# THE SPACE OF ANR's OF A CLOSED SURFACE 

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#### Abstract

We study the hyperspace (denoted $2_{h}^{M}$ ) of ANR's of a (polyhedral) closed surface $M$. The topology of $2_{h}^{M}$ is induced by Borsuk's homotopy metric. We show the subpolyhedra of $M$ are dense in $2_{h}^{M}$. We obtain a necessary and sufficient condition for an arc in $2_{h}^{M}$ joining two points. We show that $2_{h}^{M}$ is an ANR ( $\left.\mathscr{M}\right)$. We prove that the subspace of $2_{h}^{M}$ whose members are AR's has the homotopy type of $M$.


O. Introduction. For a finite-dimensional compactum $X$ with metric $\rho$, let $2_{h}^{X}$ denote the space of nonempty compact ANR subsets of $X$. The topology of $2_{h}^{X}$ is induced by the metric $\rho_{h}$ defined by Borsuk [3]. In [1] and [2], Ball and Ford studied several properties of $2_{h}^{X}$, particularly for the case $X=S^{2}$. In this paper we generalize several of their results.

Throughout this paper, $M$ will denote a (polyhedral) closed surface. We show the nonempty polyhedral subcompacta of $M$ are dense in $2_{h}^{M}$. We give a necessary and sufficient condition for the existence of an arc in $2_{h}^{M}$ joining two given members of $2_{h}^{M}$. We show $2_{h}^{K}$ is an absolute neighborhood retract for metrizable spaces (ANR ( $\mathscr{l}$ )) and that the subspace of $2_{h}^{M}$ whose members are the compact AR subsets of $M$ has the homotopy type of $M$.

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1. Preliminaries. Let $\rho$ be a metric for $M$. We use the following notation: If $x \in M$ and $A \subset M$, then

$$
B(x, r)=\{y \in M \mid \rho(x, y)<r\} ;
$$

$\bar{A}$, Int $A$, and $\operatorname{Bd} A$ are the closure, interior, and boundary of $A$ (in $M$ ) respectively.

Euclidean $n$-space is denoted $R^{n}$. The interval $[0,1]$ is denoted I. If $x, y \in R^{n}$ and $t \in R^{1}$, then $x+y$ will indicate the vector sum, and $t \cdot x$ will indicate scalar multiplication of $x$ by $t$.

If $A$ is a polyhedron, we will assume $A$ is compact unless otherwise stated.

A $m a p$ is a continuous function.
We use the following notation and terminology of [1] and [2]:

A $\delta$-set or a $\delta$-arc is a set or arc of diameter less than $\delta$. A $\delta$-map or a $\delta$-embedding is a map or embedding that moves no point by as much as $\delta$. The words "every $\delta$-subset of $A$ contracts to a point in an $\varepsilon$-subset of $A^{\prime \prime}$ are denoted $s(A, \delta, \varepsilon)$.

Where more than one topology is considered on a set, the topology in which a sequence converges will be indicated by an obvious notation. For example, $a_{n} \underset{\rho}{\rightarrow} a_{0}$ indicates that the sequence $\left\{a_{n}\right\}_{n=1}^{\infty}$ converges to $a_{0}$ in the topology of the metric $\rho$.

Let $X$ be a finite-dimensional compactum. Let $\rho$ be a metric for $X$. Let $A$ and $B$ be nonempty compact ANR subsets of $X$. The Hausdorff metric $\rho_{s}$ is given by

$$
\rho_{\mathrm{s}}(A, B)=\max \{\sup \{\rho(a, B) \mid a \in A\}, \sup \{\rho(b, A) \mid b \in B\}\}
$$

The homotopy metric $\rho_{h}$ is characterized in [3] by the following: Let $A$ and $\left\{A_{n}\right\}_{n=1}^{\infty}$ be nonempty compact ANR subsets of a finitedimensional compactum $X$. Then $A_{n} \underset{\rho_{h}}{ } A$ if and only if
(a) $A_{n} \xrightarrow[\rho_{s}]{ } A$, and
(b) given $\varepsilon>0$, there is a $\delta>0$ such that for all $n, s\left(A_{n}, \delta, \varepsilon\right)$.

We denote by $2_{h}^{X}$ the topological space whose members are the nonempty compact ANR subsets of $X$ and whose topology is induced by the metric $\rho_{h}$. It is shown in [3] that $2_{h}^{X}$ is complete and separable, and that $2_{h}^{X}$ is a topological invariant of $X$. We mention here other useful results of Borsuk: If $\rho_{h}(A, B)<\varepsilon$, then there are $\varepsilon$-maps $f: A \rightarrow B$ and $g: B \rightarrow A$. For $C \in 2_{h}^{x}$, let $[C]_{X}$ denote the collection of all members of $2_{h}^{X}$ that have the same homotopy type as $C$. Then $[C]_{X}$ is open in $2_{h}^{X}$. Since these sets partition $2_{h}^{X},[C]_{X}$ is also closed.

The terms homotopy, deformation retraction, isotopy, etc. will be used in standard fashion, except that it will be convenient not to insist that the interval be $I$. For example, if $c<d$, a deformation retraction of $A$ onto $B$ is a map $H: A \times[c, d] \rightarrow A$ such that $H_{c}=\mathrm{Id}_{A}$ and $H_{d}$ is a retraction of $A$ onto $B$. (We use the notation $H_{t}(\alpha)=$ $H(a, t)$ for all $(a, t) \in A \times[c, d]$.) It will occasionally be convenient to refer to the map $H_{d}$ as a deformation retraction. A map $H: A \times$ $[c, d] \rightarrow A$ is strongly contracting if $c \leqq u \leqq v \leqq d$ implies $H_{u} \circ H_{v}(A) \subset$ $H_{v}(A) \subset H_{u}(A)([1]$, p. 37).

The term surface will be used to refer to a (second countable) connected 2-manifold, with or without boundary. A closed surface is a compact surface without boundary. A bounded surface is a compact surface with boundary. We differ from [1] and [2] in that we will call an annulus any space homeomorphic to $\left\{(x, y) \in R^{2} \mid 1 \leqq\right.$ $\left.x^{2}+y^{2} \leqq 2\right\}$.

The following gives a useful criterion for convergence in $2_{h}^{X}$ :

Lemma 1.1 ([1], 3.4, p. 38). Let $A$ and $B$ be members of $2_{h}^{X}$ ( $X$ an arbitrary finite-dimensional compactum). Let $h: A \times I \rightarrow A$ be a strong deformation retraction of $A$ onto $B$. Let $\left\{t_{n}\right\}_{n=1}^{\infty}$ be an increasing sequence in $I$ converging to 1 . Suppose that for each $n, A_{n}=h_{t_{n}}(A)$ is an ANR. If
(a) $h$ is strongly contracting, or
(b) for all $n, h \mid A_{n} \times\left[t_{n}, t_{n+1}\right]$ is a strong deformation retraction of $A_{n}$ onto $A_{n+1}$, then $A_{n} \xrightarrow[\rho_{h}]{\rightarrow} B$.

Remarks. Case (b) above is not proved in [1], but the proof is identical to that of (a). We will use both cases.

The next two lemmas will be used in questions of arcs.
Lemma 1.2 ([1], 4.1, p. 43). If $A_{n} \overrightarrow{\rho_{h}} A$ in $2_{h}^{X}$ and if for each $n$ there is an $\varepsilon_{n}$-embedding $g_{n}: A_{n} \rightarrow X$ of $A_{n}$ into $X$, where $\varepsilon_{n} \rightarrow 0$, then $g_{n}\left(A_{n}\right) \xrightarrow[\rho_{h}]{ } A$.

Lemma 1.3 ([1], 4.2 and 4.3, p. 43). If $A \in 2_{h}^{X}$ and $f: A \times I \rightarrow X$ is an isotopy, then $\left\{f_{t}(A) \mid t \in I\right\}$ contains an arc in $2_{h}^{X}$ from $A$ to $f_{1}(A)$.

The next two results will be used several times:
Theorem 1.4 ([11], 3.4, pp. 382-383). Let $N$ be a compact surface with $m$ boundary curves. Let $L$ be a closed surface containing disjoint open disks $D_{1}, \cdots, D_{m}$ such that $N=L \backslash \bigcup_{j=1}^{m} D_{j}$. Let $r: N \rightarrow N$ be a deformation retraction of $N$, and let $R=r(N)$. Then $L \backslash R$ is a union of $m$ simply-connected components $G_{1}, \cdots, G_{m}$, with $D_{j} \subset G_{j}$ for $j=1, \cdots, m$.

An immediate consequence of the above is:
Corollary 1.5. Let $N$ be a bounded surface. Let $R \subset \operatorname{Int} N$ be a bounded surface that is a deformation retract of $N$. Then each component of $\overline{N \backslash R}$ is an annulus.

In the following theorems of Epstein, $N$ will denote a surface, with or without boundary, compact or not.

Theorem 1.6 ([8], 1.7, p. 85). If a simple closed curve $S \subset N$ contracts to a point in $N$ then $S$ bounds a disk in $N$.

Theorem 1.7 ([8], A2, p. 106) (stated in a different form). Sup-
pose $N$ is a polyhedral surface and $f: I \rightarrow N$ is an embedding with $f^{-1}(\operatorname{Bd} N)=\{0,1\}$. Let $U$ be a neighborhood of $f(I)$ in $N$. Then there is an ambient isotopy of $N$ that is fixed on $\operatorname{Bd} N$ and outside $U$ and that changes $f$ to a piecewise linear embedding.

The following lemmas will be used in the next section.
Lemma 1.8. Let $Y$ be a topological space, $L \subset Y$, and let $\beta$ be an arc with endpoints $u$ and $v$ such that $\beta \subset L$. Suppose there is an open set $D$ in $Y \backslash\{u, v\}$ and an arc $\bar{\gamma} \subset L$ with endpoints $a$ and $b$ such that $\{a, b\} \subset \operatorname{Bd} D$ and $\gamma=\bar{\gamma} \backslash\{a, b\}$ is a component of $L \cap D$. Then either $\gamma \cap \beta=\phi$ or $\bar{\gamma} \subset \beta$.

Proof. Let $p:(I, 0,1) \rightarrow(\beta, u, v)$ be a homeomorphism. (The notation means that $p$ is a map from $I$ to $\beta$ such that $p(0)=u$ and $p(1)=v$.) Suppose $\gamma \cap \beta \neq \phi$. There is an $x \in \gamma$ and a $t_{0} \in(0,1)$ such that $p\left(t_{0}\right)=x$. Then $A=p^{-1}(\beta \cap D)$ is a nonempty open set in $I$ contained in ( 0,1 ). Thus $t_{0}$ lies in a component $\left(a_{0}, b_{0}\right)$ of $A$. We have $x \in p\left(\left(a_{0}, b_{0}\right)\right) \subset \beta \cap D \subset L \cap D$, so $p\left(\left(a_{0}, b_{0}\right)\right)$ is a connected subset of $L \cap D$ containing $x$. Thus $p\left(\left(a_{0}, b_{0}\right)\right) \subset \gamma$ and $\left\{p\left(a_{0}\right), p\left(b_{0}\right)\right\} \cap D=\phi$, so $\left\{p\left(a_{0}\right), p\left(b_{0}\right)\right\} \subset \operatorname{Bd} D$. The arc $B=p\left(\left[a_{0}, b_{0}\right]\right)$ has its interior in $\gamma$, but the endpoints of $B$ are not in $\gamma$. Therefore $\bar{\gamma}=B \subset p(I)=\beta$.

The following is an immediate consequence of ([7], 4.2, p. 360):
Lemma 1.9. If $A$ is an annulus with boundary curves $T_{1}$ and $T_{2}$, let $H: T_{2} \times I \rightarrow A$ be a map such that $H_{0}=\operatorname{Id}_{T_{2}}$ and $H_{1}\left(T_{2}\right)=T_{1}$. Then $H\left(T_{2} \times I\right)=A$.

We say $Y$ dominates $X$ if there are maps $f: X \rightarrow Y$ and $g: Y \rightarrow X$ such that $g \circ f$ is homotopic to $\mathrm{Id}_{X}$. We write $\Delta X=\min \{\operatorname{dim} Y / Y$ is a finite simplicial complex that dominates $X$ \}.
2. The role of the polyhedra. In [3], Borsuk asked the following questions: If $X$ is a polyhedron, is the collection of all nonempty subpolyhedra of $X$ dense in $2_{h}^{X}$ ? What is the category (in the sense of Baire) of the collection of all nonempty subpolyhedra of $X$ in $2_{h}^{X}$ ? In [1], the first question was answered affirmatively for the case $X=S^{2}$, and the second question was given the following answer: If $X$ is a connected polyhedron with no 1-dimensional open subset, the collection of all nonempty polyhedra properly contained in $X$ is a first category subset of $2_{h}^{x}$. It was also shown in [1] that the collection of nonempty topological polyhedra (i.e., homeomorphic images of polyhedra) properly contained in $S^{2}$ is a dense $G_{\delta}$, hence
second category, subset of $2_{h}^{S^{2}}$. We will extend the above to closed surfaces.

Lemma 2.1. If $X$ is a finite-dimensional compactum and $U$ is open in $X$, then $\mathscr{G}=\left\{C \in 2_{h}^{X} \mid C \subset U\right\}$ is open in $2_{h}^{X}$.

Proof. Let $\left\{A_{n}\right\}_{n=1}^{\infty} \subset 2_{h}^{X} \backslash \mathscr{Z}$. Assume $A_{n} \underset{\rho_{h}}{ } A_{0}$. For each $n$ there exists $x_{n} \in A_{n} \backslash U$. Since $X$ is compact we may assume (by taking a subsequence if necessary) that $x_{n} \rightarrow x_{0} \in X \backslash U$. Since $A_{n} \rightarrow A_{0}$, we have $x_{0} \in A_{0}$. Therefore $A_{0} \notin \mathscr{U}$, so $\mathscr{U}$ is open.

We prove a theorem about the Baire category of the collection of topological polyhedra in $M$ as a subset of $2_{h}^{K}$. (Recall $M$ is a (polyhedral) closed surface.)

Theorem 2.2. Let $\mathscr{T}$ be the collection of nonempty topological polyhedra properly contained in $M$. Then $\mathscr{T}$ is a second category subset of $2_{h}^{M}$.

Proof. Let $D$ be a disk contained in $M$. By 2.1, $\mathscr{C}=$ $\left\{Y \in 2_{h}^{M} \mid Y \subset \operatorname{Int} D\right\}$ is open in $2_{h}^{M}$, and thus is topologically complete. Let $f$ : Int $D \rightarrow S^{2}$ be an embedding. Then the map $f_{*}: \mathscr{Z} \rightarrow 2_{h}^{S^{2}}$ given by $f_{*}(Y)=f(Y)$ is an open embedding ([3], p. 198). Since the collection of nonempty topological polyhedra contained in $S^{2}$ is a dense $G_{\dot{o}}$ subset of $2_{h}^{S^{2}}$ ([1], 3.12, p. 42), it follows that $\mathscr{C} \backslash \mathscr{T}$ is a first category subset of $\mathscr{U}$. The classical Baire category theorem implies $\mathscr{C} \cap \mathscr{T}$ is a second category subset of $\mathscr{C}$, and thus of $2_{h}^{M}$. Hence $\mathscr{T}$ is a second category subset of $2_{h}^{M}$.

The rest of this section is devoted to proving the following:
Theorem 2.3. The collection of nonempty subpolyhedra of $M$ is dense in $2_{h}^{M}$.

To prove 2.3, we show in 2.4 that for a given $C \in 2_{h}^{M}$ we can split $M$ into two pieces that join along simple closed curves such that the intersection of $C$ with each piece is an ANR. Each of the pieces of $M$ embeds in $S^{2}$. In 2.5, we use the fact that the result is known for $S^{2}$ to construct a sequence of polyhedra whose intersection is $C$ satisfying the hypotheses of 1.1.

Lemma 2.4. Let $q$ be a positive integer. Assume $M$ is orientable with genus $q$ or nonorientable with genus $2 q$. Let $C \in 2_{h}^{M}$. Then there are compact subsurfaces $X_{1}$ and $X_{2}$ of $M$ and simple closed curves $\alpha_{1}, \cdots, \alpha_{q+1}$ in $M$ such that:
(a) $M=X_{1} \cup X_{2}$.
(b) The $\alpha_{n}$ are pairwise disjoint.
(c) $\mathrm{Bd} X_{1}=\operatorname{Bd} X_{2}=X_{1} \cap X_{2}=\bigcup_{n=1}^{q+1} \alpha_{n}$.
(d) $X_{1}$ and $X_{2}$ both are homeomorphic to a sphere with $q+1$ disjoint open disks removed.
(e) $\bigcup_{n=1}^{q+1} \alpha_{n} \backslash C$ has finitely many components.

Proof. It is an easy consequence of the standard way to represent a surface that there are subsurfaces $X_{1}^{\prime}$ and $X_{2}^{\prime}$ of $M$ and simple closed curves $\alpha_{1}^{\prime}, \cdots, \alpha_{q+1}^{\prime}$ in $M$ satisfying (a) through (d). It follows that for each $n$ there is a two-sided collar $N_{n}$ of $\alpha_{n}^{\prime}$ in $M$ such that the $N_{n}$ are pairwise disjoint. For any $n$ such that $\alpha_{n}^{\prime} \backslash C$ has finitely many components, set $\alpha_{n}=\alpha_{n}^{\prime}$. Thus we suppose $\alpha^{\prime}$ is any of the $\alpha_{n}^{\prime}$ such that $\alpha_{n}^{\prime} \backslash C$ has infinitely many components. We write $N=N_{n}$. Clearly we may write $\alpha^{\prime} \backslash C=\bigcup_{m=1}^{\infty} \gamma_{m}$, where the $\gamma_{m}$ are distinct components of $\alpha^{\prime} \backslash C$ and each $\bar{\gamma}_{m}$ is an arc whose endpoints $a_{m}$ and $b_{m}$ lie in $C$.

Let $Z=\lim \sup \left\{\bar{\gamma}_{m}\right\}_{m=1}^{\infty}$, i.e., $Z$ is the set of all $x \in \alpha^{\prime}$ such that every neighborhood of $x$ meets infinitely many $\bar{\gamma}_{m}$. Then $Z$ is closed (see [13], p. 10). Thus $Z$ is a compact subset of $\alpha^{\prime}$. It is easily seen that $Z \subset C$.

Let $w_{0}, w_{1}$, and $w_{2}$ be distinct points of $\gamma_{1}$ such that $w_{0}$ lies in the arc $\overline{w_{1} w_{2}}$ of $\gamma_{1}$ from $w_{1}$ to $w_{2}$. Let $f_{0}:(I, 0,1) \rightarrow\left(\alpha^{\prime} \backslash\left(\overline{w_{1} w_{2}} \backslash\left\{w_{1}, w_{2}\right\}\right)\right.$, $w_{1}, w_{2}$ ) be a homeomorphism. Since $N$ is an annulus,
(1) there is a disk $B \subset N$ such that $N \backslash B$ is homeomorphic to $I \times(0,1), w_{0} \in(N \backslash B) \cap \alpha^{\prime} \subset \overline{N \backslash B} \cap \alpha^{\prime} \subset \gamma_{1}$, and $Z \cup f_{0}(I) \subset$ Int $B$. Since ANR's are locally arcwise connected, (1) implies that for each $z \in Z$ there is a neighborhood $U$ of $z$ contained in $\operatorname{Int} B$ such that $U \cap C$ is arcwise connected. Since $Z$ is compact,
(2) there are open sets $U_{1}, \cdots, U_{p}$ such that $Z \subset \bigcup_{k=1}^{p} U_{k} \subset \operatorname{Int} B$ and each $U_{k} \cap C$ is arcwise connected.

It is easily seen that for almost all $m$ there is a $k$ such that $\bar{\gamma}_{m} \subset U_{k}$. We assume $\bar{\gamma}_{1}, \cdots, \bar{\gamma}_{m_{0}}$ are those $\bar{\gamma}_{m}$ that fail to lie in any $U_{k}$. Define $\Gamma_{0}=\phi$, and for $k \in\{0,1, \cdots, p-1\}$ define

$$
\Gamma_{k+1}=\left\{\bar{\gamma}_{m} \subset U_{k+1} \mid \bar{\gamma}_{m} \notin \bigcup_{j=0}^{k} \Gamma_{j}\right\}
$$

Define $\Gamma_{p+1}=\left\{\bar{\gamma}_{1}, \cdots, \bar{\gamma}_{m_{0}}\right\}$. For each $j$ let $\Gamma_{j}^{\prime}=\left\{\gamma_{m} \mid \bar{\gamma}_{m} \in \Gamma_{j}\right\}$. Clearly $\Gamma_{0}, \Gamma_{1}, \cdots, \Gamma_{p+1}$ partition $\left\{\bar{\gamma}_{m}\right\}_{m=1}^{\infty}$. Let the endpoints $a_{m}$ and $b_{m}$ of $\bar{\gamma}_{m}$ satisfy $f_{0}^{-1}\left(a_{m}\right)<f_{0}^{-1}\left(b_{m}\right)$. For $m>1, \bar{\gamma}_{m}=f_{0}\left(\left[f_{0}^{-1}\left(a_{m}\right), f_{0}^{-1}\left(b_{m}\right)\right]\right)$.

We begin an induction argument by observing that for $k=0$ we have a $\operatorname{map} f_{k}:(I, 0,1) \rightarrow\left(\operatorname{Int} B, w_{1}, w_{2}\right)$ such that:
(3) If $t \in I$ and $f_{k}(t) \notin C$ then $f_{k}(t)=f_{0}(t)$.
(4) $f_{k}(I) \backslash C$ is a union of members of $\bigcup_{j=k+1}^{p+1} \Gamma_{j}^{\prime}$.

Suppose for some $k<p, f_{k}:(I, 0,1) \rightarrow\left(\operatorname{Int} B, w_{1}, w_{2}\right)$ is a map satisfying (3) and (4). If $f_{k}(I) \backslash C$ meets no member of $\Gamma_{k+1}^{\prime}$ we define $f_{k+1}=f_{k}$; then (3) and (4) are satisfied when $k$ is replaced by $k+1$. Otherwise we define $c_{k}=\inf \left\{t \in I \mid f_{k}(t)\right.$ belongs to a member of $\left.\Gamma_{k+1}^{\prime}\right\}$, and $d_{k}=\sup \left\{t \in I \mid f_{k}(t)\right.$ belongs to a member of $\left.\Gamma_{k+1}^{\prime}\right\}$. By (4) and our choice of $\left\{w_{1}, w_{2}\right\}, 0<c_{k}<d_{k}<1$. By (3) and (4), each of $f_{k}\left(c_{k}\right)=$ $f_{0}\left(c_{k}\right)$ and $f_{k}\left(d_{k}\right)=f_{0}\left(d_{k}\right)$ must be an endpoint of some $\bar{\gamma}_{m} \in \Gamma_{k+1}$ or a member of $Z$. It follows that $\left\{f_{k}\left(c_{k}\right), f_{k}\left(d_{k}\right)\right\} \subset \overline{U_{k+1}} \cap C$.

If $\left\{f_{k}\left(c_{k}\right), f_{k}\left(d_{k}\right)\right\} \subset U_{k+1}$ then (2) implies there is an arc $\gamma_{k}^{\prime}$ in $U_{k+1} \cap C$ from $f_{k}\left(c_{k}\right)$ to $f_{k}\left(d_{k}\right)$.

If, say, $f_{k}\left(c_{k}\right) \notin U_{k+1}$ then there must be infinitely many members of $\Gamma_{k+1}^{\prime}$ that meet $f_{k}(I)$, for otherwise (4) implies $f_{k}\left(c_{k}\right)$ is an endpoint $a_{m}$ of some $\bar{\gamma}_{m} \in \Gamma_{k+1}$ and thus $f_{k}\left(c_{k}\right) \in U_{k+1}$, contrary to assumption. Thus $f_{k}\left(c_{k}\right) \in Z \cap U_{k_{1}}$ for some $k_{1}$. There is a sequence $\left\{a_{m_{r}}\right\}$ of endpoints of members $\overline{\gamma_{m_{r}}}$ of $\Gamma_{k+1}$ such that $f_{k} \circ f_{0}^{-1} \overline{\left(\gamma_{m_{r}}\right)} \not \subset C$ and $a_{m_{r}} \rightarrow f_{k}\left(c_{k}\right)$. Hence there is an $r$ such that $a_{m_{r}} \in U_{k_{1}}$. By (2) there are $\operatorname{arcs} \gamma^{\prime}$ in $U_{k_{1}} \cap C$ from $f_{k}\left(c_{k}\right)$ to $a_{m_{r}}$ and $\gamma^{\prime \prime}$ in $U_{k+1} \cap C$ from $a_{m_{r}}$ to $f_{k}\left(d_{k}\right)$. There is an arc $\gamma_{k}^{\prime} \subset \gamma^{\prime} \cup \gamma^{\prime \prime} \subset C \cap \operatorname{Int} B$ from $f_{k}\left(c_{k}\right)$ to $f_{k}\left(d_{k}\right)$.

The other cases are treated as above. So in any case, $C \cap \operatorname{Int} B$ contains an are $\gamma_{k}^{\prime}$ from $f_{k}\left(c_{k}\right)$ to $f_{k}\left(d_{k}\right)$. Let $f_{k+1}:(I, 0,1) \rightarrow\left(\operatorname{Int} B, w_{1}, w_{2}\right)$ be determined by: $f_{k+1}\left[\left[c_{k}, d_{k}\right]\right.$ is a homeomorphism of ( $\left.\left[c_{k}, d_{k}\right], c_{k}, d_{k}\right)$ onto $\left(\gamma_{k}^{\prime}, f_{k}\left(c_{k}\right), f_{k}\left(d_{k}\right)\right)$; and $f_{k+1}(t)=f_{k}(t)$ for $t \in I \backslash\left[c_{k}, d_{k}\right]$. Clearly $f_{k+1}$ is continuous. The construction shows (3) and (4) are satisfied when $k$ is replaced by $k+1$.

With the induction completed, we have by (4) a map $f_{p}:(I, 0,1) \rightarrow$ (Int $B, w_{1}, w_{2}$ ) such that $f_{p}(I) \backslash C$ is a union of members of the finite set $\Gamma_{p+1}^{\prime}$. Now $f_{p}(I)$ contains an arc $\beta$ from $w_{1}$ to $w_{2}$. Let $\gamma_{m}$ be a component of $f_{p}(I) \backslash C$. Apply 1.8 , with $Y=M, L=f_{p}(I), D=$ $M \backslash\left(C \cup\left\{w_{1}, w_{2}\right\}\right), \bar{\gamma}=\bar{\gamma}_{m}: \quad$ We have $\bar{\gamma}_{m} \subset \beta$ or $\gamma_{m} \cap \beta=\phi$. Therefore $\beta \backslash C$ has finitely many components, and $\alpha=\beta \cup \overline{w_{1} w_{2}}$ is a simple closed curve such that $\alpha \backslash C$ has finitely many components.

Let $h:$ Int $B \rightarrow R^{2}$ be a homeomorphism. Let $h^{\prime}:(I, 0,1) \rightarrow\left(\beta, w_{1}, w_{2}\right)$ be a homeomorphism. Let $g:([-1,1], 0,\{-1,1\}) \rightarrow\left(\alpha^{\prime}, w_{1},\left\{w_{2}\right\}\right)$ be a relative homeomorphism such that $g(I) \subset \operatorname{Int} B$. Define $H: \alpha^{\prime} \times I \rightarrow$ Int $N$ by

$$
H(g(s), t)=\left\{\begin{array}{l}
g(s) \text { if }-1 \leqq s \leqq 0 \\
h^{-1}\left[(1-t) \cdot h \circ g(s)+t \cdot h \circ h^{\prime}(s)\right] \quad \text { if } \quad 0 \leqq s \leqq 1
\end{array}\right.
$$

Clearly $H$ is well-defined and continuous, $H_{0}=\operatorname{Id}_{\alpha^{\prime}}$, and $H_{1}$ is a homeomorphism of $\alpha^{\prime}$ onto $\alpha$. It follows from ([7], 2.1, p. 87) that there is a homeomorphism $T: N \rightarrow N$ such that $T\left(\alpha^{\prime}\right)=\alpha$ and $T(x)=x$ for all $x \in \operatorname{Bd} N$.

By applying this construction to each of the curves $\alpha_{n}^{\prime}$, we easily obtain a homeomorphism $P: M \rightarrow M$ taking $X_{1}^{\prime}, X_{2}^{\prime}, \alpha_{1}^{\prime}, \cdots, \alpha_{q+1}^{\prime}$ onto sets satisfying (a) through (e).

Theorem 2.3 follows from 1.1 and the following:

Theorem 2.5. Let $C \in 2_{h}^{M}$ be a proper subset of $M$. Then there is a sequence $\left\{A_{n}\right\}_{n=1}^{\infty}$ in $2_{h}^{M}$ such that for all $n$ :
(a) Each component of $A_{n}$ is a polyhedral bounded surface.
(b) $C \subset A_{n+1} \subset \operatorname{Int} A_{n}$.

Also there is a sequence $0=t_{1}<t_{2}<t_{3}<\cdots$ with $\lim t_{n}=1$ and a map $h: A_{1} \times I \rightarrow A_{1}$ such that:
(c) $h$ is a strong deformation retraction of $A_{1}$ onto $C$.
(d) For each $n, h \mid A_{n} \times\left[t_{n}, t_{n+1}\right]$ is a strong deformation retraction of $A_{n}$ onto $A_{n+1}$.

Proof. We remark that the proof is long, so some of the technical details have been omitted. A more complete proof is in [5].

It is easy to see that there is no loss of generality in assuming $C$ is connected. By sewing a Moebius band onto the boundary of a disk cut out of $M \backslash C$ if necessary, we can also assume that $M$ is nonorientable of even genus, or orientable. In view of ([1], 3.2, 3.3, and 3.5 , pp. 36-39) we assume $M \neq S^{2}$.

For a given connected $C \in 2_{h}^{M}$ with $C \neq M$, let $\alpha_{1}, \cdots, \alpha_{q+1}$, $N_{1}, \cdots, N_{q+1}, X_{1}, X_{2}$ be as in 2.4 and its proof. It follows from 2.4(e) and ([4], 2.12, p. 102) that $\hat{X}_{1}=X_{1} \cap C$ and $\hat{X}_{2}=X_{2} \cap C$ are ANR's. We may assume $\hat{X}_{1} \neq \phi$. For $k=1,2, X_{k} \cup \bigcup_{j=1}^{q+1} N_{j}$ is homeomorphic to $X_{k}$, which is embeddable in $S^{2}$. If $\hat{X}_{2} \subset \operatorname{Int}\left(\bigcup_{j=1}^{q+1} N_{j}\right)$ then $C \subset$ Int ( $X_{1} \cup \bigcup_{j=1}^{q+1} N_{j}$ ), in which case we are done, by [1]. Thus we assume
(1) $\hat{X}_{2} \not \subset \operatorname{Int}\left(\bigcup_{j=1}^{q+1} N_{j}\right)$.

Let $\Gamma$ be the set of components $\gamma$ of $\bigcup_{j=1}^{q+1} \alpha_{j} \backslash C$ such that $\gamma \subset \alpha_{j}$ implies $\gamma \neq \alpha_{j}$. From 2.4(e), $\Gamma$ is a finite set. We argue by induction on the number of members of $\Gamma$.

If $\Gamma=\phi$ then for each $j \in\{1,2, \cdots, q+1\}$ either $\alpha_{j} \subset C$ or $\alpha_{j} \subset$ $M \backslash C$. Since $C$ is connected and $\hat{X}_{1} \neq \phi$, if no $\alpha_{j}$ lies in $C$ we have $C=\hat{X}_{1}$, contrary to (1). We assume
(2) $\bigcup_{j=1}^{p} \alpha_{j} \subset C$ for some $p$ with $1 \leqq p \leqq q+1$, and if $p<q+1$ then $\bigcup_{j=p+1}^{q+1} \alpha_{j} \subset M \backslash C$.

Neither $\hat{X}_{1}$ nor $\hat{X}_{2}$ need be connected; nevertheless, the theorems of [1] cited above (and their proofs) imply there are sequences $\left\{B_{n}^{k}\right\}_{n=1}^{\infty}(k=1,2)$ such that for all $n$ :
(3) Each component of $B_{n}^{k}$ is a polyhedral surface.
(4) $\hat{X}_{k} \subset B_{n+1}^{k} \subset \operatorname{Int} B_{n}^{k} \subset B_{n}^{k} \subset \operatorname{Int}\left(X_{k} \cup \bigcup_{j=1}^{q+1} N_{j}\right)$. Also there are
maps $h^{k}: B_{1}^{k} \times I \rightarrow B_{1}^{k}$ and a sequence $0=t_{1}<t_{2}<t_{3}<\cdots$ such that $\lim t_{n}=1$,
(5) $h^{k}$ is a strong deformation retraction of $B_{1}^{k}$ onto $\hat{X}_{k}$, and for each $n$ :
(6) $h^{k} \mid B_{n}^{k} \times\left[t_{n}, t_{n+1}\right]$ is a strong deformation retraction of $B_{n}^{k}$ onto $B_{n+1}^{k}$.
(7) $h^{k} \mid\left(\mathrm{Bd} B_{n}^{k}\right) \times\left[t_{n}, t_{n+1}\right]$ is an isotopy of $\mathrm{Bd} B_{n}^{k}$ onto $\mathrm{Bd} B_{n+1}^{k}$.
(8) If $y \in \operatorname{Bd} B_{n}^{k}$ and $x \in h^{k}\left(\{y\} \times\left[t_{n}, t_{n+1}\right]\right)$, then $h^{k}\left(\{x\} \times\left[t_{n}, t_{n+1}\right]\right) \subset$ $h^{k}\left(\{y\} \times\left[t_{n}, t_{n+1}\right]\right)$ and $h^{k}(x, t)=h^{k}(y, t)$ for $t \in\left[t_{n+1}, 1\right]$.
(9) For all $x \in \operatorname{Bd} B_{n}^{k}, h^{k}(\{x\} \times I)$ is an arc and $h^{k}(\{x\} \times[0,1))$ is a (noncompact) polyhedron.
(10) If $D$ is a component of $B_{n}^{k} \backslash \hat{X}_{k}$ and $E$ is a component of Bd $D$ such that $E \subset \hat{X}_{k}$, then there is a boundary curve $\beta$ of $B_{n}^{k}$ such that $\beta \subset D$ and $h_{1}^{k}(\beta)=E$.

From (2) and (4) we may assume for all $n$ and for $k=1,2$,
(11) $\bigcup_{j=1}^{p} \alpha_{j} \subset$ Int $B_{n}^{k}$ and $B_{n}^{k} \cap \bigcup_{j=p+1}^{q+1} \alpha_{j}=\phi$.

For all $n$, let $A_{n}=\left(B_{n}^{1} \cap X_{1}\right) \cup\left(B_{n}^{2} \cap X_{2}\right)$. We define a map $h$ on $A_{1} \times I$ by

$$
h(x, t)=\left\{\begin{array}{lll}
h^{1}(x, t) & \text { if } & x \in B_{1}^{1} \cap X_{1} \\
h^{2}(x, t) & \text { if } & x \in B_{1}^{2} \cap X_{2}
\end{array}\right.
$$

If $x \in\left(B_{1}^{1} \cap X_{1}\right) \cap\left(B_{1}^{2} \cap X_{2}\right)=\bigcup_{j=1}^{p} \alpha_{j}=\hat{X}_{1} \cap \hat{X}_{2}$, then (5) implies $h^{1}(x, t)=$ $x=h^{2}(x, t)$ for all $t \in I$. Therefore $h$ is well-defined and continuous. It is easily seen that
(12) if $x \in B_{1}^{k} \cap X_{k}$ then $h(x, t) \in B_{1}^{k} \cap X_{k}$. It follows that $h\left(A_{1} \times I\right)=A_{1}$.

By (11), if $\beta$ is a boundary curve of $B_{n}^{k}$ then $\beta \subset \operatorname{Int} X_{1}$ or $\beta \subset$ Int $X_{2}$. The union of those boundary curves of $B_{n}^{k}$ that lie in Int $X_{k}$ is ( $\left.\operatorname{Bd} A_{n}\right) \cap X_{k}$. It follows that $A_{n}$ is a polyhedral bounded surface.

For all $n, C \subset A_{n+1}=\left(B_{n+1}^{1} \cap X_{1}\right) \cup\left(B_{n+1}^{2} \cap X_{2}\right) \subset\left[\left(\operatorname{Int} B_{n}^{1}\right) \cap X_{1}\right] \cup$ $\left[\left(\operatorname{Int} B_{n}^{2}\right) \cap X_{2}\right]=\operatorname{Int}\left(B_{n}^{1} \cap X_{1}\right) \cup \bigcup_{j=1}^{p} \alpha_{j} \cup \operatorname{Int}\left(B_{n}^{2} \cap X_{2}\right)=\operatorname{Int} A_{n}$.

It is clear that $h_{0}=\operatorname{Id}_{A_{1}}$ and $h_{t} \mid C=\operatorname{Id}_{c}$ for all $t \in I$. Also $h_{1}\left(A_{1}\right)=$ $h_{1}^{1}\left(B_{1}^{1} \cap X_{1}\right) \cup h_{1}^{2}\left(B_{1}^{2} \cap X_{2}\right)=\left(\right.$ by (5) and (12)) $\hat{X}_{1} \cup \hat{X}_{2}=C$. Thus $h$ is a strong deformation retraction of $A_{1}$ onto $C$.

For all $n$, we see by (6) and (12) that $h \mid A_{n} \times\left[t_{n}, t_{n+1}\right]$ is a strong deformation retraction of $A_{n}$ onto $A_{n+1}$.

By (12), analogues of (7) through (9) hold when we replace $\left(\hat{X}_{k},\left\{B_{n}^{k}\right\}_{n=1}^{\infty}, h^{k}\right)$ with ( $\left.C,\left\{A_{n}\right\}_{n=1}^{\infty}, h\right)$.

If $D$ is a component of $A_{n} \backslash C$ then by (11) $D$ is a component of $B_{n}^{k} \backslash \hat{X}_{k}$ for some $k$. Then (10) and the construction imply ( $\left.C,\left\{A_{n}\right\}_{n=1}^{\infty}, h\right)$ satisfies the analogue of (10). This concludes our discussion of the case $\Gamma=\dot{\phi}$.

Suppose the theorem is true whenever $\Gamma$ has less than $r$ members
$(r>0)$. Now let $\Gamma$ have $r$ distinct members, $\gamma_{1}, \cdots, \gamma_{r}$. Topologically $\gamma_{r}$ is an open interval in some $\alpha_{j}$, say $\gamma_{r} \subset \alpha_{1}$. Let $\left\{z_{1}, z_{2}\right\}$ be the endpoints of $\gamma_{r}\left(z_{1}=z_{2}\right.$ if $\left.\bar{\gamma}_{r}=\alpha_{1}\right)$. Let $C^{\prime}=C \cup \bar{\gamma}_{r}$. Clearly $C^{\prime}$ is a connected ANR, and $\Gamma^{\prime}=\left\{\gamma_{1}, \cdots, \gamma_{r-1}\right\}$ is the set of all components $\gamma$ of $\bigcup_{j=1}^{q+1} \alpha_{j} \backslash C^{\prime}$ such that $\gamma \subset \alpha_{j}$ implies $\gamma \neq \alpha_{j}$. The inductive hypothesis gives a sequence $\left\{B_{n}\right\}_{n=1}^{\infty} \subset 2_{h}^{M}$ such that for all $n$ :
(13) $B_{n}$ is a polyhedral bounded surface.
(14) $C^{\prime} \subset B_{n+1} \subset$ Int $B_{n}$.

Also there is a map $\psi: B_{1} \times I \rightarrow B_{1}$ and a sequence $0=t_{1}<t_{2}<t_{3}<\cdots$ such that $\lim t_{n}=1$,
(15) $\psi$ is a strong deformation retraction of $B_{1}$ onto $C^{\prime}$, and for all $n$ :
(16) $\psi / B_{n} \times\left[t_{n}, t_{n+1}\right]$ is a strong deformation retraction of $B_{n}$ onto $B_{n+1}$.
(17) $\psi /\left(\mathrm{Bd} B_{n}\right) \times\left[t_{n}, t_{n+1}\right]$ is an isotopy of $\mathrm{Bd} B_{n}$ onto $\mathrm{Bd} B_{n+1}$.
(18) If $y \in \operatorname{Bd} B_{n}$ and $x \in \psi\left(\{y\} \times\left[t_{n}, t_{n+1}\right]\right)$ then $\psi\left(\{x\} \times\left[t_{n}, t_{n+1}\right]\right) \subset$ $\psi\left(\{y\} \times\left[t_{n}, t_{n+1}\right]\right)$ and $\psi(x, t)=\psi(y, t)$ for $t \in\left[t_{n+1}, 1\right]$.
(19) For all $x \in \operatorname{Bd} B_{n}, \psi(\{x\} \times I)$ is an arc and $\psi(\{x\} \times[0,1))$ is a (noncompact) polyhedron.
(20) If $D$ is a component of $B_{n} \backslash C^{\prime}$ and $E$ is a component of Bd $D$ such that $E \subset C^{\prime}$, then there is a boundary curve $\beta$ of $B_{n}$ such that $\beta \subset D$ and $\psi_{1}(\beta)=E$.

For all $n$ we define $\varepsilon_{n}=\sup \left\{\operatorname{diam} \psi(\{x\} \times I) / x \in B_{n}\right\}$. By compactness, $\varepsilon_{n}$ is finite, and we easily see
(21) $\lim \varepsilon_{n}=0$.

Let $D$ be a component of $B_{1} \backslash C^{\prime}$ such that $\bar{\gamma}_{r}$ lies in a boundary component $E$ of $D$. From (20) there is a boundary curve $\beta$ of $B_{1}$ such that $\beta \subset D$ and $\bar{\gamma}_{r} \subset \psi_{1}(\beta)$. It can be shown that:
(22) $\beta$ contains a continuum $\beta^{\prime}$ such that $\psi_{1}\left(\beta^{\prime}\right)=\bar{\gamma}_{r}$. If $\beta^{\prime}$ is an arc whose endpoints are $e_{1}$ and $e_{2}$ then $\psi_{1}\left(\left\{e_{1}, e_{2}\right\}\right)=\left\{z_{1}, z_{2}\right\}$ and $\psi_{1}\left(\beta^{\prime} \backslash\left\{e_{1}, e_{2}\right\}\right)=\gamma_{r}$.

Further, we show:
(23) If $U$ is an open set contained in $D$ such that $E \cap \operatorname{Bd} U \neq \dot{\phi}$, then $U \cap \psi(\beta \times I) \neq \phi$.
For $U$ meets a component $U_{n}$ of $\bar{B}_{n} \backslash B_{n+1}$ for some $n$. By (14), (16), and 1.5, $U_{n}$ is an annulus. From (16), (17), (18), and 1.9, $U_{n}=$ $\psi\left(\beta \times\left[t_{n}, t_{n+1}\right]\right)$, and (23) follows.

Let $y_{0} \in \gamma_{r}$. By (23) there are continua $P_{k}(k=1,2)$ such that $\beta^{\prime}=P_{k}$ satisfies (22) and $P_{k} \cap\left(\operatorname{Int} X_{k}\right) \cap B\left(y_{0}, \varepsilon_{1}\right) \neq \phi$. It can be shown that $P_{1} \cap P_{2}=\phi . \quad$ By (17), for all $n$,
(24) $\psi\left(P_{1} \times\left\{t_{n}\right\}\right) \cap \psi\left(P_{2} \times\left\{t_{n}\right\}\right)=\phi$.

It can be shown that not both of $P_{1}$ and $P_{2}$ are simple closed curves. Hence we assume $P_{1}$ is an arc. Then $P_{2}$ is an arc or a simple closed curve.

By (22) we may assume the endpoints $a_{1}^{1}$ and $b_{1}^{1}$ of $P_{1}$ satisfy $\dot{\psi}_{1}\left(a_{1}^{1}\right)=z_{1}, \psi_{1}\left(b_{1}^{1}\right)=z_{2}$. If $P_{2}$ is an arc then we may assume its endpoints $a_{1}^{2}$ and $b_{1}^{2}$ satisfy $\psi_{1}\left(a_{1}^{2}\right)=z_{1}, \psi_{1}\left(b_{1}^{2}\right)=z_{2}$. If $P_{2}$ is a simple closed curve then $z_{1}=z_{2}$, and by analogy with the above we choose $a_{1}^{2}=b_{1}^{2} \in P_{2} \cap \psi_{1}^{-1}\left(z_{1}\right)$.

By (19), $\eta^{k}=\psi\left(\left\{a_{1}^{k}\right\} \times I\right)$ and $\xi^{k}=\psi\left(\left\{b_{1}^{k}\right\} \times I\right)$ are arcs. By (17) and (18) we have
(25) $\eta^{1} \backslash\left\{z_{1}\right\}, \eta^{2} \backslash\left\{z_{1}\right\}, \xi^{1} \backslash\left\{z_{2}\right\}$ (and $\xi^{2} \backslash\left\{z_{2}\right\}$ if $\xi^{2} \neq \eta^{2}$ ) are pairwise disjoint.

Let $p_{k} \in P_{k} \cap \psi_{1}^{-1}\left(y_{0}\right), k=1,2$. Let $P_{a}^{1}$ be the arc of $P_{1}$ from $a_{1}^{1}$ to $p_{1}$. Let $P_{b}^{1}$ be the arc of $P_{1}$ from $p_{1}$ to $b_{1}^{1}$. If $a_{1}^{2} \neq b_{1}^{2}$, let $P_{a}^{2}$ and $P_{b}^{2}$ be the arcs of $P_{2}$ from $a_{1}^{2}$ to $p_{2}$ and from $p_{2}$ to $b_{1}^{2}$, respectively. If $a_{1}^{2}=b_{1}^{2}$ then $z_{1}=z_{2}$. Then let $P_{a}^{2}$ be the arc of $p_{2}$ from $a_{1}^{2}$ to $p_{2}$ contained in $P_{2} \cap \psi_{1}^{-1}\left(\psi_{1}\left(P_{a}^{1}\right)\right)$ and let $P_{b}^{2}$ be the other arc of $P_{2}$ from $a_{1}^{2}$ to $p_{2}$.

Clearly $T_{1}=\bigcup_{k=1}^{2}\left[\eta^{k} \cup P_{a}^{k} \cup \psi\left(\left\{p_{k}\right\} \times I\right)\right]$ and $T_{2}=\bigcup_{k=1}^{2}\left[\xi^{k} \cup P_{b}^{k} \cup\right.$ $\left.\psi\left(\left\{p_{k}\right\} \times I\right)\right]$ are simple closed curves that are deformed by $\psi$ into proper subsets of $\alpha_{1}$. By 1.6, $T_{1}$ and $T_{2}$ bound disks $M_{1}$ and $M_{2}$ respectively in $B_{1}$. Clearly $M_{k}=\psi\left(T_{k} \times I\right)$.

There is an arc $\lambda_{1}^{\prime}$ in $M_{1} \cap B\left(z_{1}, \varepsilon_{1}\right)$ from $a_{1}^{1}$ to $a_{1}^{2}$ such that $\left\{a_{1}^{1}, a_{1}^{2}\right\}=$ $\lambda_{1}^{\prime} \cap \operatorname{Bd} M_{1}$. Then $\lambda_{1}^{\prime} \subset B_{1} \cap B\left(z_{1}, \varepsilon_{1}\right)$ and $\lambda_{1}^{\prime} \cap \operatorname{Bd} B_{1}=\left\{a_{1}^{1}, a_{1}^{2}\right\}$. By (19), $M_{1} \backslash\left\{z_{1}, y_{0}\right\}$ is a (noncompact) polyhedron, so by 1.7 there is an ambient isotopy of $M_{1}$ that is fixed on $\left(M_{1} \backslash B\left(z_{1}, \varepsilon_{1}\right)\right) \cup \mathrm{Bd} M_{1}$ and that carries $\lambda_{1}^{\prime}$ onto a polyhedral arc $\lambda_{1}$. Similarly, there is a polyhedral are $\mu_{1}$ in $M_{2} \cap B\left(z_{2}, \varepsilon_{1}\right)$ from $b_{1}^{1}$ to $b_{1}^{2}$ such that $\left\{b_{1}^{1}, b_{1}^{2}\right\}=\mu_{1} \cap \mathrm{Bd} B_{1}$.

For all $n$, let $a_{n}^{k}=\psi\left(a_{1}^{k}, t_{n}\right) \in \operatorname{Bd} B_{n}$, and let $b_{n}^{k}=\psi\left(b_{1}^{k}, t_{n}\right) \in \operatorname{Bd} B_{n}$. Let $\eta_{0}^{k}=\eta^{k}, \xi_{0}^{k}=\xi^{k}, \eta_{n}^{k}=\psi\left(\left\{a_{n}^{k}\right\} \times\left[t_{n+1}, 1\right]\right)$ (the arc of $\eta^{k}$ from $\alpha_{n+1}^{k}$ to $\left.z_{1}\right), \xi_{n}^{k}=\psi\left(\left\{b_{n}^{k}\right\} \times\left[t_{n+1}, 1\right]\right)$ (the arc of $\xi^{k}$ from $b_{n+1}^{k}$ to $\left.z_{2}\right)$. Note that we have begun an induction argument by showing that for $n=1$, the following statements (26) through (29) are valid:
(26) There are polyhedral arcs $\lambda_{n} \subset M_{1} \cap B_{n} \cap B\left(z_{1}, \varepsilon_{n}\right)$ from $a_{n}^{1}$ to $a_{n}^{2}, \mu_{n} \subset M_{2} \cap B_{n} \cap B\left(z_{2}, \varepsilon_{n}\right)$ from $b_{n}^{1}$ to $b_{n}^{2}$ such that:
(27) $\left\{a_{n}^{1}, a_{n}^{2}\right\}=\lambda_{n} \cap \operatorname{Bd} B_{n}=\lambda_{n} \cap \mathrm{Bd} M_{1}$.

$$
\left\{b_{n}^{1}, b_{n}^{2}\right\}=\mu_{n} \cap \mathrm{Bd} B_{n}=\mu_{n} \cap \mathrm{Bd} M_{2} .
$$

(28) $\quad \lambda_{n} \cap\left(\eta_{n}^{1} \cup \eta_{n}^{2}\right)=\phi=\mu_{n} \cap\left(\xi_{n}^{1} \cup \xi_{n}^{2}\right)$.
(For $n=1$, (27) and (28) follow from observing which points are left fixed by the ambient isotopies.)
(29) $\lambda_{n} \cap \lambda_{j}=\phi=\mu_{n} \cap \mu_{j}$ for $j<n$.

Suppose $m>0$ and (26) through (29) are valid for $n=1, \cdots, m$. The inductive step is done as above, with obvious modifications. For example, to obtain $\lambda_{m+1}$ satisfying (26) through (29), we work in the disk bounded not by $T_{1}$, but by the simple closed curve

$$
\overline{u_{m} v_{m}} \cup \overline{u_{m} a_{m+1}^{1}} \cup \eta_{m}^{1} \cup \eta_{m}^{2} \cup \overline{v_{m} a_{m+1}^{2}},
$$

where $\overline{u_{m} v_{m}}$ is the arc of $\lambda_{m}$ whose endpoints $u_{m}$ and $v_{m}$ satisfy $u_{m} \in \psi\left(P_{1} \times\left\{t_{m}\right\}\right), v_{m} \in \psi\left(P_{2} \times\left\{t_{m}\right\}\right), \overline{u_{m} v_{m}} \backslash\left\{u_{m}, v_{m}\right\} \subset \operatorname{Int} B_{m+1} ; \overline{u_{m} a_{m+1}^{1}}$ is the arc of $\psi\left(P_{1} \times\left\{t_{m+1}\right\}\right)$ from $u_{m}$ to $a_{m+1}^{1}$; and $\overline{v_{m} a_{m+1}^{2}}$ is the arc of $M_{1} \cap \psi\left(P_{2} \times\left\{t_{m+1}\right\}\right)$ from $v_{m}$ to $a_{m+1}^{2}$. Thus (26) through (29) hold for all $n$.

Since $\lambda_{n} \subset M_{1}, \mu_{n} \subset M_{2}$, and $\left(\mathrm{Bd} M_{1}\right) \cap\left(\mathrm{Bd} M_{2}\right) \backslash \psi\left(\left\{p_{1}, p_{2}\right\} \times I\right)=$ $\eta^{2} \cap \xi^{2}$, (25) and (27) imply

$$
\lambda_{n} \cap \mu_{j}=\left\{\begin{array}{l}
\phi \text { if } n \neq j, \quad \text { or if } n=j \text { and } \eta^{2} \neq \xi^{2} ;  \tag{30}\\
\left\{a_{n}^{2}=b_{n}^{2}\right\} \text { if } n=j \text { and } \eta^{2}=\xi^{2} .
\end{array}\right.
$$

For $k=1,2$, let $Q_{k}$ be the boundary curve of $B_{1}$ containing $P_{k}$. Let $Q_{k}^{n}=\psi\left(Q_{k} \times\left\{t_{n}\right\}\right), P_{k}^{n}=\psi\left(P_{k} \times\left\{t_{n}\right\}\right)$. Let $E_{n}=\left[\left(Q_{1}^{n} \cup Q_{2}^{n}\right) \backslash\left(P_{1}^{n} \cup P_{2}^{n}\right)\right] \cup$ $\lambda_{n} \cup \mu_{n}$. Clearly $E_{n}$ is a polyhedron, and $E_{n} \cap E_{j}=\phi$ for $n \neq j$. If $Q_{1} \neq Q_{2}$, then (17), (24), (27), and (30) imply $E_{n}$ is a simple closed curve. (Note (30) implies if $\lambda_{n} \cap \mu_{n}=\left\{a_{n}^{2}\right\}$ then $Q_{2}^{n}=P_{2}^{n}$, so $E_{n}=\left(Q_{1}^{n} \backslash P_{1}^{n}\right) \cup \lambda_{n} \cup \mu_{n}$.) Similarly, if $Q_{1}=Q_{2}$ then either $E_{n}$ is a simple closed curve for all $n$ or $E_{n}$ is a disjoint union of two simple closed curves for all $n$.

For all $n$, let $J_{n} \subset M_{1}$ be the disk bounded by $\eta_{n-1}^{1} \cup \eta_{n-1}^{2} \cup \lambda_{n}$ and let $J_{n}^{\prime} \subset M_{2}$ be the disk bounded by $\xi_{n-1}^{1} \cup \xi_{n-1}^{2} \cup \mu_{n}$. Define $A_{n}=$ $\left[B_{n} \backslash\left(M_{1} \cup M_{2}\right)\right] \cup J_{n} \cup J_{n}^{\prime}$. To complete the proof, we must show (13) through (20) are satisfied when ( $\left\{A_{n}\right\}_{n=1}^{\infty}, C$ ) replaces ( $\left\{B_{n}\right\}_{n=1}^{\infty}, C^{\prime}$ ) and an appropriate map $h$ replaces $\psi$.

We have

$$
\operatorname{Bd} A_{n}=E_{n} \cup\left[\left(\operatorname{Bd} B_{n}\right) \backslash\left(Q_{1}^{n} \cup Q_{2}^{n}\right)\right] \quad \text { and } \quad E_{n} \cap\left[\left(\operatorname{Bd} B_{n}\right) \backslash\left(Q_{1}^{n} \cup Q_{2}^{n}\right)\right]=\phi .
$$

Therefore $A_{n}$ is a polyhedral bounded surface. The analogue of (13) is satisfied.

Since $E_{n} \cap E_{j}=\phi$ for $n \neq j,\left(\operatorname{Bd} A_{n}\right) \cap\left(\operatorname{Bd} A_{j}\right)=\phi . \quad$ Clearly $z_{1} \in$ $J_{n+1} \subset J_{n}$ and $z_{2} \in J_{n+1}^{\prime} \subset J_{n}^{\prime}$. It follows that $C \subset A_{n+1} \subset \operatorname{Int} A_{n}$. The analogue of (14) is satisfied.

It is easily seen that there are maps $h^{\prime}: J_{1} \times I \rightarrow J_{1}$ and $h^{\prime \prime}: J_{1}^{\prime} \times$ $I \rightarrow J_{1}^{\prime}$ such that for all $x \in \eta^{1} \cup \eta^{2}, y \in \xi^{1} \cup \xi^{2}, t \in I$,
(31) $h^{\prime}(x, t)=\psi(x, t) ; h^{\prime \prime}(y, t)=\psi(y, t)$; and such that $h^{\prime}$ and $h^{\prime \prime}$ satisfy analogues of (15) through (19):
(15') $h^{\prime}$ is a strong deformation retraction of $J_{1}$ onto $\left\{z_{1}\right\}$, and for all $n$ :
(16') $h^{\prime} \mid J_{n} \times\left[t_{n}, t_{n+1}\right]$ is a strong deformation retraction of $J_{n}$ onto $J_{n+1}$.
(17) $h^{\prime} \mid \lambda_{n} \times\left[t_{n}, t_{n+1}\right]$ is an isotopy of $\lambda_{n}$ onto $\lambda_{n+1}$.
(18') If $x \in h^{\prime}\left(\{y\} \times\left[t_{n}, t_{n+1}\right]\right)$ for $y \in \lambda_{n}$, then $h^{\prime}\left(\{x\} \times\left[t_{n}, t_{n+1}\right]\right) \subset h^{\prime}(\{y\} \times$ $\left.\left[t_{n}, t_{n+1}\right]\right)$ and $h^{\prime}(x, t)=h^{\prime}(y, t)$ for $t \in\left[t_{n+1}, 1\right]$.
(19') For all $x \in \lambda_{n}, h^{\prime}(\{x\} \times I)$ is an arc and $h^{\prime}(\{x\} \times[0,1))$ is a (noncompact) polyhedron.

Similar versions of ( $15^{\prime}$ ) through ( $19^{\prime}$ ) hold upon replacing $\left(h^{\prime},\left\{J_{n}\right\}_{n=1}^{\infty}, z_{1},\left\{\lambda_{n}\right\}_{n=1}^{\infty}\right)$ by $\left(h^{\prime \prime},\left\{J_{n}^{\prime}\right\}_{n=1}^{\infty}, z_{2},\left\{\mu_{n}\right\}_{n=1}^{\infty}\right)$.

Define a map $h$ on $A_{1} \times I$ by

$$
h(x, t)=\left\{\begin{array}{lll}
h^{\prime}(x, t) & \text { if } & x \in J_{1} ; \\
h^{\prime \prime}(x, t) & \text { if } & x \in J_{1}^{\prime} ; \\
\psi(x, t) & \text { otherwise } .
\end{array}\right.
$$

By (31), $h$ is well-defined and continuous. From (17) and (18),
(32) if $x \in B_{n} \backslash\left(M_{1} \cup M_{2}\right)$ then $\psi(\{x\} \times I) \subset B_{n} \backslash\left(M_{1} \cup M_{2} \backslash\left\{z_{1}, z_{2}\right\}\right)$.

By (15), (15'), and (32), $h\left(A_{1} \times I\right)=A_{1}$. Clearly $h(x, t)=x$ for all $(x, t) \in C \times I$, and $h_{1}\left(A_{1}\right)=C$. Thus $h$ satisfies the analogue of (15).

For all $n$ :
By (16), (16'), and (32), $h$ satisfies the analogue of (16).
By (17), (17), and (32), $h$ satisfies the analogue of (17).
By (18) and (18'), $h$ satisfies the analogue of (18).
By (19) and (19'), $h$ satisfies the analogue of (19).
By (20) and our construction of $E_{n}, h$ satisfies the analogue of (20). The proof of Theorem 2.5 is completed.
3. Arcs. Let $X$ be a finite-dimensional compactum and let $\left\{C_{0}, C_{1}\right\} \subset 2_{h}^{X}$. Under what circumstances is there an arc in $2_{h}^{X}$ from $C_{0}$ to $C_{1}$ ? In [1], it was found that a necessary but insufficient condition is that $C_{0}$ and $C_{1}$ have the same homotopy type; and a sufficient but unnecessary condition is that $C_{0}$ and $C_{1}$ be isotopic in $X$. For $X=M$, we obtain a condition that is both necessary and sufficient:

Theorem 3.1. Let $\left\{C_{0}, C_{1}\right\} \subset 2_{n}^{M} \backslash\{M\}$. By 2.5, there exist $A_{j} \in$ $2_{h}^{y}(j=0,1)$ such that each component of $A_{j}$ is a bounded surface, $C_{j} \subset \operatorname{Int} A_{j}$, and $C_{j}$ is a strong deformation retract of $A_{j}$. Then there is an are in $2_{n}^{h}$ from $C_{0}$ to $C_{1}$ if and only if there is an ambient isotopy of $M$ taking $A_{0}$ onto $A_{1}$.

First we prove:
Lemma 3.2. Suppose $C \in 2_{h}^{M} \backslash\{M\}$, and let $\left\{A_{n}\right\}_{n=1}^{\infty},\left\{t_{n}\right\}_{n=1}^{\infty}$, and $h$ be as in 2.5. Then there is an arc $\mathscr{A}$ in $2_{n}^{K}$ from $A_{1}$ to $C$ containing
each $A_{n}$ such that if $A \in \mathscr{A} \backslash\{C\}$, each component of $A$ is a bounded surface.

Proof. Recall the notation in the statement of Theorem 2.5. In the proof of 2.5 , we saw:
(1) $h \mid\left(\operatorname{Bd} A_{n}\right) \times\left[t_{n}, t_{n+1}\right]$ is an isotopy of $\mathrm{Bd} A_{n}$ onto $\mathrm{Bd} A_{n+1}$.

It follows from (16) and (18) of the proof of 2.5 that
(2) if $x \in \operatorname{Bd} A_{n}$ then $h\left(\{x\} \times\left[t_{n}, t_{n+1}\right]\right)=\gamma_{x}$ is an arc such that $\gamma_{x} \backslash\left\{x, h\left(x, t_{n+1}\right)\right\} \subset\left(\operatorname{Int} A_{n}\right) \backslash A_{n+1}$.

If $\varepsilon_{n}=\sup \left\{\operatorname{diam} h(\{x\} \times I) \mid x \in A_{n}\right\}$, then $\lim \varepsilon_{n}=0$, and by 1.1, $A_{n} \rightarrow C$, so it follows that there is a sequence of positive numbers $\delta_{n}$ such that
(3) $\lim \delta_{n}=0$, and for all $n, s\left(A_{n}, 6 \varepsilon_{n}, \delta_{n}\right)$.

Let $P$ be a component of $\overline{A_{n} \backslash A_{n+1} \cdot}$ By $2.5(\mathrm{a}), 2.5(\mathrm{~b}), 2.5(\mathrm{~d})$, and $1.5, P$ is an annulus. Let the boundary curves of $P$ be $\alpha_{n} \subset \operatorname{Bd} A_{n}$ and $\alpha_{n+1} \subset \mathrm{Bd} A_{n+1}$. There is a set $E=\left\{x_{0}, x_{1}, \cdots, x_{k-1}\right\} \subset \alpha_{n}$ of $k$ distinct points numbered according to an orientation of $\alpha_{n}$ (let $x_{k}=x_{0}$ ) such that if $\beta_{j}$ is the arc of $\alpha_{n}$ from $x_{j-1}$ to $x_{j}$ containing no other member of $E$, then $\operatorname{diam} \beta_{j}<\varepsilon_{n}$. For each $j$, let $y_{j}=h\left(x_{j}, t_{n+1}\right)$. By (2), $\gamma_{j}=h\left(\left\{x_{j}\right\} \times\left[t_{n}, t_{n+1}\right]\right)$ is an arc from $x_{j}$ to $y_{j}$ such that $\gamma_{j} \backslash\left\{x_{j}, y_{j}\right\} \subset \operatorname{Int} P$. By (1), the $\gamma_{j}$ are pairwise disjoint for $j \in$ $\{0,1, \cdots, k-1\}\left(\gamma_{k}=\gamma_{0}\right)$ and (also by (1)) $\zeta_{j}=h\left(\beta_{j} \times\left\{t_{n+1}\right\}\right)$ is an arc of $\alpha_{n+1}$ from $y_{j-1}$ to $y_{j}$ not containing $y_{m}$ if $y_{m} \notin\left\{y_{j-1}, y_{j}\right\}$. Clearly $\operatorname{diam} \gamma_{j} \leqq \varepsilon_{n}$.

Let $\left\{y, y^{\prime}\right\} \subset \zeta_{j}$. There exist $x, x^{\prime} \in \beta_{j}$ such that $y=h\left(x, t_{n+1}\right)$ and $y^{\prime}=h\left(x^{\prime}, t_{n+1}\right)$. Then $\rho\left(y, y^{\prime}\right) \leqq \rho(y, x)+\rho\left(x, x^{\prime}\right)+\rho\left(x^{\prime}, y^{\prime}\right) \leqq \varepsilon_{n}+$ $\operatorname{diam} \beta_{j}+\varepsilon_{n}<3 \varepsilon_{n}$. Therefore diam $\zeta_{j}<3 \varepsilon_{n}$.

Let $S_{j}$ be the simple closed curve in $P$ defined by $S_{j}=\gamma_{j-1} \cup$ $\beta_{j} \cup \gamma_{j} \cup \zeta_{j}$. Then diam $S_{j} \leqq \operatorname{diam} \gamma_{j-1}+\operatorname{diam} \beta_{j}+\operatorname{diam} \gamma_{j}+\operatorname{diam} \zeta_{j}<$ $\varepsilon_{n}+\varepsilon_{n}+\varepsilon_{n}+3 \varepsilon_{n}=6 \varepsilon_{n} . \quad$ By (3) and $1.6, S_{j}$ bounds a disk $K_{j} \subset A_{n}$ such that
(4) $\operatorname{diam} K_{j}<\delta_{n}$.

Indeed $K_{j} \subset P$, for if $K_{j}^{\prime}$ is the disk in $P$ bounded by $S_{j}$ and $K_{j}^{\prime} \neq K_{j}$, then $K_{j} \cap K_{j}^{\prime}=S_{j}$ and $K_{j} \cup K_{j}^{\prime}$ is a 2 -sphere in $A_{n}$, which is impossible.

It is easily seen that there is a map $F: P \times I \rightarrow P$ that is a strongly contracting strong deformation retraction and a pseudoisotopy of $P$ to $\alpha_{n+1}$ such that $F\left(K_{j} \times I\right) \subset K_{j}$ for all $j$. From (4) we have
(5) $\quad F_{t}$ is a $\delta_{n}$-embedding for $0 \leqq t<1$.

Apply the above construction to each component of $\overline{A_{n} \backslash A_{n+1}}$. In the above, $F_{t} \mid \alpha_{n+1}=\mathrm{Id}_{\alpha_{n+1}}$ for all $t \in I$, so we may extend each $F_{t}$ via the identity to obtain a map $F^{n}: A_{n} \times I \rightarrow A_{n}$ that is a strongly contracting strong deformation retraction and a pseudoisotopy of
$A_{n}$ onto $A_{n+1}$ moving no point by as much as $\delta_{n}$. Let $a_{n}: I \rightarrow 2_{n}^{n}$ be defined by $a_{n}(t)=F^{n}\left(A_{n} \times\{t\}\right)$. By 1.3, $a_{n}$ is continuous for $0 \leqq t<1$. By 1.1, $a_{n}$ is continuous for $t=1$.

Let $L: I \rightarrow 2_{n}^{\mu}$ be defined by

$$
L(t)= \begin{cases}a_{n}\left[\frac{t-t_{n}}{t_{n+1}-t_{n}}\right] & \text { if } t_{n} \leqq t \leqq t_{n+1} \\ C & \text { if } t=1\end{cases}
$$

Since $a_{n}(1)=A_{n+1}=a_{n+1}(0), L$ is well-defined; and $L$ is continuous for $0 \leqq t<1$. From (3), (5), and 1.2, $L$ is continuous for $t=1$. Since $L(0)=A_{1}$ and $L(1)=C, L(I)$ contains an arc in $2_{h}^{H}$ from $A_{1}$ to $C$. The second conclusion of the lemma follows from the fact that for all $n, F^{n}$ is a pseudoisotopy of $A_{n}$ onto $A_{n+1}$.

We show the existence of a basis with useful properties.
Lemma 3.3. Let $C \in 2_{n}^{H} \backslash\{M\}$ and let $\varepsilon>0$. By 1.1 and 2.5 , there exists $A$ such that $\rho_{h}(A, C)<\varepsilon$, each component of $A$ is a bounded surface, $C \subset \operatorname{Int} A$, and $C$ is a strong deformation retract of $A$. There is a neighborhood $\mathscr{U}$ of $C$ in $2_{h}^{H}$ such that $X \in \mathscr{C}$ implies $\rho_{h}(X, C)<\varepsilon, X \subset \operatorname{Int} A$, and $X$ is a strong deformation retract of A. Further, if each component of $X \in \mathscr{U}$ is a bounded surface, then there is an ambient isotopy of $M$ that carries $A$ onto $X$.

Proof. We may assume $A$ is a polyhedron, and that $\varepsilon$ is so small that two maps $f_{0}, f_{1}: C \rightarrow A$ such that $\rho\left(f_{0}, f_{1}\right)<\varepsilon$ are homotopic in A. Recall $[C]_{\mu}=\left\{X \in 2_{h}^{H} \mid X\right.$ and $C$ have the same homotopy type $\}$ is open. From 2.1 it follows that

$$
\mathscr{U}=[C]_{\mu} \cap\left\{X \in 2_{h}^{H} \mid X \subset \operatorname{Int} A\right\} \cap\left\{X \in 2_{n}^{n} \mid \rho_{h}(X, C)<\varepsilon\right\}
$$

is an open set in $2_{h}^{H}$ containing $C$.
We may assume $C$ and $A$ are connected (otherwise we apply the following by components). Let $X \in \mathscr{K}$. There is an $\varepsilon$-map $g: C \rightarrow X$. Let $i: C \rightarrow A, j: X \rightarrow A$ be inclusion maps. By choice of $\varepsilon, i_{*}=j_{*} \circ g_{*}$ : $\Pi_{1} C \rightarrow \Pi_{1} A$. By choice of $A, i_{*}$ is an isomorphism. Therefore $j_{*}: \Pi_{1} X \rightarrow \Pi_{1} A$ is a surjective homomorphism. But $\{X, A\} \subset[C]_{\mu}$, so $\Pi_{1} X$ and $\Pi_{1} A$ are isomorphic. Since $A$ is a bounded surface, $\Pi_{1} A$ is a finitely generated free group. Therefore $j_{*}$ is an isomorphism (see [10], p. 59).

Recall the definition of $\Delta X$ given in $\S 1$. Since $X$ and $A$ have the same homotopy type, $\Delta X=\Delta A$. But $\Delta A \leqq 1$, since if $A$ is a disk it has the homotopy of a point, while otherwise $A$ has the homotopy type of a wedge of finitely many simple closed curves. With $N=\Delta A \leqq 1$, we apply Whitehead's theorem ([12], 1, p. 1133)
and conclude $j: X \rightarrow A$ is a homotopy equivalence.
By 1.1 and 2.5 there is a polyhedral bounded surface $B \in \mathscr{U}$ such that $X \subset \operatorname{Int} B$ and $X$ is a strong deformation retract of $B$. Applying the above to $B$, we conclude the inclusion of $B$ into $A$ is a homotopy equivalence. Hence $B$ is a strong deformation retract of $A$ (see [6], 3.2, p. 6). Thus $X$ is a strong deformation retract of $A$.

If $X \in \mathscr{U}$ is a bounded surface, then by 1.5 each component of $\overline{A \backslash X}$ is an annulus. Let $S$ be a component of $\operatorname{Bd} A$. Let $A^{\prime}$ be the component of $\overline{A \backslash X}$ containing $S$. Let $S^{\prime}$ be the component of $\operatorname{Bd} A^{\prime}$ that lies in $X$. There are annuli $A_{1}$ and $A_{2}$ that collar $S$ in $\overline{M \backslash A}$ and $S^{\prime \prime}$ in $X$ respectively. Then $A^{\prime \prime}=A_{1} \cup A^{\prime} \cup A_{2}$ is an annulus. There is an isotopy $h: A^{\prime \prime} \times I \rightarrow A^{\prime \prime}$ of $A^{\prime \prime}$ onto itself such that $h_{1}\left(A^{\prime} \cup A_{2}\right)=A_{2}, h_{1}\left(A_{1}\right)=A^{\prime} \cup A_{1}$, and $h(z, t)=z$ for all $(z, t) \in\left(\operatorname{Bd} A^{\prime \prime}\right) \times I$. Apply this construction to each component of $\overline{A \backslash X}$ and extend via the identity on $M \backslash(\overline{A \backslash X})$ to get an ambient isotopy of $M$ that carries $A$ onto $X$.

Proof of Theorem 3.1. Suppose there is an ambient isotopy of $M$ taking $A_{0}$ onto $A_{1}$. By 1.3, there is an arc in $2_{h}^{M}$ from $A_{0}$ to $A_{1}$. By 3.2, there are arcs in $2_{h}^{M}$ from $A_{0}$ to $C_{0}$ and from $A_{1}$ to $C_{1}$. Hence there is an arc in $2_{h}^{M}$ from $C_{0}$ to $C_{1}$.

Conversely, suppose there is an embedding $p: I \rightarrow 2_{h}^{M}$ such that $p(0)=C_{0}$ and $p(1)=C_{1}$. Since $p(I)$ is compact, 3.3 implies that there exist $0 \leqq t_{0}<t_{1}<\cdots<t_{m} \leqq 1 ; A_{t_{n}} \in 2_{h}^{M}$ such that each component of $A_{t_{n}}$ is a bounded surface; and neighborhoods $\mathscr{U}_{n}$ of $p\left(t_{n}\right)$ in $2_{h}^{M}$ such that if $X \in \mathscr{U}_{n}$ and each component of $X$ is a bounded surface then there is an ambient isotopy of $M$ taking $A_{t_{n}}$ onto $X$, and such that $\mathscr{U}_{n} \cap \mathscr{U}_{n+1} \neq \phi$ and $p(I) \subset \bigcup_{n=0}^{m} \mathscr{U}_{n}$. Further, 3.3 enables us to assume that $A_{0}=A_{t_{0}}$ and $A_{1}=A_{t_{m}}$.

By 1.1 and 2.5, for each $n<m$ there exists $B_{n} \in \mathscr{U}_{n} \cap \mathscr{U}_{n+1}$ such that each component of $B_{n}$ is a bounded surface. There are ambient isotopies of $M$ taking $A_{t_{n}}$ and $A_{t_{n+1}}$ onto $B_{n}$. Therefore there is an ambient isotopy of $M$ taking $A_{t_{n}}$ onto $A_{t_{n+1}}$. Hence there is an ambient isotopy of $M$ taking $A_{0}=A_{t_{0}}$ onto $A_{t_{m}}=A_{1}$.
4. Global properties. The spaces $D(N)$ and $L(N)$ of deformation retracts (respectively, compact AR subsets) of a compact 2 -manifold $N$ were studied by Wagner in [11]. The topologies of these spaces may be described thus: $A_{n} \xrightarrow[D(N)]{\longrightarrow} C\left(A_{n} \xrightarrow[L(N)]{ } C\right)$ if and only if there are maps $r_{0}: N \rightarrow N, r_{n}: N \rightarrow N$ that are deformation retractions (that are retractions) of $N$ onto $C$ and $A_{n}$ respectively such that $r_{n} \rightarrow r_{0}$ uniformly on $N$. We show these spaces are closely related to $2_{h}^{M}$.

We will need the following lemma. In both its statement and its proof, it is similar to ([2], 3.1, pp. 212-213).

Lemma 4.1. If $C \in 2_{h}^{M} \backslash\{M\}, C$ is connected, and $\varepsilon>0$, there is $a \delta>0$ and a neighborhood $\mathscr{U}$ of $C$ in $2_{h}^{M}$ such that if $\{A, B\} \subset \mathscr{U}$, $B \subset A$, and $A$ is a bounded surface, then every pair of points in $\mathrm{Bd} A$ that can be joined by a $\delta$-arc in $M \backslash B$ can be joined by an $\varepsilon$ are in $\mathrm{Bd} A$.

Proof. By 3.3, there is a neighborhood $\mathscr{U}_{1}$ of $C$ in $2_{h}^{M}$ and a bounded surface $N \subset M$ such that for all $X \in \mathscr{U}_{1}$ we have $X \subset \operatorname{Int} N$ and $X$ is a strong deformation retract of $N$.

Since $M$ is an ANR, there exists $\eta>0$ such that $s(M, \eta, \varepsilon / 4)$. Also there is a $\delta>0$ such that:
(1) If $N$ has more than one boundary curve then
$\delta<\min \{\rho(S, T) \mid S$ and $T$ are distinct boundary curves of $N\}$.
(2) $\delta<1 / 2 \min \{\eta, \varepsilon\}$.
(3) There is a neighborhood $\mathscr{U}_{2}$ of $C$ in $2_{h}^{M}$ such that if $X \in \mathscr{H}_{2}$ then $s(X, \delta, \eta / 2)$.

Let $\mathscr{U}_{3}=\left\{X \in 2_{h}^{H} \mid \rho_{h}(X, C)<\delta / 2\right\}$. Let $\mathscr{U}=\mathscr{U}_{1} \cap \mathscr{U}_{2} \cap \mathscr{U}_{3}$. Clearly $\mathscr{W}$ is a neighborhood of $C$ in $2_{h}^{M}$.

Suppose $\{A, B\} \subset \mathscr{U}$ such that $B \subset A$ and $A$ is a bounded surface. From 1.4 (with $R=B$ ) it follows that $B$ separates each pair of boundary curves of $N$ in $N$. Since each component of $\overline{N \backslash A}$ is an annulus, it follows that
(4) $B$ separates each pair of distinct boundary curves of $A$ in $A$.

Let $p$ and $q$ be distinct points of $\operatorname{Bd} A$ such that there is a $\delta$-arc $\beta$ from $p$ to $q$ in $M \backslash B$.

Suppose $\beta$ meets distinct boundary curves $T_{1}$ and $T_{2}$ of $A$. It follows from (4) that $\beta$ must contain a $\delta$-arc $\beta^{\prime}$ from $p^{\prime} \in T_{1}$ to $q^{\prime} \in T_{2}$ such that $\beta^{\prime} \cap A=\left\{p^{\prime}, q^{\prime}\right\}$. For $n=1,2$, let $B_{n}$ be the annular component of $\overline{N \backslash A}$ containing $T_{n}$ and let $T_{n}^{\prime}$ be the component of $\mathrm{Bd} N$ that is contained in $B_{n}$. By 1.4, $T_{1}^{\prime} \neq T_{2}^{\prime}$. By (4) and 1.4, there are distinct components $B_{n}^{\prime}$ of $N \backslash B$ such that Int $B_{n} \subset B_{n}^{\prime}$. Then $T_{n} \subset B_{n} \subset \overline{B_{n}^{\prime}}$, so we must have $\beta^{\prime} \cap \operatorname{Bd} B_{n}^{\prime} \neq \phi$. Since $\operatorname{Bd} B_{n}^{\prime} \subset T_{n}^{\prime} \cup$ $\operatorname{Bd} B$ and $\beta^{\prime} \cap \operatorname{Bd} B \subset \beta^{\prime} \cap B=\phi$, we have $\beta^{\prime} \cap T_{n}^{\prime} \neq \phi$ for $n=1,2$. The latter contradicts (1). We conclude that $\beta \cap \operatorname{Bd} A$ is contained in a single component $J$ of $\mathrm{Bd} A$.

By $N_{s}(\beta)$ we will mean the set of all points in $M$ whose distance from $\beta$ is less than $s$. Since $\operatorname{diam} \beta<\delta$, there is an $s>0$ such that $\operatorname{diam} N_{s}(\beta)<\delta$. By the proof of 2.4 , we may assume $\beta \cap J$ has finitely many components. If $\gamma$ is a component of $\beta \cap J$
that is not a single point, then $\gamma$ is an arc with endpoints $b, c$. There is an arc $\gamma^{\prime} \subset N_{s}(\beta) \backslash B$ from $b$ to $c$ such that $\gamma^{\prime} \cap J=\{b, c\}$. If $\gamma_{1}, \cdots, \gamma_{m}$ are the components of $\beta \cap J$ that are arcs, then $\beta_{1}=$ $\left(\beta \backslash \bigcup_{n=1}^{m} \gamma_{n}\right) \cup \bigcup_{n=1}^{m} \gamma_{n}^{\prime}$ meets $J$ in but finitely many points and (by choice of $s$ ) contains a $\delta$-arc $\beta_{2}$ from $p$ to $q$. Thus (by replacing $\beta$ by $\beta_{2}$ if necessary) we may assume $\beta \cap J$ is a finite set.

Suppose $\beta \cap J=\{p, q\}$. We consider two cases:
( I ) Suppose $\beta \backslash\{p, q\} \subset M \backslash A$. Since diam $\beta<\delta$, (3) implies there is an $\eta / 2$-arc $\xi$ in $A$ from $p$ to $q$. We assume $\xi \backslash\{p, q\} \subset \operatorname{Int} A$. Then $K=\beta \cup \xi$ is a simple closed curve and $\operatorname{diam} K<\delta+\eta / 2<\eta$ (by (2)). By 1.6 and our choice of $\eta, K$ bounds a disk $L \subset M$ with diam $L<\varepsilon / 4$.

Let $x \in \beta \backslash\{p, q\}, y \in \xi \backslash\{p, q\}$. For any fixed $r>0, B(x, r) \cap(M \backslash A) \neq$ $\phi \neq B(y, r) \cap \operatorname{Int} A$. Suppose $L$ fails to contain an arc of $J$ from $p$ to $q$. Our choices of $\beta$ and $\xi$ imply $J \cap K=J \cap \operatorname{Bd} L=\{p, q\}$, so the assumption implies $J \cap L=\{p, q\}$. Thus $\phi=J \cap \operatorname{Int} L=(\operatorname{Bd} A) \cap \operatorname{Int} L$. Since $\phi \neq B(y, r) \cap \operatorname{Int} A$ meets $\operatorname{Int} L \cap \operatorname{Int} A$ and $\dot{\phi} \neq B(x, r) \cap(M \backslash A)$ meets Int $L \cap(M \backslash A)$, it follows that $\operatorname{Int} L=(\operatorname{Int} L \cap \operatorname{Int} A) \cup$ (Int $L \cap(M \backslash A)$ ) is disconnected. This is impossible, so $L$ contains an arc of $J$ from $p$ to $q$ that lies in $N_{\varepsilon / 4}(\beta)$ (since $\beta \subset L$ and $\operatorname{diam} L<\varepsilon / 4)$.
(II) Suppose $\beta \backslash\{p, q\} \subset \operatorname{Int} A$. Then $A=A_{1} \cup A_{2}$, where $A_{1}$ is a bounded surface containing $B, A_{2}$ is (by (4) and the fact that $\beta \subset M \backslash B)$ a bounded surface whose boundary is the union of $\beta$ and an arc of $J$ from $p$ to $q$, and $A_{1} \cap A_{2}=\beta$. By choice of $\mathscr{U}_{3}$, there is a $\delta$-map $f: A \rightarrow B$. If $z \in A_{2}$ then $f(z) \in B \subset A_{1}$, so by (3) there is an $\eta / 2$-arc $\zeta \subset A$ from $z$ to $f(z)$. Clearly $\zeta$ meets $\beta$. Hence $A_{2} \subset$ $N_{\eta / 2}(\beta)$. In particular, the arc of $J$ from $p$ to $q$ that lies in $\operatorname{Bd} A_{2}$ must lie in $N_{\eta / 2}(\beta)$.

Our choice of $\eta$ implies $\eta / 2<\varepsilon / 4$. In both (I) and (II), $J$ contains an arc from $p$ to $q$ that lies in $N_{\varepsilon / 4}(\beta)$.

More generally, if $\beta \cap J=\left\{p=p_{1}, \cdots, p_{k}=q\right\}$ where the $p_{n}$ are numbered in order from $p$ to $q$ along $\beta$, then each subarc $\overline{p_{n} p_{n+1}}$ of $\beta$ satisfies the condition of (I) or (II). For each $n<k$ there is an arc $\zeta_{n}$ of $J$ from $p_{n}$ to $p_{n+1}$ in $N_{s / 4}(\beta)$. There is an $\operatorname{arc} \zeta_{0} \subset \bigcup_{n=1}^{k-1} \zeta_{n} \subset N_{s / 4}(\beta)$ of $J$ from $p$ to $q$. Observe diam $\zeta_{0} \leqq \operatorname{diam} N_{\varepsilon / 4}(\beta) \leqq \varepsilon / 2+\operatorname{diam} \beta<$ $\varepsilon / 2+\delta<\varepsilon$ (by (2)).

We now strengthen 3.3.
Lemma 4.2. Let $C \in 2_{h}^{M} \backslash\{M\}, \varepsilon>0$. Then there exist $N \in 2_{h}^{M}$ and a neighborhood $\mathscr{U}$ of $C$ in $2_{h}^{M}$ such that each component of $N$ is a bounded surface and such that for all $X \in \mathscr{U}, \rho_{h}(X, C)<\varepsilon, X \subset \operatorname{Int} N$, and there is a strong deformation retraction $h: N \times I \rightarrow N$ of $N$ onto $X$ such that for each $t \in I, h_{t}$ is an $\varepsilon$-map.

Proof. It follows from ([2], 2.1, p. 210) that there is no loss of generality in assuming $C$ is connected.

There is a neighborhood $\mathscr{U}_{1}$ of $C$ in $2_{h}^{M}$ and a $\delta>0$ such that
(1) if $X \in \mathscr{U}_{1}$ then $s(X, \delta, \varepsilon / 2)$.

There are positive numbers $\delta_{1}$ and $\delta_{2}$ such that
(2) $17 \delta_{1}+\delta_{2}<\delta$
and (by 4.1) such that
(3) there is a neighborhood $\mathscr{U}_{2}$ of $C$ in $2_{h}^{M}$ such that if $\{X, Y\} \subset \mathscr{C}_{2}, X \subset Y$, and $Y$ is a bounded surface, then each pair of points in $\mathrm{Bd} Y$ joined by a $7 \delta_{1}$-arc in $M \backslash X$ can be joined by a $\delta_{2}$-arc in $\mathrm{Bd} Y$.

Clearly
(4) there is a neighborhood $\mathscr{C}_{3}$ of $C$ in $2_{h}^{M}$ and a $\delta_{3}>0$ such that if $X \in \mathscr{U}_{3}$ then $s\left(X, \delta_{3}, \delta_{1}\right)$.

Let $\mathscr{U}_{4}=\left\{X \in 2_{h}^{M} \mid \rho_{h}(X, C)<(1 / 2) \delta_{3}\right\}$. By 3.3 there exist a bounded surface $N \in \bigcap_{n=1}^{4} \mathscr{U}_{n}$ and a neighborhood $\mathscr{C}_{5}$ of $C$ in $2_{h}^{M}$ such that $X \in \mathscr{U}_{5}$ implies $X \subset \operatorname{Int} N$ and $X$ is a strong deformation retract of $N$.

Let $\mathscr{U}=\bigcap_{n=1}^{5} \mathscr{U}_{n}$. Clearly $\mathscr{U}$ is a neighborhood of $C$ in $2_{h}^{K}$. Fix $X \in \mathscr{C}$. By 1.1 and 2.5 there is a bounded surface $B \in \mathscr{U}$ such that $X \subset \operatorname{Int} B$ and there is a strong deformation retraction $g: B \times I \rightarrow B$ of $B$ onto $X$ such that $g_{t}$ is an $\varepsilon / 2$-map for all $t \in I$. Thus it suffices to show the existence of a strong deformation retraction $H: N \times I \rightarrow N$ of $N$ onto $B$ such that $H_{t}$ is an $\varepsilon / 2-\mathrm{map}$ for all $t \in I$.

By choice of $\mathscr{C}_{4}$ we have $\rho_{h}(N, B)<\delta_{3}$. It follows from (4) and our choice of $\mathscr{U}_{5}$ that for all $x \in \operatorname{Bd} N$ there is a $\delta_{1}$-arc in $N$ from $x$ to some $y \in \operatorname{Bd} B$. By 1.5, each component $P$ of $\overline{N \backslash B}$ is an annulus. Let $\operatorname{Bd} P=S \cup S^{\prime}$, where $S$ and $S^{\prime}$ are boundary curves of $N$ and $B$ respectively. It follows from 1.4 that $B$ separates distinct boundary curves of $N$ in $N$. Thus
(5) for all $x \in S$, there is a $\delta_{1}$-arc $\beta$ from $x$ to some $y \in S^{\prime}$, and we may assume $\beta \backslash\{x, y\} \subset \operatorname{Int} P$.

Suppose $\operatorname{diam} S<\delta$. By (1) and 1.6, $S$ bounds a disk of diameter less that $\delta / 2$ in $N$. Since $N$ is connected, the disk must be $N$ itself. In this case it is clear that we have a strong deformation $H: N \times$ $I \rightarrow N$ of $N$ onto $B$ such that $H_{t}$ is an $\varepsilon / 2$-map for all $t \in I$. Thus we assume
(6) $\operatorname{diam} S \geqq \delta$.

There is a set $G=\left\{x_{1}, \cdots, x_{k}\right\} \subset S$ of $k$ distinct points numbered according to an orientation of $S$ (let $x_{0}=x_{k}$ ) such that if $\alpha_{p}$ is the arc of $S$ from $x_{p-1}$ to $x_{p}$ containing no other member of $G$, then
(7) $2 \delta_{1}<\rho\left(x_{p-1}, x_{p}\right)$ and $\operatorname{diam} \alpha_{p}<5 \delta_{1}$.

By (2) and (6), $k>1$.
By (5), for each $p$ there exists $y_{p} \in S^{\prime}\left(y_{0}=y_{k}\right)$ and a $\delta_{1}-\operatorname{arc} \beta_{p}\left(\beta_{0}=\beta_{k}\right)$ in $P$ from $x_{p}$ to $y_{p}$ such that $\beta_{p} \backslash\left\{x_{p}, y_{p}\right\} \subset \operatorname{Int} P$. By (7), $\beta_{p-1} \cap \beta_{p}=\phi$.

Since $P$ is an annulus, it follows that the $\beta_{p}$ are pairwise disjoint. By choice of $B, \beta_{p-1} \cup \alpha_{p} \cup \beta_{p}$ is an arc in $M \backslash X$ from $y_{p-1} \in S^{\prime}$ to $y_{p} \in S^{\prime \prime}$, and (7) implies
(8) $\operatorname{diam}\left(\beta_{p-1} \cup \alpha_{p} \cup \beta_{p}\right)<\delta_{1}+5 \delta_{1}+\delta_{1}=7 \delta_{1}$.

By (3), there is a $\delta_{2}-\operatorname{arc} \gamma_{p}$ of $S^{\prime \prime}$ from $y_{p-1}$ to $y_{p}$.
We claim $\gamma_{p}$ does not contain $y_{q}$ if $y_{q} \notin\left\{y_{p-1}, y_{p}\right\}$. For it follows from the disjointness of the $\beta_{p}$ that the points $y_{1}, \cdots, y_{k}$ are numbered according to an orientation of $S^{\prime}$. If some $\gamma_{p}$ contains $y_{q}$ for $y_{q} \notin$ $\left\{y_{p-1}, y_{p}\right\}$, then $\left\{y_{1}, \cdots, y_{k}\right\} \subset \gamma_{p}$. Let $x \in \alpha_{n} \neq \alpha_{p}$. Then $\rho\left(x, \gamma_{p}\right) \leqq$ $\rho\left(x, y_{n}\right) \leqq \rho\left(x, x_{n}\right)+\rho\left(x_{n}, y_{n}\right) \leqq \operatorname{diam} \alpha_{n}+\operatorname{diam} \beta_{n}<5 \delta_{1}+\delta_{1}=6 \delta_{1}$. It follows that $\operatorname{diam} S \leqq \operatorname{diam} \alpha_{p}+\operatorname{diam}\left(S \backslash \alpha_{p}\right)<5 \delta_{1}+\operatorname{diam} N_{6 \delta_{1}}\left(\gamma_{p}\right) \leqq$ $5 \delta_{1}+12 \delta_{1}+\operatorname{diam} \gamma_{p}<17 \delta_{1}+\delta_{2}<\delta$ (by (3)), contrary to (6). The claim is established.

Then $L_{p}=\beta_{p-1} \cup \alpha_{p} \cup \beta_{p} \cup \gamma_{p}(p=1, \cdots, k)$ is a simple closed curve in $N$. By (8) and our choice of $\gamma_{p}$, diam $L_{p}<7 \delta_{1}+\delta_{2}$. By (1), (2), and 1.6, $L_{p}$ bounds a disk $D_{p}$ in $N$ with $\operatorname{diam} D_{p}<\varepsilon / 2$. As in the proof of 3.2, $D_{p}$ is the disk of $P$ bounded by $L_{p}$.

As in 3.2, there is a strong deformation retraction $K: P \times I \rightarrow P$ of $P$ onto $S^{\prime}$ such that $K\left(D_{p} \times I\right)=D_{p}$ for all $p$. Thus $K_{t}$ is an $\varepsilon / 2$-map for all $t \in I$. As in 3.2, $K$ can be extended to a strong deformation retraction $H: N \times I \rightarrow N$ of $N$ onto $B$ such that $H_{t}$ is an $\varepsilon / 2$-map for all $t \in I$.

Theorem 4.3. Let $\left\{A_{n}\right\}_{n=1}^{\infty}$ and $C$ be points of $2_{n}^{M} \backslash\{M\}$. Then $A_{n} \rightarrow C$ if and only if there exists $N \in 2_{h}^{M}$ such that each component of $\stackrel{\rho_{h}}{N}$ is a bounded surface and $A_{n} \xrightarrow[D(N)]{\longrightarrow}$.

Proof. By 3.3, there is a compact 2 -manifold with boundary $N \in 2_{h}^{K}$ and a neighborhood $\mathscr{U}$ of $C$ in $2_{h}^{K}$ such that if $X \in \mathscr{U}$ then $X \subset \operatorname{Int} N$ and $X$ is a strong deformation retract of $N$.

Suppose $A_{n} \xrightarrow[\rho_{h}]{ } C$. Let $\varepsilon>0$. By 4.2 there is a compact 2 manifold with boundary $B \in \mathscr{C}$ and a neighborhood $\mathscr{V}$ of $C$ in $2_{h}^{H}$ with $\mathscr{V} \subset \mathscr{C}$ such that if $X \in \mathscr{V}$ then $X \subset \operatorname{Int} B$ and there is an $\varepsilon / 2$-map $r: B \rightarrow B$ that is a strong deformation retraction of $B$ onto $X$. Choose an $m$ such that $n>m$ implies $A_{n} \in \mathscr{V}$.

Let $f: N \rightarrow N$ be a deformation retraction of $N$ onto $B$. Let $f_{n}: B \rightarrow B$ be an $\varepsilon / 2$-map that is a deformation retraction of $B$ onto $A_{n}$ for $n>m$. Let $f_{0}: B \rightarrow B$ be an $\varepsilon / 2$-map that is a deformation retraction of $B$ onto $C$. Define $r_{n}: N \rightarrow N$ for $n=0, n>m$ by $r_{n}(x)=$ $f_{n}(f(x))$. For all $x \in N$ and $n>m, \rho\left(r_{n}(x), r_{0}(x)\right)<\varepsilon$. Hence $A_{n} \xrightarrow[D(N)]{ } C$.

Conversely, suppose $A_{n} \xrightarrow[D(N)]{ } C$. There exist deformation retractions $r_{n}: N \rightarrow N$ of $N$ onto $A_{n^{\prime}}, r_{0}: N \rightarrow N$ of $N$ onto $C$ such that $r_{n} \rightarrow r_{0}$ uniformly on $N$.

If $x \in C, \rho\left(x, r_{n}(x)\right) \rightarrow \rho\left(x, r_{0}(x)\right)=0$. Hence $\rho\left(x, A_{n}\right) \rightarrow 0$.
If $x_{n} \in A_{n}, \rho\left(x_{n}, r_{0}\left(x_{n}\right)\right)=\rho\left(r_{n}\left(x_{n}\right), r_{0}\left(x_{n}\right)\right) \rightarrow 0$. Hence $\rho\left(x_{n}, C\right) \rightarrow 0$. We conclude $A_{n} \xrightarrow[\rho_{s}]{ } C$.

Let $\varepsilon>0$. Let $\delta>0$ be such that if $\{x, y\} \subset N$ and $\rho(x, y)<\delta$ then $\rho\left(r_{0}(x), r_{0}(y)\right)<\varepsilon / 6$. Let $\delta^{\prime}>0$ be such that $s\left(N, \delta^{\prime}, \delta\right)$. Let $m>0$ be such that $n>m$ implies that for all $x \in N, \rho\left(r_{n}(x), r_{0}(x)\right)<$ $\varepsilon / 6$.

If $\{x, y\} \subset N, \rho(x, y)<\delta$, and $n>m$, then $\rho\left(r_{n}(x), r_{n}(y)\right) \leqq \rho\left(r_{n}(x)\right.$, $\left.r_{0}(x)\right)+\rho\left(r_{0}(x), r_{0}(y)\right)+\rho\left(r_{0}(y), r_{n}(y)\right)<\varepsilon / 6+\varepsilon / 6+\varepsilon / 6=\varepsilon / 2$.

Let $K \subset A_{n} \subset N$, diam $K<\delta^{\prime}$. There is a contraction $h: K \times I \rightarrow N$ of $K$ to a point such that $\operatorname{diam} h(K \times I)<\delta$. Therefore, for $n>m$, $r_{n} \circ h: K \times I \rightarrow N$ is a contraction of $K$ to a point such that $r_{n} \circ h(K \times I) \subset A_{n}$ and $\operatorname{diam}\left(r_{n} \circ h(K \times I)\right)<\varepsilon / 2+\varepsilon / 2=\varepsilon$. Hence $s\left(A_{n}, \delta^{\prime}, \varepsilon\right)$ for $n>m$, so $A_{n} \xrightarrow[\rho_{h}]{ } C$.

Theorem 4.4. $2_{n}^{M}$ is an $\operatorname{ANR}$ (all).
Proof. If $N$ and $\mathscr{C}$ are as above, the previous theorem implies the inclusion of the set $\mathscr{C}$ into $D(N)$ is an open embedding. Since $D(N)$ is an ANR ( $\mathscr{C}$ ) ([11], 5.5, p. 389), it follows ([9], 3.1, p. 391) that $\mathscr{U}$ is an $\operatorname{ANR}(\mathscr{M})$. Since $M$ is an isolated point of $2_{h}^{M}$ (because $[M]_{M}=\{M\}$ ) the assertion follows from the fact that a local ANR ( $\mathscr{M}$ ) is an $\operatorname{ANR}(\mathscr{C})$ ([9], 3.3, p. 392).

Theorem 4.5. Let $A R_{h}^{M}=\left\{X \in 2_{h}^{I K} \mid X\right.$ is an AR $\}$. Then $A R_{h}^{H}$ is a component of $2_{h}^{H}$.

Proof. Since $A R_{h}^{M}$ is the set of all members of $2_{h}^{M}$ with the homotopy type of a point, $A R_{h}^{M}$ is open and closed in $2_{h}^{M}$, and thus is a union of components of $2_{h}^{K}$. We must show $A R_{h}^{M}$ is connected.

Let $C_{n} \in A R_{h}^{H}(n=0,1)$. By 3.2 there is an arc in $A R_{h}^{M}$ from $C_{n}$ to $N_{n}$, where $N_{n}$ is a disk. Let $p_{n} \in N$ and let $h^{n}: N_{n} \times I \rightarrow N_{n}$ be a pseudoisotopy of $N_{n}$ onto $p_{n}$. Then (using 1.3) $\left\{h^{n}\left(N_{n} \times\{t\}\right) \mid t \in I\right\}$ contains an arc in $A R_{h}^{M}$ from $N_{n}$ to $\left\{p_{n}\right\}$. Let $h: I \rightarrow M$ be a map such that $h(0)=p_{0}$ and $h(1)=p_{1}$. By $1.3,\{\{h(t)\} \mid t \in I\}$ contains an arc in $A R_{h}^{M}$ from $\left\{p_{0}\right\}$ to $\left\{p_{1}\right\}$. Thus there is an arc in $A R_{h}^{M}$ from $C_{0}$ to $C_{1}$.

THEOREM 4.6. $A R_{h}^{M}=L(M)$ as topological spaces.
Proof. Clearly they are equal as sets. Let $C \in A R_{h}^{M}$. As above, there is a disk $N \subset M$ such that $C \subset \operatorname{Int} N$ and $C$ is a strong deformation retract of $N$. We know $A_{n} \xrightarrow[\rho_{h}]{ } C$ if and only if $A_{n} \xrightarrow[D(N)]{ } C$.

But $A_{n} \xrightarrow[D(N)]{ } C$ if and only if $A_{n} \xrightarrow[L(M)]{ } C$ ([11], 5.4, p. 388).
Clearly the map $j: M \rightarrow A R_{h}^{V}$ defined by $j(x)=\{x\}$ is an embedding. We have the following:

Corollary 4.7. $j(M)$ is a deformation retract of $A R_{h}^{M}$. Thus $A R_{h}^{M}$ has the same homotopy type as $M$.

Proof. This follows from Theorem 4.6 and ([11], 5.5, p. 389).

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