## $W_{\delta}$ (T) IS CONVEX

## J. KYLE

Stampfli introduced a generalization of the numerical range for any bounded linear operator T on a Hilbert space  $\mathscr{H}$ . This is denoted by  $W_{\delta}(T)$  and is defined by

$$W_{\delta}(T) =$$
closure  $\{\langle Tx, x \rangle : ||\mathbf{x}|| = 1 \text{ and } ||Tx|| \geq \delta \}$ .

Stampfli asked whether  $W_{\delta}(T)$  is convex. In this short note we provide an affirmative answer to this question.

 $\mathscr{L}(\mathscr{H})$  will denote the set of bounded linear operators on the Hilbert space  $\mathscr{H}$ .

LEMMA 1. Suppose S and A belong to  $\mathcal{L}(\mathcal{H})$ , and that  $S=S^*$ . Then

$$S(A,\,\delta)=\{x\in\mathscr{H}\colon ||\,x\,||=1 \quad ext{and} \quad ||\,Ax\,||\geqq\delta \quad ext{and} \quad \langle Sx,\,x
angle=0\}$$
 is path connected.

*Proof.* Suppose x and y belong to  $S(A, \delta)$ . We may assume that x and y are linearly independent. (If not, they both lie on an arc of

$$\{e^{i\theta}x: 0 \le \theta \le 2\pi\}$$

which lies in  $S(A, \delta)$  if x does.)

Choose  $\theta$  in R such that  $e^{i\theta}\langle Sx,y\rangle$  is purely imaginary and let  $a=e^{i\theta}x$ .

Choose n such that  $(-1)^n Re \langle (A^*A - \delta^2 I)a, y \rangle$  is positive and let  $b = (-1)^n y$ . Then a and b may be joined by a path in  $S(A, \delta)$  to x and y respectively. Thus we need only find a path connecting a to b. Let y(t) = ta + (1-t)b and let  $x(t) = ||y(t)||^{-1}y(t)$ . Then  $\langle Sx(t), x(t) \rangle = 0 \Leftrightarrow \langle Sy(t), y(t) \rangle = 0$  and

$$egin{aligned} \langle Sy(t),\,y(t)
angle &=t^2\langle Sa,\,a
angle +(1-t)^2\langle Sb,\,b
angle \ &+2Ret(1-t)\langle Sa,\,b
angle \ &=2(-1)^nt(1-t)Ree^{i heta}\langle Sx,\,y
angle \ &=0 \;. \end{aligned}$$

Also

$$egin{aligned} ||Ay(t)||^2 &= \langle A^*Ay(t), y(t) 
angle \ &= t^2 \, ||Aa||^2 + (1-t)^2 ||Ab||^2 \ &+ 2t(1-t)Re \langle A^*Aa,b 
angle \end{aligned}$$

484 J. KYLE

$$egin{aligned} & \geq \delta^2(t^2 + (1-t)^2 + 2Ret(1-t)\langle a,b 
angle) \ & + 2t(1-t)Re\langle (A^*A - \delta^2I)a,b 
angle \ & = \delta^2 ||y(t)||^2 \ & + 2t(1-t)(-1)^*Re\langle (A^*A - \delta^2I)a,y 
angle \ & \geq \delta^2 ||y(t)||^2 \ . \end{aligned}$$

Hence  $||Ax(t)|| \ge \delta$  and so  $t \to x(t)$  is a path connecting a to b in  $S(A, \delta)$  as required.

LEMMA 2. Suppose H and K are self-adjoint elements in  $\mathcal{L}(\mathcal{H})$ . Let

$$V(A, \delta) = \{(\langle Hx, x \rangle, \langle Kx, x \rangle) : ||x|| = 1 \text{ and } ||Ax|| \ge \delta \}$$
.

Then  $V(A, \delta)$  is a convex subset of  $\mathbb{R}^2$ .

*Proof.* We need only show that  $V(A, \delta) \cap L$  is connected whennever L is a straight line in  $\mathbb{R}^2$ . Suppose L is given by

$$\alpha \xi + \beta \eta + \gamma = 0$$
.

Let

$$S = \alpha H + \beta K + \gamma I$$
.

Then the mapping  $\pi$ , given by

$$\pi(x)=(\langle Hx,x
angle,\ \langle Kx,x
angle)$$
 is continuous, and  $S(A,\delta)=\{x\colon ||x||=1;\ ||Ax||\geqq\delta \ ext{and}\ \pi(x)\in L\}$  .

Thus  $V(A, \delta) \cap L = \pi(S(A, \delta))$  is connected.

THEOREM 3. Suppose T and A are in  $\mathcal{L}(\mathcal{H})$ . Then

$$V(T; A, \delta) = \{\langle Tx, x \rangle : ||x|| = 1 \text{ and } ||Ax|| \ge \delta\}$$

is convex.

*Proof.* Suppose T = H + iK with H and K both self-adjoint. Then

$$V(T; A, \delta) = \{ \xi + i\eta : (\xi, \eta) \in V(A, \delta) \}$$
.

Hence  $V(T; A, \delta)$  is convex.

COROLLARY 4.  $W_{\delta}(T)$  is convex.

*Proof.* Take A = T. Indeed we have shown that

$$\{\langle Tx, x \rangle : ||x|| = 1 \text{ and } ||Tx|| \ge \delta\}$$

is convex.

REMARK. It will be noticed that the ideas here are improvements on basic ideas in 1.

## REFERENCES

- 1. N. P. Dekker, Joint numerical range and joint spectrum of Hilbert space operators, Thesis, University of Amsterdam, 1969.
- 2. J. G. Stampfli, The norm of a derivation, Pacific J. Math., 33 (1970), 737-747.

Received February 15, 1977.

University of Technology Loughborough Leicestershire, England