

MARKOV PROCESSES ON MANIFOLDS OF MAPS

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1. **Introduction.** In this note we describe a construction of a Markov process on a manifold of maps starting from a Gaussian measure on the space of sections of an associated vector bundle. Let S be a compact metric space of finite metric dimension and M a smooth complete finite dimensional Riemannian manifold. Our basic construction gives a family $\{\nu_t: t \geq 0\}$ of Borel probability measures on the space $C(S \times M, M)$ of continuous functions from $S \times M$ to M with the compact-open topology. The multiplication $(f, g)(s, m) = f(s, g(s, m))$ for $f, g \in C(S \times M, M)$ makes $C(S \times M, M)$ into a topological semi-group with identity. Then $\nu_t * \nu_s = \nu_{t+s}$ for $s, t \geq 0$ and the right translates of the ν_t give transition probabilities for a Markov process on $C(S \times M, M)$ with continuous sample paths. The left action of $C(S \times M, M)$ on $C(S, M)$ induces a Markov process on $C(S, M)$ with transition probability $\nu_{t,g} =$ image of ν_t under the action of $C(S \times M, M)$ on $g \in C(S, M)$.

2. **Statement of results.** Let ξ denote the product bundle $S \times TM \rightarrow S \times M$ and $C(\xi)$ the space of continuous sections of ξ . Given a Gaussian measure μ of mean zero on $C(\xi)$, define

$$Q(s, x, t, y) = \int f(s, x) \otimes f(t, y) d\mu(f) \in T_x M \otimes T_y M$$

for all $s, t \in S, x, y \in M$.

Q is a reproducing kernel for the bundle ξ (see Baxendale [1]) and determines μ uniquely. Let $X \in C(\xi)$.

For a closed isometric embedding of M inside some Euclidean space V , let $h(x)$ denote the second fundamental form for $M \subset V$ at $x \in M$. Using the natural inclusion $T_x M \subset V$ and orthogonal projection $V \rightarrow T_x M$, we think of X, Q and h taking values in V and its various tensor products.

THEOREM 1. *Suppose there exists a closed isometric embedding $M \subset V$ such that (i) h is bounded and uniformly Lipschitz with respect to the metric on M induced from V .*

Suppose moreover that there exist a Gaussian measure μ on $C(\xi)$, $X \in C(\xi)$ and $\alpha > 0, C > 0$ such that

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- (i) $\text{tr}(Q(s, x, s, x)) \leq C, \quad \forall s, x,$
- (ii) $\text{tr}(Q(s, x, s, x) + Q(t, y, t, y) - Q(s, x, t, y) - Q(t, y, s, x))$
 $\leq C(d(s, t)^{2\alpha} + |x - y|_V^2), \quad \forall s, x, t, y,$
- (iii) $|X(s, x)|_V \leq C, \quad \forall s, x,$
 $|X(s, x) - X(t, y)|_V \leq C(d(s, t)^\alpha + |x - y|_V), \quad \forall s, x, t, y.$

Then μ and X determine a family of Borel probability measures $\{\nu_t: t \geq 0\}$ on $C(S \times M, M)$ satisfying

(a) $\nu_s * \nu_t = \nu_{s+t}, \quad \forall s, t \geq 0,$

(b) the ν_t are transition probabilities for a Markov process on $C(S \times M, M)$ with continuous sample paths.

We illustrate the dependence of the $\{\nu_t\}$ on μ and X as follows. For $s = (s_1, \dots, s_r) \in S^r$ and $x = (x_1, \dots, x_r) \in M^r$ denote by

$$\rho_{s,x}: C(S \times M, M) \rightarrow M^r$$

$$\sigma_{s,x}: C(\xi) \rightarrow T_{x_1}M \times \dots \times T_{x_r}M,$$

the evaluation maps at $(s_1, x_1), \dots, (s_r, x_r)$. Let $\nu_{s,x}^t$ be the image of ν_t under $\rho_{s,x}$, then

(i) the $\nu_{s,x}^t$ for all s, x determine ν_t ,

(ii) the $\nu_{s,x}^t$ for fixed s are the transition probabilities for a Markov process on M^r with continuous sample paths.

THEOREM 2. *The Markov process corresponding $\{\nu_{s,x}^t: t \geq 0, x \in M^r\}$ has infinitesimal generator A_s , where*

$$(A_s g)(x) = \frac{1}{2} \int (\nabla^2 g)(x) (\sigma_{s,x}(h), \sigma_{s,x}(h)) d\mu(h) + (\nabla g)(x)(\sigma_{s,x}(X)),$$

where ∇ is covariant differentiation with respect to the product Riemannian structure on M^r .

3. The construction. For each s, x and $t > 0$, we construct a measure $\nu_{s,x}^t$ on M^r as follows. Using the embedding $M \subset V$ and choosing suitable extensions, we construct a Wiener process W_t in $C(S \times V, V)$ (see Gross [2]) and $\tilde{X} \in C(S \times V, V)$. Define

$$Y(s, x) = \frac{1}{2} \int_{C(\xi)} h(x)(g(s, x), g(s, x)) d\mu(g) \in T_x^\perp M \quad \text{for } x \in M,$$

and extend to $\tilde{Y} \in C(S \times V, V)$. Consider the stochastic differential equation in V^r

$$\left. \begin{aligned} d\eta_i(t) &= (\tilde{X} + \tilde{Y})(s_i, \eta_i(t))dt + dW(t)(s_i, \eta_i(t)) \\ \eta_i(0) &= x_i \end{aligned} \right\} i = 1, \dots, r.$$

The choice of \tilde{Y} ensures that if $x_i \in M$, then $\eta_i(t) \in M$ for all $t > 0$ with probability one. The conditions (i), (ii) and (iii), plus care in choosing extensions, imply that the equation has a solution for all $t > 0$, that the solution is continuous with probability one and has finite moments of all orders. We define $\nu_{s,x}^t$ to be the distribution of $(\eta_1(t), \dots, \eta_r(t)) \in M^r$. The existence of the $\{\nu_t\}$ follows from the Daniell-Kolmogorov construction and an estimate on the moments of solutions of the stochastic differential equation.

4. Examples. Suppose S and M are compact Riemannian manifolds and $p > \frac{1}{2} \dim S$, $q > \frac{1}{2} \dim M + 1$. Then $L_p^2(S) \otimes L_q^2(TM) \subset C(\xi)$ is radonifying, and the Wiener measure μ satisfies the conditions of Theorem 1. Take $X = 0$. Each pair (p, q) in the range above yields a different family $\{\nu_t\}$ of measures on $C(S \times M, M)$.

The condition that M be compact may be replaced by completeness together with certain curvature conditions.

Notice that the case $M = \mathbf{R}^n$ yields Gaussian measures. Also $S = \text{point}$ and suitable choice of μ gives Brownian motion on M under the sole condition that there exists a closed isometric embedding with $\|h(x)\| \leq C(1 + d(x, x_0))$ for some $C > 0$ and $x_0 \in M$.

REFERENCES

1. P. Baxendale, *Gaussian measures on function spaces*, Amer. J. Math. (to appear).
2. L. Gross, *Potential theory on Hilbert space*, J. Functional Analysis 1 (1967), 123–181. MR 37 #3331.

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