# A note on global existence of solutions to nonlinear Klein-Gordon equations in one space dimension 

By<br>Soichiro Katayama

## 1. Introduction

We consider the Cauchy problem for nonlinear Klein-Gordon equations

$$
\begin{cases}(\square+1) u=F\left(u, u_{t}, u_{x}, u_{t x}, u_{x x}\right) & \text { in }(0, \infty) \times \mathbf{R}  \tag{1.1}\\ u(0, x)=\varepsilon f(x), \quad u_{t}(0, x)=\varepsilon g(x) & \text { for } x \in \mathbf{R}\end{cases}
$$

where $\square=\partial_{t}^{2}-\partial_{x}^{2}, u_{t}=(\partial / \partial t) u, u_{x}=(\partial / \partial x) u$, etc. We suppose that the nonlinear term $F$ is a smooth function in its arguments around the origin and satisfies

$$
\begin{equation*}
F(\lambda)=O\left(|\lambda|^{m}\right) \text { near } \lambda=0 \tag{1.2}
\end{equation*}
$$

with some integer $m \geq 2$, where $\lambda=\left(u, u_{t}, u_{x}, u_{t x}, u_{x x}\right)$. For simplicity, we assume that $f, g \in C_{0}^{\infty}(\mathbf{R}) . \quad \varepsilon$ is a small positive parameter.

There are many studies on global existence of solutions to this type of equations, and here we recall some known results briefly. For $n$-space dimensional cases with nonlinear terms of $m$ th degree as in (1.2), Klainerman-Ponce ([11]) and Shatah ([15]) showed that if $n(m-1)^{2} /(2 m)>1$, then there exists a unique global solution, provided that $\varepsilon$ is sufficiently small. This condition means that $m \geq 4$ when $n=1, m \geq 3$ when $n=2,3,4$ and $m \geq 2$ when $n \geq 5$. For the case $n=3,4$ and $m=2$, Klainerman ([9]) and Shatah ([16]) proved independently the global existence of the solution for small $\varepsilon$. Klainerman used the "method of invariant norms" to get a decay estimate of the solution, which was first found to be useful in the study of nonlinear wave equations (see [8]). On the other hand, Shatah used the method of normal forms to eliminate the quadratic parts of the nonlinear terms and got the sufficient decay estimate. When $n=2$ and $m=2$, Georgiev-Popivanov ([4]) and Kosecki ([12]) proved the global existence of the solution, assuming that the quadratic parts of the nonlinear terms satisfy certain special conditions. For general nonlinear terms with $m=2$ in two space dimensions, Simon-Taflin ([17]) and Ozawa-Tsutaya-Tsutsumi ([14]) proved the global existence for small $\varepsilon$, and showed that the solution approaches a free solution as $t \rightarrow+\infty$. In [14], they combined the methods of normal forms and of the invariant norms to get the result.

When $n=1$ and $m=3$, Yagi ([18]) showed that if $F=c_{1} F_{1}$ in (1.1), where

$$
\begin{equation*}
F_{1}=3 u u_{t}^{2}-3 u u_{x}^{2}-u^{3} \tag{1.3}
\end{equation*}
$$

and $c_{1} \in \mathbf{R}$ is a constant, then there exists a global solution for small $\varepsilon$, and that the solution approaches a free solution as $t \rightarrow+\infty$. Recently, Moriyama ([13]) proved the same result when $F$ is a homogeneous polynomial of degree 3 which can be written as $F=\sum_{i=1}^{7} c_{i} F_{i}$, where $F_{1}$ is as in (1.3),

$$
\begin{align*}
& F_{2}=3 u_{t}^{2} u_{x}-u_{x}^{3}-3 u^{2} u_{x}+6 u u_{t} u_{t x},  \tag{1.4}\\
& F_{3}=u u_{x} u_{x x}-u^{2} u_{x}+u_{t}^{2} u_{x}+2 u u_{t} u_{t x}  \tag{1.5}\\
& F_{4}=\left(u_{t}^{2}-u_{x}^{2}-u^{2}\right) u_{x x}-2 u u_{x}^{2}  \tag{1.6}\\
& F_{5}=\left(u_{t}^{2}-u_{x}^{2}-u^{2}\right) u_{t x}-2 u u_{t} u_{x}  \tag{1.7}\\
& F_{6}=u_{t}^{3}-3 u_{x}^{2} u_{t}-3 u^{2} u_{t}-6 u u_{x} u_{t x},  \tag{1.8}\\
& F_{7}=u_{t} u_{x}^{2}+u u_{t} u_{x x}+2 u u_{x} u_{t x} \tag{1.9}
\end{align*}
$$

and $c_{i} \in \mathbf{R}(i=1, \ldots, 7)$. In the proof, he used the normal forms to eliminate the cubic terms. Unfortunately, though the normal form to eliminate quadratic parts of the nonlinear terms for the nonlinear Klein-Gordon equations is always regular transformation, the transformation to eliminate cubic parts may be singular in general. He showed that the transformation is regular if and only if $F$ is a linear combination of $F_{1}, \ldots, F_{7}$ for the quasi-linear case. His proof of this fact suggests us that these nonlinear terms can be eliminated by transformation with polynomials.

In this note, we will show that $F_{1}, \ldots, F_{7}$ can be actually eliminated by simple transformation. Then, it is easy to see that this transformation is compatible with the invariant norm method of Klainerman, and so we can easily show the same result as Moriyama's also when the nonlinearity involves not only the linear combinations of $F_{1}, \ldots, F_{7}$, but also terms satisfying the strong null condition (see Georgiev [2]; see also Christodoulou [1] and Klainerman [10]) as well as terms of higher degree (especially, of degree 4). Our approach is similar to that of Kosecki [12]. Precisely we assume
(H) $F(\lambda)$ can be written as follows:

$$
F(\lambda)=\sum_{i=1}^{10} c_{i} G_{i}(\lambda)+N(\lambda)+H(\lambda)
$$

in some neighborhood of $\lambda=\left(u, u_{t}, u_{x}, u_{t,}, u_{x x}\right)=0$, where $c_{i} \in \mathbf{R}(i=1, \ldots, 10)$ and
(i) $G_{i}(1 \leq i \leq 10)$ are defined by

$$
\begin{aligned}
& G_{1}(\lambda)=u\left(-u^{2}+3 u_{t}^{2}-3 u_{x}^{2}\right), \\
& G_{2}(\lambda)=u_{t}\left(-3 u^{2}+u_{t}^{2}-u_{x}^{2}\right)+2 u\left(u_{t} u_{x x}-u_{x} u_{t x}\right), \\
& G_{3}(\lambda)=u_{x}\left(-u^{2}+u_{t}^{2}-u_{x}^{2}\right)+2 u\left(u_{t} u_{t x}-u_{x} u_{x x}\right), \\
& G_{4}(\lambda)=u^{3}-2 u^{2} u_{x x}-3 u u_{t}^{2}+2 u_{t}^{2} u_{x x}-2 u_{t} u_{x} u_{t x}-u\left(u_{t x}^{2}-u_{x x}^{2}\right), \\
& G_{5}(\lambda)=\left(-u^{2}+u_{t}^{2}-u_{x}^{2}\right) u_{t x}-2 u u_{t} u_{x}, \\
& G_{6}(\lambda)=-u u_{x}^{2}+2 u_{x}\left(u_{t} u_{t x}-u_{x} u_{x x}\right)+u\left(u_{t x}^{2}-u_{x x}^{2}\right), \\
& G_{7}(\lambda)=3 u^{2} u_{t}-6 u u_{t} u_{x x}-u_{t}^{3}-3 u_{t}\left(u_{t x}^{2}-u_{x x}^{2}\right), \\
& G_{8}(\lambda)=u^{2} u_{x}-2 u u_{t} u_{t x}-2 u u_{x} u_{x x}-u_{t}^{2} u_{x}-u_{x}\left(u_{t x}^{2}-u_{x x}^{2}\right), \\
& G_{9}(\lambda)=-2 u u_{x} u_{t x}-u_{t} u_{x}^{2}+u_{t}\left(u_{t x}^{2}-u_{x x}^{2}\right), \\
& G_{10}(\lambda)=-u_{x}^{3}+3 u_{x}\left(u_{t x}^{2}-u_{x x}^{2}\right),
\end{aligned}
$$

(ii) $N$ is of the form

$$
\begin{aligned}
N(\lambda)= & P_{1}(\lambda)\left(u_{t} u_{t x}-u_{x} u_{x x}+u u_{x}\right)+P_{2}(\lambda)\left(u_{t} u_{x x}-u_{x} u_{t x}\right) \\
& +P_{3}(\lambda)\left(u_{t x}^{2}-u_{x x}^{2}+u u_{x x}\right)
\end{aligned}
$$

with $P_{i}(\lambda)(i=1,2,3)$ which are homogeneous polynomials of degree 1 ,
(iii) $H(\lambda)$ is a smooth function of degree 4, i.e., $H(\lambda)=O\left(|\lambda|^{4}\right)$ near $\lambda=0$.

Our main result is the following:
Theorem 1.1. Suppose that $F(\lambda)$ satisfies the assumption $(\mathrm{H})$. Then, for any given integer $k \geq 15$ and any $f, g \in C_{0}^{\infty}(\mathbf{R})$, there exists a positive constant $\varepsilon_{0}$ such that for any $\varepsilon \in\left(0, \varepsilon_{0}\right]$, the Cauchy problem (1.1) admits a unique classical solution $u \in C^{\infty}([0, \infty) \times \mathbf{R})$.

Moreover, the solution $u(t, x)$ has a free profile, i.e., there exists $\left(u_{+0}(x)\right.$, $\left.u_{+1}(x)\right) \in H^{k+1}(\mathbf{R}) \times H^{k}(\mathbf{R})$ such that

$$
\begin{equation*}
\left\|\left(u-U_{+}\right)(t, \cdot)\right\|_{H^{k+1}(\mathbf{R})}+\left\|\partial_{t}\left(u-U_{+}\right)(t, \cdot)\right\|_{H^{k}(\mathbf{R})} \rightarrow 0 \text { as } t \rightarrow+\infty, \tag{1.10}
\end{equation*}
$$

where $U_{+}(t, x)$ is the solution to the Cauchy problem for the linear Klein-Gordon equation $(\square+1) v=0$ with initial data $v(0, x)=u_{+0}(x)$ and $v_{t}(0, x)=u_{+1}(x)$.

Remark 1.2. (i) $G_{i}(i=1, \ldots, 10)$ are linearly independent as polynomials with variables in $\lambda=\left(u, u_{t}, u_{x}, u_{t x}, u_{x x}\right)$. Let $\Lambda$ be the set of homogeneous polynomials of degree 3 with variables in $\lambda$, and let $\tilde{\Lambda}$ be the subset of $\Lambda$, whose elements are given by $\sum_{i=1}^{10} c_{i} G_{i}(\lambda)+N(\lambda)$, where $N$ is as in (H). Then we can show that $\operatorname{dim} \tilde{\Lambda}=21$, though $\operatorname{dim} \Lambda=35$.

If we restrict our attention to the quasi-linear case, we can verify by straightforward calculations that

$$
\operatorname{span}\left\{G_{1}, G_{2}, G_{3}, G_{4}+G_{6}, G_{5}, G_{7}+3 G_{9}, 3 G_{8}+G_{10}\right\}=\operatorname{span}\left\{F_{1}, \ldots, F_{7}\right\},
$$

where $F_{1}, \ldots, F_{7}$ are as in (1.3)-(1.9). In fact, we have $F_{1}=G_{1}, F_{2}=\left(3 G_{3}-\right.$ $\left.3 G_{8}-G_{10}\right) / 2, \quad F_{3}=\left(G_{3}-3 G_{8}-G_{10}\right) / 4, \quad F_{4}=\left(G_{1}+G_{4}+G_{6}\right) / 2, \quad F_{5}=G_{5}, \quad F_{6}=$ $\left(3 G_{2}+G_{7}+3 G_{9}\right) / 2$ and $F_{7}=\left(-G_{2}-G_{7}-3 G_{9}\right) / 4$.
(ii) If $F$ is semilinear and satisfies ( H ), the cubic part of $F$ is of the form

$$
c_{1} u\left(-u^{2}+3 u_{t}^{2}-3 u_{x}^{2}\right)+\left(c_{2} u_{t}+c_{3} u_{x}\right)\left(-3 u^{2}+u_{t}^{2}-u_{x}^{2}\right)
$$

with constants $c_{i} \in \mathbf{R}(i=1,2,3)$.
(iii) Recently, Yordanov ([19]) proved that if $\int_{-\infty}^{\infty} f_{x}(x) g(x) d x>0$, then (1.1) with $F=u_{t}^{2} u_{x}+a u^{3} \quad(a=$ const) has no global (classical) solution for any $\varepsilon>0$. His proof is also valid for (1.1) with

$$
F=u_{t}^{2} u_{x}+H_{1}(u)+H_{2}\left(u_{x}\right) u_{x x}+H_{3}\left(u, u_{t}, u_{x}, u_{t x}, u_{x x}\right) u_{x},
$$

where $H_{1}=O\left(|u|^{2}\right), H_{2}=O\left(\left|u_{x}\right|\right), H_{3}=O\left(|u|^{2}+\left|u_{t}\right|^{2}+\left|u_{x}\right|^{2}+\left|u_{t x}\right|^{2}+\left|u_{x x}\right|^{2}\right)$ and $H_{3} \geq 0$. Especially, we can see that for some $f$ and $g$, (1.1) has no global solution if $F$ is of the form $F=u_{t}^{2} u_{x}+b u^{2} u_{x}+c u_{x}^{3}$ with non-negative constants $b$ and $c$, while there always exists a global solution for small data when $b=-3$ and $c=-1$, according to (ii).

## 2. Transformation with polynomials and some preliminaries

First, we will find some transformation to cancel $\sum_{i=1}^{10} c_{i} G_{i}(\lambda)$. For that purpose, let $\phi\left(u, u_{t}, u_{x}\right)$ be a homogeneous polynomial of degree 3 in its arguments and suppose that $u$ satisfies $(\square+1) u=F$. Then, simple calculations give us

$$
\begin{align*}
(\square+1 & ) \phi\left(u, u_{t}, u_{x}\right)  \tag{2.1}\\
= & \phi+\phi_{u} \square u+\phi_{u_{t}} \square u_{t}+\phi_{u_{x}} \square u_{x}+\phi_{u, u}\left(u_{t}^{2}-u_{x}^{2}\right) \\
& +2 \phi_{u_{,} u_{t}}\left(u_{t} u_{t t}-u_{x} u_{t x}\right)+2 \phi_{u, u_{x}}\left(u_{t} u_{t x}-u_{x} u_{x x}\right) \\
& +\phi_{u_{t}, u_{t}}\left(u_{t t}^{2}-u_{t x}^{2}\right)+2 \phi_{u_{t}, u_{x}}\left(u_{t t} u_{t x}-u_{t x} u_{x x}\right)+\phi_{u_{x}, u_{x}}\left(u_{t x}^{2}-u_{x x}^{2}\right) .
\end{align*}
$$

Substituting the relation $u_{t t}=u_{x x}-u+F$ into (2.1), we get

$$
\begin{align*}
(\square+1) & \phi\left(u, u_{t}, u_{x}\right)  \tag{2.2}\\
= & \phi-\phi_{u} u-\phi_{u_{t}} u_{t}-\phi_{u_{x}} u_{x} \\
& +\phi_{u, u}\left(u_{t}^{2}-u_{x}^{2}\right)+2 \phi_{u, u_{t}}\left(u_{t} u_{x x}-u u_{t}-u_{x} u_{t x}\right) \\
& +2 \phi_{u_{,}, u_{x}}\left(u_{t} u_{t x}-u_{x} u_{x x}\right)+\phi_{u_{t}, u_{t}}\left(u_{x x}^{2}+u^{2}-2 u u_{x x}-u_{t x}^{2}\right) \\
& +2 \phi_{u_{t}, u_{x}}\left(-u u_{t x}\right)+\phi_{u_{x}, u_{x}}\left(u_{t x}^{2}-u_{x x}^{2}\right)+R,
\end{align*}
$$

where

$$
\begin{align*}
R= & \phi_{u} F+\phi_{u_{t}} F_{t}+\phi_{u_{\mathrm{x}}} F_{x}+2 \phi_{u, u_{t}} u_{t} F  \tag{2.3}\\
& +\phi_{u_{t}, u_{t}}\left(F^{2}+2 u_{x x} F-2 u F\right)+2 \phi_{u_{t}, u_{x}} u_{t x} F .
\end{align*}
$$

Here we remark that when $F=F(\lambda), \lambda=\left(u, u_{t}, u_{x}, u_{t x}, u_{x x}\right)$ and $F=O\left(|\lambda|^{3}\right)$ near $\lambda=0$, then $R$ can be regarded as a function of

$$
\tilde{\lambda}=\left(u, u_{t}, u_{x}, u_{t x}, u_{x x}, u_{t x x}, u_{x x x}\right)
$$

and $R(\tilde{\lambda})=O\left(|\tilde{\lambda}|^{5}\right)$ near $\tilde{\lambda}=0$. Since we have assumed that $\phi$ is a homogeneous polynomial of degree $3, \phi$ can be represented as follows:

$$
\begin{align*}
\phi= & b_{1} u^{3}+b_{2} u^{2} u_{t}+b_{3} u^{2} u_{x}+b_{4} u u_{t}^{2}+b_{5} u u_{t} u_{x}  \tag{2.4}\\
& +b_{6} u u_{x}^{2}+b_{7} u_{t}^{3}+b_{8} u_{t}^{2} u_{x}+b_{9} u_{t} u_{x}^{2}+b_{10} u_{x}^{3}
\end{align*}
$$

with constants $b_{i}(i=1, \ldots, 10)$. Substituting (2.4) into (2.2), we get

$$
\begin{equation*}
(\square+1) \phi-R=2 \sum_{i=1}^{10} b_{i} G_{i} \tag{2.5}
\end{equation*}
$$

When $F$ satisfies (H), choose $b_{i}=c_{i} / 2$ for $i=1, \ldots, 10$ and we obtain

$$
\begin{equation*}
(\square+1)(u-\phi)=N(\lambda)+H(\lambda)-R(\tilde{\lambda}) . \tag{2.6}
\end{equation*}
$$

The cubic part in the right-hand side of (2.6) is $N(\lambda)$, but we can expect an extra decay with respect to time from $N(\lambda)$, because it satisfies the strong null condition. To explain this, following Klainerman [9], we introduce

$$
\begin{equation*}
Z_{1}=t \partial_{x}+x \partial_{t}, \quad Z_{2}=\partial_{t}, \quad Z_{3}=\partial_{x} . \tag{2.7}
\end{equation*}
$$

With multi-index $\alpha=\left(\alpha_{1}, \alpha_{2}, \alpha_{3}\right)$, we write $Z^{\alpha}=Z_{1}^{\alpha_{1}} Z_{2}^{\alpha_{2}} Z_{3}^{\alpha_{3}}$. One can easily check that $\left[\square+1, Z_{i}\right]=0$ holds for $i=1,2,3$.

For any sufficiently smooth function $v(t, x)$ and non-negative integer $k$, we define

$$
\begin{equation*}
|v(t, x)|_{k}=\sum_{|x| \leq k}\left|Z^{\alpha} v(t, x)\right| \tag{2.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\|v(t)\|_{k, p}=\|v(t, \cdot)\|_{k, p}=\left\||v(t, \cdot)|_{k}\right\|_{L^{p}(\mathbf{R})} \quad \text { for } 1 \leq p \leq+\infty . \tag{2.9}
\end{equation*}
$$

Let $u$ be a solution to $(\square+1) u=F$. Then we get

$$
\begin{align*}
u_{t} u_{t x}-u_{x} u_{x x}+u u_{x} & =u_{t} u_{t x}-u_{x} u_{t t}+u_{x} F=Q\left(u, u_{t}\right)+u_{x} F,  \tag{2.10}\\
u_{t} u_{x x}-u_{x} u_{t x} & =Q\left(u, u_{x}\right),  \tag{2.11}\\
u_{t x}^{2}-u_{x x}^{2}+u u_{x x} & =u_{t x}^{2}-u_{t} u_{x x}+u_{x x} F=Q\left(u_{x}, u_{t}\right)+u_{x x} F, \tag{2.12}
\end{align*}
$$

where $Q(U, V)=U_{t} V_{x}-U_{x} V_{t}$. Using $Z_{1}$, we can write

$$
Q(U, V)=\frac{1}{t}\left(U_{t}\left(Z_{1} V\right)-\left(Z_{1} U\right) V_{t}\right), \quad t \neq 0
$$

and we also have

$$
Z^{\alpha} Q(U, V)=\sum_{|\beta|+|\gamma|=|x|} C_{\beta, \gamma}^{\alpha} Q\left(Z^{\beta} U, Z^{\gamma} V\right),
$$

where $C_{\beta, \gamma}^{\alpha}$ are appropriate constants. Therefore we obtain (see Georgiev [2], Klainerman [10] and also Katayama [6], [7]):

Lemma 2.1. Suppose that $u$ satisfies $(\square+1) u=F$ and that $F(\lambda)=O\left(|\lambda|^{3}\right)$ near $\lambda=0$. Let $k(\geq 0)$ be an integer, and let $N(\lambda)$ be as in (ii) of $(H)$. If $|u(t, x)|_{[k / 2]+2} \leq 1$, then we have

$$
\begin{align*}
|N(\lambda)(t, x)|_{k} \leq & C_{k}\left\{(1+t)^{-1}|u(t, x)|_{\mid k / 2]+2}^{2}\left(|u(t, x)|_{k+1}+\left|u^{\prime}(t, x)\right|_{k+1}\right)\right.  \tag{2.13}\\
& \left.+|u(t, x)|_{\mid k / 2]+2}^{3}\left(|u(t, x)|_{k}+\left|u^{\prime}(t, x)\right|_{k+1}\right)\right\},
\end{align*}
$$

where $u^{\prime}=\left(u_{t}, u_{x}\right),[m]$ denotes the largest integer which does not exceed $m$, and $C_{k}$ is a positive constant depending on $k$.

Here we remark that the left-hand sides of (2.10) and (2.12) are concerned with the unit condition introduced by Kosecki ([12]).

We conclude this section with the following decay estimate due to Hörmander [5] (see also Georgiev [3]):

Lemma 2.2. Let $u$ be a solution to $(\square+1) u=F$ in $(0, \infty) \times \mathbf{R}$ with initial data 0 . Suppose that $\operatorname{supp} F(t, \cdot) \subset\{|x| \leq t+\rho\}$ for any $t \geq 0$ with some positive constant $\rho$. Then we have

$$
\begin{equation*}
(1+t+|x|)^{1 / 2}|u(t, x)| \leq C \sum_{j=0}^{\infty} \sum_{|\alpha| \leq 3} \sup _{s \in[0, t] \cap I_{j}}(1+s)\left\|Z^{\alpha} F(s, \cdot)\right\|_{L^{2}(\mathbf{R})}, \tag{2.14}
\end{equation*}
$$

where $I_{0}=[0,2], I_{j}=\left[2^{j-1}, 2^{j+1}\right](j \geq 1)$ and $C$ is a positive constant.

## 3. Proof of Theorem 1.1

Now we are ready to state the proof of Theorem 1.1. Because we have the local existence theorem, what we have to do is to get some a priori estimates. Let $u(t, x)$ be a solution to (1.1) for $0 \leq t<T$ with $F$ satisfying (H). We define

$$
\begin{align*}
E_{k}(T ; u)= & \sup _{0 \leq 1<T}\left\{\sup _{x \in \mathbf{R}}\left((1+t+|x|)^{1 / 2}|u(t, x)|_{|k / 2|+3}\right)+\|u(t, \cdot)\|_{k, 2}\right.  \tag{3.1}\\
& \left.+\left\|u^{\prime}(t, \cdot)\right\|_{k, 2}+(1+t)^{-\mu}\left(\|u(t, \cdot)\|_{k+2,2}+\left\|u^{\prime}(t, \cdot)\right\|_{k+2,2}\right)\right\}
\end{align*}
$$

where $u^{\prime}=\left(u_{t}, u_{x}\right), 0<\mu<1 / 2$ and $k$ is an integer $\geq 15$. In order to get the global existence, it suffices to prove

Proposition 3.1. For any $\varepsilon(\leq 1)$ and $M(\leq 1), E_{k}(T ; u) \leq M$ implies

$$
E_{k}(T ; u) \leq C_{k}\left(\varepsilon+M^{3}\right),
$$

where $C_{k}$ is a positive constant depending on $k$, but independent of $T>0, M(\leq 1)$ and $\varepsilon(\leq 1)$.

Once we get this proposition, if we choose sufficiently small $M$ and $\varepsilon_{0}$ to satisfy

$$
C_{k} M^{2} \leq \frac{1}{4}, \quad C_{k} \varepsilon_{0} \leq \frac{M}{4} \quad \text { and } \quad E_{k}(0 ; u)<M,
$$

it follows that $E_{k}(T ; u) \leq M$ implies $E_{k}(T ; u) \leq M / 2$ for any $\varepsilon \leq \varepsilon_{0}$. Then, by the continuity arguments, we can show that $E_{k}(t ; u) \leq M$ holds as long as the solution $u(t, x)$ exists, provided that $\varepsilon \leq \varepsilon_{0}$. The global existence of the solution follows immediately from this a priori estimate and the local existence theorem.

Proof of Proposition 3.1. We assume that $E_{k}(T ; u) \leq M$. From (2.6) we have

$$
\begin{equation*}
(\square+1) Z^{\alpha}(u-\phi)=Z^{\alpha}(N(\lambda)+H(\lambda)-R(\tilde{\lambda})) \tag{3.2}
\end{equation*}
$$

for $0 \leq t<T$ and for any multi-index $\alpha$, where $\phi$ and $R$ are as in (2.4) with $b_{i}=c_{i} / 2$ and in (2.3) respectively. In the following we write $C_{k}$ for various constants which are independent of $T, M$ and $\varepsilon$, but may change line by line.

Let $\alpha$ be a multi-index with $|\alpha| \leq[k / 2]+3$. Applying Lemma 2.2 to (3.2), we get

$$
\begin{align*}
(1+t+ & |x|)^{1 / 2}|(u-\phi)(t, x)|_{[k / 2]+3}  \tag{3.3}\\
& \leq C_{k} \varepsilon+C_{k} \sum_{j=0}^{\infty} \sum_{\beta \leq[k / 2]+6} \sup _{s \in[0, t] \cap I_{j}}(1+s)\left\{\left\|Z^{\beta} N(\lambda)(s, \cdot)\right\|_{L^{2}}\right. \\
& \left.+\left\|Z^{\beta} H(\lambda)(s, \cdot)\right\|_{L^{2}}+\left\|Z^{\beta} R(\tilde{\lambda})(s, \cdot)\right\|_{L^{2}}\right\} .
\end{align*}
$$

Observing that $H(\lambda)=O\left(|\lambda|^{4}\right)$, by Lemma 2.1 and the assumption we get

$$
\begin{align*}
& \left\|Z^{\beta} N(\lambda)(s, \cdot)\right\|_{L^{2}}+\left\|Z^{\beta} H(\lambda)(s, \cdot)\right\|_{L^{2}}  \tag{3.4}\\
& \leq \\
& \quad C_{k}\left\{(1+s)^{-1}\|u(s)\|_{[([k / 2]+6) / 2]+2, \infty}^{2}\left(\|u(s)\|_{[k / 2]+7,2}+\left\|u^{\prime}(s)\right\|_{[k / 2]+7,2}\right)\right. \\
& \left.\quad+\|u(s)\|_{[([k / 2]+6) / 2]+2, \infty}^{3}\left(\|u(s)\|_{[k / 2]+6,2}+\left\|u^{\prime}(s)\right\|_{[k / 2]+7,2}\right)\right\} \\
& \leq \\
& C_{k}(1+s)^{-3 / 2} M^{3} \quad \text { for }|\beta| \leq[k / 2]+6 \text { and } 0 \leq s<T .
\end{align*}
$$

Here we used $\left[\frac{[k / 2]+6}{2}\right]+2 \leq[k / 2]+3,[k / 2]+7 \leq k$ for $k \geq 13$. Since $R(\tilde{\lambda})=$
$O\left(|\tilde{\lambda}|^{5}\right)$, we have

$$
\begin{align*}
\left\|Z^{\beta} R(\tilde{\lambda})\right\|_{L^{2}} & \leq C_{k}\|u(s)\|_{[([k / 2]+6) / 2]+3, \infty}^{4}\left(\|u(s)\|_{[k / 2]+6,2}+\left\|u^{\prime}(s)\right\|_{[k / 2]+8,2}\right)  \tag{3.5}\\
& \leq C_{k}(1+s)^{-2} M^{5} \quad \text { for }|\beta| \leq[k / 2]+6 \quad \text { and } \quad 0 \leq s<T
\end{align*}
$$

because $\left[\frac{[k / 2]+6}{2}\right]+3 \leq[k / 2]+3$ and $[k / 2]+8 \leq k$ hold for $k \geq 15$. Summing up, we obtain

$$
\begin{align*}
(1+t & +|x|)^{1 / 2}|(u-\phi)(t, x)|_{[k / 2]+3}  \tag{3.6}\\
& \leq C_{k}\left(\varepsilon+\sum_{j=0}^{\infty} \sup _{s \in[0, T] \cap I_{j}}(1+s)^{-1 / 2} M^{3}\right) \\
& \leq C_{k}\left(\varepsilon+M^{3}\left(1+\sum_{j=1}^{\infty}\left(1+2^{j-1}\right)^{-1 / 2}\right)\right) \\
& \leq C_{k}\left(\varepsilon+M^{3}\right) \quad \text { for } 0 \leq t<T
\end{align*}
$$

Next, let $|\alpha| \leq k$ in (3.2). Applying the energy estimate for $(\square+1)$, we obtain

$$
\begin{align*}
& \|(u-\phi)(t, \cdot)\|_{k, 2}+\left\|(u-\phi)^{\prime}(t, \cdot)\right\|_{k, 2}  \tag{3.7}\\
& \quad \leq C_{k}\left\{\varepsilon+\int_{0}^{t}\left(\|N(\lambda)\|_{k, 2}+\|H(\lambda)\|_{k, 2}+\|R(\tilde{\lambda})\|_{k, 2}\right)(s, \cdot) d s\right\} .
\end{align*}
$$

Again from Lemma 2.1, we have

$$
\begin{align*}
& \|N(\lambda)(s)\|_{k, 2}+\|H(\lambda)(s)\|_{k, 2}  \tag{3.8}\\
& \leq C_{k}(1+s)^{-1}\|u(s)\|_{[k / 2]+2, \infty}^{2}\left(\|u(s)\|_{k+1,2}+\left\|u^{\prime}(s)\right\|_{k+1,2}\right) \\
& +C_{k}\|u(s)\|_{[k / 2]+2, \infty}^{3}\left(\|u(s)\|_{k, 2}+\left\|u^{\prime}(s)\right\|_{k+1,2}\right) \\
& \leq C_{k}(1+s)^{\mu-3 / 2} M^{3} \quad \text { for } 0 \leq s<T .
\end{align*}
$$

Since $R(\tilde{\lambda})=O\left(|\tilde{\lambda}|^{5}\right)$, Hölder's inequality gives us

$$
\begin{align*}
\|R(\tilde{\lambda})\|_{k, 2} & \leq C_{k}\|u(s)\|_{[k / 2]+3, \infty}^{4}\left(\|u(s)\|_{k, 2}+\left\|u^{\prime}(s)\right\|_{k+2,2}\right)  \tag{3.9}\\
& \leq C_{k}(1+s)^{\mu-2} M^{5} \quad \text { for } 0 \leq s<T
\end{align*}
$$

From (3.7)-(3.9) we obtain

$$
\begin{align*}
\|(u-\phi)(t)\|_{k, 2}+\left\|(u-\phi)^{\prime}(t)\right\|_{k, 2} & \leq C_{k}\left(\varepsilon+M^{3} \int_{0}^{t}(1+s)^{\mu-3 / 2} d s\right)  \tag{3.10}\\
& \leq C_{k}\left(\varepsilon+M^{3} \int_{0}^{\infty}(1+s)^{\mu-3 / 2} d s\right) \\
& \leq C_{k}\left(\varepsilon+M^{3}\right) \quad \text { for } 0 \leq t<T
\end{align*}
$$

since $\mu-3 / 2<-1$.
Finally, let $|\alpha| \leq k+2$. From (1.1), we have

$$
\begin{align*}
& (\square+1) Z^{\alpha} u-\frac{\partial F}{\partial u_{t x}} \partial_{t} \partial_{x} Z^{\alpha} u-\frac{\partial F}{\partial u_{x x}} \partial_{x}^{2} Z^{\alpha} u  \tag{3.11}\\
& \quad=Z^{\alpha} F-\frac{\partial F}{\partial u_{t x}} \partial_{t} \partial_{x} Z^{\alpha} u-\frac{\partial F}{\partial u_{x x}} \partial_{x}^{2} Z^{\alpha} u
\end{align*}
$$

From the commutative properties of $\partial_{t}, \partial_{x}$ and $Z_{i}(i=1,2,3)$, we can estimate the $L^{2}$-norm of the right-hand side of (3.11) by

$$
C_{k}\|u(t, \cdot)\|_{[(k+2) / 2]+2, \infty}^{2}\left(\|u(t, \cdot)\|_{k+2,2}+\left\|u^{\prime}(t, \cdot)\right\|_{k+2,2}\right) .
$$

Because $\left[\frac{k+2}{2}\right]+2 \leq[k / 2]+3$, this is bounded by $C_{k}(1+t)^{\mu-1} M^{3}$ for $0 \leq t<$ $T$. Therefore, applying the energy inequality for the equation of the form

$$
(\square+1) v-\gamma_{1}(t, x) \partial_{t} \partial_{x} v-\gamma_{2}(t, x) \partial_{x}^{2} v=\psi(t, x)
$$

to (3.11) with $v=Z^{\alpha} u$, we obtain

$$
\begin{align*}
\|u(t, \cdot)\|_{k+2,2}+\left\|u^{\prime}(t, \cdot)\right\|_{k+2,2} & \leq C_{k}\left(\varepsilon+M^{3} \int_{0}^{t}(1+s)^{\mu-1} d s\right)  \tag{3.12}\\
& \leq C_{k}(1+t)^{\mu}\left(\varepsilon+\frac{M^{3}}{\mu}\right)
\end{align*}
$$

for $0 \leq t<T$.
Now, since $|\phi|=O\left(|u|^{3}+\left|u^{\prime}\right|^{3}\right)$, Hölder's inequality and Sobolev's embedding theorem imply that

$$
\begin{align*}
|\phi(t, x)|_{[k / 2]+3} & \leq C_{k}|u(t, x)|_{[([k / 2]+3) / 2]+1}^{2}|u(t, x)|_{[k / 2]+4}  \tag{3.13}\\
& \leq C_{k}\|u(t, \cdot)\|_{[k / 2]+3, \infty}^{2}\|u(t, \cdot)\|_{[k / 2]+5,2} \\
& \leq C_{k}(1+t)^{-1} M^{3} \quad \text { for } 0 \leq t<T,
\end{align*}
$$

and

$$
\begin{align*}
\|\phi(t)\|_{k, 2}+\left\|\phi^{\prime}(t)\right\|_{k, 2} & \leq C_{k}\|u(t)\|_{[[k / 2]+2, \infty}^{2}\left(\|u(t)\|_{k, 2}+\left\|u^{\prime}(t)\right\|_{k+1,2}\right)  \tag{3.14}\\
& \leq C_{k} M^{3}(1+t)^{\mu-1} \leq C_{k} M^{3} \quad \text { for } 0 \leq t<T .
\end{align*}
$$

Therefore from (3.6), (3.10), (3.12), (3.13) and (3.14), we obtain

$$
\begin{equation*}
E_{k}(T ; u) \leq C_{k}\left(\varepsilon+M^{3}\right) \tag{3.15}
\end{equation*}
$$

This completes the proof of Proposition 3.1.
Now we prove the existence of a free profile. Since the solution $u(t, x)$ satisfies $E_{k}(\infty ; u) \leq M$, we can show as in the proof of Proposition 3.1 that

$$
(\square+1)(u-\phi)=N(\lambda)+H(\lambda)-R(\tilde{\lambda})
$$

and

$$
\begin{equation*}
\|(N(\lambda)+H(\lambda)-R(\tilde{\lambda}))(t, \cdot)\|_{H^{k}(\mathbf{R})} \in L^{1}(0, \infty) . \tag{3.16}
\end{equation*}
$$

Therefore, there exists $\left(u_{+0}(x), u_{+1}(x)\right) \in H^{k+1}(\mathbf{R}) \times H^{k}(\mathbf{R})$ such that

$$
\left\|\left((u-\phi)-U_{+}\right)(t, \cdot)\right\|_{H^{k+1}}+\left\|\partial_{t}\left((u-\phi)-U_{+}\right)(t, \cdot)\right\|_{H^{k}} \rightarrow 0
$$

at $t \rightarrow+\infty$, where $U_{+}(t, x)$ is as in Theorem 1.1. Since we can see from (3.14) that

$$
\|\phi(\tilde{\lambda})(t, \cdot)\|_{H^{k+1}}+\left\|\partial_{t}(\phi(\tilde{\lambda}))(t, \cdot)\right\|_{H^{k}} \leq C_{k} M^{3}(1+t)^{\mu-1} \rightarrow 0
$$

as $t \rightarrow+\infty$, we obtain

$$
\left\|\left(u-U_{+}\right)(t, \cdot)\right\|_{H^{k+1}}+\left\|\partial_{t}\left(u-U_{+}\right)(t, \cdot)\right\|_{H^{k}} \rightarrow 0
$$

as $t \rightarrow+\infty$. This completes the proof of Theorem 1.1.

Acknowledgements. The author would like to express his sincere gratitude to Professors Y. Ohya and S. Tarama for their helpful suggestions and constant encouragement.

## Department of Mathematics Wakayama University

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