# A CLASS FUNCTION ON THE TORELLI GROUP 

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#### Abstract

The Magnus representation of the Torelli group has been defined in virtue of Fox derivation. The Torelli group is a significant subgroup of the mapping class group of a surface. In this paper, we show some properties of the characteristic polynomials of matrices obtained from the Magnus representation of the Torelli group, which is a class function on the Torelli group.


## 1. Introduction

Let $\Sigma_{g, 1}$ be an oriented surface obtained from a closed surface $\Sigma_{g}$ of genus $g$ by removing an open disk. We denote by $\mathscr{M}_{g, 1}$ the mapping class group of $\Sigma_{g, 1}$ relative to the boundary, that is the group of path components of the group of orientation preserving diffeomorphisms of $\Sigma_{g, 1}$ which restrict to the identity on the boundary. Let $\mathscr{I}_{g, 1}$ be the Torelli group of $\Sigma_{g, 1}$, namely the normal subgroup of $\mathscr{M}_{g, 1}$ consisting of all the elements which act on the first homology group of $\Sigma_{g, 1}$ trivially.

We call the following mapping $r_{1}$ the Magnus representation of the Torelli group:

$$
r_{1}: \mathscr{I}_{g, 1} \rightarrow \operatorname{GL}(2 g ; \boldsymbol{Z}[H])
$$

where $H=H_{1}\left(\Sigma_{g, 1} ; \boldsymbol{Z}\right)$. We will consider the characteristic polynomials of matrices obtained from the Magnus representation of the Torelli group. That is, we will investigate

$$
R(\varphi)=\operatorname{det}\left(\lambda I_{2 g}-r_{1}(\varphi)\right)
$$

for $\varphi \in \mathscr{I}_{g, 1}$, where $I_{2 g}$ is the unit matrix and $\lambda$ is an indeterminate. Then $R$ is a class function on $\mathscr{I}_{g, 1}$.

We will prove some properties of this class function $R$. For example, we will show that the restriction of $R$ to $\mathscr{K}_{g, 1}$ is non-trivial, where $\mathscr{K}_{g, 1}$ is the normal subgroup of $\mathscr{I}_{g, 1}$ generated by all the Dehn twists along bounding simple closed curves.

## 2. Definition of the Magnus representation of the Torelli group

In this section, we recall the definition of the Magnus representation of the Torelli group.

Let $F_{n}$ be a free group of rank $n$ with free basis $z_{1}, \ldots, z_{n}$. The following simple derivation on the integral group ring $\boldsymbol{Z}\left[F_{n}\right]$ is the main ingredient of Fox derivation.

Definition 2.1 (Fox derivation). The Fox derivation is defined by the following equations:

$$
\begin{gathered}
\frac{\partial}{\partial z_{j}}\left(z_{\mu_{1}}^{\varepsilon_{1}} \cdots z_{\mu_{r}}^{\varepsilon_{r}}\right)=\sum_{i=1}^{r} \varepsilon_{i} \delta_{\mu_{i}, j} z_{\mu_{1}}^{\varepsilon_{1}} \cdots z_{\mu_{i-1}}^{\varepsilon_{i-1}} z_{\mu_{i}}^{(1 / 2)\left(\varepsilon_{i}-1\right)}, \quad \varepsilon_{i}= \pm 1 \\
\frac{\partial}{\partial z_{j}}\left(\sum a_{w} w\right)=\sum a_{w} \frac{\partial w}{\partial z_{j}}, \quad w \in F_{n}, a_{w} \in \boldsymbol{Z} .
\end{gathered}
$$

We fix a system of generators $\alpha_{1}, \ldots, \alpha_{g}, \beta_{1}, \ldots, \beta_{g}$ of the free group $\Gamma_{0}=$ $\pi_{1}\left(\Sigma_{g, 1}\right)$ as shown in Figure 1. Let us simply write $\gamma_{1}, \ldots, \gamma_{2 g}$ for them. Moreover, we obtain a system of symplectic basis $x_{i}, y_{i}$ of $H$ by abelianizing $\alpha_{i}, \beta_{i}$ respectively.

Definition 2.2. We call the mapping

$$
\begin{aligned}
r: \mathscr{M}_{g, 1} & \rightarrow \mathrm{GL}\left(2 g ; \boldsymbol{Z}\left[\Gamma_{0}\right]\right) \\
\varphi & \mapsto\left(\frac{\overline{\partial \varphi\left(\gamma_{j}\right)}}{\partial \gamma_{i}}\right)_{i, j}
\end{aligned}
$$

the Magnus representation for the mapping class group. Here $\partial / \partial \gamma_{i}$ is Fox derivation and ${ }^{-}: \boldsymbol{Z}\left[\Gamma_{0}\right] \ni \sum a \gamma \mapsto \sum a \gamma^{-1} \in \boldsymbol{Z}\left[\Gamma_{0}\right]$.


Figure 1. Generators of $\Gamma_{0}$

This mapping $r$ is a crossed homomorphism. The product formula below follows from the chain rule of Fox derivation.

Proposition 2.3 ([M1]). For any two elements $\varphi, \psi \in \mathscr{M}_{g, 1}$, we have

$$
r(\varphi \psi)=r(\varphi) \cdot{ }^{\varphi} r(\psi)
$$

where ${ }^{\varphi} r(\psi)$ denotes the matrix obtained from $r(\psi)$ by applying the automorphism $\varphi: \boldsymbol{Z}\left[\Gamma_{0}\right] \rightarrow \boldsymbol{Z}\left[\Gamma_{0}\right]$ on each entry.

We denote by $r^{\text {a }}$ the composition of the mapping $r$ by abelianizing $\mathfrak{a}: \boldsymbol{Z}\left[\Gamma_{0}\right] \rightarrow$ $\boldsymbol{Z}[H]$ the coefficients. If we consider elements of the Torelli group, we write $r_{1}$ for $r^{a}$. That is to say, we get a genuine representation $r_{1}$ by restricting this mapping $r^{a}$ to the Torelli group:

$$
r_{1}: \mathscr{I}_{g, 1} \rightarrow \mathrm{GL}(2 g ; \boldsymbol{Z}[H]) .
$$

## 3. Characteristic polynomials

In this section, we investigate characteristic polynomials of the Magnus matrices. Here the Magnus matrix means the image of $r_{1}$ for a mapping class. We define

$$
R(\varphi)=\operatorname{det}\left(\lambda I_{2 g}-r_{1}(\varphi)\right)
$$

for $\varphi \in \mathscr{I}_{g, 1}$. In particular, for any elements $\varphi_{1}, \varphi_{2} \in \mathscr{I}_{g, 1}$ we have

$$
R\left(\varphi_{2} \varphi_{1} \varphi_{2}^{-1}\right)=R\left(\varphi_{1}\right)
$$

so that $R$ is constant in the conjugacy classes of $\mathscr{g}_{g, 1}$, that is, $R$ is a class function on $\mathscr{I}_{g, 1}$.


Figure 2. Bounding simple closed curve $c_{k}$


Figure 3. Bounding pair $d_{k}, d_{k}^{\prime}$

The curve $c_{k}$ shown in Figure 2 is a bounding simple closed curve, where bounding means 0 -homologous. Let $\varphi_{k}$ denote the BSCC map which is the Dehn twist along a bounding simple closed curve $c_{k}$. We denote by $\psi_{k}$ the product of the right Dehn twist along a simple closed curve $d_{k}$ and the left Dehn twist along a simple closed curve $d_{k}^{\prime}$ which is disjoint and homologous to $d_{k}$ as shown in Figure 3. We call $\psi_{k}$ to be the BP map. It is known that the Torelli group $\mathscr{I}_{g, 1}$ is normally generated in $\mathscr{M}_{g, 1}$ by $\psi_{1}$ (see [ J$]$ for details).

First, we compute the Magnus matrices of BSCC map $\varphi_{k}$ and BP map $\psi_{k}$ directly. Since

$$
\varphi_{k}\left(\alpha_{j}\right)= \begin{cases}{\left[\beta_{k}, \alpha_{k}\right] \cdots\left[\beta_{1}, \alpha_{1}\right] \alpha_{j}\left[\alpha_{1}, \beta_{1}\right] \cdots\left[\alpha_{k}, \beta_{k}\right]} & 1 \leq j \leq k \\ \alpha_{j} & k<j\end{cases}
$$

and

$$
\varphi_{k}\left(\beta_{j}\right)=\left\{\begin{array}{ll}
{\left[\beta_{k}, \alpha_{k}\right] \cdots\left[\beta_{1}, \alpha_{1}\right] \beta_{j}\left[\alpha_{1}, \beta_{1}\right] \cdots\left[\alpha_{k}, \beta_{k}\right]} & 1 \leq j \leq k \\
\beta_{j} & k<j
\end{array},\right.
$$

these free differential calculuses are

$$
\begin{aligned}
& \frac{\partial\left(\varphi_{k}\left(\alpha_{j}\right)\right)}{\partial \alpha_{i}}=\left\{\begin{array}{rr}
{\left[\beta_{k}, \alpha_{k}\right] \cdots\left[\beta_{i+1}, \alpha_{i+1}\right] \beta_{i}} \\
& -\left[\beta_{k}, \alpha_{k}\right] \cdots\left[\beta_{i}, \alpha_{i}\right] \\
& +\delta_{i, j}\left[\beta_{k}, \alpha_{k}\right] \cdots\left[\beta_{1}, \alpha_{1}\right] \\
& +\left[\beta_{k}, \alpha_{k}\right] \cdots\left[\beta_{1}, \alpha_{1}\right] \alpha_{j}\left[\alpha_{1}, \beta_{1}\right] \cdots\left[\alpha_{i-1}, \beta_{i-1}\right] \\
\quad-\left[\beta_{k}, \alpha_{k}\right] \cdots\left[\beta_{1}, \alpha_{1}\right] \alpha_{j}\left[\alpha_{1}, \beta_{1}\right] \cdots\left[\alpha_{i-1}, \beta_{i-1}\right] \alpha_{i} \beta_{i} \bar{\alpha}_{i} \\
& 1 \leq j \leq k, i \leq k \\
0 & 1 \leq j \leq k, k<i \leq g \\
\delta_{i, j} & k<j
\end{array}\right.
\end{aligned}
$$

Then the Magnus matrix of genus $k \operatorname{BSCC}$ map $\varphi_{k}$ is

$$
r_{1}\left(\varphi_{k}\right)=I_{2 g}+a_{k} b_{k}
$$

where

$$
\begin{aligned}
& a_{k}={ }^{t}(\bar{y}_{1}-1 \cdots \bar{y}_{k}-1 \underbrace{0 \cdots 0}_{g-k \text { times }} 1-\bar{x}_{1} \cdots 1-\bar{x}_{k} \underbrace{0 \cdots 0}_{g-k \text { times }}) \\
& b_{k}=(1-\bar{x}_{1} \cdots 1-\bar{x}_{k} \underbrace{0 \cdots 0}_{g-k \text { times }} 1-\bar{y}_{1} \cdots 1-\bar{y}_{k} \underbrace{0 \cdots 0}_{g-k \text { times }}) .
\end{aligned}
$$

Similarly, since

$$
\begin{aligned}
& \psi_{k}\left(\alpha_{j}\right) \\
& \quad= \begin{cases}{\left[\alpha_{1}, \beta_{1}\right] \cdots\left[\alpha_{k}, \beta_{k}\right] \alpha_{k+1} \beta_{k+1} \bar{\alpha}_{k+1} \alpha_{j} \alpha_{k+1} \bar{\beta}_{k+1} \bar{\alpha}_{k+1}\left[\beta_{k}, \alpha_{k}\right] \cdots\left[\beta_{1}, \alpha_{1}\right]} & 1 \leq j \leq k \\
{\left[\alpha_{1}, \beta_{1}\right] \cdots\left[\alpha_{k}, \beta_{k}\right] \alpha_{k+1}} & j=k+1 \\
\alpha_{j} & k+1<j\end{cases}
\end{aligned}
$$

and

$$
\begin{aligned}
& \psi_{k}\left(\beta_{j}\right) \\
& \qquad= \begin{cases}{\left[\alpha_{1}, \beta_{1}\right] \cdots\left[\alpha_{k}, \beta_{k}\right] \alpha_{k+1} \beta_{k+1} \bar{\alpha}_{k+1} \beta_{j} \alpha_{k+1} \bar{\beta}_{k+1} \bar{\alpha}_{k+1}\left[\beta_{k}, \alpha_{k}\right] \cdots\left[\beta_{1}, \alpha_{1}\right]} & 1 \leq j \leq k \\
\beta_{j} & k<j\end{cases}
\end{aligned}
$$

the Magnus matrix of genus $k$ BP map $\psi_{k}$ is

$$
r_{1}\left(\psi_{k}\right)=\left(\begin{array}{ll}
B_{1} & B_{2} \\
B_{3} & B_{4}
\end{array}\right)
$$

where

$$
\begin{gathered}
B_{1}=\left(\begin{array}{ccccccc}
\bar{y}_{k+1}+X_{1} Y_{1} & \cdots & X_{k} Y_{1} & Y_{1} & 0 & \cdots & 0 \\
\vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\
X_{1} Y_{k} & \cdots & \bar{y}_{k+1}+X_{k} Y_{k} & Y_{k} & 0 & \cdots & 0 \\
X_{1} Y_{k+1} & \cdots & X_{k} Y_{k+1} & 1 & 0 & \cdots & 0 \\
0 & \cdots & 0 & 0 & 1 & \cdots & 0 \\
\vdots & & \vdots & \vdots & \vdots & \ddots & \vdots \\
0 & \cdots & 0 & 0 & 0 & \cdots & 1
\end{array}\right) \\
B_{2}=\left(\begin{array}{cccccc}
Y_{1} Y_{1} & \cdots & Y_{k} Y_{1} & 0 & \cdots & 0 \\
\vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\
Y_{1} Y_{k} & \cdots & Y_{k} Y_{k} & 0 & \cdots & 0 \\
Y_{1} Y_{k+1} & \cdots & Y_{k} Y_{k+1} & 0 & \cdots & 0 \\
0 & \cdots & 0 & 0 & \cdots & 0 \\
\vdots & & \vdots & \vdots & \ddots & \vdots \\
0 & \cdots & 0 & 0 & \cdots & 0
\end{array}\right)
\end{gathered}
$$

$$
B_{3}=\left(\begin{array}{ccccccc}
-X_{1} X_{1} & \cdots & -X_{k} X_{1} & -X_{1} & 0 & \cdots & 0 \\
\vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\
-X_{1} X_{k} & \cdots & -X_{k} X_{k} & -X_{k} & 0 & \cdots & 0 \\
\bar{x}_{k+1} X_{1} & \cdots & \bar{x}_{k+1} X_{k} & 0 & 0 & \cdots & 0 \\
0 & \cdots & 0 & 0 & 0 & \cdots & 0 \\
\vdots & & \vdots & \vdots & \vdots & \ddots & \vdots \\
0 & \cdots & 0 & 0 & 0 & \cdots & 0
\end{array}\right)
$$

$$
B_{4}=\left(\begin{array}{ccccccc}
\bar{y}_{k+1}-X_{1} Y_{1} & \cdots & -X_{1} Y_{k} & 0 & 0 & \cdots & 0 \\
\vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\
-X_{k} Y_{1} & \cdots & \bar{y}_{k+1}-X_{k} Y_{k} & 0 & 0 & \cdots & 0 \\
\bar{x}_{k+1} Y_{1} & \cdots & \bar{x}_{k+1} Y_{k} & 1 & 0 & \cdots & 0 \\
0 & \cdots & 0 & 0 & 1 & \cdots & 0 \\
\vdots & & \vdots & \vdots & \vdots & \ddots & \vdots \\
0 & \cdots & 0 & 0 & 0 & \cdots & 1
\end{array}\right) .
$$

Here $X_{i}=1-\bar{x}_{i}=1-x_{i}^{-1}, \quad Y_{i}=1-\bar{y}_{i}=1-y_{i}^{-1}$.
Then straightforward calculations show the following results about the characteristic polynomials of them.

Lemma 3.1. Let $\varphi_{k}, \psi_{k}$ be as above. Then we have

1. $\operatorname{det}\left(\lambda I_{2 g}-r_{1}\left(\varphi_{k}\right)\right)=(\lambda-1)^{2 g}$
2. $\operatorname{det}\left(\lambda I_{2 g}-r_{1}\left(\psi_{k}\right)\right)=(\lambda-1)^{2 g-2 k}\left(\lambda-y_{k+1}^{-1}\right)^{2 k}$.

We remark that the characteristic polynomial $R$ is a class function not on $\mathscr{M}_{g, 1}$ but on $\mathscr{I}_{g, 1}$. More precisely,

Proposition 3.2. For any $\varphi \in \mathscr{I}_{g, 1}$ and $f \in \mathscr{M}_{g, 1}$,

$$
R\left(f \varphi f^{-1}\right)=f(R(\varphi))
$$

where we also denote by $f$ the mapping $\boldsymbol{Z}\left[\lambda, x_{1}^{ \pm 1}, \ldots, x_{g}^{ \pm 1}, y_{1}^{ \pm 1}, \ldots, y_{g}^{ \pm 1}\right] \rightarrow$ $\boldsymbol{Z}\left[\lambda, f\left(x_{1}\right)^{ \pm 1}, \ldots, f\left(x_{g}\right)^{ \pm 1}, f\left(y_{1}\right)^{ \pm 1}, \ldots, f\left(y_{g}\right)^{ \pm 1}\right]$.

Proof. First, we note that ${ }^{f} r\left(f^{-1}\right)=r(f)^{-1}$, because we have

$$
I_{2 g}=r\left(f f^{-1}\right)=r(f) \cdot f_{r}\left(f^{-1}\right)
$$

Then we get

$$
\begin{aligned}
R\left(f \varphi f^{-1}\right) & =\operatorname{det}\left(I_{2 g}-r_{1}\left(f \varphi f^{-1}\right)\right) \\
& =\operatorname{det}\left(I_{2 g}-r^{\mathfrak{a}}(f) \cdot{ }_{r_{1}}(\varphi) \cdot{ }^{f \varphi} r^{\mathfrak{a}}\left(f^{-1}\right)\right) \\
& =\operatorname{det}\left(I_{2 g}-r^{\mathfrak{a}}(f) \cdot{ }_{r_{1}}(\varphi) \cdot r^{\mathfrak{a}}(f)^{-1}\right) \\
& =\operatorname{det}\left(I_{2 g}-{ }_{r_{1}}(\varphi)\right) \\
& =f\left(\operatorname{det}\left(I_{2 g}-r_{1}(\varphi)\right)\right) \\
& =f(R(\varphi))
\end{aligned}
$$

Any BSCC map $\varphi$ can be written as $\varphi=f \varphi_{k} f^{-1}$, where $f \in \mathscr{M}_{g, 1}$ and $\varphi_{k}$ is the Dehn twist along a simple closed curve $c_{k}$ as before. According to Lemma 3.1, we deduce the following corollary.

Corollary 3.3. For any BSCC map $\varphi$, we have

$$
R(\varphi)=(\lambda-1)^{2 g} .
$$

For any BSCC map $\varphi$, the characteristic polynomial of $r_{1}(\varphi)$ is trivial. However, the characteristic polynomial of a product of two BSCC maps is not always trivial. For example, we can show that

$$
R\left(\varphi_{1} v_{1} \varphi_{1} v_{1}^{-1}\right)=(\lambda-1)^{2 g}+\lambda(\lambda-1)^{2 g-2}\left(y_{1}-2+\bar{y}_{1}\right)\left(y_{2}-2+\bar{y}_{2}\right) .
$$

Here $v_{1}$ is the Dehn twist along $n_{1}$ as shown in Figure 4. This means that the restriction of $R$ to $\mathscr{K}_{g, 1}$ is non-trivial, where $\mathscr{K}_{g, 1}$ is the normal subgroup of $\mathscr{\mathscr { G }}_{g, 1}$ generated by all the BSCC maps.

Proposition 3.4. For any $\psi \in \mathscr{I}_{g, 1}, R$ has a common factor $(\lambda-1)^{2}$.
Proof. From our previous paper [S2], there exsists a non-singular matrix $P$ such that for any element $\psi \in \mathscr{I}_{g, 1}$


Figure 4. Lickorish generators

$$
P^{-1} r_{1}(\psi) P=\left(\begin{array}{c|cc|c}
1 & * & * \\
\hline 0 & & & \\
\vdots & & \rho_{B}(\psi) & \\
& * \\
\cline { 2 - 5 } & 0 & \cdots & 0
\end{array}\right) .
$$

Here $\rho_{B}$ is a $(2 g-2)$-dimensional irreducible representation of $\mathscr{I}_{g, 1}$ (see [S2] for details). This means that the assertion holds.

Moreover, from our previous paper [S2], we have

$$
\rho_{B}\left(\tau_{\zeta}\right)=I_{2 g-2},
$$

where $\tau_{\zeta}$ be the Dehn twist along a simple closed curve on $\Sigma_{g, 1}$ which is parallel to the boundary. This equality says that $R$ factors through $\mathscr{I}_{g, *}$. Here $\mathscr{I}_{g, *}$ is the Torelli group of $\Sigma_{g}$ relative to the base point $* \in \Sigma_{g}$.

## 4. The relation between $R(\psi)$ and $R\left(\psi^{-1}\right)$

The relation between $R(\psi)$ and $R\left(\psi^{-1}\right)$ is given by the following formula.
Proposition 4.1. For $\psi \in \mathscr{I}_{g, 1}$, we have

$$
R(\psi)=\overline{R\left(\psi^{-1}\right)}
$$

where $\div: x_{i} \mapsto x_{i}^{-1}, y_{i} \mapsto y_{i}^{-1}$.
To prove Proposition 4.1, we recall that the Magnus representation of the Torelli group is symplectic.

Proposition 4.2 (Morita [M1]). There exists a matrix $J \in \operatorname{GL}(2 g ; \boldsymbol{Z}[H])$ such that for any $\psi \in \mathscr{I}_{g, 1}$ we have the equality

$$
\overline{{ }^{t_{r}}(\psi)} J r_{1}(\psi)=J
$$

Here $J$ is defined as follows:

$$
J=\left(\begin{array}{ll}
J_{1} & J_{2} \\
J_{3} & J_{4}
\end{array}\right)
$$

where

$$
\begin{gathered}
J_{1}=\left(\begin{array}{ccccc}
1-x_{1} & & & \\
\left(1-x_{2}\right)\left(1-\bar{x}_{1}\right) & 1-x_{2} & & \\
\left(1-x_{3}\right)\left(1-\bar{x}_{1}\right) & \left(1-x_{3}\right)\left(1-\bar{x}_{2}\right) & 1-x_{3} & & \\
\vdots & \vdots & & \ddots & \\
\left(1-x_{g}\right)\left(1-\bar{x}_{1}\right) & \left(1-x_{g}\right)\left(1-\bar{x}_{2}\right) & \cdots & & 1-x_{g}
\end{array}\right) \\
J_{2}=\left(\begin{array}{ccccc}
x_{1} \bar{y}_{1} & & & \\
\left(1-x_{2}\right)\left(1-\bar{y}_{1}\right) & x_{2} \bar{y}_{2} & & \\
\left(1-x_{3}\right)\left(1-\bar{y}_{1}\right) & \left(1-x_{3}\right)\left(1-\bar{y}_{2}\right) & x_{3} \bar{y}_{3} & \\
\vdots & \vdots & & \ddots & \\
J_{3}= \\
J_{4}=\left(\begin{array}{ccccc}
\left.1-x_{g}\right)\left(1-\bar{y}_{1}\right) & \left(1-x_{g}\right)\left(1-\bar{y}_{2}\right) & \cdots & & x_{g} \bar{y}_{g}
\end{array}\right) \\
\left(1-y_{2}\right)\left(1-\bar{x}_{1}\right) & 1-\bar{x}_{2}-y_{2} & & & \\
\left(1-y_{3}\right)\left(1-\bar{x}_{1}\right) & \left(1-y_{3}\right)\left(1-\bar{x}_{2}\right) & 1-\bar{x}_{3}-y_{3} & & \\
\vdots & \vdots & & \ddots & \\
\left(1-y_{g}\right)\left(1-\bar{x}_{1}\right) & \left(1-y_{g}\right)\left(1-\bar{x}_{2}\right) & \cdots & & 1-\bar{x}_{g}-y_{g}
\end{array}\right) \\
\left(\begin{array}{ccccc}
1-\bar{y}_{1} & & & & \\
\left(1-y_{2}\right)\left(1-\bar{y}_{1}\right) & 1-\bar{y}_{2} & & \\
\left(1-y_{3}\right)\left(1-\bar{y}_{1}\right) & \left(1-y_{3}\right)\left(1-\bar{y}_{2}\right) & 1-\bar{y}_{3} \\
\vdots & \vdots & & \ddots & \\
\left(1-y_{g}\right)\left(1-\bar{y}_{1}\right) & \left(1-y_{g}\right)\left(1-\bar{y}_{2}\right) & \cdots & & 1-\bar{y}_{g}
\end{array}\right)
\end{gathered}
$$

Proof of Proposition 4.1. By Proposition 4.2, we get

$$
\overline{t_{r_{1}}(\psi)}=J r_{1}(\psi)^{-1} J^{-1}=J r_{1}\left(\psi^{-1}\right) J^{-1} .
$$

Hence we conclude

$$
\begin{aligned}
R(\psi) & =\operatorname{det}\left(\lambda I-r_{1}(\psi)\right) \\
& =\operatorname{det}\left(\lambda I-J r_{1}(\psi) J^{-1}\right) \\
& =\operatorname{det}\left(\lambda I-\overline{t_{r_{1}}\left(\psi^{-1}\right)}\right) \\
& =\overline{\operatorname{det}\left(\lambda I-r_{1}\left(\psi^{-1}\right)\right)} \\
& =\overline{R\left(\psi^{-1}\right)} .
\end{aligned}
$$

Corollary 3.3 states that the determinant of the Magnus matrix for any BSCC map is one. Because the group $\mathscr{K}_{g, 1}$ is generated by BSCC maps, $\operatorname{det} r_{1}(\varphi)=1$ for any $\varphi \in \mathscr{K}_{g, 1}$. Then we deduce the following.

Corollary 4.3. Let $\varphi$ be an element of $\mathscr{K}_{g, 1}$. Suppose that the characteristic polynomial is written as

$$
R(\varphi)=\lambda^{2 g}+p_{1} \lambda^{2 g-1}+p_{2} \lambda^{2 g-2}+\cdots+p_{2 g-1} \lambda+1
$$

where $p_{k} \in \boldsymbol{Z}[H]$, then $p_{k}=\overline{p_{2 g-k}}$. In particular, we have $p_{g}=\overline{p_{g}}$.
Moreover, in the case of genus 2, for any $\varphi \in \mathscr{K}_{2,1}$ the variables $p_{k}$ can be reduced to just one. That is, we have

$$
R(\varphi)=(\lambda-1)^{2}\left(\lambda^{2}+p \lambda+1\right)
$$

by Proposition 3.4. The above equation and Corollary 4.3 yield the following statement.

Corollary 4.4. For any $\varphi \in \mathscr{K}_{2,1}$ we have

$$
R(\varphi)=R\left(\varphi^{-1}\right)
$$

For higher genera, this statement does not hold. For example, an explicit calculation shows that

$$
R\left(\varphi_{1} \lambda_{2} v_{1} \varphi_{1} v_{1}^{-1} \lambda_{2}^{-1} v_{2} \lambda_{2} v_{1} \varphi_{1}^{\prime} v_{1}^{-1} \lambda_{2}^{-1} v_{2}^{-1}\right) \neq R\left(\left(\varphi_{1} \lambda_{2} v_{1} \varphi_{1} v_{1}^{-1} \lambda_{2}^{-1} v_{2} \lambda_{2} v_{1} \varphi_{1}^{\prime} v_{1}^{-1} \lambda_{2}^{-1} v_{2}^{-1}\right)^{-1}\right)
$$

Here $\varphi_{1}^{\prime}, \lambda_{2}, v_{2}$ are the Dehn twists along $c_{1}^{\prime}, l_{2}, v_{2}$ as shown in Figure 5 and Figure 4. However, for a product of two BSCC maps, we arrive at the following.


Figure 5. bounding simple closed curve $c_{i}^{\prime}$
Theorem 4.5. Let $\varphi_{1}, \varphi_{2}$ be BSCC maps. Then we have

$$
R\left(\varphi_{1} \varphi_{2}\right)=R\left(\left(\varphi_{1} \varphi_{2}\right)^{-1}\right)
$$

We provide the following to prove Theorem 4.5.

Lemma 4.6. Let $u_{1}, u_{2}$ be $n$-dimensional column vectors and $v_{1}, v_{2} n$ dimensional row vectors. Then we get

$$
\begin{aligned}
& \operatorname{det}\left(t I_{n}+u_{1} v_{1}+u_{2} v_{2}-u_{1} v_{1} u_{2} v_{2}\right) \\
& \quad=\operatorname{det}\left(t I_{n}-u_{1} v_{1}-u_{2} v_{2}-u_{1} v_{1} u_{2} v_{2}\right)+2\left(\operatorname{tr} u_{1} v_{1}+\operatorname{tr} u_{2} v_{2}\right) t^{n-1}
\end{aligned}
$$

If we write $M_{1}, M_{2}$ for $-u_{1} v_{1}-u_{2} v_{2}+u_{1} v_{1} u_{2} v_{2}, u_{1} v_{1}+u_{2} v_{2}+u_{1} v_{1} u_{2} v_{2}$ respectively, then the above equality can be stated as

$$
\operatorname{det}\left(t I_{n}-M_{1}\right)=\operatorname{det}\left(t I_{n}-M_{2}\right)+2\left(\operatorname{tr} u_{1} v_{1}+\operatorname{tr} u_{1} v_{1}\right) t^{n-1}
$$

Thus we will prove the above equation.
Proof. The characteristic polynomial of matrix $M_{l}=\left(m_{i, j}^{l}\right)$ is given as

$$
\operatorname{det}\left(t I_{n}-M_{l}\right)=t^{n}+c_{1}^{l} t^{n-1}+c_{2}^{l} t^{n-2}+\cdots+c_{n-1}^{l} t+c_{n}^{l} \quad(l=1,2)
$$

where

$$
c_{k}^{l}=(-1)^{k} \sum_{1 \leq i_{1}<i_{2}<\cdots<i_{k} \leq n}\left|\begin{array}{cccc}
m_{i_{1}, i_{1}}^{l} & m_{i_{1}, i_{2}}^{l} & \cdots & m_{i_{1}, i_{k}}^{l}  \tag{4.1}\\
m_{i_{2}, i_{1}}^{l} & m_{i_{2}, i_{2}}^{l} & \cdots & m_{i_{2}, i_{k}}^{l} \\
\vdots & \vdots & \ddots & \vdots \\
m_{i_{k}, i_{1}}^{l} & m_{i_{k}, i_{2}}^{l} & \cdots & m_{i_{k}, i_{k}}^{l}
\end{array}\right| .
$$

Since the rank of $M_{l}$ is less than 3, then

$$
c_{3}^{l}=c_{4}^{l}=\cdots=c_{n}^{l}=0
$$

This means that the difference between the characteristic polynomial of $M_{1}$ and that of $M_{2}$ appears only in terms of $t^{n-1}$ and $t^{n-2}$. First, the coefficient of $t^{n-1}$ is the difference between $\operatorname{tr} M_{1}$ and $\operatorname{tr} M_{2}$ :

$$
\left(c_{1}^{1}-c_{1}^{2}\right) t^{n-1}=\left(-\operatorname{tr} M_{1}+\operatorname{tr} M_{2}\right) t^{n-1}=2\left(\operatorname{tr} u_{1} v_{1}+\operatorname{tr} u_{2} v_{2}\right) t^{n-1}
$$

Second, we compute the term of $t^{n-2}$. We set

$$
u_{1}={ }^{t}\left(c_{1} \cdots c_{n}\right), \quad u_{2}={ }^{t}\left(d_{1} \cdots d_{n}\right), \quad v_{1}=\left(e_{1} \cdots e_{n}\right), \quad v_{2}=\left(f_{1} \cdots f_{n}\right)
$$

The $(i, j)$-components of $M_{1}$ and $M_{2}$ are

$$
m_{i, j}^{1}=-c_{i} e_{j}-d_{i} f_{j}+A c_{i} f_{j}, \quad m_{i, j}^{2}=c_{i} e_{j}+d_{i} f_{j}+A c_{i} f_{j}
$$

where $A=\sum_{k=1}^{n} e_{k} d_{k}$. Because of the equation (4.1), we get the following.

$$
\begin{aligned}
& c_{2}^{1}-c_{2}^{2}= \sum_{1 \leq i<j \leq n}\left|\begin{array}{ll}
m_{i, i}^{1} & m_{i, j}^{1} \\
m_{j, i}^{1} & m_{j, j}^{1}
\end{array}\right|-\sum_{1 \leq i<j \leq n}\left|\begin{array}{ll}
m_{i, i}^{2} & m_{i, j}^{2} \\
m_{j, i}^{2} & m_{j, j}^{2}
\end{array}\right| \\
&=\sum_{1 \leq i<j \leq n}\left(m_{i, i}^{1} m_{j, j}^{1}-m_{i, j}^{1} m_{j, i}^{1}-m_{i, i}^{2} m_{j, j}^{2}+m_{i, j}^{2} m_{j, i}^{2}\right) \\
&= \sum_{1 \leq i<j \leq n}\left\{\left(-c_{i} e_{i}-d_{i} f_{i}+A c_{i} f_{i}\right)\left(-c_{j} e_{j}-d_{j} f_{j}+A c_{j} f_{j}\right)\right. \\
& \quad\left(-c_{i} e_{j}-d_{i} f_{j}+A c_{i} f_{j}\right)\left(-c_{j} e_{i}-d_{j} f_{i}+A c_{j} f_{i}\right) \\
& \quad-\left(c_{i} e_{i}+d_{i} f_{i}+A c_{i} f_{i}\right)\left(c_{j} e_{j}+d_{j} f_{j}+A c_{j} f_{j}\right) \\
&\left.\quad+\left(c_{i} e_{j}+d_{i} f_{j}+A c_{i} f_{j}\right)\left(c_{j} e_{i}+d_{j} f_{i}+A c_{j} f_{i}\right)\right\}
\end{aligned}
$$

This means that the coefficient of $t^{n-2}$ is zero and completes the proof.
Proof of Theorem 4.5. The Magnus matrix of $\varphi_{i}$ which is any BSCC map can be written as

$$
r_{1}\left(\varphi_{i}\right)=I_{2 g}+u_{i} v_{i} \quad i=1,2
$$

where $u_{i}$ is a $n$-dimensional column vector and $v_{i}$ is a $n$-dimensional row vector. Corollary 3.3 states that $\operatorname{tr} u_{i} v_{i}=v_{i} u_{i}$ equals zero. This deduces $r_{1}\left(\varphi_{i}^{-1}\right)=$ $I_{2 g}-u_{i} v_{i}$. Therefore we have

$$
\begin{aligned}
R\left(\varphi_{2}^{-1} \varphi_{1}^{-1}\right) & =R\left(\varphi_{1}^{-1} \varphi_{2}^{-1}\right) \\
& =\operatorname{det}\left(\lambda I_{2 g}-\left(I_{2 g}-u_{1} v_{1}\right)\left(I_{2 g}-u_{2} v_{2}\right)\right) \\
& =\operatorname{det}\left((\lambda-1) I_{2 g}+u_{1} v_{1}+u_{2} v_{2}-u_{1} v_{1} u_{2} v_{2}\right) \\
& =\operatorname{det}\left((\lambda-1) I_{2 g}-u_{1} v_{1}-u_{2} v_{2}-u_{1} v_{1} u_{2} v_{2}\right) \quad \text { Because of Lemma } 4.6 \\
& =\operatorname{det}\left(\lambda I_{2 g}-\left(I_{2 g}+u_{1} v_{1}\right)\left(I_{2 g}+u_{2} v_{2}\right)\right) \\
& =R\left(\varphi_{1} \varphi_{2}\right)
\end{aligned}
$$

This completes the proof.
In general, we can not decide how many BSCC maps are producted for a given element of $\mathscr{K}_{g, 1}$. However, Corollary 3.3 and Theorem 4.5 help to determine the number. More precisely, we have the following criterion.

Corollary 4.7. First, for an element $\varphi$ of $\mathscr{K}_{g, 1}$, if the characteristic polynomial is not trivial, then the element $\varphi$ can not be written as just one BSCC map. Second, if the characteristic polynomial of $r_{1}(\varphi)$ and that of $r_{1}(\varphi)^{-1}$ are not the same, then the element $\varphi$ can neither be written as one BSCC map nor a product of two BSCC maps.

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