

Holomorphic families of isomorphisms of Möbius groups*

To Yukio Kusunoki on his 60th birthday

By

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This note contains a new proof and a slight extension of a result by Sullivan (see Proposition 1 below).

The group $\mathrm{PSL}(2, \mathbb{C})$ may be identified with the group of all conformal self-maps of the Riemann sphere $\hat{\mathbb{C}} = \mathbb{C} \cup \{\infty\}$ (Möbius transformations). In what follows G denotes a subgroup of $\mathrm{PSL}(2, \mathbb{C})$ and A a subset of $\hat{\mathbb{C}}$ invariant under G and containing at least 3 points. An isomorphism $X: G \rightarrow \mathrm{PSL}(2, \mathbb{C})$ is said to be *induced* by an injection $f: A \rightarrow \hat{\mathbb{C}}$ if

$$f \circ g(a) = X(g)f(a) \quad \text{for } g \in G, a \in A.$$

An isomorphism induced by a quasiconformal self-map of $\hat{\mathbb{C}}$ is called a *quasiconformal deformation*.

Let $D \subset \mathbb{C}$ be a domain. A *holomorphic family of injections* $\{f_\lambda\}$ of A , defined over D , is a rule assigning an injection $f_\lambda: A \rightarrow \mathbb{C}$ to every $\lambda \in D$ so that for every $a \in A$ the point $f_\lambda(a)$ depends holomorphically on λ . A *holomorphic family of isomorphisms* $\{X_\lambda\}$ of G , defined over D , is a rule assigning to each $\lambda \in D$ an isomorphism $X_\lambda: G \rightarrow \mathrm{PSL}(2, \mathbb{C})$ so that for every $a \in \hat{\mathbb{C}}$ and every $g \in G$ the point $X_\lambda(g)(a)$ depends holomorphically on λ . The family $\{X_\lambda\}$ is induced by the family $\{f_\lambda\}$ if f_λ induces X_λ for every $\lambda \in D$.

Proposition 1. *Let the holomorphic family $\{f_\lambda\}$ of injection of A induce the holomorphic family $\{X_\lambda\}$ of isomorphisms of G , both families being defined over a domain $D \subset \mathbb{C}$. If there is a $\lambda_0 \in D$ such that X_{λ_0} is a quasiconformal deformation of G , so are all X_λ , $\lambda \in D$.*

For a finitely generated group G this assertion is proved (though not formulated as a special proposition) in §6 of Sullivan's paper [3]. Sullivan observes that the proof involves a "delicate point".

We establish first a more precise result.

Proposition 2. *Under the hypotheses of Proposition 1, assume that D is the*

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unit disc $|\lambda| < 1$, $\lambda_0 = 0$ and $f_0 = id$ (so that $X_0 = id$). Then there is a holomorphic family $\{F_\lambda\}$ of quasiconformal self-maps of \hat{C} defined over the disc $|\lambda| < \frac{1}{3}$ such that $F_0 = id$ and F_λ induces X_λ (for $|\lambda| < \frac{1}{3}$).

The proof is based on Theorem 3 in Bers-Royden [1]. According to this theorem there exists a *unique* holomorphic family $\{F_\lambda\}$ of quasiconformal self-maps of \hat{C} , defined over $|\lambda| < \frac{1}{3}$, such that (i) $F_0 = id$, (ii) for $|\lambda| < \frac{1}{3}$ we have

$$F_\lambda|_A = f_\lambda,$$

and (iii) the Beltrami coefficient of F_λ , i.e.,

$$\mu_\lambda = (\partial F_\lambda / \partial \bar{z}) / (\partial F_\lambda / \partial z),$$

is harmonic in $\hat{C} \setminus \hat{A}$, where \hat{A} denotes the closure of A in \hat{C} .

Condition (iii) means that in any component of $\hat{C} \setminus \hat{A}$.

$$\mu_\lambda(z) = \rho(z)^{-2} \overline{\psi_\lambda(z)}$$

where $\rho(z)|dz|$ is the Poincaré metric in the component of $\hat{C} \setminus \hat{A}$ containing z and $\psi_\lambda(z)$ is holomorphic in that component. (The condition is vacuous if $\hat{A} = \hat{C}$).

Set, for some $g \in G$,

$$\tilde{F}_\lambda = X_\lambda(g)^{-1} \circ F_\lambda \circ g.$$

Then $\{\tilde{F}_\lambda\}$ is a holomorphic family of quasiconformal self-maps of \hat{C} , defined over $|\lambda| < \frac{1}{3}$, and $\tilde{F}_0 = id$. Since

$$f_\lambda \circ g|_A = X_\lambda(g) \circ f_\lambda$$

we have that

$$\begin{aligned} \tilde{F}_\lambda|_A &= X_\lambda(g)^{-1} \circ F_\lambda \circ g|_A \\ &= X_\lambda(g)^{-1} \circ f_\lambda \circ g|_A = f_\lambda. \end{aligned}$$

Finally, the Beltrami coefficient $\tilde{\mu}_\lambda$ of \tilde{F}_λ (in $\hat{C} \setminus \hat{A}$) is easily computed to be

$$\begin{aligned} \tilde{\mu}_\lambda(z) &= \mu_\lambda(g(z)) \overline{g'(z)} / g'(z) \\ &= [\rho(g(z)) |g'(z)|]^{-2} \overline{\psi_\lambda(g(z))} g'(z)^2 \\ &= \rho(z)^{-2} \overline{\varphi_\lambda(z)} \end{aligned}$$

where $\varphi_\lambda(z)$ is holomorphic in the component containing z . (Here we used the conformal invariance of the Poincaré metric).

The uniqueness statement of Theorem 3 in [1] implies that $\tilde{F}_\lambda = F_\lambda$ for every g . Thus

$$X_\lambda(g) = F_\lambda \circ g \circ F_\lambda^{-1} \quad \text{for } |\lambda| < \frac{1}{3}.$$

Corollary 1. *Under the hypotheses of Proposition 1, assume that D is the unit disc and $\lambda_0 = 0$. For $|\lambda| < \frac{1}{3}$ the isomorphism X_λ is a quasiconformal deformation.*

Proof. Set $\tilde{A} = f_0(A)$, $\tilde{G} = X_0(G)$, $\tilde{f}_\lambda = f_\lambda \circ f_0^{-1}$, and $\tilde{X}_\lambda = X_\lambda \circ X_0^{-1}$. Now apply Proposition 2 to the holomorphic families $\{\tilde{f}_\lambda\}$ and $\{\tilde{X}_\lambda\}$ of injections of \tilde{A} and of isomorphisms of \tilde{G} , respectively.

Corollary 2. *Under the hypotheses of Proposition 1, assume that D is simply connected and $D \neq \mathbb{C}$. For every λ inside the Poincaré disc (in D) with center λ_0 and radius $\log 2$ the isomorphism X_λ is a quasiconformal deformation.*

Proof. Map D conformally onto the unit disc, taking λ_0 into the origin. Then apply Corollary 1 and note that the Poincaré distance (in the unit disc) from 0 to a point ξ with $|\xi| = \frac{1}{3}$ is $\log 2$.

Proof of Proposition 1. It suffices to prove the proposition for the case when D is simply connected and $D \neq \mathbb{C}$ since given any λ_1 in D there is a bounded simply connected domain $D_0 \subset D$ containing λ_0 and λ_1 .

If $D \neq \mathbb{C}$ and D is simply connected, let Θ denote the set of all λ in D for which X_λ is a quasiconformal deformation. Then $\lambda_0 \in \Theta$, by hypothesis, and Θ is open and closed, by Corollary 2. Hence $\Theta = D$, q. e. d.

Here is an application of Proposition 1.

Theorem. *Let G contain two loxodromic (including hyperbolic) elements with 4 distinct fixed points.*

Let $\{X_\lambda\}$ be a holomorphic family of isomorphisms of G defined over D , with X_{λ_0} a quasiconformal deformation for some $\lambda_0 \in D$. Assume that, for all $\lambda \in D$, (i) $X_\lambda(G)$ is discrete and (ii) $X_\lambda(g)$ is parabolic if and only if $g \in G$ is. Then each X_λ is a quasiconformal deformation.

Proof. By (i) and (ii), $X_\lambda(g)$ is elliptic if and only if $g \in G$ is. Let A be the set of fixed points of loxodromic elements of G . Recalling that two loxodromic Möbius transformations with precisely 3 distinct fixed points generate a non-discrete group, we conclude from (i) and (ii) that the map f_λ which takes an attracting fixed point of a loxodromic element $g \in G$ into the attracting fixed point of $X_\lambda(g)$ is a well-defined injections of A .

Next we verify that f_λ induces X_λ . Let us denote the attracting fixed point of a loxodromic $h \in G$ by $\alpha[h]$. If g is any element of G , then

$$\begin{aligned} f_\lambda \circ g(\alpha[h]) &= f_\lambda(\alpha[g \circ h \circ g^{-1}]) \\ &= \alpha[X_\lambda(g \circ h \circ g^{-1})] = \alpha[X_\lambda(g) \circ X_\lambda(h) \circ X_\lambda(g)^{-1}] \\ &= X_\lambda(g)(\alpha[X_\lambda(h)]) = X_\lambda(g) \circ f_\lambda(\alpha[h]) \end{aligned}$$

as required.

Clearly, $f_{\lambda_0} = id.$ and $f_{\lambda}(\alpha[h]) = \alpha[X_{\lambda}(h)]$ depends holomorphically on λ , for a fixed loxodromic h . Now apply Proposition 1.

(Stronger results hold for finitely generated G , see [2]).

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References

- [1] L. Bers and H. S. Royden, Holomorphic families of injections, to appear.
- [2] D. Sullivan, Quasiconformal homeomorphisms and dynamics II. Structural stability implies hyperbolicity for Kleinian groups, *Acta Math.* 155 (1985), 243–260.

Added in proof. Hypothesis (ii) in the theorem follows easily from the others (as observed by C. McMullen).