

ADJOINTS, NUMERICAL RANGES, AND SPECTRA OF OPERATORS ON LOCALLY CONVEX SPACES

BY ROBERT T. MOORE¹

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1. Introduction. The results announced here are of two sorts. First, two important tools from operator theory on Hilbert spaces, the notions of *states* and of *numerical ranges* of operators, are extended to the setting of operator theory on general locally convex spaces. We employ several ideas developed in the work of Lumer [1] for extending these methods to Banach spaces, combining these with the generalizations of classical Banach space methods to the locally convex setting announced by the author in [3].

Second, several related results are announced concerning the approximation of spectra of operators by their numerical ranges. These results are new in the classical settings of Hilbert and Banach spaces as well as in the more general setting. An interesting motivating example on Hilbert spaces, couched in terms of familiar notions, is discussed separately in §2, unencumbered by the technical machinery of later sections.

Full details of proof will appear in two places. A short, less technical discussion of these methods as applied to Hilbert spaces, Banach spaces, B^* algebras, and Banach algebras will appear in [6]. The general theory, with concrete applications, will be included in the monograph [5], along with the results announced in [4], which use these methods to provide a unified theory of the generation of semigroups.

2. Approximation of spectra in Hilbert spaces. Let \mathfrak{H} be a complex Hilbert space with a fixed reference inner product $(\cdot, \cdot)_0$. Call another inner product (\cdot, \cdot) *equivalent* to $(\cdot, \cdot)_0$ iff the norms $\|u\| = (u, u)^{1/2}$ and $\|u\|_0 = (u, u)_0^{1/2}$ induce the same topology on \mathfrak{H} ; we view inner products as "noncanonical" structures associated with an underlying topology, subject to change when convenient.

Then, for any such inner product (\cdot, \cdot) on \mathfrak{H} , the *numerical range* is

$$(1) \quad W(T, (\cdot, \cdot)) = \{(Tu, u) \mid u \in \mathfrak{H}, \text{ and } \|u\| = 1\}.$$

It is well known that $W(T, (\cdot, \cdot))$ is a convex set with compact closure containing the spectrum of T . In fact, if $K = W(T, (\cdot, \cdot))^-$ (the

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closure of W) and $d_\lambda = \text{dist}(\lambda, K)$ for $\lambda \notin K$, then the first-order decay estimate holds:

$$(2) \quad \|(\lambda - T)^{-1}\| \leq d_\lambda^{-1}$$

and this property is known to characterize K [7].

THEOREM 0. *Let U be any open set containing the closed convex hull $\text{cocl}(\sigma(T))$ of $\sigma(T)$. Then there exists an inner product (\cdot, \cdot) on H equivalent to $(\cdot, \cdot)_0$ such that*

$$(3) \quad \sigma(T) \subset W(T, (\cdot, \cdot))^- \subset U.$$

Furthermore, if

$$(4) \quad W_H(T) = \bigcap \{W(T, (\cdot, \cdot))^- \mid (\cdot, \cdot) \text{ equivalent to } (\cdot, \cdot)_0\}$$

is the Hilbertian numerical range of T , then

$$(5) \quad \text{cocl}(\sigma(T)) = W_H(T).$$

COROLLARY. *For any operator $T \in \mathcal{B}(\mathfrak{H})$ and $\epsilon > 0$ there exists an inner product (\cdot, \cdot) such that*

$$(6) \quad \|(\lambda - T)^{-1}\| \leq [\text{dist}(\lambda, \text{cocl}(\sigma(T))) - \epsilon]^{-1}.$$

3. Geometries, numerical ranges, and first-order decay. The first step in generalizing the theory of §2 is to find a suitable geometrical structure on a general locally convex space \mathfrak{X} to replace the inner product on a Hilbert space, and then to extend the numerical range notion. In the language introduced in [3], suppose Γ calibrates a complex locally convex space (lcs) \mathfrak{X} .

LEMMA 1 (LUMER [1]). *Let $p \in \Gamma$. Then there exists a choice function $\chi_p: \mathfrak{X} \rightarrow \mathfrak{X}^*$ (frequently more than one) such that*

$$(7) \quad (a) \quad p(u)^2 = \langle u, \chi_p(u) \rangle \quad \text{for all } u \in \mathfrak{X}, \text{ and}$$

$$(8) \quad (b) \quad |\langle u, \chi_p(v) \rangle| \leq p(u)p(v) \quad \text{for all } u, v \text{ in } \mathfrak{X}.$$

(Here \mathfrak{X}^* denotes the space $\mathcal{L}(\mathfrak{X}, \mathbb{C})$ of continuous linear functionals from \mathfrak{X} to \mathbb{C} and $u \rightarrow \langle u, u_* \rangle$ denotes the action of $u_* \in \mathfrak{X}^*$ on $u \in \mathfrak{X}$.)

Then an important part of the ultimate (Lumer) geometry Λ_* for \mathfrak{X} is defined by selecting for each $p \in \Gamma$ a χ_p and setting $\Lambda_0 = \{\chi_p \mid p \in \Gamma\}$. For a general densely defined (dd) A on \mathfrak{X} , we define a first part of the numerical range:

$$(9) \quad W(A, \Lambda_0) = \{ \langle Au, \chi_p(u) \rangle \mid u \in D(A), \chi_p \in \Lambda_0, \text{ and } p(u) = 1 \}.$$

In general, $W(A, \Lambda_0)$ does not appear to be big enough to imitate the

numerical range $W(T, (,))$ in §2; duality must be brought in more strongly by considering adjoints.

Recall first that if A is any densely defined operator on \mathfrak{X} , and \mathfrak{X}^* is the space of all continuous linear functionals u_* on \mathfrak{X} , then the adjoint A^* of A is defined, for all $u_* \in \mathfrak{X}^*$ where $u \rightarrow \langle Au, u_* \rangle$ is continuous on the domain $D(A)$, by $\langle Au, u_* \rangle = \langle u, A^*u_* \rangle$. If the strong dual of \mathfrak{X} is denoted by \mathfrak{X}_β^* , we have the following analog of a familiar Banach space theorem concerning operator norms of adjoints.

THEOREM 2. *For every calibration Γ for \mathfrak{X} , there exists a natural dual calibration Γ_* for \mathfrak{X}_β^* such that the adjoint map $T \rightarrow T^*$ is an isometric isomorphism of $\mathfrak{F}_\Gamma(\mathfrak{X})$ into $\mathfrak{F}_{\Gamma_*}(\mathfrak{X}_\beta^*)$. Thus $T \rightarrow T^*$ carries $\mathfrak{F}(\mathfrak{X})$ into $\mathfrak{F}(\mathfrak{X}_\beta^*)$.*

Picking a χ_q for each $q \in \Gamma_*$, we may form a set $\Lambda_1 = \{\chi_q \mid q \in \Gamma_*\}$. Following a suggestion of Phillips [8], let \mathfrak{X}° be the closure of $D(A^*)$ in \mathfrak{X}_β^* , and let $D(A^\circ) = \{u_* \in D(A^*) \mid A^*u_* \in \mathfrak{X}^\circ\}$, $A^\circ = A^*|_{D(A^\circ)}$. Then in analogy with (9)

$$(10) \quad W(A^\circ, \Lambda_1) = \{ \langle A^\circ u_*, \chi_q(u_*) \rangle \mid u_* \in D(A^\circ), \chi_q \in \Lambda_1, q(u_*) = 1 \}.$$

DEFINITION 1. Let Γ calibrate a complex lcs \mathfrak{X} , and let Γ_* be the dual calibration of \mathfrak{X}_β^* .

(a) Then $\Lambda_* = \Lambda_0 \cup \Lambda_1$ is a (Lumer) *geometry* for (\mathfrak{X}, Γ) .

(b) Furthermore, if A is densely defined on \mathfrak{X}

$$(11) \quad W(A, \Lambda_*) = W(A, \Lambda_0) \cup W(A^\circ, \Lambda_1)$$

is the *numerical range* of A .

Then the following result generalizes §2, Lumer [1], and unpublished remarks made to the author by J. Hosack.

THEOREM 3. (a) *Suppose Γ calibrates a complete complex lcs \mathfrak{X} and A is closed dd on \mathfrak{X} . Then $W(A, \Lambda_*)^- \supset \sigma_\Gamma(A)$ and if $d_\lambda = \text{dist}(\lambda, W(A, \Lambda_*)^-)$*

$$(12) \quad \|(\lambda - A)^{-1}\|_\Gamma \leq d_\lambda^{-1}$$

for all geometries Λ_* for (\mathfrak{X}, Γ) .

(b) *Similarly, if Γ calibrates a complex normcomplete lcs \mathfrak{X} and $A \in \mathfrak{F}_\Gamma(\mathfrak{X})$, then the closed convex hull $K = \text{cocl}(W(A, \Lambda_0)) \supset \sigma_\Gamma(A)$ and if $d_\lambda = \text{dist}(\lambda, K)$, (12) holds for every Λ_* for Γ .*

(c) *Furthermore, if K is any closed convex set in \mathbb{C} such that $K \supset \sigma_\Gamma(A)$ and for $d_\lambda = \text{dist}(\lambda, K)$ (12) holds, then $K \supset W(A, \Lambda_*)$ for all Λ_* for (\mathfrak{X}, Γ) .*

(d) *In particular, if Λ_* and Λ'_* are two geometries for (\mathfrak{X}, Γ) , then in (a) or (b)*

$$(13) \quad \text{cocl}(W(A, \Lambda_*)) = \text{cocl}(W(A, \Lambda'_*)).$$

4. Convex approximation of spectra. The generalization of Theorem 0 to the locally convex setting seems to require restriction to finite operators $T \in \mathfrak{F}(\mathfrak{X}) = \cup \{ F_\Gamma(\mathfrak{X}) \mid \Gamma \text{ calibrates } \mathfrak{X} \}$; these operators are the ones which most closely imitate "bounded" operators on Banach and Hilbert spaces.

THEOREM 4. *Suppose \mathfrak{X} is a complex normcomplete lcs. Let $T \in \mathfrak{F}(\mathfrak{X})$ and suppose U is an open set containing the closed convex hull of the finite spectrum $\text{cocl}(\sigma_F^*(T))$. Then there exists a calibration Γ for \mathfrak{X} such that if Λ_* is any geometry for (\mathfrak{X}, Γ)*

$$(14) \quad \sigma_F^*(T) \subset W(T, \Lambda_*)^- \subset U.$$

Consequently, in particular

$$(15) \quad \sigma_F^*(T) \subset W_G(T) \equiv \cap \{ W(T, \Lambda_*)^- \mid T \in \mathfrak{F}_\Gamma(\mathfrak{X}), \text{ and } \Lambda_* \text{ a geometry for } (\mathfrak{X}, \Gamma) \} \subset \text{cocl}(\sigma_F^*(T)).$$

The proof of this theorem depends upon a simpler fact which is a corollary of Theorem 4 from [3], the recalibration theorem. We write $|W|(T, \Lambda_*) = \sup \{ |\lambda| \mid \lambda \in W(T, \Lambda_*) \}$ for the *numerical radius* of T with respect to Λ_* .

LEMMA 5. (a) *If $T \in \mathfrak{F}(\mathfrak{X})$,*

$$(16) \quad r_E(T) = \inf \{ |W|(T, \Lambda_*) \mid T \in \mathfrak{F}_\Gamma(\mathfrak{X}), \Lambda_* \text{ a geometry for } (\mathfrak{X}, \Gamma) \}.$$

(b) *Indeed, if $\{T_1, \dots, T_k\}$ is a finite commutative family in $\mathfrak{F}(\mathfrak{X})$, and $\epsilon > 0$, then there exists a calibration Γ with $\{T_i \mid 1 \leq i \leq k\} \subset \mathfrak{F}_\Gamma(\mathfrak{X})$ such that for every Λ_* for (\mathfrak{X}, Γ)*

$$(17) \quad r_E(T_i) \leq |W|(T_i, \Lambda_*) \leq r_E(T_i) + \epsilon, \quad 1 \leq i \leq k.$$

No satisfactory answer is known at present to the question: When is the limit in (16) of Lemma 5(a) *achieved* for some equivalent geometry Λ_* ? That is, when do we have

$$(18) \quad r_E(T) = |W|(T, \Lambda_*)$$

If Λ_* is a geometry for a Banach space $(\mathfrak{X}, \|\cdot\|)$ ($\Gamma = \{ \|\cdot\| \}$) and T is Λ_* -Hermitian ($W(T, \Lambda_*) \subset \mathbf{R}$), then Vidav [9] has essentially shown that (18) holds. Also, on a Banach space $(\mathfrak{X}, \|\cdot\|)$, (18) will occur if the operator Banach algebra generated by T and I is topologically isomorphic to its Gelfand transform function algebra (with the uniform norm).

5. Decomposition of numerical ranges by projections. Unlike numerical ranges defined by inner products, general numerical ranges need not be convex; systematic exploitation of this nonconvexity can provide useful tools in operator theory. For example, the first part $W(T, \Lambda_0)$ of the numerical range can exhibit the same sort of decomposition with respect to projections as does the spectrum. Call $\mathfrak{R} = \{E_i \mid 1 \leq i \leq k\}$ a (finite) resolution of the identity for T if $\sum E_i = I$, $E_i E_j = \delta_{ij} E_j$ and $E_i T = T E_i$ for all i, j . Let T_i denote the restriction of T to the closed invariant subspace $\mathfrak{X}_i = E_i \mathfrak{X}$. It is easy to check that $\sigma_F^*(T) = \cup \{\sigma_F^*(T_i) \mid 1 \leq i \leq k\}$ as a "canonical" topological fact, but careful choice of Γ and Λ_0 leads to the following analog for numerical ranges.

LEMMA 6. *In the above situation, suppose Λ_*^i is an equivalent geometry for \mathfrak{X}_i (with the relative topology). Then there exists an equivalent geometry Λ_* for \mathfrak{X} with first part Λ_0 satisfying*

(a) every $\chi^i \in \Lambda_0^i$ is the restriction of a $\chi \in \Lambda_0$, and
 (19) (b) $W(T, \Lambda_0) = \cup \{W(T_i, \Lambda_0^i) \mid 1 \leq i \leq k\}$.

REMARK. Even in the simplest cases, one cannot hope for a simultaneous decomposition like the above for the second part $W(T, \Lambda_1)$ as well.

This result and Theorem 3(b) allow one to piece together a better approximation theorem for the spectrum.

THEOREM 7. *Continuing as above, suppose $U_i \supset \sigma^*(T_i)$ for $1 \leq i \leq k$. Then there exist geometries Λ_*^i for the \mathfrak{X}_i and Λ_* for \mathfrak{X} such that if $Q = \cup \{\text{cocl}(W(T_i, \Lambda_0^i)) \mid 1 \leq i \leq k\}$, then $Q \supset \sigma_F^*(T)$ and for the associated calibration Γ*

(20) $\|(\lambda - T)^{-1}\|_\Gamma \leq \text{dist}(\lambda, Q)^{-1}$.

These and similar methods enable one to obtain quite detailed information, of numerical range type, about the spectrum and resolvent decay of operators with ample supplies of spectral projections. Many of the ideas date back to Dunford [2]; connections with the active current literature for locally convex spaces will be discussed in later papers.

6. Perturbation of numerical ranges. For many purposes, the dependence of the numerical range $W(T, \Lambda_*)$ of a continuous $T \in \mathcal{L}(\mathfrak{X})$ upon T is much more accessible than is the comparable dependence of $\sigma_F^*(T)$ on T . We write $\mathcal{L}_s(\mathfrak{X})$ and $\mathcal{L}_b(\mathfrak{X})$ for $\mathcal{L}(\mathfrak{X})$ with the topology of simple convergence and bounded convergence respectively.

PROPOSITION 8. Let Γ calibrate a lcs \mathfrak{X} and let Λ_* be a geometry for (\mathfrak{X}, Γ) . Suppose that for some net $\{T_\alpha | \alpha \in J\}$ in $\mathfrak{L}(\mathfrak{X})$ and some closed $K \subset \mathbb{C}$, $W(T_\alpha, \Lambda_*) \subset K$ for all $\alpha \in J$.

(a) If $T_\alpha \rightarrow T$ in $\mathfrak{L}_b(\mathfrak{X})$, then $W(T, \Lambda_*) \subset K$.

(b) If \mathfrak{X} is reflexive, and $T_\alpha \rightarrow T$ in $\mathfrak{L}_s(\mathfrak{X})$, then $W(T, \Lambda_*) \subset K$.

PROPOSITION 9. Suppose $T_0 \in \mathfrak{F}_\Gamma(\mathfrak{X})$ and U is an open set containing $W(T_0, \Lambda_*)$. Then there exists a $\|\cdot\|_\Gamma$ -neighborhood $N(T_0) \subset \mathfrak{F}_\Gamma(\mathfrak{X})$ such that if $T \in N(T_0)$, $W(T, \Lambda_*) \subset U$.

PROPOSITION 10. Let Λ_* and Γ be as in Proposition 9 and suppose S, T are in $\mathfrak{L}(\mathfrak{X})$. Then

$$(21) \quad W(S + T, \Lambda_*) \subset W(S, \Lambda_*) + W(T, \Lambda_*).$$

REMARK. Although the assumptions that T be continuous and that \mathfrak{X} be reflexive would be unrealistic in many of the classical Banach space formulations of such theories as existence and uniqueness of solutions to integro-differential equations, both assumptions are typically satisfied in the modern locally convex test-function/distribution formulations.

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UNIVERSITY OF CALIFORNIA, BERKELEY, CALIFORNIA 94720