# 10. Domains of Square Roots of Regularly Accretive Operators 

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1. Introduction. The purpose of this paper is to give a sufficient condition for the domain of the square root of a regularly accretive operator and that of its adjoint operator to be the same.

Let $X$ and $V$ be two Hilbert spaces with $V \subset X$. Let the inclusion from $V$ into $X$ be continuous, and let $V$ be dense in $X$. We denote by $(f, g)$ (resp. $(u, v)_{V}$ ) the inner product in $X$ (resp. $V$ ) and put $\|f\|=(f, f)^{1 / 2}$ and $\|u\|_{V}=(u, u)_{V}^{1 / 2}$.

Let $a[u, v]$ be a bounded sesquilinear form on $V \times V$;

$$
\begin{equation*}
|a[u, v]| \leqq M\|u\|_{V}\|v\|_{V}, \quad M>0, \text { for any } u, v \in V \tag{1.1}
\end{equation*}
$$

We suppose that $a[u, v]$ is strongly coercive;

$$
\begin{equation*}
\operatorname{Re} a[u, u] \geqq \delta\|u\|_{V}^{2}, \quad \delta>0, \text { for any } u \in V \tag{1.2}
\end{equation*}
$$

Let $A$ be the closed operator associated with the variational triple $\{V, X, a\}$, that is, $u \in V$ belongs to $D(A)$ (the domain of $A$ ) if and only if there exists $f \in X$ such that $a[u, v]=(f, v)$ for any $v \in V$, and we define $A u=f$. We call $A$ a regularly accretive operator.

We define the adjoint form $a^{*}[u, v]$ by $a^{*}[u, v]=\overline{a[v, u]}$ for any $u, v \in V$. It is known that the closed operator associated with the variational triple $\left\{V, X, a^{*}\right\}$ is the adjoint operator $A^{*}$ of $A$.

As is well known, we can construct the fractional power $A^{\theta}(0 \leqq \theta \leqq 1)$ of the regularly accretive operator $A$. Kato [3] showed that $D\left(A^{\theta}\right)=$ $D\left(A^{* \theta}\right) \subset V$ if $0 \leqq \theta<1 / 2$. But generally $D\left(A^{1 / 2}\right)=D\left(A^{* 1 / 2}\right)$ does not hold, for Mcintosh [7] gave a counterexample. On the other hand, Kato and Lions obtained the following results independently.

Theorem A (Kato [4], Lions [6]). Each of the following condition is sufficient for $D\left(A^{1 / 2}\right)=D\left(A^{* 1 / 2}\right)=V$.
(i) Both $D\left(A^{1 / 2}\right)$ and $D\left(A^{* 1 / 2}\right)$ are oversets (or subsets) of $V$.
(ii) $D\left(A^{\theta}\right)=D\left(A^{* \theta}\right)$ for $\theta=1 / 2$ or 1 .
(iii) There exists a Hilbert space $W$ which satisfies (1) $W \subset X$, (2) $V$ is a closed subspace of $[X, W]_{1 / 2}$, (3) $D(A) \subset W$ and $D\left(A^{*}\right) \subset W$, where $[X, W]_{\theta}$ $(0 \leqq \theta \leqq 1)$ denotes the complex interpolation space of $X$ and $W$.

Remark 1. Theorem A-(iii) is due only to Lions.
Remark 2. We may replace Theorem A-(ii) with $D\left(A^{\theta}\right)=D\left(A^{* \theta}\right)$ for some $\theta$ with $1 / 2 \leqq \theta \leqq 1$, because we have $\left[X, D\left(A^{\theta}\right)\right]_{1 /(2 \theta)}=D\left(A^{1 / 2}\right)$.

In the next section we give another sufficient condition for $D\left(A^{1 / 2}\right)=$ $D\left(A^{* 1 / 2}\right)=V$.
2. Main result. The sesquilinear form $a[u, v]$ can be written

$$
a=a_{R}+i a_{I}, \quad a_{R}=\frac{1}{2}\left(a+a^{*}\right), \quad a_{I}=\frac{1}{2 i}\left(a-a^{*}\right),
$$

where $a_{R}$ and $a_{I}$ are symmetric forms.
Let $\Lambda$ be the associated operator with $\left\{V, X, a_{R}\right\}$. Then it is known that $\Lambda$ is a positive self-adjoint operator satisfying $D\left(\Lambda^{1 / 2}\right)=V$ (with the equivalent norm) and $\alpha_{R}[u, u]=\left\|\Lambda^{1 / 2} u\right\|^{2}$ for $u \in V$. We note that

$$
\left|a_{I}[u, v]\right| \leqq \frac{M}{\delta}\left\|\Lambda^{1 / 2} u\right\|\left\|\Lambda^{1 / 2} v\right\|, \quad u, v \in V
$$

holds from (1.1) and (1.2). In order to obtain a sufficient condition for $D\left(A^{1 / 2}\right)=D\left(A^{* 1 / 2}\right)=V$ we need a stronger estimate for $a_{I}$ as follows.

Theorem 1. Let $0<\theta \leqq 1$. Suppose that
(2.1) $\quad\left|a_{I}[u, v]\right| \leqq M_{1}\left\|\Lambda^{\theta / 2} u\right\|\left\|\Lambda^{\theta / 2} v\right\|, \quad M_{1}>0$, for any $u, v \in V$.

Then we have for any $\sigma$ with $0<\sigma<1-\theta / 2$,
(2.2) $\quad D\left(\Lambda^{\sigma}\right) \subset D\left(A^{\sigma}\right)$,
(2.3) $\quad\left\|A^{\sigma} u-\Lambda^{\sigma} u\right\| \leqq C\left\|\Lambda^{\sigma-(1-\theta) / 2} u\right\|, \quad C>0$, for any $u \in D\left(\Lambda^{\sigma}\right)$. If we replace $A$ with $A^{*}$, (2.2) and (2.3) remain valid.

Proof. Our proof is a slight modification of Kato [3] who proved Theorem 1 when $\theta=1$.

There exists a bounded symmetric operator in $X$ such that

$$
\begin{equation*}
(B u, v)=a_{I}\left[\Lambda^{-1 / 2} u, \Lambda^{-1 / 2} v\right], \quad u, v \in X \tag{2.4}
\end{equation*}
$$

Then we have

$$
\begin{align*}
& A=\Lambda^{1 / 2}(1+i B) \Lambda^{1 / 2}  \tag{2.5}\\
& (A+\lambda)^{-1}=(\Lambda+\lambda)^{-1}+\frac{\Lambda^{1 / 2}}{\Lambda+\lambda} B D_{\lambda} \frac{\Lambda^{1 / 2}}{\Lambda+\lambda}, \quad \lambda>0 \tag{2.6}
\end{align*}
$$

where $D_{\lambda}$ is a bounded operator in $X$ with $\left\|D_{\lambda}\right\| \leqq 1+\|B\|$. The proof of (2.4)-(2.6) is found in Kato [3].

Let $0<\sigma<1-\theta / 2$. Now we shall show that for $u \in D\left(\Lambda^{\sigma}\right)$,

$$
\begin{equation*}
w=\lim _{R \rightarrow \infty} \int_{0}^{R} \lambda^{\sigma}\left\{(A+\lambda)^{-1}-(\Lambda+\lambda)^{-1}\right\} u d \lambda \tag{2.7}
\end{equation*}
$$

exists and that

$$
\begin{equation*}
\|w\| \leqq C\left\|\Lambda^{\sigma-(1-\theta) / 2} u\right\|, \quad C>0 \tag{2.8}
\end{equation*}
$$

Here and in the sequel we denote by $C$ positive constants independent of $u, v, \lambda, t, a$ and $b$ which may differ from each other. From (2.1), (2.4) and (2.6) we have for any $v \in X$,

$$
\begin{align*}
\left|\left(\left\{(A+\lambda)^{-1}-(\Lambda+\lambda)^{-1}\right\} u, v\right)\right| & \leqq\left|a_{I}\left[\Lambda^{-1 / 2} D_{\lambda} \frac{\Lambda^{1 / 2}}{\Lambda+\lambda} u, \frac{1}{\Lambda+\lambda} v\right]\right|  \tag{2.9}\\
& \leqq C\left\|\frac{\Lambda^{1 / 2}}{\Lambda+\lambda} u\right\|\left\|\frac{\Lambda^{\theta / 2}}{\Lambda+\lambda} v\right\|
\end{align*}
$$

Let $0<a<b<\infty$. It follows from (2.9) and Schwarz' inequality that

$$
\begin{aligned}
& \left|\int_{a}^{b} \lambda^{\sigma}\left(\left\{(A+\lambda)^{-1}-(\Lambda+\lambda)^{-1}\right\} u, v\right) d \lambda\right|^{2} \\
& \quad \leqq C\left(\int_{a}^{b} \lambda^{2 \sigma+\theta-1}\left\|\frac{\Lambda^{1 / 2}}{\Lambda+\lambda} u\right\|^{2} d \lambda\right)\left(\int_{a}^{b} \lambda^{1-\theta}\left\|\frac{\Lambda^{\theta / 2}}{\Lambda+\lambda} v\right\|^{2} d \lambda\right) .
\end{aligned}
$$

Let $\left\{E_{t}\right\}$ be the spectral resolution of $\Lambda$. Then we have

$$
\begin{aligned}
\int_{a}^{b} \lambda^{1-\theta}\left\|\frac{\Lambda^{\theta / 2}}{\Lambda+\lambda} v\right\|^{2} d \lambda & \leqq \int_{0}^{\infty} \lambda^{1-\theta} d \lambda \int_{0}^{\infty} \frac{t^{\theta}}{(t+\lambda)^{2}} d_{t}\left\|E_{t} v\right\|^{2} \\
& \leqq \int_{0}^{\infty}\left(\int_{0}^{\infty} \frac{\lambda^{1-\theta}}{(1+\lambda)^{2}} d \lambda\right) d_{t}\left\|E_{t} v\right\|^{2} \leqq C\|v\|^{2}
\end{aligned}
$$

Hence we obtain
where

$$
\begin{aligned}
\left\|\int_{a}^{b} \lambda^{\sigma}\left\{(A+\lambda)^{-1}-(\Lambda+\lambda)^{-1}\right\} u d \lambda\right\|^{2} & \leqq C \int_{a}^{b} \lambda^{2 \sigma+\theta-1} d \lambda \int_{0}^{\infty} \frac{t}{(t+\lambda)^{2}} d_{t}\left\|E_{t} u\right\|^{2} \\
& \leqq C \int_{0}^{\infty} t^{2 \sigma+\theta-1} F(t ; a, b) d_{t}\left\|E_{t} u\right\|^{2} \\
F(t ; a, b) & =\int_{a / t}^{b / t} \frac{\lambda^{2 \sigma+\theta-1}}{(\lambda+1)^{2}} d \lambda .
\end{aligned}
$$

Noting that $\lim _{a \rightarrow \infty} F(t ; a, b)=0$ and $F(t ; a, b) \leqq F(1 ; 0, \infty)<\infty$ for $-1<2 \sigma$ $+\theta-1<1$ and that $D\left(\Lambda^{\sigma}\right) \subset D\left(\Lambda^{\sigma-(1-\theta) / 2}\right)$, we conclude from the bounded convergence theorem that (2.7) exists and that (2.8) holds.

On the other hand, it follows from the definition of fractional powers or the spectral resolution of $\Lambda$ that

$$
\begin{equation*}
\Lambda^{\sigma} u=\frac{\sin \pi \sigma}{\pi} \lim _{R \rightarrow \infty} \int_{0}^{R} \lambda^{\sigma}\left\{\lambda^{-1}-(\Lambda+\lambda)^{-1}\right\} u d \lambda . \tag{2.10}
\end{equation*}
$$

It follows from (2.7) and (2.10) that

$$
\begin{equation*}
w^{\prime}=\frac{\sin \pi \sigma}{\pi} \lim _{R \rightarrow \infty} \int_{0}^{R} \lambda^{\sigma}\left\{\lambda^{-1}-(A+\lambda)^{-1}\right\} u d \lambda \tag{2.11}
\end{equation*}
$$

exists. Therefore we have $u \in D\left(A^{\sigma}\right)$ and $w^{\prime}=A^{\sigma} u$ (see Kato [1]). Hence we have proved $D\left(\Lambda^{\sigma}\right) \subset D\left(A^{\sigma}\right)$. (2.3) follows from (2.7), (2.8), (2.10) and (2.11).

Similarly we get the statement for $A^{*}$.
Q.E.D.

Combining Theorem A-(i) and Theorem 1, we get the following
Theorem 2. Let (2.1) hold for some $\theta$ with $0 \leqq \theta<1$. Then we have $D\left(A^{1 / 2}\right)=D\left(A^{* 1 / 2}\right)=V$.

Remark 3. Shimakura [9] treated another type of perturbation. He considered a not necessarily regularly accretive operator $A=\Lambda+K$ in the Hilbert space $X$ where $\Lambda$ is a strictly positive self-adjoint operator with the domain $D(\Lambda)$ dense in $X$, and $K$ is a linear operator whose domain $D(K)$ contains $D(\Lambda)$. He obtained $D\left(A^{\theta}\right)=D\left(\Lambda^{\theta}\right)$ for any $\theta$ with $0 \leqq \theta \leqq 1$, assuming that the resolvent $(A+\lambda)^{-1}$ and $(\Lambda+\lambda)^{-1}$ satisfy some conditions. We note that $D(A)=D(\Lambda)$ in his case. On the other hand, in Theorem 2 we have $D(A) \neq D(\Lambda)$ generally, although we restrict ourselves to the case of regularly accretive operators. Hence our result is different from Shimakura's result.

It is interesting to investigate whether Theorem 1 can be improved or not, that is, whether $D\left(A^{\sigma}\right)=D\left(A^{* \sigma}\right)=D\left(\Lambda^{\sigma}\right)$ is valid or not for any $\sigma$ with $0<\sigma<1-\theta / 2$ under condition (2.1). The following gives an affirmative example to this problem. Let $I=(0,1) \subset R$. Let $X=L_{2}(I)$ and $V=H^{2}(I)$
where $H^{2}(I)$ is the Sobolev space. For $\alpha \in \boldsymbol{C} \backslash \boldsymbol{R}$ let us put

$$
a[u, v]=\int_{I}\left(u^{\prime \prime}(x) \overline{v^{\prime \prime}(x)}+\alpha u^{\prime}(x) \overline{v^{\prime}(x)}\right) d x .
$$

The domains of fractional powers of $A, A^{*}$ and $\Lambda$ are given in terms of the boundary conditions such as

$$
\begin{align*}
& u^{\prime \prime}(0)=u^{\prime \prime}(1)=0,  \tag{2.12}\\
& \int_{0}^{1} \frac{\left|u^{\prime \prime}(x)\right|^{2}}{d(x)} d x<\infty,  \tag{2.13}\\
& u^{(3)}(0)-\alpha u^{\prime}(0)=u^{(3)}(1)-\alpha u^{\prime}(1)=0,  \tag{2.14}\\
& \int_{0}^{1} \frac{\left|u^{(3)}(x)-\alpha u^{\prime}(x)\right|^{2}}{d(x)} d x<\infty, \tag{2.15}
\end{align*}
$$

where $d(x)=\min \{|x|,|x-1|\}$. We put

$$
E_{\alpha}=\left\{u \in H^{4}(I) ; u \text { satisfies (2.12) and (2.14) }\right\}
$$

and obtain
(2.16)

$$
D(A)=E_{\alpha}, \quad A u=u^{(4)}-\alpha u^{(2)} .
$$

For $A^{*}$ (resp. $\Lambda$ ) we have (2.16) with $\alpha$ replaced by $\bar{\alpha}$ (resp. $\operatorname{Re} \alpha$ ). Clearly we have $D(A) \neq D\left(A^{*}\right) \neq D(\Lambda) \neq D(A)$. From the interpolation theorem and Grisvard [2, Theorem 8.1] it follows that

$$
\begin{array}{rll}
D\left(A^{\sigma}\right) & =\left[L_{2}(I), D(A)\right]_{\sigma} \\
& = \begin{cases}H^{4 \sigma}(I) & \left(0<\sigma<\frac{5}{8}\right) \\
\left\{u \in H^{5 / 2}(I) ; u \text { satisfies }(2.13)\right\} & \left(\sigma=\frac{5}{8}\right) \\
\left\{u \in H^{4 \sigma}(I) ; u \text { satisfies }(2.12)\right\} & \left(\frac{5}{8}<\sigma<\frac{7}{8}\right) \\
\left\{u \in H^{7 / 2}(I) ; u \text { satisfies }(2.12) \text { and }(2.15)\right\} & \left(\sigma=\frac{7}{8}\right) \\
\left\{u \in H^{4 \sigma}(I) ; u \text { satisfies }(2.12) \text { and }(2.14)\right\} & \left(\frac{7}{8}<\sigma<1\right) .\end{cases}
\end{array}
$$

The domains of fractional powers of $A^{*}$ and $\Lambda$ are given in the similar way. Therefore it follows that

$$
D\left(A^{\sigma}\right)=D\left(A^{* \sigma}\right)=D\left(\Lambda^{\sigma}\right), \quad \text { for } 0<\sigma<\frac{7}{8}
$$

and

$$
D\left(A^{\sigma}\right) \neq D\left(A^{* \sigma}\right) \neq D\left(\Lambda^{\sigma}\right) \neq D\left(A^{\sigma}\right), \quad \text { for } \frac{7}{8} \leqq \sigma \leqq 1 .
$$

On the other hand, we have for some $M_{1}>0$,

$$
\left|a_{I}[u, v]\right| \leqq|\operatorname{Im} \alpha|\left\|u^{\prime}\right\|_{L_{2}(I)}\left\|v^{\prime}\right\|_{L_{2}(I)} \leqq M_{1}\left\|\Lambda^{1 / 4} u\right\|\left\|\Lambda^{1 / 4} v\right\|
$$

where the last inequality is due to Lemma 3 in the next section. Thus this example suggests the possibility of an improvement of Theorem 1.
3. Application. We can apply Theorem 2 to the non-self-adjoint elliptic operator with non-smooth coefficients and a non-smooth boundary. Let $m$ and $n$ be positive integers. Let $\Omega$ be a bounded domain in $R^{n}$ with the restricted cone property. Let $X=L_{2}(\Omega)$. Let $V$ be the closed subspace of the Sobolev space $H^{m}(\Omega)$ including $H_{0}^{m}(\Omega)$ (the closure of $C_{0}^{\infty}(\Omega)$ in $H^{m}(\Omega)$ ). We denote by $\left\|\|_{m}\right.$ the norm of $H^{m}(\Omega)$. Let $a[u, v]$ be an integro-differential sesquilinear form of order $m$ with bounded coefficients;

$$
a[u, v]=\int_{\Omega|\alpha|,|\beta| \leq m} a_{\alpha \beta}(x) D^{\alpha} u(x) \overline{D^{\beta} v(x)} d x, \quad u, v \in V,
$$

$$
\alpha=\left(\alpha_{1}, \cdots, \alpha_{n}\right), \quad D^{\alpha}=(-\sqrt{-1})^{|\alpha|}\left(\partial / \partial x_{1}\right)^{\alpha_{1}} \cdots\left(\partial / \partial x_{n}\right)^{\alpha_{n}}
$$

which satisfies (1.2). Let $A$ and $\Lambda$ be the operators as defined in the previous sections.

Lemma 3. In the above situation we have

$$
\left\|D^{\alpha} u\right\| \leqq C\left\|\Lambda^{|\alpha| / 2 m} u\right\|, \quad 0 \leqq|\alpha| \leqq m, u \in V
$$

Proof. It follows from the complex interpolation theory that

$$
\begin{aligned}
H^{k}(\Omega) & =\left[L_{2}(\Omega), H^{m}(\Omega)\right]_{k / m} \supset\left[L_{2}(\Omega), V\right]_{k / m} \\
& =\left[L_{2}(\Omega), D\left(\Lambda^{1 / 2}\right)\right]_{k / m}=D\left(\Lambda^{k / 2 m}\right), \quad 0 \leqq k \leqq m
\end{aligned}
$$

which gives the lemma.
Q.E.D.

Theorem 4. Suppose that
(3.1) $\quad a_{\alpha \beta}=\overline{a_{\beta \alpha}} \quad(|\alpha|+|\beta|=2 m, 2 m-1)$.

Then we have $D\left(A^{1 / 2}\right)=D\left(A^{* 1 / 2}\right)=V$.
Proof. It follows from the assumption that

$$
\left|a_{I}[u, v]\right| \leqq M_{1}\|u\|_{m-1}\|v\|_{m-1}, \quad M_{1}>0, \quad \text { for any } u, v \in V
$$

Combining the above inequality and Lemma 3, we get (2.1) for $\theta=1-1 / \mathrm{m}$. Therefore we can apply Theorem 2 to obtain the theorem.
Q.E.D.

We stress that the smoothness of the coefficients $a_{\alpha \beta}$ and the boundary $\partial \Omega$ are not assumed in Theorem 4. When the coefficients and the boundary are sufficiently smooth and when $V$ satisfies some condition such as $V=$ $H^{m}(\Omega)$ or $V=H_{0}^{m}(\Omega)$ etc., Lions [6] also obtained Theorem 4 without assuming (3.1) by using the relations $D(A) \subset H^{2 m}(\Omega), D\left(A^{*}\right) \subset H^{2 m}(\Omega)$ and $\left[L_{2}(\Omega)\right.$, $\left.H^{2 m}(\Omega)\right]_{1 / 2}=H^{m}(\Omega)$, and applying Theorem A-(iii) with $W=H^{2 m}(\Omega)$. We note that $D(A) \subset H^{2 m}(\Omega)$ and $D\left(A^{*}\right) \subset H^{2 m}(\Omega)$ do not always hold when the coefficients and the boundary are not smooth. It seems reasonable to conjecture that Theorem 4 is valid without assuming (3.1). However this question remains open.

Our result remains valid if $a[u, v]$ has some boundary integrals containing derivatives of order $\leqq m-1$ when $\partial \Omega$ is sufficiently smooth.

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