# TOPOLOGY OF POLAR WEIGHTED HOMOGENEOUS HYPERSURFACES 

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#### Abstract

Polar weighted homogeneous polynomials are special polynomials of real variables $x_{i}, y_{i}, i=1, \ldots, n$ with $z_{i}=x_{i}+\sqrt{-1} y_{i}$ which enjoy a "polar action". In many aspects, their behavior looks like that of complex weighted homogeneous polynomials. We study basic properties of hypersurfaces which are defined by polar weighted homogeneous polynomials.


## 1. Introduction

We consider a polynomial $f(\mathbf{z}, \overline{\mathbf{z}})=\sum_{v, \mu} c_{v / \mu} \mathbf{z}^{\nu} \overline{\mathbf{z}}^{\mu}$ where $\mathbf{z}=\left(z_{1}, \ldots, z_{n}\right), \overline{\mathbf{z}}=$ $\left(\bar{z}_{1}, \ldots, \bar{z}_{n}\right), \mathbf{z}^{v}=z_{1}^{v_{1}} \cdots z_{n}^{v_{n}}$ for $v=\left(v_{1}, \ldots, v_{n}\right)$ (respectively $\overline{\mathbf{z}}^{\mu}=\bar{z}_{1}^{\mu_{1}} \cdots \bar{z}_{n}^{\mu_{n}}$ for $\left.\mu=\left(\mu_{1}, \ldots, \mu_{n}\right)\right)$ as usual. Here $\bar{z}_{i}$ is the complex conjugate of $z_{i}$. Writing $z_{i}=x_{i}+\sqrt{-1} y_{i}$, it is easy to see that $f$ is a polynomial of $2 n$-variables $x_{1}, y_{1}, \ldots, x_{n}, y_{n}$. Thus $f$ can be understood as a real analytic function $f: \mathbf{C}^{n} \rightarrow \mathbf{C}$. We call $f$ a mixed polynomial of $z_{1}, \ldots, z_{n}$.

A mixed polynomial $f(\mathbf{z}, \overline{\mathbf{z}})$ is called polar weighted homogeneous if there exist integers $q_{1}, \ldots, q_{n}$ and $p_{1}, \ldots, p_{n}$ and positive integers $m_{r}, m_{p}$ such that

$$
\begin{aligned}
& \operatorname{gcd}\left(q_{1}, \ldots, q_{n}\right)=1, \quad \operatorname{gcd}\left(p_{1}, \ldots, p_{n}\right)=1, \\
& \sum_{j=1}^{n} q_{j}\left(v_{j}+\mu_{j}\right)=m_{r}, \quad \sum_{j=1}^{n} p_{j}\left(v_{j}-\mu_{j}\right)=m_{p}, \quad \text { if } c_{v, \mu} \neq 0
\end{aligned}
$$

We say $f(\mathbf{z}, \overline{\mathbf{z}})$ is a polar weighted homogeneous of radial weight type $\left(q_{1}, \ldots, q_{n} ; m_{r}\right)$ and of polar weight type $\left(p_{1}, \ldots, p_{n} ; m_{p}\right)$. We define vectors of rational numbers $\left(u_{1}, \ldots, u_{n}\right)$ and $\left(v_{1}, \ldots, v_{n}\right)$ by $u_{i}=q_{i} / m_{r}, v_{i}=p_{i} / m_{p}$ and we call them the normalized radial (respectively polar) weights. Using a polar coordinate $(r, \eta)$ of $\mathbf{C}^{*}$ where $r>0$ and $\eta \in S^{1}$ with $S^{1}=\{\eta \in \mathbf{C}| | \eta \mid=1\}$, we define a polar $\mathbf{C}^{*}$-action on $\mathbf{C}^{n}$ by

[^0]\[

$$
\begin{gathered}
(r, \eta) \circ \mathbf{z}=\left(r^{q_{1}} \eta^{p_{1}} z_{1}, \ldots, r^{q_{n}} \eta^{p_{n}} z_{n}\right), \quad(r, \eta) \in \mathbf{R}^{+} \times S^{1} \\
(r, \eta) \circ \overline{\mathbf{z}}=\overline{(r, \eta) \circ \mathbf{z}}=\left(r^{q_{1}} \eta^{-p_{1}} \bar{z}_{1}, \ldots, r^{q_{n}} \eta^{-p_{n}} \bar{z}_{n}\right) .
\end{gathered}
$$
\]

Then $f$ satisfies the functional equality

$$
\begin{equation*}
f((r, \eta) \circ(\mathbf{z}, \overline{\mathbf{z}}))=r^{m_{r}} \eta^{m_{p}} f(\mathbf{z}, \overline{\mathbf{z}}) . \tag{1}
\end{equation*}
$$

This notion was introduced by Ruas-Seade-Verjovsky [12] implicitly and then by Cisneros-Molina [2].

It is easy to see that such a polynomial defines a global fibration

$$
f: \mathbf{C}^{n}-f^{-1}(0) \rightarrow \mathbf{C}^{*}
$$

The purpose of this paper is to study the topology of the hypersurface $F=f^{-1}(1)$ for a given polar weighted homogeneous polynomial, which is a fiber of the above fibration. Note that $F$ has a canonical stratification

$$
F=\amalg_{I \subset\{1,2, \ldots, n\}} F^{* I}, \quad F^{* I}=F \cap \mathbf{C}^{* I}
$$

Our main result is Theorem 10, which describes the topology of $F^{* I}$ for a simplicial polar weighted polynomial.

## 2. Polar weighted homogeneous hypersurface

This section is the preparation for the later sections. Proposition 2 and Proposition 3 are added for consistency but they are essentially known from the series of works by J. Seade and coauthors [12, 13, 10, 11, 14].
2.1. Smoothness of a mixed hypersurface. Let $f(\mathbf{z}, \overline{\mathbf{z}})$ be a mixed polynomial and we consider a hypersurface $V=\left\{\mathbf{z} \in \mathbf{C}^{n} ; f(\mathbf{z}, \overline{\mathbf{z}})=0\right\}$. Put $z_{j}=x_{j}+i y_{j}$. Then $f(\mathbf{z}, \overline{\mathbf{z}})$ is a real analytic function of $2 n$ variables $(\mathbf{x}, \mathbf{y})$ with $\mathbf{x}=\left(x_{1}, \ldots, x_{n}\right)$ and $\mathbf{y}=\left(y_{1}, \ldots, y_{n}\right)$. Put $f(\mathbf{z}, \overline{\mathbf{z}})=g(\mathbf{x}, \mathbf{y})+i h(\mathbf{x}, \mathbf{y})$ where $g, h$ are real analytic functions. Recall that

$$
\frac{\partial}{\partial z_{j}}=\frac{1}{2}\left(\frac{\partial}{\partial x_{j}}-i \frac{\partial}{\partial y_{j}}\right), \quad \frac{\partial}{\partial \bar{z}_{j}}=\frac{1}{2}\left(\frac{\partial}{\partial x_{j}}+i \frac{\partial}{\partial y_{j}}\right)
$$

Thus

$$
\frac{\partial k}{\partial z_{j}}=\frac{1}{2}\left(\frac{\partial k}{\partial x_{j}}-i \frac{\partial k}{\partial y_{j}}\right), \quad \frac{\partial k}{\partial \bar{z}_{j}}=\frac{1}{2}\left(\frac{\partial k}{\partial x_{j}}+i \frac{\partial k}{\partial y_{j}}\right)
$$

for any analytic function $k(\mathbf{x}, \mathbf{y})$. Thus for a complex valued function $f$, we define

$$
\frac{\partial f}{\partial z_{j}}=\frac{\partial g}{\partial z_{j}}+i \frac{\partial h}{\partial z_{j}}, \quad \frac{\partial f}{\partial \bar{z}_{j}}=\frac{\partial g}{\partial \bar{z}_{j}}+i \frac{\partial g}{\partial \bar{z}_{j}}
$$

We assume that $g, h$ are non-constant polynomials. Then $V$ is a real codimension two subvariety. Put

$$
\begin{aligned}
& d_{\mathbf{R}} g(\mathbf{x}, \mathbf{y})=\left(\frac{\partial g}{\partial x_{1}}, \ldots, \frac{\partial g}{\partial x_{n}}, \frac{\partial g}{\partial y_{1}}, \ldots, \frac{\partial g}{\partial y_{n}}\right) \in \mathbf{R}^{2 n} \\
& d_{\mathbf{R}} h(\mathbf{x}, \mathbf{y})=\left(\frac{\partial h}{\partial x_{1}}, \ldots, \frac{\partial h}{\partial x_{n}}, \frac{\partial h}{\partial y_{1}}, \ldots, \frac{\partial h}{\partial y_{n}}\right) \in \mathbf{R}^{2 n}
\end{aligned}
$$

For a complex valued mixed polynomial, we use the notation:

$$
d f(\mathbf{z}, \overline{\mathbf{z}})=\left(\frac{\partial f}{\partial z_{1}}, \ldots, \frac{\partial f}{\partial z_{n}}\right) \in \mathbf{C}^{n}, \quad \bar{d} f(\mathbf{z}, \overline{\mathbf{z}})=\left(\frac{\partial f}{\partial \bar{z}_{1}}, \ldots, \frac{\partial f}{\partial \bar{z}_{n}}\right) \in \mathbf{C}^{n}
$$

Recall that a point $\mathbf{z} \in V$ is a singular point of $V$ if and only if the two vectors $d g(\mathbf{x}, \mathbf{y}), d h(\mathbf{x}, \mathbf{y})$ are linearly dependent over $\mathbf{R}$ (see Milnor [4]). This condition is not so easy to be checked, as the calculation of $g(\mathbf{x}, \mathbf{y}), h(\mathbf{x}, \mathbf{y})$ from a given $f(\mathbf{z}, \overline{\mathbf{z}})$ is not immediate. However we have

Proposition 1. The following two conditions are equivalent.
(1) $\mathbf{z} \in V$ is a singular point of $V$ and $\operatorname{dim}_{\mathbf{R}}(V, \mathbf{z})=2 n-2$.
(2) There exists a complex number $\alpha,|\alpha|=1$ such that $\overline{d f(\mathbf{z}, \overline{\mathbf{z}})}=\alpha \bar{d} f(\mathbf{z}, \overline{\mathbf{z}})$.

Proof. First assume that $d_{\mathbf{R}} g, d_{\mathbf{R}} h$ are linearly dependent at $\mathbf{z}$. Suppose for example that $d g(\mathbf{x}, \mathbf{y}) \neq 0$ and write $d h(\mathbf{x}, \mathbf{y})=t d g(\mathbf{x}, \mathbf{y})$ for some $t \in \mathbf{R}$. This implies that

$$
\begin{gathered}
\frac{\partial f}{\partial x_{j}}=(1+t i) \frac{\partial g}{\partial x_{j}}, \quad \frac{\partial f}{\partial y_{j}}=(1+t i) \frac{\partial g}{\partial y_{j}}, \quad \text { thus } \\
\frac{\partial f}{\partial z_{j}}=(1+t i)\left(\frac{\partial g}{\partial x_{j}}-i \frac{\partial g}{\partial y_{j}}\right), \quad \frac{\partial f}{\partial \bar{z}_{j}}=(1+t i)\left(\frac{\partial g}{\partial x_{j}}+i \frac{\partial g}{\partial y_{j}}\right) .
\end{gathered}
$$

Thus

$$
\begin{aligned}
& d f(\mathbf{z}, \overline{\mathbf{z}})=(1+t i)\left(\frac{\partial g}{\partial x_{1}}-i \frac{\partial g}{\partial y_{1}}, \ldots, \frac{\partial g}{\partial x_{n}}-i \frac{\partial g}{\partial y_{n}}\right)=2(1+t i) d_{\mathbf{z}} g(\mathbf{z}, \overline{\mathbf{z}}) \\
& \bar{d} f(\mathbf{z}, \overline{\mathbf{z}})=(1+t i)\left(\frac{\partial g}{\partial x_{1}}+i \frac{\partial g}{\partial y_{1}}, \ldots, \frac{\partial g}{\partial x_{n}}+i \frac{\partial g}{\partial y_{n}}\right)=2(1+t i) d_{\overline{\mathbf{z}}} g(\mathbf{z}, \overline{\mathbf{z}})
\end{aligned}
$$

Here $d_{\mathbf{z}} g=\left(\frac{\partial g}{\partial z_{1}}, \ldots, \frac{\partial g}{\partial z_{n}}\right)$ and $d_{\overline{\mathbf{z}}} g=\left(\frac{\partial g}{\partial \bar{z}_{1}}, \ldots, \frac{\partial g}{\partial \bar{z}_{n}}\right)$. As $g$ is a real valued polynomial, using the equality $\overline{d_{\mathbf{z}} g(\mathbf{x}, \mathbf{y})}=d_{\overline{\mathbf{z}}} g(\mathbf{x}, \mathbf{y})$ we get

$$
\overline{d f(\mathbf{z}, \overline{\mathbf{z}})}=\frac{1-t i}{1+t i} \bar{d} f(\mathbf{z}, \overline{\mathbf{z}})
$$

Thus it is enough to take $\alpha=\frac{1-t i}{\frac{1+t i}{d(z 2)}}$.
Conversely assume that $\overline{d f(\mathbf{z}, \overline{\mathbf{z}})}=\alpha \bar{d} f(\mathbf{z}, \overline{\mathbf{z}})$ for some $\alpha=a+b i$ with $a^{2}+b^{2}=1$. Using the notations

$$
d_{x} g=\left(\frac{\partial g}{\partial x_{1}}, \ldots, \frac{\partial g}{\partial x_{n}}\right), \quad d_{y} g=\left(\frac{\partial g}{\partial y_{1}}, \ldots, \frac{\partial g}{\partial y_{n}}\right), \text { etc, }
$$

we get

$$
\begin{aligned}
& (1-a) d_{x} g+b d_{y} g=-b d_{x} h-(1+a) d_{y} h \\
& -b d_{x} g+(1-a) d_{y} g=(a+1) d_{x} h-b d_{y} h .
\end{aligned}
$$

Solving these equations assuming $a \neq 1$, we get

$$
d_{\mathbf{R}} g=\left(d_{x} g, d_{y} g\right)=\frac{-2 b}{(1-a)^{2}+b^{2}} d_{\mathbf{R}} h
$$

which proves the assertion. If $a=1$, the above equations implies that $d h_{\mathbf{R}}=0$ and the linear dependence is obvious.
2.2. Polar weighted homogeneous hypersurfaces. Let $f$ be a polar weighted homogeneous polynomial of radial weight type $\left(q_{1}, \ldots, q_{n} ; m_{r}\right)$ and of polar weight type $\left(p_{1}, \ldots, p_{n} ; m_{p}\right)$. By differentiating (1) in $\S 1$, we get

$$
\begin{align*}
& m_{r} f(\mathbf{z}, \overline{\mathbf{z}})=\sum_{i=1}^{n} q_{i}\left(\frac{\partial f}{\partial z_{i}} z_{i}+\frac{\partial f}{\partial \bar{z}_{i}} \bar{z}_{i}\right)  \tag{2}\\
& m_{p} f(\mathbf{z}, \overline{\mathbf{z}})=\sum_{i=1}^{n} p_{i}\left(\frac{\partial f}{\partial z_{i}} z_{i}-\frac{\partial f}{\partial \bar{z}_{i}} \bar{z}_{i}\right) .
\end{align*}
$$

We call these equalities Euler equalities. Recall that $\mathbf{C}^{n}$ has the canonical hermitian inner product defined by

$$
(\mathbf{z}, \mathbf{w})=z_{1} \bar{w}_{1}+\cdots+z_{n} \bar{w}_{n} .
$$

Identifying $\mathbf{C}^{n}$ with $\mathbf{R}^{2 n}$ by $\mathbf{z} \leftrightarrow(\mathbf{x}, \mathbf{y})$, the Euclidean inner product of $\mathbf{R}^{2 n}$ is given as $(\mathbf{z}, \mathbf{w})_{\mathbf{R}}=\Re(\mathbf{z}, \mathbf{w})$. Or we can also write as

$$
(\mathbf{z}, \mathbf{w})_{\mathbf{R}}=\frac{1}{2}((\mathbf{z}, \mathbf{w})+(\overline{\mathbf{z}}, \overline{\mathbf{w}}))
$$

Proposition 2. For any $\alpha \neq 0$, the fiber $F_{\alpha}:=f^{-1}(\alpha)$ is a smooth $2(n-1)$ real-dimensional manifold and it is canonically diffeomorphic to $F_{1}=f^{-1}(1)$.

Proof. Take a point $\mathbf{z} \in F_{\alpha}$. We consider two particular vectors $\mathbf{v}_{r}, \mathbf{v}_{\theta} \in T_{\mathbf{z}} \mathbf{C}^{n}$ which are the tangent vectors of the respective orbits of $\mathbf{R}$ and $S^{1}$ :

$$
\begin{aligned}
& \mathbf{v}_{r}=\left.\frac{d(r \circ \mathbf{z})}{d r}\right|_{r=1}=\left(q_{1} z_{1}, \ldots, q_{n} z_{n}\right), \\
& \mathbf{v}_{\theta}=\left.\frac{d\left(e^{i \theta} \circ \mathbf{z}\right)}{d \theta}\right|_{\theta=0}=\left(i p_{1} z_{1}, \ldots, i p_{n} z_{n}\right) .
\end{aligned}
$$

Taking the differential of the equality

$$
f((r, \exp (i \theta)) \circ \mathbf{z}))=r^{m_{r}} \exp \left(m_{p} \theta i\right) f(\mathbf{z}, \overline{\mathbf{z}}),
$$

we see that $d f_{z}: T_{\mathbf{z}} \mathbf{C}^{n} \rightarrow T_{\alpha} \mathbf{C}^{*}$ satisfies

$$
d f_{z}\left(\mathbf{v}_{r}\right)=m_{r}|\alpha| \frac{\partial}{\partial r}, \quad d f_{z}\left(\mathbf{v}_{\theta}\right)=m_{p} \frac{\partial}{\partial \theta}
$$

where $(r, \theta)$ is the polar coordinate of $\mathbf{C}^{*}$. This implies that $f: \mathbf{C}^{n} \rightarrow \mathbf{C}$ is a submersion at $\mathbf{z}$. Thus $F_{\alpha}$ is a smooth codimension 2 submanifold. A diffeomorphism $\varphi_{\alpha}: F_{1} \rightarrow F_{\alpha}$ is simply given as $\varphi(\mathbf{z})=\left(r^{1 / m_{r}}, \exp ^{i \theta / m_{p}}\right) \circ \mathbf{z}$ where $\alpha=r \exp (i \theta)$.

The above proof does not work for $\alpha=0$. Recall that the polar $\mathbf{R}^{+}$-action along the radial direction is written in real coordinates as

$$
r \circ(\mathbf{x}, \mathbf{y})=\left(r^{q_{1}} x_{1}, \ldots, r^{q_{n}} x_{n}, r^{q_{1}} y_{1}, \ldots, r^{q_{n}} y_{n}\right), \quad r \in \mathbf{R}^{+} .
$$

Proposition 3. Let $V=f^{-1}(0)$. Assume that $q_{j}>0$ for any $j$. Then $V$ is contractible to the origin $O$. If further $O$ is an isolated singularity of $V, V \backslash\{O\}$ is smooth.

Proof. A canonical deformation retract $\beta_{t}: V \rightarrow V$ is given as $\beta_{t}(\mathbf{z})=t \circ \mathbf{z}$, $0 \leq t \leq 1$. (More precisely $\beta_{0}(\mathbf{z})=\lim _{t \rightarrow 0} \beta_{t}(\mathbf{z})$.) Then $\beta_{1}=\operatorname{id}_{V}$ and $\beta_{0}$ is the contraction to $O$. Assume that $\mathbf{z} \in V \backslash\{O\}$ is a singular point. Consider the decomposition into real analytic functions $f(z)=g(\mathbf{x}, \mathbf{y})+i h(\mathbf{x}, \mathbf{y})$. Using the radial $\mathbf{R}^{+}$-action, we see that

$$
\begin{equation*}
g(r \circ(\mathbf{x}, \mathbf{y}))=r^{m_{r}} g(\mathbf{x}, \mathbf{y}), \quad h(r \circ(\mathbf{x}, \mathbf{y}))=r^{m_{r}} h(\mathbf{x}, \mathbf{y}) . \tag{4}
\end{equation*}
$$

This implies that $g(\mathbf{x}, \mathbf{y}), h(\mathbf{x}, \mathbf{y})$ are weighted homogeneous polynomials of $(\mathbf{x}, \mathbf{y})$ and the Euler equality can be restated as

$$
\begin{aligned}
& m_{r} g(\mathbf{x}, \mathbf{y})=\sum_{j=1}^{n} p_{j}\left(x_{j} \frac{\partial g}{\partial x_{j}}(\mathbf{x}, \mathbf{y})+y_{j} \frac{\partial g}{\partial y_{j}}(\mathbf{x}, \mathbf{y})\right) \\
& m_{r} h(\mathbf{x}, \mathbf{y})=\sum_{j=1}^{n} p_{j}\left(x_{j} \frac{\partial h}{\partial x_{j}}(\mathbf{x}, \mathbf{y})+y_{j} \frac{\partial h}{\partial y_{j}}(\mathbf{x}, \mathbf{y})\right) .
\end{aligned}
$$

Differentiating the equalities (4) in $r$, we get

$$
\frac{\partial g}{\partial x_{j}}(r \circ(\mathbf{x}, \mathbf{y}))=r^{m_{r}-q_{j}} \frac{\partial g}{\partial x_{j}}(\mathbf{x}, \mathbf{y}), \quad \frac{\partial h}{\partial x_{j}}(r \circ(\mathbf{x}, \mathbf{y}))=r^{m_{r}-q_{j}} \frac{\partial h}{\partial x_{j}}(\mathbf{x}, \mathbf{y}) .
$$

This implies that these differentials are also weighted homogeneous polynomials of degree $m_{r}-q_{j}$. Thus the jacobian matrix

$$
\left(\frac{\partial(g, h)}{\partial\left(x_{i}, y_{i}\right)}(r \circ(\mathbf{x}, \mathbf{y}))\right)
$$

is the same with the jacobian matrix at $\mathbf{z}=(\mathbf{x}, \mathbf{y})$ up to scalar multiplications in the column vectors by $r^{m_{r}-q_{1}}, \ldots, r^{m_{r}-q_{n}}, r^{m_{r}-q_{1}}, \ldots, r^{m_{r}-q_{n}}$ respectively. Thus any points of the orbit $r \circ(\mathbf{x}, \mathbf{y}), r>0$ are singular points of $V$. This is a contradiction to the assumption that $O$ is an isolated singular point of $V$, as $\lim _{r \rightarrow 0} r \circ(\mathbf{x}, \mathbf{y})=O$.

Proposition 4. (Transversality) Under the same assumption as in Proposition 3, the sphere $S_{\tau}=\left\{\mathbf{z} \in \mathbf{C}^{n} ;|\mathbf{z}|=\tau\right\}$ intersects transversely with $V$ for any $\tau>0$.

Proof. Let $\phi(\mathbf{x}, \mathbf{y})=\|\mathbf{z}\|^{2}=\sum_{j=1}^{n}\left(x_{j}^{2}+y_{j}^{2}\right)$. Then $S_{\tau}$ intersects transversely with $V$ if and only if the gradient vectors $d_{\mathbf{R}} g, d_{\mathbf{R}} h, d_{\mathbf{R}} \phi$ are linearly independent over R. Note that $d_{\mathbf{R}} \phi(\mathbf{x}, \mathbf{y})=2(\mathbf{x}, \mathbf{y})$. Suppose that the sphere $S_{\|\mathbf{z}\|}$ is tangent to $V$ at $\mathbf{z}=(\mathbf{x}, \mathbf{y}) \in V$. Then we have for example, a linear relation $d g(\mathbf{x}, \mathbf{y})=$ $\alpha d h(\mathbf{x}, \mathbf{y})+\beta d \phi(\mathbf{x}, \mathbf{y})$ with some $\alpha, \beta \in \mathbf{R}$. Note that the tangent vector $\mathbf{v}_{r}$ to the $\mathbf{R}^{+}$-oribit is tangent to $V$ and it is written $\mathbf{v}_{r}=\left(q_{1} x_{1}, \ldots, q_{n} x_{n}, q_{1} y_{1}, \ldots, q_{n} y_{n}\right)$ as a real vector. Then we have

$$
\begin{aligned}
0= & \left.\frac{d g(r \circ(\mathbf{x}, \mathbf{y})}{d r}\right|_{r=1}
\end{aligned}=\sum_{j=1}^{n} q_{j}\left(x_{j} \frac{\partial g}{\partial x_{j}}(\mathbf{x}, \mathbf{y})+y_{j} \frac{\partial g}{\partial y_{j}}(\mathbf{x}, \mathbf{y})\right) .
$$

as $\left(\mathbf{v}_{r}(\mathbf{x}, \mathbf{y}), d h(\mathbf{x}, \mathbf{y})\right)_{\mathbf{R}}=0$ by the same reason. This is the case only if $\beta=0$ which is impossible as $V \backslash\{O\}$ is non-singular by Proposition 3 .
2.2.1. Remark. Let $f(\mathbf{z}, \overline{\mathbf{z}})$ be a polar weighted homogeneous polynomial with respective weights $\left(q_{1}, \ldots, q_{n} ; m_{r}\right)$ and $\left(p_{1}, \ldots, p_{n} ; m_{p}\right)$. Proposition 3 does not hold if the radial weights contain some negative $q_{j}$. Assume that $q_{j} \geq 0$ for any $j$ and $I_{0}:=\left\{j \mid q_{j}=0\right\}$ is not empty. Then it is easy to see that $f$ does not have monomial which does not contain any $z_{i}$ with $i \notin I_{0}$, as if such monomial exists, its radial degree is 0 . This implies that $V=f^{-1}(0)$ contains the coordinate subspace $\mathbf{C}^{I_{0}}=\left\{\mathbf{z} \mid z_{i}=0, i \notin I_{0}\right\}$. We call $\mathbf{C}^{I_{0}}$ the canonical retract coordinate subspace. Then Proposition 3 can be modified as $\mathbf{C}^{I_{0}}$ is a deformation retract of $V$. Of course, $\mathbf{C}^{I_{0}}$ can be contracted to $O$ but this contraction is not through the action and not related to the geometry of $V$.
2.2.2. Example. Consider the following examples.

$$
g_{1}(\mathbf{z}, \overline{\mathbf{z}})=z_{1}^{a_{1}} \bar{z}_{2}+\cdots+z_{n}^{a_{n}} \bar{z}_{1}, \quad a_{i} \geq 1, j=1, \ldots, n
$$

and there exists $j$ such that $a_{j} \geq 2$

$$
g_{2}(\mathbf{z}, \overline{\mathbf{z}})=z_{1}^{a_{1}} \bar{z}_{2}+\cdots+z_{n-1}^{a_{n-1}} \bar{z}_{n}+z_{n}^{a_{n}}, \quad a_{j} \geq 1, j=1, \ldots, n
$$

Proposition 5. (1) The radial weight vector $\left(q_{1}, \ldots, q_{n}\right)$ of $g_{1}(\mathbf{z}, \overline{\mathbf{z}})$ is semipositive, i.e. $q_{j} \geq 0$ for any $j$ if $a_{i} \geq 1$ for any $i$. ( $\exists j, a_{j} \geq 2$ by the existence of polar action.) It is not strictly positive if and only if $n=2 m$ is even and either (a) $a_{1}=a_{3}=\cdots=a_{2 m-1}=1$ or (b) $a_{2}=a_{4}=\cdots=$ $a_{2 m}=1$.

In case (a) (respectively (b)), we have $q_{2}=q_{4}=\cdots=q_{2 m}=0$ and $q_{2 j+1} \geq 1,0 \leq j \leq m-1$ (resp. $q_{1}=q_{3}=\cdots=q_{2 m-1}=0$ and $q_{2 j} \geq 1$, $1 \leq j \leq m)$.
(2) The radial weight vector $\left(q_{1}, \ldots, q_{n}\right)$ of $g_{2}(\mathbf{z}, \overline{\mathbf{z}})$ is semi-positive. It is not strictly positive if and only if $a_{n}=1$. Let $s$ be the integer such that $a_{n}=a_{n-2}=\cdots=a_{n-2 s}=1$ and $a_{n-2 s-2} \geq 2$. Then $q_{n-1}=\cdots=$ $q_{n-2 s+1}=0$ and $q_{j} \geq 1$ otherwise.

Proof. We first consider $g_{1}(\mathbf{z}, \overline{\mathbf{z}})=z_{1}^{a_{1}} \bar{z}_{2}+\cdots+z_{n}^{a_{n}} \bar{z}_{1}$. By an easy calculation, using the notation $a_{i+n}=a_{i}$ the normalized radial weigts ( $u_{1}, \ldots, u_{n}$ ) are given as

$$
\begin{gathered}
u_{j}=\frac{1}{a_{1} \cdots a_{n}-1} \sum_{i=0}^{m-1}\left(a_{j+2 i+1}-1\right) a_{j+2 i+2} \cdots a_{j+n-1}, \quad \text { if } n=2 m \\
u_{j}=\frac{1}{a_{1} \cdots a_{n}+1}\left(1+\sum_{i=0}^{m-1}\left(a_{j+2 i+1}-1\right) a_{j+2 i+2} \cdots a_{j+n-1}\right), \quad \text { if } n=2 m+1
\end{gathered}
$$

and the assertion follows immediately from this expression.
Next we consider $g_{2}(\mathbf{z}, \overline{\mathbf{z}})=z_{1}^{a_{1}} \bar{z}_{2}+\cdots+z_{n}^{a_{n-1}} \bar{z}_{n}+z_{n}^{a_{n}}$. Then the normalized radial weigts $\left(u_{1}, \ldots, u_{n}\right)$ are given as

$$
\begin{aligned}
u_{j} & =\frac{1}{a_{j}}-\frac{1}{a_{j} a_{j+1}}+\cdots+(-1)^{n-j} \frac{1}{a_{j} a_{j+1} \cdots a_{n}} \\
& =\left\{\begin{array}{l}
\frac{a_{j+1}-1}{a_{j} a_{j+1}}+\cdots+\frac{a_{n}-1}{a_{j} a_{j+1} \cdots a_{n}}, \quad n-j: \text { odd } \\
\frac{a_{j+1}-1}{a_{j} a_{j+1}}+\cdots+\frac{a_{n-1}-1}{a_{j} a_{j+1} \cdots a_{n-1}}+\frac{1}{a_{j} a_{j+1} \cdots a_{n}}
\end{array} \quad n-j:\right. \text { even }
\end{aligned}
$$

As $a_{i} \geq 1$, the assertion follows from the above expression.
2.3. Simplicial mixed polynomial. Let $f(\mathbf{z}, \overline{\mathbf{z}})=\sum_{j=1}^{s} c_{j} \mathbf{z}^{\mathbf{n}_{\overline{\mathbf{z}}} \mathbf{m}_{j}}$ be a mixed polynomial. Here we assume that $c_{1}, \ldots, c_{s} \neq 0$. Put

$$
\hat{f}(\mathbf{w}):=\sum_{j=1}^{s} c_{j} \mathbf{w}^{\mathbf{n}_{j}-\mathbf{m}_{j}} .
$$

We call $\hat{f}$ the the associated Laurent polynomial. This polynomial plays an important role for the determination of the topology of the hypersurface $F=f^{-1}(1)$. Note that

Proposition 6. If $f(\mathbf{z}, \overline{\mathbf{z}})$ is a polar weighted homogeneous polynomial of polar weight type $\left(p_{1}, \ldots, p_{n} ; m_{p}\right), \hat{f}(\mathbf{w})$ is also a weighted homogeneous Laurent polynomial of type $\left(p_{1}, \ldots, p_{n} ; m_{p}\right)$ in the complex variables $w_{1}, \ldots, w_{n}$.

A mixed polynomial $f(\mathbf{z}, \overline{\mathbf{z}})$ is called simplicial if the exponent vectors $\left\{\mathbf{n}_{j} \pm \mathbf{m}_{j} \mid j=1, \ldots, s\right\}$ are linearly independent in $\mathbf{Z}^{n}$ respectively. In particular, simplicity implies that $s \leq n$. When $s=n$, we say that $f$ is full. Put $\mathbf{n}_{j}=$ $\left(n_{j, 1}, \ldots, n_{j, n}\right), \mathbf{m}_{j}=\left(m_{j, 1}, \ldots, m_{j, n}\right)$ in $\mathbf{N}^{n}$. Assume that $s \leq n$. Consider two integral matrix $N=\left(n_{i, j}\right)$ and $M=\left(m_{i, j}\right)$ where the $k$-th row vectors are $\mathbf{n}_{k}, \mathbf{m}_{k}$ respectively.

Lemma 7. Let $f(\mathbf{z}, \overline{\mathbf{z}})$ be a mixed polynomial as above. If $f(\mathbf{z}, \overline{\mathbf{z}})$ is simplicial, then $f(\mathbf{z}, \overline{\mathbf{z}})$ is a polar weighted homogeneous polynomial. In the case $s=n$, $f(\mathbf{z}, \overline{\mathbf{z}})$ is simplicial if and only if $\operatorname{det}(N \pm M) \neq 0$.

Proof. First we assume that $s=n$ and consider the system of linear equations

$$
\begin{align*}
& \left\{\begin{array}{c}
\left(n_{1,1}+m_{1,1}\right) u_{1}+\cdots+\left(n_{1, n}+m_{1, n}\right) u_{n}=1 \\
\cdots \\
\left(n_{n, 1}+m_{n, 1}\right) u_{1}+\cdots+\left(n_{n, n}+m_{n, n}\right) u_{n}=1
\end{array}\right.  \tag{5}\\
& \left\{\begin{array}{l}
\left(n_{1,1}-m_{1,1}\right) v_{1}+\cdots+\left(n_{1, n}-m_{1, n}\right) v_{n}=1 \\
\cdots \\
\left(n_{n, 1}-m_{n, 1}\right) v_{1}+\cdots+\left(n_{n, n}-m_{n, n}\right) v_{n}=1
\end{array}\right. \tag{6}
\end{align*}
$$

It is easy to see that equations (5) and (6) have solutions if $\operatorname{det} N \pm M \neq 0$ which is equivalent for $f$ to be simplicial by definition. Note that the solutions $\left(u_{1}, \ldots, u_{n}\right)$ and $\left(v_{1}, \ldots, v_{n}\right)$ are rational numbers. We call them the normalized radial (respectively polar) weights. Now let $m_{r}, m_{p}$ be the least common multiple of the denominators of $u_{1}, \ldots, u_{n}$ and $v_{1}, \ldots, v_{n}$ respectively. Then the weights are given as $q_{j}=u_{j} m_{r}, p_{j}=v_{j} m_{p}, j=1, \ldots, n$ respectively.

Now suppose that $s<n$. It is easy to choose positive integral vectors $\mathbf{n}_{j}$, $j=s+1, \ldots, n_{\tilde{M}}$ (and put $\left.\mathbf{m}_{j}=0, j=s+1, \ldots, n\right)$ such that $\operatorname{det}(\tilde{N} \pm \tilde{M}) \neq 0$, where $\tilde{N}$ and $\tilde{M}$ are $n \times n$-matrices adding $(n-s)$ row vectors $\mathbf{n}_{s+1}, \ldots, \mathbf{n}_{n}$. Then the assertion follows from the case $s=n$.

This corresponds to considering the mixed polynomial:

$$
f(\mathbf{z}, \overline{\mathbf{z}})=\sum_{j=1}^{s} c_{j} \mathbf{z}^{\mathbf{n}_{j} \overline{\mathbf{z}}_{j}^{\mathbf{m}_{j}}}+0 \times \sum_{j=s+1}^{n} \mathbf{z}^{\mathbf{n}_{j}} .
$$

2.3.1. Example. Let

$$
\begin{gathered}
f_{\mathbf{a}, \mathbf{b}}(\mathbf{z}, \overline{\mathbf{z}})=z_{1}^{a_{1}} \bar{z}_{2}^{b_{1}}+\cdots+z_{n}^{a_{n}} \bar{z}_{1}^{b_{n}}, \quad a_{i}, b_{i} \geq 1, i=1, \ldots, n \\
k(\mathbf{z}, \overline{\mathbf{z}})=z_{1}^{d}\left(\bar{z}_{1}+\bar{z}_{2}\right)+\cdots+z_{n}^{d}\left(\bar{z}_{n}+\bar{z}_{1}\right), \quad d \geq 2 .
\end{gathered}
$$

The associated Laurent polynomials are

$$
\begin{gathered}
\widehat{f_{\mathbf{a}, \mathbf{b}}}(\mathbf{w})=w_{1}^{a_{1}} w_{2}^{-b_{1}}+\cdots+w_{n}^{a_{n}} w_{1}^{-b_{n}} \\
\hat{k}(\mathbf{w})=w_{1}^{d}\left(1 / w_{1}+1 / w_{2}\right)+\cdots+w_{n}^{d}\left(1 / w_{n}+1 / w_{1}\right) .
\end{gathered}
$$

Corollary 8. For the polynomial $f_{\mathbf{a}, \mathbf{b}}$, the following conditions are equivalent.
(1) $f_{\mathbf{a}, \mathbf{b}}$ is simplicial.
(2) $f_{\mathbf{a}, \mathbf{b}}$ is a polar weighted homogeneous polynomial.
(3) (SC) $a_{1} \cdots a_{n} \neq b_{1} \cdots b_{n}$.

Proof. The assertion follows from the equality:

$$
\begin{aligned}
\operatorname{det}(\mathbf{n} \pm \mathbf{m}) & =\operatorname{det}\left(\begin{array}{cccc}
a_{1} & 0 & \cdots & \pm b_{n} \\
\pm b_{1} & a_{2} & \cdots & 0 \\
\vdots & \ddots & \ddots & \vdots \\
0 & \cdots & \pm b_{n-1} & a_{n}
\end{array}\right) \\
& =\left\{\begin{array}{l}
a_{1} a_{2} \cdots a_{n}+(-1)^{n-1} b_{1} b_{2} \cdots b_{n} \text { for } \mathbf{n}+\mathbf{m} \\
a_{1} a_{2} \cdots a_{n}-b_{1} b_{2} \cdots b_{n} \text { for } \mathbf{n}-\mathbf{m} .
\end{array}\right.
\end{aligned}
$$

The polynomial $k(\mathbf{z}, \overline{\mathbf{z}})$ is a polar weighted homogeneous polynomial with respective weight types $(1, \ldots, 1 ; d+1)$ and $(1, \ldots, 1 ; d-1)$. However it is not simplicial.

Now we consider an example which does not satisfy the simplicial condition (SC) of Corollary 8: $\phi_{a}:=z_{1}^{a} z_{1}^{a}+\cdots+z_{n}^{a} \bar{z}_{n}^{a}$. This does not have any polar action as they are polynomials of $\left|z_{1}\right|^{2}, \ldots,\left|z_{n}\right|^{2}$ and it takes only non-negative values. Note also that $\phi_{a}^{-1}(1)$ is real codimension 1 as $\phi_{a}(\mathbf{x}, \mathbf{y})=\sum_{j=1}^{n}\left(x_{j}^{2}+y^{2}\right)^{a}$.

As typical simplicial polar weighted polynomials, we consider again the following two polar weighted polynomials.

$$
\begin{gathered}
g_{1}(\mathbf{z}, \overline{\mathbf{z}})=z_{1}^{a_{1}} \bar{z}_{2}+\cdots+z_{n}^{a_{n}} \bar{z}_{1}, \quad a_{i} \geq 1, j=1, \ldots, n \\
\text { and there exists } j \text { such that } a_{j} \geq 2 \\
g_{2}(\mathbf{z}, \overline{\mathbf{z}})=z_{1}^{a_{1}} \bar{z}_{2}+\cdots+z_{n-1}^{a_{n-1}} \bar{z}_{n}+z_{n}^{a_{n}}, \quad a_{i} \geq 1, j=1, \ldots, n .
\end{gathered}
$$

The polynomial $g_{1}(\mathbf{z}, \overline{\mathbf{z}})$ with $a_{i} \geq 2,(i=1, \ldots, n)$ is a special case of $\sigma$-twisted Brieskorn polynomial and has been studied intensively ([12]). In our case, we only assume $a_{i} \geq 2$ for some $i$. The existence of $i$ with $a_{i} \geq 2$ is the condition for the existence of polar action. We consider the two hypersurfaces defined by $V_{i}=g_{i}^{-1}(0)$ for $i=1,2$. The condition for a hypersurface defined by a polar weighted homogeneous polynomial to have an isolated singularity is more complicated than that of the singularity defined by a complex anaytic hypersurface. For the above examples, we assert the following.

Proposition 9. For $V_{1}, V_{2}$, we have the following criterion.
(1) $V_{i} \cap \mathbf{C}^{* n}, i=1,2$ are non-singular.
(2) $V_{1}=g_{1}^{-1}(0)$ has no singularity outside of the origin if and only if one of the following conditions is satisfied.
(a) $n$ is odd.
(b) $n$ is even and there are (at least) two indices $i, j(i<j)$ such that $a_{i}, a_{j} \geq 2$ and $j-i$ is odd.
(3) $V_{2}=g_{2}^{-1}(0)$ has no singularity outside of the origin if and only if one of the following conditions is satisfied.
(a) $a_{n} \geq 2$.
(b) $a_{n}=1, n=2 m+1$ is odd and $a_{2 j-1}=1$ for any $1 \leq j \leq m+1$.

Proof. We use Proposition 1. So assume that

$$
(\#): \quad \overline{d f(\mathbf{z}, \overline{\mathbf{z}})}=\alpha \bar{d} f(\mathbf{z}, \overline{\mathbf{z}}), \quad|\alpha|=1
$$

(1) We consider $V_{1}$. Suppose $\mathbf{z} \in V_{1} \cap \mathbf{C}^{* n}$ is a singular point. Note that

$$
d f(\mathbf{z}, \overline{\mathbf{z}})=\left(a_{1} z_{1}^{a_{1}-1} \bar{z}_{2}, \ldots, a_{n} z_{n}^{a_{n}-1} \bar{z}_{1}\right), \quad \bar{d} f(\mathbf{z}, \overline{\mathbf{z}})=\left(z_{n}^{a_{n}}, z_{1}^{a_{1}}, \ldots, z_{n-1}^{a_{n-1}}\right)
$$

(\#) implies that

$$
\begin{equation*}
a_{j} z_{j}^{a_{j}-1} z_{j+1}=\alpha z_{j-1}^{a_{j-1}}, \quad j=1, \ldots, n,|\alpha|=1 . \tag{7}
\end{equation*}
$$

In this case, indices should be understood to be integers modulo $n$. So $z_{n+1}=z_{1}$, and so on. If $\mathbf{z} \in \mathbf{C}^{* n}$, the multiplication of the absolute values of the both sides gives a contradiction: $\prod_{i=1}^{n} a_{i}\left|z_{i}\right|^{a_{i}}=\prod_{i=1}^{n}\left|z_{i}\right|^{a_{i}}$.

Now we consider the smoothness on $V_{1} \backslash\{O\}$. Assume that $\mathbf{z}$ is a singular point of $V_{1} \backslash\{O\}$. For simplicity, we may assume that $a_{n} \geq 2$ as $g_{1}$ is symmetric with the permutation $i \rightarrow i+1$.

Assume that $z_{l} \neq 0$. Then the $(l+1)$-th component of $\bar{d} f(\mathbf{z}, \overline{\mathbf{z}})$ is nonzero. Thus by (\#), ( $l+1$ )-th component of $d f(\mathbf{z}, \overline{\mathbf{z}})$ is also non-zero. That is, $z_{l+1}^{a_{l}-1} \bar{z}_{l+2} \neq 0$. In particular, $z_{l+2} \neq 0$. We repeat the same argument and get a sequence of non-zero components $z_{l}, z_{l+2}, \ldots$. Thus we arrive to the conclusion that either $z_{n-1} \neq 0$ (if $n-\imath$ is odd) or $z_{n} \neq 0$ (if $n-\imath$ is even).

- If $n-l$ is odd and $z_{n-1} \neq 0$, the last component of $d f(\mathbf{z}, \overline{\mathbf{z}})$ is non-zero and we have $z_{n}, z_{1} \neq 0$ as we have assumed that $a_{n} \geq 2$. This creates two nonzero sequences $z_{n}, z_{2}, z_{4}, \ldots$ and $z_{1}, z_{3}, \ldots$. Thus we conclude that $\mathbf{z} \in \mathbf{C}^{* n}$, which is impossible by the first argument.
- If $n-\imath$ is even, $z_{l}, z_{l+2}, \ldots, z_{n} \neq 0$. Thus we see that the first component of $\bar{d} f(\mathbf{z}, \overline{\mathbf{z}})$ is non-zero. By the same argument, we get a non-zero sequence $z_{2}, z_{4}, \ldots$.

Thus to show that $\mathbf{z} \in \mathbf{C}^{* n}$, it is enough to show that $z_{n-1} \neq 0$.
(a) Assume first $n$ is odd. If $l$ is even, then we see that $z_{l}, z_{l+2}, \ldots, z_{n-1} \neq 0$ and we are done.

If $l$ is odd, we get $z_{n} \neq 0$, which implies the first component of $\bar{d} f(\mathbf{z}, \overline{\mathbf{z}})$ is non-zero. Thus as the second round, we have non-zero a sequence $z_{2}, z_{4}, \ldots$ which contains $z_{n-1}$. Thus we are done.
(b) Now we assume that $n$ is even but there is another integer $1 \leq i<n$ such that $a_{i} \geq 2$ and $a_{n} \geq 2$ and $i$ is odd. If $l$ is odd, we have shown that $\mathbf{z} \in \mathbf{C}^{* n}$.

If $l$ is even, we get $z_{n} \neq 0$ and thus $z_{2} \neq 0$. Then the sequence $z_{2}, z_{4}, \ldots$ contains $z_{i-1}$. As $a_{i} \geq 2$, looking at the $i$-th component of $d f(\mathbf{z}, \overline{\mathbf{z}})$, we get $z_{i} \cdot z_{i+1} \neq 0$. Thus we get a non-zero sequence $z_{i}, z_{i+2}, \ldots$ which contains $z_{n-1}$, and we are done.

Now to show that one of the conditions (a) or (b) is necessary, we assume that $n$ is even and $a_{v}=1$ for any odd $v$ and $a_{n} \geq 2$. Thus putting $n=2 m$,

$$
f=\left(z_{1} \bar{z}_{2}+z_{2}^{a_{2}} \bar{z}_{3}\right)+\cdots+\left(z_{2 m-1} \bar{z}_{2 m}+z_{2 m}^{a_{2 m}} \bar{z}_{1}\right)
$$

Consider the subvariety $z_{1}=z_{3}=\cdots=z_{n-1}=0$. Then

$$
d f(\mathbf{z}, \overline{\mathbf{z}})=\left(\bar{z}_{2}, 0, \bar{z}_{4}, 0, \ldots, \bar{z}_{2 m}, 0\right), \quad \bar{d} f(\mathbf{z}, \overline{\mathbf{z}})=\left(z_{n}^{a_{n}}, 0, \ldots, z_{2 m-2}^{a_{2 m-2}}, 0\right)
$$

the condition (\#) is written as

$$
\text { (\#) } \quad z_{2}=\alpha z_{n}^{a_{n}}, \quad z_{4}=\alpha z_{2}^{a_{2}}, \ldots, z_{2 m}=\alpha z_{2 m-2}^{a_{2 m-2}}
$$

which has real one-dimensional solution

$$
\begin{gathered}
z_{2 j}=\alpha^{\beta_{j}} u^{\gamma_{j}} \quad(j=1, \ldots, m), \quad \alpha^{\beta_{m}} u^{\gamma_{m} a_{2 m}-1}=1 \\
\beta_{j}=1+\sum_{i=1}^{j-1} a_{2(j-1)} a_{2(j-2)} \cdots a_{2(j-i)}, \quad \gamma_{j}=a_{2} a_{4} \cdots a_{2(j-1)}
\end{gathered}
$$

(2) We consider the case $V_{2}$. We will see first $V_{2} \cap \mathbf{C}^{* n}$ is non-singular. Take a singular point of $V_{2}$. Then we have some $\alpha \in S^{1}$ so that

$$
(\#): \quad \overline{d f}(\mathbf{z}, \overline{\mathbf{z}})=\alpha \bar{d} f(\mathbf{z}, \overline{\mathbf{z}})
$$

As we have

$$
\begin{aligned}
& d f(\mathbf{z}, \overline{\mathbf{z}})=\left(a_{1} z_{1}^{a_{1}-1} \bar{z}_{2}, \ldots, a_{n-1} z_{n-1}^{a_{n-1}-1} \bar{z}_{n}, a_{n} z_{n}^{a_{n}-1}\right) \\
& \bar{d} f(\mathbf{z}, \overline{\mathbf{z}})=\left(0, z_{1}^{a_{1}}, \ldots, z_{n-1}^{a_{n-1}}\right)
\end{aligned}
$$

we see that (\#) implies that $z_{1}^{a_{1}-1} \bar{z}_{2}=0$. Thus there are no singularities on $V_{2} \cap \mathbf{C}^{* n}$. Suppose that $z_{l} \neq 0$ for some $l$. If $l<n-1$, this implies $(l+1)$-th component of $\bar{d} f(\mathbf{z}, \overline{\mathbf{z}})$ is non-zero. Thus (\#) implies that $(l+1)$-th component of $d f$ is non-zero. In particular, $z_{l+2}$ is non-zero. (Of course, $z_{l+1} \neq 0$ if $a_{t+1}>1$.) Repeating this argument, we arrive to the conclusion: either $z_{n-1}$ or $z_{n}$ is non zero.

First assume that $a_{n} \geq 2$. Comparing the last components of $d f(\mathbf{z}, \overline{\mathbf{z}})$ and $\bar{d} f(\mathbf{z}, \overline{\mathbf{z}})$, we observe that $z_{n-1}$ and $z_{n}$ are both non-zero. Now we go in the reverse direction. As the $(n-1)$-th component of $d f(\mathbf{z}, \overline{\mathbf{z}})$ is non-zero, the corresponding $(n-1)$-th component $z_{n-2}^{a_{n-2}}$ of $\bar{d} f(\mathbf{z}, \overline{\mathbf{z}})$ is non-zero. Then the $(n-2)$-th component of $d f(\mathbf{z}, \overline{\mathbf{z}})$ is non-zero. Going downwords, we see that $z \in \mathbf{C}^{* n}$. However this is impossible, as we have already seen above.

Next we assume that $a_{n}=1$ and $n$ is odd and $a_{2 j-1}=1$ for any $j$. Note that the last component of $d f(\mathbf{z}, \overline{\mathbf{z}})$ is 1 . Thus $z_{n-1} \neq 0$. If $z_{n} \neq 0$, we get a
contradiction as above $\mathbf{z} \in \mathbf{C}^{* n}$. Thus we may assume that $z_{n}=0$. Comparing (2j)-components of $d f(\mathbf{z}, \overline{\mathbf{z}})$ and $\alpha \bar{d} f(\mathbf{z}, \overline{\mathbf{z}})$, we get

$$
z_{2}=0, \quad z_{4}=\alpha z_{2}^{a_{2}}, \ldots, z_{n-1}=z_{n-3}^{a_{n-3}}
$$

which has no solution with $z_{n-1} \neq 0$.
Now we show that the condition (a) or (b) in (3) is necessary.
(i) Assume that $a_{n}=1$ and $n$ is even ans put $n=2 m$. Let $s$ be the maximal integer such that $a_{2 s} \geq 2$. If there does not exists such $s$, we put $s=0$. Nonisolated singularities are given by the solutions of

$$
\begin{gathered}
z_{2}=z_{4}=\cdots=z_{2 m}=0, \quad z_{2 j-1}=0, j \leq s \\
z_{2 s+3}=\alpha z_{2 s+1}^{a_{2 s+1}}, \ldots, z_{2 m-1}=\alpha z_{2 m-3}^{a_{2 m-3}}, \quad 1=\alpha z_{2 m-1}^{a_{2 m-1}} .
\end{gathered}
$$

(ii) Assume that $a_{n}=1, n=2 m+1$ is odd, and there exists odd index such that $a_{2 j+1} \geq 2$. Put $s$ be the maximum integer of such $j$. Non-isolated singularities are given by the solutions of

$$
\begin{gathered}
z_{1}=z_{3}=\cdots=z_{2 m+1}=0, \quad z_{2 j}=0, j \leq s \\
z_{2 s+4}=\alpha z_{2 s+2}^{a_{2 s}}, \ldots, z_{2 m}=\alpha z_{2 m-2}^{a_{2 m}}, \quad 1=\alpha z_{2 m}^{a_{2 m}} .
\end{gathered}
$$

2.3.2. Remark. 1. The polynomial $g_{1}(\mathbf{z}, \overline{\mathbf{z}})=z_{1}^{a_{1}} \bar{z}_{2}+\cdots+z_{n}^{a_{n}} \bar{z}_{1}$ is an example of so-called $\sigma$-twisted Brieskorn polynomial if $a_{i} \geq 2, i=1, \ldots, n$. Let $\sigma$ be a permutation of $\{1,2, \ldots, n\}$. Then $\sigma$-twisted Brieskorn polynomial is defined as

$$
f_{\sigma}(\mathbf{z}, \overline{\mathbf{z}})=z_{1}^{a_{1}} \bar{z}_{\sigma(1)}+\cdots+z_{n}^{a_{n}} \bar{z}_{\sigma(n)}, \quad a_{1}, \ldots, a_{n} \geq 2
$$

and the corresponding assertions in Proposition 3 and 4 are proved in [13]. See also [14] for more systematical treatment for real analytic polynomials which define Milnor fibrations. In [3], similar conditions for the isolatedness condition as Proposition 9 are considered. For our purpose, we call $f_{\sigma}(\mathbf{z}, \overline{\mathbf{z}})$ a weak $\sigma$ twisted Brieskorn polynomial if $\sigma \in \mathscr{S}_{n}$ and $a_{i} \geq 1$ for any $i=1, \ldots, n$.
2. Consider a product $\mathbf{C}^{n}=\mathbf{C}^{s} \times \mathbf{C}^{n-s}$ and use variables $\mathbf{v} \in \mathbf{C}^{s}$ and $\mathbf{w} \in \mathbf{C}^{n-s}$. Assume that there exist mixed polynomials $h(\mathbf{v}, \overline{\mathbf{v}})$ and $k(\mathbf{w}, \overline{\mathbf{w}})$ so that $f(\mathbf{z}, \overline{\mathbf{z}})=h(\mathbf{v}, \overline{\mathbf{v}})+k(\mathbf{w}, \overline{\mathbf{w}}) . \quad f(\mathbf{z}, \overline{\mathbf{z}})$ is a polar weighted polynomial if and only if $h(\mathbf{v}, \overline{\mathbf{v}}), k(\mathbf{w}, \overline{\mathbf{w}})$ are polar weighted polynomial and it is known that $f^{-1}(1)$ is homotopic to the join $h^{-1}(1) \star k^{-1}(1)$ if $f$ is polar weighted. Such a polynomial is called a polynomial of join type ([2], see also [6]).

Now consider a weak $\sigma$-twisted Brieskorn polynomial $f_{\sigma}(\mathbf{z}, \overline{\mathbf{z}})$. If $\sigma$ has order $n$, it is (up to a change of ordering) equal to the cyclic permutation $\sigma=(1,2, \ldots, n)$ and $f_{\sigma}=g_{1}$. In general, $\sigma$ can be written as a product of mutually commuting cyclic permutations $\sigma=\tau_{1} \tau_{2} \cdots \tau_{v}$. Put $\left|\tau_{i}\right|=\left\{j \mid \tau_{i}(j) \neq j\right\}$ and put $f_{\tau_{i}}$ be the partial sum of monomials in $f(\mathbf{z}, \overline{\mathbf{z}})$ written in variables $\left\{z_{j}|j \in| \tau_{i} \mid\right\}$. Thus $f_{\sigma}$ is a join type polynomial of $v$ weak $\tau_{i}$-twisted Brieskorn polynomial $f_{\tau_{i}}$. Thus $f_{\sigma}(\mathbf{z}, \overline{\mathbf{z}})$ has an isolated singularity if and only if each polynomial $f_{\tau_{i}}$ has an isolated singularity. A similar assertion is also proved in [3].
3. Observe that the singularities of $V_{1}, V_{2}$ are on the canonical retract coordinate subspaces $\mathbf{C}^{I_{0}}$. Note also that the polar action is trivial on $\mathbf{C}^{I_{0}}$.
2.4. Milnor fibration. Let $f(\mathbf{z}, \overline{\mathbf{z}})$ be a polar weighted homogeneous polynomial of radial weight type $\left(q_{1}, \ldots, q_{n} ; m_{r}\right)$ and of polar weight type $\left(p_{1}, \ldots, p_{n} ; m_{p}\right)$. Then

$$
f: \mathbf{C}^{n}-f^{-1}(0) \rightarrow \mathbf{C}^{*}
$$

is a locally trivial fibration. The local triviality is given by the action. In particular, the monodromy map $h: F \rightarrow F$ is given by $h(\mathbf{z})=\exp \left(2 \pi i / m_{p}\right) \circ \mathbf{z}=$ $\left(z_{1} \exp \left(2 p_{1} \pi i / m_{p}\right), \ldots, z_{n} \exp \left(2 p_{n} \pi i / m_{p}\right)\right)$ where $F=f^{-1}(1)([12,2])$.

## 3. Topology of simplicial polar weighted homogeneous hypersurfaces

Let $f(\mathbf{z}, \overline{\mathbf{z}})=\sum_{j=1}^{s} c_{j} \mathbf{z}^{\mathbf{n}_{j}} \mathbf{m}^{\mathbf{m}_{j}}$ be a polar weighted homogeneous polynomial of radial weight type $\left(q_{1}, \ldots, q_{n} ; m_{r}\right)$ and of polar weight type $\left(p_{1}, \ldots, p_{n} ; m_{p}\right)$. Let $F=f^{-1}(1)$ be the fiber.
3.1. Canonical stratification of $F$ and the topology of each stratum. For any subset $I \subset\{1,2, \ldots, n\}$, we define

$$
\mathbf{C}^{I}=\left\{\mathbf{z} \mid z_{j}=0, j \notin I\right\}, \quad \mathbf{C}^{* I}=\left\{\mathbf{z} \mid z_{i} \neq 0 \text { iff } i \in I\right\}, \quad \mathbf{C}^{* n}=\mathbf{C}^{*\{1, \ldots, n\}}
$$

and we define mixed polynomials $f^{I}$ by the restriction: $f^{I}=\left.f\right|_{\mathbf{C}^{I}}$. For simplicity, we write a point of $\mathbf{C}^{I}$ as $\mathbf{z}_{I}$. Put $F^{* I}=\mathbf{C}^{* I} \cap F$. Note that $F^{* I}$ is a non-empty subset of $\mathbf{C}^{* I}$ if and only if $f^{I}\left(\mathbf{z}_{I}, \overline{\mathbf{z}}_{I}\right)$ is not constantly zero. Now we observe that the hypersurface $F=f^{-1}(1)$ has the canonical stratification

$$
F=\amalg_{I} F^{* I} .
$$

Thus it is essential to determine the topology of each stratum $F^{* I}$. Put $F^{*}:=F \cap \mathbf{C}^{* n}$, the open dense stratum and put $\hat{F}^{*}:=\hat{f}^{-1}(1) \cap \mathbf{C}^{* n}$ where $\hat{f}(\mathbf{w})$ is the associated Laurent weighted homogeneous polynomial.

Theorem 10. Assume that $f(\mathbf{z}, \overline{\mathbf{z}})$ is a simplicial polar weighted homogeneous polynomial and let $\hat{f}(\mathbf{w})$ be the associated Laurent weighted homogeneous polynomial. Then there exists a canonical diffeomorphism $\varphi: \mathbf{C}^{* n} \rightarrow \mathbf{C}^{* n}$ which gives an isomorphism of the two Milnor fibrations defined by $f(\mathbf{z}, \overline{\mathbf{z}})$ and $\hat{f}(\mathbf{w})$ :

and it satisfies $\varphi\left(F^{* n}\right)=\hat{F}^{* n}$ and $\varphi$ is compatible with the respective canonical monodromy maps.

Proof. Assume first that $s=n$ for simplicity. Recall that

$$
\hat{f}(\mathbf{w})=\sum_{j=1}^{n} c_{j} \mathbf{w}^{\mathbf{n}_{j}-\mathbf{m}_{j}} .
$$

Let $\mathbf{w}=\left(w_{1}, \ldots, w_{n}\right)$ be the complex coordinates of $\mathbf{C}^{n}$ which is the ambient space of $\hat{F}$. We construct $\varphi: \mathbf{C}^{* n} \rightarrow \mathbf{C}^{* n}$ so that $\varphi(\mathbf{z})=\mathbf{w}$ satisfies

$$
\mathbf{w}(\varphi(\mathbf{z}))^{\mathbf{n}_{j}-\mathbf{m}_{j}}=\mathbf{z}^{\mathbf{n}_{j} \overline{\mathbf{z}}^{\mathbf{m}_{j}}}, \quad \text { thus } \hat{f}(\varphi(\mathbf{z}))=f(\mathbf{z}) .
$$

For the construction of $\varphi$, we use the polar coordinates $\left(\rho_{j}, \theta_{j}\right)$ for $z_{j} \in \mathbf{C}^{*}$ and the polar coordinates $\left(\xi_{j}, \eta_{j}\right)$ for $\mathbf{w}_{j}$. Thus $\mathbf{z}_{j}=\rho_{j} \exp \left(i \theta_{j}\right)$ and $\mathbf{w}_{j}=\xi_{j} \exp \left(i \eta_{j}\right)$. First we take $\eta_{j}=\theta_{j}$. Put $\mathbf{n}_{j}=\left(n_{j, 1}, \ldots, n_{j, n}\right), \mathbf{m}_{j}=\left(m_{j, 1}, \ldots, m_{j, n}\right)$ in $\mathbf{N}^{n}$. Consider two integral matrix $N=\left(n_{i, j}\right)$ and $M=\left(m_{i, j}\right)$ where the $k$-th row vector are $\mathbf{n}_{k}, \mathbf{m}_{k}$ respectively. Now taking the logarithm of the equality $\mathbf{z}^{\mathbf{n}_{j} \overline{\mathbf{z}}^{\mathbf{m}_{j}}}=\mathbf{w}^{\mathbf{n}_{j}-\mathbf{m}_{j}}$, we get an equivalent equality:

$$
\begin{aligned}
& \left(n_{j 1}+m_{j 1}\right) \log \rho_{1}+\cdots+\left(n_{j n}+m_{j n}\right) \log \rho_{n} \\
& \quad=\left(n_{j 1}-m_{j 1}\right) \log \xi_{1}+\cdots+\left(n_{j n}-m_{j n}\right) \log \xi_{n}, \quad j=1, \ldots, n .
\end{aligned}
$$

This can be written as

$$
(N+M)\left(\begin{array}{c}
\log \rho_{1}  \tag{8}\\
\vdots \\
\log \rho_{n}
\end{array}\right)=(N-M)\left(\begin{array}{c}
\log \xi_{1} \\
\vdots \\
\log \xi_{n}
\end{array}\right)
$$

Put $(N-M)^{-1}(N+M)=\left(\lambda_{i j}\right) \in \operatorname{GL}(n, \mathbf{Q})$. Now we define $\varphi$ as follows.

$$
\begin{aligned}
\varphi: \mathbf{C}^{* n} & \rightarrow \mathbf{C}^{* n}, \quad \mathbf{z}=\left(\rho_{1} \exp \left(i \theta_{1}\right), \ldots, \rho_{n} \exp \left(i \theta_{n}\right)\right) \\
& \mapsto \mathbf{w}=\left(\xi_{1} \exp \left(i \theta_{1}\right), \ldots, \xi_{n} \exp \left(i \theta_{n}\right)\right)
\end{aligned}
$$

where $\xi_{j}$ is given by $\xi_{j}=\exp \left(\sum_{i=1}^{n} \lambda_{j i} \log \rho_{i}\right)$ for $j=1, \ldots, n$. It is obvious that $\varphi$ is a real analytic isomorphism of $\mathbf{C}^{* n}$ to $\mathbf{C}^{* n}$. Let us consider the Milnor fibrations of $f(\mathbf{z}, \overline{\mathbf{z}})$ and $\hat{f}(\mathbf{w})$ in the respective ambient tori $\mathbf{C}^{* n}$.

$$
f: \mathbf{C}^{* n} \backslash f^{-1}(0) \rightarrow \mathbf{C}^{*}, \quad \hat{f}: \mathbf{C}^{* n} \backslash \hat{f}^{-1}(0) \rightarrow \mathbf{C}^{*}
$$

Recall that the monodromy maps $h^{*}, \hat{h}^{*}$ are given as

$$
\begin{aligned}
h^{*}: F^{*} \rightarrow F^{*}, & \mathbf{z} & \mapsto \exp \left(2 \pi i / m_{p}\right) \circ \mathbf{z} \\
\hat{h}^{*}: \hat{F}^{*} \rightarrow \hat{F}^{*}, & \mathbf{w} & \mapsto \exp \left(2 \pi i / m_{p}\right) \circ \mathbf{w} .
\end{aligned}
$$

Note that the $\mathbf{C}^{*}$-action associated with $\hat{f}(\mathbf{w})$ is the polar action of $f(\mathbf{z}, \overline{\mathbf{z}})$. Namely $\exp i \theta \circ \mathbf{w}=\left(\exp \left(i p_{1} \theta\right) w_{1}, \ldots, \exp \left(i p_{n} \theta\right) w_{n}\right)$. Thus we have the commutative diagram:

where $F_{\alpha}^{*}=f^{-1}(\alpha) \cap \mathbf{C}^{* n}$ and $\hat{F}_{\alpha}^{*}=\hat{f}^{-1}(\alpha) \cap \mathbf{C}^{* n}$ for $\alpha \in \mathbf{C}^{*}$.

### 3.1.1. Remark. The case $f(\mathbf{z}, \overline{\mathbf{z}})=z_{1}^{a_{1}} \bar{z}_{1}+\cdots+z_{n}^{a_{n}} \bar{z}_{n}$ is studied in [12].

3.2. Zeta-functions. Now we know that by [7, 8], the inclusion map $\hat{F}^{*} \hookrightarrow \mathbf{C}^{* n}$ is $(s-1)$-equivalence and $\chi\left(\hat{F}^{*}\right)=(-1)^{n-1} \operatorname{det}(N-M)$ for $s=n$ and 0 otherwise. Note also the monodromy map $\hat{h}: \hat{F}^{*} \rightarrow \hat{F}^{*}$ has a period $m_{p}$. The fixed point locus of $(\hat{h})^{k}$ is $F^{*}$ if $m_{p} \mid k$ and $\emptyset$ otherwise. Thus using the formula of the zeta function (see, for example [4]),

$$
\zeta_{\hat{h}^{*}}(t)=\exp \left(\sum_{j=0}^{\infty}(-1)^{n-1} d t^{j m_{p}} /\left(j m_{p}\right)\right)=\left(1-t^{m_{p}}\right)^{(-1)^{n} d / m_{p}}
$$

where $d=\operatorname{det}(N-M)$ if $s=n$ and $d=0$ for $s<n$. Translating this in the monodromy $h^{*}: F^{*} \rightarrow F^{*}$, we obtain

Corollary 11. $F^{*}$ has a homotopy type of CW-complex of dimension $n-1$ and the inclusion map $F^{*} \hookrightarrow \mathbf{C}^{* n}$ is an $(s-1)$-equivalence. The zeta function $\zeta_{h^{*}}(t)$ of $h^{*}: F^{*} \rightarrow F^{*}$ is given as $\left(1-t^{m_{p}}\right)^{(-1)^{n} d / m_{p}}$ with $d=\operatorname{det}(N-M)$ if $s=n$ and $\zeta_{h^{*}}(t)=1$ for $s<n$.
3.2.1. Remark. In general, the restriction of the polar action on $\mathbf{C}^{n}$ to $\mathbf{C}^{* I}$ may not effective and to make the action effective, we need to define polar weights as $p_{I, i}=p_{i} / r_{I}$ and $m_{I, P}=m_{p} / r_{I}$ where $r_{I}$ is the gratest common divisor of $\left\{p_{i} \mid i \in I\right\}$. However the monodromy map $h_{I}: F^{* I} \rightarrow F^{* I}$ is equal to the restriction of $h: F \rightarrow F$.

## 4. Connectivity of $F$

Now we are ready to patch together the information of the strata $F^{* I}$ for the topology of $F$. First we introduce the notion of $k$-convenience which is introduced for holomorphic functions ([8]). We say $f(\mathbf{z}, \overline{\mathbf{z}})$ is $k$-convenient if $f^{I} \nsupseteq 0$ for any $I \subset\{1,2, \ldots, n\}$ with $|I| \geq n-k$. The following is obvious by the definition.

Proposition 12. Assume that $f(\mathbf{z}, \overline{\mathbf{z}})$ is a simplicial polar weighted homogeneous polynomial with $s$ monomials and assume that $f$ is $k$-convenient. Then $k \leq s-1$.

Now we have the following result about the connectivity of $F$.

Theorem 13. Assume that $f(\mathbf{z}, \overline{\mathbf{z}})$ is a simplicial polar weighted homogeneous polynomial with $s$ monomials and assume that $f$ is $k$-convenient. Then $F$ is $\min (k, n-2)$-connected.

For the proof, we show the following stronger assertion. Let $I \subset\{1,2, \ldots, n\}$ and put

$$
\begin{gathered}
\mathbf{C}^{n}(* I)=\left\{\mathbf{z}=\left(z_{1}, \ldots, z_{n}\right) \in \mathbf{C}^{n} \mid z_{j} \neq 0, j \in I\right\}, \quad F(* I)=F \cap \mathbf{C}^{n}(* I) . \\
\mathbf{C}^{* I}=\left\{\mathbf{z} \in \mathbf{C}^{n} \mid z_{j} \neq 0 \text { iff } j \in I\right\}, \quad F^{* I}=F \cap \mathbf{C}^{* I} .
\end{gathered}
$$

Lemma 14. Under the assumption as in Theorem 13, the inclusion $F(* I) \hookrightarrow \mathbf{C}^{n}(* I)$ is $\min (k+1, n-1)$-equivalence.

We prove the assertion by double induction on $(n, k)$. Put

$$
\begin{aligned}
I_{j} & =\{j, \ldots, n\}, \quad K_{j}=\{1, \ldots, \stackrel{\vee}{j}, \ldots, n\} \\
\mathbf{C}_{j}^{n-1} & =\mathbf{C}^{K_{j}}=\mathbf{C}^{n} \cap\left\{z_{j}=0\right\}, \quad F_{j}=F \cap \mathbf{C}_{j}^{n-1} .
\end{aligned}
$$

Note that $F_{j}$ is the Milnor fiber of $f^{K_{j}}$. Theorem 13 follows from Lemma 14 by taking $I=\emptyset$. Changing the ordering if necessary, we may assume that $I=I_{t}$ for some $t$. We consider the filtration of $F$ :

$$
F^{*}=F\left(* I_{1}\right) \subset F\left(* I_{2}\right) \subset F\left(* I_{3}\right) \subset \cdots \subset F\left(* I_{n}\right) \subset F=F(* \emptyset) .
$$

A key lemma is
Lemma 15. The inclusion map $\left(F\left(* I_{j}\right), F\left(* I_{j-1}\right)\right) \hookrightarrow\left(\mathbf{C}^{n}\left(* I_{j}\right), \mathbf{C}^{n}\left(* I_{j-1}\right)\right)$ is $\min (k+1, n-1)$-equivalence.

Proof. Let $T_{j}$ be a tubular neighborhood of $\left\{z_{j}=0\right\}$ in $\mathbf{C}^{n}\left(* I_{j+1}\right)$ such that $T_{j} \cap F\left(* I_{j+1}\right)$ is a tubular neighborhood of $F_{j}\left(* I_{j+1}\right)=\left\{z_{j}=0\right\} \cap F\left(* I_{j+1}\right)$ in $F\left(* I_{j+1}\right)$. Consider the following diagrams by the excision isomorphisms and by the Thom isomorphisms $\psi$ for $D^{2}$-bundle:


Now note that $f^{K_{j}}$ is $(k-1)$-convenient. Thus by the induction assumption on Lemma 15, $\tau_{j}^{\prime \prime}$ is isomorphism for $\ell-1 \leq k-1$. This implies that $\tau_{j}^{\prime}, \tau_{j}$ is isomorphism for $\ell+1 \leq k+1$.

Proof of Lemma 14. Now we can prove Lemma 14 by the induction on $j$ and Five Lemma, assuming $I=I_{j}$ for some $j$, applied to two exact sequences for the pairs $\left(F\left(* I_{j+1}\right), F\left(* I_{j}\right)\right)$ and $\left(\mathbf{C}^{n}\left(* I_{j+1}\right), F\left(* I_{j}\right)\right)$ and commutative diagrams:


Induction starts for $j=1$ : $\quad l_{1}$ is $\min (k+1, n-1)$-equivalence by Corollary 11 . This completes the proof of Lemma 14.
 polar weighted homogeneous. Let

$$
\mathscr{S}=\left\{I \subset\{1, \ldots, n\} ; f^{I} \text { is full }\right\}
$$

and put $r_{I}=\operatorname{gcd}_{i \in I}\left\{p_{i}\right\}$ and $m_{p, I}=m_{p} / r_{I}$ and put $d_{I}=\left|\operatorname{det}_{i \in I}\left(\mathbf{n}_{i}-\mathbf{m}_{i}\right)\right|$. Thus for $I \in \mathscr{S}, f^{I}$ is a simplicial full polar weighted homogeneous polynomial of polar weight type $\left(p_{i} / r_{I}\right)_{i \in I}$ with degree $m_{p, I}$. We observed in Remark 3.2.1 that the monodromy map $h^{* I}: F^{* I} \rightarrow F^{* I}$ is equal to the restriction of the monodromy map $h: F \rightarrow F$. We denote the zeta function of the monodromy map

$$
h: F \rightarrow F, \quad h^{* I}=\left.h\right|_{F^{* I}}: F^{* I} \rightarrow F^{* I}
$$

by $\zeta(t), \zeta^{* I}(t)$ respectively. Recall that $\zeta(t)$ is an alternating product of characteristic polynomials ([4]). Namely

$$
\zeta(t)=\prod_{j=0}^{n-1} P_{j}(t)^{(-1)^{j+1}}
$$

where $P_{j}$ is the characteristic polynomial of the monodromy action on $h_{*}: H_{j}(F, \mathbf{Q}) \rightarrow H_{j}(F, \mathbf{Q})$. By Theorem 10 and the additive formula for the Euler characteristics, using a similar argument as that of Proposition 2.8, [8], we have:

Theorem 16. (1) $\chi(F)=\sum_{I \in \mathscr{S}}(-1)^{|I|-1} d_{I}$.
(2) $\zeta(t)=\prod_{I \in \mathscr{G}} \zeta^{* I}(t), \zeta^{* I}(t)=\left(1-t^{m_{p, I}}\right)^{(-1)^{I I}} d_{I} / m_{p, I}$.
4.2. Examples. 1. Assume that $f_{1}(\mathbf{z})$ is a homogeneous polynomial defined by

$$
f_{1}(\mathbf{z})=z_{1}^{a_{1}}+z_{2}^{a_{2}}+\cdots+z_{n}^{a_{n}}, \quad a_{1}, \ldots, a_{n} \geq 2
$$

Then $F=f_{1}^{-1}(1)$ is $(n-2)$-connected and

$$
\chi(F)=\sum_{j=1}^{n} \sum_{|I|=j} \chi\left(F^{* I}\right)=\left(a_{1}-1\right)\left(a_{2}-1\right) \cdots\left(a_{n}-1\right)-(-1)^{n}
$$

and

$$
\operatorname{div}\left(\zeta_{h}\right)=\left(\Lambda_{a_{1}}-1\right) \cdots\left(\Lambda_{a_{n}}-1\right)-(-1)^{n}
$$

as is well-known by $[9,1,5]$. Here $\operatorname{div}\left(\left(t-\lambda_{1}\right) \cdots\left(t-\lambda_{k}\right)\right)=\sum_{i=1}^{k} \lambda_{i} \in \mathbf{Z} \cdot \mathbf{C}^{*}$ and $\Lambda_{m}=\operatorname{div}\left(t^{m}-1\right)$.
2. Consider

$$
f_{2}(\mathbf{z}, \overline{\mathbf{z}})=z_{1}^{a_{1}} \bar{z}_{2}+\cdots+z_{n-1}^{a_{n-1}} \bar{z}_{n}+z_{n}^{a_{n}}
$$

Then $f_{2}$ is a simplicial polar weighted polynomial and put

$$
\mathscr{S}=\left\{I_{j}=\{1, \ldots, j\} \mid j=0, \ldots, n-1\right\} .
$$

Thus we have

$$
\begin{gathered}
\chi(F)=(-1)^{n-1}\left(a_{1} a_{2} \cdots a_{n}-a_{2} \cdots a_{n}+\cdots+(-1)^{n-1} a_{n}\right) \\
\log \zeta(t)=(-1)^{n}\left(\frac{1}{\left(1-t^{a_{1} \cdots a_{n}}\right)}-\frac{1}{\left(1-t^{a_{2} \cdots a_{n}}\right)}+\cdots+(-1)^{n-1} \frac{1}{\left(1-t^{a_{n}}\right)}\right)
\end{gathered}
$$

Proof. The polar weight of $f_{2}$ is given by $\left(p_{1}, \ldots, p_{n} ; m_{p}\right)$ where

$$
\begin{gathered}
m_{p}=a_{1} \cdots a_{n}, \quad p_{1}=m_{p}\left(\frac{1}{a_{1}}+\cdots+\frac{1}{a_{1} \cdots a_{n}}\right), \\
p_{2}=m_{p}\left(\frac{1}{a_{2}}+\cdots+\frac{1}{a_{2} \cdots a_{n}}\right) \\
\vdots \\
p_{n-1}=m_{p}\left(\frac{1}{a_{n-1}}+\frac{1}{a_{n-1} a_{n}}\right), \quad p_{n}=\frac{m_{p}}{a_{n}}
\end{gathered}
$$

Thus the assertion follows from Corollary 11.
4.3. Surface cases. Consider the case $n=3$. We consider two simplicial polar weighted homogeneous polynomials.

$$
\begin{gathered}
f_{1}(\mathbf{z}, \overline{\mathbf{z}})=z_{1}^{a_{1}} \bar{z}_{2}^{b_{1}}+z_{2}^{a_{2}} z_{3}^{b_{2}}+z_{3}^{a_{3}}, \quad a_{1}, a_{2}, b_{1}, b_{2}>0 \\
f_{2}(\mathbf{z}, \overline{\mathbf{z}})=z_{1}^{a_{1}} z_{2}^{b_{1}}+z_{2}^{a_{2}} z_{3}^{b_{2}}+z_{3}^{a_{3}} \bar{z}_{1}^{b_{3}}, \quad a_{1} a_{2} a_{3}>b_{1} b_{2} b_{3}>0 .
\end{gathered}
$$

They are 1-convenient. Let $F_{1}=f_{1}^{-1}(1)$ and $F_{2}=f_{2}^{-1}(1)$. By Theorem 13, $F_{1}$, $F_{2}$ are simply connected. Their Betti numbers $b_{2}\left(F_{i}\right)$ are given as

$$
b_{2}\left(F_{1}\right)=a_{1} a_{2} a_{3}-a_{2} a_{3}+a_{3}-1, \quad b_{2}\left(F_{2}\right)=a_{1} a_{2} a_{3}-b_{1} b_{2} b_{3}-1
$$

(I) First we consider $f_{1}$. The normalized polar weight for $f_{1}$ is given as

$$
v_{1}=\frac{b_{1} b_{2}}{a_{1} a_{2} a_{3}}+\frac{b_{1}}{a_{1} a_{2}}+\frac{1}{a_{1}}, \quad v_{2}=\frac{b_{2}}{a_{2} a_{3}}+\frac{1}{a_{2}}, \quad v_{3}=\frac{1}{a_{3}}
$$

Let $r=\operatorname{gcd}\left(b_{1} b_{2}, a_{1} a_{2} a_{3}\right), r_{1}=\operatorname{gcd}\left(b_{2}, a_{2} a_{3}\right)$. Then $m_{p}$ is given as $a_{1} a_{2} a_{3} / r$ and the zeta function of $h_{1}: F_{1} \rightarrow F_{1}$ is given as

$$
\zeta_{h_{1}}(t)=P_{0}(t)^{-1} P_{2}(t)^{-1}=\frac{\left(1-t^{a_{2} a_{3} / r_{1}}\right)^{r_{1}}}{\left(1-t^{a_{1} a_{2} a_{3} / r}\right)^{r}\left(1-t^{a_{3}}\right)}
$$

where $P_{2}(t)$ is the characteristic polynomial of the monodromy action $h_{1 *}: H_{2}\left(F_{1} ; \mathbf{Q}\right) \rightarrow H_{2}\left(F_{1} ; \mathbf{Q}\right)$. Note that $P_{0}(t)=1-t$. For example,

$$
\begin{gathered}
\zeta_{h_{1}}(t)=\frac{\left(1-t^{a_{2} a_{3}}\right)}{\left(1-t^{a_{1} a_{2} a_{3}}\right)\left(1-t^{a_{3}}\right)}, \quad b_{1}=b_{2}=1 \\
\zeta_{h_{1}}(t)=\frac{\left(1-t^{a_{2}^{\prime} a_{3}}\right)^{2}}{\left(1-t^{a_{1}^{\prime} a_{2}^{\prime} a_{3}}\right)^{4}\left(1-t^{a_{3}}\right)}, \quad a_{1}=2 a_{1}^{\prime}, \quad a_{2}=2 a_{2}^{\prime}, b_{1}=b_{2}=2 .
\end{gathered}
$$

(II) We consider $f_{2}$. The normalized polar weight for $f_{2}$ is given as:

$$
v_{1}=\frac{a_{2} a_{3}+b_{1} a_{3}+b_{1} b_{2}}{a_{1} a_{2} a_{3}-b_{1} b_{2} b_{3}}, \quad v_{2}=\frac{a_{1} a_{3}+a_{1} b_{2}+b_{2} b_{3}}{a_{1} a_{2} a_{3}-b_{1} b_{2} b_{3}}, \quad v_{3}=\frac{a_{1} a_{2}+a_{2} b_{3}+b_{1} b_{3}}{a_{1} a_{2} a_{3}-b_{1} b_{2} b_{3}} .
$$

Put $d=a_{1} a_{2} a_{3}-b_{1} b_{2} b_{3}$. The least common multiple $m_{p}$ of the denominators of $v_{1}, v_{2}, v_{3}$ depends on $\operatorname{gcd}\left(d, a_{2} a_{3}+b_{1} a_{3}+b_{1} b_{2}\right)$ and so on. We only gives two examples.
(1) Assume that $a_{1}=a_{2}=a_{3}=a, b_{1}=b_{2}=b_{3}=b$. Then $v_{1}=v_{2}=v_{3}=$ $\frac{1}{a-b}$. Thus

$$
\zeta_{h_{2}}(t)=\left(1-t^{a-b}\right)^{a^{2}+a b+b^{2}} .
$$

(2) Assume that $\operatorname{gcd}\left(d, a_{2} a_{3}+b_{1} a_{3}+b_{1} b_{2}\right)=\operatorname{gcd}\left(d, a_{1} a_{3}+a_{1} b_{2}+b_{2} b_{3}\right)=$ $\operatorname{gcd}\left(d, a_{1} a_{2}+a_{2} b_{3}+b_{1} b_{3}\right)=1$. Then $m_{p}=d$ and $\zeta_{h_{2}}(t)=\left(1-t^{d}\right)$.

For example, if $a_{1}=2, a_{2}=3, a_{3}=5$ and $b_{1}=b_{2}=b_{3}=1$, we get $\zeta_{h_{2}}(t)=$ $\left(1-t^{29}\right)$.

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