# A COMPLEX ANALOGUE OF HARTMAN-NIRENBERG CYLINDER THEOREM 

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## 1. Introduction

Hartman and Nirenberg [3] proved, in 1959,
Theorem (Hartman-Nirenberg). Let $M^{n}$ be a connected complete Riemannian hypersurface in an $(n+1)$-dimensional Euclidean space $R^{n+1}$. If the rank of the Gauss map is $\leq 1$ everywhere, then $M^{n}$ is cylindrical.

This theorem is the first global determination of a flat hypersurface $M$ in Euclidean space. Indeed the condition about the rank of Gauss map is equivalent to the flatness of $M$. Classically, we had only the local classification of flat surfaces. In this paper, we shall show the complex version of the above theorem.

Let $M^{n}$ be a complex $n$-dimensional complete connected Kählerian hypersurface isometrically and holomorphically immersed by $f$ into an ( $n+1$ )complex space $C^{n+1}$.

Let $\tilde{\phi}: M^{n} \rightarrow C P^{n}$ be a mapping from $M^{n}$ to the complex projective $n$-space $C P^{n}$ which assigns to a point $x$ in $M^{n}$ the normal plane of $f\left(M^{n}\right)$ at $f(x)$ in $C^{n+1}$, which we can identify with a point in $C P^{n}$ by the parallel displacement in $C^{n+1}$. We call this mapping the Gauss map for the complex hypersurface $M^{n}$ in $C^{n+1}$.

Let $\xi$ be any unit normal vector field around $x$, and denote by $A$ the tensor field of type $(1,1)$ given by

$$
\tilde{\nabla}_{X} \xi=-A_{\xi} X+\hat{\nabla}_{X} \xi,
$$

where $\tilde{V}$ is the canonical connection of $C^{n+1}$ and $\hat{V}$ is the normal connection induced by $\tilde{\nabla}$. Then we have:
(1.1) $\quad \tilde{\phi}_{*}(X)=0$ if and only if $A X=0$, where $\tilde{\phi}_{*}$ is the Jacobian of $\tilde{\phi}$;
(1.2) the rank of $\tilde{\phi}_{*}$ is equal to that of $A$;
(1.3) the Gauss map $\tilde{\phi}$ is anti-holomorphic.

For the proof of (1.1), (1.2) and (1.3), see K. Nomizu and B. Smyth [5]. Now our main theorem is stated as follows.

[^0]Theorem. Let $M^{n}$ be an n-dimensional Kählerian hypersurface of $C^{n+1}$ immersed into $C^{n+1}$ holomorphically and isometrically. Then the following conditions are equivalent:
(1.4) $\quad$ The rank of $\tilde{\phi}_{*}$ is $\leq 2$ everywhere, where $\tilde{\phi}_{*}$ is the Jacobian of $\tilde{\phi}$; (1.5) $\tilde{\phi}$ maps $M^{n}$ into some complex projective line, say $C P^{1}$, in $C P^{n}$;
(1.6) The manifold $M^{n}$ is cylindrical, i.e., there exist an ( $n-1$ )-dimensional Kählerian manifold $M_{1}^{n-1}$ and a Kählerian curve $M_{2}^{1}$ such that there exists a holomorphic isometry $g: M_{1}^{n-1} \times M_{2}^{1} \rightarrow M^{n}$ whose composition with $f$, i.e., $f \circ g$, restricted to $M_{1}^{n-1} \times\{y\}$ in $M_{1}^{n-1} \times M_{2}^{1}$, for each $y$, i.e., $f \circ g \mid M^{n-1} \times\{y\}$, maps $M_{1}^{n-1} \times\{y\}$ holomorphically and isometrically onto an $(n-1)$-dimensional complex plane which is parallel to each other in $C^{n+1}$, and $f \circ g$ restricted to $\{x\} \times M_{2}^{1}$ in $M_{1}^{n-1} \times M_{2}^{1}$, i.e., $f \circ g \mid\{x\} \times M_{2}^{1}$, maps $\{x\} \times M_{2}^{1}$ into a 2 -dimensional complex subspace of $C^{n+1}$ which is perpendicular to $f \circ g\left(M^{n-1} \times\{y\}\right)$ at $f \circ g(x, y)$ ) for each $x \in M_{1}^{n-1}$ and $y \in M_{2}^{1}$.
This theorem is the answer to the problem proposed in [5].

## 2. Preparations

Let $\alpha(X, Y)$, for $X$ and $Y \in T M$, be the second fundamental form of an isometric immersion $f: M^{n} \rightarrow M^{N}(c)$, where $M^{n}$ is a Riemannian manifold, $T M$ is the tangent space of $M^{n}$, and $M^{N}(c)$ is the space form of constant curvature $c$. For any $x$ in $M$, the subspace $R N(x)$ of the tangent space $T X(x)$ of $M^{n}$ at $x$ defined by $R N(x)=\{X \in T M(x): \alpha(X, Y)=0$, for all $Y\}$ is called the relative nullity space of $f$ at $x$, and the dimension $\nu(x)$ of $R N(x)$ is called the relative nullity of $f$ at $x$. Following Chern and Kuiper [2], we also call $\nu=\min \nu(x)$ for $x \in M$ the index of relative nullity of $f$. It is well known that the subset $G$ of $M$ defined by $G=\left\{x \in M^{n}: \nu(x)=\nu\right\}$ is open, and we can define on $G$ the relative nullity distribution which assigns to $x$ in $G$ the relative nullity space $R N(x)$. It is also well known that the distribution is differentiable, involutive and totally geodesic; for more details of this see [1] in which we have shown that the maximal integral submanifolds of the distribution, i.e., the leaves, are complete if $M^{n}$ is complete. It was also shown that if $M^{n}$ is a complete Kählerian manifold of complex dimension $n$, and $M^{N}(c)$ is the complex space form of holomorphic sectional curvature $c$ and of complex dimension $N$, then the leaves are totally geodesic Kählerian submanifolds in both $M^{n}$ and $M^{N}$.

In particular, in our case here, each leaf is a complex ( $n-1$ )-dimensional plane, since $G=\left\{x \in M^{n}\right.$ : the rank of $\left.\tilde{\phi}_{*}(x)=2\right\}$ by (1.1), (1.2). Now we shall introduce the notion of conullity operater which was defined by Rosenthal [6].

Let $x$ be a point in a leaf in $G$. For any $\eta_{x}$ in the relative nullity space $R N(x)$ at $x$ define a linear operator, say $\bar{A}_{\eta_{x}}$ of the orthogonal complement $R N(x)^{\perp}$ of $R N(x)$ in $T M_{x}$, by

$$
\begin{equation*}
\bar{A}_{\eta_{x}} X=P_{n}^{\perp}\left(\nabla_{X} \eta\right)_{x}, \tag{2.1}
\end{equation*}
$$

where $\nabla$ is the connection in $M^{n}, \eta$ is an extension of $\eta_{x}$ in a neighborhood of $x$, and $P_{x}^{\perp}$ is the projection of $T M_{x}$ onto $R N(x)^{\perp}$. The following Propositions 2.1 and 2.2 are due to Rosenthal [7].

Proposition 2.1. $\quad \bar{A}_{\eta_{x}}$ depends only on the vector $\eta_{x}$ and not on the extensions.

Proof. Let $g$ be a $C^{\infty}$ function on $M^{n}$, and $\eta$ an extension of $\eta_{x}$ on a neighborhood of $x$. It suffices to show that $\bar{A}_{\left(g_{\eta}\right)} X=g(x) \cdot \bar{A}_{\eta_{x}} X$. By the definition of the operator, for $X$ in $R N(x)^{\perp}, \bar{A}_{(g \eta) x} X=P_{x}^{\perp}\left(\nabla_{X} g \eta\right)_{x}=P_{x}^{\perp}\left(X g \cdot \eta+g \nabla_{X} \eta\right)_{x}$ $=g(x) P_{x}^{-}\left(\nabla_{X} \eta\right)_{x}=g(x) \bar{A}_{\eta_{x}} X$.

Proposition 2.2. Let $\alpha$ be the second fundamental form of $M^{n}$ in $C^{n+1}$. Then $\alpha\left(X, \bar{A}_{\eta_{x}} Y\right)=\alpha\left(Y, \bar{A}_{\eta_{x}} X\right)$ for any $X, Y$ in $R N(x)^{\perp}$.

Proof. For $X$ and $Y$ in $R N(x)^{\perp}$ and $\eta$ in $R N(x)$, we have $\tilde{R}(X, Y) \eta=$ $R(X, Y) \eta+\alpha\left(X, \nabla_{Y} \eta\right)-\alpha\left(Y, \nabla_{X} \eta\right)$, where $R$ and $\tilde{R}$ are the curvature tensor fields of $M^{n}$ and $C^{n+1}$, respectively. Since $\tilde{R}=0, \alpha\left(X, \nabla_{Y} \eta\right)=\alpha\left(Y, \nabla_{X} \eta\right)$ holds. From this last equality and the definition of $\bar{A}$, we obtain the equality in Proposition 2.2.

Proposition 2.3. For any $x$ in $G$ and any $\eta_{x}$ in $R N(x), \bar{A}_{\eta_{x}}$ is a complex linear function of $R N(x)^{\perp}$.

Proof. This proposition is slightly more general than the one in [7]. Let J be the complex structure of $M^{n}$. Then as is seen in [1, Proposition 2.3.1], $R N(x)$ and $R N(x)^{\perp}$ are invariant subspaces of $J$. First of all, we have $\alpha(X$, $\left.\bar{A}_{\eta_{x}} J Y\right)=\alpha\left(J Y, \bar{A}_{\eta_{x}} X\right)=J \alpha\left(Y, \bar{A}_{\eta_{x}} X\right)$ by Proposition 2.2. and the fact that $M^{n}$ is a Kählerian submanifold. On the other hand, $\alpha\left(X, J \bar{A}_{\eta_{x}} Y\right)=$ $J \alpha\left(X, \bar{A}_{\eta_{x}} Y\right)$. So we have

$$
\alpha\left(X, \bar{A}_{\eta_{x}} J Y\right)-\alpha\left(X, J \bar{A}_{\eta_{x}} Y\right)=\alpha\left(X,\left(\bar{A}_{\eta_{x}} J-J \bar{A}_{\eta_{x}}\right) Y\right)=0 .
$$

Suppose that $\bar{A}_{\eta_{x}} J-J \bar{A}_{\eta_{x}} \neq 0$. Then there exists $Y^{\prime}$ in $R N(x)^{\perp}$ such that $\left(\bar{A}_{\eta_{x}} J-J \bar{A}_{\eta_{x}}\right) Y^{\prime} \neq 0$. However, $\left(\bar{A}_{\eta_{x}} J-J \bar{A}_{\eta_{x}}\right) Y^{\prime}$ is in $R N(x)^{\perp}$, so there must exist $X^{\prime}$ in $R N(x)^{\perp}$ such that $\alpha\left(\left(A_{\eta_{x}} J-J A_{\eta_{x}}\right) Y^{\prime}, X^{\prime}\right) \neq 0$. This is a contradiction. Hence $\bar{A}$ and $J$ commute. q.e.d.

Notice that by Proposition 2.3 we have the following expression of $\bar{A}_{\eta_{x}}$ with respect to a unitary frame:

$$
\bar{A}_{\eta_{x}}=\left[\begin{array}{cc}
\alpha(x) & -\beta(x)  \tag{2.2}\\
\beta(x) & \alpha(x)
\end{array}\right]
$$

## 3. Lemmas

Lemma 3.1. Under the assumptions in $\S 1, \bar{A}_{\eta_{x}}=0$ for all $x$ in $G$ and all $\eta_{x}$ in $R N(x)$.

Proof. We claim that all eigenvalues of $\bar{A}_{\eta_{x}}$ are zero. As is mentioned in
$\S 1$, we have shown that the leaves of the relative nullity distribution are complete; see [1, Theorem 1.8.1]. Therefore the argument in the proof of [6, Theorem 3.1] is applicable to our Lemma 3.1, and consequently the real eigenvalues of $\bar{A}_{\eta_{x}}$ are zero. In order to show that the complex eigenvalues, if any, are also zero, let $a+b i$ be a complex eigenvalue. Then there exists a vector $X$ in $R N(x)^{\perp}$ such that $\bar{A}_{\eta_{x}} X=a X+b J X$. Consider a new vector $\xi_{x}$ in $R N(x)$ given by $\xi_{x}=a \eta_{x}-b \eta_{\eta_{x}}$, so that $\bar{A}_{\xi_{x}} X=\left(a^{2}+b^{2}\right) X$. Again by the same argument as mentioned above, $a^{2}+b^{2}=0$, i.e., $a=b=0$, so that $a+b i=0$. Now by (2.2), $\alpha \pm \beta i$ are the only possible eigenvalues of $\bar{A}_{\eta_{x}}$. Thus $\alpha \pm \beta i=0$ implies that $\alpha=\beta=0$, i.e., $\bar{A}_{\eta_{x}}=0$.

Lemma 3.2. The distributions $R N$ and $R N^{\perp}$ (the distribution defined by the orthogonal complement of $R N$ ) are parallel. In particular, $R N^{\perp}$ is involutive.

Proof. Let $\eta$ and $\zeta$ be in $R N$, and $X$ and $Y$ in $R N^{\perp}$. Since $R N$ is totally geodesic, $g\left(\tilde{\nabla}_{\xi} \eta, X\right)=0$. Also $g\left(\tilde{\nabla}_{Y} \eta, X\right)=g\left(\bar{A}_{\eta}(Y), X\right)=0$ by Lemma 3.1. Therefore $R N$ is parallel, and so is $R N^{\perp}$ automatically.

Lemma 3.3. Let $M^{n}$ be given as in the introduction of this paper. Then the set $G=\left\{x \in M^{n} ; \nu(x)=2(n-1)\right\}=\left\{x \in M^{n} ;\right.$ the rank of the Gauss map $\left.=2\right\}$ is open and dense in $M^{n}$.

Proof. By upper semi-continuity of $\nu, G$ is open. Suppose that $M-G$ contains an interior point, say $x$. Then we have a minimal geodesic $\gamma(t)$ in $M$ which joins $x$ to a point $y$ in $G$, i.e., $\gamma(0)=y$ and $\gamma\left(t_{0}\right)=x$.

Let $e_{1}$ and $J e_{1}$ at $y$ be such that $g\left(R\left(e_{1}, J e_{1}\right) J e_{1}, e_{1}\right) \neq 0$. By the parallel displacement along $\gamma$, we have real analytic vector fields $e_{1}(t)$ and $J e_{1}(t)$ along $\gamma(t)$.

Define a function $K:\left[0, t_{0}\right] \rightarrow R$ by

$$
\begin{equation*}
K(t)=g\left(A(t)\left(e_{1}(t)\right), e_{1}(t)\right)^{2}+g\left(J A(t)\left(e_{1}(t)\right), e_{1}(t)\right)^{2} \tag{3.1}
\end{equation*}
$$

where $A$ is a (1, 1)-tensor field defined by $\tilde{V}_{X} \xi=-A X+\hat{V}_{X} \xi$. Then clearly $K$ is a real analytic function and $-K(t)$ is the holomorphic sectional curvature of the plane spanned by $e_{1}$ and $J e_{1}$ at $t, 0 \leq t \leq t_{0}$.

Since $y$ is in $G, K(0) \neq 0$. Therefore on $\left[0, t_{0}\right], K$ is not identically zero so that it must have at most finite zeros. This contradicts the assumption that $x$ is an interior point of $M-G$.

Lemma 3.4. Let $x$ be any point in $M-G$. Then there exists an $\varepsilon$-ball around $x$ such that in the ball any geodesic starting at $x$ is either entirely in $M-G$ or intersects with $M-G$ at finitely many points.

Proof. Let $e_{1}, \cdots, e_{2 n}$ be a unitary frame at $x$ such that $e_{i+n}=J e_{i}, 1 \leq$ $i \leq n$. Then for small $\varepsilon>0$, we can take an $\varepsilon$-ball where we can define a real analytic frame by the parallel displacement of $e_{1}, \cdots, e_{2 n}$ along each geodesic starting at $x$. For convenience, we will denote the frame field on the ball by the same letters.

Let $\gamma$ be any geodesic segment such that $\gamma(0)=x$ and the whole segment is
in the ball. If $\gamma$ is not in $M-G$ entirely, then there is a point $y$ on $\gamma$ such that $y=\gamma\left(t_{0}\right)$ is in $G$. Thus we can find a pair of vectors, say $e_{i}$ and $J e_{i}$, among $e_{1}, \cdots, e_{2 n}$ such that the function $K(t)$ in (3.1) with $e_{1}$ replaced by $e_{i}$ is nonzero at $y$. Since $K(t)$ is a real analytic function, there exist at most finitely many zeros on $\gamma(t)$.

Lemma 3.5. Let $x$ be any point in $M$. Then there exists a complex ( $n-1$ )dimensional plane, say $p(f(x))$, in $C^{n+1}$ such that:
(3.2) $\quad p(f(x))$ is tangent to $f(M)$, i.e., there exists a complex $(n-1)$-dimensional plane $p(x)$ in $T M_{x}$ such that $f_{*}(p(x))=p(f(x))$,
(3.3) $\quad p(f(x))$ is parallel to a fixed complex $(n-1)$-dimensional plane, say $C^{n-1}$, in $C^{n+1}$ for all $x$ in $M$.
Proof. To define the above fixed plane $C^{n-1}$ in $C^{n+1}$, take a fixed point $x_{0}$ in $G$, and consider the image of the leaf passing through $x_{0}$ by $f$, which is a complex ( $n-1$ )- plane in $C^{n+1}$ by [1, Theorem 2.3.1]. So we may define $C^{n-1}$ to be the $(n-1)$-dimensional plane passing through the origin of $C^{n+1}$ and parallel to the image plane of the leaf containing $x_{0}$.

If $x$ is in $G$, then define $p(f(x))$ to be the image plane of the leaf passing through $x$. Since $f$ is an isometric immersion, (3.2) is satisfied.

If $x$ is in $M-G$, by Lemmas 3.3 and 3.4 we can find a connected component of $G$, say $G^{\prime}$, such that there exists a geodesic segment of $\gamma^{\prime}(t), 0 \leq t \leq \varepsilon^{\prime}$, which, except $\gamma^{\prime}(0)=x$, belongs to $G^{\prime}$. By Lemma 3.2 the image planes $p(f(\bar{x}))$ where $\bar{x}$ is in $G^{\prime}$ are parallel in $C^{n+1}$. Thus define $p(f(x))$ to be the point set limit of the planes $p\left(f\left(\gamma^{\prime}(t)\right)\right), 0 \leq t \leq \varepsilon^{\prime}$, as $t$ approaches 0 . Notice here that such a limit plane as above is also parallel to the planes in $f\left(G^{\prime}\right)$.

Next we show that the definition of $p(f(x)), x \in M-G$, does not depend on the choice of the connected component of $G$. Let $G^{\prime \prime}$ be another connected component of $G$ such that there exists a geodesic segment $\gamma^{\prime \prime}(t), 0 \leq t \leq \varepsilon^{\prime \prime}$, starting at $x$ and belonging to $G^{\prime \prime}$ except at $\gamma^{\prime \prime}(0)=x$. Let $p^{\prime \prime}$ be the plane defined as $p(f(x))$ by $G^{\prime \prime}$. Note that these planes are tangent to $M$ in the sense of (3.2), because $M$ is complete and $f$ is an isometric immersion.

Let $\left(x^{1}, \cdots, x^{2 n}\right)$ be a local coordinate system around $x$ in $M$, and for convenience let $f(x)$ be the origin of $C^{n+1}$. Then we can regard $f_{*}\left(T M_{x}\right)$ as a $2 n$ dimensional subspace passing through the origin in $R^{2 n+2}=C^{n+1}$.

Let $e_{1}, \cdots, e_{2 n}, e_{2 n_{+1}}, e_{2 n+2}$ be a basis of $R^{2 n+2}$ such that $e_{1}=f_{*}\left(\partial / \partial x^{1}\right), \cdots$, $e_{2 n}=f_{*}\left(\partial / \partial x^{2 n}\right)$, and $e_{2 n+1}$ and $e_{2 n+2}$ are orthogonal to $f_{*}\left(T_{x} M\right)$. Define $\tilde{p}: R^{2 n+2} \rightarrow f_{*}\left(T M_{x}\right)$ to be the natural projection. Then the Jacobian of $\tilde{p} \circ f: M$ $\rightarrow T M_{x}$ at $x$ is nothing but the identity matrix with respect to the basis introduced above. Thus $\tilde{p} \circ f$ is a diffeomorphism on a small neighborhood $U$ of $x$ where $f$ is an isometry. Therefore $\tilde{p}$ is a diffeomorphism on $f(U)$.

Since the projection $\tilde{p}$ preserves parallelism for affine subspaces in $R^{2 n+2}$, $\tilde{p}(p(f(x)))$ is parallel to $\tilde{p}\left(p\left(f\left(\gamma^{\prime}(t)\right)\right)\right)$ in $f^{*}\left(T M_{x}\right)$ for all $\gamma^{\prime}(t), 0 \leq t \leq \varepsilon^{\prime}$, in $U$ as $2(n-1)$-dimensional subspaces. Note that $\tilde{p}$ is a local diffeomorphism on $f(U)$, and $p(f(x)) \subset f(M), p\left(f\left(\gamma^{\prime}(t)\right)\right) \subset f(M)$, so the $\tilde{p}$-images of these planes
have the same dimension as that of $p(f(x))$ and $p\left(f\left(\gamma^{\prime}(t)\right)\right)$ for $\gamma^{\prime}(t)$ in $U$.
Suppose $p^{\prime \prime} \neq p(f(x))$ as complex ( $n-1$ )-dimensional subspace of $f_{*}\left(T M_{x}\right)$. This assumption makes sense because $p^{\prime \prime}$ and $p(f(x))$ are actually in $f_{*}\left(T M_{x}\right)$. Then we have a complex line $H$ in $p^{\prime \prime}$ such that $H \cap f(p(x))=\{0\}$, and $H$ and $f(p(x))$ span $f_{*}\left(T M_{x}\right)$. Under the above condition, we know that any complex ( $n-1$ )-dimensional affine subspace of $f_{*}\left(T_{*} M_{x}\right)$ which is parallel to $p(f(x))$ must intersect $H$. So for sufficiently small $t_{0}>0, \tilde{p}\left(p\left(f\left(\gamma^{\prime}\left(t_{0}\right)\right)\right)\right.$ must intersect $H$ in $\tilde{p} \circ f(U)$. Therefore $H \cap p\left(f\left(\gamma^{\prime}\left(t_{0}\right)\right)\right) \neq \emptyset$ in $f(U)$. Since this is impossible, we have shown $p^{\prime \prime}=p(f(x))$.

To show each $p(f(x))$ is parallel to $C^{n-1}$, take a minimal geodesic segment $\gamma(t)$ between $x$ and $x_{0}$ such that $\gamma(0)=x_{0}$ and $\gamma\left(t_{*}\right)=x$. Then by the same argument as in the proofs of Lemmas 3.3 and 3.4, we find finitely many points, say $0<t_{1}<, \cdots,<t_{k} \leq t_{*}$, which are in $M-G$. By the above argument, we know that $p(f(\gamma(0)))=p\left(f\left(x_{0}\right)\right), p\left(f\left(\gamma\left(t_{1}\right)\right)\right), \cdots, p\left(f\left(\gamma\left(t_{k}\right)\right)\right)$ and $p\left(f\left(\gamma\left(t_{*}\right)\right)\right)$ are parallel to each other, hence $p(f(x))$ is parallel to $C^{n-1}$ in $C^{n+1}$.

## 4. Proof of the theorem

Proposition 4.1. (1.4) in the theorem implies (1.5).
Proof. For convenience, let ( $Z^{0}, \cdots, Z^{n}$ ) be the natural coordinate system in $C^{n+1}$ such that $C^{n-1}$ in Lemma 3.5 is given as the set $\left\{\left(Z^{0}, \cdots, Z^{n-2}, 0,0\right) \in\right.$ $C^{n+1}$.

By the definition of Gauss map and by Lemma 3.5 the point $\tilde{\phi}(x)$ for $x \in M$ must be identified with a complex line given by the parallel transformation in $C^{n+1}$ from a complex line orthogonal to $p(f(x))$. Thus $\phi(M)$ must be in the complex projective line $C P^{1}$ in $C P^{n}$ which corresponds to the linear subspace $\left\{\left(0, \cdots, 0, Z^{n-1}, Z^{n}\right)\right\}$ in $C^{n+1}$. q.e.d.

It is almost obvious that (1.6) implies (1.4). To show that (1.5) implies (1.6), we start with the following lemma.

Lemma 4.1. Under the conditions (1.5) in the theorem, we can find $C^{\infty}$ distributions on $M$, say $D$ and $D^{\perp}$, whose complex dimensions are $n-1$ and 1, respectively, and which satisfy the following:
(4.1) $D$ and $D^{\perp}$ are of $C^{\infty}$ and invariant by $J$,
(4.2) $D$ and $D^{\perp}$ are parallel,
(4.3) $D^{\perp}(x)$ is orthogonal to $D(x)$ at each $x$ in $M$.

Proof. For convenience, let $C P^{1} \subset C P^{n}$ be given as in the above Proposition 4.1, and let $\tilde{\phi}(M) \subset C P^{1} \subset C P^{n}$.

Since $f$ is an isometric immersion, for any $x$ in $M, T M_{x}$ contains a complex ( $n-1$ )-dimensional plane whose image by $f_{*}$ is parallel to $C^{n-1}$ in $C^{n+1}$.

Define $D(x)$ to be the ( $n-1$ )-plane in $T M_{x}$, and $D^{\perp}(x)$ to be the plane in $T M_{x}$ orthogonal to $D(x)$ at each $x$. Then (4.1) and (4.3) are clear by the definition of $D$ and $D^{\perp}$. To show (4.2) for any $X \in T M$ and $Y$ in $D$, we have

$$
\tilde{\nabla}_{f_{*}(X)} f_{*}(Y)=f_{*}\left(\nabla_{X} Y\right)+\alpha(X, Y)
$$

By the definition of $D$, we have $\tilde{V}_{f_{*}(X)} f_{*}(Y) \subset f_{*}(D)$. Thus

$$
\nabla_{X} Y=f_{*}^{-1}\left(f_{*}\left(\nabla_{X} Y\right)\right)=f_{*}^{-1}\left(\tilde{\nabla}_{f_{*}(X)} f_{*}(Y)\right) \subset D
$$

Hence $D$ is parallel.
Since the parallel transformation preserves the Riemannian metric, $D^{\perp}$ is parallel. q.e.d.

Now applying the de Rham decomposition theorem [4], we have the local product structure. To extend it globally, let ( $\tilde{M}, P$ ) be the universal covering manifold of $M$ with the projection $P$. Then we can put the canonical Kählerian structure induced from that of $M$ in $\tilde{M}$.

Define distributions $\tilde{D}$ and $\tilde{D}^{\perp}$ on $\tilde{M}$ as follows: $\tilde{D}(\tilde{x})$ is the subspace of $T \tilde{M}_{\tilde{x}}$ which is mapped isometrically to $D(P(\tilde{x}))$ in $T M_{P(\tilde{x})}$ by $P_{*}$, and $\tilde{D} \perp(\tilde{x})$ is the orthogonal complement of $\tilde{D}(\tilde{x})$ in $T \tilde{M}_{\tilde{x}}$.

Since $P$ is an isometric immersion, $P_{*}\left(\tilde{D}^{\perp}(\tilde{x})\right)=D^{\perp}(x)$, and therefore
(4.4) $\quad \tilde{D}$ and $\tilde{D}^{\perp}$ are of $C^{\infty}$ and invariant by the complex structure in $\tilde{M}$, (4.5) $\tilde{D}$ and $\tilde{D}^{\perp}$ are parallel,
(4.6) $\tilde{D}^{\perp}(\tilde{x})$ is orthogonal to $\tilde{D}(\tilde{x})$ at $\tilde{x}$.

Hence by the de Rham decomposition theorem for Kählerian manifolds [4, Vol. II], we have an ( $n-1$ )-dimensional Kählerian manifold $\tilde{M}_{1}^{n-1}$ and a 1-dimensional Kählerian manifold $\tilde{M}_{2}^{1}$ such that there exists a holomorphic isometry $\tilde{q}: \tilde{M}_{1}^{n-1} \times \tilde{M}_{2}^{1} \rightarrow M$ mapping each ( $\tilde{M}_{1}^{n-1}, \tilde{x}_{2}$ ), for $\tilde{x}_{2} \in \tilde{M}_{2}^{1}$, to the leaf of $\tilde{D}$ passing through $\left(\tilde{x}_{1}, \tilde{x}_{2}\right), \tilde{x}_{1} \in \tilde{M}_{1}^{n-1}$, holomorphically and isometrically.

When we consider $\tilde{M}$ as a submanifold of $C^{n+1}$ immersed by $f \circ p$, we will easily see that each leaf of the foliation by $\tilde{D}$ is totally geodesic in $C^{n+1}$ as well as in $M$ and $\tilde{M}$. Completeness of the leaves is also obtained from completeness of $\tilde{M}$ by the same argument as in [4], once we know that the leaves are totally geodesic. Thus $f \circ p \circ \tilde{q} \mid\left(\tilde{M}_{1}^{n-1}, \tilde{x}\right)$, i.e., the restriction of $f \circ p \circ \tilde{q}$ to $\left(\tilde{M}_{1}^{n-1}, \tilde{x}_{2}\right)$, maps ( $\tilde{M}_{1}^{n-1}, \tilde{x}_{2}$ ) holomorphically and isometrically onto a complex $(n-1)$ dimensional plane which is parallel to $C^{n-1}$ in $C^{n+1}$.

Since $\left(\tilde{x}_{1}, \tilde{M}_{2}^{1}\right)$, for $\tilde{x}_{1}$ in $\tilde{M}_{1}^{n-1}$, is orthogonal to $\left(\tilde{M}_{1}^{n-1}, \tilde{x}_{2}\right)$ at ( $\tilde{x}_{1}, \tilde{x}_{2}$ ) in $\tilde{M}_{1}^{n-1} \times \tilde{M}_{2}^{1}$, we also know that $\left(\tilde{x}_{1}, \tilde{M}_{2}^{1}\right)$ is mapped by $f \circ p \circ \tilde{q}$ into the complex 2-dimensional plane orthogonal to $C^{n-1}$; this is the product structure for $\tilde{M}$.

It is not difficult to derive the product structure of $M^{n}$ from that of $\tilde{M}^{n}$ which is given above. q.e.d.

Remark. In the real case [3], the condition that the rank of the Gauss map be $\leq 1$ is equivalent to that the manifold be flat. However, in the complex case, our condition (1.4) does not imply that $M^{n}$ is flat. To be more precise, if $M^{n}$ is a flat Kählerian hypersurface of $C^{n+1}$, then $M^{n}$ is a $C^{n}$ in $C^{n+1}$.

For higher codimension, the result corresponding to our theorem in this paper can also be obtained, and the proof is a slight modification of the one given here.

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