## ON THE LIMIT OF A SEQUENCE OF POINT SETS

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A variable point  $P_n$  is said to approach the point P as its limit if to an arbitrary positive  $\epsilon$  there corresponds an m such that

$$\overline{P_nP}<\epsilon, \qquad (n>m).$$

In other words, P is to have the property that every neighborhood of it contains almost all\* the points  $P_n$ .

In attempting to generalize this definition to a sequence of point sets  $M_1$ ,  $M_2$ ,  $\cdots$ , one is naturally led to begin with a definition of the neighborhood of a set and then write down (Definition  $A_0$ ) the last sentence of the last paragraph, replacing the letter P by M.

DEFINITION. By the  $\epsilon$ -neighborhood of a set M is meant the set of all points which have a distance  $< \epsilon$  from some point of M. We shall denote it by  $(\epsilon)_M$ .

DEFINITION  $A_0$ . A point set M is called a limit of the sequence of sets  $M_1, M_2, \cdots$ , if every neighborhood of it contains almost all the sets  $M_i$  as partial sets.

But the above definition is far from being useful, because the limit would then not be unique. In the first place, if the set M is a limit in the sense of Definition  $A_0$ , and if M has a cluster point C, then the set M-C has also the property of being a limit of the sequence. Secondly every set containing M as a partial set is a fortiori a limit.

The first difficulty is overcome by requiring M to be closed, and the second difficulty is met by adding still another condition  $(\gamma)$ :

DEFINITION A. A set M is said to be the limit of the sequence of sets  $M_1, M_2, \cdots$ , if it has the following properties:

( $\alpha$ ) M is closed.

<sup>\*</sup> Thereby is meant that at most a finite number of the points  $P_i$  can lie outside the neighborhood.

- (β) For an arbitrary  $\epsilon > 0$ ,  $(\epsilon)_M \supset M_i^*$  for almost all indices i.
- ( $\gamma$ ) For an arbitrary  $\epsilon > 0$ ,  $(\epsilon)_{M_i} \supset M$  for almost all indices i.

Observe that in the case of a sequence of points,  $(\alpha)$  is fulfilled,  $(\beta)$  and  $(\gamma)$  become equivalent, and the definition reduces to the old one.

The following are immediate consequences of the definition:

- (1) If a sequence of sets has a limit, the limit is unique.
- (2) If a sequence  $\mathfrak{S}$  of point sets has the limit M, every partial sequence of  $\mathfrak{S}$  has the same limit M.

Further results hereby obtained consist of two fundamental criteria for the existence of a limit, when we restrict the sets of the sequence to lying in the same finite region of space. Given a sequence  $\mathfrak{S}$  of sets  $M_1, M_2, \cdots$ , an L-point of  $\mathfrak{S}$  shall be defined as a point which is the limit of a sequence of points  $P_1, P_2, \cdots$ , where each  $P_i$  belongs to the set  $M_i$ .

THEOREM A. Let

$$\mathfrak{S}$$
:  $M_1, M_2, \cdots$ 

be a sequence of point sets such that all the  $M_i$ 's lie in the same finite region of space. Then  $\mathfrak{S}$  has a limit when and only when, whatever partial sequence  $\mathfrak{S}_1$  be selected from  $\mathfrak{S}$ , the set of L-points of  $\mathfrak{S}_1$  coincides with the set of L-points of  $\mathfrak{S}$ . The limit of  $M_i$  is then the set of L-points of  $\mathfrak{S}$ .

THEOREM B. A necessary and sufficient condition for the sequence of sets  $M_i$ , lying in the same finite region of space, to have a limit is that, to an arbitrary positive  $\epsilon$ , there corresponds an  $M_m$  such that

- $(\beta')$   $(\epsilon)_{M_m} \supset M_i$  for almost all indices i,
- $(\gamma')$   $(\epsilon)_{M_i} \supset M_m$  for almost all indices i.

EXAMPLE 1. If each  $M_i$  is closed,  $M_1$  is bounded, and  $M_i \supset M_{i+1}$  for all i's, then a limit M exists and is equal to the set of points common to all the  $M_i$ 's.

EXAMPLE 2. If  $M_{i+1} \supset M_i$  and all the  $M_i$ 's lie in the same finite region of space, then a limit M exists and is equal to the closed cover  $\dagger$  of the set of points which belong to one of the  $M_i$ 's.

<sup>\*</sup> Read: "the  $\epsilon$ -neighborhood of M contains  $M_i$  as a partial set."

<sup>†</sup> The closed cover of a set is the sum of the set and its first derived set.

In the case where each  $M_i$  is a point, the meaning of Theorem A is obvious, while Theorem B leads directly to the fundamental criterion for the variable point  $P_n$  to approach a limit, namely, to an arbitrary  $\epsilon > 0$  there corresponds an m such that  $\overline{P_n P_{n'}} < \epsilon$ , provided that n, n' < m.

But what do these theorems tell us when the set  $M_i$  corresponds to a point function?

To be exact, consider a sequence of functions  $f_1(P)$ ,  $f_2(P)$ ,  $\cdots$ , defined in the same bounded set N of (n-1)-dimensional space, and converging toward a limiting function f(P), in each point P of N. Moreover, let the functions  $f_i(P)$ , f(P) be bounded; that is,  $|f_i(P)| < G$ , |f(P)| < G, where G is the same number for all the functions. To each  $f_i$  corresponds then a bounded set  $M_i$ , formed of the points  $(x_1, x_2, \cdots, x_{n-1}, x_n)$ , where  $P: (x_1, x_2, \cdots, x_{n-1})$  is a point of N and  $x_n = f_i(P)$ . Furthermore, all the sets  $M_i$  lie in the same finite region of space. Let M be the set corresponding to f as  $M_i$  to  $f_i$ . The following result is immediate. If  $f_i$  is uniformly convergent,  $M_i$  has the closed cover of M as its limit. But the converse is not true. For example, let N be the interval (0, 1), and

$$f_i = \begin{cases} \epsilon_i & \text{when } 0 \le x \le \eta_i, \\ 1 - \epsilon_i & \text{when } \eta_i < x \le 1, \end{cases}$$

where  $\epsilon_i > 0$ ,  $\eta_i > 0$ ,  $\epsilon_i > \epsilon_{i+1}$ ,  $\eta_i < \eta_{i+1}$ ,  $\lim_{n=\infty} \epsilon_n = 0$ ,  $\lim_{n=\infty} \eta_n = 1/2$ . Here  $f_i$  converges non-uniformly, while  $M_i$  has the closed cover of M as its limit.

Nevertheless it is true that if N is closed and f is continuous, then  $f_i$  converges uniformly when  $M_i$  approaches M as its limit. Thus under appropriate restrictions Theorem B is equivalent to the condition for uniform convergence, namely,  $f_i$  converges uniformly when and only when, to an arbitrary  $\epsilon > 0$ , there corresponds an m, independent of P, such that

$$|f_n(P) - f_{n'}(P)| < \epsilon, \qquad (m < n, n').$$

Under the same restrictions Theorem A may be translated as follows. The function  $f_i$  is uniformly convergent when and only when, for every sequence of points  $P_1, P_2, \cdots$  of N with the limit P, the sequence of numbers  $f_1(P_1), f_2(P_2), \cdots$  has the limit f(P).

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