

## NON-UNIQUENESS OF OBSTACLE PROBLEM ON FINITE RIEMANN SURFACE

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### Abstract

In [1], R. Fehlmann and F. P. Gardiner studied an extremal problem for a finite Riemann surface to establish a slit mapping theorem. In this article, we give a condition for non-uniqueness of such slit mappings, by using a deformation of a Riemann surface.

### 1. Introduction

Let  $S$  be an analytically finite Riemann surface, namely, a compact Riemann surface minus finitely many points. Though all the results in the present note are generalized for topologically finite Riemann surfaces in an appropriate way (see [5]), for simplicity, we restrict ourselves to this case.

Let  $A(S)$  be the set of integrable holomorphic quadratic differentials  $\varphi$  on  $S$ . For  $\varphi \in A(S)$  set  $\|\varphi\| = \iint_S |\varphi| dx dy$ ,  $z = x + iy$ . Let  $\mathfrak{C}(S)$  be the family of simple closed curves on  $S$ , which are homotopic neither to a point of  $S$  nor to a puncture of  $S$ . Let  $\mathfrak{C}[S]$  be the set of free homotopy classes of elements of  $\mathfrak{C}(S)$ . For  $\varphi \in A(S)$  and  $\gamma \in \mathfrak{C}(S)$ , we denote the height of  $\gamma$  with respect to  $\varphi$  by

$$\text{height}_\varphi(\gamma) = \int_\gamma |\text{Im}(\sqrt{\varphi(z)} dz)|$$

and the height of the homotopy class  $[\gamma]$  by

$$\text{height}_\varphi[\gamma] = \inf_\beta \text{height}_\varphi(\beta),$$

where the infimum is taken over all closed curves  $\beta \in \mathfrak{C}(S)$  freely homotopic to  $\gamma$  in  $S$ .

**DEFINITION 1.1.** We say that  $E$  is an *obstacle* in  $S$  if  $E$  is a compact subset of  $S$ , if  $S \setminus E$  is connected and if  $E$  is contained in a topological disk in  $S$ .

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*Remark 1.2.* In [1] Fehlmann and Gardiner called  $E$  an obstacle if  $E$  is a compact subset in  $S$  consisting of finitely many components, each of which is simply connected, and if the natural embedding  $S \setminus E \rightarrow S$  induces a surjective homomorphism  $\pi_1(S \setminus E) \rightarrow \pi_1(S)$ . An obstacle in the sense of Definition 1.1 satisfies these conditions (see Lemma 2.3 in [5]). A compact set consisting of finitely many simply connected components may not be an obstacle in the sense of Fehlmann and Gardiner. The next example was learned from Professor Masahiko Taniguchi. Let  $E'_0 = \{x + i \sin(\pi/x) \mid x \in (-1, 0) \cup (0, 1]\} \cup \{iy \mid -1 \leq y \leq 1\}$  and set  $E_0 = \{e^{\pi iz} \mid z \in E'_0\}$ . Then we can see that the compact set  $E_0$  is connected and simply connected and  $E_0$  separates  $0$  from  $\infty$  in  $\mathbf{C}^* = \mathbf{C} \setminus \{0\}$ . Let  $\gamma$  be a non-trivial simple closed curve on an analytically finite Riemann surface  $S$ . Then there is a topological embedding  $g : \mathbf{C}^* \rightarrow S$  such that the image of the unite circle  $S^1$  under  $g$  is freely homotopic to  $\gamma$  in  $S$ . The set  $E = g(E_0)$  is connected and simply connected. Since  $S \setminus E$  is homeomorphic to  $S \setminus \gamma$  the homomorphism  $\pi_1(S \setminus E) \rightarrow \pi_1(S)$  is not surjective.

For an obstacle  $E$  of  $S$ , let  $\mathfrak{F}(S, E)$  be the family of pairs  $(f, S_f)$ , where  $f$  is a conformal map of  $S \setminus E$  into another Riemann surface  $S_f$  of the same analytic type as  $S$  such that  $f$  maps each puncture of  $S$  to a puncture of  $S_f$ . Then  $(f, S_f) \in \mathfrak{F}(S, E)$  induces an isomorphism  $\iota_f$  of the fundamental group  $\pi_1(S)$  of  $S$  onto  $\pi_1(S_f)$  (cf. [5, Lemma 2.5]). We denote by  $[S_f, \iota_f]$  the Teichmüller (equivalence) class of  $(S_f, \iota_f)$  in  $T(S)$ . Here, pairs  $(R_j, \iota_j)$ ,  $j = 1, 2$ , of Riemann surfaces  $R_j$  and orientation-preserving isomorphisms  $\iota_j : \pi_1(S) \rightarrow \pi_1(R_j)$  are said to be Teichmüller equivalent if there exists a conformal map  $h : R_1 \rightarrow R_2$  such that  $\iota_2 = h_* \circ \iota_1$ . We refer to [4] for basic facts about Teichmüller spaces. We remark that, for every  $(f, S_f) \in \mathfrak{F}(S, E)$  the set  $f(E) := S_f \setminus f(S \setminus E)$  is an obstacle of  $S_f$ .

The heights mapping theorem (cf. [3]) states that, for every  $(f, S_f) \in \mathfrak{F}(S, E)$  and  $\varphi \in A(S) \setminus \{0\}$ , there exists the unique holomorphic quadratic differential  $\varphi_f \in A(S_f) \setminus \{0\}$  such that

$$\text{height}_\varphi[\gamma] = \text{height}_{\varphi_f}(\iota_f[\gamma]) \quad \text{for every } [\gamma] \in \mathfrak{S}[S].$$

**DEFINITION 1.3.** A compact subset  $E$  of  $S$  is said to be a *horizontal slit* for  $\varphi \in A(S) \setminus \{0\}$  if each connected component of  $E$  is either a horizontal arc of  $\varphi$  or a finite union of horizontal arcs and critical points of  $\varphi$ .

Let  $E$  be an obstacle of  $S$  and  $\varphi \in A(S) \setminus \{0\}$ . Fehlmann and Gardiner [1] posed an *obstacle problem* for  $(S, E, \varphi)$  which asks the existence of  $(f, S_f) \in \mathfrak{F}(S, E)$  maximizing the quantity

$$M_f = \|\varphi_f\|_{L^1(S_f)} = \iint_{S_f} |\varphi_f|$$

in  $\mathfrak{F}(S, E)$ , and showed the following result.

**THEOREM 1.4 (Fehlmann-Gardiner).** *Suppose that  $S$  is an analytically finite Riemann surface, and that  $\varphi \in A(S) \setminus \{0\}$ . Let  $E$  be an obstacle of  $S$  with finitely*

many components. Then there exists an element  $(g, S_g) \in \mathfrak{F}(S, E)$  such that  $M_g$  attains the supremum:

$$M_g = \sup_{(f, S_f) \in \mathfrak{F}(S, E)} M_f.$$

Moreover,  $g(E)$  is a horizontal slit for  $\varphi_g$ . Furthermore if  $(f, S_f) \in \mathfrak{F}(S, E)$  is also extremal for  $(S, E, \varphi)$ , then  $f^*\varphi_f = g^*\varphi_g$  on  $S \setminus E$ .

The point  $(g, S_g) \in \mathfrak{F}(S, E)$  in Theorem 1.4 is called *extremal* for  $(S, E, \varphi)$ , and the associated differential  $\varphi_g$  is called the *extremal differential*.

Fehlmann and Gardiner asserted in [1] moreover that if  $(f, S_f) \in \mathfrak{F}(S, E)$  is also extremal for  $(S, E, \varphi)$ , then  $g \circ f^{-1}$  extends to a conformal map of  $S_f$  onto  $S_g$ . This is not necessarily valid. We show it in the following theorem. To state the result, we introduce a technical concept.

**DEFINITION 1.5.** Let  $S$  be an analytically finite Riemann surface and  $m$  be an integer with  $m \geq 2$ . Suppose that an obstacle  $E$  of  $S$  is a horizontal slit for  $\varphi \in A(S) \setminus \{0\}$ . We will call  $p_0 \in E$  a *refolding point of order  $m$*  for  $(S, E, \varphi)$  if  $p_0$  is a zero of  $\varphi$  of order  $m$  and if  $E$  contains two horizontal arcs  $\ell_1$  and  $\ell_2$  with common end point  $p_0$  such that the angle formed by them at  $p_0$  is greater than  $2\pi/(m+2)$ .

**THEOREM 1.6.** Let  $E$  be an obstacle of an analytically finite Riemann surface  $S$  and  $\varphi \in A(S) \setminus \{0\}$ . Suppose that  $(g, S_g) \in \mathfrak{F}(S, E)$  is extremal for  $(S, E, \varphi)$  and that  $g(E)$  has a refolding point  $p_0$  of order  $m \geq 3$  for  $(S_g, g(E), \varphi_g)$ . Then, there exists another extremal element  $(f, S_f) \in \mathfrak{F}(S, E)$  for  $(S, E, \varphi)$  such that  $S_f$  is not conformally equivalent to  $S_g$ .

*Remark 1.7.* In the proof, by parametrizing the arcs  $\kappa_j$ ,  $j = 1, 2$ , by  $t \in [0, 1]$  so that the  $\varphi_g$ -length of  $\kappa_j([0, t])$  is  $t$  times that of  $\kappa_j([0, 1])$ , we can actually construct a family of extremal elements  $(f_t, S_{f_t}) \in \mathfrak{F}(S, E)$ ,  $0 \leq t \leq 1$ , for the same obstacle problem for  $(S, E, \varphi)$  satisfying

- (i)  $(f_0, S_{f_0}) = (g, S_g)$ ,
- (ii) the marked Riemann surface  $\tau_t = [S_{f_t}, \iota_{f_t}]$  varies continuously in  $T(S)$ , and
- (iii)  $\tau_t \neq \tau_0$  for  $t \neq 0$ .

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## 2. Example

In this section we give an example of triple  $(S, E, \varphi)$  which satisfies the assumptions of Theorem 1.6.

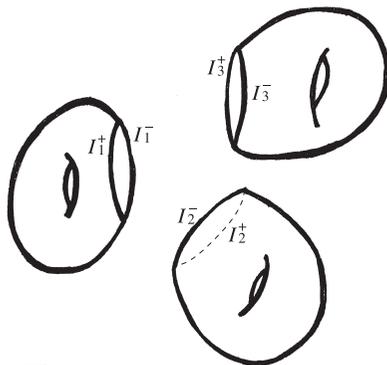


FIGURE 1.

First take three copies  $M_1, M_2, M_3$  of the rectangle

$$M = \{z = x + iy \in \mathbf{C} \mid |x| \leq 2, |y| \leq 1\},$$

and let  $z_j$  be the coordinate corresponding to  $z$  on each  $M_j$ . Next on each  $M_j$ , identify the two pairs of parallel sides under the translations

$$z_j \rightarrow z_j + 4, \quad z_j \rightarrow z_j + 2i.$$

Then we obtain three copies  $T_1, T_2, T_3$  of a torus  $T$ . The quadratic differential  $dz^2$  on  $M$  induces a holomorphic quadratic differential  $\varphi_0$  on  $T$ .

Cut  $T_j$  along the segment

$$I_j = \{z_j = x_j + iy_j \mid -1 \leq x_j \leq 0, y_j = 0\},$$

and glue them cyclically. More precisely, we paste the upper edge  $I_1^+$  of the slit  $I_1$  to the lower edge  $I_2^-$  of the slit  $I_2$ , the upper edge  $I_2^+$  of the slit  $I_2$  to the lower edge  $I_3^-$  of the slit  $I_3$ , and the upper edge  $I_3^+$  of the slit  $I_3$  to the lower edge  $I_1^-$  of the slit  $I_1$ . Then we obtain a compact Riemann surface  $S$  of genus three (see Figures 1 and 2).

Let  $\Pi$  be the natural projection of  $S$  onto the torus  $T$ , and  $\varphi$  be the pull-back of  $\varphi_0$  by  $\Pi$ . Finally, let  $E$  be the subset of  $S$  consisting of  $\ell_1$  and  $\ell_2$ , where  $\ell_i$  is the arc on  $T_i$  corresponding to  $\{z \mid 0 \leq x \leq 1, y = 0\}$ .

We now consider the obstacle problem for  $(S, E, \varphi)$ . Then the obstacle  $E$  is a horizontal slit for  $\varphi$ . Hence we know that the identity mapping of  $S$  gives an extremal slit map associated with the extremal problem for this triple. Moreover, we can easily see that the point  $p_0 = \Pi^{-1}(0)$  in  $S$  is a refolding point of order 4 for  $(S, E, \varphi)$ .

Thus the assumptions in Theorem 1.6 are satisfied and, as a consequence, the points in  $T(S)$  which are induced by the extremals for  $(S, E, \varphi)$  are not uniquely determined.

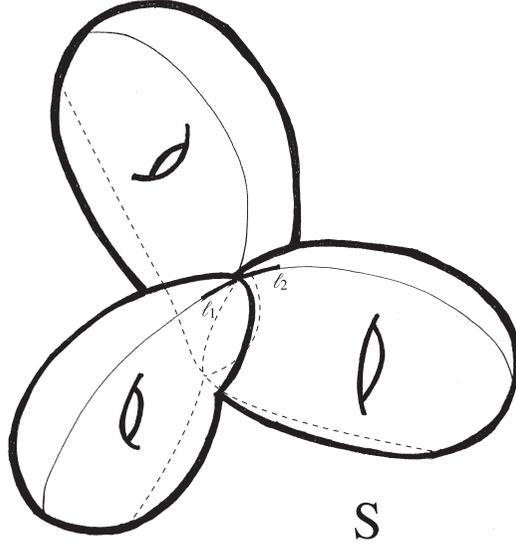


FIGURE 2.

### 3. Proof of Theorem 1.6

Assume that a component  $J$  of  $g(E)$  contains a refolding point  $p_0$  of order  $m \geq 3$  for  $(S_g, g(E), \varphi_g)$  and horizontal arcs  $\ell_1$  and  $\ell_2$  with common end point  $p_0$  and that an angle formed by  $\ell_1$  and  $\ell_2$  at  $p_0$  is

$$\frac{2k\pi}{m+2} \quad \left( 2 \leq k \leq \frac{m+2}{2} \right).$$

Note that the arcs  $\ell_1, \ell_2$  are segments on the real axis with endpoint at the origin with respect to the natural parameter

$$\zeta = \int_{z_0}^z \sqrt{\varphi_g(z)} dz,$$

where  $z$  is a local chart near  $p_0$  and  $z_0 = z(p_0)$ .

We take closed subarcs  $\kappa_j \subset \ell_j$ ,  $j = 1, 2$ , with the same  $\varphi_g$ -length such that  $p_0$  is an endpoint of each  $\kappa_j$  and that  $\varphi_g$  has no zeros on  $\kappa_j \setminus \{p_0\}$ . Let  $p_j$  be the other endpoint of  $\kappa_j$  for each  $j$ . Also set  $K = \kappa_1 \cup \kappa_2$ .

Now, cut  $S_g$  along  $\kappa_1$  and  $\kappa_2$ . For each  $j$ , let  $\kappa_j^+$  and  $\kappa_j^-$  be the right-side and the left-side edges of the slit  $\kappa_j$ , respectively, with respect to the orientation which corresponds to the move along the slit from  $p_0$  to  $p_j$ . Assume that  $\kappa_1^-$  and  $\kappa_2^+$ ,  $\kappa_1^+$  and  $\kappa_2^-$  form the angles

$$\frac{2k\pi}{m+2} \quad \text{and} \quad \frac{2\pi(m+2-k)}{m+2}.$$

at  $p_0$ , respectively.

Paste  $\kappa_1^-$  and  $\kappa_2^+$  so that points having the same absolute value with respect to  $\zeta$  are identified. In the same way, paste  $\kappa_1^+$  and  $\kappa_2^-$ . Let  $\tilde{K}$  be the union of the pasted segments. Then we obtain a new analytically finite Riemann surface  $R$  and the natural conformal embedding  $u: S_g \setminus K \rightarrow R$ . Set  $f = u \circ g$  and  $S_f = R$ . Then the pair  $(f, S_f)$  is an element of the family  $\mathfrak{F}(S, E)$ . (Figure 2 exhibits the case when  $m = 4$  and  $k = 2$ .)

Moreover, from the construction we can extend  $(u^{-1})^* \varphi_g$  naturally to a holomorphic quadratic differential  $\psi \in A(S_f)$  satisfying  $\|\psi\|_{L^1(S_f)} = \|\varphi_g\|_{L^1(S_g)}$ . The obstacle  $f(E)$  is a horizontal slit for  $\psi$ .

The following proposition is crucial in the proof of Lemma 3.2 and Lemma 3.3.

**PROPOSITION 3.1** (Second Minimal Norm Property [2, p. 54]). *Assume  $S$  is an analytically finite Riemann surface. Let  $\varphi \in A(S)$  and let  $\psi$  be a quadratic differential, continuous except possibly at the punctures of  $S$ . Suppose  $\text{height}_\varphi[\gamma] \leq \text{height}_\psi[\gamma]$  for every  $[\gamma] \in \mathfrak{S}[S]$ . Then*

$$\|\varphi\| \leq \iint_S |\sqrt{\varphi} \sqrt{\psi}| \, dx dy \leq \|\varphi\|^{1/2} \|\psi\|^{1/2}$$

and  $\|\varphi\| = \|\psi\|$  if and only if  $\varphi = \psi$ .

**LEMMA 3.2.**  $\psi = \varphi_f$ .

*Proof.* If  $\text{height}_\psi[\gamma] \leq \text{height}_{\varphi_f}[\gamma]$  for every  $[\gamma] \in \mathfrak{S}[S_f]$ , then by Proposition 3.1 we can see  $\|\psi\|_{L^1(S_f)} \leq \|\varphi_f\|_{L^1(S_f)}$ . On the other hand, since  $(g, S_g)$  is extremal for  $(S, E, \varphi)$  and  $\|\psi\|_{L^1(S_f)} = \|\varphi_g\|_{L^1(S_g)}$ , we obtain  $\|\varphi_f\|_{L^1(S_f)} \leq \|\psi\|_{L^1(S_f)}$ . Hence,  $\|\psi\|_{L^1(S_f)} = \|\varphi_f\|_{L^1(S_f)}$ . Proposition 3.1 implies  $\psi = \varphi_f$  on  $S_f$ . So we have only to show that  $\text{height}_\psi[\gamma] \leq \text{height}_{\varphi_f}[\gamma]$  for every  $[\gamma] \in \mathfrak{S}[S_f]$ .

We say that a curve  $\beta$  on  $S_g$  is a  $\varphi_g$ -polygonal curve, if  $\beta$  is the union of finitely many horizontal arcs and vertical arcs of  $\varphi_g$ . Note that for every  $[\gamma] \in \mathfrak{S}[S_g]$

$$\text{height}_{\varphi_g}[\gamma] = \inf_{\beta} \text{height}_{\varphi_g}(\beta),$$

where the infimum is taken over all  $\varphi_g$ -polygonal curves  $\beta$  freely homotopic to  $\gamma$  in  $S_g$ .

Let  $[\gamma] \in \mathfrak{S}[S]$  and  $\beta$  be a  $\varphi_g$ -polygonal curve in  $S_g$  with  $[\beta] = \iota_g[\gamma]$  in  $\mathfrak{S}[S_g]$ . We can add horizontal segments contained in  $\tilde{K}$  to the (possibly broken) curve  $u(\beta \setminus K)$  so that the resulting set  $\tilde{\beta}$  is a  $\psi$ -polygonal (closed) curve and satisfies  $[\tilde{\beta}] = \iota_f[\gamma]$  in  $\mathfrak{S}[S_f]$ . Then,

$$\text{height}_\psi(\iota_f[\gamma]) \leq \text{height}_\psi(\tilde{\beta}) = \text{height}_{\varphi_g}(\beta).$$

Hence we obtain

$$\text{height}_\psi(\iota_f[\gamma]) \leq \text{height}_{\varphi_g}(\iota_g[\gamma]) = \text{height}_{\varphi_f}(\iota_f[\gamma]).$$

Thus we have proved the assertion.  $\square$

By Lemma 3.2, we see that  $(f, S_f)$  is extremal for  $(S, E, \varphi)$  and the obstacle  $f(E)$  of  $S_f$  is a horizontal slit for  $\varphi_f$ .

LEMMA 3.3.  $[S_g, \iota_g] \neq [S_f, \iota_f]$  in  $T(S)$ .

*Proof.* Suppose that  $[S_g, \iota_g] = [S_f, \iota_f]$  in  $T(S)$ . Then there exists a conformal map  $h : S_g \rightarrow S_f$  with  $\iota_f = h_* \circ \iota_g$ . Since  $\text{height}_{h^*\varphi_f}[\gamma] = \text{height}_{\varphi_f}[h(\gamma)]$ , we obtain

$$\text{height}_{h^*\varphi_f}[\gamma] = \text{height}_{\varphi_g}[\gamma]$$

for every  $[\gamma] \in \mathfrak{S}[S_g]$ . Hence Proposition 3.1 implies that

$$h^*\varphi_f = \varphi_g \quad \text{on } S_g.$$

In particular, the map  $h$  sends the zeros of  $\varphi_g$  to those of  $\varphi_f$  while keeping multiplicities. From the argument together with the relation  $u^*\varphi_f = \varphi_g$  on  $S_g \setminus \tilde{K}$ , the number of zeros of a given order of  $\varphi_g$  on  $K$  is equal to that of  $\varphi_f$  on  $\tilde{K}$ . This is impossible, because from the construction the zero  $p_0$  of  $\varphi_g$  of order  $m \geq 3$  breaks into two zeros of  $\varphi_f$  of orders  $k - 2$  and  $m - k$ , respectively, where  $2 \leq k \leq (m + 2)/2$ . Hence the number of zeros of  $\varphi_g$  of order  $m$  on  $K$  is less than that of  $\varphi_f$  on  $\tilde{K}$ , which is a contradiction.  $\square$

Thus we have proved the assertion in Remark 1.7, and hence Theorem 1.6.

In [5], the author gave the uniqueness result under the condition that the obstacle possibly consists of infinitely many components. It is expansion of Theorem 1.4.

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