# FABER'S POLYNOMIALS, II. 

By Shohei NAGURA.
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## § 3. Coefficient Problem

3.1. Preliminary remarks. In the previous part ${ }^{(7)}$ we have discussed fundamental identities on Faber's polynomials and their applications to distortion theorems. In the present section we shall deal with the coefficient problem for the family of schlicht functions (2), especially the estimations of its second and third coefficients.

In the formula (14), if we put, instead of $Z, \varepsilon Z$ with an arbitrary $\varepsilon$ such as $|\varepsilon|=1$, it becomes

$$
\text { (20) } \quad I_{\xi} \frac{\bar{\varepsilon} f(\varepsilon Z)}{2}=\sum_{v=1}^{\infty} \frac{P_{v}(0) \varepsilon^{v}}{v} z^{v},\left(\bar{\varepsilon}=\frac{1}{\varepsilon}\right)
$$

Therefore, so far as we are concerned with the estimation of absolute value of each coefficient, it may be supposed that the real part of the respective coefficient is real and non-negative.

On the other hand, differentiating (14) with respect to $Z$, we easily obtain

$$
\begin{aligned}
&(21) \quad(n-1) a_{n}=\sum_{v=1}^{n-1} a_{v} P_{n-v}(0) \\
&(n=2, \equiv \cdots) .
\end{aligned}
$$

3.2. Parameter representation by means of Löwner's differential equation. Let
(22)

$$
\begin{aligned}
& h(z, t)=e^{-\left(t_{0}-t\right)}\left(z+\sum_{v=2}^{\infty} c_{v-1}(t) z^{v}\right), \\
& f(z, t)=e^{-t}\left(z+\sum_{v=2}^{\infty} b_{v-1}(t) z^{v}\right)
\end{aligned}
$$

be functions defined by Prof. Y.Komatu ${ }^{(8)}$ for slit mapping functions of Lönner's theory.

Lönner ${ }^{(9)}$ derived the differential equation for $h(z, t)$ such that

$$
\frac{\partial h(z, t)}{\partial t}=z \frac{\partial h(z, t)}{\partial z} \frac{1+k(t) z}{1-K(t) z}
$$

where $\bar{K}(t)=e^{-i \theta(t)} \quad(|k(t)|=1)$ is the starting point of the slit, the boundary condition being $h\left(z, t_{0}\right)=z$. From this equation we obtain

$$
\text { (24) } \frac{\partial \operatorname{l}_{g} h(z, t)}{\partial t}=z \frac{\partial \operatorname{l}_{g} h(z, t)}{\partial Z} \frac{1+K(t) Z}{1-K(t) Z} \text {. }
$$

Both functions $e^{t_{0}-t} h(z, t)$ and $e^{t f(z, t)}$ are schlicht and normalized at the origin. Hence, we can make use of the formula (14) for them. The constant terms of Faber's polynomials belong ing to $e^{t_{0}-t} h(z, t)$ and $e^{t} f(z, t)$ may be, without ambiguity, denoted by $Q_{v}(t)$ and $P_{v}(t)$ instead of
$Q_{v}(0) P_{v}(0)$ respectively, since $Q_{v}(0)$ and $P_{v}(0)$ in (14) depend now on the parameter $\pi$.

Substituting (22) into (14), we have the following differential equations

$$
\begin{align*}
Q_{1}^{\prime}(t)= & Q_{1}(t)+2 x(t)  \tag{25}\\
Q_{n}^{\prime}(t)= & n Q_{n}(t)+2 n\left(\sum_{v=1}^{n-1} x(t)^{n-v} Q_{v}(t)\right.  \tag{26}\\
& \left.+x(t)^{n}\right) \quad(n=2,3, \cdots
\end{align*}
$$

Integrating these equations with res spect to $\pi$ from $\pi$ to $t_{0}$ with the boundary condition $Q_{m}\left(\pi_{0}\right)=0$, we have the explicit formulae for $Q_{n}(t)$ For $P_{n}(t)$, it is sufficient to put $0, t^{t}$ in place of $t$, $t_{0}$ concerm… ing to $Q_{n}(t)$.
3.3. Estimation of coefficients.

In case $\eta=1$, we have, from (25),

$$
\begin{aligned}
& Q_{1}(t)=-2 e^{t} \int_{t}^{t_{0}} e^{-\tau} x(\tau) d \tau
\end{aligned}
$$

and hence, by the above-mentioned fact,
(27)

$$
P_{1}(t)=-2 \int_{0}^{t} e^{-\tau} x(\tau) d \tau
$$

From the last relation, we can eastiy obtain

$$
\begin{aligned}
(2,8) \quad\left|P_{1}(t)\right| & \leqq 2 \int_{0}^{t} e^{-\tau} d \tau \\
& =2\left(1-e^{-t}\right) \leqq 2
\end{aligned}
$$

This 2s, however, an immediate consequence of Koebe-Bfeberbach 's distortion theorem.

In case $n=2$, we have

$$
\begin{aligned}
Q_{2}(t)= & 4 e^{2 \pi}\left(\int_{t}^{t_{0}} e^{-\tau} x(\tau) d \tau\right)^{2} \\
& -4 e^{t} \int_{t}^{t_{0}} e^{-2 \tau} x(\tau)^{2} d \tau
\end{aligned}
$$

and so
(29) $P_{2}(t)=4\left(\int_{0}^{t} e^{-\tau} k(\tau) d \tau\right)^{2}-4 \int_{0}^{t} e^{-2 \tau} k(\tau)^{2} d \tau$.
Considering the real parts of (29) we

$$
\begin{aligned}
\operatorname{Ret} & \begin{aligned}
2 P_{2}(t)= & 4\left(\left(\int_{0}^{t} e^{-\tau} \cos \theta(\tau) d \tau\right)^{2}-\left(\int_{0}^{t} e^{-\tau} \sin \theta(\tau) d \tau\right)^{2}\right) \\
& -4 \int_{0}^{t} e^{-2 \tau} \cos 2 \theta(\tau) d \tau
\end{aligned}, r
\end{aligned}
$$

and hence we obtain

$$
\begin{aligned}
\mathcal{R} P_{2}(t) & \leqq 4 \int_{0}^{t}\left(e^{-\tau}-e^{-2 \tau}\right) \cos ^{2} \theta(\tau) d \tau+1-e^{-2 t} \\
& \leqq 2-2 e^{-t}\left(2-e^{-t}\right) \\
& \leqq 2
\end{aligned}
$$

In both relations (28) and (29), the equalities hold only for the limiting case $t \rightarrow \infty$ with $K(t) \equiv 1$, that is, for the extremal function

$$
f(x)=\frac{z}{(1-z)^{2}}
$$

By virtue of (21), we easily have

$$
\left|a_{2}\right| \leqq 2 \text { and } \quad\left|a_{3}\right| \leqq 3,
$$

which are the Bieberbach's and Löwner's coefficient theorems.
(*) Received March 27, 1950.
(7) S.Naguxa: Faber's polynomials. Kodai Math. Sem. Rep. No. 5. 5-6 (1949).
(8) Y.Komatu: Uber einen Satz von Herrn Löwner. Proc.Imp.Acad. Tokyo. 16 (1940), 512-4.
(9) K.Löwner: Untersuchungen über schlichte konforme Abbildungen des Einheitskreises, I. Math. Ann. 89 (1923), 103-121.
(10) A.C.Schaeffer, M.Schiffier and D.C.Spencer: The coefficient regions of schlicht functions, Duke Math. Journ. Vol. 16 (1949), 493-527.

On the other hand, above mentioned method can also be proceeded almost verbatin for Schaefter--Spencer's differential equation. Cf. A.C.Schaef fer and Spencer, The coefficients of schlicht function, II. Duke Math. Journ. 12 (1945), 107-25.
(To be concluded)
Nagoya University.

