# SYMMETRIC DIFFERENCE IN ABELIAN GROUPS 

G. Grätzer and R. Padmanabhan


#### Abstract

A groupoid $\mathfrak{H}=\langle A ; *\rangle$ is called a left (resp. right) difference group if there is a binary operation + in $A$ such that the system $\langle A ;+\rangle$ is an abelian group and $x * y=-x+y$ (resp. $x * y=x-y$ ). A symmetric difference group is a groupoid satisfying all the identities common to both left and right difference groups. In this note we determine the structure of a symmetric difference group. Using this, we show that any finitely based equational theory of symmetric difference groups is one-based. This includes the known result that the theories of left and right difference groups are onebased. Other known results on finitely based theories of rings also follow.


Let $I$ (resp. $J$ ) stand for the class of all binary identities true in all left (resp. right) difference groups. Then the equational class of groupoids satisfying all the identities $I \cap J$ is, by definition, the class of all symmetric difference groups (SD-groups, for brevity). For example, the identity

$$
\begin{equation*}
(x * y) *(((x * z) *(u * u)) * y)=z \tag{1}
\end{equation*}
$$

belongs to the class $I \cap J$ and hence valid in every SD-group. To see this we only have to check whether (1) is true when $x * y=$ $-x+y$ or $x * y=x-y$ in abelian groups. This is indeed the case. The main result of this paper is that the converse of the above statement is true, namely, any groupoid satisfying identity (1) is, in fact, an SD-group (Theorem 2). This is obtained through a structure theorem for groupoids satisfying identity (1).

1. The structure theorem. We prepare the proof of the structure theorem with a lemma.

Lemma 1. Let $\mathfrak{H}=\langle A ; F\rangle$ be an algebra having a binary polynomial * and let $w$ be a polynomial of the type of $\mathfrak{A}$. Then the algebra satisfies the identity

$$
\begin{equation*}
(x * y) *(((x * z) * w) * y)=z \tag{2}
\end{equation*}
$$

iff $\mathfrak{2 l}$ has an abelian group reduct $\langle A ;+,-, 0\rangle$ and there exists a $\operatorname{map} \alpha: A \rightarrow A$ such that
(i) $\mathfrak{A}$ satisfies the identity $w=0$;
(ii) $\alpha$ is an involutoric ${ }^{1}$ endomorphism of the group; and

[^0](iii) $x * y=x \alpha-y \alpha$.

Proof. If there exists a map $\alpha: A \rightarrow A$ satisfying (i)-(iii) then

$$
\begin{aligned}
(x * y) & *(((x * z) * w) * y) \\
& =(x \alpha-y \alpha) \alpha-\left((x \alpha-z \alpha) \alpha^{2}-y \alpha\right) \alpha \\
& =(x-y)-(x-z-y) \\
& =x-y-x+z+y=z
\end{aligned}
$$

and hence (2) is valid in $\mathfrak{A}$.
Conversely, let $\mathfrak{A}$ satisfy the identity (2). Let us make $x * z$ into a variable $a$ by substituting $x=a * w$ and $z=((a * a) * w) * w$ to obtain

$$
((a * w) * y) *((a * w) * y)=((a * a) * w) * w
$$

Notice that we can change the term $(\alpha * w) * y$ into an arbitrary variable $z$ by substituting $y=((a * z) * w) * w$. So we have

$$
\begin{equation*}
z * z=((\alpha * \alpha) * w) * w \tag{3}
\end{equation*}
$$

and hence $z * z$ is a constant, say 0 .
Observe that we have the left cancellation property for *. Indeed, $x * z=x * t$ implies that

$$
\begin{align*}
z & =(x * y) *(((x * z) * w) * y)  \tag{2}\\
& =(x * y) *(((x * t) * w) * y)  \tag{2}\\
& =t
\end{align*}
$$

So, from (3) we get

$$
(0 * w) *(0 * w)=(0 * w) * w
$$

which implies that $0 * w=w$.
Putting $x=z=0$ and $y=w$ in (2) and using the above we get

$$
w * 0=0=w * w
$$

and hence

$$
\begin{equation*}
w=0 \tag{4}
\end{equation*}
$$

Let $x=z$ and $y=0$ in (2). We have

$$
\begin{equation*}
(x * 0) * 0=x . \tag{5}
\end{equation*}
$$

Putting $y=0$ in (2) we get, by (5),

$$
\begin{equation*}
(x * 0) *(x * z)=z . \tag{6}
\end{equation*}
$$

Now multiply (2) on the left by $(x * y) * 0$ to obtain

$$
((x * y) * 0) *\{(x * y) *(((x * z) * 0) * y)\}=((x * y) * 0) * z,
$$

which reduces, by (6), to

$$
\begin{equation*}
((x * z) * 0) * y=((x * y) * 0) * z \tag{7}
\end{equation*}
$$

Finally, putting $x=y=z$ in (2) we get

$$
\begin{equation*}
0 *(0 * x)=x \tag{8}
\end{equation*}
$$

We have obtained enough identities now to recover the group structure. Define

$$
x+y=(x * 0) *(0 * y)
$$

and

$$
-x=(0 * x) * 0 .
$$

We claim that the reduct $\langle A ;+,-, 0\rangle$ is an abelian group.
Compute:

$$
\begin{array}{rlrl}
0+x & =(0 * 0) *(0 * x) & \\
& =0 *(0 * x) & & \text { by (8) } \\
& =x ; & & \\
-x+x & =(((0 * x) * 0) * 0) *(0 * x) & & \text { by }(5) \\
& =(0 * x) *(0 * x) &  \tag{5}\\
& =0 ; & & \\
(x+y)+z & =(((x * 0) *(0 * y)) * 0) *(0 * z) & & \\
& =(((x * 0) *(0 * z)) * 0) *(0 * y) & & \\
& =(x+z)+y . & &
\end{array}
$$

In particular, putting $x=0$, we get $y+z=z+y$. This completes the proof that the reduct $\langle A ;+,-, 0\rangle$ is an abelian group and the algebra $\mathfrak{A}$ satisfies the identity $w=0$.

Let us substitute, in (2), $x=a * 0$ and $z=a * c$. By (6) we have $x * z=c$. Hence (2) becomes

$$
((a * 0) * y) *((c * 0) * y)=a * c
$$

Putting $y=c * 0$ and multiplying both sides by 0 , on the right we obtain using (5)

$$
\begin{equation*}
(a * 0) *(c * 0)=(a * c) * 0 \tag{9}
\end{equation*}
$$

Now define $\alpha: A \rightarrow A$ by $x \alpha=x * 0$.

We have

$$
\begin{align*}
(x+y) \alpha & =(x+y) * 0 \\
& =((x * 0) *(0 * y)) * 0 \\
& =((x * 0) * 0) *((0 * y) * 0)  \tag{9}\\
& =x *((0 * y) * 0) \\
& =x *(0 *(y * 0))  \tag{9}\\
& =x \alpha+y \alpha
\end{align*}
$$

Moreover,

$$
\begin{aligned}
x \alpha^{2} & =(x * 0) * 0 \\
& =x,
\end{aligned}
$$

and thus $\alpha$ is an involutoric endomorphism of the abelian group $\langle A ;+,-, 0\rangle$. Finally

$$
\begin{aligned}
x \alpha-y \alpha & =(x * 0)+(0 *(y \alpha * 0)) \\
& =(x * 0)+(0 * y) \\
& =((x * 0) * 0) *(0 *(0 * y)) \\
& =x * y,
\end{aligned}
$$

and this completes the proof of the lemma.
Now we are ready to state and prove the structure theorem.

Theorem 1. Let $\mathfrak{U}=\langle A ; *\rangle$ be an SD-group. Then there is a binary operation + on $A$ such that $\langle A ;+\rangle$ is an abelian group and $x * y=x \alpha-y \alpha$ for some involutoric endomorphism $\alpha$ of the abelian group $\langle A ;+\rangle$.

Proof. If $\mathfrak{A}=\langle A ; *\rangle$ is an SD-group then it satisfies identity (1) which is a special case of (2) with $w=u * u$. Hence, by Lemma 1, $\mathfrak{A}$ has an abelian group reduct with the desired properties. The additional condition $u * u=0$ is, of course, true in all SD-groups as it belongs to $I \cap J$. This completes the proof of the theorem.
2. One-based theories. Let $L$ (resp. $\boldsymbol{R}$ ) denote the equational class of all left difference groups (resp. right difference groups). So the lattice join $\boldsymbol{L} \vee \boldsymbol{R}$ in the lattice of all equational classes of groupoids is precisely the class of all groupoids satisfying the identities $I \cap J$ and hence $L \vee R$ is the class of all SD-groups. Let $S$ denote the equational class of groupoids satisfying identity (1). Then it is clear that $S \supseteq \boldsymbol{L} \vee \boldsymbol{R}$. Thus to prove that identity (1) is indeed a base for the equational theory of $I \cap J$, it is sufficient to prove
that $\boldsymbol{S} \subseteq \boldsymbol{L} \vee \boldsymbol{R}$. For these and other universal algebraic notions we refer to the relevant sections of [1].

Let $X$ and $X^{\prime}$ be disjoint sets with $\alpha: X \leftrightarrow X^{\prime}$ a bijection between them.

Let $A b\left(X \cup X^{\prime}\right)=\langle F ;+,-, 0\rangle$ be the free abelian group generated by the set $X \cup X^{\prime}$. Now $\alpha$ is a mapping of the set $X \cup X^{\prime}$ into $F$ and by the freeness of $A b\left(X \cup X^{\prime}\right)$ we can extend this to an endomorphism $\alpha$. Moreover, since $x \alpha^{2}=x$ for all $x \in X \cup X^{\prime}$, we have $x \alpha^{2}=x$ for all $x \in F$. For $x, y$ in $F$, define $x * y=x \alpha-y \alpha$. It is clear that the groupoid $\mathfrak{A}=\langle F ; *\rangle$ satisfies identity (1) of Theorem 1 and hence $\mathfrak{A} \in \boldsymbol{S}$.

Lemma 2. The groupoid $\mathfrak{A}=\langle F ; *\rangle$ constructed above is the free $S$-groupoid generated by the set $X$.

Proof. Let $\mathfrak{B}=\langle B ; *\rangle$ be any $S$-groupoid and let $\varphi$ be a mapping from $X$ into $B$. By Theorem 1, $\mathfrak{B}$ has an abelian group reduct $\langle B ;+,-, 0\rangle$ and an involutoric endomorphism $\beta$ of the group structure such that $x * y=x \beta-y \beta$ for all $x, y \in B$. Given an $x^{\prime} \in X^{\prime}$, there is a unique $x \in X$ such that $x \alpha=x^{\prime}$. Define $x^{\prime} \varphi=x \varphi \beta$ and extend the map $\varphi: X \cup X^{\prime} \rightarrow B$ to a homomorphism of the free abelian group $A b\left(X \cup X^{\prime}\right)$ into $\langle B ;+,-, 0\rangle$. We claim that $x \alpha \varphi=x \varphi \beta$ for all $x \in F$ (see Figure 1). Indeed, if $x \in F$, then $x \alpha \varphi=x^{\prime} \varphi=x \varphi \beta$ by


## Figure 1

definition; if $x^{\prime} \in X^{\prime}$ then $x^{\prime} \alpha \varphi=x \alpha \alpha \varphi=x \varphi$ while $x^{\prime} \varphi \beta=x \varphi \beta \beta=x \varphi$ and hence $x \alpha \varphi=x \varphi \beta$ for all $x \in X \cup X^{\prime}$ and hence for all $x \in F$. Now, for $x, y \in F$,

$$
\begin{aligned}
(x * y) \varphi & =(x \alpha-y \alpha) \varphi \\
& =x \alpha \varphi-y \alpha \varphi \\
& =x \varphi \beta-y \varphi \beta \\
& =x \varphi * y \varphi,
\end{aligned}
$$

and hence $\varphi: \mathfrak{A} \rightarrow \mathfrak{B}$ is a homomorphism. This completes the proof that $\mathfrak{A}$ is the free $S$-groupoid with $X$ as its free set of generators.

Lemma 3. $\mathfrak{A}=\langle F ; *\rangle$ of Lemma 2 belongs to the equational class $\boldsymbol{L} \vee \boldsymbol{R}$.

Proof. For $x, y \in F$, define $\langle x, y\rangle \in \Theta$ iff $x \alpha-y \alpha=-x+y$. It is easy to see that $\Theta$ is an equivalence relation on the set $F$. Moreover, if $\langle x, y\rangle \in \Theta$ and $\langle z, t\rangle \in \Theta$, then

$$
\begin{aligned}
-(x * z)+(y * t) & =-(x \alpha-z \alpha)+(y \alpha-t \alpha) \\
& =-(x \alpha-y \alpha)+(z \alpha-t \alpha) \\
& =-(-x+y)+(-z+t) \\
& =(x-z)-(y-t) \\
& =(x \alpha-z \alpha) \alpha-(y \alpha-t \alpha) \alpha \\
& =(x * z) \alpha-(y * t) \alpha
\end{aligned}
$$

and hence $\langle x * z, y * t\rangle \in \Theta$ which shows that $\Theta$ is a congruence relation on $\mathfrak{A}=\langle F ; *\rangle$. Since, by the proof of Lemma $1 x-y$ is a polynomial of $*, \Theta$ is also a group congruence.

Now, for all $x, y \in F$,

$$
\begin{aligned}
(x * y) \alpha-(x-y) \alpha & =(x \alpha-y \alpha) \alpha-(x \alpha-y \alpha) \\
& =(x-y)-(x \alpha-y \alpha) \\
& =(x-y)-(x * y) \\
& =-(x * y)+(x-y)
\end{aligned}
$$

and hence $\langle x * y, x-y\rangle \in \Theta$ for all $x, y$ in $F$. So, in the $S$-groupoid $\mathfrak{Y} / \Theta$, we have $x * y=x-y$, the left difference and hence $\mathfrak{y} / \Theta \in L$. Similarly, the $S$-groupoid $\mathfrak{U} / \Phi \in R$ where

$$
\Phi=\{\langle x, y\rangle \mid x, y \in F, x \alpha-y \alpha=x-y\}
$$

and so their direct product $\mathfrak{X} / \Theta \times \mathfrak{Y} / \Phi \in \boldsymbol{L} \vee \boldsymbol{R}$. Now, for each $x \in F$, let $x \lambda=\langle[x] \Theta,[x] \Phi\rangle$. Thus $\lambda$ is a homomorphism of $\mathfrak{A}$ into $\mathfrak{H} / \Theta \times \mathfrak{Y} / \Phi$. If $x \lambda=y \lambda$ for some $x, y$ in $F$ then $\langle x, y\rangle \in \Theta \cap \Phi$ and this implies that $-x+y=x-y$ or $2 x=2 y$. But since the group structure in $\mathfrak{A}$ is free, we have $x=y$. Thus $\mathfrak{A}$ is isomorphic to subalgebra of the direct product and hence $\mathfrak{A} \in \boldsymbol{L} \vee \boldsymbol{R}$. This completes the proof of the lemma.

Theorem 2. The identity (1) is a base for the equational theory of $I \cap J$.

Proof. As mentioned in the beginning of this section, it is sufficient to prove that $\boldsymbol{S} \subseteq \boldsymbol{L} \vee \boldsymbol{R}$. Now, if $\mathfrak{B}=\langle B ; *\rangle$ is any $\boldsymbol{S}$ groupoid then it is a homomorphic image of some free $S$-groupoid $\mathfrak{A}=\langle F ; *\rangle$ and by Lemma 2 every such $\mathfrak{A}$ belongs to $\boldsymbol{L} \vee \boldsymbol{R}$. Since
equational classes are closed under homomorphic images we get the conclusion that $\boldsymbol{S} \subseteq \boldsymbol{L} \vee \boldsymbol{R}$.
3. Applications. In §2 we have used only identity (1) which is a special case of identity (2) of Lemma 1. In this section we will apply identity (2) to establish that certain familiar theories are onebased.

THEOREM 3. A finitely based equational theory $\Theta$ of symmetric difference groups is one-based.

Proof. Let $\Theta$ be an equational theory of groupoids by defined $I \cap J$ together with a finite set of identities. Recalling that $\Theta$ has the left cancellation property (because of (1) which belongs to $I \cap J$ ), any identity $f=g$ is equivalent to $f * g=0$. Now let $f=0$ and $g=0$ be any two identities in $\Theta$ with disjoint sets of variables. It is clear that, in presence of $I \cap J$, these two identities are equivalent to the single identity $f * g=0$. Thus we can assume that $\Theta$ is defined by $I \cap J$ together with one identity $w=0$. Hence $\Theta$ contains the identity (2) of Lemma 1 . Conversely, the theory defined by the identity (2) with the above $w$ contains, by Lemma 1 , identity (1) and $w=0$. Now, by Theorem 2, identity (1) is a base for $I \cap J$ and hence we have $I \cap J$ together with $w=0$. This completes the proof of the theorem.

Corollary 1 (G. Higman and B. H. Neumann [3]). Any finitely based equational theory of $J$ is one-based.

Proof. $J$ has the identity $x * 0=x$. Conversely, if a groupoid $\mathfrak{A}=\langle A ; *\rangle$ satisfies both (1) and $x * 0=x$ then by property (iii) of Lemma 1, $x \alpha-0 \alpha=x$, that is $x \alpha=x$ for all $x$ and hence $x * y=$ $x-y$, the right difference and hence $\mathfrak{H}$ satisfies all the identities of $J$. Thus $J$ itself is defined by (1) together with $x * 0=0$ and hence any finitely based theory of $J$ is one-based.

Corollary 2. Any finitely based theory which contains a theory of rings with right unit as a reduct is one-based.

Remark. The above result was announced independently in [2] and [4].

Proof. Let $\Theta$ be a finitely based theory of type $\tau$ and let,+ $-, \cdot, 0,1$ be operation symbols in $\Theta$ such that their reduct in $\Theta$ is a theory of rings with right unit i.e. $x 1=x$ is an identity. It is
well-known that such a theory of rings is definitionally equivalent to a theory in which + and - are replaced by a single binary operation * which stands for, say, the right difference. Now let $f=0$ and $g=0$ be two identities in $\Theta$ and let $z$ and $t$ be variables not occurring in $f$ or $g$. It is clear that these two identities imply $f z * g t=0$. Conversely, if $f z * g t=0$, then $f z * g t=f z * f z$ and one left cancellation yields $f z=g t$. Finally the substitution $z=1, t=0$ yields $f=0$ and similarly $g=0$. In other words, modulo $x 1=x$, $x 0=0 x=0$, and the symmetric difference properties of $*$, any finite number of identities in $\Theta$ can be equivalently expressed by a single identity, say $w_{1}=0$. Now define the polynomial $w$ as

$$
\left(w_{1} x * w_{1} y\right) *\left(\left(\left(x_{1}\left(x_{2} * x_{3}\right)\right) *\left(x_{1} x_{2} * x_{1} x_{3}\right)\right) *\left(\left(x_{4} 1 * 0 x_{5}\right) *\left(x_{4} * 0\right)\right)\right),
$$

where $x, y, x_{1}, \cdots, x_{5}$ are variables not occurring in $w_{1}$ and multiplication has precedence over *.

Let $\mathfrak{A}=\langle A ; F\rangle$ be an algebra of type $\tau$ satisfying identity (2) of Lemma 1 with this $w$. Then the reduct $\langle A ; *\rangle$ is an SD-group and $\mathfrak{A}$ satisfies the identity $w=0$.

In the following computation we will often apply the property that $a * b=0$ implies $a=b$ which is true in any SD-group. From $w=0$ we get immediately

$$
\begin{equation*}
\left(w_{1} x\right) *\left(w_{1} y\right)=\left(\left(x_{1}\left(x_{2} * x_{3}\right)\right) *\left(x_{1} x_{2} * x_{1} x_{3}\right)\right) *\left(x_{4} 1 * 0 x_{5}\right) *\left(x_{4} * 0\right) . \tag{10}
\end{equation*}
$$

The substitution $x=y$ in the above yields

$$
\begin{equation*}
\left(x_{1}\left(x_{2} * x_{3}\right)\right) *\left(x_{1} x_{2} * x_{1} x_{3}\right)=\left(x_{4} 1 * 0 x_{5}\right) *\left(x_{4} * 0\right) \tag{11}
\end{equation*}
$$

Now $x_{4}=0, x_{5}=1$ in the above makes the right hand side $0 *(0 * 0)=$ $0 * 0=0$ and hence we obtain the distributive identity

$$
\begin{equation*}
x_{1}\left(x_{2} * x_{3}\right)=x_{1} x_{2} * x_{1} x_{3} \tag{12}
\end{equation*}
$$

Setting $x_{2}=x_{3}$ in the above we get

$$
\begin{equation*}
x_{1} 0=0 \tag{13}
\end{equation*}
$$

Now from (11) and (12) we have

$$
x_{4} 1 * 0 x_{5}=x_{4} * 0
$$

Putting $x_{5}=0$ and using (13) and (15) we obtain

$$
\begin{equation*}
x_{4} 1=x_{4} \tag{14}
\end{equation*}
$$

which, in turn, yields, by the left cancellation property of *,

$$
0 x_{5}=0
$$

and hence $w_{1}=0$ is satisfied in $\mathfrak{A}$. This proves that the theory $\Theta$ is one-based.

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University of Manitoba
Winnipeg R3T 2N2
Canada


[^0]:    ${ }^{1}$ We call a $\operatorname{map} \alpha: A \rightarrow A$ involutoric if $\alpha^{2}$ is the identity map on $A$.

