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written as

$$
\begin{equation*}
(D \mathscr{R} \varphi)(z)=-\frac{1}{\lambda} \varphi\left(L_{+}(\tau z)\right)-\frac{r}{\lambda} f^{\prime}\left(L_{+}(\tau z)\right) f(\tau z)^{r-1} \varphi(\tau z) . \tag{3.6}
\end{equation*}
$$

If we define the linear operator $Q$ by

$$
\begin{equation*}
(Q \varphi)(z)=\frac{\varphi(z)}{f^{\prime}(z)}, \tag{3.7}
\end{equation*}
$$

then

$$
\begin{equation*}
Q D \mathscr{R}=T Q, T=Q D \mathscr{R} Q^{-1} . \tag{3.8}
\end{equation*}
$$

The domains of these operators will be chosen to be certain spaces of functions holomorphic in complex neighborhoods of $[0,1]$ in such a way that these equations make sense. The spectrum of $D \mathscr{R}$ will then be the same as that of $T$.

It is natural to expect (and true) that $T$ will preserve the class of functions holomorphic in the same domain as $f$. Indeed recall that $U$ is holomorphic in $\Omega(\lambda)$ which it maps bijectively onto a certain bounded open subset $\Delta$ of $\mathbf{C}$, on which $f$ is holomorphic. By (2.7), $\tau \Delta \subset \Delta$. The identity (2.15) shows that $L_{+} \circ \tau$ is analytic on $\Delta$ and maps it into itself. But $L(\tau \Delta)=U(-\lambda \Omega(\lambda))$ is not relatively compact in $\Delta$ since their non-real points are the same. We will therefore use a sub-domain of $\Delta$ to make $T$ analyticity-improving. A convenient choice is given by

$$
\begin{equation*}
\Delta_{1}=U\left(\left\{z:|z|<\frac{1}{\lambda}\right\}\right), \quad \Delta_{0}=U(\{z:|z|<u(-1)\}) . \tag{3.9}
\end{equation*}
$$

Note that $\Delta_{0} \Subset \Delta_{1}$ since

$$
1=u(-\lambda)<u(-1)<u(-1 / \lambda)=x_{0} / \lambda .
$$

Lemma 3.1. If $v$ is a real function on $[0,1]$ which extends to a holomorphic function on $\Delta_{0}$, then Tv extends to a holomorphic function on $\Delta_{1}$. For every $\Delta^{\prime} \Subset \Delta_{1}$ one has

$$
\sup _{z \in \Lambda^{\prime}}|(T v)(z)| \leqq \frac{1}{\tau} \sup _{z \in \mathbb{J}^{\prime}}\left(1+\left|\frac{1}{\bar{L}_{+}^{\prime}(\tau z)}\right|\right) \cdot \sup _{y \in \Delta_{0}}|v(y)| .
$$

Proof. We shall use the following simple fact: if a Herglotz or anti-Herglotz function is holomorphic on a real segment $(a, b)$ and maps it into the real segment $\left(a^{\prime}, b^{\prime}\right)$, then it maps the disk with diameter $(a, b)$ into the disk with diameter $\left(a^{\prime}, b^{\prime}\right)$. (See e.g. [E2].)

We claim now that $\tau \Delta_{1} \subset \Delta_{0}$ and $L_{+}\left(\tau \Delta_{1}\right) \subset \Delta_{0}$. Indeed, let $z=U(\zeta)$, for some $|\zeta|<1 / \lambda$. Then $\tau z=U(u(-\lambda \zeta)$ ), and $u(-\lambda \zeta)$ is contained in the disk with diameter $(0, u(-1))$; hence $\tau z \in \Delta_{0}$. On the other hand, by (2.15), we have $L_{+}(\tau z)=U(-\lambda \zeta)$ and this is also in $\Delta_{0}$. The derivative of $L_{+} \circ \tau$ tends to zero near $y_{0} / \tau$. But its reciprocal is bounded in modulus in any $\Delta^{\prime} \Subset \Delta_{1}$. This completes the proof of the lemma.

We denote by $\mathscr{B}$ the Banach space of holomorphic, bounded functions on $\Delta_{0}$ which are real on [0,1], equipped with the "sup" norm. It follows from Lemma 3.1 that $T \mathscr{B} \subset \mathscr{B}$ and $T$ is a compact linear operator on $\mathscr{B}$ whose eigenvalues form an exponentially decaying sequence.

We use the following lemma to take advantage of the simple form of $T$ :
Lemma 3.2. The function $L_{+}$is convex on $\left[0, y_{0}\right]$, and the function $L_{-}$is convex on [ $\left.y_{0}, 1\right]$.
Proof. By our general assumptions, the function $U$ is holomorphic and antiHerglotzian in the cut plane $\Omega(\lambda)$, described by (2.3). As such it has positive Schwarzian derivative on the interval ( $-\lambda^{-1}, \lambda^{-2}$ ), i.e. $\phi=U^{\prime \prime} / U^{\prime}$ satisfies $2 \phi^{\prime} / \phi^{2}$ $-1 \geqq 0$. Integrating this inequality gives

$$
\begin{equation*}
-\frac{2 \lambda}{1+\lambda z} \leqq \frac{U^{\prime \prime}(z)}{U^{\prime}(z)} \leqq \frac{2 \lambda^{2}}{1-\lambda^{2} z} . \tag{3.10}
\end{equation*}
$$

By (2.14),

$$
\begin{equation*}
-\frac{S_{ \pm}^{\prime \prime}(\zeta)}{S_{ \pm}^{\prime}(\zeta)}=\frac{1}{r \zeta}\left[r-1-z \frac{U^{\prime \prime}(z)}{U^{\prime}(z)}\right] \quad \text { with } \quad z= \pm \zeta^{1 / r} \tag{3.11}
\end{equation*}
$$

We now use the lower bound for $r$ obtained in [E1]:

$$
\begin{equation*}
r>\frac{1+\lambda^{2}}{1-\lambda^{2}} . \tag{3.12}
\end{equation*}
$$

For $z=\zeta^{1 / r}>0$ we find:

$$
\begin{equation*}
-\frac{S_{+}^{\prime \prime}(\zeta)}{S_{+}^{\prime}(\zeta)}>\frac{1}{r \zeta}\left[\frac{1+\lambda^{2}}{1-\lambda^{2}}-\frac{1+\lambda^{2} z}{1-\lambda^{2} z}\right] . \tag{3.13}
\end{equation*}
$$

This is positive for $z<1$. For $z=-\zeta^{1 / r} \leqq 0$, we get:

$$
\begin{equation*}
-\frac{S_{-}^{\prime \prime}(\zeta)}{S_{-}^{\prime}(\zeta)}>\frac{1}{r \zeta}\left[\frac{1+\lambda^{2}}{1-\lambda^{2}}-\frac{1-\lambda z}{1+\lambda z}\right] . \tag{3.14}
\end{equation*}
$$

This is positive for $-\lambda \leqq z \leqq 0$. Thus:

$$
\begin{equation*}
-\frac{S_{+}^{\prime \prime}(\zeta)}{S_{+}^{\prime}(\zeta)}>0 \quad \forall \zeta \in[0,1], \quad-\frac{S_{-}^{\prime \prime}(\zeta)}{S_{-}^{\prime}(\zeta)}>0 \quad \forall \zeta \in[0, \tau] . \tag{3.15}
\end{equation*}
$$

To see that the inequalities (3.15) remain strict even in the limit $r \rightarrow \infty$, we rewrite $r$ in $(3.11)$ as $\log (1 / \tau) / \log (1 / \lambda)$ and, using again the bounds (3.10), and $\log (1 / \lambda)$ $<1 / \lambda-1$, we find:

$$
\begin{equation*}
-\frac{S_{+}^{\prime \prime}(\zeta)}{S_{+}^{\prime}(\zeta)}>\frac{1}{\zeta}\left[1-\frac{1+\lambda^{2}}{\lambda(1+\lambda) \log (1 / \tau)}\right] \forall \zeta \in(0,1], \tag{3.16}
\end{equation*}
$$

and exactly the same inequality for $S_{-}^{\prime \prime} / S_{-}^{\prime}$ on $(0, \tau]$. This proves that $L_{+}$and $L_{-}$are convex on $\left[0, y_{0}\right]$ and $\left[y_{0}, 1\right]$ respectively. This completes the proof of Lemma 3.2.

Corollary 3.3. For all $z \in[0,1]$, we have $L_{+}(\tau z)>\tau z$ and $L_{+}^{\prime}(\tau z)<-1$.
Proof. By the monotonicity and convexity of $L_{+}$it suffices to prove this for $z=1$. Applying the functional equation (2.11) and its derivative at $z=0$ gives

$$
\begin{equation*}
L(1)=-\tau, \quad L^{\prime}(1)=-1 . \tag{3.17}
\end{equation*}
$$

Reapplying them at $z=1$ gives

$$
\begin{equation*}
L(L(\tau))=\tau^{2}, \quad L^{\prime}(L(\tau)) L^{\prime}(\tau)=1 \tag{3.18}
\end{equation*}
$$

It follows that $L(\tau)<y_{0}$, and also $L(\tau)>\tau$. Otherwise $L(L(\tau) / \tau)$ would be in $[-1,1]$, contradicting

$$
\begin{equation*}
L(L(\tau) / \tau)=-L\left(\tau^{2}\right) / \tau<-L\left(\tau y_{0}\right) / \tau=-y_{0} / \tau<-1 . \tag{3.19}
\end{equation*}
$$

The convexity of $L_{+}$implies $-L^{\prime}(\tau)>-L^{\prime}(L(\tau))$ and hence $-L^{\prime}(\tau)>1$ by (3.18).
From the convexity of $L_{ \pm}$we can now derive, following an idea of [CE], the existence of invariant cones for the operator $T$. However, the cones we define here do not coincide with the cones defined there because of the use of $v=\delta f / f^{\prime}$ instead of $\delta g$. (The cones of [CE] could not be shown to be invariant under the tangent map for $r$ much above 2 because of the lack of concavity of $g$ on $\left(x_{0}, 1\right]$.)
Definition. Define $\Gamma_{1}$ as the set of real $\mathscr{C}^{1}$ functions $v$ on $[0,1]$ for which
i) $v(z) \geqq 0$ for all $z \in[0,1]$,
ii) $v^{\prime}(z) \leqq 0$ for all $z \in[0,1]$.

We also define $\Gamma=\Gamma_{1} \cap \mathscr{B} . \Gamma$ is a closed cone with non-empty interior in $\mathscr{B}$.
Lemma 3.4. The tangent map T maps $\Gamma_{1}$ into itself. Furthermore, $T^{2}$ maps any nonzero vector in $\Gamma$ into the interior of $\Gamma$.

Proof. Suppose $v \in \Gamma_{1}$. Then, since (by Corollary 3.3) for any $z \in[0,1], L_{+}(\tau z)>\tau z$, and since $v$ is decreasing,

$$
\begin{equation*}
\tau(T v)(z) \geqq v(\tau z)\left[1+1 / L_{+}^{\prime}(\tau z)\right] . \tag{3.20}
\end{equation*}
$$

This is non-negative since $L_{+}^{\prime}(\tau z)<-1$ by Corollary 3.3. Furthermore

$$
\begin{equation*}
(T v)^{\prime}(z)=v^{\prime}\left(L_{+}(\tau z)\right)-\frac{v\left(L_{+}(\tau z)\right) L_{+}^{\prime \prime}(\tau z)}{L_{+}^{\prime}(\tau z)^{2}}+v^{\prime}(\tau z) \tag{3.21}
\end{equation*}
$$

The point is now that all three terms of this formula are non-positive, so that $T v$ is indeed in $\Gamma_{1}$. The interior of $\Gamma$ is clearly composed of those $v$ for which the inequalities defining $\Gamma$ are all strict. Suppose $v \in \Gamma$ is not 0 . If $v(z)$ vanished for some $z \in[0,1)$, it would have to vanish on $[z, 1]$, hence everywhere by analyticity, i.e. 1 is the only place in $[0,1]$ where $v$ can vanish. But $T v$ cannot vanish even at 1 by (3.20). Furthermore the middle term in (3.21) cannot vanish in ( 0,1 , and can vanish at 0 only if $v(1)=0$. Hence $T^{2} v$ is in the interior of $\Gamma$ as claimed.

## 4. Inequalities and Numerical Bounds

Suppose $v_{e} \in \Gamma \backslash\{0\}$ and $T v_{e}=\varrho v_{e}$. Then $v_{e}$ is in the interior of $\Gamma$ by Lemma 3.4, and

$$
\begin{equation*}
\varrho v_{e}(0)=\frac{v_{e}(1)}{\tau L^{\prime}(0)}+\frac{v_{e}(0)}{\tau}>v_{e}(0)\left[\frac{1}{\tau}+\frac{1}{\tau L^{\prime}(0)}\right]>v_{e}(0)\left(\frac{1}{\tau}-\frac{1}{\lambda}\right) . \tag{4.1}
\end{equation*}
$$

The last inequality uses $-\tau L^{\prime}(0)>\lambda$ due to the convexity of $L_{+}$. The middle inequality is strict because $v_{e}$ is in the interior of $\Gamma$, so that $v_{e}(1)<v_{e}(0)$. Finally,
since $v_{e}(1)>0$, we get the inequality announced in the Introduction:

$$
\begin{equation*}
\frac{1}{\tau}-\frac{1}{\lambda}<\frac{1}{\tau}+\frac{1}{\tau L^{\prime}(0)}<\varrho<\frac{1}{\tau} . \tag{4.2}
\end{equation*}
$$

Applying the theorem of Krein and Rutman [KR] we obtain from Lemma 3.4:
Lemma 4.1. As an operator on $\mathscr{B}, T$ possesses an eigenvalue of largest modulus $\delta$ which is real and positive. The spectral subspace corresponding to this eigenvalue is one-dimensional and generated by an element of the interior of $\Gamma$ which is (up to rescaling) the only eigenvector of $T$ in $\Gamma$. This eigenvalue satisfies the bounds (4.2). The adjoint $T^{*}$ of $T$ has a unique eigenvector $\varphi_{e}$ in the cone $\Gamma^{*}$ dual to $\Gamma$ (i.e., the set of continuous linear functionals on $\mathscr{B}$ which take positive values on all elements of $\Gamma$ ) and the corresponding eigenvalue is $\delta$.

At $r=\infty$, we can use the rigorous numerical bounds obtained in [EW1], written here just as ordinary numbers, not as intervals:

$$
y_{0}=0.391132999351022542, \tau=0.033381055, L_{+}^{\prime}(0)=-67.42069 .
$$

This gives

$$
\frac{1}{\tau}=29.957112, \frac{1}{\tau}-1=28.957112, \frac{1}{\tau}\left(1+\frac{1}{L^{\prime}(0)}\right)=29.5128
$$

to be compared with the following numerical estimate of $\delta$ :

$$
\delta=29.5763
$$

This shows that the bounds (4.2) become rather satisfactory at $r=\infty$. They are poorer at, e.g. $r=2$, where

$$
\begin{gathered}
\delta=4.669201609, \text { while } \frac{1}{\tau}=6.26454783121704, \frac{1}{\tau}-\frac{1}{\lambda}=3.7616, \\
f^{\prime}(0)=-1.52763299703630145, \frac{1}{\tau}\left(1+\frac{1}{L^{\prime}(0)}\right)=4.2141 .
\end{gathered}
$$

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Note added in proof. Using the upper bounds on $\tau$ given in [E1], it is easy to see that $(1 / \tau-1 / \lambda)>1$ (and hence $\delta>1$ ) for all $r>1$.


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