## EQUIVALENCE OF NEARBY DIFFERENTIABLE ACTIONS OF A COMPACT GROUP

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In this note we will be concerned with the proof and consequences of the following fact: if  $\phi_0$  is a differentiable action of a compact Lie group on a compact differentiable manifold M, then any differentiable action of G on M sufficiently close to  $\phi_0$  in the  $C^1$ -topology is equivalent to  $\phi_0$ .

- 1. **Notation.** In what follows differentiable means class  $\mathbb{C}^{\infty}$ . If M and V are differentiable manifolds,  $\mathfrak{M}(M, V)$  is the space of differentiable maps of M into V in the  $C^{K}$ -topology where K is a positive integer or  $\infty$  fixed throughout. We denote by Diff (M) the group of automorphisms of M topologized as a subspace of  $\mathfrak{M}(M, M)$ . As such it is a topological group.  $\mathfrak{D}(M)$  is the subgroup of Diff (M) consisting of diffeomorphisms which are the identity outside of some compact set and  $\mathfrak{D}_0(M)$  is the arc component of  $i_M$ , the identity map of M, in  $\mathfrak{D}(M)$ . If M is compact  $\mathfrak{D}(M)$  is locally arcwise connected and  $\mathfrak{D}_0(M)$  is open in  $\mathfrak{D}(M)$  and in fact in  $\mathfrak{M}(M, M)$ . For a definition of the  $C^{K}$ -topology and a proof of the statements made above, see [6]. If G is a Lie group we denote by  $\mathfrak{A}(G, M)$  the space of differentiable actions of G on M, i.e. continuous homomorphisms of G into Diff (M), topologized with the compact-open topology. If  $\phi: g \to g^{\phi}$  is an element of  $\mathfrak{A}(G, M)$  then by a theorem of D. Montgomery [2]  $\tilde{\phi}: (g, m) \to g^{\phi}m$  is an element of  $\mathfrak{M}(G \times M, M)$ . Given  $\phi \in \alpha(G, M)$  and  $f \in \text{Diff}(M)$  then  $\phi$  composed with the inner automorphism of Diff (M) defined by f is another element  $f\phi$  of  $\alpha(G, M)(g^{f\phi} = fg^{\phi}f^{-1})$ . Clearly  $(f, \phi) \rightarrow f\phi$  is jointly continuous<sup>2</sup> and defines an action of Diff (M) on  $\alpha(G, M)$ . We henceforth consider  $\mathfrak{A}(G, M)$  as a Diff (M)-space and, a fortiori as a  $\mathfrak{D}(M)$  and  $\mathfrak{D}_0(M)$ space. Note that the orbit space  $\alpha(G, M)/\text{Diff}(M)$  is just the set of equivalence classes of actions of G on M.
- 2. Statement of main theorem and consequences. The following theorem will be proved in §3.

THEOREM A. If M is a compact differentiable manifold and G is a compact Lie group then the  $\mathfrak{D}_0(M)$ -space  $\mathfrak{A}(G, M)$  admits local cross sections; i.e. given  $\phi_0 \in \mathfrak{A}(G, M)$  there is a neighborhood U of  $\phi_0$  in

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<sup>&</sup>lt;sup>2</sup> This follows from the proposition in [6, §1].

 $\mathfrak{A}(G, M)$  and a continuous map  $\chi: U \to \mathfrak{D}_0(M)$  such that  $\chi(\phi_0) = i_M$  and  $\chi(\phi)\phi_0 = \phi$ .

COROLLARY 1. If  $\phi_t$  is a continuous arc in  $\alpha(G, M)$  then there is a continuous arc  $f_t$  in  $\mathfrak{D}_0(M)$  such that  $f_0 = i_M$  and  $\phi_t = f_t \phi_0$ .

REMARKS. Corollary 1 was proved in [7] by the author and T. E. Stewart under the added hypothesis that  $(g, m, t) \rightarrow \tilde{\phi}_t(g, m)$  was jointly differentiable in all three variables. It was shown there by counter-example that Corollary 1 is invalid if we consider continuous rather than differentiable actions or if we drop either of the conditions that G or M be compact. It follows that all these conditions are also necessary for the validity of Theorem A.

Using that  $\mathfrak{D}_0(M)$  is locally arcwise connected:

COROLLARY 2.  $\mathfrak{A}(G,M)$  is locally arcwise connected. If  $\phi_0 \in \mathfrak{A}(G,M)$  then its orbit under  $\mathfrak{D}_0(M)$  is its arc component in  $\mathfrak{A}(G,M)$  hence an open set, and its orbit under  $\mathfrak{D}(M)$  (i.e. the class of actions equivalent to  $\phi_0$ ) is also open and so a union of arc components. Moreover if  $\Delta = \{f \in \mathfrak{D}(M) | f\phi_0 = \phi_0\}$  is the group of automorphisms of the differentiable G-space  $(M,\phi_0)$  then  $f\Delta \to f\phi_0$  is a homeomorphism of  $\mathfrak{D}(M)/\Delta$  onto  $\mathfrak{D}(M)\phi_0$ .

Since  $\alpha(G, M)$  is separable metric and each equivalence class is open:

COROLLARY 3. There are at most countably many inequivalent differentiable actions of G on M.

REMARKS. It seems likely that by modifying a construction of R. Bing [1] one could construct uncountably many continuous actions of  $Z_2$  on  $S^3$  with fixed point sets pairwise inequivalently embedded 2-spheres. These actions would of course all be inequivalent.

The following extension theorem generalizes Theorem A. On the other hand it is an easy consequence of Theorem A above and Theorem B of [6].

Theorem B. Let H be a Lie group, W a differentiable manifold (neither necessarily compact), G a compact subgroup of H, and M a compact submanifold of W. Let  $\psi_0 \in \mathfrak{A}(H, W)$  such that M is invariant under  $\psi_0 | G$  and let  $\phi_0 \in \mathfrak{A}(G, M)$  be the induced action of G on M. Then given any neighborhood  $\mathfrak O$  of M in W there exists a neighborhood U of  $\phi_0$  in  $\mathfrak{A}(G, M)$  and a map  $\psi: U \to \mathfrak{A}(H, W)$  such that  $\psi(\phi_0) = \psi_0$ ,  $\psi(\phi) | G$  leaves M invariant and induces  $\phi$  on M, and  $\psi(\phi)$  agrees with  $\psi_0$  outside  $\mathfrak O$ . In fact there is a continuous map  $\chi: U \to \mathfrak{D}_0(W)$  such that  $\chi(\phi)$  is the identity outside  $\mathfrak O$  and such that  $\psi(\phi) = \chi(\phi)\psi_0$  satisfies the above conditions.

- 3. **Proof of Theorem A.** By a theorem proved independently by the author [5] and G. D. Mostow [4] there exists an orthogonal representation  $g \rightarrow g^{\psi}$  of G in a Euclidean vector space V and a differentiable  $\phi_0$ -equivariant embedding  $f_0: M \rightarrow V$ . Let  $\emptyset$  be a tubular neighborhood of  $f_0(M)$  in V with respect to the Euclidean metric. Then  $\emptyset$  is invariant under the representation  $\psi$  and the map  $\pi : \mathfrak{O} \rightarrow f_0(M)$  carrying a point of  $\mathfrak{O}$  into the unique nearest point of  $f_0(M)$  is a differentiable equivariant retraction of  $\mathfrak{O}$  onto  $f_0(M)$ . Given  $\phi \in \mathfrak{A}(G, M)$  define  $f_{\phi} : M \to V$  by  $f_{\phi}(m) = \int g^{-1\psi} f_0(g^{\phi}m) dg$  where the integral is with respect to Haar measure on G. Then (cf. [4, p. 434])  $f_{\phi}$  is  $\phi$ -equivariant and clearly  $f_{\phi_0} = f_0$ . The map  $F_{\phi} \in \mathfrak{M}(G \times M, V)$ defined by  $F_{\phi}(g, m) = \tilde{\psi}(g^{-1}, f_0 \circ \tilde{\phi}(g, m))$  is easily seen<sup>2</sup> to depend continuously on  $\phi \in \alpha(G, M)$  and since  $f_{\phi} = \int F_{\phi}(g, m) dg$  it follows that  $\phi \rightarrow f_{\phi}$  is a continuous map of  $\alpha(G, M)$  into  $\mathfrak{M}(M, V)$ . Then for  $\phi$  in a neighborhood U' of  $\phi_0$  in  $\mathfrak{A}(G,M)f_{\phi}(M)\subseteq\mathfrak{O}$  so  $\sigma(\phi)=f_{\phi_0}^{-1}\circ\pi\circ f_{\phi}$  $\in \mathfrak{M}(M, M)$ . Now  $\sigma: U' \rightarrow \mathfrak{M}(M, M)$  is continuous<sup>2</sup> and clearly  $\sigma(\phi_0) = i_M$ . Since  $\mathfrak{D}_0(M)$  is open in  $\mathfrak{M}(M, M)$ , for some smaller neighborhood U of  $\phi_0$  in  $\alpha(G, M)$   $\sigma: U \rightarrow \mathfrak{D}_0(M)$ . Since  $f_{\phi}$ ,  $\pi$ , at  $f_{\phi_0}$  are respectively  $\phi$ -,  $\pi$ - and  $\phi_0$ -equivariant maps into  $(V, \psi)$  it follows that  $\sigma(\phi)g^{\phi} = g^{\phi_0}\sigma(\phi)$  or putting  $\chi(\phi) = \sigma(\phi)^{-1}$ ,  $\chi(\phi)\phi_0 = \phi$ . Q.E.D.
- 4. Conjugacy of neighboring compact subgroups of Diff(M). It is suggested by Theorem A that an analogue of the Montgomery and Zippin conjugacy theorem for neighboring compact subgroups of a Lie group [3] might hold for Diff(M), i.e. that given a compact subgroup G of Diff(M) every compact subgroup of Diff(M) sufficiently close to G is conjugate in Diff(M) to a subgroup of G. This in fact is the case and was the basis of an earlier more complicated proof of Theorem A. A proof will appear elsewhere.

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