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# Sets of inhomogeneous linear forms can be not isotropically winning 

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We give an example of irrational vector $\boldsymbol{\theta} \in \mathbb{R}^{2}$ such that the set

$$
\operatorname{Bad}_{\theta}:=\left\{\left(\eta_{1}, \eta_{2}\right): \inf _{x \in \mathbb{N}} x^{1 / 2} \max _{i=1,2}\left\|x \theta_{i}-\eta_{i}\right\|>0\right\}
$$

is not absolutely winning with respect to McMullen's game.

## 1. Introduction

We consider a problem related to inhomogeneous Diophantine approximation. Given $\boldsymbol{\theta}=\left(\theta_{1}, \theta_{2}\right) \in \mathbb{R}^{2}$ we study the set of pairs $\left(\eta_{1}, \eta_{2}\right) \in \mathbb{R}^{2}$ such that the system of two linear forms

$$
\left\|x \theta_{1}-\eta_{1}\right\|, \quad\left\|x \theta_{2}-\eta_{2}\right\|,
$$

where $\|\cdot\|$ stands for the distance to the nearest integer, is badly approximable. We prove a statement complementary to our recent result from [Bengoechea et al. 2017]. We construct $\boldsymbol{\theta}$ such that the set

$$
\operatorname{Bad}_{\theta}:=\left\{\left(\eta_{1}, \eta_{2}\right): \inf _{x \in \mathbb{N}} x^{1 / 2} \max _{i=1,2}\left\|x \theta_{i}-\eta_{i}\right\|>0\right\}
$$

is not isotropically winning.
Our paper is organized as follows. In Section 2 we discuss different games appearing in Diophantine problems. In Section 3 we give a brief survey on inhomogeneous badly approximable systems of linear forms and formulate our main result, Theorem 3.1. Sections 4 and 5 are devoted to some auxiliary observations. In Sections 6, 7, and 8 we give a proof for Theorem 3.1.

## 2. Schmidt's game and its generalizations

The following game was introduced by Schmidt [1966; 1969; 1980]. Let $0<\alpha, \beta<1$. Suppose that two players A and B choose in turn a nested sequence of closed balls:

$$
B_{1} \supset A_{1} \supset B_{2} \supset A_{2} \supset \cdots
$$

with the property that the diameters $\left|A_{i}\right|,\left|B_{i}\right|$ of the balls $A_{i}, B_{i}$ satisfy

$$
\left|A_{i}\right|=\alpha\left|B_{i}\right|, \quad\left|B_{i+1}\right|=\beta\left|A_{i}\right| \quad \text { for all } i=1,2,3, \ldots,
$$

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for fixed $0<\alpha, \beta<1$. A set $E \subset \mathbb{R}^{n}$ is called $(\alpha, \beta)$-winning if player A has a strategy which guarantees that intersection $\bigcap A_{i}$ meets $E$ regardless of the way B chooses to play. A set $E \supset \mathbb{R}^{n}$ is called an $\alpha$-winning set if it is $(\alpha, \beta)$-winning for all $0<\beta<1$.

There are different modifications of Schmidt's game: the strong game and absolute game introduced in [McMullen 2010], the hyperplane absolute game introduced in [Kleinbock and Weiss 2010], the potential game considered in [Fishman et al. 2013], and some others. In [Bengoechea et al. 2017], we introduced isotropically winning sets. Let us describe here some of these generalizations in more detail.

The definition of an absolutely winning set was given in [McMullen 2010]. Consider the following game. Suppose $A$ and $B$ choose in turn a sequence of balls $A_{i}$ and $B_{i}$ such that the sets

$$
B_{1} \supset\left(B_{1} \backslash A_{1}\right) \supset B_{2} \supset\left(B_{2} \backslash A_{2}\right) \supset B_{3} \supset \cdots
$$

are nested. For fixed $0<\beta<\frac{1}{3}$ we suppose

$$
\left|B_{i+1}\right| \geq \beta\left|B_{i}\right|, \quad\left|A_{i}\right| \leq \beta\left|B_{i}\right|
$$

We say $E$ is an absolute winning set if for all $\beta \in\left(0, \frac{1}{3}\right)$, player A has a strategy which guarantees that $\cap B_{i}$ meets $E$ regardless of how B chooses to play. Mcmullen proved that an absolute winning set is $\alpha$-winning for all $\alpha<\frac{1}{2}$. Several examples of absolute winning sets were exhibited by McMullen [2010]. In particular, a set of badly approximable numbers in $\mathbb{R}$ is absolutely winning. However the set of simultaneously badly approximable vectors in $\mathbb{R}^{n}$ for $n>1$ is not absolutely winning.

In [Bengoechea et al. 2017] another strong variant of the winning property was given. We say that a set $E \subset \mathbb{R}^{n}$ is isotropically winning if for each $d \leq n$ and for each $d$-dimensional affine subspace $\mathcal{A} \subset \mathbb{R}^{n}$ the intersection $E \cap \mathcal{A}$ is $\frac{1}{2}$-winning for Schmidt's game considered as a game in $\mathcal{A}$. It is clear that an absolute winning set is isotropically winning for each $\alpha \leq \frac{1}{2}$.

## 3. Inhomogeneous approximations

The first important result on inhomogeneous approximations in the one-dimensional case is due to Khinchine [1926]. He proved that there exists an absolute constant $\gamma$ such that for every $\theta \in \mathbb{R}$ there exists $\eta \in \mathbb{R}$ such that

$$
\inf _{q \in \mathbb{Z}} q\|q \theta-\eta\|>\gamma
$$

Later (see [Khinchin 1937; 1948]) he proved that for given positive numbers $n, m \in \mathbb{Z}$ there exists a positive constant $\gamma_{n m}$ such that for any $m \times n$ real matrix $\boldsymbol{\theta}$ there exists a vector $\boldsymbol{\eta} \in \mathbb{R}^{n}$ such that

$$
\inf _{\boldsymbol{x} \in \mathbb{Z}^{m} \backslash\{0\}}\left(\|\boldsymbol{\theta} \boldsymbol{x}-\boldsymbol{\eta}\|_{\mathbb{Z}^{n}}\right)^{n}\|\boldsymbol{x}\|^{m}>\gamma_{n m}
$$

(here $\|\cdot\|_{\mathbb{Z}^{n}}$ stands for the distance to the nearest integral point in sup-norm). These results are presented in a wonderful book by Cassels [1957].

Jarník [1941], proved a generalization of this statement. Suppose $\psi(t)$ is a function decreasing to zero as $t \rightarrow+\infty$. Let $\rho(t)$ be the function inverse to the function $t \mapsto 1 / \psi(t)$. Suppose that for all $t>1$ one has $\psi_{\theta}(t) \leq \psi(t)$. Then there exists a vector $\eta \in \mathbb{R}^{n}$ such that

$$
\inf _{\boldsymbol{x} \in \mathbb{Z}^{m} \backslash\{0\}}\left(\|\boldsymbol{\theta} \boldsymbol{x}-\boldsymbol{\eta}\|_{\mathbb{Z}^{n}}\right) \cdot \rho(8 m \cdot\|\boldsymbol{x}\|)>\gamma
$$

with appropriate $\gamma=\gamma(n, m)$.
Denote by

$$
\operatorname{Bad}_{\theta}=\left\{\alpha \in[0,1): \inf _{q \in \mathbb{N}} q \cdot\|q \theta-\alpha\|>0\right\}
$$

It happens that the winning property of this inhomogeneous Diophantine set was considered quite recently. Tseng [2009] showed that $\mathrm{Bad}_{\theta}$ is winning for all real numbers $\theta$ in classical Schmidt's sense. For the corresponding multidimensional sets

$$
\operatorname{Bad}(n, m)=\left\{\boldsymbol{\theta} \in \operatorname{Mat}_{n \times m}(\mathbb{R}): \inf _{q \in \mathbb{Z}_{\neq 0}^{m}} \max _{1 \leq i \leq n}\left(|q|^{m / n}\left\|\boldsymbol{\theta}_{i}(q)\right\|\right)>0\right\}
$$

the winning property is shown, for example, in [Einsiedler and Tseng 2011; Moshchevitin 2011]. In [Broderick et al. 2013] it was shown that the set $\operatorname{Bad}(n, m)$ is hyperplane absolutely winning. The methods used in [Broderick et al. 2013] come from [Broderick et al. 2011].

Further generalizations deal with the twisted sets

$$
\operatorname{Bad}(i, j)=\left\{\left(\theta_{1}, \theta_{2}\right) \in \mathbb{R}^{2}: \inf _{q \in \mathbb{N}} \max \left(q^{i}\left\|q \theta_{1}\right\|, q^{j}\left\|q \theta_{2}\right\|\right)>0\right\}
$$

where $i, j$ are real positive numbers satisfying $i+j=1$, introduced by Schmidt. In [An 2016] it was proved that $\operatorname{Bad}(i, j)$ is winning for the standard Schmidt game. In higher dimension, we fix an $n$-tuple $\boldsymbol{k}=\left(k_{1}, \ldots, k_{n}\right)$ of real numbers satisfying

$$
\begin{equation*}
k_{1}, \ldots, k_{n}>0 \quad \text { and } \quad \sum_{i=1}^{n} k_{i}=1 \tag{1}
\end{equation*}
$$

and define

$$
\operatorname{Bad}(\boldsymbol{k}, n, m)=\left\{\boldsymbol{\theta} \in \operatorname{Mat}_{n \times m}(\mathbb{R}): \inf _{q \in \mathbb{Z}_{\neq 0}^{m}} \max _{1 \leq i \leq n}\left(|q|^{m k_{i}}\left\|\boldsymbol{\theta}_{i}(q)\right\|\right)>0\right\}
$$

Here, $|\cdot|$ denotes the supremum norm, $\boldsymbol{\theta}=\left(\boldsymbol{\theta}_{i j}\right)$, and $\boldsymbol{\theta}_{i}(q)$ is the product of the $i$-th line of $\boldsymbol{\theta}$ with the vector $q$, i.e.,

$$
\boldsymbol{\theta}_{i}(q)=\sum_{j=1}^{m} q_{j} \boldsymbol{\theta}_{i j}
$$

In the twisted setting, much less is known. In particular up to now the winning property of the set $\operatorname{Bad}(\boldsymbol{k}, n, m)$ in dimension greater that two is not proved.

Given $\boldsymbol{\theta} \in \operatorname{Mat}_{n \times m}(\mathbb{R})$, we define

$$
\operatorname{Bad}_{\boldsymbol{\theta}}(\boldsymbol{k}, n, m)=\left\{x \in \mathbb{R}^{n}: \inf _{q \in \mathbb{Z}_{\neq 0}^{m}} \max _{1 \leq i \leq n}\left(|q|^{m k_{i}}\left\|\boldsymbol{\theta}_{i}(q)-x_{i}\right\|\right)>0\right\} .
$$

Harrap and Moshchevitin [2017] showed that this set is winning provided that $\boldsymbol{\theta} \in \operatorname{Bad}(\boldsymbol{k}, n, m)$. In [Bengoechea et al. 2017] it was proved that if we suppose that $\boldsymbol{\theta} \in \operatorname{Bad}(\boldsymbol{k}, n, m)$, the set $\operatorname{Bad}_{\boldsymbol{\theta}}(\boldsymbol{k}, n, m)$ is isotropically winning. ${ }^{1}$

We should note that even in the case $n=2, m=1$ it is not known if the set $\operatorname{Bad}_{\boldsymbol{\theta}}(\boldsymbol{k}, 2,1)$ is $\alpha$-winning for some positive $\alpha$ without the condition $\boldsymbol{\theta} \in \operatorname{Bad}(\boldsymbol{k}, 2,1)$.

[^0]In this article we show that the condition $\boldsymbol{\theta}$ be from $\operatorname{Bad}(\boldsymbol{k}, n, m)$ is essential for the isotropically winning property, and prove the following theorem.

Theorem 3.1. There exists a vector $\boldsymbol{\theta}=\left(\theta_{1}, \theta_{2}\right)$ such that:
(1) $1, \theta_{1}, \theta_{2}$ are linearly independent over $\mathbb{Z}$.
(2) $\operatorname{Bad}_{\theta}:=\left\{\left(\eta_{1}, \eta_{2}\right): \inf _{x \in \mathbb{N}} x^{1 / 2} \max _{i=1,2}\left\|x \theta_{i}-\eta_{i}\right\|>0\right\}$ is not isotropically winning.

## 4. Some more remarks

In the sequel, $\boldsymbol{x}=\left(x_{0}, x_{1}, x_{2}\right)$ is a vector in $\mathbb{R}^{3},|\cdot|$ stands for the Euclidean norm of the vector, and by ( $\boldsymbol{w}, \boldsymbol{t}$ ) we denote the inner product of vectors $\boldsymbol{w}$ and $\boldsymbol{t}$.

The proof of Theorem 3.1 we will give in Section 6 . There we will construct a special $\boldsymbol{\theta}$ and a onedimensional affine subspace $\mathcal{P}$ such that $\boldsymbol{\theta} \in \mathcal{P}$ and for the segment $\mathcal{D}=\mathcal{P} \cap\{|\boldsymbol{z}-\boldsymbol{\theta}| \leq 1\}$ one has $\mathcal{D} \cap \operatorname{Bad}_{\theta}=\varnothing$. Moreover, given an arbitrary positive function $\omega(t)$ monotonically (slowly) increasing to infinity we can ensure that for all $\eta=\left(\eta_{1}, \eta_{2}\right) \in \mathcal{D}$ there exist infinitely many $x \in \mathbb{Z}$ such that

$$
\max _{i=1,2}\left\|x \theta_{i}-\eta_{i}\right\|<\frac{\omega(x)}{x}
$$

To explain the construction of the proof it is useful to consider the case when $\theta_{1}, \theta_{2}, 1$ are linearly dependent. This case we will discuss in Section 5.

Remark 4.1. From the result of the paper [Bengoechea et al. 2017] it follows that the vector $\boldsymbol{\theta}$ constructed in Theorem 3.1 does not belong to the set

$$
\operatorname{Bad}=\left\{\left(\theta_{1}, \theta_{2}\right) \mid \inf _{x \in \mathbb{N}} x^{1 / 2} \max \left(\left\|\theta_{1} x\right\|,\left\|\theta_{2} x\right\|\right)>0\right\}
$$

Remark 4.2. Let $\boldsymbol{\theta}=\left(a_{1} / q, a_{2} / q\right)$ be rational. Let $\eta=\left(\eta_{1}, \eta_{2}\right) \notin \frac{1}{q} \cdot \mathbb{Z}^{2}$; then for any $x \in \mathbb{Z}$,

$$
\max _{i=1,2}\left\|x \frac{a_{i}}{q}-\eta_{i}\right\| \geq \operatorname{dist}\left(\boldsymbol{\eta}, \frac{1}{q} \cdot \mathbb{Z}^{2}\right)>0
$$

So the set

$$
\mathcal{B}=\left\{\eta: \inf _{x \in \mathbb{Z}} \max _{i=1,2}\left\|x \frac{a_{i}}{q}-\eta_{i}\right\|>0\right\}
$$

contains $\mathbb{R}^{2} \backslash \frac{1}{q} \cdot \mathbb{Z}^{2}$ and is trivially winning. It is clear that for any one-dimensional affine subspace $\ell$ we have $\mathcal{B} \cap \ell \supset\left(\mathbb{R}^{2} \backslash \frac{1}{q} \cdot \mathbb{Z}^{2}\right) \cap \ell$. So obviously $\mathcal{B} \cap \ell$ is also winning in $\ell$.

## 5. Linearly dependent case

Let $1, \theta_{1}, \theta_{2}$ be linearly dependent and at least one of $\theta_{j}$ is irrational. This means that there exists $z=\left(z_{0}, z_{1}, z_{2}\right) \in \mathbb{Z}^{3}$ such that $(\boldsymbol{z}, \boldsymbol{\theta})=0$. Let us consider the two-dimensional rational subspace

$$
\pi=\left\{\boldsymbol{x} \in R^{3}:(\boldsymbol{x}, \boldsymbol{z})=0\right\},
$$

so $\boldsymbol{\theta} \in \pi$.
Let us define the one-dimensional subspace $\mathcal{P}=\left\{\left(x_{1}, x_{2}\right):\left(1, x_{1}, x_{2}\right) \in \pi\right\} \subset \mathbb{R}^{2}$.

We will prove that there exists a constant $\gamma$ such that for any $\eta=\left(\eta_{1}, \eta_{2}\right) \in \mathcal{P}$ the inequality

$$
\max _{i=1,2}\left\|\theta_{i} x-\eta_{i}\right\|<\frac{\gamma}{x}
$$

has infinitely many solutions in $x \in \mathbb{N}$. (This statement is similar to Chebyshev's theorem [Khinchin 1964, Theorem 24, Chapter 2].)

Denote by $\Lambda=\pi \cap \mathbb{Z}^{3}$ the integer lattice with the determinant $d:=\operatorname{det} \Lambda=|\boldsymbol{z}|$. Denote by $\left\{\boldsymbol{g}_{\nu}=\right.$ $\left.\left(q_{\nu}, a_{1 \nu}, a_{2 v}\right)\right\}_{\nu=1,2,3, \ldots} \subset \Lambda$ the sequence of the best approximations of $\boldsymbol{\theta}$ by the lattice $\Lambda$ and the corresponding parallelograms

$$
\Pi_{v}=\left\{\boldsymbol{x}=\left(x_{0}, x_{1}, x_{2}\right) \in \pi: 0 \leq x_{0} \leq q_{\nu}, \operatorname{dist}(\boldsymbol{x}, l(\boldsymbol{\theta})) \leq \operatorname{dist}\left(\boldsymbol{g}_{\nu-1}, l(\boldsymbol{\theta})\right)\right\}
$$

which contains a fundamental domain of the two-dimensional $\Lambda$. Obviously, vol $\Pi_{v} \leq 4 d$. So,

$$
\begin{equation*}
\operatorname{dist}\left(\boldsymbol{g}_{v-1}, l(\theta)\right) \ll \frac{d}{q_{v}} \tag{2}
\end{equation*}
$$

with an absolute constant in the sign $\ll$. It is clear that for any point $\boldsymbol{\eta} \in \pi$, the shift $\boldsymbol{\eta}+\Pi_{\nu}$ contains a point of $\Lambda$.

For any $\boldsymbol{\eta}=\left(\eta_{1}, \eta_{2}\right) \in \mathcal{P}$ and for any positive integer $v$ the planar domain $\overline{\boldsymbol{\eta}}+\Pi_{v}, \overline{\boldsymbol{\eta}}=\left(1,-\eta_{1},-\eta_{2}\right)$ contains an integer point $\boldsymbol{y}=\left(x, y_{1}, y_{2}\right) \in \Lambda$.

It is clear that

$$
\begin{equation*}
1 \leq x \leq 1+q_{v} \tag{3}
\end{equation*}
$$

and

$$
\max _{i=1,2}\left\|\theta_{i} x-\eta_{i}\right\| \ll \operatorname{dist}(\boldsymbol{y}, l(\boldsymbol{\theta})+\overline{\boldsymbol{\eta}}) \ll \operatorname{dist}\left(l(\boldsymbol{\theta}), \boldsymbol{g}_{v-1}\right)
$$

and by (2),

$$
\begin{equation*}
\max _{i=1,2}\left\|\theta_{i} x-\eta_{i}\right\| \ll \frac{d}{q_{v}} \tag{4}
\end{equation*}
$$

From (3), (4) it follows that the inequality

$$
\max _{i=1,2}\left\|\theta_{i} x-\eta_{i}\right\| \ll \frac{d}{x}
$$

has infinitely many solutions and everything is proved.

## 6. Inductive construction of integer points

Let $\omega(t)$ be arbitrary positive function monotonically (slowly) increasing to infinity. Here we describe the inductive construction of integer points $z_{v}=\left(q_{\nu}, z_{1 \nu}, z_{2 v}\right)$. The base of the induction process is trivial. One can take an arbitrary primitive pair of integer vectors that can be completed to a basis of $\mathbb{Z}^{3}$.

Suppose that we have two primitive integer vectors

$$
z_{v-1}=\left(q_{v-1}, z_{1 v-1}, z_{2 v-1}\right) \in \mathbb{Z}^{3}, \quad z_{v}=\left(q_{v}, z_{1 v}, z_{2 v}\right) \in \mathbb{Z}^{3}
$$

Now we explain how to construct the next integer vector $\boldsymbol{z}_{v+1}$.
We consider the two-dimensional subspace

$$
\pi_{v}=\left\langle\boldsymbol{z}_{v-1}, \boldsymbol{z}_{v}\right\rangle_{\mathbb{R}}
$$

The pair of vectors $\boldsymbol{z}_{v-1}$ and $\boldsymbol{z}_{v}$ is primitive, so the lattice spanned by them is

$$
\Lambda_{v}:=\left\langle z_{v-1}, z_{v}\right\rangle_{\mathbb{Z}}=\pi_{v} \cap \mathbb{Z}^{3}
$$

By $d_{v}=\operatorname{det} \Lambda_{v}$ we denote the two-dimensional fundamental volume of the lattice $\Lambda_{v}$. Now we define the vector $\boldsymbol{n}_{v}=\left(n_{0 v}, n_{1 v}, n_{2 v}\right) \in \mathbb{R}^{3}$ from the conditions

$$
\pi_{v}=\left\{\boldsymbol{x} \in \mathbb{R}^{3}:\left(\boldsymbol{x}, \boldsymbol{n}_{v}\right)=0\right\}, \quad\left|\boldsymbol{n}_{v}\right|=1
$$

Put

$$
\begin{equation*}
\sigma_{v}=\operatorname{dist}\left(\boldsymbol{z}_{v-1}, l\left(\boldsymbol{z}_{v}\right)\right) \tag{5}
\end{equation*}
$$

Obviously, $\left|z_{\nu}\right| \asymp q_{\nu}$ and

$$
\begin{equation*}
\sigma_{v} \asymp \frac{d_{v}}{q_{v}} \tag{6}
\end{equation*}
$$

We define a vector $\boldsymbol{e}_{v}$ from the conditions

$$
\begin{equation*}
\boldsymbol{e}_{\nu} \in \pi_{\nu}, \quad\left|\boldsymbol{e}_{\nu}\right|=1, \quad\left(\boldsymbol{e}_{\nu}, \boldsymbol{z}_{v}\right)=0 \tag{7}
\end{equation*}
$$

so $\boldsymbol{e}_{\nu}$ is parallel to $\pi_{\nu}$ and orthogonal to $\boldsymbol{z}_{v}$.
Define the rectangle

$$
\Pi_{v}=\left\{\boldsymbol{x}=\left(x_{0}, x_{1}, x_{2}\right): \boldsymbol{x}=t \boldsymbol{z}_{v}+r \boldsymbol{e}_{v}, 0 \leq t \leq\left|\boldsymbol{z}_{v}\right|,|r| \leq \sigma_{v}\right\} .
$$

It is clear that rectangle $\Pi_{\nu} \subset \pi_{\nu}$ contains a fundamental domain of the lattice $\Lambda_{v}$. We need two axillary vectors $z_{v}^{a}$ and $z_{v}^{b}$ defined as

$$
\boldsymbol{z}_{v}^{a}=\boldsymbol{z}_{v}+a_{v} \boldsymbol{e}_{v}, \quad \boldsymbol{z}_{v}^{b}=\boldsymbol{z}_{v}^{a}+b_{v} \boldsymbol{n}_{v}
$$

where positive $a_{v}$ is chosen in such a way that

$$
\begin{equation*}
a_{v} d_{v}^{2} \leq v^{-1} \omega\left(\frac{q_{v}^{2}}{d_{v}^{2}} \cdot \frac{1}{a_{v}}\right) \tag{8}
\end{equation*}
$$

and

$$
\begin{equation*}
b_{v}=a_{v} \min \left(1, \frac{d_{v}}{q_{v}}\right) \tag{9}
\end{equation*}
$$

From the construction, it follows that

$$
\begin{equation*}
\left|z_{v}^{a}\right| \asymp\left|z_{v}^{b}\right| \asymp\left|z_{v}\right| \asymp q_{v} \tag{10}
\end{equation*}
$$

The integer lattice $\mathbb{Z}^{3}$ splits into levels with respect to the two-dimensional sublattice $\Lambda_{v}$ in such a way that

$$
\mathbb{Z}^{3}=\bigsqcup_{i \in \mathbb{Z}} \Lambda_{v, i}
$$

where $\Lambda_{\nu, j}=\Lambda_{v}+j z^{\prime}, j \in \mathbb{Z}$ and integer vector $\boldsymbol{z}^{\prime}$ completes the couple $\boldsymbol{z}_{v-1}, \boldsymbol{z}_{\nu}$ to the basis in $\mathbb{Z}^{3}$. We consider the affine subspace $\pi_{v}^{1}=\pi_{v}+z^{\prime} \supset \Lambda_{v, 1}$, which is parallel to $\pi_{\nu}$. It is clear that dist $\left(\pi_{\nu}, \pi_{v}^{1}\right)=1 / d_{v}$.

We need to determine the next integer point $z_{v+1}$. Denote by $\mathfrak{P}$ the central projection with center 0 onto the affine subspace $\pi_{v}^{1}$. We consider the triangle $\Delta$ with vertices $\boldsymbol{z}_{v}, \boldsymbol{z}_{v}^{a}$, $\boldsymbol{z}_{v}^{b}$ and its image $\mathfrak{P} \Delta$ under


Figure 1. The central projection $\mathfrak{P}$.
the projection $\mathfrak{P}$ (Figure 1).
Define

$$
\begin{equation*}
Z=\mathfrak{P} z_{v}^{b} \tag{11}
\end{equation*}
$$

One can see that

$$
\begin{equation*}
|\boldsymbol{Z}| \asymp \frac{q_{v}}{d_{v} b_{v}} \tag{12}
\end{equation*}
$$

Define rays

$$
\mathcal{R}_{1}=\left\{z=Z+t z_{v}: t \geq 0\right\} \quad \text { and } \quad \mathcal{R}_{2}=\left\{z=\mathbf{Z}+t z_{v}^{a}: t \geq 0\right\}
$$

It is clear that $\mathcal{R}_{1} \cap \mathcal{R}_{2}=\{\boldsymbol{Z}\}$ and $\mathcal{R}_{1}, \mathcal{R}_{2} \subset \pi_{\nu}^{1}$. Moreover, the whole convex angle bounded by rays $\mathcal{R}_{1}, \mathcal{R}_{2}$ form the image of the triangle $\Delta$ under the projection $\mathfrak{P}$ :

$$
\mathfrak{P} \Delta=\operatorname{conv}\left(\mathcal{R}_{1} \cup \mathcal{R}_{2}\right)
$$

The affine subspace $\pi_{v}^{1}$ contains the affine lattice $\Lambda_{v}^{1}=\Lambda_{v}+z^{\prime}$ which is congruent to the lattice $\Lambda_{v}$. Thus, for any $\zeta \in \pi_{v}^{1}$, the shift $\Pi_{v}+\zeta$ contains an integer point from $\Lambda_{v}^{1}$.

Put

$$
\begin{equation*}
\tau_{\nu}=\frac{2 \sigma_{\nu}\left|z_{\nu}\right|}{a_{\nu}} \tag{13}
\end{equation*}
$$

Consider the point

$$
\zeta_{v}=\boldsymbol{Z}+\tau_{\nu} \boldsymbol{z}_{v}+\sigma_{v} \boldsymbol{e}_{v} \in \pi_{\nu}^{1}
$$

and the rectangle

$$
\Pi_{v}^{1}=\Pi_{v}+\zeta_{v} \subset \pi_{v}^{1}
$$

It is clear that

$$
\Pi_{v}^{1} \subset \mathfrak{P} \Delta
$$

(here $\boldsymbol{Z}$ was defined in (11), $\boldsymbol{e}_{\nu}$ was defined in (7), and the parameters $\sigma_{\nu}, \tau_{\nu}$ come from (5) and (13)).
Now we take the integer point

$$
z_{v+1}=\left(q_{v+1}, z_{1 v+1}, z_{2 v+1}\right) \in \Lambda_{v}^{1} \cap \Pi_{v}^{1}
$$

From the construction it follows that

$$
q_{v+1} \asymp\left|z_{v+1}\right| \asymp|z|+\tau_{\nu}\left|z_{\nu}\right|+\left|z_{\nu}\right| \asymp q_{\nu}\left(1+\frac{1}{d_{\nu} b_{v}}+\frac{\sigma_{v}}{a_{\nu}}\right) \asymp q_{\nu}\left(1+\frac{1}{d_{\nu} b_{v}}\right)+\frac{d_{\nu}}{a_{v}} \asymp \frac{q_{v}}{d_{\nu} b_{v}} .
$$

(Here we use (6), (9), (10), (12), and (13).) From (9) we see that

$$
\begin{equation*}
q_{v+1} \gg\left(\frac{q_{v}}{d_{v}}\right)^{2} \frac{1}{a_{v}} \tag{14}
\end{equation*}
$$

Now we are able to define the next two-dimensional lattice

$$
\Lambda_{v+1}=\left\langle z_{v}, z_{v+1}\right\rangle_{\mathbb{Z}}
$$

Let $d_{v+1}$ be its fundamental volume. We will estimate the value of $d_{v+1}$ taking into account (9) as

$$
\begin{equation*}
d_{v+1} \ll q_{v} \cdot \operatorname{dist}\left(\boldsymbol{z}_{v+1}, l\left(\boldsymbol{z}_{v}\right)\right) \ll \frac{q_{v}}{d_{v}} \cdot \frac{a_{v}}{b_{v}} \ll\left(\frac{q_{v}}{d_{v}}\right)^{2} \ll q_{v}^{2} \tag{15}
\end{equation*}
$$

From (14) and (15), we deduce that

$$
d_{v+1} \ll a_{\nu} d_{v}^{2} q_{v+1}
$$

By the choice of $a_{v}$ (by formula (8)) we have

$$
\begin{equation*}
d_{v+1} \leq \frac{\omega\left(q_{v+1}\right)}{v} \tag{16}
\end{equation*}
$$

## 7. The vector $\theta$

Now we define

$$
\boldsymbol{\theta}_{v}=\left(\theta_{1 v}, \theta_{2 v}\right), \quad \theta_{j v}=\frac{q_{j v}}{q_{v}}
$$

We consider the angles between the successive vectors $\boldsymbol{n}_{v}$ and $\boldsymbol{n}_{v+1}$ :

$$
\alpha_{v}=\operatorname{angle}\left(\boldsymbol{n}_{v}, \boldsymbol{n}_{v+1}\right) \asymp \tan \operatorname{angle}\left(\boldsymbol{n}_{v}, \boldsymbol{n}_{v+1}\right)
$$

Since $z_{v+1} \in \mathfrak{P} \Delta$ (see Figure 2), we have

$$
\tan \operatorname{angle}\left(\boldsymbol{n}_{v}, \boldsymbol{n}_{v+1}\right) \leq \frac{b_{v}}{a_{v}},
$$



Figure 2. The vector $z_{v+1}$ intersects the interior of the triangle $\Delta=z_{\nu} z_{v}^{a} z_{v}^{b}$.
and so

$$
\begin{equation*}
\alpha_{v} \ll \frac{b_{v}}{a_{v}} \tag{17}
\end{equation*}
$$

As $\boldsymbol{z}_{v+1} \in \mathfrak{P} \Delta$, we have

$$
\begin{equation*}
\left|\boldsymbol{\theta}_{v}-\boldsymbol{\theta}_{v+1}\right| \ll \frac{\sqrt{a_{v}^{2}+b_{v}^{2}}}{q_{v}} \ll \frac{a_{v}}{q_{v}} \tag{18}
\end{equation*}
$$

by the same argument. There exist limits

$$
\lim _{v \rightarrow \infty} \boldsymbol{\theta}_{v}=\boldsymbol{\theta}=\left(\theta_{1}, \theta_{2}\right) \quad \text { and } \quad \lim _{v \rightarrow \infty} \boldsymbol{n}_{v}=\boldsymbol{n}
$$

and from (17) and (18) we deduce that

$$
\begin{equation*}
0<\left|\boldsymbol{\theta}-\boldsymbol{\theta}_{v}\right| \ll \frac{a_{v}}{q_{v}} \tag{19}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{angle}\left(\boldsymbol{n}, \boldsymbol{n}_{v}\right) \ll \frac{b_{v}}{a_{v}} \tag{20}
\end{equation*}
$$

It is clear that $\boldsymbol{\theta} \notin \mathbb{Q}^{2}$. A slight modification ${ }^{2}$ of the procedure of choosing vectors $\boldsymbol{z}_{v}$ ensures the condition that $1, \theta_{1}, \theta_{2}$ are linearly independent over $\mathbb{Z}$. Define $\pi=\left\{\boldsymbol{x} \in \mathbb{R}^{3}:(\boldsymbol{x}, \boldsymbol{n})=0\right\}$. Then $\boldsymbol{\theta} \in \pi$ by continuity and we can assume that $\boldsymbol{n} \notin \mathbb{Q}^{3}$.

## 8. Winning property

Consider the one-dimensional affine subspaces

$$
\mathcal{P}_{\nu}=\left\{\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}:\left(1, x_{1}, x_{2}\right) \in \pi_{\nu}\right\} \subset \mathbb{R}^{2}
$$

and

$$
\mathcal{P}=\left\{\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}:\left(1, x_{1}, x_{2}\right) \in \pi\right\} \subset \mathbb{R}^{2},
$$

where $\pi$ was defined at the end of the previous section. Let

$$
B_{1}(\boldsymbol{\theta})=\left\{\boldsymbol{\xi} \in \mathbb{R}^{2}: \operatorname{dist}(\boldsymbol{\xi}, \boldsymbol{\theta})<1\right\} .
$$

We will show that for any $\eta=\left(\eta_{1}, \eta_{2}\right) \in \mathcal{P} \cap B_{1}(\boldsymbol{\theta})$ there exists infinitely many solutions of the inequality

$$
\max _{i=1,2}\left\|\theta_{i} x-\eta_{i}\right\|<\frac{\omega(x)}{x}
$$

in integers $x$. Denote by $\boldsymbol{\eta}_{v}=\left(\eta_{1 v}, \eta_{2 v}\right)$ the orthogonal projection of $\boldsymbol{\eta}$ onto $\mathcal{P}_{v}$. From (20) we see that

$$
\begin{equation*}
\left|\boldsymbol{\eta}-\boldsymbol{\eta}_{v}\right| \ll \frac{b_{v}}{a_{v}} \tag{21}
\end{equation*}
$$

[^1]For any $\boldsymbol{\eta}_{\nu}=\left(\eta_{1 \nu}, \eta_{2 v}\right) \in \mathcal{P}_{\nu}$ the planar domain $\overline{\boldsymbol{\eta}}_{v}+\Pi_{\nu}, \overline{\boldsymbol{\eta}}_{\nu}=\left(1,-\eta_{1 \nu},-\eta_{2 v}\right)$ contains an integer point $\boldsymbol{y}_{v}=\left(x_{v}, y_{1 \nu}, y_{2 v}\right) \in \Lambda_{v}$. It is clear that

$$
\begin{equation*}
\left|x_{v}\right| \ll q_{v} \tag{22}
\end{equation*}
$$

and

$$
\begin{equation*}
\max _{i=1,2}\left|\theta_{i v} x_{v}-\eta_{i v}-y_{i v}\right| \ll \frac{d_{v}}{q_{v}} \tag{23}
\end{equation*}
$$

By (19), (21), (22), and (23) we have

$$
\max _{i=1,2}\left\|\theta_{i} x_{v}-\eta_{i}\right\| \leq\left|x_{v}\right| \max _{i=1,2}\left|\theta_{i}-\theta_{i v}\right|+\max _{i=1,2}\left\|\theta_{i v} x_{v}-\eta_{i v}\right\|+\max _{i=1,2}\left|\eta_{i}-\eta_{i v}\right| \ll a_{v}+\frac{d_{v}}{q_{v}}+\frac{b_{v}}{a_{v}} \ll \frac{d_{v}}{q_{v}}
$$

In the last inequality we use (9). By (16) we have

$$
\max _{i=1,2}\left\|\theta_{i} x_{v}-\eta_{i}\right\| \leq \frac{\omega\left(q_{v}\right)}{q_{v}}
$$

for large $\nu$. As $\overline{\boldsymbol{\eta}} \in \pi$ and $\boldsymbol{y}_{\nu} \in \pi_{\nu}, \max _{i=1,2}\left\|\theta_{i} x_{\nu}-\eta_{i}\right\| \neq 0$ infinitely often (in fact for all large $\nu$ ).

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[^0]:    ${ }^{1}$ In fact, the approach from [Bengoechea et al. 2017] gives a little bit more. Instead of property that for any subspace $\mathcal{A}$ the intersection $E \cap \mathcal{A}$ is $\frac{1}{2}$-winning in $\mathcal{A}$, one can see that it is $\alpha$-winning for all $\alpha \in\left(0, \frac{1}{2}\right]$. It is not completely clear for the author if these two properties are equivalent. (For a closely related problem, see [Dremov 2002].)

[^1]:    ${ }^{2}$ A similar procedure was explained in [Moshchevitin 2012]. There, the author provides the linear independence of coordinates of the limit vector by "going away from all rational subspaces" (the beginning of the proof of Theorem 1 in the case $k=1$, p. 132 and the beginning of $\S 5$, p. 146).

