SUBMANIFOLDS OF CODIMENSION 3 ADMITTING ALMOST CONTACT METRIC STRUCTURE IN A COMPLEX PROJECTIVE SPACE

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ABSTRACT. In this paper we prove the following : Let M be a semi-invariant submanifold with almost contact metric structure (ϕ, ξ, g) of codimension 3 in a complex projective space $P_{n+1}\mathbb{C}$. Suppose that the third fundamental form n satisfies $dn = 2\theta\omega$ for a certain scalar $\theta(<\frac{c}{2})$, where $\omega(X,Y) = g(X,\phi Y)$ for any vectors X and Y on M. Then M has constant eigenvalues correponding the shape operator A in the direction of the distinguished normal and the structure vector ξ is an eigenvector of A if and only if M is locally congruent to a homogeneous real hypersurface of $P_n\mathbb{C}$.

0. Introduction

A submanifold M is called a CR submanifold of a Kaehlerian manifold \tilde{M} with complex structure J if there exists a differentiable distribution T: $p \to T_p \subset M_p$ on M such that T is J-invariant and the complementary orthogonal distribution T^{\perp} is totally real, where M_p denotes the tangent space to M at each point p in M([1], [20]). In particular, M is said to be a semi-invariant submanifold provided that dim $T^{\perp} = 1$. The unit normal vector field in JT^{\perp} is called the distinguished normal to the semi-invariant submanifold ([18]). A semi-invariant submanifold admits an induced almost contact metric structure, and many results are known by using this structure ([4], [10], [15], etc.).

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A typical example of a semi-invariant submanifold is real hypersurface. When the ambient manifold \tilde{M} is a complex projective space $P_n\mathbb{C}$, real hypersurfaces were investigated by many geometers in connection with the shape operator and the induced almost contact metric structure ([3], [7], [9], [16], [17], etc.). One of them, the third named author asserts that the following :

Theorem T([17]). Let M be a homogeneous real hyperspace of $P_n\mathbb{C}$. Then M is locally congruent to one of the followings:

- (A₁) a geodesic hypersphere (that is, a tube over a hyperplane $P_{n-1}\mathbb{C}$),
- (A₂) a tube over a totally geodesic $P_k\mathbb{C}(1 \le k \le n-2)$,
 - (B) a tube over a complex quadric Q_{n-1} ,
 - (C) a tube over $P_1 \mathbb{C} \times P_{(n-1)/2} \mathbb{C}$ and $n \geq 5$ is odd,
- (D) a tube over a complex Grassman $G_{2,5}\mathbb{C}$ and n = 9,
- (E) a tube over a Hermitian symmetric space SO(10)/U(5) and n = 15.

Cecil-Ryan ([3]) and Kimura ([9]) extensively investigated a real hypersurface which is realized as a tube of constant radius r over a complex submanifold of $P_n\mathbb{C}$ on which ξ is a principal curvature vector.

On the other hand, submanifolds of codimension 3 addmitting an almost contact metric structure in a complex space form have been studied in ([8], [19]) when the normal connection is L-flat or the distinguished normal is parallel in the normal bundle.

The main purpose of the present paper is to extend Theorem T under certain conditions on a semi-invariant submanifold of codimension 3 in a complex projective space $P_{n+1}\mathbb{C}$, and to give new examples of nontrivial semi-invariant submanifolds in $P_{n+1}\mathbb{C}$.

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1. Preliminaries

Let \overline{M} be a real 2(n+1)-dimensional Kaehlerian manifold equipped with parallel almost complex structure J and a Riemannian metric tensor G, which J-Hermitian and covered by a system of coordinate neighborhoods $\{W; y^A\}$.

Let M be a real (2n-1)-dimensional Riemannian manifold covered by a system of coordinate neighborhoods $\{V; x^h\}$ and immersed isometrically in \tilde{M} by the immersion $i: M \to \tilde{M}$.

Throughout the present paper the following convention on the range of indices are used, unless otherwise stated :

$$A, B, \dots = 1, 2, \dots, 2n+2 ; i, j, \dots = 1, 2, \dots, 2n-1.$$

The summation convention will be used with respect to those system of indices. When the argument is local, M need not to be distinguished from i(M). Thus, for simplicity, a point p in M may be identified with i(p) and a tangent vector X at p may also be identified with the tangent vector $i_*(X)$ at i(p) via the differential i^* of i. We represent the immersion i locally by $y^A = y^A(x^h)$ and $B_j = (B_j^A)$ are also (2n-1)-linearly independent local tangent vectors of M, where $B_j^A = \partial_j y^A$ and $\partial_j = \partial/\partial x^j$. Three mutually orthogonal unit normals C, D and E may then be chosen. The induced Riemannian metric tensor g with components g_{ji} on M is given by $g_{ji} = G(B_j, B_i)$ because the immersion i is isometric.

Denoting by ∇_j the operator of van der Waerden-Bortolotti covariant differentiation with respect to the induced Riemannian metric, equations of the Gauss for M of \tilde{M} is obtained :

(1.1)
$$\nabla_j B_i = A_{ji}C + K_{ji}D + L_{ji}E,$$

where A_{ji}, K_{ji} and L_{ji} are components of the second fundamental forms in the direction of normals C, D and E respectively.

Equations of the Weingarten are also given by

(1.2)
$$\nabla_{j}C = -A_{j}{}^{h}B_{h} + l_{j}D + m_{j}E,$$
$$\nabla_{j}D = -K_{j}{}^{h}B_{h} - l_{j}C + n_{j}E,$$
$$\nabla_{j}E = -L_{i}{}^{h}B_{h} - m_{i}C - n_{i}D,$$

where $A = (A_j^h), A_{(2)} = (K_j^h)$ and $A_{(3)} = (L_j^h)$, which are related by $A_{ji} = A_j^r g_{ir}, K_{ji} = K_j^r g_{ir}$ and $L_{ji} = L_j^r g_{ir}$ respectively, and l_j, m_j and n_j being components of the third fundamental forms.

In the sequel, we denote the normal components of $\nabla_j C$ by $\nabla_j^{\perp} C$. The normal vector field C is said to be *parallel* in the normal bundle if we have $\nabla_j^{\perp} C = 0$, that is, l_j and m_j vanish identically.

On the other hand, a submanifold M is called a CR submanifold of a Kaehlerian manifold \tilde{M} if there exists a differentiable distribution $T: p \rightarrow T$

 $T_p \subset M_p$ on M satisfying the following conditions, where M_p denotes the tangent space to M at each point p in M:

(1) T is invariant, that is, $JT_p = T_p$ for each p in M, (2) the complementary orthogonal distribution $T^{\perp} : p \to T_p^{\perp} \subset M_p$ is totally real, that is, $JT_p^{\perp} \subset M_p^{\perp}$ for each p in M, where M_p^{\perp} denotes the normal space to M at $p \in M([1], [20], [21])$. In particular M is said to be a *semi-invariant submanifold* provided that $\dim T^{\perp} = 1$. In this case the unit normal vector field in JT^{\perp} is called a *distinguished normal* to the semi-invariant submanifold and denoted this by C([2], [18]). More precisely, we choose an orthonormal basis e_1, \dots, e_{n-1}, e_n of M_p in such a way that $e_1, \dots, e_{n-1} \in T$. Then we see that

$$G(Je_n, e_i) = -G(e_n, Je_i) = -G(e_n, \sum_{k=1}^{n-1} F_{ik}e_k) = 0 \text{ for } i = 1, \cdots, n-1.$$

Also we have $G(Je_n, e_n) = 0$ because J is skew-symmetric. Therefore Je_n is orthogonal to M_p . We put $C = -Je_n$. Then we can write

(1.3)
$$JB_i = \phi_i{}^h B_h + \xi_i C, \quad JC = -\xi^h B_h, \quad JD = -E, \quad JE = D$$

in each coordinate neighborhood, where we have put $\phi_{ji} = G(JB_j, B_i), \xi_i = G(JB_i, C), \xi^h$ being associated component of ξ_h . By the property of the almost Hermitian structure J, it is clear that ϕ_{ji} is skew-symmetric. A tensor fied of type (1,1) with components ϕ_i^h will be denoted by ϕ . By properties of the almost complex structure J it follows that

$$\phi_{i}{}^{r}\phi_{r}{}^{h} = -\delta_{i}{}^{h} + \xi_{i}\xi^{h}, \quad \xi^{r}\phi_{r}{}^{h} = 0, \quad \xi_{r}\phi_{i}{}^{r} = 0,$$

$$\xi_{r}\xi^{r} = 1, \quad g_{rs}\phi_{j}{}^{r}\phi_{i}{}^{s} = g_{ji} - \xi_{j}\xi_{i}.$$

Since J is parallel, by differentiating the first equation of (1.3) covariantly along M and using (1.1), (1.2) and (1.3), and by comparing the tangential and normal parts, we find (see [19])

(1.4)
$$\nabla_j \phi_i^{\ h} = -A_{ji} \xi^h + A_j^{\ h} \xi_i,$$

(1.5)
$$\nabla_j \xi_i = -A_{jr} \phi_i^{\ r},$$

(1.6)
$$K_{ji} = -L_{jr}\phi_i^{\ r} - m_j\xi_i,$$

$$(1.7) L_{ji} = K_{jr}\phi_i{}^r + l_j\xi_i.$$

The last two relations give

(1.8)
$$K_{jt}\xi^t = -m_j, \quad L_{jt}\xi^t = l_j,$$

(1.9)
$$m_t \xi^t = -k, \quad l_t \xi^t = l$$

where $k = T_r A_{(2)}, l = T_r A_{(3)}$.

Here we may assume that l = 0. In fact, for a normal vector v of M we denote by A_v the second fundamental tensor of M in the direction of v. Then we have $A_{-v} = -A_v$. Hence there is a unit normal vector D' of M in the plane spanned by two vectors D and E such that $T_r A_{D'} = 0$, which proves our assertion. Therefore we have by (1.9)

$$(1.10) l_t \xi^t = 0.$$

Transforming (1.7) by $\phi_k^{\ j}$ and using (1.6), we obtain

$$-K_{ik} - m_i \xi_k = K_{st} \phi_i^{\ s} \phi_k^{\ t} + \xi_i \phi_{kt} l^t,$$

which implies

$$m_k \xi_i - m_i \xi_k = \xi_i \phi_{kt} l^t - \xi_k \phi_{it} l^t,$$

or, using (1.9)

$$(1.11) \qquad \qquad \phi_{it}$$

 $\phi_{it}l^t = m_i + k\xi_i.$

Similarly we have

$$(1.12) \qquad \qquad \phi_{ir}m^r = -l_i$$

because of (1.10).

Transforming (1.6) and (1.7) by L_k^i and using (1.6), (1.7) and (1.8), we have respectively

(1.13)
$$K_{jr}L_{i}^{r} + K_{ir}L_{j}^{r} = -(l_{j}m_{i} + l_{i}m_{j}),$$

(1.14)
$$L_{ji}^{2} - K_{ji}^{2} = l_{j}l_{i} - m_{j}m_{i}.$$

The ambient Kaehlerian manifold \tilde{M} is assumed to be of constant holomorphic sectional curvature c, which is called a *complex space form* and denoted by $M_{n+1}(c)$. Then equations of the Gauss and Codazzi are given by

(1.15)

$$R_{kjih} = \frac{c}{4} (g_{kh}g_{ji} - g_{jh}g_{ki} + \phi_{kh}\phi_{ji} - \phi_{jh}\phi_{ki} - 2\phi_{kj}\phi_{ih}) + A_{kh}A_{ji} - A_{jh}A_{ki} + K_{kh}K_{ji} - K_{jh}K_{ki} + L_{kh}L_{ji} - L_{jh}L_{ki},$$

(1.16)
$$\nabla_{k}A_{ji} - \nabla_{j}A_{ki} - l_{k}K_{ji} + l_{j}K_{ki} - m_{k}L_{ji} + m_{j}L_{ki}$$
$$= \frac{c}{4}(\xi_{k}\phi_{ji} - \xi_{j}\phi_{ki} - 2\xi_{i}\phi_{kj}),$$

(1.17)
$$\nabla_k K_{ji} - \nabla_j K_{ki} + l_k A_{ji} - l_j A_{ki} - n_k L_{ji} + n_j L_{ki} = 0,$$

(1.18)
$$\nabla_k L_{ji} - \nabla_j L_{ki} + m_k A_{ji} - m_j A_{ki} + n_k K_{ji} - n_j K_{ki} = 0,$$

where R_{kjih} is covariant components of the Riemann-Christoffel curvature tensor of M, and those of the Ricci by

(1.19)
$$\nabla_k l_j - \nabla_j l_k + A_{kr} K_j^r - A_{jr} K_k^r + m_k n_j - m_j n_k = 0,$$

(1.20)
$$\nabla_k m_j - \nabla_j m_k + A_{kr} L_j^r - A_{jr} L_k^r + n_k l_j - n_j l_k = 0,$$

(1.21)
$$\nabla_k n_j - \nabla_j n_k + K_{kr} L_j^r - K_{jr} L_k^r + l_k m_j - l_j m_k = \frac{c}{2} \phi_{kj}.$$

In the following we need the following definition. The normal connection of a semi-invariant submanifold M of codimension 3 in a complex space form is said to be L-flat if it satisfies $dn = \frac{c}{2}\omega$, that is, $\nabla_j n_i - \nabla_i n_j = \frac{c}{2}\phi_{ji}$, where $\omega(X,Y) = g(X,\phi Y)$ for any vectors X and Y on M (p514, [13]).

Differentiating $A\xi = \alpha \xi$ covariantly along M, and using (1.5), we find

(1.22)
$$\xi^r \nabla_k A_{jr} = A_{jr} A_{ks} \phi^{rs} - \alpha A_{kr} \phi_j^r + (\nabla_k \alpha) \xi_j,$$

which together with (1.8) and (1.16) yields

(1.23)
$$2A_{jr}A_{ks}\phi^{rs} - \alpha(A_{kr}\phi_{j}{}^{r} - A_{jr}\phi_{k}{}^{r}) + \frac{c}{2}\phi_{kj}$$
$$= \xi_{k}\nabla_{j}\alpha - \xi_{j}\nabla_{k}\alpha + 2(m_{k}l_{j} - m_{j}l_{k}).$$

Transvecting ξ^k to this and using $A\xi = \alpha\xi$, (1.8) and (1.10), we obtain

(1.24)
$$\nabla_j \alpha - (\xi^t \nabla_t \alpha) \xi_j = 2kl_j.$$

2. The third fundamental forms of semi-invariant submanifolds

In the rest of this paper we shall suppose that M is a real (2n - 1)dimensional semi-invariant submanifold of codimension 3 in a complex projective space $P_{n+1}\mathbb{C}$ and that the third fundamental form n satisfies $dn = 2\theta\omega$ for a certain scalar θ on M, that is,

(2.1)
$$\nabla_j n_i - \nabla_i n_j = 2\theta \phi_{ji}.$$

Then we have by (1.21)

$$K_{jr}L_{i}^{r} - K_{ir}L_{j}^{r} + l_{j}m_{i} - l_{i}m_{j} = -2(\theta - \frac{c}{4})\phi_{ji},$$

or, using (1.13)

(2.2)
$$K_{jr}L_{i}^{r} + l_{j}m_{i} = -(\theta - \frac{c}{4})\phi_{ji},$$

which together with (1.8), (1.9) and (1.10) yields

Remark 2.1. To write our formulas in a convention form, in the sequel we denote by $h_{(2)} = A_{ji}A^{ji}$, $h = g^{ji}A_{ji}$, $\alpha = A_{ji}\xi^{j}\xi^{i}$, $K_{(2)} = K_{ji}K^{ji}$ and $L_{(2)} = L_{ji}L^{ji}$.

Multiplying (2.2) with ϕ^{ji} and summing for j and i, and using (1.6), (1.8) and (1.11), we find

$$K_{(2)} - k^2 = 2(n-1)(\theta - \frac{c}{4}),$$

which together with (1.8) implies that

(2.4)
$$|| K_{ji} - k\xi_j\xi_i ||^2 = 2(n-1)(\theta - \frac{c}{4}),$$

where $||F||^2 = g(F, F)$ for any tensor field F on M.

In the same way, we have from (1.7), (1.10), (1.12) and (2.2)

(2.5)
$$L_{(2)} = 2(n-1)(\theta - \frac{c}{4}).$$

Differentiating (2.1) covariantly along M and using (1.4), we obtain

$$\nabla_{k}(\nabla_{j}n_{i}-\nabla_{i}n_{j})=2(\nabla_{k}\theta)\phi_{ji}+2\theta(A_{ki}\xi_{j}-A_{kj}\xi_{i}),$$

or, using the first Bianchi identity,

$$(\nabla_k \theta) \phi_{ji} + (\nabla_j \theta) \phi_{ik} + (\nabla_i \theta) \phi_{kj} = 0,$$

which implies $(n-2)\nabla_k \theta = 0$. Thus $\theta \geq \frac{c}{4}$ is constant if n > 2.

Lemma 2.1. Let M be a semi-invariant submanifold of codimension 3 with L-flat normal connection in a complex projective space $P_{n+1}\mathbb{C}$. If the structure vector ξ is an eigenvector of the shape operator A in the direction of the distinguished normal, then we have $A_{(2)} = A_{(3)} = 0$ and $\nabla_j^{\perp} C = 0$.

Remark 2.2. This lemma was proved in [8]. But we give a simpler proof of it here.

Proof. By the hypotheses we have $\theta = \frac{c}{4}$. Thus (2.4) and (2.5) are reduce respectively to

$$K_{ji} = k\xi_j\xi_i, \ L_{ji} = 0$$

and hence $m_j = -k\xi_j$ and $l_j = 0$ because of (1.8). It sufficies to show that k = 0. In this case (1.19) turns out to be

$$k(\xi_j A_{kr}\xi^r - \xi_k A_{jr}\xi^r) = k(\xi_k n_j - \xi_j n_k),$$

which together with $A\xi = \alpha\xi$ gives

$$k(n_j - x\xi_j) = 0,$$

where $x = n_t \xi^t$.

We also have by (1.18)

$$k\{\xi_k(A_{ji}+n_j\xi_i)-\xi_j(A_{ki}+n_k\xi_i)\}=0,$$

which implies

$$k(h-\alpha)=0.$$

Now, let Ω_0 be a set of points such that $k \neq 0$ on M and suppose that Ω_0 be non void. Then we have

$$h - \alpha = 0, \quad n_j = x\xi_j$$

on Ω_0 . Differentiating the last equation covariantly along Ω_0 and using (1.5), we find

$$\nabla_k n_j = (\nabla_k x) \, \xi_j - x A_{kr} \phi_j^{\ r}.$$

Since it is assumed to be $A\xi = \alpha\xi$ and (2.1) with $\theta = \frac{c}{4}$, we verified that

$$\frac{c}{2}\phi_{kj} + x(A_{kr}\phi_j^{\ r} - A_{jr}\phi_k^{\ r}) = 0,$$

a contradiction because of $h - \alpha = 0$. This completes the proof.

Transforming (2.2) by ϕ_k^{i} and taking account of (1.6) and (1.12), we have

(2.6)
$$K_{jk}^{2} + \xi_{j}(K_{kr}m^{r}) + l_{j}l_{k} = (\theta - \frac{c}{4})(g_{jk} - \xi_{j}\xi_{k}),$$

which enable us to obtain

 $\xi_j(K_{kr}m^r) - \xi_k(K_{jr}m^r) = 0.$

Therefore we have

because of (1.8). Thus it follows that

(2.8)
$$K_{ji}^{2} + l_{j}l_{i} - (m_{r}m^{r})\xi_{j}\xi_{i} = (\theta - \frac{c}{4})(g_{ji} - \xi_{j}\xi_{i}).$$

In the same way, we have from (2.2)

(2.9)
$$L_{jr}l^{r} = km_{j} + (l_{t}l^{t} + k^{2})\xi_{j}.$$

Transvecting (2.2) with m^i and making use of (1.11) and (2.3), we obtain

$$(\theta - \frac{c}{4} - m_r m^r)l_j = 0.$$

Similary, we verify, using (2.2) and (2.9), that

$$(\theta - \frac{c}{4} - l_r l^r - k^2)(m_t m^t - k^2) = 0.$$

Now, let Ω be a set of points such that $l_t l^t \neq 0$ on M and suppose that Ω be non-empty. Then we have

(2.10)
$$m_r m^r = \theta - \frac{c}{4}, \quad l_r l^r + k^2 = \theta - \frac{c}{4}$$

on Ω . From now on, we discuss our arguments on the open subset Ω of M. Then (2.8) turns out to be

(2.11)
$$K_{ji}^{2} = (\theta - \frac{c}{4})g_{ji} - l_{j}l_{i}.$$

Differentiating this covariantly along Ω , we find

(2.12)
$$K_j \, {}^r \nabla_k K_{ir} + K_i \, {}^r \nabla_k K_{jr} + l_j \nabla_k l_i + l_i \nabla_k l_j = 0,$$

from which, taking the skew-symmetric part with respect to indices k and j and making use of (1.17) and (1.19),

$$K_{j} {}^{r} \nabla_{k} K_{ir} - K_{k} {}^{r} \nabla_{j} K_{ir} + l_{j} \nabla_{k} l_{i} - l_{k} \nabla_{j} l_{i} + K_{i} {}^{r} (l_{j} A_{kr} - l_{k} A_{jr} + n_{k} L_{jr} - n_{j} L_{kr}) + l_{i} (A_{j} {}^{r} K_{kr} - A_{k} {}^{r} K_{jr} + n_{k} m_{j} - n_{j} m_{k}) = 0$$

for any indices k, j and i. Thus, interchanging indices k and i, we have

$$K_{j} {}^{r} \nabla_{i} K_{kr} - K_{i} {}^{r} \nabla_{j} K_{kr} + l_{j} \nabla_{i} l_{k} - l_{i} \nabla_{j} l_{k} + l_{j} A_{ir} K_{k} {}^{r} - l_{i} A_{jr} K_{k} {}^{r} + n_{i} K_{k} {}^{r} L_{jr} - n_{j} K_{k} {}^{r} L_{ir} + l_{k} (K_{i} {}^{r} A_{jr} - K_{j} {}^{r} A_{ir} + n_{i} m_{j} - n_{j} m_{i}) = 0.$$

Hence, if we use (1.13), (1.17), (1.19) and (2.2), then we get

$$K_j \nabla_k K_{ir} - K_i \nabla_k K_{jr} + l_j \nabla_k l_i - l_i \nabla_k l_j + 2l_j A_{kr} K_i^r - 2l_i A_{kr} K_j^r + 2(\theta - \frac{c}{4}) n_k \phi_{ji} = 0.$$

Adding this to (2.12), we obtain

(2.13)
$$K_j {}^r \nabla_k K_{ir} + l_j (\nabla_k l_i + A_{kr} K_i {}^r) - l_i A_{kr} K_j {}^r + (\theta - \frac{c}{4}) n_k \phi_{ji} = 0.$$

Since we have (1.7), (2.3) and (2.11), by transforming K_h^{j} , we have

(2.14)

$$(\theta - \frac{c}{4})(\nabla_k K_{hi} - n_k L_{hi} + n_k l_h \xi_i - l_i A_{hk}) - l_h (l^r \nabla_k K_{ir}) + k l_h (\nabla_k l_i + A_{kr} K_i^r) + (A_{kr} l^r) l_h l_i = 0.$$

On the other hand, differentiating the first equation of (2.3) covariantly along Ω , we find

$$l^{r} \nabla_{k} K_{jr} + K_{j}^{r} \nabla_{k} l_{r} = k \nabla_{k} l_{j} + (\nabla_{k} k) l_{j},$$

which, transvecting l^{j} and using (2.10),

$$(\nabla_k K_{ji})l^j l^i = (\theta - \frac{c}{4} - k^2)\nabla_k k.$$

Thus, if we transvect l^i to (2.14) and use (2.9) and (2.10), then we obtain

(2.15)
$$(\nabla_k K_{jr})l^r = l_j \nabla_k k - l_j A_{kr} l^r + (\theta - \frac{c}{4} - k^2) A_{jk} + n_k \{ km_j + (\theta - \frac{c}{4}) \xi_j \}$$

because $\theta - \frac{c}{4} \neq 0$ on Ω , from which, taking the skew-symmetric part and making use of (2.9),

(2.16)
$$l_j(2A_{kr}l^r - \nabla_k k) = l_k(2A_{jr}l^r - \nabla_j k).$$

Therefore it follows that

for some function σ on Ω . By means of (2.15) and (2.17), the equation (2.14) turns out to be

(2.18)
$$(\theta - \frac{c}{4})(\nabla_k K_{ji} - n_k L_{ji} - l_i A_{jk} - l_j A_{ik}) + \sigma l_k l_j l_i - k l_j n_k m_i + k^2 l_j A_{ik} + k l_j (\nabla_k l_i + A_{kr} K_i^r) = 0,$$

from which, taking the skew-symmetric part with respect to j and i,

$$kl_{j}(kA_{ik} - n_{k}m_{i} + \nabla_{k}l_{i} + A_{kr}K_{i}^{r}) = kl_{i}(kA_{jk} - n_{k}m_{j} + \nabla_{k}l_{j} + A_{kr}K_{j}^{r}).$$

If we transvect l^{j} to this and make use of (2.17), we get

$$k(l_t l^t)(kA_{ik} - n_k m_i + \nabla_k l_i + A_{kr} K_i^{-r}) = k^2 \sigma l_i l_k.$$

From this and (2.18), we have

(2.19)
$$\nabla_k K_{ji} = n_k L_{ji} + l_i A_{jk} + l_j A_{ik} + \tau l_j l_k l_i$$

for some function τ on Ω . Multiplying g^{ji} to (2.19) and summing for j and i, and using (2.17) we have

$$(2.20) (l_t l^t) \tau = -\sigma.$$

Differentiating the first equation of (1.8) covariantly and taking account of (1.5), (1.6) and (2.19), we obtain

(2.21)
$$\nabla_k m_j = -n_k l_j - A_{kr} L_j^r.$$

Differentiating the first equation of (1.9) covariantly and using (1.11) and (2.21), we find

$$(2.22) \nabla_j k = 2A_{jr}l^r,$$

which together with (2.17) implies that $\tau l^2 = -\sigma$. This means that $\sigma = \tau = 0$ on Ω by virtue of (2.20). Therefore (2.19) reduces to

(2.23)
$$\nabla_k K_{ji} = n_k L_{ji} + l_i A_{jk} + l_j A_{ik}.$$

Substituting (2.23) into (2.13), we obtain

$$n_{k}K_{jr}L_{i}^{r} + kl_{j}A_{ki} + l_{j}(\nabla_{k}l_{i} + A_{kr}K_{i}^{r}) + (\theta - \frac{c}{4})n_{k}\phi_{ji} = 0,$$

-- 69 ---

which transvect l^{j} and using (1.11), (2.9) and (2.10),

(2.24)
$$\nabla_k l_j = n_k m_j - A_{kr} K_j^r - k A_{jk}.$$

Differentiating (1.7) covariantly and using (1.4), (1.5), (1.11) and (2.24), we also find

(2.27)
$$\nabla_k L_{ji} = -n_k K_{ji} + m_j A_{ik} + m_i A_{jk}.$$

Differentiating (2.22) covariantly along Ω and taking account of (2.24), we get

$$\nabla_k \nabla_j k = 2(\nabla_k A_{jr})l^r + 2A_j^r (n_k m_r - A_{ks} K_r^s - kA_{kr}) + n_j (2A_{kr} m^r - kn_k),$$

from which, taking the skew-symmetric part and making use of (1.11), (1.16), (2.3) and (2.9),

$$(\theta-\frac{c}{2})(m_k\xi_j-m_j\xi_k)=0.$$

Therefore it follows that $(\theta - \frac{c}{2})(m_j + k\xi_j) = 0$ and hence $\theta = \frac{c}{2}$ on Ω because of (2.10). Thus we have by the first equation of (1.2)

Lemma 2.2. Let M be a semi-invariant submanifold of codimension 3 in $P_{n+1}\mathbb{C}$ satisfying (2.1). If $\theta \neq \frac{c}{2}$, then we have $\nabla_j^{\perp}C = -k\xi_j E$ on M.

3. Further properties of the third fundamental forms

We continue now, our arguments under the same hypotheses (2.1) as in section 2. Furthermore suppose, throughout this section, that $\theta \neq \frac{c}{2}$ holds and that the structure vector ξ satisfies $A_{jr}\xi^r = \alpha\xi_j$. Then we have by Lemma 2.2

$$l_j = 0$$

and hence

 $(3.2) m_j = -k\xi_j$

because of (1.2). Thus (1.6), (1.7), (1.8), (1.13) and (1.14) are recuded respectively to

$$(3.3) L_{jr}\phi_i{}^r = -K_{ji} + k\xi_j\xi_i,$$

(3.6)
$$L_{jr}K_{i}^{\ r} + L_{ir}K_{j}^{\ r} = 0,$$

(3.7)
$$L_{ji}^{2} = K_{ji}^{2} - k^{2}\xi_{j}\xi_{i}.$$

From (3.2) we have

$$\nabla_k m_j = -\xi_j \nabla_k k + k A_{kr} \phi_j^r,$$

from which, taking the skew-symmetric part and using (1.20), (3.1) and (3.2),

$$A_{kr}L_{j}{}^{r} - A_{jr}L_{k}{}^{r} + k(A_{kr}\phi_{j}{}^{r} - A_{jr}\phi_{k}{}^{r}) = \xi_{j}\nabla_{k}k - \xi_{k}\nabla_{j}k.$$

Since we have $A\xi = \alpha\xi$, we then have

$$(3.8) \nabla_{k}k = \lambda\xi_{k}$$

because of (3.5), where $\lambda = \xi^t \nabla_t k$. From the last two equations, it is clear that

(3.9)
$$A_{kr}L_{j}{}^{r} - A_{jr}L_{k}{}^{r} = k(A_{jr}\phi_{k}{}^{r} - A_{kr}\phi_{j}{}^{r}).$$
Similarly, we also have from (1.19), (3.1) and (3.2)

(3.10)
$$k(n_j - \mu \xi_j) = 0,$$

(3.11)
$$A_{kr}K_{j}^{r} - A_{jr}K_{k}^{r} = 0,$$

where $\mu = k n_t \xi^t$.

Lemma 3.1. Let M be a semi-invariant submanifold of codimension 3 in $P_{n+1}\mathbb{C}$ satisfying $dn = 2\theta\omega$, $(\theta \neq \frac{c}{2})$. If it satisfies $A\xi = \alpha\xi$, then $T_rA_{(2)} = const$. *Proof.* Differentiating (3.8) covariantly and making use of (1.5), we find

$$\nabla_k \nabla_j \lambda = \xi_j \nabla_k \lambda - \lambda A_{kr} \phi_j^r,$$

which together with $A\xi = \alpha\xi$ yields

(3.12)
$$\lambda(A_{jr}\phi_i^{\ r} - A_{ir}\phi_j^{\ r}) = 0.$$

On the other hand, by means of (3.1), the equation (1.24) becomes $\nabla_j \alpha = (\xi^t \nabla_t \alpha) \xi_j$. Hence (1.23) implies $\lambda (A_{jr}^2 \phi_k^{\ r} + \frac{c}{4} \phi_{kj}) = 0$ because of (3.1) and (3.12). By the properties of the almost contact metric structure, it follows that

$$\lambda\{h_{(2)} - \alpha^2 + \frac{c}{2}(n-1)\} = 0,$$

which means

$$\lambda\{\|A_{ji} - \alpha\xi_j\xi_i\|^2 + \frac{c}{2}(n-1)\} = 0.$$

Hence $\lambda = 0$ by virtue of c > 0 and thus k = const. because of (3.8). This complete the proof of Lemma 3.1.

In the following we discuss our arguments the case where $k \neq 0$. Then by (3.10) we have

$$n_j = \mu \xi_j.$$

From this we have

$$\nabla_k n_j = \xi_j \nabla_k \mu - \mu A_{kr} \phi_j^r,$$

which implies

$$2\theta\phi_{kj} = \xi_j \nabla_k \mu - \xi_k \nabla_j \mu - \mu (A_{kr}\phi_j^r - A_{jr}\phi_k^r).$$

 ξ being an eigenvector with respect to A, it is seen that

where we have put $\rho\theta = -\mu$. Thus (3.9) turns out to be

(3.14)
$$A_{jr}L_{i}^{\ r} - A_{ir}L_{j}^{\ r} = 2\rho k\phi_{ij}.$$

Using (1.24), (3.1) and (3.13), the relationship (1.23) becomes

(3.15)
$$A_{jr}A_{ks}\phi^{rs} = (\rho\alpha - \frac{c}{4})\phi_{kj}.$$

Applying (3.13) by $A_i^{\ j}$ and using (3.15), we obtain

$$(\rho\alpha - \frac{c}{4})\phi_{ki} = A_{ir}^2 \phi_k^{\ r} + 2\rho A_{ir} \phi_k^{\ r}.$$

Thus, it follows that

(3.16)
$$A_{ji}^{2} + 2\rho A_{ji} = (\rho\alpha - \frac{c}{4})g_{ji} + (\alpha^{2} + \rho\alpha + \frac{c}{4})\xi_{j}\xi_{i}.$$

Lemma 3.2. ρ is nonzero constant if n > 2.

Proof. Since we have $\theta \rho = -\mu$, ρ does not vanish because we have $\theta \geq \frac{c}{4}$ and $n_j = \mu \xi_j$.

Differentiating (3.13) covariantly and taking account of (1.4) and (3.16), we find

$$(\nabla_k A_{jr})\phi_i^r - (\nabla_k A_{ir})\phi_j^r - 2(\nabla_k \rho)\phi_{ji}$$

= $\{\alpha A_{ik} + (\rho\alpha - \frac{c}{4})g_{ik}\}\xi_j - \{\alpha A_{jk} + (\rho\alpha - \frac{c}{4})g_{jk}\}\xi_i.$

If we take the cyclic sum with respect to k, j and i, and make use of (1.16), then we have

$$(\nabla_k \rho)\phi_{ji} + (\nabla_j \rho)\phi_{ik} + (\nabla_i \rho)\phi_{kj} = 0.$$

Thus, ρ is constant for n > 2. This completes the proof of the lemma.

Lemma 3.3. α and h are constant if $k \neq 0$.

Proof. Since we have $\nabla_j \alpha = (\xi^t \nabla_t \alpha) \xi_j$ as is already seen, we can verify, using the same method as in the proof of Lemma 3.1, that $\xi^t \nabla_t \alpha = 0$ and hence α is constant. From (3.13) we obtain

$$(3.17) \qquad \qquad \alpha - h = 2(n-1)\rho.$$

Thus h is constant because of Lemma 3.2. Therefore Lemma 3.3 is proved.

Since (2.6) is valid by the assumption (2.1), it is , using (3.1), (3.2) and (3.5), verify that

(3.18)
$$K_{ji}^{2} = (\theta - \frac{c}{4})g_{ji} + (k^{2} - \theta + \frac{c}{4})\xi_{j}\xi_{i}.$$

Differentiating (3.18) covariantly and using (1.5), we have

(3.19)
$$K_{i}^{r}(\nabla_{k}K_{jr}) + K_{j}^{r}(\nabla_{k}K_{ir}) = -(k^{2} - \theta + \frac{c}{4})(\xi_{j}A_{kr}\phi_{i}^{r} + \xi_{i}A_{kr}\phi_{j}^{r})$$

because θ and k are both constant.

Using the same method as that used to (2.13) from (2.12), we can derive from (3.19) the following :

(3.20)

$$K_{j}{}^{r}\nabla_{k}K_{ir} = -(\theta - \frac{c}{4})n_{k}\phi_{ji} + \rho(k^{2} - \theta + \frac{c}{4})(\xi_{k}\phi_{ji} + \xi_{i}\phi_{jk} + \xi_{j}\phi_{ki}) - (k^{2} - \theta + \frac{c}{4})\xi_{j}A_{kr}\phi_{i}{}^{r},$$

where we have used (1.17), (3.13) and (3.14). Transvecting ξ^{j} to this, we get

$$k\xi^{r}\nabla_{k}K_{ir} = -(k^{2}-\theta+\frac{c}{4})(A_{kr}\phi_{i}^{r}-\rho\phi_{ki}).$$

On the other hand, differentiating the first equation of (3.5) covariantly and taking account of (1.5) and (3.4), we obtain

(3.21)
$$\xi^r \nabla_k K_{ir} = -A_{kr} L_i^r - k A_{kr} \phi_i^r$$

From the last two equations, it follows that

(3.22)
$$-kA_{kr}L_{i}^{\ r} = (\theta - \frac{c}{4})A_{kr}\phi_{i}^{\ r} + \rho(k^{2} - \theta + \frac{c}{4})\phi_{ki}.$$

Transforming this by K_j^i and making of (2.2), (3.1) and (3.4), we find

$$(\theta - \frac{c}{4})(A_{kr}L_{j}^{r} + kA_{kr}\phi_{j}^{r}) = \rho(k^{2} - \theta + \frac{c}{4}),$$

which together with (3.22) yields

(3.23)
$$(k^2 - \theta + \frac{c}{4}) \{ \rho k L_{ji} - (\theta - \frac{c}{4}) (A_{jr} \phi_i^{\ r} - \rho \phi_{ji}) \} = 0.$$

Transforming (3.20) by K_l^{j} and making use of (3.4), (3.5), (3.18) and (3.21), we find

$$(\theta - \frac{c}{4})(\nabla_k K_{li} - n_k L_{li}) = (k^2 - \theta + \frac{c}{4})\{\xi_l(A_{kr}L_i^r + \rho k\phi_{ki}) - \rho(\xi_k L_{li} + \xi_i L_{lk})\},\$$

from which, taking the skew-symmetric part with respect to indices l and i,

$$(k^{2} - \theta + \frac{c}{4})\{\xi_{l}(A_{kr}L_{i}^{r} + \rho k\phi_{ki} + \rho L_{ki}) - \xi_{i}(A_{kr}L_{l}^{r} + \rho k\phi_{kl} + \rho L_{kl})\} = 0.$$

From the last two equations, it follows that

(3.24)
$$\nabla_k K_{ji} = n_k L_{ji} - a(\xi_k L_{ji} + \xi_i L_{jk} + \xi_j L_{ki}),$$

where we have put

(3.25)
$$a(\theta - \frac{c}{4}) = \rho(k^2 - \theta + \frac{c}{4}).$$

Differentiating (3.4) covariantly and using (1.4) and (3.24), we can verify that

(3.26)

$$\nabla_k L_{ji} = -n_k K_{ji} + a(\xi_k K_{ji} + \xi_j K_{ki} + \xi_i K_{kj}) - k(\xi_j A_{ki} + \xi_i A_{kj}) + k\{n_k + (2\alpha - a)\xi_k\}\xi_j\xi_i.$$

If we differentiate (3.24) covariantly and substitute (1.5), we find

— 75 —

$$\nabla_l \nabla_k K_{ji} = (\nabla_l n_k) L_{ji} + n_k \nabla_l L_{ji} + a\{(A_{lr} \phi_k^{\ r}) L_{ji} + (A_{lr} \phi_i^{\ r}) L_{jk} + (A_{lr} \phi_j^{\ r}) L_{ki}\} - a(\xi_k \nabla_l L_{ji} + \xi_i \nabla_l L_{jk} + \xi_j \nabla_l L_{ki}).$$

Multiplying this with ϕ^{lk} and summing for l and k, and taking account of (3.3), (3.4), (3.10), (3.11), (3.17) and (3.26), we obtain

$$\phi^{lk} \nabla_l \nabla_k K_{ji} = (\phi^{lk} \nabla_l n_k) L_{ji} + a \{ 2(n-1)\rho L_{ji} - A_{jr} L_i^r - A_{ir} L_j^r \},$$

or, using (2.1) and the Ricci identity for K_{ji} ,

$$-\frac{1}{2}\phi^{lk}(R_{lkjr}K_{i}^{r}+R_{lkir}K_{j}^{r})=2(n-1)(\theta-a\rho)L_{ji}-a(A_{jr}L_{i}^{r}+A_{ir}L_{j}^{r}).$$

On the other hand we have from (1.15)

$$\phi^{lk} R_{lkji} = \{c(n+1) - 4\theta - 2(\rho\alpha - \frac{c}{4})\}\phi_{ij}.$$

where we have used (2.2) with $l_j = 0$, (3.3), (3.4) and (3.15). Combining with last two equations, it is seen that

$$\{(n+1)(c-2\theta) - 2(\rho\alpha - \frac{c}{4})\}L_{ji} = 2(n-1)a\rho L_{ji} - a(A_{jr}L_{i}^{r} + A_{ir}L_{j}^{r}).$$

Multiplying L^{ji} to this and summing for j and i, and making use of (2.5), (3.7) and (3.18), we have

(3.27)
$$(n+1)(c-2\theta) - 2(\rho\alpha - \frac{c}{4}) = 2n\rho a.$$

Lemma 3.4. $\rho\alpha + \theta - \frac{3}{4}c = 0$ if $k \neq 0$. *Proof.* Suppose that $k^2 = \theta - \frac{c}{4}$. Then we have by (3.22)

$$A_{kr}L_i^{\ r} + kA_{kr}\phi_i^{\ r} = 0,$$

which together with (3.16) implies that

$$(\rho\alpha - \frac{c}{4})(L_{ji} - k\phi_{ji}) = 0.$$

Thus, it is seen that $\rho \alpha = \frac{c}{4}$. Therefore (3.25) and (3.27) will produce a contradiction because $\theta = \frac{c}{2}$ was assumed. Accordingly we have $k^2 - \theta + \frac{c}{4} = 0$ and hence

(3.28)
$$\rho k L_{ji} - (\theta - \frac{c}{4}) (A_{jr} \phi_i^{\ r} - \rho \phi_{ji}) = 0$$

by virtue of (3.23). If we take the usual norm of this and make use of (3.3), (3.16) and (3.17), then we obtain

(3.29)
$$\rho^2 k^2 = (\theta - \frac{c}{4})(\rho^2 + \rho\alpha - \frac{c}{4}),$$

which together with (3.27) gives the required relationship. This completes the proof of Lemma 3.4.

Multiplying (3.14) with ϕ^{ji} and summing for j and i, and taking account of (3.3), we get

(3.30)
$$A_{ji}K^{ji} = \{\alpha + (n-1)\rho\}k.$$

Now, we are going to prove that the distinguished normal C is parallel in the normal bundle. From (1.15) we verify that the Ricci tensor S of M with components S_{ji} is given by

$$(3.31) \quad S_{ji} = \frac{c}{4} \{ (2n+1)g_{ji} - 3\xi_j\xi_i \} + hA_{ji} - A_{ji}^2 + kK_{ji} - K_{ji}^2 - L_{ji}^2,$$

which together with (3.5), (3.17) and Lemma 3.4 implies that

(3.32)
$$S_{ji}\xi^{j}\xi^{i} = 2(n-1)(\theta - \frac{c}{2}).$$

If we multiply (3.31) with K^{ji} and sum for j and i, then we obtain

— 77 —

$$S_{ji}K^{ji} = 2(n-1)\{\theta - 2(n-2)\rho^2\}k,$$

where we have used (3.6), (3.16), (3.17), (3.18), (3.30) and Lemma 3.4.

Transforming (3.31) by $\phi_k^{\ i}$ and using (3.4), (3.7), (3.16), (3.17), (3.18) and Lemma 3.4, we find

$$S_{jr}\phi_{k}^{r} = \{\frac{c}{4}(2n+1) - \theta\}\phi_{kj} + \{\alpha - 2(n-2)\rho\}A_{jr}\phi_{k}^{r} + kL_{jk}.$$

Multiplying L^{jk} to this and making use of (2.5), (3.3), (3.30), (3.32), (3.33) and Lemma 3.4, we see that $k(\theta - \frac{c}{4}) = 0$. Therefore we have $\theta = \frac{c}{4}$. Because of Lemma 2.1, it follows that k = 0, a contradiction. Thus we have

Proposition 3.5. Let M be a real (2n - 1)-dimensional (n > 2) semiinvariant submanifold of codimension 3 in $P_{n+1}\mathbb{C}$. If it satisfies $dn = 2\theta\omega$ for $\theta \neq \frac{c}{2}$ and $A\xi = \alpha\xi$. Then $\nabla_j^{\perp}C = 0$, namely, the distinguished normal is parallel in the normal bundle.

4. Parallel distinguished normal vectors

In this section, we consider a semi-invariant submanifold of codimension 3 satisfying $dn = 2\theta\omega$ in a complex projective space.

Suppose that the distinguished normal C is parallel in the normal bundle. Then we have $l_j = m_j = 0$. Thus, (1.16), (1.17), (1.19) and (1.20) turn out respectively to

(4.1)
$$\nabla_k A_{ji} - \nabla_j A_{ki} = \frac{c}{4} (\xi_k \phi_{ji} - \xi_j \phi_{ki} - 2\xi_i \phi_{kj}),$$

(4.2)
$$\nabla_k K_{ji} - \nabla_j K_{ki} = n_k L_{ji} - n_j L_{ki},$$

(4.3)
$$A_{jr}K_{i}^{r} - A_{ir}K_{j}^{r} = 0, \quad A_{jr}L_{i}^{r} - A_{ir}L_{j}^{r} = 0.$$

Since we have $dn = 2\theta\omega$, relationships (2.2) and (2.8) are reduced respectively to

(4.4)
$$K_{jr}L_{i}^{\ r} = -(\theta - \frac{c}{4})\phi_{ji},$$

(4.5)
$$K_{ji}^{2} = (\theta - \frac{c}{4})(g_{ji} - \xi_{j}\xi_{i}).$$

Since we have $K_{ir}\xi^r = 0$, by differentiating covariantly along M and using (1.7) with $l_j = 0$, we find

$$(4.6) \qquad (\nabla_k K_{ir})\xi^r = -L_{ir}A_k^r.$$

Differentiating (4.5) covariantly along M and using (1.5), we have

(4.7)
$$K_{j}^{r}(\nabla_{k}K_{ir}) + K_{i}^{r}(\nabla_{k}K_{jr}) = (\theta - \frac{c}{4})(\xi_{j}A_{kr}\phi_{i}^{r} + \xi_{i}A_{kr}\phi_{j}^{r}).$$

Using the quaite same method as that used to (2.13) from (2.12), we can derive from (4.7) the following :

(4.8)
$$2K_{j}{}^{r}\nabla_{k}K_{ir} = (\theta - \frac{c}{4})\{2n_{k}\phi_{ij} + (A_{ir}\phi_{j}{}^{r} - A_{jr}\phi_{i}{}^{r})\xi_{k} + (A_{kr}\phi_{j}{}^{r} - A_{jr}\phi_{k}{}^{r})\xi_{i} + (A_{kr}\phi_{i}{}^{r} + A_{ir}\phi_{k}{}^{r})\xi_{j}\},$$

where we have used (4.2) and (4.4).

In the following, we are going to prove $A_{(2)} = 0$. By means of (4.5), we may only consider the case where $\theta - \frac{c}{4} \neq 0$ because it is already seen that θ is constant. By (4.2) we can, using k = l = 0, verify that $\nabla_r K_j^r = L_{jr} n^r$. Thus, multiplying (4.8) with g^{ki} and summing for k and i, we find

$$K_{j}^{\ r}L_{rs}n^{s} = (\theta - \frac{c}{4})(\phi_{rj}n^{r} + \xi^{s}A_{sr}\phi_{j}^{\ r}),$$

which together with (4.4) implies that $\xi^{s} A_{sr} \phi_{j}^{r} = 0$ and hence

Therefore, if we transvect (4.8) with ξ^{j} and take account of (1.8) and (4.9), then we obtain

From this and (4.1) we can prove the followings (cf. [7], [11]):

(4.11)
$$A_{ji}^{2} = \alpha A_{ji} + \frac{c}{4}(g_{ji} - \xi_{j}\xi_{i}),$$

(4.12)
$$\nabla_k A_{ji} = -\frac{c}{4} (\xi_j \phi_{ki} + \xi_i \phi_{kj}).$$

By means of (4.10), the equation (4.8) can be written as

$$K_j^{\ r} \nabla_k K_{ir} = (\theta - \frac{c}{4})(n_k \phi_{ij} + \xi_k A_{ir} \phi_j^{\ r} + \xi_i A_{kr} \phi_j^{\ r}).$$

Transforming by K_h^{j} and using (1.7), (4.3), (4.5) and (4.6), we obtain

(4.13)
$$\nabla_k K_{ji} = n_k L_{ji} - \xi_k A_{jr} L_i^{\ r} - \xi_i A_{kr} L_j^{\ r} - \xi_j A_{ir} L_k^{\ r},$$

Differentiating (1.7) with $l_j = 0$ covariantly and using (1.4) and (4.13), we have

(4.14)
$$\nabla_k L_{ji} = -n_k K_{ji} + \xi_k A_{jr} K_i^{\ r} + \xi_i A_{kr} K_j^{\ r} + \xi_j A_{ir} K_k^{\ r},$$

which together (1.8) with $l_j = 0$ and (4.9) implies that

(4.15)
$$T_r(AA_{(2)}) = 0, \quad T_r(A^2A_{(2)}) = 0$$

because of (4.11).

On the other hand, we have $A_{(2)}\xi = 0$ and $T_rA_{(2)} = 0$ and (4.5), the shape operator $A_{(2)}$ has at most three distinct constant eigenvalues $0, \sqrt{\theta - \frac{c}{4}}, -\sqrt{\theta - \frac{c}{4}}$ with multiplicities 1, n - 1, n - 1 respectively.

By (4.9), (4.10) and (4.11), we also see that A has at most three distinct constant eigenvalues α , $(\alpha + \sqrt{D})/2$, $(\alpha - \sqrt{D})/2$ with multiplicities 1, r, s respectively, where $D = \alpha^2 + c, r + s = 2n - 2$.

Since we have $AA_{(2)} = A_{(2)}A$, it follows that A and $A_{(2)}$ are diagonalizable at the same time. Because of (4.15), we have $(\theta - \frac{c}{4})r(\alpha^2 + c) = 0$. Thus s = 2(n-1) and consequently A has two constant eigenvalues α and $(\alpha - \sqrt{D})/2$ with multiplicities 1, 2(n-1) repectively. Accordingly the trace h of A is given by

$$(4.16) h = n\alpha - (n-1)\sqrt{D}.$$

Differentiating (4.13) covariantly along M and using (1.5), (1.8), (4.11), (4.12) and (4.13), we find

$$\nabla_{h}\nabla_{k}K_{ji} = (\nabla_{h}n_{k})L_{ji} - \frac{c}{4}(K_{ki}\xi_{j}\xi_{h} + K_{jh}\xi_{k}\xi_{i} + 2K_{ih}\xi_{j}\xi_{k}) + B_{hkji} - \alpha(\xi_{j}\xi_{h}A_{kr}K_{i}^{\ r} + \xi_{k}\xi_{i}A_{jr}K_{k}^{\ r} + 2\xi_{j}\xi_{k}A_{ir}K_{h}^{\ r}) + (A_{hs}\phi_{j}^{\ s})(A_{kr}L_{i}^{\ r}) + (A_{hs}\phi_{k}^{\ s})(A_{ir}L_{j}^{\ r}) + (A_{hs}\phi_{i}^{\ s})(A_{jr}L_{k}^{\ r}),$$

where B_{hkji} is a certain tensor with $B_{hkji} = B_{khji}$, from which, taking the skew-symmetric part with respect to h and k, and making use of (2.1), (4.10) and the Ricci identity for K_{ji} ,

$$(4.17) R_{khjr}K_{i}^{r} + R_{khir}K_{j}^{r} = 2\theta\phi_{hk}L_{ji} - \frac{c}{4}\{\xi_{j}(\xi_{k}K_{ih} - \xi_{h}K_{ik}) + \xi_{i}(\xi_{k}K_{jh} - \xi_{h}K_{jk})\} - \alpha\{\xi_{j}(\xi_{k}A_{ir}K_{h}^{r} - \xi_{h}A_{ir}K_{k}^{r}) + \xi_{i}(\xi_{k}A_{jr}K_{h}^{r} - \xi_{h}A_{jr}K_{k}^{r})\} + (A_{hs}\phi_{j}^{s})(A_{kr}L_{i}^{r}) - (A_{ks}\phi_{j}^{s})(A_{hr}L_{i}^{r}) + (A_{hs}\phi_{i}^{s})(A_{kr}L_{j}^{r}) - (A_{ks}\phi_{j}^{s})(A_{jr}L_{i}^{r}).$$

Multiplying (4.17) with ϕ^{kh} and summing for k and h, and using (1.6), (1.7), (2.1), (4.10) and (4.11), we find

(4.18)
$$\phi^{kh}(R_{khjr}K_i^r + R_{khir}K_j^r) = \{c - 4(n-1)\theta\}L_{ji} + 2(h+\alpha)A_{jr}L_i^r.$$

- 81 ---

On the other hand, we have from (1.15)

$$\phi^{kl}R_{klih} = (cn + \frac{c}{2})\phi_{hi} - 2\alpha A_{hr}\phi_{i}^{\ r} + 4K_{hr}L_{i}^{\ r},$$

where we have used (1.7), (1.8), (4.10) and (4.11), which together with (1.7) and (4.5) gives

$$\phi^{kl}(R_{klir}K_{j}^{r} + R_{kljr}K_{i}^{r}) = \{8\theta - (2n+3)c\}L_{ji} - 4\alpha A_{jr}L_{i}^{r}.$$

From this and (4.18), it is seen that

(4.19)
$$(h+3\alpha)A_{jr}L_{i}^{r} = \{2(n+1)\theta - (n+2)c\}L_{ji},$$

which implies

$$(h+3\alpha)(A_{ji}-\alpha\xi_{j}\xi_{i}) = \{2(n+1)\theta - (n+2)c\}(g_{ji}-\xi_{j}\xi_{i}).$$

If we take the trace of this, then we obtain

(4.20)
$$(h+3\alpha)(h-\alpha) = 2(n-1)\{2(n+1)\theta - (n+2)c\}.$$

In the same way, multiplying A^{jk} to (4.17) and summing for j and k, and taking account of (1.6), (1.8), (4.3), (4.9) ~ (4.11), we also have

$$(R_{kjir}K_{h}^{\ r} + R_{kjhr}K_{i}^{\ r})A^{ik} = (3\alpha^{2} - 2\theta + c)A_{hr}K_{j}^{\ r} + \frac{3}{4}c\alpha K_{jh}.$$

On the other hand, we have from (1.15)

$$(R_{kjir}K_{h}^{r} + R_{kjhr}K_{i}^{r})A^{ik} = (2\theta - 2c - h_{(2)})A_{hr}K_{j}^{r} + \{(\theta - \frac{c}{2})(h - \alpha) - \frac{c}{4}\alpha\}K_{jh},$$

where we have used (1.6), (1.7), (4.3), (4.4), (4.5) and (4.11). From the last two equations, it follows that

(4.21)
$$(4\theta - 3c - h_{(2)} - 3\alpha^2) A_{jr} K_i^{\ r} = \{c\alpha - (\theta - \frac{c}{2})(h - \alpha)\} K_{ji},$$

which implies

(4.22)
$$(4\theta - 3c - h_{(2)} - 3\alpha^2)(h - \alpha) = 2(n - 1)\{c\alpha - (\theta - \frac{c}{2})(h - \alpha)\}.$$

If we take account of (4.11), then (4.22) can be written as

$$2(n+1)(\theta - \frac{3}{4}c)(h-\alpha) - \alpha(h+3\alpha)(h-\alpha) = 2(n-1)c\alpha,$$

or use (4.20),

(4.23)
$$(\theta - \frac{3}{4}c)(h - \alpha) = 2(n - 1)\alpha(\theta - \frac{c}{2}).$$

By the way, we have from (4.16) and (4.20)

$$lpha(lpha-\sqrt{D})=2(heta-rac{3}{4}c).$$

Combining (4.16), (4.23) and the last equation, we see that

$$(\theta - \frac{3}{4}c)^2 = \alpha^2(\theta - \frac{c}{2}).$$

From this, (2.5) and (4.5) we have

Lemma 4.1. Let M be a real (2n-1)-dimensional (n > 2) semi-invariant submanifold of codimension 3 satisfying $dn = 2\theta\omega$ for a certain scalar $\theta < \frac{c}{2}$ in a complex projective space $P_{n+1}\mathbb{C}$. If the distinguished normal is parallel in the normal bundle, then we have $A_{(2)} = A_{(3)} = 0$.

Let $N_0(p) = \{\eta \in T_p^{\perp}(M) \mid A_{\eta} = 0\}$ and $H_0(p)$ the maximal J-invariant subspace of $N_0(p)$. As a consequence of Lemma 4.1, we have $A_{(2)} = A_{(3)} = 0$, the orthogonal complement of $H_0(p)$ is invariant under parallel translation with respect to the normal connection because of $\nabla_j^{\perp}C = 0$. Thus, by the reduction theorem in [5], [14] and by Lemma 2.2 and Proposition 3.5 we have

Theorem 4.2. Let M be a real (2n-1)-dimensional (n > 2) semi-invariant submanfold of codimension 3 in a complex projective space $P_{n+1}\mathbb{C}$. If the structure vector ξ is an eigenvector for the shape operator in the direction of the distinguished normal and the third fundamental tensor n satisfies dn = $2\theta\omega$ for a certain scalar $\theta(<\frac{c}{2})$, then M is a real hypersurface in a complex projective space $P_n\mathbb{C}$.

Owing to Theorem T and Theorem 4.2, we have

— 83 —

Theorem 4.3. Let M be a real (2n-1)-dimensional (n > 2) semi-invariant submanfold of codimension 3 in a complex projective space $P_{n+1}\mathbb{C}$ such that the third fundamental tensor satisfies $dn = 2\theta\omega$ for a certain scalar $\theta(<\frac{c}{2})$, where $\omega(X,Y) = g(X,\phi Y)$ for any vectors X and Y on M. Then M has constant eigenvalues corresponding the shape operator A in the direction of distinguished normal and the structure vector ξ is an eigenvector of A if and only if M is locally congruent to a homogeneous real hypersurfaces of $P_n\mathbb{C}$.

5. Examples of a nontrivial semi-invariant submanifold

In this section, we shall give an example of a nontrivial semi-invariant submanifold in $P_n\mathbb{C}$.

Let $p, q(3 \le p \le q)$ be integers. We denote by $M_{p,q}\mathbb{C}$ the space of $p \times q$ matrices over \mathbb{C} , which can be considered as a complex Euclidean space \mathbb{C}^{pq} with the standard Hermitian inner product. Let denote the unitary group of degree p by U(p). Then the Lie group $G := S(U(p) \times U(q))$ acts on $\mathbb{C}^{pq} \equiv M_{p,q}\mathbb{C}$ as follows:

$$(\sigma, \tau)X = \sigma X \tau^{-1}, \ (\sigma, \tau) \in G, X \in \mathbb{C}^{pq}.$$

Thus we can consider G as a unitary subgroup of U(pq). Remark that this action is nothing but the linear isotropic representation of the compact Hermitian symmetric space $SU(p+q)/S(U(p) \times U(q))$ of type AIII(cf. [6]).

Let π be the canonical projection of $\mathbb{C}^{pq} - \{0\}$ onto $P_{pq-1}\mathbb{C}$, and $S^{2pq-1}(r)$ the hypersphere in \mathbb{C}^{pq} of radius r centered at the origin.

Then, for any element A of $\mathbb{C}^{pq} - \{0\}$, the orbit G(A) of A under G is a compact homogeneous submanifold in $S^{2pq-1}(|A|)$, and the space $\pi(G(A))$ is a compact homogeneous submanifolds in $P_{pq-1}\mathbb{C}$. Moreover, for any normal vector N of G(A) in $S^{2pq-1}(|A|)$, the mean curvature of G(A) in the direction N is equal to the one of $\pi(G(A))$ in the direction π_*N in $P_{pq-1}\mathbb{C}$.(see e.g. [12]). In particular, G(A) is minimal in $S^{2pq-1}(|A|)$ if and only if $\pi(G(A))$ is minimal in $P_{pq-1}\mathbb{C}$.

Here, for $i = 1, \dots, p$ and $\alpha = 1, \dots, q$, we denote by $E_{i\alpha}$ the element of $M_{p,q}\mathbb{C}$ whose (i, α) -entry is 1 and other entries are all 0. In the sequel we shall show

(5.1) If $A = a_1 E_{11} + a_2 E_{22}$ satisfies $a_1 a_2 \neq 0$, $a_1^2 \neq a_2^2$, and $a_1^2 + a_2^2 = r^2$, then $\pi(G(A))$ is a (4p+4q-11)-dimensional semi-invariant submanifold in $P_{pq-1}\mathbb{C}$. By the definition, the tangent space $T_A(G(A))$ of the orbit of A under G is generated by the vectors

XA and AY,

where X(resp.Y) ranges over all skew-Hermitian matrices of degree p(degree q). Hence the space $T_A(G(A))$ are spanned over \mathbb{R} by the following vectors :

$$a_1\sqrt{-1}E_{11} + a_2\sqrt{-1}E_{22}, \ a_1\sqrt{-1}E_{11} - a_2\sqrt{-1}E_{22},$$

$$E_{12}, \sqrt{-1}E_{12}, E_{21}, \sqrt{-1}E_{21}, E_{i\alpha}, \sqrt{-1}E_{i\alpha}, E_{j\beta}, \sqrt{-1}E_{j\beta},$$

where $1 \leq i \leq 2, 3 \leq \alpha \leq q, 3 \leq j \leq p$ and $1 \leq \beta \leq 2$. Thus the intersection of the vector space $\sqrt{-1}T_A(G(A))$ and the normal space of G(A) at A in $S^{2pq-1}(r)$ is spanned by the vector

$$a_2\sqrt{-1}E_{11}-a_1\sqrt{-1}E_{22},$$

which shows that $\pi(G(A))$ is semi-invariant in $P_{pq-1}\mathbb{C}$. Since the space $SU(p+q)/S(U(p) \times U(q))$ is irreducible as a symmetric space, our space $\pi(G(A))$ is not trivially semi-invariant, *i.e.*, it satisfies $A_{(2)} \neq 0$ and $A_{(3)} \neq 0$ in the previous notation.

Remark 5.1. In the case p = q = 3, the space $\pi(G(A))$ is a submanifold of codimension 3 in $P_8\mathbb{C}$.

Remark 5.2. We can see that, among the spaces $\pi(G(A))$ satisfying the conditions $0 < a_1 < a_2$ and $a_1^2 + a_2^2 = r^2$, there is uniqully a minimal one. About this we shall work out in a forthcoming paper.

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