Seventeenth International Conference on Geometry, Integrability and Quantization June 5–10, 2015, Varna, Bulgaria Ivaïlo M. Mladenov, Guowu Meng and Akira Yoshioka, Editors **Avangard Prima**, Sofia 2016, pp 256–269 doi: 10.7546/giq-17-2016-256-269



BOUR SURFACE COMPANIONS IN SPACE FORMS

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Abstract. In this paper, we give explicit parametrizations for Bour type surfaces in various three-dimensional space forms, using Weierstrass-type representations. We also determine classes and degrees of some Bour type zero mean curvature surfaces in three-dimensional Minkowski space.

MSC: 53A35, 53C42

Keywords: Bour type surface, class, constant mean curvature surface, degree, zero mean curvature surface

1. Introduction

Minimal surfaces in three-dimensional Euclidean space \mathbb{R}^3 isometric to rotational surfaces were first introduced by Bour [2] in 1862. All such minimal surfaces are given via the well-known Weierstrass representation for minimal surfaces by choosing suitable data depending on a parameter m, as shown by Schwarz [15]. They are called Bour's minimal surfaces \mathfrak{B}_m of value m. Furthermore, when m is an integer greater than one, \mathfrak{B}_m become algebraic, that is, there is an implicit polynomial equation satisfied by the three coordinates of \mathfrak{B}_m , see also [5, 13, 18]. Kobayashi [9] gave an analogous Weierstrass-type representation for conformal spacelike surfaces with mean curvature identically zero, called maximal surfaces, in three-dimensional Minkowski space $\mathbb{R}^{2,1}$. We remark that Magid [12] gave a Weierstrass-type representation for timelike surfaces with mean curvature identically zero, called timelike minimal surfaces, in $\mathbb{R}^{2,1}$, see also [8].

On the other hand, Lawson [10] showed that there is an isometric correspondence between constant mean curvature (CMC for short) surfaces in Riemannian space forms, and Palmer [14] showed that there is an analogous correspondence between spacelike CMC surfaces in Lorentzian space forms. In particular, minimal surfaces in \mathbb{R}^3 correspond to CMC 1 surfaces in three-dimensional hyperbolic space \mathbb{H}^3 , and maximal surfaces in $\mathbb{R}^{2,1}$ correspond to CMC 1 surfaces in three-dimensional de Sitter space $\mathbb{S}^{2,1}$. Thus it is natural to expect existence of corresponding Weierstrass-type representations in these cases. Bryant [3] gave such a representation formula for CMC 1 surfaces in \mathbb{H}^3 , and Umehara, Yamada [16] applied it. Similarly, Aiyama and Akutagawa [1] gave a representation formula for CMC 1 surfaces in $\mathbb{S}^{2,1}$. However, analogues of Bour's surfaces in other three-dimensional space forms had not yet been studied.

In Sections 2 and 3 of this paper, in order to show that several maximal and time-like minimal Bour's surfaces of value m are algebraic, we review Weierstrass-type representations for maximal surfaces and timelike minimal surfaces in $\mathbb{R}^{2,1}$, and give explicit parametrizations for spacelike and timelike minimal Bour's surfaces of value m. In Section 4, we introduce Bour type CMC 1 surfaces in \mathbb{H}^3 and $\mathbb{S}^{2,1}$, and show several properties of those surfaces. Finally, in Section, 5 we calculate the degrees, classes and implicit equations of the maximal and timelike minimal Bour's surfaces of values 2, 3, 4 in $\mathbb{R}^{2,1}$ in terms of their coordinates. We remark that in the cases of \mathbb{H}^3 and $\mathbb{S}^{2,1}$, all surfaces are algebraic in some sense, because the Lorentz ($\mathbb{R}^{3,1}$) norm of all elements in $\mathbb{H}^3 \subset \mathbb{R}^{3,1}$ or $\mathbb{S}^{2,1} \subset \mathbb{R}^{3,1}$ is constant. However, we have the following three remaining problems:

Problem.

- What is the class of maximal and timelike minimal Bour's surfaces of general value m in $\mathbb{R}^{2,1}$?
- Are there any other implicit equations for CMC 1 Bour type surfaces? If there exist implicit equations, what are the corresponding degrees and classes?

2. Spacelike Maximal Bour Type Surfaces in $\mathbb{R}^{2,1}$

Let $\mathbb{R}^{n,1}:=\left(\{x=(x_1,\cdots,x_n,x_0)^t\colon x_i\in\mathbb{R}\},\langle\cdot,\cdot\rangle\right)$ be the (n+1)-dimensional Lorentz-Minkowski (for short, Minkowski) space with Lorentz metric $\langle x,y\rangle=x_1y_1+\cdots+x_ny_n-x_0y_0$. Then the three-dimensional hyperbolic space \mathbb{H}^3 and three-dimensional de Sitter space $\mathbb{S}^{2,1}$ are defined as follows

$$\mathbb{H}^{3} := \{ x \in \mathbb{R}^{3,1} \, ; \, \langle x, x \rangle = -1, \, x_{0} > 0 \} \cong \{ F \bar{F}^{t} \, ; \, F \in \mathrm{SL}(2, \mathbb{C}) \}$$
$$\mathbb{S}^{2,1} := \{ x \in \mathbb{R}^{3,1} \, ; \, \langle x, x \rangle = 1 \} \cong \left\{ F \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \bar{F}^{t} \, ; \, F \in \mathrm{SL}(2, \mathbb{C}) \right\}.$$

A vector $x \in \mathbb{R}^{n,1}$ is called spacelike if $\langle x,x \rangle > 0$, timelike if $\langle x,x \rangle < 0$, and lightlike if $x \neq 0$ and $\langle x,x \rangle = 0$. A surface in $\mathbb{R}^{n,1}$ is called spacelike (respectively timelike, lightlike) if the induced metric on the tangent planes is a positive definite Riemannian (respectively Lorentzian, degenerate) metric.

Kobayashi [9] has found a Weierstrass-type representation for spacelike conformal maximal surfaces in $\mathbb{R}^{2,1}$.

Theorem 1. Let g be a meromorphic function and let ω be a holomorphic function defined on a simply connected open subset $\mathcal{U} \subset \mathbb{C}$ such that ω does not vanish on \mathcal{U} . Then

$$f(z) = \operatorname{Re} \int \begin{pmatrix} (1+g^2) \omega \\ i(1-g^2) \omega \\ 2g\omega \end{pmatrix} dz$$

is a spacelike conformal immersion with mean curvature identically 0 (i.e., spacelike conformal maximal surface). Conversely, any spacelike conformal maximal surface can be described in this manner.

Remark 2. A pair of a meromorphic function g and a holomorphic function ω (g,ω) is called Weierstrass data for a maximal surface. In Section 4 we also call (g,ω) the Weierstrass data for CMC 1 surfaces in \mathbb{H}^3 and $\mathbb{S}^{2,1}$.

We call maximal surfaces \mathfrak{B}_m $(m \in \mathbb{Z}_{\geq 2} := \{n \in \mathbb{Z}; n \geq 2\})$ given by $(g, \omega) = (z, z^{m-2})$ the spacelike Bour's maximal surfaces \mathfrak{B}_m of value m (spacelike \mathfrak{B}_m , for short). Several properties of spacelike \mathfrak{B}_m can be found in the first author's paper [6]. The parametrization of spacelike \mathfrak{B}_m is

$$\mathfrak{B}_m(u,v)$$

$$= \operatorname{Re} \left(\frac{\frac{1}{m-1} \sum_{k=0}^{m-1} {m-1 \choose k} u^{m-1-k} (\mathrm{i}v)^k + \frac{1}{m+1} \sum_{k=0}^{m+1} {m+1 \choose k} u^{m+1-k} (\mathrm{i}v)^k}{\sum_{k=0}^{m-1} {m-1 \choose k} u^{m-1-k} (\mathrm{i}v)^k - \frac{\mathrm{i}}{m+1} \sum_{k=0}^{m+1} {m+1 \choose k} u^{m+1-k} (\mathrm{i}v)^k} \right) \frac{2}{m} \sum_{k=0}^{m} {m \choose k} u^{m-k} (\mathrm{i}v)^k$$

with a Gauss map $n=\left(\frac{2u}{u^2+v^2-1},\frac{2v}{u^2+v^2-1},\frac{u^2+v^2+1}{u^2+v^2-1}\right)$, where $z=u+\mathrm{i}v$. The left two pictures in Figure 1 are two examples of spacelike \mathfrak{B}_m .

3. Timelike Minimal Bour Type Surfaces in $\mathbb{R}^{2,1}$

Next, we give the Weierstrass-type representation for timelike minimal surfaces in $\mathbb{R}^{2,1}$, which was obtained by Magid [12] (see also [8]).

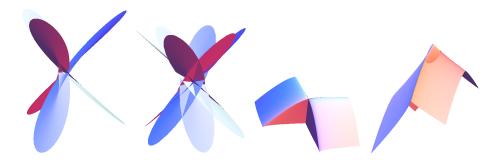


Figure 1. Left two pictures: spacelike \mathfrak{B}_3 and \mathfrak{B}_6 in $\mathbb{R}^{2,1}$. Right two pictures: timelike \mathfrak{B}_3 and \mathfrak{B}_6 in $\mathbb{R}^{2,1}$.

Theorem 3. Let $g_1(u)$, $\omega_1(u)$ (respectively $g_2(v)$, $\omega_2(v)$) be smooth functions depending on only u (respectively v) on a connected orientable 2-manifold with local coordinates u, v. Then

$$\hat{f}(u,v) = \int \begin{pmatrix} 2g_1\omega_1 \\ (1-g_1^2)\omega_1 \\ -(1+g_1^2)\omega_1 \end{pmatrix} du + \int \begin{pmatrix} 2g_2\omega_2 \\ (1-g_2^2)\omega_2 \\ (1+g_2^2)\omega_2 \end{pmatrix} dv$$

is a timelike surface with mean curvature identically 0 (i.e., timelike minimal surface). Conversely, any timelike minimal surface can be described in this manner.

The timelike minimal surfaces given by $(g_1(u), \omega_1(u)) = (u, u^{m-2}), (g_2(v), \omega_2(v)) = (v, v^{m-2})$ are called timelike Bour surfaces \mathfrak{B}_m of value m (timelike \mathfrak{B}_m , for short) in $\mathbb{R}^{2,1}$, where $m \in \mathbb{Z}_{\geq 2}$. The parametrization of timelike \mathfrak{B}_m is

$$\mathfrak{B}_{m}(u,v) = \begin{pmatrix} \frac{2}{m} (u^{m} + v^{m}) \\ \frac{1}{m-1} (u^{m-1} + v^{m-1}) - \frac{1}{m+1} (u^{m+1} + v^{m+1}) \\ -\frac{1}{m-1} (u^{m-1} - v^{m-1}) - \frac{1}{m+1} (u^{m+1} - v^{m+1}) \end{pmatrix}$$
(2)

with Gauss map $n=\left(\dfrac{uv-1}{1+uv},\dfrac{u+v}{1+uv},\dfrac{u-v}{1+uv}\right)$.

The right two pictures in Figure 1 are two examples of timelike \mathfrak{B}_m .

4. CMC 1 Bour Type Surfaces in \mathbb{H}^3 and $\mathbb{S}^{2,1}$

In this section we consider CMC 1 surfaces in \mathbb{H}^3 and $\mathbb{S}^{2,1}$. Here we identify elements in \mathbb{H}^3 and $\mathbb{S}^{2,1}$ with $SL_2\mathbb{C}$ matrix forms as in Section 2. In this setting Bryant [3] showed the following representation formula for CMC 1 surfaces in \mathbb{H}^3 , and Aiyama and Akutagawa [1] showed the following Bryant-type representation formula for CMC 1 surfaces in $\mathbb{S}^{2,1}$.

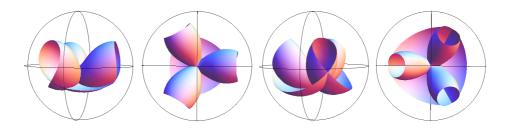


Figure 2. Left two pictures: \mathfrak{B}_3 cousins in \mathbb{H}^3 . Right two pictures: their dual cousins in \mathbb{H}^3 (in the Poincaré ball model for \mathbb{H}^3).

Theorem 4. Let $F \in \mathrm{SL}(2,\mathbb{C})$ be a solution of the equation

$$\frac{\mathrm{d}F}{\mathrm{d}z} = F \begin{pmatrix} g & -g^2 \\ 1 & -g \end{pmatrix} \omega, \qquad F|_{z=z_0} \in \mathrm{SL}(2, \mathbb{C})$$
 (3)

for some z_0 in a given domain, where (g,ω) is Weierstrass data. Then the surface $f = F\bar{F}^t$ (respectively $f = F\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}\bar{F}^t$) is a conformal CMC 1 immersion into \mathbb{H}^3 (respectively $\mathbb{S}^{2,1}$). Conversely, any conformal CMC 1 immersion in \mathbb{H}^3 (respectively $\mathbb{S}^{2,1}$) can be described in this way.

We call CMC 1 surfaces in \mathbb{H}^3 and $\mathbb{S}^{2,1}$ given by the Weierstrass data $(g,\omega)=(z,z^{m-2})$ the Bour type CMC 1 cousins \mathfrak{B}_m of value m (\mathfrak{B}_m cousin, for short). We now describe F explicitly

Theorem 5. Let $F(z) = \begin{pmatrix} a(z) & b(z) \\ c(z) & d(z) \end{pmatrix} \in SL(2,\mathbb{C})$ be a solution of equation (3) with $(g,\omega) = (z,z^{m-2}dz)$ and with initial condition $F(0) = \mathrm{Id}$. Then

$$a(z) = m^{\frac{1}{m}} \Gamma\left(\frac{m+1}{m}\right) z^{\frac{m-1}{2}} \operatorname{Bessel I}\left(-\frac{m-1}{m}, \frac{2}{m} z^{\frac{m}{2}}\right)$$

$$b(z) = -m^{\frac{1}{m}} \Gamma\left(\frac{m+1}{m}\right) z^{\frac{m+1}{2}} \operatorname{Bessel I}\left(\frac{m+1}{m}, \frac{2}{m} z^{\frac{m}{2}}\right)$$

$$c(z) = m^{\frac{-1}{m}} \Gamma\left(\frac{m-1}{m}\right) z^{\frac{m-1}{2}} \operatorname{Bessel I}\left(\frac{m-1}{m}, \frac{2}{m} z^{\frac{m}{2}}\right)$$

$$d(z) = -m^{\frac{-1}{m}} \Gamma\left(\frac{m-1}{m}\right) z^{\frac{m+1}{2}} \operatorname{Bessel I}\left(-\frac{m+1}{m}, \frac{2}{m} z^{\frac{m}{2}}\right)$$

$$(4)$$

where Γ denotes the Gamma function and Bessel I represents the modified Bessel function. The definition of Bessel I can be found in standard textbooks, for example, see [7].

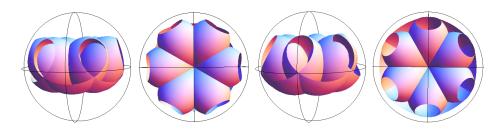


Figure 3. Left two pictures: \mathfrak{B}_6 cousins in \mathbb{H}^3 . Right two pictures: their dual cousins in \mathbb{H}^3 .

Proof: Equation (3) gives

$$X'' - \frac{\omega'}{\omega}X' - g'\omega X = 0, \qquad X = a(z), \ c(z)$$
 (5)

$$Y'' - \frac{(g^2\omega)'}{g^2\omega}Y' - g'\omega Y = 0, Y = b(z), d(z) (6)$$

which are given in [16]. Here we solve equation (5). Inserting $(g, \omega) = (z, z^{m-2})$ into equation (5), we have

$$X'' - \frac{m-2}{z}X' - z^{m-2}X = 0, \qquad m \in \mathbb{Z}_{\geq 2}.$$
 (7)

We give two independent power series solutions of the differential equation (7) by the Frobenius method. The indicial equation at z=0 is $\rho(\rho-1)-(m-2)\rho=0$. So we see that the characteristic exponents of the equation (7) are 0 and m-1. Then we have a solution of the form

$$z^{m-1} \sum_{p=0}^{\infty} a_p z^p$$

where the coefficients a_p are inductively given by

$$\begin{aligned} a_{mk+l} &= 0, & l &= 0, \cdots, m \\ a_{m(k-1)+m-1} &= \frac{a_{m(k-1)+m-1}}{(m-2)k(mk+m-1)} \\ &= \frac{\Gamma(\frac{m-1}{m}+k)}{m^2\Gamma(\frac{m-1}{m}+k+1)} a_{m(k-1)+m-1}, & l &\geq m+1. \end{aligned}$$

Therefore we obtain a solution of the differential equation (7)

$$z^{\frac{m-1}{2}} \sum_{k=0}^{\infty} \frac{(-1)^k}{k! \Gamma(\frac{m-1}{m}+k+1)} \left(\frac{z^{\frac{m}{2}}}{m}\right)^{2k+\frac{m-1}{m}} = z^{\frac{m-1}{2}} \operatorname{Bessel} \operatorname{I}\left(\frac{m-1}{m}, \frac{2}{m}z^{\frac{m}{2}}\right).$$

Similarly, we obtain another independent solution as

$$z^{\frac{m-1}{2}} \sum_{k=0}^{\infty} \frac{(-1)^k}{k! \Gamma(\frac{1-m}{m}+k+1)} \left(\frac{z^{\frac{m}{2}}}{m}\right)^{2k-\frac{m-1}{m}} = z^{\frac{m-1}{2}} \operatorname{BesselI}\left(\frac{1-m}{m}, \frac{2}{m}z^{\frac{m}{2}}\right).$$

So we have two independent solutions of equation (5). Next, we find two independent solutions of equation (6). Inserting $(g,\omega)=(z,z^{m-2})$ into equation (6), we have

$$Y'' - \frac{m}{z}Y' - z^{m-2}Y = 0, \quad m \in \mathbb{Z}_{\geq 2}.$$

Similarly to the way we solved equation (5), we have two independent solutions

$$z^{\frac{m+1}{2}}\operatorname{Bessel}\operatorname{I}\left(\frac{m+1}{m},\frac{2}{m}z^{\frac{m}{2}}\right), \qquad z^{\frac{m+1}{2}}\operatorname{Bessel}\operatorname{I}\left(-\frac{m+1}{m},\frac{2}{m}z^{\frac{m}{2}}\right).$$

Using the initial conditions, we have the solution F as in equations (4).

Remark 6. If F is a solution of equation (3), the surface

$$f^{\sharp} = (F^{-1})\overline{(F^{-1})}^t \ \left(\text{respectively } f^{\sharp} = (F^{-1}) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \overline{(F^{-1})}^t \right)$$

is also a CMC 1 surface in \mathbb{H}^3 (respectively $\mathbb{S}^{2,1}$). This was proven in [17] (respectively [11]). The surface f^{\sharp} is called the CMC 1 dual of f.

Using the explicit parametrization of the \mathfrak{B}_m cousin, we can easily show the following corollary, which implies the rotational symmetric property of the \mathfrak{B}_m cousins in \mathbb{H}^3 and $\mathbb{S}^{2,1}$.

Corollary 7. Let $F(z) \in \operatorname{SL}_2\mathbb{C}$ be the form as in Theorem 5 with complex coordinate z. Then

$$F(e^{i\frac{2\pi}{m}} \cdot z) = \begin{pmatrix} a(z) & e^{i\frac{2\pi}{m}} \cdot b(z) \\ e^{-i\frac{2\pi}{m}} \cdot c(z) & d(z) \end{pmatrix}.$$

Writing \mathfrak{B}_m cousin in \mathbb{H}^3 or $\mathbb{S}^{2,1}$ as $f(z)=(x_1(z),x_2(z),x_3(z),x_0(z))^t$, given by Theorem 5, and setting $f\left(\mathrm{e}^{\mathrm{i}\frac{2\pi}{m}}\cdot z\right)=(\hat{x}_1(z),\hat{x}_2(z),\hat{x}_3(z),\hat{x}_0(z))^t$. By Corollary 7, we have

$$\hat{x}_1(z) = \cos\left(\frac{2\pi}{m}\right) x_1(z) - \sin\left(\frac{2\pi}{m}\right) x_2(z)$$

$$\hat{x}_2(z) = \sin\left(\frac{2\pi}{m}\right) x_1(z) + \cos\left(\frac{2\pi}{m}\right) x_2(z)$$

$$\hat{x}_3(z) = x_3(z), \qquad \hat{x}_0(z) = x_0(z)$$

that is, by rotating z by angle $\frac{2\pi}{m}$, the first and second coordinates are also rotated by the same angle. So like in \mathbb{R}^3 and $\mathbb{R}^{2,1}$, \mathfrak{B}_m has symmetry with respect to rotation by angle $\frac{2\pi}{m}$. Its dual $(\mathfrak{B}_m)^{\sharp}$ also has the same symmetry.



Figure 4. Left two pictures: \mathfrak{B}_3 cousins in $\mathbb{S}^{2,1}$. Right two pictures: their dual cousins in $\mathbb{S}^{2,1}$.

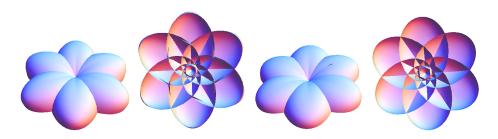


Figure 5. Left two pictures: \mathfrak{B}_6 cousins in $\mathbb{S}^{2,1}$. Right two pictures: their dual cousins in $\mathbb{S}^{2,1}$.

In order to see CMC 1 surfaces in \mathbb{H}^3 , we use a stereographic projection. Consider the map

$$\begin{array}{ccc}
\mathbb{H}^{3} & \longrightarrow & \mathbb{B}^{3} \\
 & & & & & & & & \\
(x_{1}, x_{2}, x_{3}, x_{0})^{t} & \longmapsto & \left(\frac{x_{1}}{1 + x_{0}}, \frac{x_{2}}{1 + x_{0}}, \frac{x_{3}}{1 + x_{0}}\right)^{t}
\end{array}$$

where \mathbb{B}^3 denotes the 3-dimensional unit ball. This is the Poincaré ball model for \mathbb{H}^3 . The pictures in Fig. 2 and Fig. 3 are two examples of \mathfrak{B}_m cousins projected into \mathbb{B}^3 .

In order to show graphics of CMC 1 surfaces in $\mathbb{S}^{2,1}$, the hollow ball model is used, see [4] for example. Consider the map

where $\mathbb{B}^3_{(-\pi,\pi)} := \{(y_1,y_2,y_3)^t \in \mathbb{R}^3 \; ; \; \mathrm{e}^{-\pi} < y_1^2 + y_2^2 + y_3^2 < \mathrm{e}^{\pi} \}$. Fig. 4 and Fig. 5 show two examples of \mathfrak{B}_m projected into $\mathbb{B}^3_{(-\pi,\pi)}$.

5. Degree and Class of Bour Type Surfaces in $\mathbb{R}^{2,1}$

For $\mathbb{R}^{2,1}$, the set of roots of a polynomial Q(x,y,z)=0 gives an algebraic surface. An algebraic surface f is said to be of degree (or order) n when $n=\deg(f)$. The tangent plane at a point (u,v) on a surface f (u,v)=(x(u,v),y(u,v),z(u,v)) is given by

$$Xx + Yy - Zz + P = 0 (8)$$

where the Gauss map is n=(X(u,v),Y(u,v),Z(u,v)) and P=P(u,v). We have inhomogeneous tangential coordinates $a=X/P,\,b=Y/P,$ and c=Z/P. When we can obtain an implicit equation $\hat{Q}(a,b,c)=0$ of f(u,v) in tangential coordinates, the maximum degree of the equation gives the *class* of f(u,v).

Next, using Groebner and other polynomial elimination methods (in Maple software), we calculate the implicit equations, degrees and classes of spacelike and timelike \mathfrak{B}_2 , \mathfrak{B}_3 and \mathfrak{B}_4 .

5.1. Degree and Class of Spacelike $\mathfrak{B}_2, \mathfrak{B}_3, \mathfrak{B}_4$ in $\mathbb{R}^{2,1}$

From (2), the parametrization of \mathfrak{B}_2 (maximal Enneper surface) is

$$\mathfrak{B}_{2}(u,v) = \begin{pmatrix} \frac{1}{3}u^{3} - uv^{2} + u \\ u^{2}v - \frac{1}{3}v^{3} - v \\ u^{2} - v^{2} \end{pmatrix} = \begin{pmatrix} x(u,v) \\ y(u,v) \\ z(u,v) \end{pmatrix}$$

where $u, v \in \mathbb{R}$. In this section, $Q_m(x, y, z) = 0$ denotes the irreducible implicit equation that spacelike or timelike \mathfrak{B}_m will satisfy. Then

$$\begin{aligned} Q_2(x,y,z) &= -64z^9 + 432x^2z^6 - 432y^2z^6 + 1215x^4z^3 + 6318x^2y^2z^3 \\ &- 3888x^2z^5 + 1215y^4z^3 - 3888y^2z^5 + 1152z^7 + 729x^6 - 2187x^4y^2 \\ &- 4374x^4z^2 + 2187x^2y^4 + 6480x^2z^4 - 729y^6 + 4374y^4z^2 - 6480y^2z^4 \\ &- 729x^4z + 1458x^2y^2z + 3888x^2z^3 - 729y^4z + 3888y^2z^3 - 5184z^5 \end{aligned}$$

and its degree is $\deg(\mathfrak{B}_2)=9$. Therefore, \mathfrak{B}_2 is an algebraic maximal surface. To find the class of the surface \mathfrak{B}_2 , we obtain $P_2(u,v)=\frac{(u^2+v^2-3)(u-v)(u+v)}{3(u^2+v^2-1)}$, where $P_m(u,v)$ denotes the function as in equation (8) for spacelike or timelike \mathfrak{B}_m . The inhomogeneous tangential coordinates are $a=\frac{6u}{\alpha(u,v)},\ b=\frac{6v}{\alpha(u,v)},\ c=\frac{6(u^2+v^2+1)}{\alpha(u,v)}$, where $\alpha(u,v)=(u^2+v^2-3)(u-v)(u+v)$. In

a, b, c coordinates \mathfrak{B}_2 is given by

$$\hat{Q}_2(a,b,c) = 4a^6 + 9a^4 + 9b^4 + 6a^2b^2c^2 + 12b^2c^3 - 3b^4c^2 - 18b^4c - 4a^4b^2 + 18a^4c - 12a^2c^3 - 4a^2b^4 - 3a^4c^2 + 18a^2b^2 - 4a^2b^4 + 4b^6$$

and in general $\hat{Q}_m(a,b,c) = 0$ denotes the irreducible implicit equation for spacelike or timelike \mathfrak{B}_m in terms of tangential coordinates. Therefore, the class of the spacelike \mathfrak{B}_2 is $cl(\mathfrak{B}_2) = 6$. Similarly

$$\mathfrak{B}_{3}\left(u,v\right) = \begin{pmatrix} \frac{u^{4}}{4} + \frac{v^{4}}{4} - \frac{3}{2}u^{2}v^{2} + \frac{u^{2}}{2} - \frac{v^{2}}{2} \\ u^{3}v - uv^{3} - uv \end{pmatrix} = \begin{pmatrix} x(u,v) \\ y(u,v) \\ z(u,v) \end{pmatrix}$$

$$\mathfrak{B}_{4}\left(u,v\right) = \begin{pmatrix} \frac{1}{3}u^{3} - uv^{2} + \frac{1}{5}u^{5} - 2u^{3}v^{2} + uv^{4} \\ -u^{2}v + \frac{1}{3}v^{3} + u^{4}v - 2u^{2}v^{3} + \frac{1}{5}v^{5} \end{pmatrix} = \begin{pmatrix} x(u,v) \\ y(u,v) \\ z(u,v) \end{pmatrix}$$

and

$$Q_3(x,y,z) = -43046721z^{16} + 272097792x^3z^{12} - 816293376xy^2z^{12}$$

 $+3009871872x^6z^8 + 14834368512x^4y^2z^8 + (69 \text{ other lower order terms})$

$$Q_4(x, y, z) = -1514571848868138319872z^{25}$$

$$+9244212944751820800000x^4z^{20}$$

$$-24192761655761718750000000x^4y^{12}z^5$$

$$-55465277668510924800000x^2y^2z^{20}$$

$$-3065257232666015625000000x^{12}y^6z^2 + (233 \text{ other lower order terms})$$

and their degrees are $deg(\mathfrak{B}_3) = 16$, $deg(\mathfrak{B}_4) = 25$. Therefore, \mathfrak{B}_3 and \mathfrak{B}_4 are algebraic spacelike maximal surfaces. Furthermore

$$P_3(u,v) = \frac{u(u^2 + v^2 - 2)(u^2 - 3v^2)}{(u^2 + v^2 - 1)}$$

$$P_4(u,v) = \frac{(3u^2 + 3v^2 - 5)(u^2 - 2uv - v^2)(u^2 + 2uv - v^2)}{30(u^2 + v^2 - 1)}$$

and the inhomogeneous tangential coordinates are

$$a = \frac{12}{\beta(u,v)}, \quad b = \frac{12v}{u\beta(u,v)}, \quad c = \frac{6(u^2 + v^2 + 1)}{u\beta(u,v)}, \qquad m = 3$$

$$a = \frac{60u}{\gamma(u,v)}, \quad b = \frac{60v}{\gamma(u,v)}, \quad c = \frac{30(u^2 + v^2 + 1)}{\gamma(u,v)}, \qquad m = 4$$

where
$$\beta(u,v)=(u^2+v^2-2)(u^2-3v^2)$$
, $\gamma(u,v)=(3u^2+3v^2-5)(u^2-2uv-v^2)(u^2+2uv-v^2)$. Then

$$\begin{split} \hat{Q}_3(a,b,c) &= 9a^8 + 72a^6b^2 - 8a^6c^2 + 144a^4b^4 - 168a^4b^2c^2 \\ &- 96a^2b^4c^2 + 96a^2b^2c^4 + 64b^6c^2 - 48b^4c^4 - 72a^7 \\ &- 288a^5b^2 + 288a^5c^2 + 288a^3b^2c^2 - 192a^3c^4 + 144a^6 \\ \hat{Q}_4(a,b,c) &= -16a^{10} - 8640a^2b^2c^5 - 9000a^4b^4c - 3600a^2b^6c \\ &+ 12000a^2b^4c^3 + 570a^4b^4c^2 - 180a^2b^6c^2 + 15b^8c^2 - 900b^8 + 1440a^4c^5 \\ &+ 1440b^4c^5 - 5400a^4b^4 - 3600a^2b^6 + 900b^8c - 2400b^6c^3 - 416a^6b^4 \\ &- 416a^4b^6 + 176a^2b^8 - 16b^{10} + 12000a^4b^2c^3 - 3600a^6b^2c - 180a^6b^2c^2 \\ &- 3600a^6b^2 + 176a^8b^2 - 2400a^6c^3 + 900a^8c + 15a^8c^2 - 900a^8. \end{split}$$

Therefore, $cl(\mathfrak{B}_3) = 8$ and $cl(\mathfrak{B}_4) = 10$.

5.2. Degree and Class of Timelike \mathfrak{B}_2 , \mathfrak{B}_3 , \mathfrak{B}_4 in $\mathbb{R}^{2,1}$

From (2), the parametrization of \mathfrak{B}_2 (timelike Enneper surface) is

$$\mathfrak{B}_{2}(u,v) = \begin{pmatrix} u^{2} + v^{2} \\ u + v - \frac{1}{3}(u^{3} + v^{3}) \\ -u + v - \frac{1}{3}(u^{3} - v^{3}) \end{pmatrix} = \begin{pmatrix} x(u,v) \\ y(u,v) \\ z(u,v) \end{pmatrix}$$

where $u, v \in \mathbb{R}$. Then

$$\begin{split} Q_2(x,y,z) &= -16z^9 - 2916y^4z + 4374x^4y^2 - 6318y2x^2z^3 + 4374x^2y^4 \\ &- 15552y^2z^3 - 2916x^4z - 5832x^2y^2z - 20736z^5 + 1152z^7 - 8748x^4z^2 \\ &+ 8748y^4z^2 + 3888y^2z^5 - 3888x^2z^5 + 15552x^2z^3 + 1215x^4z^3 + 1458x^6 \\ &+ 216x^2z^6 + 1458y^6 + 1215y^4z^3 + 216y^2z^6 + 12960y^2z^4 + 12960x^2z^4. \end{split}$$

Its degree is $\deg(\mathfrak{B}_2)=9$. Hence, \mathfrak{B}_2 is an algebraic timelike minimal surface. To find the class of surface \mathfrak{B}_2 we obtain $P_2(u,v)=\frac{(uv+3)(u^2+v^2)}{3(uv+1)}$, and the inhomogeneous tangential coordinates are $a=-\frac{(uv-1)(3uv+3)}{\hat{\alpha}(u,v)},\ b=-\frac{(u+v)(3uv+3)}{\hat{\alpha}(u,v)},\ c=-\frac{(u-v)(3uv+3)}{\hat{\alpha}(u,v)}$, where $\hat{\alpha}(u,v)=(uv+1)(uv+3)(u^2+v^2)$. Then

$$\hat{Q}_2(a,b,c) = 16a^6 + 9a^4 + 36b^4c + 24a^2c^3 + 24b^2c^3 - 24a^2b^2c^2 -12a^4c^2 - 16a^2b^4 - 12b^4c^2 - 36a^4c + 16a^4b^2 + 9b^4 - 16b^6 - 18a^2b^2.$$

Hence, $cl(\mathfrak{B}_2) = 6$. Similarly

$$\mathfrak{B}_{3}\left(u,v\right) = \begin{pmatrix} \frac{2}{3}\left(u^{3}+v^{3}\right) \\ \frac{1}{2}\left(u^{2}+v^{2}\right) - \frac{1}{4}\left(u^{4}+v^{4}\right) \\ -\frac{1}{2}\left(u^{2}-v^{2}\right) - \frac{1}{4}\left(u^{4}-v^{4}\right) \end{pmatrix} = \begin{pmatrix} x(u,v) \\ y(u,v) \\ z(u,v) \end{pmatrix}$$

$$\mathfrak{B}_{4}(u,v) = \begin{pmatrix} \frac{1}{2} \left(u^{4} + v^{4} \right) \\ \frac{1}{3} \left(u^{3} + v^{3} \right) - \frac{1}{5} \left(u^{5} + v^{5} \right) \\ -\frac{1}{3} \left(u^{3} - v^{3} \right) - \frac{1}{5} \left(u^{5} - v^{5} \right) \end{pmatrix} = \begin{pmatrix} x(u,v) \\ y(u,v) \\ z(u,v) \end{pmatrix}$$

and

$$\begin{split} Q_3(x,y,z) &= 43046721z^{16} - 1836660096z^{14} \\ &+ 5435817984x^6z^4 + 602404356096x^4z^8 \\ &+ 165112971264x^2z^8 + (69 \text{ other lower order terms}) \\ Q_4(x,y,z) &= 311836912602146628334544598941564928z^{25} \\ &- 3806602937037922709161921373798400000x^4z^{20} \\ &- 22839617622227536254971528242790400000x^2y^2z^{20} \\ &- 3806602937037922709161921373798400000y^4z^{20} \\ &- 2718338279012676739330717777920000000000x^8z^{15} \\ &+ (233 \text{ other lower order terms}). \end{split}$$

So $deg(\mathfrak{B}_3) = 16$, $deg(\mathfrak{B}_4) = 25$. In the tangential coordinates a, b, c

$$\begin{split} \hat{Q}_3(a,b,c) &= 81a^6b^2 - 27a^4b^4 - 72a^4b^2c^2 - 45a^2b^6 - 48a^2b^4c^2 - 9b^8 \\ &- 8b^6c^2 - 108a^6b + 180a^4b^3 + 432a^4bc^2 - 36a^2b^5 - 288a2b^3c^2 - 288a^2bc^4 \\ &- 36b^7 - 144b^5c^2 - 96b^3c^4 + 36a^6 - 108a^4b^2 + 108a^2b^4 - 36b^6 \\ \hat{Q}_4(a,b,c) &= -16a^{10} + 16b^{10} - 450a^8c + 15b^8c^2 - 225b^8 - 720a^4c^5 \\ &- 1350a^4b^4 + 900a^2b^6 - 450b^8c - 1200b^6c^3 - 416a^6b^4 + 416a^4b^6 \\ &+ 176a^2b^8 - 4320a^2b^2c^5 + 4500a^4b^4c - 1800a^2b^6c - 6000a^2b^4c^3 \\ &+ 570a^4b^4c^2 + 180a^2b^6c^2 + 6000a^4b^2c^3 - 1800a^6b^2c + 180a^6b^2c^2 \\ &- 225a^8 - 720b^4c^5 + 900a^6b^2 - 176a^8b^2 + 1200a^6c^3 + 15a^8c^2. \end{split}$$

Therefore, $cl(\mathfrak{B}_3) = 8$, $cl(\mathfrak{B}_4) = 10$.

Remark 8. It is clear that deg(x) = m, deg(y) = m + 1, deg(z) = m + 1 for Bour's algebraic maximal and timelike \mathfrak{B}_m .

Acknowledgements

The authors thank Wayne Rossman for helpful discussions and Christos Konaxis for assisting with Maple code. The first author was supported by the 2219-TUBITAK International Post Doctoral Research Fellowship Programme, and the third author was supported by the Grant-in-Aid for JSPS Fellows Number 26-3154.

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