AN APPROXIMATION TO THE SAMPLE SIZE IN SELECTION PROBLEMS¹

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0. Summary. Let $f(\mathbf{x} \mid P_1)$ be the pdf of a (k-1)-dimensional normal distribution with zero means, unit variances, and correlation matrix P_1 . Consider the integral, for $\delta > 0$,

(1)
$$\int_{-\delta}^{\infty} \cdots \int_{-\delta}^{\infty} f(\mathbf{x} \mid P_1) \, dx \, \cdots \, dx_{k-1} = \alpha(\delta), \quad \text{say}.$$

Assume that no element of P_1 is a function of δ . Note that $\alpha(\delta)$ is an increasing function of δ and $\alpha(\delta) \to 1$ as $\delta \to \infty$. The problem is to obtain an approximation to δ , for a large specified value, α , of $\alpha(\delta)$. This is given by the theorem of Section 1.

This result is used to obtain approximations to the sample size in a selection procedure of Bechhofer and in a problem of selection from a multivariate normal population. The closeness of the approximation is illustrated for the procedure of Bechhofer (Table 1).

1. The Approximation to δ .

Theorem. For large α (near 1), an approximation to δ , which satisfies the equation

(2)
$$\int_{-\delta}^{\infty} \cdots \int_{-\delta}^{\infty} f(\mathbf{x} \mid P_1) \ dx_1 \cdots dx_{k-1} = \alpha,$$

is $\delta^2 \sim -2 \log_e (1 - \alpha)$. The ratio tends to 1 as $\alpha \to 1$. This approximation is independent of k.

PROOF.

(3)
$$\alpha(\delta) = \int_{-\delta}^{\infty} \cdots \int_{-\delta}^{\infty} f(\mathbf{x} \mid P_1) \, dx_1 \cdots dx_{k-1}$$
$$= P[\bigcap_{i=1}^{k-1} \{Z_i > -\delta\}] = P[\bigcap_i E_i], \text{ say.}$$

Then,

$$(4) 1 - \alpha(\delta) = P[\mathbf{U}_i \bar{E}_i].$$

Expressing the union as a disjoint union, we obtain

(5)
$$1 - \alpha(\delta) = \sum_{i=1}^{k-1} P[E_1 E_2 \cdots \bar{E}_i].$$

Now

$$P[E_1E_2\cdots\bar{E}_i] = \int_{-\delta}^{\infty}\cdots\int_{-\delta}^{\infty}\int_{-\infty}^{-\delta}f_i(\mathbf{x}\mid P_2) dx_1 \cdots dx_{i-1} dx_i,$$

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where $f_i(\mathbf{x} \mid P_2)$ is the pdf of an *i*-dimensional normal distribution with zero means, unit variances, and correlation matrix obtained from P_1 by deleting the last k-i rows and columns. The *j*th of the i-1 integrals on $(-\delta, \infty)$ can be replaced by some multiplier $C_j(i)$ between 0 and $(\pi^{k-1}k)^{\frac{1}{2}}$ which tends to a limit as $\delta \to \infty$ $(j=1, \cdots, i-1)$, and using problem 1 of Feller (1957), p. 179, the remaining integral on $(-\infty, -\delta)$, which equals the integral on (δ, ∞) , can be approximated as

$$1 - \Phi(\delta) \sim \delta^{-1} (2\pi)^{-\frac{1}{2}} e^{-\delta^2/2}$$
.

Letting $C_i = C_1(i) \cdots C_{i-1}(i)$,

$$P[E_1E_2\cdots \bar{E}_i] \sim C_i(\delta(2\pi)^{\frac{1}{2}})^{-1}e^{-\delta^2/2}$$

and letting $\bar{C} = (C_1 + \cdots + C_{k-1})(k-1)^{-1}$, $\bar{C} = \bar{C}(\delta) \to \text{a limit as } \delta \to \infty$ and an approximation to δ , such that $\alpha(\delta) = \alpha$, can be obtained from the equation

$$1 - \alpha \sim (k-1)\bar{C}(\delta(2\pi)^{\frac{1}{2}})^{-1}e^{-\delta^{2}/2}$$

Hence $\delta^2 \sim -2 \log_e (1 - \alpha)$.

2. The approximation to sample size. Ranking and selection procedures have been receiving increasing interest recently, one reason being that they furnish a method of sample size selection which is appropriate in many situations. However, the tables available for this use (e.g. those of Bechhofer (1954) and Teichroew (1955)) are not extensive enough to cover all situations which arise in practice, e.g. in drug screening where the number of populations may be very large. Also, these tables do not apply if certain independence assumptions are violated. The theorem of Section 1 provides an approximation to the sample size in a selection procedure of Bechhofer and in a multivariate situation.

Consider the following problem: Given k populations π_1, \dots, π_k the observations from which are known to be identically distributed except for a location parameter (i.e., an observation X_i from population π_i has cdf $F(x - \nu_i)$, where $F(\cdot)$ may be either known or unknown), select any one of the (at least one) populations associated with $\nu_{[k]} = \max(\nu_1, \dots, \nu_k)$. For the case in which $F(\cdot)$ is known to be normal with a known variance σ^2 , Bechhofer (1954) has suggested use of the means procedure: Take N independent vectors $X_j = (X_{1j}, \dots, X_{kj})$, $j = 1, \dots, N$, where X_{ij} denotes the jth observation from the ith population π_i ; choose the population associated with the largest $\sum_{j=1}^{N} X_{ij} (i = 1, \dots, k)$ as being associated with $\nu_{[k]}$. Let $\{\lambda^*, P^*\} (0 < \lambda^* < \infty, 1/k < P^* < 1)$ be two specified constants, and denote the ranked means by $\nu_{[1]} \leq \dots \leq \nu_{[k]}$. Then N is to be set as the smallest sample size which guarantees the following probability requirement: We are to select the population associated with $\nu_{[k]}$, i.e. we are to make a correct selection (CS), with probability $P(\text{CS}) \geq P^*$ whenever $\nu_{[k]} - \nu_{[k-1]} \geq \lambda^* \sigma$.

It is known (see Bechhofer (1954), p. 23) that, if the means procedure is used for this problem in the normal case, then subject to $\nu_{[k]} - \nu_{[k-1]} \ge \lambda^* \sigma$ the P(CS)

is minimized over $\nu_{[1]}$, \cdots , $\nu_{[k]}$ when

(6)
$$\nu_{[1]} = \cdots = \nu_{[k-1]}, \nu_{[k]} - \nu_{[k-1]} = \lambda^* \sigma,$$

the least favorable configuration (LFC) of the population parameters; call this minimal P(CS) by α .

THEOREM. As $\alpha \mapsto 1$,

$$(7) N \sim -4(\lambda^*)^{-2} \log_e (1 - \alpha),$$

the ratio tending to 1 as $N \rightarrow \infty$ due to having $\alpha \rightarrow 1$.

PROOF. From Bechhofer (1954), p. 20, eq. (13), we know that

(8)
$$\alpha = \int_{-\lambda^*(\frac{1}{2}N)^{\frac{1}{2}}}^{\infty} \cdots \int_{-\lambda^*(\frac{1}{2}N)^{\frac{1}{2}}}^{\infty} f(\mathbf{x} \mid P_1) \ dx_1 \cdots \ dx_{k-1},$$

where P_1 is the $(k-1) \times (k-1)$ correlation matrix with $\rho_{ij} = \frac{1}{2}(i \neq j)$. The theorem follows from (2).

3. Numerical study of the approximation. We can compare the N_A calculated via (7) with N_T from the tables of Bechhofer (1954) for moderate k, obtaining Table 1. (We use $\lambda^* = 1$ for convenience.) The tables of Gupta (1963), p. 810, and of Teichroew (1955) are useful in making comparisons for large k and for high P^* , respectively.

Note that the approximation (7) appears to overestimate N, thus being somewhat conservative, for $k \leq 10$. If we had $\lambda^* \neq 1$, each entry (N_T) as well as N_A would be divided by $(\lambda^*)^2$. Thus, the ratio (which by derivation approaches 1 as $N \to \infty$ due to having $\alpha \to 1$) is independent of λ^* . Although it does not appear to be the case that $|N_A - N_T| \to 0$ (indeed the difference could conceivably be unbounded) the approach of the ratio to 1 appears fairly rapid.

4. Extension to multivariate normal selection. Use of the special nature of the correlation matrix P_1 in (8) has not been made. Thus, result (7) is valid whenever a reduction of α to form (8) is possible, provided only that P_1 does not depend on N.

Now, consider the following *problem*: Given one k-variate population II the observations from which are k-variate normal, select any one of the (at least one) factors associated with $\nu_{[k]}$. Suppose that the means procedure stated in Section 2

TABLE 1 0.9990.900.950.970.990.995α N_A 27.63109.2104 11.9829 14.0262 18.420721.193313.0849 15.6159 21.5760 N_{T} 4.97387.34469.1397.71.74.78 .65 N_T/N_A .54.61 9.334211.2419 15.3633 17.9725 24.05806.7584 N_{T} .87 N_T/N_A .73 .78 .80 .83 .85 N_T 26.95378.8977 11.6841 13.712218.025120.7234.98 .98 N_T/N_A .97.98 .98 .98

is used. We then observe N independent k-variate normal vectors $X_j = (X_{1j}, \dots, X_{kj}), j = 1, \dots, N$, and select the factor associated with the largest $\bar{X}_i = \sum_{j=1}^N X_{ij}/N$ $(i = 1, \dots, N)$ as being associated with $\nu_{[k]}$.

Denote the k-variate normal distribution of any $X_j(j=1,\dots,N)$ by $N(\mathbf{v}_1,\Sigma_1)$ where $\mathbf{v}_1=(\nu_1,\dots,\nu_k)$ is unknown and Σ_1 is some covariance matrix, say $\Sigma_1=(\sigma_{ij})$ for $i,j=1,\dots,k$. Let round brackets about a subscript denote the quantity associated with that one of the ranked means; thus, $X_{(j)}(j=1,\dots,N)$ is $N(\mathbf{v}_{(1)},\Sigma_{(1)})$ where $\mathbf{v}_{(1)}=(\nu_{[1]},\dots,\nu_{[k]})$ and $\Sigma_{(1)}=(\sigma_{(i)(j)})$ for $i,j=1,\dots,k$. Now, our development will be a generalization of Bechhofer (1954), p. 20. Then (assuming $\nu_{(k)}-\nu_{(k-1)}>0$)

$$P(CS) = P[\bar{X}_{(1)} < \bar{X}_{(k)}, \dots, \bar{X}_{(k-1)} < \bar{X}_{(k)}]$$

$$= P[\bar{X}_{(k)} - \bar{X}_{(1)} > 0, \dots, \bar{X}_{(k)} - \bar{X}_{(k-1)} > 0]$$

$$= P[Y_1 > 0, \dots, Y_{k-1} > 0], \quad \text{say,}$$

where

$$(\bar{X}_{(1)}, \dots, \bar{X}_{(k)})$$
 is $N(\mathbf{v}_{(1)}, N^{-1}\Sigma_{(1)})$.

Now, (Y_1, \dots, Y_{k-1}) is (k-1)-variate normal say $N(\delta, \Sigma_2)$ with $\delta_i = EY_i = \nu_{[k]} - \nu_{[i]}$ and

(10)
$$\sigma^{2}(Y_{i}) = N^{-1}(\sigma_{(k)}^{2} + \sigma_{(i)}^{2} - 2\sigma_{(i)(k)})$$
$$\sigma(Y_{i}Y_{j}) = N^{-1}(\sigma_{(k)}^{2} - \sigma_{(i)(k)} - \sigma_{(j)(k)} + \sigma_{(i)(j)}).$$

Now, (9) is minimized subject to $\nu_{[k]} - \nu_{[k-1]} \ge \lambda^* \sigma$ (now $\sigma > 0$ is simply some constant) by the LFC (6). Thus,

(11)
$$\alpha = P[(Y_i - \lambda^* \sigma) / \sigma(Y_i) > -\lambda^* \sigma / \sigma(Y_i), \qquad i = 1, \dots, k-1]$$
$$= P[Z_i > -\lambda^* \sigma / \sigma(Y_i), \qquad i = 1, \dots, k-1], \text{ say.}$$

 (Z_1, \cdots, Z_{k-1}) is (k-1)-variate normal $N(0, \Sigma_3)$ with

(12)
$$\sigma^2(Z_i) = 1, \quad \sigma(Z_i Z_j) = \sigma(Y_i Y_j) / \sigma(Y_i) \sigma(Y_j).$$

Therefore,

$$\alpha = |\Sigma_{3}|^{-\frac{1}{2}}/(2\pi)^{\frac{1}{2}(k-1)} \int_{(-\lambda\sigma^{*}/\sigma(Y_{1}))}^{\infty} \cdots \int_{(-\lambda^{*}\sigma/\sigma(Y_{k-1}))}^{\infty} \exp(-\frac{1}{2}x'\Sigma_{3}^{-1}x) dx_{1} \cdots dx_{k-1}$$

$$(13) \qquad \geq |\Sigma_{3}|^{-\frac{1}{2}}/(2\pi)^{\frac{1}{2}(k-1)} \int_{(-\lambda^{*}\sigma N^{\frac{1}{2}/2^{\frac{1}{2}}}\sigma_{M})}^{\infty} \cdots \int_{(-\lambda^{*}\sigma N^{\frac{1}{2}/2^{\frac{1}{2}}}\sigma_{M})}^{\infty} \exp(-\frac{1}{2}x'\Sigma_{3}^{-1}x) dx_{1} \cdots dx_{k-1},$$

where

(14)
$$\sigma_{M} = \max_{1 \le i \le k-1} \left[\frac{1}{2} (\sigma_{(k)}^{2} + \sigma_{(i)}^{2}) - \sigma_{(i)(k)} \right]^{\frac{1}{2}}.$$

Since Σ_3 is independent of N, our proof of (7) shows that the minimal N needed to make the lower bound in (13) equal to α , say \bar{N} , is such that we have the

THEOREM. As $\alpha \rightarrow 1$,

(15)
$$\bar{N} \sim -4(\lambda^*)^{-2} (\sigma/\sigma_M)^{-2} \log_e (1-\alpha),$$

the ratio tending to 1 as $\bar{N} \to \infty$ due to having $\alpha \to 1$.

Due to its construction, \bar{N} overprotects against an incorrect selection. Even if one has no knowledge whatever of σ_M , result (15) allows one to obtain an approximation to \bar{N} , if one sets $\sigma = \sigma_M$, i.e. if one makes his probability requirement in terms of multiples of the (unknown) σ_M .

If one has special knowledge then σ_M may sometimes be evaluated. E.g., if $\sigma_1^2 = \cdots = \sigma_k^2 = \sigma_0^2$ (say) and $\sigma_{(i)(k)} \geq -B$ ($B \geq 0$) for $i = 1, \dots, k$ with at least one equality, then $\sigma_M = (\sigma_0^2 + B)^{\frac{1}{2}}$. In this case the "best" such B (in terms of \bar{N}) is B = 0. (If one knew only $\sigma_{(i)(k)} \geq C$ for $i = 1, \dots, k$, then one would obtain $\sigma_M \geq (\sigma_0^2 - C)^{\frac{1}{2}}$.)

The upper bound \bar{N} will be "exact" as N is in (7) in that the minimal $N = \bar{N}$ iff (13) is an equality; this is so iff

$$\frac{1}{2}(\sigma_{(1)}^2) - \sigma_{(1)(k)} = \cdots = \frac{1}{2}(\sigma_{(k-1)}^2) - \sigma_{(k-1)(k)},$$

which occurs if, e.g., $\sigma_1^2 = \cdots = \sigma_k^2$ and $\sigma_{(1)(k)} = \cdots = \sigma_{(k-1)(k)}$. For the latter to be satisfied it is sufficient (but not necessary) that *all* covariances be equal. (Note that the case when all covariances are equal and they and σ are known has been mentioned by Milton (1963), pp. 5-6, whose tables may then be used.)

 \bar{N} will be "exact" and approximation (15) identical to approximation (7) in the case $\sigma_1^2 = \cdots = \sigma_k^2 = \sigma^2$ and all covariances are equal to 0 (the case of independence). Now, if one knew that $\sigma_1^2 = \cdots = \sigma_k^2 = \sigma^2$ and that components of any k-vector tended to vary together if at all (i.e. $\sigma_{ij} \geq 0$ ($i, j = 1, \cdots, k$), then one might extend the LFC and choose the "worst" such covariances (those which would maximize the approximation to the "exact" \bar{N}). One sees (from criterion (16) and the role of σ_M in (13)) that all covariances equal to 0 accomplish this.

One may consider such extended LFC's in other cases specified by one's knowledge. If one knows $\sigma_1^2 = \cdots = \sigma_k^2 = \sigma^2$ and $\sigma_{ij} = C$ ($i \neq j; i, j = 1, \cdots, k$) then \bar{N} will be "exact" and the worst value of C is the smallest possible (smallest such that the variance-covariance matrix is positive definite). Since for this case the matrix is positive definite iff $\sigma^2 > C > -\sigma^2/(k-1)$, as $C \downarrow -\sigma^2/(k-1), \sigma_M \uparrow [k/(k-1)]^{\frac{1}{2}}\sigma$. Thus, in this case approximation (15) to \bar{N} will differ from approximation (7) by a factor $k/(k-1) = 1 + (k-1)^{-1}$.

 \bar{N} will differ from approximation (7) by a factor $k/(k-1)=1+(k-1)^{-1}$. Finally, since $\sigma_M \leq 2^{\frac{1}{2}}\sigma$ (in the case $\sigma_1^2 = \cdots = \sigma_k^2 = \sigma^2$), the approximation to \bar{N} is at most twice that of (7). Thus, for large α at most twice as many observations per population will be required as in the case of independence.

5. Remarks. We make the following remarks.

- 1. For the case k=2, result (7) may be derived in a manner similar to that used by Dudewicz (1966), Section 2-B (i), in another context.
 - 2. As the problem statement of Section 2 should intimate, result (7) is con-

jectured to hold for a general location parameter family whose observations obey the (classical) Central Limit Theorem. A similar result can be conjectured for Section 4, and is not intimated by our problem statement there only so as to avoid a cumbersome notation.

- 3. In their monograph, Bechhofer, Kiefer, and Sobel (1968) have independently previously obtained (7) via a different proof. Although they obtain higher order corrections, their proof does not appear to generalize to multivariate problems. (See their Theorem 6.2.1, eq. 6.4.1, eq. 6.4.3, Lemma 6.5.1, and eq. 14.2.10.)
- 4. Thanks are especially due to Professor Robert E. Bechhofer for his suggestions for and guidance of Dudewicz (1966), which contains result (7), and to a referee for substantial simplification of the presentation and for the reference to Gupta (1963).

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