# INFINITE MARKOV PARTICLE SYSTEMS ASSOCIATED WITH ABSORBING STABLE MOTION ON A HALF SPACE 

SEIJI HIRABA

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#### Abstract

In general, for a Markov process which does not have an invariant measure, it is possible to realize a stationary Markov process with the same transition probability by extending the probability space and by adding new paths which are born at random times. The distribution (which may not be a probability measure) is called a Kuznetsov measure. By using this measure we can construct a stationary Markov particle system, which is called an equilibrium process with immigration. This particle system can be decomposed as a sum of the original part and the immigration part (see [2]). In the present paper, we consider an absorbing stable motion on a half space $H$, i.e., a time-changed absorbing Brownian motion on $H$ by an increasing strictly stable process. We first give the martingale characterization of the particle system. Secondly, we discuss the finiteness of the number of particles near the boundary of the immigration part. (cf. [2], [3], [4].)


## 1. Introduction

Let $0<\alpha<2, d \geq 1$ and $H=\mathbf{R}^{d-1} \times(0, \infty)$ be the half space. Let $\left(w^{-}(t), P_{x}^{-}\right)=$ ( $w^{-, \alpha}(t), P_{x}^{-, \alpha}$ ) be an absorbing $\alpha$-stable motion on $H ; w^{-}(0)=x \in H$, i.e., $w^{-, \alpha}(t)=$ $B^{0}\left(y^{\alpha / 2}(t)\right)$, where $B^{0}(t)$ is an absorbing Brownian motion on $H ; B^{0}(0)=x$ and $y^{\alpha / 2}(t)$ is an increasing strictly $\alpha / 2$-stable process on $[0, \infty)$ such that $y^{\alpha / 2}(0)=0$ and $\left(y^{\alpha / 2}(t)\right)$ is independent of $\left(B^{0}(t)\right)$. The Laplace transform of $y^{\alpha / 2}(t)$ is given by $E\left[\exp \left(-u y^{\alpha / 2}(t)\right)\right]=$ $\exp \left[-c t u^{\alpha / 2}\right](c>0)$ and the life time $\zeta\left(w^{-}\right)=\zeta\left(w^{-, \alpha}\right)$ of $w^{-}(t)$ is given as $\zeta\left(w^{-}\right)=$ $\inf \left\{t>0 ; y^{\alpha / 2}(t) \geq \zeta\left(B^{0}\right)\right\}$, where $\zeta\left(B^{0}\right)$ is the life time of $B^{0}(t)$.

Let $H_{\Delta}=H \cup \Delta$ with a fixed extra point $\Delta \notin H$, Define a path space $W$ as $w \in W \stackrel{\text { def }}{\Longleftrightarrow} w: \mathbf{R} \rightarrow H_{\Delta}$; there exists $(\beta(w), \gamma(w)) \neq \emptyset$ such that $w$ is $H$-valued càdlàg path on $(\beta(w), \gamma(w)), w(t)=\Delta$ for $t \notin(\beta(w), \gamma(w))$. Moreover set $W_{0}=W \cap\{\beta=0\}$ be a family of all càdlàg excursions on $H$.

In order to define a Kuznetsov measure associated with $\left(w^{-}(t), P_{x}^{-}\right)$, we need an entrance law $\left(\nu_{t}\right)_{t>0}$, that is, a family of $\sigma$-finite measures such that $v_{s} P_{t-s}^{-}=v_{t}$ for $s<t$, where $\left(P_{t}^{-}\right)$is the transition semi-group of $\left(w^{-}(t), P_{x}^{-}\right)$. $\left(v_{t}\right)$ is defined as for

[^0]$x=\left(\tilde{x}, x_{d}\right) \in H\left(\tilde{x} \in \partial H=\mathbf{R}^{d-1}, x_{d}>0\right)$,
$$
v_{t}(d y):=\left.\int_{\mathbf{R}^{d-1}} d \tilde{x} \partial_{d} P_{t}^{-}(x, d y)\right|_{x_{d}=0+}
$$
where $\partial_{d}=\partial / \partial x_{d}$. Then we also have
$$
v_{t}(d y)=v_{t}\left(y_{d}\right) d y \quad \text { with } \quad v_{t}\left(y_{d}\right)=-2 \int_{\mathbf{R}^{d-1}} \partial_{d} p_{t}^{\alpha}\left(\left(\tilde{x}, y_{d}\right)\right) d \tilde{x}
$$
where $p_{t}^{\alpha}(x)$ is a density of the rotation invariant $\alpha$-stable process $\left(w^{\alpha}(t), P_{0}^{\alpha}\right)$ on $\mathbf{R}^{d}$. In fact, the transition density of $P_{t}^{-}(x, d y)=p_{t}^{-}(x, y) d y$ is given by the following.
\[

$$
\begin{aligned}
p_{t}^{-}(x, y) \equiv p_{t}^{\alpha,-}(x, y) & =p_{t}^{\alpha}(y-x)-p_{t}^{\alpha}\left(\left(\tilde{y},-y_{d}\right)-x\right) \\
& =p_{t}^{\alpha}(y-x)-p_{t}^{\alpha}\left(y-\left(\tilde{x},-x_{d}\right)\right) \\
& =-\int_{-x_{d}}^{x_{d}} \partial_{d} p_{t}^{\alpha}\left(\left(\tilde{y}-\tilde{x}, y_{d}+v\right)\right) d v
\end{aligned}
$$
\]

Hence the density of an entrance law at a boundary point $\tilde{x} \in \partial H$ is defined as

$$
v_{t}^{\tilde{x}}(y)=\left.\partial_{d} p_{t}^{-}(x, y)\right|_{x_{d}=0+}=-2 \partial_{d} p_{t}^{\alpha}\left(\left(\tilde{y}-\tilde{x}, y_{d}\right)\right)
$$

We define the density of an entrance law by

$$
v_{t}(y):=\int_{\mathbf{R}^{d-1}} v_{t}^{\tilde{x}}(y) d \tilde{x}=-2 \int_{\mathbf{R}^{d-1}} \partial_{d} p_{t}^{\alpha}\left(\left(\tilde{x}, y_{d}\right)\right) d \tilde{x}
$$

Since the last term is independent of $\tilde{y}$, we can write $v_{t}(y)=v_{t}\left(y_{d}\right)$.
By $p_{t}^{\alpha}(x)=t^{-d / \alpha} p_{1}^{\alpha}\left(t^{-1 / \alpha} x\right)$, we have $\partial_{d} p_{t}^{\alpha}(x)=t^{-(d+1) / \alpha} \partial_{d} p_{1}^{\alpha}\left(t^{-1 / \alpha} x\right)$ and

$$
v_{t}\left(y_{d}\right)=t^{-2 / \alpha} \nu_{1}\left(t^{-1 / \alpha} y_{d}\right)
$$

The density of the invariant measure is given as

$$
m\left(y_{d}\right)=m^{\alpha}\left(y_{d}\right)=\int_{0}^{\infty} d t v_{t}\left(y_{d}\right)=c_{\alpha} y_{d}^{\alpha-2}
$$

with a positive constant

$$
c_{\alpha}=\alpha \int_{0}^{\infty} u^{1-\alpha} v_{1}(u) d u=-2 \alpha \int_{0}^{\infty} d u u^{1-\alpha} \int_{\mathbf{R}^{d-1}} \partial_{d} p_{1}^{\alpha}(\tilde{v}, u) d \tilde{v}
$$

Note that this integral is finite because it holds that with some constant $C>0$ (see [3]),

$$
\left|\partial_{d} p_{1}^{\alpha}(x)\right| \leq C\left(1 \wedge x_{d} \wedge x_{d}|x|^{-2-d-\alpha}\right) \quad \text { for } \quad x \in H
$$

Let

$$
m(d x)=m^{\alpha}(d x):=\int_{0}^{\infty} d t v_{t}(d x)=m^{\alpha}\left(x_{d}\right) d x=c_{\alpha} x_{d}^{\alpha-2} d x .
$$

The excursion law $Q^{0}$ on $W_{0}$ and the Kuznetsov measure $Q_{m}$ on $W$ are defined by the following:

$$
Q^{0}:=\lim _{r \downarrow 0} \int_{H} v_{r}(d x) P_{x}^{-}, \quad Q_{m}:=\int_{-\infty}^{\infty} \theta_{-s}\left(Q^{0}\right) d s
$$

where $\theta_{-s}$ is a time-shift operator such that $\theta_{-s} w(t):=w(t-s)$ for $w \in W_{0}$ and $\theta_{-s}\left(Q^{0}\right)(A)=Q^{0}\left(\left\{w \in W_{0} ; \theta_{-s} w \in A\right\}\right)$ for $A \subset W \cap\{\beta=-s\}$. Note that these measures are infinite. Then $\left(w(t), Q_{m}\right)$ is a stationary Markov process with the invariant measure $m=m^{\alpha}$ and the same transition probability as the absorbing $\alpha$-stable motion $\left(w^{-}(t), P_{x}^{-}\right)=\left(w^{-, \alpha}(t), P_{x}^{-, \alpha}\right)$.

Furthermore by using this process we can introduce an infinite stationary Markov particle system; the equilibrium process $\left(X_{t}, \mathbf{P}\right)$ as follows.

$$
\begin{aligned}
& \omega \in \Omega \stackrel{\text { def }}{\Longleftrightarrow} \omega=\sum \delta_{w_{n}}, \quad w_{n} \in W, \\
& X_{t}(\omega)=\left.\omega(t)\right|_{H} \text { for } \omega \in \Omega, \\
& \mathbf{P}=\Pi_{Q_{m}} \text { is } Q_{m} \text {-Poisson measure },
\end{aligned}
$$

i.e., the distribution of the Poisson random measure with intensity $Q_{m}$. Then $\left(X_{t}, \mathbf{P}\right)$ is a stationary Markov particle system such that

$$
\mathbf{E} \exp \left[-\left\langle X_{t}, f\right\rangle\right]=\exp \left[-\left\langle m, 1-e^{-f}\right\rangle\right] .
$$

for nonnegative measurable function $f$.
Note that the equilibrium process $\left(X_{t}, \mathbf{P}\right)$ is a stationary independent Markov particle system such that the initial distribution is a Poisson measure. More precisely, let $m$ be a $\sigma$-finite measure on a state space $S$. We consider many independent identically distributed Markov processes $\left\{w_{n}(t)\right\}$ which have an invariant measure $m$. For the particle system $X_{t}=\sum \delta_{w_{n}(t)}$, if the initial state $X_{0}$ is a Poisson random measure with intensity $m$, then $\left\{X_{t}\right\}$ is a stationary Markov process. This particle system $\left\{X_{t}\right\}$ is called the equilibrium process (cf. [6]). This definition is equivalent to the above one (see below). The typical example is the independent Brownian particle system in $\mathbf{R}^{d}$ with the Lebesgue measure $m(d x)=d x$ on $\mathbf{R}^{d}$. In this case $Q_{m}$ is identified as $P_{m}:=\int_{\mathbf{R}^{d}} P_{x} d x$, where $P_{x}$ is a distribution of a Brownian motion starting from $x \in \mathbf{R}^{d}$.

If we restrict to $t \geq 0$, then this process can be decomposed as $X_{t}=X_{t}^{O}+X_{t}^{I}$ such that

$$
\begin{aligned}
X_{t}^{O} & =\left.\int_{(-\infty, 0)} \int_{W_{0}} \delta_{w(t-s)}\right|_{H} N^{0}(d s d w) \\
X_{t}^{I} & =\left.\int_{[0, t]} \int_{W_{0}} \delta_{w(t-s)}\right|_{H} N^{0}(d s d w)
\end{aligned}
$$

where $N^{0}(d s d w)$ is the Poisson random measure with intensity $d s Q^{0}(d w)$ on $\mathbf{R} \times$ $W_{0} . X_{t}^{O}$ is the original part of $X_{t}, X_{t}^{I}$ is the immigration part of $X_{t}$ and they are independent. This process is called the infinite Markov particle system with singular immigration associated with absorbing stable motions on $H$.


Moreover for a fixed suitable measure $\mu=\sum \delta_{x_{n}}\left(\in \mathcal{M}_{p, 0}\right.$, see the next section), it is possible to construct a Markov process ( $X_{t}, \mathbf{P}_{\mu}$ ) starting from $\mu$ such that $X_{t}=X_{t}^{O}+$ $X_{t}^{I}$, where $X_{t}^{I}$ is the same as above, $X_{t}^{O}$ is the independent Markov particle system starting from $\mu$, i.e., $X_{0}=X_{0}^{O}=\mu$ and $\left\{X_{t}^{O}\right\},\left\{X_{t}^{I}\right\}$ are independent. Furthermore $\mathbf{P}_{\mu}=\mathbf{P}_{\mu}^{O} \otimes \mathbf{P}^{I}$ where $\mathbf{P}_{\mu}^{O}=\otimes P_{x_{n}}^{-}$and $\mathbf{P}^{I}$ is the distribution of $\left\{X_{t}^{I}\right\}$, that is, the $\int_{0}^{\infty} \theta_{-s}\left(Q^{0}\right) d s$-Poisson measure. Let $\left\{\mathcal{F}_{t}\right\}$ be the filtration generated by $\left\{X_{t}\right\}$. Then it satisfies that if $s<t$, then

$$
\mathbf{E}_{\mu}\left[\exp \left(-\left\langle X_{t}, f\right\rangle\right) \mid \mathcal{F}_{s}\right]=\exp \left[-\left\langle X_{s}, V_{t-s} f\right\rangle-\int_{0}^{t-s}\left\langle v_{r}, 1-e^{-f}\right\rangle d r\right]
$$

for some nonnegative suitable functions $f$ on $H$ ( $f \in D_{p}$, see also the next section), where

$$
V_{t} f(x)=-\log E_{x}^{-}\left[\exp \left(-f\left(w^{-}(t)\right)\right]=-\log \left\{1-P_{t}^{-}\left(1-e^{-f}\right)(x)\right\}\right.
$$

Note that if we let $\Pi_{m}$ be the $m$-Poisson measure, then the distribution of the equilibrium process can be also defined as $\mathbf{P}=\int \Pi_{m}(d \mu) \mathbf{P}_{\mu}$ and we also have

$$
\begin{aligned}
\mathbf{E} \exp \left[-\left\langle X_{t}, f\right\rangle\right] & =\exp \left[-\left\langle m, 1-e^{-V_{t} f}\right\rangle-\int_{0}^{t}\left\langle v_{r}, 1-e^{-f}\right\rangle d r\right] \\
& =\exp \left[-\left\langle m, 1-e^{-f}\right\rangle\right] .
\end{aligned}
$$

by $1-e^{-V_{t} f}=P_{t}^{-}\left(1-e^{-f}\right)$ and $m P_{t}^{-}=\int_{0}^{\infty} \nu_{r} P_{t}^{-} d r=\int_{0}^{\infty} \nu_{r+t} d r=\int_{t}^{\infty} \nu_{r} d r$.
In $\S 2$ we consider the martingale problem for $\left(X_{t}, \mathbf{P}_{\mu}\right)$. In order to give the martingale characterization we have to investigate the properties of the transition probabilities of absorbing stable motions in $H$ (which are given in [4]) and the entrance laws.

In $\S 3$ we discuss the finiteness of the number of particles near the boundary of immigration. The obtained results and the proofs are similar to the case of absorbing the Brownian motion in [2]. However we have to extend the case by using the scaling property of the absorbing stable motion.

## 2. Martingale Problem for $\left(X_{t}, P_{\mu}\right)$

The martingale problem can be shown by the same way as in case of the absorbing Brownian motion on $H$ in [2] and the independent Markov particle system with no immigration in [4].

Let $h_{0}(v)$ be a $C_{b}^{\infty}$-function on $(0, \infty)$ such that $0<h_{0} \leq 1$ on $(0, \infty), h_{0}(v)=v$ for $v \in(0,1 / 2], h_{0}(v)=1$ for $v \geq 1$ and $\left\|h_{0}^{\prime}\right\|_{\infty}=1$.

Let $d<p<d+\alpha$. Set $g_{p}(x):=\left(1+|x|^{2}\right)^{-p / 2}, g_{p, 0}(x):=g_{p}(x) h_{0}\left(x_{d}\right)$ for $x \in$ $H$ and

$$
\begin{aligned}
& \left.f \in C_{p} \equiv C_{p}(H) \stackrel{\text { def }}{\Longleftrightarrow} f \in C\left(\mathbf{R}^{d}\right)\right|_{H} ; \quad\left\|f / g_{p}\right\|_{\infty}<\infty, \\
& \left.f \in C_{p, 0} \equiv C_{p, 0}(H) \stackrel{\text { def }}{\Longleftrightarrow} f \in C\left(\mathbf{R}^{d}\right)\right|_{H} ; \quad\left\|f / g_{p, 0}\right\|<\infty .
\end{aligned}
$$

Moreover set

$$
\begin{aligned}
& \left.f \in C_{p, 0}^{3} \equiv C_{p, 0}^{3}(H) \stackrel{\text { def }}{\Longleftrightarrow} f \in C_{b}^{3}\left(\mathbf{R}^{d}\right)\right|_{H} ; \\
& \text { for } \quad i, j \neq d, f, \partial_{d}^{2} f, \partial_{i} f, \partial_{i j}^{2} f \in C_{p, 0} \quad \text { and } \quad \partial_{d} f, \partial_{i d}^{2} f \in C_{p} .
\end{aligned}
$$

We define a space of counting measures $\mathcal{M}_{p, 0}$ by

$$
\mu \in \mathcal{M}_{p, 0} \equiv \mathcal{M}_{p, 0}(H) \stackrel{\text { def }}{\Longleftrightarrow} \mu=\sum \delta_{x_{n}} \quad \text { on } H \text { such that }\left\langle\mu, g_{p, 0}\right\rangle<\infty
$$

$\mathcal{M}_{p, 0}$ is furnished with the vague topology, i.e.,

$$
\mu_{n} \rightarrow \mu \text { in } \mathcal{M}_{g_{p, 0}} \stackrel{\text { def }}{\Longleftrightarrow} \sup \left\langle\mu_{n}, g_{p, 0}\right\rangle<\infty,\left\langle\mu_{n}, f\right\rangle \rightarrow\langle\mu, f\rangle \text { for all } f \in C_{c},
$$

where $C_{c} \equiv C_{c}(H)$ denotes the space of all continuous functions with compact supports in $H$. Then it holds that $\left\langle\mu, g_{p, 0}\right\rangle \leq \lim \inf \left\langle\mu_{n}, g_{p, 0}\right\rangle<\infty$, and thus, $\mu \in \mathcal{M}_{g_{p, 0}}$. Note that for each $1 \leq K<\infty$, we define

$$
\left\{\begin{array}{l}
\mu \in \mathcal{M}_{g_{p, 0}, K} \equiv \mathcal{M}_{g_{p, 0}, K}(H) \stackrel{\text { def }}{\Longleftrightarrow} \mu \mu \in \mathcal{M}_{g_{p, 0},}\left\langle\mu, g_{p, 0}\right\rangle \leq K, \\
\mu_{n} \rightarrow \mu \text { in } \mathcal{M}_{g_{p, 0}, K} \stackrel{\text { def }}{\Longleftrightarrow}\left\langle\mu_{n}, f\right\rangle \rightarrow\langle\mu, f\rangle \text { for all } f \in C_{c} .
\end{array}\right.
$$

Then $\mathcal{M}_{g_{p, 0}, K}$ is a Polish space and $\mu_{n} \rightarrow \mu$ in $\mathcal{M}_{g_{p, 0}}$ is equivalent to $\mu_{n} \rightarrow \mu$ in $\mathcal{M}_{g_{p, 0}, K}$ for some $K \geq 1$. Hence $\mathcal{M}_{g_{p, 0}}$ is a metrizable and separable space (for the metric $\rho$ in $\mathcal{M}_{p, 0}$, see [4] in which $g_{0}=g_{p, 0}$ ).

For $\mu \in \mathcal{M}_{p, 0}$, let ( $X_{t}, \mathbf{P}_{\mu}$ ) be the independent Markov particle system with singular immigration associated with $\left(w^{-}(t), P_{x}^{-}\right)=\left(w^{-, \alpha}(t), P_{x}^{-, \alpha}\right)$ and $m=m^{\alpha}$ on $H$. We denote the generator of ( $w^{-, \alpha}(t), P_{x}^{-, \alpha}$ ) as $A=A^{-, \alpha}$ (more concrete formula is given latter).

The generator $\mathcal{L}$ of this particle system is given as $\mathcal{L}=\mathcal{L}^{O}+\mathcal{L}^{I}$, where $\mathcal{L}^{O}, \mathcal{L}^{I}$ are given by the following: for $f \in C_{c}^{\infty}$,

$$
\begin{aligned}
\mathcal{L}^{O} e^{-\langle, f\rangle}(\mu) & =-\left\langle\mu, e^{f} A\left(1-e^{-f}\right)\right\rangle e^{-\langle\mu, f\rangle} \\
& =-\langle\mu, A f-\Gamma f\rangle e^{-\langle\mu, f\rangle},
\end{aligned}
$$

where $\Gamma f:=A f-e^{f} A\left(1-e^{-f}\right)$, and

$$
\begin{aligned}
\mathcal{L}^{I} e^{-\langle\cdot f\rangle}(\mu) & =-\lim _{r \downarrow 0}\left\langle v_{r}, 1-e^{-f}\right) e^{-\langle\mu, f\rangle} \\
& =-c_{0}\left\langle\tilde{m}, \partial_{d} f(\cdot, 0+)\right\rangle e^{-\langle\mu, f\rangle},
\end{aligned}
$$

where $c_{0}=\int_{0}^{\infty} y \nu_{1}(y) d y$ and $\tilde{m}$ is the Lebesgue measure on $\mathbf{R}^{d-1}$. Note that $c_{0}$ depends on $\alpha$ and it is finite. In fact, by $\left|\partial_{d} p_{1}^{\alpha}(x)\right| \leq C\left(1 \wedge x_{d} \wedge x_{d}|x|^{-2-d-\alpha}\right)$ for $x \in H$,

$$
c_{0}=\int_{0}^{\infty} y v_{1}(y) d y=-2 \int_{0}^{\infty}\left(y \int_{\mathbf{R}^{d-1}} \partial_{d} p_{1}^{\alpha}(\tilde{x}, y) d \tilde{x}\right) d y<\infty .
$$

Hence

$$
\mathcal{L} e^{-\langle\cdot, f\rangle}(\mu)=-\left\{\langle\mu, A f-\Gamma f\rangle+c_{0}\left\langle\tilde{m}, \partial_{d} f(\cdot, 0+)\right\rangle\right\} e^{-\langle\mu, f\rangle} .
$$

Set $D_{p}:=C_{p, 0}^{3}$ (this is a core for $A$, see (B1) in $\S 3$ of [4]). Moreover for a function $f \in D_{p}$, let $\bar{f}$ be an extension of $f$ to on $\mathbf{R}^{d}$ defined as

$$
\bar{f}(x)= \begin{cases}f(x) & \left(x_{d}>0\right) \\ f(\tilde{x}, 0+)=0 & \left(x_{d}=0\right) \\ -f\left(\tilde{x},-x_{d}\right) & \left(x_{d}<0\right)\end{cases}
$$

Note that if $x \in H$, then $\bar{f}(x)=f(x)$. The generator $A \equiv A^{-} \equiv A^{-, \alpha}$ is given as $(A$ is the same as $L^{-}$in $\S 4$ of [3], however in which we have some miss-prints)

$$
\begin{aligned}
A^{-, \alpha} f(x)= & c \int_{\mathbf{R}^{d} \backslash\{0\}}[\bar{f}(x+y)-\bar{f}(x)-\nabla \bar{f}(x) \cdot y I(|y|<1)] \frac{d y}{|y|^{d+\alpha}} \\
= & c \int_{\mathbf{R}^{d-1}} d \tilde{y} \int_{-x_{d}}^{x_{d}}[f(x+y)-f(x)-\nabla f(x) \cdot y I(|y|<1)] \frac{d y_{d}}{|y|^{d+\alpha}} \\
& +c \int_{\mathbf{R}^{d-1}} d \tilde{y} \int_{x_{d}}^{\infty}\left[f(x+y)-f\left(\tilde{y}+\tilde{x}, y_{d}-x_{d}\right)-2 f(x)\right] \frac{d y_{d}}{|y|^{d+\alpha}}
\end{aligned}
$$

with a positive constant $c$. We can also write that if $0<\alpha<1$, then

$$
\begin{aligned}
& A^{-, \alpha} f(x) \\
& =c \int_{\mathbf{R}^{d} \backslash\{x\}}[\bar{f}(y)-\bar{f}(x)] \frac{d y}{|y-x|^{d+\alpha}} \\
& =c \int_{\mathbf{R}^{d-1}} d \tilde{y}\left\{\int_{0}^{\infty}[f(y)-f(x)] K(x, y) d y_{d}-2 f(x) \int_{0}^{\infty} \frac{d y_{d}}{\left.\left|\left(\tilde{y}-\tilde{x}, y_{d}+x_{d}\right)\right|^{d+\alpha}\right\},}\right. \\
& =c \int_{\mathbf{R}^{d-1}} d \tilde{y} \int_{0}^{\infty}[f(y)-f(x)] K(x, y) d y_{d}-f(x) k(x),
\end{aligned}
$$

and that if $1 \leq \alpha<2$, then

$$
\begin{aligned}
& \begin{aligned}
& A^{-, \alpha} f(x) \\
&= c \int_{\mathbf{R}^{d} \backslash\{x\}}[\bar{f}(y)-\bar{f}(x)-\nabla \bar{f}(x) \cdot(y-x) I(|y-x|<1)] \frac{d y}{|y-x|^{d+\alpha}} \\
&= c \int_{\mathbf{R}^{d-1}} d \tilde{y}\left\{\int_{0}^{\infty}[f(y)-f(x)-\nabla f(x) \cdot(y-x) I(|y-x|<1)] K(x, y) d y_{d}\right. \\
& \quad+\int_{0}^{\infty}[-2 f(x)-\nabla f(x) \cdot(y-x) I(|y-x|<1) \\
&\left.\left.\quad-\nabla f(x) \cdot\left(\tilde{y}-\tilde{x},-y_{d}-x_{d}\right) I\left(\left|\left(\tilde{y}-\tilde{x}, y_{d}+x_{d}\right)\right|<1\right)\right] \frac{d y_{d}}{\left|\left(\tilde{y}-\tilde{x}, y_{d}+x_{d}\right)\right|^{d+\alpha}}\right\} \\
&= c \int_{\mathbf{R}^{d-1}} d \tilde{y} \int_{0}^{\infty}[f(y)-f(x)-\nabla f(x) \cdot(y-x) I(|y-x|<1)] K(x, y) d y_{d} \\
& \quad-f(x) k(x)+\nabla f(x) \cdot c(x),
\end{aligned}
\end{aligned}
$$

where

$$
\begin{aligned}
& K(x, y)=\frac{I(y \neq x)}{|y-x|^{d+\alpha}}-\frac{1}{\left|\left(\tilde{y}-\tilde{x}, y_{d}+x_{d}\right)\right|^{d+\alpha}}, \\
& k(x)=k\left(x_{d}\right)=2 c \int_{\mathbf{R}^{d-1}} d \tilde{y} \int_{x_{d}}^{\infty} \frac{d y_{d}}{|y|^{d+\alpha}}
\end{aligned}
$$

and

$$
\begin{aligned}
& c(x)=c \int_{\mathbf{R}^{d-1}} d \tilde{y} \int_{0}^{\infty} {\left[-\left(\tilde{y}-\tilde{x},-y_{d}-x_{d}\right) I\left(\left|\left(\tilde{y}-\tilde{x}, y_{d}+x_{d}\right)\right|<1\right)\right.} \\
&\quad-(y-x) I(|y-x|<1)] \frac{d y_{d}}{\left|\left(\tilde{y}-\tilde{x}, y_{d}+x_{d}\right)\right|^{d+\alpha}} \\
&=c \int_{\mathbf{R}^{d-1}} d \tilde{y} \int_{0}^{\infty}\left[\left(\tilde{y}, y_{d}+x_{d}\right) I\left(\left|\left(\tilde{y}, y_{d}+x_{d}\right)\right|<1\right)\right. \\
&\left.\quad-\left(\tilde{y}, y_{d}-x_{d}\right) I\left(\left|\left(\tilde{y}, y_{d}-x_{d}\right)\right|<1\right)\right] \frac{d y_{d}}{\left|\left(\tilde{y}, y_{d}+x_{d}\right)\right|^{d+\alpha}} .
\end{aligned}
$$

For $\eta \in \mathcal{M}_{p, 0}$, let $F(\eta)=\Phi\left(\left\langle\eta, f_{1}\right\rangle, \ldots,\left\langle\eta, f_{n}\right\rangle\right) \in \mathcal{D}_{0} \stackrel{\text { def }}{\Longleftrightarrow} \Phi(x) \in C^{\infty}\left(\mathbf{R}^{n}\right)$ is a polynomial growth function with polynomial growth derivatives of all orders and $f_{i} \in$ $D_{p}, i=1, \ldots, n$. For this functional $F(\eta)$, the generator $\mathcal{L}=\mathcal{L}^{O}+\mathcal{L}^{I}$ can be expressed by the following form:

$$
\begin{aligned}
& \mathcal{L}^{O} F(\eta) \\
& =\sum_{i=1}^{n} \partial_{i} \Phi\left(\left\langle\eta, f_{1}\right\rangle, \ldots,\left\langle\eta, f_{n}\right\rangle\right)\left\langle\eta, A f_{i}\right\rangle \\
& +\int_{H}\left\{\int _ { H \backslash \{ x \} } v ( x , d y ) \left[\Phi\left(\left\langle\eta, f_{1}\right\rangle+f_{1}(y)-f_{1}(x), \ldots,\left\langle\eta, f_{n}\right\rangle+f_{n}(y)-f_{n}(x)\right)\right.\right. \\
& -\Phi\left(\left\langle\eta, f_{1}\right\rangle, \ldots,\left\langle\eta, f_{n}\right\rangle\right) \\
& \left.-\sum_{i=1}^{n} \partial_{i} \Phi\left(\left\langle\eta, f_{1}\right\rangle, \ldots,\left\langle\eta, f_{n}\right\rangle\right)\left(f_{i}(y)-f_{i}(x)\right)\right] \\
& +k(x)\left[\Phi\left(\left\langle\eta, f_{1}\right\rangle-f_{1}(x), \ldots,\left\langle\eta, f_{n}\right\rangle-f_{n}(x)\right)-\Phi\left(\left\langle\eta, f_{1}\right\rangle, \ldots,\left\langle\eta, f_{n}\right\rangle\right)\right. \\
& \left.\left.+\sum_{i=1}^{n} \partial_{i} \Phi\left(\left\langle\eta, f_{1}\right\rangle, \ldots,\left\langle\eta, f_{n}\right\rangle\right) f_{i}(x)\right]\right\} \eta(d x),
\end{aligned}
$$

where $v(x, d y)$ is the Lévy kernel of $A$ (i.e., $v(x, d y)=c K(x, y) d y$ ) and $k(x)=k\left(x_{d}\right)$ is the killing rate given in the above. Moreover

$$
\mathcal{L}^{I} F(\eta)=c_{0} \sum_{i=1}^{n} \partial_{i} \Phi\left(\left\langle\eta, f_{1}\right\rangle, \ldots,\left\langle\eta, f_{n}\right\rangle\right)\left\langle\tilde{m}, \partial_{d} f(\cdot, 0+)\right\rangle .
$$

Note that $\Gamma$ can be expressed as

$$
\Gamma f(x)=\int_{H \backslash\{x\}}\left(e^{-[f(y)-f(x)]}-1+[f(y)-f(x)]\right) \nu(x, d y)+k(x)\left(e^{f(x)}-1-f(x)\right) .
$$

Theorem 1 (Martingale problem for $\left(\mathcal{L}, \mathcal{D}_{0}, \mu\right)$ ). Let $\mu \in \mathcal{M}_{p, 0}$.
(i) $\mathbf{P}_{\mu}\left(X_{0}=\mu\right)=1$ and for $F(\eta)=\Phi\left(\left\langle\eta, f_{1}\right\rangle, \ldots,\left\langle\eta, f_{n}\right\rangle\right) \in \mathcal{D}_{0}$,

$$
M_{t}^{F}=F\left(X_{t}\right)-F\left(X_{0}\right)-\int_{0}^{t} \mathcal{L} F\left(X_{s}\right) d s \quad \text { is a } \mathbf{P}_{\mu} \text {-martingale. }
$$

(ii) If there is a probability measure $\mathbf{Q}_{\mu}$ on $\mathbf{D}=\mathbf{D}\left([0, \infty) \rightarrow \mathcal{M}_{p, 0}\right)$ such that the canonical process $\tilde{X}_{t}(\omega)=\omega(t)(\omega \in \mathbf{D})$ satisfies the same conditions as $\left(X_{t}, \mathbf{P}_{\mu}\right)$ in (i) and

$$
\int_{0}^{t}\left\langle\tilde{X}_{s}, g_{p}\right\rangle d s<\infty \quad \mathbf{Q}_{\mu} \text {-a.s. for all } t \geq 0
$$

then $\mathbf{Q}_{\mu}=\mathbf{P}_{\mu} \circ X^{-1}$ on $\mathbf{D}$, that is, martingale problem for $\left(\mathcal{L}, \mathcal{D}_{0}, \mu\right)$ on $\mathbf{D}$ is well-posed.
Proof of (i) in Theorem 1. In order to show it we need several lemmas.

Lemma 1. $\sup _{0<r \leq T}\left\langle v_{r}, g_{p, 0}\right\rangle<\infty$ for each $T>0$.
Proof. We first note that $\left|\partial_{d} g_{p, 0}(x)\right| \leq(p+1) g_{p}(x) \leq(p+1) g_{p}(\tilde{x})$ for any $x=$ $\left(\tilde{x}, x_{d}\right) \in H$. Moreover note that $g_{p, 0}(x)=x_{d} \partial_{d} g_{p, 0}\left(\left(\tilde{x}, \theta x_{d}\right)\right)$ with some $0<\theta<1$. Now by using scaling property; $\nu_{t}(y)=t^{-2 / \alpha} \nu_{1}\left(t^{-1 / \alpha} y\right)$ and changing of variable $t^{-1 / \alpha} x_{d}=y$ we can get

$$
\begin{aligned}
\left\langle v_{r}, g_{p, 0}\right\rangle & =\int_{\mathbf{R}^{d-1}} d \tilde{x} \int_{0}^{\infty} t^{-2 / \alpha} \nu_{1}\left(t^{-1 / \alpha} x_{d}\right) g_{p, 0}(x) d x_{d} \\
& =\int_{\mathbf{R}^{d-1}} d \tilde{x} \int_{0}^{\infty} t^{-1 / \alpha} \nu_{1}(y) g_{p, 0}\left(\tilde{x}, t^{-1 / \alpha} y\right) d y \\
& =\int_{\mathbf{R}^{d-1}} d \tilde{x} \int_{0}^{\infty} \nu_{1}(y) y \partial_{d} g_{p, 0}\left(\tilde{x}, \theta t^{-1 / \alpha} y\right) d y \\
& \leq C \int_{\mathbf{R}^{d-1}} g_{p}(\tilde{x}) d \tilde{x} \int_{0}^{\infty} y \nu_{1}(y) d y<\infty
\end{aligned}
$$

By this lemma the following holds: for every $f \in D_{p}$, noting that $f(\tilde{x}, 0+)=0$,

$$
\lim _{r \downarrow 0}\left\langle v_{r}, 1-e^{-f}\right\rangle=\lim _{r \downarrow 0}\left\langle\nu_{r}, f\right\rangle=c_{0}\langle\tilde{m}, f(\cdot, 0+)\rangle
$$

and if $n \geq 2$, then $\lim _{r \downarrow 0}\left\langle v_{r}, f\right\rangle^{n}=0$.
The following is given in [4] as Lemma 4.1.
Lemma 2. For each $f \in C_{c}^{\infty}$ and $T>0, \sup _{t \in[0, T]}\left\|g_{p, 0}^{-1} \partial_{t} V_{t} f\right\|_{\infty}<\infty$.
Proof. Let $g_{0} \equiv g_{p, 0}$. In [4] we have $A^{-} C_{p, 0}^{3} \subset C_{p, 0}$ and $\sup _{t \leq T}\left\|g_{0}^{-1} P_{t}^{-} g_{0}\right\|_{\infty}<$ $\infty$. Hence by $\left\|V_{t} f\right\|_{\infty} \leq\|f\|_{\infty}$ and $\left|A^{-}\left(1-e^{-f}\right)\right| \leq C g_{0}$ we have

$$
\left|\partial_{t} V_{t} f\right|=\left|e^{V_{t} f} P_{t}^{-} A^{-}\left(1-e^{-f}\right)\right| \leq C e^{\|f\|_{\infty}} P_{t}^{-} g_{0}
$$

Thus the claim follows.
From the above results we can show the martingale property (i) of Theorem 1. In fact, it is reduced to the following first result.

Theorem 2. For $f \in C_{c}^{\infty}$,

$$
e^{-\left\langle X_{t}, f\right\rangle}-e^{-\left\langle X_{0}, f\right\rangle}-\int_{0}^{t} \mathcal{L} e^{-\langle\cdot f\rangle}\left(X_{s}\right) d s
$$

is a $\mathbf{P}_{\mu}$-martingale. Moreover

$$
H_{t}(f)=\exp \left[-\left\langle X_{t}, f\right\rangle+\int_{0}^{t}\left\langle X_{s}, A f-\Gamma f\right\rangle d s+t c_{0}\left\langle\tilde{m}, \partial_{d} f(\cdot, 0+)\right\rangle\right]
$$

is also a $\mathbf{P}_{\mu}$-martingale.
Proof. By the above lemma, if $s<t$, then

$$
\begin{aligned}
\partial_{t} \mathbf{E}_{\mu}\left[e^{-\left\langle X_{t}, f\right\rangle} \mid \mathcal{F}_{s}\right] & =\partial_{t} \exp \left[-\left\langle X_{s}, V_{t-s} f\right\rangle-\int_{0}^{t-s}\left\langle v_{r}, 1-e^{-f}\right\rangle d r\right] \\
& =\partial_{u=0+} \exp \left[-\left\langle X_{s}, V_{t-s+u} f\right\rangle-\int_{0}^{t-s+u}\left\langle\nu_{r}, 1-e^{-f}\right\rangle d r\right] \\
& =\partial_{u=0+} \mathbf{E}_{\mu}\left[\exp \left\{-\left\langle X_{t}, V_{u} f\right\rangle-\int_{0}^{u}\left\langle v_{r}, 1-e^{-f}\right\rangle d r\right\} \mid \mathcal{F}_{s}\right] \\
& =\mathbf{E}_{\mu}\left[\partial_{u=0+} \exp \left[-\left\langle X_{t}, V_{u} f\right\rangle-\int_{0}^{u}\left\langle v_{r}, 1-e^{-f}\right\rangle d r\right] \mid \mathcal{F}_{s}\right] \\
& =\mathbf{E}_{\mu}\left[\mathcal{L} e^{-\langle, f\rangle}\left(X_{t}\right) \mid \mathcal{F}_{s}\right],
\end{aligned}
$$

where $\partial_{u=0+}$ denotes the right differential operator at $u=0$. Hence the first claim follows. The second claim follows from Corollary 3.3 of Chapter 2 in [1].

In order to show (ii) of Theorem 1, we need the semi-martingale representation of $\left(X_{t}, \mathbf{P}_{\mu}\right)$.

Theorem 3 (Semi-martingale representation of $\left.\left(X_{t}, \mathbf{P}_{\mu}\right)\right)$. Let $\mu \in \mathcal{M}_{p, 0} .\left(X_{t}, \mathbf{P}_{\mu}\right)$ has the following semi-martingale representation: for $f \in D_{p}$,

$$
\left\langle X_{t}, f\right\rangle=\left\langle X_{0}, f\right\rangle+\int_{0}^{t}\left\langle X_{s}, A f\right\rangle d s+t c_{0}\langle\tilde{m}, f(\cdot, 0+)\rangle+M_{t}^{d}(f)
$$

where

$$
M_{t}^{d}(f)=\int_{0}^{t} \int_{\mathcal{M}_{p, 0}^{ \pm}}\langle\mu, f\rangle \tilde{N}(d s, d \mu) \quad \text { is a purely discontinuous } L^{2} \text {-martingale }
$$

with $\tilde{N}=N-\hat{N}$ is the martingale measure such that for $\Delta X_{u}=X_{u}-X_{u-}$,

$$
\begin{aligned}
& N(d s, d \mu)=\sum_{u ; \Delta X_{u} \neq 0} \delta_{\left(u, \Delta X_{u}\right)}(d s, d \mu): \text { the jump measure of }\left\{X_{t}\right\} \\
& \hat{N}(d s, d \mu)=d s \int X_{s}(d x)\left(\int v(x, d y) \delta_{\left(\delta_{y}-\delta_{x}\right)}+k(x) \delta_{-\delta_{x}}\right)(d \mu)
\end{aligned}
$$

the compensator of $N$,
where $\mathcal{M}_{p, 0}^{ \pm}$is the family of signed-measures of $\mu^{+}-\mu^{-} ; \mu^{+}, \mu^{-} \in \mathcal{M}_{p, 0}$.
Proof. For $f \in C_{c}^{\infty}$, let

$$
G_{t}(f)=\exp \left[-\int_{0}^{t}\left\langle X_{s}, A f-\Gamma f\right\rangle d s-t c_{0}\left\langle\tilde{m}, \partial_{d} f(\cdot, 0+)\right\rangle\right]
$$

be a continuous process of bounded variation. Since $H_{t}(f)$ in Theorem 2 is a martingale,

$$
Z_{t}(f):=\exp \left[-\left\langle X_{t}, f\right\rangle\right]=H_{t}(f) G_{t}(f)
$$

is a semi-martingale, more exactly, a special semi-martingale, i.e., a bounded variation part is (locally) integrable. In fact, by Proposition 3.2 of Chapter 2 in [1] we have

$$
\begin{align*}
d Z_{t}(f) & =H_{t}(f) d G_{t}(f)+G_{t}(f) d H_{t}(f)  \tag{2.1}\\
& =-\left(\left\langle X_{t}, A f-\Gamma f\right\rangle+c_{0}\left\langle\tilde{m}, \partial_{d} f(\cdot, 0+)\right\rangle\right) Z_{t}(f) d t+d \text { (martingale) }
\end{align*}
$$

On the other hand, $\left\langle X_{t}, f\right\rangle$ is also a special semi-martingale. Hence by (1.10) of Chapter 4 in [5], $\left\langle X_{t}, f\right\rangle$ has the following expression:

$$
\left\langle X_{t}, f\right\rangle=\left\langle X_{0}, f\right\rangle+C_{t}(f)+M_{t}^{c}(f)+\tilde{N}_{t}(f)+N_{t}(f)
$$

where $C_{t}(f)$ is a continuous process of locally bounded variation, $M_{t}^{c}(f)$ is a continuous $L^{2}$-martingale with quadratic variation $\left\langle\left\langle M^{c}(f)\right\rangle\right\rangle_{t}$, and

$$
\begin{aligned}
& \tilde{N}_{t}(f)=\int_{0}^{t} \int_{\mathcal{M}^{ \pm}}\langle\mu, f\rangle I(\|\mu\|<1) \tilde{N}(d s, d \mu) \\
& N_{t}(f)=\int_{0}^{t} \int_{\mathcal{M}^{ \pm}}\langle\mu, f\rangle I(\|\mu\| \geq 1) N(d s, d \mu)
\end{aligned}
$$

with the jump measure $N$ of $X$, its compensator $\hat{N}$ and $\tilde{N}=N-\hat{N}$. By using Ito's formula we have

$$
\begin{align*}
& d Z_{t}(f)=Z_{t-}(f)\{ -d C_{t}(f)+\frac{1}{2} d\left\langle\left\langle M^{c}(f)\right\rangle\right\rangle_{t} \\
&+\int_{\mathcal{M}^{ \pm}}\left[e^{-\langle\mu, f\rangle}-1+\langle\mu, f\rangle\right] I(\|\mu\|<1) \hat{N}(d t, d \mu) \\
&\left.+\int_{\mathcal{M}^{ \pm}}\left[e^{-\langle\mu, f\rangle}-1\right] I(\|\mu\| \geq 1) N(d t, d \mu)\right\}+d \text { (martingale) }  \tag{2.2}\\
&=Z_{t-}(f)\left\{-\left(d C_{t}(f)+\int_{\{\|\mu\| \geq 1\}}\langle\mu, f\rangle \hat{N}(d t, d \mu)\right)+\frac{1}{2} d\left\langle\left\langle M^{c}(f)\right\rangle\right\rangle_{t}\right. \\
&\left.+\int_{\mathcal{M}^{ \pm}}\left[e^{-\langle\mu, f\rangle}-1+\langle\mu, f\rangle\right] \hat{N}(d t, d \mu)\right\}+d \text { (martingale) }
\end{align*}
$$

If we set

$$
B_{t}(f)=C_{t}(f)+\int_{0}^{t} \int_{\{\|\mu\| \geq 1\}}\langle\mu, f\rangle \hat{N}(d s, d \mu)
$$

then by the expressions (2.1), (2.2) and by the uniqueness of special semi-martingale with predictable locally bounded part (see Theorem 2.1.1 in [5]), we have

$$
\begin{aligned}
& -d B_{t}(f)+\frac{1}{2} d\left\langle\left\langle M^{c}(f)\right\rangle\right\rangle_{t}+\int\left[e^{-\langle\mu, f\rangle}-1+\langle\mu, f\rangle\right] \hat{N}(d t, d \mu) \\
& =\left[-\left(\left\langle X_{t}, A f\right\rangle+c_{0}\left\langle\tilde{m}, \partial_{d} f(\cdot, 0+)\right\rangle\right)+\left\langle X_{t}, \Gamma f\right\rangle\right] d t
\end{aligned}
$$

Hence it is easy to see that $\left\langle\left\langle M^{c}(f)\right\rangle\right\rangle_{t} \equiv 0$, i.e., $M_{t}^{c}(f) \equiv 0$,

$$
B_{t}(f)=\int_{0}^{t}\left\langle X_{s}, A f\right\rangle d s+t c_{0}\left\langle\tilde{m}, \partial_{d} f(\cdot, 0+)\right\rangle
$$

and

$$
\begin{aligned}
& \int_{0}^{t} \int\left[e^{-\langle\mu, f\rangle}-1+\langle\mu, f\rangle\right] \hat{N}(d s, d \mu) \\
& =\int_{0}^{t}\left\langle X_{s}, \Gamma f\right\rangle d s \\
& =\int_{0}^{t} d s \int X_{s}(d x)\left\{\int\left(e^{-[f(y)-f(x)]}-1+[f(y)-f(x)]\right) \nu(x, d y)\right. \\
& \left.\quad+k(x)\left(e^{f(x)}-1-f(x)\right)\right\}
\end{aligned}
$$

That is,

$$
\hat{N}(d s, d \mu)=d s \int X_{s}(d x)\left(\int v(x, d y) \delta_{\left(\delta_{y}-\delta_{x}\right)}+k(x) \delta_{-\delta_{x}}\right)(d \mu)
$$

Therefore we have the desired representation of $\left\langle X_{t}, f\right\rangle$ for $f \in C_{c}^{\infty}$. Finally it is possible to extend $f \in C_{c}^{\infty}$ to $f \in D_{g}$.

Moreover we can get the following (which is shown in the proof of Corollary 5.1 in [4]).

Lemma 3. For each $f \in\left(C_{c}^{\infty}\right)^{+}, t>0, A V_{t} f=-\log \left(1-P_{t}^{-}\left(1-e^{-f}\right)\right)$ is welldefined and $A V_{t} f$ is continuous in $t$ under the norm $\left\|\cdot / g_{p}\right\|_{\infty}$, i.e.,

$$
\left\|\left(A V_{t} f-A V_{t_{0}} f\right) / g_{p}\right\|_{\infty} \rightarrow 0 \quad\left(t \rightarrow t_{0}\right)
$$

Proof of (ii) in Theorem 1. In order to show the uniqueness of martingale problem it is enough to show that

$$
\exp \left[-\left\langle\tilde{X}_{t}, V_{T-t} f\right\rangle+\int_{0}^{t}\left\langle\nu_{T-r}, 1-e^{-f}\right\rangle d r\right]
$$

is $\mathbf{Q}_{\mu}$-martingale. In fact, this implies

$$
\tilde{\mathbf{Q}}_{\mu}\left[e^{-\left\langle\tilde{X}_{t}, f\right\rangle} \mid \mathcal{F}_{s}\right]=\exp \left[-\left\langle\tilde{X}_{s}, V_{t-s} f\right\rangle-\int_{0}^{t-s}\left\langle v_{u}, 1-e^{-f}\right\rangle d u\right] .
$$

Hence this implies the uniqueness in the sense of finite dimensional distributions, and separability of $\left(\mathcal{M}_{p, 0}, \rho\right)$ implies the uniqueness in the sense of distributions on $\left.\mathbf{D}\right)$.

Now for a fixed $f \in\left(C_{c}^{\infty}\right)^{+}$, by Lemma 2 we have

$$
\partial_{t} V_{t} f \quad \text { is continuous in } t \text { under the norm }\|\cdot\|_{g_{p, 0}}=\left\|\cdot / g_{p, 0}\right\|_{\infty}
$$

Moreover by the above lemma we see that

$$
\Gamma V_{t} f \in C_{b} \quad \text { is continuous in } t \text { under the norm }\left\|\cdot / g_{p}\right\|_{\infty}
$$

and $v_{t} \equiv v_{t}^{T}=V_{T-t} f(0 \leq t \leq T)$ is the unique solution to the equation:

$$
\left(\partial_{t}+A-\Gamma\right) v_{t}=0 \quad \text { and } \quad v_{T}=f .
$$

Let $\Phi(v)=e^{-v}$ and

$$
\phi_{t} \equiv \phi_{t}^{T}=\exp \left[\int_{0}^{t}\left\langle\nu_{T-r}, 1-e^{-f}\right\rangle d r\right] .
$$

By Theorem $3\left(\tilde{X}_{t}, \mathbf{Q}_{\mu}\right)$ has the same semi-martingale representation as ( $X_{t}, \mathbf{P}_{\mu}$ ). Hence by using the above results and Ito's formula the following is a $\mathbf{Q}_{\mu}$-martingale:

$$
\begin{aligned}
& \Phi\left(\left\langle\tilde{X}_{t}, v_{t}\right\rangle\right) \phi_{t}-\Phi\left(\left\langle\tilde{X}_{0}, v_{0}\right\rangle\right) \phi_{0}-\int_{0}^{t} \Phi\left(\left\langle\tilde{X}_{s}, v_{s}\right\rangle\right) \phi_{s}\left\langle v_{T-s, 1-e^{-f}}\right\rangle d s \\
& -\int_{0}^{t} \Phi^{\prime}\left(\left\langle\tilde{X}_{s}, v_{s}\right\rangle\right) \phi_{s}\left(\left\langle\tilde{X}_{s}, \partial_{s} v_{s}+A v_{s}\right\rangle+c_{0}\left\langle\tilde{m}, \partial_{d} v_{s}(\cdot, 0+)\right\rangle\right) d s \\
& -\int_{0}^{t} \int_{\mathcal{M}_{ \pm}}\left[\Phi\left(\left\langle\tilde{X}_{s}+\eta, v_{s}\right\rangle\right)-\Phi\left(\left\langle\tilde{X}_{s}, v_{s}\right\rangle\right)-\Phi^{\prime}\left(\left\langle\tilde{X}_{s}, v_{s}\right\rangle\right)\left\langle\eta, v_{s}\right\rangle\right] \phi_{s} \hat{N}(d s d \eta) \\
& =\exp \left[-\left\langle\tilde{X}_{t}, v_{t}\right\rangle\right] \phi_{t}-\exp \left[-\left\langle\tilde{X}_{0}, v_{0}\right\rangle\right]+\int_{0}^{t}\left\langle\tilde{X}_{s}, \partial_{s} v_{s}+A v_{s}\right\rangle \exp \left[-\left\langle\tilde{X}_{s}, v_{s}\right\rangle\right] \phi_{s} d s \\
& \quad-\int_{0}^{t}\left\langle\tilde{X}_{s}, \Gamma v_{s}\right\rangle \exp \left[-\left\langle\tilde{X}_{s}, v_{s}\right\rangle\right] \phi_{s} d s
\end{aligned}
$$

$$
\begin{aligned}
& =\exp \left[-\left\langle\tilde{X}_{t}, v_{t}\right\rangle\right] \phi_{t}-\exp \left[-\left\langle\tilde{X}_{0}, v_{0}\right\rangle\right]+\int_{0}^{t}\left\langle\tilde{X}_{s},\left(\partial_{s}+A-\Gamma\right) v_{s}\right\rangle \exp \left[-\left\langle\tilde{X}_{s}, v_{s}\right\rangle\right] \phi_{s} d s \\
& =\exp \left[-\left\langle\tilde{X}_{t}, V_{T-t} f\right\rangle\right] \phi_{t}-\exp \left[-\left\langle\tilde{X}_{0}, V_{T} f\right\rangle\right] .
\end{aligned}
$$

In the first equality we use

$$
\left\langle v_{T-s}, 1-e^{-f}\right\rangle=\lim _{r \downarrow 0}\left\langle v_{r}, V_{T-s} f\right\rangle=c_{0}\left\langle\tilde{m}, \partial_{d} v_{s}(\cdot, 0+)\right\rangle .
$$

Therefore we have the desired result.

## 3. Immigration particles near the boundary

For $S=\mathbf{R}^{d}$ or $H$, we denote

$$
\mu \in \mathcal{M}_{p}(S) \stackrel{\text { def }}{\Longleftrightarrow} \mu=\sum \delta_{x_{n}} \quad \text { on } S \text { such that } \quad\left\langle\mu, g_{p}\right\rangle<\infty .
$$

In particular, if $S=H$, then we simply denote $\mathcal{M}_{p}=\mathcal{M}_{p}(H)$.
Let $0<\alpha<2$ and $d<p<d+\alpha$. In [4] it is shown that if ( $X_{t}^{\alpha}, \mathbf{P}_{\mu}$ ) is an infinite independent Markov particle system associated with $\alpha$-stable motions, i.e., rotation invariant $\alpha$-stable processes on $\mathbf{R}^{d}$, starting from $X_{0}^{\alpha}=\mu \in \mathcal{M}_{p}\left(\mathbf{R}^{d}\right)$, then

$$
\mathbf{P}_{\mu}\left(X_{t}^{\alpha} \in \mathcal{M}_{p} \text { for all } t \geq 0\right)=1
$$

This implies that for the original part $\left(X_{t}^{O}, \mathbf{P}_{\mu}\right)$ (which is an infinite independent Markov particle system associated with absorbing stable motions on $H$ ), by $X_{t}^{O} \leq\left. X_{t}^{\alpha}\right|_{H}$, if $\mu \in$ $\mathcal{M}_{p}$, then

$$
\mathbf{P}_{\mu}\left(X_{t}^{O} \in \mathcal{M}_{p} \text { for all } t \geq 0\right)=1
$$

Moreover if $\mu \in \mathcal{M}_{p, 0}$ (and even if $\mu \notin \mathcal{M}_{p}$ ), then

$$
\mathbf{P}_{\mu}\left(X_{t}^{O} \in \mathcal{M}_{p} \text { for all } t>0\right)=1
$$

On the other hand for the immigration part $X_{t}^{I}$,

$$
\mathbf{E}\left[\left\langle X_{t}^{I}, g_{p}\right\rangle\right] \leq\left\langle m^{\alpha}, g_{p}\right\rangle
$$

and the right hand side is finite at least if $1<\alpha<2$. This implies that at least if $1<\alpha<2$, then for each fixed $t>0, \mathbf{P}\left(X_{t}^{I} \in \mathcal{M}_{p}\right)=1$ and

$$
\mathbf{P}\left(X_{t}^{I} \in \mathcal{M}_{p} \text { for } d t \text {-a.a. } t>0\right)=1 .
$$

Here we have the following question.

Question 1. For the immigration part $X_{t}^{I}$, which does it hold that $X_{t}^{I} \in \mathcal{M}_{p}$ or $X_{t}^{I} \in \mathcal{M}_{p, 0} \backslash \mathcal{M}_{p}$ for all $t>0$, P-a.s.?

We can obtain the following answer.
Theorem 4. For every $0<\alpha<2$ and for all $T>0$, it holds that

$$
\mathbf{P}\left(X_{t}^{I} \in \mathcal{M}_{p, 0} \backslash \mathcal{M}_{p} \text { for infinitely many t's in }(0, T]\right)=1 .
$$

This result depends on the number of particles near the boundary $\partial H$.
From now on, we only consider the immigration part $X_{t}^{I}$. and for simplicity, we consider the one-dimensional case, i.e., $d=1, H=(0, \infty)$ (the case of $d \geq 2$ is essentially the same).

For any $\varepsilon>0$, by $\nu_{t}(x)=t^{-2 / \alpha} \nu_{1}\left(t^{-1 / \alpha} x\right), \nu_{1}(y)=\left(p_{1}^{\alpha}\right)^{\prime}(y)$ and $\left|\left(p_{1}^{\alpha}\right)^{\prime}(y)\right| \leq C(1 \wedge$ $\left.y \wedge y^{-2-\alpha}\right)(y>0)$, we have

$$
\begin{aligned}
\int_{\varepsilon}^{\infty} v_{t}(x) d x & \leq t^{-1 / \alpha} \int_{t^{-1 / \alpha} \varepsilon}^{\infty} \nu_{1}(y) d y \\
& \leq C /(1+\alpha) t^{-1 / \alpha}\left(t^{-1 / \alpha} \varepsilon\right)^{-1-\alpha} \\
& =C /(1+\alpha) \varepsilon^{-1-\alpha} t \rightarrow 0 \quad(t \downarrow 0) .
\end{aligned}
$$

Moreover

$$
\begin{aligned}
\mathbf{E} X_{t}^{I}((0, \varepsilon)) & =\int_{0}^{t} \int_{W_{0}} 1_{(0, \varepsilon)}(w(t-s)) d s Q^{0}(d w) \\
& =\int_{0}^{t} \nu_{u}((0, \varepsilon)) d u \\
& \leq m^{\alpha}((0, \varepsilon))=c_{\alpha} \int_{0}^{\varepsilon} y^{\alpha-2} d y
\end{aligned}
$$

This is finite at least for $1<\alpha<2$. Hence Question 1 is reduced to the following.
Question 2. Let $\varepsilon>0$. At least if $1<\alpha<2$, then for each fixed time $t>0$, the number of particles near the boundary is finite with probability one: $\mathbf{P}\left(X_{t}^{I}((0, \varepsilon))<\right.$ $\infty)=1$. Moreover it also holds that

$$
\mathbf{P}\left(X_{t}^{I}((0, \varepsilon))<\infty \text { for } d t \text {-a.a. } t\right)=1 .
$$

Now does it hold that for each $0<\alpha<2$ and for any $0 \leq a<b$,

$$
\mathbf{P}\left(X_{t}^{I}((0, \varepsilon))<\infty, \text { for all } t \in(a, b)\right)=1 ?
$$

For this question we have the following answer, which implies Theorem 4.

Theorem 5. Let $\varepsilon>0$. For each $0<\alpha<2$ and for any $0 \leq a<b$,

$$
\mathbf{P}\left(X_{t}^{I}((0, \varepsilon))=\infty \text { for some } t \in(a, b)\right)=1
$$

REmARK 1. It also holds that $\mathbf{P}\left(\sup _{t \in \mathbf{Q} \cap(a, b)} X_{t}^{I}((0, \varepsilon))=\infty\right)=1$.
Proof of Theorem 5. For the absorbing Brownian motion on the half space, we already gave the same result in [2]. So the proof is essentially the same as it. However the key is the Claim 1 of the following proposition.

Let $\varepsilon>0 . X_{t}^{I}((0, \varepsilon))$ can be expressed as $N^{0}\left(D_{t}\right)$ with

$$
D_{t}=\left\{(s . w) \in[0, \infty) \times W_{0}: w(t-s) \in(0, \varepsilon), 0 \leq s<t\right\} .
$$

We define a smaller process $S_{k, t} \leq X_{t}^{I}((0, \varepsilon))$ as follows ( $k$ is determined by $\varepsilon$ ):


$$
\begin{aligned}
a_{k}= & 1 / 2^{k}, \quad b_{k}=a_{k}^{2 / \alpha}, \\
\xi^{k}:= & N^{0}\left(V^{k}\right): \text { the number of excursions in } V^{k}, \\
v^{k}= & \left\{(s, w) \in\left[0, a_{k}^{2}\right) \times W_{0} ;\right. \\
& w\left(a_{k}^{2}-s\right), w\left(2 a_{k}^{2}-s\right) \in\left[b_{k}, 2 b_{k}\right), \\
& w\left(3 a_{k}^{2}-s\right)=\Delta, \\
& \left.\gamma(w)<T_{\left[2 b_{k}, \infty\right)}^{a_{k}^{2}-s}(w)\right\},
\end{aligned}
$$

where $T_{[a, \infty)}^{t_{0}}(w)$ is the hitting time after the time $t_{0}$ to $[a, \infty)$ of $w$, i.e.,

$$
T_{[a, \infty)}^{t_{0}}(w):=\inf \left\{t>t_{0} ; w(t) \in[a, \infty)\right\}
$$

For each $j \geq 1$, let $t_{j}^{k}=j / 4^{k}$. If $t_{j}^{k} \leq t<t_{j+1}^{k}$, then set

$$
\xi_{t}^{k} \equiv \xi_{t_{j}^{k}}^{k}:=N^{0}\left(V_{j}^{k}\right) \quad \text { with } \quad V_{j}^{k}=\theta_{-t_{j-1}^{k}}\left(V^{k}\right)
$$

(note that $\xi_{t}^{k}$ is undefined for $0 \leq t<t_{1}^{k}$ ). It holds that $\xi_{t}^{k} \stackrel{(\mathrm{~d})}{=} \xi^{k}$. In particular, if we denote $\xi_{j}^{(k)}=\xi_{t_{j}^{k}}^{k}$, then $\left\{\xi_{j}^{(k)}: j=1,2, \ldots, k=1,2, \ldots\right\}$ are independent. Because $b_{k}=a_{k}^{2 / \alpha}>2 a_{k+1}^{2 / \alpha}=2 b_{k+1}$ by $2 / \alpha>1$ (this is important).

REMARK 2. $\xi^{k}$ denotes the number of particles which are born during the time interval $\left[0, a_{k}^{2}\right.$ ), stay in $\left[b_{k}, 2 b_{k}\right.$ ) at each time point $a_{k}^{2}, 2 a_{k}^{2}$ and die during the time
interval $\left(2 a_{k}^{2}, 3 a_{k}^{3}\right]$, and also which never hit $2 b_{k}$ after the time $a_{k}^{2}$. Also $\xi_{t}^{k}$ is the shifted $\xi^{k}$ by the time $t_{j-1}^{k}$ if $t_{j}^{k} \leq t<t_{j+1}^{k}$. Hence we may regard that the box $\left[t_{j}^{k}, t_{j+1}^{k}\right) \times$ $\left[b_{k}, 2 b_{k}\right.$ ) has the random number $\xi_{t}^{k}$.

Now for each $k \geq 1$, set

$$
S_{k, t}=\sum_{n=k}^{\infty} \xi_{t}^{n}
$$



Clearly for every $k ; 2 b_{k} \leq \varepsilon$, if $t \geq t_{1}^{k}\left(=a_{k}^{2}=1 / 4^{k}\right)$, then $S_{k, t} \leq X_{t}^{I}((0, \varepsilon))$. Hence in order to prove Theorem 5 it is enough to show the following proposition:

Proposition 1. For each $k, i \geq 1, \mathbf{P}\left(S_{k, t}=\infty\right.$ for some $\left.t_{1}^{k} \leq t<t_{i+1}^{k}\right)=1$.
Proof. We define a random variable $U_{k}^{*, i_{0}}$ for each $k, i_{0} \geq 1$ as follows:


We first start from $\xi_{j}^{(k)}$,s which take the maximum of $\xi_{j}^{(k)}, j=1,2, \ldots, i_{0}$, and look at $\xi_{j}^{(k+1)}$,s under the above $\xi_{j}^{(k)}$,s. Next we start from $\xi_{j}^{(k+1)}$,s which take the maximum of the above $\left\{\xi_{j}^{(k+1)}\right\}$. We continue these operations and define $U_{k}^{*, i_{0}}$ by adding each maximum number. That is, we set

$$
U_{k}^{1, i_{0}}=\max _{1 \leq j \leq i_{0}} \xi_{j}^{(k)}
$$

and

$$
\begin{aligned}
& I_{1}=\left\{i=1,2, \ldots, i_{0}: \xi_{i}^{(k)}=\max _{1 \leq j \leq i_{0}} \xi_{j}^{(k)}\right\}, \\
& J_{1}=4^{k}+\left[\left(4 I_{1}-3\right) \cup\left(4 I_{1}-2\right) \cup\left(4 I_{1}-1\right) \cup 4 I_{1}\right] .
\end{aligned}
$$

Also we define

$$
U_{k}^{2, i_{0}}=U_{k}^{1, i_{0}}+\max _{j \in J_{1}} \xi_{j}^{(k+1)}
$$

If we have $I_{n}, J_{n}, U_{k}^{n+1, i_{0}}$, then set

$$
\begin{aligned}
& I_{n+1}=\left\{i \in J_{n}: \xi_{i}^{(k+n)}=\max _{j \in J_{n}} \xi_{j}^{(k+n)}\right\} \\
& J_{n+1}=4^{k+n}+\left[\left(4 I_{n+1}-3\right) \cup\left(4 I_{n+1}-2\right) \cup\left(4 I_{n+1}-1\right) \cup 4 I_{n+1}\right]
\end{aligned}
$$

and

$$
U_{k}^{n+2, i_{0}}=U_{k}^{n+1, i_{0}}+\max _{j \in J_{n+1}} \xi_{j}^{(k+n+1)}
$$

So we define

$$
U_{k}^{*, i_{0}}=\lim _{n \rightarrow \infty} U_{k}^{n, i_{0}}
$$

We can show the following two claims:
Claim 1. $\lambda_{k}:=\mathbf{E} \xi^{k}=\lambda_{0} / 2^{k(2-2 / \alpha)}=2^{2 / \alpha-2} \lambda_{k-1}$ for all $k \geq 1\left(\lambda_{0}=\mathbf{E} \xi^{0}>0\right)$.

Claim 2. For each $k, i_{0} \geq 1, \mathbf{P}\left(U_{k}^{*, i_{0}}=\infty\right)=1$.
Obviously Claim 2 implies Proposition 1.

Proof of Claim 1. Let $\left(w^{\alpha}(t), P_{x}^{\alpha}\right)$ be the rotation invariant $\alpha$-stable process on $\mathbf{R}$.
Then for $a>0, w^{\alpha}\left(a^{2} t\right) \stackrel{(\mathrm{d})}{=} a^{2 / \alpha} w^{\alpha}(t)$ and recall $v_{r}\left(a^{2 / \alpha} x\right)=a^{-4 / \alpha} v_{r / a^{2}}(x)(r, x>0)$.

Let $V_{s}^{k}$ denote the $s$-section of $V^{k}$.

$$
\begin{aligned}
& \lambda_{k}= \mathbf{E} N^{0}\left(V^{k}\right)=\int_{0}^{a_{k}^{2}} d s Q^{0}\left(V_{s}^{k}\right) \\
&= \int_{0}^{a_{k}^{2}} d s Q^{0}\left(w\left(a_{k}^{2}-s\right) \in\left[b_{k}, 2 b_{k}\right),\right. \\
&\left.w\left(2 a_{k}^{2}-s\right) \in\left[b_{k}, 2 b_{k}\right), w\left(3 a_{k}^{2}-s\right)=\Delta, \gamma(w)<T_{\left[2 b_{k}, \infty\right)}^{a_{k}^{2}-s}(w)\right) \\
&= \int_{0}^{a_{k}^{2}} d u Q^{0}\left(w(u) \in\left[b_{k}, 2 b_{k}\right),\right. \\
&=\left.\int_{0}^{a_{k}^{2}} d u \int_{b_{k}}^{2 b_{k}} d x a_{k}^{2}+u\right) \in\left[b_{k}, 2 b_{k}\right), w\left(2 a_{k}^{2}+u\right) P_{x}^{-}\left(w^{-}\left(a_{k}^{2}\right) \in\left[b_{k}, 2 b_{k}\right), \zeta\left(w^{-}\right) \leq\left(2 a_{k}^{2}\right) \wedge T_{\left[2 b_{k}, \infty\right)}\left(w^{-}\right)\right) \\
&= \int_{0}^{a_{k}^{2}} d u \int_{b_{k}}^{2 b_{k}} d x v_{u}(x) P_{x}^{\alpha}\left(w^{\alpha}\left(a_{k}^{2}\right) \in\left[b_{k}, 2 b_{k}\right), a_{k}^{2}<\zeta\left(w^{\alpha}\right) \leq\left(2 a_{k}^{2}\right) \wedge T_{\left[2 b_{k}, \infty\right)}\left(w^{\alpha}\right)\right),
\end{aligned}
$$

where $T_{[a, \infty)}=T_{[a, \infty)}^{0}$ is a hitting time to $[a, \infty)$ of $w^{-}(t)$ or $w^{\alpha}(t)$, and $\zeta\left(w^{\alpha}\right)$ is essentially the same as $\zeta\left(w^{-}\right)$. That is, by $w^{\alpha}(t)=B\left(y^{\alpha / 2}(t)\right)$

$$
\zeta\left(w^{\alpha}\right):=\inf \left\{t>0 ; y^{\alpha / 2}(t) \geq T_{0}(B)\right\}
$$

where $\{B(t)\}$ is the Brownian motion on $\mathbf{R}$ which is independent of $\left\{y^{\alpha / 2}(t)\right\}$ such that $B(0)=x$, and $T_{0}(B)$ is the hitting time to 0 of $B(t)$. By changing variables $u / a_{k}^{2}=v$, $x / b_{k}=y$ and by using scaling properties; $w^{\alpha}\left(a_{k}^{2} t\right) \stackrel{(\mathrm{d})}{=} a_{k}^{2 / \alpha} w^{\alpha}(t)=b_{k} w^{\alpha}(t), v_{a_{k}^{2} v}\left(b_{k} y\right)=$ $b_{k}^{-2} v_{v}(y)$, we have

$$
\begin{aligned}
\lambda_{k} & =\int_{0}^{1} a_{k}^{2} d v \int_{1}^{2} b_{k} d y v_{a_{k}^{2} v}\left(b_{k} y\right) P_{b_{k} y}^{\alpha}\left(w^{\alpha}\left(a_{k}^{2}\right) \in\left[b_{k}, 2 b_{k}\right), a_{k}^{2}<\zeta\left(w^{\alpha}\right) \leq\left(2 a_{k}^{2}\right) \wedge T_{\left[2 b_{k}, \infty\right)}\left(w^{\alpha}\right)\right) \\
& =\int_{0}^{1} a_{k}^{2} d v \int_{1}^{2} b_{k} d y b_{k}^{-2} v_{v}(y) P_{y}^{\alpha}\left(b_{k} w^{\alpha}(1) \in\left[b_{k}, 2 b_{k}\right), 1<\zeta\left(w^{\alpha}\right) \leq 2 \wedge T_{[2, \infty)}\left(w^{\alpha}\right)\right) \\
& =a_{k}^{2} b_{k}^{-1} \int_{0}^{1} d v \int_{1}^{2} d y v_{v}(y) P_{y}^{\alpha}\left(w^{\alpha}(1) \in[1,2), 1<\zeta\left(w^{\alpha}\right) \leq 2 \wedge T_{[2, \infty)}\left(w^{\alpha}\right)\right) \\
& =a_{k}^{2-2 / \alpha} \lambda_{0}
\end{aligned}
$$

where we use the following result. For $a>0$, by $y^{\alpha / 2}(a t)=a^{4 / \alpha} y^{\alpha / 2}(t), \zeta\left(w^{\alpha}\left(a^{2} \cdot\right)\right)$ under $P_{a^{2 / \alpha} y}^{\alpha}$ has the same distribution as $\zeta\left(a^{2 / \alpha} w^{\alpha}(\cdot)\right)=\zeta\left(w^{\alpha}\right)$ under $P_{y}^{\alpha}$. In fact, under $P_{b y}^{\alpha},\left[\zeta\left(w^{\alpha}\right)>a^{2} t \Longleftrightarrow T_{0}(B)>y^{\alpha / 2}\left(a^{2} t\right) \Longleftrightarrow T_{0}(B)>a^{4 / \alpha} y^{\alpha / 2}(t) \Longleftrightarrow \exists t_{0}>\right.$ $\left.y^{\alpha / 2}(t) ; B\left(a^{4 / \alpha} t_{0}\right)=0\right] \Longleftrightarrow$ under $P_{y}^{\alpha},\left[\exists t_{0}>y^{\alpha / 2}(t) ; a^{2 / \alpha} B\left(t_{0}\right)=0\right.$, i.e., $B\left(t_{0}\right)=0 \Longleftrightarrow$ $\left.T_{0}(B)>y^{\alpha / 2}(t) \Longleftrightarrow \zeta\left(w^{\alpha}\right)>t\right]$.

The positivity of $\lambda_{0}=\mathbf{E} \xi^{0}$ would be intuitively obvious. However for the completeness of the proof we shall show it. Recall

$$
\lambda_{0}=\int_{0}^{1} d t \int_{1}^{2} d x v_{t}(x) P_{x}^{\alpha}\left(w^{\alpha}(1) \in[1,2), 1<\zeta\left(w^{\alpha}\right) \leq 2 \wedge T_{[2, \infty)}\left(w^{\alpha}\right)\right)
$$

By $w^{\alpha}(t) \stackrel{(\mathrm{d})}{=} B\left(y^{\alpha / 2}(t)\right)$ and independence of $\{B(t)\},\left\{y^{\alpha / 2}\right\}$, we have

$$
\begin{aligned}
& P_{x}^{\alpha}\left(w^{\alpha}(1) \in[1,2), 1<\zeta\left(w^{\alpha}\right) \leq 2 \wedge T_{[2, \infty)}\left(w^{\alpha}\right)\right) \\
& \geq P_{0}\left(y^{\alpha / 2}(1) \in[1,1+\varepsilon), y^{\alpha / 2}(2) \geq 2\right) \\
& \quad \times P_{x}\left(B(t) \in(1,2) \text { for all } 0 \leq t \leq 1+\varepsilon, T_{0} \leq 2, T_{0}<T_{2}\right) .
\end{aligned}
$$

Moreover for $0<\varepsilon<1 / 2$,

$$
\begin{aligned}
& P_{0}\left(y^{\alpha / 2}(1) \in[1,1+\varepsilon), y^{\alpha / 2}(2) \geq 2\right) \\
& \geq P_{0}\left(y^{\alpha / 2}(1) \in[1,1+\varepsilon)\right) P_{0}\left(y^{\alpha / 2}(1) \geq 1\right)=: C_{\varepsilon}>0 .
\end{aligned}
$$

If $1<x<2$, then

$$
\begin{aligned}
& P_{x}\left(B(t) \in(1,2) \text { for all } 0 \leq t \leq 1+\varepsilon, T_{0} \leq 2, T_{0}<T_{2}\right) \\
& \geq \int_{1}^{2} d y p_{1+\varepsilon}^{1,2}(x, y) P_{y}\left(T_{0} \leq 2, T_{0}<T_{2}\right)
\end{aligned}
$$

where $p_{t}^{1,2}(x, y)=p_{t}^{0,1}(x-1, y-1)$ and for $0<u, v<b$

$$
p_{t}^{0, b}(u, v)=P_{u}\left(B(t)=v ; t<T_{0} \wedge T_{b}\right)=\sum_{n=-\infty}^{\infty} p_{t}^{0}(u, v+2 n b)
$$

with

$$
p_{t}^{0}(u, v)=p_{t}(u, v)-p_{t}(u,-v) \quad \text { and } \quad p_{t}(u, v)=\frac{1}{\sqrt{2 \pi t}} e^{-(v-u)^{2} /(2 t)}
$$

and for $0<y<b$

$$
P_{y}\left(T_{0} \in d t ; T_{0}<T_{b}\right)=\frac{d t}{\sqrt{2 \pi t^{3}}} \sum_{n=-\infty}^{\infty}(y+2 n b) \exp \left[-\frac{(y+2 n b)^{2}}{2 t}\right]
$$

Hence

$$
\lambda_{0} \geq C_{\varepsilon} \int_{0}^{1} d t \int_{1}^{2} d x v_{t}(x) \int_{1}^{2} d y p_{1+\varepsilon}^{1,2}(x, y) P_{y}\left(T_{0} \leq 2, T_{0}<T_{2}\right)
$$

By the continuities and the positivities of $p_{1+\varepsilon}^{1,2}(x, y), P_{y}\left(T_{0} \leq 2, T_{0}<T_{2}\right)$, we have $\lambda_{0}>0$. (Note that the positivities follows directly from the positivities of each sum of terms for $n=k,-k-1(k \geq 0)$ in the above summations in $n \in \mathbf{Z}$.)


Proof of Claim 2. We shall show that for each $k, i_{0} \geq 1$ and $m \geq 0, \mathbf{P}\left(U_{k}^{*, i_{0}} \leq\right.$ $m)=0$ by the mathematical induction.
(1) For each $k, i_{0} \geq 1, \mathbf{P}\left(U_{k}^{*, i_{0}}=0\right)=0$.

In fact, if $U_{k}^{*, i_{0}}=0$, then $\xi_{j}^{(k+n)}=0$ for all $n \geq 0,4^{n} \leq j<4^{n}\left(i_{0}+1\right)$. However the sum of these expectations is given as $i_{0}\left(\lambda_{k}+4 \lambda_{k+1}+4^{2} \lambda_{k+2}+\cdots\right)$ and this is infinite by Claim 1 (the rate is $4\left(a_{k+1} / a_{k}\right)^{2-2 / \alpha}=2^{2} \cdot 2^{2 / \alpha-2}=2^{2 / \alpha}>1$ ). Hence the probability of this event is 0 .

$$
\begin{aligned}
\mathbf{P}\left(U_{k}^{*, i_{0}}=0\right) & \leq \lim _{n \rightarrow \infty} \mathbf{P}\left(\xi^{k}=0\right)^{i_{0}} \mathbf{P}\left(\xi^{k+1}=0\right)^{4_{0}} \cdots \mathbf{P}\left(\xi^{k+n}=0\right)^{4^{n} i_{0}} \\
& =\lim _{n \rightarrow \infty} \exp \left[-i_{0}\left(\lambda_{k}+4 \lambda_{k+1}+\cdots+4^{n} \lambda_{k+n}\right)\right]=0 .
\end{aligned}
$$

(2) If we assume that $\mathbf{P}\left(U_{k}^{* i_{0}} \leq m-1\right)=0$ for all $k, i_{0} \geq 1$, then

$$
\begin{aligned}
\mathbf{P}\left(U_{k}^{*, i_{0}} \leq m\right)= & \sum_{m_{k}=0}^{m} \mathbf{P}\left(\xi^{k}=m_{k}\right)^{i_{0}} \mathbf{P}\left(U_{k+1}^{*, 4 i_{0}} \leq m-m_{k}\right) \\
& +\sum_{j=1}^{i_{0}-1}\binom{i_{0}}{j} \sum_{m_{k}=1}^{m} \mathbf{P}\left(\xi^{k}=m_{k}\right)^{j} \mathbf{P}\left(\xi^{k} \leq m_{k}-1\right)^{i_{0}-j} \mathbf{P}\left(U_{k+1}^{*, 4 j} \leq m-m_{k}\right) \\
= & \mathbf{P}\left(\xi^{k}=0\right)^{i_{0}} \mathbf{P}\left(U_{k+1}^{*, 4 i_{0}} \leq m\right) \\
= & \mathbf{P}\left(\xi^{k}=0\right)^{i_{0}} \mathbf{P}\left(\xi^{k+1}=0\right)^{4 i_{0}} \mathbf{P}\left(U_{k+2}^{*, 4^{2} i_{0}} \leq m\right) \\
\leq & \mathbf{P}\left(\xi^{k}=0\right)^{i_{0}} \mathbf{P}\left(\xi^{k+1}=0\right)^{4 i_{0}} \cdots \mathbf{P}\left(\xi^{k+n}=0\right)^{4^{n} i_{0}} \\
= & \exp \left[-i_{0}\left(\lambda_{k}+4 \lambda_{k+1}+\cdots+4^{n} \lambda_{k+n}\right)\right] \rightarrow 0 \quad(n \rightarrow \infty)
\end{aligned}
$$

by Claim 1. This implies $\mathbf{P}\left(U_{k}^{* i_{0}} \leq m\right)=0$ for all $k, i_{0} \geq 1$.
(3) From the above results (1) and (2) we have Claim 2.

Proof of Remark 1. For each $k \geq 1$, we set

$$
S_{k}^{*} \equiv \lim _{n \rightarrow \infty} \max _{t_{1}^{k} \leq t<t_{2}^{k}} \sum_{j=k}^{k+n} \xi_{t}^{j}
$$

It holds that for all $m \geq 0$,

$$
\mathbf{P}\left(S_{k}^{*} \leq m\right)=\sum_{m_{k}=0}^{m} \mathbf{P}\left(\xi^{k}=m_{k}\right) \mathbf{P}\left(S_{k+1}^{*} \leq m-m_{k}\right)^{4}
$$

Hence by the same way as in the case of $U_{k}^{*, i}$, we can show $\mathbf{P}\left(S_{k}^{*} \leq m\right)=0$ for all $m \geq 0$. This implies for all $\varepsilon>0$ and $k ; 2 b_{k} \leq \varepsilon, \mathbf{P}\left(\sup _{t \in \mathbf{Q} \cap\left[t_{1}^{k}, t_{2}^{k}\right)} X_{t}^{I}((0, \varepsilon))=\infty\right)=1$. Furthermore if we change $t_{1}^{k}, t_{2}^{k}$ to any $t_{j}^{k}, t_{j+1}^{k}(j \geq 1)$, then the same result holds.

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> Department of Mathematics
> Faculty of Science and Technology
> Tokyo University of Science 2641 Yamazaki, Noda City Chiba 278-8510 Japan e-mail: hiraba_seiji@ma.noda.tus.ac.jp


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