

## 72. On Asymptotic Equivalence of Bounded Solutions of Two Integro-Differential Equations

By Moses A. BOUDOURIDES

Department of Mathematics, Democritus University  
of Thrace, Xanthi, Greece

(Communicated by Kôzaku YOSIDA, M. J. A., June 11, 1981)

**Abstract.** In this note we consider some problems concerning the asymptotic equivalence of bounded solutions of integro-differential equations.

Consider the perturbed system of integro-differential equations

$$(P) \quad x'(t) = A(t)x(t) + \int_{t_0}^t B(t, s)x(s)ds + f(x)(t), \quad t \geq t_0,$$

where  $A, B$  are given  $n \times n$  matrices and the perturbation  $n$  vector  $f(x)(\cdot)$  is an operator mapping the set of functions defined for  $t \geq t_0$  into itself; for example, typical perturbations are of the form

$$f(x)(t) = f(t, x(t)) \quad \text{or} \quad \int_{t_0}^t K(t, s, x(s))ds$$

$$\text{or} \quad x(t) \int_{t_0}^t K(t, s, x(s))ds.$$

We are interested in comparing the bounded solutions of (P) with those of the related unperturbed linear system

$$(L) \quad y'(t) = A(t)y(t) + \int_{t_0}^t B(t, s)y(s)ds, \quad t \geq t_0.$$

In particular, we will determine conditions on  $A, B$  and  $f$  so that each bounded solution  $y$  of (L) corresponds to a bounded solution  $x$  of (P), in such a way that their difference  $y - x$  tends to zero asymptotically, and conversely, each bounded solution  $x$  of (P) corresponds to a bounded solution  $y$  of (L) such that their difference  $x - y$  tends again to zero asymptotically. In other words, the systems (P) and (L) should be asymptotically equivalent.

J. A. Nohel ([7], [8]) has established the asymptotic equivalence of (P) and (L) in the case that the linear system (L) is asymptotically stable. Our aim is to cover the cases that the linear system (L) is conditionally asymptotically stable, conditionally uniformly asymptotically stable and conditionally uniformly stable.

The fundamental solution matrix (or resolvent kernel) of (L) is the solution  $Y(t, s)$  of the matrix equation

$$\frac{\partial}{\partial t} Y(t, s) = A(t)Y(t, s) + \int_s^t B(t, r)Y(r, s)dr, \quad t \geq s \geq t_0,$$

$$Y(s, s) = I,$$

$\lambda, 0 < \lambda < \infty,$

$$(1) \quad \limsup_{\substack{t \rightarrow \infty \\ s \geq t}} \omega(s, \lambda) = 0,$$

then, corresponding to each bounded solution  $y$  of (L), there exists a bounded solution  $x$  of (P) such that

$$(2) \quad \lim_{t \rightarrow \infty} |x(t) - y(t)| = 0.$$

Conversely, to each bounded solution  $x$  of (P) there corresponds a bounded solution  $y$  of (L) such that (2) holds.

**Theorem 2.** Suppose that  $H_1^q$  and  $H_3$  hold for  $1 < q < \infty$ . If for every  $\lambda, 0 < \lambda < \infty,$  and  $p, 1 < p < \infty, p^{-1} + q^{-1} = 1,$

$$(3) \quad \int_0^\infty \omega^p(s, \lambda) ds < \infty,$$

then the conclusions of Theorem 1 remain true.

The above theorems in the case  $p \equiv 0$  (i.e. (L) asymptotically stable) are reduced to the results of Nohel ([7], [8]). In the differential equations case ( $B \equiv 0$ ) they are reduced to the results of Coppel [2] and Hallam [5]. Note that in the latter case, it turns out that  $P(t) = -P_2 Y^{-1}(t),$  where  $Y(t)$  is a fundamental solution matrix, and so  $W(t, s) = Y(t) P_2 Y^{-1}(s)$  and  $V(t, s) = Y(t) P_1 Y^{-1}(s),$  where  $P_1, P_2$  are complementary projections.

The conditions on  $\omega$  in Theorem 2 can be slightly extended in the cost of slightly restricting the hypothesis  $H_1^q$ . Thus the next theorem generalizes to integro-differential equations a result of Lovelady [6] for differential equations.

**Theorem 3.** Suppose that  $H_3$  holds and that there exist constants  $K, q,$  with  $K > 0$  and  $1 < q < \infty,$  such that for each  $t \geq t_0$

$$(4) \quad \left\{ \sum_{k=t_0}^t \int_k^{k+1} |V(t, s)| ds \right\}^{1/q} + \left\{ \sum_{k=t}^\infty \int_k^{k+1} |W(t, s)| ds \right\}^{1/q} \leq K.$$

If for every  $\lambda, 0 < \lambda < \infty,$  and  $p, 1 < p < \infty, p^{-1} + q^{-1} = 1,$

$$(5) \quad \lim_{t \rightarrow \infty} \int_t^{t+1} \omega^p(s, \lambda) ds = 0,$$

then the conclusions of Theorem 1 remain true.

The next theorem establishes the asymptotic equivalence of (P) and (L) under conditions which imply that (L) is conditionally uniformly asymptotically stable.

**Theorem 4.** Suppose that  $H_1^\infty$  and  $H_3$  hold. If for every  $\lambda, 0 < \lambda < \infty,$  either (1) or (3) is valid, the latter for  $p$  such that  $1 < p < \infty,$  then the conclusions of Theorem 1 remain true.

When the linear system (L) is conditionally uniformly stable, the following theorem establishes the asymptotic equivalence of (P) and (L) generalizing the differential equations result of Brauer and Wong [1].

**Theorem 5.** Suppose that  $H_2^\infty$  and  $H_3$  hold. If for every  $\lambda, 0 < \lambda < \infty,$

where  $I$  is the  $n \times n$  identity matrix. If  $s > t \geq t_0$ , we define  $Y(t, s) \equiv 0$ . In what follows, we will assume that  $A(t)$  and  $B(t, s)$  are locally integrable for  $t \geq t_0$  and  $t \geq s \geq t_0$  respectively. Then (cf. [8]),  $Y(t, s)$  exists, it is continuous and, for locally integrable perturbations  $f(x)(\cdot)$ , (P) is equivalent to the following Volterra integral equation

$$x(t) = Y(t, t_0)x(t_0) + \int_{t_0}^t Y(t, s)f(x)(s)ds, \quad t \geq t_0.$$

We will assume that there exists an  $n \times n$  matrix  $P(t)$ , locally integrable for  $t \geq t_0$ , in terms of which we define the following matrices (in the notation of [3])

$$\begin{aligned} V(t, s) &= Y(t, s) - Y(t, t_0)P(s), & t_0 \leq s \leq t, \\ W(t, s) &= -Y(t, t_0)P(s), & t_0 \leq t \leq s. \end{aligned}$$

Concerning the linear system (L) we make the following hypotheses

$H_1^q$ : there exist constants  $K, q$ , with  $K > 0$  and  $1 \leq q < \infty$ , such that for each  $t \geq t_0$

$$\left\{ \int_{t_0}^t |V(t, s)|^q ds \right\}^{1/q} + \left\{ \int_t^\infty |W(t, s)|^q ds \right\}^{1/q} \leq K;$$

$H_1^\infty$ : there exist constants  $K_1, K_2, a_1, a_2$ , all positive, such that for each  $t \geq t_0$

$$\begin{aligned} |V(t, s)| &\leq K_1 e^{-a_1(t-s)}, & t_0 \leq s \leq t, \\ |W(t, s)| &\leq K_2 e^{-a_2(s-t)}, & t_0 \leq t \leq s; \end{aligned}$$

$H_2$ : there exists a constant  $K > 0$  such that for each  $t \geq t_0$

$$\begin{aligned} |V(t, s)| &\leq K, & t_0 \leq s \leq t, \\ |W(t, s)| &\leq K, & t_0 \leq t \leq s; \end{aligned}$$

$H_3$ : for each fixed  $T \geq t_0$

$$\lim_{t \rightarrow \infty} \int_{t_0}^T |V(t, s)| ds = 0.$$

J. M. Cushing ([3], [4]) has shown that the above hypotheses are necessary and sufficient conditions for the admissibility of certain function spaces and for conditional stability of (L). Moreover, he has shown that conditional stability is preserved for (P) under appropriate perturbations  $f(x)(\cdot)$ .

Let  $C$  denote the Banach space of continuous and bounded vector functions  $u(t)$  for  $t \geq t_0$ . The norm of  $u \in C$  is  $\|u\| = \sup_{t \geq t_0} |u(t)|$ .

As for the perturbation  $f(x)(\cdot)$ , we assume that  $f: C \rightarrow C$  is continuous and such that for any  $x \in C$  and  $t \geq t_0$

$$|f(x)(t)| \leq \omega(t, \|x\|),$$

where  $\omega(t, r)$  is a given nonnegative function which is continuous in  $t \geq 0$  for each fixed  $r \geq 0$  and nondecreasing in  $r \geq 0$  for each fixed  $t \geq 0$ .

Now we are in the position to establish the asymptotic equivalence of (P) and (L) under conditions which imply that (L) is conditionally asymptotically stable.

**Theorem 1.** *Suppose that  $H_1^q$  and  $H_3$  hold for  $q=1$ . If for every*

$$(6) \quad \int_0^{\infty} \omega(s, \lambda) ds < \infty,$$

then the conclusions of Theorem 1 remain true.

The proofs of all the above theorems are similar to those of the differential equations cases (cf. [1], [2], [5], [6]). Here we will only indicate the essential steps of proof.

On an appropriate closed ball  $S$  of  $C$  we define, for given  $y \in C$  solution of (L), the mapping

$$Tx(t) = y(t) + \int_{t_0}^t V(t, s)f(x)(s)ds + \int_t^{\infty} W(t, s)f(x)(s)ds.$$

Using the hypotheses on  $V$ ,  $W$  and  $\omega$ , we obtain (through Hölder's inequality) that  $T$  is a continuous mapping of  $S$  into itself. Clearly  $TS$  is uniformly bounded. Since  $z = Tx$  solves the integral equation

$$z(t) = Y(t, t_0) \left\{ y(t_0) - \int_{t_0}^{\infty} P(s)f(x)(s)ds \right\} + \int_{t_0}^t Y(t, s)f(x)(s)ds,$$

it follows that  $z$  solves the nonhomogeneous linear system

$$z'(t) = A(t)z(t) + \int_{t_0}^t B(t, s)z(s)ds + f(x)(t),$$

i.e.  $TS$  is equicontinuous. Hence, Schauder's Fixed Point theorem implies the existence of a solution  $x \in C$  of (P), which is easily seen to verify (2). The converse is quite simple.

### References

- [1] F. Brauer and J. S. W. Wong: On the asymptotic relationships between solutions of two systems of ordinary differential equations. *J. Differential Equations*, **6**, 527-543 (1969).
- [2] W. A. Coppel: *Stability and Asymptotic Behavior of Differential Equations*. Heath, Boston (1965).
- [3] J. M. Cushing: An operator equation and bounded solutions of integro-differential systems. *SIAM J. Math. Anal.*, **6**, 433-445 (1975).
- [4] —: Bounded solutions of perturbed Volterra integro-differential systems. *J. Differential Equations*, **20**, 61-70 (1976).
- [5] T. G. Hallam: On asymptotic equivalence of the bounded solutions of two systems of differential equations. *Michigan Math. J.*, **16**, 353-363 (1969).
- [6] D. L. Lovelady: Nonlinear Stepanoff-bounded perturbation problems. *J. Math. Anal. Appl.*, **50**, 350-360 (1975).
- [7] J. A. Nohel: Perturbations of Volterra equations and admissibility. Japan-United States Seminar on Ordinary Differential and Functional Equations. *Lect. Notes in Math.*, vol. 243, pp. 40-53 (1971).
- [8] —: Asymptotic equivalence of Volterra equations. *Ann. Mat. Pura Appl.*, (4) **96**, 339-347 (1973).