# Generic submanifolds of an odd-dimensional sphere 

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Dedicated to professor Younki Chae on his 60th birthday

## Introduction

Submanifolds of a Sasakian manifold were investigated from two different points of view, namely, one is the case where submanifolds are tangent to the structure vector, and the other is the case where those are normal to the structure vector [3], [6], [7] etc. But, without these considerations generic submanifolds of a Sasakian manifold are defined as follows : Let $M$ be a submanifold of a Sasakian manifold $\tilde{M}$ with almost contact metric structure ( $\phi, G, V$ ). If each normal space is mapped into the tangent space under the action of $\phi, M$ is called a generic submanifold of $\tilde{M}[4]$. For example, hypersurfaces of a Sasakian manifold are generic.

The purpose of the present paper is to investigate generic submanifolds of an odd-dimensional sphere with nonvanishing parallel mean curvature vector.

In $\S 1$, we state general formulas on generic submanifolds of a Sasakian manifold. $\S 2$ is devoted to the study a generic submanifold of a Sasakian manifold, which is not tangent to the structure vector. Moreover, we suppose that the shape operator in the direction of the mean curvature vector commutes with the structure tensor induced on the submanifold. In $\S 3$ we study generic submanifolds which is not tangent to the structure vector of an odd-dimensional unit sphere with nonvanishing parallel mean curvature vector. In $\S 4$, we consider generic submanifolds, tangent to the structure vector, of an odd-dimensional sphere and compute the restricted Laplacian

[^0]for the shape operator in the direction of the mean curvature vector. As applications of these, in the last $\S 5$ we prove our main results.

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## 1. Generic submanifolds of a Sasakian manifold

In this section, the fundamental properties of generic submanifolds of a Sasakian manifold are recalled [4], [7].

Let $\tilde{M}$ be a Sasakian manifold of dimension $2 m+1$ with almost contact metric structure $(\phi, G, V)$. Then for any vector fields $X$ and $Y$ on $\tilde{M}$, we have

$$
\begin{gathered}
\phi^{2} X=-X+v(X) V, G(\phi X, \phi Y)=G(X, Y)-v(X) v(Y) \\
v(\phi X)=0, \phi V=0, v(V)=1, G(X, V)=v(X)
\end{gathered}
$$

Since $\tilde{M}$ is a Sasakian manifold, we then have

$$
\begin{equation*}
\tilde{\nabla}_{X} V=\phi X, \quad\left(\tilde{\nabla}_{X} \phi\right) Y=-G(X, Y) V+v(Y) X \tag{1.1}
\end{equation*}
$$

where $\tilde{\nabla}$ denotes the Riemannian connection of $\tilde{M}$.
Let $M$ be an ( $\mathrm{n}+1$ )-dimensional Riemannian manifold covered by a system of coordinate neighborhoods $\left\{U ; x^{h}\right\}$ and isometrically immersed in $\tilde{M}$ by the immersion $i: M \longrightarrow \tilde{M}$. When the argument is local, $M$ need not be distinguished from $i(M)$ itself. Throughout this paper the indices $i, j, k, \cdots$ run from 1 to $n+1$. We represent the immersion $i$ locally by

$$
y^{A}=y^{A}\left(x^{h}\right), \quad(A=1, \cdots, n+1, \cdots, 2 m+1)
$$

and put $B_{j}^{A}=\partial_{j} y^{A}, \quad\left(\partial_{j}=\frac{\partial}{\partial x^{j}}\right)$ then $B_{j}=\left(B_{j}^{A}\right)$ are (n+1)-linearly independent local tangent vector fields of $M$. We choose $2 m-n$ mutually orthogonal unit normals $C_{x}=\left(C_{x}{ }^{A}\right)$ to $M$. Hereaafter the indices $u, v, w, x, \cdots$
run from $n+2$ to $2 m+1$ and the summation convention will be used. The immersion being isometric, the induced Riemannian metric tensor $g$ with compoents $g_{j i}$ and the metric tensor $\delta$ with components $\delta_{y x}$ of the normal bundle are respectively obtained :

$$
g_{j i}=G\left(B_{j}, B_{i}\right), \quad \delta_{y x}=G\left(C_{y}, C_{x}\right) .
$$

By denoting $\nabla_{j}$ the operator of van der Waerden-Bortolotti covariant differentiation with respect to $g$ and $G$, the equations of Gauss and Weingarten for the submanifold $M$ are respectively given by

$$
\begin{equation*}
\nabla_{j} B_{i}=A_{j i}{ }^{x} C_{x}, \quad \nabla_{j} C_{x}=-A_{j}{ }_{x}^{h} B_{h}, \tag{1.2}
\end{equation*}
$$

where $A_{j i}{ }^{x}$ are components of the second fundamental tensors and the shape operator $A^{x}$ in the direction of $C_{x}$ are related by

$$
A^{x}=\left(A_{j}^{h x}\right)=\left(A_{j i y} g^{i h} \delta^{y x}\right), \quad g^{j i}=\left(g_{j i}\right)^{-1} .
$$

An ( $n+1$ )-dimensional submanifold $M$ of a Sasakian manifold $\tilde{M}$ is called a generic submanifold if

$$
\phi N_{p}(M) \subset T_{p}(M)
$$

at each point $p \in M$, where $T_{p}(M)$ is the tangent space of $M$ at $p$ and $N_{p}(M)$ the normal space at $p,[4],[6]$.

From now on, we have only to consider generic submanifolds of a Sasakian manifold. Then the transforms of $B_{i}$ and $C_{x}$ by $\phi$ are respectively represented in each coordinate neighborhood as follows :

$$
\begin{equation*}
\phi B_{j}=f_{j}{ }^{h} B_{h}-J_{j}{ }^{x} C_{x}, \quad \phi C_{x}=J_{x}{ }^{h} B_{h}, \tag{1.3}
\end{equation*}
$$

where we have put $f_{j i}=G\left(\phi B_{j}, B_{i}\right), J_{\boldsymbol{j} \boldsymbol{x}}=-G\left(\phi B_{\boldsymbol{j}}, C_{x}\right), J_{x j}=G\left(\phi C_{x}, B_{j}\right)$, $f_{j}{ }^{h}=f_{j i} g^{i h}$ and $J_{j}{ }^{x}=J_{j y} \delta^{y x}$. From these definitions we verify that $f_{j i}+$ $f_{i j}=0$ and $J_{j x}=J_{x j}$.

Also, we can put the Sasakian structure vector $V$ of the form

$$
\begin{equation*}
V=\xi^{h} B_{h}+w^{x} C_{x}, \tag{1.4}
\end{equation*}
$$

where $\xi_{i}=G\left(B_{i}, V\right)$ and $w_{x}=G\left(C_{x}, V\right), \xi^{h}$ being the associated vector with $\xi_{i}$.

By the properties of the Sasakian structure tensor, it follows from (1.3) and (1.4) that we obtain

$$
\begin{equation*}
f_{j}{ }^{t} f_{t}^{h}=-\delta_{j}^{h}+\xi_{j} \xi^{h}+J_{j}^{x} J_{x}^{h}, \tag{1.5}
\end{equation*}
$$

$$
\begin{equation*}
J_{y}{ }^{t} J_{t}^{x}=\delta_{y}^{x}-w_{y} w^{x} \tag{1.6}
\end{equation*}
$$

$$
\begin{equation*}
f_{t}{ }^{h} J_{x}^{t}=w_{x} \xi^{h}, \quad f_{j t} \xi^{t}=J_{j x} w^{x}, \tag{1.7}
\end{equation*}
$$

$$
\begin{equation*}
J_{t}{ }^{x} \xi^{t}=0 \tag{1.8}
\end{equation*}
$$

$$
\begin{equation*}
w_{x} w^{x}=1-\xi_{t} \xi^{t} \tag{1.9}
\end{equation*}
$$

Differentiating (1.3) and (1.4) covariantly along $M$ and making use of (1.1), (1.2) and these equations, we easily find (cf. [4])

$$
\begin{equation*}
\nabla_{k} f_{j}^{h}=-g_{k j} \xi^{h}+\delta_{k}^{h} \xi_{j}+A_{k j}^{x} J_{x}^{h}-A_{k}^{h x} J_{j x}, \tag{1.10}
\end{equation*}
$$

$$
\begin{equation*}
\nabla_{k} J_{j x}=g_{k j} w_{x}+A_{k r x} f_{j}^{r} \tag{1.11}
\end{equation*}
$$

$$
\begin{equation*}
A_{j r x} J^{r y}=A_{j}^{r y} J_{r x}, \tag{1.12}
\end{equation*}
$$

$$
\begin{equation*}
\nabla_{j} \xi_{i}=f_{j i}+A_{j i x} w^{x} \tag{1.13}
\end{equation*}
$$

$$
\begin{equation*}
\nabla_{j} w_{x}=-J_{j x}-A_{j r x} \xi^{r} \tag{1.14}
\end{equation*}
$$

Remark 1. We notice here that if $\xi_{j}=0$ on some open set, then $f_{j i}=0$ and $A_{j v x} w^{x}=0$ because of (1.13).

Promise. In the following, we define

$$
\begin{equation*}
\lambda_{x}=A_{j i x} \xi^{j} \xi^{i} /|\xi|^{2}, \quad P_{x y z}=A_{j i x} J_{y}{ }^{j} J_{z}{ }^{i} . \tag{1.15}
\end{equation*}
$$

Then it is clear that $P_{x y z}$ is symmetric for all indices because of (1.12). In the sequel the index $n+2$ will be denoted by the symbol $*$.

For the shape operator $A^{*}$ a function $h_{(m)}$ for any integer $m \geq 2$ is introduced as follows :

$$
\begin{equation*}
h_{(m)}=\operatorname{tr}\left(A^{*}\right)^{m} . \tag{1.16}
\end{equation*}
$$

## 2. The structure tensor of generic submanifolds

Let $M$ be a generic submanifold of a Sasakian manifold and denote by $\alpha=w_{x} w^{x}$. Suppose that the function $\alpha(1-\alpha)$ does not vanish almost everywhere, and that $A^{*} f=f A^{*}$, namely

$$
\begin{equation*}
A_{j r}{ }^{*} f_{i}{ }^{r}+A_{i r}{ }^{*} f_{j}{ }^{r}=0 \tag{2.1}
\end{equation*}
$$

holds on $M$. By transvecting $f_{k}{ }^{i}$ and making use of (1.5), we then have

$$
A_{j k}{ }^{*}-\left({A_{j r}}^{*} J_{z}^{r}\right) J_{k}^{z}-\left(A_{j r}{ }^{*} \xi^{r}\right) \xi_{k}-A_{s r}{ }^{*} f_{j}{ }^{s} f_{k}^{r}=0,
$$

and hence taking the skew-symmetric part with respect to $k$ and $j$,

$$
\begin{equation*}
\left(A_{j r *} J_{z}{ }^{r}\right) J_{k}{ }^{z}-\left(A_{k r *} J_{z}^{r}\right) J_{j}{ }^{z}+\left(A_{j r *} \xi^{r}\right) \xi_{k}-\left(A_{k r *} \xi^{r}\right) \xi_{j}=0 . \tag{2.2}
\end{equation*}
$$

If we transvect this by $\xi^{k}$ and make use of (1.8) and (1.9), then we get

$$
\begin{equation*}
(1-\alpha) A_{j r *} \xi^{r}-\left(A_{s r *} \xi^{s} \xi^{r}\right) \xi_{j}-\left(A_{s r *} \xi^{s} J_{z}^{r}\right) J_{j}^{z}=0 \tag{2.3}
\end{equation*}
$$

Transvecting this with $J_{y}{ }^{j}$ and using (1.6) and (1.8), we find

$$
\alpha A_{s r *} \xi^{r} J_{y}^{s}-w_{y}\left(A_{s r *} \xi^{s} J_{z}^{r} w^{z}\right)=0
$$

which joined with (1.7) gives

$$
\alpha A_{s r *} \xi^{r} J_{y}{ }^{s}+w_{y}\left(A_{j r *} f_{i}{ }^{r} \xi^{j} \xi^{i}\right)=0
$$

Thus it is, taking account of (2.1), clear that $A_{s r *} \xi^{r} J_{y}{ }^{s}=0$ because the function $\alpha$ is not vanish almost everywhere. Hence (2.3) implies $(1-\alpha)\left(A_{j r *} \xi^{r}-\right.$ $\left.\lambda_{*} \xi_{j}\right)=0$ because of (1.15) and consequently

$$
\begin{equation*}
A_{j r *} \xi^{r}=\lambda_{*} \xi_{j} \tag{2.4}
\end{equation*}
$$

with the aid of (1.9). Therefore (2.2) is reduced to

$$
\begin{equation*}
\left(A_{j r *} J_{z}^{r}\right) J_{i}^{z}-\left(A_{i r *} J_{z}^{r}\right) J_{j}^{z}=0 \tag{2.5}
\end{equation*}
$$

Because of (1.7), (2.1) and (2.4), we have

$$
A_{j r *} J_{z}^{r} w^{z}=-A_{j r *} f_{s}^{r} \xi^{s}=\lambda_{*} w_{z} J_{j}^{z}
$$

Thus, by transvecting $J_{w}^{i}$ to (2.5) and using (1.6) and (1.15), we find

$$
\begin{equation*}
A_{j r *} J_{x}^{r}=Q_{x z *} J_{j}^{z} \tag{2.6}
\end{equation*}
$$

where we have put

$$
\begin{equation*}
Q_{x z *}=\lambda_{*} w_{x} w_{z}+P_{x z *} \tag{2.7}
\end{equation*}
$$

Transforming (2.6) by $f_{i}^{j}$ and taking account of (1.7), (2.1) and (2.4), we find

$$
\left(\lambda_{*} w_{x}-Q_{x z *} w^{z}\right) \xi_{j}=0
$$

and hence

$$
\begin{equation*}
Q_{x z *} w^{z}=\lambda_{*} w_{x} \tag{2.8}
\end{equation*}
$$

because the function $1-\alpha$ does not vanish almost everywhere.
Differentiating (2.8) covariantly along $M$ and making use of (1.14), we find

$$
\begin{aligned}
w^{z} & \nabla_{k} Q_{y z *}-\left(J_{k}^{z}+A_{k r}^{z} \xi^{r}\right) Q_{y z *} \\
& =\left(\nabla_{k} \lambda_{*}\right) w_{y}-\lambda_{*}\left(J_{k y}+A_{k r y} \xi^{r}\right)
\end{aligned}
$$

By transvecting $\xi^{k}$ and using (1.8) and (1.15), we can get

$$
\begin{equation*}
\xi^{k} w^{z} \nabla_{k} Q_{y z *}=\left(\xi^{k} \nabla_{k} \lambda_{*}\right) w_{y}+(1-\alpha)\left(Q_{y z *} \lambda^{z}-\lambda_{*} \lambda_{y}\right) \tag{2.9}
\end{equation*}
$$

From (2.7) we have

$$
Q_{* * *}=\lambda_{*} w_{*}^{2}+A_{j i}^{*} J_{*}^{j} J_{*}^{i}
$$

by virtue of the second equation of (1.15). Differentiating the last equation covariantly and using (1.11), (1.14) and (2.6), we find

$$
\begin{aligned}
\nabla_{k} Q_{* * *} & =\left(\nabla_{k} \lambda_{*}\right) w_{*}^{2}-2 \lambda_{*} w_{*}\left(J_{k *}+A_{k r *} \xi^{r}\right) \\
& +\left(\nabla_{k} A_{j i}^{*}\right) J_{*}^{j} J_{*}^{i}+2 Q_{z * *}\left(w_{*} J_{k}^{z}+J^{j z} A_{k r *} f_{j}^{r}\right)
\end{aligned}
$$

which together with (1.7) and (2.8) gives

$$
\begin{align*}
\nabla_{k} Q_{* * *}=\left(\nabla_{k} \lambda_{*}\right) w_{*}^{2}+2 w_{*}\left(Q_{z * *} J_{k}^{z}\right. & \left.-\lambda_{*} J_{k *}\right)  \tag{2.10}\\
& +\left(\nabla_{k} A_{j i}^{*}\right) J_{*}^{j} J_{*}^{i}
\end{align*}
$$

3. Generic submanifolds with parallel mean curvature vector

In this section, we consider that a generic submanifold $M$ of an odddimensional unit sphere $S^{2 m+1}$. Then, the equations of Gauss, Codazzi and Ricci for $M$ are respectively obtained :

$$
\begin{equation*}
R_{k j i h}=g_{k h} g_{j i}-g_{j h} g_{k i}+A_{k h}^{x} A_{j i x}-A_{j h}^{x} A_{k i x} \tag{3.1}
\end{equation*}
$$

$$
\begin{gather*}
\nabla_{k} A_{j i}^{x}-\nabla_{j} A_{k i}^{x}=0,  \tag{3.2}\\
R_{j i y x}={A_{j r}}^{x} A_{i}^{r}{ }_{y}-A_{i r}^{x} A_{j}^{r} .
\end{gather*}
$$

where $R_{k j i h}$ and $R_{j i y x}$ are components of the Riemannian curvature tensor of $M$ and that with respect to the connection induced in the normal bundle of $M$, respectively.

Let $H$ be a mean curvature vector of a generic submanifold $M$. Namely, it is defined by

$$
H=g^{j i} A_{j i}{ }^{x} C_{x} /(n+1)=h^{x} C_{x} /(n+1),
$$

which is independent of the choice of the local field of orthonormal frames $\left\{C_{x}\right\}$.

In what follows we suppose that the mean curvature vector $H$ of $M$ is nonzero and is parallel in the normal bundle. Then we may choose a local filed $\left\{C_{x}\right\}$ in such a way that $H=\sigma C_{n+2}=\sigma C_{*}$, where $\sigma=|H|$ is nonzero constant. Because of the choice of the local field, the parallelism of $H$ yields

$$
\left\{\begin{array}{l}
h^{x}=0, \quad x \geq n+3  \tag{3.4}\\
h^{*}=(n+1) \sigma .
\end{array}\right.
$$

Then by (3.1), the Ricci tensor $S$ with components $S_{j i}$ of $M$ is given by

$$
\begin{equation*}
S_{j i}=n g_{j i}+h^{*} A_{j i *}-A_{j r}{ }^{x} A_{i}{ }_{x}{ }_{x} . \tag{3.5}
\end{equation*}
$$

Here we notice that the condition (2.1) does not depend on the choice of the local field because of (3.4).

The parallelism of the mean curvature vector yields that the restricted Laplacian $\Delta A_{j i}{ }^{*}$ of $A^{*}$ is given by

$$
\begin{equation*}
\Delta A_{j i}^{*}=S_{j r} A_{i}^{r *}-R_{k j i h} A^{k h *} \tag{3.6}
\end{equation*}
$$

because of (3.2), and that $\boldsymbol{R}_{\boldsymbol{j i * x}}=0$ shows

$$
\begin{equation*}
A_{j r}^{x} A_{i}^{r *}-A_{i r}^{x} A_{j}^{r *}=0 \tag{3.7}
\end{equation*}
$$

with the aid of (3.3).

Lemma 3.1. Let $M$ be an $(n+1)$-dimensional generic submanifold satisfying (2.1) of $S^{2 m+1}$ with nonvanishing parallel mean curvature vector. If the function $\alpha(1-\alpha)$ does not vanish almost everywhere, then we have

$$
\begin{equation*}
A_{j i y} A^{j i *}=h^{*} Q_{y * *} \tag{3.8}
\end{equation*}
$$

Proof. Transforming (3.7) by $J_{y}{ }^{i} J_{z}{ }^{j}$ and using (1.15) and (2.6), we find

$$
\begin{equation*}
Q_{y u *} P_{z}^{u x}=Q_{z u *} P_{y}^{u x} \tag{3.9}
\end{equation*}
$$

which enable us to obtain

$$
\begin{equation*}
Q_{y z *} P_{x}^{y z}=P^{z} Q_{x z *} \tag{3.10}
\end{equation*}
$$

for any index $x$, where we have defined $P^{z}=P_{x}{ }^{x z}$. Thus, it is clear that

$$
\begin{equation*}
Q_{y z *} P^{y z *}=P^{z} Q_{z * *} \tag{3.11}
\end{equation*}
$$

Differentiating (2.6) covariantly and substituting (1.12), we find

$$
\begin{align*}
& \left(\nabla_{k} A_{j r *}\right) J_{y}^{r}+A_{k j *} w_{y}+A_{j r *} A_{k s y} f^{r s}  \tag{3.12}\\
& =\left(\nabla_{k} Q_{y z *}\right) J_{j}^{z}+Q_{y z *} w^{z} g_{k j}+Q_{y z *} A_{k r}^{z} f_{j}^{r}
\end{align*}
$$

from which taking the skew-symmetric part with respect to indices $k$ and $j$, and making use of (2.1) and (3.2),

$$
\begin{aligned}
& A_{r}^{s *} A_{k s y} f_{j}^{r}-A_{r}^{s *} A_{j s y} f_{k}^{r} \\
& =\left(\nabla_{k} Q_{y z *}\right) J_{j}^{z}-\left(\nabla_{j} Q_{y z *}\right) J_{k}^{z}+Q_{y z *}\left(A_{k r}^{z} f_{j}^{r}-A_{j r}^{z} f_{k}^{r}\right)
\end{aligned}
$$

If we transvect $f^{j k}$ to this and take account of (1.5) and (1.7), then we obtain

$$
\begin{aligned}
& A_{r}^{s *} A_{k s y}\left(g^{k r}-\xi^{k} \xi^{r}-J^{k z} J_{z}^{r}\right) \\
& =\xi^{k}\left(\nabla_{k} Q_{y z *}\right) w^{z}+Q_{y z *} A_{k r}^{z}\left(g^{k r}-\xi^{k} \xi^{r}-J^{k u} J_{u}^{r}\right),
\end{aligned}
$$

which together with (1.15), (2.4), (2.6), (2.8), (2.9) and (3.4) yields

$$
A_{j i y} A^{j i *}=\left(\xi^{k} \nabla_{k} \lambda_{*}\right) w_{y}+h^{*} Q_{y * *}+Q_{u z *} P_{y}^{u z}-P^{z} Q_{z y *} .
$$

Because of (3.10), it is seen that

$$
\begin{equation*}
A_{j i y} A^{j i *}=\left(\xi^{k} \nabla_{k} \lambda_{*}\right) w_{y}+h^{*} Q_{y * *} \tag{3.13}
\end{equation*}
$$

On the other hand, differentiating (2.4) covariantly and substituting (1.13), we obtain

$$
\begin{equation*}
\left(\nabla_{k} A_{j r *}\right) \xi^{r}+A_{j}^{r *}\left(f_{k r}+A_{k r x} w^{x}\right)=\left(\nabla_{k} \lambda_{*}\right) \xi_{j}+\lambda_{*}\left(f_{k j}+A_{k j x} w^{x}\right) \tag{3.14}
\end{equation*}
$$

Transvecting $g^{k j}$ to this and taking account of (3.2) and (3.4), we get

$$
w^{x} A_{j i x} A^{j i *}=\xi^{k} \nabla_{k} \lambda_{*}+\lambda_{*} h^{*} w_{*},
$$

which together with (2.8) and (3.13) give raise to $(1-\alpha) \xi^{k} \nabla_{k} \lambda_{*}=0$ and hence

$$
\begin{equation*}
\xi^{k} \nabla_{k} \lambda_{*}=0 \tag{3.15}
\end{equation*}
$$

because the function $1-\alpha$ is not zero almost everywhere. By (3.13) our assertion is thus proved.

Lemma 3.2. Under the same hypothesis as that in Lemma 3.1, we have

$$
\begin{gather*}
h^{*}=(n+1) \lambda^{*}  \tag{3.16}\\
A_{j i *}=\lambda_{*}\left(g_{j i}-J_{j}^{z} J_{i z}\right)+Q_{y z *} J_{j}^{y} J_{i}^{z} . \tag{3.17}
\end{gather*}
$$

Proof. If we take the skew-symmetric part with respect to $k$ and $j$ in (3.14), and make use of (2.1), (3.2) and (3.7), then we find

$$
2 A_{j r *} f_{k}^{r}=\left(\nabla_{k} \lambda_{*}\right) \xi_{j}-\left(\nabla_{j} \lambda_{*}\right) \xi_{k}+2 \lambda_{*} f_{k j}
$$

By transvecting $\xi^{j}$ and using (2.4) and (3.15), we see that $\lambda_{*}=$ const. Therefore we have

$$
\begin{equation*}
A_{j r *} f_{k}^{r}=\lambda_{*} f_{k j} \tag{3.18}
\end{equation*}
$$

Accordingly (3.14) is reduced to

$$
\left(\nabla_{k} A_{j r *}\right) \xi^{r}=-A_{j r *} A_{k}^{r x} w_{x}+\lambda_{*} A_{k j x} w^{x}
$$

from which, transforming ${f_{l}}^{j}$ and taking account of (3.18),

$$
\begin{equation*}
\left(\nabla_{k} A_{j r *}\right) \xi^{r} f_{l}^{j}=0 \tag{3.19}
\end{equation*}
$$

Differentiating (3.18) covariantly and using (1.10), (2.4) and (2.6), we obtain

$$
\begin{align*}
\left(\nabla_{k} A_{i r *}\right) f_{j}^{r}= & \left(A_{k r x} A_{i}^{r *}-\lambda_{*} \dot{A}_{k i x}\right) J_{j}^{x}-\left(A_{k i *}-\lambda_{*} g_{k i}\right) \xi_{j}  \tag{3.20}\\
& -\left(Q_{x z *} J_{i}^{z}-\lambda_{*} J_{i x}\right) A_{k j}^{x}
\end{align*}
$$

which together with (3.2) and (3.7) implies that

$$
A_{k j}^{x}\left(Q_{x z *} J_{i}^{z}-\lambda_{*} J_{i x}\right)=A_{k i}^{x}\left(Q_{x z *} J_{j}^{z}-\lambda_{*} J_{j x}\right) .
$$

Therefore (3.20) implies

$$
\begin{gathered}
\left(\nabla_{k} A_{i r *}\right) f_{j}^{r}-\left(\nabla_{k} A_{j r *}\right) f_{i}^{r}+\left(A_{k i *}-\lambda_{*} g_{k i}\right) \xi_{j}-\left(A_{k j *}-\lambda_{*} g_{k j}\right) \xi_{i} \\
=\left(A_{k r x} A_{i}^{r *}-\lambda_{*} A_{k i x}\right) J_{j}^{x}-\left(A_{k r x} A_{j}^{r *}-\lambda_{*} A_{k j x}\right) J_{i}^{x} .
\end{gathered}
$$

If we transvect $\xi^{j}$ to this and take account of (1.8), (2.4) and (3.19), then we get

$$
\left(\nabla_{k} A_{i r *}\right) f_{j}{ }^{r} \xi^{j}+(1-\alpha)\left(A_{k i *}-\lambda_{*} g_{k i}\right)=0
$$

and hence $(1-\alpha)\left\{h^{*}-(n+1) \lambda_{*}\right\}=0$. Thus (3.16) is obtained.
Transforming (3.18) by $f_{i}{ }^{k}$ and using (1.5), (2.4) and (2.6), we can verify that (3.17) is valid. This completes the proof of Lemma 3.2.

Lemma 3.3. Under the same hypothesis as that in Lemma 3.1, we have

$$
\begin{equation*}
h_{(3)}=h^{*} Q_{z * *} Q^{z * *} . \tag{3.21}
\end{equation*}
$$

Proof. Since we have (3.17), it follows that we obtain

$$
A_{j i y} A^{j i *}=\lambda_{*}\left(h_{y}-P_{y}\right)+Q_{z x *} P_{y}^{z x},
$$

which joined with (3.8) and (3.10) gives

$$
\begin{equation*}
P^{z} Q_{y z *}=h^{*} Q_{y * *}+\lambda_{*}\left(P_{y}-h_{y}\right), \tag{3.22}
\end{equation*}
$$

which implies

$$
\begin{equation*}
P^{z} Q_{z * *}=h^{*} Q_{* * *}+\lambda_{*}\left(P^{*}-h^{*}\right) . \tag{3.23}
\end{equation*}
$$

Thus, (3.11) turns out to be

$$
\begin{equation*}
Q_{y z *} P^{y z *}=h^{*} Q_{* * *}+\lambda_{*}\left(P^{*}-h^{*}\right) \tag{3.24}
\end{equation*}
$$

Making use of (3.9) and (3.22), it is seen that

$$
\begin{equation*}
Q_{u z *} P^{x z *} Q_{x}^{u *}=h^{*} Q_{z * *} Q^{z * *}+(\lambda *)^{2}\left(P^{*}-h^{*}\right) \tag{3.25}
\end{equation*}
$$

On the other hand, we have from (3.17)

$$
A_{j r}^{*} A_{i}^{r *}=\lambda_{*}\left(A_{j i *}-Q_{y z *} J_{j}^{y} J_{i}^{z}\right)+Q_{y z *} Q_{w}{ }^{y *} J_{j}{ }^{w} J_{i}^{z}
$$

by virtue of (2.6). Transvecting $A^{j i *}$ to the last equation and taking account of (1.15) and (1.16), we get

$$
h_{(3)}=\lambda_{*}\left(h_{(2)}-Q_{y z *} P^{y z *}\right)+Q_{y z *} Q_{w}{ }^{y *} P^{w z *}
$$

Since we have from (3.8)

$$
\begin{equation*}
h_{(2)}=h^{*} Q_{* * *}, \tag{3.26}
\end{equation*}
$$

it follows, using (3.24) and (3.25), that $h_{(3)}=h^{*} Q_{z * *} Q^{z * *}$. Hence Lemma 3.3 is proved .

Lemma 3.4. Under the same assumptions as that in Lemma 3.1, we have

$$
\begin{equation*}
\Delta h_{(2)}=(n-1)\left\{h_{(2)}-\frac{1}{n+1}\left(h^{*}\right)^{2}\right\} \tag{3.27}
\end{equation*}
$$

Proof. By (3.6) we have

$$
\begin{equation*}
\Delta A_{j i}^{*}=(n+1) A_{j i}^{*}-h^{*} g_{j i}+h^{*}\left(A_{j i}^{*}\right)^{2}-h^{*} Q_{x * *} A_{j i}^{x} \tag{3.28}
\end{equation*}
$$

where we have used (3.1), (3.5), (3.7) and (3.8). If we transvect (3.28) with $J_{*}^{j} J_{*}^{i}$ and make use of (1.6), (1.15), (2.6) and (2.7), we obtain

$$
\begin{equation*}
\left(\Delta A_{j i}^{*}\right) J_{*}^{j} J_{*}^{i}=(n+1) P_{* * *}-h^{*}\left(1-w_{*}^{2}\right) \tag{3.29}
\end{equation*}
$$

As is, in the proof of Lemma 3.2, already shown that $\lambda_{*}$ is constant, (2.10) turns out to be

$$
\nabla_{k} Q_{* * *}=2 w_{*}\left(Q_{z * *} J_{k}^{z}-\lambda_{*} J_{k *}\right)+\left(\nabla_{k} A_{j i}^{*}\right) J_{*}^{j} J_{*}^{i} .
$$

We then have

$$
\begin{aligned}
\Delta Q_{* * *} & =-2\left(J_{j *}+\lambda_{*} \xi_{j}\right)\left(Q_{z * *} J^{j z}-\lambda_{*} J^{j *}\right)+\left(\Delta A_{j i}^{*}\right) J_{*}^{j} J_{*}^{i} \\
& +2 w_{*}\left\{\left(\nabla_{j} Q_{z * *}\right) J^{j z}+(n+1)\left(Q_{z * *} w^{z}-\lambda_{*} w_{*}\right)\right\}
\end{aligned}
$$

because of (1.11), (1.14), (2.4) and (3.2), which joined with (1.6), (1.8), (2.7), (2.8), (3.16) and (3.29) yields

$$
\begin{equation*}
\Delta Q_{* * *}=(n-1)\left\{Q_{* * *}-\frac{1}{n+1} h^{*}\right\}+2 w_{*}\left(\nabla_{j} Q_{z * *}\right) J^{j z} \tag{3.30}
\end{equation*}
$$

On the other hand, transvecting (3.12) with $g^{k j}$ and taking account of (3.2), (3.4), (3.7) and (3.16), the last term of (3.30) vanishes identically. Thus we arrive at (3.27) because of (3.26). This completes the proof.

By (3.28) we have

$$
\begin{equation*}
A^{j i *} \Delta A_{j i}^{*}=(n+1) h_{(2)}-\left(h^{*}\right)^{2} \tag{3.31}
\end{equation*}
$$

by virtue of Lemma 3.1 and Lemma 3.3.
Since we have in general

$$
\begin{equation*}
\frac{1}{2} \Delta h_{(2)}=A^{j i *} \Delta A_{j i *}+\left|\nabla A^{*}\right|^{2} \tag{3.32}
\end{equation*}
$$

it is seen that

$$
(n+3)\left|A^{*}-\frac{h^{*}}{n+1} I\right|^{2}+2\left|\nabla A^{*}\right|^{2}=0
$$

by (3.31) and Lemma 3.4., where $I$ denotes the unit tensor. Therefore $M$ is pseudo-umbilical and hence $A^{*}$ is parallel. Thus we have

Theorem 3.5. Let $M$ be a generic submanifold satisfying (2.1) of $S^{2 m+1}$ with nonvanishing parallel mean curvature vector. If the function $\alpha(1-\alpha)$ is not zero almost everywhere, then $M$ is pseudo-umbilical.

Remark 2. The hypersurface satisfying (2.1) in a Sasakian space form is totally umbilical (cf. [5]).

## 4. Generic submanifolds tangent to the structure vector

Let $M$ be a generic submanifold satisfying (2.1) of an odd-dimensional sphere $S^{2 m+1}$. Suppose that the mean curvature vector of $M$ is nonzero and is parallel in the normal bundle. Moreover, we suppose that the submanifold $M$ is tangent to the structure vector $V$. Then by (1.4) we have

$$
\begin{equation*}
w_{x}=0 \tag{4.1}
\end{equation*}
$$

and hence $\xi_{t} \xi^{t}=1$. Thus, (1.6) and (1.7) become respectively

$$
\begin{equation*}
J_{x}{ }^{t} J_{t}^{y}=\delta_{x}^{y} \tag{4.2}
\end{equation*}
$$

$$
\begin{equation*}
f_{t}^{h} J_{x}^{t}=0, \quad f_{j t} \xi^{t}=0 \tag{4.3}
\end{equation*}
$$

We also obtain from (1.14)

$$
\begin{gather*}
A_{j r x} \xi^{r}=-J_{j x}  \tag{4.4}\\
-101-
\end{gather*}
$$

Consequently (2.2) leads to

$$
\left(A_{j r *} J_{z}^{r}\right) J_{i}^{z}-\left(A_{i r *} J_{z}^{r}\right) J_{j}^{z}+J_{i *} \xi_{j}-J_{j *} \xi_{i}=0 .
$$

Transvecting this with $J_{y}{ }^{i}$ and using (4.2) and (4.3), we get

$$
\begin{equation*}
A_{j r *} J_{y}{ }^{r}=P_{y z *} J_{j}{ }^{z}-\delta_{y *} \xi_{j} . \tag{4.5}
\end{equation*}
$$

If we transvect (3.7) with $J_{y}{ }^{i} J_{u}{ }^{j}$ and use (4.4) and (4.5), then we obtain

$$
\begin{equation*}
P_{y z *} P_{x u}{ }^{z}-P_{z u *} P_{x y}{ }^{z}=\delta_{u *} \delta_{x y}-\delta_{y *} \delta_{x u} \tag{4.6}
\end{equation*}
$$

and thus

$$
\begin{equation*}
P_{x z *} P_{y}^{x z}-P^{z} P_{z y *}=(p-1) \delta_{y *}, \tag{4.7}
\end{equation*}
$$

where $p=2 m-n$.
Lemma 4.1. Let $M$ be a generic submanifold satisfying (2.1) of $S^{2 m+1}$ with nonvanishing parallel mean curvature vector. If $M$ is tangent to the structure vector, then we have

$$
\begin{gather*}
A_{j i y} A^{j i *}=h^{*} P_{y * *}+(n+1) \delta_{y *},  \tag{4.8}\\
h_{(3)}=h^{*} P_{z * *} P^{z * *}+(n+1) P_{* * *}+h^{*} .
\end{gather*}
$$

Proof. Differentiating (4.5) covariantly along $M$ and making use of (1.11), (1.13), (2.1) and (4.1), we find

$$
\left(\nabla_{k} A_{j r *}\right) J_{y}{ }^{r}+A_{r^{*}}{ }_{*} A_{k s y} f_{j}^{r}=\left(\nabla_{k} P_{y z *}\right) J_{j}{ }^{z}+P_{y z *} A_{k r}{ }^{z} f_{j}^{r}-\delta_{y *} f_{k j} .
$$

Hence, if we take the skew-symmetric part with respect to $k$ and $j$, then we obtain
(4.10) $A_{r}{ }^{s}{ }_{*} A_{k s y} f_{j}^{r}-A_{r}{ }^{s}{ }_{*} A_{j s y} f_{k}{ }^{r}$

$$
=\left(\nabla_{k} P_{y z *}\right) J_{j}^{z}-\left(\nabla_{j} P_{y z *}\right) J_{k}^{z}+P_{y z *}\left(A_{k r}^{z} f_{j}^{r}-A_{j r}^{z} f_{k}^{r}\right)+2 \delta_{y *} f_{j k}
$$

Transvecting (4.10) with $f^{j k}$ and using (1.5) and (4.3), we can get

$$
\begin{aligned}
& A_{r}^{s} A_{k s y}\left(g^{k r}-\xi^{k} \xi^{r}-J^{k w} J_{w}^{r}\right) \\
& =P_{y z *} A_{k r}^{z}\left(g^{k r}-\xi^{k} \xi^{r}-J^{k w} J_{w}^{r}\right)+\delta_{y *}(n-p)
\end{aligned}
$$

which joined with (3.4), (4.4) and (4.5) yields

$$
\begin{aligned}
& A_{j i y} A^{j i *}+J_{*} A_{k s y} \xi^{k}-\left(P_{w z *} J^{s w}-\delta_{z *} \xi^{s}\right) A_{k s y} J^{k z} \\
& =h^{*} P_{y * *}-P^{z} P_{z y *}+(n-p) \delta_{y *} .
\end{aligned}
$$

Hence we have

$$
A_{j i y} A^{j i *}=h^{*} P_{y * *}+P_{w z *} P_{y}^{w z}-P^{z} P_{y z *}+2 J_{s y} J^{s *}+(n-p) \delta_{y *}
$$

where we have used (1.12) and (4.4), which together with (4.2) and (4.7) implies that (4.8) is valid.

When $y=*$ in (4.10), we have

$$
\begin{align*}
-2 A_{j s}^{*} A_{r}^{s *} f_{k}^{r} & =\left(\nabla_{k} P_{z * *}\right) J_{j}^{z}-\left(\nabla_{j} P_{z * *}\right) J_{k}^{z}  \tag{4.11}\\
& +P_{z * *}\left(A_{k r}^{z} f_{j}^{r}-A_{j r}{ }^{z} f_{k}^{r}\right)+2 f_{j k}
\end{align*}
$$

because of (2.1).
By the way we have

$$
A^{j r *} f_{r}^{t}\left(\nabla_{t} P_{z * *}\right) J_{j}^{z}=0
$$

with the aid of (4.3) and (4.5). Hence, by transvecting $A_{s}{ }^{j *} f^{k s}$ to (4.11) and using (1.5), we find

$$
\begin{aligned}
& A_{r}^{t *} A_{t s}^{*} A_{i}^{s *}\left(g^{r i}-\xi^{r} \xi^{i}-J^{r z} J_{z}^{i}\right) \\
& =P_{z * *} A_{r s}^{z} A_{i}^{r *}\left(g^{s i}-\xi^{s} \xi^{i}-J^{s z} J_{z}^{i}\right)+A_{r i}^{*}\left(g^{r i}-\xi^{r} \xi^{i}-J^{r z} J_{z}^{i}\right)
\end{aligned}
$$

or, using (4.2), (4.3), (4.4) and (4.5)

$$
\begin{aligned}
& h_{(3)}-A^{s t *}\left(P_{y z *} J_{t}^{y}-\delta_{z *} \xi_{t}\right)\left(P_{x}^{z *} J_{s}^{x}-\delta^{z *} \xi_{s}\right) \\
& =P_{z * *} A_{j i}^{z} A^{j i *}-P_{z * *} A_{j s}^{z} J^{s w}\left(P_{y w *} J^{j y}-\delta_{w *} \xi^{j}\right)+h^{*}-P^{*}
\end{aligned}
$$

Thus it follows that we obtain

$$
\begin{aligned}
& h_{(3)}-P_{y z *} P_{x}^{z *} P^{x y *} \\
& =h^{*} P_{z * *} P^{z * *}+(n+2) P_{* * *}-P_{z * *} P_{y w *} P^{z w y}+h^{*}-P^{*}
\end{aligned}
$$

because of (4.2), (4.4) and (4.8). Since we have from (4.6)

$$
\begin{equation*}
P_{y z *} P_{x}^{z *} P^{x y *}-P_{z * *} P_{x y *} P^{x y z}=P^{*}-P_{* * *} \tag{4.11}
\end{equation*}
$$

above equation can be written as

$$
h_{(3)}=h^{*} P_{z * *} P^{z * *}+(n+1) P_{* * *}+h^{*}
$$

which proves (4.9). Hence, Lemma 4.1 is proved.

Lemma 4.2. Under the same hypothesis as that in Lemma 4.1, the function $h_{(2)}$ is harmonic.

Proof. By definition, we have $P_{* * *}=A_{j i}{ }^{*} J_{*}{ }^{j} J_{*}{ }^{i}$. Differentiating this covariantly and making use of (1.11), (4.1) and (4.5), we find

$$
\nabla_{k} P_{* * *}=\left(\nabla_{k} A_{j i}^{*}\right) J_{*}^{j} J_{*}^{i}+2\left(P_{z * *} J_{j}^{z}-\xi_{j}\right) A_{k r}^{*} f^{j r}
$$

which gives $\nabla_{k} P_{* * *}=\left(\nabla_{k} A_{j i}{ }^{*}\right) J_{*}{ }^{j} J_{*}^{i}$ because of (4.3). Thus the Laplacian of the function $P_{* * *}$ is given by

$$
\Delta P_{* * *}=\left(\Delta A_{j i}^{*}\right) J_{*}^{j} J_{*}^{i}+2\left(\nabla_{k} A_{j i}^{*}\right) J_{*}^{i} A_{r}^{k *} f^{j r}
$$

which together with (2.1) and (3.2) yields

$$
\Delta P_{* * *}=\left(\Delta A_{j i}^{*}\right) J_{*}^{j} J_{*}^{i}
$$

Hence, by (3.6) we have

$$
\begin{equation*}
\Delta P_{* * *}=S_{j r} A_{i}^{r *} J_{*}^{j} J_{*}^{i}-R_{k j i h} A^{k h *} J_{*}^{j} J_{*}^{i} \tag{4.12}
\end{equation*}
$$

On the other hand, we verify, taking account of (3.5), (4.4) and (4.5), that

$$
S_{j i} J_{*}^{i}=(n-1) J_{j *}+h^{*}\left(P_{z * *} J_{j}^{z}-\xi_{j}\right)-P_{w x}^{*} A_{j r}^{x} J^{r w}
$$

Thus, using (1.8), (4.2), (4.3) and (4.4) we obtain
(4.13) $\quad S_{j r} A_{i}{ }^{r *} J_{*}{ }^{i} J_{*}^{j}$

$$
=(n-1) P_{* * *}+h^{*} P_{z * *} P^{z * *}-P_{y * *} P_{w x *} P^{y x w}+h^{*}-P^{*}
$$

We also have from (3.1)

$$
\begin{aligned}
R_{k j i h} A^{k h *} J_{*}^{j} J_{*}^{i} & =h^{*}-P_{* * *}+P_{z * *} A^{k h *} A_{k h}^{z} \\
& -A^{k h *}\left(P_{w x *} J_{h}^{w}-\delta_{x *} \xi_{h}\right)\left(P_{y}^{x *} J_{k}^{y}-\delta^{x *} \xi_{k}\right)
\end{aligned}
$$

because of (4.2), which joined with (4.3), (4.4), (4.8) and (4.11) yields

$$
\begin{aligned}
& R_{k j i h} A^{k h *} J_{*}^{j} J_{*}^{i} \\
& =h^{*}-P^{*}+h^{*} P_{z * *} P^{z * *}+(n-1) P_{* * *}-P_{z * *} P_{x y *} P^{x y z}
\end{aligned}
$$

Hence the right hand side of (4.12) vanishes identically by virtue of (4.13). Since we have from (4.8)

$$
\begin{equation*}
h_{(2)}=h^{*} P_{* * *}+n+1 \tag{4.14}
\end{equation*}
$$

it follows that we have $\Delta h_{(2)}=0$ because the mean curvature vector is parallel. This completes the proof.

On the other hand, we have from (3.5)

$$
S_{j s} A_{i}{ }^{s *} A^{j i *}=n h_{(2)}+h^{*} h_{(3)}-A_{j r}{ }^{x} A_{s}{ }^{r}{ }_{x} A_{i}{ }^{s *} A^{j i *},
$$

which together with (3.7), (4.9) and (4.14) implies that

$$
\begin{aligned}
S_{j s} A_{i}^{s *} A^{j i *} & =\left(h^{*}\right)^{2} P_{z * *} P^{z * *}+(2 n+1) h^{*} P_{* * *}+n(n+1) \\
& +\left(h^{*}\right)^{2}-A_{j r}^{x} A_{i s x} A^{r s *} A^{j i *} .
\end{aligned}
$$

We also have from (3.1)

$$
\begin{aligned}
R_{k j i h} A^{k h *} A^{j i *} & =\left(h^{*}\right)^{2}-h^{*} P_{* * *}-(n+1)+\left(h^{*}\right)^{2} P_{z * *} P^{z * *} \\
& +2(n+1) h^{*} P_{* * *}+(n+1)^{2}-A_{j r}^{x} A_{i s x} A^{r s *} A^{j i *}
\end{aligned}
$$

because of (4.8) and (4.14). From the last two equations, it follows that we obtain

$$
S_{j s} A_{i}^{s *} A^{j i *}-R_{k j i h} A^{k h *} A^{j i *}=0 .
$$

Therefore, by (3.6) we have $A^{j i *} \Delta A_{j i *}=0$ and consequently $\nabla A^{*}=0$ by virtue of (3.32) and Lemma 4.2. Thus we have

Theroem 4.3. Let $M$ be a generic submanifold satisfying (2.1) of an odd-dimensional unit sphere with nonvanishing parallel mean curvature vector. If the structure vector $V$ is tangent to $M$, then the shape operator in the direction of the mean curvature vector is parallel.

Remark 3. An example satisfying all conditions of Theorem 4.3 is given in [2].

## 5. Theorems

Let $M$ be a generic submanifold of an odd-dimensional unit sphere. Suppose that the mean curvature vector of $M$ is nonzero and is parallel in the normal bundle, and that $A^{*} f=f A^{*}$ holds on $M$.

If we now put $M_{0}=\{p \in M \mid \alpha(p)=0\}, M_{1}=\{p \in M \mid \alpha(p)=1\}$ and $\bar{M}=M-M_{0} \cup M_{1}$, then we have $M=\bar{M} \cup M_{0} \cup M_{1}$, where $\alpha=\left|w_{x}\right|^{2}$. The sets $M_{0}$ and $M_{1}$ are then geometrically characterized as follows: The structure vector field $V$ in the ambient space is tangent to the generic submanifold $M$ at any point in the set $M_{0}$, and the vector field $V$ is orthogonal to $M$ at each point in $M_{1}$ because of (1.4).

If we suppose that there is an open subset $U$ contained in $M_{1}$, then we have $A_{j i x} w^{x}=0$ in $U$ by Remark 1 and hence $h^{*} w_{*}=0$ because of (3.4). Consequently we see that $w_{*}=0$ on $U$ since the mean curvature vector is not zero, and therefore $J_{j *}=0$ on $U$ by (1.14). This contradicts (1.6). Thus the set $M_{1}$ is bordered. Hence we may discuss properties of the covariant derivative of the second fundamental tensor $A^{*}$ only on $\bar{M} \cup M_{0}$ since it is continuous.

Suppose that there exists a connected component $W$ of the set $M_{0}$. Then, by Theorem 4.3, we have $\nabla A^{*}=0$ on $W$. When $\bar{M}$ is not empty, as a consequence of Theorem 3.5 , we see that $\nabla A^{*}=0$. Hence $\nabla A^{*}=0$ on each component of $\bar{M}$ and $M_{0}$. Since $\nabla A^{*}$ is continuous it follows that we obtain $\nabla A^{*}=0$ on $M$. When $\bar{M}$ is empty, Theorem 4.3 implies $\nabla A^{*}=0$. Thus we have

Theorem 5.1. Let $M$ be a generic submanifold of an odd-dimensional unit sphere with nonvanishing parallel mean curvature vector. If the shape operator $A^{*}$ in the direction of the mean curvature vector commutes with the structure tensor $f$ induced on $M$, then $A^{*}$ is parallel.

We will consider the case where $A^{*}$ is parallel on $M$. For any point in $M$ we can choose a local orthonormal frame $\left\{E_{i}\right\}$ so that the shape operator $A^{*}$ is diagonalizable at that point $q$, say $A_{j i}{ }^{*}=\lambda_{j} \delta_{j i}$. Then $h_{(m)}$ can be written as

$$
h_{(m)}=\sum_{i} \lambda_{i}^{m}, \quad(m=1,2, \cdots)
$$

Because of $\nabla A^{*}=0$, we see that $h_{(m)}=$ const. for any integer $m \geq 1$, it is seen that $\lambda_{i}$ constant, namely all eigenvalues of $A^{*}$ are constant. Taking accout of the Ricci formula for $A^{*}$ and the facts that $R_{j i * x}=0$ and $\nabla A^{*}=0$, we find

$$
\left(\lambda_{j}-\lambda_{i}\right) \sigma_{j i}=0
$$

for any fixed $j$ and $i$, where $\sigma_{j i}$ denotes the sectional curvature spanned by $E_{j}$ and $E_{i}$. If eigenvalues of $A^{*}$ are mutually distinct, we then obtain $\sigma_{j i}=0$. Because each eigenvector of $A^{*}$ is parallel, it follows that we have

Theorem 5.2. Let $M$ be a generic submanifold of $S^{2 m+1}$ with nonvanishing parallel mean curvature vector. If $A^{*} f=f A^{*}$ and if the eigenvalues of $A^{*}$ are mutually distinct, then $M$ is flat.

Now, let $\mu_{1}, \cdots, \mu_{s}$ be mutually distinct eigenvalues of $A^{*}$ and $n_{1}, \cdots, n_{s}$ their multiplicities. Since $A^{*}$ is parallel, the smooth distribution $T_{a}(a=$ $1, \cdots, s)$ which consists of all eigenvalues accociated with the eigenvalue can be defined and is parallel. $M$ is assumed to be simply connected and complete, then by means of the de Rham decomposition theorem, the submanifold is a product of Riemannian manifolds $M_{1} \times \cdots \times M_{s}$, where the tangent bundle of $M_{a}$ correspond to $T_{a}$. Since the shape operator $A^{*}$ restricted to $T_{a}$ is proprotional to the identity transformation of $T_{a}$ and each submanifold $M_{a}$ is totally geodesic in $M$, the mean curvature of $M$ is an umbilical section of $M_{a}$ in $S^{2 m+1}$. Thus, by means of the above arguments and Theorem 5.1, we have

Theorem 5.3. Let $M$ be a complete and simply connected generic submanifold of $S^{2 m+1}$ with nonvanishing parallel mean curvature vector. If the shape operator $A^{*}$ in the direction of the mean curvature vector commutes with the structure tensor $f$ induced on $M$, then $M$ is a product of Riemannian manifolds $M_{1} \times \cdots \times M_{s}$, where $s$ is the number of distinct eigenvalues of $A^{*}$, and the mean curvature vector of $M$ is an umbilical section of $M_{a}(a=1, \cdots, s)$.

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