

57. A Sharp Form of the Existence Theorem for Hyperbolic Mixed Problems of Second Order

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§ 1. Introduction. In this paper we consider the following initial boundary value problem

$$\{P, B\} \begin{cases} Pu = f(x, t), & \text{for } x \in \Omega, t > 0, \\ Bu|_{\partial\Omega} = g(s, t) & \text{for } s \in \partial\Omega, t > 0, \\ D_t^j u|_{t=0} = u_j(x), (j=0, 1), & \text{for } x \in \Omega, \end{cases}$$

in the cylindrical domain $\Omega \times (0, \infty)$, where Ω is the exterior or the interior of a smooth and compact hypersurface $\partial\Omega$ in R^{n+1} . P is a regularly hyperbolic operator with respect to t , and $\partial\Omega$ is non-characteristic to P . Moreover we assume that the only one of $\tau_1(\nu)$ and $\tau_2(\nu)$ is negative for all $(s, t) \in \partial\Omega \times (0, \infty)$, where $\tau_j(\xi)$ are the roots of $P(s, t; \xi, \tau) = 0$ and ν is the inner unit normal at (s, t) . This condition means that the number of boundary conditions is one. B is a first order operator:

$$B = B(s, t; D_x, D_t) = \sum_{j=1}^{n+1} b_j(s, t) D_{x_j} - c(s, t) D_t, \quad D_t = \frac{1}{i} \frac{\partial}{\partial t} \quad \text{etc.},$$

where $\sum_{j=1}^{n+1} b_j(s, t) \nu_j = B(s, t, \nu, 0) = 1$. We assume that all the coefficients are smooth and bounded, and that they remain constant outside some compact sets.

We are concerned with the following question: Under what condition the solution $u(t)$ of $\{P, B\}$ has the continuity for the initial data in the same Sobolev space? The answer is just the condition (H) below, which was derived in [2].¹⁾ We state it as

Theorem 1. *The necessary and sufficient condition that the energy inequality*

1) (H) was introduced as a characterization of problems which satisfy

$$r |u|_{1,r}^2 \leq \frac{c}{r} |Pu|_{0,r}^2,$$

holds for any smooth function with compact support satisfying the homogeneous boundary condition, in the case of constant coefficients. See also [1] and [3]. In [2] we proved the existence theorem with the initial data in a weaker sense. It is difficult to prove the estimate (1.1) as the direct extension of the arguments in [2]. For this purpose we need more precise considerations on the global properties of (H).

$$(1.1) \quad \sum_{j=0}^1 \|(D_t^j u)(t)\|_{1-j} \leq C(T) \left\{ \sum_{j=0}^1 \|(D_t^j u)(0)\|_{1-j} + \int_0^t \|(Pu)(s)\|_0 ds \right\}$$

holds for any $u = u(x, t)$ in $C_0^\infty(\bar{\Omega} \times R^1)$ satisfying $Bu|_{\partial\Omega} = 0$ and for any t in $(0, T)$ with some constant $C(T)$, is the following condition (H).

(H): For all $(s, t, \eta) \in \partial\Omega \times R^1 \times S^n$, $(\eta \cdot \nu = 0)$, $\{P, B\}$ satisfies the followings. (We state the case $P = \square$. In general, see Theorem 2 in [2].)

$$(I) \quad A = \begin{pmatrix} 2 \operatorname{Re} \alpha & \operatorname{Im}(\alpha\bar{\beta}) \\ \operatorname{Im}(\alpha\bar{\beta}) & 2 \operatorname{Re} \beta \end{pmatrix} \geq 0, \text{ when } |\operatorname{Re} \alpha| + |\operatorname{Re} \beta| \neq 0,$$

$$(II) \quad 1 + (\operatorname{Im} \alpha)(\operatorname{Im} \beta) \geq \delta > 0, \text{ when } |\operatorname{Re} \alpha| + |\operatorname{Re} \beta| = 0.$$

Here $\alpha = c(s, t) + B(s, t, \eta, 0)/|\eta|$ and $\beta = c(s, t) - B(s, t, \eta, 0)/|\eta|$.

$\|u(t)\|_k$ means Sobolev k -norm in Ω .

We can say more, that is

Theorem 2. Suppose (H). If $f(t) \in \mathcal{E}_t^0(L^2(\Omega))$,²⁾ $g \in \mathcal{E}_t^i(H^k(\partial\Omega))$ and $u_j \in H^{1-j}(\Omega)$, ($j = 0, 1$), then there exists a solution $u(t)$ of $\{P, B\}$ in $\mathcal{E}_t^0(H^1(\Omega)) \cap \mathcal{E}_t^1(L_2(\Omega))$ satisfying the following energy estimate (E) with $k = 0$. Moreover if we assume that the smooth data $\{f, g, u_0, u_1\}$ satisfy the compatibility condition³⁾ of order k , ($k \geq 1$), then the solution satisfies

$$(E) \quad \sum_{j=0}^1 \|(D_t^j u)(t)\|_{1-j+k}^2 + \gamma \sum_{i+j \leq k} \int_0^t e^{r(t-s)} \langle\langle (D_x^i D_t^j u)(s) \rangle\rangle_{\frac{1}{2}-i-j+k}^2 ds \\ \leq C e^{r t} \left\{ \sum_{j=0}^1 \|u_j\|_{1-j+k}^2 + \frac{1}{\gamma} \sum_{j \leq k} \int_0^t e^{-r s} (\| (D_t^j f)(s) \|_{k-j}^2 + \langle\langle (D_t^j g)(s) \rangle\rangle_{\frac{1}{2}+k-j}^2) ds \right\},$$

for $\gamma > \gamma_k$, where C and γ_k are positive constants.

$\langle\langle v(s) \rangle\rangle_r$ means Sobolev r -norm in $\partial\Omega$. The solution has the same propagation speed as that in the case of Cauchy problem.

Remark. If $g \equiv 0$ in the problem $\{P, B\}$, the above solution u satisfies (1.1).

The detailed proof will be given in a forthcoming paper. Here we sketch the proofs of (1.1) and (E) in the case where $P = \square$ and $\Omega = R_+^{n+1} = \{(x, y) : x > 0, y \in R^n\}$ for simplicity.

§ 2. The choice of Q . We prove (1.1) by the integration by parts of

$$\mathcal{Q}((0, t), P, Q; \varphi_j u) = 2i \operatorname{Im} \int_0^t \int_{R_+^{n+1}} e^{-2r t} P \varphi_j u \overline{Q \varphi_j u} dx dy dt,$$

where Q is a suitable first order operator. Here $\varphi_j u = \overline{\mathcal{F}_y} \varphi_j \mathcal{F}_y u$ is a localization of u corresponding to the partition of unity:

$$(*) \quad \sum_{j=0}^{\text{finite}} \varphi_j(x, y, t, \eta) \equiv 1 \text{ on } \bar{R}_+^1 \times R^n \times \bar{R}_+^1 \times R^n,$$

where φ_j , ($j \geq 1$), are homogeneous of degree zero in η for $|\eta| \geq 1$. We take Q in a neighbourhood of the boundary as follows:

2) $\mathcal{E}_t^k(H) \ni u(t)$ means that u is a continuous function in H , up to their k -th derivatives.

3) See §9 in [2].

(I) $Q = (\alpha_1 z_1 + \beta_1 z_2) + \varepsilon(z_1 + cz_2 - d\xi)$, if the supports of φ_j contain any point satisfying $\alpha_1 \beta_1 = 0$, ($z_1 = \tau - |\eta|$, $z_2 = \tau + |\eta|$, $\alpha = \alpha_1 + i\alpha_2$, $\beta = \beta_1 + i\beta_2$).

(II) $Q = (\alpha_1 z_1 + \beta_1 z_2) - \varepsilon(2\xi - c_1 z_1 - c_2 z_2)$, in other cases.

Here ε is a sufficiently small positive number and c_1, c_2 and c are positive functions in (y, t, η) . We choose these as follows:

$$(1.1) \quad 2(\alpha_1 z + \beta_1)(c_1 z + c_2) = |\alpha|^2 z^2 + 2(2 + \operatorname{Re} \alpha \bar{\beta})z + |\beta|^2 + (\det A) / \alpha_1^2,$$

$$(1.2) \quad \varepsilon_1 < c < 1 / \varepsilon_2$$

$$(1.3) \quad d = 4(d_1 X + d_2 Y),$$

where $X = (\beta_1 - \alpha_1 \varepsilon_1) / \rho(1 - \varepsilon_1 \varepsilon_2)$,

$$Y = (\alpha_1 - \beta_1 \varepsilon_2) / \rho(1 - \varepsilon_1 \varepsilon_2),$$

and

$$\begin{pmatrix} d_1 \\ d_2 \end{pmatrix} = \frac{1}{1 - \varepsilon_1 \varepsilon_2} \begin{pmatrix} 1 & -\varepsilon_2 \\ -\varepsilon_1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ c \end{pmatrix}.$$

Here $\varepsilon_1, \varepsilon_2$ and ρ are defined by

$$(1.4) \quad |\alpha|^2 z^2 + 2(2 + \operatorname{Re} \alpha \bar{\beta})z + |\beta|^2 = \rho(z + \varepsilon_1)(1 + \varepsilon_2 z).$$

We remark that for the estimates (1.1) and (E) we need the localization of type (*). This makes the choice of Q difficult. In the actual calculations we employ a special device concerning the reverse process of Green formula which will be explained below. We need these, because the estimates (1.1) and (E) are finer than the estimate; $\gamma |u|_{1,r}^2 \leq \frac{c}{\gamma} |Pu|_{0,r}^2$ which was treated earlier in [2], [1] and [3].

§ 3. Green formula associated with the boundary condition.

To $\mathcal{G}((0, t), P, Q; u)$ there corresponds the following symbolic calculus:

$$\begin{aligned} G(P, Q) &= P(\xi, \eta, \tau)Q(\zeta, \eta, \bar{\tau}) - Q(\xi, \eta, \tau)P(\zeta, \eta, \bar{\tau}) \\ &= (\xi - \zeta)G_x(P, Q) - (\tau - \bar{\tau})G_t(P, Q). \end{aligned}$$

Here $G_x(P, Q)$ and $G_t(P, Q)$ are quadratic forms in (ξ, z_1, z_2) , z_1 and z_2 being $z_1 = \tau - |\eta|$ and $z_2 = \tau + |\eta|$ respectively. Now, taking account of the boundary condition $D_x u \Big|_{x=0} = \frac{1}{2}(\alpha z_1 + \beta z_2)(D)u \Big|_{x=0} + g$, we substitute

$\frac{1}{2}(\alpha z_1 + \beta z_2)$ into ξ in $G_x(P, Q)$, and $\frac{1}{2}(\bar{\alpha} z_1 + \bar{\beta} z_2)$ into ζ in $G_x(P, Q)$. Then $G_x(P, Q)$ becomes an Hermite form $G'_x(P, Q)$ in (z_1, z_2) . Denote the *anti-symmetric part* of $G'_x(P, Q)$ by $i \operatorname{Im} g(P, Q)_{1,2}(z_1 \bar{z}_2 - z_2 \bar{z}_1)$ and notice that

$$(\xi - \zeta)\{z_1 \bar{z}_2 - z_2 \bar{z}_1\} = -(\tau - \bar{\tau})\{\xi \bar{z}_1 - \xi \bar{z}_2 - z_1 \zeta + z_2 \xi\}.$$

Hence we have

$$G(P, Q) = (\xi - \zeta)\tilde{G}_x(P, Q) - (\tau - \bar{\tau})\tilde{G}_t(P, Q),$$

where $\tilde{G}_x(P, Q)$ is a symmetric part of $G'_x(P, Q)$ and \tilde{G}_t is an *Hermite form*:

$$\tilde{G}_t(P, Q) = G_t(P, Q) + i \operatorname{Im} g(P, Q)_{1,2}\{\xi \bar{z}_1 - \xi \bar{z}_2 - z_1 \zeta + z_2 \xi\}.$$

Using Q defined in § 2 we can prove $\tilde{G}_x \geq 0$ and $\tilde{G}_t > 0$.

References

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