# On the Decomposition of a Linearly Connected Manifold with Torsion. 

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## § 1. Introduction

Let $M$ be a differentiable manifold with a linear connection, and let $\Phi_{x}$ be the homogeneous holonomy group at a point $x \in M$. If the tangent vector space at $x$ is decomposed into a direct sum of subspaces which are invariant under $\Phi_{x}$, then by the parallel displacements along curves on $M$, parallel distributions are defined on $M$ corresponding to those subspaces. If $M$ is a Riemannian manifold and its connection is Riemannian, then by the de Rham decomposition theorem ( $[7]$ or [4] p. 185) the above parallel distributions are completely integrable and, at any point, $M$ is locally isometric to the direct product of leaves through the point. Moreover, if $M$ is simply connected and complete, it is globally isometric to the direct product of those leaves (see also [7] or [4] p. 192).

The above local and global decomposition theorems of de Rham are generalized to the case of pseudo-Riemannian manifold by $\mathrm{H} . \mathrm{Wu}([9])$. On the other hand, in [2], S. Kashiwabara generalized the global decomposition theorem to the case of linearly connected manifold without torsion, under the assumption of local decomposability.

In the present paper, a linearly connected manifold with torsion will be treated and a condition of local decomposition will be given in terms of curvature and torsion (Theorem 1). Next, in §4, the results will be applied to a reductive homogeneous space with the canonical connection of the second kind, using the notion of algebra introduced by A. A. Sagle in [8].

Finally, in §5, we shall remark about the decomposition of a local loop with any point in $M$ as its origin ([3]), corresponding to the local decomposition of the linearly connected manifold $M$.

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## § 2. Integrability of parallel distributions

Let $(M, \nabla)$ be a connected differentiable manifold with a linear connection, where $V$ means the covariant differentiation of the connection. The curvature tensor $R$ and the torsion tensor $S$ are defined by the formulas:

$$
\begin{align*}
& R(X, Y) Z=\nabla_{X} \nabla_{Y} Z-\nabla_{Y} \nabla_{X} Z-\nabla_{[X, Y]} Z  \tag{2.1}\\
& S(X, Y)=\nabla_{X} Y-\nabla_{Y} X-[X, Y] \tag{2.2}
\end{align*}
$$

for vector fields $X, Y$ and $Z$ on $M$.
Definition 1. For a subspace $T_{x}^{\prime}$ of the tangent vector space $T_{x}(M)$ at $x$, the torsion tensor $S$ is said to be inducible to $T_{x}^{\prime}$ at $x$ if $S_{x}\left(X_{x}, Y_{x}\right) \in T_{x}^{\prime}$ for any $X_{x}$ and $Y_{x}$ in $T_{x}^{\prime}$. When $T_{x}(M)$ is decomposed into a direct sum of complementary subspaces $T_{x}^{\prime}$ and $T_{x}^{\prime \prime}$, the torsion $S$ is said to be completely inducible with respect to the direct sum if $S$ is inducible to each of $T_{x}^{\prime}$ and $T_{x}^{\prime \prime}$, and $S_{x}\left(X_{x}, Y_{x}\right)=0$ for $X_{x} \in T_{x}^{\prime}$ and $Y_{x} \in T_{x}^{\prime \prime}$. The complete inducibility of torsion with respect to a direct sum of finite number of subspaces will be defined similarly. The torsion $S$ is said to be inducible or completely inducible to distributions if it is so at every point in $M$.

If, at a point $x_{0}$ in $M$, a subspace $T_{x_{0}}^{\prime}$ of the tangent vector space $T_{x_{0}}(M)$ is invariant under the homogeneous holonomy group $\Phi_{x_{0}}$, the parallel displacements along curves joining $x_{0}$ to all points of $M$ define a parallel distribution $T^{\prime}$ on $M$. In fact the result of parallel displacement of $T_{x_{0}}^{\prime}$ to a point $x$ is independent of the choice of curves from $x_{0}$ to $x$.

Proposition 1. A parallel distribution $T$ is completely integrable if and only if the torsion tensor $S$ is inducible to $T$.

Proof. Let $Y$ be a vector field in $T$. Since $T$ is parallel, $\nabla_{X} Y$ also belongs to $T$ for any vector field $X$ on $M$. Hence for any pair of vector fields $X, Y$ in $T$, vector fields $\nabla_{X} Y$ and $\nabla_{Y} X$ belong to $T$. Now, from (2.2) the bracket [ $X, Y]$ of $X$ and $Y$ in $T$ belongs to $T$ if and only if $S(X, Y)$ belongs to $T$.

Proposition 2. Let $T^{\prime}$ be a completely integrable parallel distribution on $M$, and $N$ be a leaf (maximal integral manifold) of $T^{\prime}$. Then $N$ is a totally geodesic submanifold of $(M, \nabla)$. Moreover, $(M, \nabla)$ induces a linear connection $\nabla^{\prime}$ on $N$ whose curvature tensor $R^{\prime}$ and torsion tensor $S^{\prime}$ are tensors induced naturally in $N$ from $R$ and $S$ respectively.

Proof. A geodesic which passes through a point $x$ in $N$ and is tangent to $N$ at $x$ has its tangent vectors in the parallel distribution $T^{\prime}$. Since $N$ is a leaf of $T^{\prime}$ through $x$, this geodesic is a curve in $N([4]$, p. 86). Hence by definition $N$ is a totally geodesic submanifold of $M$. Next, let $X, Y$ be tangent vector fields on $N$. If $X_{x_{0}} \neq 0$, denote by $\tau(s)$ the parallel displacement of vectors along a trajectory $c(s)$ of $X$ in a neighborhood of $x_{0}=c(0)$ in $N$. Since any vector obtained by parallel displacement of a tangent vector of $N$ also is tangent to $N, \tau(s)^{-1} Y_{c(s)}$ is contained in $T_{x_{0}}(N)$. Thus we can define an operation $\nabla^{\prime}$ by the formula:

$$
\begin{equation*}
\left(\nabla_{x}^{\prime} Y\right)_{x_{0}}=\lim _{s \rightarrow 0} \frac{1}{s}\left(\tau(s)^{-1} Y_{c(s)}-Y_{x_{0}}\right) \tag{2.3}
\end{equation*}
$$

for any vector fields $X\left(X_{x_{0}} \neq 0\right)$ and $Y$ on $N$, and by setting $\left(\nabla_{X}^{\prime} Y\right)_{x_{0}}=0$ for $X_{x_{0}}=0$. Then $\nabla^{\prime}$ defines a linear connection on $N$. In fact, let ( $u^{1}, u^{2}, \ldots, u^{n}$, $u^{n+1}, \ldots, u^{m}$ ) be a system of coordinates valid in a neighborhood $V$ of $x_{0}$ in $M$ such that $u^{n+1}=0, \ldots, u^{m}=0$ define $N$ in a neighborhood of $x_{0}$ and ( $u^{1}, \ldots, u^{n}$ ) is a system of coordinates in a neighborhood $U$ of $x_{0}$ in $N$. Then the second term of (2.3) has an expression

$$
\begin{equation*}
\left(\frac{d Y^{a}}{d s}+\Gamma_{b c}^{a} \frac{d c^{b}}{d s} Y^{c}\right)_{s=0}\left(\frac{\partial}{\partial u^{a}}\right)_{x_{0}}, \quad 1 \leqq a, b, c \leqq n \tag{2.4}
\end{equation*}
$$

in the local coordinates, where $\Gamma_{j k}^{i}$ 's are the coefficients of given connection expressed in $V\left([1]\right.$, p. 41). From (2.4) we see that the operation $\nabla^{\prime}: \mathfrak{X}^{\prime} \times \mathfrak{X}^{\prime} \rightarrow \mathfrak{X}^{\prime}$ satisfies the conditions of covariant differentiation on $N$, where $\mathfrak{X}^{\prime}$ denotes the module of vector fields on $N$. For any vector fields $X, Y$ on $N$, if we choose vector fields $X^{*}, Y^{*}$ on $M$ which coincide with $X, Y$ respectively on an open subset $U$ of $N$, we have $\left(\nabla_{X^{*}} Y^{*}\right)_{x}=\left(\nabla_{X}^{\prime} Y\right)_{x}$ at each point $x$ in $U$. Therefore, from (2.1) and (2.2), the curvature $R^{\prime}$ and the torsion $S^{\prime}$ of ( $N, \nabla^{\prime}$ ) are equal to the tensors induced naturally by restricting $R$ and $S$ to $N$ respectively.

## § 3. Decomposition of linearly connected manifolds

Let $\left(M^{\prime}, \nabla^{\prime}\right)$ and ( $\left.M^{\prime \prime}, \nabla^{\prime \prime}\right)$ be connected manifolds each of which has a linear connection. We choose a covering of $M=M^{\prime} \times M^{\prime \prime}$ by coordinate neighborhoods adapted to the direct product, that is, each coordinate neighborhood $U$ is a direct product of coordinate neighborhoods $U^{\prime}$ in $M^{\prime}$ and $U^{\prime \prime}$ in $M^{\prime \prime}$ with a system of coordinates ( ${ }^{\prime} u^{1},{ }^{\prime} u^{2}, \ldots,{ }^{\prime} u^{a}, \ldots,{ }^{\prime} u^{m^{\prime}},{ }^{\prime \prime} u^{1}, \ldots,{ }^{\prime \prime} u^{\alpha}, \ldots,{ }^{\prime \prime} u^{m^{\prime \prime}}$ ) where (' $u^{a}$ ) and ( ${ }^{\prime \prime} u^{\alpha}$ ) are systems of local coordinates on $U^{\prime}$ and $U^{\prime \prime}$ respectively and $m^{\prime}=\operatorname{dim} M^{\prime}, m^{\prime \prime}=\operatorname{dim} M^{\prime \prime}$.

We shall define a linear connection on $M$ by associating a family of functions $\Gamma_{(U)}=\left\{\Gamma_{j k}^{i}\left({ }^{\prime} u^{a},{ }^{\prime \prime} u^{\alpha}\right)\right\}$ with each adapted coordinate neighborhood $U$ as follows

$$
\begin{align*}
& \Gamma_{b c}^{a}\left({ }^{\prime} u,{ }^{\prime \prime} u\right)={ }^{\prime} \Gamma_{b c}^{a}\left({ }^{\prime} u\right) \quad \text { for } \quad 1 \leqq a, b, c \leqq m^{\prime} \text {, }  \tag{3.1}\\
& \Gamma_{j k}^{i}\left({ }^{\prime} u,{ }^{\prime \prime} u\right)={ }^{\prime \prime} \Gamma_{\beta \gamma}^{\alpha}\left({ }^{\prime \prime} u\right) \text { for } 1 \leqq \alpha, \beta, \gamma \leqq m^{\prime \prime} \text {, and } i=m^{\prime}+\alpha \text {, }  \tag{3.2}\\
& j=m^{\prime}+\beta, \quad k=m^{\prime}+\gamma, \\
& \Gamma_{j k}^{i}\left({ }^{\prime} u,{ }^{\prime \prime} u\right)=0 \text { for the rest, } \tag{3.3}
\end{align*}
$$

where ${ }^{\prime} \Gamma_{b c}^{a}\left({ }^{\prime} u\right)$ 's (resp. ${ }^{\prime \prime} \Gamma_{\beta \gamma}^{\alpha}\left({ }^{\prime \prime} u\right)$ 's) are the coefficients of the connection on $M^{\prime}$ (resp. $M^{\prime \prime}$ ) with respect to the local coordinates (' $u^{a}$ ) (resp. (" $u^{\alpha}$ )). If $U=$ $U^{\prime} \times U^{\prime \prime}$ and $V=V^{\prime} \times V^{\prime \prime}$ are coordinate neighborhoods adapted to the direct product and if they have common points, two families $\Gamma_{(U)}$ and $\Gamma_{(V)}$ are related to each other in the law of transformation of coefficients of a linear connection;

$$
\begin{align*}
\Gamma_{(V) q r}^{p}= & \sum_{i, j, k=1}^{m^{\prime}+m^{\prime \prime}} \frac{\partial u^{j}}{\partial v^{q}} \frac{\partial u^{k}}{\partial v^{r}} \frac{\partial v^{p}}{\partial u^{i}} \Gamma_{(U) j k}^{i}  \tag{3.4}\\
& +\sum_{i=1}^{m^{\prime}+m^{\prime \prime}} \frac{\partial^{2} u^{i}}{\partial v^{q} \partial v^{r}} \frac{\partial v^{p}}{\partial u^{i}}, \quad 1 \leqq p, q, r \leqq m^{\prime}+m^{\prime \prime}
\end{align*}
$$

Thus a linear connection is defined on $M=M^{\prime} \times M^{\prime \prime}$.
Definition 2. The product manifold $M=M^{\prime} \times M^{\prime \prime}$ with the linear connection defined above will be called the affine product of $\left(M^{\prime}, \nabla^{\prime}\right)$ and ( $M^{\prime \prime}, \nabla^{\prime \prime}$ ) ([2]).

Theorem 1. Let ( $M, \nabla$ ) be a connected differentiable manifold with a linear connection. Suppose that the homogeneous holonomy group $\Phi_{x_{0}}$ leaves complementary subspaces $T_{x_{0}}^{\prime}$ and $T_{x_{0}}^{\prime \prime}$ of the tangent space at $x_{0}$ invariant and denote by $T^{\prime}$ and $T^{\prime \prime}$ the corresponding parallel distributions. If (1) the curvature $R$ satisfies $R(X, Y)=0$ for $X \in T^{\prime}$ and $Y \in T^{\prime \prime}$, (2) the torsion $S$ is completely inducible to these distributions, then $T^{\prime}$ and $T^{\prime \prime}$ are both completely integrable, and at each point of $M,(M, \nabla)$ is locally affinely isomorphic to the affine product of $\left(M^{\prime}, \nabla^{\prime}\right)$ and $\left(M^{\prime \prime}, \nabla^{\prime \prime}\right)$ where $M^{\prime}\left(\right.$ resp. $\left.M^{\prime \prime}\right)$ is a leaf of $T^{\prime}$ (resp. $\left.T^{\prime \prime}\right)$ with the connection $\nabla^{\prime}$ (resp. $\nabla^{\prime \prime}$ ) induced naturally from ( $M, \nabla$ ).

Proof. Since the torsion $S$ is inducible to $T^{\prime}$ and $T^{\prime \prime}$, these distributions are completely integrable (Proposition 1), and every leaf $M^{\prime}$ (resp. $M^{\prime \prime}$ ) of $T^{\prime}$ (resp. $T^{\prime \prime}$ ) has a naturally induced connection (Proposition 2). Let $x_{0}$ be any point in $M$ and assume that $M^{\prime}$ and $M^{\prime \prime}$ contain $x_{0}$ in common. There exists a coordinate neighborhood $U^{\prime}$ in $M^{\prime}$ (resp. $U^{\prime \prime}$ in $M^{\prime \prime}$ ) with a system of coordinates $\left(u^{1}, u^{2}, \ldots, u^{a}, \ldots, u^{m^{\prime}}\right)\left(\operatorname{resp} .\left(u^{m^{\prime}+1}, \ldots, u^{\alpha}, \ldots, u^{m^{\prime}+m^{\prime \prime}}\right)\right)$ such that $U^{\prime} \times U^{\prime \prime}$ is diffeomorphic to a neighborhood $U$ of $x_{0}$ in $M$ and that $\left(\frac{\partial}{\partial u^{1}}, \ldots, \frac{\partial}{\partial u^{a}}, \ldots\right.$, $\left.\frac{\partial}{\partial u^{m^{\prime}}}\right)$ and $\left(\frac{\partial}{\partial u^{m^{\prime}+1}}, \ldots, \frac{\partial}{\partial u^{\alpha}}, \ldots, \frac{\partial}{\partial u^{m^{\prime}+m^{\prime \prime}}}\right)$ form local bases for $T^{\prime}$ and $T^{\prime \prime}$ respectively if we choose ( $u^{1}, \ldots, u^{a}, \ldots, u^{m^{\prime}}, u^{m^{\prime}+1}, \ldots, u^{m^{\prime}+m^{\prime \prime}}$ ) as local coordinates in $U$. Denote by $\Gamma_{j k}^{h}\left(u^{i}\right)\left(h, i, j, k=1,2, \ldots, m^{\prime}+m^{\prime \prime}\right)$ the coefficients of the connection with respect to the above coordinates in $U$. In the rest of the proof we shall adopt notational conventions of indices as $1 \leqq a, b, c, \ldots \leqq m^{\prime}$; $m^{\prime}+1 \leqq \alpha, \beta, \gamma, \cdots \leqq m^{\prime}+m^{\prime \prime}$ and $1 \leqq i, j, k, \cdots \leqq m^{\prime}+m^{\prime \prime}$.

Since $\nabla_{\frac{\partial}{\partial u^{\nu}}} \frac{\partial}{\partial u^{c}}$ belong to $T^{\prime}$, all coefficients of the type $\Gamma_{b c}^{\alpha}\left(u^{i}\right)$ vanish and $\Gamma_{\alpha \beta}^{b}$ 's similarly vanish. By the assumption (2) we have

$$
\begin{equation*}
\nabla_{\frac{\partial}{\partial u^{a}}} \frac{\partial}{\partial u^{\alpha}}-\nabla_{\partial}^{\partial u^{\alpha}} \frac{\partial}{\partial u^{a}}=0 . \tag{3.5}
\end{equation*}
$$

On the other hand since the distributions $T^{\prime}$ and $T^{\prime \prime}$ are parallel, $\nabla_{\frac{\partial}{\partial u^{a}}} \frac{\partial}{\partial u^{\alpha}}$ is in $T^{\prime \prime}$ as long as $\frac{\partial}{\partial u^{\alpha}}$ is in $T^{\prime \prime}$, and $\nabla_{\frac{\partial}{\partial u^{\alpha}}} \frac{\partial}{\partial u^{a}}$ is in $T^{\prime}$ simultaneously with $\frac{\partial}{\partial u^{a}}$.

Therefore, from (3.5) we have $\frac{\nabla_{\partial}}{\partial u^{a}} \frac{\partial}{\partial u^{\alpha}}=\frac{\nabla_{\partial}}{\partial u^{\alpha}} \frac{\partial}{\partial u^{a}}=0$, which gives $\Gamma_{a \alpha}^{b}=\Gamma_{\alpha a}^{b}$ $=0$ and $\Gamma_{a \alpha}^{\beta}=\Gamma_{\alpha a}^{\beta}=0$.

By the assumption (1), $R\left(\frac{\partial}{\partial u^{a}}, \frac{\partial}{\partial u^{\alpha}}\right)=0$, from which we have $\frac{\partial}{\partial u^{a}} \Gamma_{\beta \gamma}^{\alpha}\left(u^{i}\right)=0$ and $\frac{\partial}{\partial u^{\alpha}} \Gamma_{b c}^{a}\left(u^{i}\right)=0$. From the definition of connection on a leaf $M^{\prime}$, we have $\Gamma_{c d}^{b}\left(u^{i}\right)=^{\prime} \Gamma_{c d}^{b}\left(u^{a}\right)$ on $M^{\prime}$ where the coefficients of the connection $\nabla^{\prime}$ on $M^{\prime}$ are denoted by ' $\Gamma_{c d}^{b}\left(u^{a}\right)$. Similarly we have $\Gamma_{\gamma \delta}^{\beta}\left(u^{i}\right)={ }^{\prime \prime} \Gamma_{\gamma \delta}^{\beta}\left(u^{\alpha}\right)$ on $M^{\prime \prime}$, where ${ }^{\prime \prime} \Gamma_{\gamma \delta}^{\beta}\left(u^{\alpha}\right)$ 's are coefficients of the connection $\nabla^{\prime \prime}$ on $M^{\prime \prime}$.

After all, we can conclude that ( $M, \nabla$ ) is locally affinely isomorphic to the affine product of $\left(M^{\prime}, \nabla^{\prime}\right)$ and $\left(M^{\prime \prime}, \nabla^{\prime \prime}\right)$ by the diffeomorphism of $U$ onto $U^{\prime} \times U^{\prime \prime}$.

Remark. From the definition of the affine product (Definition 2), it is clear that the conditions (1) and (2) are necessary for ( $M, \nabla$ ) to be locally affinely isomorphic at each point to an affine product of leaves of parallel distributions containing the point.

Definition 3. A linearly connected differentiable manifold ( $M, \nabla$ ) is said to be locally reductive if the curvature tensor $R$ and the torsion tensor $S$ are both parallel with respect to the connection, i. e., $\nabla R=0$ and $\nabla S=0$.

Corollary. Let $(M, \nabla)$ be a connected differentiable manifold with a linear connection which is locally reductive. Suppose that, at a point $x_{0}$ in $M$, the following conditions are satisfied:
(1) The tangent space $T_{x_{0}}$ to $M$ is decomposed into a direct sum of subspaces invariant under the homogeneous holonomy group, such as $T_{x_{0}}=$ $T_{x_{0}}^{\prime}+T_{x_{0}}^{\prime \prime}$;
(2) $R_{x_{0}}(X, Y)=0$ for $X \in T_{x_{0}}^{\prime}$ and $Y \epsilon T_{x_{0}}^{\prime \prime}$;
(3) $S_{x_{0}}$ is completely inducible (Definition 1) with respect to the direct sum.

Then any point of $M$ has a neighborhood which is locally affinely isomorphic to an affine product of locally reductive spaces.

Proof. If $\nabla S=0$, we have $S_{x}\left(\tau X_{x_{0}}, \tau Y_{x_{0}}\right)=\tau S_{x_{0}}\left(X_{x_{0}}, Y_{x_{0}}\right)$ for any $X_{x_{0}}$ and $Y_{x_{0}}$ in $T_{x_{0}}(M)$, where $\tau$ is the parallel displacement of tangent vectors along a curve starting at $x_{0}$ and ending to any point $x$ in $M$. Hence $S_{x}$ is inducible to the tangent subspace $T_{x}^{\prime}=\tau T_{x_{0}}^{\prime}$ at $x$ if $S_{x_{0}}$ is inducible to the subspace $T_{x_{0}}^{\prime}$ at $x_{0}$. Complete inducibility at any point $x$ follows similarly. In the same way, if $\nabla R=0$ we have $R_{x}\left(\tau X_{x_{0}}, \tau Y_{x_{0}}\right) \tau Z_{x_{0}}=\tau\left(R_{x_{0}}\left(X_{x_{0}}, Y_{x_{0}}\right) Z_{x_{0}}\right)$. Hence $R\left(T_{x}^{\prime}\right.$, $\left.T_{x}^{\prime \prime}\right)=0$ at any point $x$ if and only if $R\left(T_{x_{0}}^{\prime}, T_{x_{0}}^{\prime \prime}\right)=0$, where $R\left(T_{x}^{\prime}, T_{x}^{\prime \prime}\right)=\left\{R_{x}(X\right.$, $Y) ; X \in T_{x}^{\prime}$ and $\left.Y \in T_{x}^{\prime \prime}\right\}$. Therefore the corresponding parallel distributions $T^{\prime}$ and $T^{\prime \prime}$ satisfy the conditions (1) and (2) in Theorem 1, and any point in $M$ has a neighborhood which is locally affinely isomorphic to the affine product of leaves $M^{\prime}$ and $M^{\prime \prime}$ of $T^{\prime}$ and $T^{\prime \prime}$ respectively. Since $\nabla R=0$ and $\nabla S=0$ on $M$,
the naturally induced tensors $R^{\prime}$ and $S^{\prime}$ (resp. $R^{\prime \prime}$ and $S^{\prime \prime}$ ) are also parallel with respect to the induced connection on $M^{\prime}\left(\right.$ resp. $\left.M^{\prime \prime}\right)$.

Theorem 2. Let ( $M, \nabla$ ) be a connected and simply connected differentiable manifold with a complete linear connection. Then under the assumptions same as in Theorem 1 we have the global affine isomorphism of ( $M, \nabla$ ) to the affine product of $\left(M^{\prime}, \nabla^{\prime}\right)$ and $\left(M^{\prime \prime}, \nabla^{\prime \prime}\right)$.

For the proof, see [2]. In [2] a global decomposition of a linearly connected manifold without torsion has been treated and it is also valid in our case.

## § 4. Application to reductive homogeneous spaces ${ }^{1)}$.

Definition 4. A homogeneous space $G / H$ of a connected Lie group $G$ is called reductive if the following condition is satisfied; in the Lie algebra (5) of $G$ there exists a subspaces $\mathfrak{M}$ such that $\mathbb{C S}^{5}$ is decomposed into a direct sum $\mathfrak{B}=\mathfrak{M}+\mathfrak{F}$ and $\operatorname{ad}(H) \mathfrak{M} \subset \mathfrak{M}$, where $\mathfrak{S c}$ is the subalgebra of $\mathfrak{E}$ corresponding to H.

Let $M=G / H$ be a reductive homogeneous space with a fixed Lie algebra decomposition $\mathfrak{B}=\mathfrak{M}+\mathfrak{K}$ (direct sum), and let $V$ denote the canonical connection (of the second kind in the sense of Nomizu [6]). The connection $\nabla$ is $G$ invariant on $M$ whose curvature tensor $R$ and torsion tensor $S$ are parallel on $M$. Let $\pi$ denote the natural projection of $G$ onto $M$. By identifying $\mathfrak{M}$ with the tangent space at the origin $x_{0}=\pi(e)$ ( $e$ is the identity of $G$ ), we have

$$
\begin{align*}
& R_{x_{0}}(X, Y)=\operatorname{ad}\left(-[X, Y]_{\mathfrak{g}}\right)  \tag{4.1}\\
& S_{x_{0}}(X, Y)=-[X, Y]_{\mathfrak{M}} \tag{4.2}
\end{align*}
$$

for any $X, Y$ in $\mathfrak{M}$, where $[X, Y]_{5}$ and ${\underset{\mathfrak{S}}{3}}^{[ } X, Y]_{\mathfrak{M}}$ denote the $\mathfrak{S}$-component and the $\mathfrak{M}$-component of the bracket with respect to the direct sum $\mathfrak{G}=\mathfrak{M}+\mathfrak{C}([6]$ Theorem 10. 3).

We shall define two mappings $([8]) \varphi(X, Y)=-[X, Y]_{m}$ and $h(X, Y)=$ $-[X, Y]_{\mathfrak{\xi}}$ for any $X, Y$ in $\mathfrak{M}$. The mapping $\varphi$ is an anti-symmetric and bilinear binary operation on $\mathfrak{M}$ which defines an algebra ( $\mathfrak{M}, \varphi$ ). The subalgebra $\mathfrak{M}^{\prime}$ of $\mathfrak{M}$ is said to be simple if $\varphi\left(\mathfrak{M}^{\prime}, \mathfrak{M}^{\prime}\right) \neq 0$ and $\mathfrak{M}^{\prime}$ has no proper ideal of $\mathfrak{M}^{\prime}$. The subalgebra $\mathfrak{M}^{\prime}$ is said to be semi-simple if it is a direct sum

$$
\begin{equation*}
\mathfrak{M}^{\prime}=\mathfrak{M}_{1}+\mathfrak{M}_{2}+\cdots+\mathfrak{M}_{p} \quad \text { (direct sum) } \tag{4.3}
\end{equation*}
$$

of ideals $\mathfrak{M}_{i}(i=1,2, \ldots, p)$ each of which is simple.
If $\mathfrak{M}^{\prime}$ is semi-simple with direct sum decomposition (4.3) into simple ideals, then $\varphi\left(\mathfrak{M}_{i}, \mathfrak{M}_{i}\right) \subset \mathfrak{M}_{i}$ and $\varphi\left(\mathfrak{M}_{i}, \mathfrak{M}_{j}\right)=0$ for $i \neq j$, and since $S_{x_{0}}(X, Y)=\varphi(X, Y)$

[^0]the torsion $S$ is completely inducible with respect to the decomposition (4.3) of the tangent subspace at $x_{0}$ (by identifying $\mathfrak{M}^{\prime}$ with $d \pi_{e}\left(\mathfrak{M}^{\prime}\right)$ ).

On the other hand, for two subalgebras $\mathfrak{M}^{\prime}$ and $\mathfrak{M}^{\prime \prime}$ of $\mathfrak{M}$, if we set $\mathfrak{D}\left(\mathfrak{M}^{\prime}\right.$, $\left.\mathfrak{M}^{\prime \prime}\right)=\left\{\operatorname{ad} h(X, Y) ; X \in \mathfrak{M}^{\prime}, Y \in \mathfrak{M}^{\prime \prime}\right\}, \mathfrak{D}(\mathfrak{M}, \mathfrak{M})$ can be regarded as the holonomy algebra of $(M, \nabla)$ since $R_{x_{0}}(X, Y)=$ ad $h(X, Y)$ for any $X, Y$ in $\mathfrak{M}$. Therefore, if $M=G / H$ is simply connected, the subalgebra $\mathfrak{N}^{\prime}$ of $\mathfrak{M}$ is $\mathfrak{D}(\mathfrak{M}, \mathfrak{M})$-invariant if and only if the tangent subspace $d \pi_{e}\left(\mathfrak{M}^{\prime}\right)$ is invariant under the connected homogeneous holonomy group at $x_{0}$.

Theorem 3. Let $M=G / H$ be a simply connected reductive homogeneous space of a connected Lie group $G$ with a fixed Lie algebra decomposition $\mathbb{B}=$ $\mathfrak{M}+\mathfrak{F}$. Suppose that:
(1) The algebra ( $\mathfrak{M}, \varphi$ ) is a direct sum of the subspace $\mathfrak{M}_{0}=\{X \epsilon \mathfrak{M}$; $\varphi(X, \mathfrak{M})=0\}$ and a semi-simple subalgebra $\mathfrak{M}^{\prime}$ which is decomposed into a direct sum of simple ideals as (4.3).
(2) $\mathfrak{D}\left(\mathfrak{M}_{i}, \mathfrak{M}_{j}\right)=0 \quad$ for $\quad i \neq j$.
(3) Each subspace $\mathfrak{M}_{i}(i=0,1,2, \ldots, p)$ is $\mathfrak{D}(\mathfrak{M}, \mathfrak{M})$-invariant.

Then $(M, \nabla)$ is globally affinely isomorphic to an affine product of a locally affine symmetric space $M_{0}$ and locally reductive spaces $M_{1}, M_{2}, \ldots, M_{p}$.

Proof. By identifying $\mathfrak{M}$ with the tangent space at $x_{0}=\pi(e)$, the assumptions (1), (2) and (3) correspond to those in Corollary to Theorem 1 respectively. In fact, as mentioned above, (1) and (3) are equivalent to the corresponding conditions of complete inducibility of the torsion and holonomy invariance of the subspaces respectively. The condition (2) implies that ad $h(X, Y)=0$ for $X \in \mathfrak{M}_{i}$ and $Y \in \mathfrak{M}_{j}(i \neq j)$, which is equivalent to $R_{x_{0}}\left(\mathfrak{M}_{i}, \mathfrak{M}_{j}\right)=0$ for $i \neq j$.

Since $\nabla R=0$ and $\nabla S=0$ on $M$, Corollary of Theorem 1 implies that there pass through $x_{0}$ the leaves $M_{0}, M_{1}, \ldots, M_{p}$ of distributions obtained by parallel displacement of the subspaces $\mathfrak{M}_{0}, \mathfrak{M}_{1}, \ldots, \mathfrak{M}_{p}$ respectively and that $M$ is locally affinely isomorphic to the affine product $M_{0} \times M_{1} \times \cdots \times M_{p}$. Since each $M_{i}(i=0,1,2, \ldots, p)$ has a connection induced naturally from the canonical connection $\nabla$ on $M$, its curvature and torsion are both parallel on $M_{i}$, in particular, $M_{0}$ has zero torsion by the definition of the subspace $M_{0}$, i. e., $M_{0}$ is a locally affine symmetric space. Since the canonical connection of a reductive homogeneous space is complete, we have a global decomposition of ( $G / H, \nabla$ ) by Theorem 2.

Remark. In the Theorem 3, if the condition (3) is replaced by (3') each $\mathfrak{M}_{i}$ is ad ( $\mathfrak{C}$ )-invariant, then ( $M, \nabla$ ) is locally affinely isomorphic to an affine product of reductive homogeneous spaces $M_{i}=G_{i} / H(i=0,1, \ldots, p)$ with canonical connections, where $G_{i}$ is a connected subgroup of $G$ corresponding to Lie subalgebra $\mathscr{A}_{i}=\mathfrak{M}_{i}+\mathfrak{K}_{2}$.

In fact, since ad ( $\mathfrak{C}$ ) contains $\mathfrak{D}(\mathfrak{M}, \mathfrak{M}),\left(3^{\prime}\right)$ implies (3). Moreover, under the assumption ( $3^{\prime}$ ) it is easy to see that $\mathscr{H}_{i}=\mathfrak{M}_{i}+\mathscr{S}_{2}$ is a Lie subalgebra of $\mathbb{C S}$.

Since $H$ is connected $M_{i}^{\prime}=G_{i} / H$ is well defined and reductive. Each locally reductive space $M_{i}(i=0,1, \ldots, p)$ obtained in Theorem 3 has the same curvature and the torsion at $x_{0}$ as those of $M_{i}^{\prime}$ at the origin, with respect to the canonical connection. Therefore, $M_{i}$ and $M_{i}^{\prime}$ are locally affinely isomorphic to each other at their origin ( $[5]$ p. 62). For any point $x$ in $M$, there exists a local affine isomorphism of ( $M, \nabla$ ) which sends $x$ to $x_{0}$. Thus, for any point $x$ in $M$, there exists a local affine isomorphism of some neighborhood of $x$ to a neighborhood of the origin of affine product $M_{0}^{\prime} \times M_{1}^{\prime} \times \cdots \times M_{p}^{\prime}$.

## § 5. Some remarks about local loops

Any point $p$ of a linearly connected manifold $M$ has a neighborhood $U$ in which a binary operation $f_{p}$ can be defined so as to form a local loop $\mathcal{L}\left(U, f_{p}\right)$ ([3]). The binary operation $f_{p}$ is defined as follows; let $U$ be a normal neighborhood in which two points are joined by one and only one geodesic arc and let $x$ and $y$ be any two points of $U$, then there exist the unique geodesic arc $x(t)(0 \leqq t \leqq a)$ in $U$ joining $p=x(0)$ to $x=x(a)$ and the unique geodesic arc $y(s)$ ( $0 \leqq s \leqq b$ ) joining $p=y(0)$ to $y=y(b)$ (parameters are all affine). Let $X_{p}$ be the vector tangent to $x(t)$ at $p$ and $X_{y}$ be the vector obtained by the parallel displacement of $X_{p}$ to $y$ along the arc $y(s)$, then we have the unique geodesic arc $z(t)\left(0 \leqq t \leqq a^{\prime}\right)$ in $U$ starting from $y$ and tangent to $X_{y}$. If $z(t)$ can be defined for $t=a$, we define $f_{p}(x, y)=z(a)$ and call it the product of $x$ and $y$ in $U$ with respect to the origin $p$.

The product operation $f_{p}$ defines a differentiable local loop $\mathcal{L}\left(U, f_{p}\right)$ on $U$, that is, (1) for any point $x$ in $U$ if we define $\rho_{x}(y)=f_{p}(x, y)$ and $\lambda_{x}(y)=f_{p}(y, x)$ ( $y \in U$ ), each of $\rho_{x}$ and $\lambda_{x}$ is a local diffeomorphism of a neighborhood of $p$ onto a neighborhood of $x$; (2) $f_{p}(p, x)=f_{p}(x, p)=x$ for any $x \in U$, i. e., $p$ is the unit.

The associative law does not hold in general.
Let $T$ be a parallel distribution on $M$ and suppose that the torsion tensor is inducible to $T$, then by Proposition $1 T$ is completely integrable. Let $N$ be the maximal integral manifold of $T$ containing $p$, then there exists a normal neighborhood $U^{\prime}$ of $p$ in $N$ (with respect to the naturally induced connection $\nabla^{\prime}$ ) which is contained in the connected component of $N \cap U$, where $U$ is the underlying neighborhood of a local loop $\mathcal{L}\left(U, f_{p}\right)$. The local loop $\mathcal{L}\left(U^{\prime}, f_{p}^{\prime}\right)$ is thereby defined in ( $N, \nabla^{\prime}$ ).

Proposition 3. The local loop $\mathcal{L}\left(U^{\prime}, f_{p}^{\prime}\right)$ is a local subloop of $\mathcal{L}\left(U, f_{p}\right)$.
Proof. Let $x$ and $y$ be two points in $U^{\prime} \subset U$ and let $x(t)(0 \leqq t \leqq a)$ and $y(s)(0 \leqq s \leqq b)$ be geodesic arcs in $U$ joining $p$ to $x$ and $y$ respectively. Since $T$ is parallel any geodesic in ( $M, \nabla$ ) tangent to $N$ at a point is a geodesic in ( $N, \nabla^{\prime}$ ) and the parallel displacement of a vector in $T_{p}(N)$ with respect to $\nabla^{\prime}$ coincides with one with respect to $\nabla$, along any curve in $N$. Therefore,
$f_{p}^{\prime}(x, y)^{\prime}=f_{p}(x, y)$ if both sides are defined.
Theorem 4. Let $T^{\prime}$ and $T^{\prime \prime}$ be complementary parallel distributions on a linearly connected manifold $(M, \nabla)$ and let $\mathcal{L}\left(U, f_{p}\right)$ be a local loop in $M$ with origin $p$. Suppose that the conditions (1) and (2) in theorem 1 are satisfied, then $\mathcal{L}\left(U, f_{p}\right)$ is locally isomorphic to the direct product of local loops $\mathcal{L}\left(U^{\prime}, f_{p}^{\prime}\right)$ and $\mathcal{L}\left(U^{\prime \prime}, f_{p}^{\prime \prime}\right)$ where $U^{\prime}$ and $U^{\prime \prime}$ are normal neighborhoods of $p$ with respect to $\nabla^{\prime}$ and $\nabla^{\prime \prime}$ respectively introduced on the integral manifolds of $T^{\prime}$ and $T^{\prime \prime}$ containing $p$.

Proof. By the above Proposition, local loops $\mathcal{L}\left(U^{\prime}, f_{p}^{\prime}\right)$ and $\mathcal{L}\left(U^{\prime \prime}, f_{p}^{\prime \prime}\right)$ can be defined with respect to $\nabla^{\prime}$ and $\nabla^{\prime \prime}$ respectively, and they are local subloops of $\mathcal{L}\left(U, f_{p}\right)$. Without loss of generality, we can suppose that $U^{\prime} \times U^{\prime \prime}$ is affinely isomorphic to $U$ and that they are coordinate neighborhoods such as considered in the proof of Theorem 1. Then any geodesic arc $x(t)(0 \leqq t \leqq a)$ in $U$ is represented by ( $x^{\prime}(t), x^{\prime \prime}(t)$ ) in $U^{\prime} \times U^{\prime \prime}$ where $x^{\prime}(t)$ (resp. $x^{\prime \prime}(t)$ ) is a geodesic in $U^{\prime}\left(\right.$ resp. $\left.U^{\prime \prime}\right)$ with respect to $\nabla^{\prime}\left(\right.$ resp. $\left.\nabla^{\prime \prime}\right)$, and a parallel vector field $X(t)$ on the geodesic $x(t)$ is represented by $\left(X^{\prime}(t), X^{\prime \prime}(t)\right)$ where $X^{\prime}(t)$ (resp. $\left.X^{\prime \prime}(t)\right)$ is the parallel vector field along $x^{\prime}(t)$ (resp. $x^{\prime \prime}(t)$ ). In fact the above facts are clear at a glance of corresponding equations in local coordinates by taking account of the condition that the coefficients $\Gamma_{j k}^{i}$ of $\nabla$ containing some distinct sort of indices vanish. Therefore, identifying $U$ with $U^{\prime} \times U^{\prime \prime}$ by the affine isomorphism we have $f_{p}(x, y)=\left(f_{p}^{\prime}\left(x^{\prime}, y^{\prime}\right), f_{p}^{\prime \prime}\left(x^{\prime \prime}, y^{\prime \prime}\right)\right)$ for two points $x=\left(x^{\prime}, x^{\prime \prime}\right)$ and $y=\left(y^{\prime}, y^{\prime \prime}\right)$ in $U$, if the left or the right side of the equation is defined.

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[^0]:    1) For the details of reductive homogeneous space, see Nomizu [6] or Lichnerowicz [5] p. 48.
