\right)=\phi_{2}\left(x_{1} y_{3}\right)-b_{2}\left(x_{1} y_{1}\right) \\
& =\phi_{3}\left(x_{2} y_{3}\right)-b_{3}\left(x_{2} y_{1}\right)
\end{align*}\right.
$$

where $x_{i}, y_{j}$ are in $] 0,1\left[\right.$ with $x_{1}+x_{2} \leqq 1, y_{1}+y_{2}+y_{3} \leqq 1$.
We shall give the general solutions of equation (2.6) through the following lemma.

Lemma 2.1. The general solutions of the functional equation

$$
\begin{equation*}
f(r s)-g(r t)=h(s)-k(t) \tag{2.7}
\end{equation*}
$$

for all $r, s, t \in] 0,1[$ with $s+t \leqq 1$, are given by

$$
\left\{\begin{array}{l}
f(x)=\psi(x)+A  \tag{2.8}\\
g(x)=\psi(x)+A+C \\
h(x)=\psi(x)+B \\
k(x)=\psi(x)+B+C
\end{array}\right.
$$

for all $x \in] 0,1[$, where $A, B, C$ are constants and $\psi:] 0, \infty[\rightarrow \boldsymbol{R}$ (reals)
is a solution of the Cauchy equation,

$$
\begin{equation*}
\psi(r s)=\psi(r)+\dot{\psi}(s) \tag{2.9}
\end{equation*}
$$

Proof. We rewrite equation (2.7) as

$$
\begin{equation*}
f(r s)-h(s)=g(r t)-k(t) \tag{2.10}
\end{equation*}
$$

for all $r, s, t \in] 0,1[$ with $s+t \leqq 1$. Thus $f(r s)-h(s)$ is a function of $r$ only, say

$$
\begin{equation*}
f(r s)-h(s)=l(r) \tag{2.11}
\end{equation*}
$$

for all $r, s \in] 0,1[$. Thus by $[11, \mathrm{p} .59]$ there exists $\psi:] 0, \infty[\rightarrow \boldsymbol{R}$ satisfying

$$
\begin{equation*}
\psi(r s)=\psi(r)+\psi(s) \tag{2.9}
\end{equation*}
$$

for all $r, s \in] 0, \infty[$ such that it represents $f, h$, and $l$ through the equations

$$
\left\{\begin{array}{l}
f(x)=\psi(x)+A  \tag{2.12}\\
h(x)=\psi(x)+B \\
l(x)=\psi(x)+A-B
\end{array}\right.
$$

for all $x \in] 0,1[$, where $A$ and $B$ are arbitrary constants. Similarly $g$ and $k$ are given by

$$
\left\{\begin{array}{l}
g(x)=\psi(x)+A+C,  \tag{2.13}\\
k(x)=\psi(x)+B+C,
\end{array}\right.
$$

for all $x \in] 0,1[$ and where $C$ is an arbitrary constant. This completes the proof of Lemma 2.1.

Thus the general solution of the equations (2.6) is given by

$$
\begin{cases}b_{2}(x)=\psi(x)+A_{i}, & i=1,2,3  \tag{2.14}\\ \theta_{i}(x)=\psi(x)+A_{i}+B, & i=1,2,3 \\ \phi_{i}(x)=\psi(x)+A_{2}+C, & i=1,2,3\end{cases}
$$

for all $x \in] 0,1\left[\right.$, where $A_{i}, B, C$ are constants and $\psi$ is a solution of the Cauchy equation (2.9).

Now we shall determine the function $g$ and the 'constants' $c_{i}$ 's in equation (2.2). We prepare our result by the following lemma.

Lemma 2.2. Let $\left.k_{i}:\right] 0,1[\rightarrow \boldsymbol{R}, i=1,2,3$ be functions satisfying the functional equation

$$
\begin{equation*}
k_{1}(r)+k_{2}(r s)+k_{3}(r t)=T(s, t) \tag{2.15}
\end{equation*}
$$

for all $r, s, t \in] 0,1[$ with $s+t \leqq 1$. Then, and only then, there exist functions $\psi, \dot{\phi}:] 0, \infty[\rightarrow \boldsymbol{R}$ which are solutions of (2.9) and constants $A, B, C$ such that

$$
\left\{\begin{array}{l}
k_{1}(x)=-\psi(x)-\phi(x)+C  \tag{2.16}\\
k_{2}(x)=\psi(x)+A \\
k_{3}(x)=\phi(x)+B
\end{array}\right.
$$

Proof. As the right side of (2.15) is independent of $r$, we have

$$
\begin{equation*}
k_{1}(r)+k_{2}(r s)+k_{3}(r t)=k_{1}\left(r^{\prime}\right)+k_{2}\left(r^{\prime} s\right)+k_{3}\left(r^{\prime} t\right), \tag{2.17}
\end{equation*}
$$

for all $\left.r, r^{\prime}, s, t \in\right] 0,1\left[\right.$ with $s+t \leqq 1$. For arbitrary $\left.s, s^{\prime} \in\right] 0,1[$ we can choose $t \in] 0,1\left[\right.$ such that $s+t, s^{\prime}+t \leqq 1$ and thus from (2.17) we get

$$
\begin{equation*}
k_{2}(r s)-k_{2}\left(r^{\prime} s\right)=k_{2}\left(r s^{\prime}\right)-k_{2}\left(r^{\prime} s^{\prime}\right) \tag{2.18}
\end{equation*}
$$

for all $\left.r, r^{\prime}, s, s^{\prime} \in\right] 0,1\left[\right.$. We can now fix $r^{\prime}$ and $s^{\prime}$ arbitrarily and then equation (2.18) reduces to

$$
\begin{equation*}
k_{2}(r s)=l_{1}(r)+l_{2}(s) \tag{2.19}
\end{equation*}
$$

for all $r, s \in] 0,1\left[\right.$, (for some functions $l_{i}$ ), which is an equation similar to (2.11). Thus there exists a function $\psi:] 0, \infty[\rightarrow R$ satisfying (2.9) such that

$$
k_{2}(x)=\psi(x)+A
$$

for all $x \in] 0,1[$, where $A$ is a constant. Similarly there exists $\phi:] 0, \infty[\rightarrow \boldsymbol{R}$ satisfying (2.9) such that

$$
k_{3}(x)=\phi(x)+B
$$

for all $x \in] 0,1\left[\right.$. If we replace $k_{2}, k_{3}$ by $\psi, \phi$ respectively in equation (2.17) while fixing $r^{\prime}$ we get $k_{1}$ as is in (2.16). This proves our lemma.

From equation (2.2), we see that $g$ is a function of $p$ and $x_{1}$ only, say

$$
\begin{equation*}
g\left(p, x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right)=g\left(p, x_{1}\right) \tag{2.20}
\end{equation*}
$$

Now, from equation (2.2), we see that $-c_{1}\left(y_{1}\right)+c_{2}\left(x_{1} y_{1}\right)+c_{3}\left(x_{2} y_{1}\right)$ is independent of $y_{1}$ and therefore by Lemma 2.2 we have

$$
\left\{\begin{array}{l}
c_{1}(x)=\psi_{1}(x)+\phi_{1}(x)+D_{1}  \tag{2.21}\\
c_{2}(x)=\psi_{1}(x)+E_{1} \\
c_{3}(x)=\phi_{1}(x)+F_{1}
\end{array}\right.
$$

for all $x \in] 0,1\left[\right.$, where $\psi_{1}$ and $\phi_{1}$ are solutions of the equation (2.9) and $D_{1}, E_{1}, F_{1}$ are arbitrary constants. Similarly we have

$$
\left\{\begin{array}{l}
c_{4}(x)=\psi_{2}(x)+\phi_{2}(x)+D_{2}  \tag{2.22}\\
c_{5}(x)=\psi_{2}(x)+E_{2} \\
c_{6}(x)=\phi_{2}(x)+F_{2} \\
c_{7}(x)=\psi_{3}(x)+\phi_{3}(x)+D_{3} \\
c_{8}(x)=\psi_{3}(x)+E_{3} \\
c_{9}(x)=\phi_{3}(x)+F_{3}
\end{array}\right.
$$

where $\psi_{2}, \phi_{2}, \psi_{3}, \phi_{3}$ are solutions of (2.9) again. If we replace the $c_{i}$ ' $s$ in the second equation of (2.2) by equations (2.20), (2.21), and (2.22) we see that $-g\left(1-p, x_{1}\right)-\psi\left(x_{1}\right) p+\psi\left(x_{1}\right)+\psi_{1}\left(x_{1}\right)+\psi_{2}\left(x_{1}\right)+\psi_{3}\left(x_{1}\right)$ is independent of $x_{1}$, say

$$
\begin{align*}
g\left(1-p, x_{1}\right)= & g(1-p)-\psi\left(x_{1}\right) p+\psi\left(x_{1}\right)  \tag{2.23}\\
& +\psi_{1}\left(x_{1}\right)+\psi_{2}\left(x_{1}\right)+\psi_{3}\left(x_{1}\right)
\end{align*}
$$

for all $p \in[0,1]$ and $\left.x_{1} \in\right] 0,1[$, where $g:[0,1] \rightarrow \boldsymbol{R}$ is an arbitrary measurable function.

Combining equations (2.1), (2.2), (2.3), (2.4), (2.5), (2.14), (2.21), (2.22), and $(2.23)$ we are ready to conclude the following theorem.

Theorem 2.1. Let $\left.F_{i j}, G_{i}, H_{j}:[0,1] \times\right] 0,1[\rightarrow \boldsymbol{R}(i=1,2, j=$ $1,2,3)$ be functions which are measurable in their first variables. Then these functions satisfy the functional equation (1.8) if and only if there exist $\left.\dot{\psi}, \psi_{2}, \dot{\phi}_{2}:\right] 0, \infty[\rightarrow \boldsymbol{R}$ all satisfy the Cauchy equation (2.9) such that

$$
\left\{\begin{align*}
H_{1}(q, y)= & a q \log q+\left[\psi(y)+A_{1}\right] q+\psi_{1}(y)+\phi_{1}(y)+D_{1},  \tag{2.24}\\
H_{2}(q, y)= & a q \log q+\left[\psi(y)+A_{1}+B\right] q+\psi_{2}(y)+\dot{\phi}_{2}(y)+D_{2}, \\
H_{3}(q, y)= & a q \log q+\left[\psi(y)+A_{1}+c\right] q+\psi_{3}(y)+\phi_{3}(y)+D_{3}, \\
F_{1,1}(p, y)= & a p \log p+\left[\psi(y)+A_{2}\right] p+\psi_{1}(y)+E_{1}, \\
F_{1,2}(p, y)= & a p \log p+\left[\psi(y)+A_{2}+B\right] p+\psi_{2}(y)+E_{2}, \\
F_{1,3}(p, y)= & a p \log p+\left[\psi(y)+A_{2}+c\right] p+\psi_{3}(y)+E_{3}, \\
F_{2,1}(p, y)= & a p \log p+\left[\psi(y)+A_{3}\right] p+\phi_{1}(y)+F_{1}, \\
F_{2,2}(p, y)= & a p \log p+\left[\psi(y)+A_{3}+B\right] p+\phi_{2}(y)+F_{2}, \\
F_{2,3}(p, y)= & a p \log p+\left[\psi(y)+A_{3}+c\right] p+\phi_{3}(y)+F_{3}, \\
G_{1}(p, x)= & g(p)+\psi(x) p+\psi_{1}(x)+\psi_{2}(x)+\psi_{3}(x), \\
G_{2}(p, x)= & -g(1-p)+a[p \log p+(1-p) \log (1-p)] \\
& +\left[\psi(x)+A_{3}-A_{2} p+\phi_{1}(x)+\phi_{2}(x)+\phi_{3}(x)+A_{2}\right. \\
& -A_{1}-D_{1}-D_{2}-D_{3}+E_{1}+E_{2}+E_{3}+F_{1}+F_{2}+F_{3},
\end{align*}\right.
$$

for all $p, q \in[0,1], x, y \in] 0,1\left[\right.$, where $a, A_{\imath}, B, c, D_{i}, E_{i}, F_{\imath}, i=1,2,3$, are all constants, and $g$ is an arbitrary measurable function.

Theorem 2.2. If $F:[0,1] \times] 0,1[\rightarrow \boldsymbol{R}$ is measurable in its first variable, then it satisfies the functional equation (1.6) for all $P \in \Delta_{2}$, $Q \in \Delta_{3}, X \in \Delta_{2}^{\prime}, Y \in \Delta_{3}^{\prime}$ if and only if $F$ is of the form

$$
\begin{equation*}
F(p, x)=a p \log p+[\psi(x)+A] p, \tag{2.25}
\end{equation*}
$$

for all $p \in[0,1], x \in] 0,1[$, where ir is a solution of the Cauchy equation (2.9) and $a, A$ are constants.
3. On the measurable solutions of the functional equation (1.7). Let $F:[0,1] \times] 0,1[\times] 0,1[\rightarrow \boldsymbol{R}$ be measurable in its first variable and satisfy the equation (1.7) for all $P \in \Delta_{2}, Q \in \Delta_{3}, X, U \in \Delta_{2}^{\prime}$, $Y, V \in \Delta_{3}^{\prime}$.

For each fixed $u_{\imath}, v_{j}$ equation (1.7) reduces to the form (1.8). Thus by Theorem 2.1 there exist in particular $\psi, \psi_{1}, \psi_{2}, \phi_{1}, \phi_{2}$ satisfying the Cauchy equation (2.9) in their first variables and $A_{1}, A_{2}, A_{3}, a, B, D_{1}$, $D_{2}, E_{1}, E_{2}, F_{1}$ such that

$$
\left\{\begin{align*}
F\left(q, y, v_{1}\right)= & a\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right) q \log q+\left[\psi\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)\right. \\
& \left.+A_{1}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)\right] q+\left(\psi_{1}+\phi_{1}\right)\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right) \\
& +D_{1}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right), \\
F\left(q, y, v_{2}\right)= & a\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right) q \log q+\left[\psi\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)\right. \\
& \left.+\left(A_{1}+B\right)\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)\right] q+\left(\psi_{2}+\phi_{2}\right)  \tag{3.1}\\
& \left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)+D_{2}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right), \\
F\left(q, y, u_{1} v_{1}\right)= & a\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right) q \log q+\left[\psi\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)\right. \\
& \left.+A_{2}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)\right] q+\psi_{1}\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right) \\
& +E_{1}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right), \\
F\left(q, y, u_{1} v_{2}\right)= & a\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right) q \log q+\left[\psi\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)\right. \\
& \left.+\left(A_{2}+B\right)\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)\right] q \\
& +\psi_{2}\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)+E_{2}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right), \\
F\left(q, y, u_{2} v_{1}\right)= & a\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right) q \log q+\left[\psi\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)\right.  \tag{3.2}\\
& \left.+A_{3}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)\right] q+\phi_{1}\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right) \\
& +F_{1}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right) . \\
a\left(u_{1},\right. & \left.u_{2}, v_{1}, v_{2}, v_{3}\right) \equiv a \operatorname{constant}=a .
\end{align*}\right.
$$

Hence it follows that

$$
\begin{align*}
& \psi\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)+A_{1}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)  \tag{3.3}\\
& \quad \equiv a \text { function of } y \text { and } v_{1} \text { only }=\theta\left(y, v_{1}\right),
\end{align*}
$$

$$
\begin{align*}
& \dot{\psi}\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)+A_{1}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)+B\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)=\theta\left(y, v_{2}\right),  \tag{3.4}\\
& \quad \psi\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)+A_{2}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)=\theta\left(y, u_{1} v_{1}\right) \\
& \quad \psi\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)+A_{2}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)+B\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right) \\
& \quad=\theta\left(y, u_{1} v_{2}\right) .
\end{align*}
$$

From equations (3.3) to (3.6) we have

$$
\begin{equation*}
\theta\left(y, v_{2}\right)-\theta\left(y, v_{1}\right)=\theta\left(y, u_{1} v_{2}\right)-\theta\left(y, u_{1} v_{1}\right) \tag{3.7}
\end{equation*}
$$

and

$$
\begin{equation*}
A_{2}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)-A_{1}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)=\theta\left(y, u_{1} v_{1}\right)-\theta\left(y, v_{1}\right) . \tag{3.8}
\end{equation*}
$$

For (3.7), by Lemma 2.1 there exists, for each fixed $y$, a function $\theta_{1}(\cdot, y)$ satisfying the Cauchy equation (2.9) and a constant $\theta_{2}(y)$ such that, we have

$$
\begin{equation*}
\theta(y, v)=\theta_{1}(v, y)+\theta_{2}(y) \tag{3.9}
\end{equation*}
$$

Now equations (3.8) and (3.9) yield

$$
\begin{equation*}
\theta_{1}(v, y) \equiv \text { a function of } v \text { alone }=\theta_{1}(v) \tag{3.10}
\end{equation*}
$$

Thus we can rewrite the first equation of (3.1) as

$$
\begin{align*}
F\left(q, y, v_{1}\right)= & a q \log q+\left[\theta_{1}\left(v_{1}\right)+O_{2}(y)\right] q  \tag{3.11}\\
& +\left(\psi_{1}+\phi_{1}\right)\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)+D_{1}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)
\end{align*}
$$

From (3.11) we see that $\left(\psi_{1}+\phi_{1}\right)\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)+D_{1}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)$ depends on $y$ and $v_{1}$ only. Since $\dot{\psi}_{1}, \dot{\varphi}_{1}$ satisfy the Cauchy equation (2.9), $\left(\dot{\psi}_{1}+\dot{\varphi}_{1}\right)\left(y, u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)$ and $D_{1}\left(u_{1}, u_{2}, v_{1}, v_{2}, v_{3}\right)$ depend on $\left(y, v_{1}\right)$ and $v_{1}$ only respectively. Thus we can write (3.11) in the form

$$
\begin{align*}
F(q, y, v)= & a q \log q+\left[\theta_{1}(v)+\theta_{2}(y)\right] q \\
& +\alpha_{1}(y, v)+\alpha_{2}(v) \tag{3.12}
\end{align*}
$$

where $\theta_{1}$ and $\alpha_{1}(\cdot, v)$ satisfy the Cauchy equation (2.9).
From the first, third, and fifth equations of (3.1) and (3.12) we have

$$
\alpha_{1}\left(y, v_{1}\right)=\alpha_{1}\left(y, u_{1} v_{1}\right)+\alpha_{1}\left(y, u_{2} v_{1}\right)
$$

for all $\left.u_{1}, u_{2}, v_{1} \in\right] 0,1\left[\right.$ with $u_{1}+u_{2} \leqq 1$. Hence $\alpha_{1}$ is independent of the second variable and we may write the equation (3.12) as

$$
\begin{equation*}
F(q, y, v)=a q \log q+\left[\theta_{1}(v)+\theta_{2}(y)\right] q+\alpha_{1}(y)+\alpha_{2}(v) \tag{3.13}
\end{equation*}
$$

for all $q \in[0,1], y, v \in] 0,1\left[\right.$ where $\theta_{1}$ and $\alpha_{1}$ are solutions of the Cauchy
equation (2.9). If we interchange the roles of the second and the third arguments of $F$ in the above procedure we see that $\theta_{2}, \alpha_{2}$ are also solutions of the Cauchy equation (2.9).

Substituting (3.13) into (1.7), taking into account that $\theta_{i}, \alpha_{i}$ are solutions of the Cauchy equation (2.9) we get $\alpha_{i} \equiv 0$. Thus we have proved the following theorem.

Theorem 3.1. Let $F:[0,1] \times] 0,1[\times] 0,1[\rightarrow \boldsymbol{R}$ be measurable in its first variable. Then $F$ satisfies the functional equation (1.7) if and only if $F$ has the form

$$
\begin{equation*}
F(q, y, v)=a q \log q+\left[\theta_{1}(v)+\theta_{2}(y)\right] q \tag{3.14}
\end{equation*}
$$

where $\left.\theta_{1}, \theta_{2}:\right] 0, \infty[\rightarrow \boldsymbol{R}$ satisfy the Cauchy equation (2.9).
Corollary 3.1. Let $F:([0,1] \times] 0,1[\times] 0,1[) \cup\{(0,0,[0,1[)\} \cup$ $\{(1,1] 0,1]),\} \cup\{(0,[0,1[, 0)\} \cup\{(1] 0,1], 1),\} \rightarrow \boldsymbol{R}$ be measurable in its first variable. Then it satisfies the equation (1.7) if and only if $F$ has the form given by (3.14) on $[0,1] \times] 0,1[\times] 0,1[$ and on the boundary $F(0,0, \cdot) \equiv 0, F(1,1, \cdot)=\theta_{1}(\cdot), F(0, \cdot, 0) \equiv 0$ and $F(1, \cdot, 1)=\theta_{2}(\cdot)$.

Remark. The measures $H_{n}, I_{n}, D_{n}$ in (1.2), (1.3), (1.4) possess in particular properties: (a) Symmetry: $H_{n}, I_{n}, D_{n}$ are symmetric in the pairs $\left(p_{i}, q_{i}\right),\left(p_{i}, q_{i}\right),\left(p_{i}, q_{i}, r_{i}\right)$ respectively, (b) Expansibility: If $P=$ $\left(p_{1}, p_{2}, \cdots, p_{n}\right), Q=\left(q_{1}, q_{2}, \cdots, q_{n}\right), R=\left(r_{1}, r_{2}, \cdots, r_{n}\right)$ and $P^{\prime}=\left(p_{1}, p_{2}, \cdots\right.$, $\left.p_{n}, 0\right), Q^{\prime}=\left(q_{1}, q_{2}, \cdots, q_{n}, 0\right), R^{\prime}=\left(r_{1}, r_{2}, \cdots, r_{n}, 0\right)$, then $H_{n}(P \| Q)=$ $H_{n+1}\left(P^{\prime} \| Q^{\prime}\right), I_{n}(P \| Q)=I_{n+1}\left(P^{\prime} \| Q^{\prime}\right)$ and $D_{n}(P \| Q \mid R)=D_{n+1}\left(P^{\prime} \| Q^{\prime} \mid R^{\prime}\right)$, (c) Branching: If $P=\left(p_{1}, p_{2}, \cdots, p_{n}\right), Q=\left(q_{1}, q_{2}, \cdots, q_{n}\right), R=\left(r_{1}, r_{2}\right.$, $\left.\cdots, r_{n}\right)$ and $P^{\prime}=\left(p_{1}+p_{2}, p_{3}, \cdots, p_{n}\right), Q^{\prime}=\left(q_{1}+q_{2}, q_{3}, \cdots, q_{n}\right)$ and $R^{\prime}=\left(r_{1}+r_{2}, r_{3}, \cdots, r_{n}\right)$, then $H_{n}(P \| Q)-H_{n-1}\left(P^{\prime} \| Q^{\prime}\right), I_{n}(P \| Q)-$ $I_{n-1}\left(P^{\prime} \| Q^{\prime}\right)$ and $D_{n}(P \| Q \mid R)-D_{n-1}\left(P^{\prime} \| Q^{\prime} \mid R\right)$ depend on $\left(p_{1}, p_{2}, q_{1}, q_{2}\right)$, ( $p_{1}, p_{2}, q_{1}, q_{2}$ ) and ( $p_{1}, p_{2}, q_{1}, q_{2}, r_{1}, r_{2}$ ) respectively. It is shown by C. T. Ng [14] that these three properties are equivalent to the representability of $H_{n}, I_{n}, D_{n}$ in the form $H_{n}(P \| Q)=\sum_{i=1}^{n} f\left(p_{i}, q_{i}\right)$, $I_{n}(P \| Q)=\sum_{i=1}^{n} g\left(p_{i}, q_{i}\right)$ and $D_{n}(P| | Q \mid R)=\sum_{i=1}^{n} h\left(p_{i}, q_{i}, r_{i}\right)$ where $f$, $g, h$ are any function satisfying $f(0,0)=g(0,0)=h(0,0,0)=0$. From these representations, the additivity property of these measures motivates the study of the functional equations (1.6) and (1.7).

The Theorems 2.2 and 3.1 lead to a characterization of directed divergence and inaccuracy and of generalized directed divergence respectively. These three measures are determined by (a) Symmetry, (b) Expansibility, (c) Branching, (d) Additivity, and (e) Regularity conditions such as Lebesgue measurability and appropriate initial conditions.

## References

1. J. Aczél, Lectures on Functional Equations and Their Applications, Academic Press, New York, 1966.
2. J. Aczél and Z. Daróczy, Charakterisierung der Entropien positiver Ordnung und der Shannonschen Entropie, Acta Math. Acad. Sci. Hungar., 14 (1963), 95-121.
3. J. Aczél and P. Nath, Axiomatic characterization of some measures of divergence in information, Z. Wahrscheinlichkeitstheorie verw. Geb., 21 (1972), 215-224.
4. T. W. Chaundy and J. B. McLeod, On a functional equation, Edinburgh Math. Notes, 43 (1962), 7-8.
5. Z. Daróczy, On the measurable solutions of a functional equation, Acta Math. Acad. Sci. Hungar., 22 (1971), 11-14.
6. Pl. Kannappan, On Shannon's entropy, directed divergence and inaccuracy, Z. Wahrscheinlichkeitstheorie verw. Geb., 22 (1972), 95-100.
7. -, On directed divergence and inaccuracy, Z. Wahrscheinlichkeitstheorie verw. Geb., 25 (1972), 49-55.
8. ——, On generalized directed divergence, Funk. Ekvacioj, 16 (1973), 71-77.
9. ——, On a functional equation connected with generalized directed divergence, Aequationes Math., (to appear).
10. D. F. Kerridge, Inaccuracy and inference, J. Royal Statist. Soc. Ser. B, 23 (1961), 184-194.
11. S. Kullback, Information Theory and Statistics, J. Wiley \& Sons, New York, 1959.
12. J. P. Mokanski, Extensions of functions satisfying Cauchy and Pexider type equations, Ph.D. Thesis, University of Waterloo, 1971.
13. C. T. Ng, On the measurable solutions of the functional equation

$$
\sum_{i=1}^{2} \sum_{j=1}^{3} F_{i, j}\left(p_{i} q_{j}\right)=\sum_{i=1}^{2} G_{i}\left(p_{i}\right)+\sum_{j=1}^{3} H_{j}\left(q_{j}\right)
$$

Acta Math. Acad. Sci. Hungar., 25 (1974).
14. —, Representation of measures of information with the branching property, Information and Control, 25 (1974), 45-56.
15. A. Rényi, On measures of entropy and information, Proc. Fourth Berkeley Sympos. Math. Statistics, Probab., (1960), 547-561.
16. C. E. Shannon, A mathematical theory of communication, Bell System Tech. J., 27 (1948), 378-423 and 623-656.

Received June 15, 1973 and in revised form January 16, 1974. This research is partially supported by NRC of Canada grants.

University of Waterloo

