# 90. A Class of General Boundary Conditions for Multi-Dimensional Diffusion Equation 

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1. Let $D$ be the upper half space $R_{+}^{N}=\left\{\left(x_{1}, \cdots, x_{N}\right) \in R^{N} \mid x_{N}>0\right\}$ of $R^{N}$, or a bounded open domain with smooth boundary in $R^{N}$, and let

$$
\begin{align*}
\frac{\partial u}{\partial t}= & A u=\sum_{1 \leq i, j \leq N} a_{i j}(x) \frac{\partial^{2} u}{\partial x_{i} \partial x_{j}}(t, x) .  \tag{1}\\
& +\sum_{1 \leq i \leq N} b_{i}(x) \frac{\partial u}{\partial x_{i}}(t, x)+c(x) u(t, x)
\end{align*}
$$

be a diffusion equation on $D$ with real smooth coefficients defined on $\bar{D}=D \cup \partial D$.

Here, we should like to introduce an existence theorem for (1) with boundary conditions of type

$$
\begin{equation*}
L u(x)=\tilde{A} u(x)+\delta(x) A u(x)+\partial u / \partial n(x)+\nu[u](x)=0, \tag{2}
\end{equation*}
$$

where $\tilde{A}$ is an elliptic differential operator with real coefficients on $\partial D$

$$
\begin{equation*}
\tilde{A} u(x)=\sum_{0 \leq|\alpha| \leq 2 n} \tilde{a}_{\alpha}(x) \tilde{D}^{\alpha} u(x), \quad x \in \partial D, \tag{3}
\end{equation*}
$$

$\tilde{D}^{\alpha} u(x)=\partial^{|\alpha|} u(x) / \partial \xi_{1, x}^{\alpha_{1}} \cdots \partial \xi_{N-1}^{\alpha N-1, x}, \alpha=\left(\alpha_{1}, \cdots, \alpha_{N-1}\right) . \quad\left\{\xi_{i, x}(y), 1 \leq i \leq N\right\}$ is a local coordinate near $x \in \partial D$, and is also a set of bounded functions on a neighbourhood of $\bar{D} . \delta(x)$ is a non-positive function on $\partial D . u \rightarrow \nu[u]$ is an integro-differential operator of type

$$
\begin{equation*}
\nu[u](x)=(-1)^{[m / 2]} \int_{\bar{D} \backslash x x\}}\left(u(y)-\sum_{0 \leq|\alpha| \leq m} \frac{1}{\alpha!} \tilde{D}^{\alpha} u(x) \xi_{x}^{\alpha}(y)\right) \nu(x, d y), \tag{4}
\end{equation*}
$$

where $\xi_{x}^{\alpha}(y)=\xi_{1, x}^{\alpha_{1}}(y) \cdots \xi_{N-1, x}^{\alpha_{N}-1}(y)$ and $\alpha!=\alpha_{1}!\cdots \alpha_{N-1}!. \nu(x, \cdot)$ is a measure on $\bar{D} \backslash\{x\}$ such that, for each neighbourhood $U_{x}$ of $x \in \partial D$,

$$
\begin{equation*}
\int_{U_{x} \backslash\{x\}}\left(\sum_{1 \leq i \leq N-1}\left|\xi_{i, x}(y)\right|^{m+1}+\xi_{N, x}(y)\right) \nu(x, d y)+\nu\left(x, \bar{D} \backslash U_{x}\right)<\infty . \tag{5}
\end{equation*}
$$

$\frac{\partial}{\partial n}$ is the inward directed normal derivative defined relative to $\left\{a_{i j}(x)\right\}$. The detailed proof of our existence theorem will be published elsewhere.

In case $m=n=1$, (2) was obtained by Wentzell [1] as a necessary condition for positive solutions of (1) on a certain set up. The sufficiency was proved by [1], Ueno [2] or Sato-Ueno [3], Bony et al. [4], Taira [5], Ueno [6] or [7], and others under auxiliary conditions.

The results for general $m$ and $n$ in this paper were motivated by the method in [7], where (conditional) positive definiteness is essential instead of the positivity in the case of $m=n=1$. Another motivation
is a theorem of Gelfand-Vilenkin [8], where a conditionally positive generalized function $F$ of order $n$, on a certain space of functions, is characterized by a form
$(F, \varphi)=\sum_{0 \leq|\alpha| \leq 2 n} a_{\alpha} D^{\alpha} \varphi(0)+\int_{R^{N} \backslash\{0\}}\left(\varphi(x)-\alpha(x) \sum_{0 \leq|\alpha| \leq 2 n-1} 1 / \alpha!D^{\alpha} \varphi(0) x^{\alpha}\right) \nu(d x)$,
where $a_{\alpha}, \alpha(x)$ and $\nu(\cdot)$ satisfy certain conditions.
In case $m \geq 2$ or $n \geq 2$, the solutions of (1)-(2) for positive initial datas are not necessarily positive, and hence the solutions have no probabilistic meanings in the ordinary sense. But, in view of the works by Krylov [9], Miyamoto [10] and Hochberg [11], it seems that the diffusion equation with the boundary condition of type (2) will be interpreted intuitively in some natural way.

As in the case of $m \leq 1$ and $n=1$, the semigroups on the boundary also exist, and the wave equation with similar boundary conditions can be solved. These will be discussed in other articles.
2. We assume, for simplicity, that $\partial D$ is of class $C^{\infty}$ when $D$ is bounded, and that the coefficients of $A$ and $\tilde{A}$ and $\delta(x)$ are $C^{\infty}$ functions on $\bar{D}$ and $\partial D$, and all derivatives of the coefficients are bounded. Moreover, we assume that $A$ is strongly elliptic uniformly on $\bar{D}$.

In case $D=R_{+}^{N}$, we choose a $C^{\infty}$ function $a(x)$ on $[0, \infty)$ such that $a(x)$ $=1$ when $x \leq 1$, and $0<a(x) \leq a /|x|^{m+1}$ when $x>1$, and put

$$
\xi_{i, x}(y)=\alpha(|y-x|)\left(y_{i}-x_{i}\right), \quad 1 \leq i \leq N
$$

In case $D$ is bounded, let $\left\{\xi_{i, x}(y)\right\}$ be of class $C^{\infty}, \xi_{N, x}(y) \geq 0$ on $\bar{D}$, and $\xi_{N, x}(y)=0$ characterizes $\partial D$, and $\xi_{i, x}(x)=0$ for $1 \leq i \leq N$.

Let $\nu_{D}(x, \cdot)$ and $\nu_{\rho}(x, \cdot)$ be the restrictions of $\nu(x, \cdot)$ to $D$ and $\partial D$, and let $\nu_{D}[f]$ and $\nu_{\nu}[f]$ be defined as in (4). In case $D=R_{+}^{N}, \nu_{\partial}(x, \cdot)$ and $\nu_{D}(x, \cdot)$ are called spatially homogeneous, if there are measures $\tilde{\nu}_{\partial}(\cdot)$ on $\partial D$ and $\tilde{\nu}_{D}(\cdot)$ on $D$ such that, for each measurable subset $A$ of $\bar{D}$,

$$
\begin{align*}
& \nu_{\partial}(x,\{y+x \mid y \in A\})=\tilde{\nu}_{\partial}(A),  \tag{6}\\
& \nu_{D}(x,\{y+x \mid y \in A\})=\tilde{\nu}_{D}(A), \quad x \in \partial D .
\end{align*}
$$

A spatially homogeneous $\nu_{\partial}(x, \cdot)$ is called symmetric with respect to $x$, if

$$
\tilde{\nu}_{\partial}(\{-y \mid y \in A\})=\tilde{\nu}_{\partial}(A) .
$$

When $D=R_{+}^{N}$, let $K_{0}$ be the set of all real valued rapidly decreasing functions of class $C^{\infty}$ on $\bar{D}$. When $D$ is bounded, let $K_{0}$ $=C^{\infty}(\bar{D})$. For $f$ and $g$ on $\bar{D}$, we write

$$
\begin{gathered}
(f, g)=\int_{D} f(x) \overline{g(x)} d x,\langle f, g\rangle=\int_{\partial D} f(x) \overline{g(x)} d \tilde{x}, \\
\langle f, g\rangle_{n}=\sum_{|\alpha| \leq n}\left\langle\tilde{D}^{\alpha} f, \tilde{D}^{\alpha} g\right\rangle,
\end{gathered}
$$

$\|f\|=(f, f)^{1 / 2},\|f\|_{\partial}=\langle f, f\rangle^{1 / 2},\|f\|_{\partial, n}=\langle f, f\rangle_{n}^{1 / 2}$, where $d \tilde{x}$ is the surface element of $\partial D$. In case $D=R_{+}^{N}$, we write, for $s>0$,

$$
\langle f, g\rangle_{s}=\left\langle(1+|z|)^{s} \hat{f}(z),(1+|z|)^{s} \hat{g}(z)\right\rangle, \quad\|f\|_{\partial, s}=\langle f, f\rangle_{s}^{1 / 2}
$$

where $\hat{f}$ and $\hat{g}$ are the Fourier transforms of $f$ and $g$ as functions on $\partial D$.

Proposition 1. Let $\nu_{D}(f)(x)=\int_{D} \nu_{D}(x, d y) f(y)$ be continuous in $x \in \partial D$, and let
(7)

$$
\left\|\nu_{D}(f)\right\|_{\partial} \leq C\|f\|, \quad f \in K_{0} .
$$

Let $\nu_{D}(x, \cdot)$ be spatially homogeneous when $D=R_{+}^{N}$, and let $m=0$ when $D$ is bounded. Then, for $f$ and $g$ in $K_{0}$, and a constant $\bar{\nu}$,

$$
\begin{equation*}
\left|\left\langle\nu_{D}[f], g\right\rangle\right| \leq \bar{\nu}\left(\|f\| \cdot\|g\|_{\partial}+\|f\|_{\partial, m / 2} \cdot\|g\|_{\partial, m / 2}\right) . \tag{8}
\end{equation*}
$$

Proposition 2. Let $D=R_{+}^{N}$. If $\nu(x, \cdot)$ satisfies (5) and $\nu_{\rho}(x, \cdot)$ is spatially homogeneous, then, for each $\varepsilon>0$, there is a constant $C_{\mathrm{c}}$ such that
(9) $\left|\left\langle\nu_{\partial}[f], g\right\rangle\right| \leq \varepsilon\|f\|_{\partial,(m+1) / 2} \cdot\|g\|_{\partial,(m+1) / 2}+C_{\varepsilon}\|f\|_{\partial} \cdot\|g\|_{\partial}, f, g \in K_{0}$.

Proposition 3. Let $D=R_{+}^{N}$, and $m / 2<s<(m+1) / 2$. We assume that
(i) $\nu_{\jmath}(x, \cdot)$ is spatially homogeneous,
(ii) there are circular cones $C^{1}, C^{2}, \cdots, C^{l}$ on $\partial D$ with the origin $0=(0, \cdots, 0)$ as the vertices and with the vertical angles less than $\pi / 2$, and $\partial D=\bigcup_{1 \leq k \leq 1} C^{k}$,
(iii) there is a sequence $r_{1}=1, r_{2}, r_{3}, \cdots$ such that

$$
\begin{array}{cl}
\underline{a} \cdot r_{j}<r_{j+1}<\bar{a} \cdot r_{j}, & \text { for } 0<\underline{a}<\bar{a}<1, j=1,2, \cdots \\
\underline{c} \cdot r_{j}^{-2 s}<\tilde{\nu}\left(C_{j}^{k}\right)<\bar{c} \cdot r_{j}^{-2 s}, & \text { where } C_{j}^{k}=\left\{x \in C^{k}\left|r_{j+1}<|x| \leq r_{j}\right\} .\right.
\end{array}
$$

Then, there are constants $\underline{b}$, and $\bar{b}$ such that, for $f$ and $g$ in $K_{0}$,

$$
\begin{equation*}
-\left\langle\nu_{\partial}[f], f\right\rangle \geq \underline{b}\|f\|_{\partial, s}^{2}, \tag{10}
\end{equation*}
$$

$$
\begin{equation*}
\left|\left\langle\nu_{\partial}[f], g\right\rangle\right| \leq \bar{b}\|f\|_{\partial, s} \cdot\|g\|_{\partial, s} \tag{11}
\end{equation*}
$$

3. We define, for $f$ and $g$ in $K_{0}$,

$$
\begin{gathered}
(f, g)_{\delta}=(f, g)+\langle f, g \cdot| \delta| \rangle, \quad\|f\|_{\delta}=(f, f)_{\delta}^{1 / 2} \\
B_{\lambda}(f, g)=(\lambda f-A f, g)_{i}-\langle L f, g\rangle, \quad \lambda \geq 0
\end{gathered}
$$

Now, we consider the following four cases (I)-(IV).
( I ) $D=R_{+}^{N} . \quad \tilde{A}$ is strongly elliptic of order $2 n$ uniformly on $\partial D$. $\nu(x, \cdot)$ satisfies (5), $\nu_{\rho}(x, \cdot)$ is spatially homogeneous and symmetric with respect to $x$, and $\nu_{D}(x, \cdot)$ vanishes.
(II) $D=R_{+}^{N}$, and $n \geq(m+1) / 2 . \quad \tilde{A}$ is strongly elliptic of order $2 n$ uniformly on $\partial D . \nu(x, \cdot)$ satisfies (5), $\nu_{j}(x, \cdot)$ is spatially homogeneous, and $\nu_{D}(x, \cdot)$ satisfies the condition of Proposition 1.
(III) $D=R_{+}^{N}$, and $n \leq m / 2 . \quad \tilde{A}$ is a differential operator of order at most $2 n$ on $\partial D . \nu(x, \cdot)$ satisfies (5), $\nu_{D}(x, \cdot)$ and $\nu_{\partial}(x, \cdot)$ satisfy the conditions of Propositions 1 and 3, respectively.
(IV) $D$ is bounded, and $m=0 . \quad \tilde{A}$ is strongly elliptic of order $2 n$ uniformly on $\partial D . \quad \nu[f](x)$ is continuous for each $C^{\infty}$ function $f$ on $\bar{D}$. $\nu_{0}(x, \cdot)$ has a symmetric density $\nu_{\partial}(x, y)$ with respect to the surface element $d \tilde{x}$, and $\nu_{D}(x, \cdot)$ satisfies the condition of Proposition 1.

Proposition 4. If one of the conditions (I), (II), (III) and (IV) is satisfied, then there is a constant $\lambda_{0}>0$ such that $\|f\|_{L}=B_{\lambda_{0}}(f, f)^{1 / 2}$ is a
norm on $K_{0}$, and for $f$ and $g$ in $K_{0}$,

$$
\begin{gather*}
\left|B_{\lambda}(f, g)\right| \leq k_{2}\|f\|_{L} \cdot\|g\|_{L}, \quad \lambda \geq \lambda_{0},  \tag{12}\\
B_{\lambda}(f, f) \geq k\|f\|_{L}^{2}, \quad \lambda \geq \lambda_{0},  \tag{13}\\
B_{\lambda}(f, f) \geq\|f\|_{\delta}^{2}, \quad \lambda \geq \lambda_{0} . \tag{14}
\end{gather*}
$$

When one of (I), (II), (III) and (IV) is satisfied, let $H_{\delta}$ and $K$ be the completions of $K_{0}$ with respect to $\left\|\|_{\sigma}\right.$ and $\| \|_{L}$, respectively. Since it can be proved that $\left\|\|_{L}\right.$ is closable with respect to $\| \|_{\partial}, K$ is imbedded in $H_{\delta}$ uniquely. By Proposition 4, $B_{\lambda}(f, g)$ can be extended to a bilinear form on $K$, which, with the same notation, satisfies (12) -(14) for $f, g$ in $K$. Moreover, it can be proved as in [7] that the following definition is possible.

Definition. Let $\mathfrak{D}\left(A_{L}\right)$ be the set of all $f$ in $K$ such that there are a sequence $\left\{f_{n}\right\}$ in $K_{0}$ and $g$ in $H_{\delta}$ such that $\lim _{n \rightarrow \infty}\left\|f_{n}-f\right\|_{L}=0$, and

$$
\lim _{n \rightarrow \infty}\left\{\left(A f_{n}-g, h\right)_{\delta}+\left\langle L f_{n}, h\right\rangle\right\}=0, \quad \text { for each } h \in K_{0}
$$

We define $A_{L}$ by $A_{L} f=g$ for above $f$ in $\mathfrak{D}\left(A_{L}\right)$.
Theorem. Under one of the conditions (I), (II), (III) and (IV), $A_{L}$ is the generator of a semigroup $\left\{T_{t}, t \geq 0\right\}$ of linear operators on $H_{\dot{\delta}}$, which is strongly continuous in $t \geq 0$, and satisfies

$$
\left\|T_{t} f\right\|_{\delta} \leq e^{\lambda_{0} t}\|f\|_{\delta}, \quad f \in H_{\delta}
$$

The domain $\mathfrak{D}\left(A_{L}\right)$ is a dense subspace of $K$.
Remark. If $f$ in $K_{0}$ satisfies $L f(x)=0$ on $\partial D$, then $f$ belongs to $\mathfrak{D}\left(A_{L}\right)$. Conversely, if $f$ belongs to $\mathfrak{D}\left(A_{L}\right) \cap K_{0}$ and $A_{L} f$ is continuous on $\bar{D}$, then $f$ satisfies $L f(x)=0$ on $\partial D$.

The conditions in Proposition 3 are satisfied in the followings.
Example 1. $D=R_{+}^{N} . \quad \tilde{\nu}_{\partial}(\cdot)$ in (6) vanishes on $\partial D \cap\{x||x|>1\}$ and

$$
\tilde{\nu}_{\partial}(d x)=|x|^{-2 s-1} d \tilde{x}, \quad|x| \leq 1
$$

Example 2. $D=R_{+}^{N}$ and $0<a<1 . \quad \underline{\underline{x}}_{k, j}$ and $-\underline{\underline{x}}_{k, j}$ are the points whose $k$-th coordinates are $a^{j}$ and $-a^{j}$ respectively, and other coordinates are $0 . \quad \tilde{\nu}_{j}(\cdot)$ is concentrated on $\left\{\underline{\underline{x}}_{k, j},-\underline{\underline{x}}_{k, j}, i \leq k \leq N-1\right.$, $j \geq 1\}$, and

$$
\tilde{\nu}_{\partial}\left(\left\{\underline{\underline{x}}_{k, j}\right\}\right)=\tilde{\nu}_{\partial}\left(\left\{-\underline{\underline{x}}_{k, j}\right\}\right)=c_{k} a^{-2 j s}, \quad 1 \leq k \leq N-1, j \geq 1 .
$$

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