A CLASS OF RIEMANNIAN MANIFOLDS SATISFYING $R(X,Y) \cdot R = 0$

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1. Introduction

Let (M, g) be a Riemannian manifold and let R be its Riemannian curvature tensor. If (M, g) is a locally symmetric space, we have

(*)
$$R(X,Y) \cdot R = 0$$
 for all tangent vectors X,Y

where the endomorphism R(X,Y) (i.e., the curvature transformation) operates on R as a derivation of the tensor algebra at each point of M. There is a question: Under what additional condition does this algebraic condition (*) on R imply that (M,g) is locally symmetric (i.e., $\nabla R = 0$)? A conjecture by K. Nomizu [5] is as follows: (*) implies $\nabla R = 0$ in the case where (M,g) is complete and irreducible, and dim $M \ge 3$. He gave an affirmative answer in the case where (M,g) is a certain complete hypersurface in a Euclidean space ([5]).

With respect to this problem, K. Sekigawa and H. Takagi [8] proved that if (M, g) is a complete conformally flat Riemannian manifold with dim $M \ge 3$ and satisfies (*), then (M, g) is locally symmetric.

On the other hand, R.L. Bishop and B.O'Neill [1] constructed a wide class of Riemannian manifolds of negative curvature by warped product using convex functions. For two Riemannian manifolds B and F, a warped product is denoted by $B \times_f F$, where f is a positive C^{∞} -function on B. The purpose of this paper is to prove

THEOREM A. Let (F,g) be a Riemannian manifold of constant curvature $K \leq 0$. Let E^n be an n-dimensional Euclidean space and let f be a positive C^{∞} -function on E^n . On a warped product $E^n \times {}_f F$, assume that

- (i) the condition (*) is satisfied, and
- (ii) the scalar curvature is constant.

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Then $E^n \times {}_{t}F$ is locally symmetric. The converse is clear.

In theorem A, if $n \ge 2$, we see that $E^n \times {}_f F$ is not of constant curvature. If n = 1, we have

THEOREM B. Let (F,g) be a Riemannian manifold of constant curvature $K \leq 0$. Let E^1 be a Euclidean 1-space and let f be a non-constant positive C^{∞} -function on E^1 . Then $E^1 \times_f F$ satisfies the condition (*) if and only if $E^1 \times_f F$ is of constant curvature.

Concerning theorem B, it is remarked that, as is stated in [1], p. 28, a hyperbolic *m*-space is expressed as $H^m = E^1 \times_f E^{m-1}$ for $f = e^t$ or $= E^1 \times_f H^{m-1}$ for $f = \cosh t$.

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2. The Riemannian curvature tensor of $E^n \times {}_{f}F$

Let (F,g) be a Riemannian manifold and let E^n be a Euclidean n-space. We consider the product manifold $E^n \times F$. For vector fields A, B, C, etc. on E^n , we denote vector fields (A,0), (B,0), (C,0), etc. on $E^n \times F$ by also A, B, C, etc. Likewise, for vector fields X, Y, etc. on F, we denote vector fields (0,X), (0,Y), etc. on $E^n \times F$ by X, Y, etc.

We denote the inner product of A and B on E^n by $\langle A, B \rangle$. Let f be a positive C^n -function on E^n . Then the (Riemannian) inner product \langle , \rangle for A+X and B+Y on the warped product $E^n \times {}_{f}F$ at (a,x) is given by (cf. [1])

$$(2.1) \qquad \langle A+X, B+Y \rangle_{(a,x)} = \langle A, B \rangle_{(a)} + f^2(a)g_x(X,Y).$$

We extend the function f on E^n to that on $E^n \times_f F$ by f(a, x) = f(a). The Riemannian connections defined by \langle , \rangle on E^n and $E^n \times_f F$ are denoted by ∇^0 and ∇ , respectively. The Riemannian connection defined by g on F is denoted by D. Then we have the identities (cf. Lemma 7.3, [1])

$$\nabla_A B = \nabla_A^0 B,$$

$$\nabla_A X = \nabla_X A = (Af/f)X,$$

$$\nabla_{\mathbf{X}} Y = D_{\mathbf{X}} Y - (\langle X, Y \rangle / f) \text{ grad } f.$$

By (2.2) we identify ∇^0 with ∇ in the sequel. In (2.4) grad f on E^n is identified with grad f on $E^n \times {}_f F$ and we have

$$\langle \operatorname{grad} f, A \rangle = df(A) = Af$$
.

The Riemannian curvature tensors by ∇ and D are denoted by R and S respectively. We use both notations R(X,Y) and R_{XY} , etc.:

$$R(X,Y) = R_{XY} = \nabla_{[X,Y]} - [\nabla_X, \nabla_Y], \text{ etc.}$$

Then, noticing that E^n is flat, we have (cf. Lemma 7.4, [1])

$$(2.5) R_{AB}C = 0,$$

$$(2.6) R_{AX}B = -(1/f)\langle \nabla_A \operatorname{grad} f, B \rangle X,$$

$$(2.7) R_{AB}X = R_{XY}A = 0,$$

$$(2.8) R_{AX}Y = R_{AY}X = (1/f) \langle X, Y \rangle \nabla_A \operatorname{grad} f,$$

$$(2.9) R_{XY}Z = S_{XY}Z - (\langle \operatorname{grad} f, \operatorname{grad} f \rangle / f^2) (\langle X, Z \rangle Y - \langle Y, Z \rangle X).$$

3. The condition (*)

From now on (§ $3 \sim \S 8$) we assume that (F, g) is of constatn curvature $K \leq 0$. Then we have

$$\begin{split} S_{XY}Z &= K\left(g(X,Z)Y - g(Y,Z)X\right) \\ &= (K/f^2)\left(\langle X,Z\rangle Y - \langle Y,Z\rangle X\right). \end{split}$$

In this case, (2.9) is written as

$$(3.1) R_{XY}Z = P(\langle X, Z \rangle Y - \langle Y, Z \rangle X),$$

where we have put

$$(3.2) P = (K - \langle \operatorname{grad} f, \operatorname{grad} f \rangle)/f^2 \leq 0.$$

Now by definition we have

$$(R(X,Y)\cdot R)(Z,V)W = R_{XY}R_{ZY}W - R(R_{XY}Z,V)W - R(Z,R_{XY}V)W - R_{ZY}R_{XY}W$$

which vanishes by (3.1). Likewise, by $(2.5) \sim (2.8)$, (3.1), we have

$$(R(X,Y) \cdot R) (Z,A)W = 0,$$

$$(R(X,Y) \cdot R) (Z,B)A = 0,$$

$$(R(X,Y) \cdot R) (C,B)A = 0,$$

from which we have

$$(R(X,Y)\cdot R)(A,Z)W = -(R(X,Y)\cdot R)(Z,A)W = 0,$$

$$(3.3) \qquad (R(X,Y) \cdot R) (Z,W) A = -(R(X,Y) \cdot R) (A,Z) W - (R(X,Y) \cdot R) (W,A) Z = 0,$$

$$(3.4) (R(X,Y) \cdot R) (C,B)W = -(R(X,Y) \cdot R) (W,C)B - (R(X,Y) \cdot R) (B,W)C = 0.$$

Next, by similar calculations we have

$$(3.5) \qquad (R(X,A)\cdot R)\,(Z,V)W = \\ (fP\,\nabla_A\,\mathrm{grad}\,f + \nabla_Q\,\mathrm{grad}\,f)\,(\langle V,W\rangle\,\langle X,Z\rangle - \langle Z,W\rangle\,\langle X,V\rangle)/f^2,$$

where we have put $Q = \nabla_A \operatorname{grad} f$.

$$(R(X, A) \cdot R) (Z, B)W = (\langle fP \nabla_A \operatorname{grad} f, B \rangle + \langle \nabla_A \operatorname{grad} f, \nabla_B \operatorname{grad} f \rangle) (\langle X, W \rangle Z - \langle Z, W \rangle X)/f^2,$$

$$(3.7) \qquad (R(X,A)\cdot R)\,(Z,B)C = \\ \langle X,Z\rangle\,(\langle\nabla_B\operatorname{grad} f,C\rangle\,\nabla_A\operatorname{grad} f - \langle\nabla_A\operatorname{grad} f,C\rangle\,\nabla_B\operatorname{grad} f)/f^2,$$

$$(R(X,A) \cdot R) (C,B)G =$$

$$(\langle \nabla_A \operatorname{grad} f, B \rangle \langle \nabla_G \operatorname{grad} f, G \rangle - \langle \nabla_A \operatorname{grad} f, C \rangle \langle \nabla_B \operatorname{grad} f, G \rangle)X/f^2.$$

Finally we have $R(A, B) \cdot R = 0$, since $R_{AB} = 0$.

LEMMA 3.1. On $E^n \times {}_{t}F$, the condition (*) is equivalent to

(3.9)
$$fP \nabla_A \operatorname{grad} f + \nabla_Q \operatorname{grad} f = 0$$
, $Q = \nabla_A \operatorname{grad} f$, and

$$(3.10) \langle \nabla_B \operatorname{grad} f, C \rangle \nabla_A \operatorname{grad} f = \langle \nabla_A \operatorname{grad} f, C \rangle \nabla_B \operatorname{grad} f.$$

Proof. $R(X,Y) \cdot R = 0$ and $R(A,B) \cdot R = 0$ hold always. If (*) holds, then (3.5) and (3.7) imply (3.9) and (3.10). Conversely, (3.5) and (3.9) imply $(R(X,A) \cdot R) (Z,V)W = 0$. Since

$$\langle \nabla_Q \operatorname{grad} f, B \rangle = \langle \nabla_B \operatorname{grad} f, Q \rangle$$

= $\langle \nabla_B \operatorname{grad} f, \nabla_A \operatorname{grad} f \rangle$,

(3.6) and (3.9) imply $(R(X,A) \cdot R) (Z,B)W = 0$. (3.7) and (3.10) imply $(R(X,A) \cdot R) (Z,B)C = 0$. Similarly, (3.8) and (3.10), together with the fact that $\langle \nabla_A \operatorname{grad} f, B \rangle = \langle \nabla_B \operatorname{grad} f, A \rangle$, imply $(R(X,A) \cdot R) (C,B)G = 0$. Finally we have $(R(X,A) \cdot R) (Z,V)B = 0$ and $(R(X,A) \cdot R) (C,B)W = 0$ in the same way as (3.3) and (3.4).

4. The condition for $\nabla R = 0$

Using the identity

$$(\nabla_{\mathbf{X}}R)(Y,Z)W = \nabla_{\mathbf{X}}(R_{YZ}W) - R(\nabla_{\mathbf{X}}Y,Z)W - R(Y,\nabla_{\mathbf{X}}Z)W - R_{YZ}(\nabla_{\mathbf{X}}W),$$

together with (2.3), (2.4) and (2.8), we get

$$(4.1) \qquad (\nabla_X R) (Y, Z) W =$$

$$(\langle X,Y\rangle\langle Z,W\rangle - \langle X,Z\rangle\langle Y,W\rangle)(fP\operatorname{grad} f + \nabla_{\operatorname{grad} f}\operatorname{grad} f)/f^2,$$

where we have used $\nabla_x P = XP = 0$. Similarly we get

$$\begin{aligned} \left(\nabla_{X} R \right) (A,Y) W &= \\ \left(\left(\nabla_{A} \operatorname{grad} f \right) f + f P A f \right) \left(\langle Y,W \rangle X - \langle X,W \rangle Y \right) / f^{2}, \end{aligned}$$

$$\langle Y, W \rangle (f \nabla_A \nabla_B \operatorname{grad} f - f \nabla_T \operatorname{grad} f - Af \nabla_B \operatorname{grad} f) / f^2, \quad T = \nabla_A B,$$

$$(\nabla_X R) (Y, A) B =$$

$$\langle X, Y \rangle (Bf \nabla_A \operatorname{grad} f - \langle \nabla_A \operatorname{grad} f, B \rangle \operatorname{grad} f) / f^2,$$

$$(\nabla_{A}R) (B, X)C =$$

$$(Af \langle \nabla_{B} \operatorname{grad} f, C \rangle + f \langle \nabla_{T} \operatorname{grad} f, C \rangle - f \langle \nabla_{A}\nabla_{B} \operatorname{grad} f, C \rangle)X/f^{2}.$$

LEMMA 4.1. On $E^n \times {}_{t}F$, $\nabla R = 0$ if and only if

(4.6)
$$fP \operatorname{grad} f + \nabla_{\operatorname{grad} f} \operatorname{grad} f = 0$$
,

(4.7)
$$f \nabla_A \nabla_B \operatorname{grad} f - f \nabla_T \operatorname{grad} f - A f \nabla_B \operatorname{grad} f = 0, T = \nabla_A B, \text{ and}$$

(4.8)
$$Bf \nabla_A \operatorname{grad} f - \langle \nabla_A \operatorname{grad} f, B \rangle \operatorname{grad} f = 0.$$

Proof. Necessity comes from (4.1), (4.3) and (4.4). Conversely, assume that (4.6) \sim (4.8) hold. Then, we have $(\nabla_X R)(Y, Z)W=0$ and $(\nabla_A R)(B, Y)W=0$ by (4.1) and (4.3). We take the inner products of A and both sides of (4.6) to get

$$0 = f P A f + \langle \nabla_{\operatorname{grad} f} \operatorname{grad} f, A \rangle$$
$$= f P A f + \langle \nabla_{A} \operatorname{grad} f, \operatorname{grad} f \rangle$$
$$= f P A f + (\nabla_{A} \operatorname{grad} f) f.$$

Therefore, we have $(\nabla_X R)(A,Y)W=0$ by (4.2). Next we take the inner products of C and both sides of (4.7). Then we have $(\nabla_A R)(B,X)C=0$ by (4.5). By (4.4) and (4.8) we have $(\nabla_X R)(Y,A)B=0$. These, together with the first and second Bianchi identities, imply $(\nabla_X R)(Y,W)A=(\nabla_A R)(X,Y)W=(\nabla_A R)(Y,W)B=(\nabla_Y R)(A,B)W=(\nabla_X R)(A,B)C=(\nabla_A R)(B,C)X=0$. Finally, $(\nabla_A R)(B,C)G=0$ follows from (2.5).

5. The scalar curvature

In this section, we obtain the expression of the scalar curvature. Let $(A_{\alpha}, X_i; \alpha = 1, \dots, n; i = 1, \dots, r = \dim F)$ be vector fields on some open set

on $E^n \times F$ such that they make an orthonormal basis at each point of the open set. We denote by R_1 the Ricci curvature tensor. Then we have

$$R_1(Y,Z) = \sum_i \langle R(Y,X_i)Z, X_i \rangle + \sum_{\alpha} \langle R(Y,A_{\alpha})Z, A_{\alpha} \rangle$$

which is calculated by (2.8) and (3.1), and we get

$$\begin{split} R_{1}(Y,Z) &= P \sum_{i} \langle \langle Y,Z \rangle X_{i} - \langle X_{i},Z \rangle Y, X_{i} \rangle \\ &+ \sum_{a} \langle - (1/f) \langle Z,Y \rangle \nabla_{A_{\alpha}} \operatorname{grad} f, A_{\alpha} \rangle \\ &= \left[(r-1) P - (1/f) \sum_{a} \langle \nabla_{A_{\alpha}} \operatorname{grad} f, A_{\alpha} \rangle \right] \langle Y,Z \rangle, \end{split}$$

where we have used

$$\sum_{i} \langle \langle X_i, Z \rangle Y, X_i \rangle = \sum_{i} \langle Y, X_i \rangle \langle X_i, Z \rangle$$
$$= \sum_{i} \langle \langle Y, X_i \rangle X_i, Z \rangle = \langle Y, Z \rangle.$$

Similarly we have

$$R_1(B, C) = \sum_i \langle R(B, X_i)C, X_i \rangle + \sum_{\alpha} \langle R(B, A_{\alpha})C, A_{\alpha} \rangle$$

= $-(r/f) \langle \nabla_B \operatorname{grad} f, C \rangle$.

Therefore we get

The scalar curvature $= \sum_{i} R_1(X_i, X_i) + \sum_{\alpha} R_1(A_\alpha, A_\alpha)$

$$(5.1) = r[(r-1)P - (2/f)\sum_{\alpha}\langle \nabla_{A_{\alpha}} \operatorname{grad} f, A_{\alpha}\rangle].$$

6. Two lemmas

LEMMA 6.1. On $E^n \times {}_f F$, (4.6) is equivalent to P = constant.

Proof. By (3.2) and (4.6) we have

$$(1/f)(K - \langle \operatorname{grad} f, \operatorname{grad} f \rangle) \operatorname{grad} f + \nabla_{\operatorname{grad} f} \operatorname{grad} f = 0.$$

Since this equation is considered as an equation on E^n , we introduce the natural coordinate symtem $(x^{\alpha}; \alpha = 1, \dots, n)$ on E^n . Then the last equation is nothing but

$$\left(K - \sum_{\alpha} \frac{\partial f}{\partial x^{\alpha}} - \frac{\partial f}{\partial x^{\alpha}}\right) - \frac{\partial f}{\partial x^{\beta}} + f \sum_{\alpha} \frac{\partial^{2} f}{\partial x^{\alpha} \partial x^{\beta}} - \frac{\partial f}{\partial x^{\alpha}} = 0,$$

which implies that each partial derivative of

(6.1)
$$P = \left[K - \sum_{\alpha} \left(\frac{\partial f}{\partial x^{\alpha}}\right)^{2}\right] / f^{2}$$

vanishes. Thus, P is constant. The converse is clear.

Lemma 6.2. On $E^n \times_f F$, if the condition (*) is satisfied and the scalar curvature is constant, then P is constant.

Proof. If f is constant, Lemma 6.2 is trivial. Therefore we assume that f is not constant. We put $A = \partial/\partial x^a$, $B = \partial/\partial x^\beta$ and $C = \partial/\partial x^r$, which are parallel on E^n . Then (3.9) and (3.10) are written as

$$(6.2) fP \frac{\partial^2 f}{\partial x^a \partial x^b} + \sum_{\theta} \frac{\partial^2 f}{\partial x^{\theta} \partial x^b} \frac{\partial^2 f}{\partial x^{\theta} \partial x^a} = 0,$$

(6.3)
$$\frac{\partial^2 f}{\partial x^{\beta} \partial x^{\tau}} - \frac{\partial^2 f}{\partial x^{\alpha} \partial x^{\delta}} = \frac{\partial^2 f}{\partial x^{\alpha} \partial x^{\tau}} - \frac{\partial^2 f}{\partial x^{\beta} \partial x^{\delta}}.$$

Summing with respect to α and γ in (6.3), and substituting the result into (6.2), we have

(6.4)
$$\left(fP + \sum_{\theta} \frac{\partial^2 f}{\partial x^{\theta} \partial x^{\theta}} \right) \frac{\partial^2 f}{\partial x^{\theta} \partial x^{\theta}} = 0.$$

Define a subset Θ of E^n by

$$\Theta = \left\{ x \in E^n \; ; \left(\frac{\partial^2 f}{\partial x^a \partial x^b} \right)(x) = 0 \; \text{ for all } \; \alpha, \; \delta \right\}.$$

Let Θ_0 be a component of Θ . If Θ_0 contains an open set, f is of the form $f = a_{\alpha}x^{\alpha} + b$ on the interior of Θ_0 for some constant a_{α} , b (if the same letter appears as a subscript and as a superscript, we abbreviate Σ). Since f is positive and C^{∞} -differentiable, $\Psi = E^n - \Theta = E^n \cap \Theta^c$ can not be empty. Since Θ is closed, Ψ is a non-empty open set. On Ψ we have

(6.5)
$$f P + \sum_{\alpha} \frac{\partial^2 f}{\partial x^{\alpha} \partial x^{\alpha}} = 0.$$

On the other hand, the scalar curvature is given by (5.1), which is also written as

(6.6) the scalar curvature =
$$r \left[(r-1)P - (2/f) \sum_{\alpha} \frac{\partial^2 f}{\partial x^{\alpha} \partial x^{\alpha}} \right]$$
.

By (6.5) and (6.6), we get

(6.7)
$$r(r+1)P = \text{the scalar curvature} = \text{constant},$$

which shows that P is constant on Ψ .

On Θ_0 , if $a_{\alpha} = 0$ for all $\alpha = 1, \dots, n$, then P is constant on Θ_0 too. So we assume that at least one of a_{α} is not zero. Then, by (6.1) and $K \leq 0$,

we get

(6.8)
$$P = (K - \sum_{\alpha} a_{\alpha}^{2})/(a_{\beta}x^{\beta} + b)^{2} < 0.$$

We easily see that the function P on Θ_0 given by (6.8) can not be C^{∞} -differentiably extended to P on $\Theta_0 \cup \Psi$ so that P is constant on Ψ . Therefore Θ can not contain any open set where f is not constant. Hence, we have (6.7) on E^n .

7. Proof of Theorem A

Since $E^n \times_f F$ satisfies the condition (*) and the scalar curvature is constant, P is constant by Lemma 6.2. By Lemma 6.1 we see that (4.6) is equivalent to (6.1) with P = constant. Now we solve (6.1) and show that the solution f satisfies (4.7) and (4.8). Then $E^n \times_f F$ is locally symmetric by Lemma 4.1. (6.1) is

(7.1)
$$K - \sum_{\alpha} \left(\frac{\partial f}{\partial x^{\alpha}} \right)^{2} - P f^{2} = 0.$$

We solve the last partial differential equation by Lagrange-Charpit method. First we put

$$p_{\alpha}=\frac{\partial f}{\partial x^{\alpha}}, \quad \alpha=1, \cdot \cdot \cdot, n.$$

Then the characteristic differential equations of (7.1) are

(7.2)
$$\frac{dx^{1}}{-2p_{1}} = \frac{dx^{2}}{-2p_{2}} = \cdots = \frac{dx^{n}}{-2p_{n}}$$

$$= \frac{df}{-2(p_{1})^{2} - \cdots - 2(p_{n})^{2}}$$

$$= \frac{-dp_{1}}{-2f P p_{1}} = \cdots = \frac{-dp_{n}}{-2f P p_{n}}.$$

If f is constant, Theorem A is trivial. Hence, we assume that f is not constant. Then at least one of p_1, \dots, p_n does not vanish. So we assume $p_1 \neq 0$ (locally, if necessary) and furthermore we can assume that p_1 is positive. In this case, the last (n-1) equations of (7.2) give the first integrals

$$p_{\alpha} = s_{\alpha} p_{1}, \quad \alpha = 2, \cdots, n,$$

where s_{α} are constants. Then (7.1) is

$$K - (p_1)^2(1 + s_2^2 + \cdots + s_n^2) - P f^2 = 0.$$

If we put $s_1 = 1$, we have

$$p_1 = \left[rac{K - P f^2}{\sum_{lpha} S_{lpha}^2}
ight]^{1/2},$$

$$df = p_{lpha} dx^{lpha} = p_1 s_{lpha} dx^{lpha}.$$

Then we get

(7.3)
$$\frac{df}{[K-Pf^2]^{1/2}} = \frac{d(s_{\beta}x^{\beta})}{[\sum s_{\alpha}^2]^{1/2}}.$$

By putting $[K - P f^2]^{1/2} = \sqrt{-P} f + y$, we have

$$f = \frac{K - y^2}{2\sqrt{-P}y},$$

(7.5)
$$\frac{-(K+y^2)dy/(2\sqrt{-P}y^2)}{(K+y^2)/2y} = \frac{d(s_{\beta}x^{\beta})}{[\sum_{\alpha}s_{\alpha}^2]^{1/2}}.$$

Therefore we have

$$(7.6) y = b \exp \left[-(-P/\sum s_{\alpha}^{2})^{1/2} (s_{\beta} x^{\beta}) \right].$$

If we put $[-P/\sum s_a^2]^{1/2}s_{\beta} = c_{\beta}$, then, by (7.4) and (7.6), we have

(7.7)
$$f = \frac{1}{2\sqrt{-P}} \left[\frac{K}{b} \exp\left(c_{\beta}x^{\beta}\right) - b \exp\left(-c_{\beta}x^{\beta}\right) \right],$$

which is a solution of (7.1). Consequently, we see that f satisfies (4.7) and (4.8), which are written as

$$f \frac{\partial^{3} f}{\partial x^{\alpha} \partial x^{\beta} \partial x^{7}} - \frac{\partial f}{\partial x^{\alpha}} \frac{\partial^{2} f}{\partial x^{\beta} \partial x^{7}} = 0,$$

$$\frac{\partial f}{\partial x^{\beta}} \frac{\partial^{2} f}{\partial x^{\alpha} \partial x^{7}} - \frac{\partial^{2} f}{\partial x^{\alpha} \partial x^{\beta}} \frac{\partial f}{\partial x^{7}} = 0.$$

8. Proof of Theorem B

Assume that $E^1 \times {}_f F$ satisfies condition (*). Then (3.9) or (6.2) is written as

(8.1)
$$\left(f P + \frac{d^2 f}{dx^2} \right) \frac{d^2 f}{dx^2} = 0,$$

where x is the natural coordinate system of E^1 . Similarly as in §6, we define Θ and Ψ . Then on Ψ , by (6.1) and (8.1), we have

(8.2)
$$\left[K - \left(\frac{df}{dx}\right)^2\right] + f \frac{d^2f}{dx^2} = 0,$$

which implies that the derivative of $P = [K - (df/dx)^2]/f^2$ is zero so that P is constant on each component of Ψ . On the other hand, on an open interval contained in Θ , f is of the form f = cx + d for some constants c and d. Since P is C^{∞} -differentiable, Θ can not contain any open interval where f is not constant. Thus, P is constant on E^1 . Since f is non-constant, P is a negative constant. Now we have

$$K - \left(\frac{df}{dx}\right)^2 - Pf^2 = 0,$$

whose solution f is

$$f = \frac{1}{2\sqrt{-P}} \left[\frac{K}{b} \exp \sqrt{-P} \ x - b \exp \left(\sqrt{-P} \ x \right) \right]$$

where b < 0 is a constant. Then we have

$$\nabla_A \operatorname{grad} f = - f P A$$
,

and hence, (2.6), (2.8) are expressed as

(8.3)
$$R_{AX}B = (-1/f) < -PfA, B > X$$
$$= P(\langle A, B \rangle X - \langle X, B \rangle A),$$

(8.4)
$$R_{AX}Y = (1/f)\langle X, Y \rangle (-PfA)$$
$$= P(\langle A, Y \rangle X - \langle X, Y \rangle A).$$

Thus, (8.3), (2.7), (8.4) and (3.1) show that $E^1 \times_f F$ is of constant curvature P < 0.

9. Remarks

- (i) If (F, g) is a complete Riemannian manifold, then $E^n \times {}_f F$ is also a complete Riemannian manifold (cf. Lemma 7.2, [1]).
- (ii) Assume that (F,g) is of constant curvature K<0. If $(\partial^2 f/\partial x^a\partial x^\beta)$ is non-singular at some point of E^n and n is sufficiently small with respect to $r=\dim F$ (for example, n=2), then $E^n\times_f F$ is irreducible. In fact, by a result due to D. Montgomery and H. Samelson [3] we see that there is no proper subgroup of the orthogonal group 0(n+r) of order greater than (n+r-1)(n+r-2)/2, provided $n+r\neq 4$. On the other hand, the holonomy algebra is generated by (cf. [4])

$$R_{AX}$$
, R_{XY} , \cdots , etc.

which are given by $(2.5) \sim (2.8)$, (3.1). And under the circumstance stated above the restricted homogeneous holonomy group at the point is SO(n+r).

- (iii) It is an open question if one can get complete solutions of non-linear partial differential equations (6.1), (6.2) and (6.3) (i.e., the condition (*) on $E^n \times_f F$, $n \ge 2$). If one can get the complete solutions, then one sees whether the assumption on the scalar curvature is necessary or not in Theorem A.
 - (iv) The condition (*) is expressed in local coordinates as

$$\nabla_r \nabla_s R^h_{ijk} - \nabla_s \nabla_r R^h_{ijk} = 0.$$

In [6], K. Nomizu and H. Ozeki showed that if $\nabla \nabla R = 0$ (more generally, $\nabla^k R = 0$ for some k) on a (complete) Riemannian manifold, then $\nabla R = 0$.

(v) Studies concerning $R(X,Y) \cdot R$ were made also by A. Lichnerowich [2], p. 11, P. J. Ryan [7], K. Sekigawa and S. Tanno [9], J. Simons [10], S. Tanno and T. Takahashi [11], etc.

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