# MINIMAL HYPERSURFACES AND BOUNDARY <br> BEHAVIOR OF COMPACT MANIFOLDS WITH NONNEGATIVE SCALAR CURVATURE 

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#### Abstract

On a compact Riemannian manifold with boundary having positive mean curvature, a fundamental result of Shi and Tam states that, if the manifold has nonnegative scalar curvature and if the boundary is isometric to a strictly convex hypersurface in the Euclidean space, then the total mean curvature of the boundary is no greater than the total mean curvature of the corresponding Euclidean hypersurface. In 3-dimension, Shi-Tam's result is known to be equivalent to the Riemannian positive mass theorem.

In this paper, we provide a supplement to Shi-Tam's result by including the boundary effect of minimal hypersurfaces. More precisely, given a compact manifold $\Omega$ with nonnegative scalar curvature, assuming its boundary consists of two parts, $\Sigma_{H}$ and $\Sigma_{O}$, where $\Sigma_{H}$ is the union of all closed minimal hypersurfaces in $\Omega$ and $\Sigma_{o}$ is assumed to be isometric to a suitable 2 -convex hypersurface $\Sigma$ in a spatial Schwarzschild manifold of mass $m$, we establish an inequality relating $m$, the area of $\Sigma_{H}$, and two weighted total mean curvatures of $\Sigma_{O}$ and $\Sigma$.

In 3-dimension, our inequality has implications to isometric embedding and quasi-local mass problems. In a relativistic context, the result can be interpreted as a quasi-local mass type quantity of $\Sigma_{O}$ being greater than or equal to the Hawking mass of $\Sigma_{H}$. We further analyze the limit of this quantity associated with suitably chosen isometric embeddings of large spheres in an asymptotically flat 3-manifold $M$ into a spatial Schwarzschild manifold. We show that the limit equals the ADM mass of $M$. It follows that our result on the compact manifold $\Omega$ is equivalent to the Riemannian Penrose inequality.


## 1. Introduction and statement of results

The main goal of this paper is to prove the following theorem:

[^0]Theorem 1.1. Let $\left(\Omega^{n+1}, \breve{g}\right)$ be a compact, connected, orientable, ( $n+1$ )-dimensional Riemannian manifold with nonnegative scalar curvature, with boundary $\partial \Omega$. Suppose $\partial \Omega$ is the disjoint union of two pieces, $\Sigma_{O}$ and $\Sigma_{H}$, where
(i) $\Sigma_{O}$ has positive mean curvature $H$; and
(ii) $\Sigma_{H}$, if nonempty, is a minimal hypersurface (with one or more components) and there are no other closed minimal hypersurfaces in $(\Omega, \breve{g})$.
Let $\mathbb{M}_{m}^{n+1}$ denote an $(n+1)$-dimensional spatial Schwarzschild manifold, outside the horizon, of mass $m>0$. Suppose $\Sigma_{O}$ is isometric to a closed, star-shaped, 2-convex hypersurface $\Sigma^{n} \subset \mathbb{M}_{m}^{n+1}$ with $\overline{\operatorname{Ric}}(\nu, \nu) \leq$ 0 , where $\overline{\operatorname{Ric}}$ is the Ricci curvature of $\mathbb{M}_{m}^{n+1}$ and $\nu$ is the outward unit normal to $\Sigma$.

If $n<7$, then

$$
\begin{equation*}
m+\frac{1}{n \omega_{n}} \int_{\Sigma} N H_{m} d \sigma \geq \frac{1}{2}\left(\frac{\left|\Sigma_{H}\right|}{\omega_{n}}\right)^{\frac{n-1}{n}}+\frac{1}{n \omega_{n}} \int_{\Sigma_{O}} N H d \sigma \tag{1.1}
\end{equation*}
$$

Here $H_{m}$ is the mean curvature of $\Sigma$ in $\mathbb{M}_{m}^{n+1}$, d $\sigma$ is the area element on $\Sigma$ and $\Sigma_{O}, \omega_{n}$ is the area of the standard unit sphere $\mathbb{S}^{n}, N$ is the static potential function on $\mathbb{M}_{m}^{n+1}$ given by

$$
N=\frac{1-\frac{m}{2}|x|^{1-n}}{1+\frac{m}{2}|x|^{1-n}}
$$

if one writes

$$
\mathbb{M}_{m}^{n+1}=\left(\mathbb{R}^{n+1} \backslash\left\{|x|<\left(\frac{m}{2}\right)^{\frac{1}{n-1}}\right\},\left(1+\frac{m}{2}|x|^{1-n}\right)^{\frac{4}{n-1}} g_{E}\right)
$$

where $g_{E}$ is the Euclidean metric, $N$ is also viewed as a function on $\Sigma_{O}$ via the isometry between $\Sigma$ and $\Sigma_{O},\left|\Sigma_{H}\right|$ denotes the area of $\Sigma_{H}$, and $\left|\Sigma_{H}\right|$ is taken to be 0 if $\Sigma_{H}=\emptyset$.

Moreover, if equality in (1.1) holds, then

$$
H=H_{m} \text { and } \frac{1}{2}\left(\frac{\left|\Sigma_{H}\right|}{\omega_{n}}\right)^{\frac{n-1}{n}}=m
$$

In particular, $\Sigma_{H}$ must be nonempty in this case.
Remark 1.1. Compact manifolds ( $\Omega, \breve{g}$ ) satisfying conditions (i) and (ii) in Theorem 1.1 exist widely. For instance, given any compact, connected, orientable Riemannian manifold ( $\tilde{\Omega}, \breve{g}$ ) with disconnected boundary $\partial \tilde{\Omega}$, if the mean curvature vector of $\partial \tilde{\Omega}$ points inward at each boundary component, then by minimizing area among all hypersurfaces that bounds a domain with a chosen boundary component, one can always construct such an $(\Omega, \breve{g})$ (under the given dimension assumption). In a relativistic context, a compact manifold $(\Omega, \breve{g})$ satisfying conditions
(i) and (ii) represents a finite body surrounding the apparent horizon of the black hole in a time-symmetric initial data set.

REMARK 1.2. A hypersurface $\Sigma \subset \mathbb{M}_{m}^{n+1}$ is called 2-convex if $\sigma_{1}>0$ and $\sigma_{2}>0$, where $\sigma_{1}$ and $\sigma_{2}$ are the first and second elementary symmetric functions of the principal curvatures of $\Sigma$ in $\mathbb{M}_{m}^{n+1}$, respectively.

REmARK 1.3. Let $\Sigma_{H}^{S}=\partial \mathbb{M}_{m}^{n+1}$ be the minimal hypersurface boundary of $\mathbb{M}_{m}^{n+1}$. Using the fact $m=\frac{1}{2}\left(\frac{\left|\Sigma_{H}^{S}\right|}{\omega_{n}}\right)^{\frac{n-1}{n}}$, we can write (1.1) equivalently as
$\frac{1}{2}\left(\frac{\left|\Sigma_{H}^{S}\right|}{\omega_{n}}\right)^{\frac{n-1}{n}}+\frac{1}{n \omega_{n}} \int_{\Sigma} N H_{m} d \sigma \geq \frac{1}{2}\left(\frac{\left|\Sigma_{H}\right|}{\omega_{n}}\right)^{\frac{n-1}{n}}+\frac{1}{n \omega_{n}} \int_{\Sigma_{O}} N H d \sigma$.
Such an inequality has the following variational interpretation. Let $g$ denote the induced metric on $\Sigma$ from the Schwarzschild metric $\bar{g}$ on $\mathbb{M}_{m}^{n+1}$. Let $\stackrel{\circ}{\mathcal{F}}_{(\Sigma, g)}$ be the set of fill-ins of $(\Sigma, g)$ with outermost horizon inner boundary, i.e. $\stackrel{\circ}{\mathcal{F}}_{(\Sigma, g)}$ consists of all compact, connected, orientable manifolds $(\Omega, \breve{g})$ with nonnegative scalar curvature, with boundary satisfying (i) and (ii) such that $\Sigma_{O}=\Sigma$ and $\left.\breve{g}\right|_{\Sigma_{O}}=g$, where $\breve{g} \mid \Sigma_{O}$ is the induced metric on $\Sigma_{O}$ from $\breve{g}$. Let $N$ be the function on $\Sigma_{O}=\Sigma$, which is the restriction of the static potential on $\mathbb{M}_{m}^{n+1}$ to $\Sigma$. On $\mathcal{F}_{(\Sigma, g)}$, consider the functional

$$
(\Omega, \breve{g}) \longmapsto \frac{1}{2}\left(\frac{\left|\Sigma_{H}\right|}{\omega_{n}}\right)^{\frac{n-1}{n}}+\frac{1}{n \omega_{n}} \int_{\Sigma_{O}} N H d \sigma
$$

Inequality (1.2) asserts that this functional is maximized at $\left(\Omega^{S}, \bar{g}\right)$, where $\Omega^{S}$ is the domain in $\mathbb{M}_{m}^{n+1}$ bounded by $\Sigma$ and $\Sigma_{H}^{S}$. (Such an interpretation of (1.2) in terms of fill-ins relates to the work of Mantoulidis and the second author [30].)

Treating the assumption that $\Sigma_{O}$ is isometric to $\Sigma \subset \mathbb{M}_{m}^{n+1}$ as a condition of having an isometric embedding of $\Sigma_{O}$ into $\mathbb{M}_{m}^{n+1}$, we have the following result.

Theorem 1.2. Let $\left(M^{3}, \breve{g}\right)$ be an asymptotically flat 3-manifold. Let $S_{r}$ denote the coordinate sphere of coordinate radius $r$ in a coordinate chart defining the asymptotic flatness of $\left(M^{3}, \breve{g}\right)$. Let $g_{r}$ be the induced metric on $S_{r}$. Then, given any constant $m>0$, there exists an isometric embedding

$$
X_{r}:\left(S_{r}, g_{r}\right) \longrightarrow \mathbb{M}_{m}^{3}
$$

for each sufficiently large $r$, such that $\Sigma_{r}=X_{r}\left(S_{r}\right)$ is a star-shaped, convex surface in $\mathbb{M}_{m}^{3}$, with $\overline{\operatorname{Ric}}(\nu, \nu)<0$ where $\nu$ is the outward unit
normal to $\Sigma_{r}$; moreover,

$$
\begin{equation*}
\lim _{r \rightarrow \infty}\left(m+\frac{1}{8 \pi} \int_{S_{r}} N\left(H_{m}-H\right) d \sigma\right)=\mathfrak{m} \tag{1.3}
\end{equation*}
$$

and

$$
\begin{equation*}
V(r)-V_{m}(r)=2 \pi r^{2}(\mathfrak{m}-m)+o\left(r^{2}\right), \text { as } r \rightarrow \infty \tag{1.4}
\end{equation*}
$$

Here $\mathfrak{m}$ is the ADM mass of $\left(M^{3}, \breve{g}\right)$, $H$ is the mean curvature of $S_{r}$ in $\left(M^{3}, \breve{g}\right)$ and $H_{m}$ is the mean curvature of $\Sigma_{r}$ in $\mathbb{M}_{m}^{3}, N$ is the static potential on $\mathbb{M}_{m}^{3}, N$ and $H_{m}$ are viewed as functions on $S_{r}$ via the embedding $X_{r}, V(r)$ is the volume of the region enclosed by $S_{r}$ in $\left(M^{3}, \breve{g}\right)$ and $V_{m}(r)$ is the volume of the region enclosed by $\Sigma_{r}$ in $\mathbb{M}_{m}^{3}$.

Now we explain the motivations to and the implications of Theorem 1.1. Our first motivation to Theorem 1.1 is the following theorem of Shi and Tam [41].

Theorem $1.3([41])$. Let $\left(\tilde{\Omega}^{n+1}, \breve{g}\right)$ be a compact, Riemannian spin manifold with nonnegative scalar curvature, with boundary $\partial \tilde{\Omega}$. Let $\Sigma_{i}$, $1 \leq i \leq k$, be the connected components of $\partial \tilde{\Omega}$. Suppose each $\Sigma_{i}$ has positive mean curvature and each $\Sigma_{i}$ is isomeric to a strictly convex hypersurface $\hat{\Sigma}_{i} \subset \mathbb{R}^{n+1}$. Then

$$
\begin{equation*}
\int_{\hat{\Sigma}_{i}} H_{0} d \sigma \geq \int_{\Sigma_{i}} H d \sigma \tag{1.5}
\end{equation*}
$$

where $H_{0}$ is the mean curvature of $\hat{\Sigma}_{i}$ in $\mathbb{R}^{n+1}$ and $H$ is the mean curvature of $\Sigma_{i}$ in $(\tilde{\Omega}, \breve{g})$. Moreover, if equality holds for some $i$, then $k=1$ and $(\tilde{\Omega}, \breve{g})$ is isometric to a domain in $\mathbb{R}^{n+1}$.

Theorem 1.3 is a fundamental result on compact manifolds with nonnegative scalar curvature with boundary, obtained via the Riemannian positive mass theorem [42, 46]. For the purpose of later explaining the proof of Theorem 1.1, we outline the proof of Theorem 1.3 from [41] as follows. For simplicity, we assume $k=1$ and denote $\Sigma_{1}$ by $\Sigma$. Identifying $\Sigma$ with its isometric image in $\mathbb{R}^{n+1}$ and using the assumption that $\Sigma$ is convex in $\mathbb{R}^{n+1}$, one can write the Euclidean metric $g_{E}$ on $\mathbb{E}$, the exterior of $\Sigma$, as $g_{E}=d t^{2}+g_{t}$, where $g_{t}$ is the induced metric on the hypersurface $\Sigma_{t}$ that has a fixed Euclidean distance $t$ to $\Sigma$. Given the mean curvature function $H>0$ on $\Sigma$, one shows that there exists a function $u>0$ on $\mathbb{E}$ such that $g_{u}=u^{2} d t^{2}+g_{t}$ has zero scalar curvature, $\left(\mathbb{E}, g_{u}\right)$ is asymptotically flat, and the mean curvature $H_{u}$ of $\Sigma_{t}$ in $\left(\mathbb{E}, g_{u}\right)$ satisfies $H_{u}=H$ at $\Sigma_{0}=\Sigma$. A key feature of such an $\left(\mathbb{E}, g_{u}\right)$ is that the integral

$$
\begin{equation*}
\frac{1}{n \omega_{n}} \int_{\Sigma_{t}}\left(H_{0}-H_{u}\right) d \sigma \tag{1.6}
\end{equation*}
$$

is monotone nonincreasing and it converges to $\mathfrak{m}\left(g_{u}\right)$, where $\mathfrak{m}\left(g_{u}\right)$ is the ADM mass $[\mathbf{1}]$ of $\left(\mathbb{E}, g_{u}\right)$. By gluing $(\tilde{\Omega}, \breve{g})$ and $\left(\mathbb{E}, g_{u}\right)$ along their common boundary $\Sigma$ and applying the Riemannian positive mass theorem, which is still valid under the condition that the mean curvatures of $\Sigma$ in $(\tilde{\Omega}, \breve{g})$ and ( $\left.\mathbb{E}, g_{u}\right)$ agree (see $\left.[41,33]\right)$, one concludes that

$$
\begin{equation*}
\frac{1}{n \omega_{n}} \int_{\Sigma}\left(H_{0}-H\right) d \sigma \geq \lim _{t \rightarrow \infty} \frac{1}{n \omega_{n}} \int_{\Sigma_{t}}\left(H_{0}-H\right) d \sigma=\mathfrak{m}\left(g_{u}\right) \geq 0 \tag{1.7}
\end{equation*}
$$

which proves (1.5).
One of the most important features of Theorem 1.3 is that, when $n=2$, by the solution to the Weyl embedding problem ([38, 39]), Theorem 1.3 implies the positivity of the Brown-York quasi-local mass $([\mathbf{9}, \mathbf{1 0}])$ of $\partial \tilde{\Omega}$, under the assumption that $\partial \tilde{\Omega}$ is a topological 2 -sphere with positive Gauss curvature.

Remark 1.4. When $n>2$, Eichmair, Wang and the second author [17] proved that Theorem 1.3 remains valid if each component $\Sigma_{i}$ is isometric to a star-shaped hypersurface with positive scalar curvature in $\mathbb{R}^{n+1}$. It was also noted in [17] that the spin assumption therein can be dropped when $n<7$. Recently, Schoen and Yau [43] proved that the Riemannian positive mass theorem holds in all dimensions without a spin assumption. Therefore, by the argument in [17], results in [41, 17] also hold in all dimensions without a spin assumption.

To motivate Theorem 1.1 from Theorem 1.3, one may consider the setting $k>1$ of Theorem 1.3. In this case, given any boundary component $\Sigma_{i}$, there exists a minimal hypersurface $S_{i}$, possibly disconnected, in the interior of $(\tilde{\Omega}, \breve{g})$ such that $S_{i}$ and $\Sigma_{i}$ bounds a domain $\Omega$ satisfying conditions (i) and (ii) in Theorem 1.1. Thus, besides the nonnegative scalar curvature, one wants to understand the influence of $S_{i}$ on $\Sigma_{i}$. This is indeed related to the following Riemannian Penrose inequality, which is our second motivation to Theorem 1.1.

Theorem $1.4([\mathbf{2 6}, \mathbf{4}, \mathbf{6}])$. Let $M^{n+1}$ be an asymptotically flat manifold with nonnegative scalar curvature, with boundary $\partial M$, where $n<7$. Suppose $\partial M$ is an outer minimizing, minimal hypersurface (with one or more component), then

$$
\begin{equation*}
\mathfrak{m}(M) \geq \frac{1}{2}\left(\frac{|\partial M|}{\omega_{n}}\right)^{\frac{n-1}{n}} \tag{1.8}
\end{equation*}
$$

where $\mathfrak{m}(M)$ is the $A D M$ mass of $M$ and $|\partial M|$ is the area of $\partial M$. Moreover, equality holds if and only if $M$ is isometric to a spatial Schwarzschild manifold outside its horizon.

When $n=2$, Theorem 1.4 was first proved by Huisken and Ilmanen $[\mathbf{2 5}, \mathbf{2 6}]$ for the case that $\partial M$ is connected, and later proved by Bray [4] for the general case in which $\partial M$ can have multiple components. For
higher dimensions, Bray and Lee [6] proved inequality (1.8) for $n<7$ and established the rigidity case assuming that $M$ is spin. (Without the spin assumption, the rigidity case follows by combining results of Bray and Lee [6] and McFeron and Székelyhidi [31].)

To compare Theorem 1.1 and Theorem 1.4, we can write (1.1) equivalently as

$$
\begin{equation*}
m+\frac{1}{n \omega_{n}} \int_{\Sigma_{O}} N\left(H_{m}-H\right) d \sigma \geq \frac{1}{2}\left(\frac{\left|\Sigma_{H}\right|}{\omega_{n}}\right)^{\frac{n-1}{n}} \tag{1.9}
\end{equation*}
$$

by identifying $\Sigma_{O}$ and $\Sigma$. The quantity on the left side of (1.9) depends only on the assumption on the (outer) boundary component $\Sigma_{O}$ of $\Omega$, while the mass $\mathfrak{m}(M)$ in (1.8) is determined solely by the asymptotically flat end of $M$. In this sense, Theorem 1.1 can be viewed as a localization of Theorem 1.4 to a compact manifold with boundary satisfying conditions (i) and (ii). Indeed, by (1.3) in Theorem 1.2 and the fact that our proof of Theorem 1.1 uses (1.8), Theorem 1.1 is equivalent to the Riemannian Penrose inequality (1.8) when $n=2$. In this case, the right side of (1.9) is the Hawking quasi-local mass [24] of $\Sigma_{H}$, and (1.9) describes how $\Sigma_{H}$, which models the apparent horizon of black hole, contributes to the quasi-local mass of a body surrounding it.

Remark 1.5. In [14], Chen, Wang, Wang and Yau introduced a notion of quasi-local energy in reference to a general static spacetime. Setting $\tau=0$ in equation (2.10) in [14], one sees that the quasi-local energy of a 2 -surface $\Sigma$ defined in [14] with respect to an isometric embedding of $\Sigma$ into a time-symmetric slice of Schwarzschild the Schwarzschild spacetime with mass $m$ is given by $\frac{1}{8 \pi} \int_{\Sigma} N\left(H_{m}-H\right) d \sigma$, which agrees with the surface integral on the left side of (1.9) with $\Sigma=\Sigma_{O}$.

To illustrate that Theorem 1.1 provides a supplement to Shi-Tam's result, we want to make a connection between (1.9) and an inequality that can be obtained by directly combining (1.8) and Shi-Tam's proof of Theorem 1.3. Only for the convenience of making a comparison, we list the following inequality in a theorem format:

Theorem 1.3'. Let $\left(\Omega^{n+1}, \breve{g}\right)$ be a compact Riemannian manifold with nonnegative scalar curvature, with boundary $\partial \Omega$, satisfying conditions (i) and (ii) in Theorem 1.1. Suppose $\Sigma_{H} \neq \emptyset$ and $\Sigma_{O}$ is isometric to $a$ strictly convex hypersurface $\Sigma^{n} \subset \mathbb{R}^{n+1}$. If $n<7$, then

$$
\begin{equation*}
\frac{1}{n \omega_{n}} \int_{\Sigma_{O}}\left(H_{0}-H\right) d \sigma>\frac{1}{2}\left(\frac{\left|\Sigma_{H}\right|}{\omega_{n}}\right)^{\frac{n-1}{n}} \tag{1.10}
\end{equation*}
$$

where $H_{0}$ is the mean curvature of $\Sigma$ in $\mathbb{R}^{n+1}$.
The proof of (1.10) is identical to Shi-Tam's proof of Theorem 1.3 outlined earlier, except that in the final inequality of (1.7), one replaces
the Riemannian positive mass theorem by the Riemannian Penrose inequality to yield

$$
\begin{align*}
\frac{1}{n \omega_{n}} \int_{\Sigma_{O}}\left(H_{0}-H\right) d \sigma & \geq \lim _{t \rightarrow \infty} \frac{1}{n \omega_{n}} \int_{\Sigma_{t}}\left(H_{0}-H\right) d \sigma \\
& =\mathfrak{m}\left(g_{u}\right) \geq \frac{1}{2}\left(\frac{\left|\Sigma_{H}\right|}{\omega_{n}}\right)^{\frac{n-1}{n}} \tag{1.11}
\end{align*}
$$

The fact that (1.8) is applicable to the manifold obtained by gluing $(\Omega, \breve{g})$ and $\left(\mathbb{E}, g_{u}\right)$ was demonstrated in [35] for $n=2$ and in $[32]$ for $n<7$.

Remark 1.6. By the argument in [17], (1.10) holds with the assumption that $\Sigma \subset \mathbb{R}^{n+1}$ is strictly convex replaced by that $\Sigma$ is star-shaped with positive scalar curvature. Such a statement is precisely the $m=0$ analogue of Theorem 1.1 for the case $\Sigma_{H} \neq \emptyset$.

Inequality (1.10) takes a simpler form than (1.9), however it is always a strict inequality. This is because, if the first inequality in (1.11) were equality, the function $u$ would be identically 1 (implied by the monotonicity calculation of (1.6) in $[41,17]$ ), consequently $H_{0}=H$ identically, which would show $0 \geq\left|\Sigma_{H}\right|$, contradicting the assumption $\Sigma_{H} \neq \emptyset$. A more intuitive reason for (1.10) to be strict is that, though $\Sigma_{H}$ is a nonempty minimal hypersurface in $\Omega^{n+1},(1.10)$ is obtained by comparing $\Sigma_{O}$ to a hypersurface in $\mathbb{R}^{n+1}$ which is free of closed minimal hypersurfaces.

For the above reason, we consider an assumption $\Sigma_{O}$ is isometric to an $\Sigma \subset \mathbb{M}_{m}^{n+1}$ in Theorem 1.1. In particular, (1.9) does become an equality when $\Omega$ itself is the domain in $\mathbb{M}_{m}^{n+1}$ bounded by $\Sigma$ and the Schwarzschild horizon $\Sigma_{H}^{S}$.

The fact that (1.9) gives a refined estimate on $\left|\Sigma_{H}\right|$, sharper than (1.10), can be illustrated by the case in which $\Sigma_{O}$ is isometric to a round sphere. In the following example, for simplicity, we take $n=2$.

Example 1. Suppose $\Omega$ is a compact 3 -manifold with nonnegative scalar curvature, with boundary $\partial \Omega$, satisfying conditions (i) and (ii) in Theorem 1.1. Suppose $\Sigma_{H} \neq \emptyset$ and $\Sigma_{O}$ is isometric to a round sphere with area $4 \pi R^{2}$. Then (1.10) shows

$$
\begin{equation*}
R-\frac{1}{8 \pi} \int_{\Sigma_{O}} H d \sigma>\sqrt{\frac{\left|\Sigma_{H}\right|}{16 \pi}} \tag{1.12}
\end{equation*}
$$

On the other hand, Theorem 1.1 applies to any $\mathbb{M}_{m}^{3}$ with $m \in\left(0, \frac{1}{2} R\right)$ since $\Sigma_{O}$ is isometric to a rotationally symmetric sphere in such an $\mathbb{M}_{m}^{3}$. Thus, by (1.9),

$$
\begin{equation*}
m+\frac{1}{8 \pi} \int_{\Sigma_{O}} N\left(N \frac{2}{R}-H\right) d \sigma \geq \sqrt{\frac{\left|\Sigma_{H}\right|}{16 \pi}} \tag{1.13}
\end{equation*}
$$

with $N=\sqrt{1-\frac{2 m}{R}}$. Let $\Phi(m)$ denote the quantity on the left side of (1.13). (The left side of (1.12) equals $\lim _{m \rightarrow 0+} \Phi(m)$.) By (1.13),

$$
\begin{equation*}
\min _{0<m<\frac{R}{2}} \Phi(m) \geq \sqrt{\frac{\left|\Sigma_{H}\right|}{16 \pi}} . \tag{1.14}
\end{equation*}
$$

Note that either (1.12) or (1.13) implies $0<\frac{1}{8 \pi R} \int_{\Sigma_{O}} H d \sigma<1$. Therefore, via direct calculation, one has

$$
\begin{align*}
R-\frac{1}{8 \pi} \int_{\Sigma_{O}} H d \sigma & >\min _{0<m<\frac{R}{2}} \Phi(m)=\frac{R}{2}\left[1-\left(\frac{1}{8 \pi R} \int_{\Sigma_{O}} H d \sigma\right)^{2}\right]  \tag{1.15}\\
& \geq \sqrt{\frac{\left|\Sigma_{H}\right|}{16 \pi}}
\end{align*}
$$

(It is clear that, if $\Omega$ is the region bounded by a rotationally symmetric sphere and the horizon boundary in some $\mathbb{M}_{m}^{3}$, then $\min _{0<m<\frac{R}{2}} \Phi(m)=$ $\sqrt{\frac{\left|\Sigma_{H}\right|}{16 \pi}}$.) In (1.15), it is also intriguing to note that $\min _{0<m<\frac{R}{2}} \Phi(m)$ is achieved at $m=m_{*}$ where $m_{*}$, determined by $N=\frac{1}{8 \pi R} \int_{\Sigma_{O}} H d \sigma$, agrees with $\min _{0<m<\frac{R}{2}} \Phi(m)$, i.e.

$$
\begin{equation*}
m_{*}=\min _{0<m<\frac{R}{2}} \Phi(m) . \tag{1.16}
\end{equation*}
$$

This means that an optimal background $\mathbb{M}_{m_{*}}^{3}$ that is used to be compared with $\Omega$ is indeed determined by the minimal value of $\Phi(m)$.

REMARK 1.7. Calculation in relation to the example above was first carried out in [35] where the special case of Theorem 1.1 in which $\Sigma_{O}$ is isometric to a round sphere was proved. The implication of (1.16) on the quasi-local mass of such round surfaces was also discussed in [35].

Next, we comment on the implication of Theorem 1.1 on isometric embeddings of a 2 -sphere into a Schwarzschild manifold $\mathbb{M}_{m}^{3}$ with $m>$ 0 . It was proved by Li and Wang [28] that, if $\sigma$ is a metric on the 2 -sphere $\mathbb{S}^{2}$, an isometric embedding of $\left(\mathbb{S}^{2}, \sigma\right)$ into $\mathbb{M}^{3}$ may not be unique. Indeed, it was shown in [28] that, if $\sigma_{r}$ is the standard round metric of area $4 \pi r^{2}$ with $r>2 m$, then $\left(\mathbb{S}^{2}, \sigma_{r}\right)$ admits an isometric embedding into $\mathbb{M}_{m}^{3}$ that is close to but different from the standard embedding whose image is a rotationally symmetric sphere. For this reason, one knows that inequality (1.1) does depend on the choice of the isometry between $\Sigma_{O}$ and $\Sigma$. (This contrasts with inequality (1.5) which only depends on the intrinsic metric on $\Sigma_{i}$.) However, in the following example, we demonstrate that (1.1) can be applied to reveal information on such different isometric embeddings into $\mathbb{M}_{m}^{3}$.

Example 2. Let $\Sigma \subset \mathbb{M}_{m}^{3}$ be a closed, star-shaped, convex surface with $\overline{\operatorname{Ric}}(\nu, \nu) \leq 0$. Let $H_{m}$ denote its mean curvature. Suppose $\iota$ : $\Sigma \rightarrow \tilde{\Sigma}$ is an isometry between $\Sigma$ and another surface $\tilde{\Sigma} \subset \mathbb{M}_{m}^{3}$ with properties
(a) $\tilde{\Sigma}$ bounds a domain $D$ with the Schwarzschild horizon $\Sigma_{H}^{S}=\partial \mathbb{M}_{m}^{3}$, and
(b) $\tilde{\Sigma}$ has positive mean curvature $\tilde{H}_{m}$ with respect to the outward unit normal.
Then Theorem 1.1 is applicable to the domain $D$ to give

$$
\begin{equation*}
m+\frac{1}{8 \pi} \int_{\Sigma} N H_{m} d \sigma \geq \sqrt{\frac{\left|\Sigma_{H}^{S}\right|}{16 \pi}}+\frac{1}{8 \pi} \int_{\tilde{\Sigma}} \tilde{N} \tilde{H}_{m} d \sigma \tag{1.17}
\end{equation*}
$$

with $\tilde{N}=N \circ \iota^{-1}$. (Note that, if (a) is replaced by an assumption $\tilde{\Sigma}=\partial D$ for some $D$, then the term involving $\left|\Sigma_{H}^{S}\right|$ will be absent in (1.17) and the inequality is strict.) Since $m=\sqrt{\frac{\left|\Sigma_{H}^{S}\right|}{16 \pi}}$, (1.17) shows

$$
\begin{equation*}
\int_{\Sigma} N H_{m} d \sigma \geq \int_{\tilde{\Sigma}} \tilde{N} \tilde{H}_{m} d \sigma \tag{1.18}
\end{equation*}
$$

with equality holds only if $H_{m} \circ \iota^{-1}=\tilde{H}_{m}$. Now suppose we consider the special case in which $\Sigma$ is a rotationally symmetric sphere, then $N$ is a constant on $\Sigma$, hence $\tilde{N}$ is also a constant that equals $N$. In this case, (1.18) becomes

$$
\begin{equation*}
\int_{\Sigma} H_{m} d \sigma \geq \int_{\tilde{\Sigma}} \tilde{H}_{m} d \sigma \tag{1.19}
\end{equation*}
$$

(In the case of $\tilde{\Sigma}=\partial D$, one has $8 \pi m N^{-1}+\int_{\Sigma} H_{m} d \sigma>\int_{\tilde{\Sigma}} \tilde{H}_{m} d \sigma$.) Since $H_{m}$ is a constant, equality in (1.19) holds only if $\tilde{H}_{m}$ is a constant. By the result of Brendle [7], we conclude that $\tilde{\Sigma}$ must be $\Sigma$ when equality holds in (1.19).

We now outline the proof of Theorem 1.1. The first step in our proof is to generalize the monotonicity of the Brown-York mass type integral (1.6) in Shi-Tam's proof of Theorem 1.3 to the monotonicity of a weighted Brown-York mass type integral

$$
\begin{equation*}
\int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma \tag{1.20}
\end{equation*}
$$

in a general static background on which $N$ is a positive static potential function. The idea of imposing a suitable weight function in (1.20) to obtain monotonicity goes back to the work of Wang and Yau [45] in which isometric embeddings of surfaces into hyperbolic spaces are considered. Given a static Riemannian manifold ( $\mathbb{N}, \bar{g}$ ) (see Definition 2.1), let $\left\{\Sigma_{t}\right\}$ be a family of closed hypersurfaces evolving in $(\mathbb{N}, \bar{g})$ with speed $f>0$, we show that, as long as $\Sigma_{t}$ is 2 -convex and $\frac{\partial N}{\partial \nu}>0$,
(1.20) is monotone nonincreasing along the flow. Here 2 -convexity of $\Sigma_{t}$ means that $\sigma_{1}>0$ and $\sigma_{2}>0$, where $\sigma_{1}$ and $\sigma_{2}$ are the first and second elementary symmetric functions of the principal curvatures of $\Sigma_{t}$ in $(\mathbb{N}, \bar{g}) ; \nu$ denotes the unit normal giving the direction of the flow; and $\bar{H}, H_{\eta}$ denote the mean curvature of $\Sigma_{t}$ with respect to $\bar{g}=f^{2} d t^{2}+$ $g_{t}, g_{\eta}=\eta^{2} d t^{2}+g_{t}$, respectively, where $g_{\eta}$ is taken to have the same scalar curvature as $\bar{g}$. (The idea of considering such a metric $g_{\eta}$ goes back to Bartnik [3].) To apply this monotonicity formula, in the next step we study a family of closed, star-shaped, hypersurfaces $\left\{\Sigma_{t}\right\}$ in a spatial Schwarzschild manifold $\mathbb{M}_{m}^{n+1}$, given by $\Sigma_{t}=X\left(t, \mathbb{S}^{n}\right)$, where $X:[0, \infty) \times \mathbb{S}^{n} \rightarrow \mathbb{M}_{m}^{n+1}$ is a smooth map evolving according to

$$
\begin{equation*}
\frac{\partial X}{\partial t}=\frac{n-1}{2 n} \frac{\sigma_{1}}{\sigma_{2}} \nu \tag{1.21}
\end{equation*}
$$

We show that, if the initial hypersurface $\Sigma_{0}$ is 2-convex with $\overline{\operatorname{Ric}}(\nu, \nu) \leq$ 0 , then (1.21) admits a long time solution $\left\{\Sigma_{t}\right\}_{0 \leq t<\infty}$ so that each $\Sigma_{t}$ is 2-convex and has positive scalar curvature. Writing the Schwarzschild background metric $\bar{g}$ on the exterior region $\mathbb{E}$ of $\Sigma_{0}$ as $\bar{g}=f^{2} d t^{2}+g_{t}$, we then demonstrate that there exists a positive function $\eta$ on $\mathbb{E}$ such that $g_{\eta}=\eta^{2} d t^{2}+g_{t}$ has zero scalar curvature, the mean curvature of $\Sigma_{0}$ in $\left(\mathbb{E}, g_{\eta}\right)$ equals $H$ which is the mean curvature of $\Sigma_{O}$ in $(\Omega, \breve{g})$; and $\left(\mathbb{E}, g_{\eta}\right)$ is asymptotically flat with mass

$$
\begin{equation*}
\mathfrak{m}\left(g_{\eta}\right)=m+\lim _{t \rightarrow \infty} \frac{1}{n \omega_{n}} \int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma \tag{1.22}
\end{equation*}
$$

Finally, by gluing $(\Omega, \breve{g})$ and $\left(\mathbb{E}, g_{\eta}\right)$ along $\Sigma_{O}$ (which is identified with $\left.\Sigma=\Sigma_{0}\right)$ to get an asymptotically flat manifold $(\hat{M}, \hat{h})$, we conclude

$$
\begin{align*}
m+\frac{1}{n \omega_{n}} \int_{\Sigma_{O}} N\left(H_{m}-H\right) d \sigma & \geq m+\lim _{t \rightarrow \infty} \frac{1}{n \omega_{n}} \int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma  \tag{1.23}\\
& =\mathfrak{m}\left(g_{\eta}\right) \geq \frac{1}{2}\left(\frac{\left|\Sigma_{H}\right|}{\omega_{n}}\right)^{\frac{n-1}{n}}
\end{align*}
$$

where in the last step we used the fact that the Riemannian Penrose inequality holds on such an ( $\hat{M}, \hat{h}$ ) (see $[\mathbf{3 5}, 32]$ ).

It is worth of mentioning that, similar to the fact that Shi-Tam's proof of Theorem 1.3 gives an upper bound of the Bartnik mass $\mathfrak{m}_{B}(\Sigma)$ [2] for a 2 -surface $\Sigma$ that is isometric to a convex surface in $\mathbb{R}^{3}$ in terms of its Brown-York mass, our proof of Theorem 1.1 yields

$$
\begin{equation*}
\mathfrak{m}_{B}(\Sigma) \leq m+\frac{1}{8 \pi} \int_{\Sigma} N\left(H_{m}-H\right) d \sigma \tag{1.24}
\end{equation*}
$$

for a surface $\Sigma$ that is isometric to a convex surface with $\overline{\operatorname{Ric}}(\nu, \nu) \leq 0$ in an $\mathbb{M}_{m}^{3}$ (see Theorem 5.1). Such an estimate on the Bartnik mass
verifies a special case of Conjecture 4.1 in [34], which is formulated for a surface that admits an isometric embedding into a general static manifold.

This paper is organized as follows. In Section 2, we derive the monotonicity formula of the weighted Brown-York mass type integral (1.20) in a general static background. In Section 3, we study a family of inverse curvature flows in a spatial Schwarzschild manifold $\mathbb{M}_{m}^{n+1}$, which includes (1.21) as a special case. In Section 4, we prove that a warped metric of the form $g_{\eta}=\eta^{2} d t^{2}+g_{t}$, with zero scalar curvature, exists on the Schwarzschild exterior region $\mathbb{E}$ swept out by the solution $\left\{\Sigma_{t}\right\}_{0 \leq t \leq \infty}$ to (1.21), and show that $g_{\eta}$ is asymptotically flat and its mass is given by (1.22). In Section 5 , we attach $\left(\mathbb{E}, g_{\eta}\right)$ to $(\Omega, \breve{g})$ along $\Sigma_{O}$ and apply the Riemannian Penrose inequality to prove Theorem 1.1. We also discuss the implication of our work to the Bartnik mass. We end the paper by proving Theorem 1.2 in Section 6.

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## 2. Monotonicity formula in a static background

The Euclidean space $\mathbb{R}^{n+1}$ and the spatial Schwarzschild manifolds $\mathbb{M}_{m}^{n+1}$ both are examples of a static Riemannian manifold according to the following definition.

Definition 2.1 ([15]). A Riemannian manifold $(\mathbb{N}, \bar{g})$ is called static if there exists a nontrivial function $N$ such that

$$
\begin{equation*}
(\bar{\Delta} N) \bar{g}-\bar{D}^{2} N+N \overline{R i c}=0 \tag{2.1}
\end{equation*}
$$

where $\overline{R i c}$ is the Ricci curvature of $(\mathbb{N}, \bar{g}), \bar{D}^{2} N$ is the Hessian of $N$ and $\bar{\Delta}$ is the Laplacian of $N$. The function $N$ is called a static potential.

Throughout this section, we let $(\mathbb{N}, \bar{g})$ denote a static Riemannian manifold with a static potential $N$. The scalar curvature $\bar{R}$ of such an $(\mathbb{N}, \bar{g})$ is necessarily a constant (see [15, Proposition 2.3]). Consider a smooth family of embedded hypersurfaces $\left\{\Sigma_{t}\right\}$ evolving in $(\mathbb{N}, \bar{g})$ according to

$$
\begin{equation*}
\frac{\partial X}{\partial t}=f \nu \tag{2.2}
\end{equation*}
$$

where $X$ denotes points in $\Sigma_{t}, f>0$ denotes the speed of the flow, and $\nu$ is a unit normal to $\Sigma_{t}$. Let $\sigma_{1}$ and $\sigma_{2}$ be the first and second elementary symmetric functions of the principal curvatures of $\Sigma_{t}$ in $(\mathbb{N}, \bar{g})$, respectively. In particular, $\sigma_{1}$ equals the mean curvature of $\Sigma_{t}$.

The metric $\bar{g}$ over the region $U$ swept by $\left\{\Sigma_{t}\right\}$ can be written as

$$
\begin{equation*}
\bar{g}=f^{2} d t^{2}+g_{t} \tag{2.3}
\end{equation*}
$$

where $g_{t}$ is the induced metric of $\Sigma_{t}$. Now consider another metric

$$
\begin{equation*}
g_{\eta}=\eta^{2} d t^{2}+g_{t} \tag{2.4}
\end{equation*}
$$

where $\eta>0$ is a function on $U$. We impose the condition that the scalar curvature $R\left(g_{\eta}\right)$ of $g_{\eta}$ equals the scalar curvature of $\bar{g}$, i.e.

$$
\begin{equation*}
R\left(g_{\eta}\right)=\bar{R} \tag{2.5}
\end{equation*}
$$

Proposition 2.2. Under the above notations and assumptions,

$$
\begin{aligned}
& \frac{d}{d t}\left(\int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma\right) \\
= & -\int_{\Sigma_{t}} \eta^{-1}(\eta-f)^{2} \bar{H} \frac{\partial N}{\partial \nu} d \sigma-\int_{\Sigma_{t}} N \sigma_{2} \eta^{-1}(\eta-f)^{2} d \sigma
\end{aligned}
$$

where $\bar{H}$ and $H_{\eta}$ are the mean curvature of $\Sigma_{t}$ with respect to $\bar{g}$ and $g_{\eta}$, respectively.

Proof. Denote $\bar{A}$ and $A_{\eta}$ the second fundamental form of $\Sigma_{t}$ with respect to $\bar{g}$ and $g_{\eta}$, respectively. By (2.3) and (2.4),

$$
\begin{equation*}
H_{\eta}=\eta^{-1} f \bar{H}, \quad A_{\eta}=\eta^{-1} f \bar{A} \tag{2.6}
\end{equation*}
$$

By the second variation formula,

$$
\begin{equation*}
\frac{\partial}{\partial t} \bar{H}=-\Delta f-f\left(|\bar{A}|^{2}+\overline{\operatorname{Ric}}(\nu, \nu)\right) \tag{2.7}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{\partial}{\partial t} H_{\eta}=-\Delta \eta-\eta\left(\left|A_{\eta}\right|^{2}+\operatorname{Ric}_{g_{\eta}}(\nu, \nu)\right) \tag{2.8}
\end{equation*}
$$

where $\Delta$ is the Laplacian operator on $\left(\Sigma_{t}, g_{t}\right)$ and $\operatorname{Ric}_{g_{\eta}}$ is the Ricci curvature of $g_{\eta}$.

Let $R$ denote the scalar curvature of $\left(\Sigma_{t}, g_{t}\right)$. Let $\sigma_{2 \eta}$ be the second elementary symmetric functions of the principal curvatures of $\Sigma_{t}$ in $\left(\mathbb{N}, g_{\eta}\right)$. By Gauss equation,

$$
\begin{equation*}
\sigma_{2}=\frac{R-\bar{R}}{2}+\overline{\operatorname{Ric}}(\nu, \nu), \quad \sigma_{2 \eta}=\frac{R-\bar{R}}{2}+\operatorname{Ric}_{g_{\eta}}(\nu, \nu) \tag{2.9}
\end{equation*}
$$

Together with (2.6), we have

$$
\begin{align*}
\operatorname{Ric}_{g_{\eta}}(\nu, \nu) & =\overline{\operatorname{Ric}}(\nu, \nu)+\sigma_{2 \eta}-\sigma_{2} \\
& =\overline{\operatorname{Ric}}(\nu, \nu)+\sigma_{2}\left(\eta^{-2} f^{2}-1\right) \tag{2.10}
\end{align*}
$$

Putting (2.7), (2.8) and (2.10) together, we have

$$
\begin{aligned}
& \frac{\partial}{\partial t}\left(\bar{H}-H_{\eta}\right) \\
= & \Delta(\eta-f)-f\left(|\bar{A}|^{2}+\overline{\operatorname{Ric}}(\nu, \nu)\right)+\eta\left(\left|A_{\eta}\right|^{2}+\operatorname{Ric}_{g_{\eta}}(\nu, \nu)\right) \\
= & \Delta(\eta-f)+\overline{\operatorname{Ric}}(\nu, \nu)(\eta-f)+|\bar{A}|^{2}\left(\eta^{-1} f^{2}-f\right)+\sigma_{2}\left(\eta^{-1} f^{2}-\eta\right) .
\end{aligned}
$$

Using the formula $\frac{\partial}{\partial t} d \sigma=f H d \sigma,(2.6)$ and integrating by part, we thus have

$$
\begin{aligned}
& \frac{d}{d t}\left(\int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma\right) \\
= & \int_{\Sigma_{t}} f \frac{\partial N}{\partial \nu} \bar{H}\left(1-\eta^{-1} f\right) d \sigma+\int_{\Sigma_{t}} N \bar{H}\left(1-\eta^{-1} f\right) f \bar{H} d \sigma \\
& +\int_{\Sigma_{t}}(\Delta N(\eta-f)+N \overline{\operatorname{Ric}}(\nu, \nu)(\eta-f)) d \sigma \\
& +\int_{\Sigma_{t}}\left(N|\bar{A}|^{2}\left(\eta^{-1} f^{2}-f\right)+N \sigma_{2}\left(\eta^{-1} f^{2}-\eta\right)\right) d \sigma \\
= & \int_{\Sigma_{t}}(\eta-f)\left(\Delta N+N \overline{\operatorname{Ric}}(\nu, \nu)+\eta^{-1} f \bar{H} \frac{\partial N}{\partial \nu}\right) d \sigma \\
& +\int_{\Sigma_{t}} N \sigma_{2}\left(2\left(f-\eta^{-1} f^{2}\right)+\eta^{-1} f^{2}-\eta\right) d \sigma \\
= & \int_{\Sigma_{t}}(\eta-f)\left(\Delta N+N \overline{\operatorname{Ri} c}(\nu, \nu)+\eta^{-1} f \bar{H} \frac{\partial N}{\partial \nu}\right) d \sigma \\
& -\int_{\Sigma_{t}} N \sigma_{2} \eta^{-1}(\eta-f)^{2} d \sigma .
\end{aligned}
$$

The static equation (2.1) implies

$$
\begin{aligned}
& \Delta N+N \overline{\operatorname{Ric}}(\nu, \nu) \\
= & \bar{\Delta} N-\bar{D}^{2} N(\nu, \nu)-\bar{H} \frac{\partial N}{\partial \nu}+N \overline{\operatorname{Ric}}(\nu, \nu)=-\bar{H} \frac{\partial N}{\partial \nu} .
\end{aligned}
$$

Therefore, we conclude

$$
\begin{aligned}
& \frac{d}{d t}\left(\int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma\right) \\
= & \int_{\Sigma_{t}}(\eta-f)\left(-1+\eta^{-1} f\right) \bar{H} \frac{\partial N}{\partial \nu} d \sigma-\int_{\Sigma_{t}} N \sigma_{2} \eta^{-1}(\eta-f)^{2} d \sigma \\
= & -\int_{\Sigma_{t}} \eta^{-1}(\eta-f)^{2} \bar{H} \frac{\partial N}{\partial \nu} d \sigma-\int_{\Sigma_{t}} N \sigma_{2} \eta^{-1}(\eta-f)^{2} d \sigma .
\end{aligned}
$$

q.e.d.

Corollary 2.3. Suppose $(\mathbb{N}, \bar{g})$ has a positive static potential $N$. Along $\left\{\Sigma_{t}\right\}$, suppose

$$
\begin{equation*}
\frac{\partial N}{\partial \nu}>0 \text { and } \sigma_{i}>0, i=1,2 \tag{2.11}
\end{equation*}
$$

Then $\int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma$ is monotone nonincreasing and it is a constant if and only if $\eta=f$.

## 3. Inverse curvature flows in Schwarzschild manifolds

Corollary 2.3 suggests one consider foliations $\left\{\Sigma_{t}\right\}$ satisfying condition (2.11) in a static manifold with a positive static potential. In this section, we use an inverse curvature flow to construct such foliations in the Schwarzschild manifold $\mathbb{M}_{m}^{n+1}$.

We begin by fixing some notations. Henceforth, we will always use $\bar{g}$ to denote the metric on $\mathbb{M}_{m}^{n+1}$. We write

$$
\begin{equation*}
\left(\mathbb{M}_{m}^{n+1}, \bar{g}\right)=\left([0, \infty) \times \mathbb{S}^{n}, d r^{2}+\phi^{2}(r) \sigma\right) \tag{3.1}
\end{equation*}
$$

where $\sigma$ is the standard metric on the unit $n$-sphere $\mathbb{S}^{n}$ and $\phi=\phi(r)>0$ satisfies $\phi(0)=(2 m)^{\frac{1}{n-1}}$ and

$$
\begin{equation*}
\phi^{\prime}=\sqrt{1-2 m \phi^{1-n}} \tag{3.2}
\end{equation*}
$$

In terms of this coordinate $r$, the static potential function $N$ in Theorem 1.1 equals $\phi^{\prime}$. We use $\bar{R}(\cdot, \cdot, \cdot, \cdot), \overline{\operatorname{Ric}}(\cdot, \cdot)$ to denote the curvature tensor, the Ricci curvature of $\bar{g}$, respectively. The scalar curvature $\bar{R}$ of $\bar{g}$ is identically zero.

Given any integer $1 \leq k \leq n$, the Garding's cone $\Gamma_{k} \subset \mathbb{R}^{n}$ is defined by

$$
\Gamma_{k}=\left\{\left(\kappa_{1}, \ldots, \kappa_{n}\right) \in \mathbb{R}^{n} \mid \sigma_{j}>0,1 \leq j \leq k\right\}
$$

where $\sigma_{j}$ is the $j$-th elementary symmetric function of $\left(\kappa_{1}, \ldots, \kappa_{n}\right)$. We also define $\sigma_{0}=1$. A hypersurface $\Sigma \subset \mathbb{M}_{m}^{n+1}$ is called $k$-convex if its principal curvature $\left(\kappa_{1}, \ldots, \kappa_{n}\right) \in \Gamma_{k}$.

Theorem 3.1. Let $\Sigma_{0}^{n}$ be a star-shaped, $k$-convex, closed hypersurface in $\mathbb{M}_{m}^{n+1}$. Consider a smooth family of hypersurfaces $\left\{\Sigma_{t}\right\}_{t \geq 0}$ evolving according to

$$
\begin{equation*}
\frac{\partial X}{\partial t}=\frac{\nu}{F} \tag{3.3}
\end{equation*}
$$

where $\nu$ is the outward unit normal and $F=n \frac{C_{n}^{k-1}}{C_{n}^{k}} \frac{\sigma_{k}}{\sigma_{k-1}}>0$ which is evaluated at the principal curvatures of $\Sigma_{t}$. Then (3.3) has a smooth solution that exists for all time, each $\Sigma_{t}$ remains star-shaped, and the second fundamental form $h$ of $\Sigma_{t}$ satisfies

$$
\left|h_{j}^{i} \phi-\delta_{j}^{i}\right| \leq C e^{-\alpha t}
$$

where $\phi$ is evaluated at $\Sigma_{t}$ and $C, \alpha$ depends only on $\Sigma_{0}, n, k$.
We remark that inverse curvature flows in Euclidean spaces were first studied by Gerhardt [19] and Urbas [44]. They considered the flow equation (3.3) where $F$ is a concave function of homogeneous degree one, evaluated at the principal curvature, and proved that the solution exists for all time and the normalized flow converges to a round sphere if the initial hypersurface is suitably star-shaped. For flows in other space forms, Gerhardt $[\mathbf{2 0}, \mathbf{2 1}]$ proved the solution exists for all time
and the second fundamental form converges (see also earlier work by Ding [16]). Recently, Brendle-Hung-Wang [8] and Scheuer [40] proved that the same results hold in anti-de Sitter-Schwarzschild manifold and a class of warped product manifolds for the inverse mean curvature flow, i.e. $F=\sigma_{1}$. However, as pointed out by Neves [37] and Hung-Wang [27], for the inverse mean curvature flow, the rescaled limiting hypersurface is not necessarily a round sphere in an anti-de Sitter-Schwarzschild manifold. The case of $F=n \frac{C_{n}^{k-1}}{C_{n}^{k}} \frac{\sigma_{k}}{\sigma_{k-1}}$ in anti-de Sitter-Schwarzschild manifolds was analyzed by $\mathrm{Lu}[\mathbf{2 9}]$ and Chen-Mao [13] independently. They proved that the flow exists for all time and the second fundamental converges exponentially fast if the initial hypersurface is star-shaped and $k$-convex.

In what follows, we prove Theorem 3.1 following the steps in [29]. We divide the proof into a few subsections.
3.1. Basic formulae. We first collect some well-known formulae in Schwarzschild manifold. Given a hypersurface $\Sigma^{n} \subset \mathbb{M}_{m}^{n+1}$, we always use $g$ to denote the induced metric on $\Sigma$. Define

$$
\Phi(r)=\int_{0}^{r} \phi(\rho) d \rho, \quad u=\left\langle\phi \frac{\partial}{\partial r}, \nu\right\rangle
$$

where $\nu$ is the outer unit normal of $\Sigma$ and $\langle\cdot, \cdot\rangle$ also denotes the metric product on $\mathbb{M}_{m}^{n+1}$. Let $i, j . . \in\{1, \ldots, n\}$ denote indices of local coordinates on $\Sigma$. Let $h$ be the second fundamental form on $\Sigma$.

The following formula is well-known (see [22] for instance),

$$
\begin{equation*}
\Phi_{; i j}=\phi^{\prime} g_{i j}-h_{i j} u \tag{3.4}
\end{equation*}
$$

where ";" denotes the covariant differentiation on $\Sigma$.
Let $R(\cdot, \cdot, \cdot, \cdot)$ be the curvature tensor of $g$ on $\Sigma$. The Gauss equation and Codazzi equation are

$$
\begin{gather*}
R_{i j k l}=\bar{R}_{i j k l}+\left(h_{i k} h_{j l}-h_{i l} h_{j k}\right)  \tag{3.5}\\
\nabla_{k} h_{i j}-\nabla_{j} h_{i k}=\bar{R}_{\nu i j k} \tag{3.6}
\end{gather*}
$$

and the interchanging formula is

$$
\begin{align*}
\nabla_{i} \nabla_{j} h_{k l}= & \nabla_{k} \nabla_{l} h_{i j}-h_{l}^{p}\left(h_{i p} h_{k j}-h_{i j} h_{p k}\right)-h_{j}^{p}\left(h_{p i} h_{k l}-h_{i l} h_{p k}\right)  \tag{3.7}\\
& +h_{l}^{p} \bar{R}_{i k j p}+h_{j}^{p} \bar{R}_{i k l p}+\nabla_{k} \bar{R}_{i j l \nu}+\nabla_{i} \bar{R}_{j k l \nu} .
\end{align*}
$$

Here $\nabla$ is another notation for the covariant differentiation on $\Sigma$.
The function $u$ is known as the support function of $\Sigma$. We have (see in [29])

## Lemma 3.2.

$$
\begin{aligned}
\nabla_{i} u & =g^{k l} h_{i k} \nabla_{l} \Phi \\
\nabla_{i} \nabla_{j} u & =g^{k l} \nabla_{k} h_{i j} \nabla_{l} \Phi+\phi^{\prime} h_{i j}-\left(h^{2}\right)_{i j} u+g^{k l} \nabla_{l} \Phi \bar{R}_{\nu j k i}
\end{aligned}
$$

where $\left(h^{2}\right)_{i j}=g^{k l} h_{i k} h_{j l}, \bar{R}_{\nu j k i}$ is the curvature of ambient space.
As for the curvature, we have the following curvature estimates, for proof, we refer readers to [8].

Lemma 3.3. The sectional curvature satisfies

$$
\begin{aligned}
\bar{R}\left(\partial_{i}, \partial_{j}, \partial_{k}, \partial_{l}\right) & =\phi^{2}\left(1-\phi^{\prime 2}\right)\left(\sigma_{i k} \sigma_{j l}-\sigma_{i l} \sigma_{j k}\right) \\
\bar{R}\left(\partial_{i}, \partial_{r}, \partial_{j}, \partial_{r}\right) & =-\phi \phi^{\prime \prime} \sigma_{i j}
\end{aligned}
$$

Together with (3.2), this gives

$$
\begin{aligned}
& \bar{R}\left(\partial_{i}, \partial_{j}, \partial_{k}, \partial_{l}\right)=2 m \phi^{3-n}\left(\sigma_{i k} \sigma_{j l}-\sigma_{i l} \sigma_{j k}\right) \\
& \bar{R}\left(\partial_{i}, \partial_{r}, \partial_{j}, \partial_{r}\right)=-m(n-1) \phi^{1-n} \sigma_{i j}
\end{aligned}
$$

thus

$$
\bar{R}_{\alpha \beta \gamma \mu}=O\left(r^{-n-1}\right), \quad \bar{\nabla}_{\rho} \bar{R}_{\alpha \beta \gamma \mu}=O\left(r^{-n-1}\right)
$$

Here $\left\{\partial_{i}\right\}$ is the coordinate frame on $\mathbb{S}^{n}$, $\sigma_{i j}$ is the standard metric of $\mathbb{S}^{n}$, and $\left\{e_{\alpha}\right\}$ denotes an orthonormal frame on $\mathbb{M}_{m}^{n+1}$.

We also need the following two lemmas regarding to $\sigma_{k}$, see in [29] for detailed proof.

Lemma 3.4. let $F=n \frac{C_{n}^{k-1}}{C_{n}^{k}} \frac{\sigma_{k}}{\sigma_{k-1}}$, thus $F$ is of homogeneous degree 1 , and $F(I)=n$, then we have

$$
\sum_{i} F^{i i} \lambda_{i}^{2} \geq \frac{F^{2}}{n}
$$

Lemma 3.5. Let $F=n \frac{C_{n}^{k-1}}{C_{n}^{k}} \frac{\sigma_{k}}{\sigma_{k-1}}$ and $\left(\lambda_{i}\right) \in \Gamma_{k}$, then

$$
n \leq \sum_{i} F^{i i} \leq n k
$$

3.2. Parametrization on graph and $C^{0}$ estimate. Since the initial hypersurface $\Sigma_{0}$ is star-shaped, we can consider it as a graph on $\mathbb{S}^{n}$, i.e. $X=(x, r)$ where $x$ is the coordinate on $\mathbb{S}^{n}$ and $r$ is the radial function. By taking derivatives, we have

$$
\begin{equation*}
X_{i}=\partial_{i}+r_{i} \partial_{r}, \quad g_{i j}=r_{i} r_{j}+\phi^{2} \sigma_{i j} \tag{3.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\nu=\frac{1}{v}\left(-\frac{r^{i}}{\phi^{2}} \partial_{i}+\partial_{r}\right) \tag{3.9}
\end{equation*}
$$

where $\nu$ is the unit normal vector, $v=\left(1+\frac{|\nabla r|^{2}}{\phi^{2}}\right)^{\frac{1}{2}}$. Note that all the derivatives are on $\mathbb{S}^{n}$.

Thus

$$
\frac{d r}{d t}=\frac{1}{F v}, \dot{x}^{i}=-\frac{r^{i}}{\phi^{2} F v}
$$

we have

$$
\begin{equation*}
\frac{\partial r}{\partial t}=\frac{d r}{d t}-r_{j} \dot{x}^{j}=\frac{v}{F} \tag{3.10}
\end{equation*}
$$

By a direct computation, cf. (2.6) in [16] we have

$$
\begin{equation*}
h_{i j}=\frac{1}{v}\left(-r_{i j}+\phi \phi^{\prime} \sigma_{i j}+\frac{2 \phi^{\prime} r_{i} r_{j}}{\phi}\right) \tag{3.11}
\end{equation*}
$$

Now we consider a function

$$
\begin{equation*}
\varphi=\int_{r_{0}}^{r} \frac{1}{\phi} \tag{3.12}
\end{equation*}
$$

thus

$$
\begin{equation*}
\varphi_{i}=\frac{r_{i}}{\phi}, \varphi_{i j}=\frac{r_{i j}}{\phi}-\frac{\phi^{\prime} r_{i} r_{j}}{\phi^{2}} \tag{3.13}
\end{equation*}
$$

If we write everything in terms of $\varphi$, we have

$$
\begin{equation*}
\frac{\partial \varphi}{\partial t}=\frac{v}{\phi F} \tag{3.14}
\end{equation*}
$$

and

$$
\begin{equation*}
v=\left(1+|D \varphi|^{2}\right)^{\frac{1}{2}}, g_{i j}=\phi^{2}\left(\varphi_{i} \varphi_{j}+\sigma_{i j}\right), g^{i j}=\phi^{-2}\left(\sigma^{i j}-\frac{\varphi^{i} \varphi^{j}}{v^{2}}\right) \tag{3.15}
\end{equation*}
$$

Moreover,

$$
\begin{align*}
h_{i j} & =\frac{\phi}{v}\left(\phi^{\prime}\left(\sigma_{i j}+\varphi_{i} \varphi_{j}\right)-\varphi_{i j}\right),  \tag{3.16}\\
h_{j}^{i} & =g^{i k} h_{k j}=\frac{\phi^{\prime}}{\phi v} \delta_{j}^{i}-\frac{1}{\phi v} \tilde{\sigma}^{i k} \varphi_{k j},
\end{align*}
$$

where $\tilde{\sigma}^{i j}=\sigma^{i j}-\frac{\varphi^{i} \varphi^{j}}{v^{2}}$.
Lemma 3.6. Let $\bar{r}(t)=\sup _{\mathbb{S}^{n}} r(\cdot, t)$ and $\underline{r}(t)=\inf _{\mathbb{S}^{n}} r(\cdot, t)$, then we have

$$
\begin{align*}
& \phi(\bar{r}(t)) \leq e^{t / n} \phi(\bar{r}(0))  \tag{3.17}\\
& \phi(\underline{r}(t)) \geq e^{t / n} \phi(\underline{r}(0)) .
\end{align*}
$$

Proof. Recall that $\frac{\partial r}{\partial t}=\frac{v}{F}$, where $F$ is a normalized operator on $\left(h_{j}^{i}\right)$. At the point where the function $r(\cdot, t)$ attains its maximum, we have $\nabla r=0,\left(r_{i j}\right) \leq 0$, from (3.13), we deduce that $\nabla \varphi=0,\left(\varphi_{i j}\right) \leq 0$ at the maximum point. From (3.16), we have $\left(h_{j}^{i}\right) \geq\left(\frac{\phi^{\prime}}{\phi} \delta_{j}^{i}\right)$, where
we may assume $\left(g_{i j}\right)$ and $\left(h_{i j}\right)$ is diagonalized if necessary. Since $F$ is homogeneous of degree 1 , and $F(1, \cdots, 1)=n$, we have

$$
v^{2}=1+|\nabla \varphi|^{2}=1, F\left(h_{j}^{i}\right) \geq \frac{\phi^{\prime}}{\phi} F\left(\delta_{j}^{i}\right)=\frac{n \phi^{\prime}}{\phi}
$$

thus

$$
\frac{d}{d t} \bar{r}(t) \leq \frac{\phi(\bar{r}(t))}{n \phi^{\prime}(\bar{r}(t))}
$$

i.e.

$$
\frac{d}{d t} \log \phi(\bar{r}(t)) \leq \frac{1}{n}
$$

which yields to the first inequality. Similarly, we can prove the second inequality, thus we have the lemma.
3.3. Evolution equations and $C^{1}$ estimate. Before we go on with the estimate, let's derive some evolution equations first. We have

$$
\begin{equation*}
\dot{g}_{i j}=\frac{2 h_{i j}}{F}, \quad \dot{\nu}=\frac{g^{i j} F_{i} e_{j}}{F^{2}} \tag{3.18}
\end{equation*}
$$

and

$$
\begin{equation*}
\grave{h}_{j}^{i}=-\frac{1}{F} h_{k}^{i} h_{j}^{k}-\nabla^{i} \nabla_{j}\left(\frac{1}{F}\right)-\frac{1}{F} \bar{R}_{\nu j \nu}^{i} \tag{3.19}
\end{equation*}
$$

Together with the interchanging formula (3.7), we have

$$
\begin{align*}
\dot{h}_{j}^{i}= & -\frac{1}{F} h_{k}^{i} h_{j}^{k}+\frac{F^{p q, r s} h_{p q}{ }^{i} h_{r s j}}{F^{2}}-\frac{2 F^{p q} h_{p q}{ }^{i} F^{r s} h_{r s j}}{F^{3}}-\frac{1}{F} \bar{R}_{\nu j \nu}^{i}  \tag{3.20}\\
& +\frac{g^{k i} F^{p q}}{F^{2}}\left(h_{k j, p q}-h_{q}^{l}\left(h_{k l} h_{p j}-h_{k j} h_{l p}\right)-h_{j}^{l}\left(h_{l k} h_{p q}-h_{k q} h_{l p}\right)\right. \\
& \left.+h_{q}^{l} \bar{R}_{k p j l}+h_{j}^{l} \bar{R}_{k p q l}+\nabla_{p} \bar{R}_{k j q \nu}+\nabla_{k} \bar{R}_{j p q \nu}\right),
\end{align*}
$$

where $F^{i j}=\frac{\partial F}{\partial h_{p q}}$ and $F^{p q, r s}=\frac{\partial^{2} F}{\partial h_{p q} \partial h_{r s}}$.
We also need the evolution equation for the support function

$$
u=\left\langle\phi \frac{\partial}{\partial r}, \nu\right\rangle
$$

which is given by

$$
\begin{equation*}
\dot{u}=\frac{\phi^{\prime}}{F}+\frac{\phi g^{i j} F_{i} r_{j}}{F^{2}} \tag{3.21}
\end{equation*}
$$

Now, we need to consider the curvature term. By Lemma 3.3, (3.8) and (3.9), we have

$$
\bar{R}_{\nu j n k}=\frac{r_{n} \delta_{j k}}{v}\left(-\phi \phi^{\prime \prime}-\left(1-\left(\phi^{\prime}\right)^{2}\right)\right)+\frac{r_{k} \delta_{j n}}{v}\left(\phi \phi^{\prime \prime}+\left(1-\phi^{\prime 2}\right)\right)
$$

Note that $g^{p n}=\phi^{-2}\left(\sigma^{p n}-\frac{r^{p} r^{n}}{v^{2} \phi^{2}}\right)$, where $r^{p}=g^{p q} r_{q}$. Thus

$$
\begin{equation*}
g^{p n} \nabla_{p} \Phi \bar{R}_{\nu j n k}=\left(\frac{|\nabla r|^{2} \delta_{j k}-r_{j} r_{k}}{\phi v^{3}}\right)\left(-\phi \phi^{\prime \prime}-\left(1-\phi^{\prime 2}\right)\right) \leq 0 \tag{3.22}
\end{equation*}
$$

Lemma 3.7. Along the flow, $|\nabla \varphi| \leq C$, where $C$ depends on $\Sigma_{0}, n, k$.
Proof. By (3.14) and (3.16), we have

$$
\frac{\partial \varphi}{\partial t}=\frac{v}{\phi F}=\frac{v^{2}}{\tilde{F}\left(\phi^{\prime} \delta_{i j}-\tilde{\sigma}^{i k} \varphi_{k j}\right)}=\frac{1}{G}
$$

where $\tilde{F}=\phi v F$.
Let $G^{i j}=\frac{\partial G}{\partial \varphi_{i j}}, G^{k}=\frac{\partial G}{\partial \varphi_{k}}, G_{\varphi}=\frac{\partial G}{\partial \varphi}$ then

$$
G^{i j}=-\frac{1}{v^{2}} \tilde{F}_{l}^{i} \tilde{\sigma}^{l j}, \quad G_{\varphi}=\frac{1}{v^{2}} \tilde{F}_{i}^{i} \phi \phi^{\prime \prime}
$$

Let $\omega=\frac{1}{2}|\nabla \varphi|^{2}$, we have

$$
\begin{aligned}
\frac{\partial \omega}{\partial t} & =\nabla_{k} \varphi \nabla_{k} \dot{\varphi}=-\frac{\varphi^{k}}{G^{2}} \nabla_{k} G=-\frac{\varphi^{k}}{G^{2}}\left(G^{i j} \varphi_{i j k}+G^{l} \varphi_{l k}+G_{\varphi} \varphi_{k}\right) \\
& =\frac{1}{v^{2} G^{2}}\left(\tilde{F}_{l}^{i} \tilde{\sigma}^{l j} \varphi^{k} \varphi_{i j k}-v^{2} G^{l} \omega_{l}-2 \tilde{F}_{i}^{i} \phi \phi^{\prime \prime} \omega\right)
\end{aligned}
$$

We want to write the term $\tilde{\sigma}^{l j} \varphi_{i j k}$ in terms of second derivative of $\omega$. Note that

$$
\begin{aligned}
\omega_{i j} & =\varphi_{k i j} \varphi^{k}+\varphi_{k i} \varphi_{j}^{k} \\
& =\varphi_{i j k} \varphi^{k}+\left(\sigma_{i j} \sigma_{k p}-\sigma_{i k} \sigma_{j p}\right) \varphi^{p} \varphi^{k}+\varphi_{k i} \varphi_{j}^{k} \\
& =\varphi_{i j k} \varphi^{k}+\sigma_{i j}|\nabla \varphi|^{2}-\varphi_{i} \varphi_{j}+\varphi_{k i} \varphi_{j}^{k}
\end{aligned}
$$

and

$$
\tilde{\sigma}^{l j}\left(\sigma_{i j}|\nabla \varphi|^{2}-\varphi_{i} \varphi_{j}\right)=\delta_{i}^{l}|\nabla \varphi|^{2}-\varphi_{i} \varphi^{l}
$$

Thus we have

$$
\begin{align*}
\frac{\partial w}{\partial t}= & \frac{1}{v^{2} G^{2}}\left(\tilde{F}_{l}^{i} \tilde{\sigma}^{l j} \omega_{i j}-\tilde{F}_{i}^{i}|\nabla \varphi|^{2}+\tilde{F}_{l}^{i} \varphi_{i} \varphi^{l}-v^{2} G^{l} \omega_{l}-2 \tilde{F}_{i}^{i} \phi \phi^{\prime \prime} \omega\right)  \tag{3.23}\\
& -\frac{1}{v^{2} G^{2}} \tilde{F}_{l}^{i} \tilde{\sigma}^{l j} \varphi_{k i} \varphi_{j}^{k}
\end{align*}
$$

Note that $-\tilde{F}_{i}^{i}|\nabla \varphi|^{2}+\tilde{F}_{l}^{i} \varphi_{i} \varphi^{l} \leq 0$ and $-\tilde{F}_{l}^{i} \tilde{\sigma}^{l j} \varphi_{k i} \varphi_{j}^{k} \leq 0$, thus by the maximum principle, we have

$$
\omega(\cdot, t) \leq \sup \omega_{0}
$$

Lemma 3.8. Along the flow, $u \geq c e^{\frac{t}{n}}$, where $u$ is the support function and $c$ depends on $\Sigma_{0}, n, k$.

Proof. Recall that $u=\left\langle\phi \partial_{r}, \nu\right\rangle$. By Lemma 3.6, $\phi \geq C e^{\frac{t}{n}}$; by Lemma $3.7,\left\langle\partial_{r}, \nu\right\rangle \geq C$. It follows that $u \geq c e^{\frac{t}{n}}$.

Lemma 3.9. Suppose $\overline{\operatorname{Ric}}(\nu, \nu) \leq 0$ for $\Sigma_{0}$, then $\overline{\operatorname{Ric}}(\nu, \nu) \leq 0$ for all $\Sigma_{t}$. If $k \geq 2$, this implies $R>0$ for all $\Sigma_{t}$.

Proof. By Lemma 3.3, we have

$$
\overline{\operatorname{Ric}}=\left((n-1)\left(1-\phi^{\prime 2}\right)-\phi \phi^{\prime \prime}\right) g_{\mathbb{S}^{n}}-n \frac{\phi^{\prime \prime}}{\phi} d r^{2}
$$

Together with (3.9), i.e. $\nu=\frac{1}{v}\left(\partial_{r}-\frac{r^{j} \partial_{j}}{\phi^{2}}\right)$, we have

$$
\begin{aligned}
\overline{\operatorname{Ric}}(\nu, \nu) & =-n \frac{\phi^{\prime \prime}}{\phi v^{2}}+\frac{(n-1)\left(1-\phi^{\prime 2}\right)-\phi \phi^{\prime \prime}}{\phi^{4} v^{2}}|\nabla r|^{2} \\
& =-n \frac{\phi^{\prime \prime}}{\phi v^{2}}+\frac{(n-1)\left(1-\phi^{2}\right)-\phi \phi^{\prime \prime}}{\phi^{2} v^{2}}\left(v^{2}-1\right) \\
& =\frac{(n-1)\left(1-\phi^{\prime 2}\right)-\phi \phi^{\prime \prime}}{\phi^{2}}-(n-1) \frac{1-\phi^{\prime 2}+\phi \phi^{\prime \prime}}{\phi^{2} v^{2}} .
\end{aligned}
$$

Since $\phi^{\prime}=\sqrt{1-2 m \phi^{1-n}}$, thus

$$
1-\phi^{\prime 2}=2 m \phi^{1-n}, \quad \phi \phi^{\prime \prime}=m(n-1) \phi^{1-n}
$$

Thus

$$
\overline{\operatorname{Ric}}(\nu, \nu)=m(n-1) \phi^{-1-n}-m(n-1)(n+1) \phi^{-1-n} v^{-2} .
$$

On the other hand, $v^{2}=1+|\nabla \varphi|^{2}$ and, by Lemma 3.7, $|\nabla \varphi|$ is bounded above by the initial data. Thus it follows that, if initially $\overline{\operatorname{Ric}}(\nu, \nu) \leq 0$, i.e. $|\nabla \varphi|^{2} \leq n$, then it remains true along the flow.

To prove the second assertion, it suffices to note that

$$
\sigma_{2}=\frac{R}{2}+\overline{\operatorname{Ric}}(\nu, \nu)>0
$$

along the flow. Thus $R>0$ along the flow.
q.e.d.

### 3.4. Bound for principal curvature.

Lemma 3.10. Along the flow, $F \phi \leq C$, where $C$ depends only on $\Sigma_{0}, n, k$.

Proof. Consider $F \phi$, at the maximum point, we have

$$
\frac{\dot{\phi}}{\phi}+\frac{\dot{F}}{F} \geq 0
$$

and

$$
\frac{\phi_{i}}{\phi}+\frac{F_{i}}{F}=0, \quad \frac{\phi_{i j}}{\phi}+\frac{F_{i j}}{F}-2 \frac{F_{i} F_{j}}{F^{2}} \leq 0
$$

By (3.10) and (3.19), we have

$$
\begin{aligned}
0 & \leq \frac{\phi^{\prime} v}{F \phi}+\frac{F_{i}^{j}}{F}\left(-\frac{1}{F} h_{k}^{i} h_{j}^{k}-\nabla^{i} \nabla_{j}\left(\frac{1}{F}\right)-\frac{1}{F} \bar{R}_{\nu j \nu}^{i}\right) \\
& =\frac{\phi^{\prime} v}{F \phi}+\frac{F_{i}^{j}}{F}\left(-\frac{1}{F} h_{k}^{i} h_{j}^{k}+\frac{\nabla^{i} \nabla_{j} F}{F^{2}}-2 \frac{\nabla^{i} F \nabla_{j} F}{F^{3}}-\frac{1}{F} \bar{R}_{\nu j \nu}^{i}\right) .
\end{aligned}
$$

By the critical equation above and (3.11), we have

$$
\begin{aligned}
0 \leq & \frac{\phi^{\prime} v}{F \phi}+\frac{F_{i}^{j}}{F}\left(-\frac{1}{F} h_{k}^{i} h_{j}^{k}-\frac{\nabla^{i} \nabla_{j} \phi}{F \phi}-\frac{1}{F} \bar{R}_{\nu j \nu}^{i}\right) \\
= & \frac{\phi^{\prime} v}{F \phi}+\frac{F_{i}^{j}}{F^{2}}\left(-h_{k}^{i} h_{j}^{k}-\bar{R}_{\nu j \nu}^{i}\right)-\frac{F^{i j}}{F^{2} \phi}\left(\phi^{\prime \prime} r_{i} r_{j}+\phi^{\prime} r_{i j}\right) \\
= & \frac{\phi^{\prime} v}{F \phi}+\frac{F_{i}^{j}}{F^{2}}\left(-h_{k}^{i} h_{j}^{k}-\bar{R}_{\nu j \nu}^{i}\right) \\
& -\frac{F^{i j}}{F^{2} \phi}\left(\phi^{\prime \prime} r_{i} r_{j}+\phi^{\prime}\left(\phi \phi^{\prime} \sigma_{i j}+\frac{2 \phi^{\prime} r_{i} r_{j}}{\phi}-h_{i j} v\right)\right) \\
= & 2 \frac{\phi^{\prime} v}{F \phi}-\frac{F_{i}^{j}}{F^{2}}\left(h_{k}^{i} h_{j}^{k}+\bar{R}_{\nu j \nu}^{i}\right) \\
& -\frac{F^{i j}}{F^{2} \phi}\left(\phi^{\prime \prime} r_{i} r_{j}+\phi^{\prime}\left(\phi \phi^{\prime} \sigma_{i j}+\frac{2 \phi^{\prime} r_{i} r_{j}}{\phi}\right)\right)
\end{aligned}
$$

By Lemma 3.3 and property of $\phi$, we have

$$
\begin{aligned}
0 & \leq 2 \frac{\phi^{\prime} v}{F \phi}-\frac{F_{i}^{j}}{F^{2}} h_{k}^{i} h_{j}^{k}+C \frac{F_{i}^{i}}{F^{2} \phi^{n+1}} \\
& -\frac{F^{i j}}{F^{2} \phi}\left(\phi^{\prime \prime} r_{i} r_{j}+\frac{2\left(\phi^{\prime}\right)^{2} r_{i} r_{j}}{\phi}\right)-\frac{F^{i j} \sigma_{i j}\left(\phi^{\prime}\right)^{2}}{F^{2}}
\end{aligned}
$$

By Lemma 3.4, we have

$$
\begin{aligned}
0 & \leq 2 \frac{\phi^{\prime} v}{F \phi}-\frac{1}{n}+C \frac{F_{i}^{i}}{F^{2} \phi^{n+1}} \\
& -\frac{F^{i j}}{F^{2} \phi}\left(\phi^{\prime \prime} r_{i} r_{j}+\frac{2\left(\phi^{\prime}\right)^{2} r_{i} r_{j}}{\phi}\right)-\frac{F^{i j} \sigma_{i j}\left(\phi^{\prime}\right)^{2}}{F^{2}}
\end{aligned}
$$

Using the fact that $F^{i j} r_{i} r_{j} \geq 0$, we have

$$
0 \leq 2 \frac{\phi^{\prime} v}{F \phi}-\frac{1}{n}+C \frac{F_{i}^{i}}{F^{2} \phi^{n+1}}-\frac{F^{i j} \sigma_{i j}\left(\phi^{\prime}\right)^{2}}{F^{2}}
$$

Note that $\sigma_{i j}=\frac{g_{i j}-r_{i} r_{j}}{\phi^{2}}$, we have

$$
\begin{equation*}
0 \leq 2 \frac{\phi^{\prime} v}{F \phi}-\frac{1}{n}+C \frac{F_{i}^{i}}{F^{2} \phi^{n+1}}-\frac{F_{i}^{i}\left(\phi^{\prime}\right)^{2}}{F^{2} \phi^{2}}+\frac{F^{i j} r_{i} r_{j}\left(\phi^{\prime}\right)^{2}}{F^{2} \phi^{2}} \tag{3.24}
\end{equation*}
$$

By Lemma 3.7, we have $g^{i j} \leq C \phi^{-2}$, it follows that

$$
\frac{F^{i j} r_{i} r_{j}\left(\phi^{\prime}\right)^{2}}{F^{2} \phi^{2}} \leq C \frac{F_{i}^{i}\left(\phi^{\prime}\right)^{2}}{F^{2} \phi^{2}}
$$

Together with Lemma 3.5 and property of $\phi$, we have

$$
0 \leq \frac{C}{F \phi}-\frac{1}{n}+\frac{C}{F^{2} \phi^{n+1}}+\frac{C}{F^{2} \phi^{2}}
$$

thus $F \phi$ is bounded above. q.e.d.

Lemma 3.11. Along the flow, $|\dot{\varphi}| \leq C$, where $C$ depends on $\Sigma_{0}, n, k$.
Proof. By (3.14) and (3.16), we have

$$
\frac{\partial \varphi}{\partial t}=\frac{v}{\phi F}=\frac{v^{2}}{\tilde{F}\left(\phi^{\prime} \delta_{i j}-\tilde{\sigma}^{i k} \varphi_{k j}\right)}=\frac{1}{G}
$$

where $\tilde{F}=\phi v F$.
Let $G^{i j}=\frac{\partial G}{\partial \varphi_{i j}}, G^{k}=\frac{\partial G}{\partial \varphi_{k}}, G_{\varphi}=\frac{\partial G}{\partial \varphi}$ then

$$
G^{i j}=-\frac{1}{v^{2}} \tilde{F}_{l}^{i} \tilde{\sigma}^{l j}, \quad G_{\varphi}=\frac{1}{v^{2}} \tilde{F}_{i}^{i} \phi \phi^{\prime \prime}
$$

thus

$$
\begin{aligned}
\frac{\partial \dot{\varphi}}{\partial t} & =-\frac{\dot{G}}{G^{2}}=-\frac{1}{G^{2}}\left(G^{i j} \dot{\varphi}_{i j}+G^{k} \dot{\varphi}_{k}+G_{\varphi} \dot{\varphi}\right) \\
& =\frac{1}{v^{2} G^{2}}\left(\tilde{F}_{l}^{i} \tilde{\sigma}^{l j} \dot{\varphi}_{i j}-v^{2} G^{k} \dot{\varphi}_{k}-\tilde{F}_{i}^{i} \phi \phi^{\prime \prime} \dot{\varphi}\right)
\end{aligned}
$$

By maximum principle, we conclude that $|\dot{\varphi}|$ is bounded above. q.e.d.
Lemma 3.12. Along the flow, $F \phi \geq c$, where $c$ depends on $\Sigma_{0}, n, k$.
Proof. Since $\dot{\varphi}=\frac{v}{\phi F}$, by Lemma 3.11, we have

$$
\frac{v}{\phi F} \leq C
$$

thus $F \phi \geq c$.
q.e.d.

Lemma 3.13. Along the flow, $\left|\kappa_{i} \phi\right| \leq C$, where $\kappa_{i}$ is the principal curvature of $\Sigma_{t}, C$ depends on $\Sigma_{0}, n, k$.

Proof. Consider $\log \eta-\log u+\frac{2 t}{n}$, where

$$
\eta=\sup \left\{h_{i j} \xi^{i} \xi^{j}: g_{i j} \xi^{i} \xi^{j}=1\right\}
$$

WLOG, we suppose that the maximum point occurs at $\eta=h_{1}^{1}$, and we have

$$
\begin{equation*}
\frac{\dot{h}_{1}^{1}}{h_{1}^{1}}-\frac{\dot{u}}{u}+\frac{2}{n} \geq 0 \tag{3.25}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{h_{1 i}^{1}}{h_{1}^{1}}-\frac{u_{i}}{u}=0, \quad \frac{h_{1 i j}^{1}}{h_{1}^{1}} \leq \frac{u_{i j}}{u} . \tag{3.26}
\end{equation*}
$$

By (3.20), (3.21) and the critical equation, we have

$$
\begin{align*}
0 \leq & \frac{1}{h_{1}^{1}}\left(-\frac{1}{F} h_{k}^{1} h_{1}^{k}+\frac{F^{p q, r s} h_{p q}{ }^{1} h_{r s 1}}{F^{2}}-\frac{2 F^{p q} h_{p q}{ }^{1} F^{r s} h_{r s 1}}{F^{3}}-\frac{1}{F} \bar{R}_{\nu 1 \nu}^{1}\right.  \tag{3.27}\\
& +\frac{g^{k 1} F^{p q}}{F^{2}}\left(h_{k 1, p q}-h_{q}^{m}\left(h_{k m} h_{p 1}-h_{k 1} h_{m p}\right)-h_{1}^{m}\left(h_{m k} h_{p q}-h_{k q} h_{m p}\right)\right. \\
& \left.\left.+h_{q}^{m} \bar{R}_{k p 1 m}+h_{1}^{m} \bar{R}_{k p q m}+\nabla_{p} \bar{R}_{k 1 q \nu}+\nabla_{k} \bar{R}_{1 p q \nu}\right)\right) \\
& -\frac{\phi^{\prime}}{F u}-\frac{\phi g^{i j} F_{i} r_{j}}{F^{2} u}+\frac{2}{n} .
\end{align*}
$$

Consider the term $\frac{F^{p q}}{F^{2}} \frac{h_{1, p q}^{1}}{h_{1}^{1}}$, by (3.26) and Lemma 3.2, we have

$$
\begin{align*}
\frac{F^{p q}}{F^{2}} \frac{h_{1, p q}^{1}}{h_{1}^{1}} & \leq \frac{F^{p q}}{F^{2}} \frac{u_{p q}}{u}  \tag{3.28}\\
& =\frac{F^{p q}}{F^{2} u}\left(g^{k l} h_{p q k} \Phi_{l}+\phi^{\prime} h_{p q}-\left(h^{2}\right)_{p q} u+g^{k l} \nabla_{l} \Phi \bar{R}_{\nu p k q}\right)
\end{align*}
$$

Inserting (3.28) into (3.27), together with the concavity of $F$, yields

$$
\begin{align*}
0 \leq & \frac{g^{k 1} F^{p q}}{h_{1}^{1} F^{2}}\left(h_{q}^{m} \bar{R}_{k p 1 m}+h_{1}^{m} \bar{R}_{k p q m}+\nabla_{p} \bar{R}_{k 1 q \nu}+\nabla_{k} \bar{R}_{1 p q \nu}-h_{1}^{m} h_{m k} h_{p q}\right)  \tag{3.29}\\
& +\frac{1}{h_{1}^{1}}\left(-\frac{1}{F} h_{k}^{1} h_{1}^{k}-\frac{1}{F} \bar{R}_{\nu 1 \nu}^{1}\right)+\frac{g^{k l} F^{p q}}{F^{2} u} \nabla_{l} \Phi \bar{R}_{\nu p k q}+\frac{2}{n}
\end{align*}
$$

By (3.22), we have

$$
\begin{align*}
0 \leq & \frac{g^{k 1} F^{p q}}{h_{1}^{1} F^{2}}\left(h_{q}^{m} \bar{R}_{k p 1 m}+h_{1}^{m} \bar{R}_{k p q m}+\nabla_{p} \bar{R}_{k 1 q \nu}+\nabla_{k} \bar{R}_{1 p q \nu}-h_{1}^{m} h_{m k} h_{p q}\right)  \tag{3.30}\\
& +\frac{1}{h_{1}^{1}}\left(-\frac{1}{F} h_{k}^{1} h_{1}^{k}-\frac{1}{F} \bar{R}_{\nu 1 \nu}^{1}\right)+\frac{2}{n}
\end{align*}
$$

By Lemma 3.3, all terms involving curvature terms of the ambient space are uniformly bounded by $C \phi^{-1-n}$, i.e.

$$
\begin{aligned}
& \frac{g^{k 1} F^{p q}}{F^{2}}\left(h_{q}^{m} \bar{R}_{k p 1 m}+h_{1}^{m} \bar{R}_{k p q m}+\nabla_{p} \bar{R}_{k 1 q \nu}+\nabla_{k} \bar{R}_{1 p q \nu}\right) \\
\leq & \frac{C F_{i}^{i}}{F^{2} \phi^{n+1}} h_{1}^{1} \leq C h_{1}^{1}
\end{aligned}
$$

where we have used Lemma 3.5 and Lemma 3.12 in the last inequality. Plug it into (3.30), we have

$$
\begin{aligned}
0 & \leq \frac{1}{h_{1}^{1}}\left(-\frac{2}{F} h_{k}^{1} h_{1}^{k}-\frac{1}{F} \bar{R}_{\nu 1 \nu}^{1}\right)+C \leq \frac{1}{h_{1}^{1}}\left(-\frac{2}{F \phi} h_{k}^{1} h_{1}^{k} \phi+\frac{C}{F \phi^{n+1}}\right)+C \\
& \leq-C h_{1}^{1} \phi+\frac{C}{h_{1}^{1} \phi}+C
\end{aligned}
$$

i.e. $h_{1}^{1} \phi \leq C$.

By Lemma 3.6 and Lemma 3.8, $c e^{\frac{t}{n}} \leq u \leq \phi \leq C e^{\frac{t}{n}}$, the lemma now follows by the definition of the test function.
q.e.d.

Lemma 3.14. Along the flow, $F$ is uniformly elliptic.
Proof. It follows directly from Lemma 3.10, Lemma 3.12 and Lemma 3.13. q.e.d.

### 3.5. Asymptotic behaviors.

Lemma 3.15. Along the flow, $|\nabla \varphi| \leq C e^{-\alpha t}$, where $C, \alpha$ depends on $\Sigma_{0}, n, k$.

Proof. We proceed as in Lemma 3.7, by (3.23), we have

$$
\begin{aligned}
\frac{\partial w}{\partial t}= & \frac{1}{v^{2} G^{2}}\left(\tilde{F}_{l}^{i} \tilde{\sigma}^{l j} \omega_{i j}-\tilde{F}_{i}^{i}|\nabla \varphi|^{2}+\tilde{F}_{l}^{i} \varphi_{i} \varphi^{l}-v^{2} G^{l} \omega_{l}-2 \tilde{F}_{i}^{i} \phi \phi^{\prime \prime} \omega\right) \\
& -\frac{1}{v^{2} G^{2}} \tilde{F}_{l}^{i} \tilde{\sigma}^{l j} \varphi_{k i} \varphi_{j}^{k}
\end{aligned}
$$

By Lemma 3.14, $F$ is uniformly elliptic, i.e. $\tilde{F}^{i j}$ is uniformly elliptic, by Lemma $3.10, \phi F$ is bounded above, then consider $\tilde{\omega}=\omega e^{\lambda t}$, at the maximum point, we have

$$
\frac{\partial \tilde{\omega}}{\partial t} \leq \frac{1}{v^{2} G^{2}}\left(-\tilde{F}_{i}^{i}|\nabla \varphi|^{2}+\tilde{F}_{l}^{i} \varphi_{i} \varphi^{l}\right) e^{\lambda t}+\lambda \tilde{\omega} \leq\left(-\frac{c}{\phi^{2} F^{2}}+\lambda\right) \tilde{\omega}
$$

thus $\tilde{\omega}$ is uniformly bounded, we have $|\nabla \varphi|$ decays exponentially. q.e.d.
Lemma 3.16. Along the flow, $F \phi \leq n+C e^{-\alpha t}$, where $C, \alpha$ depends only on $\Sigma_{0}, n, k$.

Proof. We proceed as in Lemma 3.10, by (3.24), we have

$$
0 \leq 2 \frac{\phi^{\prime} v}{F \phi}-\frac{1}{n}+C \frac{F_{i}^{i}}{F^{2} \phi^{n+1}}-\frac{F_{i}^{i}\left(\phi^{\prime}\right)^{2}}{F^{2} \phi^{2}}+\frac{F^{i j} r_{i} r_{j}\left(\phi^{\prime}\right)^{2}}{F^{2} \phi^{2}}
$$

By Lemma 3.14, $F$ is uniformly elliptic, by Lemma 3.15, $|\nabla \varphi|$ decays exponentially, then

$$
0 \leq \frac{2}{F \phi}-\frac{1}{n}-\frac{n}{F^{2} \phi^{2}}+C e^{-\alpha t}
$$

i.e.

$$
F \phi \leq n+C e^{-\alpha t} . \quad \text { q.e.d. }
$$

Lemma 3.17. We have

$$
\left|h_{j}^{i} \phi-\delta_{j}^{i}\right| \leq C e^{-\alpha t}
$$

where $C, \alpha$ depends only on $\Sigma_{0}, n, k$. Moreover, for any $p, q \geq 0$, we have

$$
\left|\left(\frac{\partial}{\partial t}\right)^{p}(\phi \nabla)^{q} \phi^{2} \nabla h_{j}^{i}\right| \leq C e^{-\alpha t}
$$

where $\nabla$ is the unit gradient on $\Sigma_{t}$ and $C$ depends in addition on $p, q$.
Proof. To prove the lemma, we first notice that by (3.16) and (3.14), we have

$$
h_{j}^{i}=\frac{\phi^{\prime}}{\phi v} \delta_{j}^{i}-\frac{1}{\phi v} \tilde{\sigma}^{i k} \varphi_{k j}
$$

and

$$
\frac{\partial \varphi}{\partial t}=\frac{v}{\phi F}=\frac{v}{\tilde{F}}
$$

where

$$
\tilde{F}=\phi F=F\left(\frac{\phi^{\prime}}{v} \delta_{j}^{i}-\frac{1}{v} \tilde{\sigma}^{i k} \varphi_{k j}\right)
$$

By the Lemma 3.7 and Lemma 3.13, we know that $\nabla \varphi$ and $\nabla^{2} \varphi$ is uniformly bounded. By Evans-Krylov, we have $|\varphi|_{2, \alpha} \leq C$. By standard interpolation inequality, we have $\nabla^{2} \varphi$ decays exponentially as $\nabla \varphi$ decays exponentially by Lemma 3.15. Thus from the definition of $h_{j}^{i}$ above, we have the first inequality.

By Schauder estimate, we have $|\varphi|_{l} \leq C e^{-\alpha t}$ for all $l \geq 1$.
By the definition of $h_{j}^{i}$, we have

$$
\begin{aligned}
\nabla h_{j}^{i}= & \left(\frac{\phi^{\prime \prime}}{\phi v}-\frac{\phi^{2}}{\phi^{2} v}\right) \delta_{j}^{i} \nabla r-\frac{\phi^{\prime}}{\phi v^{3}} \delta_{j}^{i} \varphi_{k} \nabla \varphi_{k} \\
& +\frac{\phi^{\prime}}{\phi^{2} v} \tilde{\sigma}^{i k} \varphi_{k j} \nabla r+\frac{1}{\phi v^{3}} \tilde{\sigma}^{i k} \varphi_{k j} \varphi_{l} \nabla \varphi_{l} \\
& +\frac{1}{\phi v} \nabla \varphi^{i} \varphi^{k} \varphi_{k j}+\frac{1}{\phi v} \nabla \varphi^{k} \varphi^{i} \varphi_{k j}-\frac{1}{\phi v} \tilde{\sigma}^{i k} \nabla \varphi_{k j} .
\end{aligned}
$$

Since $|\varphi|_{l} \leq C e^{-\alpha t}$ for all $l \geq 1$, this implies

$$
\left|\phi^{2} \nabla h_{j}^{i}\right| \leq C e^{-\alpha t}
$$

By induction, we have

$$
\left|\left(\frac{\partial}{\partial t}\right)^{p}(\phi \nabla)^{q} \phi^{2} \nabla h_{j}^{i}\right| \leq C e^{-\alpha t}
$$

for all $p, q \geq 0$.
q.e.d.

Lemma 3.18. Let $\tilde{g}_{i j}=\phi^{-2} g_{i j}$ be a normalized metric, then

$$
\left|\tilde{g}_{i j}-\sigma_{i j}\right| \leq C e^{-\alpha t},
$$

where $\sigma_{i j}$ is the standard metric on $\mathbb{S}^{n}$ and $C, \alpha$ depends only on $\Sigma_{0}, n, k$. Moreover, for any $p, q \geq 0$, we have

$$
\left|\left(\frac{\partial}{\partial t}\right)^{p}(\phi \nabla)^{q} \phi \nabla \tilde{g}_{i j}\right| \leq C e^{-\alpha t}
$$

where $\nabla$ is the unit gradient on $\Sigma_{t}$ and $C$ depends in addition on $p, q$.
Proof. Following the step in [19], we consider the rescaled hypersurface as $\hat{X}=X e^{-\frac{t}{n}}$. Then we have $\hat{r}=r e^{-\frac{t}{n}}$, thus

$$
\hat{g}_{i j}=\phi^{2}(\hat{r}) \sigma_{i j}+\hat{r}_{i} \hat{r}_{j} .
$$

By Lemma 3.6 and Lemma 3.15, we have $c_{0} \leq \hat{r} \leq C_{0}$ uniformly, and $\left|\hat{r}_{i}\right| \leq C e^{-\alpha t}$, thus

$$
c_{0} \sigma \leq \hat{g} \leq C_{0} \sigma
$$

for $t$ large enough, i.e. $\hat{g}$ is well defined.
Now let's prove that $\hat{g}$ converges to $\hat{g}_{\infty}$. By Lemma 3.15, we have

$$
\frac{\partial \hat{g}_{i j}}{\partial t}=2 \phi(\hat{r}) \phi^{\prime}(\hat{r})\left(\frac{v}{F} e^{-\frac{t}{n}}-\frac{1}{n} r e^{-\frac{t}{n}}\right) \sigma_{i j}+\frac{\partial}{\partial t}\left(\hat{r}_{i} \hat{r}_{j}\right) \leq C e^{-\alpha t}
$$

Thus $\hat{g}$ converges exponentially fact to $\hat{g}_{\infty}$. To prove that $\hat{g}_{\infty}$ is a round metric, we only need to prove that $\hat{r}$ is constant. Since $\hat{r}$ is defined on $\mathbb{S}^{n}$, we take derivative of $\mathbb{S}^{n}$ on $\hat{r}$ to obtain

$$
\left|\nabla_{\mathbb{S}^{n}} \hat{r}\right|=\left|\nabla_{\mathbb{S}^{n}} r e^{-\frac{t}{n}}\right| \leq C e^{-\alpha t}
$$

Thus $\hat{r}$ is constant for $t=\infty$, i.e. we have

$$
r=r_{0} e^{\frac{t}{n}}+O\left(e^{\left(\frac{1}{n}-\alpha\right) t}\right)
$$

and

$$
\phi(r)=r_{0} e^{\frac{t}{n}}+O\left(e^{\left(\frac{1}{n}-\alpha\right) t}\right)
$$

Hence, at time $t$, we have

$$
g_{i j}=\phi^{2}(r)\left(\sigma_{i j}+\varphi_{i} \varphi_{j}\right)=r_{0}^{2} e^{\frac{2 t}{n}} \sigma_{i j}+O\left(e^{\left(\frac{2}{n}-2 \alpha\right) t}\right)
$$

and the normalized metric $\tilde{g}_{i j}$ satisfies

$$
\tilde{g}_{i j}=\phi^{-2} g_{i j}=\sigma_{i j}+O\left(e^{-\alpha t}\right)
$$

Similar to the previous lemma, high regularity decay estimates follows by Lemma 3.15 and the definition of $\tilde{g}_{i j}$. q.e.d.

Remark 3.1. Let $k \geq 2$. Let $g$ be a metric on $\mathbb{S}^{n}$ so that $\left(S^{n}, g\right)$ isometrically embeds into $\mathbb{M}_{m}^{n+1}$ as a star-shaped, $k$-convex, closed hypersurface in $\mathbb{M}_{m}^{n+1}$ with $\operatorname{Ric}(\nu, \nu) \leq 0$. Combining results in this section and arguments in [12, Section 3], one knows that $g$ can be connected to a round metric within the space of positive scalar curvature metrics on $\mathbb{S}^{n}$. Therefore, repeating the proof in [12], we know that the conclusion of [12, Theorem 1.2] holds for such a metric $g$.

## 4. Bartnik-Shi-Tam type asymptotically flat extensions

Let $\Sigma^{n} \subset \mathbb{M}_{m}^{n+1}$ be a closed, star-shaped, 2-convex hypersurface satisfying

$$
\begin{equation*}
\overline{\operatorname{Ric}}(\nu, \nu) \leq 0 \tag{4.1}
\end{equation*}
$$

Here $\overline{\operatorname{Ric}}(\cdot, \cdot)$ is the Ricci curvature of the Schwarzschild manifold $\mathbb{M}_{m}^{n+1}$ and $\nu$ is the outward unit normal to $\Sigma$. By Theorem 3.1, there exists a smooth solution $\left\{\Sigma_{t}\right\}_{0 \leq t \leq \infty}$, consisting of star-shaped hypersurfaces, to

$$
\begin{equation*}
\frac{\partial X}{\partial t}=\frac{n-1}{2 n} \frac{\sigma_{1}}{\sigma_{2}} \nu \tag{4.2}
\end{equation*}
$$

with initial condition $\Sigma_{0}=\Sigma$. By Lemma 3.9, condition (4.1) implies that the scalar curvature $R$ of each $\Sigma_{t}$ is positive.

Let $\mathbb{E}$ denote the exterior of $\Sigma$ in $\mathbb{M}_{m}^{n+1}$, which is swept by $\left\{\Sigma_{t}\right\}_{0 \leq t \leq \infty}$. On $\mathbb{E}$, the Schwarzschild metric $\bar{g}$ can be written as

$$
\bar{g}=f^{2} d t^{2}+g_{t}
$$

where $g_{t}$ is the induced metric on $\Sigma_{t}$ and

$$
f=\frac{n-1}{2 n} \frac{\sigma_{1}}{\sigma_{2}}>0
$$

Prompted by Proposition 2.2, we are interested in a new metric $g_{\eta}$ on $\mathbb{E}$, which takes the form of

$$
g_{\eta}=\eta^{2} d t^{2}+g_{t}
$$

and has zero scalar curvature. Here $\eta>0$ is a function on $\mathbb{E}$.
We first derive the equation for $\eta$. Adopting the notations in Section 2 , by (2.6), (2.8) and Gauss equation (2.9), we have

$$
\begin{aligned}
\frac{\partial}{\partial t} H_{\eta} & =-\Delta \eta-\eta\left(\left|A_{\eta}\right|^{2}+\operatorname{Ric}_{g_{\eta}}(\nu, \nu)\right) \\
& =-\Delta \eta-\eta\left(\eta^{-2} f^{2}|\bar{A}|^{2}+\eta^{-2} f^{2} \sigma_{2}-\frac{R}{2}\right) \\
& =-\Delta \eta-\eta^{-1} f^{2}|\bar{A}|^{2}-\eta^{-1} f^{2} \sigma_{2}+\frac{R}{2} \eta
\end{aligned}
$$

On the other hand,

$$
\frac{\partial}{\partial t} H_{\eta}=\frac{\partial}{\partial t}\left(\frac{f \bar{H}}{\eta}\right)=-\frac{f \bar{H}}{\eta^{2}} \frac{\partial \eta}{\partial t}+\frac{1}{\eta} \frac{\partial}{\partial t}(f \bar{H})
$$

Thus

$$
-\frac{f \bar{H}}{\eta^{2}} \frac{\partial \eta}{\partial t}+\frac{1}{\eta} \frac{\partial}{\partial t}(f \bar{H})=-\Delta \eta-u^{-1} f^{2}|\bar{A}|^{2}-\eta^{-1} f^{2} \sigma_{2}+\frac{R}{2} \eta
$$

i.e.

$$
\begin{equation*}
-\frac{\partial \eta}{\partial t}+\frac{\eta^{2}}{f \bar{H}} \Delta \eta=\frac{\eta^{3} R}{2 f \bar{H}}-\frac{\eta}{f \bar{H}}\left(f^{2}|\bar{A}|^{2}+f^{2} \sigma_{2}+\frac{\partial}{\partial t}(f \bar{H})\right) \tag{4.3}
\end{equation*}
$$

Equation (4.3) is as the same as (5) in [17]. The following assertion on the long time existence of $\eta$ on $\mathbb{E}$ follows directly from [17, Proposition 2] and Lemma 3.9.

Lemma 4.1. Let $\Sigma$ be a closed, star-shaped, 2-convex hypersurface in $\mathbb{M}_{m}^{n+1}$ with $\overline{\operatorname{Ric}}(\nu, \nu) \leq 0$. Given any positive function $\psi>0$ on $\Sigma$, the solution to (4.3) with initial condition $\left.\eta\right|_{t=0}=\psi$ exists for all time and remains positive.

In what follows, we analyze the asymptotic behavior of $g_{\eta}$.
4.1. $C^{0}$ estimate of $\eta$. For the convenience of estimating $\eta$, we consider

$$
w=f^{-1} \eta
$$

By (4.3), (2.7) and (2.9), it is easily seen that $w$ satisfies the equation

$$
\begin{equation*}
-\frac{\partial w}{\partial t}+\frac{w^{2}}{\bar{H}}(f \Delta w+2 \nabla w \nabla f)=\frac{1}{2 \bar{H}}(f R-2 \Delta f)\left(w^{3}-w\right) \tag{4.4}
\end{equation*}
$$

Lemma 4.2. $w$ satisfies the estimate

$$
|w-1| \leq C \phi^{1-n}
$$

where $C$ depends only on $\Sigma_{0}$ and $n$.
Proof. It suffices to focus on $w$ for $t \geq t_{0}$ where $t_{0}$ is sufficiently large. Following the steps in [41], we define

$$
A(t)=\min _{\Sigma_{t}} \frac{f R-2 \Delta f}{\bar{H}}, \quad B(t)=\max _{\Sigma_{t}} \frac{f R-2 \Delta f}{\bar{H}}
$$

By Lemma 3.17, Lemma 3.3 and Gauss equation (2.9), we have

$$
\frac{f R-2 \Delta f}{\bar{H}}=\frac{n-1}{n}+C e^{-\alpha t}
$$

thus both $A(t)$ and $B(t)$ are positive for $t \geq t_{0}$.
We first seek an upper bound for $w$. Define

$$
P(t)=\left(1-C_{1} \exp \left(-\int_{t_{0}}^{t} A(s) d s\right)\right)^{-\frac{1}{2}}
$$

with $C_{1}=1-\left(\max _{\Sigma_{t_{0}}} w+1\right)^{-2}$. It is clear that $P-w \geq 0$ at $t_{0}$. Taking derivative, we have

$$
\begin{aligned}
\frac{d}{d t} P(t) & =-\frac{1}{2}\left(1-C_{1} \exp \left(-\int_{t_{0}}^{t} A(s) d s\right)\right)^{-\frac{3}{2}} C_{1} \exp \left(-\int_{t_{0}}^{t} A(s) d s\right) A(t) \\
& =\frac{1}{2} P^{3}\left(P^{-2}-1\right) A=\frac{1}{2}\left(P-P^{3}\right) A
\end{aligned}
$$

At the minimum point of $P-w$, we have

$$
\frac{d}{d t}(P-w) \leq 0, \quad \nabla w=0, \quad \nabla^{2} w \leq 0
$$

thus

$$
0 \geq \frac{1}{2}\left(P-P^{3}\right) A+\frac{1}{2 \bar{H}}(f R-2 \Delta f)\left(w^{3}-w\right)
$$

Since $A \leq \frac{f R-2 \Delta f}{\bar{H}}$, we have

$$
0 \geq P-P^{3}+w^{3}-w
$$

i.e. $P-w \geq 0$ as $P \geq 1$. Therefore, $w \leq P$ for all time $t \geq t_{0}$.

Next, we seek a lower bound of $w$. We consider two cases.
Case 1: $\min _{\Sigma_{t_{0}}} w \geq 1$. Define

$$
Q(t)=\left(1+C_{2} \exp \left(-\int_{t_{0}}^{t} B(s) d s\right)\right)^{-\frac{1}{2}}
$$

where $C_{2}=\left(\min _{\Sigma_{t_{0}}} w\right)^{-2}-1$. It's clear that $w-Q \geq 0$ at $t_{0}$. By a similar computation as above, we have

$$
\frac{d}{d t} Q(t)=\frac{1}{2}\left(Q-Q^{3}\right) B
$$

At the minimum point of $w-Q$,

$$
\frac{d}{d t}(w-Q) \leq 0, \quad \nabla w=0, \quad \nabla^{2} w \geq 0
$$

Thus

$$
0 \geq-\frac{1}{2 \bar{H}}(f R-2 \Delta f)\left(w^{3}-w\right)-\frac{1}{2}\left(Q-Q^{3}\right) B
$$

Since $B \geq \frac{f R-2 \Delta f}{\bar{H}}$, we have

$$
0 \geq w-w^{3}+Q^{3}-Q
$$

which implies $w \geq Q$ as $Q \geq 1$. Thus, $w \geq Q$ for all $t \geq t_{0}$.
Case 2: $\min _{\Sigma_{t_{0}}} w<1$. Define

$$
\tilde{Q}(t)=\left(1+\left(C_{2}+\epsilon\right) \exp \left(-\int_{t_{0}}^{t}(A(s)-\epsilon) d s\right)\right)^{-\frac{1}{2}}
$$

For $\epsilon$ small enough, we have

$$
\tilde{Q}\left(t_{0}\right)=\left(1+C_{2}+\epsilon\right)^{-\frac{1}{2}}<\min _{\Sigma_{t_{0}}} w
$$

Suppose now at some $t_{1}>t_{0}$, we have $\min _{\Sigma_{t_{1}}}(w-\tilde{Q})=0$ and, for $t_{0} \leq t \leq t_{1}$, we have $w-\tilde{Q} \geq 0$. Then at $t_{1}$,

$$
\frac{d}{d t}(w-\tilde{Q}) \leq 0, \quad \nabla w=0, \quad \nabla^{2} w \geq 0
$$

Since

$$
\frac{d}{d t} \tilde{Q}(t)=\frac{1}{2}\left(\tilde{Q}-\tilde{Q}^{3}\right)(A-\epsilon)
$$

we have

$$
0 \geq-\frac{1}{2 \bar{H}}(f R-2 \Delta f)\left(w^{3}-w\right)-\frac{1}{2}\left(\tilde{Q}-\tilde{Q}^{3}\right)(A-\epsilon)
$$

Since $A-\epsilon<\frac{f R-2 \Delta f}{H}$, the above implies

$$
0 \geq \tilde{Q}-\tilde{Q}^{3}
$$

Contradict to the fact $\tilde{Q}<1$. Since $\epsilon$ is arbitrary, we thus have

$$
w \geq\left(1+C_{2} \exp \left(-\int_{t_{0}}^{t} A(s) d s\right)\right)^{-\frac{1}{2}}
$$

Finally, note that $A(t)=\frac{n-1}{n}+O\left(e^{-\alpha t}\right)$, we have

$$
\exp \left(-\int_{t_{0}}^{t} A(t)\right) \leq C e^{-\frac{n-1}{n} t} \leq C \phi^{1-n}
$$

Therefore, $w \geq 1-C \phi^{1-n}$. Similarly, $w \leq 1+C \phi^{1-n}$. Thus, we conclude

$$
|w-1| \leq C \phi^{1-n} . \quad \text { q.e.d. }
$$

4.2. Asymptotic behavior of $w$. Following [41], we consider the rescaled metric

$$
\tilde{g}_{i j}=\phi^{-2} g_{i j}
$$

on each $\Sigma_{t}$. Here we omit writing $t$ for the sake of convenience. Note that by Lemma 3.18, $\tilde{g}_{i j}$ converges to $\sigma_{i j}$ exponentially fast.

For any function $h$ and $l$,

$$
<\tilde{\nabla} h, \tilde{\nabla} l>_{\tilde{g}}=\phi^{2}<\nabla h, \nabla l>_{g}
$$

Henceforth, for convenience, we simply write the above as

$$
\tilde{\nabla} h \tilde{\nabla} l=\phi^{2} \nabla h \nabla l .
$$

Direct calculation gives

$$
\Delta=\phi^{-2} \tilde{\Delta}+(n-2) \phi^{-3} \tilde{\nabla} \phi \tilde{\nabla}
$$

In terms of $\tilde{g}_{i j}$, equation (4.4) becomes

$$
\begin{align*}
& -\frac{\partial w}{\partial t}+\frac{w^{2}}{\bar{H} \phi^{2}}\left(f \tilde{\Delta} w+(n-2) f \phi^{-1} \tilde{\nabla} \phi \tilde{\nabla} w+2 \tilde{\nabla} w \tilde{\nabla} f\right)  \tag{4.5}\\
= & \frac{1}{2 \bar{H}}\left(f R-2 \phi^{-2} \tilde{\Delta} f-2(n-2) \phi^{-3} \tilde{\nabla} \phi \tilde{\nabla} f\right)\left(w^{3}-w\right),
\end{align*}
$$

which can be re-written as

$$
\begin{aligned}
& -\frac{\partial w}{\partial t}+\tilde{\nabla}\left(\frac{f w^{2}}{\bar{H} \phi^{2}} \tilde{\nabla} w\right)-\frac{2 f}{\bar{H} \phi^{2}}|\tilde{\nabla} w|^{2} \\
= & w^{2} \tilde{\nabla}\left(\frac{f}{\bar{H} \phi^{2}}\right) \tilde{\nabla} w-\frac{w^{2}}{\bar{H} \phi^{2}}\left((n-2) f \phi^{-1} \tilde{\nabla} \phi+2 \tilde{\nabla} f\right) \tilde{\nabla} w \\
& +\frac{1}{2 \bar{H}}\left(f R-2 \phi^{-2} \tilde{\Delta} f-2(n-2) \phi^{-3} \tilde{\nabla} \phi \tilde{\nabla} f\right)\left(w^{3}-w\right) .
\end{aligned}
$$

By Lemma 4.2, this is a uniformly parabolic PDE. In addition, the term $-\frac{2 f}{H \phi^{2}}|\tilde{\nabla} w|^{2}$ has a good sign and the coefficient of $\tilde{\nabla} w$ is uniformly bounded. Thus we may directly apply standard Moser iteration to conclude that $w \in C^{\alpha}$.

By considering the equation for $w-1$ and applying Schauder estimate and Lemma 4.2 , for any $k, l \geq 0$, we have

$$
\begin{equation*}
\left|\left(\frac{\partial}{\partial t}\right)^{k} \tilde{\nabla}^{l}(w-1)\right| \leq C \phi^{1-n} \tag{4.6}
\end{equation*}
$$

where $C$ depends only on $\Sigma_{0}, n$ and $k, l$. As in [41], we define

$$
\begin{equation*}
\mathfrak{m}=\frac{1}{2} \phi^{n-1}\left(1-w^{-2}\right) . \tag{4.7}
\end{equation*}
$$

Lemma 4.3. There exists a constant $m_{0}$, such that

$$
\left|\mathfrak{m}-m_{0}\right|+\left|\nabla_{0} \mathfrak{m}\right|+\left|\frac{\partial \mathfrak{m}}{\partial t}\right| \leq C e^{-\alpha t}
$$

where $\nabla_{0}$ is the standard gradient on $\mathbb{S}^{n}$ and $C, \alpha$ depends only on $\Sigma_{0}$ and $n$.

Proof. By (4.6) and definition of $\mathfrak{m}$, for any $k, l \geq 0$, we have

$$
\left|\left(\frac{\partial}{\partial t}\right)^{k} \tilde{\nabla}^{l} \mathfrak{m}\right| \leq C
$$

where $C$ depends only on $\Sigma_{0}, n$ and $k, l$. By (4.5), $\mathfrak{m}$ satisfies

$$
\begin{aligned}
\frac{\partial \mathfrak{m}}{\partial t}= & \frac{n-1}{2} \phi^{n-2} \phi^{\prime}\left(1-w^{-2}\right) \frac{\partial r}{\partial t}+\phi^{n-1} w^{-3} \frac{\partial w}{\partial t} \\
= & \frac{n-1}{2} \phi^{n-2} \phi^{\prime} v f\left(1-w^{-2}\right) \\
& +\frac{\phi^{n-3}}{\bar{H} w}\left(f \tilde{\Delta} w+(n-2) f \phi^{-1} \tilde{\nabla} \phi \tilde{\nabla} w+2 \tilde{\nabla} w \tilde{\nabla} f\right) \\
& -\frac{\phi^{n-1}}{2 \bar{H} w^{3}}\left(f R-2 \phi^{-2} \tilde{\Delta} f-2(n-2) \phi^{-3} \tilde{\nabla} \phi \tilde{\nabla} f\right)\left(w^{3}-w\right)
\end{aligned}
$$

Denote by $p$ any function that satisfies

$$
\left|\left(\frac{\partial}{\partial t}\right)^{k} \tilde{\nabla}^{l} p\right| \leq C e^{-\alpha t}
$$

for any $k, l \geq 0$, where $C, \alpha$ is uniform constants may depend on $k, l$. By Lemma 3.7 and Lemma 3.17, we have

$$
\phi^{-1} \tilde{\nabla} \phi=p, \quad \phi^{-1} \tilde{\nabla} f=p
$$

Thus

$$
\frac{\phi^{n-3}}{\bar{H} w} f \phi^{-1} \tilde{\nabla} \phi \tilde{\nabla} w=\left(\phi^{n-1} \tilde{\nabla} w\right)\left(\phi^{-1} \tilde{\nabla} \phi\right) \frac{f}{\bar{H} w \phi^{2}}=p
$$

Similarly,

$$
\begin{gathered}
\frac{\phi^{n-3}}{\bar{H} w} \tilde{\nabla} w \tilde{\nabla} f=\left(\phi^{n-1} \tilde{\nabla} w\right)\left(\phi^{-1} \tilde{\nabla} f\right) \frac{1}{\bar{H} w \phi}=p \\
\frac{\phi^{n-1}}{\bar{H} w^{3}} \phi^{-2} \tilde{\Delta} f\left(w^{3}-w\right)=\left(\phi^{n-1}\left(1-w^{-2}\right)\right)\left(\phi^{-1} \tilde{\Delta} f\right) \frac{1}{\bar{H} \phi}=p
\end{gathered}
$$

and

$$
\begin{aligned}
& \frac{\phi^{n-1}}{\bar{H} w^{3}} \phi^{-3} \tilde{\nabla} \phi \tilde{\nabla} f\left(w^{3}-w\right) \\
= & \left(\phi^{n-1}\left(1-w^{-2}\right)\right)\left(\phi^{-1} \tilde{\nabla} f\right)\left(\phi^{-1} \tilde{\nabla} \phi\right) \frac{1}{\bar{H} \phi}=p .
\end{aligned}
$$

Hence,

$$
\frac{\partial \mathfrak{m}}{\partial t}=\frac{n-1}{2} \phi^{n-2} \phi^{\prime} v f\left(1-w^{-2}\right)+\frac{\phi^{n-3} f}{\bar{H} w} \tilde{\Delta} w-\frac{\phi^{n-1} f R}{2 \bar{H}}\left(1-w^{-2}\right)+p
$$

On the other hand,

$$
\begin{aligned}
& \frac{n-1}{2} \phi^{n-2} \phi^{\prime} v f\left(1-w^{-2}\right)-\frac{\phi^{n-1} f R}{2 \bar{H}}\left(1-w^{-2}\right) \\
= & \frac{\phi^{n-1}\left(1-w^{-2}\right)}{2} f\left((n-1) \phi^{-1} \phi^{\prime} v-\frac{R}{\bar{H}}\right)=p .
\end{aligned}
$$

Therefore,

$$
\frac{\partial \mathfrak{m}}{\partial t}=\frac{\phi^{n-3} f}{\bar{H} w} \tilde{\Delta} w+p
$$

Note that

$$
\tilde{\nabla} \mathfrak{m}=\frac{n-1}{2} \phi^{n-2} \tilde{\nabla} \phi\left(1-w^{-2}\right)+\phi^{n-1} w^{-3} \tilde{\nabla} w
$$

and

$$
\begin{aligned}
\tilde{\Delta} \mathfrak{m}= & \frac{(n-1)(n-2)}{2} \phi^{n-3}|\tilde{\nabla} \phi|^{2}\left(1-w^{-2}\right)+\frac{n-1}{2} \phi^{n-2} \tilde{\Delta} \phi\left(1-w^{-2}\right) \\
& +2(n-1) \phi^{n-2} w^{-3} \tilde{\nabla} \phi \tilde{\nabla} w-3 \phi^{n-1} w^{-4}|\tilde{\nabla} w|^{2}+\phi^{n-1} w^{-3} \tilde{\Delta} w
\end{aligned}
$$

Thus,

$$
\tilde{\Delta} \mathfrak{m}=-3 \phi^{n-1} w^{-4}|\tilde{\nabla} w|^{2}+\phi^{n-1} w^{-3} \tilde{\Delta} w+p=\phi^{n-1} w^{-3} \tilde{\Delta} w+p
$$

Therefore,

$$
\begin{aligned}
\frac{\partial \mathfrak{m}}{\partial t} & =\frac{\phi^{n-3} f}{\bar{H} w}\left(\phi^{1-n} w^{3} \tilde{\Delta} \mathfrak{m}+\phi^{1-n} w^{3} p\right)+p \\
& =\frac{f w^{2}}{\bar{H} \phi^{2}} \tilde{\Delta} \mathfrak{m}+p=\frac{1}{n^{2}} \tilde{\Delta} \mathfrak{m}+p
\end{aligned}
$$

By Lemma 3.18, we have $\tilde{g}_{i j}=\sigma_{i j}+p$, where $\sigma_{i j}$ is the standard metric on $\mathbb{S}^{n}$. Thus $\tilde{\Delta} \mathfrak{m}=\Delta_{0} \mathfrak{m}+p$, where $\Delta_{0}$ is the standard Laplacian on $\mathbb{S}^{n}$. Now, by Lemma 2.6 in [41], we conclude that there exists a constant $m_{0}$, such that

$$
\left|\mathfrak{m}-m_{0}\right|+\left|\nabla_{0} \mathfrak{m}\right|+\left|\frac{\partial \mathfrak{m}}{\partial t}\right| \leq C e^{-\alpha t} . \quad \text { q.e.d. }
$$

Lemma 4.3 directly implies the following asymptotic expansion of $w$.
Lemma 4.4. As $t \rightarrow \infty$, $w$ satisfies

$$
w=1+m_{0} \phi^{1-n}+p
$$

where $p=O\left(\phi^{1-n-\alpha}\right)$ and $\left|\nabla_{0} p\right|=O\left(\phi^{-n-\alpha}\right)$. Here $\nabla_{0}$ denotes the standard gradient on $\left(\mathbb{S}^{n}, \sigma\right)$.
4.3. ADM mass of $g_{\eta}$. We now verify that the metric $g_{\eta}$ is asymptotically flat and we compute its ADM mass. Note that

$$
g_{\eta}=f^{2} d t^{2}+g_{t}+\left(\eta^{2}-f^{2}\right) d t^{2}=\bar{g}+\left(w^{2}-1\right) f^{2} d t^{2}
$$

where $\bar{g}$ is the metric on the Schwarzschild manifold $\mathbb{M}_{m}^{n+1}$ with mass $m$.

Let $r$ be the radial coordinate in (3.1). Let $z=\left(z_{1}, \ldots, z_{n+1}\right)$ denote the standard rectangular coordinates on the background Euclidean space

$$
\mathbb{R}^{n+1}=\left([0, \infty) \times \mathbb{S}^{n}, d r^{2}+r^{2} \sigma\right)
$$

Writing $\bar{g}=\bar{g}_{i j} d z_{i} d z_{j}$ and $g_{\eta}=g_{i j} d z_{i} d z_{j}$, we have

$$
\begin{equation*}
g_{i j}=\bar{g}_{i j}+b_{i j} \tag{4.8}
\end{equation*}
$$

where

$$
b_{i j}=\left(w^{2}-1\right) f^{2} \frac{\partial t}{\partial z_{i}} \frac{\partial t}{\partial z_{j}} .
$$

We need to analyze the term $\frac{\partial t}{\partial z_{i}}$. As $r=|z|$,

$$
\partial_{z_{i}}=\frac{z_{i}}{r} \partial_{r}+\left(\partial_{z_{i}}\right)^{T}
$$

where $\left(\partial_{z_{\alpha}}\right)^{T}$ is tangential to $\mathbb{S}^{n}$. By definition,

$$
\frac{\partial t}{\partial z_{i}}=d t\left(\partial_{z_{i}}\right)=\left\langle\bar{\nabla} t, \partial_{z_{i}}\right\rangle_{\bar{g}}=f^{-1}\left\langle\nu, \partial_{z_{i}}\right\rangle_{\bar{g}}
$$

Plugging in $\nu=\frac{1}{v}\left(\partial_{r}-\frac{r^{j} \partial_{j}}{\phi^{2}}\right)$, we have

$$
\begin{align*}
\frac{\partial t}{\partial z_{i}} & =\frac{1}{f v}\left(\frac{z_{i}}{r}-\frac{r^{j}}{\phi^{2}}\left\langle\partial_{j},\left(\partial_{z_{i}}\right)^{T}\right\rangle_{\bar{g}}\right)  \tag{4.9}\\
& =\frac{1}{f v}\left(\frac{z_{i}}{r}-r^{j}\left\langle\partial_{j},\left(\partial_{z_{i}}\right)^{T}\right\rangle_{\sigma}\right)
\end{align*}
$$

Thus,

$$
b_{i j}=\frac{w^{2}-1}{v^{2}}\left(\frac{z_{i}}{r}-r^{k}\left\langle\partial_{k},\left(\partial_{z_{i}}\right)^{T}\right\rangle_{\sigma}\right)\left(\frac{z_{j}}{r}-r^{l}\left\langle\partial_{l},\left(\partial_{z_{j}}\right)^{T}\right\rangle_{\sigma}\right)
$$

By Lemma 4.4, Lemma 3.7 and the fact that $\left|\left(\partial_{z_{i}}\right)^{T}\right| \leq \frac{1}{r}$, we have

$$
\left|b_{i j}\right|=O\left(|z|^{1-n}\right)
$$

Similarly computation gives

$$
|z|\left|\partial_{z} b_{i j}\right|+|z|^{2}\left|\partial_{z} \partial_{z} b_{i j}\right|=O\left(|z|^{1-n}\right)
$$

This shows that $g_{\eta}$ is asymptotically flat.
Lemma 4.5. The $A D M$ mass of $g_{\eta}=\eta^{2} d t^{2}+g_{t}$ equals $m+m_{0}$.
Proof. The ADM mass of $g_{\eta}$ is given by

$$
\frac{1}{2 n \omega_{n}} \lim _{r \rightarrow \infty} \int_{\mathbb{S}^{n}}\left(\frac{\partial g_{\eta_{i j}}}{\partial z_{i}}-\frac{\partial g_{\eta_{i i}}}{\partial z_{j}}\right) r^{n-1} z_{j} d \sigma
$$

By (4.8) and the fact that the ADM mass of $\bar{g}$ is $m$, the above limit is equal to

$$
\begin{equation*}
m+\frac{1}{2 n \omega_{n}} \lim _{r \rightarrow \infty} \int_{\mathbb{S}^{n}}\left(\frac{\partial b_{i j}}{\partial z_{i}}-\frac{\partial b_{i i}}{\partial z_{j}}\right) r^{n-1} z_{j} d \sigma \tag{4.10}
\end{equation*}
$$

Thus it suffices to calculate $\frac{\partial b_{i j}}{\partial z_{i}}$ and $\frac{\partial b_{i i}}{\partial z_{j}}$. We have

$$
\begin{aligned}
\frac{\partial b_{i j}}{\partial z_{i}}= & 2 w f^{2} \frac{\partial w}{\partial z_{i}} \frac{\partial t}{\partial z_{i}} \frac{\partial t}{\partial z_{j}}+2\left(w^{2}-1\right) f \frac{\partial f}{\partial z_{i}} \frac{\partial t}{\partial z_{i}} \frac{\partial t}{\partial z_{j}} \\
& +\left(w^{2}-1\right) f^{2}\left(\frac{\partial^{2} t}{\partial z_{i}^{2}} \frac{\partial t}{\partial z_{j}}+\frac{\partial t}{\partial z_{i}} \frac{\partial^{2} t}{\partial z_{j} \partial z_{i}}\right)
\end{aligned}
$$

Similarly,

$$
\begin{aligned}
\frac{\partial b_{i i}}{\partial z_{j}}= & 2 w f^{2} \frac{\partial w}{\partial z_{j}}\left(\frac{\partial t}{\partial z_{i}}\right)^{2}+2\left(w^{2}-1\right) f \frac{\partial f}{\partial z_{j}}\left(\frac{\partial t}{\partial z_{i}}\right)^{2} \\
& +2\left(w^{2}-1\right) f^{2} \frac{\partial t}{\partial z_{i}} \frac{\partial^{2} t}{\partial z_{j} \partial z_{i}}
\end{aligned}
$$

Thus,

$$
\begin{aligned}
\frac{\partial b_{i j}}{\partial z_{i}}-\frac{\partial b_{i i}}{\partial z_{j}}= & 2 w f^{2} \frac{\partial t}{\partial z_{i}}\left(\frac{\partial w}{\partial z_{i}} \frac{\partial t}{\partial z_{j}}-\frac{\partial w}{\partial z_{j}} \frac{\partial t}{\partial z_{i}}\right) \\
& +2\left(w^{2}-1\right) f \frac{\partial t}{\partial z_{i}}\left(\frac{\partial f}{\partial z_{i}} \frac{\partial t}{\partial z_{j}}-\frac{\partial f}{\partial z_{j}} \frac{\partial t}{\partial z_{i}}\right) \\
& +\left(w^{2}-1\right) f^{2}\left(\frac{\partial^{2} t}{\partial z_{i}^{2}} \frac{\partial t}{\partial z_{j}}-\frac{\partial t}{\partial z_{i}} \frac{\partial^{2} t}{\partial z_{j} \partial z_{i}}\right)
\end{aligned}
$$

By Lemma 4.4, we have

$$
\frac{\partial w}{\partial z_{i}}=(1-n) m_{0} \phi^{-n-1} z_{i}+O\left(\phi^{-n-\alpha}\right)
$$

By Lemma 3.7 and (4.9), we have

$$
\frac{\partial t}{\partial z_{i}}=\frac{1}{f} \frac{z_{i}}{\phi}+O\left(\phi^{-1-\alpha}\right)
$$

Therefore,

$$
2 w f^{2} \frac{\partial t}{\partial z_{i}}\left(\frac{\partial w}{\partial z_{i}} \frac{\partial t}{\partial z_{j}}-\frac{\partial w}{\partial z_{j}} \frac{\partial t}{\partial z_{i}}\right)=O\left(\phi^{-n-\alpha}\right)
$$

On other hand, by Lemma 3.17 and straightforward computation,

$$
\frac{\partial f}{\partial z_{i}}=\frac{z_{i}}{n \phi}+O\left(\phi^{-\alpha}\right)
$$

Thus,

$$
2\left(w^{2}-1\right) f \frac{\partial t}{\partial z_{i}}\left(\frac{\partial f}{\partial z_{i}} \frac{\partial t}{\partial z_{j}}-\frac{\partial f}{\partial z_{j}} \frac{\partial t}{\partial z_{i}}\right)=O\left(\phi^{-n-\alpha}\right)
$$

Again by Lemma 3.17, Lemma 3.7 and (4.9), we have

$$
\frac{\partial^{2} t}{\partial z_{i}^{2}}=\frac{n(n-2)}{\phi^{2}}+O\left(\phi^{-2-\alpha}\right), \frac{\partial^{2} t}{\partial z_{i} \partial z_{j}}=-\frac{2 n}{\phi^{4}} z_{i} z_{j}+O\left(\phi^{-2-\alpha}\right)
$$

Thus,

$$
\begin{aligned}
\left(w^{2}-1\right) f^{2}\left(\frac{\partial^{2} t}{\partial z_{i}^{2}} \frac{\partial t}{\partial z_{j}}-\frac{\partial t}{\partial z_{i}} \frac{\partial^{2} t}{\partial z_{j} \partial z_{i}}\right) & =2 m_{0} \phi^{1-n} f^{2} \frac{n^{2}}{\phi^{2}} \frac{z_{j}}{f \phi} \\
& =2 n m_{0} \phi^{-1-n} z_{j}+O\left(\phi^{-n-\alpha}\right)
\end{aligned}
$$

Therefore, we conclude

$$
\frac{\partial b_{i j}}{\partial z_{i}}-\frac{\partial b_{i i}}{\partial z_{j}}=2 n m_{0} \phi^{-1-n} z_{j}+O\left(\phi^{-n-\alpha}\right)
$$

which implies that the ADM mass of $g_{\eta}$ is $m+m_{0}$ by (4.10). q.e.d.
REmark 4.1. A more geometric way to compute the ADM mass of $g_{\eta}$ is as follows. The foliation $\left\{\Sigma_{t}\right\}$ is a family of nearly round hypersurfaces according to Definition 2.1 in [36]. Thus, if $\mathfrak{m}\left(g_{\eta}\right)$ is the mass of $g_{\eta}$, then by Theorem 1.2 in [36],

$$
\begin{align*}
& 2 n(n-1) \omega_{n} \mathfrak{m}\left(g_{\eta}\right) \\
= & \lim _{t \rightarrow \infty}\left(\frac{\left|\Sigma_{t}\right|}{\omega_{n}}\right)^{\frac{1}{n}} \int_{\Sigma_{t}}\left(R-\frac{n-1}{n} H_{\eta}^{2}\right) d \sigma \\
= & \lim _{t \rightarrow \infty}\left(\frac{\left|\Sigma_{t}\right|}{\omega_{n}}\right)^{\frac{1}{n}} \int_{\Sigma_{t}}\left(R-\frac{n-1}{n} \bar{H}^{2}+\frac{n-1}{n}\left(1-w^{-2}\right) \bar{H}^{2}\right) d \sigma  \tag{4.11}\\
= & 2 n(n-1) \omega_{n}\left(m+m_{0}\right),
\end{align*}
$$

where we have used the fact $\bar{g}$ has mass $m$ and

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \int_{\Sigma_{t}}\left(1-w^{-2}\right) \bar{H}^{2} d \sigma=2 n^{2} \omega_{n} m_{0} \tag{4.12}
\end{equation*}
$$

which follows from Lemma 4.4, Lemma 3.17 and Lemma 3.18.

## Lemma 4.6.

$$
\lim _{t \rightarrow \infty} \int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma=\lim _{t \rightarrow \infty} \int_{\Sigma_{t}} N \bar{H}\left(1-w^{-1}\right) d \sigma=n m_{0} \omega_{n}
$$

Proof. Similar to (4.12), this is a direct consequence of Lemma 4.4, Lemma 3.17 and Lemma 3.18.
q.e.d.

We summarize the results in Lemmas 4.1, 4.4, 4.5 and 4.6 in the following theorem.

Theorem 4.7. Let $\Sigma^{n} \subset \mathbb{M}_{m}^{n+1}$ be a closed, star-shaped, 2-convex hypersurface with $\overline{\operatorname{Ric}}(\nu, \nu) \leq 0$, where $\overline{\operatorname{Ric}}(\cdot, \cdot)$ is the Ricci curvature of $\mathbb{M}_{m}^{n+1}$ and $\nu$ is the outward unit normal to $\Sigma$. Let $\mathbb{E}$ denote the exterior of $\Sigma^{n}$ in $\mathbb{M}_{m}^{n+1}$, which is swept by a family of star-shaped hypersurfaces $\left\{\Sigma_{t}\right\}_{0 \leq t \leq \infty}$ that is a smooth solution to

$$
\frac{\partial X}{\partial t}=\frac{n-1}{2 n} \frac{\sigma_{1}}{\sigma_{2}} \nu
$$

with initial condition $\Sigma_{0}=\Sigma^{n}$. On $\mathbb{E}$, writing the Schwarzschild metric $\bar{g}$ as

$$
\bar{g}=f^{2} d t^{2}+g_{t}
$$

where $g_{t}$ is the induced metric on $\Sigma_{t}$ and $f=\frac{n-1}{2 n} \frac{\sigma_{1}}{\sigma_{2}}$. Then, given any smooth function $\psi>0$ on $\Sigma$, there exists a smooth function $\eta>0$ on $\mathbb{E}$ such that
(i) $\left.\eta\right|_{\Sigma}=\psi$, the metric $g_{\eta}=\eta^{2} d t^{2}+g_{t}$ has zero scalar curvature, and $\eta$ satisfies

$$
f^{-1} \eta=1+m_{0} \phi^{1-n}+p
$$

where $m_{0}$ is a constant, $p=O\left(\phi^{1-n-\alpha}\right)$ and $\left|\nabla_{0} p\right|=O\left(\phi^{-n-\alpha}\right)$;
(ii) the Riemannian manifold $\left(\mathbb{E}, g_{\eta}\right)$ is asymptotically flat; and
(iii) the ADM mass $\mathfrak{m}\left(g_{\eta}\right)$ of $g_{\eta}$ is given by

$$
\mathfrak{m}\left(g_{\eta}\right)=m+m_{0}=m+\lim _{t \rightarrow \infty} \frac{1}{n \omega_{n}} \int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma
$$

Remark 4.2. Since ( $\mathbb{E}, g_{\eta}$ ) is foliated by $\left\{\Sigma_{t}\right\}_{0 \leq t \leq \infty}$, which has positive mean curvature for each $t$, the boundary $\partial \mathbb{E}=\Sigma$ is outer minimizing in $\left(\mathbb{E}, g_{\eta}\right)$, meaning that $\Sigma$ minimizes area among all hypersurfaces in $\mathbb{E}$ that enclose $\Sigma$.

## 5. Geometric applications

In this section, we give applications of results in Sections 2-4. First, we prove Theorem 1.1.

Proof of Theorem 1.1. Let $\left(\Omega^{n+1}, \breve{g}\right)$ be a compact manifold given in Theorem 1.1. By assumptions (i), (ii) and the standard geometric measure theory, $\Sigma_{H}$ minimizes area among all closed hypersurfaces in $(\Omega, \breve{g})$ that encloses $\Sigma_{H}$.

Let $\mathbb{E}$ denote the exterior of $\Sigma^{n}$ in $\mathbb{M}_{m}^{n+1}$. Let $\eta>0$ be the smooth function on $\mathbb{E}$ given by Theorem 4.7 with an initial condition

$$
\begin{equation*}
\left.\eta\right|_{\Sigma}=\left.f\right|_{\Sigma} H^{-1} H_{m} \tag{5.1}
\end{equation*}
$$

This condition implies that the mean curvature of $\Sigma$ in $\left(\mathbb{E}, g_{\eta}\right)$ agrees with the mean curvature $H$ of $\Sigma_{O}$ in $(\Omega, \breve{g})$. Since $\Sigma_{O}$ is isometric to $\Sigma=\partial \mathbb{E}$, we can attach $\left(\mathbb{E}, g_{\eta}\right)$ to $(\Omega, \breve{g})$ along $\Sigma=\Sigma_{O}$ by matching the Gaussian neighborhood of $\Sigma$ in $\left(\mathbb{E}, g_{\eta}\right)$ to that of $\Sigma_{O}$ in $(\Omega, \breve{g})$. Denote the resulting manifold by $\hat{M}$ and its metric by $\hat{h}$. By construction, $\hat{h}$ is Lipschitz across $\Sigma$ and smooth everywhere else on $\hat{M} ; \hat{h}$ has nonnegative scalar curvature away from $\Sigma$; and the mean curvature of $\Sigma$ from both sides in $(\hat{M}, \hat{h})$ agree. Moreover, $\partial \hat{M}=\Sigma_{H}$ is a minimal hypersurface that is outer minimizing in $(\hat{M}, \hat{h})$. This outer minimizing property of $\Sigma_{H}$ is guaranteed by the fact that $\Sigma$ is outer minimizing in $\left(\mathbb{E}, g_{\eta}\right)$ and $\Sigma_{H}$ minimizes area among closed hypersurfaces in $(\Omega, \breve{g})$ that encloses
$\Sigma_{H}$. On such an $(\hat{M}, \hat{h})$, it is known that the Riemannian Penrose inequality, i.e. Theorem 1.4, still holds. (For a proof of this claim, see pages 279-280 in [35] for the case $n=2$ and Proposition 3.1 in [32] for $2 \leq n \leq 6$ ). Therefore, we have

$$
\begin{equation*}
\mathfrak{m}\left(g_{\eta}\right) \geq \frac{1}{2}\left(\frac{\left|\Sigma_{H}\right|}{\omega_{n}}\right)^{\frac{n-1}{n}} \tag{5.2}
\end{equation*}
$$

By (iii) in Theorem 4.7, this gives

$$
\begin{equation*}
m+\lim _{t \rightarrow \infty} \frac{1}{n \omega_{n}} \int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma \geq \frac{1}{2}\left(\frac{\left|\Sigma_{H}\right|}{\omega_{n}}\right)^{\frac{n-1}{n}} \tag{5.3}
\end{equation*}
$$

On the other hand, since $\frac{\partial N}{\partial \nu}>0$ as $\Sigma_{t}$ is star-shaped and $\Sigma_{t}$ has positive $\sigma_{1}$ and $\sigma_{2}$ in $\mathbb{M}_{m}^{n+1}$, Corollary 2.3 applies with $(\mathbb{N}, \bar{g})$ given by $\mathbb{M}_{m}^{n+1}$ to show that

$$
\int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma
$$

is monotone nonincreasing. At $\Sigma=\Sigma_{0}$, we have $H_{m}=\bar{H}$ and $H=H_{\eta}$. Therefore,

$$
\begin{align*}
\int_{\Sigma} N\left(H_{m}-H\right) d \sigma & =\int_{\Sigma_{0}} N\left(\bar{H}-H_{\eta}\right) d \sigma \\
& \geq \lim _{t \rightarrow \infty} \int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma \tag{5.4}
\end{align*}
$$

Therefore, it follows from (5.3) and (5.4) that

$$
\begin{equation*}
m+\frac{1}{n \omega_{n}} \int_{\Sigma} N\left(H_{m}-H\right) d \sigma \geq \frac{1}{2}\left(\frac{\left|\Sigma_{H}\right|}{\omega_{n}}\right)^{\frac{n-1}{n}} \tag{5.5}
\end{equation*}
$$

which proves (1.1). If equality in (5.5) holds, then $\int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma$ is a constant for all $t$. By Corollary 2.3, we have $\eta=f$ on $\mathbb{E}$, hence $H=H_{m}$ by (5.1). Consequently,

$$
m=\frac{1}{2}\left(\frac{\left|\Sigma_{H}\right|}{\omega_{n}}\right)^{\frac{n-1}{n}}
$$

This completes the proof of Theorem 1.1. q.e.d.

REmARK 5.1. We conjecture that, when equality in (1.1) holds, $(\Omega, \breve{g})$ is isometric to the domain enclosed by $\Sigma$ and the horizon boundary $\Sigma_{H}^{S}$ in $\mathbb{M}_{m}^{n+1}$. It is clear from the above proof that in this case (5.2) becomes equality. Thus, if one can establish the rigidity statement for the Riemannian Penrose inequality on manifolds with corners (cf. $[33,41,31])$, then this conjecture will follow.

Next, we note an implication of Corollary 2.3 and Theorem 4.7 on the concept of Bartnik mass [2]. Given a pair $(g, H)$, where $g$ is a metric
and $H$ is a function on $\mathbb{S}^{2}$, the Bartnik mass of $(g, H)$, which we denote by $\mathfrak{m}_{B}(g, H)$, can be defined by

$$
\begin{aligned}
& \mathfrak{m}_{B}(g, H) \\
= & \inf \left\{\mathfrak{m}(h) \mid(M, h) \text { is an admissible extension of }\left(\mathbb{S}^{2}, g, H\right)\right\} .
\end{aligned}
$$

Here $\mathfrak{m}(h)$ is the ADM mass of ( $M, h$ ) which is an asymptotically flat 3-manifold with boundary $\partial M .(M, h)$ is called an admissible extension of $\left(\mathbb{S}^{2}, g, H\right)$ provided $(M, h)$ has nonnegative scalar curvature, $\partial M$ is isometric to $\left(\mathbb{S}^{2}, g\right)$, and the mean curvature of $\partial M$ in $(M, h)$ equals $H$ under the identification of $\partial M$ with $\left(\mathbb{S}^{2}, g\right)$ via the isometry. Moreover, it is assumed that either $(M, h)$ contains no closed minimal surfaces or $\partial M$ is outer minimizing in $(M, h)$ (see $[\mathbf{2}, \mathbf{4}, \mathbf{5}, \mathbf{2 6}])$.

Theorem 5.1. Given a pair $(g, H)$ on $\mathbb{S}^{2}$, suppose $H>0$ and $\left(\mathbb{S}^{2}, g\right)$ is isometric to a closed, star-shaped, convex surface $\Sigma$ with $\overline{\operatorname{Ric}}(\nu, \nu) \leq 0$ in a spatial Schwarzschild manifold $\mathbb{M}_{m}^{n+1}$ with $m>0$. Then

$$
\mathfrak{m}_{B}(g, H) \leq m+\frac{1}{8 \pi} \int_{\Sigma} N\left(H_{m}-H\right) d \sigma
$$

Moreover, equality holds if and only if $H=H_{m}$ and $\mathfrak{m}_{B}(g, H)=m$.
Proof. Taking $n=2$ in Theorem 4.7, let $\eta$ be the function given on $\mathbb{E}$ with an initial condition $\left.\eta\right|_{\Sigma}=\left.f\right|_{\Sigma} H^{-1} H_{m}$. The asymptotically flat manifold $\left(\mathbb{E}, g_{\eta}\right)$ is an admissible extension of $\left(\mathbb{S}^{2}, g, H\right)$. Therefore, by (iii) in Theorem 4.7,

$$
\begin{equation*}
\mathfrak{m}_{B}(g, H) \leq \mathfrak{m}\left(g_{\eta}\right)=m+\lim _{t \rightarrow \infty} \frac{1}{8 \pi} \int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma . \tag{5.6}
\end{equation*}
$$

By Corollary 2.3,

$$
\begin{equation*}
\int_{\Sigma} N\left(H_{m}-H\right) d \sigma \geq \lim _{t \rightarrow \infty} \int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma \tag{5.7}
\end{equation*}
$$

The inequality now follows from (5.6) and (5.7). If equality holds, then (5.6) and (5.7) are equalities. In this case, by Corollary $2.3, \eta=f$. Therefore, $H=H_{m}$ and $\mathfrak{m}_{B}(g, H)=m$. q.e.d.

REmARK 5.2. Indeed our method shows the following is true - given a pair $(g, H)$ on $\mathbb{S}^{2}$, suppose $\left(\mathbb{S}^{2}, g\right)$ is isometric to the boundary of a static, asymptotically flat manifold $\left(\mathbb{N}^{3}, \bar{g}\right)$ with a positive static potential $N$. Suppose ( $\mathbb{N}, \bar{g}$ ) satisfies:
(i) $\Sigma=\partial \mathbb{N}$ has positive $\sigma_{1}$ and $\sigma_{2}$;
(ii) the inverse curvature flow (1.21) in $(\mathbb{N}, \bar{g})$, with initial condition $\Sigma_{0}=\Sigma$, admits a long time, smooth solution $\left\{\Sigma_{t}\right\}_{0 \leq t<\infty}$ with $\frac{\partial N}{\partial \nu}>0$; and
(iii) the warped metric $g_{\eta}$ defined by (2.4), satisfying $R\left(g_{\eta}\right)=0$ on $\mathbb{N}$ and $H_{\eta}=H$ at $\Sigma$, can be constructed on $\mathbb{N}$ such that $g_{\eta}$ is asymptotically flat with

$$
\mathfrak{m}\left(g_{\eta}\right)=\mathfrak{m}(\bar{g})+\lim _{t \rightarrow \infty} \frac{1}{8 \pi} \int_{\Sigma_{t}} N\left(\bar{H}-H_{\eta}\right) d \sigma .
$$

Then, by Corollary 2.3, the Bartnik mass of $(g, H)$ satisfies

$$
\begin{equation*}
\mathfrak{m}_{B}(g, H) \leq \mathfrak{m}(\bar{g})+\frac{1}{8 \pi} \int_{\Sigma} N(\bar{H}-H) d \sigma \tag{5.8}
\end{equation*}
$$

Here $\mathfrak{m}(\bar{g})$ is the ADM mass of $(\mathbb{N}, \bar{g})$ and $\bar{H}$ is the mean curvature of $\Sigma$ in $(\mathbb{N}, \bar{g})$. Estimate (5.8) appeared as Conjecture 4.1 in [34].

## 6. Limits along isomeric embeddings of large spheres into Schwarzschild manifolds

In this section, we prove Theorem 1.2 which was inspired by the results of Fan, Shi and Tam [18]. We divide the proof into two parts, the existence of the embedding and the calculation of the limits.
6.1. Isometric embedding of large spheres. In [38], Nirenberg shows that a 2 -sphere with positive Gauss curvature can be isometrically embedded in $\mathbb{R}^{3}$ as a strictly convex surface. By adopting the iteration scheme used in the proof of the openness part in [38], one can verify that a perturbation of a standard round sphere can be isometrically embedded in a 3 -dimensional Schwarzschild manifold with small mass. This assertion, which is the main tool we use in this section, is indeed a special case of [28, Theorem 1] (see also [11]).

Proposition 6.1 ([11, 28]). Let $\sigma$ be the standard metric on $\mathbb{S}^{2}$ with area $4 \pi$. There exists $\epsilon>0$ and $\delta>0$, such that if $\tilde{\sigma}$ is a metric on $\mathbb{S}^{2}$ with $\|\tilde{\sigma}-\sigma\|_{C^{2, \alpha}}<\epsilon$ and if $m$ is a positive constant with $m<\delta$, then there exists an isometric embedding $\tilde{X}$ of $\left(\mathbb{S}^{2}, \tilde{\sigma}\right)$ in

$$
\begin{equation*}
\mathbb{M}_{m}^{3}=\left([2 m, \infty) \times \mathbb{S}^{2}, \frac{1}{1-\frac{2 m}{\rho}} d \rho^{2}+\rho^{2} \sigma\right) \tag{6.1}
\end{equation*}
$$

Moreover, $\tilde{X}$ can be chosen so that

$$
\begin{equation*}
\|\tilde{X}-X\|_{C^{2, \alpha}} \leq C\|\tilde{\sigma}-\sigma\|_{C^{2, \alpha}} . \tag{6.2}
\end{equation*}
$$

Here $X$ is the isometric embedding of $\left(\mathbb{S}^{2}, \sigma\right)$ in $\mathbb{M}_{m}^{3}$ given by $X(\omega)=$ $(1, \omega), \forall \omega \in \mathbb{S}^{2}$.

Remark 6.1. Estimate (6.2) is not stated in the statement of theorems in $[\mathbf{1 1}, \mathbf{2 8}]$, but it follows from both proofs therein.

We now consider an asymptotically flat 3-manifold $(M, \breve{g})$ given in Theorem 1.2. Precisely, this means that, outside a compact set, $M$
is diffeomorphic to $\mathbb{R}^{3}$ minus a ball and with respect to the standard coordinates on $\mathbb{R}^{3}, \breve{g}$ satisfies $\breve{g}_{i j}=\delta_{i j}+p_{i j}$ with

$$
\begin{equation*}
\left|p_{i j}\right|+|x|\left|\partial p_{i j}\right|+|x|^{2}\left|\partial \partial p_{i j}\right|+|x|^{3}\left|\partial \partial \partial p_{i j}\right|=O\left(|x|^{-\tau}\right) \tag{6.3}
\end{equation*}
$$

for some constant $\tau>\frac{1}{2}$, where $\partial$ denotes the partial derivative. Moreover, it is assumed that the scalar curvature of $\breve{g}$ is integrable on $(M, \breve{g})$. Under such assumptions, the ADM mass of $(M, \breve{g})$ is well defined, which we will denote by $\mathfrak{m}$.

Given a large constant $r>0$, let $S_{r}=\{|x|=r\}$ denote the coordinate sphere in $(M, \breve{g})$. Let $g_{r}$ be the induced metric on $S_{r}$ and let $\tilde{g}_{r}=r^{-2} g_{r}$. Identifying $S_{r}$ with $\mathbb{S}^{2}=\{|y|=1\}$ via a map $y=r^{-1} x$, one can deduce from (6.3) that

$$
\begin{equation*}
\left\|\tilde{g}_{r}-\sigma\right\|_{C^{3}} \leq C r^{-\tau} \tag{6.4}
\end{equation*}
$$

(see (2.17) in [18] for instance). Here $\sigma$ is the standard metric on $\mathbb{S}^{2}$ with area $4 \pi$ and $C>0$ is a constant independent on $r$.

Let $m>0$ be any fixed constant. Define $m_{r}=r^{-1} m$. Applying Proposition 6.1 and (6.4), we conclude, for sufficiently large $r$, there exists an isometric embedding

$$
\tilde{X}_{r}:\left(\mathbb{S}^{2}, \tilde{g}_{r}\right) \longrightarrow \mathbb{M}_{m_{r}}^{3}=\left(\left[2 m_{r}, \infty\right) \times \mathbb{S}^{2}, \frac{1}{1-\frac{2 m_{r}}{\rho}} d \rho^{2}+\rho^{2} \sigma\right)
$$

satisfying

$$
\begin{equation*}
\left\|\tilde{X}_{r}-X_{\sigma}\right\|_{C^{2, \alpha}}=O\left(r^{-\tau}\right) \tag{6.5}
\end{equation*}
$$

where $X_{\sigma}(\omega)=(1, \omega), \forall \omega \in \mathbb{S}^{2}$. It follows from (6.5) that $\tilde{X}_{r}\left(\mathbb{S}^{2}\right)$ is star-shaped and convex; moreover, if $\tilde{\nu}_{r}$ is the outward unit normal to $\tilde{X}_{r}\left(\mathbb{S}^{2}\right)$, then

$$
\begin{equation*}
\tilde{\nu}_{r}=\left(1+O\left(r^{-\tau}\right)\right) \partial_{\rho}+O\left(r^{-\tau}\right) \partial_{\omega_{1}}+O\left(r^{-\tau}\right) \partial_{\omega_{2}} \tag{6.6}
\end{equation*}
$$

where $\omega_{i}, i=1,2$, are local coordinates on $\mathbb{S}^{2}$.
Let $\overline{\operatorname{Ric}}_{r}$ denote the Ricci curvature of $\mathbb{M}_{m_{r}}^{3}$. In the rotationally symmetric form, it is given by $\overline{\operatorname{Ric}}_{r}=m_{r} \rho^{-3} \Psi$, where

$$
\Psi=-\frac{2}{1-\frac{2 m_{r}}{\rho}} d \rho^{2}+\rho^{2} \sigma .
$$

By (6.5) and (6.6),

$$
\begin{align*}
\overline{\operatorname{Ric}}_{r}\left(\tilde{\nu}_{r}, \tilde{\nu}_{r}\right) & =m_{r} \rho^{-3} \Psi\left(\tilde{\nu}_{r}, \tilde{\nu}_{r}\right) \\
& =-2 m_{r}\left(1+O\left(r^{-\tau}\right)\right) . \tag{6.7}
\end{align*}
$$

In particular, $\overline{\operatorname{Ric}}_{r}\left(\tilde{\nu}_{r}, \tilde{\nu}_{r}\right)<0$ for large $r$.
The map $\tilde{X}_{r}$ leads to an isometric embedding of $\left(S_{r}, g_{r}\right)$ in $\mathbb{M}_{m}^{3}$ because $\mathbb{M}_{m}^{3}$ and $\mathbb{M}_{m_{r}}^{3}$ only differer by a constant scaling. More precisely, consider the map

$$
F_{r}: \mathbb{M}_{m_{r}}^{3} \longrightarrow \mathbb{M}_{m}^{3}
$$

where $F_{r}(\rho, \omega)=(r \rho, \omega)$. Define $X_{r}=F_{r} \circ \tilde{X}_{r}$, then

$$
X_{r}:\left(S_{r}, g_{r}\right) \longrightarrow \mathbb{M}_{m}^{3}
$$

is an isometric embedding such that $X_{r}\left(S_{r}\right)$ is a star-shaped, convex surface with

$$
\begin{equation*}
\overline{\operatorname{Ric}}\left(\nu_{r}, \nu_{r}\right)=-2 m r^{-3}\left(1+O\left(r^{-\tau}\right)\right) \tag{6.8}
\end{equation*}
$$

Here $\nu_{r}$ is the outward unit normal to $X_{r}\left(\mathbb{S}^{2}\right)$ in $\mathbb{M}_{m}^{3}$ and (6.8) follows from (6.7). Thus, we have proved the first part of Theorem 1.2 on the existence of the desired isometric embedding of $\left(S_{r}, g_{r}\right)$ into $\mathbb{M}_{m}^{3}$.
6.2. Evaluation of the limits. To prove the remaining part of Theorem 1.2, we write $X_{r}=\left(\rho_{r}, \theta_{r}\right)$. By (6.5), we have

$$
\begin{equation*}
\left\|\rho_{r}-r\right\|_{C^{2, \alpha}}=O\left(r^{1-\tau}\right) \tag{6.9}
\end{equation*}
$$

Similarly, if $H_{m}$ denotes the mean curvature of $X_{r}\left(S_{r}\right)$ in $\mathbb{M}_{m}^{3}$, then (6.5) gives

$$
\begin{equation*}
H_{m}=2 r^{-1}+O\left(r^{-\tau-1}\right) \tag{6.10}
\end{equation*}
$$

We first compute $\int_{S_{r}} N H d \sigma$, where $N=\left(1-\frac{2 m}{\rho}\right)^{\frac{1}{2}}$ is the static potential on $\mathbb{M}_{m}^{3}$ and $H$ is the mean curvature of $S_{r}$ in $(M, \breve{g})$. Let $A(r)$ be the area of $\left(S_{r}, g_{r}\right)$. By [18, Lemma 2.1],

$$
H=2 r^{-1}+O\left(r^{-1-\tau}\right) \text { and } A(r)=4 \pi r^{2}+O\left(r^{2-\tau}\right)
$$

By [18, Lemma 2.2],

$$
\int_{S_{r}} H d \sigma=r^{-1} A(r)+4 \pi r-8 \pi \mathfrak{m}+o(1) .
$$

Therefore, by (6.9),

$$
\begin{align*}
\int_{S_{r}} N H d \sigma & =\int_{S_{r}}\left(1-m r^{-1}\right) H d \sigma+o(1)  \tag{6.11}\\
& =r^{-1} A(r)+4 \pi r-8 \pi \mathfrak{m}-8 \pi m+o(1)
\end{align*}
$$

Next, we compute $\int_{S_{r}} N H_{m} d \sigma$. Identifying $S_{r}$ with its image $\Sigma_{r}=$ $X_{r}\left(S_{r}\right)$, we carry out the computation in $\mathbb{M}_{m}^{3}$. Following notations in Section 3, we rewrite the Schwarzschild metric $g_{m}=\frac{1}{N^{2}} d \rho^{2}+\rho^{2} \sigma$ as

$$
g_{m}=d s^{2}+\phi^{2}(s) \sigma
$$

by setting $s=\int_{2 m}^{\rho} \frac{1}{N(t)} d t$. Then $\phi(s)=\rho$ and $\phi^{\prime}(s)=N$. Define

$$
\Phi(s)=\int_{0}^{s} \phi(t) d t \text { and } u=\left\langle\phi \partial_{s}, \nu_{r}\right\rangle
$$

On $\Sigma_{r}$, (3.4) becomes

$$
\begin{equation*}
\Phi_{; i j}=\phi^{\prime} g_{r_{i j}}-h_{i j} u \tag{6.12}
\end{equation*}
$$

where $h$ is the second fundamental form of $\Sigma_{r}$. Taking trace of (6.12) gives

$$
\begin{equation*}
0=2 \int_{\Sigma_{r}} \phi^{\prime} d \sigma-\int_{\Sigma_{r}} H_{m} u d \sigma \tag{6.13}
\end{equation*}
$$

Now we apply [23, Lemma 2.5] to get another Minkowski type identity. Precisely, let $\sigma_{2}^{i j}=\frac{\partial \sigma_{2}}{\partial h_{i j}}=\sigma_{1} g_{r}{ }^{i j}-h^{i j}$. Contracting $\sigma_{2}^{i j}$ with $\Phi_{i j}$ shows

$$
\begin{equation*}
\int_{\Sigma_{r}} \sigma_{2}^{i j} \Phi_{; i j} d \sigma=\int_{S_{r}} H_{m} \phi^{\prime} d \sigma-2 \int_{S_{r}} \sigma_{2} u d \sigma \tag{6.14}
\end{equation*}
$$

Integrating by parts and applying the Codazzi equation, we have

$$
\int_{S_{r}} \sigma_{2}^{i j} \Phi_{; i j} d \sigma=-\int_{S_{r}}\left(\sigma_{2}^{i j}\right)_{; j} \Phi_{; i} d \sigma=\int_{S_{r}} \overline{\operatorname{Ric}}\left(\nu_{r}, \nabla \Phi\right) d \sigma
$$

where $\nabla \Phi$ is the gradient of $\Phi$ on $\Sigma_{r}$. By (6.9),

$$
\begin{equation*}
|\nabla \Phi|^{2}=g_{r}{ }^{i j} \Phi_{; i} \Phi_{; j}=O\left(r^{2-2 \tau}\right) \tag{6.15}
\end{equation*}
$$

This combined with the fact $\left|\overline{\operatorname{Ric}}\left(\nu_{r}, \cdot\right)\right|=O\left(r^{-3}\right)$ shows

$$
\int_{S_{r}} \sigma_{2}^{i j} \Phi_{; i j} d \sigma=o(1)
$$

Therefore, by (6.14),

$$
\begin{equation*}
\int_{S_{r}} H_{m} \phi^{\prime} d \sigma=2 \int_{S_{r}} \sigma_{2} u d \sigma+o(1) \tag{6.16}
\end{equation*}
$$

Note that $u^{2}=|\bar{\nabla} \Phi|^{2}-|\nabla \Phi|^{2}$, where $\bar{\nabla}$ denotes the gradient on $\mathbb{M}_{m}^{3}$. Thus, by (6.15),

$$
\begin{equation*}
u=r+O\left(r^{1-\tau}\right) \tag{6.17}
\end{equation*}
$$

Now let $K$ be the Gauss curvature of $\left(S_{r}, g_{r}\right)$. By [18, Lemma 2.1], if we let $\bar{K}=K-r^{-2}$, then $\bar{K}=O\left(r^{-2-\tau}\right)$. Thus, by the Gauss equation and (6.8),

$$
\sigma_{2}=K+\overline{\operatorname{Ric}}\left(\nu_{r}, \nu_{r}\right)=\bar{K}+r^{-2}-2 m r^{-3}+o\left(r^{-3}\right)
$$

Following the steps in [18], we have

$$
\begin{align*}
\int_{\Sigma_{r}} H_{m} \phi^{\prime} d \sigma & =2 \int_{\Sigma_{r}}\left(\bar{K}+r^{-2}\right) u d \sigma-4 m r^{-3} \int_{\Sigma_{r}} u d \sigma+o(1)  \tag{6.18}\\
& =2 r^{-2} \int_{\Sigma_{r}}\left\langle\bar{\nabla} \Phi, \nu_{r}\right\rangle d v o l+2 \int_{S_{r}} \bar{K} u d \sigma-16 \pi m+o(1) \\
& =6 r^{-2} \int_{\Omega_{r}} \phi^{\prime} d \mathrm{vol}+2 r \int_{S_{r}}\left(K-r^{-2}\right) d \sigma-16 \pi m+o(1) \\
& =6 r^{-2} \int_{\Omega_{r}} \phi^{\prime} d \mathrm{vol}+8 \pi r-2 r^{-1} A(r)-16 \pi m+o(1),
\end{align*}
$$

where $\Omega_{r}$ is the bounded domain enclosed by $\Sigma_{r}$ and the horizon boundary of $\mathbb{M}_{m}^{3}$ and $d \mathrm{vol}$ is the volume element on $\mathbb{M}_{m}^{3}$.

Next, let $\bar{H}_{m}=H_{m}-2 r^{-1}$. By (6.10), $\bar{H}=O\left(r^{-1-\tau}\right)$. By (6.13),

$$
\begin{aligned}
2 \int_{\Sigma_{r}} \phi^{\prime} d \sigma & =\int_{\Sigma_{r}} H_{m} u d \sigma=\int_{\Sigma_{r}}\left(2 r^{-1}+\bar{H}_{m}\right) u d \sigma \\
& =6 r^{-1} \int_{\Omega_{r}} \phi^{\prime} d \mathrm{vol}+\int_{\Sigma_{r}} \bar{H}_{m} u d \sigma
\end{aligned}
$$

Since $u=r+O\left(r^{1-\tau}\right)$ and $\phi^{\prime}=N=1+O\left(r^{-1}\right)$, we have $u=r \phi^{\prime}+$ $O\left(r^{1-\tau}\right)$. Thus,
$\begin{aligned} 2 \int_{\Sigma_{r}} \phi^{\prime} d \sigma & =6 r^{-1} \int_{\Omega_{r}} \phi^{\prime} d \mathrm{vol}+\int_{\Sigma_{r}} \bar{H}_{m}\left(r \phi^{\prime}+O\left(r^{1-\tau}\right)\right) d \sigma \\ & =6 r^{-1} \int_{\Omega_{r}} \phi^{\prime} d \mathrm{vol}+r \int_{\Sigma_{r}} H_{m} \phi^{\prime} d \sigma-2 \int_{\Sigma_{r}} \phi^{\prime} d \sigma+O\left(r^{2-2 \tau}\right) .\end{aligned}$
Since $\phi^{\prime}=N=1-m r^{-1}+O\left(r^{-1-\tau}\right)$, we also have

$$
\begin{equation*}
\int_{\Sigma_{r}} \phi^{\prime} d \sigma=A(r)-4 \pi m r+O\left(r^{1-\tau}\right) \tag{6.20}
\end{equation*}
$$

Thus, it follows from (6.19) and (6.20) that

$$
\begin{equation*}
\int_{\Sigma_{r}} H_{m} \phi^{\prime} d \sigma=-6 r^{-2} \int_{\Omega_{r}} \phi^{\prime} d v o l+4 r^{-1} A(r)-16 \pi m+o(1) \tag{6.21}
\end{equation*}
$$

Combining (6.18) and (6.21), and replacing $\phi^{\prime}$ by $N$, we have

$$
\begin{equation*}
\int_{S_{r}} N H_{m} d \sigma=4 \pi r+\frac{A(r)}{r}-16 \pi m+o(1) \tag{6.22}
\end{equation*}
$$

By (6.11) and (6.22), we therefore conclude

$$
\int_{S_{r}} N\left(H_{m}-H\right) d \sigma=-8 \pi m+8 \pi \mathfrak{m}+o(1)
$$

or equivalently

$$
\lim _{r \rightarrow \infty}\left(m+\frac{1}{8 \pi} \int_{S_{r}} N\left(H_{m}-H\right) d \sigma\right)=\mathfrak{m}
$$

which proves (1.3).
To prove (1.4), by (6.18) and (6.21), we also have

$$
\begin{equation*}
\int_{\Omega_{r}} N d \mathrm{vol}=\int_{\Omega_{r}} \phi^{\prime} d \mathrm{vol}=\frac{1}{2} r A(r)-\frac{2}{3} \pi r^{3}+o\left(r^{2}\right) \tag{6.23}
\end{equation*}
$$

Let $V(r)$ be the volume of the region enclosed by $S_{r}$ in $(M, \breve{g})$. By (2.28) in [18],

$$
\begin{equation*}
V(r)=\frac{1}{2} r A(r)-\frac{2}{3} \pi r^{3}+2 \pi \mathfrak{m} r^{2}+o\left(r^{2}\right) \tag{6.24}
\end{equation*}
$$

Hence, it follows from (6.23) and (6.24) that

$$
\begin{equation*}
\int_{\Omega_{r}} N d \mathrm{vol}-V(r)=-2 \pi \mathfrak{m} r^{2}+o\left(r^{2}\right) \tag{6.25}
\end{equation*}
$$

Next, let $V_{m}(r)$ denote the volume of $\Omega_{r}$ in $\mathbb{M}_{m}^{3}$. We claim

$$
\begin{equation*}
\int_{\Omega_{r}} N d \mathrm{vol}=V_{m}(r)-2 \pi m r^{2}+o\left(r^{2}\right) \tag{6.26}
\end{equation*}
$$

To see this, let $D_{\rho}$ denote the region in $\mathbb{M}_{m}^{3}$ bounded by the rotationally symmetric sphere with area $4 \pi \rho^{2}$ and the horizon boundary. Let $\rho_{0}>$ $2 m$ be a fixed constant such that, for any $\rho>\rho_{0}$,

$$
\begin{equation*}
\left|N-\left(1-\frac{m}{\rho}\right)\right| \leq C_{1} \rho^{-2} \tag{6.27}
\end{equation*}
$$

where $C_{1}>0$ is independent on $\rho$. By (6.9) and (6.27), for large $r$, we have

$$
\begin{align*}
\int_{\Omega_{r}} N d v o l & =\int_{\Omega_{r} \backslash D_{\rho_{0}}} N d \mathrm{vol}+O(1) \\
& =\int_{\Omega_{r} \backslash D_{\rho_{0}}}\left(1-\frac{m}{\rho}\right) d \mathrm{vol}+O(r)  \tag{6.28}\\
& =V_{m}(r)-\int_{\Omega_{r} \backslash D_{\rho_{0}}} \frac{m}{\rho} d \mathrm{vol}+O(r) .
\end{align*}
$$

By (6.9), we also have

$$
\int_{\left(D_{r-C r^{1-\tau}}\right) \backslash D_{\rho_{0}}} \rho^{-1} d \mathrm{vol} \leq \int_{\Omega_{r} \backslash D_{\rho_{0}}} \rho^{-1} d \mathrm{vol} \leq \int_{\left(D_{r+C r^{1-\tau}}\right) \backslash D_{\rho_{0}}} \rho^{-1} d \mathrm{vol}
$$

which implies

$$
\begin{equation*}
\int_{\Omega_{r} \backslash D_{\rho_{0}}} \rho^{-1} d v o l=2 \pi r^{2}+o\left(r^{2}\right) \tag{6.29}
\end{equation*}
$$

Thus, (6.26) follows from (6.28) and (6.29). By (6.25) and (6.26), we conclude that

$$
V(r)-V_{m}(r)=2 \pi(\mathfrak{m}-m) r^{2}+o\left(r^{2}\right)
$$

which proves (1.4) of Theorem 1.2.
We end this paper with the following corollary.
Corollary 6.2. Let $\left(M^{3}, \breve{g}\right)$ be an asymptotically flat 3-manifold with nonnegative scalar curvature, with boundary $\partial M$ being an outer minimizing minimal surface (with one or more components). Let $S_{r}$ denote the large coordinate sphere in $\left(M^{3}, \breve{g}\right)$ with the induced metric $g_{r}$. Let $m=\sqrt{\frac{|\partial M|}{16 \pi}}$. For large $r$, let $X_{r}$ be the isometric embedding of $\left(S_{r}, g_{r}\right)$ into $\mathbb{M}_{m}^{3}$ given by Theorem 1.2. Let $V(r)$ and $V_{m}(r)$ be the volume of the region enclosed by $S_{r}$ in $\left(M^{3}, \breve{g}\right)$ and the region enclosed by $X_{r}\left(S_{r}\right)$
in $\mathbb{M}_{m}^{3}$, respectively. Then

$$
\lim _{r \rightarrow \infty} \frac{V(r)-V_{m}(r)}{2 \pi r^{2}} \text { exists and } i s \geq 0
$$

and "=" holds if and only if $\left(M^{3}, \breve{g}\right)$ is isometric to $\mathbb{M}_{m}^{3}$.
Proof. This follows directly from (1.4) and the 3-dimensional Riemannian Penrose inequality.
q.e.d.

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