62. The Topological Invariant of Three-manifolds Based on the U(1) Gauge Theory

Ву Тоги GOCHO

Department of Mathematics, University of Tokyo

(Communicated by Kunihiko KODAIRA, M. J. A., Oct. 12, 1990)

In this paper, we shall construct a topological invariants of threemanifolds using a series of representations of the Siegel modular group. We denote by Sp(2g, Z) the Siegel modular group. By a series of projective unitary representations $\rho = \{\rho_g\}_{g \in N}$ of $Sp(Z) = \{Sp(2g, Z)\}_{g \in N}$, we shall mean that $\rho_g: Sp(2g, Z) \rightarrow PU(V_g)$ is a projective unitary representation on a hermitian vector space V_g for each $g \in N$.

We shall consider the following two conditions on ρ .

Condition 1. There exists a hermitian vector space isomorphism φ_g : $V_g \otimes V_1 \rightarrow V_{g+1}$ for each $g \in N$, satisfying

 $\bar{\varphi}_{g}(\rho_{g}(X), \rho_{g}(Y)) = \rho_{g+1}(\iota_{g}(X, Y)) \quad \text{for } X \in Sp(2g, Z) \text{ and } Y \in Sp(2, Z),$ where $\bar{\varphi}_{g}: PU(V_{g}) \times PU(V_{1}) \rightarrow PU(V_{g+1})$ is the homomorphism induced by φ_{g} and $\iota_{g}: Sp(2g, Z) \times Sp(2, Z) \rightarrow Sp(2g+2, Z)$ is the natural inclusion map.

Condition 2. There exists an unit vector $v_0^{(1)} \in V_1$, and if we define $v_0^{(g)} \in V_g$ inductively by $v_0^{(g)} = \varphi_{g-1}(v_0^{(g-1)} \otimes v_0^{(1)})$, then $v_0^{(g)}$ is a simultaneous eigenvector of $\rho_g(\mathfrak{p}_g)$ ($\subset PU(V_g)$), where $\mathfrak{p}_g = \left\{ \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in Sp(2g, \mathbb{Z}) \, \middle| \, C = 0 \right\}$.

If we are given a series of projective unitary representations $\rho = \{\rho_g\}_{g \in \mathbb{Z}}$ of $Sp(\mathbb{Z})$ satisfying above Conditions 1 and 2, we can construct a C/U(1) valued topological invariant W(M) for a closed oriented three manifold M in the following manner.

We can represent M by a Heegaard splitting $M = H_g \cup_h (-H_g)$, where H_g is the handle body of genus g, and $h: \sum_g (=\partial H_g) \to \sum_g$ is an orientation preserving homeomorphism. We fix a basis $\{\lambda_i\}_{i=1}^{2g}$ of $H^1(\sum_g, Z)$ satisfying

(1)
$$\begin{cases} \omega(\lambda_i, \lambda_j) = \omega(\lambda_{g+i}, \lambda_{g+j}) = 0\\ \omega(\lambda_i, \lambda_{g+j}) = \delta_{i,j}, \end{cases} \quad i, j = 1, 2, \dots, g,$$

where ω is the intersection form on \sum_{g} , and

(2)
$$\operatorname{Im} i^* = \bigoplus_{i=1}^{q} Z\lambda_i,$$

where $i^*: H^1(\sum_{g}, Z) \to H^1(\sum_{g}, Z)$ is the homomorphism induced by the inclusion map $i: \sum_{g} \to H_g$.

Then we regard $\hat{h} = (h^{-1})^*$: $H^1(\sum_g, Z) \to H^1(\sum_g, Z)$ as an element of Sp(2g, Z) with respect to the basis $\{\lambda_i\}_{i=1}^{2g}$.

Now we define

$$W(M) = c_0^{1-g} \langle \rho_g(\hat{h}) v_0^{(g)}, v_0^{(g)} \rangle \qquad (\in C/U(1)),$$

and

$$c_0 = \langle \rho_1(J_2) v_0^{(1)}, v_0^{(1)} \rangle \qquad (\in C/U(1)),$$

where $J_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$.

The well-definedness of above definition is guaranteed by the following.

Theorem 1. W(M) does not depend on the particular Heegaard splitting of M. Therefore W(M) is a topological invariant of M.

Using the stabilization theorem due to Reidemeister and Singer ([2]), Theorem 1 easily follows from Conditions 1 and 2. And it is also easy to see that W(M) does not depend on the particular basis $\{\lambda_i\}_{i=1}^{2g}$ satisfying (1) and (2).

An example of a series of projective unitary representations of Sp(Z) satisfying Conditions 1 and 2 can be obtained by some geometric construction. More precisely we can construct the hermitian vector bundle $E^{(k)}$ over the Siegel's upper half plane \mathfrak{F}_q for each $k \in 2N$, which has a natural projectively flat connection, and Sp(2g, Z) acts on $E^{(k)} \rightarrow \mathfrak{F}_q$.

The monodromy representation of the above action $\rho_q^{(k)}$ can be given as follows. Let V_q be the hermitian vector space with the unitary basis $\{\Psi_l\}_{l \in I_q^{(k)}}$ parametrized by

$$I_{g}^{(k)} = \left\{ l = \begin{pmatrix} l_{1} \\ \vdots \\ l_{g} \end{pmatrix} \in \mathbb{Z}^{g} \mid 0 \leq l_{i} < k, i = 1, 2, \cdots, g \right\}.$$

Note that Sp(2g, Z) is generated by the elements of the forms $\begin{pmatrix} I_g \\ -I_g \end{pmatrix}$, $\begin{pmatrix} A \\ {}^{\iota}A^{-1} \end{pmatrix}$ and $\begin{pmatrix} I_g & B \\ I_g \end{pmatrix}$, where $A \in GL(g, Z)$ and $B \in M_g(Z)$ with ${}^{\iota}B = B$. We define

$$\rho_{g}^{(k)} \begin{pmatrix} I_{g} \end{pmatrix} \Psi_{l} = k^{-g/2} \sum_{\substack{l' \in I_{g}^{(k)} \\ g'}} e^{2\pi \sqrt{-1} k^{-1ll' \cdot l}} \Psi_{l'},$$

$$\rho_{g}^{(k)} \begin{pmatrix} A \\ & {}^{l}A^{-1} \end{pmatrix} \Psi_{l} = \sum_{\substack{l' \in I_{g}^{(k)} \\ g'}} a_{l'l} \Psi_{l'},$$
where $a_{l'l} = \begin{cases} 1 & \text{if } {}^{l}Al' \equiv l \mod kZ^{g}, \\ 0 & \text{if } {}^{l}Al' \equiv l \mod kZ^{g}, \end{cases}$

and

$$\rho_g^{(k)} \begin{pmatrix} I_g & B \\ & I_g \end{pmatrix} \Psi_l = e^{\pi \sqrt{-1} k^{-1} l B l} \Psi_l.$$

Then the projective unitary representation $\rho_g^{(k)}$: $Sp(2g, Z) \rightarrow PU(V_g)$ is defined by these equations. And it is easy to see that $\rho^{(k)} = \{\rho_g^{(k)}\}_{g \in N}$ satisfies Conditions 1 and 2. Hence these give rise to a topological invariant $W_k(M)$ of M parametrized by $k \in 2N$.

Example.

$$\begin{split} W_k(S^1 \times S^2) &= 1\\ W_k(S^3) &= \frac{1}{k^{1/2}}\\ W_k(L_{p,1}) &= \frac{1}{k} \sum_{l=0}^{k-1} e^{-\pi \sqrt{-1} k - 1 p l^2}\\ W_k(L_{2m+1,2}) &= \frac{1}{k^{3/2}} \sum_{l,l'=0}^{k-1} e^{-\pi \sqrt{-1} k - 1 (m l^2 - 2l \cdot l' - 2l'^2)}. \end{split}$$

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The detailed discussion and proofs will be given in the forthcoming paper.

References

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