# 52. Index, Localization and Classification of Characteristic Surfaces for Linear Partial Differential Operators 

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Let $P(z, \partial)$ be a linear partial differential operator of order $m$ with holomorphic coefficients in $\Omega \subset C^{n+1}$, and $K$ be a connected nonsingular hypersurface in $\Omega$. Characteristic indices and the localization on $K$ of $P(z, \partial)$ are defined by means of a special coordinate in [6]. In the present paper we give another definition of them, new notions and a classification of characteristic surfaces of $P(z, \partial)$.
§1. Definitions. $z=\left(z_{0}, z_{1}, \cdots, z_{n}\right)=\left(z_{0}, z^{\prime}\right)$ denotes a point in $C^{n+1}, \partial=\left(\partial_{0}, \partial_{1}, \cdots, \partial_{n}\right)=\left(\partial_{0}, \partial^{\prime}\right), \partial_{i}=\partial / \partial_{z_{i}} . \quad$ For a domain $U \subset C^{n+1}, \mathcal{O}(U)$ is the set of all holomorphic functions in $U$ and $\mathcal{L}(U)$ is the set of all holomorphic vector fields in $U$. For a multi-index $\alpha=\left(\alpha_{0}, \alpha_{1}, \cdots, \alpha_{n}\right)=$ $\left(\alpha_{0}, \alpha^{\prime}\right), \alpha_{i} \in Z_{+}=N \cup\{0\},|\alpha|=\alpha_{0}+\left|\alpha^{\prime}\right|=\alpha_{0}+\alpha_{1}+\cdots+\alpha_{n}$ and for $X=\left(X_{0}\right.$, $\left.X_{1}, \cdots, X_{n}\right)=\left(X_{0}, X^{\prime}\right) \in \mathcal{L}(U)^{n+1}, X^{\alpha}=\left(X_{0}\right)^{\alpha_{0}}\left(X_{1}\right)^{\alpha_{1}} \cdots\left(X_{n}\right)^{\alpha_{n}}=\left(X_{0}\right)^{\alpha_{0}}\left(X^{\prime}\right)^{\alpha^{\prime}}$.

For a point $p \in K$, there is a neighbourhood $U$ of $p$ such that $K \cap U$ $=\{z \in U ; \varphi(z)=0\}$ with $\varphi(z) \in \mathcal{O}(U)$ and $d \varphi(z) \neq 0$ on $K$. For $f(z) \in \mathcal{O}(U)$, $|f|=j \in Z_{+} \cup\{+\infty\}$ means that $f(z)=\varphi(z)^{j} g(z)$ with $g(z) \neq 0$ on $K$. If $f(z) \equiv 0,|f|=+\infty$.

We can find $X=\left(X_{0}, X_{1}, \cdots, X_{n}\right) \in \mathcal{L}(U)^{n+1}$, by shrinking $U$ if necessary, such that
(1.1) $\left\langle d \varphi, X_{0}\right\rangle \neq 0$ on $K$ and $\left\langle d \varphi, X_{i}\right\rangle=0$ on $K$ for $1 \leq i \leq n$,
(1.2) $\left\{X_{i}\right\}(0 \leq i \leq n)$ are linearly independent at each point in $U$, where $\langle$,$\rangle means the product of cotangent and tangent vectors.$

Hence we can write $P(z, \partial)$ in $U$, by using $\left\{X_{i}\right\}$, as follows :

$$
\begin{equation*}
P(z, \partial)=\sum_{k=0}^{m}\left(\sum_{|\alpha|=k} A_{\alpha}(z) X^{\alpha}\right)=\sum_{k=0}^{m}\left(\sum_{|\alpha|=k} a_{\alpha}(z) \varphi(z)^{j_{\alpha}}\left(X_{0}\right)^{\alpha_{0}}\left(X^{\prime}\right)^{\alpha^{\alpha}}\right), \tag{1.3}
\end{equation*}
$$

where $A_{\alpha}(z)=a_{\alpha}(z) \varphi(z)^{j \alpha}$ and $j_{\alpha}=\left|A_{\alpha}\right|$. Put

$$
\left\{\begin{array}{l}
d_{k}=\min \left\{j_{\alpha}+\left|\alpha^{\prime}\right| ;|\alpha|=k\right\}, \quad J_{k}=\min \left\{j_{\alpha} ;|\alpha|=k, j_{\alpha}+\left|\alpha^{\prime}\right|=d_{k}\right\},  \tag{1.4}\\
L_{k}=d_{k}-J_{k} .
\end{array}\right.
$$

We can define quantities $\left\{\sigma_{i}\right\}$ and $\left\{\sigma_{p, j}\right\}$ by the same way as in [6]. Let $A=\left\{\left(k, d_{k}\right) \in R^{2} ; d_{k} \neq+\infty, 0 \leq k \leq m\right\}$ and $\hat{A}$ be the convex hull of $A$. If $A=\left\{\left(m, d_{m}\right)\right\}$, we put $\sigma_{1}=1$. Otherwise the lower convex part of the boundary $\partial \hat{A}$ of $\hat{A}$ consists of segments $\Sigma_{1}(i)(1 \leq i \leq l)$ (see Fig. 1). Let $A_{1}=\left\{\left(k_{i}, d_{k_{i}}\right) ; 0 \leq i \leq l\right\}, m=k_{0}>k_{1}>\cdots>k_{l} \geq 0$, be the set of vertices of $\bigcup_{i=1}^{l} \Sigma_{1}(i)$. Put

$$
\begin{equation*}
\sigma_{i}=\max \left\{\left(d_{k_{i-1}}-d_{k_{i}}\right) /\left(k_{i-1}-k_{i}\right), 1\right\} . \tag{1.5}
\end{equation*}
$$

Then there is a $p \in N$ such that $\sigma_{1}>\sigma_{2}>\cdots>\sigma_{p}=1$. Put

$$
\begin{align*}
C(i)=\left\{\alpha \in Z_{+}^{n+1} ;|\alpha|=k_{i},\left|\alpha^{\prime}\right|=\right. & \left.L_{k_{i}}, j_{\alpha}=J_{k_{i}}\right\}  \tag{1.6}\\
\tilde{P}_{i}(z, \partial)=\sum_{\alpha \in C(i)} a_{\alpha}(z)\left(X^{\prime}\right)^{\alpha^{\prime}} & (0 \leq i \leq p-1) \tag{1.7}
\end{align*}
$$


(Fig. 1)

(Fig. 2)

Let us also consider $B=\left\{\left(k, J_{k}\right) \in R^{2} ; d_{k_{p-1}}-d_{k}=k_{p-1}-k, 0 \leq k\right.$ $\left.\leq k_{p-1}\right\}$ to define $\left\{\sigma_{p, i}\right\}$. If $B=\left\{\left(k_{p-1}, J_{k_{p-1}}\right)\right\}$, we put $\sigma_{p, 1}=1$. Otherwise the lower convex part of the boundary $\partial \hat{B}$ of the convex hull $\hat{B}$ of $B$ consists of segments $\Sigma_{2}(i)\left(1 \leq i \leq l^{\prime}\right)$ (see Fig. 2). Let $B_{1}=\left\{\left(r_{i}, J_{r_{i}}\right) ; 0 \leq i\right.$ $\left.\leq l^{\prime}\right\}, k_{p-1}=r_{0}>r_{1}>\cdots>r_{l^{\prime}}>0$. Put (1.8)

$$
\sigma_{p, i}=\max \left\{\left(J_{r_{i-1}}-J_{r_{i}}\right) /\left(r_{i-1}-r_{i}\right), 1\right\}
$$

Hence there is a $q \in N$ such that $\sigma_{p, 1}>\sigma_{p, 2}>\cdots>\sigma_{p, q}=1$. Put

$$
\begin{gather*}
C(p, i)=\left\{\alpha \in \mathrm{Z}_{+}^{n+1} ;|\alpha|=r_{i},\left|\alpha^{\prime}\right|=L_{r_{i}}, j_{\alpha}=J_{r_{i}}\right\},  \tag{1.9}\\
\tilde{P}_{p, i}(z, \partial)=\sum_{\alpha \in C(p, i)} a_{\alpha}(z)\left(X^{\prime}\right)^{\alpha^{\prime}} \quad(1 \leq i \leq q-1) .
\end{gather*}
$$

Definition 1.1. We call $\sigma_{i}(1 \leq i \leq p)$ the $i$-th characteristic index of $K$ and $\sigma_{p, i}(1 \leq i \leq q)$ the ( $p, i$ )-characteristic index of $K$ for $P(z, \partial)$.

We may restrict $\tilde{P}_{i}(\mathrm{z}, \partial)(0 \leq i \leq p-1)$ and $\tilde{P}_{p, i}(z, \partial)(1 \leq i \leq q-1)$ on $K$, have operators on $K$ and denote them by $P_{\mathrm{loc}, K, i}$ and $P_{1 \mathrm{loc}, K,(p, i)}$ respectively.

Definition 1.2. We call $P_{\mathrm{loc}, K, i}$ the $i$-th localization on $K$ of $P(z, \partial)$ and $P_{\text {loc }, K,(p, i)}$ the ( $\left.p, i\right)$-localization on $K$ of $P(z, \partial)$.

Remark 1.3. In [6] we call $\sigma_{p, i}$ the $i$-th subcharacteristic index and only $P_{\text {loc }, K, 0}$ is defined and called the localization.

The characteristic indices and the localizations are defined by $\varphi(z)$ and $\left\{X_{i}\right\}(0 \leq i \leq n)$. Let $\psi(z) \in \mathcal{O}(V)$ be another function defining $K$ and $Y=\left(Y_{0}, Y_{1}, \cdots, Y_{n}\right) \in \mathcal{L}(V)^{n+1}$ be vector fields with properties (1.1)(1.2) for $\psi(z)$ and $\left\{Y_{i}\right\}(0 \leq i \leq n)$ in a neighbourhood $V$ of $p$. Then we have in $U \cap V$,

$$
\begin{equation*}
\varphi(z)=\chi(z) \psi(z), \quad X_{i}=\sum_{j=0}^{n} a_{i, j}(z) Y_{j} \quad(0 \leq i \leq n), \tag{1.11}
\end{equation*}
$$

where $\chi(z), a_{i, j}(z) \in \mathcal{O}(U \cap V), \quad \chi(z) \neq 0$ and $\operatorname{det}\left(a_{i, j}(z)\right) \neq 0$ in $U \cap V$. From (1.1)-(1.2), we have

Lemma 1.1. The following holds in (1.11):

$$
\begin{equation*}
\left.a_{0,0}(z)\right|_{K \cap U \cap V} \neq 0 \quad \text { and } \quad a_{i, 0}(z)_{K \cap U \cap V}=0 \quad \text { for } 1 \leq i \leq n . \tag{1.12}
\end{equation*}
$$

We denote by $\sigma_{i}(\psi, Y)\left(1 \leq i \leq p^{\prime}\right)$ and $\sigma_{p^{\prime}, j}(\psi, Y)\left(1 \leq j \leq q^{\prime}\right)$ characteristic indices, and by $P_{\text {loc }, K, i}(\psi, Y)$ and $P_{\text {loo }, K,\left(p^{\prime}, j\right)}(\psi, Y)$ localizations of $P(z, \partial)$ defined by $\psi(z)$ and $Y$. Let $Q(z, \partial)$ be an operator homogeneous in $X$ with degree $k$,
(1.13) $\quad Q(z, \partial)=\sum_{|\alpha|=k} B_{\alpha}(z) X^{\alpha}=\sum_{|\alpha|=k} B_{\alpha}(z)\left\{\prod_{i=0}^{n}\left(\sum_{j=0}^{n} a_{i, j}(z) Y_{j}\right)^{\alpha i}\right\}$.

In the sequel P.S.L means the principal symbol of an operator $L$. We have from Lemma 1.1,

Lemma 1.2. The followings hold for $Q(z, \partial)$ :

$$
\begin{equation*}
\sigma_{1}(\varphi, X)=\sigma_{1,1}(\varphi, X)=\sigma_{1}(\psi, Y)=\sigma_{1,1}(\psi, Y)=1 \tag{1.14}
\end{equation*}
$$ where $h(s)(s \in K \cap U \cap V)$ is a holomorphic function on $K \cap U \cap V$ and $h(s)$ does not vanish on $K \cap U \cap V$.

Consequently we have from Lemma 1.2,
Theorem 1.3. The characteristic indices $\left\{\sigma_{i}\right\}(1 \leq i \leq p)$ and $\left\{\sigma_{p, j}\right\}$ $(1 \leq j \leq q)$ don't depend on $\varphi(z)$ defining $K$ and vector fields $\left\{X_{i}\right\}(0 \leq i$ $\leq n)$ satisfying (1.1)-(1.2).

For the localization we have
Theorem 1.4. There are holomorphic functions $h_{i}(s)(0 \leq i \leq p$ $-1)$ and $h_{p, j}(s)(1 \leq j \leq q-1)$ on $K \cap U \cap V$ such that
(i) $h_{i}(s) \neq 0$ and $h_{p, j}(s) \neq 0$ on $K \cap U \cap V$,
(ii )-(a) P.S.P ${ }_{\text {⿺oc, } K, i}(\varphi, X)=h_{i}(s)$ P.S. $\mathrm{P}_{\mathrm{loc}, K, i}(\psi, Y)$,
-(b) P.S. $\mathrm{P}_{1 \mathrm{oc}, K,(p, j)}(\varphi, X)=h_{p, j}(s)$ P.S.P $\mathrm{P}_{1 \mathrm{oc}, K,(p, j)}(\psi, Y)$.
Finally we give a classification of characteristic surfaces.
Definition 1.4. Suppose that $K$ is characteristic for $P(z, \partial)$.
(a) If $\sigma_{1}>1$, then $K$ is called irregular.
(b) If $\sigma_{1}=1$ and $\sigma_{1,1}>1$, then $K$ is called weakly irregular.
(c) If $\sigma_{1}=\sigma_{1,1}=1$, then $K$ is called regular.
§2. Remarks. (i) Let $P(z, \partial)$ be an operator with decomposable principal part, namely said to have constant multiple characteristics (see [2], [4]), and $K$ be its characteristic surface. Let $\tilde{\sigma}$ be the irregularity of characteristic elements defined in [4]. Then $\sigma_{1} \leq \tilde{\sigma}$. For $P(z, \partial)=\left(\partial_{1}\right)^{2}+z_{0} \partial_{0}$ and $K=\left\{z_{0}=0\right\}$, we have $\sigma_{1}=1$, but $\tilde{\sigma}=2$. If $P(z, \partial)$ satisfies the Levi's condition, namely $\tilde{\sigma}=1$, we have $\sigma_{1}=\sigma_{1,1}=1$.
(ii) Let $P(z, \partial)$ be an operator treated in [1], [3], where characteristic initial value problems were considered. We have $\sigma_{1}=\sigma_{1,1}=1$ for their initial characteristic surface.
(iii) If $K$ is generically noncharacteristic, that is, P.S.P ( $z$, $\xi)\left.\right|_{z \in K, \xi=d \varphi(z)} \neq 0$, then $\sigma_{1}=\sigma_{1,1}=1$. If $P(z, \partial)$ is an ordinary differential operator, then $\sigma_{p, 1}=1$.

We give some examples. Let $K=\left\{z_{0}=0\right\}$.

$$
\begin{align*}
& \left\{\begin{array}{l}
P(z, \partial)=\left(\partial_{0}\right)^{m-l}\left(\partial_{1}\right)^{l}+\sum_{|\beta| \leq m, \beta \neq \alpha} a_{\beta}(z) \partial^{\beta}, \quad \alpha=(m-l, l, 0, \cdots, 0), \\
\left.a_{\beta}(z)=0\left(\mid z_{0}\right)^{\beta}\right) \quad\left(\delta=\max \left(\beta_{0}-m+l, 0\right)\right) \quad \text { for }|\beta|=m \text { and } \beta \neq \alpha, \\
P_{\text {loc }, K, 0}=\left(\partial_{1}\right)^{l}+\sum_{\left|\beta^{\prime}\right|=l, \beta \neq \alpha} a_{\left(m-l, \beta^{\prime}\right)}\left(0, z^{\prime}\right)\left(\partial^{\prime}\right)^{\beta^{\prime}} .
\end{array}\right.  \tag{2.1}\\
& \left\{\begin{array}{l}
P(z, \partial)=\left(z_{0}\right)^{2}\left(\partial_{0}\right)^{2}\left(\partial_{1}\right)^{2}+\left(\partial_{1}\right)^{4}+\left(z_{0}\right)^{2}\left(\partial_{0}\right)^{3}+\left(\partial_{1}\right)\left(\partial_{0}\right), \\
\sigma_{1}=2, \quad \sigma_{2}=1, \quad \sigma_{2,1}=2, \quad \sigma_{2,2}=1, \quad P_{\text {loc }, K, 0}=\left(\partial_{1}\right)^{4}, \quad P_{1 \mathrm{oc}, K, 1}=I, \\
P_{\text {1oc }, K,(2,1)}=\partial_{1} .
\end{array}\right. \\
& \left\{\begin{array}{l}
P(z, \partial)=\left(z_{0}\right)^{2}\left(\partial_{0}\right)^{2} \partial_{1}+\left(\partial_{1}\right)^{2}+z_{0} b(z) \partial_{0}+c(z) \partial_{1}+d(z), \\
\sigma_{1}=1, \quad \sigma_{1,1}=2, \quad \sigma_{1,2}=1, \quad P_{1 \mathrm{oc}, K, 0}=\partial_{1}, \quad P_{1 \mathrm{oc}, K,(1,1)}=\left(\partial_{1}\right)^{2} .
\end{array}\right.
\end{align*}
$$

Operators of the form (2.1) were treated in [7]. $K$ is weakly irregular in (2.3) and irregular in (2.2).

In [6], some theorems concerning with existence of solutions with singularity on $K$ for $P(z, \partial) u(z)=f(z)$ are stated, where $\sigma_{1}, \sigma_{1,1}$ and $P_{\text {loc }, K, 0}$ are used. It follows from Theorem 1.3 and 1.4 that the conditions in [6] are invariant by coordinate transformations. Not only $\sigma_{1}$ and $P_{\mathrm{loc}, K, 0}$ but also other $\sigma_{i}$ and $P_{\mathrm{loc}, K, i}$ are used in [5], where the relation between genuine solutions and solutions of formal power series for characteristic Cauchy problems is studied.

## References

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