Perturbations of *M*-accretive operators and quasi-linear evolution equations

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1. Introduction.

Let X be a complex Banach space and let A be an *m*-accretive operator with domain $D(A) \subseteq X$ and range $R(A) \subseteq X$. Then a rather common problem in nonlinear perturbation theory is the following: given an accretive operator $B: D(B) \rightarrow X(D(B) \subseteq D(A))$, what additional assumptions on B ensure the *m*accretiveness of A+B? This problem can be rephrased as follows: let U(v)u $=Au+Bv, (u, v) \in D(A) \times D(A)$. Assume that U is *m*-accretive in u and accretive in v. What additional assumptions on U w.r.t. v ensure the *m*-accretiveness of the operator $U_1: u \rightarrow U(u)u$? Our main purpose here is to present such a result for operators U(v)u which are not necessarily equal to the sum of two operators A and B as above. This result will be shown after we establish the existence of solutions to quasi-linear problems of the form

(I)
$$x'(t)+U(x(t))x(t)=0, \quad x(0)=x_0, \quad t\in[0,\infty).$$

The method here employs the contraction principle on an operator T associated with the equation

$$(II)_u x'(t) + U(u(t))x(t) = 0, x(0) = x_0, t \in [0, T],$$

where u is taken from a suitable family of continuous functions. This operator T maps u(t) into the unique solution $x_u(t), t \in [0, T]$ of $(II)_u$ which is assumed to exist by known results. In case U(v)u is linear in u, the problem $(II)_u$ is linear, and this is why problems like (I) are called "quasi-linear".

Quasi-linear problems for ordinary differential equations go at least as far back as Corduneanu [1]. The reader is also referred to the papers of Lasota and Opial [11], Opial [15], Avramescu [2], Kartsatos [4-6] and Kartsatos and Ward [7] for some further results. For quasi-linear problems concerning partial differential equations, the reader is referred to Kato [10], Ward [16] and the references therein. Ward employed in [16] the Schauder-Tychonov theorem for a suitable space of functions associated with the weak topology of X.

The second purpose of this paper is to obtain solutions in a Banach function space of

(**)
$$x' + A(t)x = G(t, x), \quad t \in [0, +\infty)$$

where A(t) is now linear and *m*-accretive. This result extends in a certain direction the applicability of Theorem 2.2 of Massera and Schäffer [13, p. 292]. These authors assumed that A(t) is a bounded linear operator, excluding thus large classes of linear partial differential operators.

2. Preliminaries.

In what follows, X will be a complex Banach space with uniformly convex dual X^* . By F we denote the duality map of X, i.e., for each $x \in X$, F(x) is the unique functional in X^* with $\langle x, F(x) \rangle = ||x||^2 = ||F(x)||^2$. Here $\langle x, f \rangle$ denotes the value of $f \in X^*$ at x and $|| \cdot ||$ is the norm in X or X^* . This map F is well defined and uniformly continuous on bounded subsets of X (cf. Kato [8]). An operator $A: D(A) \rightarrow X$ with (domain) $D(A) \subseteq X$ is said to be "accretive" if

$$\operatorname{Re}\langle Ax - Ay, F(x-y) \rangle \geq 0 \quad \text{for every} \quad x, y \in D(A).$$

An accretive operator A is said to be "m-accretive" if the range $R(I+\lambda A)=X$ for every $\lambda>0$. Here I is the identity operator. Now consider the Cauchy problem

(2.1)
$$x' + A(t)x = 0$$
, $x(0) = x_0$, $t \in [0, T]$,

where T is a positive constant and $x_0 \in D(A(0)) = D(A(t))$, $t \in [0, T]$. By a "strong solution" of (2.1) we mean a function x(t), $t \in [0, T]$ which is strongly continuous on [0, T], strongly differentiable a.e., and satisfies (2.1) a.e.

3. Main results.

We shall first establish a theorem concerning the existence of a unique strong solution of the problem

(I)
$$x'(t) + A(t, x(t))x(t) = 0, \quad x(0) = x_0,$$

where A(t, u)v is Lipschitzian in t, u and *m*-accretive in v.

THEOREM 3.1. Let (I) satisfy the following:

(i) the domain of the operator $U(t, \cdot, \cdot)$ with U(t, u, v) = A(t, u)v is the set $\overline{D} \times D$, $D \subseteq X$ for every $t \in [0, T)$, and the range $R(U(t, \cdot, \cdot)) \subseteq X$. Moreover, $x_0 \in D$,

(ii) for every $(t, u) \in [0, T) \times \overline{D}$, A(t, u)v is m-accretive in v,

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(iii)
$$||A(t, u_1)v - A(s, u_2)v||$$

 $\leq r(||u_1||, ||u_2||, ||v||)[|t - s|(1 + ||A(s, u_2)v||) + ||u_1 - u_2||]$

for every $t, s \in [0, T), u_1, u_2, v \in \overline{D}$. Here $r: R_+^3 \to R_+ = [0, +\infty)$ is increasing in all three variables. Then there exists $T_1 < T$ such that (I) has a unique strong solution $x(t), t \in [0, T_1]$ which is also uniformly Lipschitz continuous on $[0, T_1]$.

PROOF. Let $M=1+||A(0, x_0)x_0||$ and L be a positive constant with L/M < T. Let $0 < T_1 \le L/M$. Consider the set $S = \{u : [0, T_1] \to X; u(0) = x_0, u(t) \in \overline{D}, t \in [0, T_1], ||u(t)-u(t')|| \le M|t-t'|, t, t' \in [0, T_1]\}$. Then for every $u \in S$ we have $||u(t)-x_0|| \le Mt \le MT_1 \le L$. Moreover, $S \neq \emptyset$ because $u(t) \equiv x_0 \in S$. Now let $u \in S$ and consider the problem

(I)_u
$$x'(t) + A(t, u(t))x(t) = 0, \quad x(0) = x_0, \quad t \in [0, T_1].$$

This problem has a unique strong solution $x_u(t)$ because the operator $B_u(t)v \equiv A(t, u(t))v$ satisfies all the assumptions of Theorem 1 in [8]. Actually, this solution $x_u(t)$ is also weakly continuously differentiable on $[0, T_1]$ and such that A(t, u(t))x(t) is weakly continuous in t. Furthermore, x(t) satisfies $(I)_u$ everywhere if x'(t) denotes now the weak derivative of x(t). We are planning to show that the operator $T: u \rightarrow x_u$ is a contraction mapping on S if T_1 is chosen small enough. To this end, fix $u \in S$ and consider the approximating equations

$$(3.1)_n x'_n + A_n(t)x_n = 0, x_n(0) = x_0.$$

Here $A_n(t)=A_n(t, u(t))\equiv A(t, u(t))[I+(1/n)A(t, u(t))]^{-1}$, $n=1, 2, \cdots$, are defined and Lipschitz-continuous on X with Lipschitz constants not exceeding 2n. Moreover, the operators $J_n(t)\equiv [I+(1/n)A(t, u(t))]^{-1}$: $X \rightarrow D$ are also Lipschitzcontinuous on X with Lipschitz constants not exceeding 1. Each one of the equations $(3.1)_n$ has a unique strongly continuously differentiable solution $x_n(t)$ defined on $[0, T_1]$, and such that $\lim_{n \to \infty} x_n(t)=x_u(t)$ strongly and uniformly w.r.t. t on $[0, T_1]$ (cf. Kato [8]). We are planning to show that the sequence $\{x_n(t)\}, n=1, 2, \cdots$, is uniformly bounded on $[0, T_1]$ independently of $u \in S$, and that $\{x_n(t)\}$ is also uniformly Lipschitz-continuous on $[0, T_1]$ independently of $u \in S$. To this end, let us first note that the following inequality holds as in Kato [8, Lemma 4.1]:

$$\|A_n(t, u(t))v - A_n(s, u(s))v\|$$

$$\leq r(\|u(t)\|, \|u(s)\|, \|v\|) |t-s|(1+M+\|v\|+2\|A_n(s, u(s))v\|)$$

for any $t, s \in [0, T_1]$, $v \in D$. Now we have

(3.1)
$$(d/dt) \|x_n(t) - x_0\|^2 = 2 \operatorname{Re} \langle x'_n(t), F(x_n(t) - x_0) \rangle$$
$$= -2 \operatorname{Re} \langle A_n(t, u(t)) x_n(t) - A_n(t, u(t)) x_0, F(x_n(t) - x_0) \rangle$$

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$$\begin{aligned} -2 \operatorname{Re} \langle A_n(t, u(t)) x_0, F(x_n(t) - x_0) \rangle \\ &\leq 2 \|A_n(t, u(t)) x_0\| \|x_n(t) - x_0\| \\ &\leq 2 [\|A_n(0, x_0) x_0\| + r(\|u(t)\|, \|x_0\|, \|x_0\|) \cdot \\ & [(1 + M + \|x_0\| + 2\|A_n(0, x_0)\|)T_1 + \|u(t) - x_0\|]] \|x_n(t) - x_0\| \\ &\leq 2 [\|A_n(0, x_0) x_0\| + r(\|x_0\| + L, \|x_0\|, \|x_0\|) \cdot \\ & [(1 + \|x_0\| + M + 2\|A_n(0, x_0) x_0\|)(L/M) + L]] \|x_n(t) - x_0\|. \end{aligned}$$

This inequality holds almost everywhere in [0, T_1]. Dividing by $2||x_n(t)-x_0||$ and integrating from 0 to $t \leq T_1$ we obtain

(3.2)
$$\|x_{n}(t) - x_{0}\| \leq [\|A_{n}(0, x_{0})x_{0}\| + r(\|x_{0}\| + L, \|x_{0}\|, \|x_{0}\|) \cdot (1 + M + \|x_{0}\| + 2\|A_{n}(0, x_{0})x_{0}\|)(L/M) + L)]T_{1} = K_{1}T_{1}$$

where the constant $K_1 > 0$ is independent of T_1 , $u \in S$, but depends on n. In order to find an upper bound for the derivative $x'_n(t)$, consider first the function $z_n(t) \equiv x_n(t+h) - x_n(t)$, $0 \leq t$, $t+h < T_1$. Then we have

$$(3.3) \qquad (1/2)(d/dt) \|z_n(t)\|^2 = \operatorname{Re} \langle z'_n(t), F(z_n(t)) \rangle \\ = -\operatorname{Re} \langle A_n(t+h, u(t+h))x_n(t+h) \\ -A_n(t, u(t))x_n(t), F(z_n(t)) \rangle \\ = -\operatorname{Re} \langle A_n(t+h, u(t+h))x_n(t+h) \\ -A_n(t+h, u(t+h))x_n(t), F(z_n(t)) \rangle \\ -\operatorname{Re} \langle A_n(t+h, u(t+h))x_n(t) - A_n(t, u(t))x_n(t), F(z_n(t)) \rangle \\ \leq r(\|u(t+h)\|, \|u(t)\|, \|x_n(t)\|) [(1+M+\|x_n(t)\| \\ +2\|A_n(t, u(t))x_n(t)\|)|h| + \|u(t+h) - u(t)\|] \|z_n(t)\| \\ \leq r(\|x_0\| + L, \|x_0\| + L, \|x_0\| + K_1T_1) . \\ [(1+\|x'_n(t)\| + 2M + \|x_0\| + K_1T_1)] \|z_n(t)\| |h|. \end{cases}$$

Dividing above by $||z_n(t)|| |h|$ and integrating we obtain, after passage to the limit for $h \rightarrow 0$,

 $(3.4) ||x'_n(t)|| \le ||x'_n(0)||$

+
$$\int_{0}^{t} r(||x_{0}||+L, ||x_{0}||+L, ||x_{0}||+K_{1}T_{1}) \cdot ||x_{n}'(s)|| ds$$

+ $r(||x_{0}||+L, ||x_{0}||+L, ||x_{0}||+K_{1}T_{1})(1+2M+||x_{0}||+K_{1}T_{1})T_{1}.$

Thus, by Gronwall's inequality, we have

(3.5)
$$||x_n'(t)|| \leq [K_2 T_1 + ||A_n(0, x_0) x_0|]] e^{K_2 T_1},$$

where K_2 is independent of T_1 , $u \in S$. Now since $||A_n(0, x_0)x_0|| \leq ||A(0, x_0)x_0||$ (cf. Kato [8]), we obtain from (3.2), (3.5) that $||x_n(t)|| \leq ||x_0|| + K_3T_1$, $||x'_n(t)|| \leq (K_2T_1 + K_4)e^{K_2T_1}$ with K_2 , K_3 , K_4 independent of T_1 , $u \in S$ and n. Moreover, we also have $||x_u(t)|| \leq ||x_0|| + K_3T_1$, $||x_u(t) - x_u(t')|| \leq (K_2T_1 + K_4)e^{K_2T_1}|t - t'|$ for every $t, t' \in [0, T_1]$.

New let $u_1, u_2 \in S$ and x_1, x_2 be the corresponding solutions of $(I)_u$. Then we have

$$(3.6) \qquad (1/2)(d/dt) \|x_1(t) - x_2(t)\|^2 = -\operatorname{Re}\langle A(t, u_1(t))x_1(t) - A(t, u_2(t))x_2(t), F(x_1(t) - x_2(t))\rangle = -\operatorname{Re}\langle A(t, u_1(t))x_1(t) - A(t, u_1(t))x_2(t), F(x_1(t) - x_2(t))\rangle -\operatorname{Re}\langle A(t, u_1(t))x_2(t) - A(t, u_2(t))x_2(t), F(x_1(t) - x_2(t))\rangle \leq r(\|u_1(t)\|, \|u_2(t)\|, \|x_2(t)\|) \cdot \|u_1(t) - u_2(t)\| \|x_1(t) - x_2(t)\|$$

from which, by division by $||x_1(t)-x_2(t)||$ and integration, we get

(3.7) $\sup_{t \in [0, T_{1}]} \|x_{1}(t) - x_{2}(t)\| \\ \leq T_{1} r(\|x_{0}\| + L, \|x_{0}\| + L, \|x_{0}\| + K_{3}L/M) \sup_{t \in [0, T_{1}]} \|u_{1}(t) - u_{2}(t)\| \\ = K_{5} \sup_{t \in [0, T_{1}]} \|u_{1}(t) - u_{2}(t)\| .$

Now we may (and do) choose T_1 small enough so that

$$[K_2T_1+K_4]e^{K_2T_1} \leq M$$

and $K_5 < 1$; then the operator $T: u \rightarrow x_u$ maps the set S into itself and is a contraction. Since S is a complete metric space under the sup-norm, T has a fixed point $x(t), t \in [0, T_1]$. This is the desired strong solution of (I). Uniqueness follows from 3.6 by replacing u_1, u_2 by x_1, x_2 respectively.

The above result generalizes the existence result in the proof of Theorem 11.2 of Kato [9]. Kato considered the case $A(t, u, v) \equiv Au + Bv$ under a "localized" Lipschitz condition on B and m-accretiveness of a multi-valued A.

It should be noted that if $U(t, u, u) \equiv A(u)u$ (independent of t) and accretive in u, then the solution guaranteed by Theorem 3.1 is extendable to $[0, \infty)$ if we further assume that A(u)u is "demiclosed" (i. e., if $u_n \in D, n=1, 2,$ \cdots , and $u_n \rightarrow u$ and $A(u_n)u_n \rightarrow v \in X$ then $u \in D$ and A(u)u=v). In fact, (cf. proof of Theorem 11.2 of [9]) in this case, if [0, T') is the maximal interval of existence of x(t) with $T' < +\infty$, then $\lim_{t \to T} x(t) = x(T') \in D$ exists.

Now we are ready for the following perturbation result:

THEOREM 3.2. Let D be a subset of X. Let A: $\overline{D} \times D \to X$ be such that A(u)v is m-accretive in v and $||A(u_1)v - A(u_2)v|| \leq r(||u_1||, ||u_2||, ||v||)||u_1 - u_2||$ for

any $u_1, u_2 \in \overline{D}$, $v \in D$. Then if A(u)u is demiclosed and accretive, it is m-accretive.

PROOF. Taking into consideration the proof of Theorem 11.2 in Kato's paper [9] (cf. also Mermin [14, Lemma 4.2]), it suffices to show the existence of some $x_0 \in D$ such that for all $p \in X$ the Cauchy problem

(3.8)
$$x'(t) + A(x(t))x(t) + x(t) - p = 0, x(0) = x_0$$

has a unique strong solution on $[0, \infty)$. To show this, we simply remark that the operator $B(u)v \equiv A(u)v + v - p$ satisfies the assumptions placed on A in Theorem 3.1, and that the local strong solution obtained there is extendable to $[0, \infty)$ by the discussion above.

Theorem 3.1 holds of course if we perturb Equation (I) by a Lipschitzian function. This is the content of the following

COROLLARY 3.1. Let the operator A(u)v be as in Theorem 3.1, and let $G: [0, T) \times \overline{D} \to X$ satisfy:

$$\|G(t_1, u_1) - G(t_2, u_2)\| \leq r_1(\|u_1\|, \|u_2\|) [|t_1 - t_2| + \|u_1 - u_2\|]$$

for every $t_1, t_2 \in [0, T)$ and $u_1, u_2 \in \overline{D}$. Then the conclusion of Theorem 1 is true for the equation

(I)_G
$$x'(t) + A(t, x(t))x(t) = G(t, x(t)).$$

PROOF. It suffices to consider instead of A(t, u)v the operator $B(t, u)v \equiv A(t, u)v - G(t, u)$.

The above corollary has points of contact with the main result of Gröger [3] who considered $A(t, u)v \equiv A(t)v$ and G Lipschitzian and defined on the whole of X w.r.t. the second variable.

4. Linear *M*-accretive A(t).

Let C be the space of all X-valued continuous functions on R_+ with the topology of uniform convergence on finite intervals. Then C is a Fréchet space. Now consider the differential equation

(*)
$$x' + A(t)x = f(t), x(0) = x_0 \in D, t \in [0, \infty)$$

where D(A(t))=D(A(0))=D, $R(A(t))\subseteq X$ with A linear, closed and $f\in C$. Let f be Lipschitzian on $[0, +\infty)$ and, moreover, let

(S)
$$||A(t)v - A(s)v|| \le L |t-s| \cdot ||A(s)v||$$

for every $s, t \in R_+, v \in D$, where L is a positive constant. Then the operator $A_1(t): D \to X$ with $A_1(t)x \equiv A(t)x - f(t)$ satisfies all the hypotheses of Theorem 2.1 of Mermin's dissertation [14] (cf. also Kato [8, Theorems 1, 2]). Consequently, the equation (*) has a unique solution $x(t), t \in R_+$ which is strongly differentiable a.e., weakly continuously differentiable, and satisfying (*) (x'(t)) here is

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the weak derivative) on R_+ . Thus, under the above assumptions on A(t), Equation(*) has always solutions on $[0, \infty)$ if f belongs to a proper Banach space of Lipschitzian functions. The Banach spaces B considered below consist of functions $f: [0, +\infty) \rightarrow X$ which are at least Lipschitzian on $[0, +\infty)$.

Let B, E be two complex Banach spaces in C which are stronger than C(convergence in B or E implies convergence in C). Then the pair (B, E) is "admissible" if for every $f \in B$ there exists al least one solution $x \in E$ of(*). We denote by X_{0E} the linear manifold of X consisting of all initial values of E-solutions of the homogeneous Cauchy problem

$$(4.1) x' + A(t)x = 0.$$

Now let X_1 be any (but fixed) subspace of X supplementary to X_{0E} and let X_{1E} be the linear manifold consisting of all initial values of *E*-solutions of (*) belonging to X_1 and corresponding to all possible $f \in B$. We have the following theorem which extends a variation of Theorem 2.2 of Massera and Schäffer [13] to unbounded operators:

THEOREM 4.1. Let D(A(t))=D(A(0))=D with A linear, closed m-accretive and satisfying (S). Moreover, let B, E be two complex Banach spaces such that the pair (B, E) is admissible, X_{0E} , X_{1E} as above and $P_1(D)=\{P_1u; u\in D\}\subseteq D$, where P_1 is the projection of X_1 . Then there exists a constant K>0 such that for every $f\in B$ Equation (*) has a unique solution $x\in E$ with $x(0)\in X_{1E}$ and satisfying $\|x\|_E \leq K \|f\|_B$.

PROOF. We partially follow the steps of Massera and Schäffer in [12]. Let Y be the linear manifold consisting of all possible E-solutions of (*) with initial values in X_{1E} while f ranges in B. Now let $x \in Y$. We define

$$||x||_{Y} = ||x||_{E} + ||x'(0)|| + ||x' + A(\cdot)x||_{B}$$
,

where x'(0) is the weak derivative of the solution x(t).

Then $\|\cdot\|_{Y}$ is a norm on Y, and we show that under this norm Y is complete. Let $x_n \in Y$, $n=1, 2, \cdots$ be a Cauchy sequence. Then for every $\varepsilon > 0$ there exists $N(\varepsilon) > 0$ such that

$$(4.2) \quad \|x_m - x_n\|_{Y} = \|x_m - x_n\|_{E} + \|x'_m(0) - x'_n(0)\| + \|x'_m + A(\cdot)x_m - [x'_n + A(\cdot)x_n]\|_{E} < \varepsilon$$

for every m, n with $m, n > N(\varepsilon)$. Thus, in particular, $\{x_n\}$ is a Cauchy sequence in E and, since E is stronger than C (which is complete), there is a continuous function $x(t), t \in R_+$ such that $x_n \to x$ in C. In particular, $x_n(0) \to x(0)$ as $n \to \infty$. On the other hand, since X is a Banach space, there exists a vector $y \in X$ such that the sequence $\{x'_n(0)\}$ converges strongly to y as $n \to \infty$. It is also true that there exists $f \in B$ such that

(4.3)
$$\lim_{n \to \infty} \|f_n - f\|_B = 0, \quad C - \lim_{n \to \infty} f_n = f,$$

where $f_n(t) = x'_n(t) + A(t)x_n(t)$. Since A(0) is closed and $x'_n(0) + A(0)x_n(0) = f_n(0)$ with $x'_n(0) \rightarrow y \in X$ and $f_n(0) \rightarrow f(0)$, we obtain $x(0) \in D$ and A(0)x(0) = -y + f(0). Now let $\bar{x}(t), t \in R_+$ be the solution of (*) with $\bar{x}(0) = x(0)$. This solution exists because $x(0) \in D$. Then we have

(4.4)
$$x'_n(t) + A(t)x_n(t) = f_n(t), \quad t \in R_+,$$

(4.5)
$$\bar{x}'(t) + A(t)\bar{x}(t) = f(t), \quad t \in R_+.$$

Subtracting (4.5) from (4.4) and applying the functional $F(x_n(t)-\bar{x}(t))$ on both members of the resulting equation, we easily obtain

(4.6)
$$(d/dt) \|x_n(t) - \bar{x}(t)\|^2 = 2 \operatorname{Re} \langle x'_n(t) - \bar{x}'(t), F(x_n(t) - \bar{x}(t)) \rangle$$

 $= -2 \operatorname{Re} \langle A(t)x_n(t) - A(t)\bar{x}(t), F(x_n(t) - \bar{x}(t)) \rangle$
 $-2 \operatorname{Re} \langle f_n(t) - f(t), F(x_n(t) - \bar{x}(t)) \rangle$
 $\leq \|f_n(t) - f(t)\| \|x_n(t) - \bar{x}(t)\|$

almost everywhere in [0, c], where c is a fixed positive constant. From (4.6) we obtain

(4.7)
$$(d/dt)||x_n(t) - \bar{x}(t)|| \le ||f_n(t) - f(t)||$$
, a.e. in $[0, c]$,

which implies

(4.8)
$$\|x_n(t) - \bar{x}(t)\| \leq \|x_n(0) - \bar{x}(0)\| + \int_0^c \|f_n(s) - f(s)\| ds$$
$$\leq \|x_n(0) - \bar{x}(0)\| + c \sup_{t \in [0, c]} \|f_n(t) - f(t)\|.$$

Consequently, $x_n(t)$ converges strongly and uniformly to x(t) on the interval of [0, c]. Since c > 0 is arbitrary $\bar{x}(t) \equiv x(t)$ and x'(t) + A(t)x(t) = f(t). Consequently, x'(0) = y and

$$\lim_{n \to \infty} \|x_n - x\|_Y = 0$$

which proves the completeness of Y. Now consider the operator $T: Y \rightarrow B$ with (Tx)(t) = x'(t) + A(t)x(t).

The operator T is linear and bounded. In fact, $||Tx||_B \leq ||x||_Y$. T is oneto-one. To this end, let $x_1, x_2 \in Y$ with $Tx_1 = Tx_2$. Then since $T(x_1 - x_2) = 0$ and $x_1 - x_2 \in E$, we must have $x_1(0) - x_2(0) \in X_{0E}$. Since $X_{0E} \cap X_{1E} = \{0\}$, $x_1(0) = x_2(0)$ which implies $x_1(t) \equiv x_2(t)$, $t \in R_+$. To show that T is onto, let $f \in B$, and let $x \in E$ with x' + A(t)x = f. Then since $P_1(D) \subseteq D$, $P_1x(0) \in D$. Let $x_1(t)$ be the solution of (*) with $x_1(0) = P_1x(0)$. Then $x(0) - x_1(0) = P_0x(0) \in X_{0E}$. Here P_0 is the projection of X_{0E} . Thus, $x - x_1 \in E$ which implies $x_1 \in E$. Since $x_1(0) \in X_{1E}$, $Tx_1 = f$, which proves the ontoness of T. Now it follows from a well known theorem in Functional Analysis that the operator $T^{-1}: B \to Y$ is bounded and

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since $||T|| \leq 1$, we must have $||T^{-1}|| \geq 1$. Let $K = ||T^{-1}|| - 1$. Then $||x||_E \leq ||x||_Y - ||f||_B \leq ||T^{-1}f||_B - ||f||_B \leq (||T^{-1}|| - 1)||f||_B = K||f||_B$. This completes the proof.

As an application of the above considerations, we show the existence of solutions in E of a perturbed linear equation of the form

(4.9)
$$x' + A(t)x = G(t, x), \quad t \in [0, +\infty).$$

COROLLARY 4.1. Let A(t), B, E satisfy the hypotheses of Theorem 4.1. Let $M = \{u \in E; \|u\| \leq r\}$, where r is a positive constant. Let $G: R_+ \times \{v \in X; \|v\| \leq r\}$ $\rightarrow X$ satisfy:

(i) the operator U defined by (Ux)(t)=G(t, x(t)) maps M into B,

(ii) $||G(\cdot, u_1(\cdot)) - G(\cdot, u_2(\cdot))||_B \leq L ||u_1 - u_2||_E$

for every $u_1, u_2 \in M$ and $||G(\cdot, 0)||_B \leq \lambda$ with the constants λ, L, r satisfying $(\lambda+Lr)K \leq r$ and KL < 1. Here K is the constant of Theorem 4.1. Then (4.9) has at least one solution $x(t), t \in [0, \infty)$ with $x(0) \in X_{1E}$.

PROOF. Consider the operator $T: M \to E$ which maps the function $u \in M$ into the unique solution $x_u \in E$ $(x_u(0) \in X_{1E})$ of the equation

$$x' + A(t)x = G(t, u(t))$$
.

The solution $x_u(t)$ is guaranteed by Theorem 4.1. Moreover,

$$\|x_u\|_E \leq K \|G(\cdot, u(\cdot))\|_B$$
$$\leq K(\|G(\cdot, 0)\|_B + L\|u\|_E) \leq K(\lambda + Lr) \leq r.$$

Thus, $T(M) \subseteq M$. We also have

$$\|Tu_{1}-Tu_{2}\| \leq K \|G(\cdot, u_{1}(\cdot))-G(\cdot, u_{2}(\cdot))\|_{B}$$
$$\leq KL \|u_{1}-u_{2}\|.$$

This proves that T is a contraction on M and completes the proof.

In Theorem 3.1 we assumed that $P_1(D) \subseteq D$ to ensure that $P_1x(0) \in D$, otherwise the existence of $x_1(t)$ cannot be shown. In view of the usual spaces of definition of partial differential operators, this is not really a strong assumption. It is actually true that A(s) generates (for any but fixed $s \in [0, +\infty)$) a linear contraction semigroup T(t) on \overline{D} . Thus, we may assume without loss of generality that $X=\overline{D}$ and that A is densely defined in X.

In the results considered in this section we could have restricted ourselves to finite intervals. Systems of the form

$$(4.10) x' + A(t)x = G(t, x), Tx = 0, t \in [0, T]$$

can be considered, where T is a bounded linear operator mapping C[0, T] into X. E now would consist of all $u \in C[0, T]$ with Tu=0 and satisfying other suitable conditions.

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