A free group of rotations with rational entries on the 3-dimensional unit sphere

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ABSTRACT. Dekker showed the existence of a free group of rank 2 of rotations (special orthogonal matrices) acting on the 3-dimensional unit sphere whose non-trivial rotations does not have a fixed point. In this paper, we find a free group on the 3-dimensional unit sphere which satisfies the same condition and whose entries of matrices are rational.

Introduction.

Banach and Tarski proved a very curious paradox which enables us to partition a golf ball into finite number of pieces and reconstruct the earth from these pieces:

Paradox A [BT,W]. If U and V are any bounded subsets of the 3-dimensional Euclidean space \mathbb{R}^3 , each having non-empty interior, then U and V can be both partitioned into the same finite number of respectively (orientation-preserving) congruent pieces. Formally,

$$U = \bigcup_{l=0}^{m-1} U_l$$
. $V = \bigcup_{l=0}^{m-1} V_l$,

 $U_l \cap U_{l'} = \emptyset = V_l \cap V_{l'}$ if $0 \leq l \leq l' \leq m$, and there are (orientation-preserving) isometries $\alpha_0, \ldots, \alpha_{m-1}$ such that, for each $0 \leq l \leq m$, $\alpha_l(U_l) = V_l$.

Paradox A owes the following paradox essentially:

Paradox B [Si,W]. The 2-dimensional unit sphere $\mathbb{S}^2 = \{\vec{r} \in \mathbb{R}^3 : |\vec{r}| = 1\}$ admits three decompositions into disjoint pieces

$$\mathbb{S}^2 = A_0 \cup \cdots \cup A_{p-1} \cup B_0 \cup \cdots \cup B_{q-1}.$$

$$\mathbb{S}^2 = A'_0 \cup \dots \cup A'_{p-1}, \quad and \quad \mathbb{S}^2 = B'_0 \cup \dots \cup B'_{q-1}.$$

and $A_i \approx A_i'$ (i = 0, 1, ..., p - 1). $B_j \approx B_j'$ (j = 0, 1, ..., q - 1), where $C \approx C'$ means $\gamma(C) = C'$ for a suitable rotation γ .

Robinson [R,W] constructed decompositions for p=q=2, which is the fewest piece's decompositions. For a given set E, it is a very important problem to find

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a free group of rank 2 acting on E whose element different from the identity has no fixed point. If such a free group exists, E has a Hausdorff decomposition (see [Sa0], etc.), i.e., E is partitioned into three subsets P, Q, and R such that

$$P \approx Q \approx R \approx P \cup Q \approx Q \cup R \approx R \cup P$$
.

The existence of a Hausdorff decomposition implies the existence of 2+2 pieces decompositions, but the converse is not always true. For example, the 2-dimensional unit sphere \mathbb{S}^2 does not have a Hausdorff decomposition because every non-trivial rotation has an axis. So such a free group on \mathbb{S}^2 does not exist. In higher dimensional space, does there exist a free group of rank 2 of rotations (special orthogonal matrices) on the 3-dimensional unit sphere $\mathbb{S}^3 = \{\vec{r} \in \mathbb{R}^4 : |\vec{r}| = 1\}$ whose elements distinct from the identity have no fixed point? Dekker [D,W] proved that there exists a free group of rank 2 on the 3-dimensional unit sphere \mathbb{S}^3 whose non-trivial rotations have no fixed point. So \mathbb{S}^3 has a Hausdorff decomposition. This paper proves the existence of such a free group on \mathbb{S}^3 whose entries of matrices are all rational numbers. We show affirmative answers of Problem A and Problem B of [Sa1] in the case of $n \equiv 0.3 \pmod{4}$.

Free Groups on the unit spheres.

The following is the main theorem in this paper which gives a concrete example of a pair of matrices with rational entries which generates a free group of rotations whose non-trivial element has no fixed point:

Theorem. Let σ , τ be rotations on \mathbb{S}^3 given, respectively, by

$$\frac{1}{7} \begin{pmatrix} 2 & -6 & -3 & 0 \\ 6 & 2 & 0 & 3 \\ 3 & 0 & 2 & -6 \\ 0 & -3 & 6 & 2 \end{pmatrix} \cdot \frac{1}{7} \begin{pmatrix} 2 & 0 & -3 & -6 \\ 0 & 2 & -6 & 3 \\ 3 & 6 & 2 & 0 \\ 6 & -3 & 0 & 2 \end{pmatrix}.$$

Then σ and τ generate freely a group of rotations such that no element of this group other than unity has any fixed point on \mathbb{S}^3 .

Proof. We denote the matrix
$$\begin{pmatrix} c & -x & -y & -z \\ x & c & -z & y \\ y & z & c & -x \\ z & -y & x & c \end{pmatrix}$$
 by $\begin{bmatrix} c \\ x \\ y \\ z \end{bmatrix}$ for $c, x, y, z \in \mathbb{R}$. Four

rotations in
$$H = \left\{ \begin{bmatrix} c \\ x \\ y \\ z \end{bmatrix} : c. \, x, y, z \in \mathbb{R} \right\}$$
 are defined by

$$s = \frac{1}{\sqrt{14}} \begin{bmatrix} 3\\2\\1\\0 \end{bmatrix}, t = \frac{1}{\sqrt{14}} \begin{bmatrix} 3\\0\\1\\2 \end{bmatrix}, \sigma = s^2, \text{ and } \tau = t^2.$$

It is enough to show that every non-empty reduced word w in $\{s^{-1}, s, t^{-1}, t\}$ has no fixed points on \mathbb{S}^3 . For $w = \begin{bmatrix} c_w \\ x_w \\ y_w \\ z_w \end{bmatrix}$, we prove $\det(w-1) \neq 0$. We define the

operation * on $K = \{(c, \begin{pmatrix} x \\ y \\ z \end{pmatrix}) : c, x, y, z \in \mathbb{R}\}$ by the following:

$$(c', \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix}) * (c, \begin{pmatrix} x \\ y \\ z \end{pmatrix}) = (c'c - x'x - y'y - z'z, \begin{pmatrix} x'c + c'x + y'z - z'y \\ y'c + c'y + z'x - x'z \\ z'c + c'z + x'y - y'x \end{pmatrix}).$$

Then (H, \cdot) is isomorphic to (K, *), so [Sa1] implies $x_w^2 + y_w^2 + z_w^2 \ge 0$. Hence we get

$$\det(w-1) = ((c_w-1)^2 + x_w^2 + y_w^2 + z_w^2)^2 \ge 0. \quad \Box$$

Theorem answers affirmatively Problem A in [Sa1] for n = 4k:

Corollary 1. $<\phi_{4k}, \psi_{4k}>$, the group generated by ϕ_{4k} and ψ_{4k} , is a free group of rotations such that all the elements of $<\phi_{4k}, \psi_{4k}>$ different from the identity have no fixed point on \mathbb{S}^{4k-1} , where

$$\phi_{4k} = \begin{pmatrix} \sigma & 0 & \dots & 0 \\ 0 & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \dots & 0 & \sigma \end{pmatrix} \quad and \quad \psi_{4k} = \begin{pmatrix} \tau & 0 & \dots & 0 \\ 0 & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \dots & 0 & \tau \end{pmatrix}.$$

Theorem and [Sa1] answer affirmatively Problem B of [Sa1] for n = 4k - 1:

Corollary 2. $<\phi_{4k-1}, \psi_{4k-1}>$ is a free group of rotations which has no non-trivial element fixing a point on $\mathbb{S}^{4k-2}\cap\mathbb{Q}^{4k-1}$ and is such that if two elements $f,g\in <\phi_{4k-1}, \psi_{4k-1}>$ have a common fixed point on \mathbb{S}^{4k-2} then fg=gf, where

$$\phi_{4k-1} = \begin{pmatrix} \mu & 0 & \dots & 0 \\ 0 & \sigma & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \dots & 0 & \sigma \end{pmatrix} \quad and \quad \psi_{4k-1} = \begin{pmatrix} \nu & 0 & \dots & 0 \\ 0 & \tau & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \dots & 0 & \tau \end{pmatrix}.$$

$$\mu = \frac{1}{7} \begin{pmatrix} 6 & 2 & 3 \\ 2 & 3 & -6 \\ -3 & 6 & 2 \end{pmatrix} \quad and \quad \nu = \frac{1}{7} \begin{pmatrix} 2 & -6 & 3 \\ 6 & 3 & 2 \\ -3 & 2 & 6 \end{pmatrix}.$$

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