NOTE ON THE LEFSCHETZ FIXED POINT THEOREM

Dedicated to Professor A. Komatu on his 60th birthday

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1. Introduction

Let V be an open set of the *n*-dimensional euclidean space \mathbb{R}^n , and $f: V \to \mathbb{R}^n$ be a continuous map such that the fixed point set $F = \{x \in V | f(x) = x\}$ is compact. If $i: V \subset \mathbb{R}^n$, then i-f maps (V, V-F) to $(\mathbb{R}^n, \mathbb{R}^n = 0)$. Considering the homomorphism of the integral homology groups induced by i-f, A. Dold [2] defines the fixed point index $I_f \in \mathbb{Z}$ by

$$(i-f)_*\mu_F^V = I_f\mu_0$$
,

where $\mu_0 \in H_n(\mathbb{R}^n, \mathbb{R}^n - 0; \mathbb{Z})$ is an orientation of \mathbb{R}^n and $\mu_F \in H_n(V, V - F; \mathbb{Z})$ is the 'fundamental' class corresponding to the orientation μ_0 . With this definition, he proves the following Lefschetz fixed point theorem:

Theorem A. Let V be an open set of \mathbb{R}^n , and $f: V \to V$ be a continuous map such that f(V) is contained in a compact set $K \subset V$. Then the fixed point index I_f of f and the Lefschetz number of $(f|K)_*: H_*(K; \mathbf{Q}) \to H_*(K; \mathbf{Q})$ are both defined and they agree, where \mathbf{Q} is the field of rational numbers.

Precisely, he proves the theorem in which V is replaced by a euclidean neighborhood retract Y. However this generalization follows directly from the above one, because he defines the fixed point index of $f: Y \rightarrow Y$ to be that of the composite $i \circ f \circ r: V \rightarrow V$, where $i: Y \rightarrow V$, $r: V \rightarrow Y$ ($r \circ i = id$) is a euclidean neighborhood retraction.

On the other hand, R. Brown [1] shows the Lefschetz fixed point theorem for a compact orientable *n*-dimensional topological manifold M (see also [3]). Taking an orientation of M, let $\mu \in H_n(M; \mathbb{Z})$ and $U \in H^n(M \times M, M \times M - d(M); \mathbb{Z})$ denote the corresponding fundamental class and Thom class respectively, where d(M) is the diagonal of $M \times M$. Denote by $U' \in H^n(M \times M; \mathbb{Z})$ the image of U under the natural homomorphism. Then the theorem of Brown is as follows:

Theorem B. Let M be a compact orientable n-dimensional topological

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manifold, and $f: M \to M$ be a continuous map. Define $\hat{f}: M \to M \times M$ by $\hat{f}(x) = (f(x), x)$ for $x \in M$. Then the Kronecker product $\langle \hat{f}^*U', \mu \rangle$ is equal to the Lefschetz number of $f_*: H_*(M; Q) \to H_*(M; Q)$.

The purpose of this note is to prove a theorem which contains Theorem A and B as corollaries.

Let M be an orientable *n*-dimensional topological manifold which is not necessarily compact, and $f: M \to M$ be a continuous map such that the fixed point set F of f is compact. Take an orientation of M. Then the Thom class $U \in H^n(M \times M, M \times M - d(M); \mathbb{Z})$ and the fundamental class $\mu_F \in H_n(M, M - F; \mathbb{Z})$ are well-defined. Considering $\hat{f}: (M, M - F) \to (M \times M, M \times M - d(M))$, we define the fixed point index I(f) by

$$I(f) = \langle U, \hat{f}_* \mu_F \rangle \in \mathbb{Z}$$
.

Then our theorem is stated as follows:

Theorem C. Let M be an orientable n-dimensional topological manifold, and $f: M \to M$ be a continuous map such that f(M) is contained in a compact set $K \subset M$. Then the fixed point index I(f) of f and the Lefschetz number of $(f|K)_*$: $H_*(K; \mathbf{Q}) \to H_*(K; \mathbf{Q})$ are both defined and they agree.

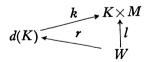
Our proof of this theorem is different from that of Theorem A due to Dold. Therefore this paper gives another proof of Theorem A.

The method we use to prove Theorem C is essentially the one due to J. Milnor [4] and is the one employed by Brown to prove Theorem B.

2. A fundamental lemma

Let M be an n-dimensional topological manifold, and $d: M \rightarrow M \times M$ be the diagonal map. Let K be a compact subset of M.

Lemma 1. There are an open neighborhood W of d(K) in $K \times M$ and a retraction $r: W \rightarrow d(K)$ such that the diagram



is homotopy commutative, where k and l are the inclusion maps.

Proof. For r > 0, let

$$O_r = \{(x_1, \dots, x_n) \in \mathbf{R}^n | x_1^2 + \dots + x_n^2 < r\}.$$

It is easily seen that there exists a finite set $\{V_1, \dots, V_s\}$ of coordinate neighbor-

hoods of M such that

$$\bigcup_{i=1}^{s} h_i^{-1}(O_1) \supset K,$$

where $h_i: V_i \approx \mathbf{R}^n$ is a homeomorphism.

Put

$$\begin{split} V'_i &= h_i^{-1}(O_1) \,, \quad V''_i = h_i^{-1}(O_2) \,, \\ V' &= \bigcup_{i=1}^s V'_i \,, \quad V'' = \bigcup_{i=1}^s V''_i \,. \end{split}$$

The space $\overline{\mathcal{V}''}/\overline{\mathcal{V}''}-V''_i$ obtained from the closure $\overline{\mathcal{V}''}$ by identifying $\overline{\mathcal{V}''}-V''_i$ to one point is homeomorphic with the *n*-sphere S^n . Therefore a homeomorphism f of V'' into $S^n \times \cdots \times S^n$ (s times) is defined by

$$f(x) = (f_1 p_1(x), \dots, f_s p_s(x)) \qquad (x \in V''),$$

where $p_i: \overline{V}'' \to \overline{V}''/\overline{V}'' - V_i''$ is the projection and $f_i: \overline{V}''/\overline{V}'' - V_i'' \approx S^n$ is a homeomorphism. Since $\overline{V}' \subset V''$ and $S^n \times \cdots \times S^n \subset \mathbb{R}^m (m=(n+1)s)$, we can regard \overline{V}' as a closed subset of \mathbb{R}^m . Since each V_i is an ANR, so is $V = \bigcup_{i=1}^{s} V_i$.

Consequently, the inclusion map $\overline{V}' \subset V$ has an extension $g: Q \to V$, where Q is a neighborhood of \overline{V}' in \mathbb{R}^m . It is obvious that there exists $\varepsilon > 0$ such that if $x, y \in \overline{V}'$ and the distance from x to y in \mathbb{R}^m is smaller than ε then $(1-t)x+ty \in Q$ for any $t \in [0, 1]$. Put

$$W = \{(x, y) \in K \times V' | d(x, y) < \varepsilon\},\$$

and define $r: W \rightarrow d(K)$ by r(x, y) = (x, x).

We can now define a homotopy $f_t: W \rightarrow K \times M$ of $k \circ r$ to l by

$$f_t(x, y) = (x, g((1-t)x+ty)).$$
 q.e.d.

Let R be a fixed principal ideal domain, and we shall take coefficients of homology and cohomology from R. Consider the cup product

$$\smile$$
: $H^*(K \times (M, M - K)) \otimes H^*(K \times M)$
 $\rightarrow H^*(K \times (M, M - K))$.

Lemma 2. For $\alpha \in H^*(M)$ and $\gamma \in H^*(K \times M, K \times M - d(K))$ we have

$$j^*\gamma \smile p_1^*i^*\alpha = j^*\gamma \smile p_2^*\alpha$$

where $p_1: K \times M \to K$, $p_2: K \times M \to M$ are the projections and $i: K \to M$, $j: K \times (M, M-K) \to (K \times M, K \times M-d(K))$ are the inclusion maps.

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Proof. By Lemma 1 and the naturality of the cup product, we have a commutative diagram

If we define $p: d(K) \rightarrow K$ by p(x, x) = x ($x \in K$), then it holds that $p_1 \circ k = p$ and $p_2 \circ k = i \circ p$. Therefore it follows that

$$l^*(\gamma \smile p_1^* i^* \alpha) = l^* \gamma \smile r^* k^* p_1^* i^* \alpha$$
$$= l^* \gamma \smile r^* p^* i^* \alpha = l^* \gamma \smile r^* k^* p_2^* \alpha$$
$$= l^*(\gamma \smile p_2^* \alpha) .$$

Since $l^*: H^*(K \times M, K \times M - d(K)) \cong H^*(W, W - d(K))$ is an excision isomorphism, we obtain

$$\gamma \smile p_2^* i^* lpha = \gamma \smile p_2^* lpha$$
 .

This, together with the naturality of the cup product, implies the desired result. q.e.d.

For topological pairs (X, A) and (Y, B), consider the slant product

 $|: H^*((X, A) \times (Y, B)) \otimes H_*(Y, B) \rightarrow H^*(X, A)$.

The following relations hold between the cup, cap and slant products: For $\gamma \in H^*((X \ A) \times (Y, B))$, $\alpha \in H^*(X)$, $\beta \in H^*(Y)$ and $b \in H_*(Y, B)$, we have

(1)
$$\alpha \smile (\gamma/b) = (p_1^* \alpha \smile \gamma)/b,$$

 $\gamma/(\beta \frown b) = (\gamma \smile p_2^* \beta)/b$

in $H^*(X, A)$, where $p_1: X \times Y \to X$ and $p_2: X \times Y \to Y$ are the projections (see [5]).

By an orientation μ over R of an *n*-dimensional topological manifold M we mean a function which assigns to each $x \in M$ a generator μ_x of $H_n(M, M-x)$ which "varies continuously" with x, in the following sense. For each x there exist a neighborhood N and an element $\mu_N \in H_n(M, M-N)$ such that the image of μ_N in $H_n(M, M-y)$ under the natural homomorphism is μ_y for each $y \in N$.

If an orientation over R of the manifold M exists, M is called *orientable* over R.

Assume that M is orientable over R and an orientation μ of M is given. Then it is known that, for each compact subset K of M, there is a unique element $\mu_K \in H_n(M, M-K)$ whose image in $H_n(M, M-x)$ under the natural homomorphism is μ_x for any $x \in K$ (see [3]). It is also known that there exists a unique

element $U \in H^n(M \times M, M \times M - d(M))$ such that

$$\langle l_x^* U, \mu_x \rangle = 1$$

for any $x \in M$, where $l_x : (M, M-x) \rightarrow (M \times M, M \times M - d(M))$ is a continuous map sending $x' \in M$ to $(x, x') \in M \times M$ (see [3], [5]). Denote by $U_K \in$ $H^n(K \times (M, M - K))$ the image of U under the natural homomorphism.

A simple calculation shows

$$(2) U_{\kappa}/\mu_{\kappa}=1.$$

We shall now prove the following fundamental lemma.

Lemma 3. The diagram

is commutative, where $i: K \subset M$.

Proof. For $\alpha \in H^{q}(M)$, we obtain by (1), (2) and Lemma 2

$$U_{\mathcal{K}}/(\alpha \frown \mu_{\mathcal{K}}) = (U_{\mathcal{K}} \smile p_2^* \alpha)/\mu_{\mathcal{K}}$$

= $(U_{\mathcal{K}} \smile p_1^* i^* \alpha)/\mu_{\mathcal{K}} = (-1)^{n_q} (p_1^* i^* \alpha \smile U_{\mathcal{K}})/\mu_{\mathcal{K}}$
= $(-1)^{n_q} i^* \alpha \smile (U_{\mathcal{K}}/\mu_{\mathcal{K}}) = (-1)^{n_q} i^* \alpha$,

which proves the desired result. q.e.d.

3. Lefschetz fixed point theorem

Let M be an *n*-dimensional topological manifold which is orientable over R. Let V be an open set of M, and K be a compact subset of V. Given an orientation μ of M, we shall denote by $\mu_K^V \in H_n(V, V-K)$ the element corresponding to μ_K under the excision isomorphism $H_n(V, V-K) \cong H_n(M, M-K)$.

If $f: V \rightarrow M$ is a continuous map such that the fixed point set F is compact, then we call

$$I(\hat{f}) = \langle U, \hat{f}_* \mu_F^V \rangle \in R$$

the fixed point index of f, where $\hat{f}: (V, V-F) \rightarrow (M \times M, M \times M - d(M))$ is a continuous map given by $\hat{f}(x) = (f(x), x)$ ($x \in V$). It follows that I(f) is independent of the choice of orientation.

For a compact set K such that $F \subset K \subset M$, we have

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$$(3) I(f) = \langle U, \hat{f}_* \mu_K^V \rangle,$$

where $\hat{f}_*: H_n(V, V-K) \rightarrow H_n(M \times M, M \times M - d(M))$. This follows from that μ_F^V is the image of μ_K^V under the natural homomorphism.

Lemma 4. In the case $M = \mathbf{R}^n$, we have

 $(i-f)_*\mu_F^V = I(f)\mu_0$,

where $i-f:(V, V-F) \rightarrow (\mathbb{R}^n, \mathbb{R}^n-0)$ is a continuous map sending $x \in V$ to $x-f(x) \in \mathbb{R}^n$.

Proof. Define $\Delta : (\mathbf{R}^n \times \mathbf{R}^n, \mathbf{R}^n \times \mathbf{R}^n - d(\mathbf{R}^n)) \rightarrow (\mathbf{R}^n, \mathbf{R}^n - 0)$ by $\Delta(x, y) = y - x$ $(x, y \in \mathbf{R}^n)$. Then, for $l_0 : (\mathbf{R}^n, \mathbf{R}^n - 0) \rightarrow (\mathbf{R}^n \times \mathbf{R}^n, \mathbf{R}^n \times \mathbf{R}^n - d(\mathbf{R}^n))$, we have $\Delta \circ l_0 = id$. Denote by $\overline{\mu}_0 \in H^n(\mathbf{R}^n, \mathbf{R}^n - 0)$ the dual to $\mu_0 \in H_n(\mathbf{R}^n, \mathbf{R}^n - 0)$. Since $\langle l_0^* \Delta^* \overline{\mu}_0, \mu_0 \rangle = 1$, we have

$$\Delta^* \overline{\mu}_0 = U \in H^n(\mathbf{R}^n \times \mathbf{R}^n, \mathbf{R}^n \times \mathbf{R}^n - d(\mathbf{R}^n)).$$

Since $\Delta \circ \hat{f} = i - f$, we obtain

$$I(f) = \langle \Delta^* \overline{\mu}_{\scriptscriptstyle 0}, \hat{f}_* \mu_F^V
angle = \langle \overline{\mu}_{\scriptscriptstyle 0}, (i-f)_* \mu_F^V
angle,$$

which shows the desired result. q.e.d.

Let N be a graded module over a field R, and $\varphi : N \rightarrow N$ be an endomorphism of degree 0 which factors through a finitely generated graded module. Taking a homogeneous basis $\{a_{\lambda}\}$ of N, put

$$\varphi(a_{\lambda}) = \sum_{\mu} r_{\lambda\mu} a_{\mu} \qquad (r_{\lambda\mu} \in R) \,.$$

Then it follows that $r_{\lambda\lambda}$ is zero except a finite number of λ , and that

$$\Lambda(\varphi) = \sum_{\lambda} (-1)^{\deg a_{\lambda}} r_{\lambda\lambda} \in \mathbb{R}$$

is independent of the choice of $\{a_{\lambda}\}$ (see [2]). $\Lambda(\phi)$ is called the *Lefschetz* number of φ .

Theorem D. Let M be an n-dimensional topological manifold which is orientable over a field R, and let $f: M \to M$ be a continuous map such that f(M) is contained in a compact set $K \subset M$. Then the fixed point index I(f) of f and the Lefschetz number $\Lambda((f|K)_*)$ of the homomorphism $(f|K)_*: H_*(K) \to H_*(K)$ of homology with coefficients in R are both defined and they agree.

Proof. The fixed point set F of f is a closed subset of K, and hence is compact. Therefore I(f) is defined.

From Lemma 3 it follows that the diagram

$$\begin{array}{c} H^{q}(K) \xrightarrow{(-1)^{nq}(f|K)^{*}} H^{q}(K) \\ \downarrow f^{*} & \uparrow U_{K} \\ H^{q}(M) \xrightarrow{\frown \mu_{K}} H_{n-q}(M, M-K) \end{array}$$

is commutative. It is obvious from the definition of the cap product that the image of the homomorphism $\frown \mu_K$ is finitely generated. Therefore $(f|K)^*$ factors through a finitely generated module, and hence $\Lambda((f|K)^*)$ is defined.

Let $\{\alpha_{\lambda}\}$ $\{\beta_{\mu}\}$ and $\{\rho_{\nu}\}$ be homogeneous bases of $H^{*}(M)$, $H^{*}(M, M-K)$ and $H^{*}(K)$ respectively, and put

$$f^*(
ho_
u) = \sum_{\lambda} m_{
u\lambda} lpha_{\lambda} ,$$

 $U_K = \sum_{
u,\mu} c_{
u\mu}
ho_
u imes eta_{\mu} ,$
 $\langle eta_\mu \smile lpha_{\lambda}, \ \mu_K
angle = y_{\mu\lambda} .$

Then it follows from the above commutative diagram that

$$(-1)^{n \operatorname{deg} \rho_{\nu}}(f \mid K)^{*} \rho_{\nu} = U_{K}/(f^{*} \rho_{\nu} \frown \mu_{K})$$

$$= \sum_{\kappa,\mu} (c_{\kappa\mu}\rho_{\kappa} \times \beta_{\mu})/(f^{*} \rho_{\nu} \frown \mu_{K})$$

$$= \sum_{\kappa,\mu} c_{\kappa\mu} \langle \beta_{\mu}, f^{*} \rho_{\nu} \frown \mu_{K} \rangle \rho_{\kappa}$$

$$= \sum_{\kappa,\lambda,\mu} c_{\kappa\mu} m_{\nu\lambda} \langle \beta_{\mu}, \alpha_{\lambda} \frown \mu_{K} \rangle \rho_{\kappa}$$

$$= \sum_{\kappa,\lambda,\mu} c_{\kappa\mu} m_{\nu\lambda} \langle \beta_{\mu} \smile \alpha_{\lambda}, \mu_{K} \rangle \rho_{\kappa}$$

$$= \sum_{\kappa,\lambda,\mu} c_{\kappa\mu} m_{\nu\lambda} y_{\mu\lambda} \rho_{\kappa}.$$

Therefore we have

$$\Delta((f|K)^*) = \sum_{\lambda,\mu,\nu} (-1)^{(n+1)\deg \rho_{\nu}} c_{\nu\mu} m_{\nu\lambda} y_{\mu\lambda} .$$

The diagram

$$\begin{array}{ccc} & & & & & \\ & & & & \\ & & & & \\ & & & \downarrow^{i*} \\ & & & & H^*(K \times (M, M-K)) \end{array} \xrightarrow{\hat{f}^*} H^*(M, M-K) \\ & & & & \uparrow^{d*} \\ & & & & & \\ & & & & H^*(M \times (M, M-K)) \end{array}$$

is commutative, where i^* is the natural homomorphism. Therefore it follows from (3) that

$$\begin{split} I(f) &= \langle U, \hat{f}_* \mu_K \rangle = \langle \hat{f}^* U, \mu_K \rangle \\ &= \langle d^*(f \times id)^* U_K, \mu_K \rangle \\ &= \sum_{\mu,\nu} c_{\nu\mu} \langle d^*(f^* \rho_\nu \times \beta_\mu), \mu_K \rangle \end{split}$$

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$$= \sum_{\mu,\nu} c_{\nu\mu} \langle f^* \rho_{\nu} \smile \beta_{\mu}, \mu_K \rangle$$

=
$$\sum_{\lambda,\mu,\nu} c_{\nu\mu} m_{\nu\lambda} \langle \alpha_{\lambda} \smile \beta_{\mu}, \mu_K \rangle$$

=
$$\sum_{\lambda,\mu,\nu} (-1)^{(n-1) \deg \rho_{\nu}} c_{\nu\mu} m_{\nu\lambda} \langle \beta_{\mu} \smile \alpha_{\lambda}, \mu_K \rangle$$

=
$$\sum_{\lambda,\mu,\nu} (-1)^{(n-1) \deg \rho_{\nu}} c_{\nu\mu} m_{\nu\lambda} y_{\mu\lambda}.$$

Consequently we obtain $I(f) = \Lambda((f|K)^*)$. Since $\Lambda((f|K)^*) = \Lambda((f|K)_*)$ is obvious, we have the desired result. q.e.d.

A topological manifold which is orientable (over Z) is orientable over Q, and I(f) for R = Z coincides with I(f) for R = Q. Therefore Theorem D implies Theorem C.

Lemma 4 shows that I(f) coincides with I_f due to Dold when $M = \mathbf{R}^n$. Therefore Theorem C implies Theorem A. It is clear that Theorem C implies Theorem B.

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