# GENERATING $O(n)$ WITH REFLECTIONS 

Morris L. Eaton and Michael Perlman

For $r \in C_{n} \equiv\left\{x \mid x \in R^{n},\|x\|=1\right\}$, let $S_{r}=I_{n}-2 r r^{\prime}$ where $r$ is a column vector. $O(n)$ denotes the orthogonal group on $R^{n}$. If $R \subseteq C_{n}$, let $\mathscr{R}=\left\{S_{r} \mid r \in R\right\}$ and let $G$ be the smallest closed subgroup of $O(n)$ which contains $\mathscr{R} . G$ is reducible if there is a nontrivial subspace $M \subseteq R^{n}$ such that $g M \subseteq M$ for all $g \in G$. Otherwise, $G$ is irreducible.

Theorem. If $G$ is infinite and irreducible, then $G=$ $O(n)$.

In what follows, $R^{n}$ denotes Euclidean $n$-space with the standard inner product, $O(n)$ is the orthogonal group of $R^{n}$, and $C_{n}=\left\{x \mid x \in R^{n}\right.$, $\|x\|=1\}$. If $U$ is a subset of $O(n),\langle U\rangle$ denotes the group generated algebraically by $U$ and $\langle\bar{U}\rangle$ denotes the closure of $\langle U\rangle$. Thus, $\langle\bar{U}\rangle$ is the smallest closed subgroup of $O(n)$ containing $U$. For an integer $k, 1 \leqq k<n, M_{k}$ denotes a $k$-dimensional linear subspace of $R^{n}$. If $r \in C_{n}$, let $S_{r}=I-2 r r^{\prime}$ where $r$ is a column vector. Thus $S_{r}$ is a reflection through $r$-henceforth called a reflection.

Suppose $R \subseteq C_{n}$ and let $\mathscr{R}=\left\{S_{r} \mid r \in R\right\}$. Set $G=\langle\overline{\mathscr{R}}\rangle$. The group $G$ is reducible if there is an $M_{k}$ such that $g M_{k} \subseteq M_{k}$ for all $g \in G$; otherwise, $G$ is irreducible. The main result of this note is the following.

Theorem 1. If $G$ is infinite and irreducible, then $G=O(n)$.
Proof of Theorem 1. First note that if $S_{r} \in \mathscr{R}$ and $g \in G$, then $g S_{r} g^{-1}=S_{g r} \in G$. Let $\Delta=\{g r \mid g \in G, r \in R\}$. Thus, $t \in \Delta$ implies that $S_{t} \in G$. Since $G$ is infinite, $\Delta$ must be infinite (see Benson and Grove (1971), Proposition 4.1.3). Since every $\Gamma$ in $O(n)$ is a product of a finite number of reflections, to show that $G=O(n)$, it suffices to show that $G$ is transitive on $C_{n}$ (if $G$ is transitive on $C_{n}$, then $\Delta=C_{n}$ so every reflection is an element of $G$ and hence $G=O(n)$ ).

The proof that $G$ is transitive on $C_{n}$ follows. By Lemma 1 (below), there is a subgroup $K_{2} \subseteq G$ and a subspace $M_{2} \subseteq R^{n}$ such that $k x=x$ if $x \in M_{2}^{\perp}$ and $k \in K_{2}$ and $K_{2}$ is transitive on $D_{2} \equiv M_{2} \cap C_{n}$. Since $G$ is irreducible, there is an $r_{2} \in R$ such that $r_{2} \notin M_{2}$ and $r_{2} \notin M_{2}^{\perp}$. Let $M_{3}=\operatorname{span}\left\{r_{2}, M_{2}\right\}$ and let $K_{3}=\left\langle\left\{K_{2}, S_{r_{2}}\right\}\right\rangle>\subseteq G$. With $D_{3} \equiv M_{3} \cap C_{n}$, Lemma 3 (below) implies that $k x=x$ for all $x \in M_{3}^{\perp}$ and $k \in K_{3}$, and $K_{3}$ is transitive on $D_{3}$. Again, since $G$ is irreducible, there is an $r_{3} \in R$ such that $r_{3} \notin M_{3}$ and $r_{3} \notin M_{3}^{\perp}$. With $M_{4}=\operatorname{span}\left\{r_{3}, M_{3}\right\}$, let $K_{4}=\left\langle\left\{K_{3}, S_{r_{3}}\right\}\right\rangle>\cong G$ and let $D_{4} \equiv M_{4} \cap C_{n}$. By Lemma 3 (below)
$k x=x$ for $x \in M_{4}^{\perp}$ and $k \in K_{4}$ and $K_{4}$ is transitive on $D_{4}$. Applying this argument $(n-2)$ times, we obtain $K_{n} \subseteq G$ and $K_{n}$ is transitive on $D_{n}=C_{n}$. Thus, $G$ is transitive on $C_{n}$ and the proof is complete.

To fill in the gaps in the above argument, it remains to prove Lemmas 1, 2, and 3. Lemma 1 provides the starting point for the stepwise argument used in the proof of Theorem 1.

Lemma 1. If $G$ is irreducible and infinite, there is a subspace $M_{2}$ and a subgroup $K_{2} \subseteq G$ such that $k x=x$ for $x \in M_{2}^{\perp}, k \in K_{2}$ and $K_{2}$ acts transitively on $D_{2} \equiv M_{2} \cap C_{n}$.

Proof. As noted in the proof of Theorem 1, the set $\Delta=\{g r \mid r \in R$, $g \in G\}$ is infinite. Thus, there is a point $\delta_{0} \in C_{n}$ such that every neighborhood of $\delta_{0}$ contains infinitely many points in $\Delta$. Thus we can select a sequence of pairs $\left(r_{i}, t_{i}\right), r_{i}, t_{i} \in \Delta$, such that $r_{i}$ and $t_{i}$ are linearly independent and $1-1 / i<r_{i}^{\prime} t_{i}<r_{i+1}^{\prime} t_{i+1}<1$ for $i=1,2, \cdots$.

For $0 \leqq \eta<2 \pi$, set

$$
\Psi(\eta)=\left(\begin{array}{rr}
\cos \eta & \sin \eta  \tag{1}\\
-\sin \eta & \cos \eta
\end{array}\right) \in O(2)
$$

Define $\theta_{i}$ by $\cos \theta_{i}=r_{i}^{\prime} t_{i}, 0 \leqq \theta_{i}<\pi$ so $\theta_{i} \rightarrow 0$ as $i \rightarrow \infty$. Let $\Gamma_{i} \in O(n)$ have first row $t_{i}^{\prime}$ and second row

$$
\left(r_{i}-t_{i}^{\prime} r_{i} t_{i}\right)^{\prime} /\left\|r_{i}-t_{i}^{\prime} r_{i} t_{i}\right\|
$$

Then an easy calculation shows that

$$
S_{t_{i}} S_{r_{i}}=\Gamma_{i}^{\prime}\left(\begin{array}{cc}
\Psi\left(2 \theta_{i}\right) & 0  \tag{2}\\
0 & I_{n-2}
\end{array}\right) \Gamma_{i}, \quad i=1,2, \cdots
$$

where $I_{n-2}$ is an $(n-2) \times(n-2)$ identity matrix. Setting $H_{i}=$ $\left\langle\Psi\left(2 \theta_{i}\right)\right\rangle \cong O(2)$, it is clear that

$$
\left\{\left.\Gamma_{i}^{\prime}\left(\begin{array}{cc}
h & 0  \tag{3}\\
0 & I_{n-2}
\end{array}\right) \Gamma_{i} \right\rvert\, h \in H_{i}\right\} \subseteq G, \quad i=1,2, \cdots
$$

By selecting an appropriate subsequence, we can assume without loss of generality that $\Gamma_{i} \rightarrow \Gamma_{0} \in O(n)$, as $i \rightarrow \infty$.

If $\Psi(\eta)$ is given by (1), we now claim that

$$
\Gamma_{0}^{\prime}\left(\begin{array}{cc}
\Psi(\eta) & 0  \tag{4}\\
0 & I_{n-2}
\end{array}\right) \Gamma_{0} \in G
$$

Since $G$ is closed and (3) holds, to establish (4), it suffices to show
there is a subsequence $i_{j}$ and $h_{i_{j}} \in H_{i_{j}}$ such that $h_{i_{j}} \rightarrow \Psi(\eta)$ as $i_{j} \rightarrow \infty$. However, the existence of such a sequence is assured since $\theta_{i} \rightarrow 0$ as $i \rightarrow \infty$. Thus (4) holds. Hence we see that

$$
K_{2} \equiv\left\{\left.\Gamma_{0}^{\prime}\left(\begin{array}{cc}
h & 0  \tag{5}\\
0 & I_{n-2}
\end{array}\right) \Gamma_{0} \right\rvert\, h \in H^{*}\right\} \cong G
$$

where $H^{*}$ is the full rotation group of $R^{2}$.
To complete the proof of Lemma 1, let $M_{2}$ be the span of the first two columns of $\Gamma_{0}^{\prime}$. With $D_{2} \equiv M_{2} \cap C_{n}$, it is easy to check that $k x=x$ for all $x \in M_{2}^{\perp}, k \in K_{2}$ and that $K_{2}$ acts transitively on $D_{2}$. This completes the proof.

The following result is used in the proof of Lemma 3.

Lemma 2. For $u_{0} \in(0,1]$, define a function $f:[0,1] \rightarrow[0,1]$ by

$$
f(u)=\left\{\begin{array}{l}
0 \quad \text { if } 0 \leqq u \leqq u_{0}  \tag{6}\\
\left.1-\left[\sqrt{u u_{0}}+\sqrt{(1-u)\left(1-u_{0}\right.}\right)\right]^{2} \text { if } u_{0} \leqq u \leqq 1
\end{array}\right.
$$

Let $v_{1}=f(1)$ and define $v_{i}=f\left(v_{i-1}\right)$ for $i=2,3, \cdots$. Then, there exists an index $i_{0}$ such that $v_{i}=0$ for $i \geqq i_{0}$.

Proof. It is not hard to verify that $f$ is a continuous convex function. Since $0 \leqq v_{1}<1, v_{2}=f\left(v_{1}\right)=f\left(\left(1-v_{1}\right) 0+v_{1} 1\right) \leqq v_{1} f(1)=v_{1}^{2}$. Proceeding by induction, $v_{i} \leqq v_{1}^{i}$ so $\lim _{i \rightarrow \infty} v_{i}=0$. Since $f$ is 0 in the interval $\left[0, u_{0}\right]$, there is an index $i_{0}$ such that $v_{i}=0$ for $i \geqq i_{0}$. This completes the proof.

After establishing Lemma 1 , the key to Theorem 1 is Lemma 3. Although the proof of Lemma 3 is quite long, the geometric idea behind the proof is fairly simple. Consider $R^{3}$ and let $D_{2}=\left\{x \mid x \in R^{3}\right.$, $\left.x_{3}=0, x_{1}^{2}+x_{2}^{2}=1\right\}$. Also, let $H=\left\{\left.\left(\begin{array}{cc}k & 0 \\ 0 & 1\end{array}\right) \right\rvert\, k\right.$ is any rotation of $\left.R^{2}\right\}$. Thus $H$ acts transitively on $D_{2}$. Consider a fixed vector $t \in R^{3}$ with $\|t\|=1$ such that $t$ is not in the $\left(x_{1}, x_{2}\right)$ plane and $t$ is not in the $x_{3}$-line. Let $S_{t}=I-2 t t^{\prime}$ be the reflection across the plane $\{t\}^{\perp}$ and let $\widetilde{H}$ be the group generated by $S_{t}$ and $H$. The claim is that $\widetilde{H}$ is transitive on $D_{3}=\left\{x \mid x \in R^{3},\|x\|=1\right\}$. For example, suppose the angle between $t$ and the $\left(x_{1}, x_{2}\right)$ plane is $45^{\circ}$. Geometrically, it is clear that the set $H\left(S_{t}\left(D_{2}\right)\right) \equiv\left\{x \mid x=h S_{t} u\right.$ for some $h \in H$, and some $\left.u \in D_{2}\right\}$ is just $D_{3}$-that is, $S_{t}\left(D_{2}\right)$ is a circle passing through $\left(\begin{array}{l}0 \\ 1 \\ 0\end{array}\right)$ and the transitivity of $H$ implies that $H$ moves the set $S_{t}\left(D_{2}\right)$ everywhere onto $D_{3}$ (picture this on the surface of a basketball). Thus, given
$v_{1}, v_{2} \in D_{3}, v_{i}=h_{i} S_{t} u_{i}$, for $h_{i} \in H$ and $u_{i} \in D_{2}$ for $i=1$, 2. Since $u_{1}=$ $h_{0} u_{2}$ for some $h_{0} \in H$, it follows that $v_{1}=h_{1} S_{t} h_{0} S_{t} h_{2}^{-1} v_{2}$ so $\tilde{H}$ is transitive on $D_{3}$. For other $t$-vectors, $D_{3}$ does not get covered by one application of $H S_{t}$ to $D_{2}$, but $D_{3}$ is covered by a finite number of applications of $H S_{t}$ to $D_{2}$-that is, $D_{3}=\left(H\left(S_{t}(\cdots) H\right) S_{t}\right)\left(D_{2}\right)$ for some finite string $H S_{t} H S_{t} \cdots H S_{t}$. Again, this implies the transitivity of $\tilde{H}$ on $D_{3}$. Lemma 3 and its proof make all of the above precise.

Lemma 3. Consider a subspace $M_{m} \subseteq R^{n}, 2 \leqq m<n$, and suppose that $K$ is a subgroup of $O(n)$ such that

$$
\left\{\begin{array}{l}
k x=x \text { for all } x \in M_{m}^{\llcorner }, k \in K  \tag{7}\\
K \text { is transitive on } D_{m} \equiv M_{m} \cap C_{n}
\end{array}\right.
$$

Let $t \in C_{n}$ be such that $t \notin M_{m}$ and $t \notin M_{m}^{\perp}$. With $M_{m+1}=\operatorname{span}\left\{t, M_{m}\right\}$, let $D_{m+1} \equiv M_{m+1} \cap C_{n}$. Then the group $K^{*} \cong O(n)$ generated by $K$ and $S_{t}=I-2 t t^{\prime}$ satisfies

$$
\left\{\begin{array}{l}
k x=x \text { for all } x \in M_{m+1}^{\perp}, k \in K^{*}  \tag{8}\\
K^{*} \text { is transitive on } D_{m+1}
\end{array}\right.
$$

Proof. That $k x=x$ for all $x \in M_{m+1}^{\perp}$ and $k \in K^{*}$ is not hard to verify. To establish the transitivity of $K^{*}$ on $D_{m+1}$, define a set $B_{1}$ by (9) $\quad B_{1}=K\left(S_{t}\left(D_{m}\right)\right)=\left\{x \mid x=k S_{t} u\right.$ for some $u \in D_{m}$, some $\left.k \in K\right\}$
and then define $B_{i}$ inductively by
(10) $\quad B_{i}=K\left(S_{t}\left(B_{i-1}\right)\right)=\left\{x \mid x=k S_{t} u\right.$ for some $u \in B_{i-1}$, some $\left.k \in K\right\}$
$i=2,3, \cdots$. Since $K\left(S_{t}\left(D_{m+1}\right)\right) \subseteq D_{m+1}$, it follows that $B_{i} \subseteq D_{m+1}$ for all $i$. The remainder of the proof is devoted to showing that there is an index $i_{0}$ such that $B_{i_{0}}=D_{m+1}$, because this implies the transitivity of $K^{*}$ on $D_{m+1}$.

Claim 1. If $B_{i_{0}}=D_{m+1}$, then $K^{*}$ is transitive on $D_{m+1}$.
Proof of Claim 1. Consider $z_{1}, z_{2} \in D_{m+1}$. If $B_{i_{0}}=D_{m+1}$, then

$$
\underbrace{K\left(S_{t}\left(K\left(S_{t} \cdots\left(D_{m}\right)\right)\right)\right)}_{i_{0} \text {-terms }}=D_{m+1} .
$$

Thus, there exists $k_{1}, \cdots, k_{i_{0}} \in K$ and $g_{1}, \cdots, g_{i_{0}} \in K$ such that

$$
z_{1}=\left[\prod_{j=1}^{i_{0}}\left(k_{j} S_{t}\right)\right] u_{1} \equiv h_{1} u_{1}
$$

and

$$
z_{2}=\left[\prod_{j=1}^{i_{0}}\left(g_{j} s_{t}\right)\right] u_{2} \equiv h_{2} u_{2}
$$

for some $u_{1}, u_{2} \in D_{m}$. Since $K$ is transitive on $D_{m}$, there exists a $k_{0} \in K$ such that $k_{0} u_{1}=u_{2}$. Thus, $z_{2}=h_{2} k_{0} h_{1}^{-1} z_{1}$ which shows that $K^{*}$ is transitive on $D_{m+1}$ as $h_{2} k_{0} h_{1}^{-1} \in K^{*}$. This completes the proof of Claim 1.

We now continue with the proof. Let $P$ denote the orthogonal projection onto $M_{m}$ and define $Z_{c}, 0 \leqq c \leqq 1$ by

$$
\begin{equation*}
Z_{c}=\left\{x \mid x \in D_{m+1},\|P x\|^{2} \geqq c\right\} \tag{11}
\end{equation*}
$$

Note that $Z_{1}=D_{m}$ and $Z_{0}=D_{m+1}$.

Remark. Geometrically, $Z_{c}$ is an equatorial zone (with equator $D_{m}$ ) which partially covers $D_{m+1}$. Smaller values of $c$ correspond to more of $D_{m+1}$ being covered.

Define $\varphi$ on [0,1] by

$$
\begin{equation*}
\varphi(c)=\inf _{x \in Z_{c}}\left\|P S_{t} x\right\|^{2}, \quad 0 \leqq c \leqq 1 \tag{12}
\end{equation*}
$$

and let

$$
\begin{equation*}
b_{1}=\inf _{x \in B_{1}}\|P x\|^{2} . \tag{13}
\end{equation*}
$$

Since each $k \in K$ commutes with $P$, we have

$$
\begin{equation*}
b_{1}=\inf _{k \in K} \inf _{x \in D_{m}}\left\|P k S_{t} x\right\|^{2}=\inf _{x \in D_{m}}\left\|P S_{t} x\right\|^{2}=\inf _{x \in Z_{1}}\left\|P S_{t} x\right\|^{2}=\varphi(1) \tag{14}
\end{equation*}
$$

Claim 2. $\quad B_{1}=Z_{b_{1}}$.
Proof of Claim 2. If $x \in B_{1},\|P x\|^{2} \geqq b_{1}$ which implies that $x \in Z_{b_{1}}$. Conversely, consider $x \in Z_{b_{1}}$ and let $Q$ denote the orthogonal projection onto the one-dimensional subspace $M_{m}^{\perp} \cap M_{m+1}$ which is spanned by the vector $t^{*} \equiv(I-P) t /\|(I-P) t\|$. Since $Z_{c}$ is compact and arcwise connected, the continuous function $u \rightarrow\left\|P S_{t} u\right\|^{2}\left(u \in Z_{c}\right)$ takes on all values between 1 and $\varphi(c)$. As $x \in Z_{b_{1}}$,

$$
\|P x\|^{2} \geqq b_{1}=\varphi(1)=\inf _{u \in D_{m}}\left\|P S_{t} u\right\|^{2}
$$

Hence, there exists a $u \in D_{m}$ such that $\left\|P S_{t} u\right\|^{2}=\|P x\|^{2}$. Thus, $1=$ $\|P x\|^{2}+\|Q x\|^{2}=\left\|P S_{t} u\right\|^{2}+\left\|Q S_{t} u\right\|^{2}$, so $\left\|Q S_{t} u\right\|^{2}=\|Q x\|^{2}$. Since $Q$ is a projection onto a one-dimensional subspace, $u$ can be chosen (by changing to $-u$ if necessary) such that $Q x=Q S_{t} u$. The transitivity of $K$ on $D_{m}$ implies there is a $k \in K$ such that $k P S_{t} u=P x$. Thus,
$k S_{t} u=k P S_{t} u+k Q S_{t} u=P x+k Q S_{t} u=P x+Q S_{t} u=P x+Q x=x$, so $x=k S_{t} u \in B_{1}$. This completes the proof of Claim 2.

Using Claim 2, $B_{2}=K\left(S_{t}\left(B_{1}\right)\right)=K\left(S_{t}\left(Z_{b_{1}}\right)\right)$. Consider

$$
\begin{equation*}
b_{2} \equiv \inf _{x \in B_{2}}\|P x\|^{2} \tag{15}
\end{equation*}
$$

Using (15) and the fact that each $k \in K$ commutes with $P$, we have

$$
\begin{equation*}
b_{2}=\inf _{x \in B_{2}}\|P x\|^{2}=\inf _{x \in Z_{b_{1}}} \inf _{k \in K}\left\|P k S_{t} x\right\|^{2}=\inf _{x \in Z_{b_{1}}}\left\|P S_{t} x\right\|^{2}=\varphi\left(b_{1}\right) \tag{16}
\end{equation*}
$$

Claim 3. $\quad B_{2}=Z_{b_{2}}$.
Proof of Claim 3. If $x \in B_{2}$, then $x \in D_{m+1}$ and $\|P x\|^{2} \geqq b_{2}$, so $x \in Z_{b_{2}}$. Conversely, consider $x \in Z_{b_{2}}$. As $u$ varies over $Z_{b_{1}}$, the function $u \rightarrow\left\|P S_{t} u\right\|^{2}$ takes on all values between 1 and $b_{2}$. Since $\|P x\|^{2} \geqq b_{2}$, there is a $u \in Z_{b_{1}}$ such that $\left\|P S_{t} u\right\|^{2}=\|P x\|^{2}$. As in the proof of Claim 2, $1=\|P x\|^{2}+\|Q x\|^{2}=\left\|P S_{t} u\right\|^{2}+\left\|Q S_{t} u\right\|^{2}$ so $\|Q x\|^{2}=$ $\left\|Q S_{t} u\right\|^{2}$, and we can choose $u$ such that $Q x=Q S_{t} u$. The transitivity of $K$ implies that there is a $k \in K$ such that $k P S_{t} u=P x$. Thus, $x=$ $P x+Q x=k P S_{t} u+Q S_{t} u=k P S_{t} u+k Q S_{t} u=k S_{t} u \in B_{2}$ since $u \in Z_{b_{1}}=B_{1}$. The proof of Claim 3 is complete.

Arguing as in the proof of Claim 3, it is an easy matter to show that $B_{i}=Z_{b_{i}}$ and $b_{i}=\varphi\left(b_{i-1}\right)$ where

$$
\begin{equation*}
b_{i}=\inf _{x \in B_{i}}\|P x\|^{2}, i=3,4, \cdots \tag{17}
\end{equation*}
$$

As noted earlier, the proof of Lemma 3 will be complete if we can show there is an index $i_{0}$ such that $B_{i_{0}}=Z_{0}=D_{m+1}$. To establish the existence of an $i_{0}$, we will explicitly calculate the function $\varphi$ defined in (12) and then apply Lemma 2. Define $z_{0} \in D_{m+1}$ by

$$
\begin{equation*}
z_{0}=S_{t} t^{*} \tag{18}
\end{equation*}
$$

where $t^{*}=(I-P) t /\|(I-P) t\|$. Then,

$$
\begin{align*}
a & \equiv\left\|P z_{0}\right\|^{2}=\frac{\left\|P S_{t}(I-P) t\right\|^{2}}{\|(I-P) t\|^{2}}=\frac{\left\|P\left(I-2 t t^{\prime}\right)(I-P) t\right\|^{2}}{\|(I-P) t\|^{2}} \\
& =\frac{4\|P t\|^{2}\left(t^{\prime}(I-P) t\right)^{2}}{\|(I-P) t\|^{2}}==4\|P t\|^{2}\left(1-\|P t\|^{2}\right) \tag{19}
\end{align*}
$$

Since $t \notin M_{m}$ and $t \notin M_{m}^{\perp}, 0<\|P t\|^{2}<1$ so $0<a \leqq 1$.
Claim 4. The function $\varphi$ is given by

$$
\varphi(c)=\left\{\begin{array}{l}
0 \quad \text { if } \quad 0 \leqq c \leqq a  \tag{20}\\
1-[\sqrt{a c}+\sqrt{(1-a)(1-c)}]^{2} \quad \text { if } \quad a \leqq c \leqq 1
\end{array}\right.
$$

Proof of Claim 4. Since $Q=t^{*} t^{* \prime}$ (see the proof of Claim 2), for each $x \in R^{n},\left\|Q S_{t} x\right\|^{2}=x^{\prime} S_{t} Q S_{t} x=x^{\prime} S_{t} t^{*} t^{*} S_{t} x=\left(z_{0}^{\prime} x\right)^{2}$. Thus,

$$
\begin{equation*}
\varphi(c)=\inf _{x \in Z_{c}}\left\|P S_{t} x\right\|^{2}=\inf _{x \in Z_{c}}\left(1-\left\|Q S_{t} x\right\|^{2}\right)=1-\sup _{x \in Z_{c}}\left(z_{0}^{\prime} x\right)^{2} \tag{21}
\end{equation*}
$$

If $a=1$, then $z_{0} \in D_{m} \subseteq Z_{c}$, so $\sup _{x \in Z_{c}}\left(z_{0}^{\prime} x\right)^{2}=1$ and $\varphi(c)=0$ for all $c \in[0,1]$.

Now, consider $a \in(0,1)$. For $x \in Z_{c}$, let $\gamma=\|P x\|^{2} \geqq c$. Then, by the Cauchy-Schwarz inequality, we have

$$
\begin{align*}
z_{0}^{\prime} x & =z_{0}^{\prime} P x+z_{0}^{\prime} Q x=\left(P z_{0}\right)^{\prime} P x+\left(Q z_{0}\right)^{\prime} Q x  \tag{22}\\
& \leqq\left\|P z_{0}\right\|\|P x\|+\left\|Q z_{0}\right\|\|Q x\|=\sqrt{a} \sqrt{\gamma}+\sqrt{1-a} \sqrt{1-\gamma}
\end{align*}
$$

Further, there is equality in the above inequality for $x=x_{0}$ where

$$
\begin{equation*}
x_{0}=\sqrt{\gamma / a} P z_{0}+\sqrt{(1-\gamma) /(1-a)} Q z_{0} \tag{23}
\end{equation*}
$$

Clearly, $\left\|P x_{0}\right\|^{2}=\gamma \geqq c$ so $x_{0} \in Z_{c}$. Thus,

$$
\begin{equation*}
\varphi(c)=1-\sup _{\gamma \in[c, 1]}[\sqrt{a \gamma}+\sqrt{(1-a)(1-\gamma)}]^{2} \tag{24}
\end{equation*}
$$

If $c \leqq a$, then $\gamma=a \in[c, 1]$ and $\varphi(c)=0$. If $c>a$, then the sup in (24) is achieved at $\gamma=c$. Thus $\varphi$ is given by (20) and the proof of Claim 4 is complete.

Now, by Lemma 2, there is an index $i_{0}$ such that $b_{i_{0}}=0$ since $b_{1}=\varphi(1)$ and $b_{i}=\varphi\left(b_{i-1}\right)$. Thus, $B_{i_{0}}=Z_{0}=D_{m+1}$ and by Claim 1, $K^{*}$ is transitive on $D_{m+1}$. This completes the proof of Lemma 3.

The following is an immediate consequence of Theorem 1.
Corollary 1. Let $G_{1}=\langle\mathscr{R}\rangle$ where $\mathscr{R}=\left\{S_{r} \mid r \in R\right\} . \quad$ If $G_{1}$ is infinite and irreducible, then the closure of $G_{1}$ is $O(n)$. Also, for each $x \in C_{n},\left\{g x \mid g \in G_{1}\right\}$ is dense in $C_{n}$.

Remark. The assumption that $G$ is generated by reflections cannot be removed since $O^{+}(n), n \geqq 2$ is infinite, closed and irreducible but $O^{+}(n) \neq O(n)$. Our interest in Theorem 1 arose in connection with results for $G$-monotone functions when $G$ is generated by reflections (see Eaton and Perlman (1976)).

## References

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University of Copenhagen
5, UNIVERSITETSPARKEN
DK 2100 Copenhagen, $\emptyset$ Denmark

